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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Details	
Product Status	Active
Core Processor	80C51
Core Size	8-Bit
Speed	48MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART, USB
Peripherals	LED, POR, PWM, WDT
Number of I/O	34
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	1.25K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/at89c5130a-rdrum

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



#### Table 3-10.USB Signal Description

Signal Name	Туре	Description	Alternate Function
D+	I/O	USB Data + signal Set to high level under reset.	-
D-	I/O	USB Data - signal Set to low level under reset.	-
VREF	0	USB Reference Voltage Connect this pin to D+ using a 1.5 k $\Omega$ resistor to use the Detach function.	-

### Table 3-11. System Signal Description

Signal Name	Туре	Description	Alternate Function			
AD[7:0]	I/O	Multiplexed Address/Data LSB for external access Data LSB for Slave port access (used for 8-bit and 16-bit modes)	P0[7:0]			
A[15:8]	I/O	Address Bus MSB for external access				
RD	I/O	Read Signal Read signal asserted during external data memory read operation. Control input for slave port read access cycles.				
WR	I/O	Write Signal Write signal asserted during external data memory write operation. Control input for slave write access cycles.				
RST	0	<b>Reset Input</b> Holding this pin low for 64 oscillator periods while the oscillator is running resets the device. The Port pins are driven to their reset conditions when a voltage lower than $V_{IL}$ is applied, whether or not the oscillator is running. This pin has an internal pull-up resistor which allows the device to be reset by connecting a capacitor between this pin and VSS. Asserting RST when the chip is in Idle mode or Power-down mode returns the chip to normal operation. This pin is tied to 0 for at least 12 oscillator periods when an internal reset occurs (hardware watchdog or power monitor).	-			
ALE	0	Address Latch Enable Output The falling edge of ALE strobes the address into external latch. This signal is active only when reading or writing external memory using MOVX instructions.	-			
PSEN	I/O	Program Strobe Enable / Hardware conditions Input for ISP Used as input under reset to detect external hardware conditions of ISP mode.				
ĒĀ	I	External Access Enable This pin must be held low to force the device to fetch code from external program memory starting at address 0000h.	-			

## Table 3-12. Power Signal Description

Signal Name	Туре	Description	Alternate Function
AVSS	GND	Analog Ground AVSS is used to supply the on-chip PLL and the USB PAD.	-

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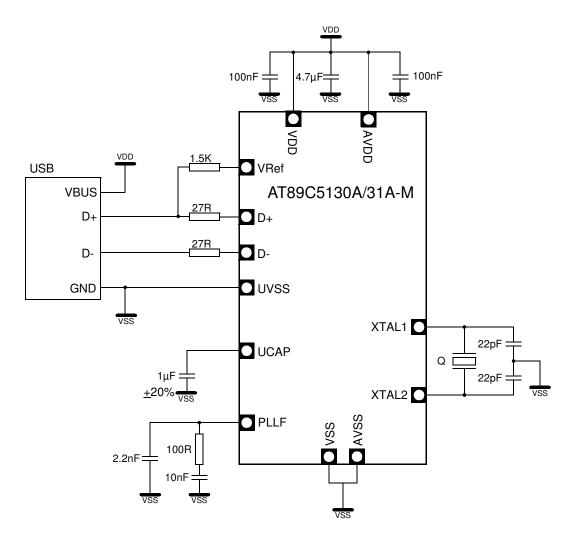
## 4. Typical Application

## 4.1 Recommended External components

All the external components described in the figure below must be implemented as close as possible from the microcontroller package.

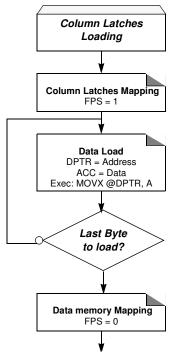
The following figure represents the typical wiring schematic.

Figure 4-1. Typical Application





#### Figure 8-5. Column Latches Loading Procedure



#### 8.3.6 Programming the Flash Spaces

8.3.6.1 User

The following procedure is used to program the User space and is summarized in Figure 8-6:

- Load data in the column latches from address 0000h to 7FFFh<sup>(1)</sup>.
- Disable the interrupts.
- Launch the programming by writing the data sequence 50h followed by A0h in FCON register.

The end of the programming indicated by the FBUSY flag cleared.

- Enable the interrupts.
- Note: 1. The last page address used when loading the column latch is the one used to select the page programming address.

#### 8.3.6.2 Extra Row

The following procedure is used to program the Extra Row space and is summarized in Figure 8-6:

- Load data in the column latches from address FF80h to FFFFh.
- Disable the interrupts.
- Launch the programming by writing the data sequence 52h followed by A2h in FCON register.

