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[Understanding Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	57
Number of Gates	3000
Voltage - Supply	3V ~ 3.6V, 4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	68-LCC (J-Lead)
Supplier Device Package	68-PLCC (24.23x24.23)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a40mx02-fplg68



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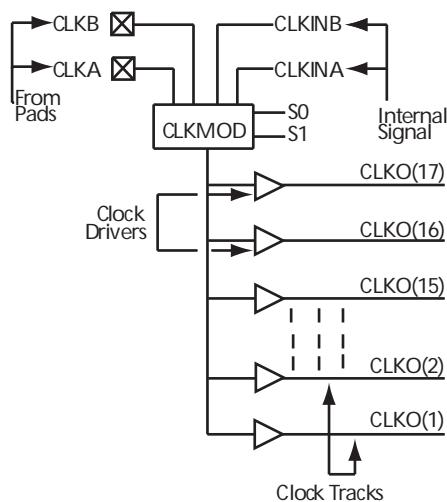
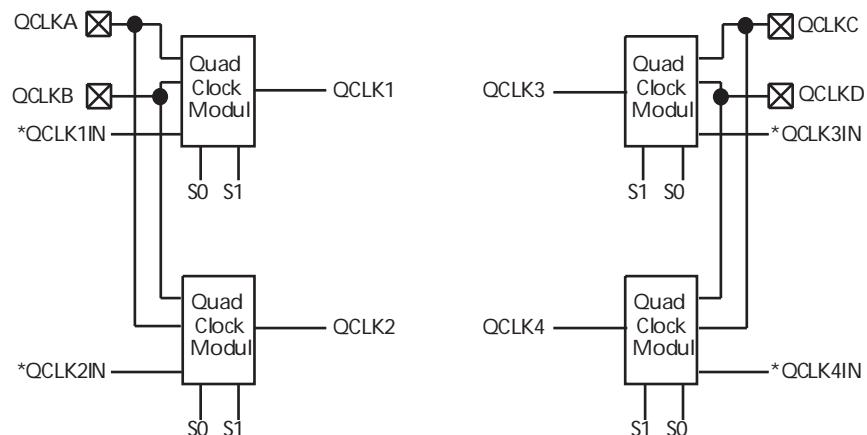
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Table 1 • Product profile

Device	A40MX02	A40MX04	A42MX09	A42MX16	A42MX24	A42MX36
Maximum Flip-Flops	147	273	516	928	1,410	1,822
Clocks	1	1	2	2	2	6
User I/O (maximum)	57	69	104	140	176	202
PCI	–	–	–	–	Yes	Yes
Boundary Scan Test (BST)	–	–	–	–	Yes	Yes
Packages (by pin count)						
PLCC	44, 68	44, 68, 84	84	84	84	–
PQFP	100	100	100, 144, 160	100, 160, 208	160, 208	208, 240
VQFP	80	80	100	100	–	–
TQFP	–	–	176	176	176	–
CQFP	–	–	–	172	–	208, 256
PBGA	–	–	–	–	–	272
CPGA	–	–	132	–	–	–

Figure 8 • Clock Networks of 42MX Devices**Figure 9 • Quadrant Clock Network of A42MX36 Devices**

Note: *QCLK1IN, QCLK2IN, QCLK3IN, and QCLK4IN are internally-generated signals.

3.2.5 MultiPlex I/O Modules

42MX devices feature Multiplex I/Os and support 5.0 V, 3.3 V, and mixed 3.3 V/5.0 V operations.

The MultiPlex I/O modules provide the interface between the device pins and the logic array. Figure 10, page 12 is a block diagram of the 42MX I/O module. A variety of user functions, determined by a library macro selection, can be implemented in the module. (See the [Antifuse Macro Library Guide](#) for more information.) All 42MX I/O modules contain tristate buffers, with input and output latches that can be configured for input, output, or bidirectional operation.

All 42MX devices contain flexible I/O structures, where each output pin has a dedicated output-enable control (Figure 10, page 12). The I/O module can be used to latch input or output data, or both, providing fast set-up time. In addition, the Designer software tools can build a D-type flip-flop using a C-module combined with an I/O module to register input and output signals. See the [Antifuse Macro Library Guide](#) for more details.

A42MX24 and A42MX36 devices also offer selectable PCI output drives, enabling 100% compliance with version 2.1 of the PCI specification. For low-power systems, all inputs and outputs are turned off to reduce current consumption to below 500 μ A.

