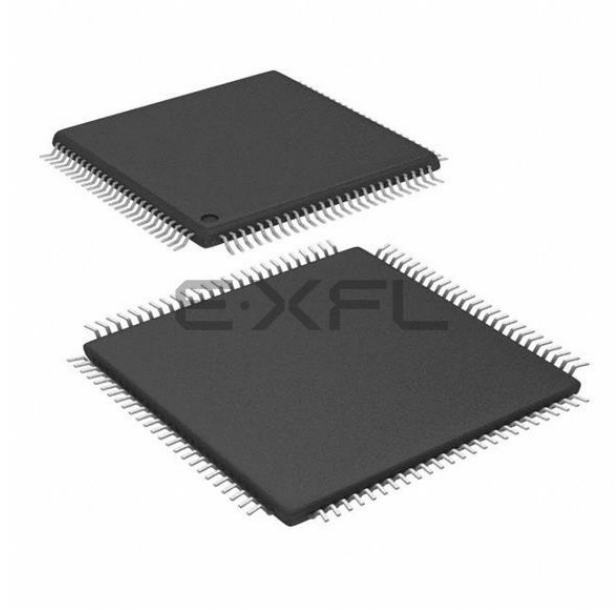
Microchip Technology - PIC24FJ512GA610-I/PT Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, LINbus, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, HLVD, POR, PWM, WDT
Number of I/O	85
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj512ga610-i-pt

TABLE 3: COMPLETE PIN FUNCTION DESCRIPTIONS (PIC24FJXXXGB606)

Pin	Function	Pin	Function
1	IC4/CTED4/PMD5/RE5	33	**RP16**/USBID/RF3
2	SCL3/IC5/PMD6/RE6	34	VBUS/RF7
3	SDA3/IC6/PMD7/RE7	35	VUSB3V3
4	C1IND/**RP21**/ICM1/OCM1A/PMA5/RG6	36	D-/RG3
5	C1INC/**RP26**/OCM1B/PMA4/RG7	37	D+/RG2
6	C2IND/**RP19**/ICM2/OCM2A/PMA3/RG8	38	VDD
7	$\overline{\text{MCLR}}$	39	OSCI/CLKI/RC12
8	C1INC/C2INC/C3INC/**RP27**/OCM2B/PMA2/PMALU/RG9	40	OSCO/CLKO/RC15
9	VSS	41	VSS
10	VDD	42	CLC4OUT/**RP2**/$\overline{\text{U6RTS}}$/U6BCLK/ICM5/RD8
11	PGEC3/AN5/C1INA/**RP18**/ICM3/OCM3A/RB5	43	**RP4**/SDA1/PMACK2/RD9
12	PGED3/AN4/C1INB/**RP28**/$\overline{\text{USBOEN}}$/OCM3B/RB4	44	**RP3**/SCL1/PMA15/PMCS2/RD10
13	AN3/C2INA/RB3	45	**RP12**/PMA14/PMCS1/RD11
14	AN2/CTCMP/C2INB/**RP13**/CTED13/RB2	46	CLC3OUT/**RP11**/$\overline{\text{U6CTS}}$/ICM6/INT0/RD0
15	PGEC1/ALTCVREF-/ALTVREF-/AN1/**RP1**/CTED12/RB1	47	SOSCI/C3IND/RC13
16	PGED1/ALTCVREF+/ALTVREF+/AN0/**RP0**/PMA6/RB0	48	SOSCO/C3INC/**RPI37**/PWRLCLK/RC14
17	PGEC2/AN6/**RP6**/RB6	49	**RP24**/U5TX/ICM4/RD1
18	PGED2/AN7/**RP7**/U6TX/RB7	50	**RP23**/PMACK1/RD2
19	AVDD	51	**RP22**/ICM7/PMBE0/RD3
20	AVSS	52	**RP25**/PMWR/PMENB/RD4
21	AN8/**RP8**/PWRGT/RB8	53	**RP20**/PMRD/$\overline{\text{PMWR}}$/RD5
22	AN9/$\overline{\text{TMPR}}$/**RP9**/T1CK/PMA7/RB9	54	C3INB/U5RX/OC4/RD6
23	TMS/CVREF/AN10/PMA13/RB10	55	C3INA/$\overline{\text{U5RTS}}$/U5BCLK/OC5/RD7
24	TDO/AN11/REFI/PMA12/RB11	56	VCAP
25	VSS	57	N/C
26	VDD	58	$\overline{\text{U5CTS}}$/OC6/RF0
27	TCK/AN12/U6RX/CTED2/PMA11/RB12	59	RF1
28	TDI/AN13/CTED1/PMA10/RB13	60	PMD0/RE0
29	AN14/**RP14**/CTED5/CTPLS/PMA1/PMALH/RB14	61	PMD1/RE1
30	AN15/**RP29**/CTED6/PMA0/PMALL/RB15	62	PMD2/RE2
31	**RP10**/SDA2/PMA9/RF4	63	CTED9/PMD3/RE3
32	**RP17**/SCL2/PMA8/RF5	64	HLVDIN/CTED8/PMD4/RE4

Legend: **RPn** and **RPIn** represent remappable pins for Peripheral Pin Select (PPS) functions.

Note: Pinouts are subject to change.

1.2 DMA Controller

PIC24FJ1024GA610/GB610 family devices have a Direct Memory Access (DMA) Controller. This module acts in concert with the CPU, allowing data to move between data memory and peripherals without the intervention of the CPU, increasing data throughput and decreasing execution time overhead. Eight independently programmable channels make it possible to service multiple peripherals at virtually the same time, with each channel peripheral performing a different operation. Many types of data transfer operations are supported.

