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Understanding [Embedded - Microprocessors](#)

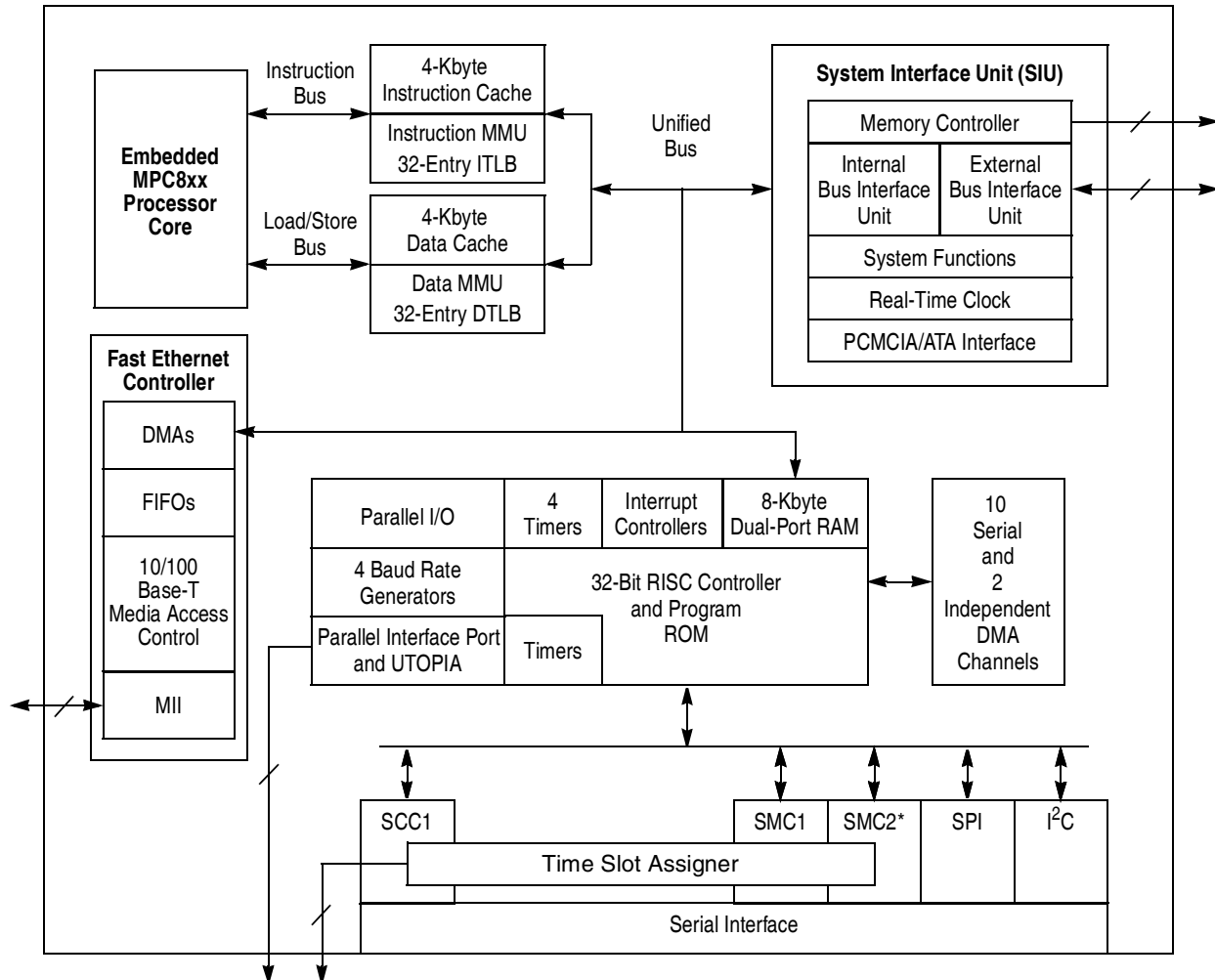
Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of [Embedded - Microprocessors](#)

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details

Product Status	Obsolete
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	100MHz
Co-Processors/DSP	Communications; CPM
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10Mbps (4), 10/100Mbps (1)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 105°C (TA)
Security Features	-
Package / Case	357-BBGA
Supplier Device Package	357-PBGA (25x25)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mpc862pvr100b



*The MPC857DSL does not contain SMC2 nor the Time Slot Assigner, and provides eight SDMA controllers.

Figure 2. MPC857T/MPC857DSL Block Diagram

3 Maximum Tolerated Ratings

This section provides the maximum tolerated voltage and temperature ranges for the MPC862/857T/857DSL. Table 2 provides the maximum ratings.

Table 2. Maximum Tolerated Ratings
(GND = 0 V)

Rating	Symbol	Value	Unit	Max Freq (MHz)
Supply voltage ¹	VDDH	-0.3 to 4.0	V	-
	VDDL	-0.3 to 4.0	V	-
	KAPWR	-0.3 to 4.0	V	-
	VDDSYN	-0.3 to 4.0	V	-

7.2 Estimation with Junction-to-Case Thermal Resistance

Historically, the thermal resistance has frequently been expressed as the sum of a junction-to-case thermal resistance and a case-to-ambient thermal resistance:

$$R_{\theta JA} = R_{\theta JC} + R_{\theta CA}$$

where:

$R_{\theta JA}$ = junction-to-ambient thermal resistance ($^{\circ}\text{C}/\text{W}$)

$R_{\theta JC}$ = junction-to-case thermal resistance ($^{\circ}\text{C}/\text{W}$)

$R_{\theta CA}$ = case-to-ambient thermal resistance ($^{\circ}\text{C}/\text{W}$)

$R_{\theta JC}$ is device related and cannot be influenced by the user. The user adjusts the thermal environment to affect the case-to-ambient thermal resistance, $R_{\theta CA}$. For instance, the user can change the air flow around the device, add a heat sink, change the mounting arrangement on the printed circuit board, or change the thermal dissipation on the printed circuit board surrounding the device. This thermal model is most useful for ceramic packages with heat sinks where some 90% of the heat flows through the case and the heat sink to the ambient environment. For most packages, a better model is required.

7.3 Estimation with Junction-to-Board Thermal Resistance

A simple package thermal model which has demonstrated reasonable accuracy (about 20%) is a two resistor model consisting of a junction-to-board and a junction-to-case thermal resistance. The junction-to-case covers the situation where a heat sink is used or where a substantial amount of heat is dissipated from the top of the package. The junction-to-board thermal resistance describes the thermal performance when most of the heat is conducted to the printed circuit board. It has been observed that the thermal performance of most plastic packages and especially PBGA packages is strongly dependent on the board temperature; see [Figure 3](#).

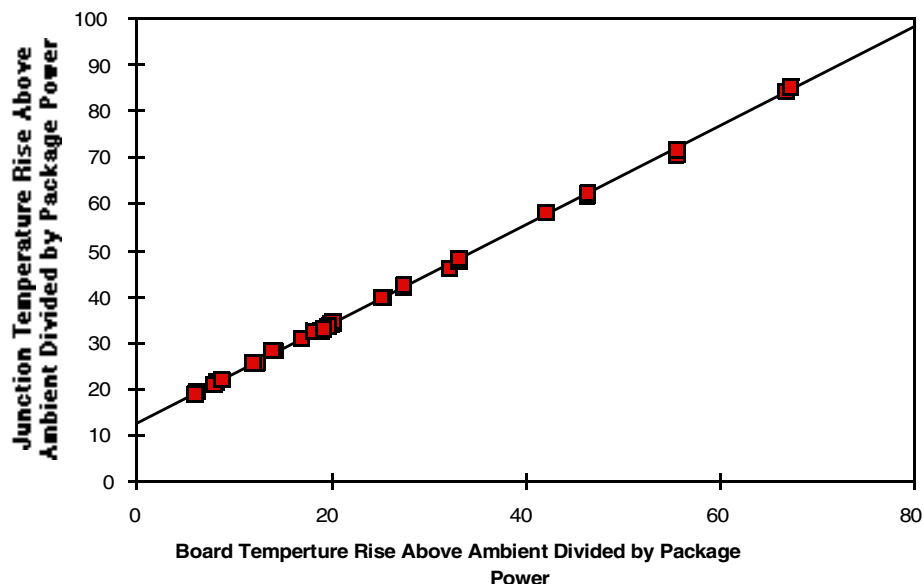


Figure 3. Effect of Board Temperature Rise on Thermal Behavior

Table 7. Bus Operation Timings (continued)

