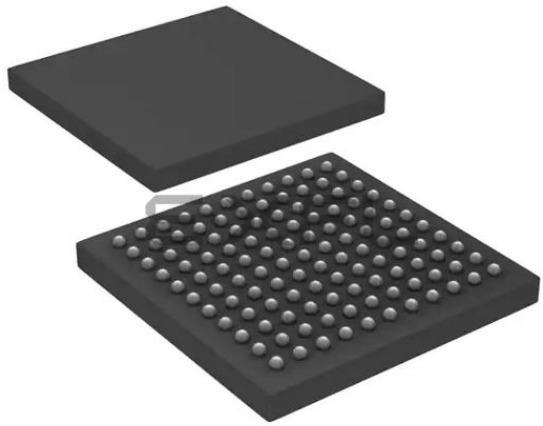
Microchip Technology - PIC24FJ512GA610T-I/BG Datasheet



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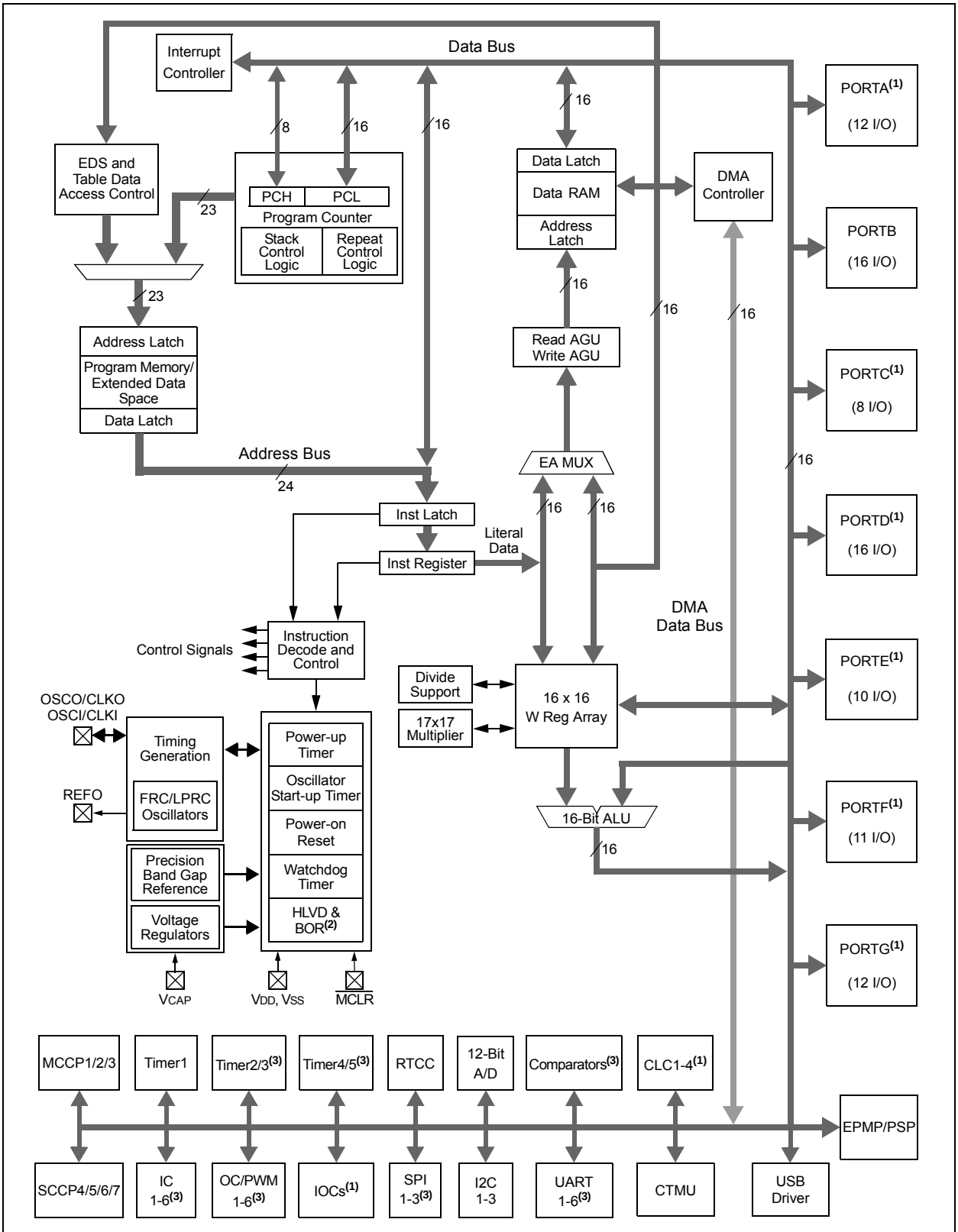
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, LINbus, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, HLVD, POR, PWM, WDT
Number of I/O	85
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	121-TFBGA
Supplier Device Package	121-TFBGA (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj512ga610t-i-bg

FIGURE 1-1: PIC24FJ1024GA610/GB610 FAMILY GENERAL BLOCK DIAGRAM



Note 1: Not all I/O pins or features are implemented on all device pinout configurations. See Table 1-3 for specific implementations by pin count.
2: BOR functionality is provided when the on-board voltage regulator is enabled.
3: Some peripheral I/Os are only accessible through remappable pins.

