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Applications of "[Embedded - Microcontrollers](#)"

Details

| | |
|----------------------------|---|
| Product Status | Not For New Designs |
| Core Processor | M16C/60 |
| Core Size | 16-Bit |
| Speed | 24MHz |
| Connectivity | I ² C, IEBus, UART/USART |
| Peripherals | DMA, WDT |
| Number of I/O | 85 |
| Program Memory Size | 128KB (128K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | 4K x 8 |
| RAM Size | 10K x 8 |
| Voltage - Supply (Vcc/Vdd) | 2.7V ~ 5.5V |
| Data Converters | A/D 26x10b; D/A 2x8b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 100-BQFP |
| Supplier Device Package | 100-QFP (14x20) |
| Purchase URL | https://www.e-xfl.com/product-detail/renesas-electronics-america/m30620fcfp-u7c |

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Table 1.11 Pin Characteristics for 128-Pin Package (2)

| Pin No. | Control Pin | Port | Interrupt Pin | Timer Pin | UART Pin | Analog Pin | Bus Control Pin |
|---------|-------------|-------|--------------------------|-----------|----------|------------|-----------------------------|
| 51 | | P5_6 | | | | | ALE |
| 52 | | P5_5 | | | | | $\overline{\text{HOLD}}$ |
| 53 | | P5_4 | | | | | $\overline{\text{HLDA}}$ |
| 54 | | P13_3 | | | | | |
| 55 | | P13_2 | | | | | |
| 56 | | P13_1 | | | | | |
| 57 | | P13_0 | | | | | |
| 58 | | P5_3 | | | | | BCLK |
| 59 | | P5_2 | | | | | $\overline{\text{RD}}$ |
| 60 | | P5_1 | | | | | $\overline{\text{WRH/BHE}}$ |
| 61 | | P5_0 | | | | | $\overline{\text{WRL/WR}}$ |
| 62 | | P12_7 | | | | | |
| 63 | | P12_6 | | | | | |
| 64 | | P12_5 | | | | | |
| 65 | | P4_7 | | | | | $\overline{\text{CS3}}$ |
| 66 | | P4_6 | | | | | $\overline{\text{CS2}}$ |
| 67 | | P4_5 | | | | | $\overline{\text{CS1}}$ |
| 68 | | P4_4 | | | | | $\overline{\text{CS0}}$ |
| 69 | | P4_3 | | | | | A19 |
| 70 | | P4_2 | | | | | A18 |
| 71 | | P4_1 | | | | | A17 |
| 72 | | P4_0 | | | | | A16 |
| 73 | | P3_7 | | | | | A15 |
| 74 | | P3_6 | | | | | A14 |
| 75 | | P3_5 | | | | | A13 |
| 76 | | P3_4 | | | | | A12 |
| 77 | | P3_3 | | | | | A11 |
| 78 | | P3_2 | | | | | A10 |
| 79 | | P3_1 | | | | | A9 |
| 80 | | P12_4 | | | | | |
| 81 | | P12_3 | | | | | |
| 82 | | P12_2 | | | | | |
| 83 | | P12_1 | | | | | |
| 84 | | P12_0 | | | | | |
| 85 | VCC2 | | | | | | |
| 86 | | P3_0 | | | | | A8(/-D7) |
| 87 | VSS | | | | | | |
| 88 | | P2_7 | | | | AN2_7 | A7(/D7/D6) |
| 89 | | P2_6 | | | | AN2_6 | A6(/D6/D5) |
| 90 | | P2_5 | | | | AN2_5 | A5(/D5/D4) |
| 91 | | P2_4 | | | | AN2_4 | A4(/D4/D3) |
| 92 | | P2_3 | | | | AN2_3 | A3(/D3/D2) |
| 93 | | P2_2 | | | | AN2_2 | A2(/D2/D1) |
| 94 | | P2_1 | | | | AN2_1 | A1(/D1/D0) |
| 95 | | P2_0 | | | | AN2_0 | A0(/D0/-) |
| 96 | | P1_7 | $\overline{\text{INT5}}$ | | | | D15 |
| 97 | | P1_6 | $\overline{\text{INT4}}$ | | | | D14 |
| 98 | | P1_5 | $\overline{\text{INT3}}$ | | | | D13 |
| 99 | | P1_4 | | | | | D12 |
| 100 | | P1_3 | | | | | D11 |

Table 1.13 Pin Characteristics for 100-Pin Package (1)

| Pin No. | | Control Pin | Port | Interrupt Pin | Timer Pin | UART Pin | Analog Pin | Bus Control Pin |
|---------|-----|-------------|------|---------------|------------------|----------------------|------------|-----------------|
| FP | GP | | | | | | | |
| 1 | 99 | | P9_6 | | | SOUT4 | ANEX1 | |
| 2 | 100 | | P9_5 | | | CLK4 | ANEX0 | |
| 3 | 1 | | P9_4 | | TB4IN | | DA1 | |
| 4 | 2 | | P9_3 | | TB3IN | | DA0 | |
| 5 | 3 | | P9_2 | | TB2IN | SOUT3 | | |
| 6 | 4 | | P9_1 | | TB1IN | SIN3 | | |
| 7 | 5 | | P9_0 | | TB0IN | CLK3 | | |
| 8 | 6 | BYTE | | | | | | |
| 9 | 7 | CNVSS | | | | | | |
| 10 | 8 | XCIN | P8_7 | | | | | |
| 11 | 9 | XCOUT | P8_6 | | | | | |
| 12 | 10 | RESET | | | | | | |
| 13 | 11 | XOUT | | | | | | |
| 14 | 12 | VSS | | | | | | |
| 15 | 13 | XIN | | | | | | |
| 16 | 14 | VCC1 | | | | | | |
| 17 | 15 | | P8_5 | NMI | | | | |
| 18 | 16 | | P8_4 | INT2 | ZP | | | |
| 19 | 17 | | P8_3 | INT1 | | | | |
| 20 | 18 | | P8_2 | INT0 | | | | |
| 21 | 19 | | P8_1 | | TA4IN/ \bar{U} | | | |
| 22 | 20 | | P8_0 | | TA4OUT/U | | | |
| 23 | 21 | | P7_7 | | TA3IN | | | |
| 24 | 22 | | P7_6 | | TA3OUT | | | |
| 25 | 23 | | P7_5 | | TA2IN/ \bar{W} | | | |
| 26 | 24 | | P7_4 | | TA2OUT/W | | | |
| 27 | 25 | | P7_3 | | TA1IN/ \bar{V} | CTS2/RTS2 | | |
| 28 | 26 | | P7_2 | | TA1OUT/V | CLK2 | | |
| 29 | 27 | | P7_1 | | TA0IN/TB5IN | RXD2/SCL2 | | |
| 30 | 28 | | P7_0 | | TA0OUT | TXD2/SDA2 | | |
| 31 | 29 | | P6_7 | | | TXD1/SDA1 | | |
| 32 | 30 | | P6_6 | | | RXD1/SCL1 | | |
| 33 | 31 | | P6_5 | | | CLK1 | | |
| 34 | 32 | | P6_4 | | | CTS1/RTS1/CTS0/CLKS1 | | |
| 35 | 33 | | P6_3 | | | TXD0/SDA0 | | |
| 36 | 34 | | P6_2 | | | RXD0/SCL0 | | |
| 37 | 35 | | P6_1 | | | CLK0 | | |
| 38 | 36 | | P6_0 | | | CTS0/RTS0 | | |
| 39 | 37 | | P5_7 | | | | | RDY/CLKOUT |
| 40 | 38 | | P5_6 | | | | | ALE |
| 41 | 39 | | P5_5 | | | | | HOLD |
| 42 | 40 | | P5_4 | | | | | HLAD |
| 43 | 41 | | P5_3 | | | | | BCLK |
| 44 | 42 | | P5_2 | | | | | RD |
| 45 | 43 | | P5_1 | | | | | WRH/BHE |
| 46 | 44 | | P5_0 | | | | | WRL/WR |
| 47 | 45 | | P4_7 | | | | | CS3 |
| 48 | 46 | | P4_6 | | | | | CS2 |
| 49 | 47 | | P4_5 | | | | | CS1 |
| 50 | 48 | | P4_4 | | | | | CS0 |

