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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	M16C/60
Core Size	16-Bit
Speed	24MHz
Connectivity	I ² C, IEBus, UART/USART
Peripherals	DMA, WDT
Number of I/O	50
Program Memory Size	-
Program Memory Type	ROMless
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 26x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LFQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/m30620sppg-u3c

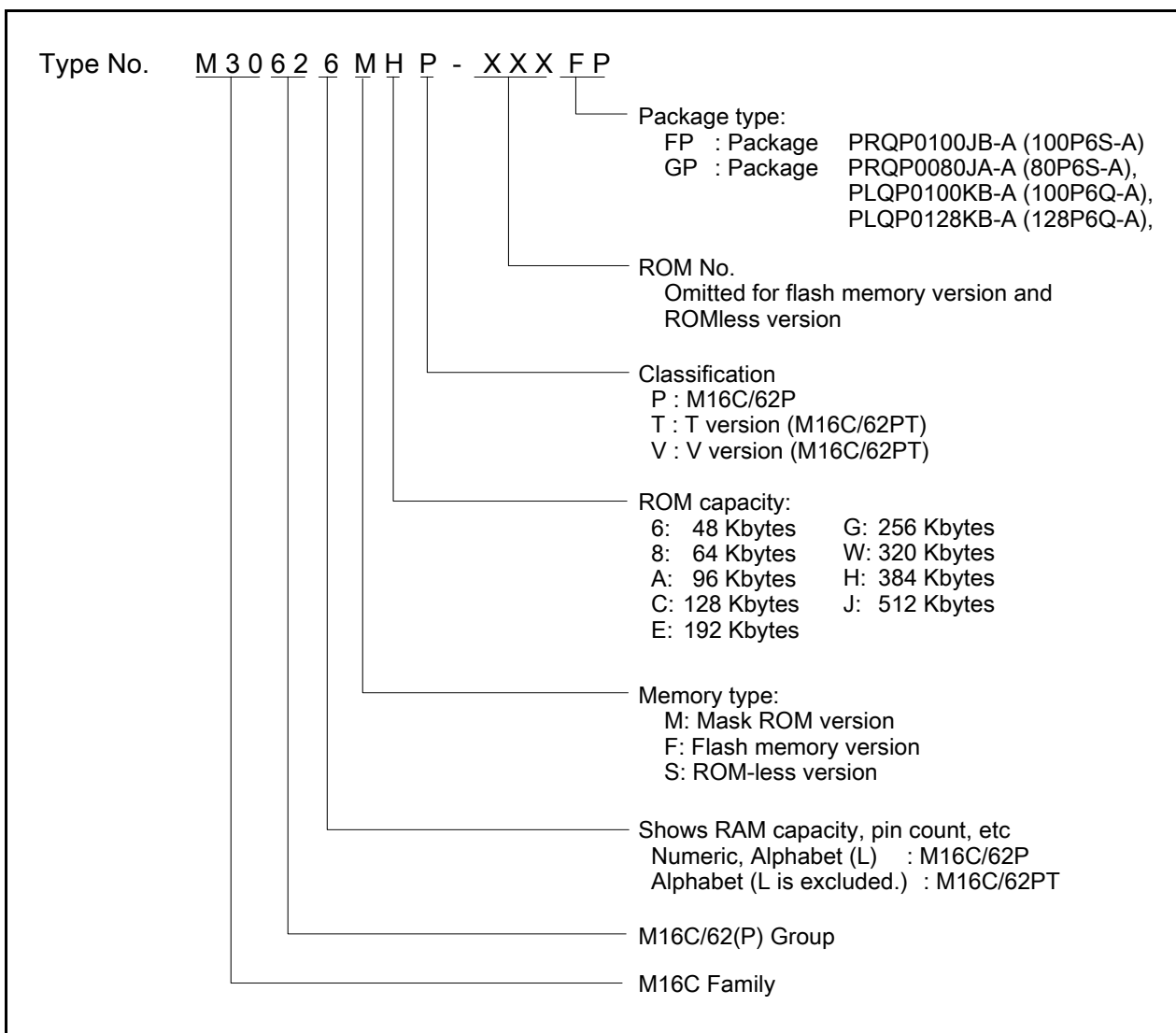


Figure 1.3 Type No., Memory Size, and Package

1.6 Pin Description

Table 1.17 Pin Description (100-pin and 128-pin Version) (1)

Signal Name	Pin Name	I/O Type	Power Supply ⁽³⁾	Description
Power supply input	VCC1,VCC2 VSS	I	–	Apply 2.7 to 5.5 V to the VCC1 and VCC2 pins and 0 V to the VSS pin. The VCC apply condition is that $VCC1 \geq VCC2$. (1, 2)
Analog power supply input	AVCC AVSS	I	VCC1	Applies the power supply for the A/D converter. Connect the AVCC pin to VCC1. Connect the AVSS pin to VSS.
Reset input	RESET	I	VCC1	The microcomputer is in a reset state when applying "L" to the this pin.
CNVSS	CNVSS	I	VCC1	Switches processor mode. Connect this pin to VSS to when after a reset to start up in single-chip mode. Connect this pin to VCC1 to start up in microprocessor mode.
External data bus width select input	BYTE	I	VCC1	Switches the data bus in external memory space. The data bus is 16 bits long when the this pin is held "L" and 8 bits long when the this pin is held "H". Set it to either one. Connect this pin to VSS when an single-chip mode.
Bus control pins ⁽⁴⁾	D0 to D7	I/O	VCC2	Inputs and outputs data (D0 to D7) when these pins are set as the separate bus.
	D8 to D15	I/O	VCC2	Inputs and outputs data (D8 to D15) when external 16-bit data bus is set as the separate bus.
	A0 to A19	O	VCC2	Output address bits (A0 to A19).
	A0/D0 to A7/D7	I/O	VCC2	Input and output data (D0 to D7) and output address bits (A0 to A7) by timesharing when external 8-bit data bus are set as the multiplexed bus.
	A1/D0 to A8/D7	I/O	VCC2	Input and output data (D0 to D7) and output address bits (A1 to A8) by timesharing when external 16-bit data bus are set as the multiplexed bus.
	CS0 to CS3	O	VCC2	Output CS0 to CS3 signals. CS0 to CS3 are chip-select signals to specify an external space.
	WRL/WR WRH/BHE RD	O	VCC2	Output WRL, WRH, (WR, BHE), RD signals. WRL and WRH or BHE and WR can be switched by program. <ul style="list-style-type: none"> WRL, WRH and RD are selected The WRL signal becomes "L" by writing data to an even address in an external memory space. The WRH signal becomes "L" by writing data to an odd address in an external memory space. The RD pin signal becomes "L" by reading data in an external memory space. WR, BHE and RD are selected The WR signal becomes "L" by writing data in an external memory space. The RD signal becomes "L" by reading data in an external memory space. The BHE signal becomes "L" by accessing an odd address. Select WR, BHE and RD for an external 8-bit data bus.
	ALE	O	VCC2	ALE is a signal to latch the address.
	HOLD	I	VCC2	While the HOLD pin is held "L", the microcomputer is placed in a hold state.
	HLDA	O	VCC2	In a hold state, HLDA outputs a "L" signal.
RDY	I	VCC2	While applying a "L" signal to the RDY pin, the microcomputer is placed in a wait state.	

I : Input O : Output I/O : Input and output

Power Supply : Power supplies which relate to the external bus pins are separated as VCC2, thus they can be interfaced using the different voltage as VCC1.

NOTES:

1. In this manual, hereafter, VCC refers to VCC1 unless otherwise noted.
2. In M16C/62PT, apply 4.0 to 5.5 V to the VCC1 and VCC2 pins. Also the apply condition is that $VCC1 = VCC2$.
3. When use $VCC1 > VCC2$, contacts due to some points or restrictions to be checked.
4. Bus control pins in M16C/62PT cannot be used.