TABLE 1-3: PIC24FJ1024GA610/GB610 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Pin Function	Pin Number/Grid Locator						I/O	Input Buffer	Description
	GA606 64-Pin QFN/TQFP/ QFP	GB606 64-Pin QFN/ TQFP/QFP	GA610 100-Pin TQFP/ QFP	GB610 100-Pin TQFP/ QFP	GA612 121-Pin BGA	GB612 121-Pin BGA			
PMD0	60	60	93	93	A4	A4	I/O	DIG/ ST/TTL	Parallel Master Port Data (Demultiplexed Master mode) or Address/Data (Multiplexed Master modes)
PMD1	61	61	94	94	B4	B4	I/O	DIG/ ST/TTL	
PMD2	62	62	98	98	B3	B3	I/O	DIG/ ST/TTL	
PMD3	63	63	99	99	A2	A2	I/O	DIG/ ST/TTL	
PMD4	64	64	100	100	A1	A1	I/O	DIG/ ST/TTL	
PMD5	1	1	3	3	D3	D3	I/O	DIG/ ST/TTL	
PMD6	2	2	4	4	C1	C1	I/O	DIG/ ST/TTL	
PMD7	3	3	5	5	D2	D2	I/O	DIG/ ST/TTL	
PMD8	—	—	90	90	A5	A5	I/O	DIG/ ST/TTL	
PMD9	—	—	89	89	E6	E6	I/O	DIG/ ST/TTL	
PMD10	—	—	88	88	A6	A6	I/O	DIG/ ST/TTL	
PMD11	—	—	87	87	B6	B6	I/O	DIG/ ST/TTL	
PMD12	—	—	79	79	A9	A9	I/O	DIG/ ST/TTL	
PMD13	—	—	80	80	D8	D8	I/O	DIG/ ST/TTL	
PMD14	—	—	83	83	D7	D7	I/O	DIG/ ST/TTL	
PMD15	—	—	84	84	C7	C7	I/O	DIG/ ST/TTL	
$\overline{\text{PMRD}}$/ $\overline{\text{PMWR}}$	53	53	82	82	B8	B8	I/O	DIG/ ST/TTL	Parallel Master Port Read Strobe/Write Strobe
PMWR/ PMENB	52	52	81	81	C8	C8	I/O	DIG/ ST/TTL	Parallel Master Port Write Strobe/Enable Strobe
PWRGT	21	21	32	32	K4	K4	O	DIG	Real-Time Clock Power Control Output
PWRLCLK	48	48	74	74	B11	B11	I	ST	Real-Time Clock 50/60 Hz Clock Input

Legend: TTL = TTL input buffer
ANA = Analog level input/output
DIG = Digital input/output
ST = Schmitt Trigger input buffer
I^2C = I^2C/SMBus input buffer
XCVR = Dedicated Transceiver

2.6 External Oscillator Pins

Many microcontrollers have options for at least two oscillators: a high-frequency Primary Oscillator and a low-frequency Secondary Oscillator (refer to **Section 9.0 "Oscillator Configuration"** for details).

The oscillator circuit should be placed on the same side of the board as the device. Place the oscillator circuit close to the respective oscillator pins with no more than 0.5 inch (12 mm) between the circuit components and the pins. The load capacitors should be placed next to the oscillator itself, on the same side of the board.

Use a grounded copper pour around the oscillator circuit to isolate it from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed.

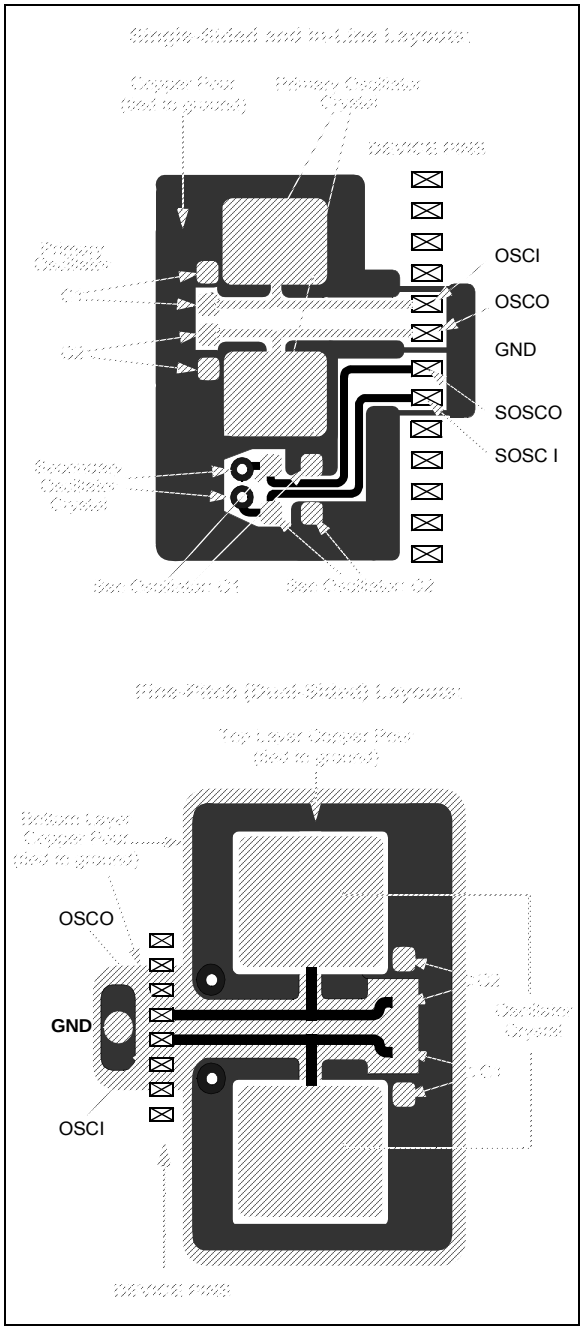
Layout suggestions are shown in Figure 2-5. In-line packages may be handled with a single-sided layout that completely encompasses the oscillator pins. With fine-pitch packages, it is not always possible to completely surround the pins and components. A suitable solution is to tie the broken guard sections to a mirrored ground layer. In all cases, the guard trace(s) must be returned to ground.