1.6 Pin Description

Table 1.17 Pin Description (100-pin and 128-pin Version) (1)

| Signal Name | Pin Name | I/O Type | Power Supply ⁽³⁾ | Description |
|--------------------------------------|-------------------------|----------|-----------------------------|---|
| Power supply input | VCC1,VCC2 VSS | I | – | Apply 2.7 to 5.5 V to the VCC1 and VCC2 pins and 0 V to the VSS pin. The VCC apply condition is that $VCC1 \geq VCC2$. (1, 2) |
| Analog power supply input | AVCC AVSS | I | VCC1 | Applies the power supply for the A/D converter. Connect the AVCC pin to VCC1. Connect the AVSS pin to VSS. |
| Reset input | RESET | I | VCC1 | The microcomputer is in a reset state when applying "L" to the this pin. |
| CNVSS | CNVSS | I | VCC1 | Switches processor mode. Connect this pin to VSS to when after a reset to start up in single-chip mode. Connect this pin to VCC1 to start up in microprocessor mode. |
| External data bus width select input | BYTE | I | VCC1 | Switches the data bus in external memory space. The data bus is 16 bits long when the this pin is held "L" and 8 bits long when the this pin is held "H". Set it to either one. Connect this pin to VSS when an single-chip mode. |
| Bus control pins ⁽⁴⁾ | D0 to D7 | I/O | VCC2 | Inputs and outputs data (D0 to D7) when these pins are set as the separate bus. |
| | D8 to D15 | I/O | VCC2 | Inputs and outputs data (D8 to D15) when external 16-bit data bus is set as the separate bus. |
| | A0 to A19 | O | VCC2 | Output address bits (A0 to A19). |
| | A0/D0 to A7/D7 | I/O | VCC2 | Input and output data (D0 to D7) and output address bits (A0 to A7) by timesharing when external 8-bit data bus are set as the multiplexed bus. |
| | A1/D0 to A8/D7 | I/O | VCC2 | Input and output data (D0 to D7) and output address bits (A1 to A8) by timesharing when external 16-bit data bus are set as the multiplexed bus. |
| | CS0 to CS3 | O | VCC2 | Output CS0 to CS3 signals. CS0 to CS3 are chip-select signals to specify an external space. |
| | WRL/WR WRH/BHE RD | O | VCC2 | Output WRL, WRH, (WR, BHE), RD signals. WRL and WRH or BHE and WR can be switched by program. • WRL, WRH and RD are selected The WRL signal becomes "L" by writing data to an even address in an external memory space. The WRH signal becomes "L" by writing data to an odd address in an external memory space. The RD pin signal becomes "L" by reading data in an external memory space. • WR, BHE and RD are selected The WR signal becomes "L" by writing data in an external memory space. The RD signal becomes "L" by reading data in an external memory space. The BHE signal becomes "L" by accessing an odd address. Select WR, BHE and RD for an external 8-bit data bus. |
| | ALE | O | VCC2 | ALE is a signal to latch the address. |
| | HOLD | I | VCC2 | While the HOLD pin is held "L", the microcomputer is placed in a hold state. |
| | HLDA | O | VCC2 | In a hold state, HLDA outputs a "L" signal. |
| | RDY | I | VCC2 | While applying a "L" signal to the RDY pin, the microcomputer is placed in a wait state. |

I : Input O : Output I/O : Input and output

Power Supply : Power supplies which relate to the external bus pins are separated as VCC2, thus they can be interfaced using the different voltage as VCC1.

NOTES:

1. In this manual, hereafter, VCC refers to VCC1 unless otherwise noted.
2. In M16C/62PT, apply 4.0 to 5.5 V to the VCC1 and VCC2 pins. Also the apply condition is that $VCC1 = VCC2$.
3. When use $VCC1 > VCC2$, contacts due to some points or restrictions to be checked.
4. Bus control pins in M16C/62PT cannot be used.

Table 1.18 Pin Description (100-pin and 128-pin Version) (2)

| Signal Name | Pin Name | I/O Type | Power Supply ⁽¹⁾ | Description |
|---|--|----------|-----------------------------|--|
| Main clock input | XIN | I | VCC1 | I/O pins for the main clock generation circuit. Connect a ceramic resonator or crystal oscillator between XIN and XOUT ⁽³⁾ . To use the external clock, input the clock from XIN and leave XOUT open. |
| Main clock output | XOUT | O | VCC1 | |
| Sub clock input | XCIN | I | VCC1 | I/O pins for a sub clock oscillation circuit. Connect a crystal oscillator between XCIN and XCOUT ⁽³⁾ . To use the external clock, input the clock from XCIN and leave XCOUT open. |
| Sub clock output | XCOUT | O | VCC1 | |
| BCLK output ⁽²⁾ | BCLK | O | VCC2 | Outputs the BCLK signal. |
| Clock output | CLKOUT | O | VCC2 | The clock of the same cycle as f _C , f ₈ , or f ₃₂ is outputted. |
| $\overline{\text{INT}}$ interrupt input | $\overline{\text{INT0}}$ to $\overline{\text{INT2}}$ | I | VCC1 | Input pins for the $\overline{\text{INT}}$ interrupt. |
| | $\overline{\text{INT3}}$ to $\overline{\text{INT5}}$ | I | VCC2 | |
| $\overline{\text{NMI}}$ interrupt input | $\overline{\text{NMI}}$ | I | VCC1 | Input pin for the $\overline{\text{NMI}}$ interrupt. Pin states can be read by the P8_5 bit in the P8 register. |
| Key input interrupt input | $\overline{\text{KI0}}$ to $\overline{\text{KI3}}$ | I | VCC1 | Input pins for the key input interrupt. |
| Timer A | TA0OUT to TA4OUT | I/O | VCC1 | These are timer A0 to timer A4 I/O pins. (however, output of TA0OUT for the N-channel open drain output.) |
| | TA0IN to TA4IN | I | VCC1 | These are timer A0 to timer A4 input pins. |
| | ZP | I | VCC1 | Input pin for the Z-phase. |
| Timer B | TB0IN to TB5IN | I | VCC1 | These are timer B0 to timer B5 input pins. |
| Three-phase motor control output | U, $\overline{\text{U}}$, V, $\overline{\text{V}}$, W, $\overline{\text{W}}$ | O | VCC1 | These are Three-phase motor control output pins. |
| Serial interface | $\overline{\text{CTS0}}$ to $\overline{\text{CTS2}}$ | I | VCC1 | These are send control input pins. |
| | $\overline{\text{RTS0}}$ to $\overline{\text{RTS2}}$ | O | VCC1 | These are receive control output pins. |
| | CLK0 to CLK4 | I/O | VCC1 | These are transfer clock I/O pins. |
| | RXD0 to RXD2 | I | VCC1 | These are serial data input pins. |
| | SIN3, SIN4 | I | VCC1 | These are serial data input pins. |
| | TXD0 to TXD2 | O | VCC1 | These are serial data output pins. (however, output of TXD2 for the N-channel open drain output.) |
| | SOUT3, SOUT4 | O | VCC1 | These are serial data output pins. |
| | CLKS1 | O | VCC1 | This is output pin for transfer clock output from multiple pins function. |
| I ² C mode | SDA0 to SDA2 | I/O | VCC1 | These are serial data I/O pins. (however, output of SDA2 for the N-channel open drain output.) |
| | SCL0 to SCL2 | I/O | VCC1 | These are transfer clock I/O pins. (however, output of SCL2 for the N-channel open drain output.) |

I : Input O : Output I/O : Input and output

NOTES:

1. When use VCC1 > VCC2, contacts due to some points or restrictions to be checked.
2. This pin function in M16C/62PT cannot be used.
3. Ask the oscillator maker the oscillation characteristic.

2.2 Address Registers (A0 and A1)

The register A0 consists of 16 bits, and is used for address register indirect addressing and address register relative addressing. They also are used for transfers and logic/logic operations. A1 is the same as A0.

In some instructions, registers A1 and A0 can be combined for use as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is configured with 16 bits, and is used for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is configured with 20 bits, indicating the start address of an interrupt vector table.

2.5 Program Counter (PC)

PC is configured with 20 bits, indicating the address of an instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

Stack pointer (SP) comes in two types: USP and ISP, each configured with 16 bits.

Your desired type of stack pointer (USP or ISP) can be selected by the U flag of FLG.

2.7 Static Base Register (SB)

SB is configured with 16 bits, and is used for SB relative addressing.

