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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	80
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-BQFP
Supplier Device Package	100-QFP (14x20)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90f347epf-ge1

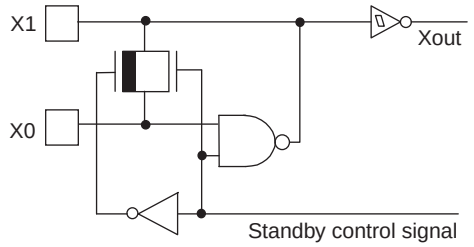
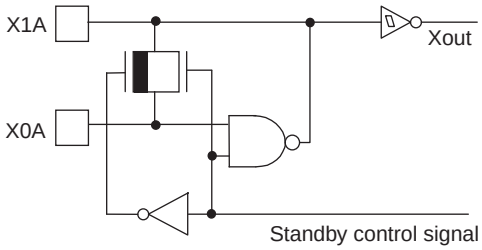
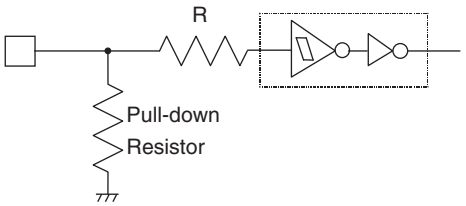
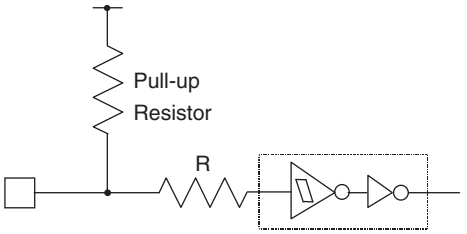
Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
61	59	P84	F	General purpose I/O pin.
		SCK0		Clock I/O pin for UART0
		INT15R		External interrupt request input pin
62	60	P85	M	General purpose I/O pin.
		SIN1		Serial data input pin for UART1
63	61	P86	F	General purpose I/O pin.
		SOT1		Serial data output pin for UART1
64	62	P87	F	General purpose I/O pin.
		SCK1		Clock I/O pin for UART1
65	63	V_{CC}	—	Power (3.5 V to 5.5 V) input pin
66	64	V_{SS}	—	GND pin
67 to 70	65 to 68	P90 to P93	F	General purpose I/O pins
		PPG1, 3, 5, 7		Output pins for PPGs
71 to 74	69 to 72	P94 to P97	F	General purpose I/O pins
		OUT0 to OUT3		Waveform output pins for output compares. This function is enabled when the OCU enables waveform output.
75	73	PA0	F	General purpose I/O pin.
		RX0		RX input pin for CAN0 Interface
		INT8R		External interrupt request input pin
76	74	PA1	F	General purpose I/O pin.
		TX0		TX Output pin for CAN0
77 to 84	75 to 82	P00 to P07	G	General purpose I/O pins. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD00 to AD07		I/O pins for 8 lower bits of the external address/data bus. This function is enabled when the external bus is enabled.
		INT8 to INT15		External interrupt request input pins.
85	83	P10	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD08		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		TIN1		Event input pin for the reload timer

(Continued)

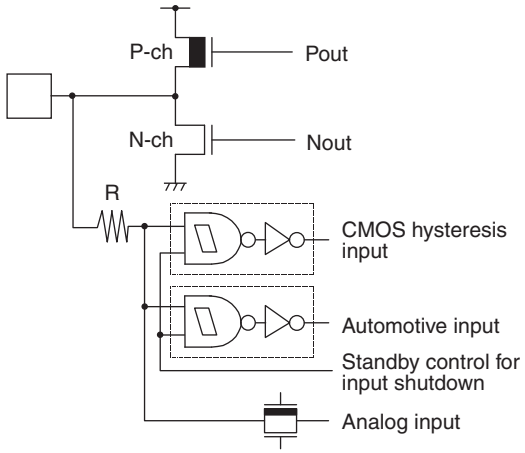
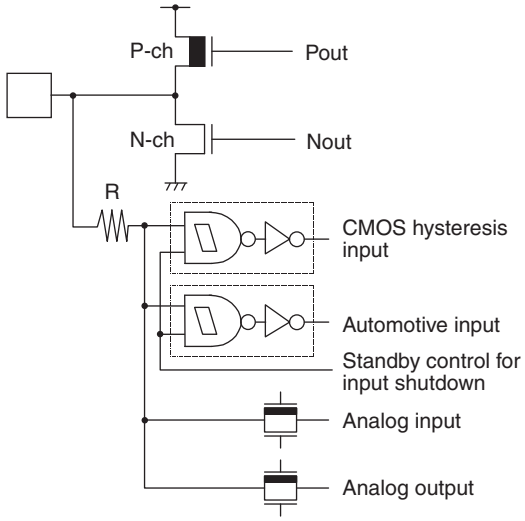
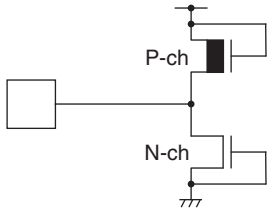
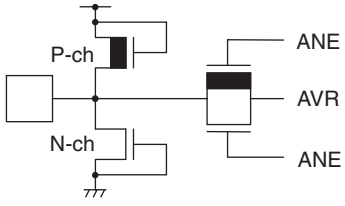
Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
86	84	P11	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD09		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		TOT1		Output pin for the reload timer
87	85	P12	N	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD10		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		SIN3		Serial data input pin for UART3
		INT11R		External interrupt request input pin
88	86	P13	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD11		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		SOT3		Serial data output pin for UART3
89	87	P14	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD12		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		SCK3		Clock I/O pin for UART3
90	88	V_{CC}	—	Power (3.5 V to 5.5 V) input pin
91	89	V_{SS}	—	GND pin
92	90	X1	A	Main clock output pin
93	91	X0		Main clock input pin
94	92	P15	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD13		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
95	93	P16	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD14		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.