In planning the application's routing and I/O assignments, ensure that adjacent port pins, and other signals in close proximity to the oscillator, are benign (i.e., free of high frequencies, short rise and fall times and other similar noise).

For additional information and design guidance on oscillator circuits, please refer to these Microchip Application Notes, available at the corporate web site (www.microchip.com):

- *AN943, "Practical PICmicro® Oscillator Analysis and Design"*
- *AN949, "Making Your Oscillator Work"*
- *AN1798, "Crystal Selection for Low-Power Secondary Oscillator"*

FIGURE 2-5: SUGGESTED PLACEMENT OF THE OSCILLATOR CIRCUIT



4.0 MEMORY ORGANIZATION

As Harvard architecture devices, PIC24F microcontrollers feature separate program and data memory spaces and buses. This architecture also allows direct access of program memory from the Data Space during code execution.

4.1 Program Memory Space

The program address memory space of the PIC24FJ1024GA610/GB610 family devices is 4M instructions. The space is addressable by a 24-bit value derived from either the 23-bit Program Counter (PC) during program execution, or from table operation or Data Space remapping, as described in **Section 4.3 "Interfacing Program and Data Memory Spaces"**.

User access to the program memory space is restricted to the lower half of the address range (000000h to 7FFFFFh). The exception is the use of TBLRD/TBLWT operations, which use TBLPAG<7> to permit access to the Configuration bits and customer OTP sections of the configuration memory space.

The PIC24FJ1024GA610/GB610 family of devices supports a Single Partition mode and two Dual Partition modes. The Dual Partition modes allow the device to be programmed with two separate applications to facilitate bootloading or to allow an application to be programmed at run time without stalling the CPU.

Memory maps for the PIC24FJ1024GA610/GB610 family of devices are shown in Figure 4-1.

REGISTER 7-1: RCON: RESET CONTROL REGISTER

R/W-0	R/W-0	R/W-1	R/W-0	U-0	U-0	R/W-0	R/W-0
TRAPR(1)	IOPUWR(1)	SBOREN	RETEN(2)	—	—	CM(1)	VREGS(3)
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
EXTR(1)	SWR(1)	SWDTEN(4)	WDTO(1)	SLEEP(1)	IDLE(1)	BOR(1)	POR(1)
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **TRAPR:** Trap Reset Flag bit(1)
1 = A Trap Conflict Reset has occurred
0 = A Trap Conflict Reset has not occurred

bit 14 **IOPUWR:** Illegal Opcode or Uninitialized W Access Reset Flag bit(1)
1 = An illegal opcode detection, an illegal address mode or Uninitialized W register is used as an Address Pointer and caused a Reset
0 = An illegal opcode or Uninitialized W register Reset has not occurred

bit 13 **SBOREN:** Software Enable/Disable of BOR bit
1 = BOR is turned on in software
0 = BOR is turned off in software

bit 12 **RETEN:** Retention Mode Enable bit(2)
1 = Retention mode is enabled while device is in Sleep modes (1.2V regulator enabled)
0 = Retention mode is disabled

bit 11-10 **Unimplemented:** Read as '0'

bit 9 **CM:** Configuration Word Mismatch Reset Flag bit(1)
1 = A Configuration Word Mismatch Reset has occurred
0 = A Configuration Word Mismatch Reset has not occurred

bit 8 **VREGS:** Fast Wake-up from Sleep bit(3)
1 = Fast wake-up is enabled (uses more power)
0 = Fast wake-up is disabled (uses less power)

bit 7 **EXTR:** External Reset ($\overline{MCLR}$) Pin bit(1)
1 = A Master Clear (pin) Reset has occurred
0 = A Master Clear (pin) Reset has not occurred

bit 6 **SWR:** Software Reset (Instruction) Flag bit(1)
1 = A RESET instruction has been executed
0 = A RESET instruction has not been executed

Note 1: All of the Reset status bits may be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

2: If the $\overline{LPCFG}$ Configuration bit is '1' (unprogrammed), the retention regulator is disabled and the RETEN bit has no effect. Retention mode preserves the SRAM contents during Sleep.

3: Re-enabling the regulator after it enters Standby mode will add a delay, TVREG, when waking up from Sleep. Applications that do not use the voltage regulator should set this bit to prevent this delay from occurring.

4: If the FWDTEN<1:0> Configuration bits are '11' (unprogrammed), the WDT is always enabled**,** regardless of the SWDTEN bit setting.

REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER

U-0	R-x(1)	R-x(1)	R-x(1)	U-0	R/W-x(1)	R/W-x(1)	R/W-x(1)
—	COSC2	COSC1	COSC0	—	NOSC2	NOSC1	NOSC0
bit 15							bit 8

R/W-0	R/W-0	R-0(3)	U-0	R/CO-0	R/W-0	R/W-0	R/W-0
CLKLOCK	IOLOCK(2)	LOCK	—	CF	POSCEN	SOSCEN	OSWEN
bit 7							bit 0

Legend:	CO = Clearable Only bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **COSC<2:0>:** Current Oscillator Selection bits(1)
111 = Oscillator with Frequency Divider (OSCFDIV)
110 = Digitally Controlled Oscillator (DCO)
101 = Low-Power RC Oscillator (LPRC)
100 = Secondary Oscillator (SOSC)
011 = Primary Oscillator with PLL module (XTPLL, ECPLL)
010 = Primary Oscillator (XT, HS, EC)
001 = Fast RC Oscillator with PLL module (FRCPLL)
000 = Fast RC Oscillator (FRC)

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **NOSC<2:0>:** New Oscillator Selection bits(1)
111 = Oscillator with Frequency Divider (OSCFDIV)
110 = Digitally Controlled Oscillator (DCO)
101 = Low-Power RC Oscillator (LPRC)
100 = Secondary Oscillator (SOSC)
011 = Primary Oscillator with PLL module (XTPLL, ECPLL)
010 = Primary Oscillator (XT, HS, EC)
001 = Fast RC Oscillator with PLL module (FRCPLL)
000 = Fast RC Oscillator (FRC)

bit 7 **CLKLOCK:** Clock Selection Lock Enable bit
If FSCM is Enabled (FCKSM<1:0> = 00):
1 = Clock and PLL selections are locked
0 = Clock and PLL selections are not locked and may be modified by setting the OSWEN bit
If FSCM is Disabled (FCKSM<1:0> = 1x):
Clock and PLL selections are never locked and may be modified by setting the OSWEN bit.

bit 6 **IOLOCK:** I/O Lock Enable bit(2)
1 = I/O lock is active
0 = I/O lock is not active

bit 5 **LOCK:** PLL Lock Status bit(3)
1 = PLL module is in lock or PLL module start-up timer is satisfied
0 = PLL module is out of lock, PLL start-up timer is running or PLL is disabled

bit 4 **Unimplemented:** Read as '0'

Note 1: Reset values for these bits are determined by the FNOSCx Configuration bits.
2: The state of the IOLOCK bit can only be changed once an unlocking sequence has been executed. In addition, if the IOL1WAY Configuration bit is '1', once the IOLOCK bit is set, it cannot be cleared.
3: This bit also resets to '0' during any valid clock switch or whenever a non-PLL Clock mode is selected.

9.4 Clock Switching Operation

With few limitations, applications are free to switch between any of the five clock sources (POSC, SOSC, FRC, DCO and LPRC) under software control and at any time. To limit the possible side effects that could result from this flexibility, PIC24F devices have a safeguard lock built into the switching process.

Note: The Primary Oscillator mode has three different submodes (XT, HS and EC), which are determined by the POSCMD<1:0> Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch between the different primary submodes without reprogramming the device.

9.4.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM<1> Configuration bit in FOSC must be programmed to '0'. (Refer to **Section 30.1 "Configuration Bits"** for further details.) If the FCKSM<1> Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled; this is the default setting.

The NOSC<2:0> control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSC<2:0> bits (OSCCON<14:12>) will reflect the clock source selected by the FNOSC<2:0> Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled; it is held at '0' at all times.

9.4.2 OSCILLATOR SWITCHING SEQUENCE

At a minimum, performing a clock switch requires this basic sequence:

1. If desired, read the COSC<2:0> bits (OSCCON<14:12>) to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSC<2:0> bits (OSCCON<10:8>) for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSC<2:0> bits with the new value of the NOSC<2:0> bits. If they are the same, then the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.
2. If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and CF (OSCCON<3>) bits are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware will wait until the OST expires. If the new source is using the PLL, then the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSC<2:0> bits values are transferred to the COSC<2:0> bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM is enabled) or SOSC (if SOSCEN remains set).

Note 1: The processor will continue to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.

2: Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transitional clock source between the two PLL modes.

REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
T5MD	T4MD	T3MD	T2MD	T1MD	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	—	ADC1MD
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **T5MD:** Timer5 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 14 **T4MD:** Timer4 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 13 **T3MD:** Timer3 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 12 **T2MD:** Timer2 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 11 **T1MD:** Timer1 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 10-8 **Unimplemented:** Read as '0'

bit 7 **I2C1MD:** I2C1 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 6 **U2MD:** UART2 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 5 **U1MD:** UART1 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 4 **SPI2MD:** SPI2 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 3 **SPI1MD:** SPI1 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 2-1 **Unimplemented:** Read as '0'

bit 0 **ADC1MD:** A/D Converter Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

REGISTER 11-3: ANSC: PORTC ANALOG FUNCTION SELECTION REGISTER

U-0	R/W-1	R/W-1	U-0	U-0	U-0	U-0	U-0
—	ANSC<14:13>		—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	U-0	U-0	U-0	U-0
—	—	—	ANSC4(1)	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-13 **ANSC<14:13>:** PORTC Analog Function Selection bits
1 = Pin is configured in Analog mode; I/O port read is disabled
0 = Pin is configured in Digital mode; I/O port read is enabled

bit 12-5 **Unimplemented:** Read as '0'

bit 4 **ANSC4:** PORTC Analog Function Selection bit(1)
1 = Pin is configured in Analog mode; I/O port read is disabled
0 = Pin is configured in Digital mode; I/O port read is enabled

bit 3-0 **Unimplemented:** Read as '0'

Note 1: ANSC4 is not available on 64-pin devices.