2.8 Flag Register (FLG)

FLG consists of 11 bits, indicating the CPU status.

2.8.1 Carry Flag (C Flag)

This flag retains a carry, borrow, or shift-out bit that has occurred in the arithmetic/logic unit.

2.8.2 Debug Flag (D Flag)

The D flag is used exclusively for debugging purpose. During normal use, it must be set to “0”.

2.8.3 Zero Flag (Z Flag)

This flag is set to “1” when an arithmetic operation resulted in 0; otherwise, it is “0”.

2.8.4 Sign Flag (S Flag)

This flag is set to “1” when an arithmetic operation resulted in a negative value; otherwise, it is “0”.

2.8.5 Register Bank Select Flag (B Flag)

Register bank 0 is selected when this flag is “0”; register bank 1 is selected when this flag is “1”.

2.8.6 Overflow Flag (O Flag)

This flag is set to “1” when the operation resulted in an overflow; otherwise, it is “0”.

2.8.7 Interrupt Enable Flag (I Flag)

This flag enables a maskable interrupt.

Maskable interrupts are disabled when the I flag is “0”, and are enabled when the I flag is “1”. The I flag is cleared to “0” when the interrupt request is accepted.

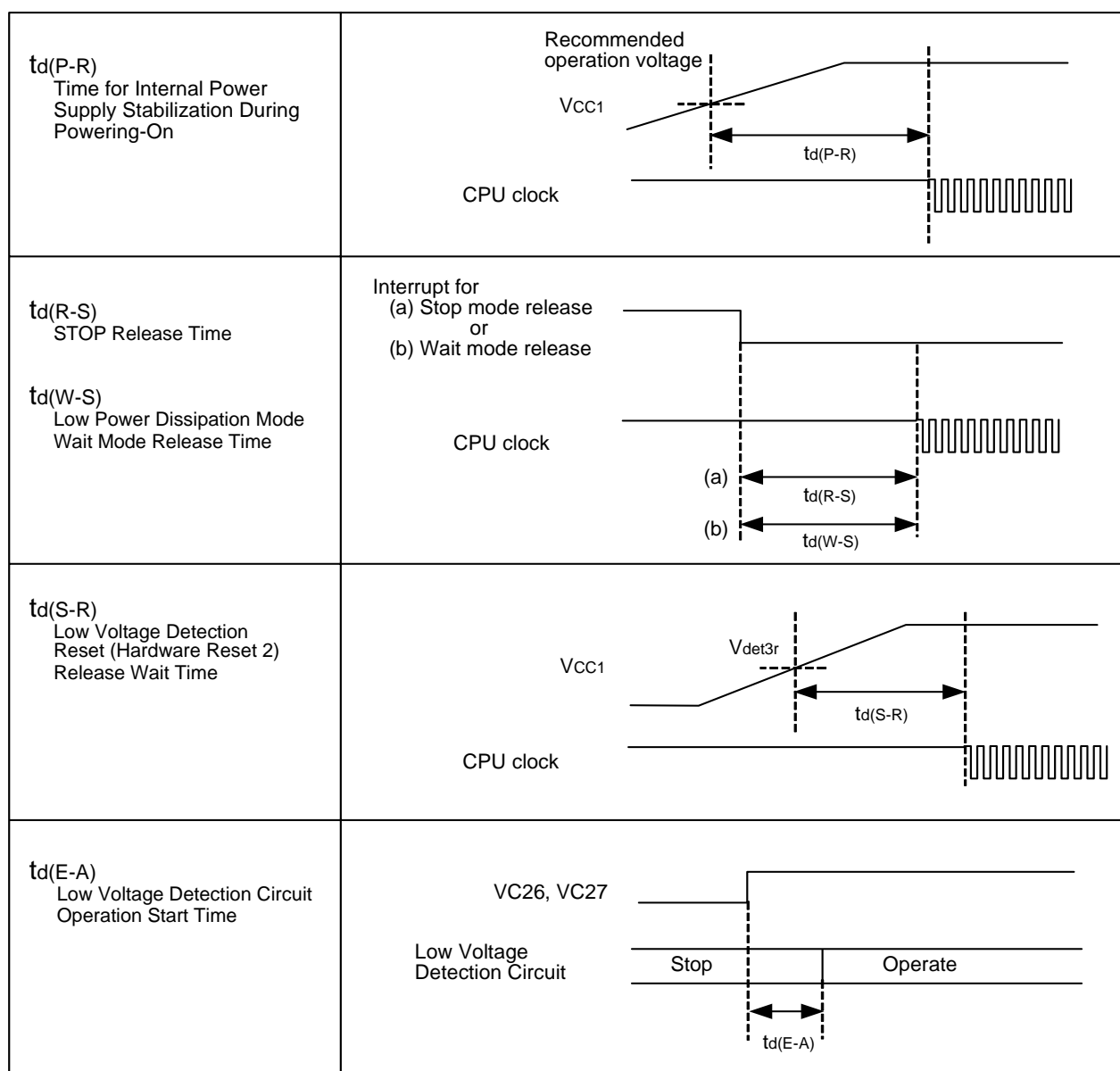


Figure 5.1 Power Supply Circuit Timing Diagram

Table 5.12 Electrical Characteristics (2) ⁽¹⁾

| Symbol | Parameter | | Measuring Condition | | Standard | | | Unit | |
|--------|--|--|--------------------------|--|----------|------|------|------|--|
| | | | | | Min. | Typ. | Max. | | |
| Icc | Power Supply Current (Vcc1=Vcc2=4.0V to 5.5V) | In single-chip mode, the output pins are open and other pins are Vss | Mask ROM | f(BCLK)=24MHz No division, PLL operation | | 14 | 20 | mA | |
| | | | | No division, On-chip oscillation | | 1 | | mA | |
| | | | Flash Memory | f(BCLK)=24MHz, No division, PLL operation | | 18 | 27 | mA | |
| | | | | No division, On-chip oscillation | | 1.8 | | mA | |
| | | | Flash Memory Program | f(BCLK)=10MHz, VCC1=5.0V | | 15 | | mA | |
| | | | Flash Memory Erase | f(BCLK)=10MHz, VCC1=5.0V | | 25 | | mA | |
| | | | Mask ROM | f(XCIN)=32kHz Low power dissipation mode, ROM ⁽³⁾ | | 25 | | μA | |
| | | | Flash Memory | f(BCLK)=32kHz Low power dissipation mode, RAM ⁽³⁾ | | 25 | | μA | |
| | | | | f(BCLK)=32kHz Low power dissipation mode, Flash Memory ⁽³⁾ | | 420 | | μA | |
| | | | | On-chip oscillation, Wait mode | | 50 | | μA | |
| | | | Mask ROM Flash Memory | f(BCLK)=32kHz Wait mode ⁽²⁾ , Oscillation capability High | | 7.5 | | μA | |
| | | | | f(BCLK)=32kHz Wait mode ⁽²⁾ , Oscillation capability Low | | 2.0 | | μA | |
| | | | | Stop mode Topr =25°C | | 0.8 | 3.0 | μA | |
| Idet4 | Low Voltage Detection Dissipation Current ⁽⁴⁾ | | | | | 0.7 | 4 | μA | |
| Idet3 | Reset Area Detection Dissipation Current ⁽⁴⁾ | | | | | 1.2 | 8 | μA | |

NOTES:

1. Referenced to V_{CC1}=V_{CC2}=4.2 to 5.5V, V_{SS} = 0V at T_{opr} = -20 to 85°C / -40 to 85°C, f(BCLK)=24MHz unless otherwise specified.
2. With one timer operated using fC32.
3. This indicates the memory in which the program to be executed exists.
4. I_{det} is dissipation current when the following bit is set to "1" (detection circuit enabled).
I_{det4}: VC27 bit in the VCR2 register
I_{det3}: VC26 bit in the VCR2 register

$$V_{CC1}=V_{CC2}=5V$$

Timing Requirements

($V_{CC1} = V_{CC2} = 5V$, $V_{SS} = 0V$, at $T_{opr} = -20$ to $85^{\circ}C$ / -40 to $85^{\circ}C$ unless otherwise specified)

