



Welcome to [E-XFL.COM](#)

[Understanding Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

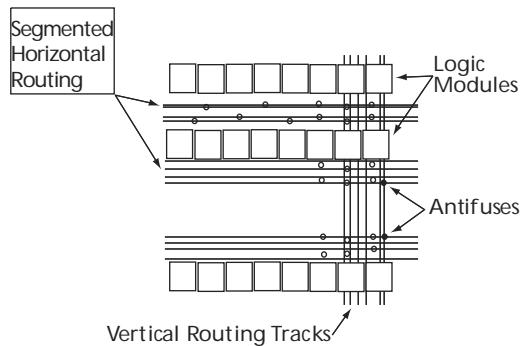
Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	69
Number of Gates	6000
Voltage - Supply	3V ~ 3.6V, 4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	100-BQFP
Supplier Device Package	100-PQFP (20x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a40mx04-1pqqg100

3.2.3.3 Antifuse Structures

An antifuse is a “normally open” structure. The use of antifuses to implement a programmable logic device results in highly testable structures as well as efficient programming algorithms. There are no pre-existing connections; temporary connections can be made using pass transistors. These temporary connections can isolate individual antifuses to be programmed and individual circuit structures to be tested, which can be done before and after programming. For instance, all metal tracks can be tested for continuity and shorts between adjacent tracks, and the functionality of all logic modules can be verified.

Figure 7 • MX Routing Structure



3.2.4 Clock Networks

The 40MX devices have one global clock distribution network (CLK). A signal can be put on the CLK network by being routed through the CLKBUF buffer.

In 42MX devices, there are two low-skew, high-fanout clock distribution networks, referred to as CLKA and CLKB. Each network has a clock module (CLKMOD) that can select the source of the clock signal from any of the following (Figure 8, page 11):

- Externally from the CLKA pad, using CLKBUF buffer
- Externally from the CLKB pad, using CLKBUF buffer
- Internally from the CLKINTA input, using CLKINT buffer
- Internally from the CLKINTB input, using CLKINT buffer

The clock modules are located in the top row of I/O modules. Clock drivers and a dedicated horizontal clock track are located in each horizontal routing channel.

Clock input pads in both 40MX and 42MX devices can also be used as normal I/Os, bypassing the clock networks.

The A42MX36 device has four additional register control resources, called quadrant clock networks (Figure 9, page 11). Each quadrant clock provides a local, high-fanout resource to the contiguous logic modules within its quadrant of the device. Quadrant clock signals can originate from specific I/O pins or from the internal array and can be used as a secondary register clock, register clear, or output enable.

3.3.7 Low Power Mode

42MX devices have been designed with a Low Power Mode. This feature, activated with setting the special LP pin to HIGH for a period longer than 800 ns, is particularly useful for battery-operated systems where battery life is a primary concern. In this mode, the core of the device is turned off and the device consumes minimal power with low standby current. In addition, all input buffers are turned off, and all outputs and bidirectional buffers are tristated. Since the core of the device is turned off, the states of the registers are lost. The device must be re-initialized when exiting Low Power Mode. I/Os can be driven during LP mode, and clock pins should be driven HIGH or LOW and should not float to avoid drawing current. To exit LP mode, the LP pin must be pulled LOW for over 200 μ s to allow for charge pumps to power up, and device initialization will begin.

3.4 Power Dissipation

The general power consumption of MX devices is made up of static and dynamic power and can be expressed with the following equation.

3.4.1 General Power Equation

$$P = [ICC_{\text{standby}} + ICC_{\text{active}}] * VCCI + IOL * VOL * N + IOH * (VCCI - VOH) * M$$

EQ 1

where:

- ICC_{standby} is the current flowing when no inputs or outputs are changing.
- ICC_{active} is the current flowing due to CMOS switching.
- IOL, IOH are TTL sink/source currents.
- VOL, VOH are TTL level output voltages.
- N equals the number of outputs driving TTL loads to VOL .
- M equals the number of outputs driving TTL loads to VOH .

