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Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, IrDA, LINbus, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, HLVD, POR, PWM, WDT
Number of I/O	85
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj256ga610-i-pt

PIC24FJ1024GA610/GB610 FAMILY

Referenced Sources

This device data sheet is based on the following individual chapters of the “dsPIC33/PIC24 Family Reference Manual”. These documents should be considered as the general reference for the operation of a particular module or device feature.

Note 1: To access the documents listed below, browse to the documentation section of the PIC24FJ1024GA610/GB610 product page of the Microchip web site (www.microchip.com) or select a family reference manual section from the following list.

In addition to parameters, features and other documentation, the resulting page provides links to the related family reference manual sections.

- “CPU with Extended Data Space (EDS)” (DS39732)
- “Data Memory with Extended Data Space (EDS)” (DS39733)
- “Direct Memory Access Controller (DMA)” (DS39742)
- “PIC24F Flash Program Memory” (DS30009715)
- “Reset” (DS39712)
- “Interrupts” (DS70000600)
- “Power-Saving Features” (DS39698)
- “I/O Ports with Peripheral Pin Select (PPS)” (DS39711)
- “Timers” (DS39704)
- “Input Capture with Dedicated Timer” (DS70000352)
- “Output Compare with Dedicated Timer” (DS70005159)
- “Capture/Compare/PWM/Timer (MCCP and SCCP)” (DS33035A)
- “Serial Peripheral Interface (SPI) with Audio Codec Support” (DS70005136)
- “Inter-Integrated Circuit (I²C)” (DS70000195)
- “UART” (DS39708)
- “USB On-The-Go (OTG)” (DS39721)
- “Enhanced Parallel Master Port (EPMP)” (DS39730)
- “RTCC with Timestamp” (DS70005193)
- “RTCC with External Power Control” (DS39745)
- “32-Bit Programmable Cyclic Redundancy Check (CRC)” (DS30009729)
- “12-Bit A/D Converter with Threshold Detect” (DS39739)
- “Scalable Comparator Module” (DS39734)
- “Dual Comparator Module” (DS39710)
- “Charge Time Measurement Unit (CTMU) and CTMU Operation with Threshold Detect” (DS30009743)
- “High-Level Integration with Programmable High/Low-Voltage Detect (HLVD)” (DS39725)
- “Watchdog Timer (WDT)” (DS39697)
- “CodeGuard™ Intermediate Security” (DS70005182)
- “High-Level Device Integration” (DS39719)
- “Programming and Diagnostics” (DS39716)
- “Dual Partition Flash Program Memory” (DS70005156)

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REGISTER 5-1: DMACON: DMA ENGINE CONTROL REGISTER

R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
DMAEN	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	PRSSEL
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15

DMAEN: DMA Module Enable bit

1 = Enables module

0 = Disables module and terminates all active DMA operation(s)

bit 14-1

Unimplemented: Read as '0'

bit 0

PRSSEL: Channel Priority Scheme Selection bit

1 = Round-robin scheme

0 = Fixed priority scheme

6.6.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

The user can program one row of Flash program memory at a time. To do this, it is necessary to erase the 8-row erase block containing the desired row. The general process is:

1. Read eight rows of program memory (1024 instructions) and store in data RAM.
2. Update the program data in RAM with the desired new data.
3. Erase the block (see Example 6-1):
 - a) Set the NVMOP<3:0> bits (NVMCON<3:0>) to '0011' to configure for block erase. Set the WREN (NVMCON<14>) bit.
 - b) Write the starting address of the block to be erased into the NVMADRU/NVMADR registers.
 - c) Write 55h to NVMKEY.
 - d) Write AAh to NVMKEY.
 - e) Set the WR bit (NVMCON<15>). The erase cycle begins and the CPU stalls for the duration of the erase cycle. When the erase is done, the WR bit is cleared automatically.
4. Update the TBLPAG register to point to the programming latches on the device. Update the NVMADRU/NVMADR registers to point to the destination in the program memory.

5. Write the first 128 instructions from data RAM into the program memory buffers (see Table 6-1).
6. Write the program block to Flash memory:
 - a) Set the NVMOPx bits to '0010' to configure for row programming. Set the WREN bit.
 - b) Write 55h to NVMKEY.
 - c) Write AAh to NVMKEY.
 - d) Set the WR bit. The programming cycle begins and the CPU stalls for the duration of the write cycle. When the write to Flash memory is done, the WR bit is cleared automatically.
7. Repeat Steps 4 through 6 using the next available 128 instructions from the block in data RAM, by incrementing the value in NVMADRU/NVMADR, until all 1024 instructions are written back to Flash memory.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPs, as shown in Example 6-2.

TABLE 6-1: EXAMPLE PAGE ERASE

Step 1: Set the NVMCON register to erase a page.	
MOV	#0x4003, W0
MOV	W0, NVMCON
Step 2: Load the address of the page to be erased into the NVMADR register pair.	
MOV	#PAGE_ADDR_LO, W0
MOV	W0, NVMADR
MOV	#PAGE_ADDR_HI, W0
MOV	W0, NVMADRU
Step 3: Set the WR bit.	
MOV	#0x55, W0
MOV	W0, NVMKEY
MOV	#0xAA, W0
MOV	W0, NVMKEY
BSET	NVMCON, #WR
NOP	
NOP	
NOP	

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REGISTER 8-2: CORCON: CPU CORE CONTROL REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/C-0	R/W-1	U-0	U-0
—	—	—	—	IPL3 ⁽²⁾	PSV	—	—
bit 7							bit 0

Legend:	C = Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-4 **Unimplemented:** Read as '0'
- bit 3 **IPL3:** CPU Interrupt Priority Level Status bit⁽²⁾
 1 = CPU Interrupt Priority Level is greater than 7
 0 = CPU Interrupt Priority Level is 7 or less
- bit 2 **PSV:** Not used as part of the interrupt module
- bit 1-0 **Unimplemented:** Read as '0'

- Note 1:** For complete register details, see Register 3-2.
- 2:** The IPL<2:0> Status bits are concatenated with the IPL3 Status bit (CORCON<3>) to form the CPU Interrupt Priority Level (IPL). The value in parentheses indicates the IPL when IPL3 = 1. User interrupts are disabled when IPL3 = 1.