REGISTER 11-4: ANSD: PORTD ANALOG FUNCTION SELECTION REGISTER

U-0	U-0	r-1	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-1	R/W-1	U-0	U-0	U-0	U-0	U-0	U-0
ANSD<7:6>		—	—	—	—	—	—
bit 7							bit 0

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **Reserved:** Read as '1'

bit 12-8 **Unimplemented:** Read as '0'

bit 7-6 **ANSD<7:6>:** PORTD Analog Function Selection bits
1 = Pin is configured in Analog mode; I/O port read is disabled
0 = Pin is configured in Digital mode; I/O port read is enabled

bit 5-0 **Unimplemented:** Read as '0'

REGISTER 11-24: RPINR15: PERIPHERAL PIN SELECT INPUT REGISTER 15

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	r-1	r-1	r-1	r-1	r-1	r-1
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-6 **Unimplemented:** Read as ‘0’

bit 5-0 **Reserved**: Maintain as ‘1’

REGISTER 11-25: RPINR17: PERIPHERAL PIN SELECT INPUT REGISTER 17

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U3RXR5	U3RXR4	U3RXR3	U3RXR2	U3RXR1	U3RXR0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **U3RXR<5:0>:** Assign UART3 Receive (U3RX) to Corresponding RPn or RPIn Pin bits

bit 7-0 **Unimplemented:** Read as ‘0’

REGISTER 14-1: ICxCON1: INPUT CAPTURE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R-0, HSC	R-0, HSC	R/W-0	R/W-0	R/W-0
—	ICI1	ICI0	ICOV	ICBNE	ICM2(1)	ICM1(1)	ICM0(1)
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **ICSIDL:** Input Capture x Stop in Idle Control bit
1 = Input Capture x halts in CPU Idle mode
0 = Input Capture x continues to operate in CPU Idle mode

bit 12-10 **ICTSEL<2:0>:** Input Capture x Timer Select bits
111 = System clock (FOSC/2)
110 = Reserved
101 = Reserved
100 = Timer1
011 = Timer5
010 = Timer4
001 = Timer2
000 = Timer3

bit 9-7 **Unimplemented:** Read as '0'

bit 6-5 **ICI<1:0>:** Input Capture x Select Number of Captures per Interrupt bits
11 = Interrupt on every fourth capture event
10 = Interrupt on every third capture event
01 = Interrupt on every second capture event
00 = Interrupt on every capture event

bit 4 **ICOV:** Input Capture x Overflow Status Flag bit (read-only)
1 = Input Capture x overflow has occurred
0 = No Input Capture x overflow has occurred

bit 3 **ICBNE:** Input Capture x Buffer Empty Status bit (read-only)
1 = Input Capture x buffer is not empty, at least one more capture value can be read
0 = Input Capture x buffer is empty

bit 2-0 **ICM<2:0>:** Input Capture x Mode Select bits(1)
111 = Interrupt mode: Input Capture x functions as an interrupt pin only when the device is in Sleep or Idle mode (rising edge detect only, all other control bits are not applicable)
110 = Unused (module is disabled)
101 = Prescaler Capture mode: Capture on every 16th rising edge
100 = Prescaler Capture mode: Capture on every 4th rising edge
011 = Simple Capture mode: Capture on every rising edge
010 = Simple Capture mode: Capture on every falling edge
001 = Edge Detect Capture mode: Capture on every edge (rising and falling); ICI<1:0> bits do not control interrupt generation for this mode
000 = Input Capture x module is turned off

Note 1: The ICx input must also be configured to an available RPn/RPIn pin. For more information, see **Section 11.4 "Peripheral Pin Select (PPS)"**.

20.0 UNIVERSAL SERIAL BUS WITH ON-THE-GO SUPPORT (USB OTG)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"dsPIC33/PIC24 Family Reference Manual"*, **"USB On-The-Go (OTG)"** (DS39721), which is available from the Microchip web site (www.microchip.com). The information in this data sheet supersedes the information in the FRM.

PIC24FJ1024GB610 family devices contain a full-speed and low-speed compatible, On-The-Go (OTG) USB Serial Interface Engine (SIE). The OTG capability allows the device to act as either a USB peripheral device or as a USB embedded host with limited host capabilities. The OTG capability allows the device to dynamically switch from device to host operation using OTG's Host Negotiation Protocol (HNP).

For more details on OTG operation, refer to the *"On-The-Go Supplement"* to the *"USB 2.0 Specification"*, published by the USB-IF. For more details on USB operation, refer to the *"Universal Serial Bus Specification"*, v2.0.

The USB OTG module offers these features:

- USB Functionality in Device and Host modes, and OTG Capabilities for Application-Controlled mode Switching
- Software-Selectable module Speeds of Full Speed (12 Mbps) or Low Speed (1.5 Mbps available in Host mode only)
- Support for All Four USB Transfer Types: Control, Interrupt, Bulk and Isochronous
- 16 Bidirectional Endpoints for a Total of 32 Unique Endpoints
- DMA Interface for Data RAM Access
- Queues up to 16 Unique Endpoint Transfers without Servicing
- Integrated, On-Chip USB Transceiver with Support for Off-Chip Transceivers via a Digital Interface
- Integrated VBUS Generation with On-Chip Comparators and Boost Generation, and Support of External VBUS Comparators and Regulators through a Digital Interface
- Configurations for On-Chip Bus Pull-up and Pull-Down Resistors

A simplified block diagram of the USB OTG module is shown in Figure 20-1.

The USB OTG module can function as a USB peripheral device or as a USB host, and may dynamically switch between Device and Host modes under software control. In either mode, the same data paths and Buffer Descriptors (BDs) are used for the transmission and reception of data.