The end of the programming indicated by the FBUSY flag cleared.

· Enable the interrupts.



#### Table 9-5. Program Lock Bits of the SSB

Progra	n Lock I	Bits	
Security Level	LB0	LB1	Protection Description
1	U	U	No program lock features enabled.
2	Р	U	ISP programming of the Flash is disabled.
3	Р	Р	Same as 2, also verify through ISP programming interface is disabled.

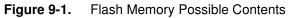
Notes: 1. U: unprogrammed or "one" level.

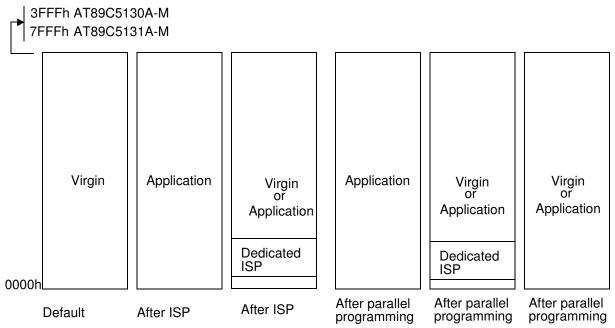
2. P: programmed or "zero" level.

3. WARNING: Security level 2 and 3 should only be programmed after Flash and code verification.

#### 9.5 Flash Memory Status

AT89C5130A/31A-M parts are delivered with the ISP boot in the Flash memory. After ISP or parallel programming, the possible contents of the Flash memory are summarized in Figure 9-1:





### 9.6 Memory Organization

In the AT89C5130A/31A-M, the lowest 16/32K of the 64 Kbyte program memory address space is filled by internal Flash.

When the  $\overline{EA}$  is pin high, the processor fetches instructions from internal program Flash. Bus expansion for accessing program memory from 16/32K upward is automatic since external instruction fetches occur automatically when the program counter exceeds 3FFFh (16K) or 7FFFh (32K). If the  $\overline{EA}$  pin is tied low, all program memory fetches are from external memory. If all storage is on chip, then byte location 3FFFh (16K) or 7FFFh (32K) should be left vacant to prevent and undesired pre-fetch from external program memory address 4000h (16K) or 8000h (32K).

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## 12. On-chip Expanded RAM (ERAM)

The AT89C5130A/31A-M provides additional Bytes of random access memory (RAM) space for increased data parameters handling and high level language usage.

AT89C5130A/31A-M devices have expanded RAM in external data space; maximum size and location are described in Table 12-1.

 Table 12-1.
 Description of Expanded RAM

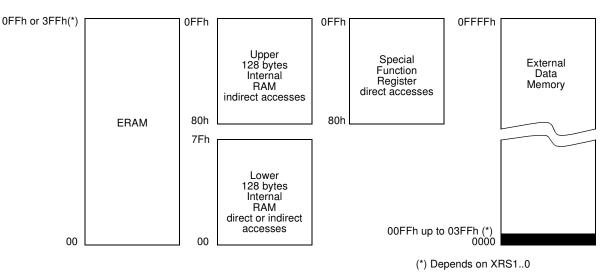
		Address		
Part Number	ERAM Size	Start	End	
AT89C5130A/31A-M	1024	00h	3FFh	

The AT89C5130A/31A-M has on-chip data memory which is mapped into the following four separate segments.

- 1. The Lower 128 bytes of RAM (addresses 00h to 7Fh) are directly and indirectly addressable.
- 2. The Upper 128 bytes of RAM (addresses 80h to FFh) are indirectly addressable only.
- 3. The Special Function Registers, SFRs, (addresses 80h to FFh) are directly addressable only.
- 4. The expanded RAM bytes are indirectly accessed by MOVX instructions, and with the EXTRAM bit cleared in the AUXR register (see Table 12-1)

The lower 128 bytes can be accessed by either direct or indirect addressing. The Upper 128 bytes can be accessed by indirect addressing only. The Upper 128 bytes occupy the same address space as the SFR. That means they have the same address, but are physically separate from SFR space.