Table 5.13 External Clock Input (XIN input) ⁽¹⁾

| Symbol | Parameter | Standard | | Unit |
|------------|---------------------------------------|----------|------|------|
| | | Min. | Max. | |
| t_c | External Clock Input Cycle Time | 62.5 | | ns |
| $t_{w(H)}$ | External Clock Input HIGH Pulse Width | 25 | | ns |
| $t_{w(L)}$ | External Clock Input LOW Pulse Width | 25 | | ns |
| t_r | External Clock Rise Time | | 15 | ns |
| t_f | External Clock Fall Time | | 15 | ns |

NOTES:

1. The condition is $V_{CC1}=V_{CC2}=3.0$ to $5.0V$.

Table 5.14 Memory Expansion Mode and Microprocessor Mode

| Symbol | Parameter | Standard | | Unit |
|---------------------|--|----------|----------|------|
| | | Min. | Max. | |
| $t_{ac1(RD-DB)}$ | Data Input Access Time (for setting with no wait) | | (NOTE 1) | ns |
| $t_{ac2(RD-DB)}$ | Data Input Access Time (for setting with wait) | | (NOTE 2) | ns |
| $t_{ac3(RD-DB)}$ | Data Input Access Time (when accessing multiplex bus area) | | (NOTE 3) | ns |
| $t_{su(DB-RD)}$ | Data Input Setup Time | 40 | | ns |
| $t_{su(RDY-BCLK)}$ | RDY Input Setup Time | 30 | | ns |
| $t_{su(HOLD-BCLK)}$ | HOLD Input Setup Time | 40 | | ns |
| $t_h(RD-DB)$ | Data Input Hold Time | 0 | | ns |
| $t_h(BCLK-RDY)$ | RDY Input Hold Time | 0 | | ns |
| $t_h(BCLK-HOLD)$ | HOLD Input Hold Time | 0 | | ns |

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 45 [ns]$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{(n-0.5) \times 10^9}{f(BCLK)} - 45 [ns] \quad n \text{ is "2" for 1-wait setting, "3" for 2-wait setting and "4" for 3-wait setting.}$$

3. Calculated according to the BCLK frequency as follows:

$$\frac{(n-0.5) \times 10^9}{f(BCLK)} - 45 [ns] \quad n \text{ is "2" for 2-wait setting, "3" for 3-wait setting.}$$

$$V_{CC1}=V_{CC2}=5V$$

Switching Characteristics

($V_{CC1} = V_{CC2} = 5V$, $V_{SS} = 0V$, at $T_{opr} = -20$ to $85^{\circ}C$ / -40 to $85^{\circ}C$ unless otherwise specified)

Table 5.29 Memory Expansion and Microprocessor Modes (for 2- to 3-wait setting, external area access and multiplex bus selection)

| Symbol | Parameter | | Standard | | Unit |
|------------------|---|-------------------|----------|------|------|
| | | | Min. | Max. | |
| $t_d(BCLK-AD)$ | Address Output Delay Time | See Figure 5.2 | | 25 | ns |
| $t_h(BCLK-AD)$ | Address Output Hold Time (in relation to BCLK) | | 4 | | ns |
| $t_h(RD-AD)$ | Address Output Hold Time (in relation to RD) | | (NOTE 1) | | ns |
| $t_h(WR-AD)$ | Address Output Hold Time (in relation to WR) | | (NOTE 1) | | ns |
| $t_d(BCLK-CS)$ | Chip Select Output Delay Time | | | 25 | ns |
| $t_h(BCLK-CS)$ | Chip Select Output Hold Time (in relation to BCLK) | | 4 | | ns |
| $t_h(RD-CS)$ | Chip Select Output Hold Time (in relation to RD) | | (NOTE 1) | | ns |
| $t_h(WR-CS)$ | Chip Select Output Hold Time (in relation to WR) | | (NOTE 1) | | ns |
| $t_d(BCLK-RD)$ | RD Signal Output Delay Time | | | 25 | ns |
| $t_h(BCLK-RD)$ | RD Signal Output Hold Time | | 0 | | ns |
| $t_d(BCLK-WR)$ | WR Signal Output Delay Time | | | 25 | ns |
| $t_h(BCLK-WR)$ | WR Signal Output Hold Time | | 0 | | ns |
| $t_d(BCLK-DB)$ | Data Output Delay Time (in relation to BCLK) | | | 40 | ns |
| $t_h(BCLK-DB)$ | Data Output Hold Time (in relation to BCLK) | | 4 | | ns |
| $t_d(DB-WR)$ | Data Output Delay Time (in relation to WR) | | (NOTE 2) | | ns |
| $t_h(WR-DB)$ | Data Output Hold Time (in relation to WR) | | (NOTE 1) | | ns |
| $t_d(BCLK-HLDA)$ | HLDA Output Delay Time | | | 40 | ns |
| $t_d(BCLK-ALE)$ | ALE Signal Output Delay Time (in relation to BCLK) | | | 15 | ns |
| $t_h(BCLK-ALE)$ | ALE Signal Output Hold Time (in relation to BCLK) | | -4 | | ns |
| $t_d(AD-ALE)$ | ALE Signal Output Delay Time (in relation to Address) | | (NOTE 3) | | ns |
| $t_h(AD-ALE)$ | ALE Signal Output Hold Time (in relation to Address) | | (NOTE 4) | | ns |
| $t_d(AD-RD)$ | RD Signal Output Delay From the End of Address | | 0 | | ns |
| $t_d(AD-WR)$ | WR Signal Output Delay From the End of Address | | 0 | | ns |
| $t_{dz}(RD-AD)$ | Address Output Floating Start Time | | | 8 | ns |

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 10 [ns]$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{(n - 0.5) \times 10^9}{f(BCLK)} - 40 [ns] \quad n \text{ is "2" for 2-wait setting, "3" for 3-wait setting.}$$

3. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 25 [ns]$$

4. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 15 [ns]$$

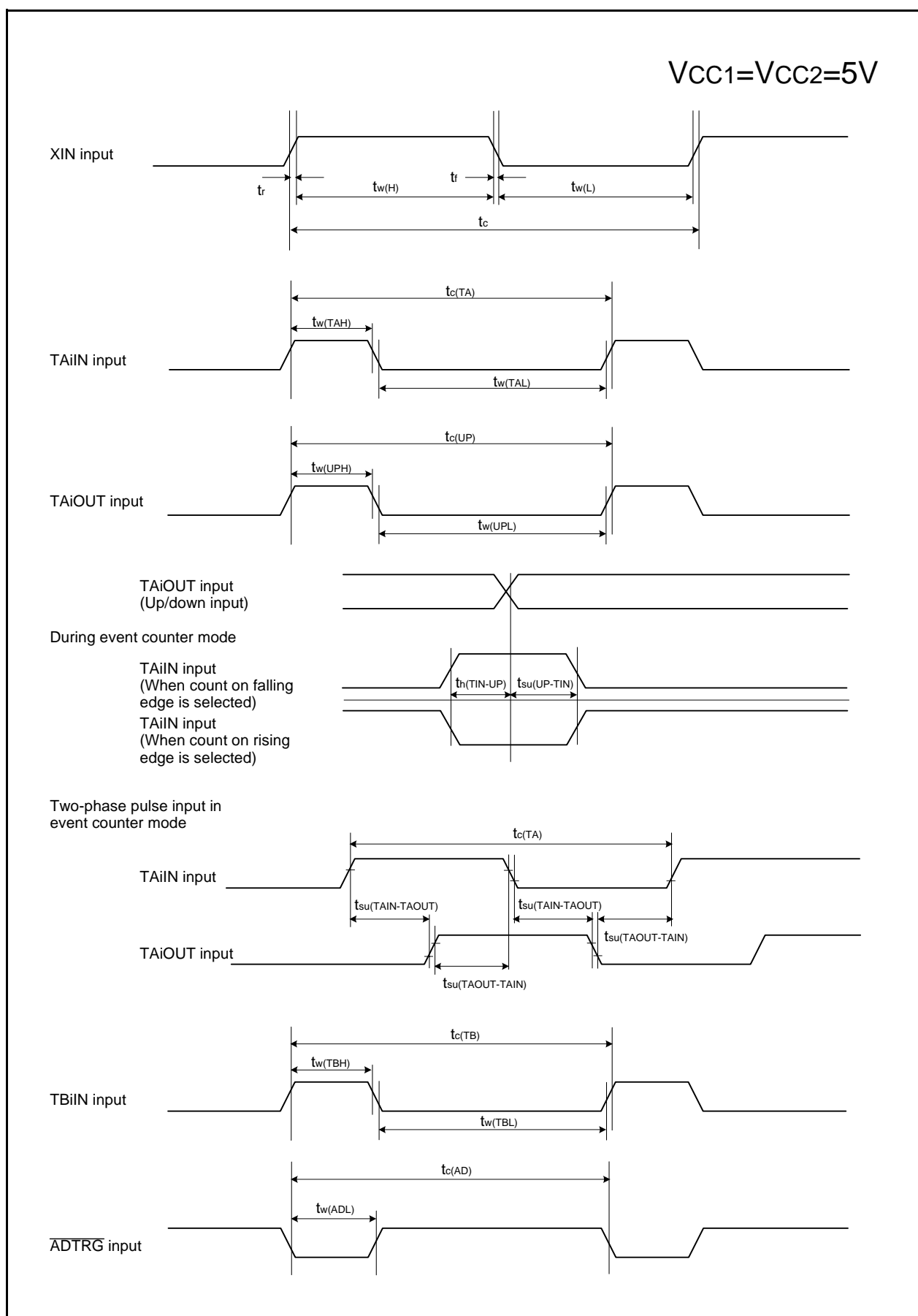


Figure 5.3 Timing Diagram (1)

