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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	I ² C, SPI, UART/USART, USB
Peripherals	POR, PWM, WDT
Number of I/O	56
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.25V
Data Converters	A/D 48x14b; D/A 2x9b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-VFBGA
Supplier Device Package	100-VFBGA (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c24094-24bvxit



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5.4 Additional System Resources

System resources provide additional capability useful to complete systems. Additional resources include a multiplier, decimator, low-voltage detection, and power-on reset (POR). Brief statements describing the merits of each resource follow.

- Full speed USB (12 Mbps) with five configurable endpoints and 256 bytes of RAM. No external components required except for two series resistors. Wider than commercial temperature USB operation (–10 °C to +85 °C).
- Digital clock dividers provide three customizable clock frequencies for use in applications. The clocks can be routed to both the digital and analog systems. Additional clocks are generated using digital PSoC blocks as clock dividers.
- Two multiply accumulates (MACs) provide fast 8-bit multipliers with 32-bit accumulate, to assist in both general math and digital filters.

- Decimator provides a custom hardware filter for digital signal processing applications including creation of Delta Sigma ADCs.
- The I²C module provides 100- and 400-kHz communication over two wires. Slave, master, multi-master are supported.
- Low-voltage detection interrupts signal the application of falling voltage levels, while the advanced POR circuit eliminates the need for a system supervisor.
- An internal 1.3-V reference provides an absolute reference for the analog system, including ADCs and DACs.
- Versatile analog multiplexer system.

5.5 PSoC Device Characteristics

Depending on your PSoC device characteristics, the digital and analog systems can have 16, 8, or 4 digital blocks and 12, 6, or 4 analog blocks. The following table lists the resources available for specific PSoC device groups. The device covered by this datasheet is shown in the highlighted row of the table.

Table 1. PSoC Device Characteristics

PSoC Part Number	Digital I/O	Digital Rows	Digital Blocks	Analog Inputs	Analog Outputs	Analog Columns	Analog Blocks	SRAM Size	Flash Size
CY8C29x66	up to 64	4	16	up to 12	4	4	12	2 K	32 K
CY8C28xxx	up to 44	up to 3	up to 12	up to 44	up to 4	up to 6	up to 12 + 4 ^[1]	1 K	16 K
CY8C27x43	up to 44	2	8	up to 12	4	4	12	256	16 K
CY8C24x94	up to 56	1	4	up to 48	2	2	6	1 K	16 K
CY8C24x23A	up to 24	1	4	up to 12	2	2	6	256	4 K
CY8C23x33	up to 26	1	4	up to 12	2	2	4	256	8 K
CY8C22x45	up to 38	2	8	up to 38	0	4	6 ^[1]	1 K	16 K
CY8C21x45	up to 24	1	4	up to 24	0	4	6 ^[1]	512	8 K
CY8C21x34	up to 28	1	4	up to 28	0	2	4[1]	512	8 K
CY8C21x23	up to 16	1	4	up to 8	0	2	4[1]	256	4 K
CY8C20x34	up to 28	0	0	up to 28	0	0	3 ^[1,2]	512	8 K
CY8C20xx6	up to 36	0	0	up to 36	0	0	3 ^[1,2]	up to 2 K	up to 32 K

Notes

- 1. Limited analog functionality.
- 2. Two analog blocks and one CapSense[®].



read and write data memory, and read and write I/O registers. You can read and write CPU registers, set and clear breakpoints, and provide program run, halt, and step control. The debugger also allows you to create a trace buffer of registers and memory locations of interest.

7.1.4 Online Help System

The online help system displays online, context-sensitive help. Designed for procedural and quick reference, each functional subsystem has its own context-sensitive help. This system also provides tutorials and links to FAQs and an online support forum to aid the designer.

8. Designing with PSoC Designer

The development process for the PSoC® device differs from that of a traditional fixed function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and by lowering inventory costs. These configurable resources, called PSoC Blocks, have the ability to implement a wide variety of user-selectable functions. The PSoC development process is summarized in four steps:

- 1. Select User Modules
- 2. Configure User Modules
- 3. Organize and Connect
- 4. Generate, Verify, and Debug

8.1 Select User Modules

PSoC Designer provides a library of prebuilt, pretested hardware peripheral components called "user modules." User modules make selecting and implementing peripheral devices, both analog and digital, simple.

8.2 Configure User Modules

Each user module that you select establishes the basic register settings that implement the selected function. They also provide parameters and properties that allow you to tailor their precise configuration to your particular application. For example, a PWM User Module configures one or more digital PSoC blocks, one for each 8 bits of resolution. The user module parameters permit you to establish the pulse width and duty cycle. Configure the parameters and properties to correspond to your chosen application. Enter values directly or by selecting values from drop-down menus. All the user modules are documented in datasheets that may be viewed directly in PSoC Designer or on the Cypress website. These user module datasheets explain the internal operation of the user module and provide performance specifications. Each datasheet describes the use of each user module parameter, and other information you may need to successfully implement your design.

7.1.5 In-Circuit Emulator

A low-cost, high-functionality In-Circuit Emulator (ICE) is available for development support. This hardware can program single devices.

The emulator consists of a base unit that connects to the PC using a USB port. The base unit is universal and operates with all PSoC devices. Emulation pods for each device family are available separately. The emulation pod takes the place of the PSoC device in the target board and performs full speed (24-MHz) operation.

8.3 Organize and Connect

You build signal chains at the chip level by interconnecting user modules to each other and the I/O pins. You perform the selection, configuration, and routing so that you have complete control over all on-chip resources.