(Continued)

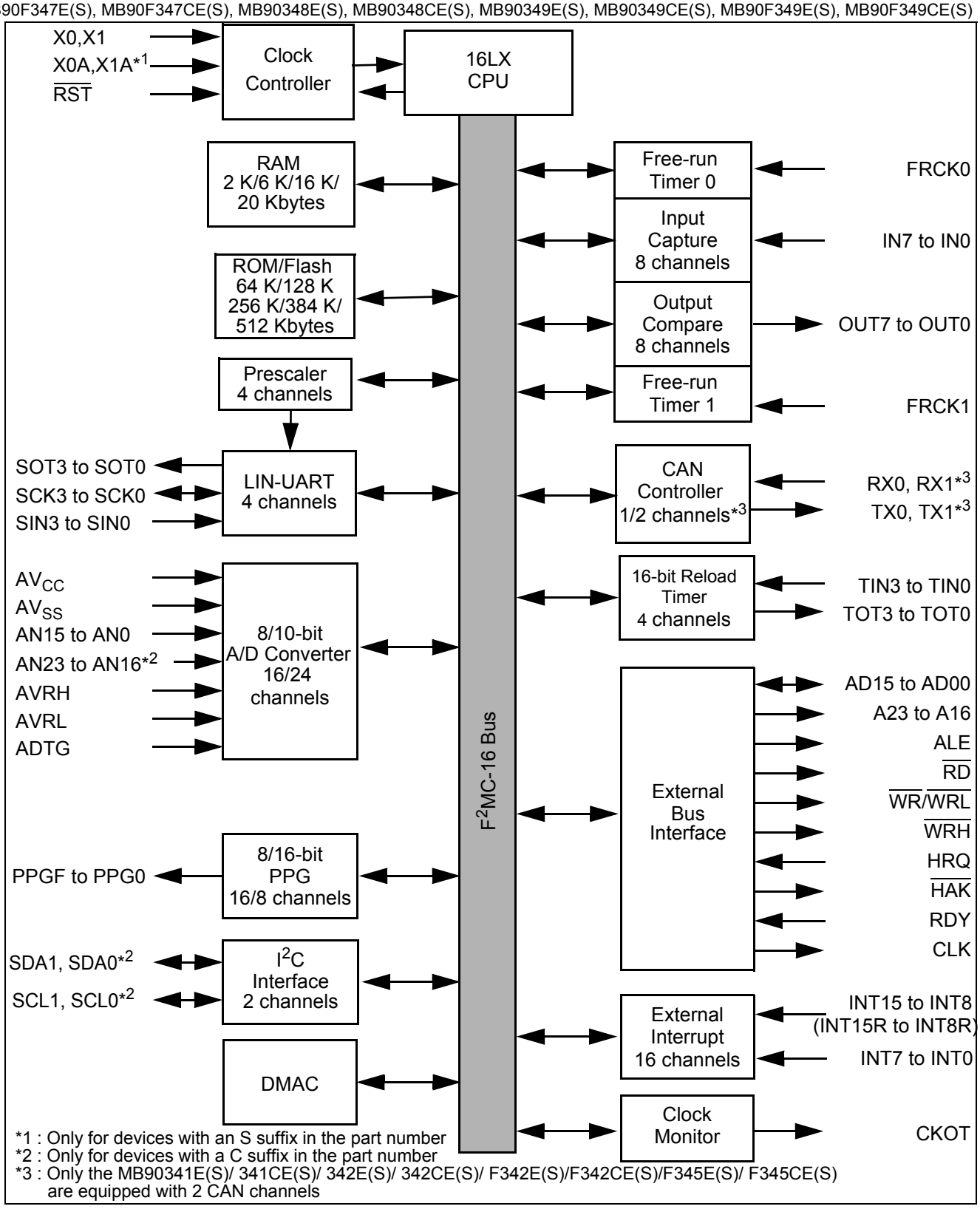
4. I/O Circuit Type

Type	Circuit	Remarks
A		Oscillation circuit High-speed oscillation feedback resistor = approx. 1 MΩ
B		Oscillation circuit Low-speed oscillation feedback resistor = approx. 10 MΩ
C		■ MASK ROM and evaluation products: CMOS hysteresis input pin ■ Flash memory products: CMOS input pin
D		MASK ROM and evaluation products: ■ CMOS hysteresis input pin ■ Pull-down resistor value: approx. 50 kΩ Flash memory products: ■ CMOS input pin ■ No pull-down
E		CMOS hysteresis input pin Pull-up resistor value: approx. 50 kΩ

(Continued)

Type	Circuit	Remarks
I		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = –4 mA) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ A/D converter analog input
J		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = –4 mA) ■ D/A analog output ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ A/D converter analog input
K		Power supply input protection circuit
L		■ A/D converter reference voltage power supply input pin, with the protection circuit ■ Flash memory devices do not have a protection circuit against V_{CC} for pin AVRH

■ MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90346E(S), MB90346CE(S), MB90F346E(S), MB90F346CE(S), MB90347E(S), MB90347CE(S), MB90F347E(S), MB90F347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S), MB90F349E(S), MB90F349CE(S)



Address	Register	Abbreviation	Access	Resource name	Initial value
000060_H	Timer Control Status 0	TMCSR0	R/W	16-bit Reload Timer 0	00000000_B
000061_H	Timer Control Status 0	TMCSR0	R/W		$XXXX0000_B$
000062_H	Timer Control Status 1	TMCSR1	R/W	16-bit Reload Timer 1	00000000_B
000063_H	Timer Control Status 1	TMCSR1	R/W		$XXXX0000_B$
000064_H	Timer Control Status 2	TMCSR2	R/W	16-bit Reload Timer 2	00000000_B
000065_H	Timer Control Status 2	TMCSR2	R/W		$XXXX0000_B$
000066_H	Timer Control Status 3	TMCSR3	R/W	16-bit Reload Timer 3	00000000_B
000067_H	Timer Control Status 3	TMCSR3	R/W		$XXXX0000_B$
000068_H	A/D Control Status 0	ADCS0	R/W	A/D Converter	$000XXXX0_B$
000069_H	A/D Control Status 1	ADCS1	R/W		$0000000X_B$
$00006A_H$	A/D Data 0	ADCR0	R		00000000_B
$00006B_H$	A/D Data 1	ADCR1	R		$XXXXXX00_B$
$00006C_H$	ADC Setting 0	ADSR0	R/W		00000000_B
$00006D_H$	ADC Setting 1	ADSR1	R/W		00000000_B
$00006E_H$	Reserved				
$00006F_H$	ROM Mirror Function Select	ROMM	W	ROM Mirror	$XXXXXXX1_B$
000070_H to $00008F_H$	Reserved for CAN Controller 0/1. Refer to "CAN Controllers"				
000090_H to $00009A_H$	Reserved				
$00009B_H$	DMA Descriptor Channel Specified Register	DCSR	R/W	DMA	00000000_B
$00009C_H$	DMA Status L Register	DSRL	R/W		00000000_B
$00009D_H$	DMA Status H Register	DSRH	R/W		00000000_B
$00009E_H$	Address Detect Control Register 0	PACSR0	R/W	Address Match Detection 0	00000000_B
$00009F_H$	Delayed Interrupt Trigger/Release Register	DIRR	R/W	Delayed Interrupt	$XXXXXXX0_B$
$0000A0_H$	Low-power Mode Control Register	LPMCR	W,R/W	Low Power Control Circuit	00011000_B
$0000A1_H$	Clock Selection Register	CKSCR	R,R/W	Low Power Control Circuit	11111100_B
$0000A2_H$, $0000A3_H$	Reserved				
$0000A4_H$	DMA Stop Status Register	DSSR	R/W	DMA	00000000_B