Accurate values for N and M are difficult to determine because they depend on the family type, on design details, and on the system I/O. The power can be divided into two components: static and active.

3.4.2 Static Power Component

The static power due to standby current is typically a small component of the overall power consumption. Standby power is calculated for commercial, worst-case conditions. The static power dissipation by TTL loads depends on the number of outputs driving, and on the DC load current. For instance, a 32-bit bus sinking 4mA at 0.33V will generate 42mW with all outputs driving LOW, and 140mW with all outputs driving HIGH. The actual dissipation will average somewhere in between, as I/Os switch states with time.

3.4.3 Active Power Component

Power dissipation in CMOS devices is usually dominated by the dynamic power dissipation. Dynamic power consumption is frequency-dependent and is a function of the logic and the external I/O. Active power dissipation results from charging internal chip capacitances of the interconnect, unprogrammed antifuses, module inputs, and module outputs, plus external capacitances due to PC board traces and load device inputs. An additional component of the active power dissipation is the totem pole current in the CMOS transistor pairs. The net effect can be associated with an equivalent capacitance that can be combined with frequency and voltage to represent active power dissipation.

The power dissipated by a CMOS circuit can be expressed by the equation:

$$\text{Power}(\mu\text{W}) = C_{\text{EQ}} * VCCA2^2 * F(1)$$

EQ 2

where:

- C_{EQ} = Equivalent capacitance expressed in picofarads (pF)

reliability. Devices should not be operated outside the recommended operating conditions.

Table 21 • Recommended Operating Conditions

Parameter	Commercial	Industrial	Military	Units
Temperature Range*	0 to +70	-40 to +85	-55 to +125	°C
VCCA	4.75 to 5.25	4.5 to 5.5	4.5 to 5.5	V
VCCI	3.14 to 3.47	3.0 to 3.6	3.0 to 3.6	V

Note: *Ambient temperature (T_A) is used for commercial and industrial grades; case temperature (T_C) is used for military grades.

3.9.3 Output Drive Characteristics for 3.3 V PCI Signaling

Table 25 • DC Specification (3.3 V PCI Signaling)¹

Symbol	Parameter	Condition	PCI		MX		Units
			Min.	Max.	Min.	Max.	
VCCI	Supply Voltage for I/Os		3.0	3.6	3.0	3.6 ²	V
VIH	Input High Voltage		0.5	VCC + 0.5	0.5	VCCI + 0.3	V
VIL	Input Low Voltage		-0.5	0.8	-0.3	0.8	V
I _{IH}	Input High Leakage Current	VIN = 2.7 V		70		10	µA
I _{IL}	Input Leakage Current			-70		-10	µA
V _{OH}	Output High Voltage	I _{OUT} = -2 mA	0.9		3.3		V
V _{OL}	Output Low Voltage	I _{OUT} = 3 mA, 6 mA	0.1		0.1 VCCI		V
C _{IN}	Input Pin Capacitance			10		10	pF
C _{CLK}	CLK Pin Capacitance		5	12		10	pF
L _{PIN}	Pin Inductance			20		< 8 nH ³	nH

1. PCI Local Bus Specification, Version 2.1, Section 4.2.2.1.

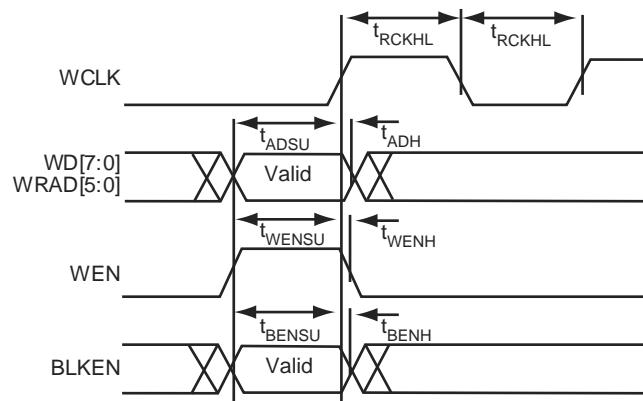
2. Maximum rating for VCCI -0.5 V to 7.0V.

