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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-670e1

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Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V _{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 μF .
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

(Continued)

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
61	59	P84	F	General purpose I/O pin.
		SCK0		Clock I/O pin for UART0
		INT15R		External interrupt request input pin
62	60	P85	M	General purpose I/O pin.
		SIN1		Serial data input pin for UART1
63	61	P86	F	General purpose I/O pin.
		SOT1		Serial data output pin for UART1
64	62	P87	F	General purpose I/O pin.
		SCK1		Clock I/O pin for UART1
65	63	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
66	64	V _{SS}	—	GND pin
67 to 70	65 to 68	P90 to P93	F	General purpose I/O pins
		PPG1, 3, 5, 7		Output pins for PPGs
71 to 74	69 to 72	P94 to P97	F	General purpose I/O pins
		OUT0 to OUT3		Waveform output pins for output compares. This function is enabled when the OCU enables waveform output.
75	73	PA0	F	General purpose I/O pin.
		RX0		RX input pin for CAN0 Interface
		INT8R		External interrupt request input pin
76	74	PA1	F	General purpose I/O pin.
		TX0		TX Output pin for CAN0
77 to 84	75 to 82	P00 to P07	G	General purpose I/O pins. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD00 to AD07		I/O pins for 8 lower bits of the external address/data bus. This function is enabled when the external bus is enabled.
		INT8 to INT15		External interrupt request input pins.
85	83	P10	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD08		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		TIN1		Event input pin for the reload timer

(Continued)

5. Handling Devices

1. Preventing latch-up

CMOS IC may suffer latch-up under the following conditions:

- A voltage higher than V_{CC} or lower than V_{SS} is applied to an input or output pin.
- A voltage higher than the rated voltage is applied between V_{CC} and V_{SS} pins.
- The AV_{CC} power supply is applied before the V_{CC} voltage.

Latch-up may increase the power supply current drastically, causing thermal damage to the device.

For the same reason, also be careful not to let the analog power-supply voltage (AV_{CC} , AV_{RH}) exceed the digital power-supply voltage.

2. Handling unused pins

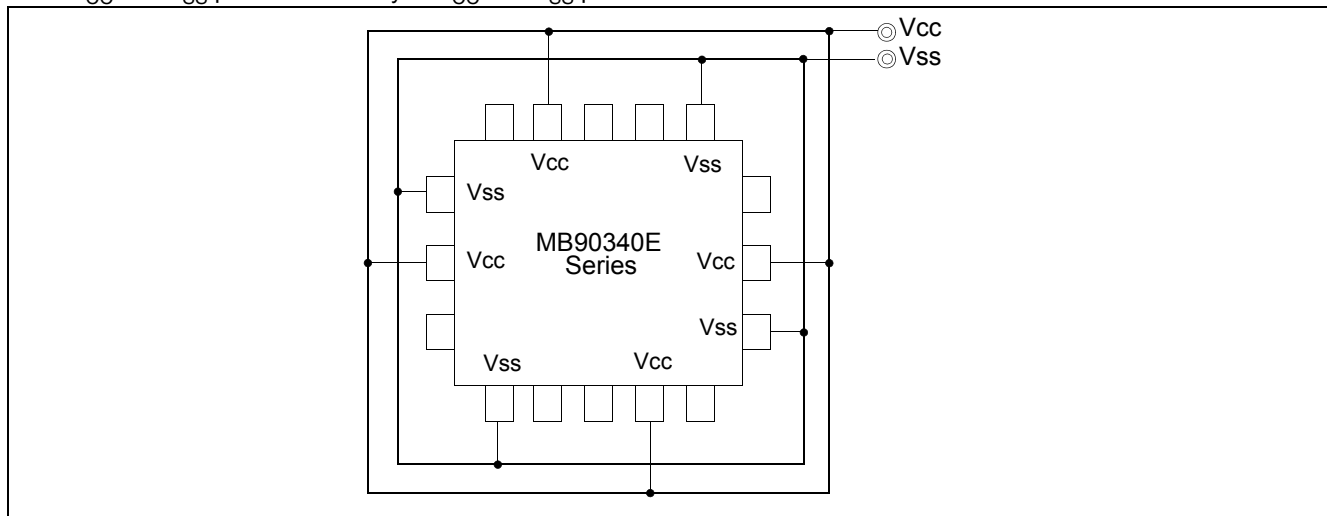
Leaving unused input terminals open may lead to permanent damage due to malfunction and latch-up; pull up or pull down the terminals through the resistors of 2 k Ω or more.

3. Power supply pins (V_{CC}/V_{SS})

- If there are multiple V_{CC} and V_{SS} pins, from the point of view of device design, pins to be of the same potential are connected inside of the device to prevent malfunction such as latch-up.

To reduce unnecessary radiation, prevent malfunctioning of the strobe signal due to the rise of ground level, and observe the standard for total output current, be sure to connect the V_{CC} and V_{SS} pins to the power supply and ground externally. Connect V_{CC} and V_{SS} pins to the device from the current supply source at a possibly low impedance.

- As a measure against power supply noise, it is recommended to connect a capacitor of about 0.1 μ F as a bypass capacitor between V_{CC} and V_{SS} pins in the vicinity of V_{CC} and V_{SS} pins of the device.

