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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	80
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90f349epmc-ge1

1. Product Lineup

Part Number Parameter	MB90V340E-101, MB90V340E-102	MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
Type	Evaluation products	Flash memory products	MASK ROM products
CPU	F ² MC-16LX CPU		
System clock	On-chip PLL clock multiplier (×1, ×2, ×3, ×4, ×6, 1/2 when PLL stops) Minimum instruction execution time : 42 ns (4 MHz osc. PLL × 6)		
ROM	External	512 Kbytes : MB90F345E(S), MB90F345CE(S) 256 Kbytes : MB90F342E(S), MB90F342CE(S), MB90F349E(S), MB90F349CE(S) 128 Kbytes : MB90F347E(S), MB90F347CE(S) 64 Kbytes : MB90F346E(S), MB90F346CE(S)	256 Kbytes : MB90342E(S), MB90342CE(S), MB90349E(S), MB90349CE(S) 128 Kbytes : MB90341E(S), MB90341CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S) 64 Kbytes : MB90346E(S), MB90346CE(S)
RAM	30 Kbytes	20 Kbytes : MB90F345E(S), MB90F345CE(S) 16 Kbytes : MB90F342E(S), MB90F342CE(S), MB90F349E(S), MB90F349CE(S) 6 Kbytes : MB90F347E(S), MB90F347CE(S) 2 Kbytes : MB90F346E(S), MB90F346CE(S)	16 Kbytes : MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S) 6 Kbytes : MB90347E(S), MB90347CE(S) 2 Kbytes : MB90346E(S), MB90346CE(S)
Emulator-specific power supply*	Yes	—	
Technology	0.35 μm CMOS with regulator for built-in power supply	0.35 μm CMOS with built-in power supply regulator + Flash memory with Charge pump for programming voltage	
Operating voltage range	5 V ± 10%	3.5 V to 5.5 V : When normal operating (not using A/D converter) 4.0 V to 5.5 V : When using the A/D converter/Flash programming 4.5 V to 5.5 V : When using the external bus	
Temperature range	—	−40°C to +105°C	
Package	PGA-299	QFP-100, LQFP-100	
LIN-UART	5 channels	4 channels	
	Wide range of baud rate settings using a dedicated baud rate generator (reload timer) Special synchronous options for adapting to different synchronous serial protocols LIN functionality working either as master or slave LIN device		
I ² C (400 kbps)	2 channels	Devices with a C suffix in the part number : 2 channels Devices without a C suffix in the part number : —	

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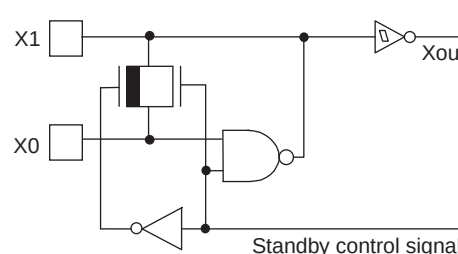
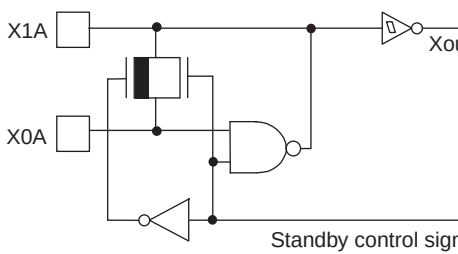
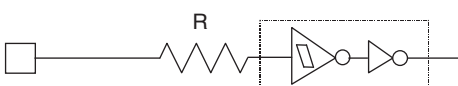
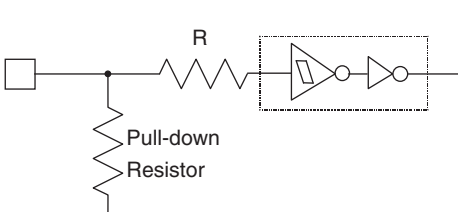
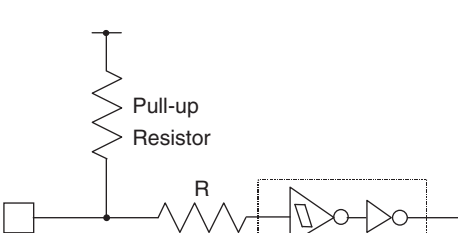
Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V _{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 μF .
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

(Continued)

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
61	59	P84	F	General purpose I/O pin.
		SCK0		Clock I/O pin for UART0
		INT15R		External interrupt request input pin
62	60	P85	M	General purpose I/O pin.
		SIN1		Serial data input pin for UART1
63	61	P86	F	General purpose I/O pin.
		SOT1		Serial data output pin for UART1
64	62	P87	F	General purpose I/O pin.
		SCK1		Clock I/O pin for UART1
65	63	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
66	64	V _{SS}	—	GND pin
67 to 70	65 to 68	P90 to P93	F	General purpose I/O pins
		PPG1, 3, 5, 7		Output pins for PPGs
71 to 74	69 to 72	P94 to P97	F	General purpose I/O pins
		OUT0 to OUT3		Waveform output pins for output compares. This function is enabled when the OCU enables waveform output.
75	73	PA0	F	General purpose I/O pin.
		RX0		RX input pin for CAN0 Interface
		INT8R		External interrupt request input pin
76	74	PA1	F	General purpose I/O pin.
		TX0		TX Output pin for CAN0
77 to 84	75 to 82	P00 to P07	G	General purpose I/O pins. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD00 to AD07		I/O pins for 8 lower bits of the external address/data bus. This function is enabled when the external bus is enabled.
		INT8 to INT15		External interrupt request input pins.
85	83	P10	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD08		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		TIN1		Event input pin for the reload timer

