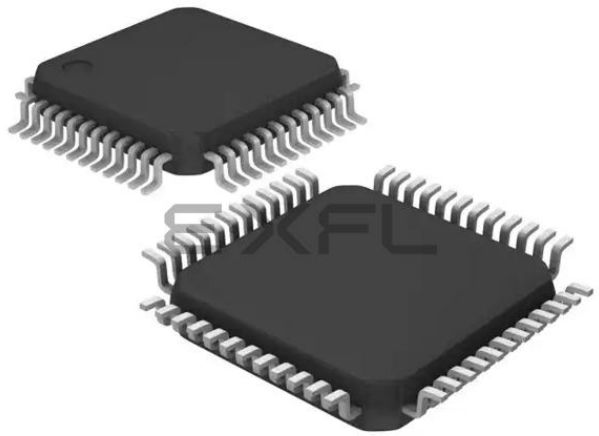

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	DMA, PDR, POR, PVD, PWM, Temp Sensor, WDT
Number of I/O	37
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 10x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f102c8t6tr

Contents

2 Description

The STM32F102xx medium-density USB access line incorporates the high-performance ARM® Cortex®-M3 32-bit RISC core operating at a 48 MHz frequency, high-speed embedded memories (Flash memory of 64 or 128 Kbytes and SRAM of 10 or 16 Kbytes), and an extensive range of enhanced peripherals and I/Os connected to two APB buses. All devices offer standard communication interfaces (two I^2Cs, two SPIs, one USB and three USARTs), one 12-bit ADC and three general-purpose 16-bit timers.

The STM32F102xx family operates in the –40 to +85 °C temperature range, from a 2.0 to 3.6 V power supply. A comprehensive set of power-saving mode allows the design of low-power applications.

The STM32F102xx medium-density USB access line is delivered in the LQFP48 7 × 7 mm and LQFP64 10 × 10 mm packages.

The STM32F102xx medium-density USB access line microcontrollers are suitable for a wide range of applications.

- Application control and user interface
- Medical and handheld equipment
- PC peripherals, gaming and GPS platforms
- Industrial applications: PLC, inverters, printers, and scanners
- Alarm systems, Video intercom, and HVAC

Figure 1 shows the general block diagram of the device family.

Low-power modes

The STM32F102xx medium-density USB access line supports three low-power modes to achieve the best compromise between low power consumption, short startup time and available wakeup sources:

- **Sleep** mode

  In Sleep mode, only the CPU is stopped. All peripherals continue to operate and can wake up the CPU when an interrupt/event occurs.

- **Stop** mode

  The Stop mode achieves the lowest power consumption while retaining the content of SRAM and registers. All clocks in the 1.8 V domain are stopped, the PLL, the HSI RC and the HSE crystal oscillators are disabled. The voltage regulator can also be put either in normal or in low power mode.
  The device can be woken up from Stop mode by any of the EXTI line. The EXTI line source can be one of the 16 external lines, the PVD output or the RTC alarm.

- **Standby** mode

  The Standby mode is used to achieve the lowest power consumption. The internal voltage regulator is switched off so that the entire 1.8 V domain is powered off. The PLL, the HSI RC and the HSE crystal oscillators are also switched off. After entering Standby mode, SRAM and registers content are lost except for registers in the Backup domain and Standby circuitry.

  The device exits Standby mode when an external reset (NRST pin), a IWDG reset, a rising edge on the WKUP pin, or an RTC alarm occurs.

Note: The RTC, the IWDG, and the corresponding clock sources are not stopped by entering Stop or Standby mode.

DMA

The flexible 7-channel general-purpose DMA is able to manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers. The DMA controller supports circular buffer management avoiding the generation of interrupts when the controller reaches the end of the buffer.

Each channel is connected to dedicated hardware DMA requests, with support for software trigger on each channel. Configuration is made by software and transfer sizes between source and destination are independent.

The DMA can be used with the main peripherals: SPI, I^2C, USART, general purpose timers TIMx and ADC.

RTC (real-time clock) and backup registers

The RTC and the backup registers are supplied through a switch that takes power either on V_{DD} supply when present or through the V_{BAT} pin. The backup registers are ten 16-bit registers used to store 20 bytes of user application data when V_{DD} power is not present.

The real-time clock provides a set of continuously running counters which can be used with suitable software to provide a clock calendar function, and provides an alarm interrupt and a periodic interrupt. It is clocked by a 32.768 kHz external crystal, resonator or oscillator, the internal low power RC oscillator or the high-speed external clock divided by 128. The internal low power RC has a typical frequency of 40 kHz. The RTC can be calibrated using an external 512 Hz output to compensate for any natural crystal deviation. The RTC features a 32-bit programmable counter for long term measurement using the Compare