Table 1.18 Pin Description (100-pin and 128-pin Version) (2)

Signal Name	Pin Name	I/O Type	Power Supply ⁽¹⁾	Description
Main clock input	XIN	I	VCC1	I/O pins for the main clock generation circuit. Connect a ceramic resonator or crystal oscillator between XIN and XOUT ⁽³⁾ . To use the external clock, input the clock from XIN and leave XOUT open.
Main clock output	XOUT	O	VCC1	
Sub clock input	XCIN	I	VCC1	I/O pins for a sub clock oscillation circuit. Connect a crystal oscillator between XCIN and XCOU ^T ⁽³⁾ . To use the external clock, input the clock from XCIN and leave XCOU ^T open.
Sub clock output	XCOU ^T	O	VCC1	
BCLK output ⁽²⁾	BCLK	O	VCC2	Outputs the BCLK signal.
Clock output	CLKOUT	O	VCC2	The clock of the same cycle as f _C , f ₈ , or f ₃₂ is outputted.
$\overline{\text{INT}}$ interrupt input	$\overline{\text{INT}}_0$ to $\overline{\text{INT}}_2$	I	VCC1	Input pins for the $\overline{\text{INT}}$ interrupt.
	$\overline{\text{INT}}_3$ to $\overline{\text{INT}}_5$	I	VCC2	
$\overline{\text{NMI}}$ interrupt input	$\overline{\text{NMI}}$	I	VCC1	Input pin for the $\overline{\text{NMI}}$ interrupt. Pin states can be read by the P8_5 bit in the P8 register.
Key input interrupt input	$\overline{\text{KI}}_0$ to $\overline{\text{KI}}_3$	I	VCC1	Input pins for the key input interrupt.
Timer A	TA0OUT to TA4OUT	I/O	VCC1	These are timer A0 to timer A4 I/O pins. (however, output of TA0OUT for the N-channel open drain output.)
	TA0IN to TA4IN	I	VCC1	These are timer A0 to timer A4 input pins.
	ZP	I	VCC1	Input pin for the Z-phase.
Timer B	TB0IN to TB5IN	I	VCC1	These are timer B0 to timer B5 input pins.
Three-phase motor control output	U, $\overline{\text{U}}$, V, $\overline{\text{V}}$, W, $\overline{\text{W}}$	O	VCC1	These are Three-phase motor control output pins.
Serial interface	$\overline{\text{CTS}}_0$ to $\overline{\text{CTS}}_2$	I	VCC1	These are send control input pins.
	$\overline{\text{RTS}}_0$ to $\overline{\text{RTS}}_2$	O	VCC1	These are receive control output pins.
	CLK0 to CLK4	I/O	VCC1	These are transfer clock I/O pins.
	RXD0 to RXD2	I	VCC1	These are serial data input pins.
	SIN3, SIN4	I	VCC1	These are serial data input pins.
	TXD0 to TXD2	O	VCC1	These are serial data output pins. (however, output of TXD2 for the N-channel open drain output.)
	SOUT3, SOUT4	O	VCC1	These are serial data output pins.
	CLKS1	O	VCC1	This is output pin for transfer clock output from multiple pins function.
I ² C mode	SDA0 to SDA2	I/O	VCC1	These are serial data I/O pins. (however, output of SDA2 for the N-channel open drain output.)
	SCL0 to SCL2	I/O	VCC1	These are transfer clock I/O pins. (however, output of SCL2 for the N-channel open drain output.)

I : Input O : Output I/O : Input and output

NOTES:

1. When use VCC1 > VCC2, contacts due to some points or restrictions to be checked.
2. This pin function in M16C/62PT cannot be used.
3. Ask the oscillator maker the oscillation characteristic.

Table 1.19 Pin Description (100-pin and 128-pin Version) (3)

Signal Name	Pin Name	I/O Type	Power Supply ⁽¹⁾	Description
Reference voltage input	VREF	I	VCC1	Applies the reference voltage for the A/D converter and D/A converter.
A/D converter	AN0 to AN7, AN0_0 to AN0_7, AN2_0 to AN2_7	I	VCC1	Analog input pins for the A/D converter.
	ADTRG	I	VCC1	This is an A/D trigger input pin.
	ANEX0	I/O	VCC1	This is the extended analog input pin for the A/D converter, and is the output in external op-amp connection mode.
	ANEX1	I	VCC1	This is the extended analog input pin for the A/D converter.
D/A converter	DA0, DA1	O	VCC1	This is the output pin for the D/A converter.
I/O port	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7 (2), P13_0 to P13_7 (2)	I/O	VCC2	8-bit I/O ports in CMOS, having a direction register to select an input or output. Each pin is set as an input port or output port. An input port can be set for a pull-up or for no pull-up in 4-bit unit by program.
	P6_0 to P6_7, P7_0 to P7_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7 (2)	I/O	VCC1	8-bit I/O ports having equivalent functions to P0. (however, output of P7_0 and P7_1 for the N-channel open drain output.)
	P8_0 to P8_4, P8_6, P8_7, P14_0, P14_1(2)	I/O	VCC1	I/O ports having equivalent functions to P0.
Input port	P8_5	I	VCC1	Input pin for the $\overline{\text{NMI}}$ interrupt. Pin states can be read by the P8_5 bit in the P8 register.

I : Input O : Output I/O : Input and output

NOTES:

1. When use VCC1 > VCC2, contacts due to some points or restrictions to be checked.
2. Ports P11 to P14 in M16C/62P (100-pin version) and M16C/62PT (100-pin version) cannot be used.

Table 1.20 Pin Description (80-pin Version) (1) (1)

Signal Name	Pin Name	I/O Type	Power Supply	Description
Power supply input	VCC1, VSS	I	–	Apply 2.7 to 5.5 V to the VCC1 pin and 0 V to the VSS pin. (1, 2)
Analog power supply input	AVCC AVSS	I	VCC1	Applies the power supply for the A/D converter. Connect the AVCC pin to VCC1. Connect the AVSS pin to VSS.
Reset input	$\overline{\text{RESET}}$	I	VCC1	The microcomputer is in a reset state when applying “L” to the this pin.
CNVSS	CNVSS (BYTE)	I	VCC1	Switches processor mode. Connect this pin to VSS to when after a reset to start up in single-chip mode. Connect this pin to VCC1 to start up in microprocessor mode. As for the BYTE pin of the 80-pin versions, pull-up processing is performed within the microcomputer.
Main clock input	XIN	I	VCC1	I/O pins for the main clock generation circuit. Connect a ceramic resonator or crystal oscillator between XIN and XOUT (3). To use the external clock, input the clock from XIN and leave XOUT open.
Main clock output	XOUT	O	VCC1	
Sub clock input	XCIN	I	VCC1	I/O pins for a sub clock oscillation circuit. Connect a crystal oscillator between XCIN and XCOU (3). To use the external clock, input the clock from XCIN and leave XCOU open.
Sub clock output	XCOU	O	VCC1	
Clock output	CLKOUT	O	VCC2	The clock of the same cycle as fC, f8, or f32 is outputted.
$\overline{\text{INT}}$ interrupt input	$\overline{\text{INT0}}$ to $\overline{\text{INT2}}$	I	VCC1	Input pins for the $\overline{\text{INT}}$ interrupt.
$\overline{\text{NMI}}$ interrupt input	$\overline{\text{NMI}}$	I	VCC1	Input pin for the $\overline{\text{NMI}}$ interrupt.
Key input interrupt input	$\overline{\text{KI0}}$ to $\overline{\text{KI3}}$	I	VCC1	Input pins for the key input interrupt.
Timer A	TA0OUT, TA3OUT, TA4OUT	I/O	VCC1	These are Timer A0, Timer A3 and Timer A4 I/O pins. (however, output of TA0OUT for the N-channel open drain output.)
	TA0IN, TA3IN, TA4IN	I	VCC1	These are Timer A0, Timer A3 and Timer A4 input pins.
	ZP	I	VCC1	Input pin for the Z-phase.
Timer B	TB0IN, TB2IN to TB5IN	I	VCC1	These are Timer B0, Timer B2 to Timer B5 input pins.
Serial interface	$\overline{\text{CTS0}}$ to $\overline{\text{CTS1}}$	I	VCC1	These are send control input pins.
	$\overline{\text{RTS0}}$ to $\overline{\text{RTS1}}$	O	VCC1	These are receive control output pins.
	CLK0, CLK1, CLK3, CLK4	I/O	VCC1	These are transfer clock I/O pins.
	RXD0 to RXD2	I	VCC1	These are serial data input pins.
	SIN4	I	VCC1	This is serial data input pin.
	TXD0 to TXD2	O	VCC1	These are serial data output pins. (however, output of TXD2 for the N-channel open drain output.)
	SOUT3, SOUT4	O	VCC1	These are serial data output pins.
	CLKS1	O	VCC1	This is output pin for transfer clock output from multiple pins function.
I ² C mode	SDA0 to SDA2	I/O	VCC1	These are serial data I/O pins. (however, output of SDA2 for the N-channel open drain output.)
	SCL0 to SCL2	I/O	VCC1	These are transfer clock I/O pins. (however, output of SCL2 for the N-channel open drain output.)

