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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	17
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 12x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SOIC (0.295", 7.50mm Width)
Supplier Device Package	20-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1508-i-so">https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1508-i-so</a>

**TABLE 6-5: SUMMARY OF REGISTERS ASSOCIATED WITH RESETS**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BORCON	SBOREN	BORFS	—	—	—	—	—	BORRDY	64
PCON	STKOVF	STKUNF	—	$\overline{\text{RWDT}}$	$\overline{\text{RMCLR}}$	$\overline{\text{RI}}$	$\overline{\text{POR}}$	$\overline{\text{BOR}}$	68
STATUS	—	—	—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC	C	19
WDTCON	—	—	WDTPS<4:0>					SWDTEN	88

**Legend:** — = unimplemented bit, reads as '0'. Shaded cells are not used by Resets.

**TABLE 6-6: SUMMARY OF CONFIGURATION WORD WITH RESETS**

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFIG1	13:8	—	—	FCMEN	IESO	CLKOUTEN	BOREN<1:0>		—	43
	7:0	CP	MCLRE	PWRT	WDTE<1:0>		FOSC<2:0>			
CONFIG2	13:8	—	—	LVP	—	LPBOR	BORV	STVREN	—	43
	7:0	—	—	—	—	—	—	WRT<1:0>		

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used by Resets.

## 9.1 Independent Clock Source

The WDT derives its time base from the 31 kHz LFINTOSC internal oscillator. Time intervals in this chapter are based on a nominal interval of 1 ms. See **Section 29.0 “Electrical Specifications”** for the LFINTOSC tolerances.

## 9.2 WDT Operating Modes

The Watchdog Timer module has four operating modes controlled by the WDTE<1:0> bits in Configuration Words. See Table 9-1.

### 9.2.1 WDT IS ALWAYS ON

When the WDTE bits of Configuration Words are set to ‘11’, the WDT is always on.

WDT protection is active during Sleep.

### 9.2.2 WDT IS OFF IN SLEEP

When the WDTE bits of Configuration Words are set to ‘10’, the WDT is on, except in Sleep.

WDT protection is not active during Sleep.

### 9.2.3 WDT CONTROLLED BY SOFTWARE

When the WDTE bits of Configuration Words are set to ‘01’, the WDT is controlled by the SWDTEN bit of the WDTCON register.

WDT protection is unchanged by Sleep. See Table 9-1 for more details.

**TABLE 9-1: WDT OPERATING MODES**

WDTE<1:0>	SWDTEN	Device Mode	WDT Mode
11	X	X	Active
10	X	Awake	Active
		Sleep	Disabled
01	1	X	Active
	0	X	Disabled
00	X	X	Disabled

**TABLE 9-2: WDT CLEARING CONDITIONS**

Conditions	WDT
WDTE<1:0> = 00	Cleared
WDTE<1:0> = 01 and SWDTEN = 0	
WDTE<1:0> = 10 and enter Sleep	
CLRWDT Command	
Oscillator Fail Detected	
Exit Sleep + System Clock = T1OSC, EXTRC, INTOSC, EXTCLK	
Exit Sleep + System Clock = XT, HS, LP	Cleared until the end of OST
Change INTOSC divider (IRCF bits)	Unaffected

## 9.3 Time-Out Period

The WDTPS bits of the WDTCON register set the time-out period from 1 ms to 256 seconds (nominal). After a Reset, the default time-out period is two seconds.

## 9.4 Clearing the WDT

The WDT is cleared when any of the following conditions occur:

- Any Reset
- CLRWDT instruction is executed
- Device enters Sleep
- Device wakes up from Sleep
- Oscillator fail
- WDT is disabled
- Oscillator Start-up Timer (OST) is running

See Table 9-2 for more information.

## 9.5 Operation During Sleep

When the device enters Sleep, the WDT is cleared. If the WDT is enabled during Sleep, the WDT resumes counting. When the device exits Sleep, the WDT is cleared again.

The WDT remains clear until the OST, if enabled, completes. See **Section 5.0 “Oscillator Module (With Fail-Safe Clock Monitor)”** for more information on the OST.

When a WDT time-out occurs while the device is in Sleep, no Reset is generated. Instead, the device wakes up and resumes operation. The TO and PD bits in the STATUS register are changed to indicate the event. The RWDT bit in the PCON register can also be used. See **Section 3.0 “Memory Organization”** for more information.

# PIC16(L)F1508/9

## REGISTER 10-5: PMCON1: PROGRAM MEMORY CONTROL 1 REGISTER

U-1	R/W-0/0	R/W-0/0	R/W/HC-0/0	R/W/HC-x/q <sup>(2)</sup>	R/W-0/0	R/S/HC-0/0	R/S/HC-0/0
— <sup>(1)</sup>	CFGS	LWLO	FREE	WRERR	WREN	WR	RD
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
S = Bit can only be set	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HC = Bit is cleared by hardware

- bit 7      **Unimplemented:** Read as '1'
- bit 6      **CFGS:** Configuration Select bit  
1 = Access Configuration, User ID and Device ID Registers  
0 = Access Flash program memory
- bit 5      **LWLO:** Load Write Latches Only bit<sup>(3)</sup>  
1 = Only the addressed program memory write latch is loaded/updated on the next WR command  
0 = The addressed program memory write latch is loaded/updated and a write of all program memory write latches will be initiated on the next WR command
- bit 4      **FREE:** Program Flash Erase Enable bit  
1 = Performs an erase operation on the next WR command (hardware cleared upon completion)  
0 = Performs a write operation on the next WR command
- bit 3      **WRERR:** Program/Erase Error Flag bit  
1 = Condition indicates an improper program or erase sequence attempt or termination (bit is set automatically on any set attempt (write '1') of the WR bit).  
0 = The program or erase operation completed normally.
- bit 2      **WREN:** Program/Erase Enable bit  
1 = Allows program/erase cycles  
0 = Inhibits programming/erasing of program Flash
- bit 1      **WR:** Write Control bit  
1 = Initiates a program Flash program/erase operation.  
The operation is self-timed and the bit is cleared by hardware once operation is complete.  
The WR bit can only be set (not cleared) in software.  
0 = Program/erase operation to the Flash is complete and inactive.
- bit 0      **RD:** Read Control bit  
1 = Initiates a program Flash read. Read takes one cycle. RD is cleared in hardware. The RD bit can only be set (not cleared) in software.  
0 = Does not initiate a program Flash read.

- Note** 1: Unimplemented bit, read as '1'.  
2: The WRERR bit is automatically set by hardware when a program memory write or erase operation is started (WR = 1).  
3: The LWLO bit is ignored during a program memory erase operation (FREE = 1).

**TABLE 14-2: SUMMARY OF REGISTERS ASSOCIATED WITH THE TEMPERATURE INDICATOR**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
FVRCON	FVREN	FVRRDY	TSEN	TSRNG	CDAFVR<1:0>		ADFVR<1:0>		125

**Legend:** Shaded cells are unused by the temperature indicator module.

## 15.2.6 ADC CONVERSION PROCEDURE

This is an example procedure for using the ADC to perform an Analog-to-Digital conversion:

1. Configure Port:
  - Disable pin output driver (Refer to the TRIS register)
  - Configure pin as analog (Refer to the ANSEL register)
  - Disable weak pull-ups either globally (Refer to the OPTION\_REG register) or individually (Refer to the appropriate WPUx register).
2. Configure the ADC module:
  - Select ADC conversion clock
  - Configure voltage reference
  - Select ADC input channel
  - Turn on ADC module
3. Configure ADC interrupt (optional):
  - Clear ADC interrupt flag
  - Enable ADC interrupt
  - Enable peripheral interrupt
  - Enable global interrupt<sup>(1)</sup>
4. Wait the required acquisition time<sup>(2)</sup>.
5. Start conversion by setting the GO/DONE bit.
6. Wait for ADC conversion to complete by one of the following:
  - Polling the GO/DONE bit
  - Waiting for the ADC interrupt (interrupts enabled)
7. Read ADC Result.
8. Clear the ADC interrupt flag (required if interrupt is enabled).