3. Dependent upon the chosen package. PCI recommends QFP and BGA packaging to reduce pin inductance and capacitance.

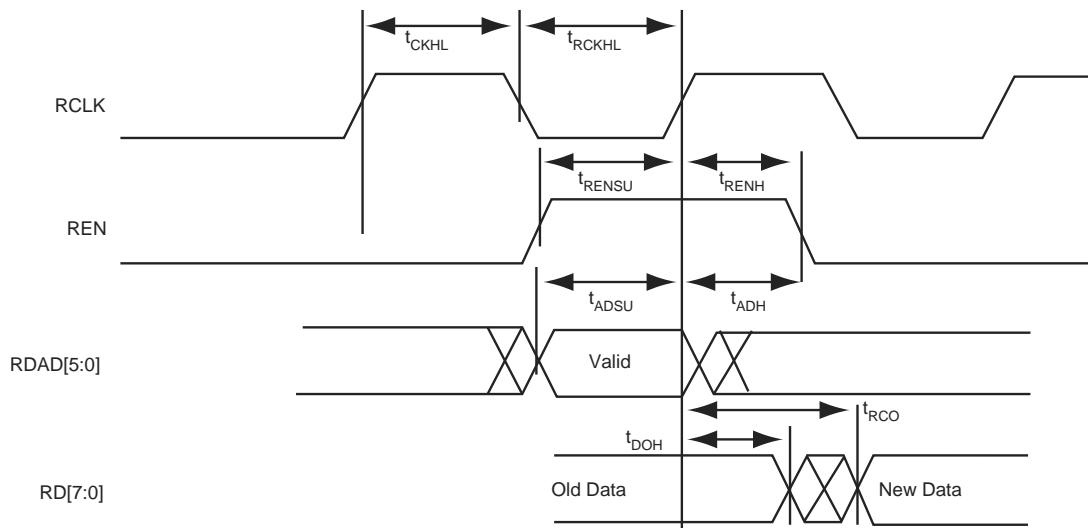
Table 26 • AC Specifications for (3.3 V PCI Signaling)^{*}

Symbol	Parameter	Condition	PCI		MX		Units
			Min.	Max.	Min.	Max.	
I _{CL}	Low Clamp Current	-5 < VIN ≤ -1	-25 + (VIN +1) /0.015		-60	-10	mA
Slew (r)	Output Rise Slew Rate	0.2 V to 0.6 V load	1		4	1.8	V/ns
Slew (f)	Output Fall Slew Rate	0.6 V to 0.2 V load	1		4	2.8	4.0
							V/ns

Note: *PCI Local Bus Specification, Version 2.1, Section 4.2.2.2.

Figure 30 • 42MX SRAM Write Operation

Note: Identical timing for falling edge clock

Figure 31 • 42MX SRAM Synchronous Read Operation

Note: Identical timing for falling edge clock

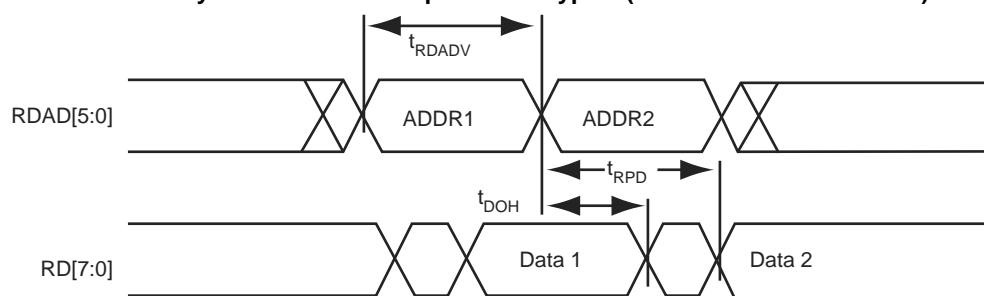
Figure 32 • 42MX SRAM Asynchronous Read Operation—Type 1 (Read Address Controlled)

