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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	11
Program Memory Size	1.5KB (1K x 12)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	72 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	16-VFQFN Exposed Pad
Supplier Device Package	16-QFN (3x3)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f505t-i-mg

NOTES:

TABLE 3-2: PIC12F508/509 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
GP0/ICSPDAT	GP0	TTL	CMOS	Bidirectional I/O pin. Can be software programmed for internal weak pull-up and wake-up from Sleep on pin change.
	ICSPDAT	ST	CMOS	In-Circuit Serial Programming™ data pin.
GP1/ICSPCLK	GP1	TTL	CMOS	Bidirectional I/O pin. Can be software programmed for internal weak pull-up and wake-up from Sleep on pin change.
	ICSPCLK	ST	CMOS	In-Circuit Serial Programming clock pin.
GP2/T0CKI	GP2	TTL	CMOS	Bidirectional I/O pin.
	T0CKI	ST	_	Clock input to TMR0.
GP3/MCLR/VPP	GP3	TTL	_	Input pin. Can be software programmed for internal weak pull-up and wake-up from Sleep on pin change.
	MCLR	ST	_	Master Clear (Reset). When configured as MCLR, this pin is an active-low Reset to the device. Voltage on MCLR/VPP must not exceed VDD during normal device operation or the device will enter Programming mode. Weak pull-up always on if configured as MCLR.
	VPP	HV	_	Programming voltage input.
GP4/OSC2	GP4	TTL	CMOS	Bidirectional I/O pin.
	OSC2	_	XTAL	Oscillator crystal output. Connections to crystal or resonator in Crystal Oscillator mode (XT and LP modes only, GPIO in other modes).
GP5/OSC1/CLKIN	GP5	TTL	CMOS	Bidirectional I/O pin.
	OSC1	XTAL	_	Oscillator crystal input.
	CLKIN	ST	_	External clock source input.
VDD	VDD		Р	Positive supply for logic and I/O pins.
Vss	Vss		Р	Ground reference for logic and I/O pins.

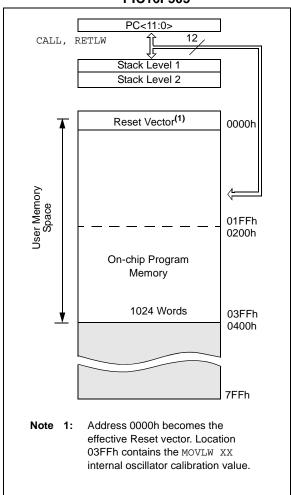
Legend: I = Input, O = Output, I/O = Input/Output, P = Power, — = Not used, TTL = TTL input, ST = Schmitt Trigger input, HV = High Voltage

4.2 Program Memory Organization For The PIC16F505

The PIC16F505 device has a 11-bit Program Counter (PC) capable of addressing a 2K x 12 program memory space.

The 1K x 12 (0000h-03FFh) for the PIC16F505 are physically implemented. Refer to Figure 4-2. Accessing a location above this boundary will cause a wrap-around within the first 1K x 12 space. The effective Reset vector is at 0000h (see Figure 4-2). Location 03FFh contains the internal oscillator calibration value. This value should never be overwritten.

FIGURE 4-2: PROGRAM MEMORY MAP
AND STACK FOR THE
PIC16F505



4.3 Data Memory Organization

Data memory is composed of registers or bytes of RAM. Therefore, data memory for a device is specified by its register file. The register file is divided into two functional groups: Special Function Registers (SFR) and General Purpose Registers (GPR).

The Special Function Registers include the TMR0 register, the Program Counter (PCL), the STATUS register, the I/O registers (ports) and the File Select Register (FSR). In addition, Special Function Registers are used to control the I/O port configuration and prescaler options.

The General Purpose Registers are used for data and control information under command of the instructions.

For the PIC12F508/509, the register file is composed of 7 Special Function Registers, 9 General Purpose Registers and 16 or 32 General Purpose Registers accessed by banking (see Figure 4-3 and Figure 4-4).

For the PIC16F505, the register file is composed of 8 Special Function Registers, 8 General Purpose Registers and 64 General Purpose Registers accessed by banking (Figure 4-5).

