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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	17
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 12x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	20-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1508-i-ss

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TABLE 1-2: PIC16(L)F1508/9 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/AN0/C1IN+/DAC1OUT1/ ICSPDAT/ICDDAT	RA0	TTL	CMOS	General purpose I/O.
	AN0	AN	—	ADC Channel input.
	C1IN+	AN	—	Comparator positive input.
	DAC1OUT1	—	AN	Digital-to-Analog Converter output.
	ICSPDAT	ST	CMOS	ICSP™ Data I/O.
	ICDDAT	ST	CMOS	In-Circuit Debug data.
RA1/AN1/CLC4IN1/VREF+/ C1IN0-/C2IN0-/ICSPCLK/ ICDCLK	RA1	TTL	CMOS	General purpose I/O.
	AN1	AN	—	ADC Channel input.
	CLC4IN1	ST	—	Configurable Logic Cell source input.
	VREF+	AN	—	ADC Positive Voltage Reference input.
	C1IN0-	AN	—	Comparator negative input.
	C2IN0-	AN	—	Comparator negative input.
	ICSPCLK	ST	—	ICSP Programming Clock.
	ICDCLK	ST	—	In-Circuit Debug Clock.
RA2/AN2/C1OUT/DAC1OUT2/ T0CKI/INT/PWM3/CLC1/ CWG1FLT	RA2	ST	CMOS	General purpose I/O.
	AN2	AN	—	ADC Channel input.
	C1OUT	—	CMOS	Comparator output.
	DAC1OUT2	—	AN	Digital-to-Analog Converter output.
	T0CKI	ST	—	Timer0 clock input.
	INT	ST	—	External interrupt.
	PWM3	—	CMOS	PWM output.
	CLC1	—	CMOS	Configurable Logic Cell source output.
	CWG1FLT	ST	—	Complementary Waveform Generator Fault input.
RA3/CLC1IN0/VPP/T1G(1)/SS(1)/ MCLR	RA3	TTL	—	General purpose input with IOC and WPU.
	CLC1IN0	ST	—	Configurable Logic Cell source input.
	VPP	HV	—	Programming voltage.
	T1G	ST	—	Timer1 Gate input.
	SS	ST	—	Slave Select input.
	MCLR	ST	—	Master Clear with internal pull-up.
RA4/AN3/SOSCO/ CLKOUT/T1G	RA4	TTL	CMOS	General purpose I/O.
	AN3	AN	—	ADC Channel input.
	SOSCO	XTAL	XTAL	Secondary Oscillator Connection.
	CLKOUT	—	CMOS	FOSC/4 output.
	T1G	ST	—	Timer1 Gate input.
RA5/CLKIN/T1CKI/NCO1CLK/ SOSCI	RA5	TTL	CMOS	General purpose I/O.
	CLKIN	CMOS	—	External clock input (EC mode).
	T1CKI	ST	—	Timer1 clock input.
	NCO1CLK	ST	—	Numerically Controlled Oscillator Clock source input.
	SOSCI	XTAL	XTAL	Secondary Oscillator Connection.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open-Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I^2C = Schmitt Trigger input with I^2C levels
HV = High Voltage XTAL = Crystal

Note 1: Alternate pin function selected with the APFCON (Register 11-1) register.

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TABLE 3-6: PIC16(L)F1508/9 MEMORY MAP, BANK 24-31

BANK 24	BANK 25	BANK 26	BANK 27	BANK 28	BANK 29	BANK 30	BANK 31
C00h Core Registers (Table 3-2) C0Bh	C80h Core Registers (Table 3-2) C8Bh	D00h Core Registers (Table 3-2) D0Bh	D80h Core Registers (Table 3-2) D8Bh	E00h Core Registers (Table 3-2) E0Bh	E80h Core Registers (Table 3-2) E8Bh	F00h Core Registers (Table 3-2) F0Bh	F80h Core Registers (Table 3-2) F8Bh
C0Ch —	C8Ch —	D0Ch —	D8Ch —	E0Ch —	E8Ch —	F0Ch See Table 3-7 for register mapping details	F8Ch See Table 3-7 for register mapping details
C0Dh —	C8Dh —	D0Dh —	D8Dh —	E0Dh —	E8Dh —	F0Dh	F8Dh
C0Eh —	C8Eh —	D0Eh —	D8Eh —	E0Eh —	E8Eh —	F0Eh	F8Eh
C0Fh —	C8Fh —	D0Fh —	D8Fh —	E0Fh —	E8Fh —	F0Fh	F8Fh
C10h —	C90h —	D10h —	D90h —	E10h —	E90h —	F10h	F90h
C11h —	C91h —	D11h —	D91h —	E11h —	E91h —	F11h	F91h
C12h —	C92h —	D12h —	D92h —	E12h —	E92h —	F12h	F92h
C13h —	C93h —	D13h —	D93h —	E13h —	E93h —	F13h	F93h
C14h —	C94h —	D14h —	D94h —	E14h —	E94h —	F14h	F94h
C15h —	C95h —	D15h —	D95h —	E15h —	E95h —	F15h	F95h
C16h —	C96h —	D16h —	D96h —	E16h —	E96h —	F16h	F96h
C17h —	C97h —	D17h —	D97h —	E17h —	E97h —	F17h	F97h
C18h —	C98h —	D18h —	D98h —	E18h —	E98h —	F18h	F98h
C19h —	C99h —	D19h —	D99h —	E19h —	E99h —	F19h	F99h
C1Ah —	C9Ah —	D1Ah —	D9Ah —	E1Ah —	E9Ah —	F1Ah	F9Ah
C1Bh —	C9Bh —	D1Bh —	D9Bh —	E1Bh —	E9Bh —	F1Bh	F9Bh
C1Ch —	C9Ch —	D1Ch —	D9Ch —	E1Ch —	E9Ch —	F1Ch	F9Ch
C1Dh —	C9Dh —	D1Dh —	D9Dh —	E1Dh —	E9Dh —	F1Dh	F9Dh
C1Eh —	C9Eh —	D1Eh —	D9Eh —	E1Eh —	E9Eh —	F1Eh	F9Eh
C1Fh —	C9Fh —	D1Fh —	D9Fh —	E1Fh —	E9Fh —	F1Fh	F9Fh
C20h Unimplemented Read as '0' C6Fh	CA0h Unimplemented Read as '0' CEFh	D20h Unimplemented Read as '0' D6Fh	DA0h Unimplemented Read as '0' DEFh	E20h Unimplemented Read as '0' E6Fh	EA0h Unimplemented Read as '0' EEFh	F20h	FA0h
C70h Accesses 70h – 7Fh CFFh	CF0h Accesses 70h – 7Fh CFFh	D70h Accesses 70h – 7Fh D7Fh	DF0h Accesses 70h – 7Fh DFFh	E70h Accesses 70h – 7Fh E7Fh	EF0h Accesses 70h – 7Fh EFFh	F70h Accesses 70h – 7Fh F7Fh	FF0h Accesses 70h – 7Fh FFFh

Legend: = Unimplemented data memory locations, read as '0'.