Table 37 • A40MX04 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCC = 3.0 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing⁴											
t _{DH}	Data-to-Pad HIGH		5.5	6.4	7.2	8.5	11.9	ns			
t _{DHL}	Data-to-Pad LOW		4.8	5.5	6.2	7.3	10.2	ns			
t _{ENZH}	Enable Pad Z to HIGH		4.7	5.5	6.2	7.3	10.2	ns			
t _{ENZL}	Enable Pad Z to LOW		6.8	7.9	8.9	10.5	14.7	ns			
t _{ENHZ}	Enable Pad HIGH to Z		11.1	12.8	14.5	17.1	23.9	ns			
t _{ENLZ}	Enable Pad LOW to Z		8.2	9.5	10.7	12.6	17.7	ns			
d _{TLH}	Delta LOW to HIGH		0.05	0.05	0.06	0.07	0.10	ns/pF			
d _{THL}	Delta HIGH to LOW		0.03	0.03	0.04	0.04	0.06	ns/pF			

1. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
2. Set-up times assume fanout of 3. Further testing information can be obtained from the Timer utility.
3. The hold time for the DFME1A macro may be greater than 0 ns. Use the Timer tool from the Designer software to check the hold time for this macro.
4. Delays based on 35 pF loading.

Table 38 • A42MX09 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays¹											
t _{PD1}	Single Module		1.2	1.3	1.5	1.8	2.5	ns			
t _{CO}	Sequential Clock-to-Q		1.3	1.4	1.6	1.9	2.7	ns			
t _{GO}	Latch G-to-Q		1.2	1.4	1.6	1.8	2.6	ns			
t _{RS}	Flip-Flop (Latch) Reset-to-Q		1.2	1.6	1.8	2.1	2.9	ns			
Logic Module Predicted Routing Delays²											
t _{RD1}	FO = 1 Routing Delay		0.7	0.8	0.9	1.0	1.4	ns			
t _{RD2}	FO = 2 Routing Delay		0.9	1.0	1.2	1.4	1.9	ns			
t _{RD3}	FO = 3 Routing Delay		1.2	1.3	1.5	1.7	2.4	ns			
t _{RD4}	FO = 4 Routing Delay		1.4	1.5	1.7	2.0	2.9	ns			
t _{RD8}	FO = 8 Routing Delay		2.3	2.6	2.9	3.4	4.8	ns			
Logic Module Sequential Timing^{3, 4}											
t _{SUD}	Flip-Flop (Latch) Data Input Set-Up		0.3	0.4	0.4	0.5	0.7	ns			
t _{HD}	Flip-Flop (Latch) Data Input Hold	0.0	0.0	0.0	0.0	0.0	0.0	ns			
t _{SUENA}	Flip-Flop (Latch) Enable Set-Up	0.4	0.5	0.5	0.6	0.8	ns				
t _{HEN} A	Flip-Flop (Latch) Enable Hold	0.0	0.0	0.0	0.0	0.0	0.0	ns			
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	3.4	3.8	4.3	5.0	7.0	ns				

Table 39 • A42MX09 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description		-3 Speed	-2 Speed	-1 Speed	Std Speed	-F Speed			
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.
TTL Output Module Timing⁵									
t _{DLH}	Data-to-Pad HIGH	3.4	3.8	4.3	5.1	7.1	ns		
t _{DHL}	Data-to-Pad LOW	4.0	4.5	5.1	6.1	8.3	ns		
t _{ENZH}	Enable Pad Z to HIGH	3.7	4.1	4.6	5.5	7.6	ns		
t _{ENZL}	Enable Pad Z to LOW	4.1	4.5	5.1	6.1	8.5	ns		
t _{ENHZ}	Enable Pad HIGH to Z	6.9	7.6	8.6	10.2	14.2	ns		
t _{ENLZ}	Enable Pad LOW to Z	7.5	8.3	9.4	11.1	15.5	ns		
t _{GLH}	G-to-Pad HIGH	5.8	6.5	7.3	8.6	12.0	ns		
t _{GHL}	G-to-Pad LOW	5.8	6.5	7.3	8.6	12.0	ns		
t _{LSU}	I/O Latch Set-Up	0.7	0.8	0.9	1.0	1.4	ns		
t _{LH}	I/O Latch Hold	0.0	0.0	0.0	0.0	0.0	ns		
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad), 64 Clock Loading	8.7	9.7	10.9	12.9	18.0	ns		
t _{ACO}	Array Clock-to-Out (Pad-to-Pad), 64 Clock Loading	12.2	13.5	15.4	18.1	25.3	ns		
d _{TLH}	Capacity Loading, LOW to HIGH	0.00	0.00	0.00	0.10	0.01	ns/pF		
d _{THL}	Capacity Loading, HIGH to LOW	0.09	0.10	0.10	0.10	0.10	ns/pF		