To achieve 5.0 V or 3.3 V PCI-compliant output drives on A42MX24 and A42MX36 devices, a chip-wide PCI fuse is programmed via the Device Selection Wizard in the Designer software (Figure 11, page 12). When the PCI fuse is not programmed, the output drive is standard.

f_{q2} = Average second routed array clock rate in MHz)

Table 7 • Fixed Capacitance Values for MX FPGAs (pF)

Device Type	r1 routed_Clk1	r2 routed_Clk2
A40MX02	41.4	N/A
A40MX04	68.6	N/A
A42MX09	118	118
A42MX16	165	165
A42MX24	185	185
A42MX36	220	220

3.4.6 Test Circuitry and Silicon Explorer II Probe

MX devices contain probing circuitry that provides built-in access to every node in a design, via the use of Silicon Explorer II. Silicon Explorer II is an integrated hardware and software solution that, in conjunction with the Designer software, allow users to examine any of the internal nets of the device while it is operating in a prototyping or a production system. The user can probe into an MX device without changing the placement and routing of the design and without using any additional resources. Silicon Explorer II's noninvasive method does not alter timing or loading effects, thus shortening the debug cycle and providing a true representation of the device under actual functional situations.

Silicon Explorer II samples data at 100 MHz (asynchronous) or 66 MHz (synchronous). Silicon Explorer II attaches to a PC's standard COM port, turning the PC into a fully functional 18-channel logic analyzer. Silicon Explorer II allows designers to complete the design verification process at their desks and reduces verification time from several hours per cycle to a few seconds.

Silicon Explorer II is used to control the MODE, DCLK, SDI and SDO pins in MX devices to select the desired nets for debugging. The user simply assigns the selected internal nets in the Silicon Explorer II software to the PRA/PRB output pins for observation. Probing functionality is activated when the MODE pin is held HIGH.

Figure 12, page 16 illustrates the interconnection between Silicon Explorer II and 40MX devices, while Figure 13, page 17 illustrates the interconnection between Silicon Explorer II and 42MX devices.

To allow for probing capabilities, the security fuses must not be programmed. (See [User Security](#), page 12 for the security fuses of 40MX and 42MX devices). [Table 8](#), page 17 summarizes the possible device configurations for probing.

PRA and PRB pins are dual-purpose pins. When the "Reserve Probe Pin" is checked in the Designer software, PRA and PRB pins are reserved as dedicated outputs for probing. If PRA and PRB pins are required as user I/Os to achieve successful layout and "Reserve Probe Pin" is checked, the layout tool will override the option and place user I/Os on PRA and PRB pins.

Figure 12 • Silicon Explorer II Setup with 40MX

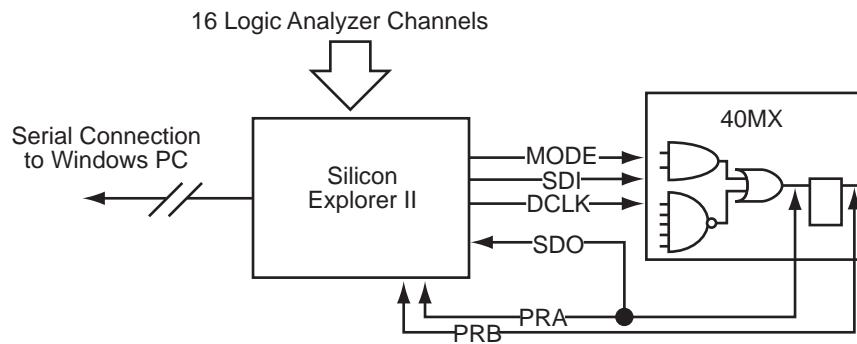
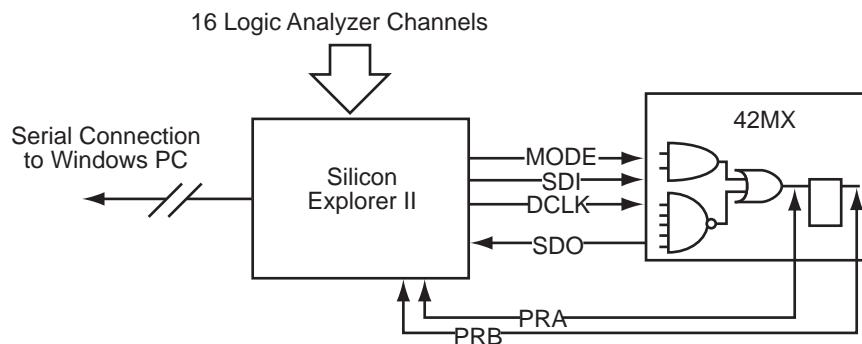


Figure 13 • Silicon Explorer II Setup with 42MX**Table 8 • Device Configuration Options for Probe Capability**