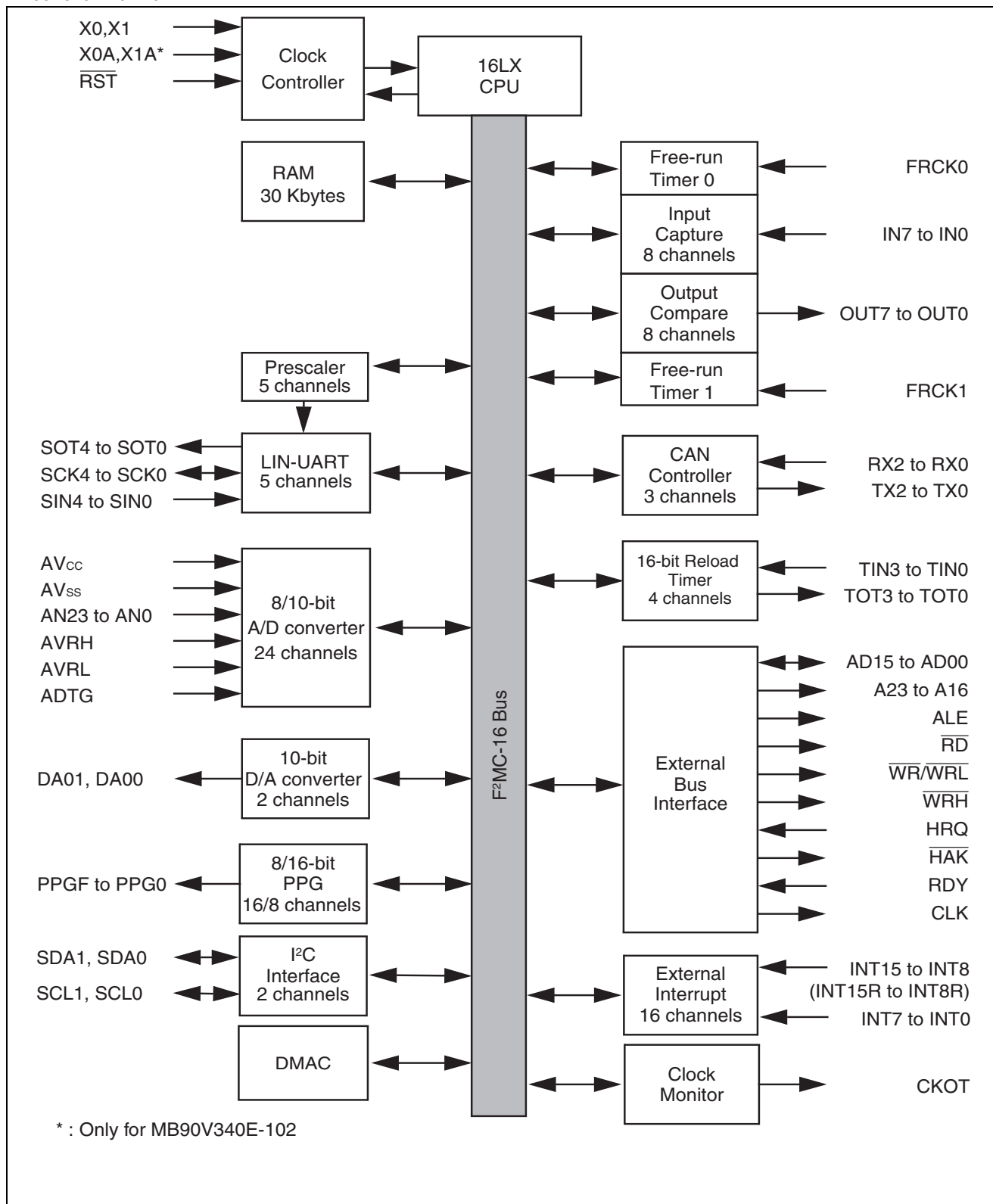


4. Mode Pins (MD0 to MD2)

Connect the mode pins directly to V_{CC} or V_{SS} pins. To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pins to V_{CC} or V_{SS} pins and to provide a low-impedance connection.

6. Block Diagrams

■ MB90V340E-101/102



Address	Register	Abbreviation	Access	Resource name	Initial value
000040 _H	PPG 8 Operation Mode Control Register	PPGC8	W,R/W	16-bit PPG 8/9	0X000XX1 _B
000041 _H	PPG 9 Operation Mode Control Register	PPGC9	W,R/W		0X000001 _B
000042 _H	PPG 8/PPG 9 Count Clock Control Register	PPG89	R/W		000000X0 _B
000043 _H	Reserved				
000044 _H	PPG A Operation Mode Control Register	PPGCA	W,R/W	16-bit PPG A/B	0X000XX1 _B
000045 _H	PPG B Operation Mode Control Register	PPGCB	W,R/W		0X000001 _B
000046 _H	PPG A/PPG B Count Clock Select Register	PPGAB	R/W		000000X0 _B
000047 _H	Reserved				
000048 _H	PPG C Operation Mode Control Register	PPGCC	W,R/W	16-bit PPG C/D	0X000XX1 _B
000049 _H	PPG D Operation Mode Control Register	PPGCD	W,R/W		0X000001 _B
00004A _H	PPG C/PPG D Count Clock Select Register	PPGCD	R/W		000000X0 _B
00004B _H	Reserved				
00004C _H	PPG E Operation Mode Control Register	PPGCE	W,R/W	16-bit PPG E/F	0X000XX1 _B
00004D _H	PPG F Operation Mode Control Register	PPGCF	W,R/W		0X000001 _B
00004E _H	PPG E/PPG F Count Clock Select Register	PPGEF	R/W		000000X0 _B
00004F _H	Reserved				
000050 _H	Input Capture Control Status 0/1	ICS01	R/W	Input Capture 0/1	00000000 _B
000051 _H	Input Capture Edge 0/1	ICE01	R/W, R		XXX0X0XX _B
000052 _H	Input Capture Control Status 2/3	ICS23	R/W	Input Capture 2/3	00000000 _B
000053 _H	Input Capture Edge 2/3	ICE23	R		XXXXXXXX _B
000054 _H	Input Capture Control Status 4/5	ICS45	R/W	Input Capture 4/5	00000000 _B
000055 _H	Input Capture Edge 4/5	ICE45	R		XXXXXXXX _B
000056 _H	Input Capture Control Status 6/7	ICS67	R/W	Input Capture 6/7	00000000 _B
000057 _H	Input Capture Edge 6/7	ICE67	R/W, R		XXX000XX _B
000058 _H	Output Compare Control Status 0	OCS0	R/W	Output Compare 0/1	0000XX00 _B
000059 _H	Output Compare Control Status 1	OCS1	R/W		0XX00000 _B
00005A _H	Output Compare Control Status 2	OCS2	R/W	Output Compare 2/3	0000XX00 _B
00005B _H	Output Compare Control Status 3	OCS3	R/W		0XX00000 _B
00005C _H	Output Compare Control Status 4	OCS4	R/W	Output Compare 4/5	0000XX00 _B
00005D _H	Output Compare Control Status 5	OCS5	R/W		0XX00000 _B
00005E _H	Output Compare Control Status 6	OCS6	R/W	Output Compare 6/7	0000XX00 _B
00005F _H	Output Compare Control Status 7	OCS7	R/W		0XX00000 _B