Table 39 • A42MX09 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing⁵											
t _{D LH}	Data-to-Pad HIGH		3.4		3.8		5.5		6.4		9.0 ns
t _{D HL}	Data-to-Pad LOW		4.1		4.5		4.2		5.0		7.0 ns
t _{ENZH}	Enable Pad Z to HIGH		3.7		4.1		4.6		5.5		7.6 ns
t _{ENZL}	Enable Pad Z to LOW		4.1		4.5		5.1		6.1		8.5 ns
t _{ENHZ}	Enable Pad HIGH to Z		6.9		7.6		8.6		10.2		14.2 ns
t _{ENLZ}	Enable Pad LOW to Z		7.5		8.3		9.4		11.1		15.5 ns
t _{GLH}	G-to-Pad HIGH		5.8		6.5		7.3		8.6		12.0 ns
t _{GHL}	G-to-Pad LOW		5.8		6.5		7.3		8.6		12.0 ns
t _{LSU}	I/O Latch Set-Up	0.7		0.8		0.9		1.0		1.4	ns
t _{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad), 64 Clock Loading		8.7		9.7		10.9		12.9		18.0 ns
t _{ACO}	Array Clock-to-Out (Pad-to-Pad), 64 Clock Loading		12.2		13.5		15.4		18.1		25.3 ns
d _{TLH}	Capacity Loading, LOW to HIGH	0.04		0.04		0.05		0.06		0.08	ns/pF
d _{THL}	Capacity Loading, HIGH to LOW	0.05		0.05		0.06		0.07		0.10	ns/pF

- For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.
- Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
- Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
- Set-up and hold timing parameters for the input buffer latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
- Delays based on 35 pF loading.

Table 40 • A42MX16 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays¹											
t _{PD1}	Single Module	1.4		1.5		1.7		2.0		2.8	ns
t _{CO}	Sequential Clock-to-Q	1.4		1.6		1.8		2.1		3.0	ns
t _{GO}	Latch G-to-Q	1.4		1.5		1.7		2.0		2.8	ns
t _{RS}	Flip-Flop (Latch) Reset-to-Q	1.6		1.7		2.0		2.3		3.3	ns
Logic Module Predicted Routing Delays²											
t _{RD1}	FO = 1 Routing Delay	0.8		0.9		1.0		1.2		1.6	ns
t _{RD2}	FO = 2 Routing Delay	1.0		1.2		1.3		1.5		2.1	ns