Table 4. Medium-density STM32F102xx pin definitions

Pins		Pin name	Type[1]	I / O level[2]	Main function[3] (after reset)	Alternate functions[3] [4]	
LQFP48	LQFP64					Default	Remap
1	1	V_{BAT}	S	-	V_{BAT}	-	-
2	2	PC13-TAMPER-RTC[5]	I/O	-	PC13[6]	TAMPER-RTC	-
3	3	PC14-OSC32_IN[5]	I/O	-	PC14[6]	OSC32_IN	-
4	4	PC15-OSC32_OUT[5]	I/O	-	PC15[6]	OSC32_OUT	-
5	5	OSC_IN	I/O	FT	OSC_IN	-	PD0[7]
6	6	OSC_OUT	I/O	FT	OSC_OUT	-	PD1[7]
7	7	NRST	I/O	-	NRST	-	-
-	8	PC0	I/O	-	PC0	ADC_IN10	-
-	9	PC1	I/O	-	PC1	ADC_IN11	-
-	10	PC2	I/O	-	PC2	ADC_IN12	-
-	11	PC3	I/O	-	PC3	ADC_IN13	-
8	12	V_{SSA}	S	-	V_{SSA}	-	-
9	13	V_{DDA}	S	-	V_{DDA}	-	-
10	14	PA0-WKUP	I/O	-	PA0	WKUP/USART2_CTS/ ADC_IN0/ TIM2_CH1_ETR[8]	-
11	15	PA1	I/O	-	PA1	USART2_RTS/ ADC_IN1/TIM2_CH2[8]	-
12	16	PA2	I/O	-	PA2	USART2_TX/ ADC_IN2/TIM2_CH3[8]	-
13	17	PA3	I/O	-	PA3	USART2_RX/ ADC_IN3/TIM2_CH4[8]	-
-	18	V_{SS_4}	S	-	V_{SS_4}	-	-
-	19	V_{DD_4}	S	-	V_{DD_4}	-	-
14	20	PA4	I/O	-	PA4	SPI1_NSS[8]/ADC_IN4 USART2_CK/	-
15	21	PA5	I/O	-	PA5	SPI1_SCK[8]/ADC_IN5	-
16	22	PA6	I/O	-	PA6	SPI1_MISO[8]/ADC_IN6/ TIM3_CH1[8]	-
17	23	PA7	I/O	-	PA7	SPI1_MOSI[8]/ADC_IN7/ TIM3_CH2[8]	-
-	24	PC4	I/O	-	PC4	ADC_IN14	-
-	25	PC5	I/O	-	PC5	ADC_IN15	-
18	26	PB0	I/O	-	PB0	ADC_IN8/TIM3_CH3[8]	-
19	27	PB1	I/O	-	PB1	ADC_IN9/TIM3_CH4[8]	-

Table 4. Medium-density STM32F102xx pin definitions (continued)

Pins		Pin name	Type[1]	I / O level[2]	Main function[3] (after reset)	Alternate functions[3] [4]	
LQFP48	LQFP64					Default	Remap
39	55	PB3	I/O	FT	JTDO	-	TIM2_CH2/ PB3/ TRACESWO/ SPI1_SCK
40	56	PB4	I/O	FT	JNTRST	-	TIM3_CH1 / PB4 SPI1_MISO
41	57	PB5	I/O	-	PB5	I2C1_SMBA	TIM3_CH2 / SPI1_MOSI
42	58	PB6	I/O	FT	PB6	I2C1_SCL[8]/ TIM4_CH1	USART1_TX
43	59	PB7	I/O	FT	PB7	I2C1_SDA[8]/ TIM4_CH2	USART1_RX
44	60	BOOT0	I	-	BOOT0	-	-
45	61	PB8	I/O	FT	PB8	TIM4_CH3	I2C1_SCL
46	62	PB9	I/O	FT	PB9	TIM4_CH4	I2C1_SDA
47	63	V_{SS_3}	S	-	V_{SS_3}	-	-
48	64	V_{DD_3}	S	-	V_{DD_3}	-	-

1. I = input, O = output, S = supply.
2. FT= 5 V tolerant.
3. Function availability depends on the chosen device. For devices having reduced peripheral counts, it is always the lower number of peripherals that is included. For example, if a device has only one SPI, two USARTs and two timers, they will be called SPI1, USART1 & USART2 and TIM2 & TIM 3, respectively. Refer to *Table 2 on page 9Table 3 on page 12*.
4. If several peripherals share the same I/O pin, to avoid conflict between these alternate functions only one peripheral should be enabled at a time through the peripheral clock enable bit (in the corresponding RCC peripheral clock enable register).
5. PC13, PC14 and PC15 are supplied through the power switch. Since the switch only sinks a limited amount of current (3 mA), the use of GPIOs PC13 to PC15 in output mode is limited: the speed should not exceed 2 MHz with a maximum load of 30 pF and these IOs must not be used as a current source (e.g. to drive an LED).
6. Main function after the first backup domain power-up. Later on, it depends on the contents of the Backup registers even after reset (because these registers are not reset by the main reset). For details on how to manage these IOs, refer to the Battery backup domain and BKP register description sections in the STM32F102xx reference manual, available from the STMicroelectronics website: www.st.com.
7. The pins number 5 and 6 in the LQFP48 package are configured as OSC_IN/OSC_OUT after reset, however the functionality of PD0 and PD1 can be remapped by software on these pins. For more details, refer to the Alternate function I/O and debug configuration section in the STM32F10xxx reference manual.
   The use of PD0 and PD1 in output mode is limited as they can only be used at 50 MHz in output mode.
8. This alternate function can be remapped by software to some other port pins (if available on the used package). For more details, refer to the Alternate function I/O and debug configuration section in the STM32F10xxx reference manual, available from the STMicroelectronics website: www.st.com.

Figure 14. Typical current consumption in Stop mode with regulator in Low-power mode versus temperature at V_{DD} = 3.3 V and 3.6 V