Num	Characteristic	33 MHz		40 MHz		50 MHz		66 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
B27	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 10, TRLX = 1 (MIN = 1.25 x B1 - 2.00)	35.90	—	29.30	—	23.00	—	16.90	—	ns
B27a	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 11, TRLX = 1 (MIN = 1.50 x B1 - 2.00)	43.50	—	35.50	—	28.00	—	20.70	—	ns
B28	CLKOUT rising edge to \overline{WE} (0:3) negated GPCM write access CSNT = 0 (MAX = 0.00 x B1 + 9.00)	—	9.00	—	9.00	—	9.00	—	9.00	ns
B28a	CLKOUT falling edge to \overline{WE} (0:3) negated GPCM write access TRLX = 0, 1, CSNT = 1, EBDF = 0 (MAX = 0.25 x B1 + 6.80)	7.60	14.30	6.30	13.00	5.00	11.80	3.80	10.50	ns
B28b	CLKOUT falling edge to \overline{CS} negated GPCM write access TRLX = 0,1, CSNT = 1 ACS = 10 or ACS = 11, EBDF = 0 (MAX = 0.25 x B1 + 6.80)	—	14.30	—	13.00	—	11.80	—	10.50	ns
B28c	CLKOUT falling edge to \overline{WE} (0:3) negated GPCM write access TRLX = 0, CSNT = 1 write access TRLX = 0,1, CSNT = 1, EBDF = 1 (MAX = 0.375 x B1 + 6.6)	10.90	18.00	10.90	18.00	7.00	14.30	5.20	12.30	ns
B28d	CLKOUT falling edge to \overline{CS} negated GPCM write access TRLX = 0,1, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 1 (MAX = 0.375 x B1 + 6.6)	—	18.00	—	18.00	—	14.30	—	12.30	ns
B29	\overline{WE} (0:3) negated to D(0:31), DP(0:3) High-Z GPCM write access, CSNT = 0, EBDF = 0 (MIN = 0.25 x B1 - 2.00)	5.60	—	4.30	—	3.00	—	1.80	—	ns
B29a	\overline{WE} (0:3) negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 0, CSNT = 1, EBDF = 0 (MIN = 0.50 x B1 - 2.00)	13.20	—	10.50	—	8.00	—	5.60	—	ns
B29b	\overline{CS} negated to D(0:31), DP(0:3), High Z GPCM write access, ACS = 00, TRLX = 0,1 & CSNT = 0 (MIN = 0.25 x B1 - 2.00)	5.60	—	4.30	—	3.00	—	1.80	—	ns
B29c	\overline{CS} negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 0, CSNT = 1, ACS = 10, or ACS = 11 EBDF = 0 (MIN = 0.50 x B1 - 2.00)	13.20	—	10.50	—	8.00	—	5.60	—	ns

Table 7. Bus Operation Timings (continued)

Num	Characteristic	33 MHz		40 MHz		50 MHz		66 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
B30c	$\overline{WE}(0:3)$ negated to A(0:31), BADDR(28:30) invalid GPCM write access, TRLX = 0, CSNT = 1. \overline{CS} negated to A(0:31) invalid GPCM write access, TRLX = 0, CSNT = 1 ACS = 10, ACS == 11, EBDF = 1 (MIN = 0.375 x B1 - 3.00)	8.40	—	6.40	—	4.50	—	2.70	—	ns
B30d	$\overline{WE}(0:3)$ negated to A(0:31), BADDR(28:30) invalid GPCM write access TRLX = 1, CSNT = 1, \overline{CS} negated to A(0:31) invalid GPCM write access TRLX = 1, CSNT = 1, ACS = 10 or 11, EBDF = 1	38.67	—	31.38	—	24.50	—	17.83	—	ns
B31	CLKOUT falling edge to \overline{CS} valid - as requested by control bit CST4 in the corresponding word in the UPM (MAX = 0.00 X B1 + 6.00)	1.50	6.00	1.50	6.00	1.50	6.00	1.50	6.00	ns
B31a	CLKOUT falling edge to \overline{CS} valid - as requested by control bit CST1 in the corresponding word in the UPM (MAX = 0.25 x B1 + 6.80)	7.60	14.30	6.30	13.00	5.00	11.80	3.80	10.50	ns
B31b	CLKOUT rising edge to \overline{CS} valid - as requested by control bit CST2 in the corresponding word in the UPM (MAX = 0.00 x B1 + 8.00)	1.50	8.00	1.50	8.00	1.50	8.00	1.50	8.00	ns
B31c	CLKOUT rising edge to \overline{CS} valid- as requested by control bit CST3 in the corresponding word in the UPM (MAX = 0.25 x B1 + 6.30)	7.60	13.80	6.30	12.50	5.00	11.30	3.80	10.00	ns
B31d	CLKOUT falling edge to \overline{CS} valid, as requested by control bit CST1 in the corresponding word in the UPM EBDF = 1 (MAX = 0.375 x B1 + 6.6)	9.40	18.00	7.60	16.00	13.30	14.10	11.30	12.30	ns
B32	CLKOUT falling edge to \overline{BS} valid- as requested by control bit BST4 in the corresponding word in the UPM (MAX = 0.00 x B1 + 6.00)	1.50	6.00	1.50	6.00	1.50	6.00	1.50	6.00	ns
B32a	CLKOUT falling edge to \overline{BS} valid - as requested by control bit BST1 in the corresponding word in the UPM, EBDF = 0 (MAX = 0.25 x B1 + 6.80)	7.60	14.30	6.30	13.00	5.00	11.80	3.80	10.50	ns
B32b	CLKOUT rising edge to \overline{BS} valid - as requested by control bit BST2 in the corresponding word in the UPM (MAX = 0.00 x B1 + 8.00)	1.50	8.00	1.50	8.00	1.50	8.00	1.50	8.00	ns

Table 7. Bus Operation Timings (continued)

Num	Characteristic	33 MHz		40 MHz		50 MHz		66 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
B37	UPWAIT valid to CLKOUT falling edge ¹² (MIN = 0.00 x B1 + 6.00)	6.00	—	6.00	—	6.00	—	6.00	—	ns
B38	CLKOUT falling edge to UPGATE valid ¹² (MIN = 0.00 x B1 + 1.00)	1.00	—	1.00	—	1.00	—	1.00	—	ns
B39	\overline{AS} valid to CLKOUT rising edge ¹³ (MIN = 0.00 x B1 + 7.00)	7.00	—	7.00	—	7.00	—	7.00	—	ns
B40	A(0:31), TSIZ(0:1), RD/WR, BURST, valid to CLKOUT rising edge (MIN = 0.00 x B1 + 7.00)	7.00	—	7.00	—	7.00	—	7.00	—	ns
B41	\overline{TS} valid to CLKOUT rising edge (setup time) (MIN = 0.00 x B1 + 7.00)	7.00	—	7.00	—	7.00	—	7.00	—	ns
B42	CLKOUT rising edge to \overline{TS} valid (hold time) (MIN = 0.00 x B1 + 2.00)	2.00	—	2.00	—	2.00	—	2.00	—	ns
B43	\overline{AS} negation to memory controller signals negation (MAX = TBD)	—	TBD	—	TBD	—	TBD	—	TBD	ns

¹ Phase and frequency jitter performance results are only valid if the input jitter is less than the prescribed value.