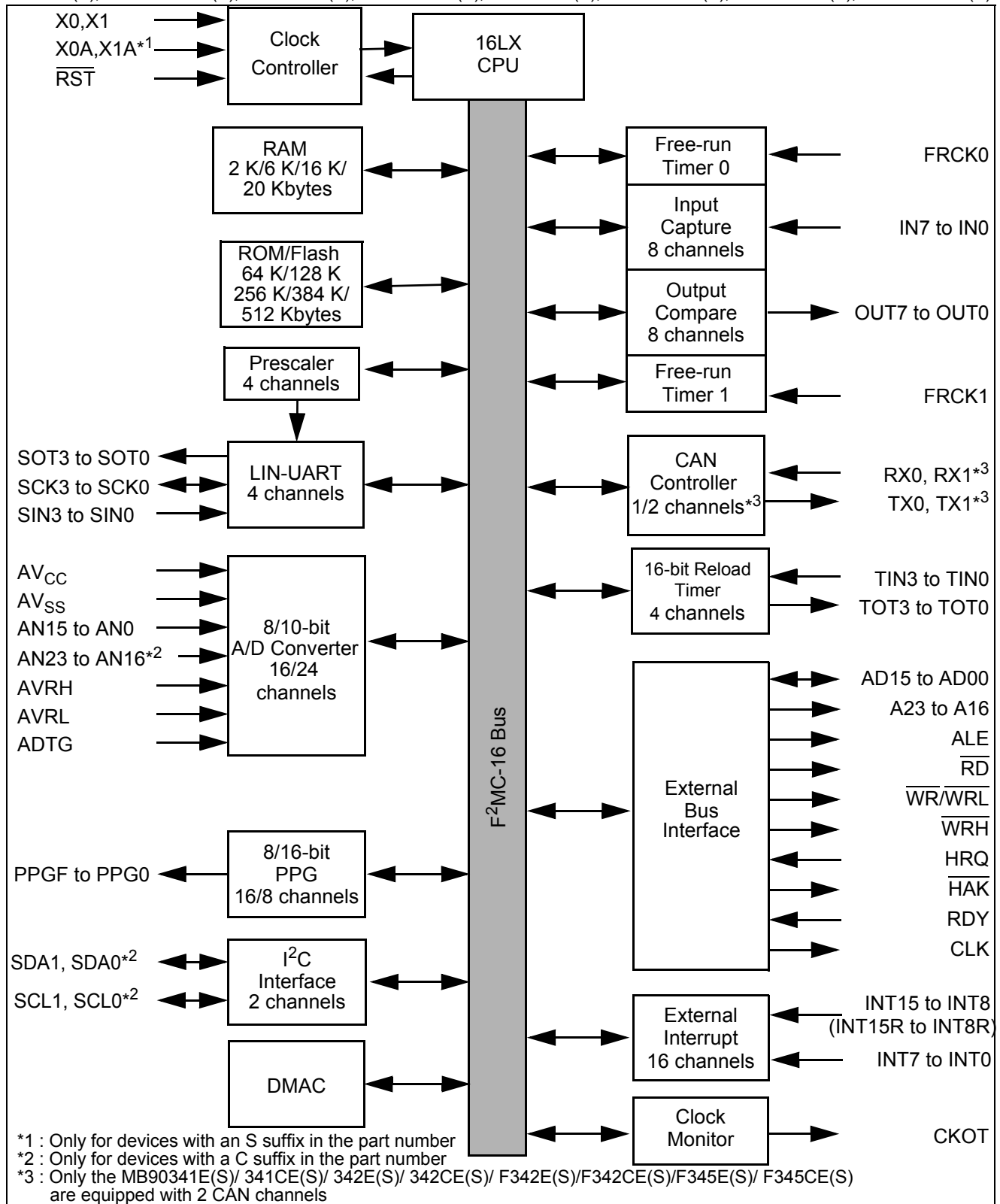
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4. I/O Circuit Type

Type	Circuit	Remarks
A		Oscillation circuit High-speed oscillation feedback resistor = approx. 1 MΩ
B		Oscillation circuit Low-speed oscillation feedback resistor = approx. 10 MΩ
C		■ MASK ROM and evaluation products: CMOS hysteresis input pin ■ Flash memory products: CMOS input pin
D		MASK ROM and evaluation products: ■ CMOS hysteresis input pin ■ Pull-down resistor value: approx. 50 kΩ Flash memory products: ■ CMOS input pin ■ No pull-down
E		CMOS hysteresis input pin Pull-up resistor value: approx. 50 kΩ

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■ MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90346E(S), MB90346CE(S), MB90F346E(S), MB90F346CE(S), MB90347E(S), MB90347CE(S), MB90F347E(S), MB90F347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S), MB90F349E(S), MB90F349CE(S)