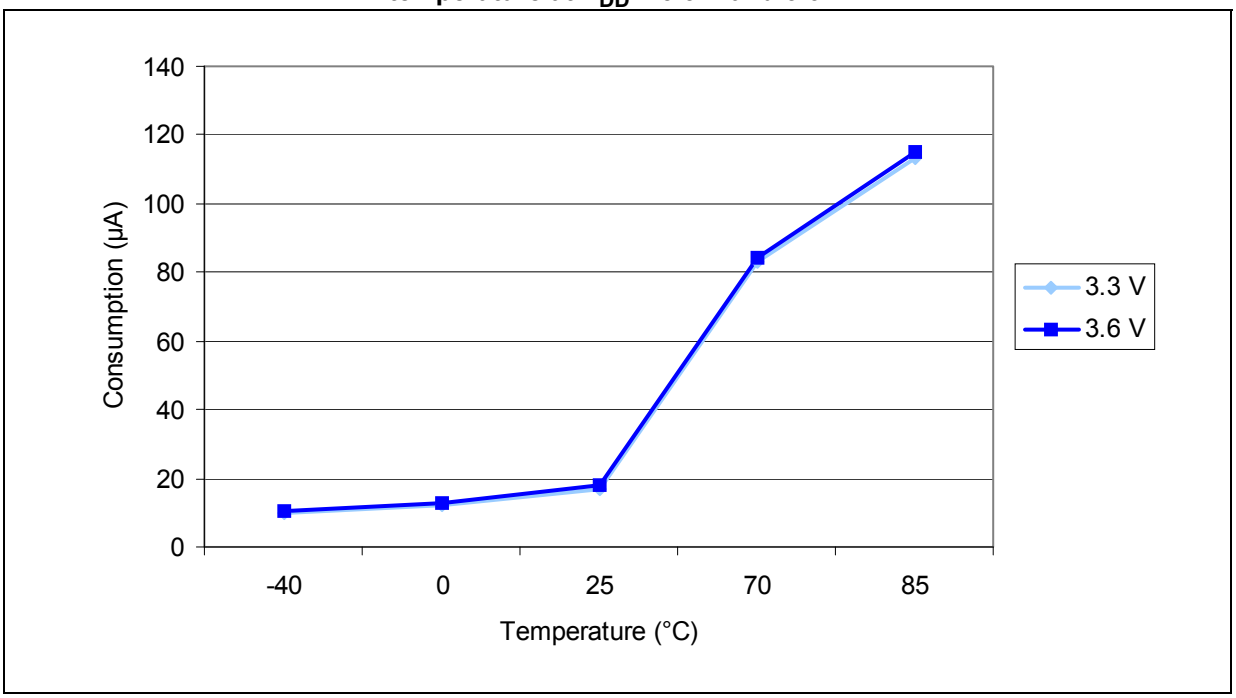
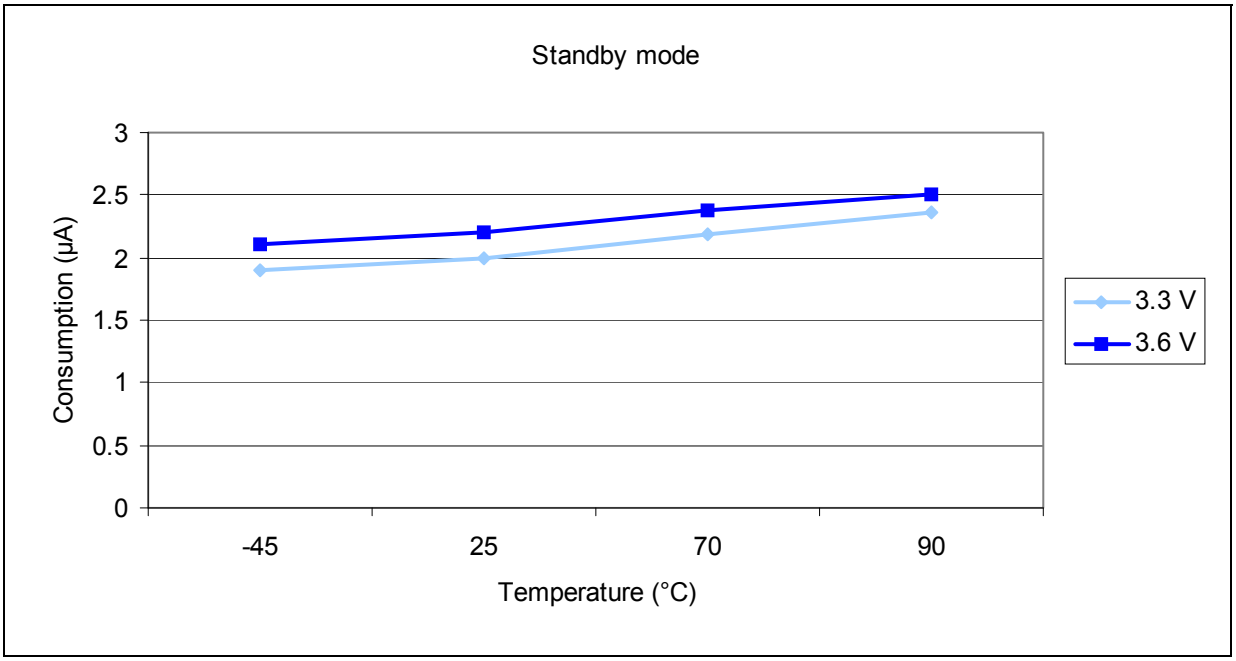


Figure 15. Typical current consumption in Standby mode versus temperature at V_{DD} = 3.3 V and 3.6 V



Typical current consumption

The MCU is placed under the following conditions:

- All I/O pins are in input mode with a static value at V_{DD} or V_{SS} (no load)
- All peripherals are disabled except if it is explicitly mentioned
- The Flash access time is adjusted to f_{HCLK} frequency (0 wait state from 0 to 24 MHz, 1 wait state from 24 to 48 MHz)
- Prefetch is on (reminder: this bit must be set before clock setting and bus prescaling)
- When the peripherals are enabled $f_{PCLK1} = f_{HCLK/4}$, $f_{PCLK2} = f_{HCLK/2}$, $f_{ADCCLK} = f_{PCLK2}/4$

The parameters given in *Table 16* are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 8*.