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
000060 _H	Timer Control Status 0	TMCSR0	R/W	16-bit Reload Timer 0	00000000 _B
000061 _H	Timer Control Status 0	TMCSR0	R/W		XXXX0000 _B
000062 _H	Timer Control Status 1	TMCSR1	R/W	16-bit Reload Timer 1	00000000 _B
000063 _H	Timer Control Status 1	TMCSR1	R/W		XXXX0000 _B
000064 _H	Timer Control Status 2	TMCSR2	R/W	16-bit Reload Timer 2	00000000 _B
000065 _H	Timer Control Status 2	TMCSR2	R/W		XXXX0000 _B
000066 _H	Timer Control Status 3	TMCSR3	R/W	16-bit Reload Timer 3	00000000 _B
000067 _H	Timer Control Status 3	TMCSR3	R/W		XXXX0000 _B
000068 _H	A/D Control Status 0	ADCS0	R/W	A/D Converter	000XXXX0 _B
000069 _H	A/D Control Status 1	ADCS1	R/W		0000000X _B
00006A _H	A/D Data 0	ADCR0	R		00000000 _B
00006B _H	A/D Data 1	ADCR1	R		XXXXXX00 _B
00006C _H	ADC Setting 0	ADSR0	R/W		00000000 _B
00006D _H	ADC Setting 1	ADSR1	R/W		00000000 _B
00006E _H	Reserved				
00006F _H	ROM Mirror Function Select	ROMM	W	ROM Mirror	XXXXXXXX1 _B
000070 _H to 00008F _H	Reserved for CAN Controller 0/1. Refer to “CAN Controllers”				
000090 _H to 00009A _H	Reserved				
00009B _H	DMA Descriptor Channel Specified Register	DCSR	R/W	DMA	00000000 _B
00009C _H	DMA Status L Register	DSRL	R/W		00000000 _B
00009D _H	DMA Status H Register	DSRH	R/W		00000000 _B
00009E _H	Address Detect Control Register 0	PACSR0	R/W	Address Match Detection 0	00000000 _B
00009F _H	Delayed Interrupt Trigger/Release Register	DIRR	R/W	Delayed Interrupt	XXXXXXXX0 _B
0000A0 _H	Low-power Mode Control Register	LPMCR	W,R/W	Low Power Control Circuit	00011000 _B
0000A1 _H	Clock Selection Register	CKSCR	R,R/W	Low Power Control Circuit	11111100 _B
0000A2 _H , 0000A3 _H	Reserved				
0000A4 _H	DMA Stop Status Register	DSSR	R/W	DMA	00000000 _B

(Continued)

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Address	Register	Abbreviation	Access	Resource name	Initial value
0079E0 _H	Detect Address Setting 0	PADR0	R/W	Address Match Detection 0	XXXXXXXX _B
0079E1 _H	Detect Address Setting 0	PADR0	R/W		XXXXXXXX _B
0079E2 _H	Detect Address Setting 0	PADR0	R/W		XXXXXXXX _B
0079E3 _H	Detect Address Setting 1	PADR1	R/W		XXXXXXXX _B
0079E4 _H	Detect Address Setting 1	PADR1	R/W		XXXXXXXX _B
0079E5 _H	Detect Address Setting 1	PADR1	R/W		XXXXXXXX _B
0079E6 _H	Detect Address Setting 2	PADR2	R/W		XXXXXXXX _B
0079E7 _H	Detect Address Setting 2	PADR2	R/W		XXXXXXXX _B
0079E8 _H	Detect Address Setting 2	PADR2	R/W		XXXXXXXX _B
0079E9 _H to 0079EF _H	Reserved				
0079F0 _H	Detect Address Setting 3	PADR3	R/W	Address Match Detection 1	XXXXXXXX _B
0079F1 _H	Detect Address Setting 3	PADR3	R/W		XXXXXXXX _B
0079F2 _H	Detect Address Setting 3	PADR3	R/W		XXXXXXXX _B
0079F3 _H	Detect Address Setting 4	PADR4	R/W		XXXXXXXX _B
0079F4 _H	Detect Address Setting 4	PADR4	R/W		XXXXXXXX _B
0079F5 _H	Detect Address Setting 4	PADR4	R/W		XXXXXXXX _B
0079F6 _H	Detect Address Setting 5	PADR5	R/W		XXXXXXXX _B
0079F7 _H	Detect Address Setting 5	PADR5	R/W		XXXXXXXX _B
0079F8 _H	Detect Address Setting 5	PADR5	R/W		XXXXXXXX _B
0079F9 _H to 0079FF _H	Reserved				
007A00 _H to 007AFF _H	Reserved for CAN Controller 0. Refer to “CAN Controllers				
007B00 _H to 007BFF _H	Reserved for CAN Controller 0. Refer to “CAN Controllers”				
007C00 _H to 007CFF _H	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
007D00 _H to 007DFF _H	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
007E00 _H to 007FFF _H	Reserved				

Note:

- Initial value of “X” represents unknown value.
- Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results in reading “X”.