1.3 Other Special Features

- **Peripheral Pin Select:** The Peripheral Pin Select (PPS) feature allows most digital peripherals to be mapped over a fixed set of digital I/O pins. Users may independently map the input and/or output of any one of the many digital peripherals to any one of the I/O pins.
- **Configurable Logic Cell:** The Configurable Logic Cell (CLC) module allows the user to specify combinations of signals as inputs to a logic function and to use the logic output to control other peripherals or I/O pins.
- **Timing Modules:** The PIC24FJ1024GA610/GB610 family provides five independent, general purpose, 16-bit timers (four of which can be combined into two 32-bit timers). The devices also include 3 multiple output and 4 single output advanced Capture/Compare/PWM/Timer peripherals, and 6 independent legacy Input Capture and 6 independent legacy Output Compare modules.
- **Communications:** The PIC24FJ1024GA610/GB610 family incorporates a range of serial communication peripherals to handle a range of application requirements. There are 3 independent I^2C modules that support both Master and Slave modes of operation. Devices also have, through the PPS feature, 6 independent UARTs with built-in IrDA® encoders/decoders and 3 SPI modules.
- **Analog Features:** All members of the PIC24FJ1024GA610/GB610 family include the new 12-bit A/D Converter (A/D) module and a triple comparator module. The A/D module incorporates a range of new features that allow the converter to assess and make decisions on incoming data, reducing CPU overhead for routine A/D conversions. The comparator module includes three analog comparators that are configurable for a wide range of operations.
- **CTMU Interface:** In addition to their other analog features, members of the PIC24FJ1024GA610/GB610 family include the CTMU interface module. This provides a convenient method for precision time measurement and pulse generation, and can serve as an interface for capacitive sensors.
- **Enhanced Parallel Master/Parallel Slave Port:** This module allows rapid and transparent access to the microcontroller data bus, and enables the CPU to directly address external data memory. The parallel port can function in Master or Slave mode, accommodating data widths of 4, 8 or 16 bits and address widths of up to 23 bits in Master modes.
- **Real-Time Clock and Calendar (RTCC):** This module implements a full-featured clock and calendar with alarm functions in hardware, freeing up timer resources and program memory space for use of the core application.

1.4 Details on Individual Family Members

Devices in the PIC24FJ1024GA610/GB610 family are available in 64-pin, 100-pin and 121-pin packages. The general block diagram for all devices is shown in Figure 1-1.

The devices are differentiated from each other in six ways:

1. Flash program memory (128 Kbytes for PIC24FJ128GX6XX devices, 256 Kbytes for PIC24FJ256GX6XX devices, 512 Kbytes for PIC24FJ512GX6XX devices and 1024 Kbytes for PIC24FJ1024GX6XX devices).
2. Available I/O pins and ports (53 pins on 6 ports for 64-pin devices and 85 pins on 7 ports for 100-pin and 121-pin devices).
3. Available Interrupt-on-Change Notification (IOC) inputs (53 on 64-pin devices and 85 on 100-pin and 121-pin devices).
4. Available remappable pins (29 pins on 64-pin devices, 44 pins on 100-pin and 121-pin devices).
5. Available USB peripheral (available on PIC24FJXXXGB6XX devices; not available on PIC24FJXXXGA6XX devices).
6. Analog input channels (16 channels for 64-pin devices and 24 channels for 100-pin and 121-pin devices).

All other features for devices in this family are identical. These are summarized in Table 1-1, Table 1-2 and Table 1-3.

A list of the pin features available on the PIC24FJ1024GA610/GB610 family devices, sorted by function, is shown in Table 1-3. Note that this table shows the pin location of individual peripheral features and not how they are multiplexed on the same pin. This information is provided in the pinout diagrams in the beginning of this data sheet. Multiplexed features are sorted by the priority given to a feature, with the highest priority peripheral being listed first.

REGISTER 6-1: NVMCON: FLASH MEMORY CONTROL REGISTER

R/S-0, HC(1)	R/W-0(1)	R-0, HSC(1)	r-0	R-0, HSC(1,3)	R-0(1)	U-0	U-0
WR	WREN	WRERR	—	SFTSWP	P2ACTIV	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0(1)	R/W-0(1)	R/W-0(1)	R/W-0(1)
—	—	—	—	NVMOP3(2)	NVMOP2(2)	NVMOP1(2)	NVMOP0(2)
bit 7							bit 0

Legend:	S = Settable bit	HC = Hardware Clearable bit	r = Reserved bit
R = Readable bit	W = Writable bit	'0' = Bit is cleared	x = Bit is unknown
-n = Value at POR	'1' = Bit is set	U = Unimplemented bit, read as '0'	
HSC = Hardware Settable/Clearable bit			

bit 15 **WR:** Write Control bit(1,4)
- 1 = Initiates a Flash memory program or erase operation; the operation is self-timed and the bit is cleared by hardware once the operation is complete
- 0 = Program or erase operation is complete and inactive

bit 14 **WREN:** Write Enable bit(1)
- 1 = Enables Flash program/erase operations
- 0 = Inhibits Flash program/erase operations

bit 13 **WRERR:** Write Sequence Error Flag bit(1)
- 1 = An improper program or erase sequence attempt, or termination has occurred (bit is set automatically on any set attempt of the WR bit)
- 0 = The program or erase operation completed normally

bit 12 **Reserved:** Maintain as '0'

bit 11 **SFTSWP:** Soft Swap Status bit(1,3)

In Single Partition Mode:
Read as '0'.

In Dual Partition Mode:
- 1 = Partitions have been successfully swapped using the BOOTSWP instruction
- 0 = Awaiting successful panel swap using the BOOTSWP instruction

bit 10 **P2ACTIV:** Dual Partition Active Status bit(1)

In Single Partition Mode:
Read as '0'.

In Dual Partition Mode:
- 1 = Partition 2 is mapped into the active region
- 0 = Partition 1 is mapped into the active region

bit 9-4 **Unimplemented:** Read as '0'

Note 1: These bits can only be reset on a Power-on Reset.

2: All other combinations of NVMOP<3:0> are unimplemented.

3: This bit may be cleared by software or by any Reset.

4: The WR bit should always be polled to indicate completion during any Flash memory program or erase operation while in Single Partition Mode.

6.6.2 PROGRAMMING A DOUBLE WORD OF FLASH PROGRAM MEMORY

If a Flash location has been erased, it can be programmed using Table Write instructions to write two instruction words (2 x 24-bit) into the write latch. The TBLPAG register is loaded with the address of the write latches and the NVMADRU/NVMADR registers are loaded with the address of the first of the two instruction words to be programmed. The TBLWTL and TBLWTH instructions write the desired data into the write latches. To configure the NVMCON register for a two-word write, set the NVMOPx bits (NVMCON<3:0>) to '0001'. The write is performed by executing the unlock sequence and setting the WR bit. An equivalent procedure in 'C', using the MPLAB® XC16 compiler and built-in hardware functions, is shown in Example 6-3.

TABLE 6-2: PROGRAMMING A DOUBLE WORD OF FLASH PROGRAM MEMORY

Step 1: Initialize the TBLPAG register for writing to the latches.
`MOV #0xFA, W12` `MOV W12, TBLPAG`
Step 2: Load W0:W2 with the next two packed instruction words to program.

`MOV #<LSW0>, W0`
`MOV #<MSB1:MSB0>, W1`
`MOV #<LSW1>, W2`

Step 3: Set the Read Pointer (W6) and Write Pointer (W7), and load the (next set of) write latches.