8.4 Generate, Verify, and Debug

When you are ready to test the hardware configuration or move on to developing code for the project, you perform the "Generate Configuration Files" step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the software for the system. The generated code provides application programming interfaces (APIs) with high-level functions to control and respond to hardware events at run time and interrupt service routines that you can adapt as needed.

A complete code development environment allows you to develop and customize your applications in either C, assembly language, or both.

The last step in the development process takes place inside PSoC Designer's debugger (access by clicking the Connect icon). PSoC Designer downloads the HEX image to the ICE where it runs at full speed. PSoC Designer debugging capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint, and watch-variable features, the debug interface provides a large trace buffer and allows you to define complex breakpoint events. These include monitoring address and data bus values, memory locations and external signals.

37

36 **=** 35 **=**

I2C SDA, M, P1[0] o M, P1[2] o EXTCLK, M, P1[4] o

P5[2], M

P5[0], M

P1[6], M



9.3 68-Pin Part Pinout

The following 68-pin QFN part table and drawing is for the CY8C24994 PSoC device.

Table 4 69 Din Bort Dinout (OENI91)

Pin	Ту	/pe	Name	Description
No.	Digital	Analog	Name	Description
1	I/O	М	P4[7]	
2	I/O	M	P4[5]	
3	I/O	M	P4[3]	
4	I/O	M	P4[1]	
5			NC	No connection. Pin must be left floating
6			NC	No connection. Pin must be left floating
7	Power		V_{SS}	Ground connection [10]
8	I/O	M	P3[7]	
9	I/O	М	P3[5]	
10	I/O	М	P3[3]	
11	I/O	M	P3[1]	
12	I/O	M	P5[7]	
13	I/O	М	P5[5]	
14	I/O	М	P5[3]	
15	I/O	М	P5[1]	
16	I/O	М	P1[7]	I ² C SCL
17	I/O	M	P1[5]	I ² C SDA
18	I/O	M	P1[3]	
19	I/O	М	P1[1]	I2C SCL ISSP SCLK ^[11]
20	Power		V_{SS}	Ground connection [10]
21	USB		D+	
22	USB		D-	
23	Power		V_{DD}	Supply voltage
24	I/O		P7[7]	
25	I/O		P7[6]	
26	I/O		P7[5]	
27	I/O		P7[4]	
28	I/O		P7[3]	
29	I/O		P7[2]	
30	I/O		P7[1]	
31	I/O		P7[0]	
32	I/O	М	P1[0]	I ² C SDA, ISSP SDATA ^[11]
22	1/0	N/I	D4IOI	

ਕ ਕ ਲੋਂ <u>ਤੋਂ</u> ਕ $\Sigma \Sigma \Sigma \Sigma \Sigma \Sigma \Sigma$ P2[1], P2[3], P2[3], P2[3], P2[3], P2[7], I P2[7], I P2[7], I P2[7], P0[3], P0[5], P0[5], P0[6], P0[6], P0[6], P0[6], P2[6], P2[P2[0], M, AI 51 **-**M, P4[5] **=** P4[6]. M M, P4[3] P4[4]. M 49 M, P4[1] = NC = NC = 48 = 47 = 46 = 45 = 43 = 43 P4[2], M P4[0], M XRES Vss = NC M, P3[7] **=** M, P3[5] **=** NC QFN P3[6], M M, P3[3] = M, P3[1] = M, P5[7] = (Top View) 42 P3[4], M 10 P3[2], M 41 40 39 12 M, P5[5] = P5[6], M 13 M, P5[3] ≡
M, P5[1] ≡
I2C SCL, M, P1[7] ≡ 14 38 P5[4], M

 $^{12}\% \ ^{\circ} \ ^{\circ}$ ______

P7[7] P7[6] P7[5] P7[4] P7[2] P7[1]

Vss D+ D-Vdd

Figure 6. CY8C24994 68-Pin PSoC Device

Pin Type Description Name Digital Analog No 50 P4[6] I/O М 51 I/O I, M P2[0] Direct switched capacitor block input 33 I/O P1[2] 52 I/O I M P2[2] Direct switched capacitor block input 34 I/O P2[4] External AGND input М P1[4] Optional EXTCLK I/O 53 М 35 I/O P1[6] 54 I/O М P2[6] External VREF input М 36 I/O P5[0] 55 I/O I, M P0[0] Analog column mux input 37 I/O М P5[2] 56 I/O I, M P0[2] Analog column mux input and column output I/O P5[4] I/O P0[4] 38 М 57 I. M Analog column mux input and column output P5[6] P0[6] Analog column mux input 39 I/O 58 I/O I. M М 40 I/O М P3[0] 59 Power Supply voltage V_{DD} 41 I/O P3[2] 60 Power Ground connection [10] V_{SS} I/O P3[4] 42 I/O М 61 I. M P0[7] Analog column mux input, integration input #1 43 I/O P0[5] I/O P3[6] 62 I/O. M Analog column mux input and column output, integration input #2 No connection. Pin must be left floating. 44 NC 63 I/O I/O. M P0[3] Analog column mux input and column output 45 No connection. Pin must be left floating. 64 I/O Analog column mux input I, M P0[1] 46 **XRES** Active high pin reset with internal 65 I/O P2[7] Input pull-down. I/O М P2[5] 47 1/0 М P4[0] 66 48 I/O М P4[2] I/O I, M P2[3] Direct switched capacitor block input I/O М P4[4] 68 I/O I, M P2[1] Direct switched capacitor block input 49

15

16

Ξ Š 12C SCL

I2C SDA, M, P1[5]

LEGEND A = Analog, I = Input, O = Output, NC = No connection. Pin must be left floating, M = Analog Mux Input.