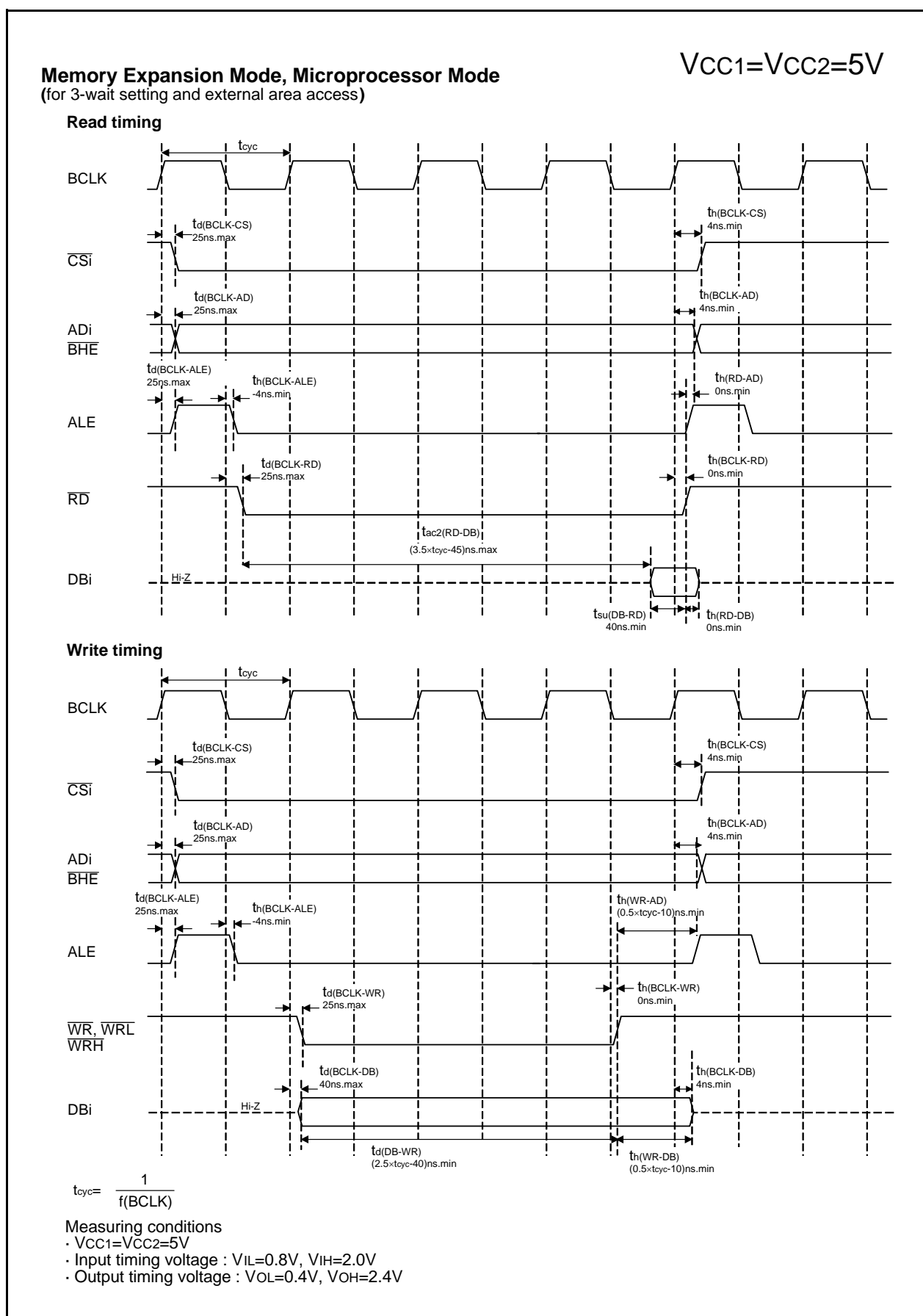


Figure 5.9 Timing Diagram (7)

$$V_{CC1}=V_{CC2}=3V$$

Table 5.30 Electrical Characteristics (1) ⁽¹⁾

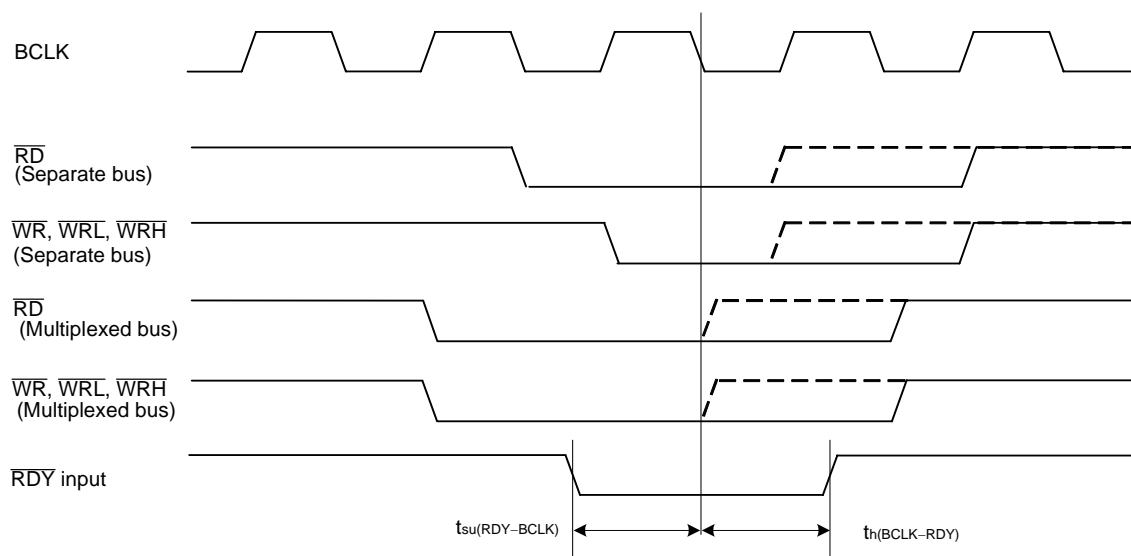
| Symbol | Parameter | | Measuring Condition | Standard | | | Unit |
|--------------------|------------------------------------|---|-------------------------|----------|-------|------|------|
| | | | | Min. | Typ. | Max. | |
| VOH | HIGH Output Voltage ⁽³⁾ | P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1 | IOH=−1mA | VCC1−0.5 | | VCC1 | V |
| | | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7 | IOH=−1mA ⁽²⁾ | VCC2−0.5 | | VCC2 | |
| VOH | HIGH Output Voltage XOUT | HIGHPOWER | IOH=−0.1mA | VCC1−0.5 | | VCC1 | V |
| | | LOWPOWER | IOH=−50μA | VCC1−0.5 | | VCC1 | |
| | HIGH Output Voltage XCOUT | HIGHPOWER | With no load applied | | 2.5 | | V |
| | | LOWPOWER | With no load applied | | 1.6 | | |
| VOL | LOW Output Voltage ⁽³⁾ | P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1 | IOL=1mA | | | 0.5 | V |
| | | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7 | IOL=1mA ⁽²⁾ | | | 0.5 | |
| VOL | LOW Output Voltage XOUT | HIGHPOWER | IOL=0.1mA | | | 0.5 | V |
| | | LOWPOWER | IOL=50μA | | | 0.5 | |
| | LOW Output Voltage XCOUT | HIGHPOWER | With no load applied | | 0 | | V |
| | | LOWPOWER | With no load applied | | 0 | | |
| VT+−VT− | Hysteresis | HOLD, RDY, TA0IN to TA4IN, TB0IN to TB5IN, INT0 to INT5, NMI, ADTRG, CTS0 to CTS2, CLK0 to CLK4, TA0OUT to TA4OUT, KI0 to KI3, RXD0 to RXD2, SCL0 to SCL2, SDA0 to SDA2, SIN3, SIN4 | | 0.2 | | 0.8 | V |
| VT+−VT− | Hysteresis | RESET | | 0.2 | (0.7) | 1.8 | V |
| I _{IH} | HIGH Input Current ⁽³⁾ | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1, XIN, RESET, CNVSS, BYTE | VI=3V | | | 4.0 | μA |
| I _{IL} | LOW Input Current ⁽³⁾ | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1, XIN, RESET, CNVSS, BYTE | VI=0V | | | −4.0 | μA |
| RPULLUP | Pull-Up Resistance ⁽³⁾ | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1 | VI=0V | 50 | 100 | 500 | kΩ |
| R _{FXIN} | Feedback Resistance XIN | | | | 3.0 | | MΩ |
| R _{FXCIN} | Feedback Resistance XCIN | | | | 25 | | MΩ |
| VRAM | RAM Retention Voltage | | At stop mode | 2.0 | | | V |