4.3.1 GENERAL PURPOSE REGISTER FILE

The General Purpose Register file is accessed, either directly or indirectly, through the File Select Register (FSR). See **Section 4.9 "Indirect Data Addressing: INDF and FSR Registers"**.

REGISTER 4-2: STATUS REGISTER (ADDRESS: 03h) (PIC16F505)

R/W-0	R/W-0	R/W-0	R-1	R-1	R/W-x	R/W-x	R/W-x
RBWUF	_	PA0	TO	PD	Z	DC	С
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7 **RBWUF: PORTB Reset bit**

1 = Reset due to wake-up from Sleep on pin change

0 = After power-up or other Reset

bit 6 Reserved: Do not use

bit 5 PA0: Program Page Preselect bits

> 1 = Page 1 (200h-3FFh) 0 = Page 0 (000h-1FFh) Each page is 512 bytes.

Using the PA0 bit as a general purpose read/write bit in devices which do not use it for program page

preselect is not recommended, since this may affect upward compatibility with future products.

bit 4

1 = After power-up, CLRWDT instruction, or SLEEP instruction

0 = A WDT time-out occurred

bit 3 PD: Power-Down bit

1 = After power-up or by the CLRWDT instruction

0 = By execution of the SLEEP instruction

bit 2 Z: Zero bit

> 1 = The result of an arithmetic or logic operation is zero 0 = The result of an arithmetic or logic operation is not zero

bit 1 DC: Digit Carry/Borrow bit (for ADDWF and SUBWF instructions)

ADDWF:

1 = A carry from the 4th low-order bit of the result occurred

0 = A carry from the 4th low-order bit of the result did not occur

1 = A borrow from the 4th low-order bit of the result did not occur

0 = A borrow from the 4th low-order bit of the result occurred

bit 0 C: Carry/Borrow bit (for ADDWF, SUBWF and RRF, RLF instructions)

> ADDWF: SUBWF: RRF or RLF:

1 = A carry occurred 1 = A borrow did not occur Load bit with LSb or MSb, respectively

0 = A carry did not occur 0 = A borrow occurred

TABLE 5-1: SUMMARY OF PORT REGISTERS

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on Power-On Reset	Value on All Other Resets
N/A	TRISGPIO ⁽¹⁾	_	_	I/O Control Register				11 1111	11 1111		
N/A	TRISB ⁽²⁾	1	_	I/O Contr	ol Registe	r				11 1111	11 1111
N/A	TRISC ⁽²⁾	_	_	I/O Contr	I/O Control Register			11 1111	11 1111		
N/A	OPTION ⁽¹⁾	GPWU	GPPU	TOCS	TOSE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
N/A	OPTION ⁽²⁾	RBWU	RBPU	TOCS	TOSE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
03h	STATUS ⁽¹⁾	GPWUF	_	PAO	TO	PD	Z	DC	С	0-01 1xxx	q00q quuu (3)
03h	STATUS ⁽²⁾	RBWUF	_	PAO	TO	PD	Z	DC	С	0-01 1xxx	q00q quuu (3)
06h	GPIO ⁽¹⁾	1	_	GP5	GP4	GP3	GP2	GP1	GP0	xx xxxx	uu uuuu
06h	PORTB ⁽²⁾	-	_	RB5	RB4	RB3	RB2	RB1	RB0	xx xxxx	uu uuuu
07h	PORTC ⁽²⁾	_	_	RC5	RC4	RC3	RC2	RC1	RC0	xx xxxx	uu uuuu

Legend: Shaded cells are not used by Port registers, read as '0'. - = unimplemented, read as '0', x = unknown, u = unchanged, q = depends on condition.

Note 1: PIC12F508/509 only.

2: PIC16F505 only.

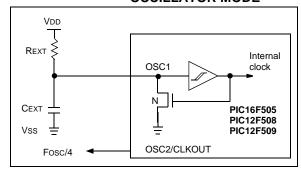
3: If Reset was due to wake-up on pin change, then bit 7 = 1. All other Resets will cause bit 7 = 0.

Although the oscillator will operate with no external capacitor (CEXT = 0 pF), we recommend using values above 20 pF for noise and stability reasons. With no or small external capacitance, the oscillation frequency can vary dramatically due to changes in external capacitances, such as PCB trace capacitance or package lead frame capacitance.