`CLR W6`
`CLR W7`
`TBLWTL [W6++], [W7]`
`TBLWTH.B [W6++], [W7++]`
`TBLWTH.B [W6++], [++W7]`
`TBLWTL.W [W6++], [W7++]`

Step 4: Set the NVMADRU/NVMADR register pair to point to the correct address.

`MOV #DestinationAddress<15:0>, W3`
`MOV #DestinationAddress<23:16>, W4`
`MOV W3, NVMADR`
`MOV W4, NVMADRU`

Step 5: Set the NVMCON register to program two instruction words.

`MOV #0x4001, W10`
`MOV W10, NVMCON`
`NOP`

Step 6: Initiate the write cycle.

`MOV #0x55, W1`
`MOV W1, NVMKEY`
`MOV #0xAA, W1`
`MOV W1, NVMKEY`
`BSET NVMCON, #WR`
`NOP`
`NOP`
`NOP`

7.0 RESETS

Note:	This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"dsPIC33/PIC24 Family Reference Manual"*, **"Reset"** (DS39712), which is available from the Microchip web site (www.microchip.com). The information in this data sheet supersedes the information in the FRM.

The Reset module combines all Reset sources and controls the device Master Reset Signal, $\overline{\text{SYSRST}}$. The following is a list of device Reset sources:

- POR: Power-on Reset
- $\overline{\text{MCLR}}$: Master Clear Pin Reset
- SWR: RESET Instruction
- WDT: Watchdog Timer Reset
- BOR: Brown-out Reset
- CM: Configuration Mismatch Reset
- TRAPR: Trap Conflict Reset
- IOPUWR: Illegal Opcode Reset
- UWR: Uninitialized W Register Reset

A simplified block diagram of the Reset module is shown in Figure 7-1.

Any active source of Reset will make the $\overline{\text{SYSRST}}$ signal active. Many registers associated with the CPU and peripherals are forced to a known Reset state. Most registers are unaffected by a Reset; their status is unknown on POR and unchanged by all other Resets.

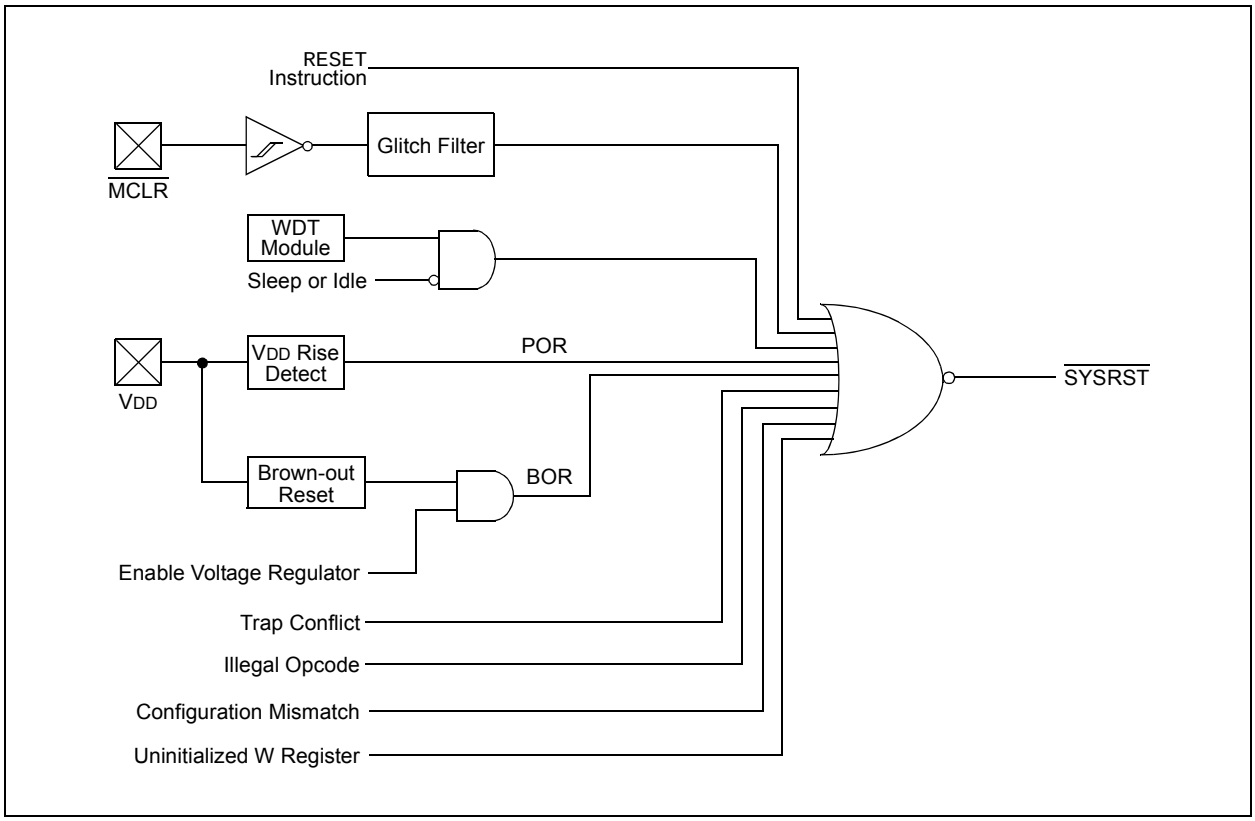
Note:	Refer to the specific peripheral or CPU section of this manual for register Reset states.

All types of device Reset will set a corresponding status bit in the RCON register to indicate the type of Reset (see Register 7-1). A POR will clear all bits, except for the BOR and POR (RCON<1:0>) bits, which are set. The user may set or clear any bit at any time during code execution. The RCON bits only serve as status bits. Setting a particular Reset status bit in software will not cause a device Reset to occur.

The RCON register also has other bits associated with the Watchdog Timer and device power-saving states. The function of these bits is discussed in other sections of this data sheet.

Note:	The status bits in the RCON register should be cleared after they are read so that the next RCON register values after a device Reset will be meaningful.