Table 45 • A42MX36 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Input Module Predicted Routing Delays²											
t _{IRD1}	FO = 1 Routing Delay		2.8	3.1	3.5	4.1	5.7	ns			
t _{IRD2}	FO = 2 Routing Delay		3.2	3.5	4.1	4.8	6.7	ns			
t _{IRD3}	FO = 3 Routing Delay		3.7	4.1	4.7	5.5	7.7	ns			
t _{IRD4}	FO = 4 Routing Delay		4.2	4.6	5.3	6.2	8.7	ns			
t _{IRD8}	FO = 8 Routing Delay		6.1	6.8	7.7	9.0	12.6	ns			
Global Clock Network											
t _{CKH}	Input LOW to HIGH	FO = 32	4.6	5.1	5.7	6.7	9.3	ns			
		FO = 635	5.0	5.6	6.3	7.4	10.3	ns			
t _{CKL}	Input HIGH to LOW	FO = 32	5.3	5.9	6.7	7.8	11.0	ns			
		FO = 635	6.8	7.6	8.6	10.1	14.1	ns			
t _{PWH}	Minimum Pulse Width HIGH	FO = 32	2.5	2.7	3.1	3.6	5.1	ns			
		FO = 635	2.8	3.1	3.5	4.1	5.7	ns			
t _{PWL}	Minimum Pulse Width LOW	FO = 32	2.5	2.7	3.1	3.6	5.1	ns			
		FO = 635	2.8	3.1	3.5	4.1	5.7	ns			
t _{CKSW}	Maximum Skew	FO = 32	1.0	1.2	1.3	1.5	2.2	ns			
		FO = 635	1.0	1.2	1.3	1.5	2.2	ns			
t _{SUEXT}	Input Latch External Set-Up	FO = 32	0.0	0.0	0.0	0.0	0.0	ns			
		FO = 635	0.0	0.0	0.0	0.0	0.0	ns			
t _{HEXT}	Input Latch External Hold	FO = 32	4.0	4.4	5.0	5.9	8.2	ns			
		FO = 635	4.6	5.2	5.9	6.9	9.6	ns			
t _P	Minimum Period (1/f _{MAX})	FO = 32	9.2	10.2	11.1	12.7	21.2	ns			
		FO = 635	9.9	11.0	12.0	13.8	23.0	ns			
f _{MAX}	Maximum Datapath Frequency	FO = 32	108	98	90	79	47	MHz			
		FO = 635	100	91	83	73	44	MHz			
TTL Output Module Timing⁵											
t _{DLH}	Data-to-Pad HIGH		3.6	4.0	4.5	5.3	7.4	ns			
t _{DHL}	Data-to-Pad LOW		4.2	4.6	5.2	6.2	8.6	ns			
t _{ENZH}	Enable Pad Z to HIGH		3.7	4.2	4.7	5.5	7.7	ns			
t _{ENZL}	Enable Pad Z to LOW		4.1	4.6	5.2	6.1	8.5	ns			
t _{ENHZ}	Enable Pad HIGH to Z		7.34	8.2	9.3	10.9	15.3	ns			
TTL Output Module Timing⁵											
t _{ENLZ}	Enable Pad LOW to Z		6.9	7.6	8.7	10.2	14.3	ns			
t _{GLH}	G-to-Pad HIGH		4.9	5.5	6.2	7.3	10.2	ns			
t _{GHL}	G-to-Pad LOW		4.9	5.5	6.2	7.3	10.2	ns			
t _{LSU}	I/O Latch Output Set-Up		0.7	0.7	0.8	1.0	1.4	ns			
t _{LH}	I/O Latch Output Hold		0.0	0.0	0.0	0.0	0.0	ns			
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.9	8.8	10.0	11.8	16.5	ns			

Table 48 • PL68

PL68		
Pin Number	A40MX02 Function	A40MX04 Function
24	I/O	I/O
25	VCC	VCC
26	I/O	I/O
27	I/O	I/O
28	I/O	I/O
29	I/O	I/O
30	I/O	I/O
31	I/O	I/O
32	GND	GND
33	I/O	I/O
34	I/O	I/O
35	I/O	I/O
36	I/O	I/O
37	I/O	I/O
38	VCC	VCC
39	I/O	I/O
40	I/O	I/O
41	I/O	I/O
42	I/O	I/O
43	I/O	I/O
44	I/O	I/O
45	I/O	I/O
46	I/O	I/O
47	I/O	I/O
48	I/O	I/O
49	GND	GND
50	I/O	I/O
51	I/O	I/O
52	CLK, I/O	CLK, I/O
53	I/O	I/O
54	MODE	MODE
55	VCC	VCC
56	SDI, I/O	SDI, I/O
57	DCLK, I/O	DCLK, I/O
58	PRA, I/O	PRA, I/O
59	PRB, I/O	PRB, I/O
60	I/O	I/O