In discussing USB operation, this section will use a controller-centric nomenclature for describing the direction of the data transfer between the microcontroller and the USB. RX (Receive) will be used to describe transfers that move data from the USB to the microcontroller and TX (Transmit) will be used to describe transfers that move data from the microcontroller to the USB. Table 20-1 shows the relationship between data direction in this nomenclature and the USB tokens exchanged.

TABLE 20-1: CONTROLLER-CENTRIC DATA DIRECTION FOR USB HOST OR TARGET

USB Mode	Direction	
	RX	TX
Device	OUT or SETUP	IN
Host	IN	OUT or SETUP

This chapter presents the most basic operations needed to implement USB OTG functionality in an application. A complete and detailed discussion of the USB protocol and its OTG supplement are beyond the scope of this data sheet. It is assumed that the user already has a basic understanding of USB architecture and the latest version of the protocol.

Not all steps for proper USB operation (such as device enumeration) are presented here. It is recommended that application developers use an appropriate device driver to implement all of the necessary features. Microchip provides a number of application-specific resources, such as USB firmware and driver support. Refer to www.microchip.com/usb for the latest firmware and driver support.

20.1 Hardware Configuration

20.1.1 DEVICE MODE

20.1.1.1 D+ Pull-up Resistor

PIC24FJ1024GB610 family devices have a built-in 1.5 kΩ resistor on the D+ line that is available when the microcontroller is operating in Device mode. This is used to signal an external host that the device is operating in Full-Speed Device mode. It is engaged by setting the USBEN bit (U1CON<0>) and powering up the USB module (USBPWR = 1). If the OTGEN bit (U1OTGCON<2>) is set, then the D+ pull-up is enabled through the DPPULUP bit (U1OTGCON<7>).

20.1.1.2 The VBUS Pin

In order to meet the *"USB 2.0 Specification"* requirement, relating to the back drive voltage on the D+/D- pins, the USB module incorporates VBUS-level sensing comparators. When the comparators detect the VBUS level below the VA_SESS_VLD level, the hardware will automatically disable the D+ pull-up resistor described in **Section 20.1.1.1 "D+ Pull-up Resistor"**. This allows the device to automatically meet the back drive requirement for D+ and D-, even if the application firmware does not explicitly monitor the VBUS level. Therefore, the VBUS microcontroller pin should not be left floating in USB Device mode application designs, and should normally be connected to the VBUS pin on the USB connector/cable (either directly or through a small resistance ≤ 100 ohms).

20.1.1.3 Power Modes

Many USB applications will likely have several different sets of power requirements and configuration. The most common power modes encountered are:

- Bus Power Only mode
- Self-Power Only mode
- Dual Power with Self-Power Dominance

Bus Power Only mode (Figure 20-2) is effectively the simplest method. All power for the application is drawn from the USB.

To meet the inrush current requirements of the *"USB 2.0 Specification",* the total effective capacitance, appearing across VBUS and ground, must be no more than 10 μF.

In the USB Suspend mode, devices must consume no more than 2.5 mA from the 5V VBUS line of the USB cable. During the USB Suspend mode, the D+ or D- pull-up resistor must remain active, which will consume some of the allowed suspend current.

In Self-Power Only mode (Figure 20-3), the USB application provides its own power, with very little power being pulled from the USB. Note that an attach indication is added to indicate when the USB has been connected and the host is actively powering VBUS.

To meet compliance specifications, the USB module (and the D+ or D- pull-up resistor) should not be enabled until the host actively drives VBUS high. One of the 5.5V tolerant I/O pins may be used for this purpose.

The application should never source any current onto the 5V VBUS pin of the USB cable when the USB module is operated in USB Device mode.

The Dual Power mode with Self-Power Dominance (Figure 20-4) allows the application to use internal power primarily, but switch to power from the USB when no internal power is available. Dual power devices must also meet all of the special requirements for inrush current and Suspend mode current previously described, and must not enable the USB module until VBUS is driven high.

FIGURE 20-2: BUS-POWERED INTERFACE EXAMPLE

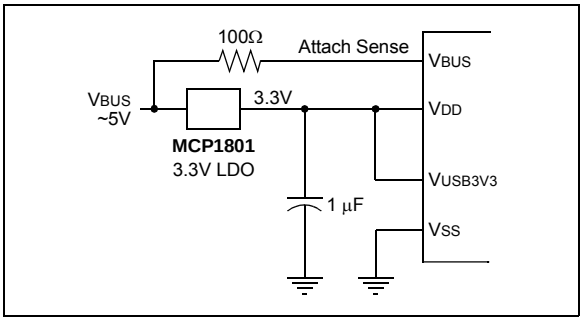


FIGURE 20-3: SELF-POWER ONLY

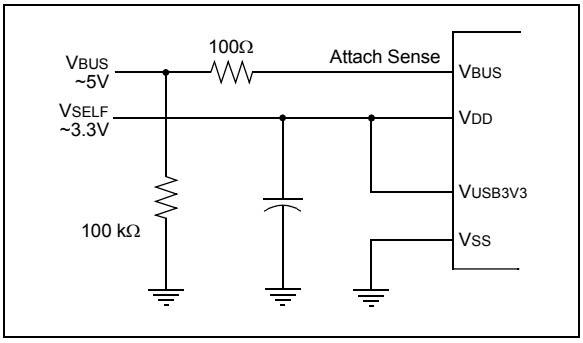
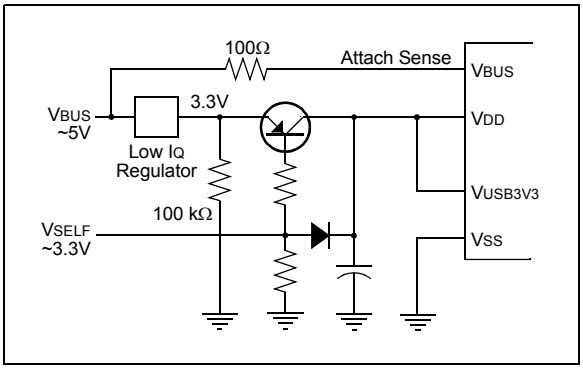