Security Fuse(s) Programmed	Mode	PRA, PRB ¹	SDI, SDO, DCLK ¹
No	LOW	User I/Os ²	User I/Os ²
No	HIGH	Probe Circuit Outputs	Probe Circuit Inputs
Yes	—	Probe Circuit Secured	Probe Circuit Secured

1. Avoid using SDI, SDO, DCLK, PRA and PRB pins as input or bidirectional ports. Since these pins are active during probing, input signals will not pass through these pins and may cause contention.
2. If no user signal is assigned to these pins, they will behave as unused I/Os in this mode. See the [Pin Descriptions](#), page 83 for information on unused I/O pins

3.4.7 Design Consideration

It is recommended to use a series 70Ω termination resistor on every probe connector (SDI, SDO, MODE, DCLK, PRA and PRB). The 70Ω series termination is used to prevent data transmission corruption during probing and reading back the checksum.

3.4.8 IEEE Standard 1149.1 Boundary Scan Test (BST) Circuitry

42MX24 and 42MX36 devices are compatible with IEEE Standard 1149.1 (informally known as Joint Testing Action Group Standard or JTAG), which defines a set of hardware architecture and mechanisms for cost-effective board-level testing. The basic MX boundary-scan logic circuit is composed of the TAP (test access port), TAP controller, test data registers and instruction register ([Figure 14](#), page 18). This circuit supports all mandatory IEEE 1149.1 instructions (EXTEST, SAMPLE/PRELOAD and BYPASS) and some optional instructions. [Table 9](#), page 18 describes the ports that control JTAG testing, while [Table 10](#), page 18 describes the test instructions supported by these MX devices.

Each test section is accessed through the TAP, which has four associated pins: TCK (test clock input), TDI and TDO (test data input and output), and TMS (test mode selector).

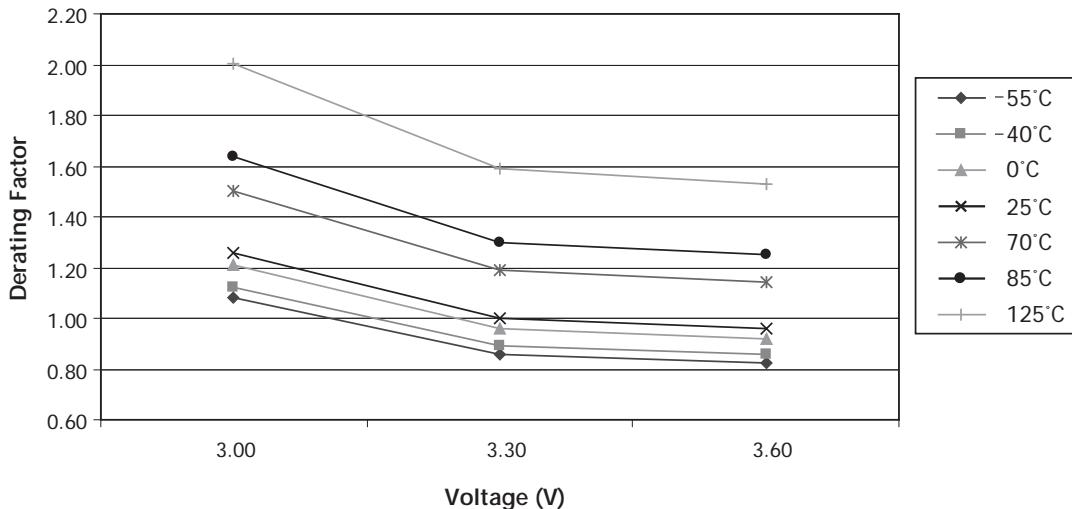
The TAP controller is a four-bit state machine. The '1's and '0's represent the values that must be present at TMS at a rising edge of TCK for the given state transition to occur. IR and DR indicate that the instruction register or the data register is operating in that state.

The TAP controller receives two control inputs (TMS and TCK) and generates control and clock signals for the rest of the test logic architecture. On power-up, the TAP controller enters the Test-Logic-Reset state. To guarantee a reset of the controller from any of the possible states, TMS must remain high for five TCK cycles.

42MX24 and 42MX36 devices support three types of test data registers: bypass, device identification, and boundary scan. The bypass register is selected when no other register needs to be accessed in a device. This speeds up test data transfer to other devices in a test data path. The 32-bit device identification register is a shift register with four fields (lowest significant byte (LSB), ID number, part number and version). The boundary-scan register observes and controls the state of each I/O pin.