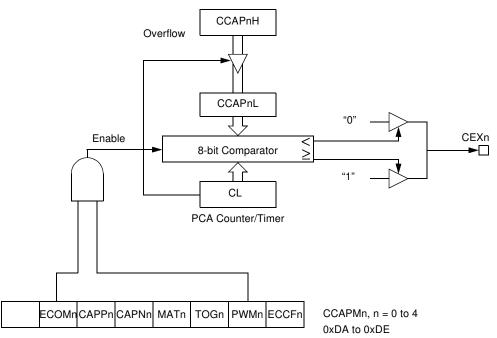
#### Figure 12-1. Internal and External Data Memory Address



When an instruction accesses an internal location above address 7Fh, the CPU knows whether the access is to the upper 128 bytes of data RAM or to SFR space by the addressing mode used in the instruction.



#### Figure 14-6. PCA PWM Mode



#### 14.5 PCA Watchdog Timer

An on-board watchdog timer is available with the PCA to improve the reliability of the system without increasing chip count. Watchdog timers are useful for systems that are susceptible to noise, power glitches, or electrostatic discharge. Module 4 is the only PCA module that can be programmed as a watchdog. However, this module can still be used for other modes if the watchdog is not needed. Figure 14-4 shows a diagram of how the watchdog works. The user pre-loads a 16-bit value in the compare registers. Just like the other compare modes, this 16-bit value is compared to the PCA timer value. If a match is allowed to occur, an internal reset will be generated. This will not cause the RST pin to be driven low.

In order to hold off the reset, the user has three options:

- 1. Periodically change the compare value so it will never match the PCA timer
- 2. Periodically change the PCA timer value so it will never match the compare values, or
- Disable the watchdog by clearing the WDTE bit before a match occurs and then reenable it

The first two options are more reliable because the watchdog timer is never disabled as in option #3. If the program counter ever goes astray, a match will eventually occur and cause an internal reset. The second option is also not recommended if other PCA modules are being used. Remember, the PCA timer is the time base for all modules; changing the time base for other modules would not be a good idea. Thus, in most applications the first solution is the best option.

This watchdog timer won't generate a reset out on the reset pin.



Bit Number	Bit Mnemonic	Description				
Number	Milemonic					
7	FE	Framing Error bit (SMOD0 = 1) Clear to reset the error state, not cleared by a valid stop bit. Set by hardware when an invalid stop bit is detected. SMOD0 must be set to enable access to the FE bit				
	SM0	Serial port Mode bit 0 Refer to SM1 for serial port mode selection. SMOD0 must be cleared to enable access to the SM0 bit				
6	SM1	Serial port Mode bit 1         SM0SM1Mode DescriptionBaud Rate         0       0       Shift RegisterF <sub>CPUPERIPH</sub> /6         0       1       8-bit UARTVariable         1       0       2       9-bit UARTF <sub>CPUPERIPH</sub> /32 or/16         1       1       3       9-bit UARTVariable				
5	SM2	erial port Mode 2 bit/Multiprocessor Communication Enable bit lear to disable multiprocessor communication feature. et to enable multiprocessor communication feature in mode 2 and 3, and eventually ode 1. This bit should be cleared in mode 0.				
4	REN	Reception Enable bit Clear to disable serial reception. Set to enable serial reception.				
3	TB8	Transmitter Bit 8/Ninth bit to Transmit in Modes 2 and 3 Clear to transmit a logic 0 in the 9th bit. Set to transmit a logic 1 in the 9th bit.				
2	RB8	Receiver Bit 8/Ninth bit received in modes 2 and 3 Cleared by hardware if 9th bit received is a logic 0. Set by hardware if 9th bit received is a logic 1. In mode 1, if SM2 = 0, RB8 is the received stop bit. In mode 0 RB8 is not used.				
1	ті	<b>Transmit Interrupt flag</b> Clear to acknowledge interrupt. Set by hardware at the end of the 8th bit time in mode 0 or at the beginning of the stop bit in the other modes.				
0	RI	Receive Interrupt flag Clear to acknowledge interrupt. Set by hardware at the end of the 8th bit time in mode 0, see Figure 15-2. and Figure 15- 3. in the other modes.				

Reset Value = 0000 0000b Bit addressable



Each interrupt source can also be individually programmed to one out of four priority levels by setting or clearing a bit in the Interrupt Priority register (Table 16-3.) and in the Interrupt Priority High register (Table 16-4). Table 16-1. shows the bit values and priority levels associated with each combination.

#### 16.2 Registers

The PCA interrupt vector is located at address 0033H, the SPI interrupt vector is located at address 004BH and Keyboard interrupt vector is located at address 003BH. All other vectors addresses are the same as standard C52 devices.

IPH.x	IPL.x	Interrupt Level Priority
0	0 0 (Lowest)	
0	1	1
1	0	2
1	1	3 (Highest)

 Table 16-1.
 Priority Level Bit Values

A low-priority interrupt can be interrupted by a high priority interrupt, but not by another low-priority interrupt. A high-priority interrupt can't be interrupted by any other interrupt source.