² If the rate of change of the frequency of EXTAL is slow (i.e. it does not jump between the minimum and maximum values in one cycle) or the frequency of the jitter is fast (i.e., it does not stay at an extreme value for a long time) then the maximum allowed jitter on EXTAL can be up to 2%.

³ The timings specified in B4 and B5 are based on full strength clock.

⁴ The timing for \overline{BR} output is relevant when the MPC862/857T/857DSL is selected to work with external bus arbiter. The timing for \overline{BG} output is relevant when the MPC862/857T/857DSL is selected to work with internal bus arbiter.

⁵ For part speeds above 50MHz, use 9.80ns for B11a.

⁶ The timing required for \overline{BR} input is relevant when the MPC862/857T/857DSL is selected to work with internal bus arbiter. The timing for \overline{BG} input is relevant when the MPC862/857T/857DSL is selected to work with external bus arbiter.

⁷ For part speeds above 50MHz, use 2ns for B17.

⁸ The D(0:31) and DP(0:3) input timings B18 and B19 refer to the rising edge of the CLKOUT in which the \overline{TA} input signal is asserted.

⁹ For part speeds above 50MHz, use 2ns for B19.

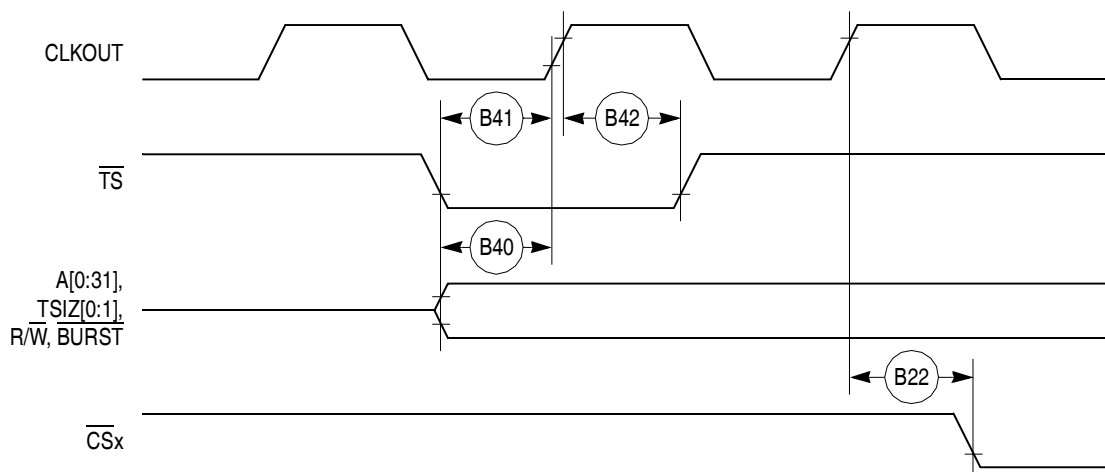
¹⁰ The D(0:31) and DP(0:3) input timings B20 and B21 refer to the falling edge of the CLKOUT. This timing is valid only for read accesses controlled by chip-selects under control of the UPM in the memory controller, for data beats where DLT3 = 1 in the UPM RAM words. (This is only the case where data is latched on the falling edge of CLKOUT.)

¹¹ The timing B30 refers to \overline{CS} when ACS = 00 and to $\overline{WE}(0:3)$ when CSNT = 0.

¹² The signal UPGATE is considered asynchronous to the CLKOUT and synchronized internally. The timings specified in B37 and B38 are specified to enable the freeze of the UPM output signals as described in Figure 19.

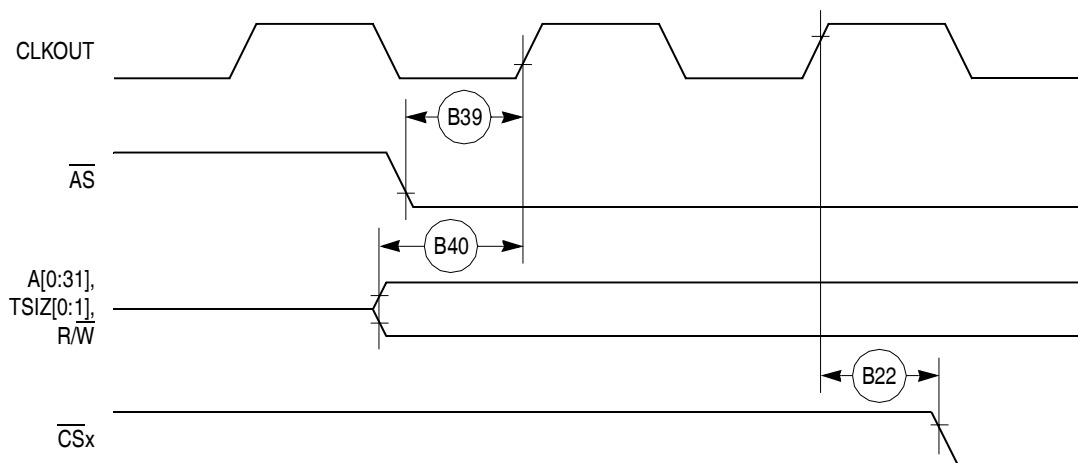
¹³ The \overline{AS} signal is considered asynchronous to the CLKOUT. The timing B39 is specified in order to allow the behavior specified in Figure 22.

Figure 21 provides the timing for the synchronous external master access controlled by the GPCM.



**Figure 21. Synchronous External Master Access Timing
(GPCM Handled ACS = 00)**

Figure 22 provides the timing for the asynchronous external master memory access controlled by the GPCM.



**Figure 22. Asynchronous External Master Memory Access Timing
(GPCM Controlled—ACS = 00)**

Figure 23 provides the timing for the asynchronous external master control signals negation.

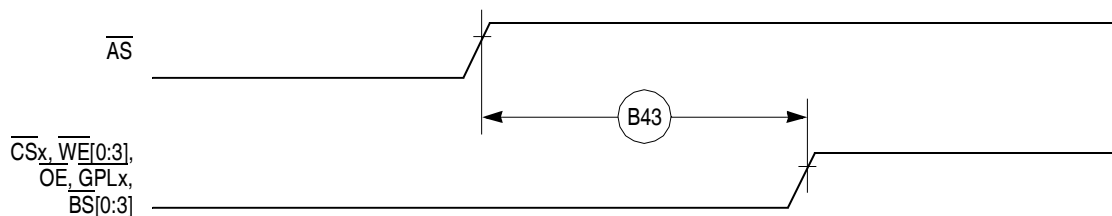


Figure 23. Asynchronous External Master—Control Signals Negation Timing

Table 8 provides interrupt timing for the MPC862/857T/857DSL.

Table 8. Interrupt Timing

Num	Characteristic ¹	All Frequencies		Unit
		Min	Max	
I39	$\overline{\text{IRQ}}_x$ valid to CLKOUT rising edge (set up time)	6.00		ns
I40	$\overline{\text{IRQ}}_x$ hold time after CLKOUT	2.00		ns
I41	$\overline{\text{IRQ}}_x$ pulse width low	3.00		ns
I42	$\overline{\text{IRQ}}_x$ pulse width high	3.00		ns
I43	$\overline{\text{IRQ}}_x$ edge-to-edge time	$4 \times T_{\text{CLKOUT}}$		—

¹ The timings I39 and I40 describe the testing conditions under which the $\overline{\text{IRQ}}$ lines are tested when being defined as level sensitive. The $\overline{\text{IRQ}}$ lines are synchronized internally and do not have to be asserted or negated with reference to the CLKOUT. The timings I41, I42, and I43 are specified to allow the correct function of the $\overline{\text{IRQ}}$ lines detection circuitry, and has no direct relation with the total system interrupt latency that the MPC862/857T/857DSL is able to support.

Figure 24 provides the interrupt detection timing for the external level-sensitive lines.