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11.1.1 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically, this instruction would be a NOP.

11.1.2 OPEN-DRAIN CONFIGURATION

In addition to the PORTx, LATx and TRISx registers for data control, each port pin can also be individually configured for either a digital or open-drain output. This is controlled by the Open-Drain Control register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs higher than VDD (e.g., 5V) on any desired digital only pins by using external pull-up resistors. The maximum open-drain voltage allowed is the same as the maximum VIH specification.

11.2 Configuring Analog Port Pins (ANSx)

The ANSx and TRISx registers control the operation of the pins with analog function. Each port pin with analog function is associated with one of the ANSx bits (see Register 11-1 through Register 11-6), which decides if the pin function should be analog or digital. Refer to Table 11-1 for detailed behavior of the pin for different ANSx and TRISx bit settings.

When reading the PORTx register, all pins configured as analog input channels will read as cleared (a low level).

11.2.1 ANALOG INPUT PINS AND VOLTAGE CONSIDERATIONS

The voltage tolerance of pins used as device inputs is dependent on the pin's input function. Most input pins are able to handle DC voltages of up to 5.5V, a level typical for digital logic circuits. However, several pins can only tolerate voltages up to VDD. Voltage excursions beyond VDD on these pins should always be avoided.

Table 11-2 summarizes the different voltage tolerances. For more information, refer to **Section 33.0 "Electrical Characteristics"** for more details.

TABLE 11-1: CONFIGURING ANALOG/DIGITAL FUNCTION OF AN I/O PIN

Pin Function	ANSx Setting	TRISx Setting	Comments
Analog Input	1	1	It is recommended to keep ANSx = 1.
Analog Output	1	1	It is recommended to keep ANSx = 1.
Digital Input	0	1	Firmware must wait at least one instruction cycle after configuring a pin as a digital input before a valid input value can be read.
Digital Output	0	0	Make sure to disable the analog output function on the pin if any is present.

TABLE 11-2: INPUT VOLTAGE LEVELS FOR PORT OR PIN TOLERATED DESCRIPTION INPUT

Port or Pin	Tolerated Input	Description
PORTA<15:14,5:0>	5.5V	Tolerates input levels above VDD; useful for most standard logic.
PORTC<3:1>		
PORTD<15:8,5:0>		
PORTE<8:5,3:0>		
PORTF<13:12,8:0>		
PORTG<15:12,1:0>		
PORTA<10:9,7:6>	VDD	Only VDD input levels are tolerated.
PORTB<15:0>		
PORTC<15:13,4> ⁽¹⁾		
PORTD<7:6>		
PORTE<9,4>		
PORTG<9:6,3:2> ⁽²⁾		

Note 1: PORTC<12> has OSCI pin function.

2: PORTG<3:2> have USB function on PIC24FJXXXXGBXXX devices.

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REGISTER 11-40: RPOR4: PERIPHERAL PIN SELECT OUTPUT REGISTER 4

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP9R5	RP9R4	RP9R3	RP9R2	RP9R1	RP9R0
bit 15						bit 8	

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP8R5	RP8R4	RP8R3	RP8R2	RP8R1	RP8R0
bit 7						bit 0	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP9R<5:0>:** RP9 Output Pin Mapping bits

Peripheral Output Number n is assigned to pin, RP9 (see Table 11-4 for peripheral function numbers).

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP8R<5:0>:** RP8 Output Pin Mapping bits

Peripheral Output Number n is assigned to pin, RP8 (see Table 11-4 for peripheral function numbers).

REGISTER 11-41: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP11R5	RP11R4	RP11R3	RP11R2	RP11R1	RP11R0
bit 15						bit 8	

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP10R5	RP10R4	RP10R3	RP10R2	RP10R1	RP10R0
bit 7						bit 0	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP11R<5:0>:** RP11 Output Pin Mapping bits

Peripheral Output Number n is assigned to pin, RP11 (see Table 11-4 for peripheral function numbers).

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP10R<5:0>:** RP10 Output Pin Mapping bits

Peripheral Output Number n is assigned to pin, RP10 (see Table 11-4 for peripheral function numbers).

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NOTES:

16.0 CAPTURE/COMPARE/PWM/TIMER MODULES (MCCP AND SCCP)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information on the MCCP/SCCP modules, refer to the “dsPIC33/PIC24 Family Reference Manual”, “**Capture/Compare/PWM/Timer (MCCP and SCCP)**” (DS33035A), which is available from the Microchip web site (www.microchip.com). The information in this data sheet supersedes the information in the FRM.

PIC24FJ1024GA610/GB610 family devices include several Capture/Compare/PWM/Timer base modules, which provide the functionality of three different peripherals of earlier PIC24F devices. The module can operate in one of three major modes:

- General Purpose Timer
- Input Capture
- Output Compare/PWM

The module is provided in two different forms, distinguished by the number of PWM outputs that the module can generate. Single Capture/Compare/PWM (SCCPs) output modules provide only one PWM output. Multiple Capture/Compare/PWM (MCCPs) output modules can provide up to six outputs and an extended range of power control features, depending on the pin count of the particular device. All other features of the modules are identical.