Table 16. Typical current consumption in Run mode, code with data processing running from Flash

Symbol	Parameter	Conditions	f_{HCLK}	Typ(1) All peripherals enabled(2)	Typ(1) All peripherals disabled	Unit
I_{DD}	Supply current in Run mode	External clock(3)	48 MHz	24.2	18.6	mA
			36 MHz	19	14.8	
			24 MHz	12.9	10.1	
			16 MHz	9.3	7.4	
			8 MHz	5.5	4.6	
			4 MHz	3.3	2.8	
			2 MHz	2.2	1.9	
			1 MHz	1.6	1.45	
			500 kHz	1.3	1.25	
			125 kHz	1.08	1.06	
		Running on high speed internal RC (HSI), AHB prescaler used to reduce the frequency	48 MHz	23.5	17.9	
			36 MHz	18.3	14.1	
			24 MHz	12.2	9.5	
			16 MHz	8.5	6.8	
			8 MHz	4.9	4	
			4 MHz	2.7	2.2	
			2 MHz	1.6	1.4	
			1 MHz	1.02	0.9	
			500 kHz	0.73	0.67	
			125 kHz	0.5	0.48	

1. Typical values are measures at $T_A = 25$ °C, $V_{DD} = 3.3$ V.
2. Add an additional power consumption of 0.8 mA per ADC for the analog part. In applications, this consumption occurs only while the ADC is on (ADON bit is set in the ADC_CR2 register).

3. External clock is 8 MHz and PLL is on when f_{HCLK} > 8 MHz.

Table 17. Typical current consumption in Sleep mode, code running from Flash or RAM

Symbol	Parameter	Conditions	f_{HCLK}	Typ(1) All peripherals enabled(2)	Typ(1) All peripherals disabled	Unit
I_{DD}	Supply current in Sleep mode	External clock(3)	48 MHz	9.9	3.9	mA
			36 MHz	7.6	3.1	
			24 MHz	5.3	2.3	
			16 MHz	3.8	1.8	
			8 MHz	2.1	1.2	
			4 MHz	1.6	1.1	
			2 MHz	1.3	1	
			1 MHz	1.11	0.98	
			500 kHz	1.04	0.96	
			125 kHz	0.98	0.95	
		Running on High Speed Internal RC (HSI), AHB prescaler used to reduce the frequency	48 MHz	9.3	3.3	
			36 MHz	7	2.5	
			24 MHz	4.8	1.8	
			16 MHz	3.2	1.2	
			8 MHz	1.6	0.6	
			4 MHz	1	0.5	
			2 MHz	0.72	0.47	
			1 MHz	0.56	0.44	
			500 kHz	0.49	0.42	
			125 kHz	0.43	0.41	

1. Typical values are measures at T_A = 25 °C, V_{DD} = 3.3 V.
2. Add an additional power consumption of 0.8 mA per ADC for the analog part. In applications, this consumption occurs only while the ADC is on (ADON bit is set in the ADC_CR2 register).
3. External clock is 8 MHz and PLL is on when f_{HCLK} > 8 MHz.

2. The BusMatrix is automatically active when at least one master is ON.
3. Specific conditions for ADC: f_{HCLK} = 48 MHz, $f_{APB1} = f_{HCLK}/2$, $f_{APB2} = f_{HCLK}$, $f_{ADCCLK} = f_{APB2}/4$.
4. When ADON bit in the ADC_CR2 register is set to 1, there is an additional current consumption equal to 0, 65 mA. When we enable the ADC, there is an additional current consumption of 0,05 mA.

5.3.6 External clock source characteristics

High-speed external user clock generated from an external source

The characteristics given in *Table 19* result from tests performed using an high-speed external clock source, and under ambient temperature and supply voltage conditions summarized in *Table 8*.

Table 19. High-speed external user clock characteristics

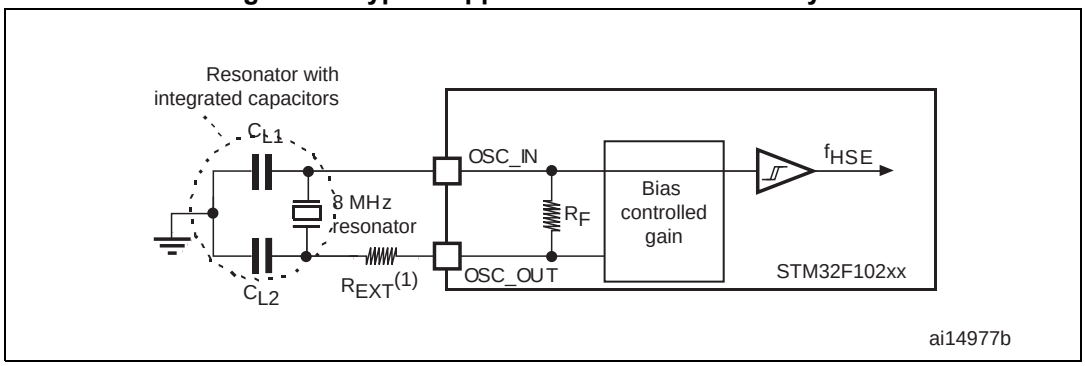
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSE_ext}	User external clock source frequency(1)	-	1	8	25	MHz
V_{HSEH}	OSC_IN input pin high level voltage		$0.7V_{DD}$	-	V_{DD}	V
V_{HSEL}	OSC_IN input pin low level voltage		V_{SS}	-	$0.3V_{DD}$	
$t_{w(HSE)}$ $t_{w(HSE)}$	OSC_IN high or low time(1)		5	-	-	ns
$t_{r(HSE)}$ $t_{f(HSE)}$	OSC_IN rise or fall time(1)		-	-	20	
$C_{in(HSE)}$	OSC_IN input capacitance(1)		-	5	-	pF
$DuCy_{(HSE)}$	Duty cycle		45	-	55	%
I_L	OSC_IN Input leakage current	$V_{SS} \leq V_{IN} \leq V_{DD}$		-	±1	µA

1. Guaranteed by design, not tested in production.

Low-speed external user clock generated from an external source

The characteristics given in *Table 20* result from tests performed using an low-speed external clock source, and under ambient temperature and supply voltage conditions summarized in *Table 8*.