(Continued)

List of Message Buffers (ID Registers) (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A40_H$	$007C40_H$	ID Register 8	IDR8	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A41_H$	$007C41_H$				
$007A42_H$	$007C42_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A43_H$	$007C43_H$				
$007A44_H$	$007C44_H$	ID Register 9	IDR9	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A45_H$	$007C45_H$				
$007A46_H$	$007C46_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A47_H$	$007C47_H$				
$007A48_H$	$007C48_H$	ID Register 10	IDR10	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A49_H$	$007C49_H$				
$007A4A_H$	$007C4A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4B_H$	$007C4B_H$				
$007A4C_H$	$007C4C_H$	ID Register 11	IDR11	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4D_H$	$007C4D_H$				
$007A4E_H$	$007C4E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4F_H$	$007C4F_H$				
$007A50_H$	$007C50_H$	ID Register 12	IDR12	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A51_H$	$007C51_H$				
$007A52_H$	$007C52_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A53_H$	$007C53_H$				
$007A54_H$	$007C54_H$	ID Register 13	IDR13	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A55_H$	$007C55_H$				
$007A56_H$	$007C56_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A57_H$	$007C57_H$				
$007A58_H$	$007C58_H$	ID Register 14	IDR14	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A59_H$	$007C59_H$				
$007A5A_H$	$007C5A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5B_H$	$007C5B_H$				
$007A5C_H$	$007C5C_H$	ID Register 15	IDR15	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5D_H$	$007C5D_H$				
$007A5E_H$	$007C5E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5F_H$	$007C5F_H$				

List of Message Buffers (DLC Registers and Data Registers) (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A80_H$ to $007A87_H$	$007C80_H$ to $007C87_H$	Data Register 0 (8 bytes)	DTR0	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A88_H$ to $007A8F_H$	$007C88_H$ to $007C8F_H$	Data Register 1 (8 bytes)	DTR1	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A90_H$ to $007A97_H$	$007C90_H$ to $007C97_H$	Data Register 2 (8 bytes)	DTR2	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A98_H$ to $007A9F_H$	$007C98_H$ to $007C9F_H$	Data Register 3 (8 bytes)	DTR3	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AA0_H$ to $007AA7_H$	$007CA0_H$ to $007CA7_H$	Data Register 4 (8 bytes)	DTR4	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AA8_H$ to $007AAF_H$	$007CA8_H$ to $007CAF_H$	Data Register 5 (8 bytes)	DTR5	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AB0_H$ to $007AB7_H$	$007CB0_H$ to $007CB7_H$	Data Register 6 (8 bytes)	DTR6	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AB8_H$ to $007ABF_H$	$007CB8_H$ to $007CBF_H$	Data Register 7 (8 bytes)	DTR7	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AC0_H$ to $007AC7_H$	$007CC0_H$ to $007CC7_H$	Data Register 8 (8 bytes)	DTR8	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AC8_H$ to $007ACF_H$	$007CC8_H$ to $007CCF_H$	Data Register 9 (8 bytes)	DTR9	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AD0_H$ to $007AD7_H$	$007CD0_H$ to $007CD7_H$	Data Register 10 (8 bytes)	DTR10	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AD8_H$ to $007ADF_H$	$007CD8_H$ to $007CDF_H$	Data Register 11 (8 bytes)	DTR11	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AE0_H$ to $007AE7_H$	$007CE0_H$ to $007CE7_H$	Data Register 12 (8 bytes)	DTR12	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AE8_H$ to $007AEF_H$	$007CE8_H$ to $007CEF_H$	Data Register 13 (8 bytes)	DTR13	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$

10. Interrupt Factors, Interrupt Vectors, Interrupt Control Register

Interrupt cause	EI^{2}OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
Reset	N	—	#08	FFFFDC$_H$	—	—
INT9 instruction	N	—	#09	FFFFD8$_H$	—	—
Exception	N	—	#10	FFFFD4$_H$	—	—
CAN 0 RX	N	—	#11	FFFFD0$_H$	ICR00	0000B0$_H$
CAN 0 TX/NS	N	—	#12	FFFFCC$_H$		
CAN 1 RX / Input Capture 6	Y1	—	#13	FFFFC8$_H$	ICR01	0000B1$_H$
CAN 1 TX/NS / Input Capture 7	Y1	—	#14	FFFFC4$_H$		
CAN 2 RX / I^{2}C0	N	—	#15	FFFFC0$_H$	ICR02	0000B2$_H$
CAN 2 TX/NS	N	—	#16	FFFFBC$_H$		
16-bit Reload Timer 0	Y1	0	#17	FFFFB8$_H$	ICR03	0000B3$_H$
16-bit Reload Timer 1	Y1	1	#18	FFFFB4$_H$		
16-bit Reload Timer 2	Y1	2	#19	FFFFB0$_H$	ICR04	0000B4$_H$
16-bit Reload Timer 3	Y1	—	#20	FFFFAC$_H$		
PPG 0/1/4/5	N	—	#21	FFFFA8$_H$	ICR05	0000B5$_H$
PPG 2/3/6/7	N	—	#22	FFFFA4$_H$		
PPG 8/9/C/D	N	—	#23	FFFFA0$_H$	ICR06	0000B6$_H$
PPG A/B/E/F	N	—	#24	FFFF9C$_H$		
Time Base Timer	N	—	#25	FFFF98$_H$	ICR07	0000B7$_H$
External Interrupt 0 to 3, 8 to 11	Y1	3	#26	FFFF94$_H$		
Watch Timer	N	—	#27	FFFF90$_H$	ICR08	0000B8$_H$
External Interrupt 4 to 7, 12 to 15	Y1	4	#28	FFFF8C$_H$		
A/D Converter	Y1	5	#29	FFFF88$_H$	ICR09	0000B9$_H$
Free-run Timer 0 / Free-run Timer 1	N	—	#30	FFFF84$_H$		
Input Capture 4/5 / I^{2}C1	Y1	6	#31	FFFF80$_H$	ICR10	0000BA$_H$
Output Compare 0/1/4/5	Y1	7	#32	FFFF7C$_H$		
Input Capture 0 to 3	Y1	8	#33	FFFF78$_H$	ICR11	0000BB$_H$
Output Compare 2/3/6/7	Y1	9	#34	FFFF74$_H$		
UART 0 RX	Y2	10	#35	FFFF70$_H$	ICR12	0000BC$_H$
UART 0 TX	Y1	11	#36	FFFF6C$_H$		
UART 1 RX / UART 3 RX	Y2	12	#37	FFFF68$_H$	ICR13	0000BD$_H$
UART 1 TX / UART 3 TX	Y1	13	#38	FFFF64$_H$		