The SCCPx and MCCPx modules can be operated only in one of the three major modes at any time. The other modes are not available unless the module is reconfigured for the new mode.

A conceptual block diagram for the module is shown in Figure 16-1. All three modules share a time base generator and a common Timer register pair (CCPxTMRH/L); other shared hardware components are added as a particular mode requires.

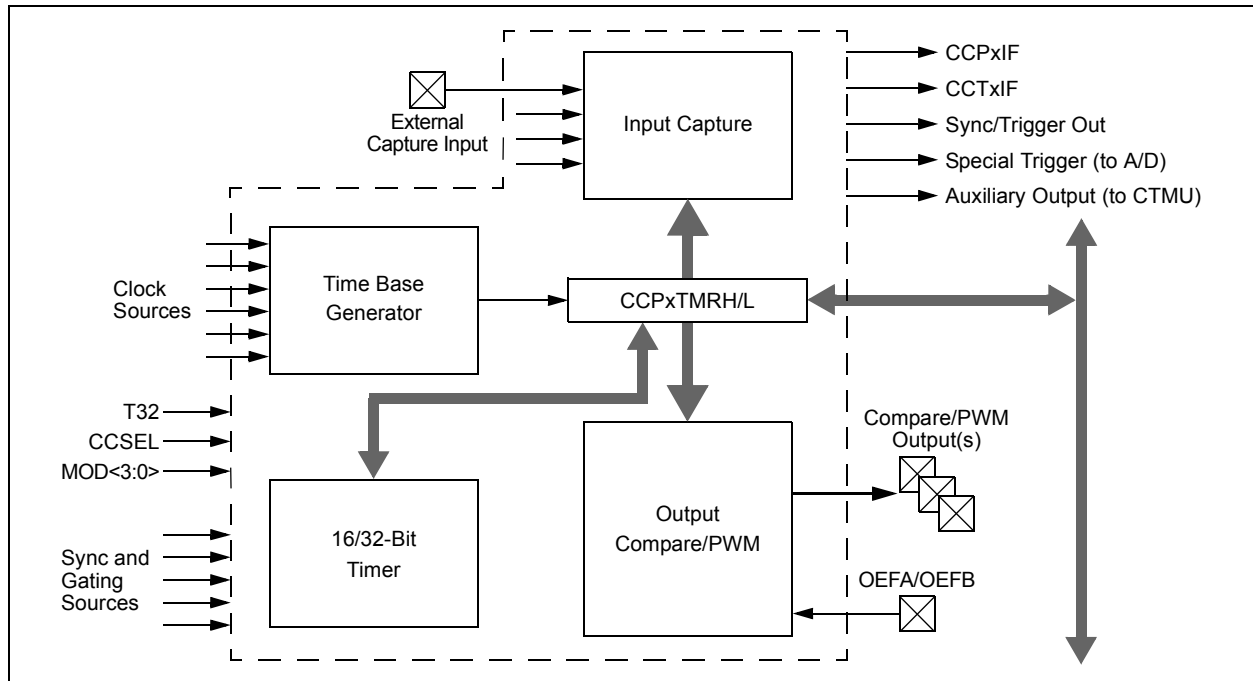
Each module has a total of 8 control and status registers:

- CCPxCON1L (Register 16-1)
- CCPxCON1H (Register 16-2)
- CCPxCON2L (Register 16-3)
- CCPxCON2H (Register 16-4)
- CCPxCON3L (Register 16-5)
- CCPxCON3H (Register 16-6)
- CCPxSTATL (Register 16-7)
- CCPxSTATH (Register 16-8)

Each module also includes 8 buffer/counter registers that serve as Timer Value registers or data holding buffers:

- CCPxTMRH/CCPxTMRL (Timer High/Low Counters)
- CCPxPRH/CCPxPRL (Timer Period High/Low)
- CCPxRA (Primary Output Compare Data Buffer)
- CCPxRB (Secondary Output Compare Data Buffer)
- CCPxBUFH/CCPxBUFL (Input Capture High/Low Buffers)

FIGURE 16-1: MCCPx/SCCPx CONCEPTUAL BLOCK DIAGRAM



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REGISTER 17-2: SPIxCON1H: SPIx CONTROL REGISTER 1 HIGH

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
AUDEN ⁽¹⁾	SPIGNEXT	IGNROV	IGNTUR	AUDMONO ⁽²⁾	URDTEN ⁽³⁾	AUDMOD1 ⁽⁴⁾	AUDMOD0 ⁽⁴⁾
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FRMEN	FRMSYNC	FRMPOL	MSEN	FRMSYPW	FRMCNT2	FRMCNT1	FRMCNT0
bit 7						bit 0	