Figure 18. Typical application with an 8 MHz crystal



1. R_{EXT} value depends on the crystal characteristics.

Low-speed external clock generated from a crystal/ceramic resonator

The low-speed external (LSE) clock can be supplied with a 32.768 kHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on characterization results obtained with typical external components specified in *Table 22*. In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Table 22. LSE oscillator characteristics (f_{LSE} = 32.768 kHz)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
R_F	Feedback resistor	-		-	5	-	MΩ
$C^{(1)}$	Recommended load capacitance versus equivalent serial resistance of the crystal (R_S)	R_S = 30 kΩ		-	-	15	pF
I_2	LSE driving current	V_{DD} = 3.3 V V_{IN} = V_{SS}		-	-	1.4	µA
g_m	Oscillator transconductance	-		5	-	-	µA/V
$t_{SU(LSE)}^{(2)}$	Startup time	V_{DD} is stabilized	T_A = 50 °C	-	1.5	-	s
			T_A = 25 °C	-	2.5	-	
			T_A = 10 °C	-	4.0	-	
			T_A = 0 °C	-	6.0	-	
			T_A = -10 °C	-	10.0	-	
			T_A = -20 °C	-	17.0	-	
			T_A = -30 °C	-	32.0	-	
			T_A = -40 °C	-	60.0	-	

1. Refer to the note and caution paragraphs below the table, and to the application note AN2867 “Oscillator design guide for ST microcontrollers”.
2. $t_{SU(LSE)}$ is the startup time measured from the moment it is enabled by software to a stabilized 32.768 kHz oscillation is reached. This value is measured for a standard crystal and can vary significantly with the crystal manufacturer, PCB layout and humidity.

2. Refer to application note AN2868 “STM32F10xxx internal RC oscillator (HSI) calibration” available from the ST website www.st.com.
3. Guaranteed by design, not tested in production.
4. Based on characterization, not tested in production.
5. The actual frequency of HSI oscillator may be impacted by a reflow, but does not drift out of the specified range.

Low-speed internal (LSI) RC oscillator

Table 24. LSI oscillator characteristics (1)

Symbol	Parameter	Min(2)	Typ	Max	Unit
f_{LSI}	Frequency	30	40	60	kHz
$t_{su(LSI)}$(3)	LSI oscillator startup time	-	-	85	µs
$I_{DD(LSI)}$(3)	LSI oscillator power consumption	-	0.65	1.2	µA

1. V_{DD} = 3 V, T_A = –40 to 85 °C unless otherwise specified.
2. Based on characterization, not tested in production.
3. Guaranteed by design, not tested in production.

Wakeup time from low-power mode

The wakeup times given in *Table 25* is measured on a wakeup phase with a 8-MHz HSI RC oscillator. The clock source used to wake up the device depends from the current operating mode:

- Stop or Standby mode: the clock source is the RC oscillator
- Sleep mode: the clock source is the clock that was set before entering Sleep mode.

All timings are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 8*.

Table 25. Low-power mode wakeup timings

Symbol	Parameter	Typ	Unit
$t_{WUSLEEP}$(1)	Wakeup from Sleep mode	1.8	µs
t_{WUSTOP}(1)	Wakeup from Stop mode (regulator in run mode)	3.6	µs
	Wakeup from Stop mode (regulator in low-power mode)	5.4	
$t_{WUSTDBY}$(1)	Wakeup from Standby mode	50	µs

1. The wakeup times are measured from the wakeup event to the point at which the user application code reads the first instruction.

5.3.8 PLL characteristics

The parameters given in *Table 26* are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 8*.

Table 34. I/O static characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{IL}	Low level input voltage	Standard IO input low level voltage	-	-	$0.28*(V_{DD}-2\ V)+0.8\ V$(1)	V
		IO FT(3) input low level voltage	-	-	$0.32*(V_{DD}-2V)+0.75\ V$(1)	
		All I/Os except BOOT0	-	-	$0.35V_{DD}$(2)	
V_{IH}	High level input voltage	Standard IO input high level voltage	$0.41*(V_{DD}-2\ V)+1.3\ V$(1)	-	-	
		IO FT(3) input high level voltage	$0.42*(V_{DD}-2\ V)+1\ V$(1)	-	-	
		All I/Os except BOOT0	$0.65V_{DD}$(2)	-	-	
V_{hys}	Standard IO Schmitt trigger voltage hysteresis(4)	-	200	-	-	mV
	IO FT Schmitt trigger voltage hysteresis(4)	-	5% V_{DD}(5)	-	-	
I_{lkg}	Input leakage current (6)	$V_{SS} \le V_{IN} \le V_{DD}$ Standard I/Os	-	-	±1	µA
		V_{IN} = 5 V I/O FT	-	-	3	
R_{PU}	Weak pull-up equivalent resistor(7)	$V_{IN} = V_{SS}$	30	40	50	kΩ
R_{PD}	Weak pull-down equivalent resistor(7)	$V_{IN} = V_{DD}$	30	40	50	
C_{IO}	I/O pin capacitance	-	-	5	-	pF

1. Data based on design simulation.
2. Tested in production.
3. FT = Five-volt tolerant, In order to sustain a voltage higher than V_{DD}+0.3 the internal pull-up/pull-down resistors must be disabled.
4. Hysteresis voltage between Schmitt trigger switching levels. Based on characterization, not tested in production.
5. With a minimum of 100 mV.
6. Leakage could be higher than max, if negative current is injected on adjacent pins.
7. Pull-up and pull-down resistors are designed with a true resistance in series with a switchable PMOS/NMOS. This PMOS/NMOS contribution to the series resistance is minimum (~10% order).