FIGURE 7-1: RESET SYSTEM BLOCK DIAGRAM



REGISTER 7-1: RCON: RESET CONTROL REGISTER (CONTINUED)

bit 5 **SWDTEN:** Software Enable/Disable of WDT bit(4)
1 = WDT is enabled
0 = WDT is disabled

bit 4 **WDTO:** Watchdog Timer Time-out Flag bit(1)
1 = WDT time-out has occurred
0 = WDT time-out has not occurred

bit 3 **SLEEP:** Wake from Sleep Flag bit(1)
1 = Device has been in Sleep mode
0 = Device has not been in Sleep mode

bit 2 **IDLE:** Wake-up from Idle Flag bit(1)
1 = Device has been in Idle mode
0 = Device has not been in Idle mode

bit 1 **BOR:** Brown-out Reset Flag bit(1)
1 = A Brown-out Reset has occurred (also set after a Power-on Reset)
0 = A Brown-out Reset has not occurred

bit 0 **POR:** Power-on Reset Flag bit(1)
1 = A Power-on Reset has occurred
0 = A Power-on Reset has not occurred

Note 1: All of the Reset status bits may be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

2: If the $\overline{\text{LPCFG}}$ Configuration bit is '1' (unprogrammed), the retention regulator is disabled and the RETEN bit has no effect. Retention mode preserves the SRAM contents during Sleep.

3: Re-enabling the regulator after it enters Standby mode will add a delay, TVREG, when waking up from Sleep. Applications that do not use the voltage regulator should set this bit to prevent this delay from occurring.

4: If the FWDTEN<1:0> Configuration bits are '11' (unprogrammed), the WDT is always enabled**,** regardless of the SWDTEN bit setting.

TABLE 7-1: RESET FLAG BIT OPERATION

Flag Bit	Setting Event	Clearing Event
TRAPR (RCON<15>)	Trap Conflict Event	POR
IOPUWR (RCON<14>)	Illegal Opcode or Uninitialized W Register Access	POR
CM (RCON<9>)	Configuration Mismatch Reset	POR
EXTR (RCON<7>)	$\overline{\text{MCLR}}$ Reset	POR
SWR (RCON<6>)	RESET Instruction	POR
WDTO (RCON<4>)	WDT Time-out	CLRWDT, PWRSAV Instruction, POR
SLEEP (RCON<3>)	PWRSAV #0 Instruction	POR
IDLE (RCON<2>)	PWRSAV #1 Instruction	POR
BOR (RCON<1>)	POR, BOR	—
POR (RCON<0>)	POR	—

Note: All Reset flag bits may be set or cleared by the user software.

REGISTER 10-4: PMD4: PERIPHERAL MODULE DISABLE REGISTER 4

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	U4MD	—	REFOMD	CTMUMD	LVDMD	USBMD(1)
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-6 **Unimplemented:** Read as '0'

bit 5 **U4MD:** UART4 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 4 **Unimplemented:** Read as '0'

bit 3 **REFOMD:** Reference Output Clock Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 2 **CTMUMD:** CTMU Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 1 **LVDMD:** High/Low-Voltage Detect Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 0 **USBMD:** USB On-The-Go Module Disable bit(1)
1 = Module is disabled
0 = Module power and clock sources are enabled

Note 1: USB is not present on PIC24FJXXXXGA6XX devices.

11.4 Peripheral Pin Select (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. In an application that needs to use more than one peripheral multiplexed on a single pin, inconvenient work arounds in application code, or a complete redesign, may be the only option.

The Peripheral Pin Select (PPS) feature provides an alternative to these choices by enabling the user's peripheral set selection and its placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the microcontroller to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of any one of many digital peripherals to any one of these I/O pins. PPS is performed in software and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

11.4.1 AVAILABLE PINS

The PPS feature is used with a range of up to 44 pins, depending on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the designation, "RPn" or "RPIn", in their full pin designation, where "n" is the remappable pin number. "RP" is used to designate pins that support both remappable input and output functions, while "RPI" indicates pins that support remappable input functions only.

PIC24FJ1024GA610/GB610 family devices support a larger number of remappable input/output pins than remappable input only pins. In this device family, there are up to 44 remappable input/output pins, depending on the pin count of the particular device selected. These pins are numbered, RP0 through RP31, and RPI32 through RPI43.

See Table 1-1 for a summary of pinout options in each package offering.

11.4.2 AVAILABLE PERIPHERALS

The peripherals managed by the PPS are all digital only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer related peripherals (input capture and output compare) and external interrupt inputs. Also included are the outputs of the comparator module, since these are discrete digital signals.

PPS is not available for these peripherals:

- I^2C (input and output)
- Input Change Notifications
- EPMP Signals (input and output)
- Analog (inputs and outputs)
- INT0

A key difference between pin select and non-pin select peripherals is that pin select peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-pin select peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

11.4.2.1 Peripheral Pin Select Function Priority

Pin-selectable peripheral outputs (e.g., output compare, UART transmit) will take priority over general purpose digital functions on a pin, such as EPMP and port I/O. Specialized digital outputs will take priority over PPS outputs on the same pin. The pin diagrams list peripheral outputs in the order of priority. Refer to them for priority concerns on a particular pin.

Unlike PIC24F devices with fixed peripherals, pin-selectable peripheral inputs will never take ownership of a pin. The pin's output buffer will be controlled by the TRISx setting or by a fixed peripheral on the pin. If the pin is configured in Digital mode, then the PPS input will operate correctly. If an analog function is enabled on the pin, the PPS input will be disabled.

11.4.3 CONTROLLING PERIPHERAL PIN SELECT

PPS features are controlled through two sets of Special Function Registers (SFRs): one to map peripheral inputs and one to map outputs. Because they are separately controlled, a particular peripheral's input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral-selectable pin is handled in two different ways, depending on if an input or an output is being mapped.

REGISTER 11-30: RPINR22: PERIPHERAL PIN SELECT INPUT REGISTER 22

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SCK2R5	SCK2R4	SCK2R3	SCK2R2	SCK2R1	SCK2R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI2R5	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **SCK2R<5:0>:** Assign SPI2 Clock Input (SCK2IN) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **SDI2R<5:0>:** Assign SPI2 Data Input (SDI2) to Corresponding RPn or RPIn Pin bits

REGISTER 11-31: RPINR23: PERIPHERAL PIN SELECT INPUT REGISTER 23

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	TXCKR5	TXCKR4	TXCKR3	TXCKR2	TXCKR1	TXCKR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SS2R5	SS2R4	SS2R3	SS2R2	SS2R1	SS2R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **TXCKR<5:0>:** Assign General Timer External Input (TxCK) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **SS2R<5:0>:** Assign SPI2 Slave Select Input (SS2IN) to Corresponding RPn or RPIn Pin bits

REGISTER 19-1: UxMODE: UARTx MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN(1)	—	USIDL	IREN(2)	RTSMD	—	UEN1	UEN0
bit 15							bit 8