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15 **AUDEN:** Audio Codec Support Enable bit⁽¹⁾
1 = Audio protocol is enabled; MSTEN controls the direction of both the SCKx and Frame (a.k.a. LRC), and this module functions as if FRMEN = 1, FRMSYNC = MSTEN, FRMCNT<2:0> = 001 and SMP = 0, regardless of their actual values
0 = Audio protocol is disabled
- bit 14 **SPIGNEXT:** SPIx Sign-Extend RX FIFO Read Data Enable bit
1 = Data from RX FIFO is sign-extended
0 = Data from RX FIFO is not sign-extended
- bit 13 **IGNROV:** Ignore Receive Overflow bit
1 = A Receive Overflow (ROV) is NOT a critical error; during ROV, data in the FIFO is not overwritten by the receive data
0 = A ROV is a critical error that stops SPI operation
- bit 12 **IGNTUR:** Ignore Transmit Underrun bit
1 = A Transmit Underrun (TUR) is NOT a critical error and data indicated by URDTEN is transmitted until the SPIxTXB is not empty
0 = A TUR is a critical error that stops SPI operation
- bit 11 **AUDMONO:** Audio Data Format Transmit bit⁽²⁾
1 = Audio data is mono (i.e., each data word is transmitted on both left and right channels)
0 = Audio data is stereo
- bit 10 **URDTEN:** Transmit Underrun Data Enable bit⁽³⁾
1 = Transmits data out of SPIxURDTL/H register during Transmit Underrun conditions
0 = Transmits the last received data during Transmit Underrun conditions
- bit 9-8 **AUDMOD<1:0>:** Audio Protocol Mode Selection bits⁽⁴⁾
11 = PCM/DSP mode
10 = Right Justified mode: This module functions as if SPIFE = 1, regardless of its actual value
01 = Left Justified mode: This module functions as if SPIFE = 1, regardless of its actual value
00 = I²S mode: This module functions as if SPIFE = 0, regardless of its actual value
- bit 7 **FRMEN:** Framed SPIx Support bit
1 = Framed SPIx support is enabled ($\overline{SSx}$ pin is used as the FSYNC input/output)
0 = Framed SPIx support is disabled

- Note 1:** AUDEN can only be written when the SPIEN bit = 0.
Note 2: AUDMONO can only be written when the SPIEN bit = 0 and is only valid for AUDEN = 1.
Note 3: URDTEN is only valid when IGNTUR = 1.
Note 4: AUDMOD<1:0> bits can only be written when the SPIEN bit = 0 and are only valid when AUDEN = 1. When NOT in PCM/DSP mode, this module functions as if FRMSYPW = 1, regardless of its actual value.

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REGISTER 20-4: U1OTGCON: USB ON-THE-GO CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	r-0	R/W-0	r-0	R/W-0
DPPULUP	DMPULUP	DPPULDWN ⁽¹⁾	DMPULDWN ⁽¹⁾	—	OTGEN ⁽¹⁾	—	VBUSDIS ⁽¹⁾
bit 7							bit 0

Legend:	r = Reserved bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	'0' = Bit is cleared
-n = Value at POR	'1' = Bit is set	x = Bit is unknown

bit 15-8	Unimplemented: Read as '0'
bit 7	DPPULUP: D+ Pull-up Enable bit 1 = D+ data line pull-up resistor is enabled 0 = D+ data line pull-up resistor is disabled
bit 6	DMPULUP: D- Pull-up Enable bit 1 = D- data line pull-up resistor is enabled 0 = D- data line pull-up resistor is disabled
bit 5	DPPULDWN: D+ Pull-Down Enable bit ⁽¹⁾ 1 = D+ data line pull-down resistor is enabled 0 = D+ data line pull-down resistor is disabled
bit 4	DMPULDWN: D- Pull-Down Enable bit ⁽¹⁾ 1 = D- data line pull-down resistor is enabled 0 = D- data line pull-down resistor is disabled
bit 3	Reserved: Maintain as '0'
bit 2	OTGEN: OTG Features Enable bit ⁽¹⁾ 1 = USB OTG is enabled; all D+/D- pull-up and pull-down bits are enabled 0 = USB OTG is disabled; D+/D- pull-up and pull-down bits are controlled in hardware by the settings of the HOSTEN and USBEN (U1CON<3,0>) bits
bit 1	Reserved: Maintain as '0'
bit 0	VBUSDIS: VBUS Discharge Enable bit ⁽¹⁾ 1 = VBUS line is discharged through a resistor 0 = VBUS line is not discharged

Note 1: These bits are only used in Host mode; do not use in Device mode.

21.0 ENHANCED PARALLEL MASTER PORT (EPMP)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “dsPIC33/PIC24 Family Reference Manual”, “Enhanced Parallel Master Port (EPMP)” (DS39730), which is available from the Microchip web site (www.microchip.com). The information in this data sheet supersedes the information in the FRM.

The Enhanced Parallel Master Port (EPMP) module provides a parallel, 4-bit (Master mode only), 8-bit (Master and Slave modes) or 16-bit (Master mode only) data bus interface to communicate with off-chip modules, such as memories, FIFOs, LCD controllers and other micro-controllers. This module can serve as either the master or the slave on the communication bus.

For EPMP Master modes, all external addresses are mapped into the internal Extended Data Space (EDS). This is done by allocating a region of the EDS for each Chip Select, and then assigning each Chip Select to a particular external resource, such as a memory or external controller. This region should not be assigned to another device resource, such as RAM or SFRs. To perform a write or read on an external resource, the CPU simply performs a write or read within the address range assigned for the EPMP.

Key features of the EPMP module are:

- Extended Data Space (EDS) Interface Allows Direct Access from the CPU
- Up to 23 Programmable Address Lines
- Up to 2 Chip Select lines
- Up to 2 Acknowledgment Lines (one per Chip Select)
- 4-Bit, 8-Bit or 16-Bit Wide Data Bus
- Programmable Strobe Options (per Chip Select):
 - Individual read and write strobes or;
 - Read/Write strobe with enable strobe
- Programmable Address/Data Multiplexing
- Programmable Address Wait States

- Programmable Data Wait States (per Chip Select)
- Programmable Polarity on Control Signals (per Chip Select)
- Legacy Parallel Slave Port Support
- Enhanced Parallel Slave Support:
 - Address support
 - 4-byte deep auto-incrementing buffer

21.1 Specific Package Variations

While all PIC24FJ1024GA610/GB610 family devices implement the EPMP, I/O pin constraints place some limits on 16-Bit Master mode operations in some package types. This is reflected in the number of dedicated Chip Select pins implemented and the number of dedicated address lines that are available. The differences are summarized in Table 21-1. All available EPMP pin functions are summarized in Table 21-2.