Input/output AC characteristics

The definition and values of input/output AC characteristics are given in *Figure 24* and *Table 36*, respectively.

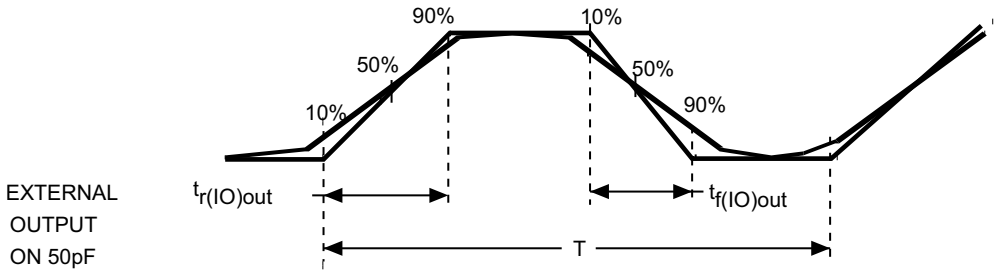
Unless otherwise specified, the parameters given in *Table 36* are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 8*.

Table 36. I/O AC characteristics(1)

MODEx [1:0] bit value(1)	Symbol	Parameter	Conditions	Max	Unit
10	$f_{max(IO)out}$	Maximum frequency(2)	C_L = 50 pF, V_{DD} = 2 V to 3.6 V	2	MHz
	$t_{f(IO)out}$	Output high to low level fall time	C_L = 50 pF, V_{DD} = 2 V to 3.6 V	125(3)	ns
	$t_{r(IO)out}$	Output low to high level rise time		125(3)	
01	$f_{max(IO)out}$	Maximum frequency(2)	C_L= 50 pF, V_{DD} = 2 V to 3.6 V	10	MHz
	$t_{f(IO)out}$	Output high to low level fall time	C_L= 50 pF, V_{DD} = 2 V to 3.6 V	25(3)	ns
	$t_{r(IO)out}$	Output low to high level rise time		25(3)	
11	$F_{max(IO)out}$	Maximum Frequency(2)	C_L= 30 pF, V_{DD} = 2.7 V to 3.6 V	50	MHz
			C_L = 50 pF, V_{DD} = 2.7 V to 3.6 V	30	MHz
			C_L = 50 pF, V_{DD} = 2 V to 2.7 V	20	MHz
	$t_{f(IO)out}$	Output high to low level fall time	C_L = 30 pF, V_{DD} = 2.7 V to 3.6 V	5(3)	ns
			C_L = 50 pF, V_{DD} = 2.7 V to 3.6 V	8(3)	
			C_L = 50 pF, V_{DD} = 2 V to 2.7 V	12(3)	
	$t_{r(IO)out}$	Output low to high level rise time	C_L = 30 pF, V_{DD} = 2.7 V to 3.6 V	5(3)	
			C_L = 50 pF, V_{DD} = 2.7 V to 3.6 V	8(3)	
			C_L = 50 pF, V_{DD} = 2 V to 2.7 V	12(3)	
-	t_{EXTIpw}	Pulse width of external signals detected by the EXTI controller	-	10	ns

1. The I/O speed is configured using the MODEx[1:0] bits. Refer to the STM32F10xxx reference manual for a description of GPIO Port configuration register.
2. The maximum frequency is defined in *Figure 24*.
3. Guaranteed by design, not tested in production.

Figure 24. I/O AC characteristics definition



Maximum frequency is achieved if $(t_r + t_f) \leq 2/3)T$ and if the duty cycle is (45-55%)
when loaded by 50pF

ai14131c

5.3.14 NRST pin characteristics

The NRST pin input driver uses CMOS technology. It is connected to a permanent pull-up resistor, R_{PU} (see *Table 34*).

Unless otherwise specified, the parameters given in *Table 37* are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 8*.

Table 37. NRST pin characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IL(NRST)}$(1)	NRST Input low level voltage	-	–0.5	-	0.8	V
$V_{IH(NRST)}$(1)	NRST Input high level voltage	-	2	-	V_{DD}+0.5	
$V_{hys(NRST)}$	NRST Schmitt trigger voltage hysteresis	-	-	200	-	mV
R_{PU}	Weak pull-up equivalent resistor(2)	$V_{IN} = V_{SS}$	30	40	50	kΩ
$V_{F(NRST)}$(1)	NRST Input filtered pulse	-	-	-	100	ns
$V_{NF(NRST)}$(1)	NRST Input not filtered pulse	-	300	-	-	ns

1. Guaranteed by design, not tested in production.
2. The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance must be minimum (~10% order).