I : Input O : Output I/O : Input and output

NOTES:

1. In this manual, hereafter, VCC refers to VCC1 unless otherwise noted.
2. In M16C/62PT, apply 4.0 to 5.5 V to the VCC1 pin.
3. Ask the oscillator maker the oscillation characteristic.

2.2 Address Registers (A0 and A1)

The register A0 consists of 16 bits, and is used for address register indirect addressing and address register relative addressing. They also are used for transfers and logic/logic operations. A1 is the same as A0.

In some instructions, registers A1 and A0 can be combined for use as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is configured with 16 bits, and is used for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is configured with 20 bits, indicating the start address of an interrupt vector table.

2.5 Program Counter (PC)

PC is configured with 20 bits, indicating the address of an instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

Stack pointer (SP) comes in two types: USP and ISP, each configured with 16 bits.

Your desired type of stack pointer (USP or ISP) can be selected by the U flag of FLG.

2.7 Static Base Register (SB)

SB is configured with 16 bits, and is used for SB relative addressing.

2.8 Flag Register (FLG)

FLG consists of 11 bits, indicating the CPU status.

2.8.1 Carry Flag (C Flag)

This flag retains a carry, borrow, or shift-out bit that has occurred in the arithmetic/logic unit.

2.8.2 Debug Flag (D Flag)

The D flag is used exclusively for debugging purpose. During normal use, it must be set to "0".

2.8.3 Zero Flag (Z Flag)

This flag is set to "1" when an arithmetic operation resulted in 0; otherwise, it is "0".

2.8.4 Sign Flag (S Flag)

This flag is set to "1" when an arithmetic operation resulted in a negative value; otherwise, it is "0".

2.8.5 Register Bank Select Flag (B Flag)

Register bank 0 is selected when this flag is "0"; register bank 1 is selected when this flag is "1".

2.8.6 Overflow Flag (O Flag)

This flag is set to "1" when the operation resulted in an overflow; otherwise, it is "0".

2.8.7 Interrupt Enable Flag (I Flag)

This flag enables a maskable interrupt.

Maskable interrupts are disabled when the I flag is "0", and are enabled when the I flag is "1". The I flag is cleared to "0" when the interrupt request is accepted.

Table 4.2 SFR Information (2) (1)

Address	Register	Symbol	After Reset
0040h			
0041h			
0042h			
0043h			
0044h	INT3 Interrupt Control Register	INT3IC	XX00X000b
0045h	Timer B5 Interrupt Control Register	TB5IC	XXXXX000b
0046h	Timer B4 Interrupt Control Register, UART1 BUS Collision Detection Interrupt Control Register	TB4IC, U1BCNIC	XXXXX000b
0047h	Timer B3 Interrupt Control Register, UART0 BUS Collision Detection Interrupt Control Register	TB3IC, U0BCNIC	XXXXX000b
0048h	SI/O4 Interrupt Control Register, INT5 Interrupt Control Register	S4IC, INT5IC	XX00X000b
0049h	SI/O3 Interrupt Control Register, INT4 Interrupt Control Register	S3IC, INT4IC	XX00X000b
004Ah	UART2 Bus Collision Detection Interrupt Control Register	BCNIC	XXXXX000b
004Bh	DMA0 Interrupt Control Register	DM0IC	XXXXX000b
004Ch	DMA1 Interrupt Control Register	DM1IC	XXXXX000b
004Dh	Key Input Interrupt Control Register	KUPIC	XXXXX000b
004Eh	A/D Conversion Interrupt Control Register	ADIC	XXXXX000b
004Fh	UART2 Transmit Interrupt Control Register	S2TIC	XXXXX000b
0050h	UART2 Receive Interrupt Control Register	S2RIC	XXXXX000b
0051h	UART0 Transmit Interrupt Control Register	S0TIC	XXXXX000b
0052h	UART0 Receive Interrupt Control Register	S0RIC	XXXXX000b
0053h	UART1 Transmit Interrupt Control Register	S1TIC	XXXXX000b
0054h	UART1 Receive Interrupt Control Register	S1RIC	XXXXX000b
0055h	Timer A0 Interrupt Control Register	TA0IC	XXXXX000b
0056h	Timer A1 Interrupt Control Register	TA1IC	XXXXX000b
0057h	Timer A2 Interrupt Control Register	TA2IC	XXXXX000b
0058h	Timer A3 Interrupt Control Register	TA3IC	XXXXX000b
0059h	Timer A4 Interrupt Control Register	TA4IC	XXXXX000b
005Ah	Timer B0 Interrupt Control Register	TB0IC	XXXXX000b
005Bh	Timer B1 Interrupt Control Register	TB1IC	XXXXX000b
005Ch	Timer B2 Interrupt Control Register	TB2IC	XXXXX000b
005Dh	INT0 Interrupt Control Register	INT0IC	XX00X000b
005Eh	INT1 Interrupt Control Register	INT1IC	XX00X000b
005Fh	INT2 Interrupt Control Register	INT2IC	XX00X000b
0060h			
0061h			
0062h			
0063h			
0064h			
0065h			
0066h			
0067h			
0068h			
0069h			
006Ah			
006Bh			
006Ch			
006Dh			
006Eh			
006Fh			
0070h			
0071h			
0072h			
0073h			
0074h			
0075h			
0076h			
0077h			
0078h			
0079h			
007Ah			
007Bh			
007Ch			
007Dh			
007Eh			
007Fh			

NOTES:

- The blank areas are reserved and cannot be accessed by users.

X : Nothing is mapped to this bit

$$V_{CC1}=V_{CC2}=5V$$

Switching Characteristics

(V_{CC1} = V_{CC2} = 5V, V_{SS} = 0V, at T_{opr} = -20 to 85°C / -40 to 85°C unless otherwise specified)

Table 5.27 Memory Expansion and Microprocessor Modes (for setting with no wait)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
t _d (BCLK-AD)	Address Output Delay Time		25	ns
t _h (BCLK-AD)	Address Output Hold Time (in relation to BCLK)	4		ns
t _h (RD-AD)	Address Output Hold Time (in relation to RD)	0		ns
t _h (WR-AD)	Address Output Hold Time (in relation to WR)	(NOTE 2)		ns
t _d (BCLK-CS)	Chip Select Output Delay Time		25	ns
t _h (BCLK-CS)	Chip Select Output Hold Time (in relation to BCLK)	4		ns
t _d (BCLK-ALE)	ALE Signal Output Delay Time		15	ns
t _h (BCLK-ALE)	ALE Signal Output Hold Time	-4		ns
t _d (BCLK-RD)	RD Signal Output Delay Time		25	ns
t _h (BCLK-RD)	RD Signal Output Hold Time	0		ns
t _d (BCLK-WR)	WR Signal Output Delay Time		25	ns
t _h (BCLK-WR)	WR Signal Output Hold Time	0		ns
t _d (BCLK-DB)	Data Output Delay Time (in relation to BCLK)		40	ns
t _h (BCLK-DB)	Data Output Hold Time (in relation to BCLK) ⁽³⁾	4		ns
t _d (DB-WR)	Data Output Delay Time (in relation to WR)	(NOTE 1)		ns
t _h (WR-DB)	Data Output Hold Time (in relation to WR) ⁽³⁾	(NOTE 2)		ns
t _d (BCLK-HLDA)	HLDA Output Delay Time		40	ns

See Figure 5.2

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(\text{BCLK})} - 40[\text{ns}] \quad f(\text{BCLK}) \text{ is } 12.5\text{MHz or less.}$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(\text{BCLK})} - 10[\text{ns}]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus.

Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL} / V_{CC2})$$

by a circuit of the right figure.