8. I/O Map

Address	Register	Abbreviation	Access	Resource name	Initial value
000000 _H	Port 0 Data Register	PDR0	R/W	Port 0	XXXXXXXX _B
000001 _H	Port 1 Data Register	PDR1	R/W	Port 1	XXXXXXXX _B
000002 _H	Port 2 Data Register	PDR2	R/W	Port 2	XXXXXXXX _B
000003 _H	Port 3 Data Register	PDR3	R/W	Port 3	XXXXXXXX _B
000004 _H	Port 4 Data Register	PDR4	R/W	Port 4	XXXXXXXX _B
000005 _H	Port 5 Data Register	PDR5	R/W	Port 5	XXXXXXXX _B
000006 _H	Port 6 Data Register	PDR6	R/W	Port 6	XXXXXXXX _B
000007 _H	Port 7 Data Register	PDR7	R/W	Port 7	XXXXXXXX _B
000008 _H	Port 8 Data Register	PDR8	R/W	Port 8	XXXXXXXX _B
000009 _H	Port 9 Data Register	PDR9	R/W	Port 9	XXXXXXXX _B
00000A _H	Port A Data Register	PDRA	R/W	Port A	XXXXXXXX _B
00000B _H	Port 5 Analog Input Enable Register	ADER5	R/W	Port 5, A/D	1111111 _B
00000C _H	Port 6 Analog Input Enable Register	ADER6	R/W	Port 6, A/D	1111111 _B
00000D _H	Port 7 Analog Input Enable Register	ADER7	R/W	Port 7, A/D	1111111 _B
00000E _H	Input Level Select Register 0	ILSR0	R/W	Ports	XXXXXXXX _B
00000F _H	Input Level Select Register 1	ILSR1	R/W	Ports	XXXX0XXX _B
000010 _H	Port 0 Direction Register	DDR0	R/W	Port 0	0000000 _B
000011 _H	Port 1 Direction Register	DDR1	R/W	Port 1	0000000 _B
000012 _H	Port 2 Direction Register	DDR2	R/W	Port 2	0000000 _B
000013 _H	Port 3 Direction Register	DDR3	R/W	Port 3	0000000 _B
000014 _H	Port 4 Direction Register	DDR4	R/W	Port 4	0000000 _B
000015 _H	Port 5 Direction Register	DDR5	R/W	Port 5	0000000 _B
000016 _H	Port 6 Direction Register	DDR6	R/W	Port 6	0000000 _B
000017 _H	Port 7 Direction Register	DDR7	R/W	Port 7	0000000 _B
000018 _H	Port 8 Direction Register	DDR8	R/W	Port 8	0000000 _B
000019 _H	Port 9 Direction Register	DDR9	R/W	Port 9	0000000 _B
00001A _H	Port A Direction Register	DDRA	R/W	Port A	00000100 _B
00001B _H	Reserved				
00001C _H	Port 0 Pull-up Control Register	PUCR0	R/W	Port 0	0000000 _B
00001D _H	Port 1 Pull-up Control Register	PUCR1	R/W	Port 1	0000000 _B
00001E _H	Port 2 Pull-up Control Register	PUCR2	R/W	Port 2	0000000 _B
00001F _H	Port 3 Pull-up Control Register	PUCR3	W, R/W	Port 3	0000000 _B

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
000040 _H	PPG 8 Operation Mode Control Register	PPGC8	W,R/W	16-bit PPG 8/9	0X000XX1 _B
000041 _H	PPG 9 Operation Mode Control Register	PPGC9	W,R/W		0X000001 _B
000042 _H	PPG 8/PPG 9 Count Clock Control Register	PPG89	R/W		000000X0 _B
000043 _H	Reserved				
000044 _H	PPG A Operation Mode Control Register	PPGCA	W,R/W	16-bit PPG A/B	0X000XX1 _B
000045 _H	PPG B Operation Mode Control Register	PPGCB	W,R/W		0X000001 _B
000046 _H	PPG A/PPG B Count Clock Select Register	PPGAB	R/W		000000X0 _B
000047 _H	Reserved				
000048 _H	PPG C Operation Mode Control Register	PPGCC	W,R/W	16-bit PPG C/D	0X000XX1 _B
000049 _H	PPG D Operation Mode Control Register	PPGCD	W,R/W		0X000001 _B
00004A _H	PPG C/PPG D Count Clock Select Register	PPGCD	R/W		000000X0 _B
00004B _H	Reserved				
00004C _H	PPG E Operation Mode Control Register	PPGCE	W,R/W	16-bit PPG E/F	0X000XX1 _B
00004D _H	PPG F Operation Mode Control Register	PPGCF	W,R/W		0X000001 _B
00004E _H	PPG E/PPG F Count Clock Select Register	PPGEF	R/W		000000X0 _B
00004F _H	Reserved				
000050 _H	Input Capture Control Status 0/1	ICS01	R/W	Input Capture 0/1	00000000 _B
000051 _H	Input Capture Edge 0/1	ICE01	R/W, R		XXX0X0XX _B
000052 _H	Input Capture Control Status 2/3	ICS23	R/W	Input Capture 2/3	00000000 _B
000053 _H	Input Capture Edge 2/3	ICE23	R		XXXXXXXX _B
000054 _H	Input Capture Control Status 4/5	ICS45	R/W	Input Capture 4/5	00000000 _B
000055 _H	Input Capture Edge 4/5	ICE45	R		XXXXXXXX _B
000056 _H	Input Capture Control Status 6/7	ICS67	R/W	Input Capture 6/7	00000000 _B
000057 _H	Input Capture Edge 6/7	ICE67	R/W, R		XXX000XX _B
000058 _H	Output Compare Control Status 0	OCS0	R/W	Output Compare 0/1	0000XX00 _B
000059 _H	Output Compare Control Status 1	OCS1	R/W		0XX00000 _B
00005A _H	Output Compare Control Status 2	OCS2	R/W	Output Compare 2/3	0000XX00 _B
00005B _H	Output Compare Control Status 3	OCS3	R/W		0XX00000 _B
00005C _H	Output Compare Control Status 4	OCS4	R/W	Output Compare 4/5	0000XX00 _B
00005D _H	Output Compare Control Status 5	OCS5	R/W		0XX00000 _B
00005E _H	Output Compare Control Status 6	OCS6	R/W	Output Compare 6/7	0000XX00 _B
00005F _H	Output Compare Control Status 7	OCS7	R/W		0XX00000 _B