(Continued)

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Interrupt cause	EI^{2}OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
UART 2 RX / UART 4 RX	Y2	14	#39	$FFFF60_H$	ICR14	$0000BE_H$
UART 2 TX / UART 4 TX	Y1	15	#40	$FFFF5C_H$		
Flash Memory	N	——	#41	$FFFF58_H$	ICR15	$0000BF_H$
Delayed Interrupt	N	——	#42	$FFFF54_H$		

Y1 : Usable
Y2 : Usable, with EI^{2}OS stop function
N : Unusable

Note:
- The peripheral resources sharing the ICR register have the same interrupt level.
- When two peripheral resources share the ICR register, only one can use Extended Intelligent I/O Service at a time.
- When either of the two peripheral resources sharing the ICR register specifies Extended Intelligent I/O Service, the other one cannot use interrupts.

11. Electrical Characteristics

11.1 Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	
	AV_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$V_{CC} = AV_{CC}$*2
	AVRH, AVRL	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$AV_{CC} \geq$ AVRH, $AV_{CC} \geq$ AVRL, AVRH $\geq$ AVRL
Input voltage*1	V_I	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*3
Output voltage*1	V_O	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*3
Maximum Clamp Current	I_{CLAMP}	−4.0	+4.0	mA	*5
Total Maximum Clamp Current	$\Sigma\lvert I_{CLAMP}\rvert$	—	40	mA	*5
“L” level maximum output current	I_{OL}	—	15	mA	*4, *6
“L” level average output current	I_{OLAV}	—	4	mA	*4, *7
“L” level maximum overall output current	ΣI_{OL}	—	100	mA	*4
“L” level average overall output current	ΣI_{OLAV}	—	50	mA	*4, *8
“H” level maximum output current	I_{OH}	—	−15	mA	*4, *6
“H” level average output current	I_{OHAV}	—	−4	mA	*4, *7
“H” level maximum overall output current	ΣI_{OH}	—	−100	mA	*4
“H” level average overall output current	ΣI_{OHAV}	—	−50	mA	*4, *8
Power consumption	P_D	—	450	mW	
Operating temperature	T_A	−40	+105	°C	
Storage temperature	T_{STG}	−55	+150	°C	

*1: This parameter is based on $V_{SS} = AV_{SS} = 0$ V

*2: Set AV_{CC} and V_{CC} to the same voltage. Make sure that AV_{CC} does not exceed V_{CC} and that the voltage at the analog inputs does not exceed AV_{CC} when the power is switched on.

*3: V_I and V_O should not exceed $V_{CC} + 0.3$ V. V_I should not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_I rating.

*4: Applicable to pins: P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0, PA1

*5:
- Applicable to pins: P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57 (Evaluation device : P50 to P55) , P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0 to PA1
- Use within recommended operating conditions.
- Use with DC voltage (current)
- The +B signal should always be applied by using a limiting resistance placed between the +B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the +B signal is applied, the input current to the microcontroller pin does not exceed the rated value, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.

(Continued)

11.4 AC Characteristics

11.4.1 Clock Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP}≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Clock frequency	f_C	X0, X1	3	—	16	MHz	When using an oscillation circuit
			4	—	16	MHz	PLL multiplied by 1 When using an oscillation circuit
			4	—	12	MHz	PLL multiplied by 2 When using an oscillation circuit
			4	—	8	MHz	PLL multiplied by 3 When using an oscillation circuit
			4	—	6	MHz	PLL multiplied by 4 When using an oscillation circuit
			—	—	4	MHz	PLL multiplied by 6 When using an oscillation circuit
			3	—	24	MHz	When using an external clock*
	f_{CL}	X0A, X1A	—	32.768	100	kHz	
Clock cycle time	t_{CYL}	X0, X1	62.5	—	333	ns	When using an oscillation circuit
		X0, X1	41.67	—	333	ns	When using an external clock
	t_{CYLL}	X0A, X1A	10	30.5	—	µs	
Input clock pulse width	P_{WH}, P_{WL}	X0	10	—	—	ns	Duty ratio is about 30% to 70%.
	P_{WHL}, P_{WLL}	X0A	5	15.2	—	µs	
Input clock rise and fall time	t_{CR}, t_{CF}	X0	—	—	5	ns	When using external clock
Internal operating clock frequency (machine clock)	f_{CP}	—	1.5	—	24	MHz	When using main clock
	f_{CPL}	—	—	8.192	50	kHz	When using sub clock
Internal operating clock cycle time (machine clock)	t_{CP}	—	41.67	—	666	ns	When using main clock
	t_{CPL}	—	20	122.1	—	µs	When using sub clock

* : When selecting the PLL clock, the range of clock frequency is limited. Use this product within the range as mentioned in “Relation between the external clock frequency and machine clock frequency”.

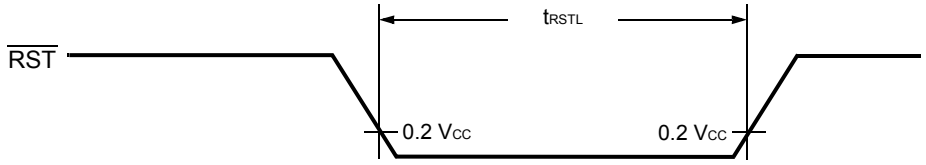
11.4.2 Reset Standby Input

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0.0 V)