For example, when V_{OL} = 0.2V_{CC2}, C = 30pF, R = 1kΩ, hold time of output "L" level is

$$t = -30\text{pF} \times 1\text{k}\Omega \times \ln(1 - 0.2V_{CC2} / V_{CC2}) = 6.7\text{ns.}$$

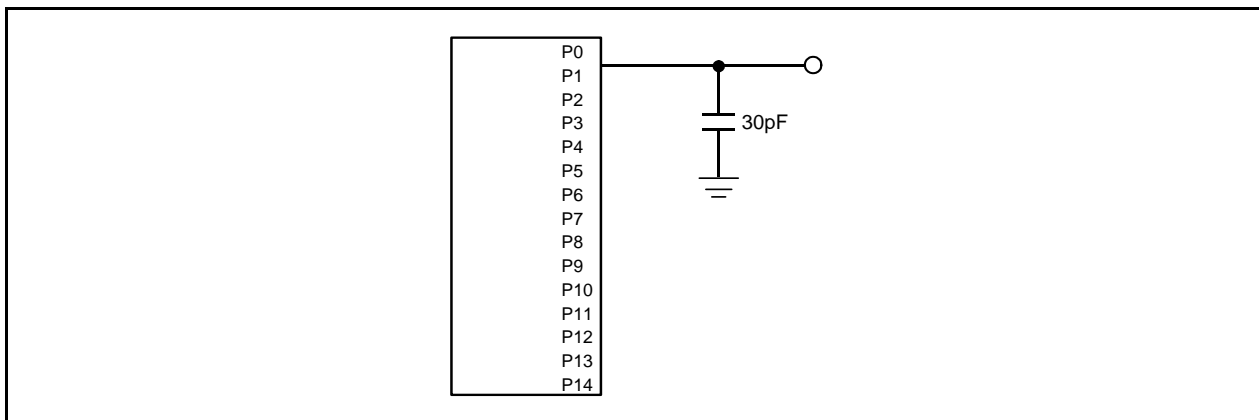
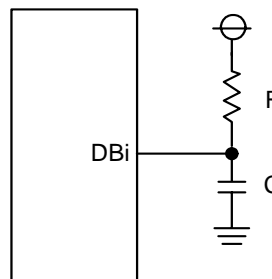


Figure 5.2 Ports P0 to P14 Measurement Circuit

$$V_{CC1}=V_{CC2}=5V$$

Switching Characteristics

($V_{CC1} = V_{CC2} = 5V$, $V_{SS} = 0V$, at $T_{opr} = -20$ to $85^{\circ}C$ / -40 to $85^{\circ}C$ unless otherwise specified)

Table 5.28 Memory Expansion and Microprocessor Modes (for 1- to 3-wait setting and external area access)

Symbol	Parameter		Standard		Unit
			Min.	Max.	
$t_d(\text{BCLK-AD})$	Address Output Delay Time	See Figure 5.2		25	ns
$t_h(\text{BCLK-AD})$	Address Output Hold Time (in relation to BCLK)		4		ns
$t_h(\text{RD-AD})$	Address Output Hold Time (in relation to RD)		0		ns
$t_h(\text{WR-AD})$	Address Output Hold Time (in relation to WR)		(NOTE 2)		ns
$t_d(\text{BCLK-CS})$	Chip Select Output Delay Time			25	ns
$t_h(\text{BCLK-CS})$	Chip Select Output Hold Time (in relation to BCLK)		4		ns
$t_d(\text{BCLK-ALE})$	ALE Signal Output Delay Time			15	ns
$t_h(\text{BCLK-ALE})$	ALE Signal Output Hold Time		-4		ns
$t_d(\text{BCLK-RD})$	RD Signal Output Delay Time			25	ns
$t_h(\text{BCLK-RD})$	RD Signal Output Hold Time		0		ns
$t_d(\text{BCLK-WR})$	WR Signal Output Delay Time			25	ns
$t_h(\text{BCLK-WR})$	WR Signal Output Hold Time		0		ns
$t_d(\text{BCLK-DB})$	Data Output Delay Time (in relation to BCLK)			40	ns
$t_h(\text{BCLK-DB})$	Data Output Hold Time (in relation to BCLK) ⁽³⁾		4		ns
$t_d(\text{DB-WR})$	Data Output Delay Time (in relation to WR)		(NOTE 1)		ns
$t_h(\text{WR-DB})$	Data Output Hold Time (in relation to WR) ⁽³⁾		(NOTE 2)		ns
$t_d(\text{BCLK-HLDA})$	HLDA Output Delay Time		40	ns	

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{(n-0.5) \times 10^9}{f(\text{BCLK})} - 40[\text{ns}]$$

n is "1" for 1-wait setting, "2" for 2-wait setting and "3" for 3-wait setting.
(BCLK) is 12.5MHz or less.

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(\text{BCLK})} - 10[\text{ns}]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus.

Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

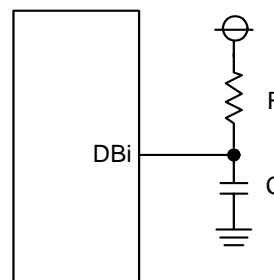
Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL} / V_{CC2})$$

by a circuit of the right figure.

For example, when $V_{OL} = 0.2V_{CC2}$, $C = 30\text{pF}$, $R = 1\text{k}\Omega$, hold time of output "L" level is

$$t = -30\text{pF} \times 1\text{k}\Omega \times \ln(1 - 0.2V_{CC2} / V_{CC2}) = 6.7\text{ns}.$$



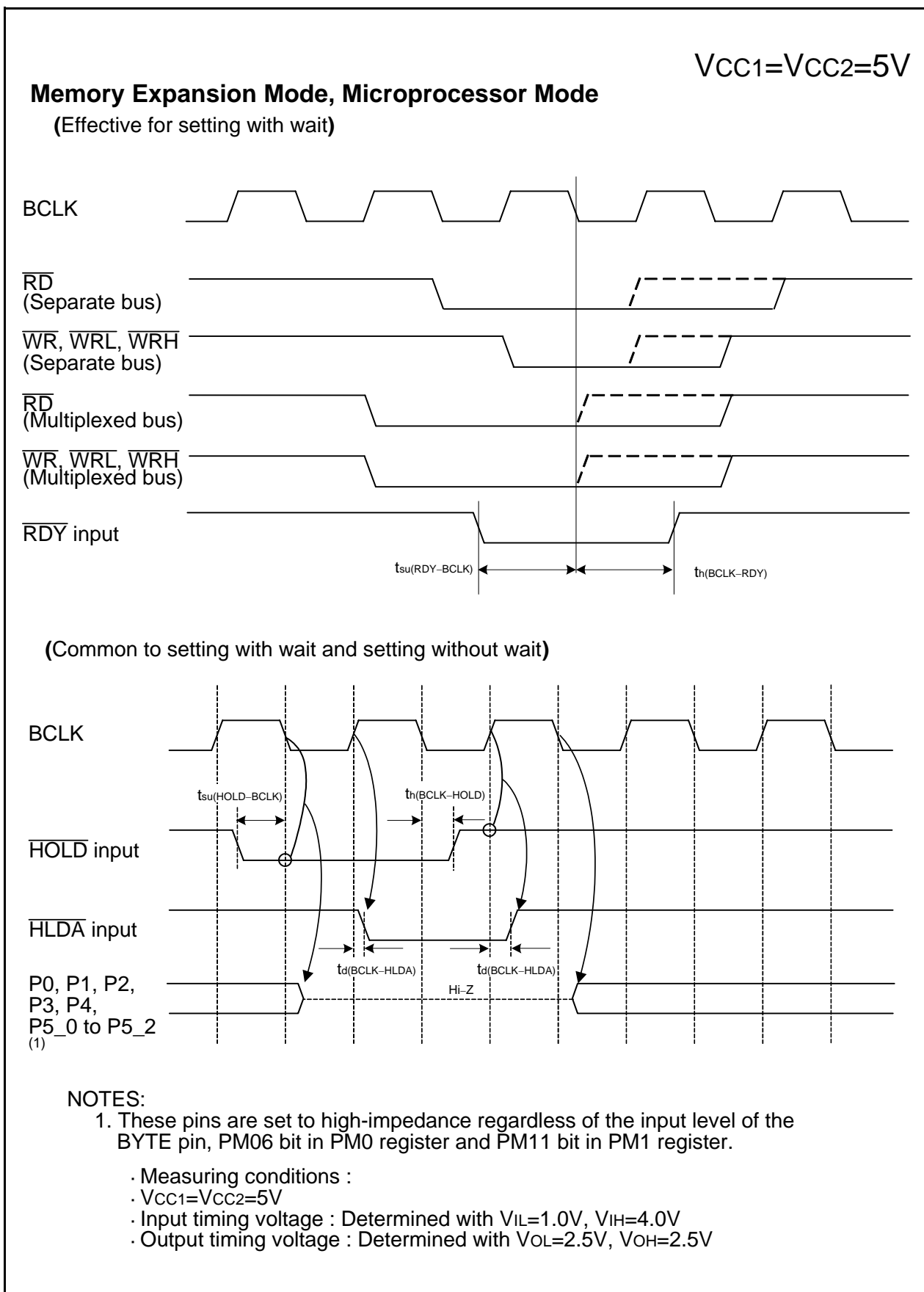


Figure 5.5 Timing Diagram (3)