Notes

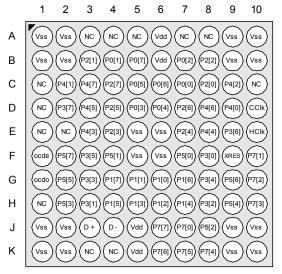
The center pad on the QFN package should be connected to ground (VSS) for best mechanical, thermal, and electrical performance. If not connected to ground, it should be electrically floated and not connected to any other signal.

^{10.} All V_{SS} pins should be brought out to one common GND plane.

^{11.} These are the ISSP pins, which are not High Z at POR. See the PSoC Technical Reference Manual for details.



Figure 9. CY8C24094 OCD (Not for Production)



BGA (Top View)



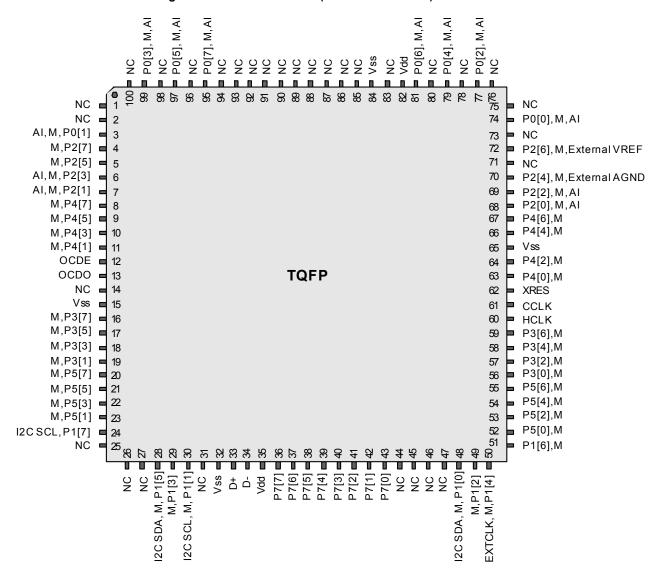


Figure 10. CY8C24094 OCD (Not for Production)



10. Register Reference

This section lists the registers of the CY8C24x94 PSoC device family. For detailed register information, see the *PSoC Technical Reference Manual*.

10.1 Register Conventions

The register conventions specific to this section are listed in the following table.

Convention	Description
R	Read register or bit(s)
W	Write register or bit(s)
L	Logical register or bit(s)
С	Clearable register or bit(s)
#	Access is bit specific

10.2 Register Mapping Tables

The PSoC device has a total register address space of 512 bytes. The register space is referred to as I/O space and is divided into two banks, Bank 0 and Bank 1. The XOI bit in the Flag register (CPU_F) determines which bank the user is currently in. When the XOI bit is set to 1, the user is in Bank 1.

Note In the following register mapping tables, blank fields are Reserved and should not be accessed.



11.3.2 DC GPIO Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and $-40~^\circ\text{C} \le T_A \le 85~^\circ\text{C}$, or 3.0 V to 3.6 V and $-40~^\circ\text{C} \le T_A \le 85~^\circ\text{C}$, respectively. Typical parameters are measured at 5 V and 3.3 V at 25 $^\circ\text{C}$ and are for design guidance only.

Table 12. DC GPIO Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
R _{PU}	Pull-up resistor	4	5.6	8	kΩ	
R _{PD}	Pull-down resistor	4	5.6	8	kΩ	
V _{OH}	High output level	V _{DD} – 1.0	_	1	V	$\begin{split} &I_{OH} = 10 \text{ mA}, V_{DD} = 4.75 \text{ V to } 5.25 \text{ V and} \\ &-40 \text{ °C} \leq T_A \leq 85 \text{ °C}, \text{ or} \\ &V_{DD} = 3.0 \text{ V to } 3.6 \text{ V and} \\ &-40 \text{ °C} \leq T_A \leq 85 \text{ °C} \\ &(8 \text{ total loads, } 4 \text{ on even port pins (for example, P0[2], P1[4]), } 4 \text{ on odd port pins (for example, P0[3], P1[5])). } 80 \text{ mA} \\ &\text{maximum combined } I_{OH} \text{ budget.} \end{split}$
V _{OL}	Low output level	_	_	0.75	V	$\begin{split} &I_{OL} = 25 \text{ mA}, \text{ V}_{DD} = 4.75 \text{ V to } 5.25 \text{ V} \\ &\text{and } -40 \text{ °C} \leq T_{A} \leq 85 \text{ °C}, \text{ or} \\ &V_{DD} = 3.0 \text{ V to } 3.6 \text{ V and} \\ &-40 \text{ °C} \leq T_{A} \leq 85 \text{ °C} \\ &(8 \text{ total loads, } 4 \text{ on even port pins (for example, P0[2], P1[4]), } 4 \text{ on odd port pins (for example, P0[3], P1[5])). } 200 \text{ mA} \\ &\text{maximum combined } I_{OL} \text{ budget.} \end{split}$
Гон	High level source current	10	_	-	mA	$V_{OH} = V_{DD} - 1.0 \text{ V}$, see the limitations of the total current in the note for V_{OH}
I _{OL}	Low level sink current	25	_	-	mA	V_{OL} = 0.75 V, see the limitations of the total current in the note for V_{OL}
V _{IL}	Input low level	-	_	0.8	V	V _{DD} = 3.0 to 5.25.
V _{IH}	Input high level	2.1	_		V	V _{DD} = 3.0 to 5.25.
V_{H}	Input hysterisis	_	60	-	mV	
I _{IL}	Input leakage (absolute value)	-	1	-	nA	Gross tested to 1 μA.
C _{IN}	Capacitive load on pins as input	-	3.5	10	pF	Package and pin dependent. Temp = 25 °C.
C _{OUT}	Capacitive load on pins as output	_	3.5	10	pF	Package and pin dependent. Temp = 25 °C.