NOTES:

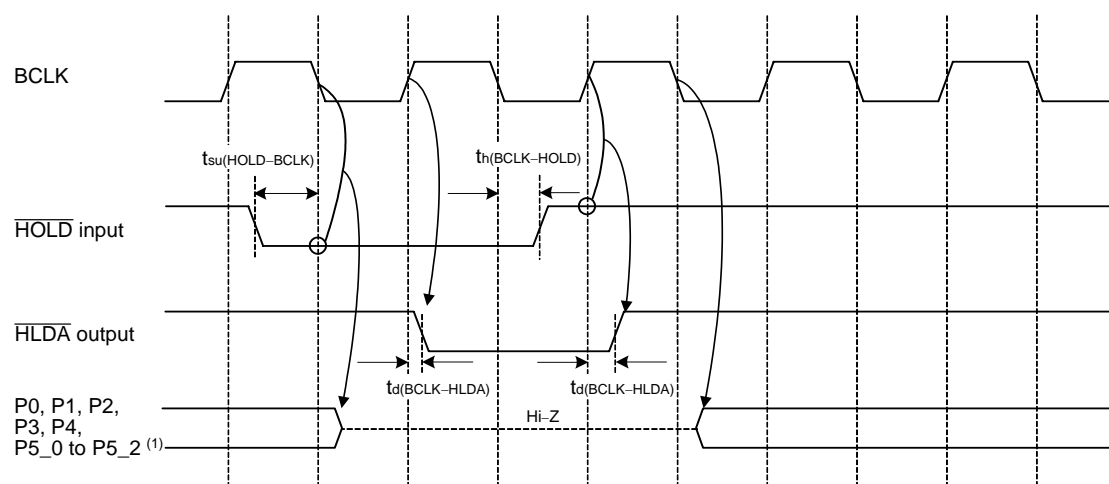
1. Referenced to VCC1 = VCC2 = 2.7 to 3.3V, VSS = 0V at T_{opr} = −20 to 85°C / −40 to 85°C, f(XIN)=10MHz no wait unless otherwise specified.
2. VCC1 for the port P6 to P11 and P14, and VCC2 for the port P0 to P5 and P12 to P13
3. There is no external connections for port P1_0 to P1_7, P4_4 to P4_7, P7_2 to P7_5 and P9_1 in 80-pin version.

Memory Expansion Mode, Microprocessor Mode

(Effective for setting with wait)

 $V_{CC1}=V_{CC2}=3V$ 

(Common to setting with wait and setting without wait)

**NOTES:**

- These pins are set to high-impedance regardless of the input level of the BYTE pin, PM06 bit in PM0 register and PM11 bit in PM1 register.

Measuring conditions :

- $V_{CC1}=V_{CC2}=3V$
- Input timing voltage : Determined with $V_{IL}=0.6V$, $V_{IH}=2.4V$
- Output timing voltage : Determined with $V_{OL}=1.5V$, $V_{OH}=1.5V$

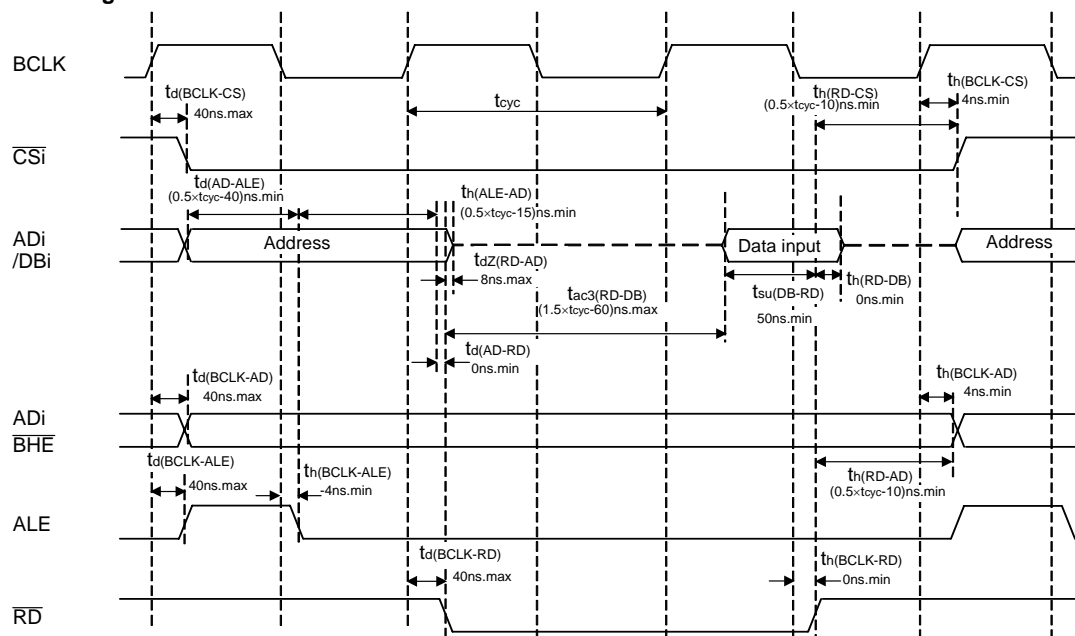
Figure 5.15 Timing Diagram (3)

Memory Expansion Mode, Microprocessor Mode

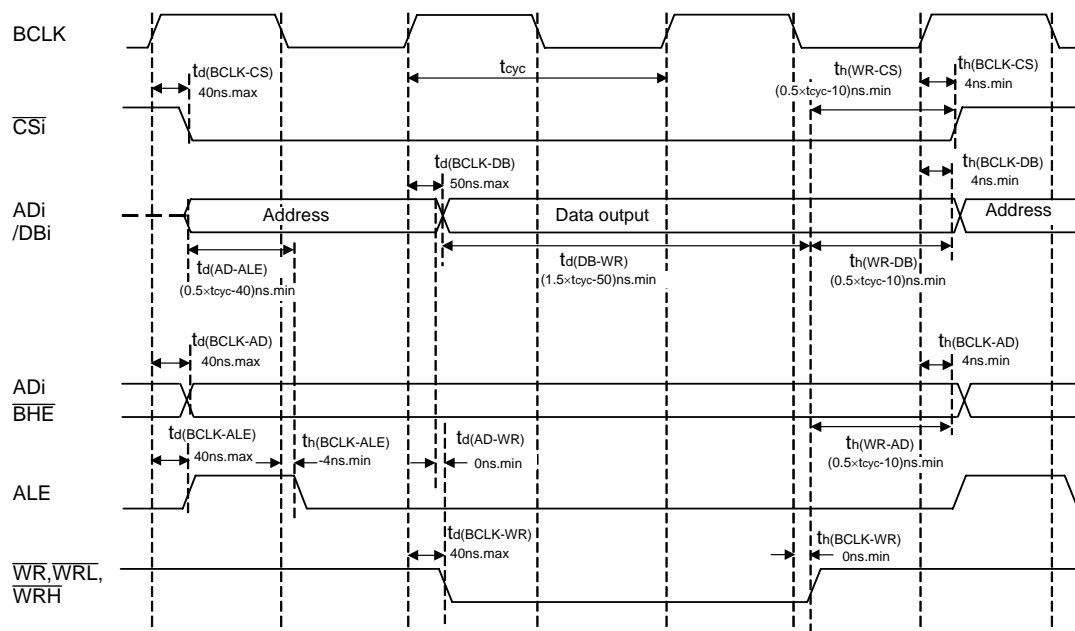
(For 2-wait setting, external area access and multiplex bus selection)