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9. CAN Controllers

The CAN controller has the following features:

- Conforms to CAN Specification Version 2.0 Part A and B
- Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmission/reception message buffers
- 29-bit ID and 8-byte data
- Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
- Two acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 kbps to 2 Mbps (when input clock is at 16 MHz)

List of Control Registers (1)

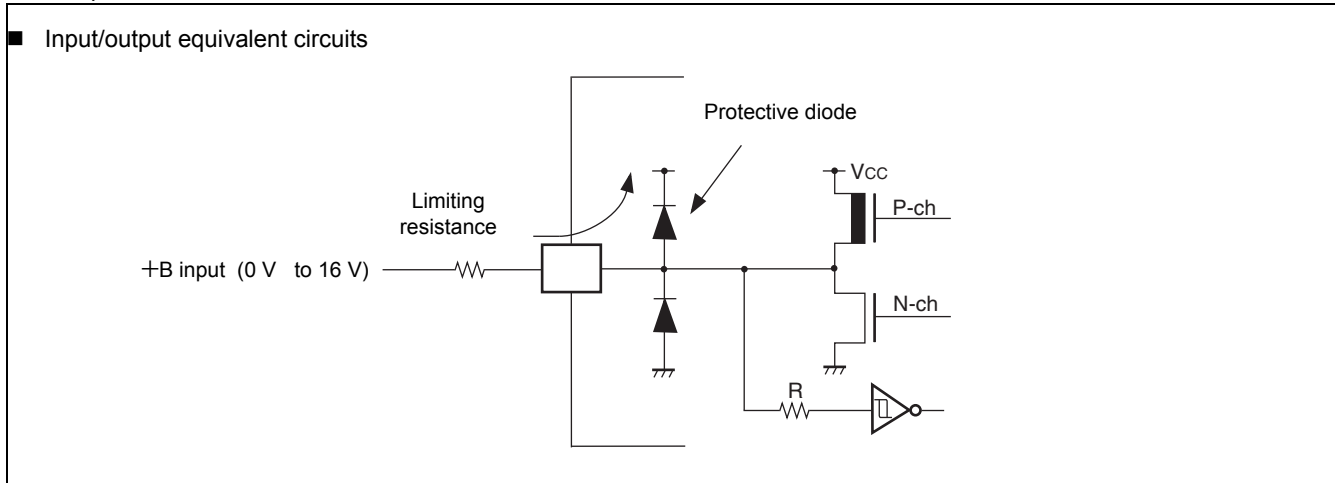
Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
000070 _H	000080 _H	Message Buffer Valid Register	BVALR	R/W	00000000 _B 00000000 _B
000071 _H	000081 _H				
000072 _H	000082 _H	Transmit Request Register	TREQR	R/W	00000000 _B 00000000 _B
000073 _H	000083 _H				
000074 _H	000084 _H	Transmit Cancel Register	TCANR	W	00000000 _B 00000000 _B
000075 _H	000085 _H				
000076 _H	000086 _H	Transmission Complete Register	TCR	R/W	00000000 _B 00000000 _B
000077 _H	000087 _H				
000078 _H	000088 _H	Receive Complete Register	RCR	R/W	00000000 _B 00000000 _B
000079 _H	000089 _H				
00007A _H	00008A _H	Remote Request Receiving Register	RRTRR	R/W	00000000 _B 00000000 _B
00007B _H	00008B _H				
00007C _H	00008C _H	Receive Overrun Register	ROVRR	R/W	00000000 _B 00000000 _B
00007D _H	00008D _H				
00007E _H	00008E _H	Reception Interrupt Enable Register	RIER	R/W	00000000 _B 00000000 _B
00007F _H	00008F _H				

List of Message Buffers (DLC Registers and Data Registers) (3)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007AF0 _H to 007AF7 _H	007CF0 _H to 007CF7 _H	Data Register 14 (8 bytes)	DTR14	R/W	XXXXXXXX _B to XXXXXXXX _B
007AF8 _H to 007AFF _H	007CF8 _H to 007CFF _H	Data Register 15 (8 bytes)	DTR15	R/W	XXXXXXXX _B to XXXXXXXX _B

(Continued)

- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on reset.
- Care must be taken not to leave the +B input pin open.
- Sample recommended circuits:



*6: The maximum output current is defined as the peak value of the current of any one of the corresponding pins.

*7: The average output current is defined as the value of the average current flowing over 100 ms at any one of the corresponding pins.

*8: The average total output current is defined as the value of the average current flowing over 100 ms at all of the corresponding pins.

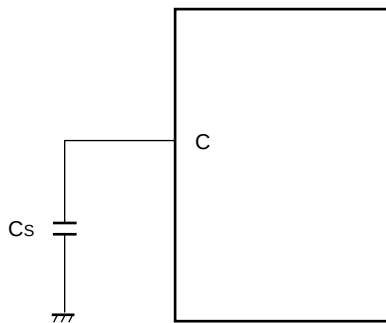
WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

11.2 Recommended Operating Conditions

($V_{SS} = AV_{SS} = 0\text{ V}$)

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Power supply voltage	V_{CC}, AV_{CC}	4.0	5.0	5.5	V	Under normal operation
		3.5	5.0	5.5	V	Under normal operation, when not using the A/D converter and not Flash programming.
		4.5	5.0	5.5	V	When External bus is used.
		3.0	—	5.5	V	Maintains RAM data in stop mode
Smoothing capacitor	C_S	0.1	—	1.0	μF	Use a ceramic capacitor or capacitor of better AC characteristics. Capacitor at the V_{CC} should be greater than this capacitor.
Operating temperature	T_A	-40	—	+105	$^{\circ}\text{C}$	