If two interrupt requests of different priority levels are received simultaneously, the request of higher priority level is serviced. If interrupt requests of the same priority level are received simultaneously, an internal polling sequence determines which request is serviced. Thus within each priority level there is a second priority structure determined by the polling sequence.

#### Table 16-2.IEN0 Register

IEN0 - Interrupt Enable Register (A8h)

7	6	5	4	3	2	1	0
EA	EC	ET2	ES	ET1	EX1	ET0	EX0

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## 16.3 Interrupt Sources and Vector Addresses

Table 16-8.Vector Table

Number	Polling Priority	Interrupt Source	Interrupt Request	Vector Address
0	0	Reset		0000h
1	1	INT0	IE0	0003h
2	2	Timer 0	TF0	000Bh
3	3	INT1	IE1	0013h
4	4	Timer 1	IF1	001Bh
5	6	UART	RI+TI	0023h
6	7	Timer 2	TF2+EXF2	002Bh
7	5	PCA	CF + CCFn (n = 0-4)	0033h
8	8	Keyboard	KBDIT	003Bh
9	9	TWI	тพііт	0043h
10	10	SPI	SPIIT	004Bh
11	11			0053h
12	12			005Bh
13	13			0063h
14	14	USB	UEPINT + USBINT	006Bh
15	15			0073h





address and the data direction bit (SLA+R). The serial interrupt flag SI must then be cleared before the serial transfer can continue.

When the slave address and the direction bit have been transmitted and an acknowledgement bit has been received, the serial interrupt flag is set again and a number of status code in SSCS are possible. There are 40h, 48h or 38h for the master mode and also 68h, 78h or B0h if the slave mode was enabled (AA=logic 1). The appropriate action to be taken for each of these status code is detailed in Table . This scheme is repeated until a STOP condition is transmitted.

SSIE, CR2, CR1 and CR0 are not affected by the serial transfer and are referred to Table 7 to Table 11. After a repeated START condition (state 10h) the TWI module may switch to the master transmitter mode by loading SSDAT with SLA+W.

#### 20.1.3 Slave Receiver Mode

In the slave receiver mode, a number of data bytes are received from a master transmitter (Figure 20-6). To initiate the slave receiver mode, SSADR and SSCON must be loaded as follows:

Table 20-2.	SSADR: Slave Receiver Mode Initialization	

A6	A5	A4	A3	A2	A1	A0	GC	
	own slave address							

The upper 7 bits are the address to which the TWI module will respond when addressed by a master. If the LSB (GC) is set the TWI module will respond to the general call address (00h); otherwise it ignores the general call address.

 Table 20-3.
 SSCON: Slave Receiver Mode Initialization

CR2	SSIE	STA	STO	SI	AA	CR1	CR0
bit rate	1	0	0	0	1	bit rate	bit rate

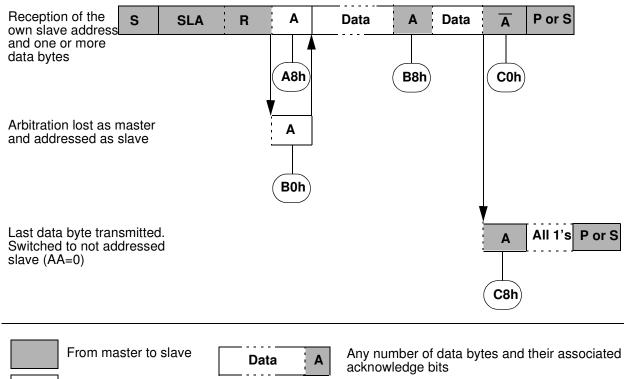
CR0, CR1 and CR2 have no effect in the slave mode. SSIE must be set to enable the TWI. The AA bit must be set to enable the own slave address or the general call address acknowledgement. STA, STO and SI must be cleared.

When SSADR and SSCON have been initialised, the TWI module waits until it is addressed by its own slave address followed by the data direction bit which must be at logic 0 (W) for the TWI to operate in the slave receiver mode. After its own slave address and the W bit have been received, the serial interrupt flag is set and a valid status code can be read from SSCS. This status code is used to vector to an interrupt service routine. The appropriate action to be taken for each of these status code is detailed in Table . The slave receiver mode may also be entered if arbitration is lost while TWI is in the master mode (states 68h and 78h).