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TABLE 3-9: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 31											
F8Ch — FE3h	—	Unimplemented								—	—
FE4h	STATUS_SHAD	—	—	—	—	—	Z_SHAD	DC_SHAD	C_SHAD	---- -xxx	---- -uuu
FE5h	WREG_SHAD	Working Register Shadow								xxxx xxxx	uuuu uuuu
FE6h	BSR_SHAD	—	—	—	Bank Select Register Shadow					---x xxxx	---u uuuu
FE7h	PCLATH_SHAD	—	Program Counter Latch High Register Shadow							-xxx xxxx	uuuu uuuu
FE8h	FSR0L_SHAD	Indirect Data Memory Address 0 Low Pointer Shadow								xxxx xxxx	uuuu uuuu
FE9h	FSR0H_SHAD	Indirect Data Memory Address 0 High Pointer Shadow								xxxx xxxx	uuuu uuuu
FEAh	FSR1L_SHAD	Indirect Data Memory Address 1 Low Pointer Shadow								xxxx xxxx	uuuu uuuu
FEBh	FSR1H_SHAD	Indirect Data Memory Address 1 High Pointer Shadow								xxxx xxxx	uuuu uuuu
FECh	—	Unimplemented								—	—
FEDh	STKPTR	—	—	—	Current Stack Pointer					---1 1111	---1 1111
FEEh	TOSL	Top-of-Stack Low byte								xxxx xxxx	uuuu uuuu
FEFh	TOSH	—	Top-of-Stack High byte							-xxx xxxx	-uuu uuuu

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved. Shaded locations are unimplemented, read as '0'.
Note 1: PIC16F1508/9 only.
2: Unimplemented, read as '1'.

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REGISTER 4-1: CONFIG1: CONFIGURATION WORD 1 (CONTINUED)

bit 2-0 **FOSC<2:0>:** Oscillator Selection bits
111 = ECH:External clock, High-Power mode: on CLKIN pin
110 = ECM: External clock, Medium Power mode: on CLKIN pin
101 = ECL: External clock, Low-Power mode: on CLKIN pin
100 = INTOSC oscillator: I/O function on CLKIN pin
011 = EXTRC oscillator: External RC circuit connected to CLKIN pin
010 = HS oscillator: High-speed crystal/resonator connected between OSC1 and OSC2 pins
001 = XT oscillator: Crystal/resonator connected between OSC1 and OSC2 pins
000 = LP oscillator: Low-power crystal connected between OSC1 and OSC2 pins

Note 1: When FSCM is enabled, Two-Speed Start-up will be automatically enabled, regardless of the IESO bit value.
2: Enabling Brown-out Reset does not automatically enable Power-up Timer.
3: Once enabled, code-protect can only be disabled by bulk erasing the device.

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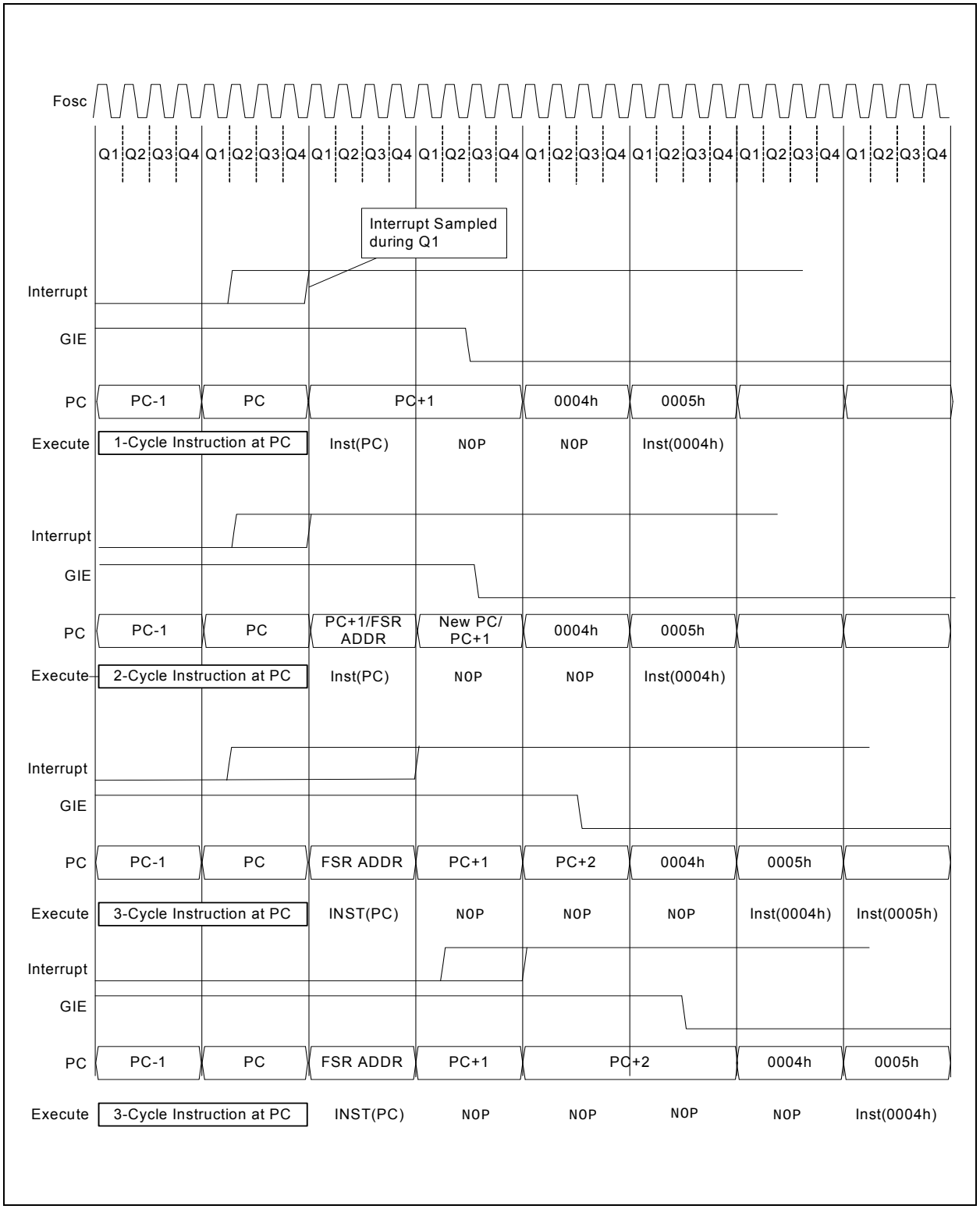
FIGURE 7-2: INTERRUPT LATENCY