List of Message Buffers (DLC Registers and Data Registers) (1)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007A60 _H	007C60 _H	DLC Register 0	DLCR0	R/W	XXXXXXXX _B
007A61 _H	007C61 _H				
007A62 _H	007C62 _H				
007A63 _H	007C63 _H	DLC Register 1	DLCR1	R/W	XXXXXXXX _B
007A64 _H	007C64 _H				
007A65 _H	007C65 _H	DLC Register 2	DLCR2	R/W	XXXXXXXX _B
007A66 _H	007C66 _H				
007A67 _H	007C67 _H	DLC Register 3	DLCR3	R/W	XXXXXXXX _B
007A68 _H	007C68 _H				
007A69 _H	007C69 _H	DLC Register 4	DLCR4	R/W	XXXXXXXX _B
007A6A _H	007C6A _H				
007A6B _H	007C6B _H	DLC Register 5	DLCR5	R/W	XXXXXXXX _B
007A6C _H	007C6C _H				
007A6D _H	007C6D _H	DLC Register 6	DLCR6	R/W	XXXXXXXX _B
007A6E _H	007C6E _H				
007A6F _H	007C6F _H	DLC Register 7	DLCR7	R/W	XXXXXXXX _B
007A70 _H	007C70 _H				
007A71 _H	007C71 _H	DLC Register 8	DLCR8	R/W	XXXXXXXX _B
007A72 _H	007C72 _H				
007A73 _H	007C73 _H	DLC Register 9	DLCR9	R/W	XXXXXXXX _B
007A74 _H	007C74 _H				
007A75 _H	007C75 _H	DLC Register 10	DLCR10	R/W	XXXXXXXX _B
007A76 _H	007C76 _H				
007A77 _H	007C77 _H	DLC Register 11	DLCR11	R/W	XXXXXXXX _B
007A78 _H	007C78 _H				
007A79 _H	007C79 _H	DLC Register 12	DLCR12	R/W	XXXXXXXX _B
007A7A _H	007C7A _H				
007A7B _H	007C7B _H	DLC Register 13	DLCR13	R/W	XXXXXXXX _B
007A7C _H	007C7C _H				
007A7D _H	007C7D _H	DLC Register 14	DLCR14	R/W	XXXXXXXX _B
007A7E _H	007C7E _H				
007A7F _H	007C7F _H	DLC Register 15	DLCR15	R/W	XXXXXXXX _B

List of Message Buffers (DLC Registers and Data Registers) (3)

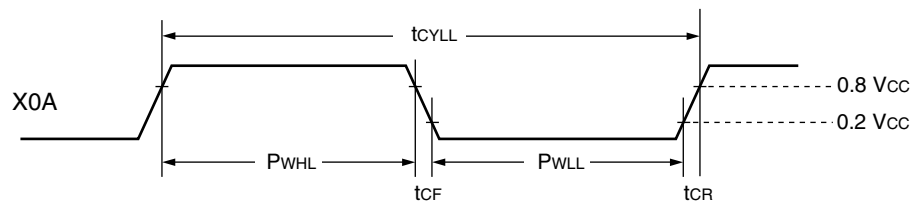
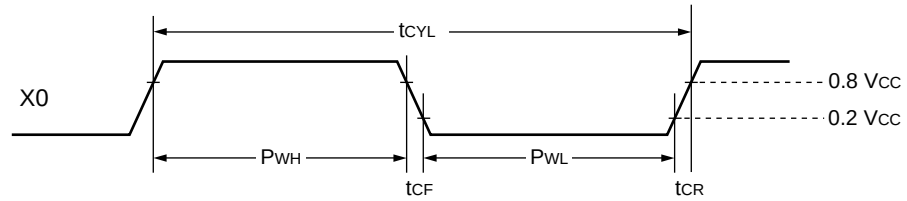
Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007AF0 _H to 007AF7 _H	007CF0 _H to 007CF7 _H	Data Register 14 (8 bytes)	DTR14	R/W	XXXXXXXX _B to XXXXXXXX _B
007AF8 _H to 007AFF _H	007CF8 _H to 007CFF _H	Data Register 15 (8 bytes)	DTR15	R/W	XXXXXXXX _B to XXXXXXXX _B

10. Interrupt Factors, Interrupt Vectors, Interrupt Control Register

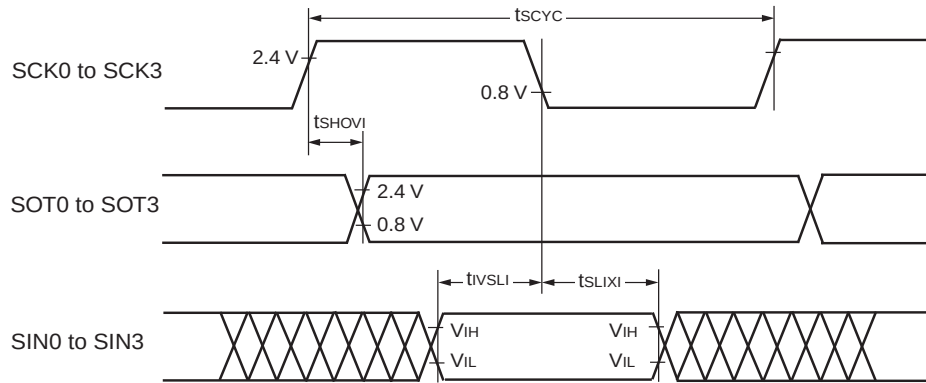
Interrupt cause	EI ² OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
Reset	N	—	#08	FFFFDC _H	—	—
INT9 instruction	N	—	#09	FFFFD8 _H	—	—
Exception	N	—	#10	FFFFD4 _H	—	—
CAN 0 RX	N	—	#11	FFFFD0 _H	ICR00	0000B0 _H
CAN 0 TX/NS	N	—	#12	FFFFCC _H		
CAN 1 RX / Input Capture 6	Y1	—	#13	FFFFC8 _H	ICR01	0000B1 _H
CAN 1 TX/NS / Input Capture 7	Y1	—	#14	FFFFC4 _H		
CAN 2 RX / I ² C0	N	—	#15	FFFFC0 _H	ICR02	0000B2 _H
CAN 2 TX/NS	N	—	#16	FFFFBC _H		
16-bit Reload Timer 0	Y1	0	#17	FFFFB8 _H	ICR03	0000B3 _H
16-bit Reload Timer 1	Y1	1	#18	FFFFB4 _H		
16-bit Reload Timer 2	Y1	2	#19	FFFFB0 _H	ICR04	0000B4 _H
16-bit Reload Timer 3	Y1	—	#20	FFFFAC _H		
PPG 0/1/4/5	N	—	#21	FFFFA8 _H	ICR05	0000B5 _H
PPG 2/3/6/7	N	—	#22	FFFFA4 _H		
PPG 8/9/C/D	N	—	#23	FFFFA0 _H	ICR06	0000B6 _H
PPG A/B/E/F	N	—	#24	FFFF9C _H		
Time Base Timer	N	—	#25	FFFF98 _H	ICR07	0000B7 _H
External Interrupt 0 to 3, 8 to 11	Y1	3	#26	FFFF94 _H		
Watch Timer	N	—	#27	FFFF90 _H	ICR08	0000B8 _H
External Interrupt 4 to 7, 12 to 15	Y1	4	#28	FFFF8C _H		
A/D Converter	Y1	5	#29	FFFF88 _H	ICR09	0000B9 _H
Free-run Timer 0 / Free-run Timer 1	N	—	#30	FFFF84 _H		
Input Capture 4/5 / I ² C1	Y1	6	#31	FFFF80 _H	ICR10	0000BA _H
Output Compare 0/1/4/5	Y1	7	#32	FFFF7C _H		
Input Capture 0 to 3	Y1	8	#33	FFFF78 _H	ICR11	0000BB _H
Output Compare 2/3/6/7	Y1	9	#34	FFFF74 _H		
UART 0 RX	Y2	10	#35	FFFF70 _H	ICR12	0000BC _H
UART 0 TX	Y1	11	#36	FFFF6C _H		
UART 1 RX / UART 3 RX	Y2	12	#37	FFFF68 _H	ICR13	0000BD _H
UART 1 TX / UART 3 TX	Y1	13	#38	FFFF64 _H		