$$V_{CC1}=V_{CC2}=3V$$

Read timing



Write timing



$$t_{\text{cyc}} = \frac{1}{f(\text{BCLK})}$$

Measuring conditions

- $V_{CC1}=V_{CC2}=3V$
- Input timing voltage : $V_{IL}=0.6V$, $V_{IH}=2.4V$
- Output timing voltage : $V_{OL}=1.5V$, $V_{OH}=1.5V$

Figure 5.20 Timing Diagram (8)

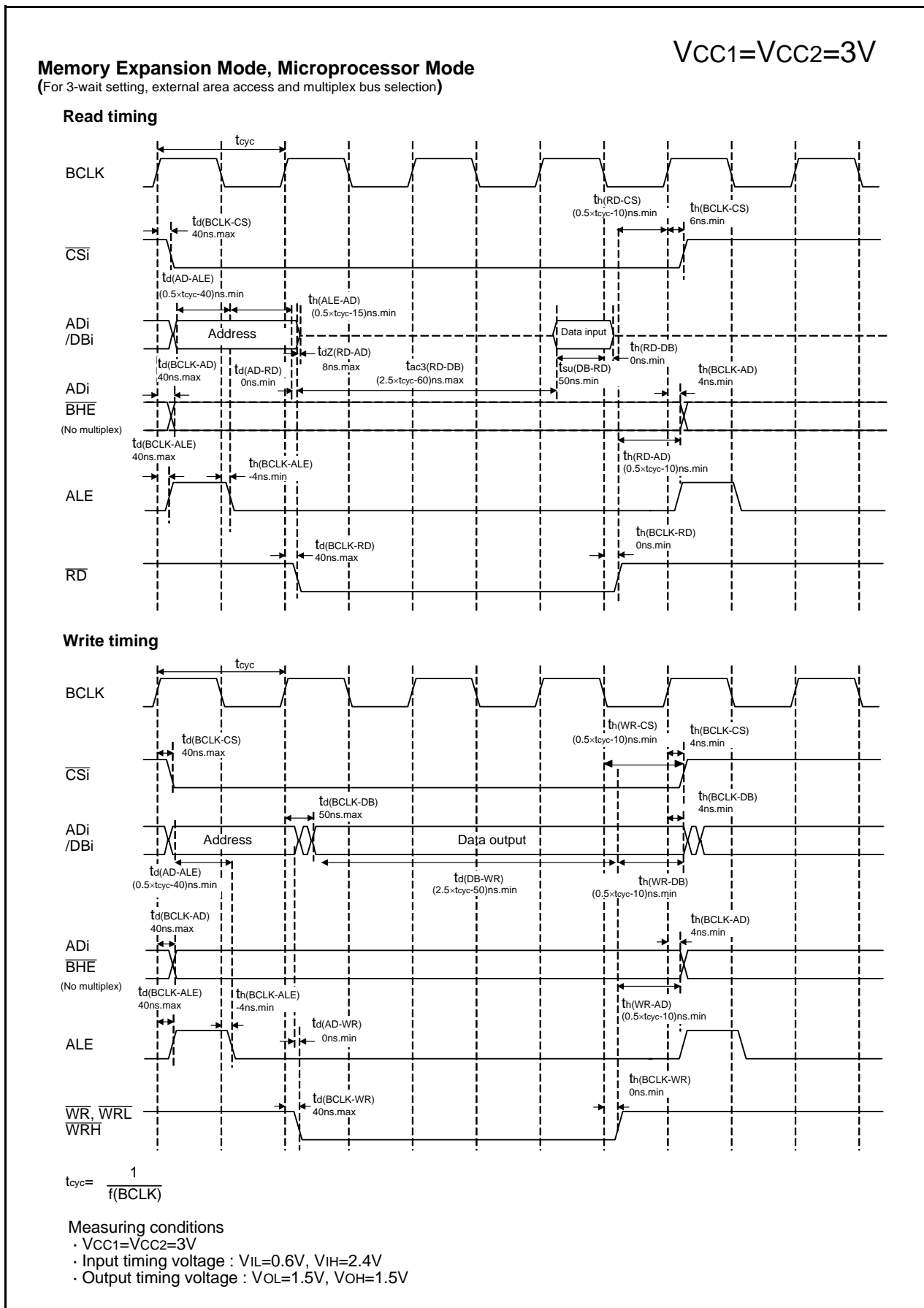


Figure 5.21 Timing Diagram (9)

Table 5.50 Recommended Operating Conditions (1) (1)

| Symbol | Parameter | | Standard | | | Unit |
|-------------------------------------|---|--|---------------------|------------------|---------------------|------|
| | | | Min. | Typ. | Max. | |
| V _{CC1} , V _{CC2} | Supply Voltage (V _{CC1} = V _{CC2}) | | 4.0 | 5.0 | 5.5 | V |
| AV _{CC} | Analog Supply Voltage | | | V _{CC1} | | V |
| V _{SS} | Supply Voltage | | | 0 | | V |
| AV _{SS} | Analog Supply Voltage | | | 0 | | V |
| V _{IH} | HIGH Input Voltage (4) | P3_1 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7 | 0.8V _{CC2} | | V _{CC2} | V |
| | | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 (during single-chip mode) | 0.8V _{CC2} | | V _{CC2} | V |
| | | P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1, XIN, RESET, CNVSS, BYTE | 0.8V _{CC1} | | V _{CC1} | V |
| | | P7_0, P7_1 | 0.8V _{CC1} | | 6.5 | V |
| V _{IL} | LOW Input Voltage (4) | P3_1 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7 | 0 | | 0.2V _{CC2} | V |
| | | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 (during single-chip mode) | 0 | | 0.2V _{CC2} | V |
| | | P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1, XIN, RESET, CNVSS, BYTE | 0 | | 0.2V _{CC} | V |
| I _{OH(peak)} | HIGH Peak Output Current (4) | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1 | | | -10.0 | mA |
| I _{OH(avg)} | HIGH Average Output Current (4) | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1 | | | -5.0 | mA |
| I _{OL(peak)} | LOW Peak Output Current (4) | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1 | | | 10.0 | mA |
| I _{OL(avg)} | LOW Average Output Current (4) | P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1 | | | 5.0 | mA |
| f(XIN) | Main Clock Input Oscillation Frequency | V _{CC1} =4.0V to 5.5V | 0 | | 16 | MHz |
| f(XCIN) | Sub-Clock Oscillation Frequency | | | 32.768 | 50 | kHz |
| f(Ring) | On-chip Oscillation Frequency | | 0.5 | 1 | 2 | MHz |
| f(PLL) | PLL Clock Oscillation Frequency | V _{CC1} =4.0V to 5.5V | 10 | | 24 | MHz |
| f(BCLK) | CPU Operation Clock | | 0 | | 24 | MHz |
| t _{su(PLL)} | PLL Frequency Synthesizer Stabilization Wait Time | V _{CC1} =5.5V | | | 20 | ms |

NOTES:

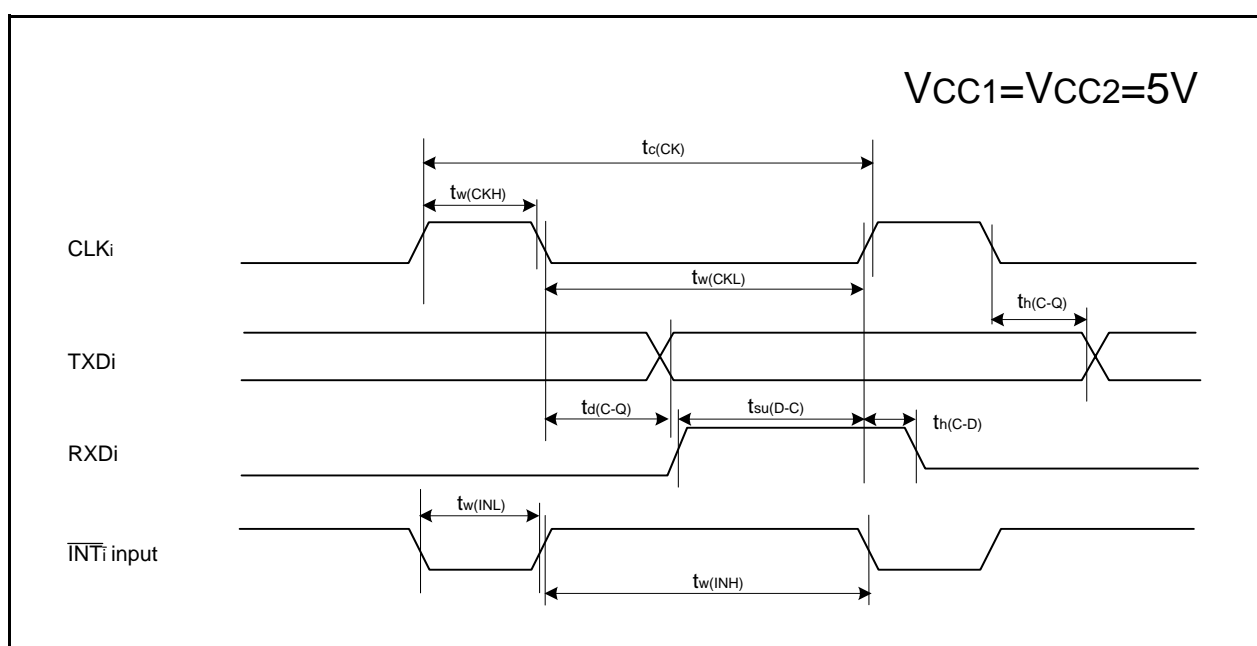
1. Referenced to V_{CC1} = V_{CC2} = 4.7 to 5.5V at T_{opr} = -40 to 85°C / -40 to 125°C unless otherwise specified.
T version = -40 to 85 °C, V version = -40 to 125 °C.
2. The Average Output Current is the mean value within 100ms.
3. The total I_{OL(peak)} for ports P0, P1, P2, P8_6, P8_7, P9, P10 P1, P14_0 and P14_1 must be 80mA max. The total I_{OL(peak)} for ports P3, P4, P5, P6, P7, P8_0 to P8_4, P12, and P13 must be 80mA max. The total I_{OH(peak)} for ports P0, P1, and P2 must be -40mA max. The total I_{OH(peak)} for ports P3, P4, P5, P12, and P13 must be -40mA max. The total I_{OH(peak)} for ports P6, P7, and P8_0 to P8_4 must be -40mA max. The total I_{OH(peak)} for ports P8_6, P8_7, P9, P10, P11, P14_0, and P14_1 must be -40mA max.
As for 80-pin version, the total I_{OL(peak)} for all ports and I_{OH(peak)} must be 80mA. max. due to one V_{CC} and one V_{SS}.
4. There is no external connections for port P1_0 to P1_7, P4_4 to P4_7, P7_2 to P7_5 and P9_1 in 80-pin version.

Table 5.58 Electrical Characteristics (2) ⁽¹⁾

| Symbol | Parameter | | Measuring Condition | | Standard | | | Unit |
|-----------------|--|--|--------------------------|--|----------|------|------|------|
| | | | | | Min. | Typ. | Max. | |
| I _{cc} | Power Supply Current (V _{CC1} =V _{CC2} =4.0V to 5.5V) | In single-chip mode, the output pins are open and other pins are V _{SS} | Mask ROM | f(BCLK)=24MHz No division, PLL operation | | 14 | 20 | mA |
| | | | | No division, On-chip oscillation | | 1 | | mA |
| | | | Flash Memory | f(BCLK)=24MHz, No division, PLL operation | | 18 | 27 | mA |
| | | | | No division, On-chip oscillation | | 1.8 | | mA |
| | | | Flash Memory Program | f(BCLK)=10MHz, V _{CC1} =5.0V | | 15 | | mA |
| | | | Flash Memory Erase | f(BCLK)=10MHz, V _{CC1} =5.0V | | 25 | | mA |
| | | | Mask ROM | f(XCIN)=32kHz Low power dissipation mode, ROM ⁽³⁾ | | 25 | | μA |
| | | | Flash Memory | f(BCLK)=32kHz Low power dissipation mode, RAM ⁽³⁾ | | 25 | | μA |
| | | | | f(BCLK)=32kHz Low power dissipation mode, Flash Memory ⁽³⁾ | | 420 | | μA |
| | | | | On-chip oscillation, Wait mode | | 50 | | μA |
| | | | Mask ROM Flash Memory | f(BCLK)=32kHz Wait mode ⁽²⁾ , Oscillation capability High | | 7.5 | | μA |
| | | | | f(BCLK)=32kHz Wait mode ⁽²⁾ , Oscillation capability Low | | 2.0 | | μA |
| | | | | Stop mode T _{opr} =25°C | | 2.0 | 6.0 | μA |
| | | | | Stop mode T _{opr} =85°C | | | 20 | μA |
| | | | | Stop mode T _{opr} =125°C | | | TBD | μA |

NOTES:

1. Referenced to V_{CC1}=V_{CC2}=4.0 to 5.5V, V_{SS} = 0V at T_{opr} = -40 to 85°C / -40 to 125°C, f(BCLK)=24MHz unless otherwise specified. T version = -40 to 85°C, V version = -40 to 125°C.
2. With one timer operated using fC32.
3. This indicates the memory in which the program to be executed exists.

**Figure 5.25 Timing Diagram (2)**

| REVISION HISTORY | | M16C/62P Group (M16C/62P, M16C/62PT) Hardware Manual | |
|------------------|--------------|--|---|
| Rev. | Date | Description | |
| | | Page | Summary |
| | | 33 34,74 36 38,55 41 41-43, 58-60 44 47-48 49-50 52 53 58 61 64-65 66-67 69 70-85 | Table 5.4 A-D Conversion Characteristics is revised. Table 5.5 D-A Conversion Characteristics revised. Table 5.6 to 5.7 and table 5.54 to 5.55 are revised. Table 5.11 is revised. Table 5.14 and 5.33 HLDA output deley time is deleted. Figure 5.1 is partly revised. Table 5.27 to 5.29 and table 5.46 to 48 HLDA output deley time is added. Figure 5.2 Timing Diagram (1) XIN input is added. Figure 5.5 to 5.6 Read timing DB → DBi Figure 5.7 to 5.8 Write timing DB → DBi Figure 5.10 DB → DBi Table 5.30 is revised. Figure 5.11 is partly revised. Figure 5.12 Timing Diagram (1) XIN input is added. Figure 5.15 to 5.16 Read timing DB → DBi Figure 5.17 to 5.18 Write timing DB → DBi Figure 5.20 DB → DBi Electrical Characteristics (M16C/62PT) is added. |
| 2.10 | Nov 07, 2003 | 8-9 23 71 72 | Table 1.5 to 1.7 Product List is partly revised. Note 1 is deleted. Table 3.1 is revised. Table 5.50 is revised. Table 5.51 is deleted. |
| 2.11 | Jan 06, 2004 | 16 17-18 31 | Table 1.9 NOTE 3 VCC1 VCC2 → VCC1 > VCC2 Table 1.10 to 1.11 NOTE 1 VCC1 VCC2 → VCC1 > VCC2 Table 5.2 Power Supply Ripple Allowable Frequency Unit MHz → kHz |
| 2.30 | Sep 01, 2004 | 12 18, 20 19,21 24 25 33 34 35 37 | Table 1.9 and Figure 1.5 are added. Table 1.11 to 1.13 are revised. Table 1.12 to 1.14 are revised. Figure 3.1 is partly revised. Note 3 is added. Note 6 is added. Table 5.3 is revised. Note 2 in Table 5.4 is added. Table 5.5 to 5.6 is partly revised. Table 5.8 is revised. Table 5.9 is revised. Table 5.11 is revised. |