Table 31 • 40MX Temperature and Voltage Derating Factors (Normalized to $T_J = 25^\circ\text{C}$, $V_{CC} = 3.3\text{ V}$)

		Temperature						
40MX Voltage	-55°C	-40°C	0°C	25°C	70°C	85°C	125°C	
3.60	0.83	0.85	0.92	0.96	1.14	1.25	1.53	

Figure 37 • 40MX Junction Temperature and Voltage Derating Curves (Normalized to $T_J = 25^\circ\text{C}$, $V_{CC} = 3.3\text{ V}$)

Note: This derating factor applies to all routing and propagation delays

3.11.5 PCI System Timing Specification

The following tables list the critical PCI timing parameters and the corresponding timing parameters for the MX PCI-compliant devices.

3.11.6 PCI Models

Microsemi provides synthesizable VHDL and Verilog-HDL models for a PCI Target interface, a PCI Target and Target+DMA Master interface. Contact the Microsemi sales representative for more details.

Table 32 • Clock Specification for 33 MHz PCI

Symbol	Parameter	PCI		A42MX24		A42MX36		Units
		Min.	Max.	Min.	Max.	Min.	Max.	
t_{CYC}	CLK Cycle Time	30	—	4.0	—	4.0	—	ns
t_{HIGH}	CLK High Time	11	—	1.9	—	1.9	—	ns
t_{LOW}	CLK Low Time	11	—	1.9	—	1.9	—	ns

Table 33 • Timing Parameters for 33 MHz PCI

Symbol	Parameter	PCI		A42MX24		A42MX36		Units
		Min.	Max.	Min.	Max.	Min.	Max.	
t_{VAL}	CLK to Signal Valid—Bused Signals	2	11	2.0	9.0	2.0	9.0	ns
$t_{VAL(PTP)}$	CLK to Signal Valid—Point-to-Point	2^2	12	2.0	9.0	2.0	9.0	ns
t_{ON}	Float to Active	2	—	2.0	4.0	2.0	4.0	ns
t_{OFF}	Active to Float	—	28	—	8.3^1	—	8.3^1	ns
t_{SU}	Input Set-Up Time to CLK—Bused Signals	7	—	1.5	—	1.5	—	ns

Table 41 • A42MX16 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t _{ACO}	Array Clock-to-Out (Pad-to-Pad),64 Clock Loading	11.3	12.5	14.2	16.7	23.3	ns				
d _{TLH}	Capacitive Loading, LOW to HIGH	0.04	0.04	0.05	0.06	0.08	ns/pF				
d _{THL}	Capacitive Loading, HIGH to LOW	0.05	0.05	0.06	0.07	0.10	ns/pF				

1. For dual-module macros use tPD1 + tRD1 + taped, to + tRD1 + taped, or tPD1 + tRD1 + tusk, whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
4. Set-up and hold timing parameters for the input buffer latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
5. Delays based on 35 pF loading.

Table 42 • A42MX24 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Combinatorial Functions¹											
t _{PD}	Internal Array Module Delay	1.2	1.3	1.5	1.8	2.5	ns				
t _{PDD}	Internal Decode Module Delay	1.4	1.6	1.8	2.1	3.0	ns				
Logic Module Predicted Routing Delays²											
t _{RD1}	FO = 1 Routing Delay	0.8	0.9	1.0	1.2	1.7	ns				
t _{RD2}	FO = 2 Routing Delay	1.0	1.2	1.3	1.5	2.1	ns				
t _{RD3}	FO = 3 Routing Delay	1.3	1.4	1.6	1.9	2.6	ns				
t _{RD4}	FO = 4 Routing Delay	1.5	1.7	1.9	2.2	3.1	ns				
t _{RD5}	FO = 8 Routing Delay	2.4	2.7	3.0	3.6	5.0	ns				
Logic Module Sequential Timing^{3, 4}											
t _{CO}	Flip-Flop Clock-to-Output	1.3	1.4	1.6	1.9	2.7	ns				
t _{GO}	Latch Gate-to-Output	1.2	1.3	1.5	1.8	2.5	ns				
t _{SUD}	Flip-Flop (Latch) Set-Up Time	0.3	0.4	0.4	0.5	0.7	ns				
t _{HD}	Flip-Flop (Latch) Hold Time	0.0	0.0	0.0	0.0	0.0	ns				
t _{RO}	Flip-Flop (Latch) Reset-to-Output	1.4	1.6	1.8	2.1	2.9	ns				
t _{SUENA}	Flip-Flop (Latch) Enable Set-Up	0.4	0.5	0.5	0.6	0.8	ns				
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0	0.0	0.0	0.0	0.0	ns				
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	3.3	3.7	4.2	4.9	6.9	ns				
t _{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width	4.4	4.8	5.3	6.5	9.0	ns				