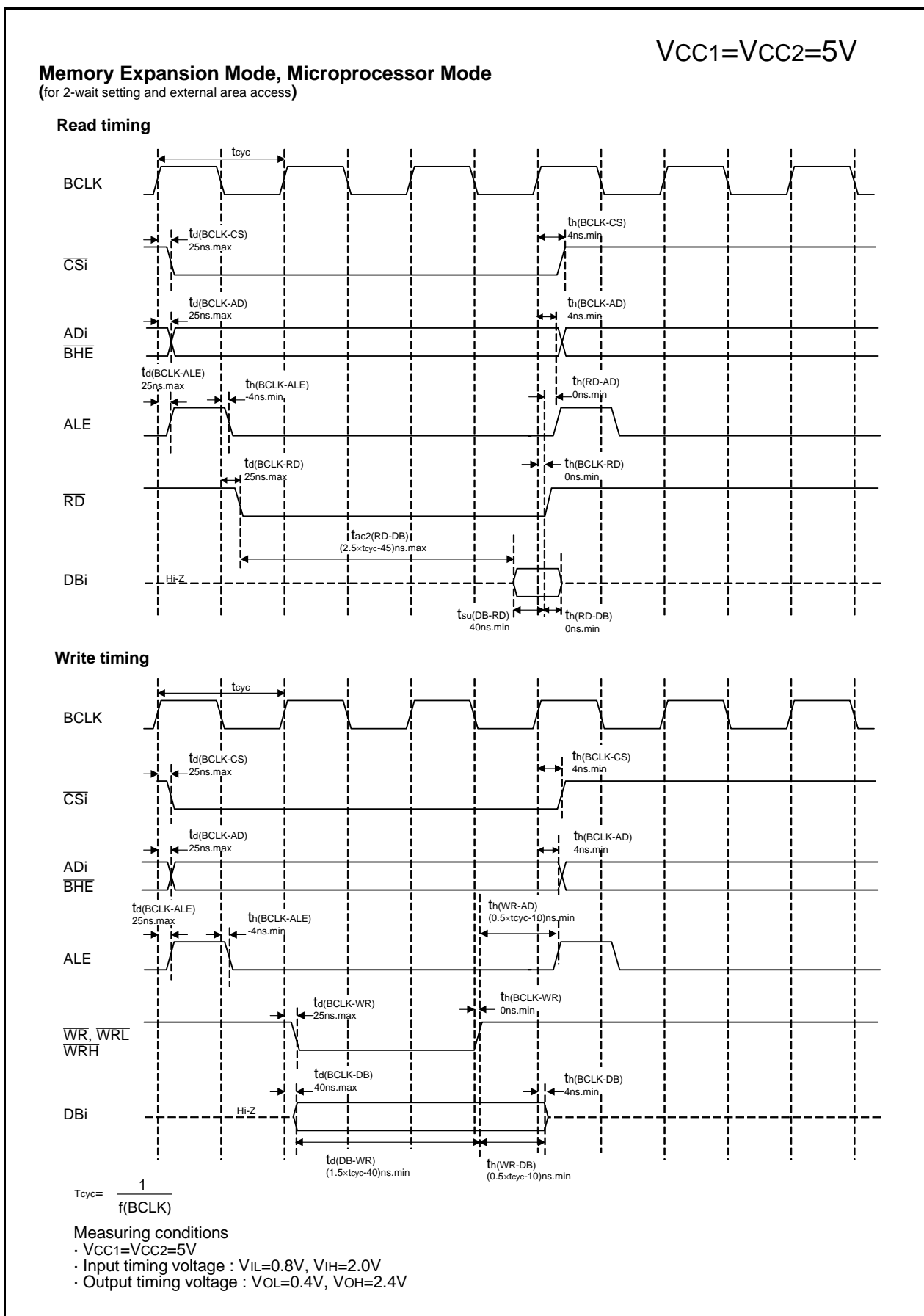


Figure 5.8 Timing Diagram (6)

$$V_{CC1} = V_{CC2} = 3V$$

Switching Characteristics

(V_{CC1} = V_{CC2} = 3V, V_{SS} = 0V, at T_{opr} = -20 to 85°C / -40 to 85°C unless otherwise specified)

Table 5.46 Memory Expansion and Microprocessor Modes (for setting with no wait)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
t _d (BCLK-AD)	Address Output Delay Time		30	ns
t _h (BCLK-AD)	Address Output Hold Time (in relation to BCLK)	4		ns
t _h (RD-AD)	Address Output Hold Time (in relation to RD)	0		ns
t _h (WR-AD)	Address Output Hold Time (in relation to WR)	(NOTE 2)		ns
t _d (BCLK-CS)	Chip Select Output Delay Time		30	ns
t _h (BCLK-CS)	Chip Select Output Hold Time (in relation to BCLK)	4		ns
t _d (BCLK-ALE)	ALE Signal Output Delay Time		25	ns
t _h (BCLK-ALE)	ALE Signal Output Hold Time	-4		ns
t _d (BCLK-RD)	RD Signal Output Delay Time		30	ns
t _h (BCLK-RD)	RD Signal Output Hold Time	0		ns
t _d (BCLK-WR)	WR Signal Output Delay Time		30	ns
t _h (BCLK-WR)	WR Signal Output Hold Time	0		ns
t _d (BCLK-DB)	Data Output Delay Time (in relation to BCLK)		40	ns
t _h (BCLK-DB)	Data Output Hold Time (in relation to BCLK) ⁽³⁾	4		ns
t _d (DB-WR)	Data Output Delay Time (in relation to WR)	(NOTE 1)		ns
t _h (WR-DB)	Data Output Hold Time (in relation to WR) ⁽³⁾	(NOTE 2)		ns
t _d (BCLK-HLDA)	HLDA Output Delay Time		40	ns

See Figure 5.12

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(\text{BCLK})} - 40[\text{ns}] \quad f(\text{BCLK}) \text{ is } 12.5\text{MHz or less.}$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(\text{BCLK})} - 10[\text{ns}]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus.

Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL} / V_{CC2})$$

by a circuit of the right figure.

For example, when V_{OL} = 0.2V_{CC2}, C = 30pF, R = 1kΩ, hold time of output "L" level is

$$t = -30\text{pF} \times 1\text{k}\Omega \times \ln(1 - 0.2V_{CC2} / V_{CC2}) = 6.7\text{ns.}$$

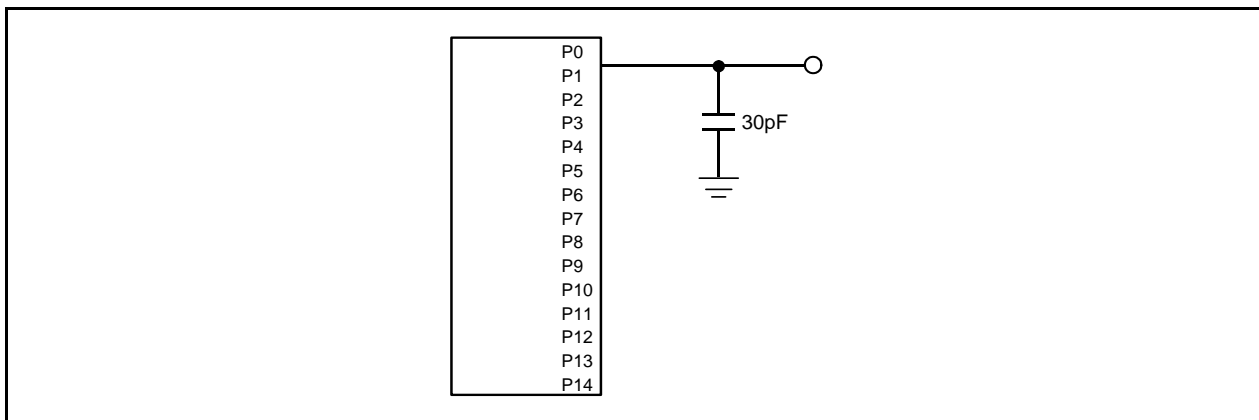
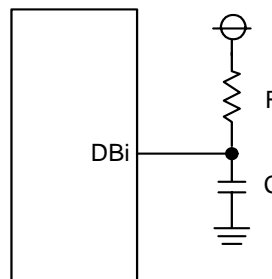