If the AA bit is reset during a transfer, TWI module will return a not acknowledge (logic 1) to SDA after the next received data byte. While AA is reset, the TWI module does not respond to its own slave address. However, the 2-wire bus is still monitored and address recognition may be resume at any time by setting AA. This means that the AA bit may be used to temporarily isolate the module from the 2-wire bus.



#### Figure 20-7. Format and State in the Slave Transmitter Mode



n

This number (contained in SSCS) corresponds to a defined state of the 2-wire bus

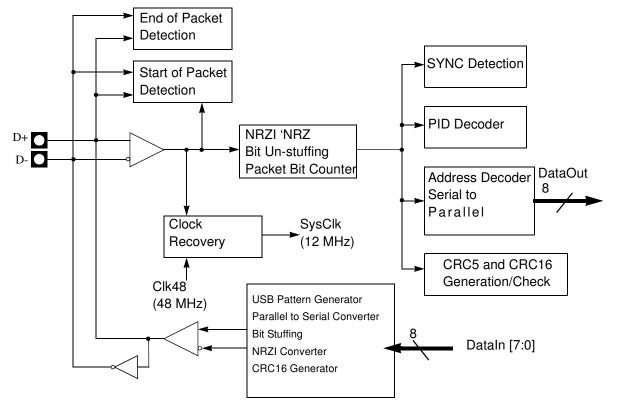
#### Table 20-8. Status in Slave Transmitter Mode

From slave to master

		Application Software Response					
Status		To/from SSDAT					
Code (SSCS)	Status of the 2-wire bus and 2-wire hardware				SI	АА	Next Action Taken By 2-wire Software
4.01	Own SLA+R has been	Load data byte or	х	0	0	0	Last data byte will be transmitted and NOT ACK will be received
A8h	received; ACK has been returned	Load data byte	х	0	0	1	Data byte will be transmitted and ACK will be received
B0h	Arbitration lost in SLA+R/W as master; own SLA+R has been	Load data byte or	х	0	0	0	Last data byte will be transmitted and NOT ACK will be received
DUI	received; ACK has been returned	Load data byte	х	0	0	1	Data byte will be transmitted and ACK will be received
B8h	Data byte in SSDAT has been	Load data byte or	х	0	0	0	Last data byte will be transmitted and NOT ACK will be received
DOII	transmitted; NOT ACK has been received	Load data byte	х	0	0	1	Data byte will be transmitted and ACK will be received

- Address checking.
- Clock generation (via DPLL).



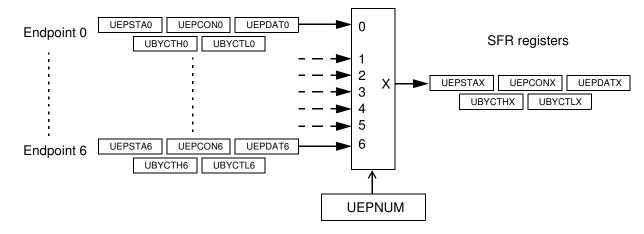


#### 21.1.2 Function Interface Unit (FIU)

The Function Interface Unit provides the interface between the AT89C5131 and the SIE. It manages transactions at the packet level with minimal intervention from the device firmware, which reads and writes the endpoint FIFOs.



#### Figure 21-6. Endpoint FIFO Configuration



#### 21.3.2 Read Data FIFO

The read access for each OUT endpoint is performed using the UEPDATX register.

After a new valid packet has been received on an Endpoint, the data are stored into the FIFO and the byte counter of the endpoint is updated (UBYCTLX and UBYCTHX registers). The firmware has to store the endpoint byte counter before any access to the endpoint FIFO. The byte counter is not updated when reading the FIFO.

To read data from an endpoint, select the correct endpoint number in UEPNUM and read the UEPDATX register. This action automatically decreases the corresponding address vector, and the next data is then available in the UEPDATX register.

#### 21.3.3 Write Data FIFO

The write access for each IN endpoint is performed using the UEPDATX register.

To write a byte into an IN endpoint FIFO, select the correct endpoint number in UEPNUM and write into the UEPDATX register. The corresponding address vector is automatically increased, and another write can be carried out.

Warning 1: The byte counter is not updated. Warning 2: Do not write more bytes than supported by the corresponding endpoint.

#### 21.4 Bulk/Interrupt Transactions

Bulk and Interrupt transactions are managed in the same way.