**Note 1:** The global interrupt can be disabled if the user is attempting to wake-up from Sleep and resume in-line code execution.

**2:** Refer to **Section 15.4 “ADC Acquisition Requirements”**.

## EXAMPLE 15-1: ADC CONVERSION

```
;This code block configures the ADC
;for polling, Vdd and Vss references, FRC
;oscillator and AN0 input.
;
;Conversion start & polling for completion
; are included.
;
BANKSEL    ADCON1    ;
MOVLW     B'11110000' ;Right justify, FRC
                                ;oscillator
MOVWF     ADCON1    ;Vdd and Vss Vref+
BANKSEL    TRISA      ;
BSF       TRISA,0    ;Set RA0 to input
BANKSEL    ANSEL      ;
BSF       ANSEL,0    ;Set RA0 to analog
BANKSEL    WPUA       ;
BCF       WPUA,0     ;Disable weak
                                pull-up on RA0
BANKSEL    ADCON0     ;
MOVLW     B'00000001' ;Select channel AN0
MOVWF     ADCON0     ;Turn ADC On
CALL      SampleTime ;Acquisition delay
BSF       ADCON0,ADGO ;Start conversion
BTFSCL    ADCON0,ADGO ;Is conversion done?
GOTO      $-1        ;No, test again
BANKSEL    ADRESH     ;
MOVF      ADRESH,W    ;Read upper 2 bits
MOVWF     RESULTHI    ;store in GPR space
BANKSEL    ADRESL     ;
MOVF      ADRESL,W    ;Read lower 8 bits
MOVWF     RESULTLO    ;Store in GPR space
```

## REGISTER 15-4: ADRESH: ADC RESULT REGISTER HIGH (ADRESH) ADFM = 0

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
ADRES<9:2>							
bit 7 <span style="float: right;">bit 0</span>							

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0      **ADRES<9:2>**: ADC Result Register bits  
Upper eight bits of 10-bit conversion result

## REGISTER 15-5: ADRESL: ADC RESULT REGISTER LOW (ADRESL) ADFM = 0

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
ADRES<1:0>		—	—	—	—	—	—
bit 7 <span style="float: right;">bit 0</span>							

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6      **ADRES<1:0>**: ADC Result Register bits  
Lower two bits of 10-bit conversion result

bit 5-0      **Reserved**: Do not use.

## 17.0 COMPARATOR MODULE

Comparators are used to interface analog circuits to a digital circuit by comparing two analog voltages and providing a digital indication of their relative magnitudes. Comparators are very useful mixed signal building blocks because they provide analog functionality independent of program execution. The analog comparator module includes the following features:

- Independent comparator control
- Programmable input selection
- Comparator output is available internally/externally
- Programmable output polarity
- Interrupt-on-change
- Wake-up from Sleep
- Programmable Speed/Power optimization
- PWM shutdown
- Programmable and fixed voltage reference

## 17.1 Comparator Overview

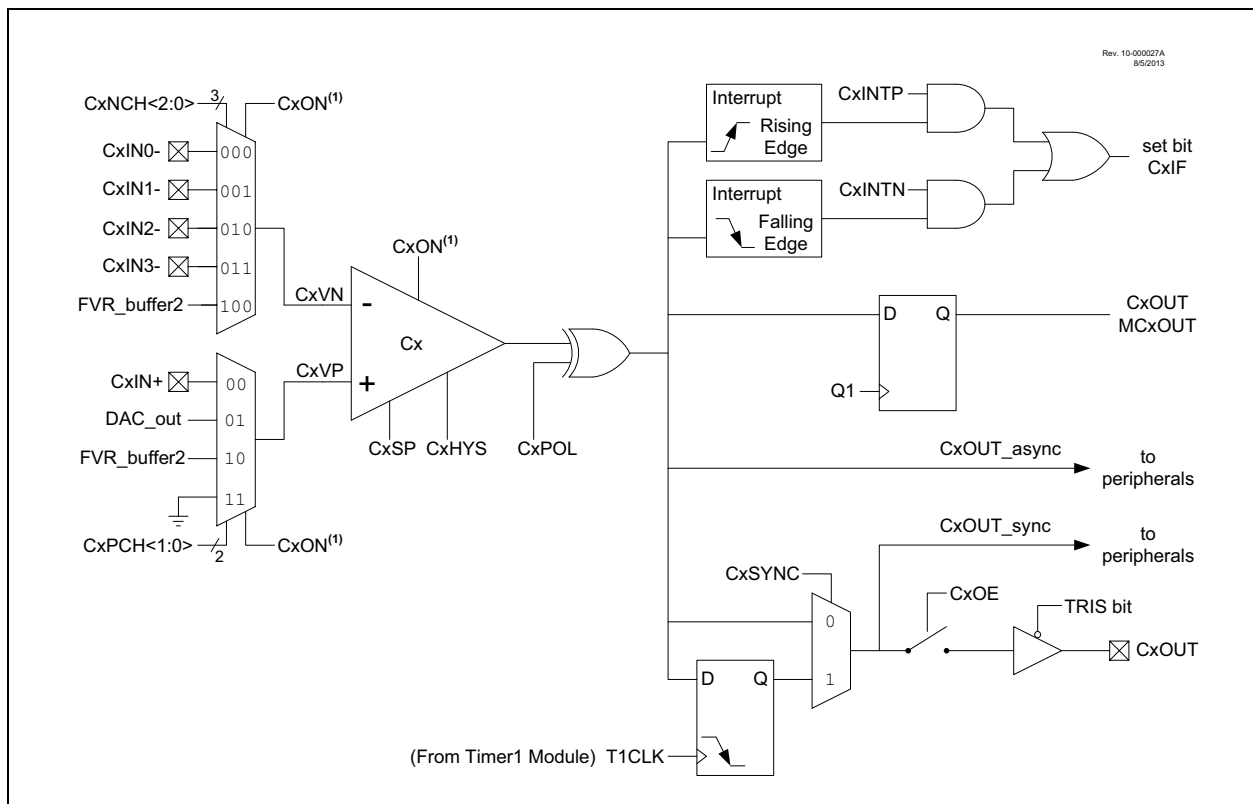
A single comparator is shown in Figure 17-2 along with the relationship between the analog input levels and the digital output. When the analog voltage at  $V_{IN+}$  is less than the analog voltage at  $V_{IN-}$ , the output of the comparator is a digital low level. When the analog voltage at  $V_{IN+}$  is greater than the analog voltage at  $V_{IN-}$ , the output of the comparator is a digital high level.

The comparators available for this device are listed in Table 17-1.

**TABLE 17-1: AVAILABLE COMPARATORS**

Device	C1	C2
PIC16(L)F1508	•	•
PIC16(L)F1509	•	•

**FIGURE 17-1: COMPARATOR MODULE SIMPLIFIED BLOCK DIAGRAM**





## 19.3 Timer1 Prescaler

Timer1 has four prescaler options allowing 1, 2, 4 or 8 divisions of the clock input. The T1CKPS bits of the T1CON register control the prescale counter. The prescale counter is not directly readable or writable; however, the prescaler counter is cleared upon a write to TMR1H or TMR1L.