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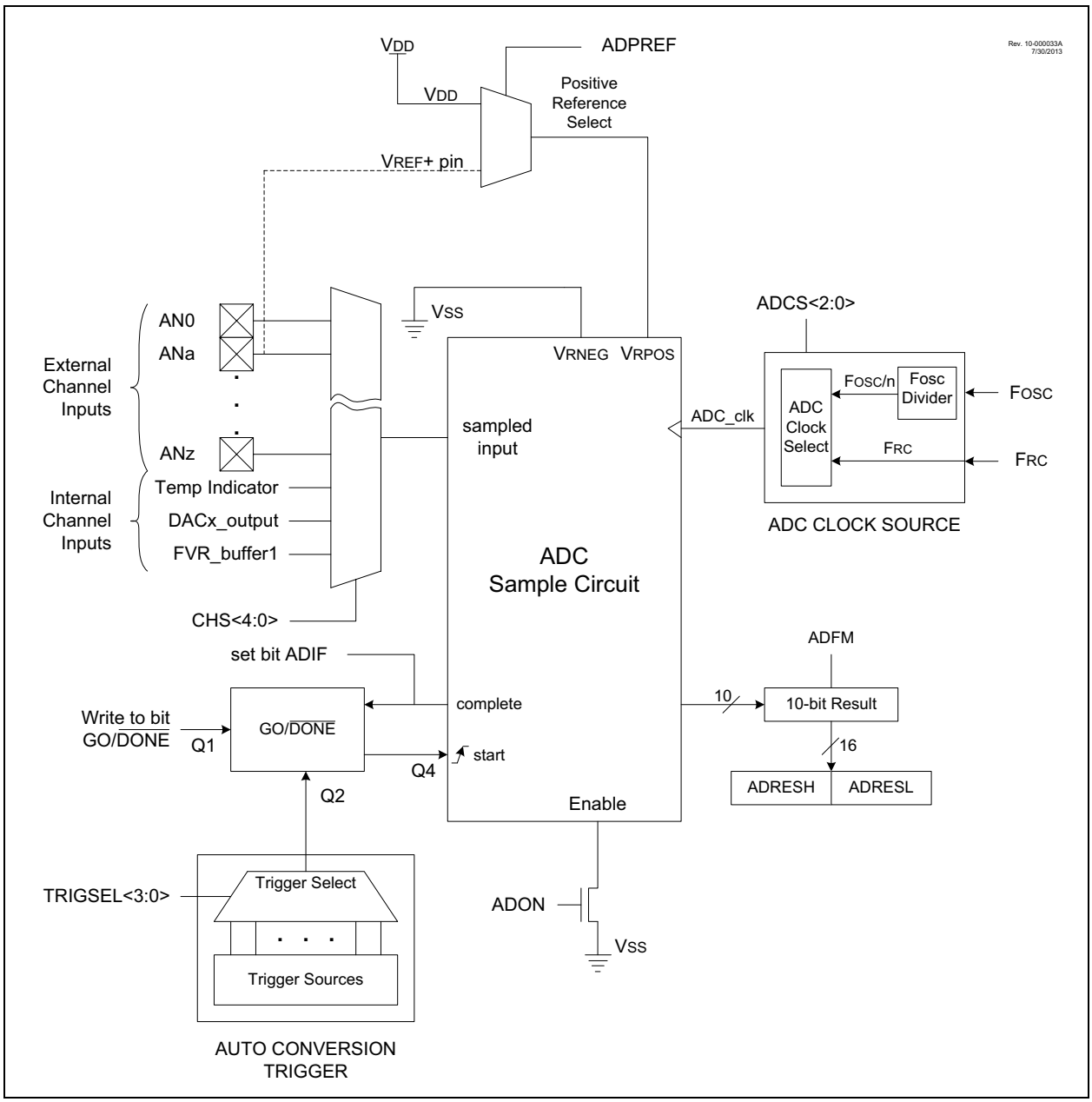
15.0 ANALOG-TO-DIGITAL CONVERTER (ADC) MODULE

The Analog-to-Digital Converter (ADC) allows conversion of an analog input signal to a 10-bit binary representation of that signal. This device uses analog inputs, which are multiplexed into a single sample and hold circuit. The output of the sample and hold is connected to the input of the converter. The converter generates a 10-bit binary result via successive approximation and stores the conversion result into the ADC result registers (ADRESH:ADRESL register pair). Figure 15-1 shows the block diagram of the ADC.

The ADC voltage reference is software selectable to be either internally generated or externally supplied.

The ADC can generate an interrupt upon completion of a conversion. This interrupt can be used to wake-up the device from Sleep.

FIGURE 15-1: ADC BLOCK DIAGRAM



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19.3 Timer1 Prescaler

Timer1 has four prescaler options allowing 1, 2, 4 or 8 divisions of the clock input. The T1CKPS bits of the T1CON register control the prescale counter. The prescale counter is not directly readable or writable; however, the prescaler counter is cleared upon a write to TMR1H or TMR1L.

19.4 Timer1 (Secondary) Oscillator

A dedicated low-power 32.768 kHz oscillator circuit is built-in between pins SOSCI (input) and SOSCO (amplifier output). This internal circuit is to be used in conjunction with an external 32.768 kHz crystal. The oscillator circuit is enabled by setting the T1OSCEN bit of the T1CON register. The oscillator will continue to run during Sleep.

Note:	The oscillator requires some time to start-up and stabilize before use. The SOSCR bit in the OSCSTAT register monitors the oscillator and indicates when the oscillator is ready for use. When T1OSCEN is set, the SOSCR bit is cleared. After 1024 cycles of the oscillator are countered, the SOSCR bit is set, indicating that the oscillator should be stable and ready for use.

19.5 Timer1 Operation in Asynchronous Counter Mode

If control bit $\overline{\text{T1SYNC}}$ of the T1CON register is set, the external clock input is not synchronized. The timer increments asynchronously to the internal phase clocks. If the external clock source is selected then the timer will continue to run during Sleep and can generate an interrupt on overflow, which will wake-up the processor. However, special precautions in software are needed to read/write the timer (see **Section 19.5.1 "Reading and Writing Timer1 in Asynchronous Counter Mode"**).

Note:	When switching from synchronous to asynchronous operation, it is possible to skip an increment. When switching from asynchronous to synchronous operation, it is possible to produce an additional increment.