FIGURE 20-4: DUAL POWER EXAMPLE



REGISTER 20-6: U1STAT: USB STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	U-0	U-0
ENDPT3	ENDPT2	ENDPT1	ENDPT0	DIR	PPBI(1)	—	—
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'		
R = Readable bit	W = Writable bit	HSC = Hardware Settable/Clearable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-4 **ENDPT<3:0>:** Number of the Last Endpoint Activity bits
(Represents the number of the BDT updated by the last USB transfer.)
1111 = Endpoint 15
1110 = Endpoint 14
•
•
•
0001 = Endpoint 1
0000 = Endpoint 0

bit 3 **DIR:** Last BD Direction Indicator bit
1 = The last transaction was a transmit transfer (TX)
0 = The last transaction was a receive transfer (RX)

bit 2 **PPBI:** Ping-Pong BD Pointer Indicator bit(1)
1 = The last transaction was to the odd BD bank
0 = The last transaction was to the even BD bank

bit 1-0 **Unimplemented:** Read as '0'

Note 1: This bit is only valid for endpoints with available even and odd BD registers.

REGISTER 20-11: U1SOF: USB OTG START-OF-TOKEN THRESHOLD REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CNT<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as ‘0’

bit 7-0 **CNT<7:0>:** Start-of-Frame Size bits
Value represents 10 + (packet size of n bytes). For example:
0100 1010 = 64-byte packet
0010 1010 = 32-byte packet
0001 0010 = 8-byte packet

REGISTER 20-17: U1IR: USB INTERRUPT STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS
STALLIF	ATTACHIF	RESUMEIF	IDLEIF	TRNIF	SOFIF	UERRIF	DETACHIF
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'		
R = Readable bit	K = Write '1' to Clear bit	HS = Hardware Settable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **STALLIF:** STALL Handshake Interrupt bit
- 1 = A STALL handshake was sent by the peripheral device during the handshake phase of the transaction in Device mode
- 0 = A STALL handshake has not been sent

bit 6 **ATTACHIF:** Peripheral Attach Interrupt bit
- 1 = A peripheral attachment has been detected by the module; it is set if the bus state is not SE0 and there has been no bus activity for 2.5 μs
- 0 = No peripheral attachment has been detected

bit 5 **RESUMEIF:** Resume Interrupt bit
- 1 = A K-state is observed on the D+ or D- pin for 2.5 μs (differential '1' for low speed, differential '0' for full speed)
- 0 = No K-state is observed

bit 4 **IDLEIF:** Idle Detect Interrupt bit
- 1 = Idle condition is detected (constant Idle state of 3 ms or more)
- 0 = No Idle condition is detected

bit 3 **TRNIF:** Token Processing Complete Interrupt bit
- 1 = Processing of the current token is complete; read the U1STAT register for endpoint information
- 0 = Processing of the current token is not complete; clear the U1STAT register or load the next token from U1STAT

bit 2 **SOFIF:** Start-of-Frame Token Interrupt bit
- 1 = A Start-of-Frame token is received by the peripheral or the Start-of-Frame threshold is reached by the host
- 0 = No Start-of-Frame token is received or threshold reached

bit 1 **UERRIF:** USB Error Condition Interrupt bit
- 1 = An unmasked error condition has occurred; only error states enabled in the U1EIE register can set this bit
- 0 = No unmasked error condition has occurred

bit 0 **DETACHIF:** Detach Interrupt bit
- 1 = A peripheral detachment has been detected by the module; Reset state must be cleared before this bit can be re-asserted
- 0 = No peripheral detachment is detected. Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits, at the moment of the write, to become cleared.

Note: Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits, at the moment of the write, to become cleared.

REGISTER 21-5: PMCSxCF: EPMP CHIP SELECT x CONFIGURATION REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
CSDIS	CSP	CSPTEN	BEP	—	WRSP	RDSP	SM
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
ACKP	PTSZ1	PTSZ0	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **CSDIS:** Chip Select x Disable bit
1 = Disables the Chip Select x functionality
0 = Enables the Chip Select x functionality

bit 14 **CSP:** Chip Select x Polarity bit
1 = Active-high (PMCSx)
0 = Active-low ($\overline{\text{PMCSx}}$)

bit 13 **CSPTEN:** PMCSx Port Enable bit
1 = PMCSx port is enabled
0 = PMCSx port is disabled

bit 12 **BEP:** Chip Select x Nibble/Byte Enable Polarity bit
1 = Nibble/byte enable is active-high (PMBE0, PMBE1)
0 = Nibble/byte enable is active-low ($\overline{\text{PMBE0}}$, $\overline{\text{PMBE1}}$)

bit 11 **Unimplemented:** Read as '0'