C Pin Connection Diagram



WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

11.3 DC Characteristics

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = AV_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Input H voltage (At $V_{CC} = 5\text{ V} \pm 10\%$)	V_{IHS}	—	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	Port inputs if CMOS hysteresis input levels are selected (except P12, P44, P45, P46, P47, P50, P82, P85)
	V_{IHA}	—	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	Port inputs if Automotive input levels are selected
	V_{IHT}	—	—	2.0	—	$V_{CC} + 0.3$	V	Port inputs if TTL input levels are selected
	V_{IHS}	—	—	$0.7 V_{CC}$	—	$V_{CC} + 0.3$	V	P12, P50, P82, P85 inputs if CMOS input levels are selected
	V_{IHI}	—	—	$0.7 V_{CC}$	—	$V_{CC} + 0.3$	V	P44, P45, P46, P47 inputs if CMOS hysteresis input levels are selected
	V_{IHR}	—	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	$\overline{\text{RST}}$ input pin (CMOS hysteresis)
	V_{IHM}	—	—	$V_{CC} - 0.3$	—	$V_{CC} + 0.3$	V	MD input pin
Input L voltage (At $V_{CC} = 5\text{ V} \pm 10\%$)	V_{ILS}	—	—	$V_{SS} - 0.3$	—	$0.2 V_{CC}$	V	Port inputs if CMOS hysteresis input levels are selected (except P12, P44, P45, P46, P47, P50, P82, P85)
	V_{ILA}	—	—	$V_{SS} - 0.3$	—	$0.5 V_{CC}$	V	Port inputs if Automotive input levels are selected
	V_{ILT}	—	—	$V_{SS} - 0.3$	—	0.8	V	Port inputs if TTL input levels are selected
	V_{ILS}	—	—	$V_{SS} - 0.3$	—	$0.3 V_{CC}$	V	P12, P50, P82, P85 inputs if CMOS input levels are selected
	V_{ILI}	—	—	$V_{SS} - 0.3$	—	$0.3 V_{CC}$	V	P44, P45, P46, P47 inputs if CMOS hysteresis input levels are selected
	V_{ILR}	—	—	$V_{SS} - 0.3$	—	$0.2 V_{CC}$	V	$\overline{\text{RST}}$ input pin (CMOS hysteresis)
	V_{ILM}	—	—	$V_{SS} - 0.3$	—	$V_{SS} + 0.3$	V	MD input pin
Output H voltage	V_{OH}	Normal outputs	$V_{CC} = 4.5\text{ V}$, $I_{OH} = -4.0\text{ mA}$	$V_{CC} - 0.5$	—	—	V	
Output H voltage	V_{OHI}	I ² C current outputs	$V_{CC} = 4.5\text{ V}$, $I_{OH} = -3.0\text{ mA}$	$V_{CC} - 0.5$	—	—	V	
Output L voltage	V_{OL}	Normal outputs	$V_{CC} = 4.5\text{ V}$, $I_{OL} = 4.0\text{ mA}$	—	—	0.4	V	
Output L voltage	V_{OLI}	I ² C current outputs	$V_{CC} = 4.5\text{ V}$, $I_{OL} = 3.0\text{ mA}$	—	—	0.4	V	

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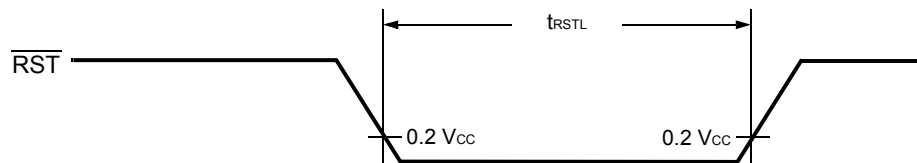
11.4.2 Reset Standby Input

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$)

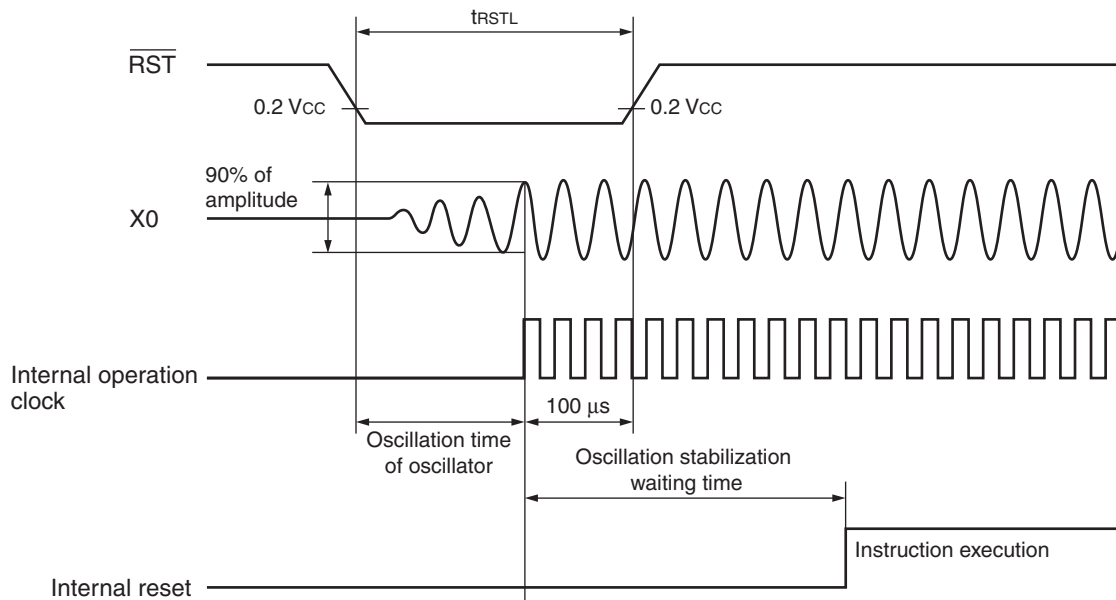
Parameter	Symbol	Pin	Value		Unit	Remarks
			Min	Max		
Reset input time	t_{RSTL}	$\overline{\text{RST}}$	500	—	ns	Under normal operation
			Oscillation time of oscillator* + 100 μs	—	μs	In Stop mode, Sub Clock mode, Sub Sleep mode and Watch mode
			100	—	μs	In Time Timer mode