11.3.7 DC Analog Reference Specifications

The following tables list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and $-40 \text{ °C} \le T_A \le 85 \text{ °C}$, or 3.0 V to 3.6 V and $-40 \text{ °C} \le T_A \le 85 \text{ °C}$, respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

The guaranteed specifications for RefHI and RefLo are measured through the Analog Continuous Time PSoC blocks. The power levels for RefHi and RefLo refer to the Analog Reference Control register. AGND is measured at P2[4] in AGND bypass mode. Each Analog Continuous Time PSoC block adds a maximum of 10mV additional offset error to guaranteed AGND specifications from the local AGND buffer. Reference control power can be set to medium or high unless otherwise noted.

Note Avoid using P2[4] for digital signaling when using an analog resource that depends on the Analog Reference. Some coupling of the digital signal may appear on the AGND.

Table 19. 5-V DC Analog Reference Specifications

Reference ence ARF_CR [5:3]	Reference Power Settings	Symbol	Reference	Description	Min	Тур	Max	Unit s
0b000	RefPower = high Opamp bias = high	V _{REFHI}	Ref High	V _{DD} /2 + Bandgap	V _{DD} /2 + 1.229	V _{DD} /2 + 1.290	V _{DD} /2 + 1.346	V
		V_{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.038	V _{DD} /2	V _{DD} /2 + 0.040	V
		V _{REFLO}	Ref Low	V _{DD} /2 – Bandgap	V _{DD} /2 – 1.356	V _{DD} /2 – 1.295	V _{DD} /2 – 1.218	V
	RefPower = high Opamp bias = low	V _{REFHI}	Ref High	V _{DD} /2 + Bandgap	V _{DD} /2 + 1.220	V _{DD} /2 + 1.292	V _{DD} /2 + 1.348	V
		V_{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.036	V _{DD} /2	V _{DD} /2 + 0.036	V
		V _{REFLO}	Ref Low	V _{DD} /2 – Bandgap	V _{DD} /2 – 1.357	V _{DD} /2 – 1.297	V _{DD} /2 – 1.225	V
	RefPower = medium	V _{REFHI}	Ref High	V _{DD} /2 + Bandgap	V _{DD} /2 + 1.221	V _{DD} /2 + 1.293	V _{DD} /2 + 1.351	V
	Opamp bias = high	V _{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.036	V _{DD} /2	V _{DD} /2 + 0.036	V
		V _{REFLO}	Ref Low	V _{DD} /2 – Bandgap	V _{DD} /2 – 1.357	V _{DD} /2 – 1.298	V _{DD} /2 – 1.228	V
med	RefPower = medium	V _{REFHI}	Ref High	V _{DD} /2 + Bandgap	V _{DD} /2 + 1.219	V _{DD} /2 + 1.293	V _{DD} /2 + 1.353	V
	Opamp bias = low	V _{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.037	V _{DD} /2 – 0.001	V _{DD} /2 + 0.036	V
		V _{REFLO}	Ref Low	V _{DD} /2 – Bandgap	V _{DD} /2 – 1.359	V _{DD} /2 – 1.299	V _{DD} /2 – 1.229	V



Table 19. 5-V DC Analog Reference Specifications (continued)

Refer- ence ARF_CR [5:3]	Reference Power Settings	Symbol	Reference	Description	Min	Тур	Max	Unit s
0b001	RefPower = high Opamp bias = high	V _{REFHI}	Ref High	P2[4]+P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.092	P2[4] + P2[6] - 0.011	P2[4] + P2[6] + 0.064	V
		V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		V _{REFLO}	Ref Low	P2[4]–P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.031	P2[4] – P2[6] + 0.007	P2[4] – P2[6] + 0.056	V
	RefPower = high Opamp bias = low	V _{REFHI}	Ref High	P2[4]+P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.078	P2[4] + P2[6] - 0.008	P2[4] + P2[6] + 0.063	V
		V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		V _{REFLO}	Ref Low	P2[4]–P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.031	P2[4] – P2[6] + 0.004	P2[4] – P2[6] + 0.043	V
	RefPower = medium	V _{REFHI}	Ref High	P2[4]+P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.073	P2[4] + P2[6] - 0.006	P2[4] + P2[6] + 0.062	V
	Opamp bias = high	V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		V _{REFLO}	Ref Low	P2[4]–P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.032	P2[4] – P2[6] + 0.003	P2[4] – P2[6] + 0.038	V
	RefPower = medium	V_{REFHI}	Ref High	P2[4]+P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.073	P2[4] + P2[6] - 0.006	P2[4] + P2[6] + 0.062	V
	Opamp bias = low	V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		V_{REFLO}	Ref Low	P2[4]–P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.034	P2[4] – P2[6] + 0.002	P2[4] – P2[6] + 0.037	V
0b010	RefPower = high	V_{REFHI}	Ref High	V_{DD}	V _{DD} – 0.037	V _{DD} – 0.007	V_{DD}	V
	Opamp bias = high	V_{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.036	V _{DD} /2 – 0.001	V _{DD} /2 + 0.036	V
		V_{REFLO}	Ref Low	V_{SS}	V_{SS}	$V_{SS} + 0.005$	$V_{SS} + 0.029$	V
	RefPower = high	V_{REFHI}	Ref High	V_{DD}	$V_{DD} - 0.034$	$V_{DD} - 0.006$	V_{DD}	V
	Opamp bias = low	V_{AGND}	AGND	V _{DD} /2	$V_{DD}/2 - 0.036$	V _{DD} /2 – 0.001	V _{DD} /2 + 0.035	V
		V_{REFLO}	Ref Low	V_{SS}	V_{SS}	$V_{SS} + 0.004$	V _{SS} + 0.024	V
	RefPower =	V_{REFHI}	Ref High	V_{DD}	V _{DD} – 0.032	V _{DD} – 0.005	V_{DD}	V
	medium Opamp bias = high	V_{AGND}	AGND	V _{DD} /2	$V_{DD}/2 - 0.036$	V _{DD} /2 – 0.001	V _{DD} /2 + 0.035	V
		V_{REFLO}	Ref Low	V_{SS}	V _{SS}	$V_{SS} + 0.003$	V _{SS} + 0.022	V
	RefPower =	V_{REFHI}	Ref High	V_{DD}	V _{DD} – 0.031	V _{DD} – 0.005	V_{DD}	V
	medium Opamp bias = low	V_{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.037	V _{DD} /2 – 0.001	V _{DD} /2 + 0.035	V
		V_{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.003	V _{SS} + 0.020	V