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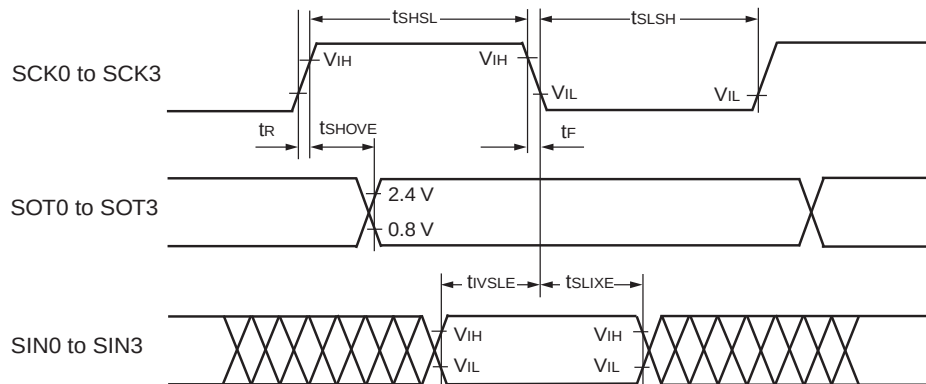
Clock Timing



• Internal Shift Clock Mode



• External Shift Clock Mode



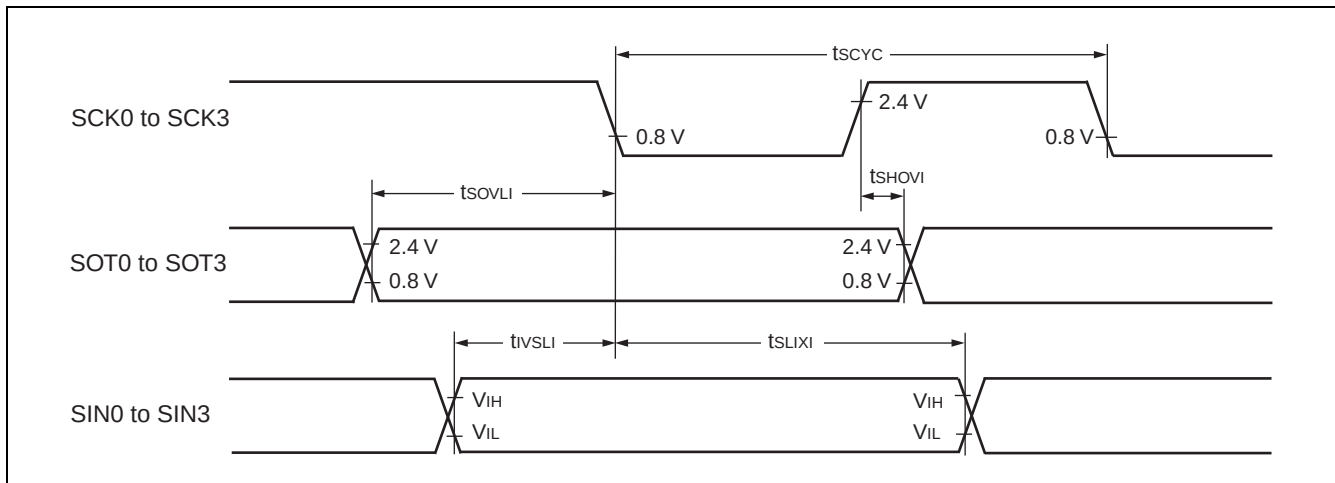
■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 1

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\uparrow \rightarrow$ SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\downarrow$	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\downarrow \rightarrow$ Valid SIN hold time	t_{SLIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT $\rightarrow$ SCK $\downarrow$ delay time	t_{SOVLI}	SCK0 to SCK3, SOT0 to SOT3		$3 t_{CP} - 70$	—	ns

Note:

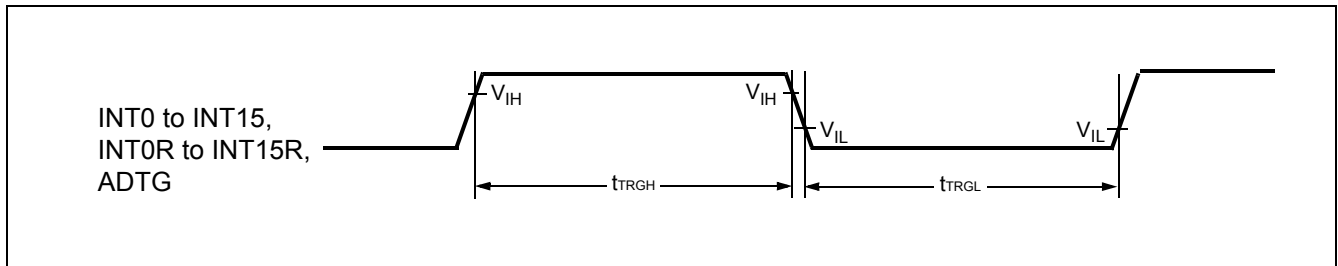
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.