* : The oscillation time of the oscillator is the time it takes for the amplitude of the oscillations to reach 90%. For crystal oscillators, this time is between several ms and several tens of ms, for ceramic oscillators the time is between several hundred μs and several ms, and for an external clock, the time is 0 ms.

● Under normal operation:



● In Stop mode, Sub Clock mode, Sub Sleep mode, Watch mode:

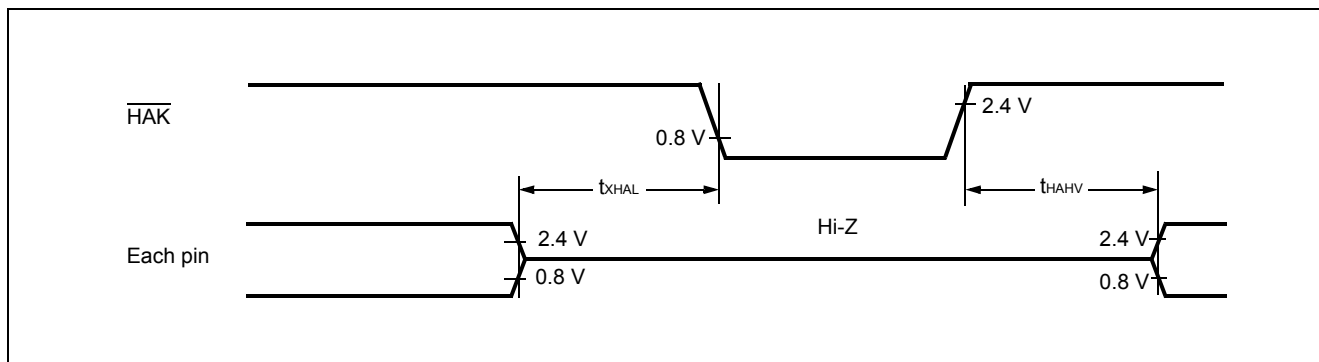


11.4.8 Hold Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Pin floating $\rightarrow \overline{\text{HAK}} \downarrow$ time	t_{XHAL}	$\overline{\text{HAK}}$	—	30	t_{CP}	ns
$\overline{\text{HAK}} \uparrow$ time $\rightarrow$ Pin valid time	t_{HAHV}	$\overline{\text{HAK}}$	—	t_{CP}	$2 t_{CP}$	ns

Note: : There is more than 1 cycle from when HRQ reads in until the $\overline{\text{HAK}}$ is changed.



11.4.9 LIN-UART0/1/2/3

■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0

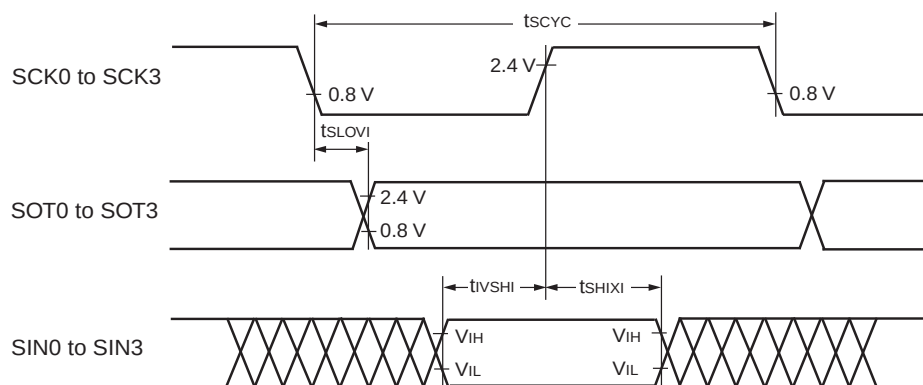
($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock "L" pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$3 t_{CP} - t_R$	—	ns
Serial clock "H" pulse width	t_{SLSH}	SCK0 to SCK3		$t_{CP} + 10$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	$2 t_{CP} + 60$	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXE}	SCK0, SCK1, SIN0 to SIN3		$t_{CP} + 30$	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