Section 10.0 "Electrical Characteristics" shows RC frequency variation from part-to-part due to normal process variation. The variation is larger for larger values of R (since leakage current variation will affect RC frequency more for large R) and for smaller values of C (since variation of input capacitance will affect RC frequency more).

Also, see the Electrical Specifications section for variation of oscillator frequency due to VDD for given REXT/CEXT values, as well as frequency variation due to operating temperature for given R, C and VDD values.

FIGURE 7-5: EXTERNAL RC OSCILLATOR MODE



7.2.5 INTERNAL 4 MHz RC OSCILLATOR

The internal RC oscillator provides a fixed 4 MHz (nominal) system clock at VDD = 5V and 25°C, (see **Section 10.0** "**Electrical Characteristics**" for information on variation over voltage and temperature).

In addition, a calibration instruction is programmed into the last address of memory, which contains the calibration value for the internal RC oscillator. This location is always uncode protected, regardless of the code-protect settings. This value is programmed as a MOVLW XX instruction where XX is the calibration value, and is placed at the Reset vector. This will load the W register with the calibration value upon Reset and the PC will then roll over to the users program at address 0x000. The user then has the option of writing the value to the OSCCAL Register (05h) or ignoring it.

OSCCAL, when written to with the calibration value, will "trim" the internal oscillator to remove process variation from the oscillator frequency.

Note: Erasing the device will also erase the preprogrammed internal calibration value for the internal oscillator. The calibration value must be read prior to erasing the part so it can be reprogrammed correctly later.

For the PIC12F508/509/16F505 devices, only bits <7:1> of OSCCAL are implemented. Bits CAL6-CAL0 are used for calibration. Adjusting CAL6-CAL0 from '0000000' to '11111111' changes the clock speed. See Register 4-5 for more information.

Note: The o bit of OSCCAL is unimplemented and should be written as 'o' when modifying OSCCAL for compatibility with future devices.

7.9 Power-down Mode (Sleep)

A device may be powered down (Sleep) and later powered up (wake-up from Sleep).

7.9.1 SLEEP

The Power-Down mode is entered by executing a SLEEP instruction.

If enabled, the Watchdog Timer will be cleared but keeps running, the $\overline{\text{TO}}$ bit (STATUS<4>) is set, the $\overline{\text{PD}}$ bit (STATUS<3>) is cleared and the oscillator driver is turned off. The I/O ports maintain the status they had before the SLEEP instruction was executed (driving high, driving low or high-impedance).

Note: A Reset generated by a WDT time-out does not drive the MCLR pin low.

For lowest current consumption while powered down, the T0CKI input should be at VDD or VSS and the (GP3/RB3)/MCLR/VPP pin must be at a logic high level if MCLR is enabled.

7.9.2 WAKE-UP FROM SLEEP

The device can wake-up from Sleep through one of the following events:

- An external Reset input on (GP3/RB3)/MCLR/ VPP pin, when configured as MCLR.
- A Watchdog Timer time-out Reset (if WDT was enabled).
- A change on input pin GP0/RB0, GP1/RB1, GP3/RB3 or RB4 when wake-up on change is enabled.

These events cause a device Reset. The $\overline{\text{TO}}$, $\overline{\text{PD}}$ and GPWUF/RBWUF bits can be used to determine the cause of device Reset. The $\overline{\text{TO}}$ bit is cleared if a WDT time-out occurred (and caused wake-up). The $\overline{\text{PD}}$ bit, which is set on power-up, is cleared when SLEEP is invoked. The GPWUF/RBWUF bit indicates a change in state while in Sleep at pins GP0/RB0, GP1/RB1, GP3/RB3 or RB4 (since the last file or bit operation on GP/RB port).

Note: Caution: Right before entering Sleep, read the input pins. When in Sleep, wake-up occurs when the values at the pins change from the state they were in at the last reading. If a wake-up on change occurs and the pins are not read before reentering Sleep, a wake-up will occur immediately even if no pins change while in Sleep mode.

The WDT is cleared when the device wakes from Sleep, regardless of the wake-up source.

7.10 Program Verification/Code Protection

If the code protection bit has not been programmed, the on-chip program memory can be read out for verification purposes.