11.4.10 Trigger Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0.0\text{ V}$)

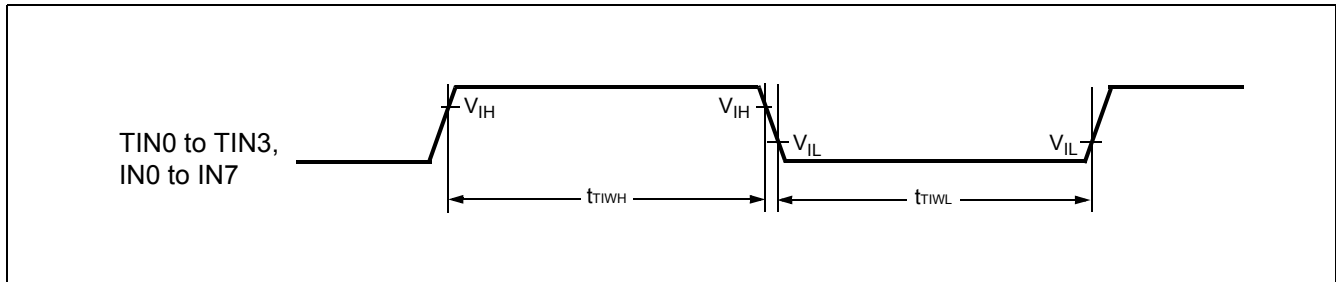
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TRGH} t_{TRGL}	INT0 to INT15, INT0R to INT15R, ADTG	—	$5 t_{CP}$	—	ns



11.4.11 Timer Related Resource Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

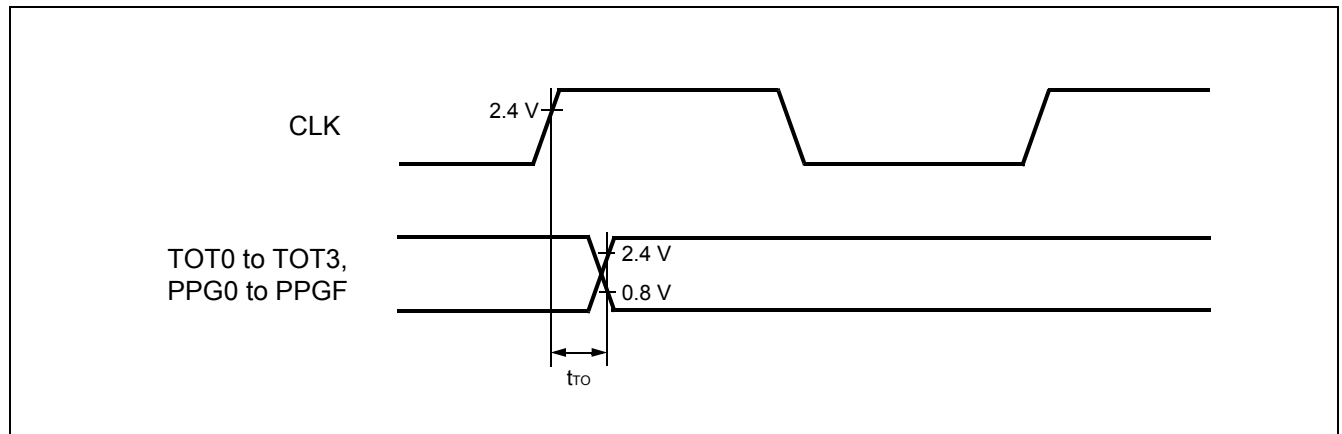
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TIWH}	TIN0 to TIN3, IN0 to IN7	—	$4 t_{CP}$	—	ns
	t_{TIWL}					