Figure 5.12 Ports P0 to P14 Measurement Circuit

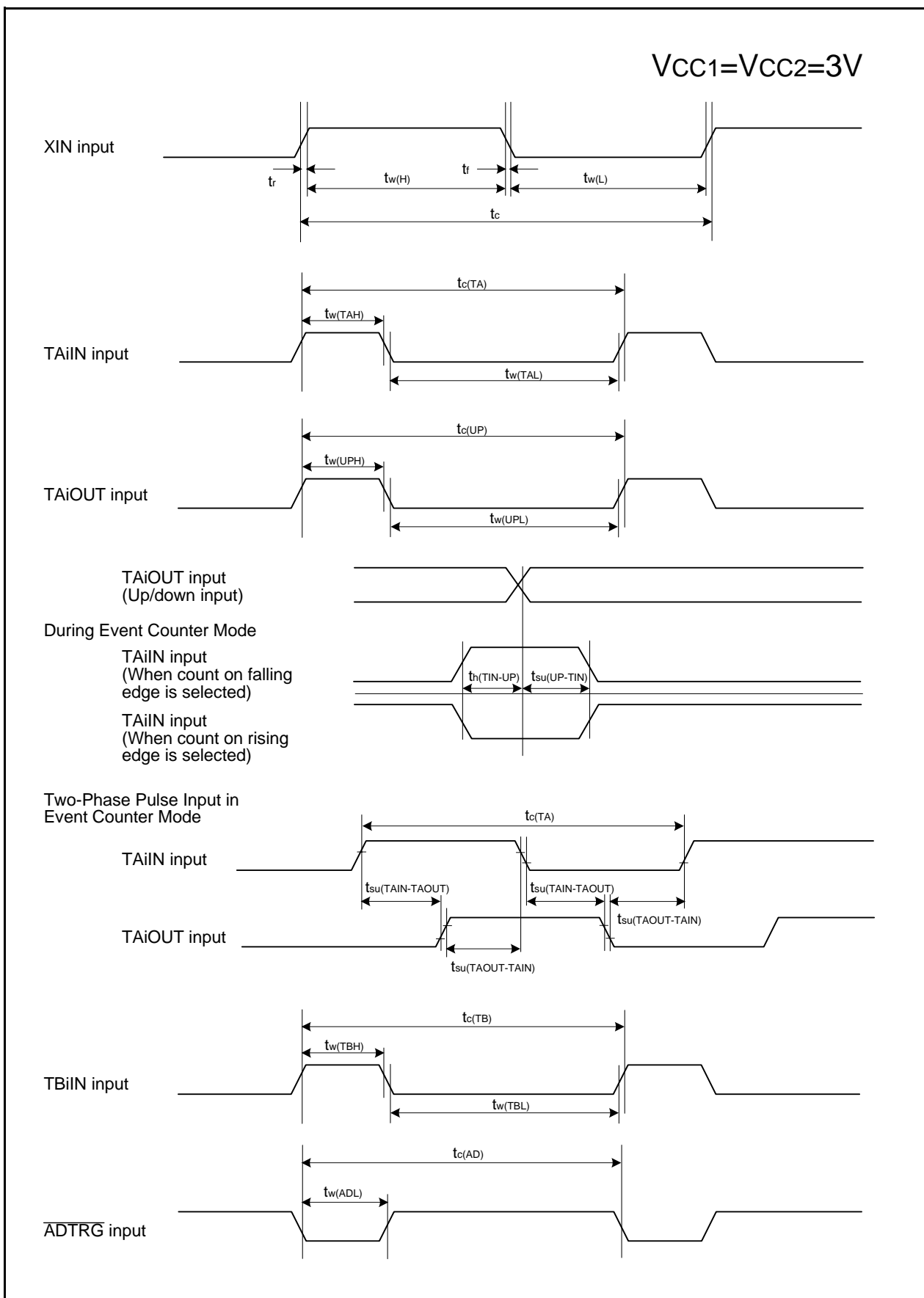


Figure 5.13 Timing Diagram (1)

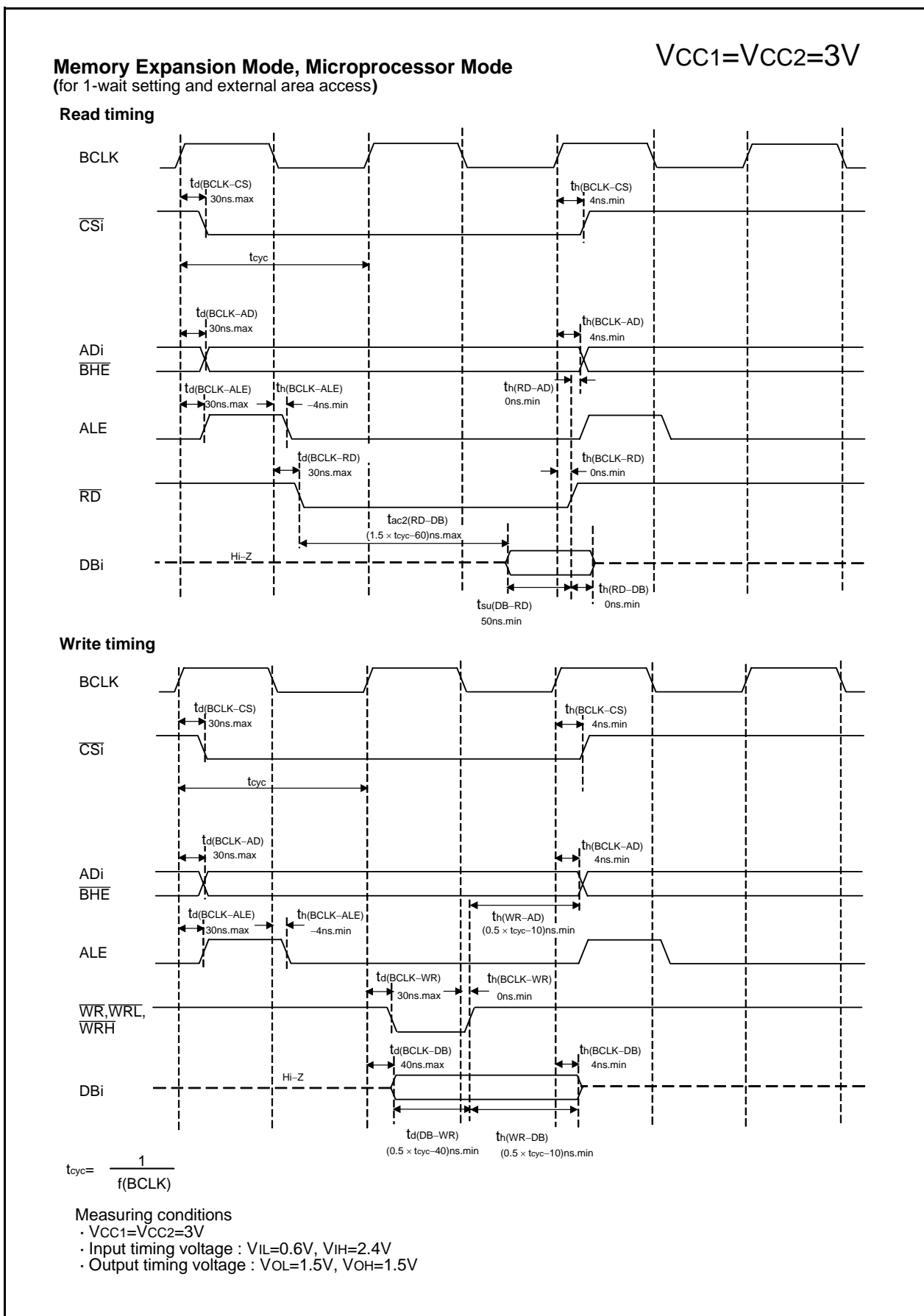


Figure 5.17 Timing Diagram (5)