The first 64 locations and the last location (OSCCAL) can be read, regardless of the code protection bit setting.

The last memory location can be read regardless of the code protection bit setting on the PIC12F508/509/16F505 devices.

7.11 ID Locations

Four memory locations are designated as ID locations where the user can store checksum or other code identification numbers. These locations are not accessible during normal execution, but are readable and writable during Program/Verify.

Use only the lower 4 bits of the ID locations and always program the upper 8 bits as '0's.

7.12 In-Circuit Serial Programming™

The PIC12F508/509/16F505 microcontrollers can be serially programmed while in the end application circuit. This is simply done with two lines for clock and data, and three other lines for power, ground and the programming voltage. This allows customers to manufacture boards with unprogrammed devices and then program the microcontroller just before shipping the product. This also allows the most recent firmware, or a custom firmware, to be programmed.

The devices are placed into a Program/Verify mode by holding the $\overline{\text{GP1/RB1}}$ and $\overline{\text{GP0/RB0}}$ pins low while raising the $\overline{\text{MCLR}}$ (VPP) pin from VIL to VIHH (see programming specification). GP1/RB1 becomes the programming clock and GP0/RB0 becomes the programming data. Both GP1/RB1 and GP0/RB0 are Schmitt Trigger inputs in this mode.

After Reset, a 6-bit command is then supplied to the device. Depending on the command, 14 bits of program data are then supplied to or from the device, depending if the command was a Load or a Read. For complete details of serial programming, please refer to the PIC12F508/509/16F505 Programming Specifications.

A typical In-Circuit Serial Programming connection is shown in Figure 7-15.

IORWF	Inclusive OR W with f
Syntax:	[label] IORWF f,d
Operands:	$0 \le f \le 31$ $d \in [0,1]$
Operation:	(W).OR. (f) \rightarrow (dest)
Status Affected:	Z
Description:	Inclusive OR the W register with register 'f'. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'.

MOVWF	Move W to f
Syntax:	[label] MOVWF f
Operands:	$0 \le f \le 31$
Operation:	(W) o (f)
Status Affected:	None
Description:	Move data from the W register to register 'f'.

MOVF	Move f
Syntax:	[label] MOVF f,d
Operands:	$0 \le f \le 31$ $d \in [0,1]$
Operation:	$(f) \to (dest)$
Status Affected:	Z
Description:	The contents of register 'f' are moved to destination 'd'. If 'd' is '0', destination is the W register. If 'd' is '1', the destination is file register 'f'. 'd' = 1 is useful as a test of a file register, since status flag Z is affected.

NOP	No Operation
Syntax:	[label] NOP
Operands:	None
Operation:	No operation
Status Affected:	None
Description:	No operation.

Move Literal to W					
[label] MOVLW k					
$0 \le k \le 255$					
$k \rightarrow (W)$					
None					
The eight-bit literal 'k' is loaded into the W register. The "don't cares" will assembled as '0's.					

OPTION	Load OPTION Register
Syntax:	[label] OPTION
Operands:	None
Operation:	$(W) \to OPTION$
Status Affected:	None
Description:	The content of the W register is loaded into the OPTION register.

10.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings^(†)

Ambient temperature under bias	40°C to +125°C
Storage temperature	65°C to +150°C
Voltage on VDD with respect to Vss	0 to +6.5V
Voltage on MCLR with respect to Vss	0 to +13.5V
Voltage on all other pins with respect to Vss	0.3V to (VDD + 0.3V)
Total power dissipation ⁽¹⁾	800 mW
Max. current out of Vss pin	200 mA
Max. current into VDD pin	150 mA
Input clamp current, Iik (VI < 0 or VI > VDD)	±20 mA
Output clamp current, IOK (Vo < 0 or Vo > VDD)	±20 mA
Max. output current sunk by any I/O pin	25 mA
Max. output current sourced by any I/O pin	25 mA
Max. output current sourced by I/O port	75 mA
Max. output current sunk by I/O port	75 mA
Note 1: Power dissipation is calculated as follows: PDIS = VDD x {IDD $-\sum$ IOH} + \sum {(VD	$DD - VOH) \times IOH\} + \sum (VOL \times IOL)$