bit 10 **WRSP:** Chip Select x Write Strobe Polarity bit
For Slave modes and Master mode when SM = 0:
1 = Write strobe is active-high (PMWR)
0 = Write strobe is active-low ($\overline{\text{PMWR}}$)
For Master mode when SM = 1:
1 = Enable strobe is active-high (PMENB)
0 = Enable strobe is active-low ($\overline{\text{PMENB}}$)

bit 9 **RDSP:** Chip Select x Read Strobe Polarity bit
For Slave modes and Master mode when SM = 0:
1 = Read strobe is active-high (PMRD)
0 = Read strobe is active-low ($\overline{\text{PMRD}}$)
For Master mode when SM = 1:
1 = Read/write strobe is active-high (PMRD/$\overline{\text{PMWR}}$)
0 = Read/Write strobe is active-low ($\overline{\text{PMRD}}$/$\overline{\text{PMWR}}$)

bit 8 **SM:** Chip Select x Strobe Mode bit
1 = Reads/writes and enables strobes (PMRD/$\overline{\text{PMWR}}$ and PMENB)
0 = Reads and writes strobes (PMRD and PMWR)

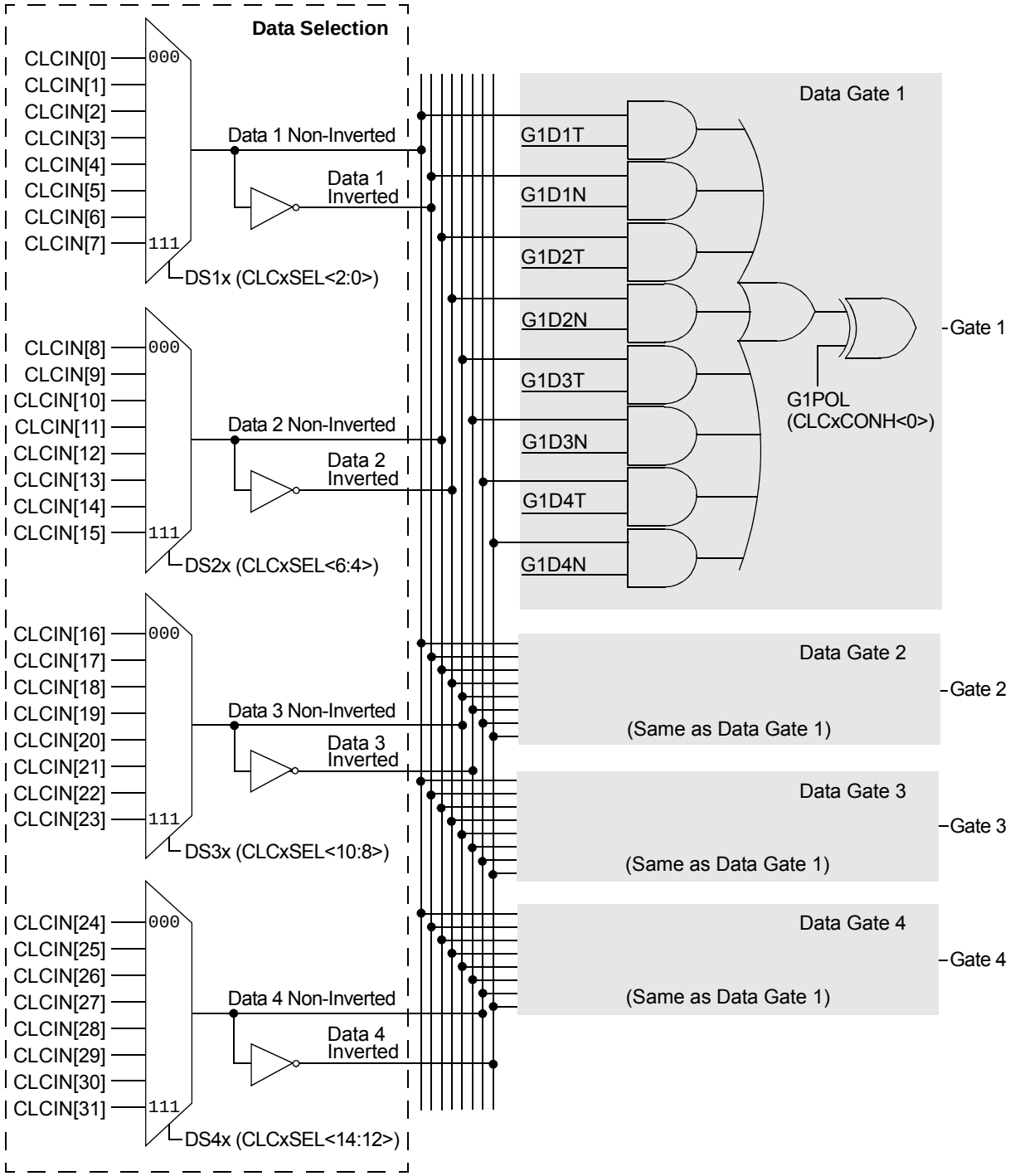
bit 7 **ACKP:** Chip Select x Acknowledge Polarity bit
1 = ACK is active-high (PMACK1)
0 = ACK is active-low ($\overline{\text{PMACK1}}$)

bit 6-5 **PTSZ<1:0>:** Chip Select x Port Size bits
11 = Reserved
10 = 16-bit port size (PMD<15:0>)
01 = 4-bit port size (PMD<3:0>)
00 = 8-bit port size (PMD<7:0>)

bit 4-0 **Unimplemented:** Read as '0'

NOTES:

FIGURE 24-3: CLCx INPUT SOURCE SELECTION DIAGRAM



Note: All controls are undefined at power-up.

Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
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