## 19.4 Timer1 (Secondary) Oscillator

A dedicated low-power 32.768 kHz oscillator circuit is built-in between pins SOSCI (input) and SOSCO (amplifier output). This internal circuit is to be used in conjunction with an external 32.768 kHz crystal. The oscillator circuit is enabled by setting the T1OSCEN bit of the T1CON register. The oscillator will continue to run during Sleep.

**Note:** The oscillator requires some time to start-up and stabilize before use. The SOSCR bit in the OSCSTAT register monitors the oscillator and indicates when the oscillator is ready for use. When T1OSCEN is set, the SOSCR bit is cleared. After 1024 cycles of the oscillator are counted, the SOSCR bit is set, indicating that the oscillator should be stable and ready for use.

## 19.5 Timer1 Operation in Asynchronous Counter Mode

If control bit T1SYNC of the T1CON register is set, the external clock input is not synchronized. The timer increments asynchronously to the internal phase clocks. If the external clock source is selected then the timer will continue to run during Sleep and can generate an interrupt on overflow, which will wake-up the processor. However, special precautions in software are needed to read/write the timer (see Section 19.5.1 “Reading and Writing Timer1 in Asynchronous Counter Mode”).

**Note:** When switching from synchronous to asynchronous operation, it is possible to skip an increment. When switching from asynchronous to synchronous operation, it is possible to produce an additional increment.

### 19.5.1 READING AND WRITING TIMER1 IN ASYNCHRONOUS COUNTER MODE

Reading TMR1H or TMR1L while the timer is running from an external asynchronous clock will ensure a valid read (taken care of in hardware). However, the user should keep in mind that reading the 16-bit timer in two 8-bit values itself, poses certain problems, since the timer may overflow between the reads.

For writes, it is recommended that the user simply stop the timer and write the desired values. A write contention may occur by writing to the timer registers, while the register is incrementing. This may produce an unpredictable value in the TMR1H:TMR1L register pair.

## 19.6 Timer1 Gate

Timer1 can be configured to count freely or the count can be enabled and disabled using Timer1 gate circuitry. This is also referred to as Timer1 Gate Enable.

Timer1 gate can also be driven by multiple selectable sources.

### 19.6.1 TIMER1 GATE ENABLE

The Timer1 Gate Enable mode is enabled by setting the TMR1GE bit of the T1GCON register. The polarity of the Timer1 Gate Enable mode is configured using the T1GPOL bit of the T1GCON register.

When Timer1 Gate Enable mode is enabled, Timer1 will increment on the rising edge of the Timer1 clock source. When Timer1 Gate Enable mode is disabled, no incrementing will occur and Timer1 will hold the current count. See Figure 19-3 for timing details.

**TABLE 19-3: TIMER1 GATE ENABLE SELECTIONS**

T1CLK	T1GPOL	T1G	Timer1 Operation
↑	0	0	Counts
↑	0	1	Holds Count
↑	1	0	Holds Count
↑	1	1	Counts

### 19.6.2 TIMER1 GATE SOURCE SELECTION

Timer1 gate source selections are shown in Table 19-4. Source selection is controlled by the T1GSS<1:0> bits of the T1GCON register. The polarity for each available source is also selectable. Polarity selection is controlled by the T1GPOL bit of the T1GCON register.

**TABLE 19-4: TIMER1 GATE SOURCES**

T1GSS	Timer1 Gate Source
00	Timer1 Gate pin (T1G)
01	Overflow of Timer0 (T0_overflow) (TMR0 increments from FFh to 00h)
10	Comparator 1 Output (C1OUT_sync) <sup>(1)</sup>
11	Comparator 2 Output (C2OUT_sync) <sup>(1)</sup>

**Note 1:** Optionally synchronized comparator output.

**TABLE 19-5: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER1**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELA	—	—	—	ANSA4	—	ANSA2	ANSA1	ANSA0	110
APFCON	—	—	—	SSSEL	T1GSEL	—	CLC1SEL	NCO1SEL	107
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	75
OSCSTAT	SOSCR	—	OSTS	HFIOFR	—	—	LFIOFR	HFIOFS	60
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSP1IE	—	TMR2IE	TMR1IE	76
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSP1IF	—	TMR2IF	TMR1IF	79
TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1 Count								159*
TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1 Count								159*
TRISA	—	—	TRISA5	TRISA4	— <sup>(1)</sup>	TRISA2	TRISA1	TRISA0	109
T1CON	TMR1CS<1:0>		T1CKPS<1:0>		T1OSCEN	T1SYN $\bar{C}$	—	TMR1ON	163
T1GCON	TMR1GE	T1GPOL	T1GTM	T1GSPM	T1GGO/ DONE	T1GVAL	T1GSS<1:0>		164

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used by the Timer1 module.

\* Page provides register information.

**Note 1:** Unimplemented, read as '1'.

# PIC16(L)F1508/9

The I<sup>2</sup>C interface supports the following modes and features:

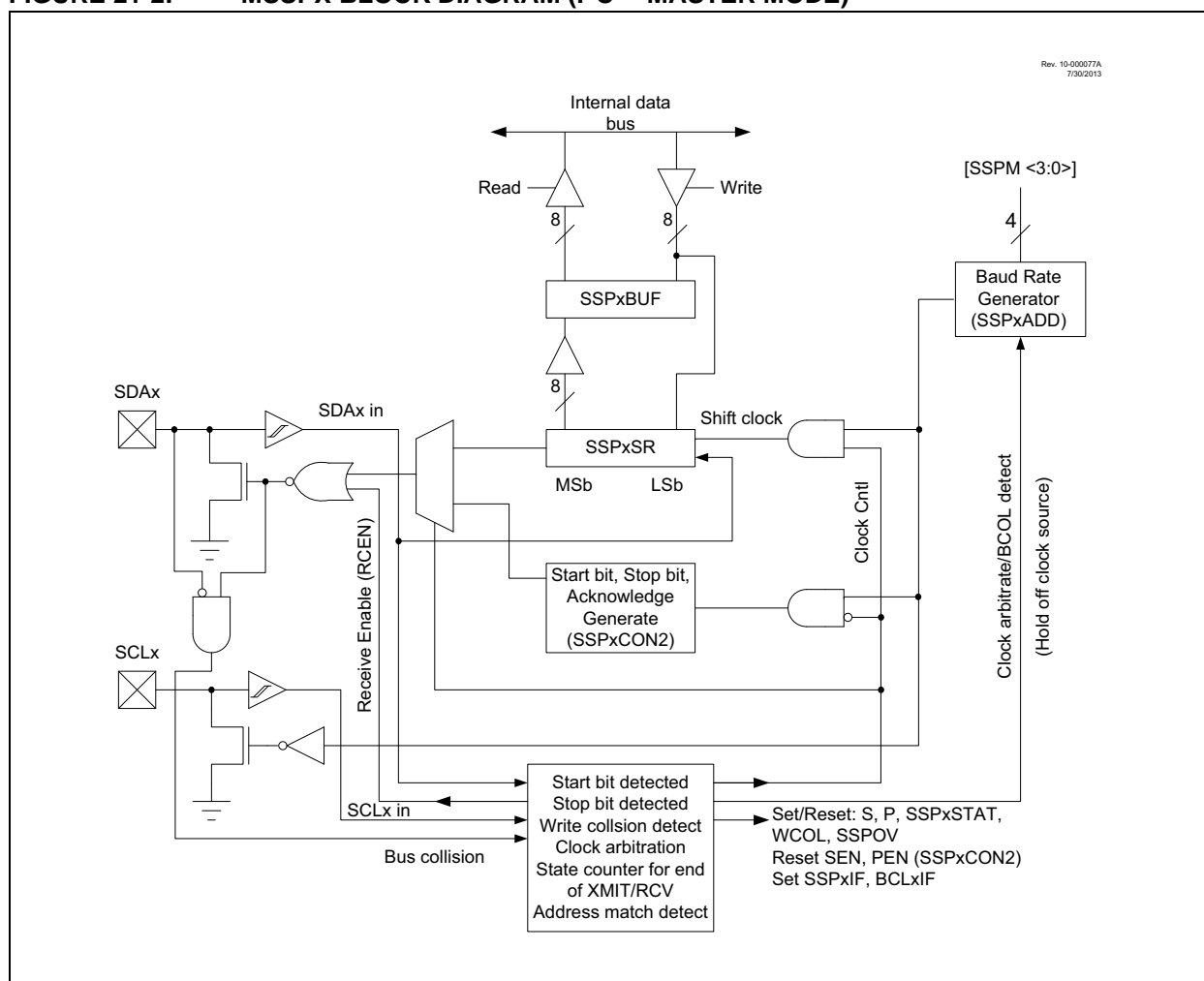
- Master mode
- Slave mode
- Byte NACKing (Slave mode)
- Limited Multi-master support
- 7-bit and 10-bit addressing
- Start and Stop interrupts
- Interrupt masking
- Clock stretching
- Bus collision detection
- General call address matching
- Address masking
- Address Hold and Data Hold modes
- Selectable SDAx hold times