19.5.1 READING AND WRITING TIMER1 IN ASYNCHRONOUS COUNTER MODE

Reading TMR1H or TMR1L while the timer is running from an external asynchronous clock will ensure a valid read (taken care of in hardware). However, the user should keep in mind that reading the 16-bit timer in two 8-bit values itself, poses certain problems, since the timer may overflow between the reads.

For writes, it is recommended that the user simply stop the timer and write the desired values. A write contention may occur by writing to the timer registers, while the register is incrementing. This may produce an unpredictable value in the TMR1H:TMR1L register pair.

19.6 Timer1 Gate

Timer1 can be configured to count freely or the count can be enabled and disabled using Timer1 gate circuitry. This is also referred to as Timer1 Gate Enable.

Timer1 gate can also be driven by multiple selectable sources.

19.6.1 TIMER1 GATE ENABLE

The Timer1 Gate Enable mode is enabled by setting the TMR1GE bit of the T1GCON register. The polarity of the Timer1 Gate Enable mode is configured using the T1GPOL bit of the T1GCON register.

When Timer1 Gate Enable mode is enabled, Timer1 will increment on the rising edge of the Timer1 clock source. When Timer1 Gate Enable mode is disabled, no incrementing will occur and Timer1 will hold the current count. See Figure 19-3 for timing details.

TABLE 19-3: TIMER1 GATE ENABLE SELECTIONS

T1CLK	T1GPOL	T1G	Timer1 Operation
↑	0	0	Counts
↑	0	1	Holds Count
↑	1	0	Holds Count
↑	1	1	Counts

19.6.2 TIMER1 GATE SOURCE SELECTION

Timer1 gate source selections are shown in Table 19-4. Source selection is controlled by the T1GSS<1:0> bits of the T1GCON register. The polarity for each available source is also selectable. Polarity selection is controlled by the T1GPOL bit of the T1GCON register.

TABLE 19-4: TIMER1 GATE SOURCES

T1GSS	Timer1 Gate Source
00	Timer1 Gate pin (T1G)
01	Overflow of Timer0 (T0_overflow) (TMR0 increments from FFh to 00h)
10	Comparator 1 Output (C1OUT_sync)(1)
11	Comparator 2 Output (C2OUT_sync)(1)

Note 1: Optionally synchronized comparator output.

21.5.3.3 7-bit Transmission with Address Hold Enabled

Setting the AHEN bit of the SSPxCON3 register enables additional clock stretching and interrupt generation after the eighth falling edge of a received matching address. Once a matching address has been clocked in, CKP is cleared and the SSPxIF interrupt is set.

Figure 21-19 displays a standard waveform of a 7-bit Address Slave Transmission with AHEN enabled.

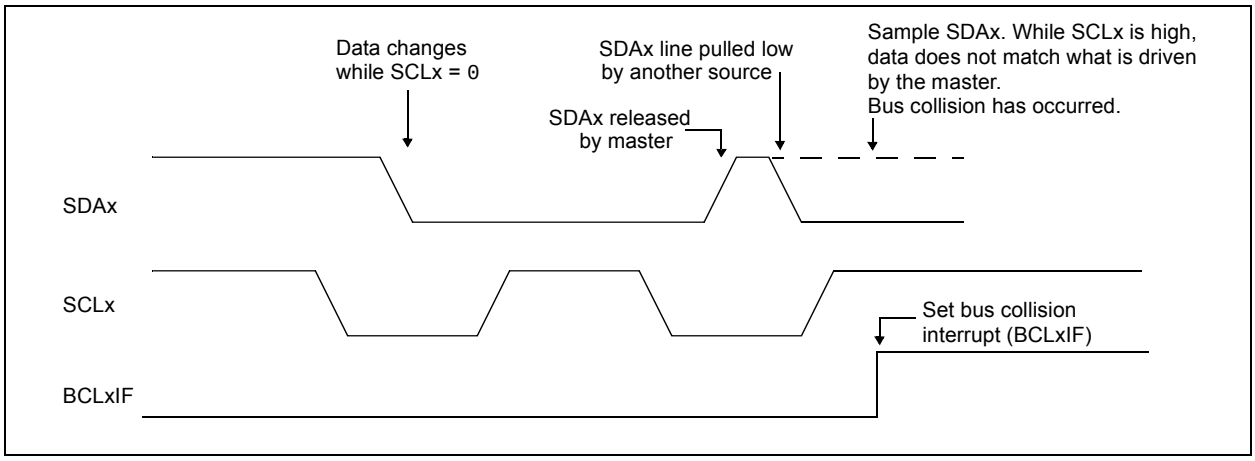
1. Bus starts idle.
2. Master sends Start condition; the S bit of SSPxSTAT is set; SSPxIF is set if interrupt on Start detect is enabled.
3. Master sends matching address with R/$\overline{W}$ bit set. After the eighth falling edge of the SCLx line the CKP bit is cleared and SSPxIF interrupt is generated.
4. Slave software clears SSPxIF.
5. Slave software reads ACKTIM bit of SSPxCON3 register, and R/$\overline{W}$ and D/$\overline{A}$ of the SSPxSTAT register to determine the source of the interrupt.
6. Slave reads the address value from the SSPxBUF register clearing the BF bit.
7. Slave software decides from this information if it wishes to $\overline{ACK}$ or not $\overline{ACK}$ and sets the ACKDT bit of the SSPxCON2 register accordingly.
8. Slave sets the CKP bit releasing SCLx.
9. Master clocks in the $\overline{ACK}$ value from the slave.
10. Slave hardware automatically clears the CKP bit and sets SSPxIF after the $\overline{ACK}$ if the R/$\overline{W}$ bit is set.
11. Slave software clears SSPxIF.
12. Slave loads value to transmit to the master into SSPxBUF setting the BF bit.

Note: SSPxBUF cannot be loaded until after the $\overline{ACK}$.

13. Slave sets the CKP bit, releasing the clock.
14. Master clocks out the data from the slave and sends an $\overline{ACK}$ value on the ninth SCLx pulse.
15. Slave hardware copies the $\overline{ACK}$ value into the ACKSTAT bit of the SSPxCON2 register.
16. Steps 10-15 are repeated for each byte transmitted to the master from the slave.
17. If the master sends a not $\overline{ACK}$ the slave releases the bus allowing the master to send a Stop and end the communication.

Note: Master must send a not $\overline{ACK}$ on the last byte to ensure that the slave releases the SCLx line to receive a Stop.