[†]NOTICE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

TABLE 10-2: PULL-UP RESISTOR RANGES - PIC12F508/509/16F505

VDD (Volts)	Temperature (°C)	Min.	Тур.	Max.
GP0(RBO)/GP1(I	RB1)			
2.0	-40	73K	105K	186K
	25	73K	113K	187K
	85	82K	123K	190K
	125	86K	132k	190K
5.5	-40	15K	21K	33K
	25	15K	22K	34K
	85	19K	26k	35K
	125	23K	29K	35K
GP3(RB3)	<u> </u>			
2.0	-40	63K	81K	96K
	25	77K	93K	116K
	85	82K	96k	116K
	125	86K	100K	119K
5.5	-40	16K	20k	22K
	25	16K	21K	23K
	85	24K	25k	28K
	125	26K	27K	29K

^{*} These parameters are characterized but not tested.

FIGURE 11-10: Voh vs. Ioh OVER TEMPERATURE (VDD = 3.0V)

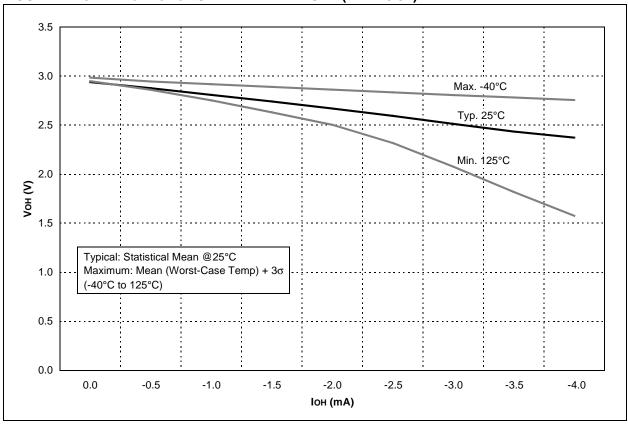


FIGURE 11-11: Voh vs. Ioh OVER TEMPERATURE (VDD = 5.0V)

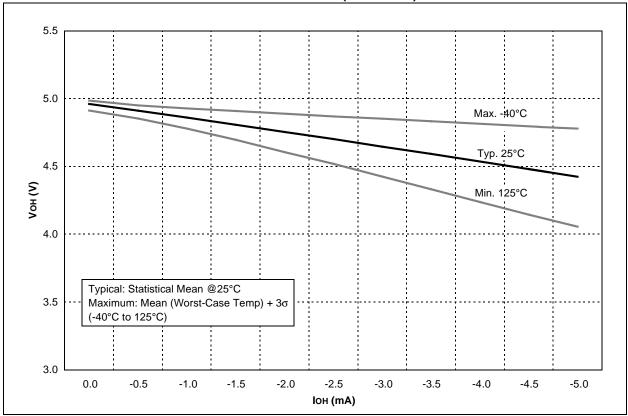
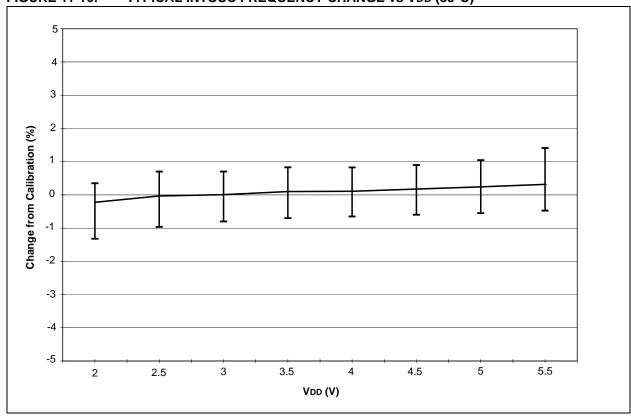
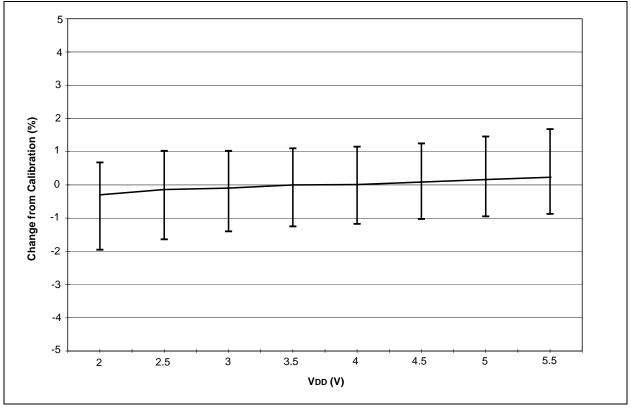