Figure 21-2 is a block diagram of the I<sup>2</sup>C interface module in Master mode. Figure 21-3 is a diagram of the I<sup>2</sup>C interface module in Slave mode.

**Note 1:** In devices with more than one MSSP module, it is very important to pay close attention to SSPxCONx register names. SSPxCON1 and SSPxCON2 registers control different operational aspects of the same module, while SSPxCON1 and SSP2CON1 control the same features for two different modules.

**2:** Throughout this section, generic references to an MSSPx module in any of its operating modes may be interpreted as being equally applicable to MSSPx or MSSP2. Register names, module I/O signals, and bit names may use the generic designator 'x' to indicate the use of a numeral to distinguish a particular module when required.

**FIGURE 21-2: MSSPx BLOCK DIAGRAM (I<sup>2</sup>C™ MASTER MODE)**



## 21.5.8 GENERAL CALL ADDRESS SUPPORT

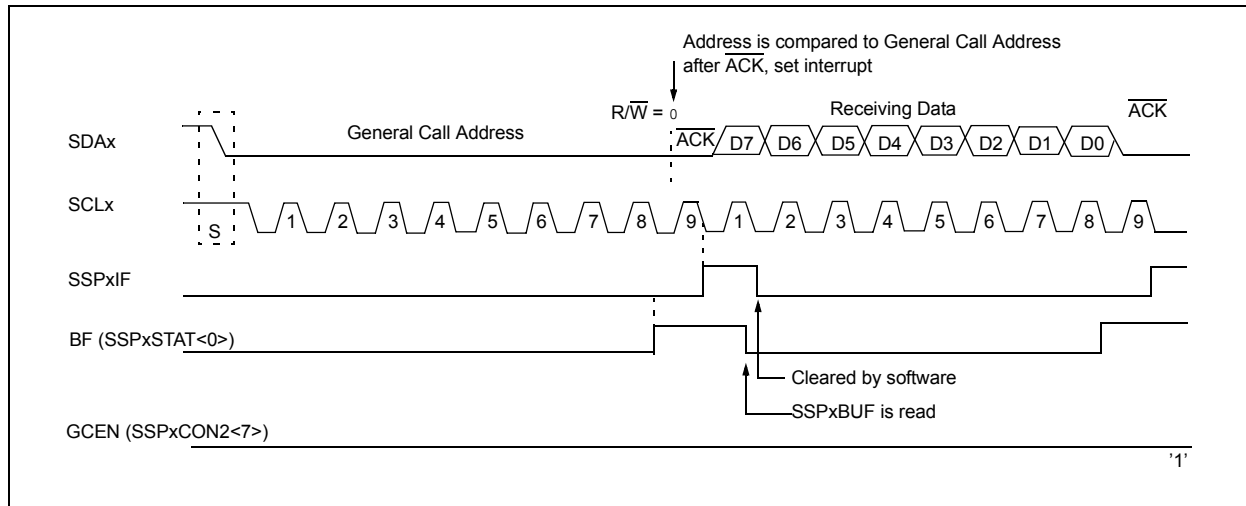
The addressing procedure for the I<sup>2</sup>C bus is such that the first byte after the Start condition usually determines which device will be the slave addressed by the master device. The exception is the general call address which can address all devices. When this address is used, all devices should, in theory, respond with an acknowledge.

The general call address is a reserved address in the I<sup>2</sup>C protocol, defined as address 0x00. When the GCEN bit of the SSPxCON2 register is set, the slave module will automatically ACK the reception of this address regardless of the value stored in SSPxADD. After the slave clocks in an address of all zeros with the R/W bit clear, an interrupt is generated and slave software can read SSPxBUF and respond. Figure 21-24 shows a General Call reception sequence.

In 10-bit Address mode, the UA bit will not be set on the reception of the general call address. The slave will prepare to receive the second byte as data, just as it would in 7-bit mode.

If the AHEN bit of the SSPxCON3 register is set, just as with any other address reception, the slave hardware will stretch the clock after the eighth falling edge of SCLx. The slave must then set its ACKDT value and release the clock with communication progressing as it would normally.

**FIGURE 21-24: SLAVE MODE GENERAL CALL ADDRESS SEQUENCE**



## 21.5.9 SSPx MASK REGISTER

An SSPx Mask (SSPxMSK) register (Register 21-5) is available in I<sup>2</sup>C Slave mode as a mask for the value held in the SSPxSR register during an address comparison operation. A zero ('0') bit in the SSPxMSK register has the effect of making the corresponding bit of the received address a "don't care".

This register is reset to all '1's upon any Reset condition and, therefore, has no effect on standard SSPx operation until written with a mask value.

The SSPx Mask register is active during:

- 7-bit Address mode: address compare of A<7:1>.
- 10-bit Address mode: address compare of A<7:0> only. The SSPx mask has no effect during the reception of the first (high) byte of the address.

# PIC16(L)F1508/9

## REGISTER 21-5: SSPxMSK: SSP MASK REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
MSK<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-1 **MSK<7:1>**: Mask bits

1 = The received address bit n is compared to SSPxADD<n> to detect I<sup>2</sup>C address match

0 = The received address bit n is not used to detect I<sup>2</sup>C address match

bit 0 **MSK<0>**: Mask bit for I<sup>2</sup>C Slave mode, 10-bit Address

I<sup>2</sup>C Slave mode, 10-bit address (SSPM<3:0> = 0111 or 1111):

1 = The received address bit 0 is compared to SSPxADD<0> to detect I<sup>2</sup>C address match

0 = The received address bit 0 is not used to detect I<sup>2</sup>C address match

I<sup>2</sup>C Slave mode, 7-bit address, the bit is ignored

## REGISTER 21-6: SSPxADD: MSSP ADDRESS AND BAUD RATE REGISTER (I<sup>2</sup>C MODE)

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
ADD<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

### Master mode:

bit 7-0 **ADD<7:0>**: Baud Rate Clock Divider bits

SCLx pin clock period = ((ADD<7:0> + 1) \* 4) / Fosc

### 10-Bit Slave mode – Most Significant Address Byte:

bit 7-3 **Not used:** Unused for Most Significant Address Byte. Bit state of this register is a “don't care”. Bit pattern sent by master is fixed by I<sup>2</sup>C specification and must be equal to '11110'. However, those bits are compared by hardware and are not affected by the value in this register.

bit 2-1 **ADD<2:1>**: Two Most Significant bits of 10-bit address

bit 0 **Not used:** Unused in this mode. Bit state is a “don't care”.