For 64-pin devices, the dedicated Chip Select pins (PMCS1 and PMCS2) are not implemented. In addition, only 16 address lines (PMA<15:0>) are available. If required, PMA14 and PMA15 can be remapped to function as PMCS1 and PMCS2, respectively.

The memory space addressable by the device depends on the number of address lines available, as well as the number of Chip Select signals required for the application. Devices with lower pin counts are more affected by Chip Select requirements, as these take away address lines. Table 21-1 shows the maximum addressable range for each pin count.

21.2 PMDOUT1 and PMDOUT2 Registers

The EPMP Data Output 1 and Data Output 2 registers are used only in Slave mode for buffered output data. These registers act as a buffer for outgoing data.

21.3 PMDIN1 and PMDIN2 Registers

The EPMP Data Input 1 and Data Input 2 registers are used in Slave modes to buffer incoming data. These registers hold data that is asynchronously clocked in.

In Master mode, PMDIN1 is the holding register for incoming data.

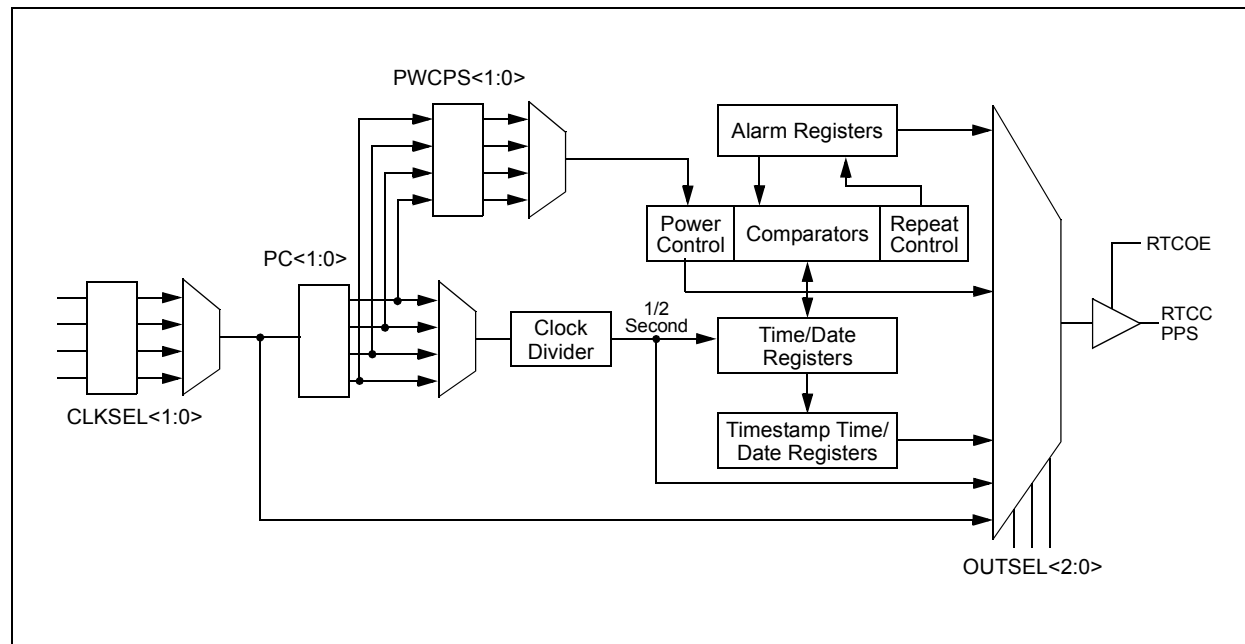
TABLE 21-1: EPMP FEATURE DIFFERENCES BY DEVICE PIN COUNT

Device	Dedicated Chip Select		Address Lines	Data Lines	Address Range (bytes)		
	CS1	CS2			No CS	1 CS ⁽¹⁾	2 CS ⁽¹⁾
PIC24FJXXXGX606 (64-Pin)	—	—	16	8	64K	32K	16K
PIC24FJXXXGX610 (100-Pin/121-Pin)	X	X	23	16	16M		

Note 1: PMA14 and PMA15 can be remapped to be dedicated Chip Selects.

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FIGURE 22-1: RTCC BLOCK DIAGRAM