FIGURE 21-32: BUS COLLISION TIMING FOR TRANSMIT AND ACKNOWLEDGE



REGISTER 21-2: SSPxCON1: SSP CONTROL REGISTER 1

R/C/HS-0/0	R/C/HS-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
WCOL	SSPOV(1)	SSPEN	CKP	SSPM<3:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets	
'1' = Bit is set	'0' = Bit is cleared	HS = Bit is set by hardware	C = User cleared

bit 7 **WCOL:** Write Collision Detect bit
Master mode:
1 = A write to the SSPxBUF register was attempted while the I^2C conditions were not valid for a transmission to be started
0 = No collision
Slave mode:
1 = The SSPxBUF register is written while it is still transmitting the previous word (must be cleared in software)
0 = No collision

bit 6 **SSPOV:** Receive Overflow Indicator bit(1)
In SPI mode:
1 = A new byte is received while the SSPxBUF register is still holding the previous data. In case of overflow, the data in SSPxSR is lost. Overflow can only occur in Slave mode. In Slave mode, the user must read the SSPxBUF, even if only transmitting data, to avoid setting overflow. In Master mode, the overflow bit is not set since each new reception (and transmission) is initiated by writing to the SSPxBUF register (must be cleared in software).
0 = No overflow
In I^2C mode:
1 = A byte is received while the SSPxBUF register is still holding the previous byte. SSPOV is a "don't care" in Transmit mode (must be cleared in software).
0 = No overflow

bit 5 **SSPEN:** Synchronous Serial Port Enable bit
In both modes, when enabled, these pins must be properly configured as input or output
In SPI mode:
1 = Enables serial port and configures SCKx, SDOx, SDIx and $\overline{SS}$x as the source of the serial port pins(2)
0 = Disables serial port and configures these pins as I/O port pins
In I^2C mode:
1 = Enables the serial port and configures the SDAx and SCLx pins as the source of the serial port pins(3)
0 = Disables serial port and configures these pins as I/O port pins

bit 4 **CKP:** Clock Polarity Select bit
In SPI mode:
1 = Idle state for clock is a high level
0 = Idle state for clock is a low level
In I^2C Slave mode:
SCLx release control
1 = Enable clock
0 = Holds clock low (clock stretch). (Used to ensure data setup time.)
In I^2C Master mode:
Unused in this mode

bit 3-0 **SSPM<3:0>:** Synchronous Serial Port Mode Select bits
0000 = SPI Master mode, clock = FOSC/4
0001 = SPI Master mode, clock = FOSC/16
0010 = SPI Master mode, clock = FOSC/64
0011 = SPI Master mode, clock = T2_match/2
0100 = SPI Slave mode, clock = SCKx pin, $\overline{SS}$ pin control enabled
0101 = SPI Slave mode, clock = SCKx pin, $\overline{SS}$ pin control disabled, $\overline{SS}$x can be used as I/O pin
0110 = I^2C Slave mode, 7-bit address
0111 = I^2C Slave mode, 10-bit address
1000 = I^2C Master mode, clock = FOSC/(4 * (SSPxADD+1))(4)
1001 = Reserved
1010 = SPI Master mode, clock = FOSC/(4 * (SSPxADD+1))(5)
1011 = I^2C firmware controlled Master mode (Slave idle)
1100 = Reserved
1101 = Reserved
1110 = I^2C Slave mode, 7-bit address with Start and Stop bit interrupts enabled
1111 = I^2C Slave mode, 10-bit address with Start and Stop bit interrupts enabled

Note 1: In Master mode, the overflow bit is not set since each new reception (and transmission) is initiated by writing to the SSPxBUF register.
2: When enabled, these pins must be properly configured as input or output.
3: When enabled, the SDAx and SCLx pins must be configured as inputs.
4: SSPxADD values of 0, 1 or 2 are not supported for I^2C mode.
5: SSPxADD value of '0' is not supported. Use SSPM = 0000 instead.

REGISTER 21-5: SSPxMSK: SSP MASK REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
MSK<7:0>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-1 **MSK<7:1>:** Mask bits
1 = The received address bit n is compared to SSPxADD<n> to detect I^2C address match
0 = The received address bit n is not used to detect I^2C address match

bit 0 **MSK<0>:** Mask bit for I^2C Slave mode, 10-bit Address
I^2C Slave mode, 10-bit address (SSPM<3:0> = 0111 or 1111):
1 = The received address bit 0 is compared to SSPxADD<0> to detect I^2C address match
0 = The received address bit 0 is not used to detect I^2C address match
I^2C Slave mode, 7-bit address, the bit is ignored

REGISTER 21-6: SSPxADD: MSSP ADDRESS AND BAUD RATE REGISTER (I^2C MODE)

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
ADD<7:0>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

Master mode:

bit 7-0 **ADD<7:0>:** Baud Rate Clock Divider bits
SCLx pin clock period = ((ADD<7:0> + 1) *4)/FOSC

10-Bit Slave mode – Most Significant Address Byte:

bit 7-3 **Not used:** Unused for Most Significant Address Byte. Bit state of this register is a "don't care". Bit pattern sent by master is fixed by I^2C specification and must be equal to '11110'. However, those bits are compared by hardware and are not affected by the value in this register.

bit 2-1 **ADD<2:1>:** Two Most Significant bits of 10-bit address

bit 0 **Not used:** Unused in this mode. Bit state is a "don't care".

10-Bit Slave mode – Least Significant Address Byte:

bit 7-0 **ADD<7:0>:** Eight Least Significant bits of 10-bit address

7-Bit Slave mode:

bit 7-1 **ADD<7:1>:** 7-bit address

bit 0 **Not used:** Unused in this mode. Bit state is a "don't care".

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24.1.2 DATA GATING

Outputs from the input multiplexers are directed to the desired logic function input through the data gating stage. Each data gate can direct any combination of the four selected inputs.

Note:	Data gating is undefined at power-up.

The gate stage is more than just signal direction. The gate can be configured to direct each input signal as inverted or non-inverted data. Directed signals are ANDed together in each gate. The output of each gate can be inverted before going on to the logic function stage.

The gating is in essence a 1-to-4 input AND/NAND/OR/NOR gate. When every input is inverted and the output is inverted, the gate is an OR of all enabled data inputs. When the inputs and output are not inverted, the gate is an AND or all enabled inputs.

Table 24-2 summarizes the basic logic that can be obtained in gate 1 by using the gate logic select bits. The table shows the logic of four input variables, but each gate can be configured to use less than four. If no inputs are selected, the output will be zero or one, depending on the gate output polarity bit.

TABLE 24-2: DATA GATING LOGIC

CLCxGLS0	LCxG1POL	Gate Logic
0x55	1	AND
0x55	0	NAND
0xAA	1	NOR
0xAA	0	OR
0x00	0	Logic 0
0x00	1	Logic 1

It is possible (but not recommended) to select both the true and negated values of an input. When this is done, the gate output is zero, regardless of the other inputs, but may emit logic glitches (transient-induced pulses). If the output of the channel must be zero or one, the recommended method is to set all gate bits to zero and use the gate polarity bit to set the desired level.