### 10-Bit Slave mode – Least Significant Address Byte:

bit 7-0 **ADD<7:0>**: Eight Least Significant bits of 10-bit address

### 7-Bit Slave mode:

bit 7-1 **ADD<7:1>**: 7-bit address

bit 0 **Not used:** Unused in this mode. Bit state is a “don't care”.

## 22.1.2.8 Asynchronous Reception Set-up:

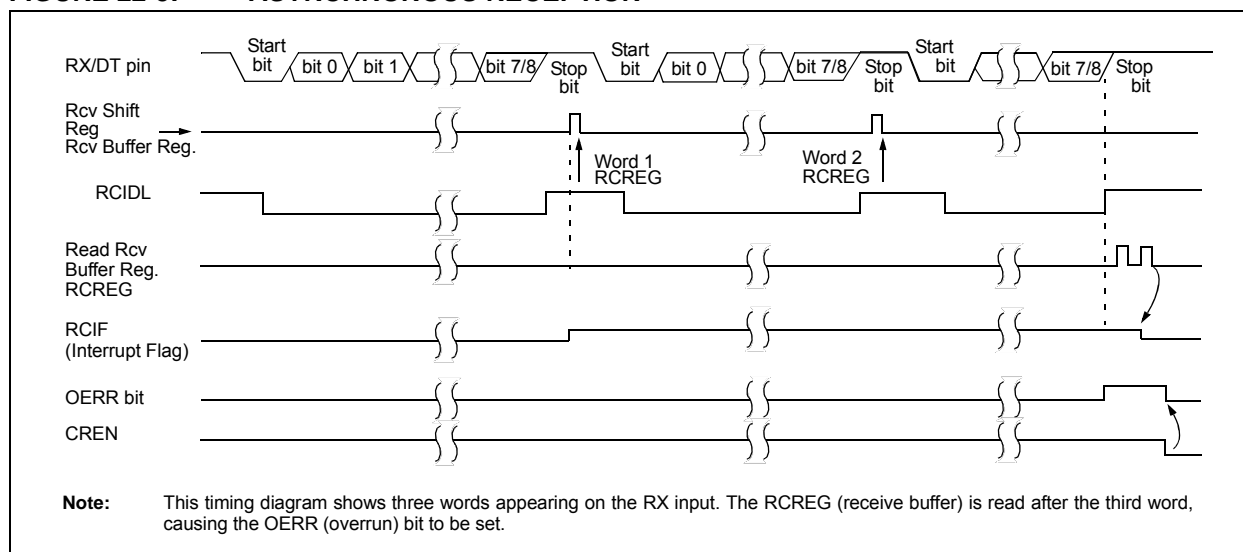
1. Initialize the SPBRGH, SPBRGL register pair and the BRGH and BRG16 bits to achieve the desired baud rate (see **Section 22.4 “EUSART Baud Rate Generator (BRG)”**).
2. Clear the ANSEL bit for the RX pin (if applicable).
3. Enable the serial port by setting the SPEN bit. The SYNC bit must be clear for asynchronous operation.
4. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
5. If 9-bit reception is desired, set the RX9 bit.
6. Enable reception by setting the CREN bit.
7. The RCIF interrupt flag bit will be set when a character is transferred from the RSR to the receive buffer. An interrupt will be generated if the RCIE interrupt enable bit was also set.
8. Read the RCSTA register to get the error flags and, if 9-bit data reception is enabled, the ninth data bit.
9. Get the received eight Least Significant data bits from the receive buffer by reading the RCREG register.
10. If an overrun occurred, clear the OERR flag by clearing the CREN receiver enable bit.

## 22.1.2.9 9-bit Address Detection Mode Set-up

This mode would typically be used in RS-485 systems. To set up an Asynchronous Reception with Address Detect Enable:

1. Initialize the SPBRGH, SPBRGL register pair and the BRGH and BRG16 bits to achieve the desired baud rate (see **Section 22.4 “EUSART Baud Rate Generator (BRG)”**).
2. Clear the ANSEL bit for the RX pin (if applicable).
3. Enable the serial port by setting the SPEN bit. The SYNC bit must be clear for asynchronous operation.
4. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
5. Enable 9-bit reception by setting the RX9 bit.
6. Enable address detection by setting the ADDEN bit.
7. Enable reception by setting the CREN bit.
8. The RCIF interrupt flag bit will be set when a character with the ninth bit set is transferred from the RSR to the receive buffer. An interrupt will be generated if the RCIE interrupt enable bit was also set.
9. Read the RCSTA register to get the error flags. The ninth data bit will always be set.
10. Get the received eight Least Significant data bits from the receive buffer by reading the RCREG register. Software determines if this is the device's address.
11. If an overrun occurred, clear the OERR flag by clearing the CREN receiver enable bit.
12. If the device has been addressed, clear the ADDEN bit to allow all received data into the receive buffer and generate interrupts.

**FIGURE 22-5: ASYNCHRONOUS RECEPTION**



## REGISTER 22-3: BAUDCON: BAUD RATE CONTROL REGISTER

R-0/0	R-1/1	U-0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0
ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7 **ABDOVF:** Auto-Baud Detect Overflow bit

#### Asynchronous mode:

1 = Auto-baud timer overflowed

0 = Auto-baud timer did not overflow

#### Synchronous mode:

Don't care

bit 6 **RCIDL:** Receive Idle Flag bit

#### Asynchronous mode:

1 = Receiver is idle

0 = Start bit has been received and the receiver is receiving

#### Synchronous mode:

Don't care

bit 5 **Unimplemented:** Read as '0'

bit 4 **SCKP:** Synchronous Clock Polarity Select bit

#### Asynchronous mode:

1 = Transmit inverted data to the TX/CK pin

0 = Transmit non-inverted data to the TX/CK pin

#### Synchronous mode:

1 = Data is clocked on rising edge of the clock

0 = Data is clocked on falling edge of the clock

bit 3 **BRG16:** 16-bit Baud Rate Generator bit

1 = 16-bit Baud Rate Generator is used

0 = 8-bit Baud Rate Generator is used

bit 2 **Unimplemented:** Read as '0'

bit 1 **WUE:** Wake-up Enable bit

#### Asynchronous mode:

1 = Receiver is waiting for a falling edge. No character will be received, RCIF bit will be set. WUE will automatically clear after RCIF is set.

0 = Receiver is operating normally

#### Synchronous mode:

Don't care

bit 0 **ABDEN:** Auto-Baud Detect Enable bit

#### Asynchronous mode:

1 = Auto-Baud Detect mode is enabled (clears when auto-baud is complete)

0 = Auto-Baud Detect mode is disabled

#### Synchronous mode:

Don't care

## 22.5.2 SYNCHRONOUS SLAVE MODE

The following bits are used to configure the EUSART for synchronous slave operation:

- SYNC = 1
- CSRC = 0
- SREN = 0 (for transmit); SREN = 1 (for receive)
- CREN = 0 (for transmit); CREN = 1 (for receive)
- SPEN = 1

Setting the SYNC bit of the TXSTA register configures the device for synchronous operation. Clearing the CSRC bit of the TXSTA register configures the device as a slave. Clearing the SREN and CREN bits of the RCSTA register ensures that the device is in the Transmit mode, otherwise the device will be configured to receive. Setting the SPEN bit of the RCSTA register enables the EUSART.