# Table 21-5.USBIEN Register<br/>USBIEN (S:BEh)<br/>USB Global Interrupt Enable Register

7	6	5	4	3	2	1	0			
-	-	EWUPCPU	EEORINT	ESOFINT	-	-	ESPINT			
Bit Number	Bit Mnemon	ic Descriptio	Description							
7-6	-	Reserved The value	Reserved The value read from these bits is always 0. Do not set these bits.							
5	EWUPCPL	Set this bit (S:BEh) U	Enable Wake Up CPU Interrupt Set this bit to enable Wake Up CPU Interrupt. (See "USBIEN Register USBIEN (S:BEh) USB Global Interrupt Enable Register" on page 141.) Clear this bit to disable Wake Up CPU Interrupt.							
4	EEORINT	Set this bit (S:BEh) U reset.	Enable End Of Reset Interrupt Set this bit to enable End Of Reset Interrupt. (See "USBIEN Register USBIEN (S:BEh) USB Global Interrupt Enable Register" on page 141.). This bit is set after reset. Clear this bit to disable End Of Reset Interrupt.							
3	ESOFINT	Set this bit Global Inte	Enable SOF Interrupt Set this bit to enable SOF Interrupt. (See "USBIEN Register USBIEN (S:BEh) USB Global Interrupt Enable Register" on page 141.). Clear this bit to disable SOF Interrupt.							
2	-	Reserved								
1	-	The value	The value read from these bits is always 0. Do not set these bits.							
0	ESPINT	Set this bit (S:BEh) U	Enable Suspend Interrupt Set this bit to enable Suspend Interrupts (see the "USBIEN Register USBIEN (S:BEh) USB Global Interrupt Enable Register" on page 141). Clear this bit to disable Suspend Interrupts.							

Reset Value = 10h





# Table 21-14.UEPINT RegisterUEPINT (S:F8h read-only)USB Endpoint Interrupt Register

7	6	5	4	3	2	1	0			
-	EP6INT	EP5INT	EP4INT	EP3INT	EP2INT	EP1INT	EP0INT			
Bit Number	Bit Mnemonic	Description	Description							
7	-	Reserved The value read	d from this bit is	s always 0. Do	not set this bit.					
6	EP6INT	This bit is set I endpoint 6. Th TXCMP, RXOI A USB interru	Endpoint 6 Interrupt This bit is set by hardware when an endpoint interrupt source has been detected on the endpoint 6. The endpoint interrupt sources are in the UEPSTAX register and can be: TXCMP, RXOUTB0, RXOUTB1, RXSETUP or STLCRC. A USB interrupt is triggered when the EP6IE bit in the UEPIEN register is set. This bit is cleared by hardware when all the endpoint interrupt sources are cleared							
5	EP5INT	This bit is set I endpoint 5. Th TXCMP, RXOI A USB interru	Endpoint 5 Interrupt This bit is set by hardware when an endpoint interrupt source has been detected on the endpoint 5. The endpoint interrupt sources are in the UEPSTAX register and can be: TXCMP, RXOUTB0, RXOUTB1, RXSETUP or STLCRC. A USB interrupt is triggered when the EP5IE bit in the UEPIEN register is set. This bit is cleared by hardware when all the endpoint interrupt sources are cleared							
4	EP4INT	Endpoint 4 Interrupt This bit is set by hardware when an endpoint interrupt source has been detected on the endpoint 4. The endpoint interrupt sources are in the UEPSTAX register and can be: TXCMP, RXOUTB0, RXOUTB1, RXSETUP or STLCRC. A USB interrupt is triggered when the EP4IE bit in the UEPIEN register is set. This bit is cleared by hardware when all the endpoint interrupt sources are cleared								
3	EP3INT	endpoint 3. Th TXCMP, RXO A USB interru	by hardware where where the standard standard standard standard standard standard standard standard standard st standard standard st standard standard st standard standard st standard standard st standard standard st standard standard st standard standard standard standard standard standard st standard standard standard standard standard standard st standard standard standard standard st standard standard st standard standard st standard standard st standard standard st standard st standard st standard st standard st st st st st st st st st st	hen an endpoin errupt sources a B1, RXSETUP vhen the EP3IE re when all the	re in the UEPS or STLCRC. bit in the UEP	TAX register a	nd can be: set.			
2	EP2INT	Endpoint 2 Interrupt This bit is set by hardware when an endpoint interrupt source has been detected on the endpoint 2. The endpoint interrupt sources are in the UEPSTAX register and can be: TXCMP, RXOUTB0, RXOUTB1, RXSETUP or STLCRC. A USB interrupt is triggered when the EP2IE bit in the UEPIEN register is set. This bit is cleared by hardware when all the endpoint interrupt sources are cleared								
1	EP1INT	Endpoint 1 Interrupt This bit is set by hardware when an endpoint interrupt source has been detected on the endpoint 1. The endpoint interrupt sources are in the UEPSTAX register and can be: TXCMP, RXOUTB0, RXOUTB1, RXSETUP or STLCRC. A USB interrupt is triggered when the EP1IE bit in the UEPIEN register is set. This bit is cleared by hardware when all the endpoint interrupt sources are cleared								
0	EPOINT	Endpoint 0 Interrupt This bit is set by hardware when an endpoint interrupt source has been detected on the endpoint 0. The endpoint interrupt sources are in the UEPSTAX register and can be: TXCMP, RXOUTB0, RXOUTB1, RXSETUP or STLCRC. A USB interrupt is triggered when the EP0IE bit in the UEPIEN register is set. This bit is cleared by hardware when all the endpoint interrupt sources are cleared								
Rosot Value	0.01									