Data gating is configured with the logic gate select registers as follows:

- Gate 1: CLCxGLS0 (Register 24-5)
- Gate 2: CLCxGLS1 (Register 24-6)
- Gate 3: CLCxGLS2 (Register 24-7)
- Gate 4: CLCxGLS3 (Register 24-8)

Register number suffixes are different than the gate numbers because other variations of this module have multiple gate selections in the same register.

Data gating is indicated in the right side of Figure 24-2. Only one gate is shown in detail. The remaining three gates are configured identically with the exception that the data enables correspond to the enables for that gate.

24.1.3 LOGIC FUNCTION

There are eight available logic functions including:

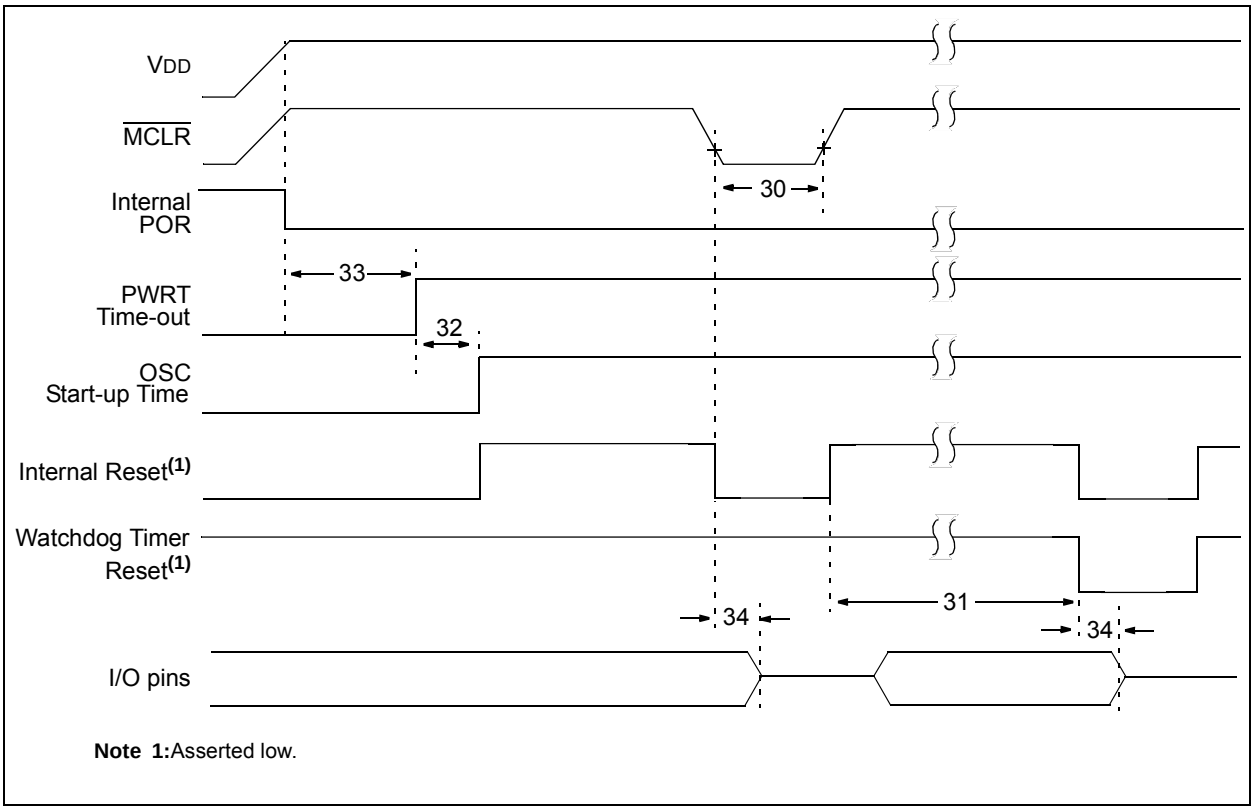
- AND-OR
- OR-XOR
- AND
- S-R Latch
- D Flip-Flop with Set and Reset
- D Flip-Flop with Reset
- J-K Flip-Flop with Reset
- Transparent Latch with Set and Reset

Logic functions are shown in Figure 24-3. Each logic function has four inputs and one output. The four inputs are the four data gate outputs of the previous stage. The output is fed to the inversion stage and from there to other peripherals, an output pin, and back to the CLCx itself.

24.1.4 OUTPUT POLARITY

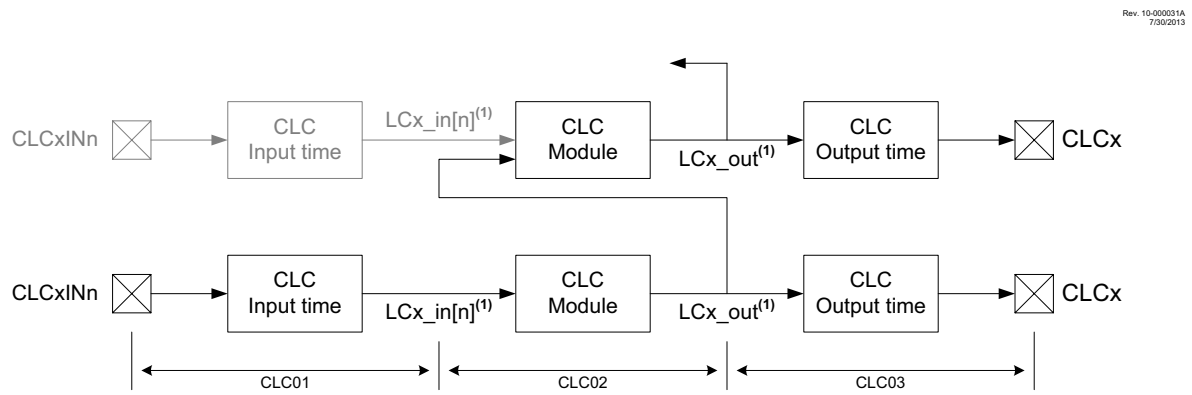
The last stage in the configurable logic cell is the output polarity. Setting the LCxPOL bit of the CLCxCON register inverts the output signal from the logic stage. Changing the polarity while the interrupts are enabled will cause an interrupt for the resulting output transition.

FIGURE 29-8: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING



Note 1: Asserted low.

FIGURE 29-11: CLC PROPAGATION TIMING



Note 1: See FIGURE 24-1:, Configurable Logic Cell Block Diagram, to identify specific CLC signals.