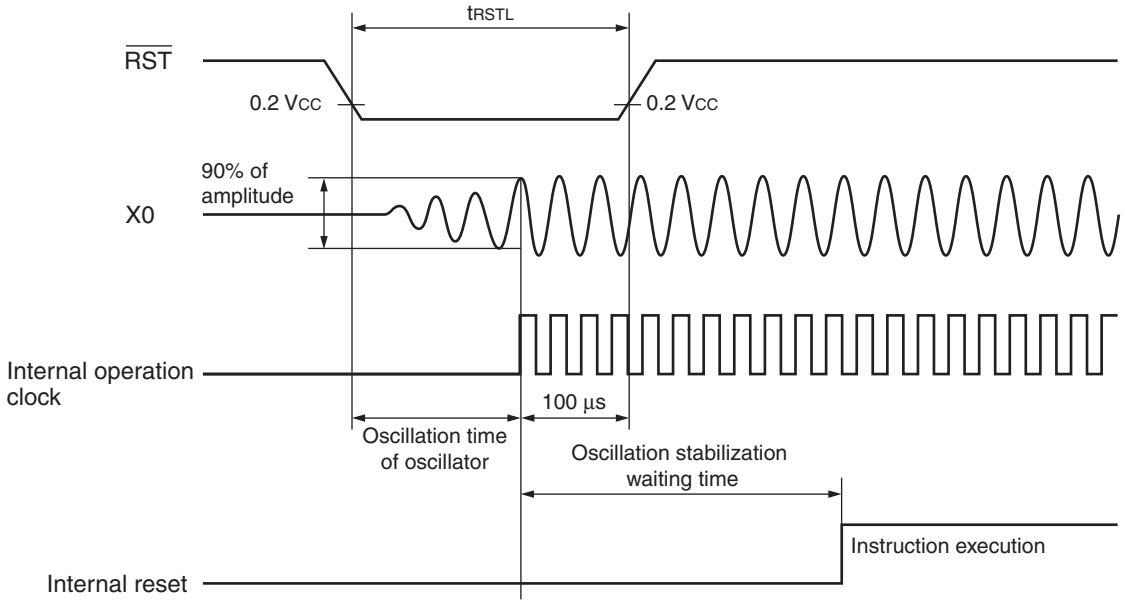
Parameter	Symbol	Pin	Value		Unit	Remarks
			Min	Max		
Reset input time	t_{RSTL}	$\overline{RST}$	500	—	ns	Under normal operation
			Oscillation time of oscillator* + 100 µs	—	µs	In Stop mode, Sub Clock mode, Sub Sleep mode and Watch mode
			100	—	µs	In Time Timer mode

* : The oscillation time of the oscillator is the time it takes for the amplitude of the oscillations to reach 90%. For crystal oscillators, this time is between several ms and several tens of ms, for ceramic oscillators the time is between several hundred µs and several ms, and for an external clock, the time is 0 ms.

- **Under normal operation:**



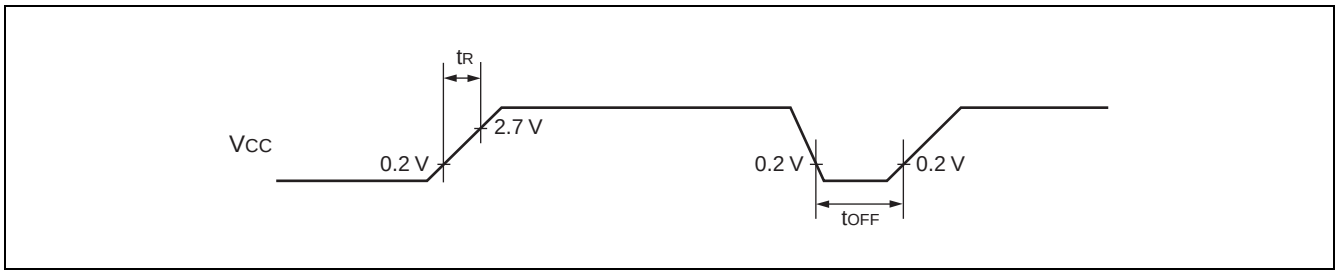
- **In Stop mode, Sub Clock mode, Sub Sleep mode, Watch mode:**



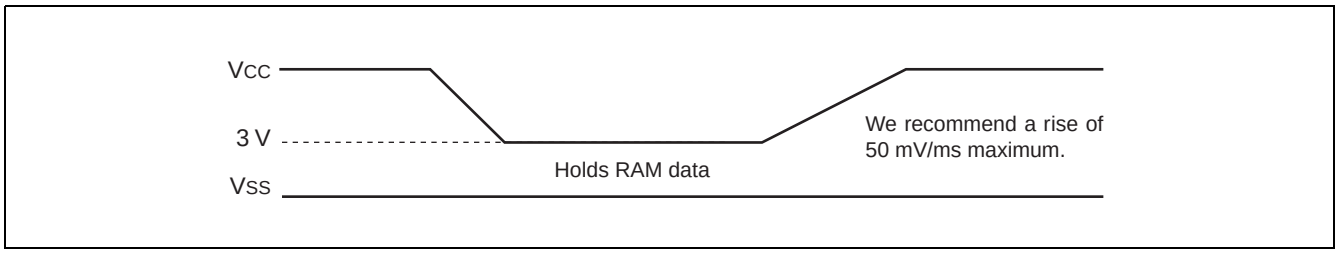
11.4.3 Power On Reset

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0.0 V)

Parameter	Symbol	Pin	Condition	Value		Unit	Remarks
				Min	Max		
Power on rise time	t_R	V_{CC}	—	0.05	30	ms	
Power off time	t_{OFF}	V_{CC}		1	—	ms	Waiting time until power-on



Note: : If you change the power supply voltage too rapidly, a power on reset may occur. We recommend that you startup smoothly by restraining voltages when changing the power supply voltage during operation, as shown in the figure below. Perform while not using the PLL clock. However, if voltage drops are within 1 V/s, you can operate while using the PLL clock.



11.4.4 Clock Output Timing

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V, f_{CP} ≤ 24 MHz)

Parameter	Symbol	Pin	Condition	Value		Unit	Remarks
				Min	Max		
Cycle time	t_{CYC}	CLK	—	62.5	—	ns	f_{CP} = 16 MHz
				41.67	—	ns	f_{CP} = 24 MHz
CLK ↑ → CLK ↓	t_{CHCL}	CLK	—	20	—	ns	f_{CP} = 16 MHz
				13	—	ns	f_{CP} = 24 MHz