Table 39. I^2C characteristics

Symbol	Parameter	Standard mode I^2C(1)(2)		Fast mode I^2C(1)(2)		Unit
		Min	Max	Min	Max	
$t_{w(SCLL)}$	SCL clock low time	4.7	-	1.3	-	µs
$t_{w(SCLH)}$	SCL clock high time	4.0	-	0.6	-	
$t_{su(SDA)}$	SDA setup time	250	-	100	-	ns
$t_{h(SDA)}$	SDA data hold time	-	3450(3)	-	900(3)	
$t_{r(SDA)}$ $t_{r(SCL)}$	SDA and SCL rise time	-	1000	-	300	
$t_{f(SDA)}$ $t_{f(SCL)}$	SDA and SCL fall time	-	300	-	300	
$t_{h(STA)}$	Start condition hold time	4.0	-	0.6	-	µs
$t_{su(STA)}$	Repeated Start condition setup time	4.7	-	0.6	-	
$t_{su(STO)}$	Stop condition setup time	4.0	-	0.6	-	µs
$t_{w(STO:STA)}$	Stop to Start condition time (bus free)	4.7	-	1.3	-	µs
t_{SP}	Pulse width of spikes that are suppressed by the analog filter	0	50(4)	0	50(4)	ns
C_b	Capacitive load for each bus line	-	400	-	400	pF

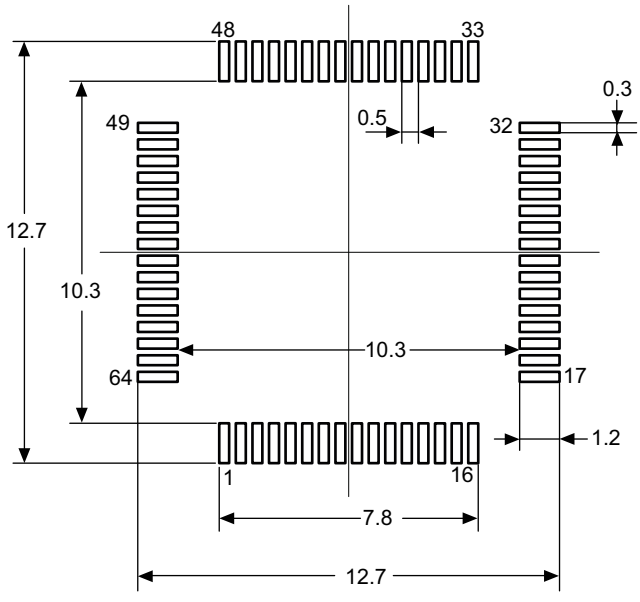
1. Values guaranteed by design, not tested in production.
2. f_{PCLK1} must be at least 2 MHz to achieve standard mode I^2C frequencies. It must be at least 4 MHz to achieve fast mode I^2C frequencies. It must be a multiple of 10 MHz to reach the 400 kHz maximum I2C fast mode clock.
3. The maximum Data hold time has only to be met if the interface does not stretch the low period of the SCL signal.
4. The analog filter minimum filtered spikes is above $t_{SP(max)}$ to ensure that spikes width up to $t_{SP(max)}$ are filtered.

Table 50. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
c	0.090	-	0.200	0.0035	-	0.0079
D	-	12.000	-	-	0.4724	-
D1	-	10.000	-	-	0.3937	-
D3	-	7.500	-	-	0.2953	-
E	-	12.000	-	-	0.4724	-
E1	-	10.000	-	-	0.3937	-
E3	-	7.500	-	-	0.2953	-
e	-	0.500	-	-	0.0197	-
K	0°	3.5°	7°	0°	3.5°	7°
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

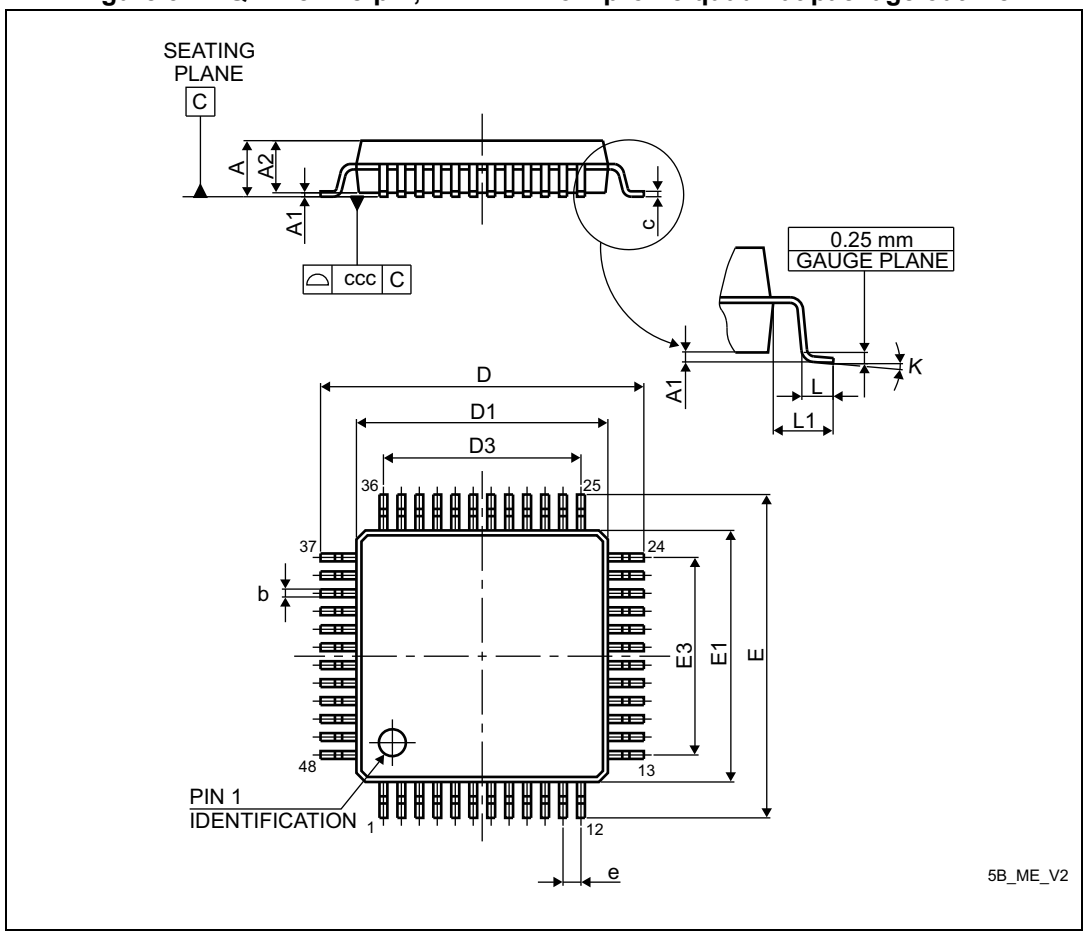
Figure 35. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package recommended footprint