TABLE 29-12: CONFIGURATION LOGIC CELL (CLC) CHARACTERISTICS

Standard Operating Conditions (unless otherwise stated)							
Param. No.	**Sym.**	**Characteristic**	**Min.**	**Typ†**	**Max.**	**Units**	**Conditions**
CLC01*	TCLCIN	CLC input time	—	7	—	ns	
CLC02*	TCLC	CLC module input to output propagation time	— —	24 12	— —	ns ns	VDD = 1.8V VDD > 3.6V
CLC03*	TCLCOUT	CLC output time Rise Time	—	OS18	—	—	**(Note 1)**
		Fall Time	—	OS19	—	—	**(Note 1)**
CLC04*	FCLCMAX	CLC maximum switching frequency	—	45	—	MHz	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: See Table 29-9 for OS18 and OS19 rise and fall times.

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FIGURE 30-1: IDD, LP OSCILLATOR, FOSC = 32 kHz, PIC16LF1508/9 ONLY

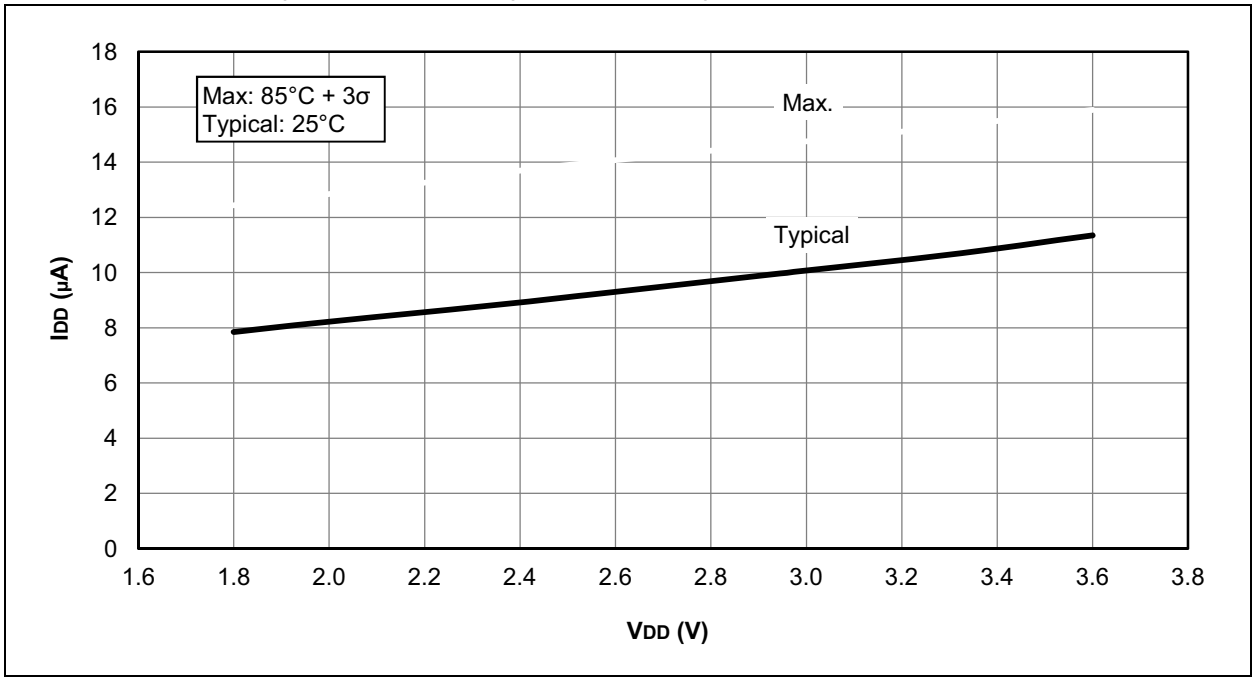

FIGURE 30-2: IDD, LP OSCILLATOR, FOSC = 32 kHz, PIC16F1508/9 ONLY

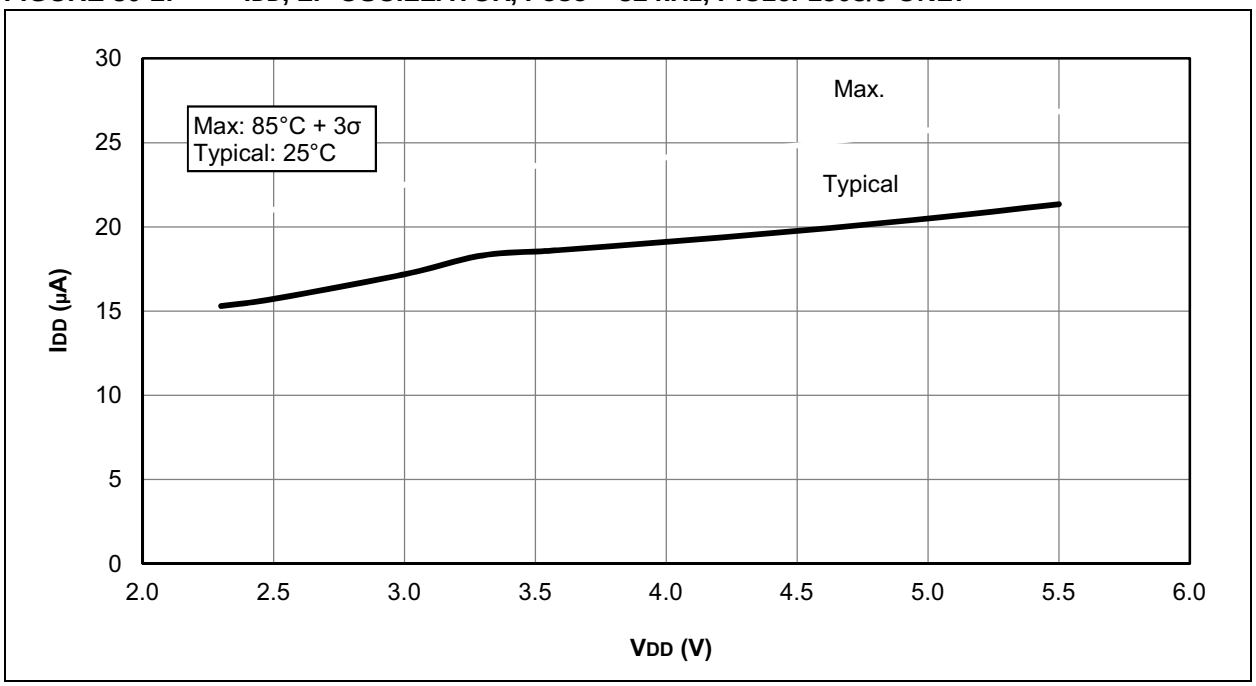

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FIGURE 30-35: IPD, FIXED VOLTAGE REFERENCE (FVR), PIC16LF1508/9 ONLY