R/W-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7							bit 0

Legend:	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **UARTEN:** UARTx Enable bit(1)
- 1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>
- 0 = UARTx is disabled; all UARTx pins are controlled by port latches, UARTx power consumption is minimal

bit 14 **Unimplemented:** Read as '0'

bit 13 **USIDL:** UARTx Stop in Idle Mode bit
- 1 = Discontinues module operation when device enters Idle mode
- 0 = Continues module operation in Idle mode

bit 12 **IREN:** IrDA® Encoder and Decoder Enable bit(2)
- 1 = IrDA encoder and decoder are enabled
- 0 = IrDA encoder and decoder are disabled

bit 11 **RTSMD:** Mode Selection for $\overline{\text{UxRTS}}$ Pin bit
- 1 = $\overline{\text{UxRTS}}$ pin is in Simplex mode
- 0 = $\overline{\text{UxRTS}}$ pin is in Flow Control mode

bit 10 **Unimplemented:** Read as '0'

bit 9-8 **UEN<1:0>:** UARTx Enable bits
- 11 = UxTX, UxRX and BCLKx pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by port latches
- 10 = UxTX, UxRX, $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins are enabled and used
- 01 = UxTX, UxRX and $\overline{\text{UxRTS}}$ pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by port latches
- 00 = UxTX and UxRX pins are enabled and used; $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$/BCLKx pins are controlled by port latches

bit 7 **WAKE:** Wake-up on Start Bit Detect During Sleep Mode Enable bit
- 1 = UARTx continues to sample the UxRX pin; interrupt is generated on the falling edge, bit is cleared in hardware on the following rising edge
- 0 = No wake-up is enabled

bit 6 **LPBACK:** UARTx Loopback Mode Select bit
- 1 = Enables Loopback mode
- 0 = Loopback mode is disabled

bit 5 **ABAUD:** Auto-Baud Enable bit
- 1 = Enables baud rate measurement on the next character – requires reception of a Sync field (55h); cleared in hardware upon completion
- 0 = Baud rate measurement is disabled or completed

bit 4 **URXINV:** UARTx Receive Polarity Inversion bit
- 1 = UxRX Idle state is '0'
- 0 = UxRX Idle state is '1'

Note 1: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn/RPIn pin. For more information, see **Section 11.4 "Peripheral Pin Select (PPS)"**.

2: This feature is only available for the 16x BRG mode (BRGH = 0).

20.5.3 SEND A FULL-SPEED BULK DATA TRANSFER TO A TARGET DEVICE

1. Follow the procedure described in **Section 20.5.1 "Enable Host Mode and Discover a Connected Device"** and **Section 20.5.2 "Complete a Control Transaction to a Connected Device"** to discover and configure a device.
2. To enable transmit and receive transfers with handshaking enabled, write 1Dh to U1EP0. If the target device is a low-speed device, also set the LSPD (U1EP0<7>) bit. If you want the hardware to automatically retry indefinitely if the target device asserts a NAK on the transfer, clear the Retry Disable bit, RETRYDIS (U1EP0<6>).
3. Set up the BD for the current (even or odd) TX EP0 to transfer up to 64 bytes.
4. Set the USB device address of the target device in the address register (U1ADDR<6:0>).
5. Write an OUT token to the desired endpoint to U1TOK. This triggers the module's transmit state machines to begin transmitting the token and the data.
6. Wait for the Token Complete Interrupt Flag, TRNIF. This indicates that the BD has been released back to the microprocessor and the transfer has completed. If the Retry Disable bit (RETRYDIS) is set, the handshake (ACK, NAK, STALL or ERROR (0Fh)) is returned in the BD PID field. If a STALL interrupt occurs, the pending packet must be dequeued and the error condition in the target device cleared. If a detach interrupt occurs (SE0 for more than 2.5 µs), then the target has detached (U1IR<0> is set).
7. Once the Token Complete Interrupt Flag occurs (TRNIF is set), the BD can be examined and the next data packet queued by returning to Step 2.

Note:	USB speed, transceiver and pull-ups should only be configured during the module setup phase. It is not recommended to change these settings while the module is enabled.

20.6 OTG Operation

20.6.1 SESSION REQUEST PROTOCOL (SRP)

An OTG A-device may decide to power down the VBUS supply when it is not using the USB link through the Session Request Protocol (SRP). SRP can only be initiated at full speed. Software may do this by configuring a GPIO pin to disable an external power transistor, or voltage regulator enable signal, which controls the VBUS supply. When the VBUS supply is powered down, the A-device is said to have ended a USB session.

An OTG A-device or embedded host may repower the VBUS supply at any time (initiate a new session). An OTG B-device may also request that the OTG A-device repower the VBUS supply (initiate a new session). This is accomplished via Session Request Protocol (SRP).

Prior to requesting a new session, the B-device must first check that the previous session has definitely ended. To do this, the B-device must check for two conditions:

1. VBUS supply is below the session valid voltage.
2. Both D+ and D- have been low for at least 2 ms.

The B-device will be notified of Condition 1 by the SESENDIF (U1OTGIR<2>) interrupt. Software will have to manually check for Condition 2.

Note:	When the A-device powers down the VBUS supply, the B-device must disconnect its pull-up resistor from power. If the device is self-powered, it can do this by clearing DPPULUP (U1OTGCON<7>) and DMPULUP (U1OTGCON<6>).

The B-device may aid in achieving Condition 1 by discharging the VBUS supply through a resistor. Software may do this by setting VBUSDIS (U1OTGCON<0>).

After these initial conditions are met, the B-device may begin requesting the new session. The B-device begins by pulsing the D+ data line. Software should do this by setting DPPULUP (U1OTGCON<7>). The data line should be held high for 5 to 10 ms.

The B-device then proceeds by pulsing the VBUS supply. Software should do this by setting PUVBUS (U1CNFG2<4>). When an A-device detects SRP signaling (either via the ATTACHIF (U1IR<6>) interrupt or via the SESVDIF (U1OTGIR<3>) interrupt), the A-device must restore the VBUS supply by properly configuring the general purpose I/O port pin controlling the external power source.

The B-device should not monitor the state of the VBUS supply while performing VBUS supply pulsing. When the B-device does detect that the VBUS supply has been restored (via the SESVDIF (U1OTGIR<3>) interrupt), the B-device must reconnect to the USB link by pulling up D+ or D- (via the DPPULUP or DMPULUP bit).

The A-device must complete the SRP by driving USB Reset signaling.

20.6.2 HOST NEGOTIATION PROTOCOL (HNP)

In USB OTG applications, a Dual Role Device (DRD) is a device that is capable of being either a host or a peripheral. Any OTG DRD must support Host Negotiation Protocol (HNP).