Table 19. 5-V DC Analog Reference Specifications (continued)

Refer- ence ARF_CR [5:3]	Reference Power Settings	Symbol	Reference	Description	Min	Тур	Max	Unit s
0b101	RefPower = high Opamp bias = high	V _{REFHI}	Ref High	P2[4] + Bandgap (P2[4] = V _{DD} /2)	P2[4] + 1.218	P2[4] + 1.291	P2[4] + 1.354	V
		V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		V _{REFLO}	Ref Low	P2[4] – Bandgap (P2[4] = V _{DD} /2)	P2[4] - 1.335	P2[4] - 1.294	P2[4] - 1.237	V
	RefPower = high Opamp bias = low	V_{REFHI}	Ref High	P2[4] + Bandgap (P2[4] = V _{DD} /2)	P2[4] + 1.221	P2[4] + 1.293	P2[4] + 1.358	V
		V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		V _{REFLO}	Ref Low	P2[4] – Bandgap (P2[4] = V _{DD} /2)	P2[4] – 1.337	P2[4] - 1.297	P2[4] - 1.243	V
	RefPower = medium	V_{REFHI}	Ref High	P2[4] + Bandgap (P2[4] = V _{DD} /2)	P2[4] + 1.222	P2[4] + 1.294	P2[4] + 1.360	V
	Opamp bias = high	V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		V _{REFLO}	Ref Low	P2[4] – Bandgap (P2[4] = V _{DD} /2)	P2[4] - 1.338	P2[4] - 1.298	P2[4] – 1.245	V
	RefPower = medium	V_{REFHI}	Ref High	P2[4] + Bandgap (P2[4] = V _{DD} /2)	P2[4] + 1.221	P2[4] + 1.294	P2[4] + 1.362	V
	Opamp bias = low	V_{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		V _{REFLO}	Ref Low	P2[4] – Bandgap (P2[4] = V _{DD} /2)	P2[4] - 1.340	P2[4] - 1.298	P2[4] - 1.245	V
0b110	RefPower = high	V_{REFHI}	Ref High	2 × Bandgap	2.513	2.593	2.672	V
	Opamp bias = high	V_{AGND}	AGND	Bandgap	1.264	1.302	1.340	V
		V_{REFLO}	Ref Low	V_{SS}	V _{SS}	$V_{SS} + 0.008$	$V_{SS} + 0.038$	V
	RefPower = high	V_{REFHI}	Ref High	2 × Bandgap	2.514	2.593	2.674	V
	Opamp bias = low	V_{AGND}	AGND	Bandgap	1.264	1.301	1.340	V
		V_{REFLO}	Ref Low	V_{SS}	V _{SS}	$V_{SS} + 0.005$	$V_{SS} + 0.028$	V
	RefPower =	V_{REFHI}	Ref High	2 × Bandgap	2.514	2.593	2.676	V
	medium Opamp bias = high	V_{AGND}	AGND	Bandgap	1.264	1.301	1.340	V
		V_{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.004	V _{SS} + 0.024	V
	RefPower =	V_{REFHI}	Ref High	2 × Bandgap	2.514	2.593	2.677	V
	medium Opamp bias = low	V_{AGND}	AGND	Bandgap	1.264	1.300	1.340	V
	. ,	V_{REFLO}	Ref Low	V _{SS}	V _{SS}	$V_{SS} + 0.003$	V _{SS} + 0.021	V

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Table 19. 5-V DC Analog Reference Specifications (continued)

Refer- ence ARF_CR [5:3]	Reference Power Settings	Symbol	Reference	Description	Min	Тур	Max	Unit s
0b111	RefPower = high	V_{REFHI}	Ref High	3.2 × Bandgap	4.028	4.144	4.242	V
	Opamp bias = high	V_{AGND}	AGND	1.6 × Bandgap	2.028	2.076	2.125	V
		V_{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.008	V _{SS} + 0.034	V
	RefPower = high	V_{REFHI}	Ref High	3.2 × Bandgap	4.032	4.142	4.245	V
	Opamp bias = low	V_{AGND}	AGND	1.6 × Bandgap	2.029	2.076	2.126	V
		V_{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.005	V _{SS} + 0.025	V
	RefPower =	V_{REFHI}	Ref High	3.2 × Bandgap	4.034	4.143	4.247	V
	medium Opamp bias = high	V_{AGND}	AGND	1.6 × Bandgap	2.029	2.076	2.126	V
	opamp blace mgm	V_{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.004	V _{SS} + 0.021	V
	RefPower = medium Opamp bias = low	V_{REFHI}	Ref High	3.2 × Bandgap	4.036	4.144	4.249	V
		V _{AGND}	AGND	1.6 × Bandgap	2.029	2.076	2.126	V
	Opamp blas – low	V_{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.003	V _{SS} + 0.019	V

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Note The bits PORLEV and VM in the following table refer to bits in the VLT_CR register. See the PSoC Technical Reference Manual for more information on the VLT_CR register.