### 22.5.2.1 EUSART Synchronous Slave Transmit

The operation of the Synchronous Master and Slave modes are identical (see **Section 22.5.1.3 “Synchronous Master Transmission”**), except in the case of the Sleep mode.

If two words are written to the TXREG and then the SLEEP instruction is executed, the following will occur:

1. The first character will immediately transfer to the TSR register and transmit.
2. The second word will remain in the TXREG register.
3. The TXIF bit will not be set.
4. After the first character has been shifted out of TSR, the TXREG register will transfer the second character to the TSR and the TXIF bit will now be set.
5. If the PEIE and TXIE bits are set, the interrupt will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will call the Interrupt Service Routine.

### 22.5.2.2 Synchronous Slave Transmission Set-up:

1. Set the SYNC and SPEN bits and clear the CSRC bit.
2. Clear the ANSEL bit for the CK pin (if applicable).
3. Clear the CREN and SREN bits.
4. If interrupts are desired, set the TXIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
5. If 9-bit transmission is desired, set the TX9 bit.
6. Enable transmission by setting the TXEN bit.
7. If 9-bit transmission is selected, insert the Most Significant bit into the TX9D bit.
8. Start transmission by writing the Least Significant eight bits to the TXREG register.

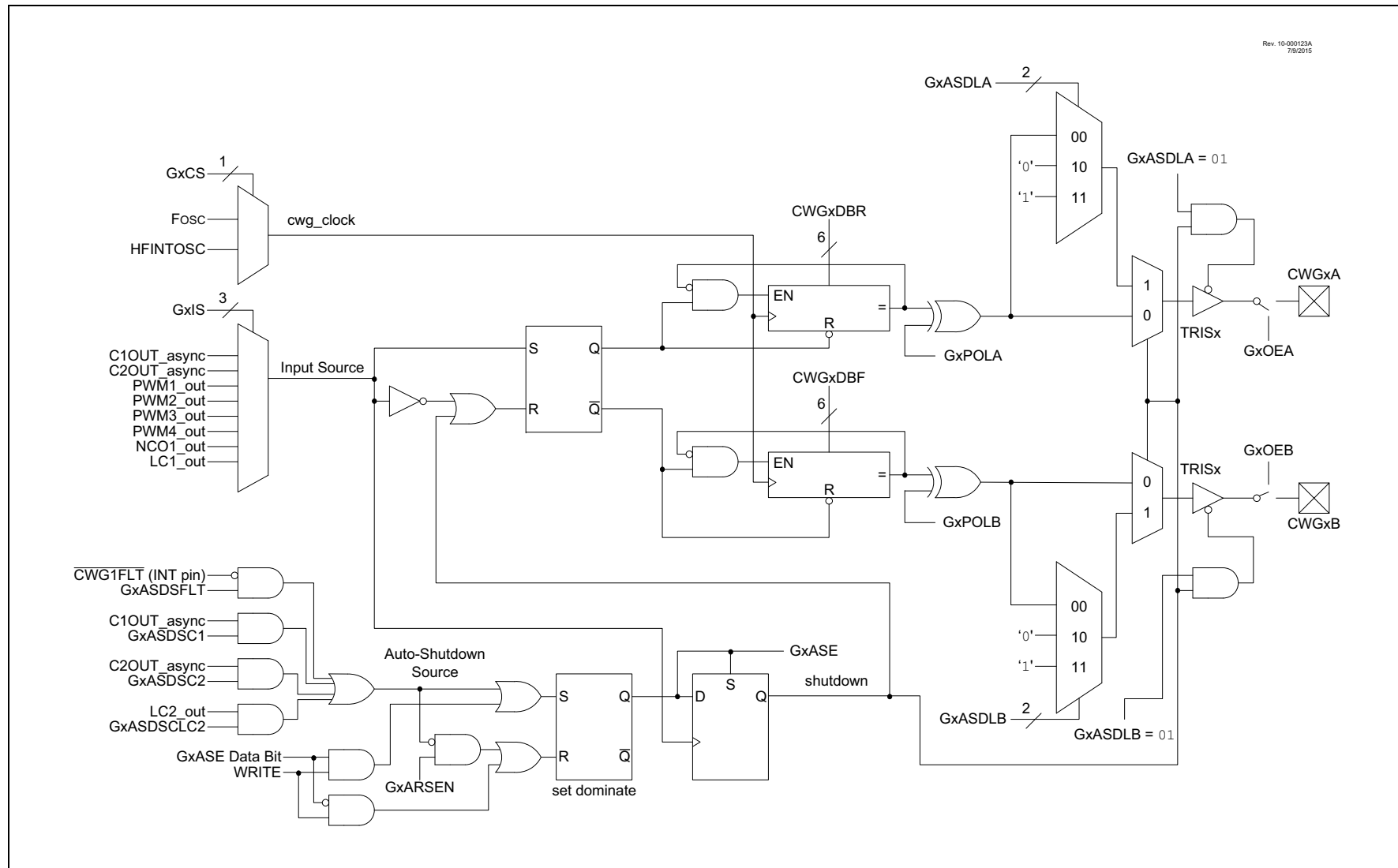
**TABLE 22-9: SUMMARY OF REGISTERS ASSOCIATED WITH SYNCHRONOUS SLAVE TRANSMISSION**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BAUDCON	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	235
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	75
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSP1IE	—	TMR2IE	TMR1IE	76
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSP1IF	—	TMR2IF	TMR1IF	79
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	234
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	113
TXREG	EUSART Transmit Data Register								225*
TXSTA	CSRC	TX9	TXEN	SYNC	SEnDB	BRGH	TRMT	TX9D	233

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used for synchronous slave transmission.

\* Page provides register information.