HNP allows an OTG B-device to temporarily become the USB host. The A-device must first enable the B-device to follow HNP. Refer to the *"On-The-Go Supplement"* to the *"USB 2.0 Specification"* for more information regarding HNP. HNP may only be initiated at full speed.

After being enabled for HNP by the A-device, the B-device requests being the host any time that the USB link is in the suspend state, by simply indicating a disconnect. This can be done in software by clearing DPPULUP and DMPULUP. When the A-device detects the disconnect condition (via the URSTIF (U1IR<0>) interrupt), the A-device may allow the B-device to take over as host. The A-device does this by signaling connect as a full-speed function. Software may accomplish this by setting DPPULUP.

If the A-device responds instead with resume signaling, the A-device remains as host. When the B-device detects the connect condition (via ATTACHIF, U1IR<6>), the B-device becomes host. The B-device drives Reset signaling prior to using the bus.

When the B-device has finished in its role as host, it stops all bus activity and turns on its D+ pull-up resistor by setting DPPULUP. When the A-device detects a suspend condition (Idle for 3 ms), the A-device turns off its D+ pull-up. The A-device may also power down the VBUS supply to end the session. When the A-device detects the connect condition (via ATTACHIF), the A-device resumes host operation and drives Reset signaling.

20.7 USB OTG Module Registers

There are a total of 37 memory-mapped registers associated with the USB OTG module. They can be divided into four general categories:

- USB OTG Module Control (12)
- USB Interrupt (7)
- USB Endpoint Management (16)
- USB VBUS Power Control (2)

This total does not include the (up to) 128 BD registers in the BDT. Their prototypes, described in Register 20-1 and Register 20-2, are shown separately in **Section 20.2 "USB Buffer Descriptors and the BDT"**.

All USB OTG registers are implemented in the Least Significant Byte (LSB) of the register. Bits in the upper byte are unimplemented and have no function. Note that some registers are instantiated only in Host mode, while other registers have different bit instantiations and functions in Device and Host modes.

The registers described in the following sections are those that have bits with specific control and configuration features. The following registers are used for data or address values only:

- U1BDTP1, U1BDTP2 and U1BDTP3: Specifies the 256-word page in data RAM used for the BDT; 8-bit value with bit 0 fixed as '0' for boundary alignment.
- U1FRML and U1FRMH: Contains the 11-bit byte counter for the current data frame.

REGISTER 21-2: PMCON2: EPMP CONTROL REGISTER 2

R-0, HSC	U-0	R/C-0, HS	R/C-0, HS	U-0	U-0	U-0	U-0
BUSY	—	ERROR	TIMEOUT	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
RADDR23(1)	RADDR22(1)	RADDR21(1)	RADDR20(1)	RADDR19(1)	RADDR18(1)	RADDR17(1)	RADDR16(1)
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown
C = Clearable bit	HS = Hardware Settable bit	HSC = Hardware Settable/Clearable bit	

bit 15 **BUSY:** Busy bit (Master mode only)
1 = Port is busy
0 = Port is not busy

bit 14 **Unimplemented:** Read as '0'

bit 13 **ERROR:** Error bit
1 = Transaction error (illegal transaction was requested)
0 = Transaction completed successfully

bit 12 **TIMEOUT:** Time-out bit
1 = Transaction timed out
0 = Transaction completed successfully

bit 11-8 **Unimplemented:** Read as '0'

bit 7-0 **RADDR<23:16>:** Parallel Master Port Reserved Address Space bits(1)

Note 1: If RADDR<23:16> = 00000000, then the last EDS address for Chip Select 2 will be FFFFFFh.

REGISTER 21-5: PMCSxCF: EPMP CHIP SELECT x CONFIGURATION REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
CSDIS	CSP	CSPTEN	BEP	—	WRSP	RDSP	SM
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
ACKP	PTSZ1	PTSZ0	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **CSDIS:** Chip Select x Disable bit
1 = Disables the Chip Select x functionality
0 = Enables the Chip Select x functionality

bit 14 **CSP:** Chip Select x Polarity bit
1 = Active-high (PMCSx)
0 = Active-low ($\overline{\text{PMCSx}}$)

bit 13 **CSPTEN:** PMCSx Port Enable bit
1 = PMCSx port is enabled
0 = PMCSx port is disabled

bit 12 **BEP:** Chip Select x Nibble/Byte Enable Polarity bit
1 = Nibble/byte enable is active-high (PMBE0, PMBE1)
0 = Nibble/byte enable is active-low ($\overline{\text{PMBE0}}$, $\overline{\text{PMBE1}}$)

bit 11 **Unimplemented:** Read as '0'

bit 10 **WRSP:** Chip Select x Write Strobe Polarity bit
For Slave modes and Master mode when SM = 0:
1 = Write strobe is active-high (PMWR)
0 = Write strobe is active-low ($\overline{\text{PMWR}}$)
For Master mode when SM = 1:
1 = Enable strobe is active-high (PMENB)
0 = Enable strobe is active-low ($\overline{\text{PMENB}}$)

bit 9 **RDSP:** Chip Select x Read Strobe Polarity bit
For Slave modes and Master mode when SM = 0:
1 = Read strobe is active-high (PMRD)
0 = Read strobe is active-low ($\overline{\text{PMRD}}$)
For Master mode when SM = 1:
1 = Read/write strobe is active-high (PMRD/$\overline{\text{PMWR}}$)
0 = Read/Write strobe is active-low ($\overline{\text{PMRD}}$/$\overline{\text{PMWR}}$)

bit 8 **SM:** Chip Select x Strobe Mode bit
1 = Reads/writes and enables strobes (PMRD/$\overline{\text{PMWR}}$ and PMENB)
0 = Reads and writes strobes (PMRD and PMWR)

bit 7 **ACKP:** Chip Select x Acknowledge Polarity bit
1 = ACK is active-high (PMACK1)
0 = ACK is active-low ($\overline{\text{PMACK1}}$)

bit 6-5 **PTSZ<1:0>:** Chip Select x Port Size bits
11 = Reserved
10 = 16-bit port size (PMD<15:0>)
01 = 4-bit port size (PMD<3:0>)
00 = 8-bit port size (PMD<7:0>)

bit 4-0 **Unimplemented:** Read as '0'

REGISTER 21-8: PMSTAT: EPMP STATUS REGISTER (SLAVE MODE ONLY)

R-0, HSC	R/W-0, HS	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
IBF	IBOV	—	—	IB3F(1)	IB2F(1)	IB1F(1)	IB0F(1)
bit 15							bit 8