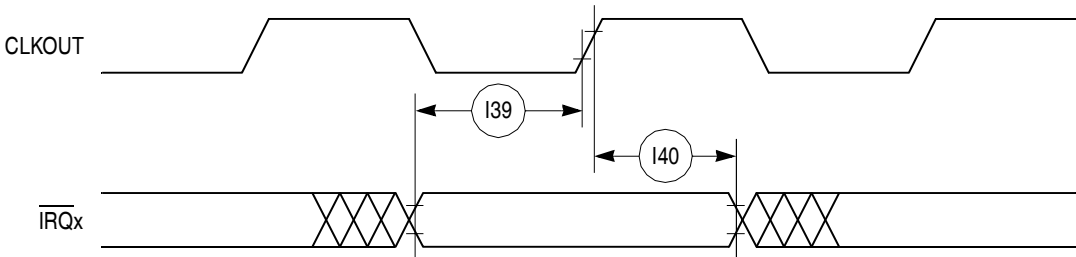


Figure 24. Interrupt Detection Timing for External Level Sensitive Lines

Figure 25 provides the interrupt detection timing for the external edge-sensitive lines.

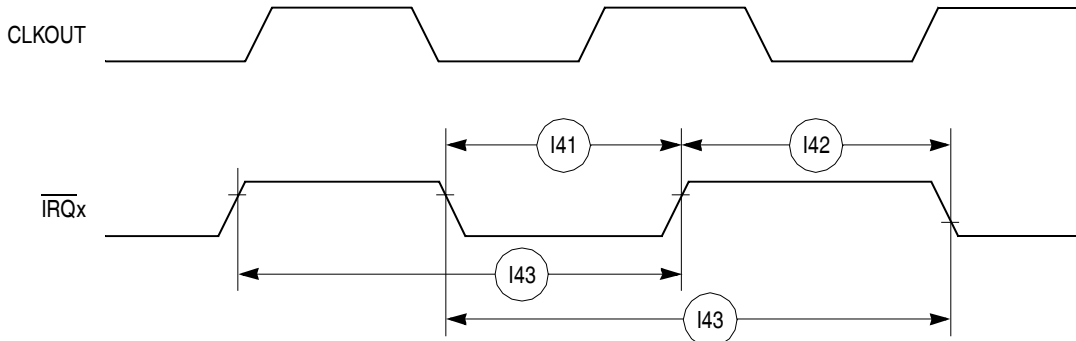


Figure 25. Interrupt Detection Timing for External Edge Sensitive Lines

Table 9 shows the PCMCIA timing for the MPC862/857T/857DSL.

Table 9. PCMCIA Timing

Num	Characteristic	33 MHz		40 MHz		50 MHz		66 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
P44	A(0:31), $\overline{\text{REG}}$ valid to PCMCIA Strobe asserted. ¹ (MIN = 0.75 x B1 - 2.00)	20.70	—	16.70	—	13.00	—	9.40	—	ns
P45	A(0:31), $\overline{\text{REG}}$ valid to ALE negation. ¹ (MIN = 1.00 x B1 - 2.00)	28.30	—	23.00	—	18.00	—	13.20	—	ns
P46	CLKOUT to $\overline{\text{REG}}$ valid (MAX = 0.25 x B1 + 8.00)	7.60	15.60	6.30	14.30	5.00	13.00	3.80	11.80	ns
P47	CLKOUT to $\overline{\text{REG}}$ Invalid. (MIN = 0.25 x B1 + 1.00)	8.60	—	7.30	—	6.00	—	4.80	—	ns
P48	CLKOUT to $\overline{\text{CE1}}$, $\overline{\text{CE2}}$ asserted. (MAX = 0.25 x B1 + 8.00)	7.60	15.60	6.30	14.30	5.00	13.00	3.80	11.80	ns
P49	CLKOUT to $\overline{\text{CE1}}$, $\overline{\text{CE2}}$ negated. (MAX = 0.25 x B1 + 8.00)	7.60	15.60	6.30	14.30	5.00	13.00	3.80	11.80	ns
P50	CLKOUT to $\overline{\text{PCOE}}$, $\overline{\text{IORD}}$, $\overline{\text{PCWE}}$, $\overline{\text{IOWR}}$ assert time. (MAX = 0.00 x B1 + 11.00)	—	11.00	—	11.00	—	11.00	—	11.00	ns
P51	CLKOUT to $\overline{\text{PCOE}}$, $\overline{\text{IORD}}$, $\overline{\text{PCWE}}$, $\overline{\text{IOWR}}$ negate time. (MAX = 0.00 x B1 + 11.00)	2.00	11.00	2.00	11.00	2.00	11.00	2.00	11.00	ns
P52	CLKOUT to ALE assert time (MAX = 0.25 x B1 + 6.30)	7.60	13.80	6.30	12.50	5.00	11.30	3.80	10.00	ns
P53	CLKOUT to ALE negate time (MAX = 0.25 x B1 + 8.00)	—	15.60	—	14.30	—	13.00	—	11.80	ns
P54	$\overline{\text{PCWE}}$, $\overline{\text{IOWR}}$ negated to D(0:31) invalid. ¹ (MIN = 0.25 x B1 - 2.00)	5.60	—	4.30	—	3.00	—	1.80	—	ns
P55	$\overline{\text{WAITA}}$ and $\overline{\text{WAITB}}$ valid to CLKOUT rising edge. ¹ (MIN = 0.00 x B1 + 8.00)	8.00	—	8.00	—	8.00	—	8.00	—	ns
P56	CLKOUT rising edge to $\overline{\text{WAITA}}$ and $\overline{\text{WAITB}}$ invalid. ¹ (MIN = 0.00 x B1 + 2.00)	2.00	—	2.00	—	2.00	—	2.00	—	ns

¹ PSST = 1. Otherwise add PSST times cycle time.
PSHT = 0. Otherwise add PSHT times cycle time.

These synchronous timings define when the $\overline{\text{WAITx}}$ signals are detected in order to freeze (or relieve) the PCMCIA current cycle. The $\overline{\text{WAITx}}$ assertion will be effective only if it is detected 2 cycles before the PSL timer expiration. See PCMCIA Interface in the *MPC862 PowerQUICC User's Manual*.

Figure 27 provides the PCMCIA access cycle timing for the external bus write.