11.4.9 LIN-UART0/1/2/3

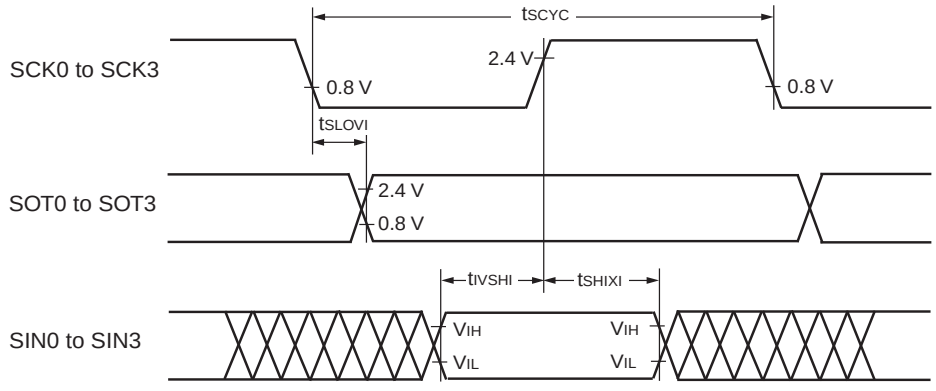
■ **Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0**

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are C_L = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		−50	+50	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock “L” pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are C_L = 80 pF + 1 TTL.	3 t_{CP} - t_R	—	ns
Serial clock “H” pulse width	t_{SLSH}	SCK0 to SCK3		t_{CP} + 10	—	ns
SCK ↓ → SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	2 t_{CP} + 60	ns
Valid SIN → SCK ↑	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXE}	SCK0, SCK1, SIN0 to SIN3		t_{CP} + 30	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

Note:
- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “ (1) Clock Timing”.

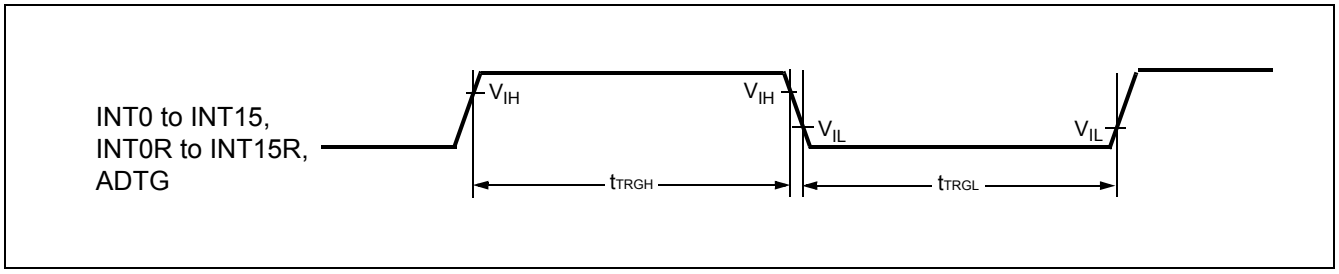
- Internal Shift Clock Mode



11.4.10 Trigger Input Timing

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0.0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TRGH} t_{TRGL}	INT0 to INT15, INT0R to INT15R, ADTG	—	5 t_{CP}	—	ns



11.4.13 I^2C Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

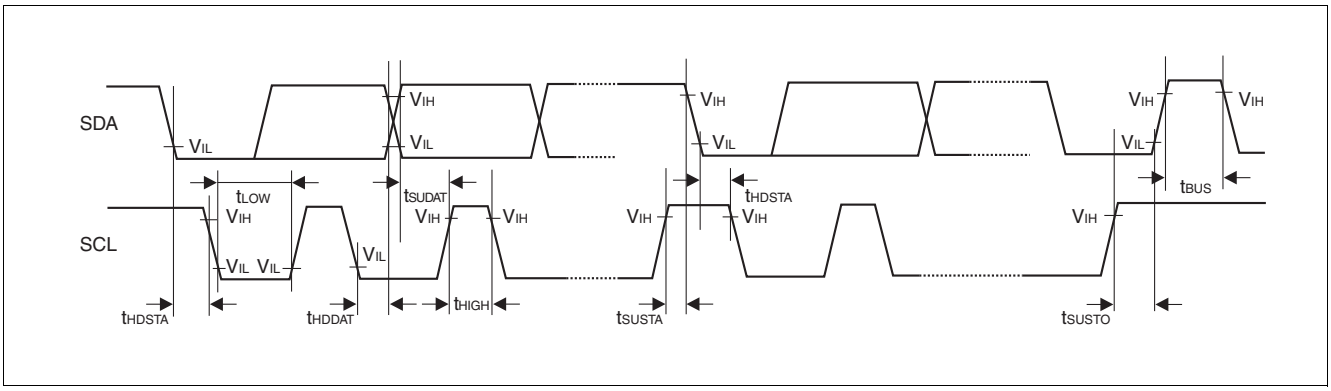
Parameter	Symbol	Condition	Standard-mode		Fast-mode*1		Unit
			Min	Max	Min	Max	
SCL clock frequency	f_{SCL}	R = 1.7 kΩ, C = 50 pF*2	0	100	0	400	kHz
Hold time (repeated) START condition SDA↓ → SCL ↓	t_{HDSTA}		4.0	—	0.6	—	µs
"L" width of the SCL clock	t_{LOW}		4.7	—	1.3	—	µs
"H" width of the SCL clock	t_{HIGH}		4.0	—	0.6	—	µs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t_{SUSTA}		4.7	—	0.6	—	µs
Data hold time SCL ↓ → SDA ↓ ↑	t_{HDDAT}		0	3.45*3	0	0.9*4	µs
Data set-up time SDA ↓ ↑ → SCL ↑	t_{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t_{SUSTO}		4.0	—	0.6	—	µs
Bus free time between a STOP and START condition	t_{BUS}		4.7	—	1.3	—	µs

*1:For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2:R,C: Pull-up resistor and load capacitor of the SCL and SDA lines.

*3:The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4:A Fast-mode I^2C-bus device can be used in a Standard-mode I^2C-bus system, but the requirement $t_{SUDAT} \geq 250$ ns must then be met.