R-1, HSC	R/W-0, HS	U-0	U-0	R-1, HSC	R-1, HSC	R-1, HSC	R-1, HSC
OBE	OBUF	—	—	OB3E	OB2E	OB1E	OB0E
bit 7							bit 0

Legend:	HS = Hardware Settable bit	HSC = Hardware Settable/Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **IBF:** Input Buffer Full Status bit
1 = All writable Input Buffer registers are full
0 = Some or all of the writable Input Buffer registers are empty

bit 14 **IBOV:** Input Buffer Overflow Status bit
1 = A write attempt to a full Input register occurred (must be cleared in software)
0 = No overflow occurred

bit 13-12 **Unimplemented:** Read as '0'

bit 11-8 **IB3F:IB0F:** Input Buffer x Status Full bits(1)
1 = Input buffer contains unread data (reading the buffer will clear this bit)
0 = Input buffer does not contain unread data

bit 7 **OBE:** Output Buffer Empty Status bit
1 = All readable Output Buffer registers are empty
0 = Some or all of the readable Output Buffer registers are full

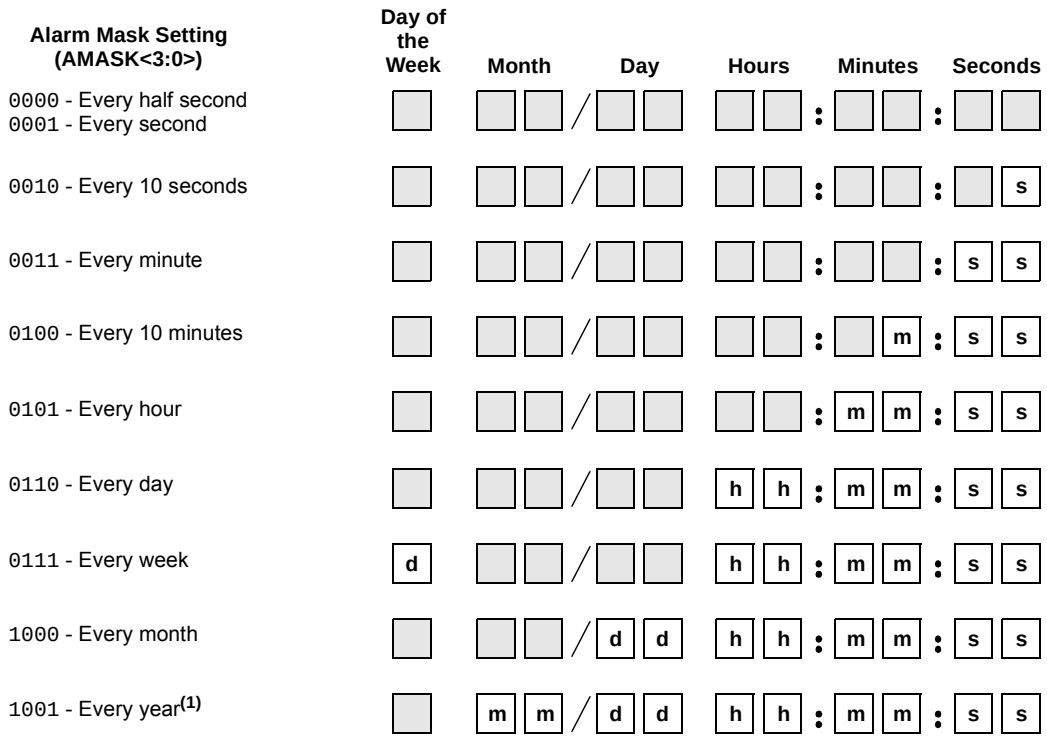
bit 6 **OBUF:** Output Buffer Underflow Status bit
1 = A read occurred from an empty Output Buffer register (must be cleared in software)
0 = No underflow occurred

bit 5-4 **Unimplemented:** Read as '0'

bit 3-0 **OB3E:OB0E:** Output Buffer x Status Empty bit
1 = Output Buffer x is empty (writing data to the buffer will clear this bit)
0 = Output Buffer x contains untransmitted data

Note 1: Even though an individual bit represents the byte in the buffer, the bits corresponding to the word (Byte 0 and 1, or Byte 2 and 3) get cleared, even on byte reading.

FIGURE 22-2: ALARM MASK SETTINGS



Note 1: Annually, except when configured for February 29.

22.6 Power Control

The RTCC includes a power control feature that allows the device to periodically wake-up an external device, wait for the device to be stable before sampling wake-up events from that device and then shut down the external device. This can be done completely autonomously by the RTCC, without the need to wake-up from the current lower power mode.

To use this feature:

1. Enable the RTCC (RTCEN = 1).
2. Set the PWCEN bit (RTCCON1L<10>).
3. Configure the RTCC pin to drive the PWC control signal (RTCOE = 1 and OUTSEL<2:0> = 011).

The polarity of the PWC control signal may be chosen using the PWCPOL bit (RTCCON1L<9>). An active-low or active-high signal may be used with the appropriate external switch to turn on or off the power to one or more external devices. The active-low setting may also be used in conjunction with an open-drain setting on the RTCC pin, in order to drive the ground pin(s) of the external device directly (with the appropriate external VDD pull-up device), without the need for external switches. Finally, the CHIME bit should be set to enable the PWC periodicity.

Once the RTCC and PWC are enabled and running, the PWC logic will generate a control output and a sample gate output. The control output is driven out on the RTCC pin (when RTCOE = 1 and OUTSEL<2:0> = 011) and is used to power up or down the device, as described above.

Once the control output is asserted, the stability window begins, in which the external device is given enough time to power up and provide a stable output.

Once the output is stable, the RTCC provides a sample gate during the sample window. The use of this sample gate depends on the external device being used, but typically, it is used to mask out one or more wake-up signals from the external device.

Finally, both the stability and the sample windows close after the expiration of the sample window and the external device is powered down.