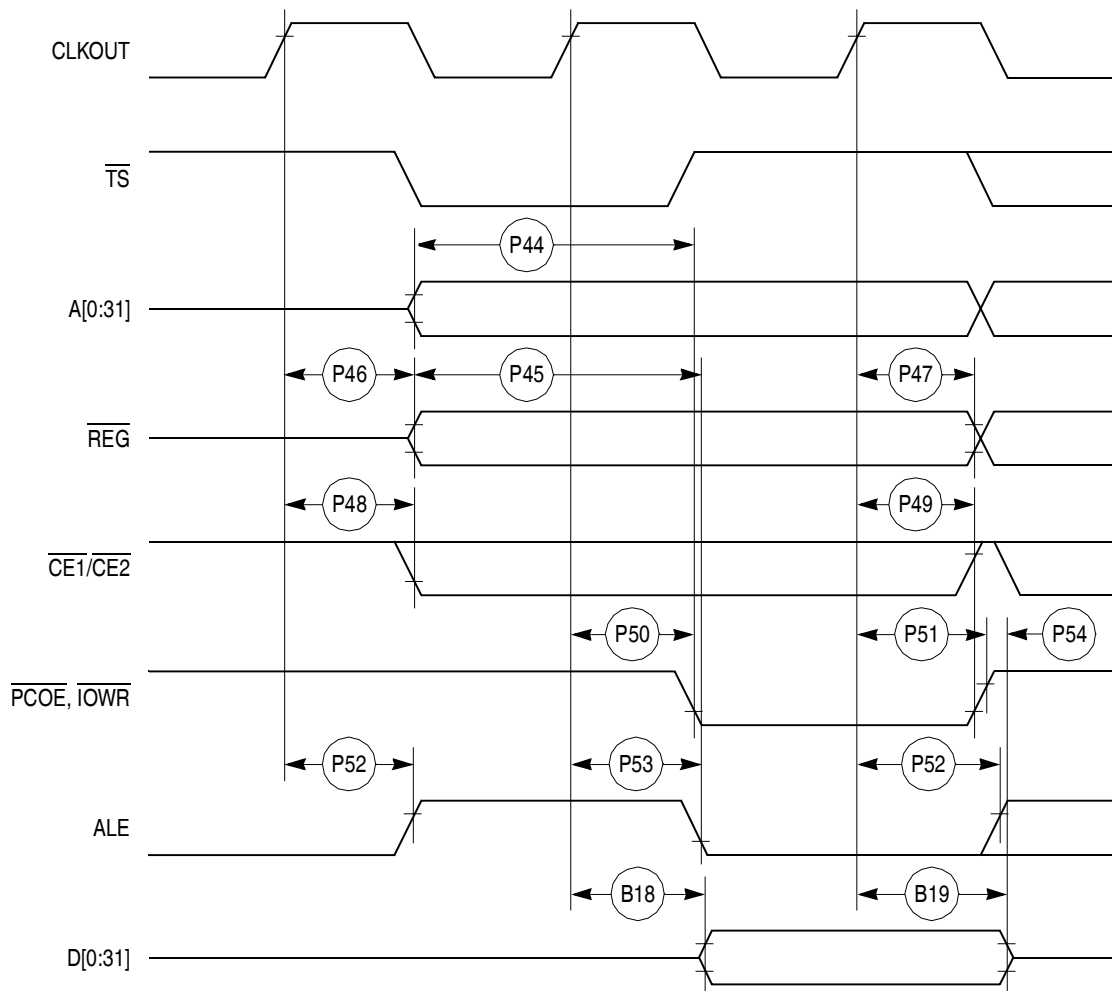


Figure 27. PCMCIA Access Cycles Timing External Bus Write

Figure 28 provides the PCMCIA $\overline{\text{WAIT}}$ signals detection timing.