Table 42 • A42MX24 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing⁵											
t _{DH}	Data-to-Pad HIGH		3.1		3.5		3.9		4.6		6.4 ns
t _{DHL}	Data-to-Pad LOW		2.4		2.6		3.0		3.5		4.9 ns
t _{ENZH}	Enable Pad Z to HIGH		2.5		2.8		3.2		3.8		5.3 ns
t _{ENZL}	Enable Pad Z to LOW		2.8		3.1		3.5		4.2		5.8 ns
t _{ENHZ}	Enable Pad HIGH to Z		5.2		5.7		6.5		7.6		10.7 ns
t _{ENLZ}	Enable Pad LOW to Z		4.8		5.3		6.0		7.1		9.9 ns
t _{GLH}	G-to-Pad HIGH		4.9		5.4		6.2		7.2		10.1 ns
t _{GHL}	G-to-Pad LOW		4.9		5.4		6.2		7.2		10.1 ns
t _{LSU}	I/O Latch Set-Up	0.5		0.5		0.6		0.7		1.0	ns
t _{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		5.5		6.1		6.9		8.1		11.3 ns
t _{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		10.6		11.8		13.4		15.7		22.0 ns
d _{TLH}	Capacitive Loading, LOW to HIGH	0.04		0.04		0.04		0.05		0.07	ns/pF
d _{THL}	Capacitive Loading, HIGH to LOW	0.03		0.03		0.03		0.04		0.06	ns/pF

- For dual-module macros, use t_{PD1} + t_{RD1} + t_{PDn}, t_{CO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.
- Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
- Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
- Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
- Delays based on 35 pF loading

Table 43 • A42MX24 Timing Characteristics (Nominal 3.3 V Operation) (Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Combinatorial Functions¹											
t _{PD}	Internal Array Module Delay	2.0		1.8		2.1		2.5		3.4	ns
t _{PDD}	Internal Decode Module Delay	1.1		2.2		2.5		3.0		4.2	ns
Logic Module Predicted Routing Delays²											
t _{RD1}	FO = 1 Routing Delay	1.7		1.3		1.4		1.7		2.3	ns
t _{RD2}	FO = 2 Routing Delay	2.0		1.6		1.8		2.1		3.0	ns
t _{RD3}	FO = 3 Routing Delay	1.1		2.0		2.2		2.6		3.7	ns
t _{RD4}	FO = 4 Routing Delay	1.5		2.3		2.6		3.1		4.3	ns
t _{RD5}	FO = 8 Routing Delay	1.8		3.7		4.2		5.0		7.0	ns

Table 44 • A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Combinatorial Functions¹											
t _{PD}	Internal Array Module Delay	1.3	1.5	1.7	2.0	2.7	ns				
t _{PDD}	Internal Decode Module Delay	1.6	1.8	2.0	2.4	3.3	ns				
Logic Module Predicted Routing Delays²											
t _{RD1}	FO = 1 Routing Delay	0.9	1.0	1.2	1.4	2.0	ns				
t _{RD2}	FO = 2 Routing Delay	1.3	1.4	1.6	1.9	2.7	ns				
t _{RD3}	FO = 3 Routing Delay	1.6	1.8	2.0	2.4	3.4	ns				
t _{RD4}	FO = 4 Routing Delay	2.0	2.2	2.5	2.9	4.1	ns				
t _{RD5}	FO = 8 Routing Delay	3.3	3.7	4.2	4.9	6.9	ns				
t _{RDD}	Decode-to-Output Routing Delay	0.3	0.4	0.4	0.5	0.7	ns				
Logic Module Sequential Timing^{3, 4}											
t _{CO}	Flip-Flop Clock-to-Output	1.3	1.4	1.6	1.9	2.7	ns				
t _{GO}	Latch Gate-to-Output	1.3	1.4	1.6	1.9	2.7	ns				
t _{SUD}	Flip-Flop (Latch) Set-Up Time	0.3	0.3	0.4	0.5	0.7	ns				
t _{HD}	Flip-Flop (Latch) Hold Time	0.0	0.0	0.0	0.0	0.0	ns				
t _{RO}	Flip-Flop (Latch) Reset-to-Output	1.6	1.7	2.0	2.3	3.2	ns				
t _{SUENA}	Flip-Flop (Latch) Enable Set-Up	0.7	0.8	0.9	1.0	1.4	ns				
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0	0.0	0.0	0.0	0.0	ns				
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	3.3	3.7	4.2	4.9	6.9	ns				
t _{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width	4.4	4.8	5.5	6.4	9.0	ns				
Synchronous SRAM Operations											
t _{RC}	Read Cycle Time	6.8	7.5	8.5	10.0	14.0	ns				
t _{WC}	Write Cycle Time	6.8	7.5	8.5	10.0	14.0	ns				
t _{RCKHL}	Clock HIGH/LOW Time	3.4	3.8	4.3	5.0	7.0	ns				
t _{RCO}	Data Valid After Clock HIGH/LOW	3.4	3.8	4.3	5.0	7.0	ns				
t _{ADSU}	Address/Data Set-Up Time	1.6	1.8	2.0	2.4	3.4	ns				
Synchronous SRAM Operations (continued)											
t _{ADH}	Address/Data Hold Time	0.0	0.0	0.0	0.0	0.0	ns				
t _{RENSU}	Read Enable Set-Up	0.6	0.7	0.8	0.9	1.3	ns				
t _{RENH}	Read Enable Hold	3.4	3.8	4.3	5.0	7.0	ns				
t _{WENSU}	Write Enable Set-Up	2.7	3.0	3.4	4.0	5.6	ns				
t _{WENH}	Write Enable Hold	0.0	0.0	0.0	0.0	0.0	ns				
t _{BENS}	Block Enable Set-Up	2.8	3.1	3.5	4.1	5.7	ns				
t _{BENH}	Block Enable Hold	0.0	0.0	0.0	0.0	0.0	ns				