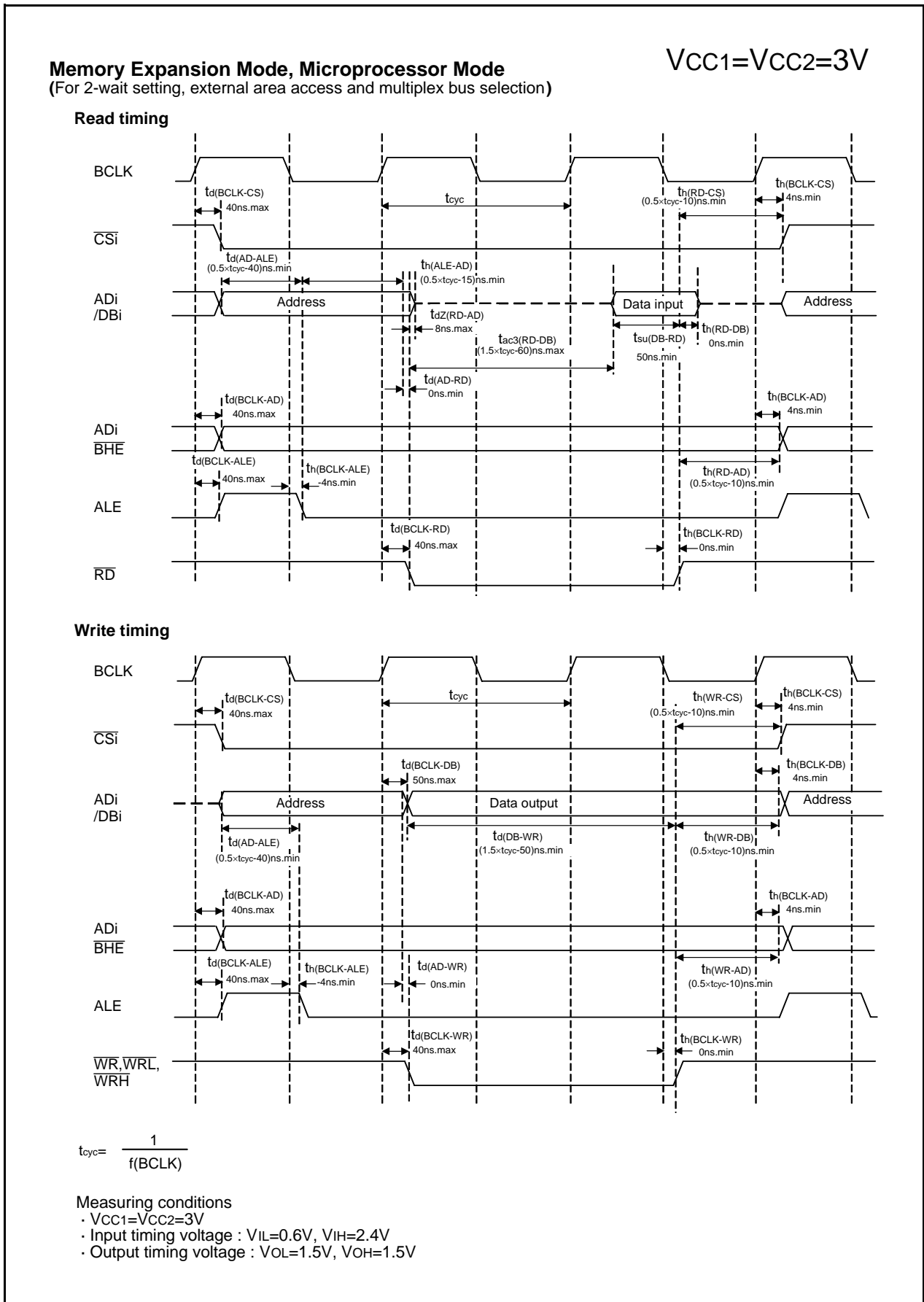


Figure 5.20 Timing Diagram (8)

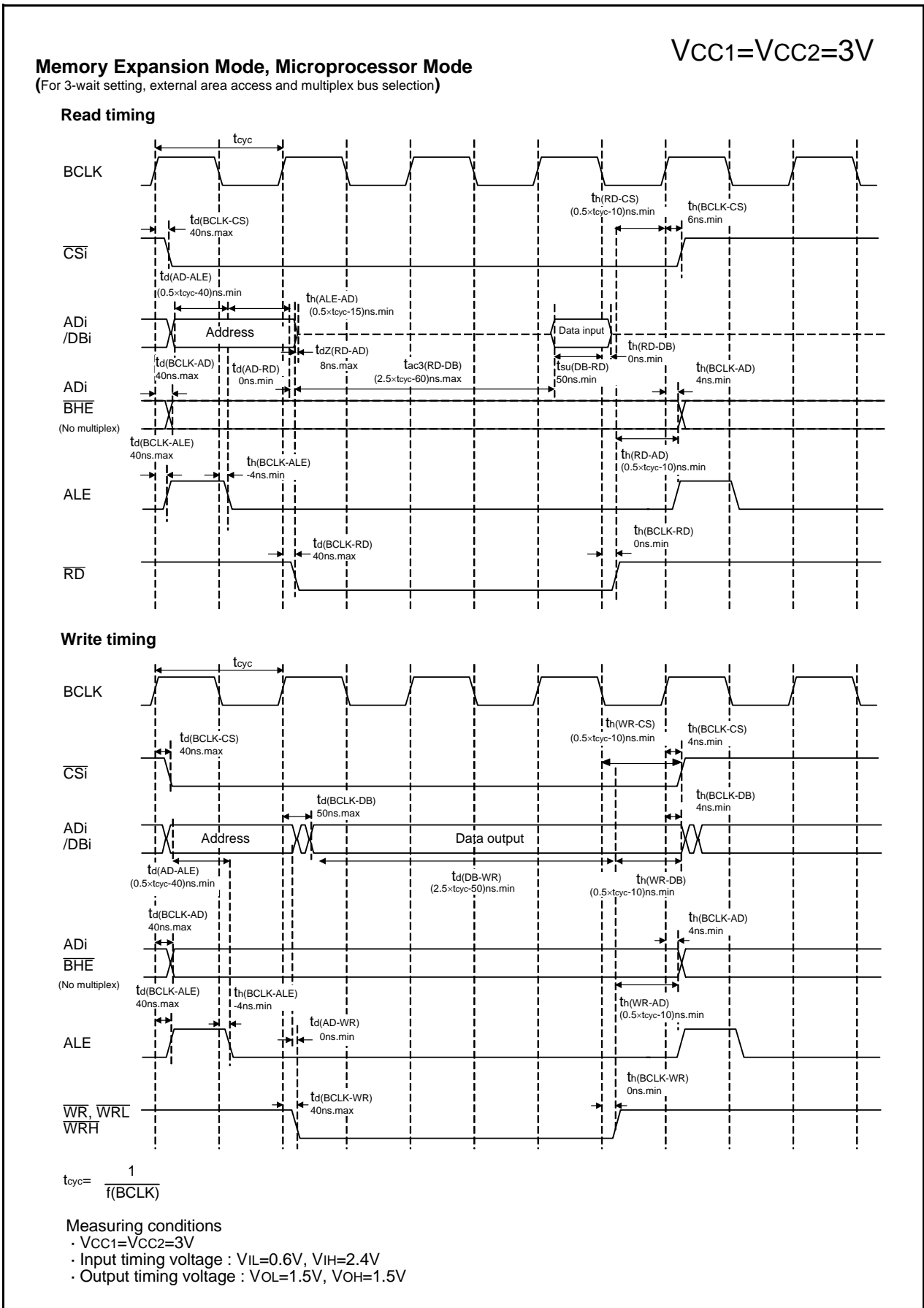


Figure 5.21 Timing Diagram (9)

Table 5.51 A/D Conversion Characteristics (1)

Symbol	Parameter		Measuring Condition	Standard			Unit
				Min.	Typ.	Max.	
–	Resolution		$V_{REF}=V_{CC1}$			10	Bits
INL	Integral Non-Linearity Error	10bit	$V_{REF}=V_{CC1}=5V$ AN0 to AN7 input, AN0_0 to AN0_7 input, AN2_0 to AN2_7 input, ANEX0, ANEX1 input			± 3	LSB
			External operation amp connection mode			± 7	LSB
		8bit	$V_{REF}=V_{CC1}=5V$			± 2	LSB
–	Absolute Accuracy	10bit	$V_{REF}=V_{CC1}=5V$ AN0 to AN7 input, AN0_0 to AN0_7 input, AN2_0 to AN2_7 input, ANEX0, ANEX1 input			± 3	LSB
			External operation amp connection mode			± 7	LSB
		8bit	$V_{REF}=V_{CC1}=5V$			± 2	LSB
–	Tolerance Level Impedance				3		$k\Omega$
DNL	Differential Non-Linearity Error					± 1	LSB
–	Offset Error					± 3	LSB
–	Gain Error					± 3	LSB
RLADDER	Ladder Resistance		$V_{REF}=V_{CC1}$	10		40	$k\Omega$
tCONV	10-bit Conversion Time, Sample & Hold Function Available		$V_{REF}=V_{CC1}=5V, \phi_{AD}=12MHz$	2.75			μs
tCONV	8-bit Conversion Time, Sample & Hold Function Available		$V_{REF}=V_{CC1}=5V, \phi_{AD}=12MHz$	2.33			μs
tsAMP	Sampling Time			0.25			μs
VREF	Reference Voltage			2.0		V_{CC1}	V
VIA	Analog Input Voltage			0		V_{REF}	V