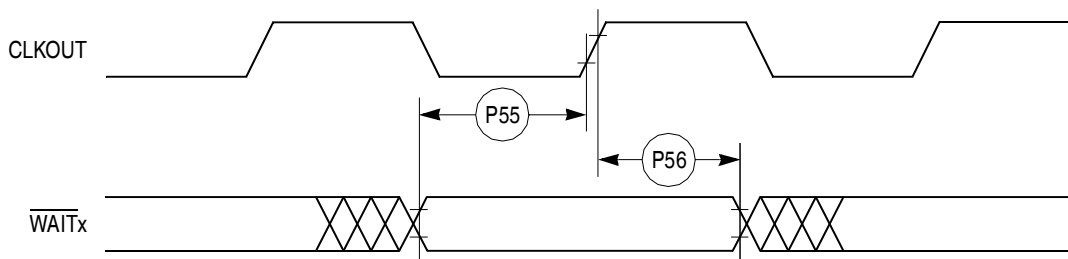


Figure 28. PCMCIA $\overline{\text{WAIT}}$ Signals Detection Timing

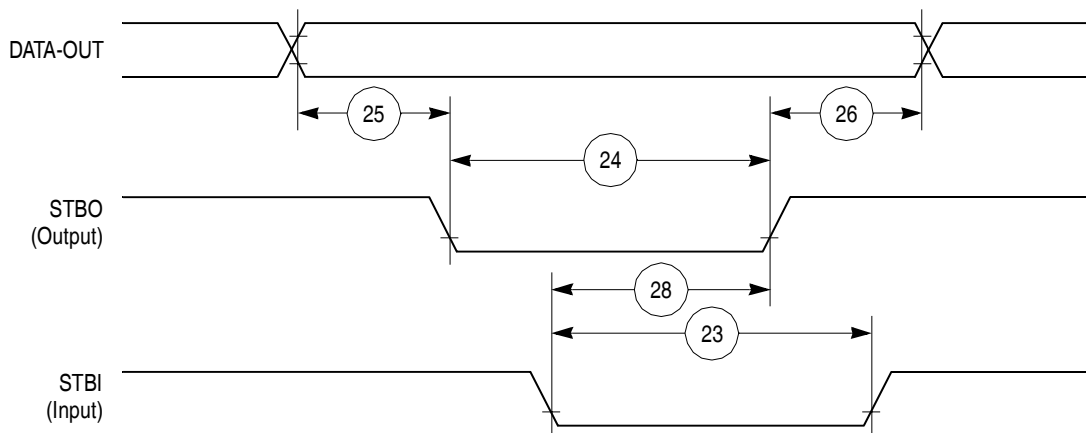


Figure 41. PIP Tx (Interlock Mode) Timing Diagram

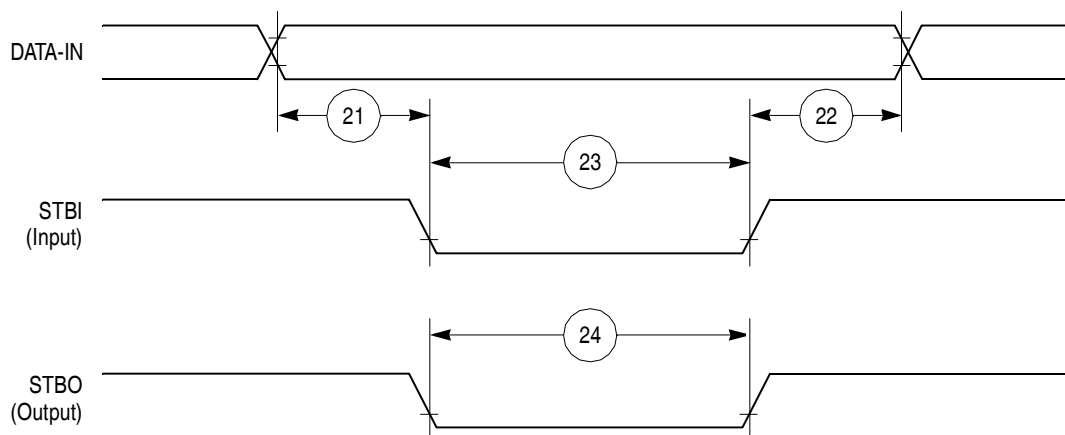


Figure 42. PIP Rx (Pulse Mode) Timing Diagram

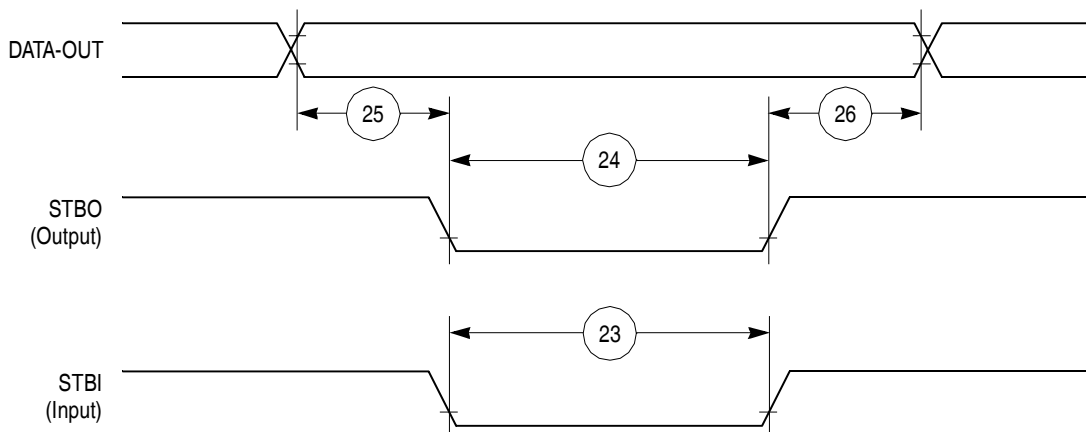


Figure 43. PIP TX (Pulse Mode) Timing Diagram

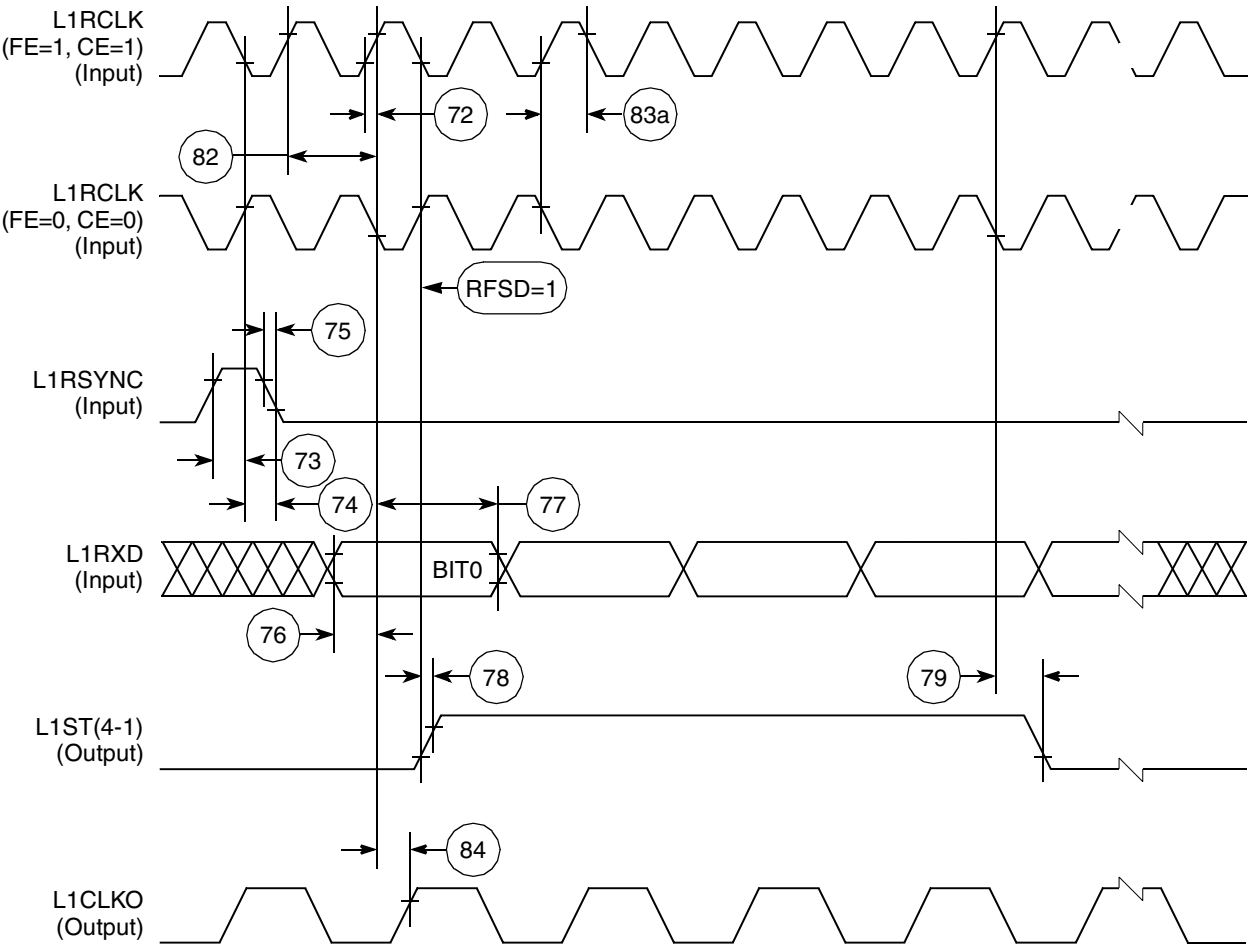


Figure 53. SI Receive Timing with Double-Speed Clocking (DSC = 1)

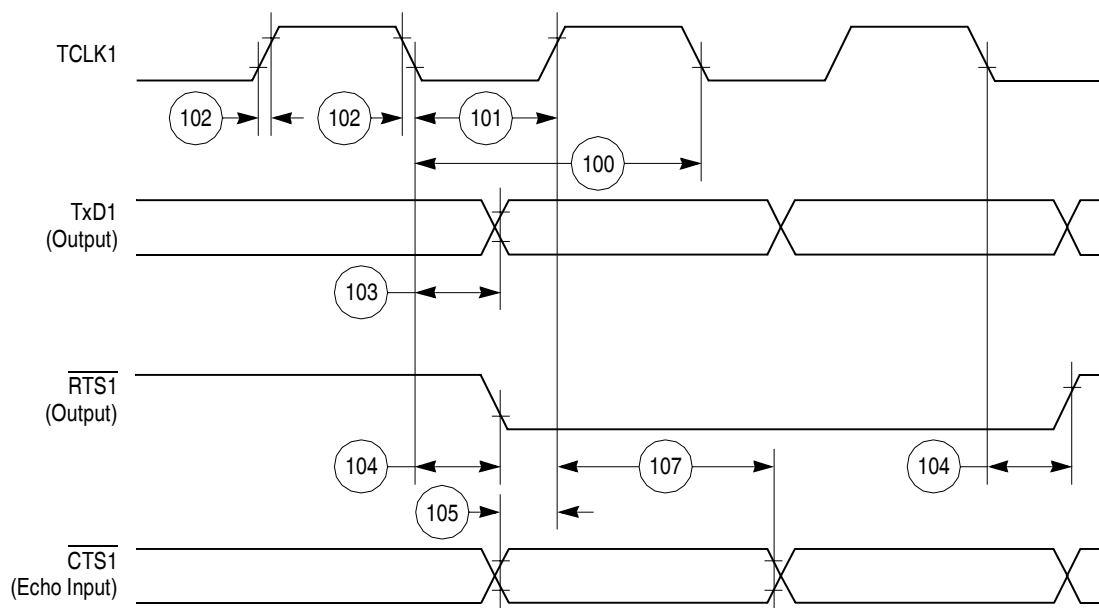


Figure 59. HDLC Bus Timing Diagram

11.8 Ethernet Electrical Specifications

Table 22 provides the Ethernet timings as shown in Figure 60 through Figure 64.

Table 22. Ethernet Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
120	CLSN width high	40	—	ns
121	RCLK1 rise/fall time	—	15	ns
122	RCLK1 width low	40	—	ns
123	RCLK1 clock period ¹	80	120	ns
124	RXD1 setup time	20	—	ns
125	RXD1 hold time	5	—	ns
126	RENA active delay (from RCLK1 rising edge of the last data bit)	10	—	ns
127	RENA width low	100	—	ns
128	TCLK1 rise/fall time	—	15	ns
129	TCLK1 width low	40	—	ns
130	TCLK1 clock period ¹	99	101	ns
131	TXD1 active delay (from TCLK1 rising edge)	10	50	ns
132	TXD1 inactive delay (from TCLK1 rising edge)	10	50	ns
133	TENA active delay (from TCLK1 rising edge)	10	50	ns