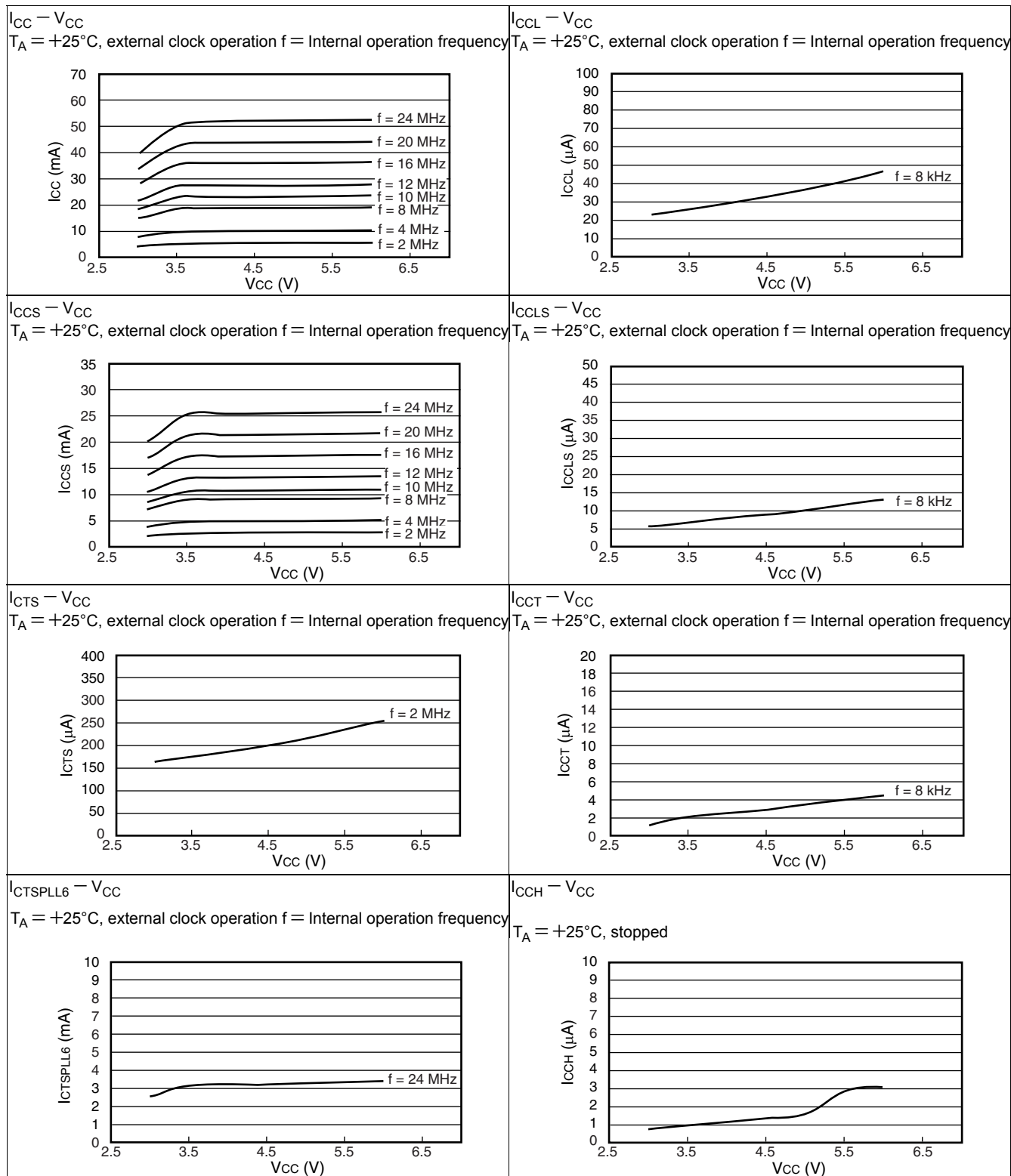
11.4.12 Timer Related Resource Output Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0.0\text{ V}$)

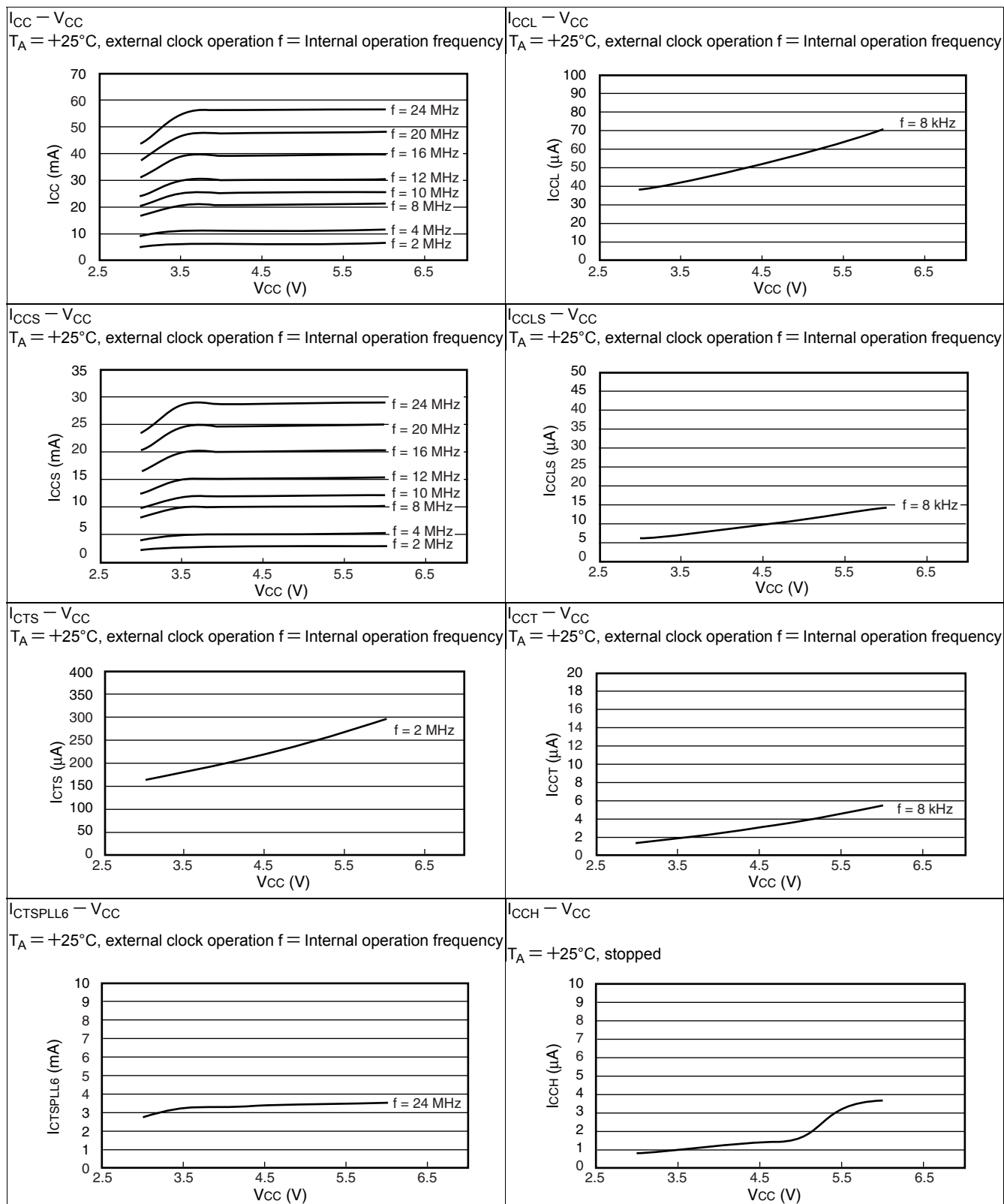
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
CLK $\uparrow \rightarrow T_{OUT}$ change time	t_{TO}	TOT0 to TOT3, PPG0 to PPGF	—	30	—	ns