Table 22. DC POR and LVD Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
V _{PPOR0R} V _{PPOR1R} V _{PPOR2R}	V _{DD} value for PPOR trip (positive ramp) PORLEV[1:0] = 00b PORLEV[1:0] = 01b PORLEV[1:0] = 10b	_	2.91 4.39 4.55	-	V V V	
V _{PPOR0} [23] V _{PPOR1} [23] V _{PPOR2} [23]	V _{DD} value for PPOR trip (negative ramp) PORLEV[1:0] = 00b PORLEV[1:0] = 01b PORLEV[1:0] = 10b	_	2.82 4.39 4.55	-	V V V	
V _{PH0} V _{PH1} V _{PH2}	PPOR hysteresis PORLEV[1:0] = 00b PORLEV[1:0] = 01b PORLEV[1:0] = 10b	_ _ _	92 0 0	- - -	mV mV mV	
VLVD0 VLVD1 VLVD2 VLVD3 VLVD4 VLVD5 VLVD6 VLVD7	V _{DD} value for LVD trip VM[2:0] = 000b VM[2:0] = 001b VM[2:0] = 010b VM[2:0] = 011b VM[2:0] = 100b VM[2:0] = 101b VM[2:0] = 110b VM[2:0] = 111b	2.86 2.96 3.07 3.92 4.39 4.55 4.63 4.72	2.92 3.02 3.13 4.00 4.48 4.64 4.73 4.81	2.98 ^[24] 3.08 3.20 4.08 4.57 4.74 ^[25] 4.82 4.91	V V V V V	

^{23.} Errata: When V_{DD} of the device is pulled below ground just before power on, the first read from each 8K Flash page may be corrupted. This issue does not affect Flash page 0 because it is the selected page upon reset. More details in "Errata" on page 66.

24. Always greater than 50 mV above PPOR (PORLEV = 00) for falling supply.

25. Always greater than 50 mV above PPOR (PORLEV = 10) for falling supply.



When bypassed by a capacitor on P2[4], the noise of the analog ground signal distributed to each block is reduced by a factor of up to 5 (14 dB). This is at frequencies above the corner frequency defined by the on-chip 8.1 K resistance and the external capacitor.

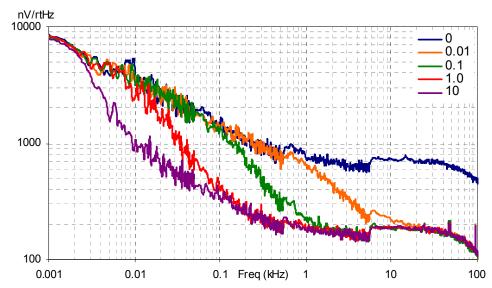


Figure 13. Typical AGND Noise with P2[4] Bypass

At low frequencies, the opamp noise is proportional to 1/f, power independent, and determined by device geometry. At high frequencies, increased power level reduces the noise spectrum level.

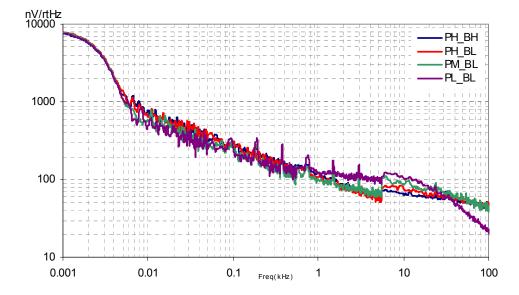


Figure 14. Typical Opamp Noise



11.5 Thermal Impedance

Table 37. Thermal Impedances per Package

Package	Typical θ _{JA} ^[36]
56-Pin QFN ^[37]	12.93 °C/W
68-Pin QFN ^[37]	13.05 °C/W
100-Ball VFBGA	65 °C/W
100-Pin TQFP	51 °C/W

11.6 Solder Reflow Peak Specifications

Table 38 shows the solder reflow temperature limits that must not be exceeded.

Table 38. Solder Reflow Specifications

Package	Maximum Peak Temperature (T _C)	Maximum Time above T _C – 5 °C	
56-Pin QFN	260 °C	30 seconds	
68-Pin QFN	260 °C	30 seconds	
100-Ball VFBGA	260 °C	30 seconds	
100-Pin TQFP	260 °C	30 seconds	

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 ^{36.} T_J = T_A + POWER × θ_{JA}.
 37. To achieve the thermal impedance specified for the QFN package, see the Application Notes for Surface Mount Assembly of Amkor's MicroLeadFrame (MLF) Packages available at http://www.amkor.com.



15. Acronyms

15.1 Acronyms Used

The following table lists the acronyms that are used in this document.