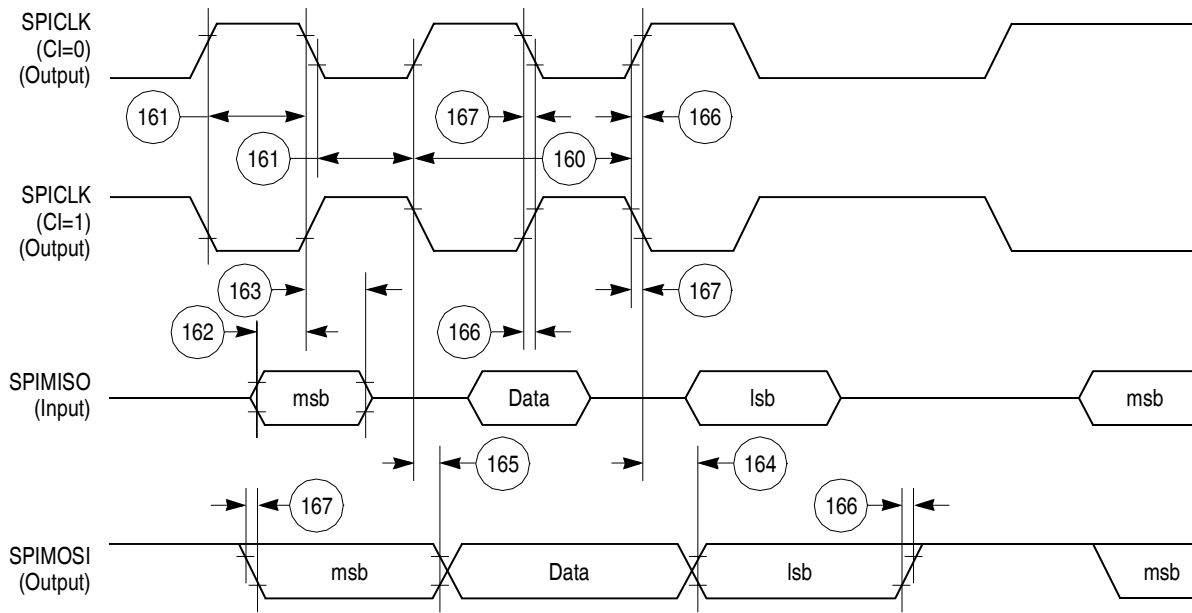


Figure 67. SPI Master (CP = 1) Timing Diagram

11.11 SPI Slave AC Electrical Specifications

Table 25 provides the SPI slave timings as shown in Figure 68 through Figure 69.

Table 25. SPI Slave Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
170	Slave cycle time	2	—	t_{cyc}
171	Slave enable lead time	15	—	ns
172	Slave enable lag time	15	—	ns
173	Slave clock (SPICLK) high or low time	1	—	t_{cyc}
174	Slave sequential transfer delay (does not require deselect)	1	—	t_{cyc}
175	Slave data setup time (inputs)	20	—	ns
176	Slave data hold time (inputs)	20	—	ns
177	Slave access time	—	50	ns

11.12 I²C AC Electrical Specifications

Table 26 provides the I²C (SCL < 100 KHz) timings.

Table 26. I²C Timing (SCL < 100 KHz)

Num	Characteristic	All Frequencies		Unit
		Min	Max	
200	SCL clock frequency (slave)	0	100	kHz
200	SCL clock frequency (master) ¹	1.5	100	kHz
202	Bus free time between transmissions	4.7	—	μs
203	Low period of SCL	4.7	—	μs
204	High period of SCL	4.0	—	μs
205	Start condition setup time	4.7	—	μs
206	Start condition hold time	4.0	—	μs
207	Data hold time	0	—	μs
208	Data setup time	250	—	ns
209	SDL/SCL rise time	—	1	μs
210	SDL/SCL fall time	—	300	ns
211	Stop condition setup time	4.7	—	μs

¹ SCL frequency is given by $SCL = BRGCLK_frequency / ((BRG\ register + 3) * pre_scaler * 2)$.
The ratio $SyncClk/(BRGCLK/pre_scaler)$ must be greater or equal to 4/1.

Table 27 provides the I²C (SCL > 100 kHz) timings.

Table 27. I²C Timing (SCL > 100 kHz)

Num	Characteristic	Expression	All Frequencies		Unit
			Min	Max	
200	SCL clock frequency (slave)	fSCL	0	BRGCLK/48	Hz
200	SCL clock frequency (master) ¹	fSCL	BRGCLK/16512	BRGCLK/48	Hz
202	Bus free time between transmissions	—	$1/(2.2 * fSCL)$	—	s
203	Low period of SCL	—	$1/(2.2 * fSCL)$	—	s
204	High period of SCL	—	$1/(2.2 * fSCL)$	—	s
205	Start condition setup time	—	$1/(2.2 * fSCL)$	—	s
206	Start condition hold time	—	$1/(2.2 * fSCL)$	—	s
207	Data hold time	—	0	—	s
208	Data setup time	—	$1/(40 * fSCL)$	—	s
209	SDL/SCL rise time	—	—	$1/(10 * fSCL)$	s
210	SDL/SCL fall time	—	—	$1/(33 * fSCL)$	s
211	Stop condition setup time	—	$1/2(2.2 * fSCL)$	—	s

¹ SCL frequency is given by $SCL = BrgClk_frequency / ((BRG\ register + 3) * pre_scaler * 2)$.
The ratio $SyncClk/(Brg_Clk/pre_scaler)$ must be greater or equal to 4/1.

Table 32. MII Serial Management Channel Timing

Num	Characteristic	Min	Max	Unit
M10	MII_MDC falling edge to MII_MDIO output invalid (minimum propagation delay)	0	—	ns
M11	MII_MDC falling edge to MII_MDIO output valid (max prop delay)	—	25	ns
M12	MII_MDIO (input) to MII_MDC rising edge setup	10	—	ns
M13	MII_MDIO (input) to MII_MDC rising edge hold	0	—	ns
M14	MII_MDC pulse width high	40%	60%	MII_MDC period
M15	MII_MDC pulse width low	40%	60%	MII_MDC period

Figure 76 shows the MII serial management channel timing diagram.

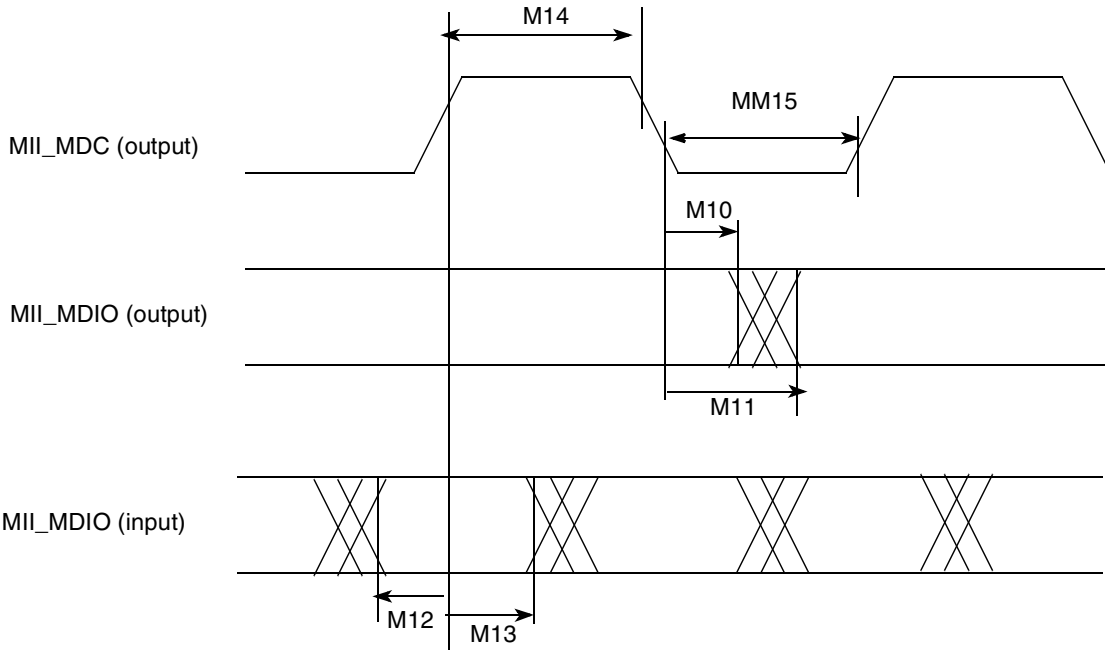


Figure 76. MII Serial Management Channel Timing Diagram

14 Mechanical Data and Ordering Information

Table 33 provides information on the MPC862/857T/857DSL derivative devices.