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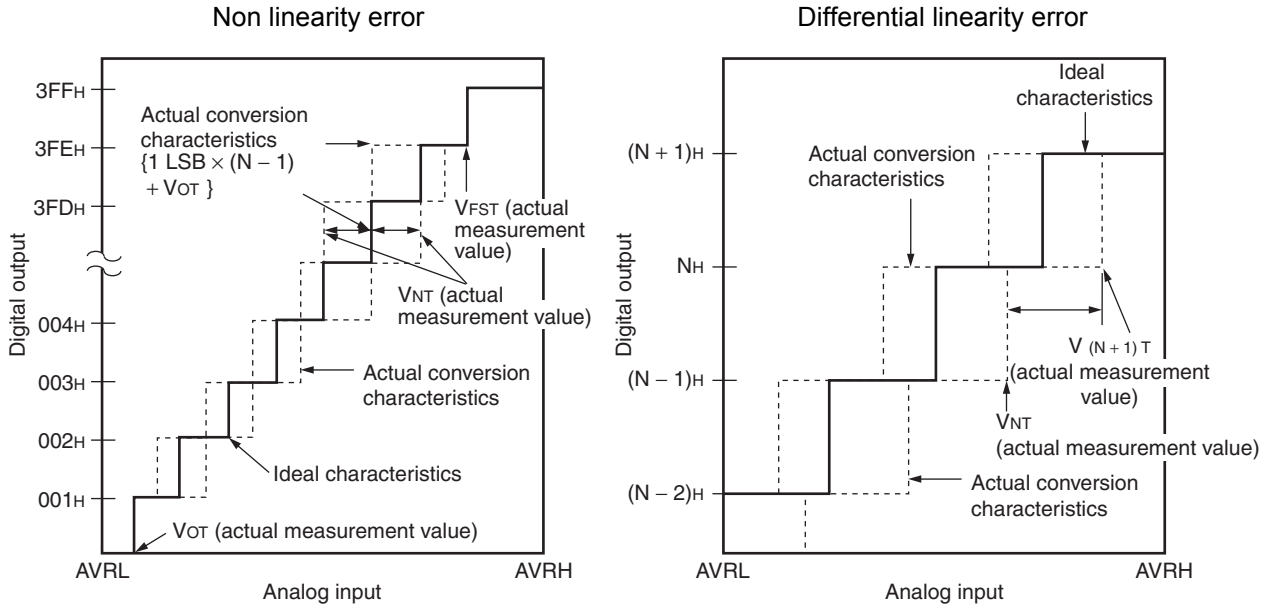


$$\text{Non linearity error of digital output N} = \frac{V_{NT} - \{1\ \text{LSB} \times (N - 1) + V_{OT}\}}{1\ \text{LSB}}\ [\text{LSB}]$$

$$\text{Differential linearity error of digital output N} = \frac{V_{(N+1)T} - V_{NT}}{1\ \text{LSB}} - 1\ \text{LSB}\ [\text{LSB}]$$

$$1\ \text{LSB} = \frac{V_{FST} - V_{OT}}{1022}\ [\text{V}]$$

N : Value of the digital output from the A/D converter
V_{OT} : Voltage at which digital output transits from "000_H" to "001_H."
V_{FST} : Voltage at which digital output transits from "$3FE_H$" to "$3FF_H$."

11.7 Notes on A/D Converter Section

Use the device with external circuits of the following output impedance for analog inputs :

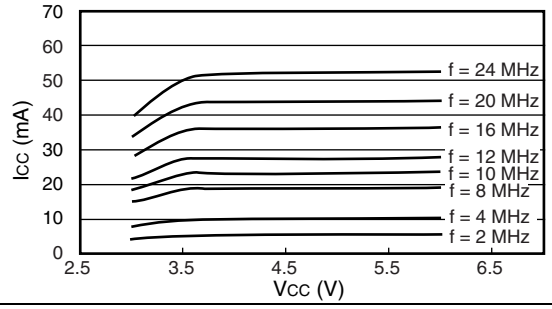
Recommended output impedance of external circuits are : Approx. 1.5 kΩ or lower (4.0 V≤ AV_{CC}≤ 5.5 V, sampling period = 0.5 µs)

If an external capacitor is used, in consideration of the capacitive voltage dividing effect between the external capacitor and the internal on-chip capacitor, it is recommended that the capacitance of the external capacitor be several thousand times greater than the capacitance of the internal capacitor.