**FIGURE 26-1: SIMPLIFIED CWG BLOCK DIAGRAM**

**FIGURE 29-8: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING**

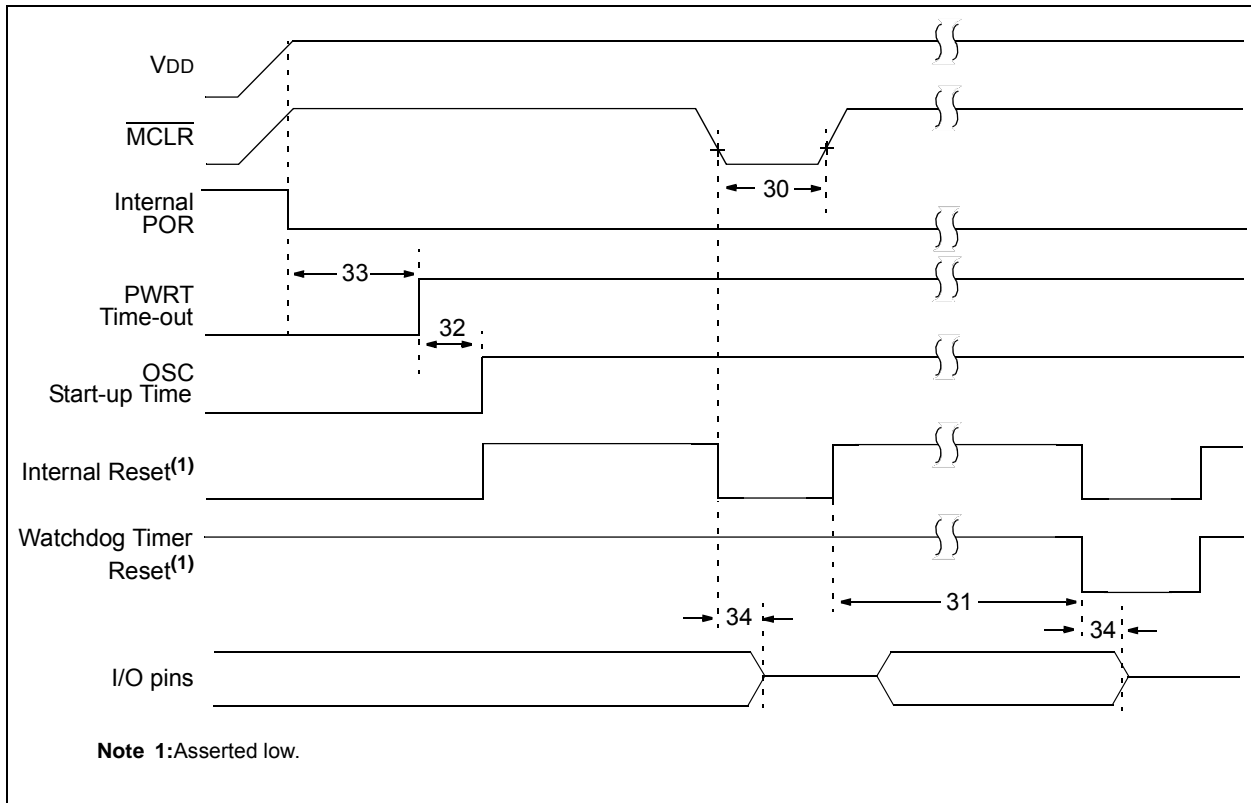


FIGURE 30-11: I<sub>DD</sub> TYPICAL, EXTERNAL CLOCK (ECM), MEDIUM POWER MODE, PIC16LF1508/9 ONLY

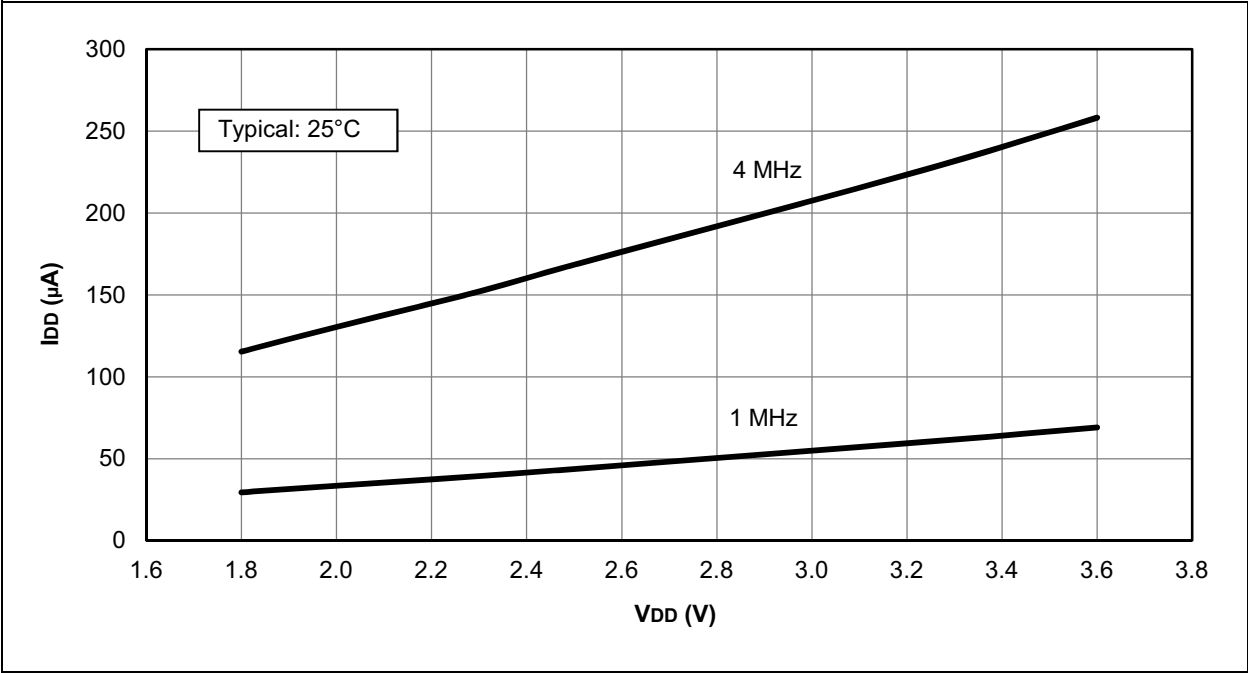
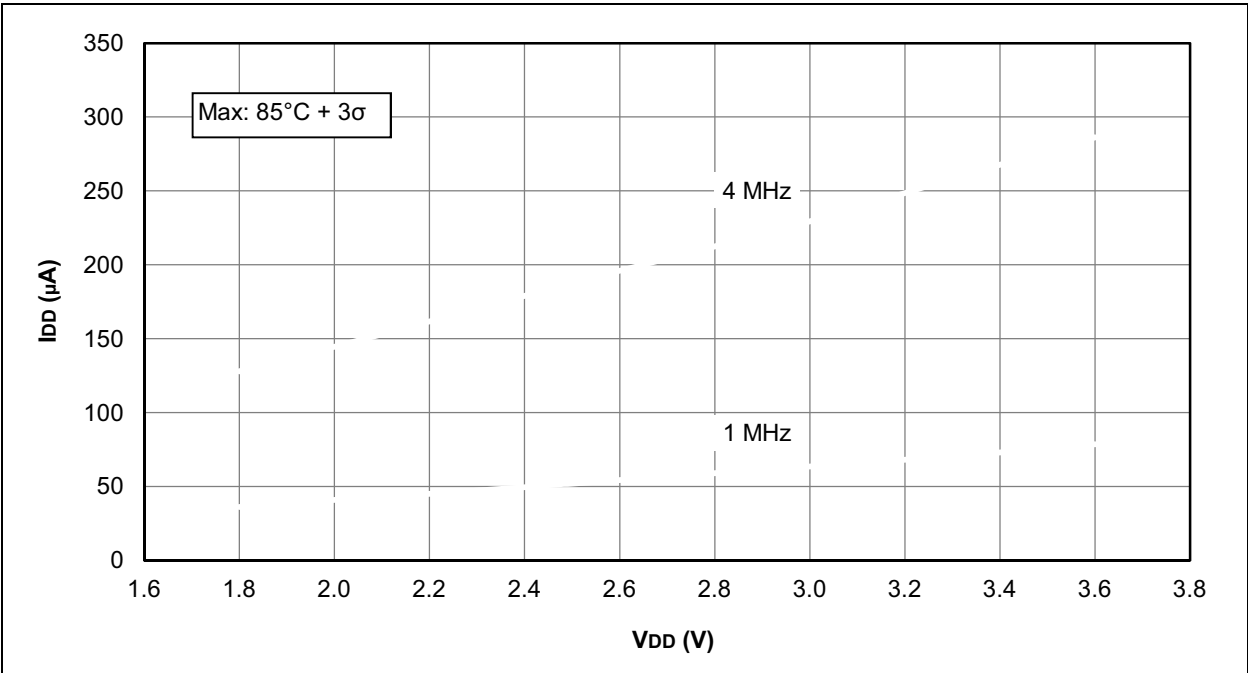
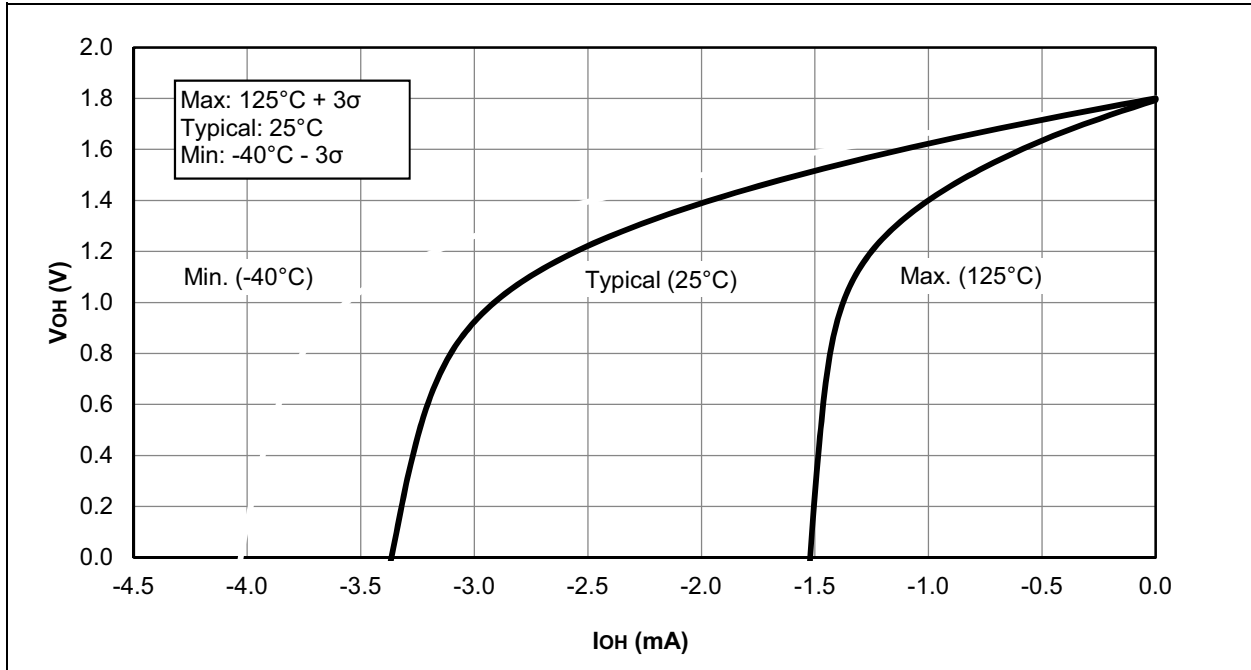