FIGURE 11-16: TYPICAL INTOSC FREQUENCY CHANGE vs VDD (85°C)

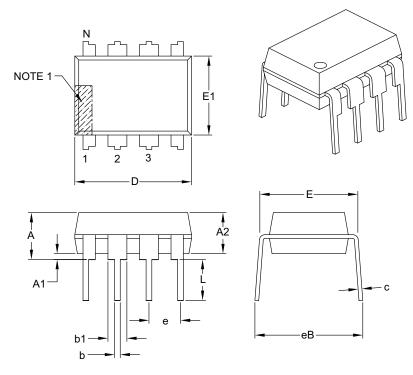






8-Lead Plastic Dual In-Line (P) - 300 mil Body [PDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		INCHES	
	Dimension Limits	MIN	NOM	MAX
Number of Pins	N		8	
Pitch	е		.100 BSC	
Top to Seating Plane	A	_	_	.210
Molded Package Thickness	A2	.115	.130	.195
Base to Seating Plane	A1	.015	-	_
Shoulder to Shoulder Width	E	.290	.310	.325
Molded Package Width	E1	.240	.250	.280
Overall Length	D	.348	.365	.400
Tip to Seating Plane	L	.115	.130	.150
Lead Thickness	С	.008	.010	.015
Upper Lead Width	b1	.040	.060	.070
Lower Lead Width	b	.014	.018	.022
Overall Row Spacing §	eB	_	-	.430

Notes:

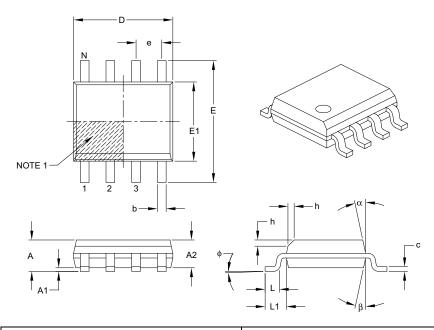
- 1. Pin 1 visual index feature may vary, but must be located with the hatched area.
- 2. § Significant Characteristic.
- 3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-018B

8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS	
Dimension	n Limits	MIN	NOM	MAX
Number of Pins	N		8	
Pitch	е		1.27 BSC	
Overall Height	Α	-	_	1.75
Molded Package Thickness	A2	1.25	_	_
Standoff §	A1	0.10	_	0.25
Overall Width	Е		6.00 BSC	
Molded Package Width	E1		3.90 BSC	
Overall Length	D		4.90 BSC	
Chamfer (optional)	h	0.25	_	0.50
Foot Length	L	0.40	_	1.27
Footprint	L1		1.04 REF	
Foot Angle	ф	0°	_	8°
Lead Thickness	С	0.17	_	0.25
Lead Width	b	0.31	_	0.51
Mold Draft Angle Top	α	5°	_	15°
Mold Draft Angle Bottom	β	5°	_	15°

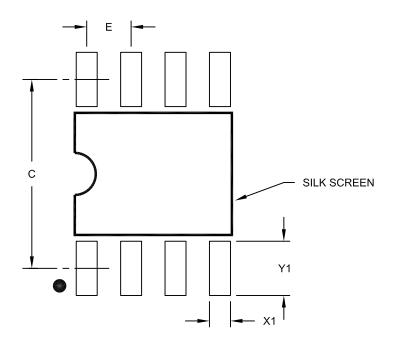
Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic.
- 3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-057B

8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm Body [SOIC]

ote: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		1.27 BSC	
Contact Pad Spacing	С		5.40	
Contact Pad Width (X8)	X1			0.60
Contact Pad Length (X8)	Y1			1.55

Notes:

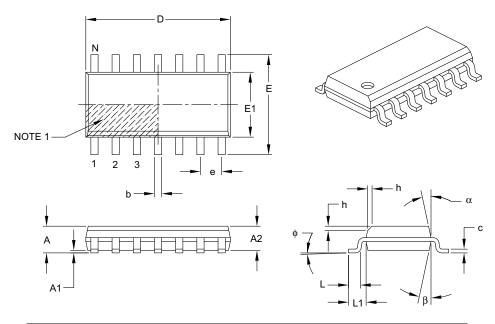
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2057A

14-Lead Plastic Small Outline (SL) - Narrow, 3.90 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS	1
Dir	mension Limits	MIN	NOM	MAX
Number of Pins	N		14	
Pitch	е		1.27 BSC	
Overall Height	Α	-	_	1.75
Molded Package Thickness	A2	1.25	_	_
Standoff §	A1	0.10	_	0.25
Overall Width	E		6.00 BSC	
Molded Package Width	E1	3.90 BSC		
Overall Length	D		8.65 BSC	
Chamfer (optional)	h	0.25	_	0.50
Foot Length	L	0.40	_	1.27
Footprint	L1		1.04 REF	
Foot Angle	ф	0°	_	8°
Lead Thickness	С	0.17	_	0.25
Lead Width	b	0.31	_	0.51
Mold Draft Angle Top	α	5°	_	15°
Mold Draft Angle Bottom	β	5°	_	15°

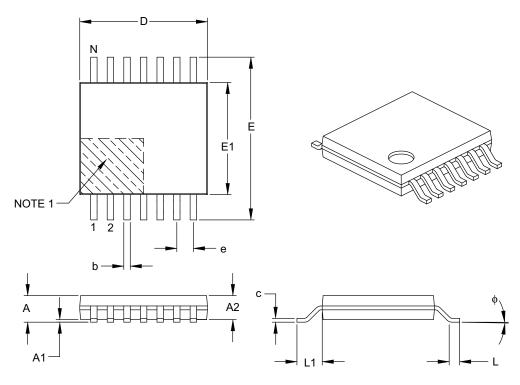
Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic.
- 3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-065B

14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS	3
Dimensi	ion Limits	MIN	NOM	MAX
Number of Pins	N		14	
Pitch	е		0.65 BSC	
Overall Height	Α	-	_	1.20
Molded Package Thickness	A2	0.80	1.00	1.05
Standoff	A1	0.05	_	0.15
Overall Width	Е		6.40 BSC	
Molded Package Width	E1	4.30	4.40	4.50
Molded Package Length	D	4.90	5.00	5.10
Foot Length	L	0.45	0.60	0.75
Footprint	L1		1.00 REF	
Foot Angle	ф	0°	_	8°
Lead Thickness	С	0.09	_	0.20
Lead Width	b	0.19	_	0.30

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
- 3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-087B

W

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PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO. Device	X /XX XXX Temperature Package Pattern Range	Examples: a) PIC12F508-E/P 301 = Extended Temp., PDIP package, QTP pattern #301 b) PIC12F508-I/SN = Industrial Temp., SOIC package
Device:	PIC16F505 PIC12F508 PIC12F509 PIC16F505T ⁽¹⁾ PIC12F508T ⁽²⁾	c) PIC12F508T-E/P = Extended Temp., PDIP package, Tape and Reel
Temperature Range:	I = -40°C to +85°C (Industrial) E = -40°C to +125°C (Extended)	
Package:	MC = 8L DFN 2x3 (DUAL Flatpack No-Leads) ^(3, 4) MS = Micro-Small Outline Package (MSOP) ^(3, 4) P = Plastic (PDIP) ⁽⁴⁾ SL = 14L Small Outline, 3.90 mm (SOIC) ⁽⁴⁾ SN = 8L Small Outline, 3.90 mm Narrow (SOIC) ⁽⁴⁾ ST = Thin Shrink Small Outline (TSSOP) ⁽⁴⁾ MG = 16L QFN (3x3x0.9) ⁽⁵⁾	Note 1: T = in tape and reel SOIC, TSSOP and QFN packages only 2: T = in tape and reel SOIC and MSOP packages only. 3: PIC12F508/PIC12F509 only. 4: Pb-free. 5: PIC16F505 only.
	Special Requirements and Reel available for only the following packages: SOIC, MSOP SSOP.	J. Pictor 303 only.