Table 51 • PQ144

PQ144	
Pin Number	A42MX09 Function
80	GNDI
81	NC
82	I/O
83	I/O
84	I/O
85	I/O
86	I/O
87	I/O
88	VKS
89	VPP
90	VCC
91	VCCI
92	NC
93	VSV
94	I/O
95	I/O
96	I/O
97	I/O
98	I/O
99	I/O
100	GND
101	GNDI
102	NC
103	I/O
104	I/O
105	I/O
106	I/O
107	I/O
108	I/O
109	I/O
110	SDI
111	I/O
112	I/O
113	I/O
114	I/O
115	I/O
116	GNDQ

Table 51 • PQ144

PQ144	
Pin Number	A42MX09 Function
117	GNDI
118	NC
119	I/O
120	I/O
121	I/O
122	I/O
123	PROBA
124	I/O
125	CLKA
126	VCC
127	VCCI
128	NC
129	I/O
130	CLKB
131	I/O
132	PROBB
133	I/O
134	I/O
135	I/O
136	GND
137	GNDI
138	NC
139	I/O
140	I/O
141	I/O
142	I/O
143	I/O
144	DCLK

Table 53 • PQ208

PQ208	Pin Number	A42MX16 Function	A42MX24 Function	A42MX36 Function
	58	I/O	WD, I/O	WD, I/O
	59	I/O	I/O	I/O
	60	VCCI	VCCI	VCCI
	61	NC	I/O	I/O
	62	NC	I/O	I/O
	63	I/O	I/O	I/O
	64	I/O	I/O	I/O
	65	I/O	I/O	QCLKA, I/O
	66	I/O	WD, I/O	WD, I/O
	67	NC	WD, I/O	WD, I/O
	68	NC	I/O	I/O
	69	I/O	I/O	I/O
	70	I/O	WD, I/O	WD, I/O
	71	I/O	WD, I/O	WD, I/O
	72	I/O	I/O	I/O
	73	I/O	I/O	I/O
	74	I/O	I/O	I/O
	75	I/O	I/O	I/O
	76	I/O	I/O	I/O
	77	I/O	I/O	I/O
	78	GND	GND	GND
	79	VCCA	VCCA	VCCA
	80	NC	VCCI	VCCI
	81	I/O	I/O	I/O
	82	I/O	I/O	I/O
	83	I/O	I/O	I/O
	84	I/O	I/O	I/O
	85	I/O	WD, I/O	WD, I/O
	86	I/O	WD, I/O	WD, I/O
	87	I/O	I/O	I/O
	88	I/O	I/O	I/O
	89	NC	I/O	I/O
	90	NC	I/O	I/O
	91	I/O	I/O	QCLKB, I/O
	92	I/O	I/O	I/O
	93	I/O	WD, I/O	WD, I/O
	94	I/O	WD, I/O	WD, I/O

Table 54 • PQ240

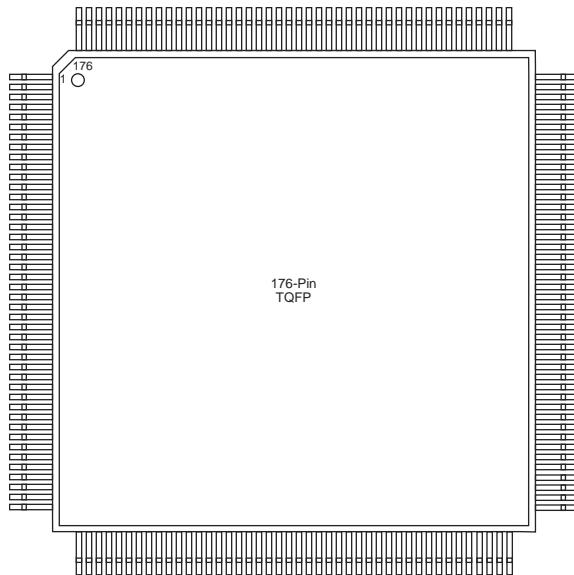
PQ240	
Pin Number	A42MX36 Function
15	QCLKC, I/O
16	I/O
17	WD, I/O
18	WD, I/O
19	I/O
20	I/O
21	WD, I/O
22	WD, I/O
23	I/O
24	PRB, I/O
25	I/O
26	CLKB, I/O
27	I/O
28	GND
29	VCCA
30	VCCI
31	I/O
32	CLKA, I/O
33	I/O
34	PRA, I/O
35	I/O
36	I/O
37	WD, I/O
38	WD, I/O
39	I/O
40	I/O
41	I/O
42	I/O
43	I/O
44	I/O
45	QCLKD, I/O
46	I/O
47	WD, I/O
48	WD, I/O
49	I/O
50	I/O
51	I/O