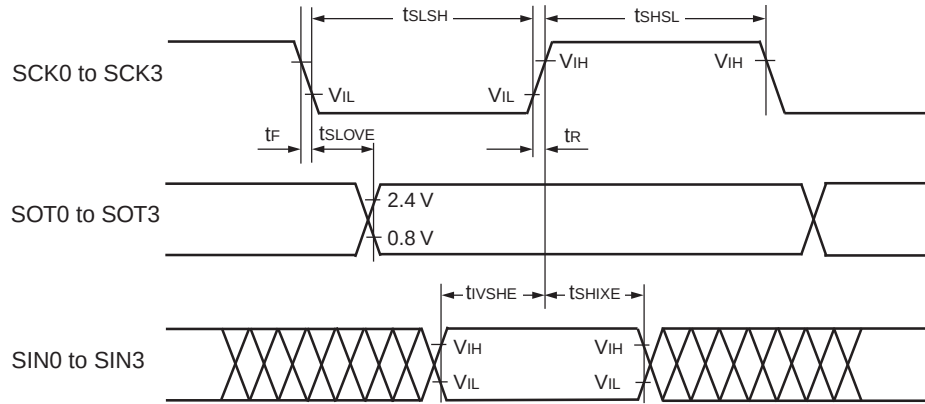
Note:

- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “ (1) Clock Timing”.

• Internal Shift Clock Mode



• External Shift Clock Mode



■ Bit setting: ESCR:SCES = 1, ECCR:SCDE = 0

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\uparrow \rightarrow$ SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\downarrow$	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\downarrow \rightarrow$ Valid SIN hold time	t_{SLIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock "H" pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$3 t_{CP} - t_R$	—	ns
Serial clock "L" pulse width	t_{SLSH}	SCK0 to SCK3		$t_{CP} + 10$	—	ns
SCK $\uparrow \rightarrow$ SOT delay time	t_{SHOVE}	SCK0 to SCK3, SOT0 to SOT3		—	$2 t_{CP} + 60$	ns
Valid SIN $\rightarrow$ SCK $\downarrow$	t_{IVSLE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK $\downarrow \rightarrow$ Valid SIN hold time	t_{SLIXE}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 30$	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

Note:

- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to "Clock Timing".

11.4.13 I²C Timing

(T_A = -40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

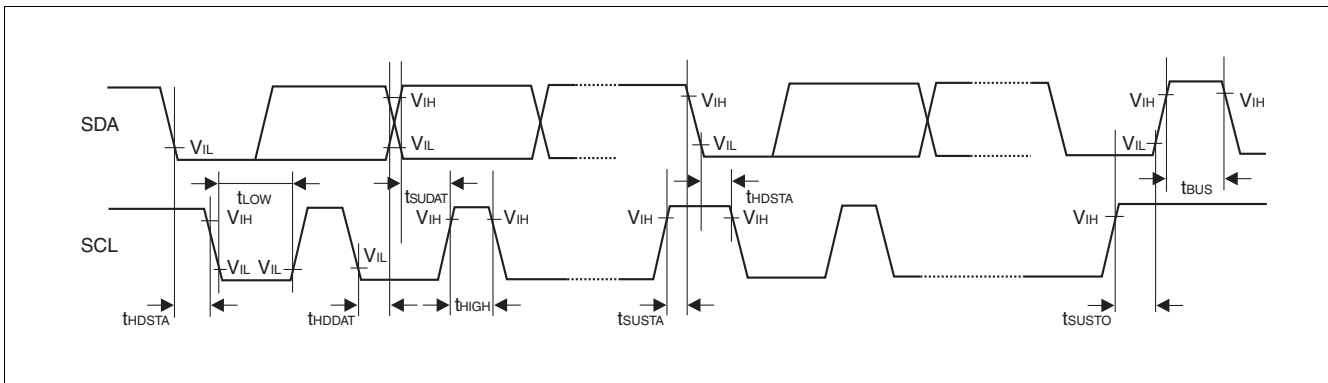
Parameter	Symbol	Condition	Standard-mode		Fast-mode* ¹		Unit
			Min	Max	Min	Max	
SCL clock frequency	f _{SCL}	R = 1.7 kΩ ₂ C = 50 pF* ²	0	100	0	400	kHz
Hold time (repeated) START condition SDA ↓ → SCL ↓	t _{HDSTA}		4.0	—	0.6	—	μs
"L" width of the SCL clock	t _{LOW}		4.7	—	1.3	—	μs
"H" width of the SCL clock	t _{HIGH}		4.0	—	0.6	—	μs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t _{SUSTA}		4.7	—	0.6	—	μs
Data hold time SCL ↓ → SDA ↓ ↑	t _{HDDAT}		0	3.45* ³	0	0.9* ⁴	μs
Data set-up time SDA ↓ ↑ → SCL ↑	t _{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t _{SUSTO}		4.0	—	0.6	—	μs
Bus free time between a STOP and START condition	t _{BUS}		4.7	—	1.3	—	μs

*1: For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.

*3: The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4: A Fast-mode I²C-bus device can be used in a Standard-mode I²C-bus system, but the requirement t_{SUDAT} ≥ 250 ns must then be met.