1. Dimensions are expressed in millimeters.

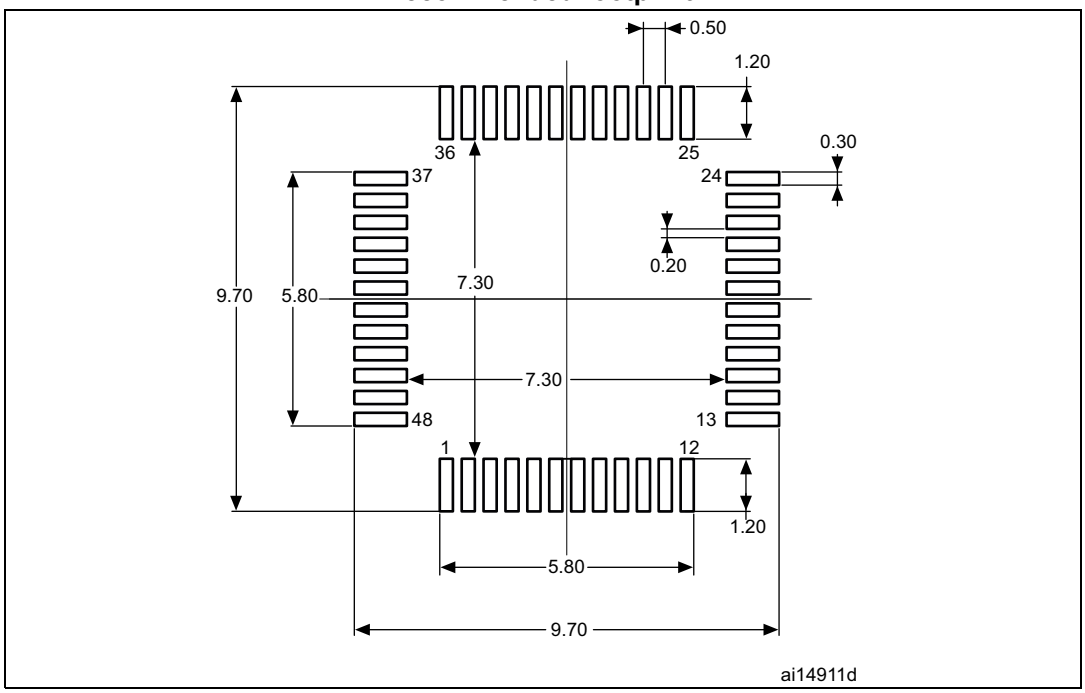
6.2 LQFP48 package information

Figure 37. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package outline



1. Drawing is not to scale.

Figure 38. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package recommended footprint

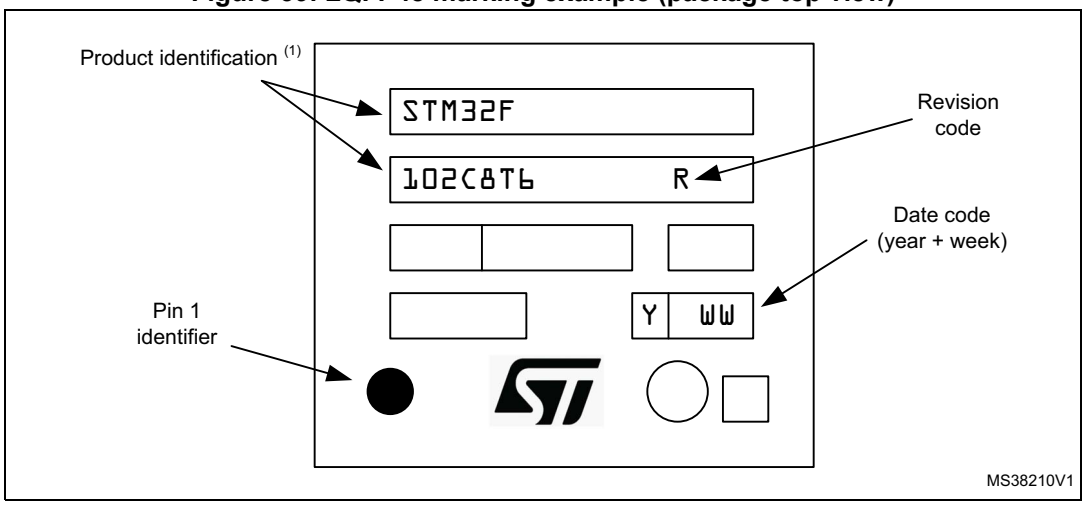


1. Dimensions are expressed in millimeters.

Device marking for LQFP48

Figure 39 gives an example of topside marking orientation versus pin 1 identifier location.

Figure 39. LQFP48 marking example (package top view)



1. Samples marked “ES” are to be considered as “Engineering Samples”: i.e. they are intended to be sent to customer for electrical compatibility evaluation and may be used to start customer qualification where specifically authorized by ST in writing. In no event ST will be liable for any customer usage in production. Only if ST has authorized in writing the customer qualification Engineering Samples can be used for reliability qualification trials.