NOTES:

1. Referenced to $V_{CC1}=AV_{CC}=V_{REF}=4.0$ to $5.5V$, $V_{SS}=AV_{SS}=0V$ at $T_{opr} = -40$ to $85^\circ C$ / -40 to $125^\circ C$ unless otherwise specified. T version = -40 to $85^\circ C$, V version = -40 to $125^\circ C$
2. ϕ_{AD} frequency must be 12 MHz or less.
3. When sample & hold is disabled, ϕ_{AD} frequency must be 250 kHz or more, in addition to the limitation in Note 2. When sample & hold is enabled, ϕ_{AD} frequency must be 1MHz or more, in addition to the limitation in Note 2.

Table 5.52 D/A Conversion Characteristics (1)

Symbol	Parameter	Measuring Condition	Standard			Unit
			Min.	Typ.	Max.	
–	Resolution				8	Bits
–	Absolute Accuracy				1.0	%
tsU	Setup Time				3	μs
RO	Output Resistance		4	10	20	$k\Omega$
I _{VREF}	Reference Power Supply Input Current	(NOTE 2)			1.5	mA

NOTES:

1. Referenced to $V_{CC1}=V_{REF}=4.0$ to $5.5V$, $V_{SS}=AV_{SS}=0V$ at $T_{opr} = -40$ to $85^\circ C$ / -40 to $125^\circ C$ unless otherwise specified. T version = -40 to $85^\circ C$, V version = -40 to $125^\circ C$
2. This applies when using one D/A converter, with the D/A register for the unused D/A converter set to "00h". The resistor ladder of the A/D converter is not included. Also, when D/A register contents are not "00h", the I_{VREF} will flow even if V_{ref} is disconnected by the A/D control register.

Table 5.56 Power Supply Circuit Timing Characteristics

Symbol	Parameter	Measuring Condition	Standard			Unit
			Min.	Typ.	Max.	
td(P-R)	Time for Internal Power Supply Stabilization During Powering-On	Vcc1=4.0V to 5.5V			2	ms
td(R-S)	STOP Release Time				150	μs
td(W-S)	Low Power Dissipation Mode Wait Mode Release Time				150	μs

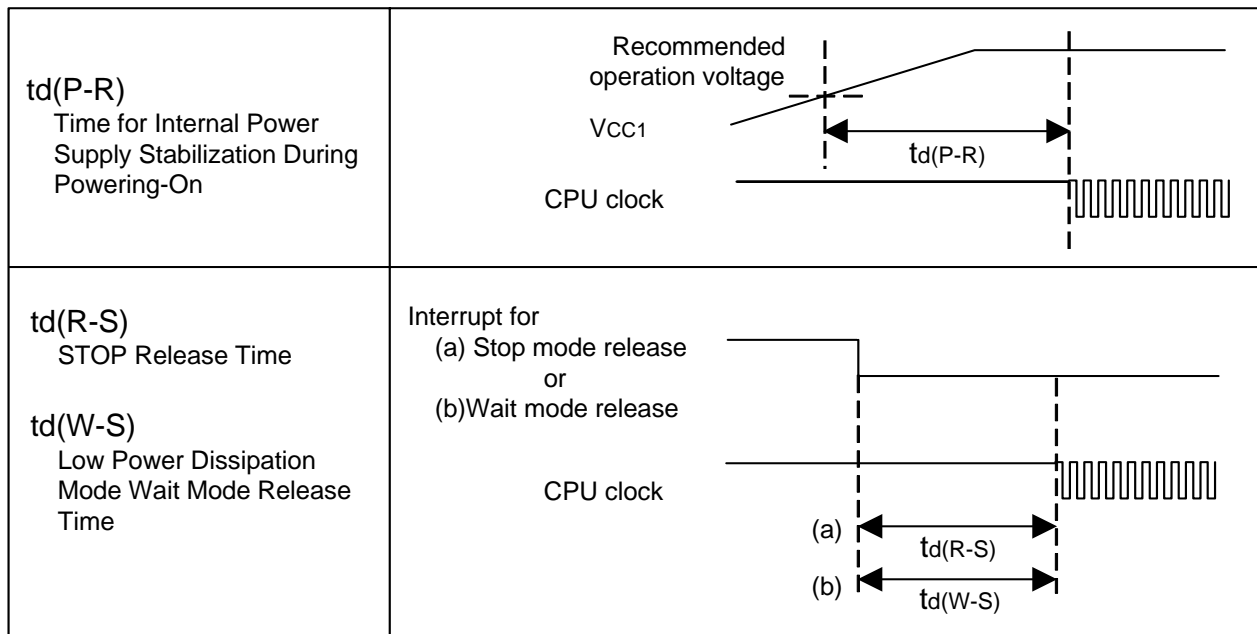


Figure 5.22 Power Supply Circuit Timing Diagram

$$V_{CC1}=V_{CC2}=5V$$

Timing Requirements

($V_{CC1} = V_{CC2} = 5V$, $V_{SS} = 0V$, at $T_{opr} = -40$ to $85^{\circ}C$ (T version) / -40 to $125^{\circ}C$ (V version) unless otherwise specified)

Table 5.59 External Clock Input (XIN input)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
t_c	External Clock Input Cycle Time	62.5		ns
$t_{w(H)}$	External Clock Input HIGH Pulse Width	25		ns
$t_{w(L)}$	External Clock Input LOW Pulse Width	25		ns
t_r	External Clock Rise Time		15	ns
t_f	External Clock Fall Time		15	ns

REVISION HISTORY

M16C/62P Group (M16C/62P, M16C/62PT) Hardware Manual

Rev.	Date	Description	
		Page	Summary
		33 34,74 36 38,55 41 41-43, 58-60 44 47-48 49-50 52 53 58 61 64-65 66-67 69 70-85	Table 5.4 A-D Conversion Characteristics is revised. Table 5.5 D-A Conversion Characteristics revised. Table 5.6 to 5.7 and table 5.54 to 5.55 are revised. Table 5.11 is revised. Table 5.14 and 5.33 HLDA output deley time is deleted. Figure 5.1 is partly revised. Table 5.27 to 5.29 and table 5.46 to 48 HLDA output deley time is added. Figure 5.2 Timing Diagram (1) XIN input is added. Figure 5.5 to 5.6 Read timing DB → DBi Figure 5.7 to 5.8 Write timing DB → DBi Figure 5.10 DB → DBi Table 5.30 is revised. Figure 5.11 is partly revised. Figure 5.12 Timing Diagram (1) XIN input is added. Figure 5.15 to 5.16 Read timing DB → DBi Figure 5.17 to 5.18 Write timing DB → DBi Figure 5.20 DB → DBi Electrical Characteristics (M16C/62PT) is added.
2.10	Nov 07, 2003	8-9 23 71 72	Table 1.5 to 1.7 Product List is partly revised. Note 1 is deleted. Table 3.1 is revised. Table 5.50 is revised. Table 5.51 is deleted.
2.11	Jan 06, 2004	16 17-18 31	Table 1.9 NOTE 3 VCC1 VCC2 → VCC1 > VCC2 Table 1.10 to 1.11 NOTE 1 VCC1 VCC2 → VCC1 > VCC2 Table 5.2 Power Supply Ripple Allowable Frequency Unit MHz → kHz
2.30	Sep 01, 2004	12 18, 20 19,21 24 25 33 34 35 37	Table 1.9 and Figure 1.5 are added. Table 1.11 to 1.13 are revised. Table 1.12 to 1.14 are revised. Figure 3.1 is partly revised. Note 3 is added. Note 6 is added. Table 5.3 is revised. Note 2 in Table 5.4 is added. Table 5.5 to 5.6 is partly revised. Table 5.8 is revised. Table 5.9 is revised. Table 5.11 is revised.