■ MB90F347E, MB90F347ES, MB90F347CE, MB90F347CES

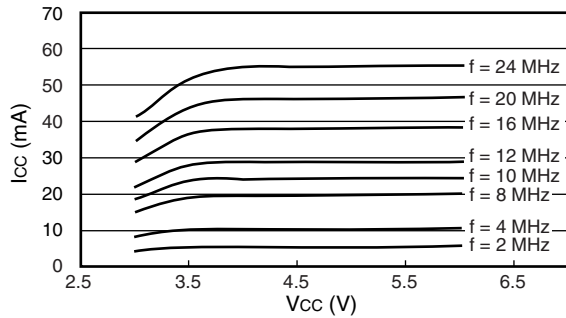


■ MB90F342E, MB90F342ES, MB90F342CE, MB90F342CES

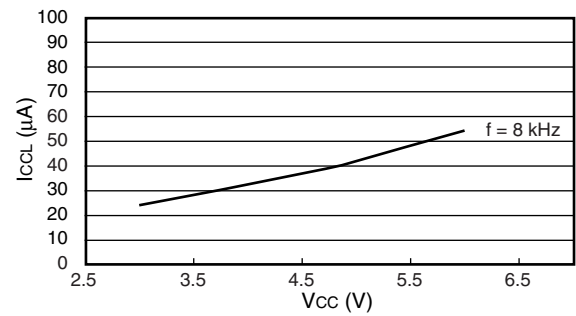


■ MB90346E, MB90346ES, MB90346CE, MB90346CES

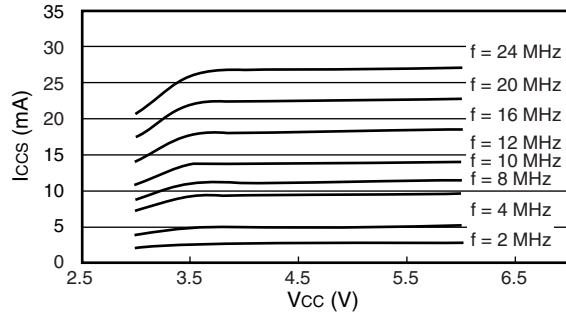
$I_{CC} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation $f =$ Internal operation frequency



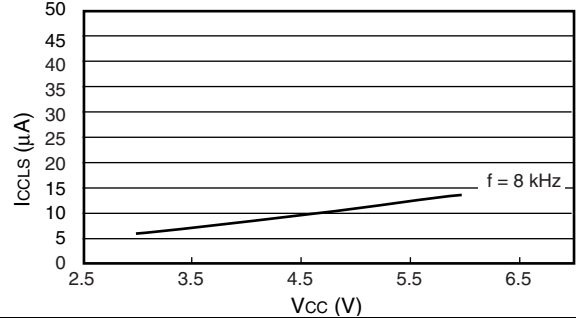
$I_{CCL} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation $f =$ Internal operation frequency



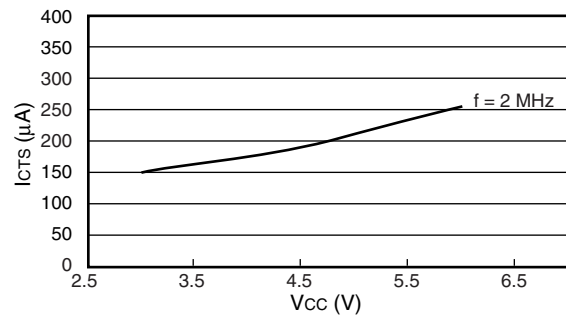
$I_{CCS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation $f =$ Internal operation frequency



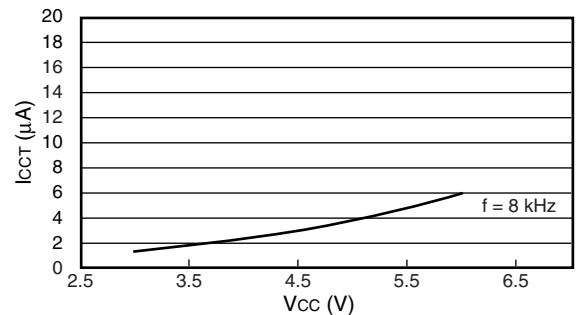
$I_{CCLS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation $f =$ Internal operation frequency



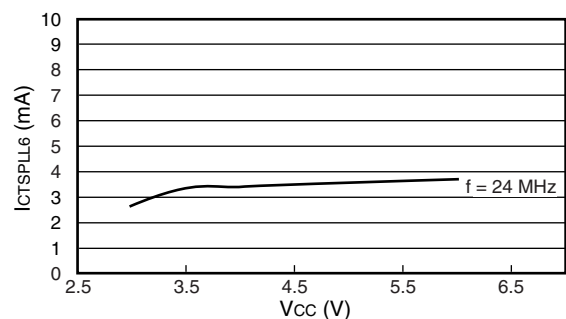
$I_{CTS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation $f =$ Internal operation frequency



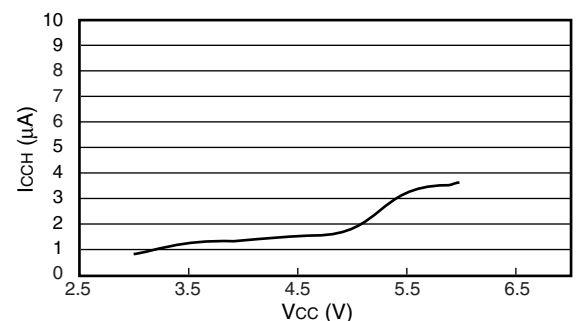
$I_{CCT} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation $f =$ Internal operation frequency



$I_{CTSPLL6} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation $f =$ Internal operation frequency



$I_{CCH} - V_{CC}$
 $T_A = +25^\circ\text{C}$, stopped



■ I/O characteristics