Reset Value = 00h



# Table 21-16.UFNUMH RegisterUFNUMH (S:BBh, read-only)USB Frame Number High Register

7	6	5	4	3	2	1	0			
-	-	CRCOK	CRCERR	-	FNUM10	FNUM9	FNUM8			
Bit Number	Bit Mnemonic	Description	Description							
5	CRCOK	This bit is set I received witho This bit is upda	Frame Number CRC OK This bit is set by hardware when a new Frame Number in Start of Frame Packet is received without CRC error. This bit is updated after every Start of Frame packet receipt. Important note: the Start of Frame interrupt is generated just after the PID receipt.							
4	CRCERR	This bit is set I received. This bit is upda	<b>Frame Number CRC Error</b> This bit is set by hardware when a corrupted Frame Number in Start of Frame packet is received. This bit is updated after every Start of Frame packet receipt. Important note: the Start of Frame interrupt is generated just after the PID receipt.							
3	-	Reserved The value read	<b>Reserved</b> The value read from this bit is always 0. Do not set this bit.							
2-0	FNUM[10:8]	Frame Number FNUM[10:8] are the upper 3 bits of the 11-bit Frame Number (see the "UFNUML Register UFNUML (S:BAh, read-only) USB Frame Number Low Register" on page 150). It is provided in the last received SOF packet (see SOFINT in the "USBIEN Register USBIEN (S:BEh) USB Global Interrupt Enable Register" on page 141). FNUM is updated if a corrupted SOF is received.								

Reset Value = 00h

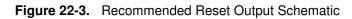
 Table 21-17.
 UFNUML Register

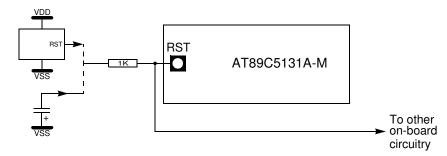
 UFNUML (S:BAh, read-only)
 USB Frame Number Low Register

7	6	5	4	3	2	1	0		
FNUM7	FNUM6	FNUM5	FNUM4	FNUM3	FNUM2	FNUM1	FNUM0		
Bit Number	Bit Mnemonic	Description							
7 - 0	FNUM[7:0]	Frame Number FNUM[7:0] are the lower 8 bits of the 11-bit Frame Number (See "UFNUMH Register UFNUMH (S:BBh, read-only) USB Frame Number High Register" on page 150.).							

Reset Value = 00h

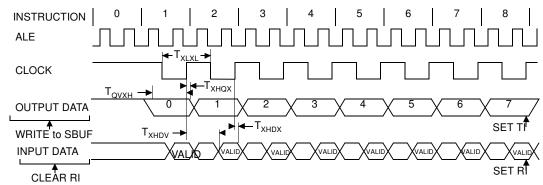








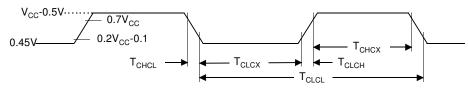
#### 27.4.8 Shift Register Timing Waveform



#### 27.4.9 External Clock Drive Characteristics (XTAL1) Table 27-11. AC Parameters

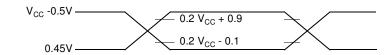
Symbol	Parameter	Min	Мах	Units
T <sub>CLCL</sub>	Oscillator Period	21		ns
T <sub>CHCX</sub>	High Time	5		ns
T <sub>CLCX</sub>	Low Time	5		ns
T <sub>CLCH</sub>	Rise Time		5	ns
T <sub>CHCL</sub>	Fall Time		5	ns
T <sub>CHCX</sub> /T <sub>CLCX</sub>	Cyclic ratio in X2 mode	40	60	%

#### 27.4.10 External Clock Drive Waveforms



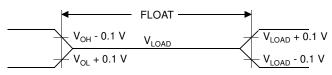
#### 27.4.11 AC Testing Input/Output Waveforms

INPUT/OUTPUT



AC inputs during testing are driven at V<sub>CC</sub> - 0.5 for a logic "1" and 0.45V for a logic "0". Timing measurement are made at V<sub>IH</sub> min for a logic "1" and V<sub>IL</sub> max for a logic "0".