Acronym	Description	Acronym	Description	
AC	alternating current	MIPS	million instructions per second	
ADC	analog-to-digital converter	OCD	on-chip debug	
API	application programming interface	PCB	printed circuit board	
CMOS	complementary metal oxide semiconductor	PDIP	plastic dual-in-line package	
CPU	central processing unit	PGA	programmable gain amplifier	
CRC	cyclic redundancy check	POR	power-on reset	
CT	continuous time	PPOR	precision power-on reset	
DAC	digital-to-analog converter	PRS	pseudo-random sequence	
DC	direct current	PSoC [®]	Programmable System-on-Chip™	
DTMF	dual-tone multi-frequency	PWM	pulse-width modulator	
EEPROM	electrically erasable programmable read-only memory	QFN	quad flat no leads	
GPIO	general purpose I/O	SAR	successive approximation register	
ICE	in-circuit emulator	SC	switched capacitor	
IDE	integrated development environment	SLIMO	slow IMO	
ILO	internal low-speed oscillator	SOIC	small-outline integrated circuit	
IMO	internal main oscillator	SPI™	serial peripheral interface	
I/O	input/output	SRAM	static random-access memory	
IrDA	infrared data association	SROM	supervisory read-only memory	
ISSP	In-System Serial Programming	TQFP	thin quad flat pack	
LCD	liquid crystal display	UART	universal asynchronous receiver / transmitter	
LED	light-emitting diode	USB	universal serial bus	
LPC	low power comparator	VFBGA	very fine-pitch ball grid array	
LVD	low-voltage detect WDT		watchdog timer	
MAC	multiply-accumulate		external reset	
MCU	microcontroller unit		,	
		_		

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17. Glossary (continued)

external reset (XRES)

An active high signal that is driven into the PSoC device. It causes all operation of the CPU and blocks to stop and return to a pre-defined state.

flash

An electrically programmable and erasable, non-volatile technology that provides users with the programmability and data storage of EPROMs, plus in-system erasability. Non-volatile means that the data is retained when power

Flash block

The smallest amount of Flash ROM space that may be programmed at one time and the smallest amount of Flash space that may be protected. A Flash block holds 64 bytes.

frequency

The number of cycles or events per unit of time, for a periodic function.

gain

The ratio of output current, voltage, or power to input current, voltage, or power, respectively. Gain is usually expressed in dB.

I²C

A two-wire serial computer bus by Philips Semiconductors (now NXP Semiconductors). I2C is an Inter-Integrated Circuit. It is used to connect low-speed peripherals in an embedded system. The original system was created in the early 1980s as a battery control interface, but it was later used as a simple internal bus system for building control electronics. I2C uses only two bi-directional pins, clock and data, both running at +5V and pulled high with resistors. The bus operates at 100 kbits/second in standard mode and 400 kbits/second in fast mode.

ICE

The in-circuit emulator that allows users to test the project in a hardware environment, while viewing the debugging device activity in a software environment (PSoC Designer).

input/output (I/O) A device that introduces data into or extracts data from a system.

interrupt

A suspension of a process, such as the execution of a computer program, caused by an event external to that process, and performed in such a way that the process can be resumed.

interrupt service routine (ISR)

A block of code that normal code execution is diverted to when the M8C receives a hardware interrupt. Many interrupt sources may each exist with its own priority and individual ISR code block. Each ISR code block ends with the RETI instruction, returning the device to the point in the program where it left normal program execution.

jitter

- 1. A misplacement of the timing of a transition from its ideal position. A typical form of corruption that occurs on serial data streams.
- The abrupt and unwanted variations of one or more signal characteristics, such as the interval between successive pulses, the amplitude of successive cycles, or the frequency or phase of successive cycles.

low-voltage detect. A circuit that senses V_{DD} and provides an interrupt to the system when V_{DD} falls lower than a selected threshold. (LVD)

M8C

An 8-bit Harvard-architecture microprocessor. The microprocessor coordinates all activity inside a PSoC by interfacing to the Flash, SRAM, and register space.

master device

A device that controls the timing for data exchanges between two devices. Or when devices are cascaded in width, the master device is the one that controls the timing for data exchanges between the cascaded devices and an external interface. The controlled device is called the slave device.

microcontroller

An integrated circuit chip that is designed primarily for control systems and products. In addition to a CPU, a microcontroller typically includes memory, timing circuits, and IO circuitry. The reason for this is to permit the realization of a controller with a minimal quantity of chips, thus achieving maximal possible miniaturization. This in turn, reduces the volume and the cost of the controller. The microcontroller is normally not used for general-purpose computation as is a microprocessor.

mixed-signal

The reference to a circuit containing both analog and digital techniques and components.



17. Glossary (continued)

SRAM An acronym for static random access memory. A memory device allowing users to store and retrieve data at a

high rate of speed. The term static is used because, after a value has been loaded into an SRAM cell, it remains

unchanged until it is explicitly altered or until power is removed from the device.

SROM An acronym for supervisory read only memory. The SROM holds code that is used to boot the device, calibrate

circuitry, and perform Flash operations. The functions of the SROM may be accessed in normal user code,

operating from Flash.

stop bit A signal following a character or block that prepares the receiving device to receive the next character or block.

synchronous 1. A signal whose data is not acknowledged or acted upon until the next active edge of a clock signal.

2. A system whose operation is synchronized by a clock signal.

tristate A function whose output can adopt three states: 0, 1, and Z (high-impedance). The function does not drive any

value in the Z state and, in many respects, may be considered to be disconnected from the rest of the circuit,

allowing another output to drive the same net.