Table 33. MPC862/857T/857DSL Derivatives

Device	Number of SCCs ¹	Ethernet Support	Multi-Channel HDLC Support	ATM Support	Cache Size	
					Instruction	Data
MPC862T	Four	10/100 Mbps	Yes	Yes	4 Kbytes	4 Kbytes
MPC862P	Four	10/100 Mbps	Yes	Yes	16 Kbytes	8 Kbytes

NOTE: This is the top view of the device.

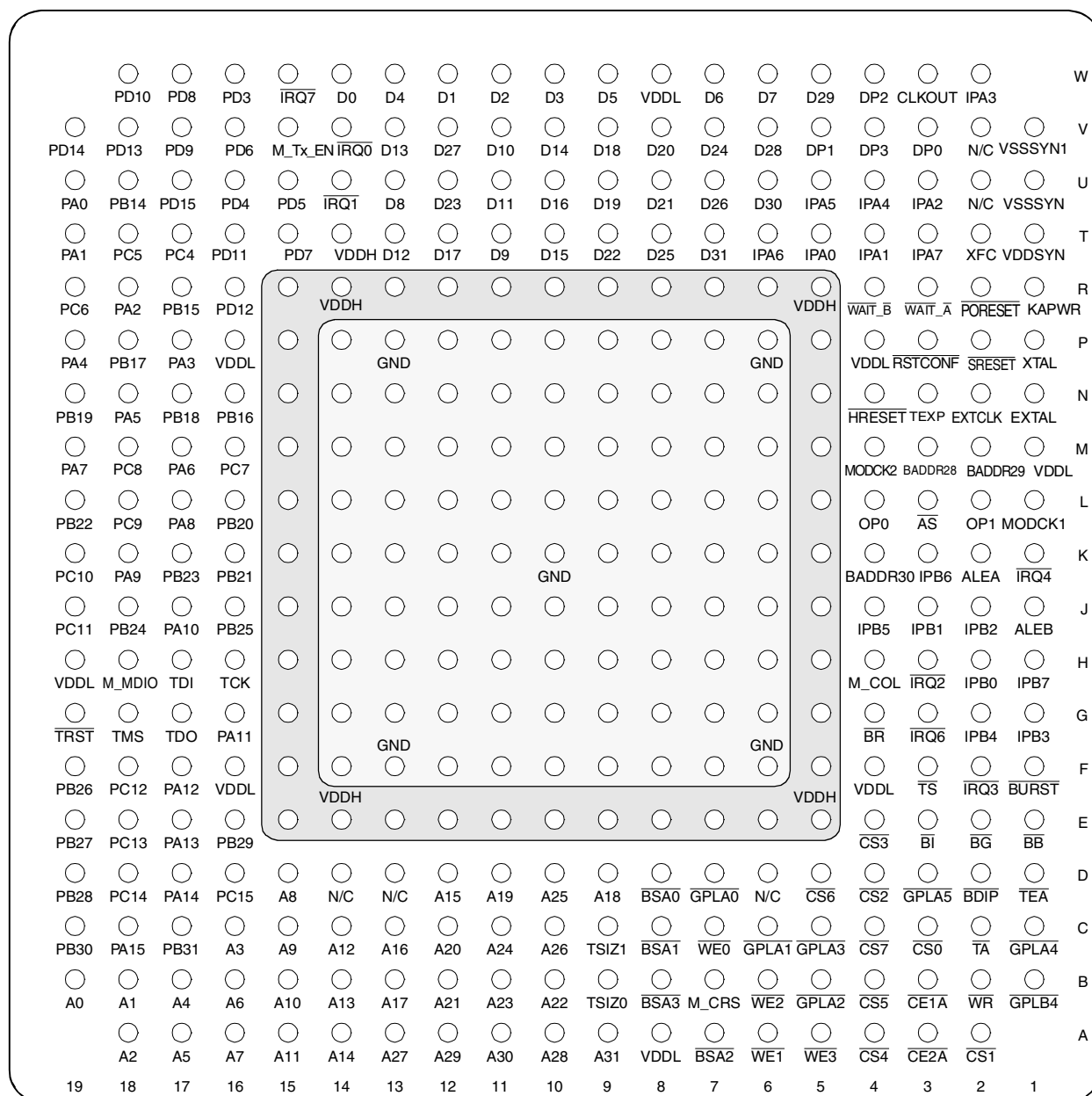


Figure 77. Pinout of the PBGA Package

Table 35 contains a list of the MPC862 input and output signals and shows multiplexing and pin assignments.

Table 35. Pin Assignments

Name	Pin Number	Type
A[0:31]	B19, B18, A18, C16, B17, A17, B16, A16, D15, C15, B15, A15, C14, B14, A14, D12, C13, B13, D9, D11, C12, B12, B10, B11, C11, D10, C10, A13, A10, A12, A11, A9	Bidirectional Three-state
TSIZ0 REG	B9	Bidirectional Three-state
TSIZ1	C9	Bidirectional Three-state
RD/WR	B2	Bidirectional Three-state
BURST	F1	Bidirectional Three-state
BDIP GPL_B5	D2	Output
TS	F3	Bidirectional Active Pull-up
TA	C2	Bidirectional Active Pull-up
TEA	D1	Open-drain
BI	E3	Bidirectional Active Pull-up
IRQ2 RSV	H3	Bidirectional Three-state
IRQ4 KR RETRY SPKROUT	K1	Bidirectional Three-state
CR IRQ3	F2	Input
D[0:31]	W14, W12, W11, W10, W13, W9, W7, W6, U13, T11, V11, U11, T13, V13, V10, T10, U10, T12, V9, U9, V8, U8, T9, U12, V7, T8, U7, V12, V6, W5, U6, T7	Bidirectional Three-state
DP0 IRQ3	V3	Bidirectional Three-state
DP1 IRQ4	V5	Bidirectional Three-state
DP2 IRQ5	W4	Bidirectional Three-state
DP3 IRQ6	V4	Bidirectional Three-state

Table 35. Pin Assignments (continued)

Name	Pin Number	Type
IP_A6 UTPB_Split6 ² MII-TXERR	T6	Input
IP_A7 UTPB_Split7 ² MII-RXDV	T3	Input
ALE_B DSCK/AT1	J1	Bidirectional Three-state
IP_B[0:1] IWP[0:1] VFLS[0:1]	H2, J3	Bidirectional
IP_B2 IOIS16_B AT2	J2	Bidirectional Three-state
IP_B3 IWP2 VF2	G1	Bidirectional
IP_B4 LWP0 VF0	G2	Bidirectional
IP_B5 LWP1 VF1	J4	Bidirectional
IP_B6 DSDI AT0	K3	Bidirectional Three-state
IP_B7 PTR AT3	H1	Bidirectional Three-state
OP0 MII-TXD0 UtpClk_Split ²	L4	Bidirectional
OP1	L2	Output
OP2 MODCK1 STS	L1	Bidirectional
OP3 MODCK2 DSDO	M4	Bidirectional
BADDR30 REG	K4	Output
BADDR[28:29]	M3, M2	Output
AS	L3	Input

Table 35. Pin Assignments (continued)

Name	Pin Number	Type
PC13 L1RQb L1ST3 RTS3	E18	Bidirectional
PC12 L1RQa L1ST4 RTS4	F18	Bidirectional
PC11 CTS1	J19	Bidirectional
PC10 CD1 TGATE1	K19	Bidirectional
PC9 CTS2	L18	Bidirectional
PC8 CD2 TGATE2	M18	Bidirectional
PC7 CTS3 L1TSYNCB SDACK2	M16	Bidirectional
PC6 CD3 L1RSYNCB	R19	Bidirectional
PC5 CTS4 L1TSYNCA SDACK1	T18	Bidirectional
PC4 CD4 L1RSYNCA	T17	Bidirectional
PD15 L1TSYNCA MII-RXD3 UTPB0	U17	Bidirectional
PD14 L1RSYNCA MII-RXD2 UTPB1	V19	Bidirectional
PD13 L1TSYNCB MII-RXD1 UTPB2	V18	Bidirectional

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