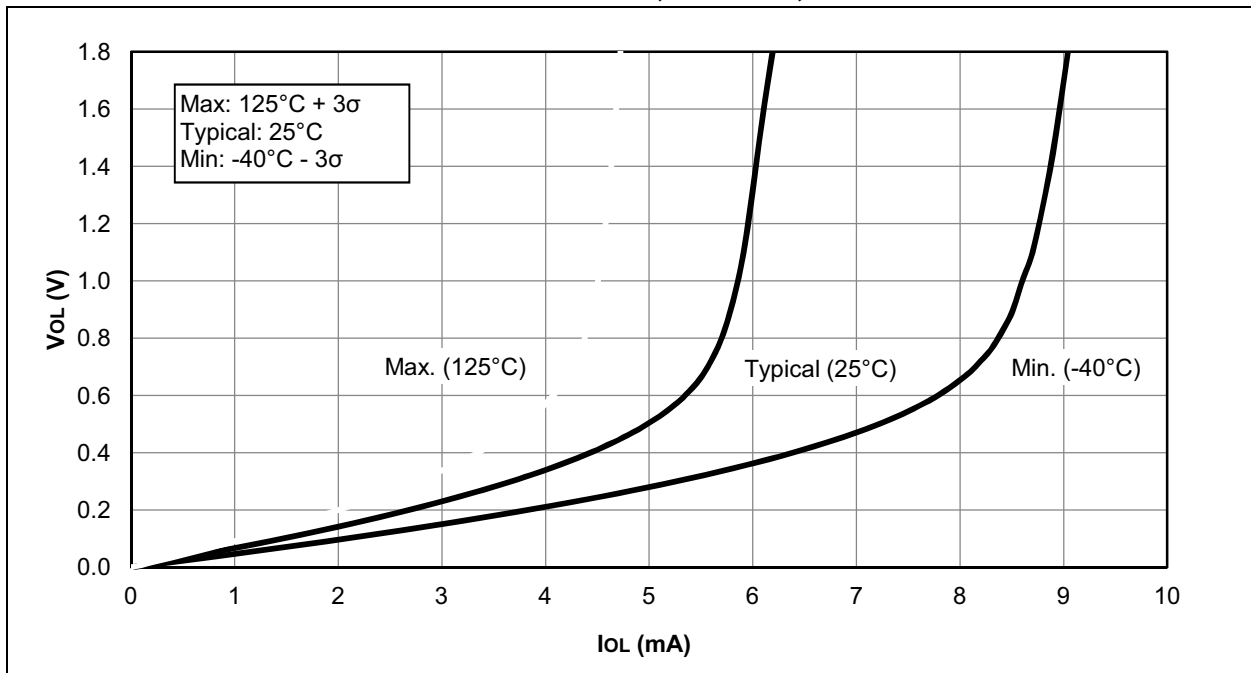
FIGURE 30-12: I<sub>DD</sub> MAXIMUM, EXTERNAL CLOCK (ECM), MEDIUM POWER MODE, PIC16LF1508/9 ONLY



**FIGURE 30-51:  $V_{OH}$  vs.  $I_{OH}$  OVER TEMPERATURE,  $V_{DD} = 1.8V$ , PIC16LF1508/9 ONLY**

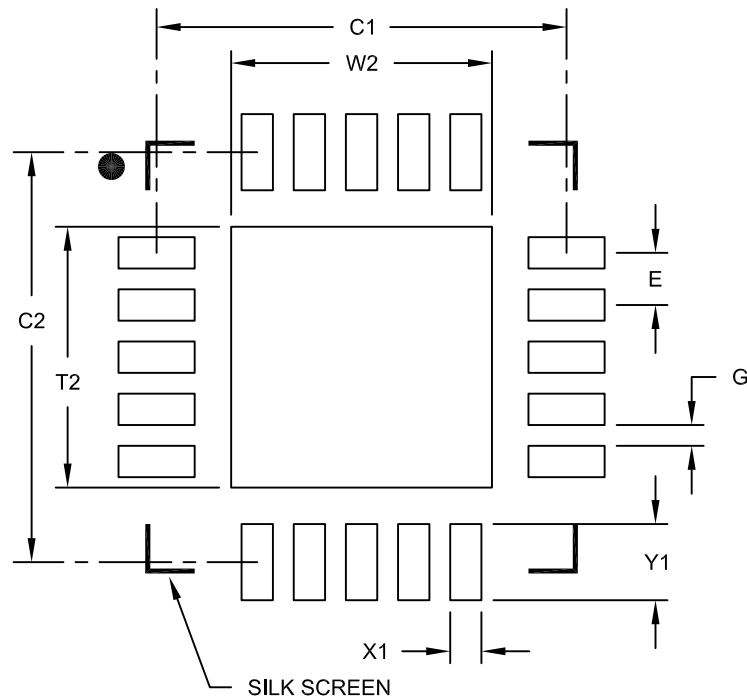


**FIGURE 30-52:  $V_{OL}$  vs.  $I_{OL}$  OVER TEMPERATURE,  $V_{DD} = 1.8V$ , PIC16LF1508/9 ONLY**



20-Lead Plastic Quad Flat, No Lead Package (ML) - 4x4 mm Body [QFN]  
With 0.40 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.50 BSC		
Optional Center Pad Width	W2			2.50
Optional Center Pad Length	T2			2.50
Contact Pad Spacing	C1		3.93	
Contact Pad Spacing	C2		3.93	
Contact Pad Width	X1			0.30
Contact Pad Length	Y1			0.73
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2126A