UART A UART or universal asynchronous receiver-transmitter translates between parallel bits of data and serial bits.

user modules Pre-build, pre-tested hardware/firmware peripheral functions that take care of managing and configuring the lower

level Analog and Digital PSoC Blocks. User Modules also provide high level API (Application Programming

Interface) for the peripheral function.

user space The bank 0 space of the register map. The registers in this bank are more likely to be modified during normal

program execution and not just during initialization. Registers in bank 1 are most likely to be modified only during

the initialization phase of the program.

 V_{DD} A name for a power net meaning "voltage drain." The most positive power supply signal. Usually 5 V or 3.3 V.

V_{SS} A name for a power net meaning "voltage source." The most negative power supply signal.

watchdog timer A timer that must be serviced periodically. If it is not serviced, the CPU resets after a specified period of time.



4. The Internal Main Oscillator (IMO) frequency parameter (FIMO245V) may increase over a period of time during usage in the field and exceed the maximum spec limit of 24.96 MHz.

■ PROBLEM DEFINITION

When the device has been operating at 4.75 V to 5.25 V for a cumulatively long duration in the field, the IMO Frequency may slowly increase over the duration of usage in the field and eventually exceed the maximum spec limit of 24.96 MHz. This may affect applications that are sensitive to the max value of IMO frequency, such as those using UART communication and result in a functional failure.

■ TRIGGER CONDITION(S)

Very long (cumulative) usage of the device in the operating voltage range of 4.75V to 5.25V, with the IMO clock running continuously, could lead to the degradation. Higher power supply voltage and lower ambient temperature are worst-case conditions for the degradation.

■ WORKAROUND

Operating the device with the power supply voltage range of 3.0 V to 3.6 V, would avoid the degradation of IMO Frequency beyond the max spec limit of 24.96 MHz.

■ FIX STATUS

A new revision of the silicon, with a fix for this issue, is expected to be available from August 1st 2015.

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19. Document History Page (continued)

Document Title: CY8C24094/CY8C24794/CY8C24894/CY8C24994, PSoC [®] Programmable System-on-Chip™ Document Number: 38-12018						
*N	2708135	BRW	05/18/2009	Added Note in the Pin Information section on page 8. Removed reference to Hi-Tech Lite Compiler in the section Development Tools Selection on page 42.		
*O	2718162	DPT	06/11/2009	Added 56-Pin QFN (Sawn) package diagram and updated ordering information		
*P	2762161	RLRM	09/10/2009	Updated the following parameters: DC _{ILO,} F32K_U, F _{IMO6} , T _{POWERUP} , T _{ERASE_ALL} , T _{PROGRAM_HOT} , and T _{PROGRAM_COLD.} Added SR _{POWER_UP} parameter in AC specs table		
*Q	2768530	RLRM	09/24/09	Ordering Information table: Changed XRES Pin value for CY8C24894-24LTXI and CY8C24894-24LTXIT to 'Yes'.		
*R	2817938	KRIS	11/30/09	Ordering Information: Updated CY8C24894-24LTXI and CY8C24894-24LTXIT parts as Sawn and updated the Digital I/O and Analog Pin values Added Contents page. Updated 68 QFN package diagram (51-85124)		
*S	2846641	RLRM	1/12/10	Added package diagram 001-58740 and updated Development Tools section.		
*T	2867363	ANUP	01/27/10	Modified Note 9 to remove voltage range 2.4 V to 3.0 V		
*U	2901653	NJF	03/30/2010	Updated Cypress website links Added T _{XRST} , DC24M, T _{BAKETEMP} and T _{BAKETIME} parameters Removed reference to 2.4 V Removed sections 'Third Party Tools' 'Build a PSoC Emulator into your Board' Updated package diagrams Removed inactive parts from ordering information table.		
*V	2938528	VMAD	05/28/2010	Updated content to match current style guide and datasheet template. No technical updates		
*W	3028596	NJF	09/20/10	Added PSoC Device Characteristics table. Added DC I ² C Specifications table. Added F _{32K U} max limit. Added Tjit IMO specification, removed existing jitter specifications. Updated Analog reference tables. Updated Units of Measure, Acronyms, Glossary, and References sections. Updated solder reflow specifications. No specific changes were made to AC Digital Block Specifications table and I ² C Timing Diagram. They were updated for clearer understanding. Updated Figure 12 since the labelling for y-axis was incorrect. Template and styles update.		
*X	3082244	NXZ	11/09/2010	Sunset review; no updates.		
*Y	3111357	BTK/NJF/ ARVM	12/15/10	Updated solder reflow specifications. Removed F _{IMO6} spec from AC chip-level specifications table. Removed the following pruned parts from the ordering information table and their references in the datasheet. 1) CY8C24794-24LFXI 2) CY8C24794-24LFXIT 3) CY8C24894-24LFXI 4) CY8C24894-24LFXIT		
*Z	3126167	BTK / ANBA / PKS	01/03/11	Updated ordering information. Removed the package diagram spec 51-85214 since there are no MPNs in the ordering information table that corresponds with this package. Updated ordering code definitions for clearer understanding.		
AA	3367463	BTK / GIR	09/22/11	Updated V _{REFHI} values for parameter '0b100' under Table 19 on page 31. Updated text under Table 19 on page 31. The text "Pin must be left floating" is included under Description of NC pin in Table 4 on page 12, Table 6 on page 14, Table 7 on page 16, and Table 8 on page 18. Updated Table 38 on page 51 to give more clarity.		
AB	3404970	MATT	10/13/11	Removed prune device CY8C24994-24BVXI from Ordering Information.		
AC	3461872	CSAI	12/13/2011	Sunset review; no content update		