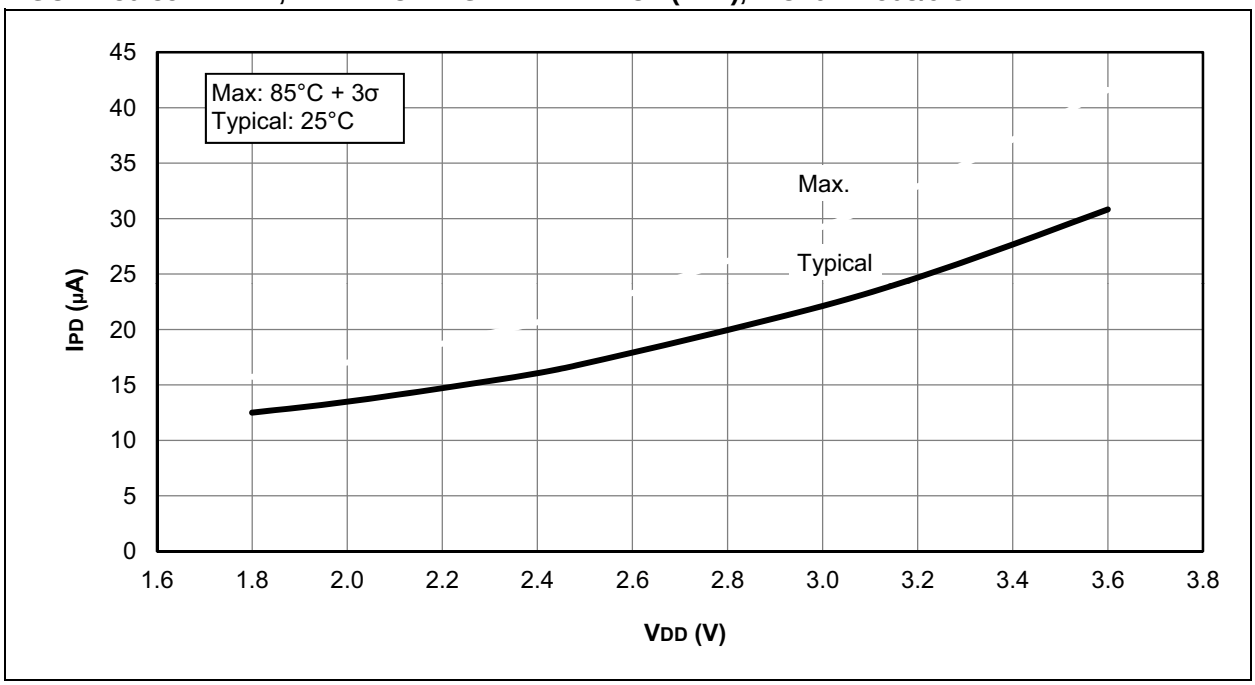
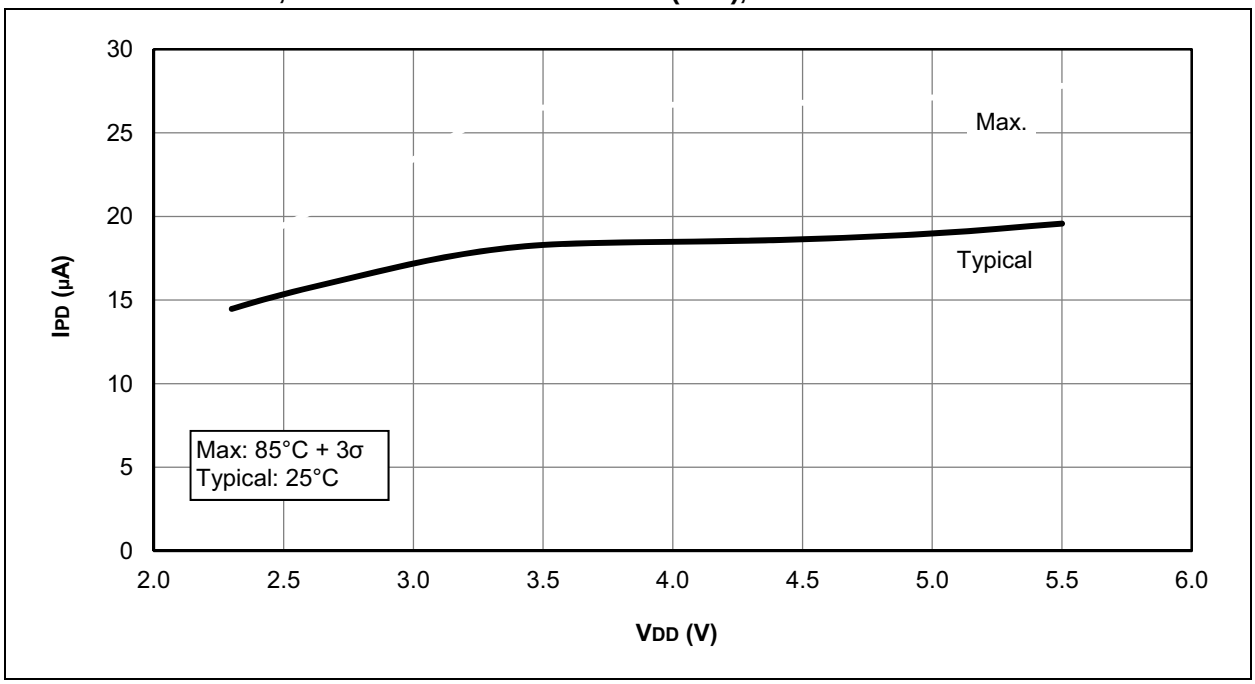


FIGURE 30-36: IPD, FIXED VOLTAGE REFERENCE (FVR), PIC16F1508/9 ONLY



APPENDIX A: DATA SHEET REVISION HISTORY

Revision A (10/2011)

Original release.

Revision B (6/2013)

Updated Electrical Specifications and added Characterization Data.

Revision C (7/2013)

Corrected upper and lower bit definitions of address, Section 3.2. Added clarification of Buffer Gain Selection bits, Section 13.2. Removed "Preliminary" status from Section 30. Updated Figures 15-1, 29-9. Clarified information in Registers 7-1,13-1, 15-2. Clarified information in Tables 29-5, 29-10, 29-13. Removed Index.

Revision D (10/2014)

Document re-release.

Revision E (10/2015)

Added Section 3.2 High-Endurance Flash. Updated Figure 26-1; Registers 4-2, 7-5, and 26-3; Sections 22.4.2, 24.1.5, 26.9.1.2, 26.11.1, and 29.1; and Table 26-2.

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