■ MB90F347E, MB90F347ES, MB90F347CE, MB90F347CES

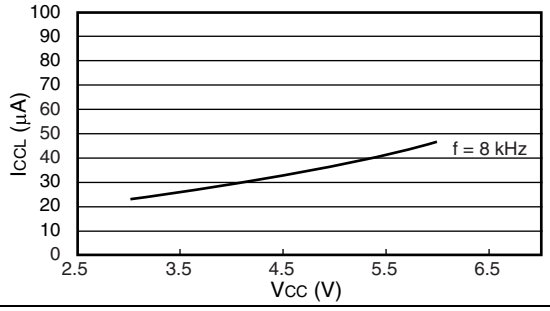
$I_{CC} - V_{CC}$

$T_A = +25°C$, external clock operation f = Internal operation frequency



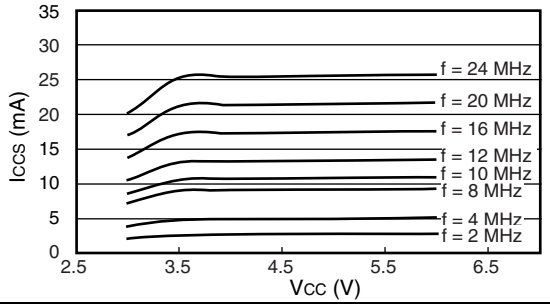
$I_{CCL} - V_{CC}$

$T_A = +25°C$, external clock operation f = Internal operation frequency



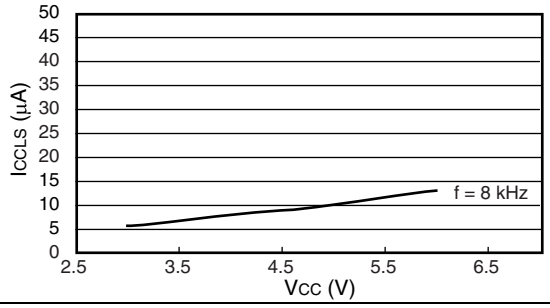
$I_{CCS} - V_{CC}$

$T_A = +25°C$, external clock operation f = Internal operation frequency



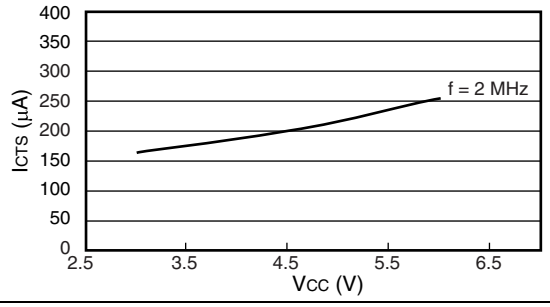
$I_{CCLS} - V_{CC}$

$T_A = +25°C$, external clock operation f = Internal operation frequency



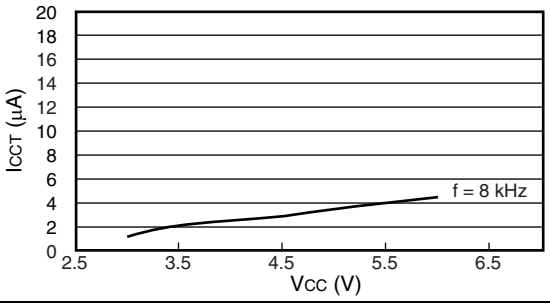
$I_{CTS} - V_{CC}$

$T_A = +25°C$, external clock operation f = Internal operation frequency



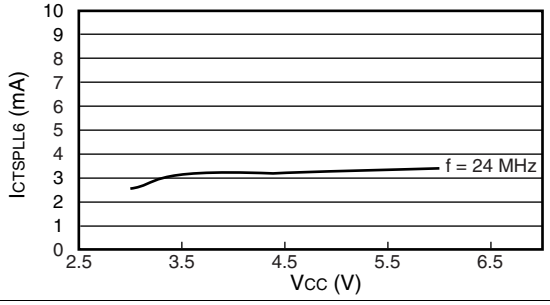
$I_{CCT} - V_{CC}$

$T_A = +25°C$, external clock operation f = Internal operation frequency



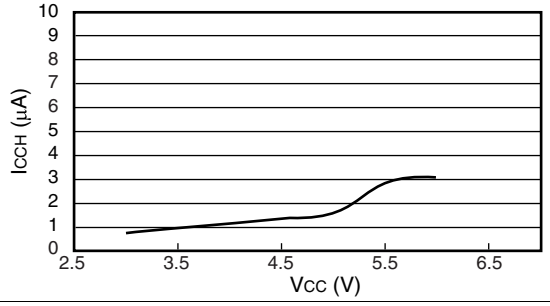
$I_{CTSPLL6} - V_{CC}$

$T_A = +25°C$, external clock operation f = Internal operation frequency



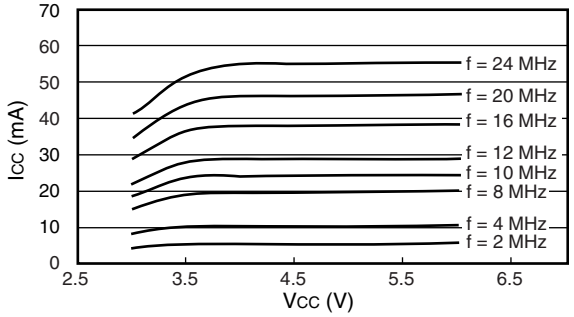
$I_{CCH} - V_{CC}$

$T_A = +25°C$, stopped

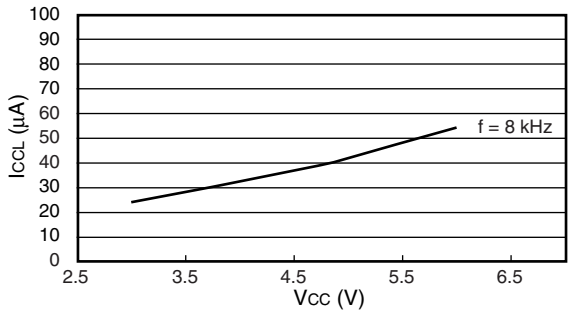


■ MB90347E, MB90347ES, MB90347CE, MB90347CES

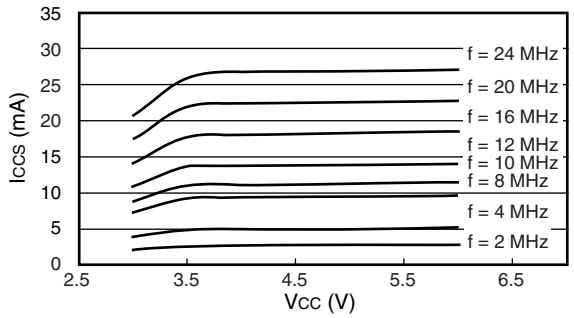
$I_{CC} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



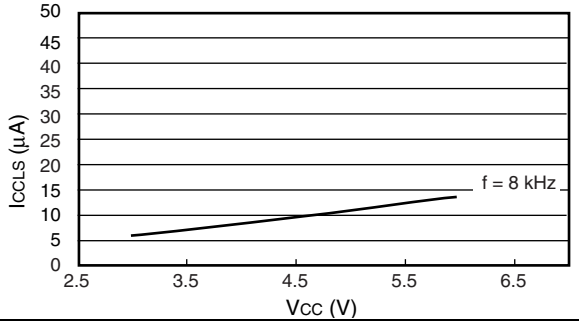
$I_{CCL} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



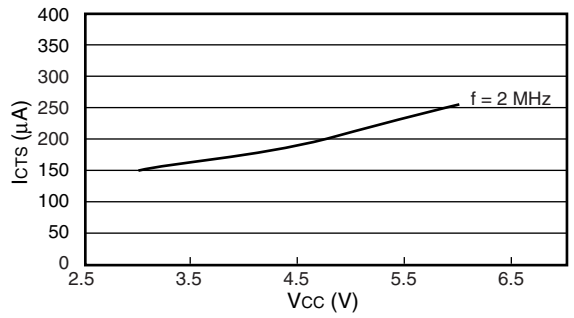
$I_{CCS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



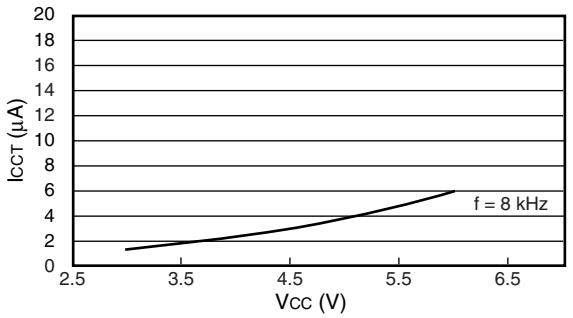
$I_{CCLS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



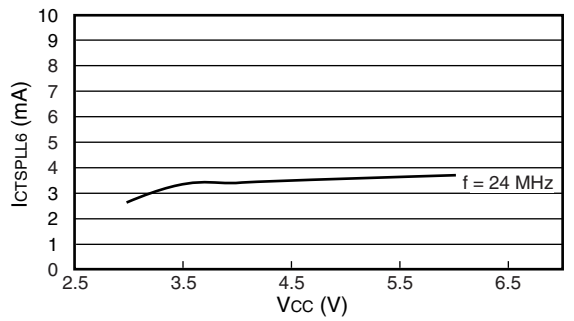
$I_{CTS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



$I_{CCT} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



$I_{CTSPLL6} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



$I_{CCH} - V_{CC}$
$T_A = +25°C$, stopped