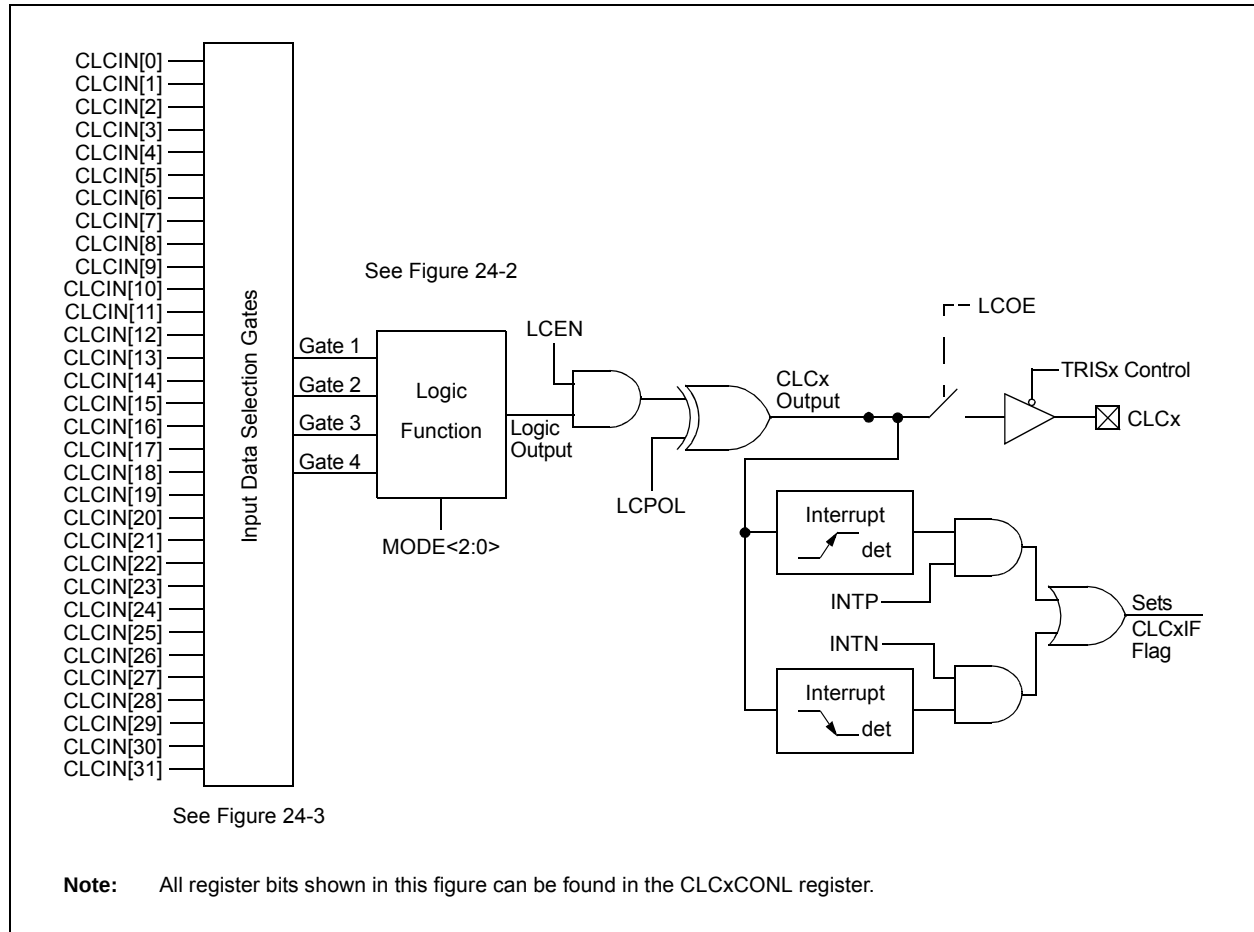


24.0 CONFIGURABLE LOGIC CELL (CLC)

The Configurable Logic Cell (CLC) module allows the user to specify combinations of signals as inputs to a logic function and to use the logic output to control other peripherals or I/O pins. This provides greater flexibility and potential in embedded designs, since the CLC module can operate outside the limitations of software execution and supports a vast amount of output designs.

There are four input gates to the selected logic function. These four input gates select from a pool of up to 32 signals that are selected using four data source selection multiplexers. Figure 24-1 shows an overview of the module. Figure 24-3 shows the details of the data source multiplexers and logic input gate connections.

FIGURE 24-1: CLCx MODULE



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REGISTER 25-4: AD1CON4: A/D CONTROL REGISTER 4

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	DMABL<2:0> ⁽¹⁾		
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3 **Unimplemented:** Read as '0'

bit 2-0 **DMABL<2:0>:** DMA Buffer Size Select bits⁽¹⁾

111 = Allocates 128 words of buffer to each analog input

110 = Allocates 64 words of buffer to each analog input

101 = Allocates 32 words of buffer to each analog input

100 = Allocates 16 words of buffer to each analog input

011 = Allocates 8 words of buffer to each analog input

010 = Allocates 4 words of buffer to each analog input

001 = Allocates 2 words of buffer to each analog input

000 = Allocates 1 word of buffer to each analog input

Note 1: The DMABL<2:0> bits are only used when AD1CON1<11> = 1 and AD1CON1<12> = 0; otherwise, their value is ignored.

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REGISTER 25-6: AD1CHS: A/D SAMPLE SELECT REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NB2	CH0NB1	CH0NB0	CH0SB4	CH0SB3	CH0SB2	CH0SB1	CH0SB0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NA2	CH0NA1	CH0NA0	CH0SA4	CH0SA3	CH0SA2	CH0SA1	CH0SA0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **CH0NB<2:0>**: Sample B Channel 0 Negative Input Select bits

1xx = Unimplemented

01x = Unimplemented

001 = Unimplemented

000 = AVss

bit 12-8 **CH0SB<4:0>**: Sample B Channel 0 Positive Input Select bits

11110 = AVDD⁽¹⁾

11101 = AVSS⁽¹⁾

11100 = Band Gap Reference (V_{BG})⁽¹⁾

11011 = Reserved

11010 = Reserved

11001 = No channels connected (used for CTMU)

11000 = No channels connected (used for CTMU temperature sensor)