4 Package Pin Assignments

The following figures and tables give the details of the package pin assignments.

Figure 38 • PL44

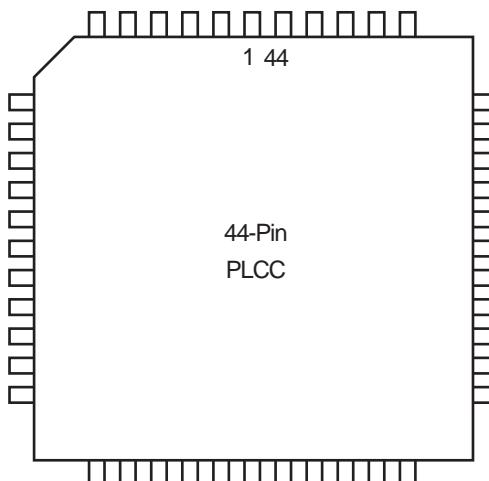
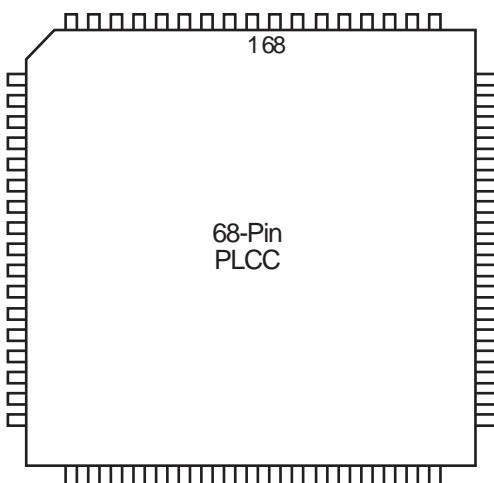


Table 47 • PL44

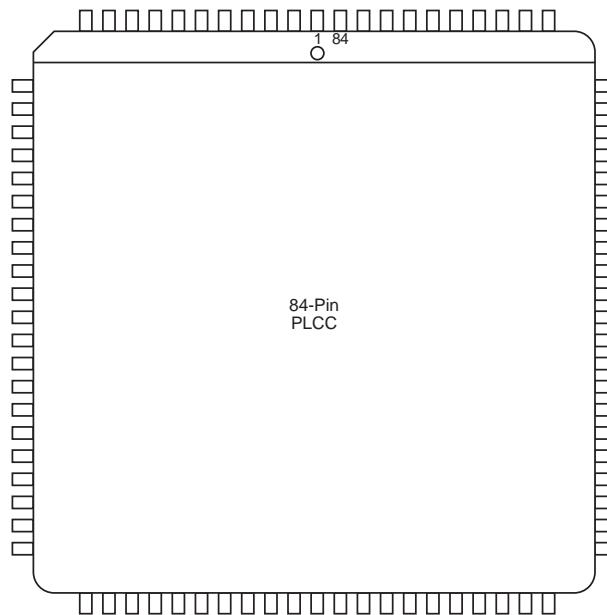
PL44		
Pin Number	A40MX02 Function	A40MX04 Function
1	I/O	I/O
2	I/O	I/O
3	VCC	VCC
4	I/O	I/O
5	I/O	I/O
6	I/O	I/O
7	I/O	I/O
8	I/O	I/O
9	I/O	I/O
10	GND	GND
11	I/O	I/O
12	I/O	I/O
13	I/O	I/O
14	VCC	VCC
15	I/O	I/O
16	VCC	VCC
17	I/O	I/O
18	I/O	I/O
19	I/O	I/O
20	I/O	I/O