#### 27.4.12 Float Waveforms



For timing purposes as port pin is no longer floating when a 100 mV change from load voltage occurs and begins to float when a 100 mV change from the loaded  $V_{OH}/V_{OL}$  level occurs.  $I_{OL}/I_{OH} \ge \pm 20$  mA.

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## $V_{DD}$ = 2.7 to 5.5 V, $T_A$ = -40 to +85°C

Symbol	Parameter	Min	Мах	Unit
	Slave Mode			
Т <sub>снсн</sub>	Clock Period	2		T <sub>PER</sub>
T <sub>CHCX</sub>	Clock High Time	0.8		T <sub>PER</sub>
T <sub>CLCX</sub>	Clock Low Time	0.8		T <sub>PER</sub>
T <sub>SLCH</sub> , T <sub>SLCL</sub>	SS Low to Clock edge	100		ns
T <sub>IVCL</sub> , T <sub>IVCH</sub>	Input Data Valid to Clock Edge	50		ns
T <sub>CLIX</sub> , T <sub>CHIX</sub>	Input Data Hold after Clock Edge	50		ns
T <sub>CLOV,</sub> T <sub>CHOV</sub>	Output Data Valid after Clock Edge		50	ns
T <sub>CLOX</sub> , T <sub>CHOX</sub>	Output Data Hold Time after Clock Edge	0		ns
T <sub>CLSH</sub> , T <sub>CHSH</sub>	SS High after Clock Edge	0		ns
T <sub>SLOV</sub>	SS Low to Output Data Valid		4T <sub>PER</sub> +20	ns
Т <sub>SHOX</sub>	Output Data Hold after SS High		2T <sub>PER</sub> +100	ns
T <sub>SHSL</sub>	$\overline{SS}$ High to $\overline{SS}$ Low	2T <sub>PER</sub> +120		
T <sub>ILIH</sub>	Input Rise Time		2	μs
T <sub>IHIL</sub>	Input Fall Time		2	μs
T <sub>OLOH</sub>	Output Rise time		100	ns
Т <sub>оног</sub>	Output Fall Time		100	ns
	Master Mode			
Т <sub>снсн</sub>	Clock Period	4		T <sub>PER</sub>
Т <sub>снсх</sub>	Clock High Time	2T <sub>PER</sub> -20		ns
T <sub>CLCX</sub>	Clock Low Time	2T <sub>PER</sub> -20		ns
T <sub>IVCL</sub> , T <sub>IVCH</sub>	Input Data Valid to Clock Edge	50		ns
T <sub>CLIX</sub> , T <sub>CHIX</sub>	Input Data Hold after Clock Edge	50		ns
T <sub>CLOV,</sub> T <sub>CHOV</sub>	Output Data Valid after Clock Edge		20	ns
T <sub>CLOX</sub> , T <sub>CHOX</sub>	Output Data Hold Time after Clock Edge	0		ns

Note: T<sub>PER</sub> is XTAL period when SPI interface operates in X2 mode or twice XTAL period when SPI interface operates in X1 mode.

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# 28. Ordering Information

Table 28-1. Possible Order Entries

Part Number	Memory Size (Kbytes)	Supply Voltage	Temperature Range	Package	Packing
AT89C5130A-RDTUM	16	2.7 to 5.5V	Industrial & Green	VQFP64	Tray & Dry Pack
AT89C5130A-PUTUM	16	2.7 to 5.5V	Industrial & Green	QFN32	Tray & Dry Pack
AT89C5130A-S3SUM	16	2.7 to 5.5V	Industrial & Green	PLCC52	Stick
AT89C5131A-RDTUM	32	2.7 to 5.5V	Industrial & Green	VQFP64	Tray & Dry Pack
AT89C5131A-PUTUM	32	2.7 to 5.5V	Industrial & Green	QFN32	Tray & Dry Pack
AT89C5131A-S3SUM	32	2.7 to 5.5V	Industrial & Green	PLCC52	Stick

Notes: 1. Optional Packing and Package options (please consult Atmel sales representative)

-Tape and Reel

-Die form