10111 = AN23

10110 = AN22

10101 = AN21

10100 = AN20

10011 = AN19

10010 = AN18

10001 = AN17

10000 = AN16

01111 = AN15

01110 = AN14

01101 = AN13

01100 = AN12

01011 = AN11

01010 = AN10

01001 = AN9

01000 = AN8

00111 = AN7

00110 = AN6

00101 = AN5

00100 = AN4

00011 = AN3

00010 = AN2

00001 = AN1

00000 = AN0

bit 7-5 **CH0NA<2:0>**: Sample A Channel 0 Negative Input Select bits

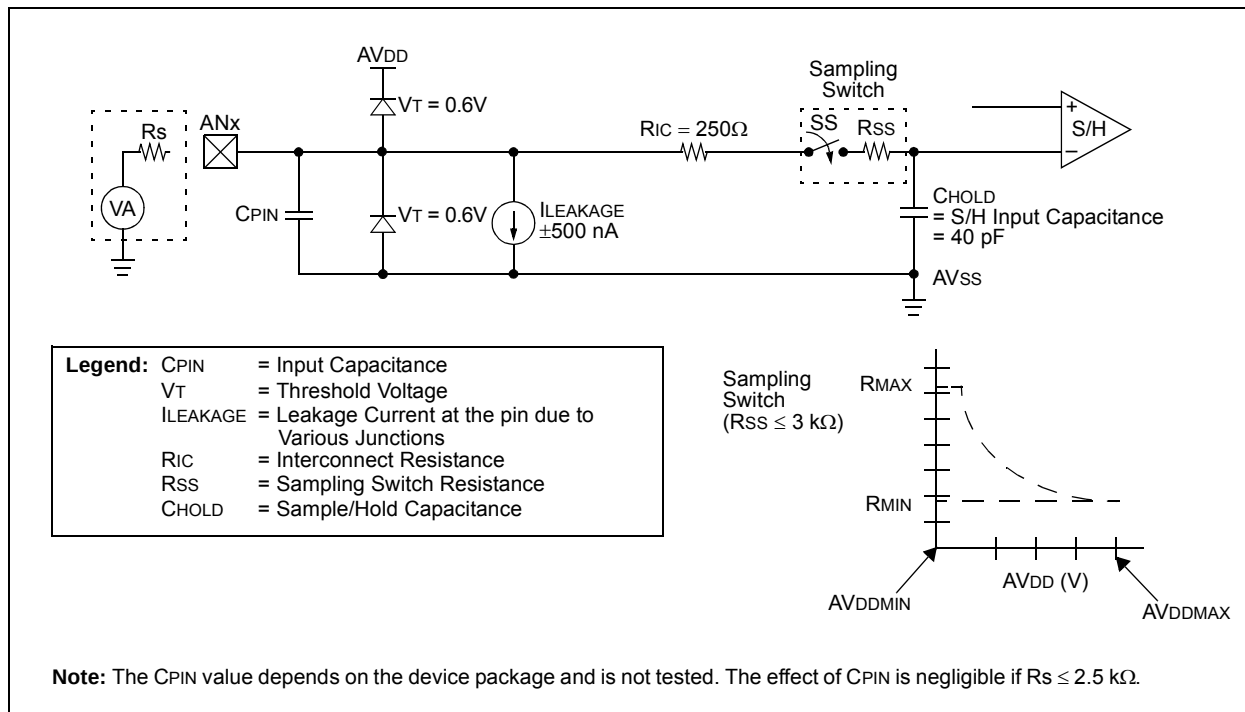
Same definitions as for CH0NB<2:0>.

bit 4-0 **CH0SA<4:0>**: Sample A Channel 0 Positive Input Select bits

Same definitions as for CH0SB<4:0>.

Note 1: These input channels do not have corresponding memory-mapped result buffers.

FIGURE 25-3: 12-BIT A/D CONVERTER ANALOG INPUT MODEL



EQUATION 25-1: A/D CONVERSION CLOCK PERIOD

$$T_{AD} = T_{CY} (ADCS + 1)$$

$$ADCS = \frac{T_{AD}}{T_{CY}} - 1$$

Note: Based on $T_{CY} = 2/F_{OSC}$; Doze mode and PLL are disabled.

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28.4 Measuring Die Temperature

The CTMU can be configured to use the A/D to measure the die temperature using dedicated A/D Channel 24. Perform the following steps to measure the diode voltage:

- The internal current source must be set for either 5.5 μA (IRNG<1:0> = 0x2) or 55 μA (IRNG<1:0> = 0x3).
- In order to route the current source to the diode, the EDG1STAT and EDG2STAT bits must be equal (either both '0' or both '1').
- The CTMREQ bit (AD1CON5<13>) must be set to '1'.
- The A/D Channel Select bits must be 24 (0x18) using a single-ended measurement.

The voltage of the diode will vary over temperature according to the graphs shown below (Figure 28-4). Note that the graphs are different, based on the magnitude of

the current source selected. The slopes are nearly linear over the range of -40°C to +100°C and the temperature can be calculated as follows:

EQUATION 28-2:

For 5.5 μA Current Source:

$$T_{die} = \frac{710 \text{ mV} - V_{diode}}{1.8}$$

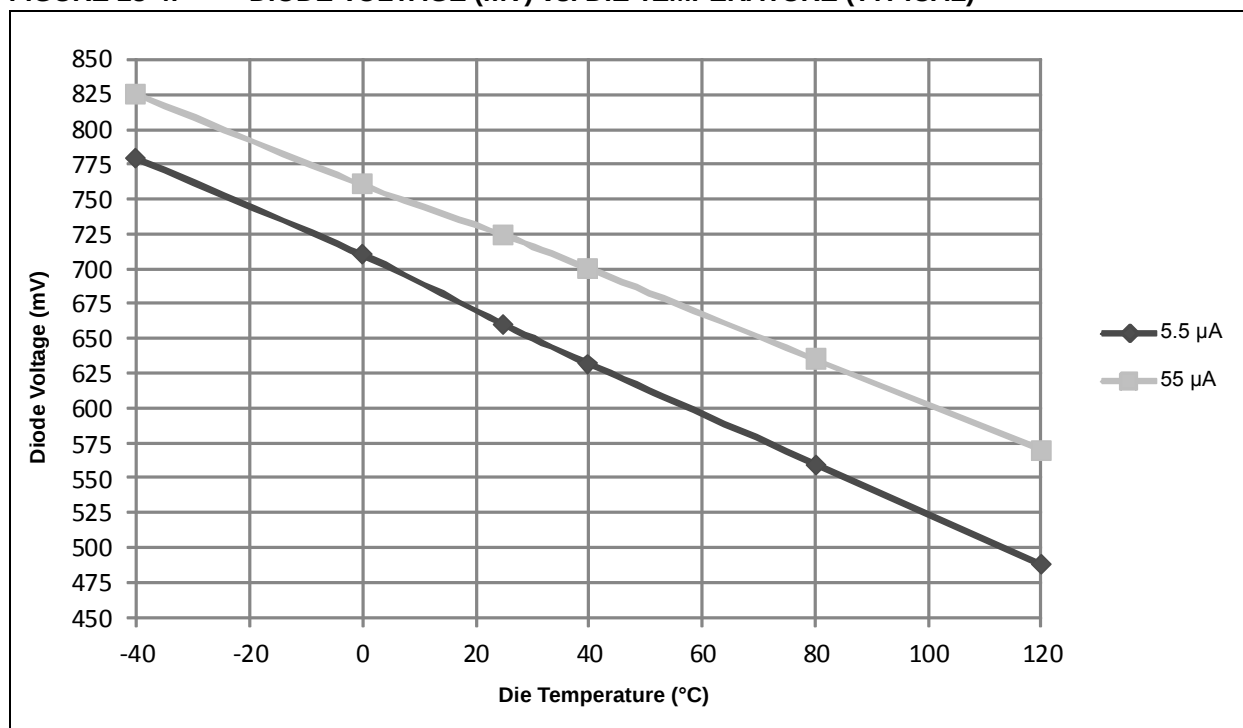
where V_{diode} is in mV, T_{die} is in °C

For 55 μA Current Source:

$$T_{die} = \frac{760 \text{ mV} - V_{diode}}{1.55}$$

where V_{diode} is in mV, T_{die} is in °C

FIGURE 28-4: DIODE VOLTAGE (mV) vs. DIE TEMPERATURE (TYPICAL)



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REGISTER 30-8: FWDT CONFIGURATION REGISTER (CONTINUED)

bit 3-0 **WDTPS<3:0>**: Watchdog Timer Postscale Select bits

1111 = 1:32,768

1110 = 1:16,384

1101 = 1:8,192

1100 = 1:4,096

1011 = 1:2,048

1010 = 1:1,024

1001 = 1:512

1000 = 1:256

0111 = 1:128

0110 = 1:64

0101 = 1:32

0100 = 1:16

0011 = 1:8

0010 = 1:4

0001 = 1:2

0000 = 1:1

31.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16, and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

31.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

31.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

31.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

FIGURE 33-7: INL vs. CODE (12-BIT MODE)

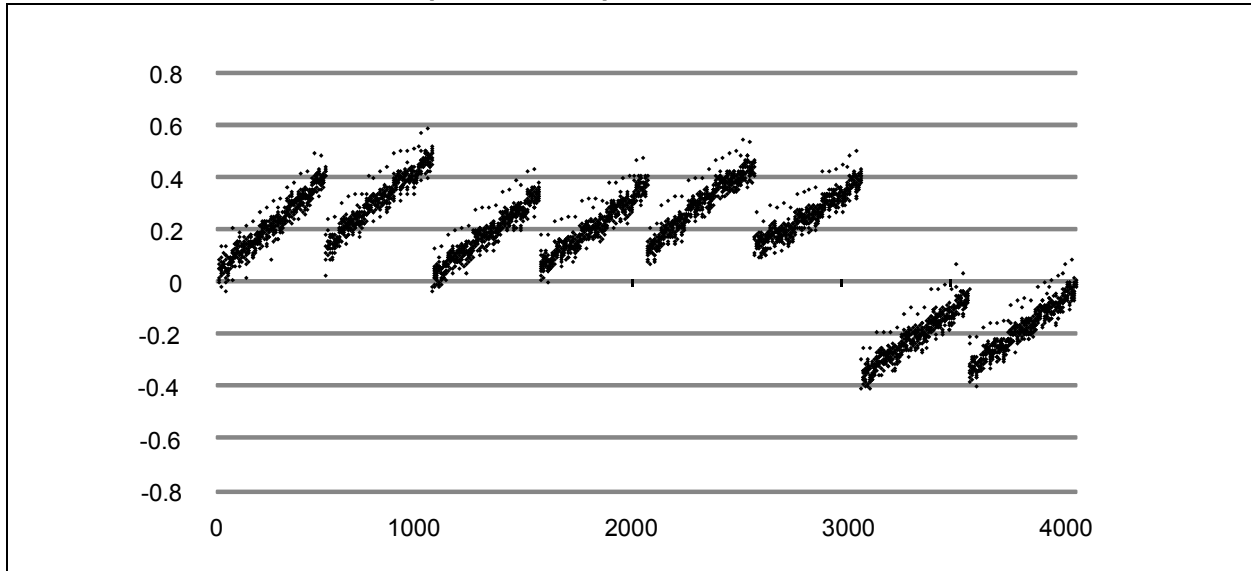


FIGURE 33-8: DNL vs. CODE (12-BIT MODE)⁽¹⁾