Figure 39 • PL68**Table 48 • PL68**

PL68		
Pin Number	A40MX02 Function	A40MX04 Function
1	I/O	I/O
2	I/O	I/O
3	I/O	I/O
4	VCC	VCC
5	I/O	I/O
6	I/O	I/O
7	I/O	I/O
8	I/O	I/O
9	I/O	I/O
10	I/O	I/O
11	I/O	I/O
12	I/O	I/O
13	I/O	I/O
14	GND	GND
15	GND	GND
16	I/O	I/O
17	I/O	I/O
18	I/O	I/O
19	I/O	I/O
20	I/O	I/O
21	VCC	VCC
22	I/O	I/O
23	I/O	I/O

Table 48 • PL68

PL68		
Pin Number	A40MX02 Function	A40MX04 Function
61	I/O	I/O
62	I/O	I/O
63	I/O	I/O
64	I/O	I/O
65	I/O	I/O
66	GND	GND
67	I/O	I/O
68	I/O	I/O

Figure 40 • PL84**Table 49 • PL84**

PL84				
Pin Number	A40MX04 Function	A42MX09 Function	A42MX16 Function	A42MX24 Function
1	I/O	I/O	I/O	I/O
2	I/O	CLKB, I/O	CLKB, I/O	CLKB, I/O
3	I/O	I/O	I/O	I/O
4	VCC	PRB, I/O	PRB, I/O	PRB, I/O
5	I/O	I/O	I/O	WD, I/O
6	I/O	GND	GND	GND
7	I/O	I/O	I/O	I/O
8	I/O	I/O	I/O	WD, I/O
9	I/O	I/O	I/O	WD, I/O

Table 50 • PQ 100

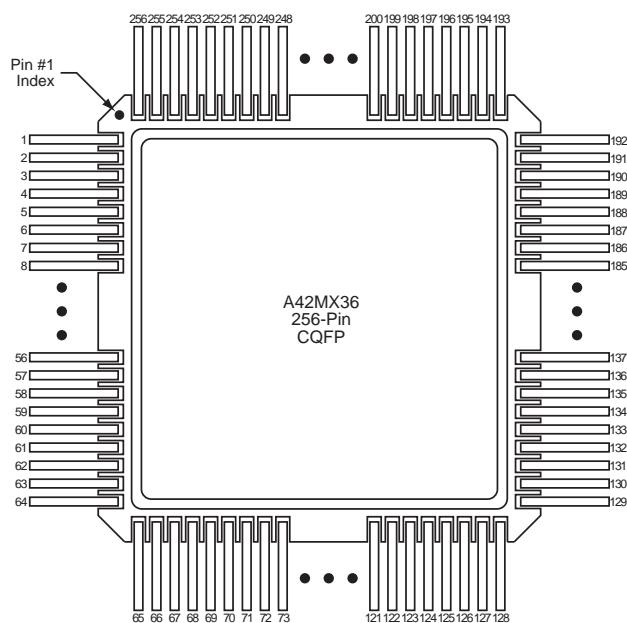
PQ100				
Pin Number	A40MX02 Function	A40MX04 Function	A42MX09 Function	A42MX16 Function
56	VCC	VCC	I/O	I/O
57	I/O	I/O	GND	GND
58	I/O	I/O	I/O	I/O
59	I/O	I/O	I/O	I/O
60	I/O	I/O	I/O	I/O
61	I/O	I/O	I/O	I/O
62	I/O	I/O	I/O	I/O
63	GND	GND	I/O	I/O
64	I/O	I/O	LP	LP
65	I/O	I/O	VCCA	VCCA
66	I/O	I/O	VCCI	VCCI
67	I/O	I/O	VCCA	VCCA
68	I/O	I/O	I/O	I/O
69	VCC	VCC	I/O	I/O
70	I/O	I/O	I/O	I/O
71	I/O	I/O	I/O	I/O
72	I/O	I/O	GND	GND
73	I/O	I/O	I/O	I/O
74	I/O	I/O	I/O	I/O
75	I/O	I/O	I/O	I/O
76	I/O	I/O	I/O	I/O
77	NC	NC	I/O	I/O
78	NC	NC	I/O	I/O
79	NC	NC	SDI, I/O	SDI, I/O
80	NC	I/O	I/O	I/O
81	NC	I/O	I/O	I/O
82	NC	I/O	I/O	I/O
83	I/O	I/O	I/O	I/O
84	I/O	I/O	GND	GND
85	I/O	I/O	I/O	I/O
86	GND	GND	I/O	I/O
87	GND	GND	PRA, I/O	PRA, I/O
88	I/O	I/O	I/O	I/O
89	I/O	I/O	CLKA, I/O	CLKA, I/O
90	CLK, I/O	CLK, I/O	VCCA	VCCA
91	I/O	I/O	I/O	I/O
92	MODE	MODE	CLKB, I/O	CLKB, I/O