REGISTER 24-1: CLCxCONL: CLCx CONTROL REGISTER (LOW) (CONTINUED)

bit 2-0 **MODE<2:0>:** CLCx Mode bits
111 = Cell is a 1-input transparent latch with S and R
110 = Cell is a JK flip-flop with R
101 = Cell is a 2-input D flip-flop with R
100 = Cell is a 1-input D flip-flop with S and R
011 = Cell is an SR latch
010 = Cell is a 4-input AND
001 = Cell is an OR-XOR
000 = Cell is a AND-OR

REGISTER 24-2: CLCxCONH: CLCx CONTROL REGISTER (HIGH)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	G4POL	G3POL	G2POL	G1POL
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-4 **Unimplemented:** Read as ‘0’

bit 3 **G4POL:** Gate 4 Polarity Control bit
1 = The output of Channel 4 logic is inverted when applied to the logic cell
0 = The output of Channel 4 logic is not inverted

bit 2 **G3POL:** Gate 3 Polarity Control bit
1 = The output of Channel 3 logic is inverted when applied to the logic cell
0 = The output of Channel 3 logic is not inverted

bit 1 **G2POL:** Gate 2 Polarity Control bit
1 = The output of Channel 2 logic is inverted when applied to the logic cell
0 = The output of Channel 2 logic is not inverted

bit 0 **G1POL:** Gate 1 Polarity Control bit
1 = The output of Channel 1 logic is inverted when applied to the logic cell
0 = The output of Channel 1 logic is not inverted

TABLE 33-9: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial				
Param No.	**Symbol**	**Characteristic**	**Min**	**Typ(1)**	**Max**	**Units**	**Conditions**
	VOL	**Output Low Voltage**					
DO10		I/O Ports	—	—	0.4	V	IOL = 6.6 mA, VDD = 3.6V
			—	—	0.8	V	IOL = 18 mA, VDD = 3.6V
			—	—	0.35	V	IOL = 5.0 mA, VDD = 2V
DO16		OSCO/CLKO	—	—	0.18	V	IOL = 6.6 mA, VDD = 3.6V
			—	—	0.2	V	IOL = 5.0 mA, VDD = 2V
	VOH	**Output High Voltage**					
DO20		I/O Ports	3.4	—	—	V	IOH = -3.0 mA, VDD = 3.6V
			3.25	—	—	V	IOH = -6.0 mA, VDD = 3.6V
			2.8	—	—	V	IOH = -18 mA, VDD = 3.6V
			1.65	—	—	V	IOH = -1.0 mA, VDD = 2V
			1.4	—	—	V	IOH = -3.0 mA, VDD = 2V
DO26		OSCO/CLKO	3.3	—	—	V	IOH = -6.0 mA, VDD = 3.6V
			1.85	—	—	V	IOH = -1.0 mA, VDD = 2V

Note 1: Data in the "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

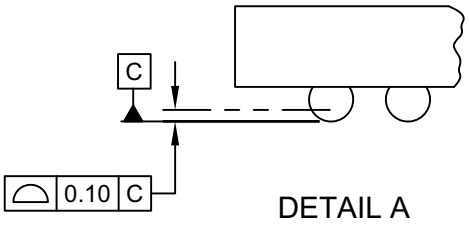
TABLE 33-10: DC CHARACTERISTICS: PROGRAM MEMORY

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial				
Param No.	**Symbol**	**Characteristic**	**Min**	**Typ(1)**	**Max**	**Units**	**Conditions**
		Program Flash Memory					
D130	EP	Cell Endurance	10000	—	—	E/W	-40°C to +85°C
D131	VPR	VDD for Read	VMIN	—	3.6	V	VMIN = Minimum operating voltage
D132B		VDD for Self-Timed Write	VMIN	—	3.6	V	VMIN = Minimum operating voltage
D133A	TIW	Self-Timed Word Write Cycle Time	—	20	—	µs	
		Self-Timed Row Write Cycle Time	—	1.5	—	ms	
D133B	TIE	Self-Timed Page Erase Time	20	—	40	ms	
D134	TRETD	Characteristic Retention	20	—	—	Year	If no other specifications are violated
D135	IDDP	Supply Current during Programming	—	5	—	mA	

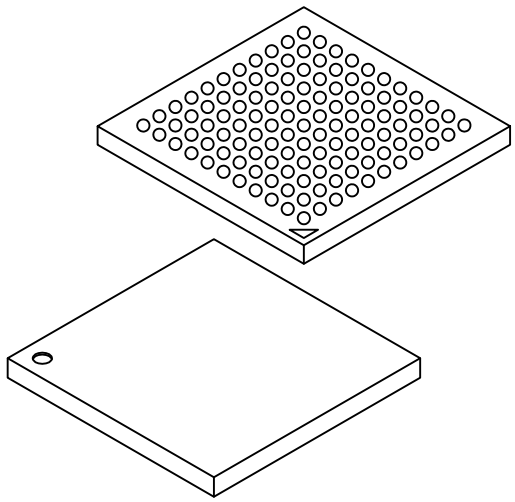
Note 1: Data in the "Typ" column is at 3.3V, +25°C unless otherwise stated.

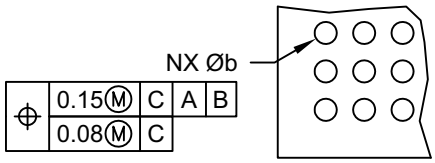
121-Ball Plastic Thin Profile Fine Pitch Ball Grid Array (BG) - 10x10x1.10 mm Body [TFBGA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



DETAIL A





DETAIL B

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Contacts	N		121	
Contact Pitch	e		0.80 BSC	
Overall Height	A	1.00	1.10	1.20
Ball Height	A1	0.25	0.30	0.35
Overall Width	E		10.00 BSC	
Array Width	E1		8.00 BSC	
Overall Length	D		10.00 BSC	
Array Length	D1		8.00 BSC	
Contact Diameter	b	0.35	0.40	0.45

Notes:

1. Ball A1 visual index feature may vary, but must be located within the hatched area.
2. Dimensioning and tolerancing per ASME Y14.5M.
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.
   REF: Reference Dimension, usually without tolerance, for information purposes only.
3. The outer rows and colums of balls are located with respect to datums A and B.
4. Ball interface to package body: 0.37mm nominal diameter.

Microchip Technology Drawing C04-148 Rev F Sheet 2 of 2

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO.	[X](1)	X	/XX	XXX
Device	Tape and Reel Option	Temperature Range	Package	Pattern

Device:	dsPIC33EP Core	
Tape and Reel Option:	Blank T	= Standard Packaging (tube or tray) = Tape and Reel(1)
Temperature Range:	I E	= -40°C to +85°C (Industrial) = -40°C to +125°C (Extended)
Package:	MR PT BG	= QFN (Plastic Quad Flat) = TQFP (Plastic Thin Quad Flatpack) = TFBGA (Plastic Thin Profile)
Pattern:	QTP, SQTP, Code or Special Requirements (blank otherwise)	

Examples:

a) PIC24FJ1024GB606-I/MR = Industrial Temperature, 64-Pin QFN Package.

b) PIC24FJ1024GB610-I/PT = Industrial Temperature, 100-Pin TQFP package.

c) PIC24FJ1024GB610-I/BG = Industrial Temperature, 121-Pin TFBGA package.

Note 1: Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.