11.5 A/D Converter

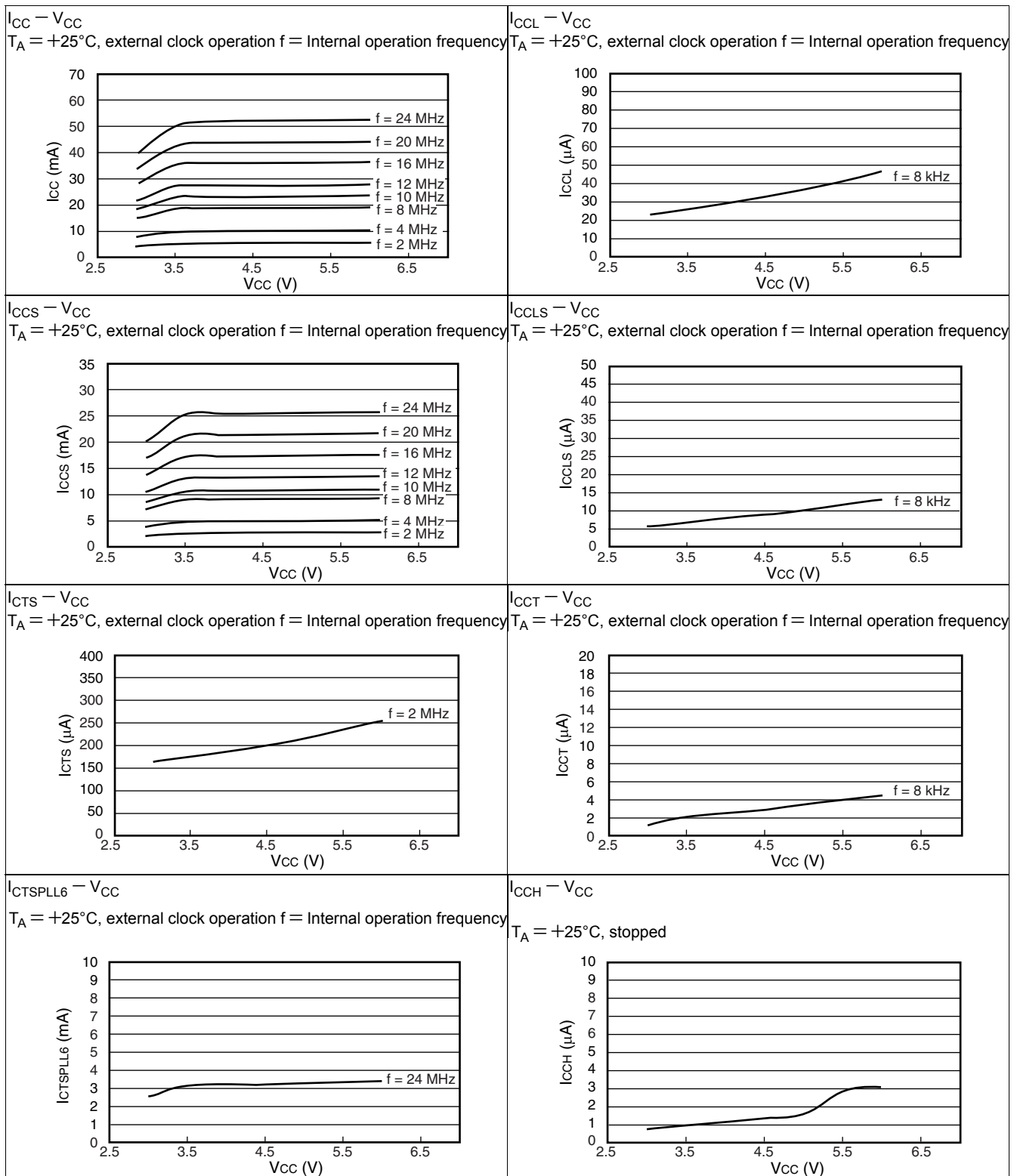
($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $3.0\text{ V} \leq \text{AVRH} - \text{AVRL}$, $V_{CC} = \text{AV}_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = \text{AV}_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	—	—	± 3.0	LSB	
Nonlinearity error	—	—	—	—	± 2.5	LSB	
Differential nonlinearity error	—	—	—	—	± 1.9	LSB	
Zero reading voltage	V_{OT}	AN0 to AN23	$\text{AVRL} - 1.5 \times \text{LSB}$	$\text{AVRL} + 0.5 \times \text{LSB}$	$\text{AVRL} + 2.5 \times \text{LSB}$	V	
Full scale reading voltage	V_{FST}	AN0 to AN23	$\text{AVRH} - 3.5 \times \text{LSB}$	$\text{AVRH} - 1.5 \times \text{LSB}$	$\text{AVRH} + 0.5 \times \text{LSB}$	V	
Compare time	—	—	1.0	—	16500	μs	$4.5\text{ V} \leq \text{AV}_{CC} \leq 5.5\text{ V}$
			2.0				$4.0\text{ V} \leq \text{AV}_{CC} < 4.5\text{ V}$
Sampling time	—	—	0.5	—	∞	μs	$4.5\text{ V} \leq \text{AV}_{CC} \leq 5.5\text{ V}$
			1.2				$4.0\text{ V} \leq \text{AV}_{CC} < 4.5\text{ V}$
Analog port input current	I_{AIN}	AN0 to AN23	-0.3	—	+0.3	μA	
Analog input voltage range	V_{AIN}	AN0 to AN23	AVRL	—	AVRH	V	
Reference voltage range	—	AVRH	$\text{AVRL} + 2.7$	—	AV_{CC}	V	
		AVRL	0	—	$\text{AVRH} - 2.7$	V	
Power supply current	I_A	AV_{CC}	—	3.5	7.5	mA	
	I_{AH}	AV_{CC}	—	—	5	μA	*
Reference voltage current	I_R	AVRH	—	600	900	μA	
	I_{RH}	AVRH	—	—	5	μA	*
Offset between input channels	—	AN0 to AN23	—	—	4	LSB	

*: If the A/D convertor is not operating, a current when CPU is stopped is applicable ($V_{CC} = \text{AV}_{CC} = \text{AVRH} = 5.0\text{ V}$).

Note: : The accuracy gets worse as $|\text{AVRH} - \text{AVRL}|$ becomes smaller.

■ MB90F347E, MB90F347ES, MB90F347CE, MB90F347CES



■ I/O characteristics