Table 57 • TQ176

TQ176			
Pin Number	A42MX09 Function	A42MX16 Function	A42MX24 Function
10	NC	I/O	I/O
11	NC	I/O	I/O
12	I/O	I/O	I/O
13	NC	VCCA	VCCA
14	I/O	I/O	I/O
15	I/O	I/O	I/O
16	I/O	I/O	I/O
17	I/O	I/O	I/O
18	GND	GND	GND
19	NC	I/O	I/O
20	NC	I/O	I/O
21	I/O	I/O	I/O
22	NC	I/O	I/O
23	GND	GND	GND
24	NC	VCCI	VCCI
25	VCCA	VCCA	VCCA
26	NC	I/O	I/O
27	NC	I/O	I/O
28	VCCI	VCCA	VCCA
29	NC	I/O	I/O
30	I/O	I/O	I/O
31	I/O	I/O	I/O
32	I/O	I/O	I/O
33	NC	NC	I/O
34	I/O	I/O	I/O
35	I/O	I/O	I/O
36	I/O	I/O	I/O
37	NC	I/O	I/O
38	NC	NC	I/O
39	I/O	I/O	I/O
40	I/O	I/O	I/O
41	I/O	I/O	I/O
42	I/O	I/O	I/O
43	I/O	I/O	I/O
44	I/O	I/O	I/O
45	GND	GND	GND
46	I/O	I/O	TMS, I/O

Table 58 • CQ208

CQ208	
Pin Number	A42MX36 Function
148	I/O
149	I/O
150	GND
151	I/O
152	I/O
153	I/O
154	I/O
155	I/O
156	I/O
157	GND
158	I/O
159	SDI, I/O
160	I/O
161	WD, I/O
162	WD, I/O
163	I/O
164	VCCI
165	I/O
166	I/O
167	I/O
168	WD, I/O
169	WD, I/O
170	I/O
171	QCLKD, I/O
172	I/O
173	I/O
174	I/O
175	I/O
176	WD, I/O
177	WD, I/O
178	PRA, I/O
179	I/O
180	CLKA, I/O
181	I/O
182	VCCI
183	VCCA
184	GND

Figure 50 • CQ256**Table 59 • CQ256**

CQ256	
Pin Number	A42MX36 Function
1	NC
2	GND
3	I/O
4	I/O
5	I/O
6	I/O
7	I/O
8	I/O
9	I/O
10	GND
11	I/O
12	I/O
13	I/O
14	I/O
15	I/O
16	I/O
17	I/O
18	I/O
19	I/O
20	I/O
21	I/O

Table 60 • BG272

BG272	
Pin Number	A42MX36 Function
A6	I/O
A7	WD, I/O
A8	WD, I/O
A9	I/O
A10	I/O
A11	CLKA
A12	I/O
A13	I/O
A14	I/O
A15	I/O
A16	WD, I/O
A17	I/O
A18	I/O
A19	GND
A20	GND
B1	GND
B2	GND
B3	DCLK, I/O
B4	I/O
B5	I/O
B6	I/O
B7	WD, I/O
B8	I/O
B9	PRB, I/O
B10	I/O
B11	I/O
B12	WD, I/O
B13	I/O
B14	I/O
B15	WD, I/O
B16	I/O
B17	WD, I/O
B18	I/O
B19	GND
B20	GND
C1	I/O
C2	MODE

Table 61 • PG132

PG132	
Pin Number	A42MX09 Function
N10	I/O
M10	I/O
N11	I/O
L10	I/O
M11	I/O
N12	SDO
M12	I/O
L11	I/O
N13	I/O
M13	I/O
K11	I/O
L12	I/O
L13	I/O
K13	I/O
H10	I/O
J12	I/O
J13	I/O
H11	I/O
H12	I/O
H13	VKS
G13	VPP