Table 56 • VQ100

VQ100		
Pin Number	A42MX09 Function	A42MX16 Function
21	I/O	I/O
22	I/O	I/O
23	I/O	I/O
24	I/O	I/O
25	I/O	I/O
26	I/O	I/O
27	I/O	I/O
28	I/O	I/O
29	I/O	I/O
30	I/O	I/O
31	I/O	I/O
32	GND	GND
33	I/O	I/O
34	I/O	I/O
35	I/O	I/O
36	I/O	I/O
37	I/O	I/O
38	VCCA	VCCA
39	I/O	I/O
40	I/O	I/O
41	I/O	I/O
42	I/O	I/O
43	I/O	I/O
44	GND	GND
45	I/O	I/O
46	I/O	I/O
47	I/O	I/O
48	I/O	I/O
49	I/O	I/O
50	SDO, I/O	SDO, I/O
51	I/O	I/O
52	I/O	I/O
53	I/O	I/O
54	I/O	I/O
55	GND	GND
56	I/O	I/O

Table 56 • VQ100

VQ100		
Pin Number	A42MX09 Function	A42MX16 Function
93	I/O	I/O
94	GND	GND
95	I/O	I/O
96	I/O	I/O
97	I/O	I/O
98	I/O	I/O
99	I/O	I/O
100	DCLK, I/O	DCLK, I/O

Figure 48 • TQ176**Table 57 • TQ176**

TQ176			
Pin Number	A42MX09 Function	A42MX16 Function	A42MX24 Function
1	GND	GND	GND
2	MODE	MODE	MODE
3	I/O	I/O	I/O
4	I/O	I/O	I/O
5	I/O	I/O	I/O
6	I/O	I/O	I/O
7	I/O	I/O	I/O
8	NC	NC	I/O
9	I/O	I/O	I/O

Table 57 • TQ176

TQ176	Pin Number	A42MX09 Function	A42MX16 Function	A42MX24 Function
	121	NC	NC	I/O
	122	I/O	I/O	I/O
	123	I/O	I/O	I/O
	124	NC	I/O	I/O
	125	NC	I/O	I/O
	126	NC	NC	I/O
	127	I/O	I/O	I/O
	128	I/O	I/O	I/O
	129	I/O	I/O	I/O
	130	I/O	I/O	I/O
	131	I/O	I/O	I/O
	132	I/O	I/O	I/O
	133	GND	GND	GND
	134	I/O	I/O	I/O
	135	SDI, I/O	SDI, I/O	SDI, I/O
	136	NC	I/O	I/O
	137	I/O	I/O	WD, I/O
	138	I/O	I/O	WD, I/O
	139	I/O	I/O	I/O
	140	NC	VCCI	VCCI
	141	I/O	I/O	I/O
	142	I/O	I/O	I/O
	143	NC	I/O	I/O
	144	NC	I/O	WD, I/O
	145	NC	NC	WD, I/O
	146	I/O	I/O	I/O
	147	NC	I/O	I/O
	148	I/O	I/O	I/O
	149	I/O	I/O	I/O
	150	I/O	I/O	WD, I/O
	151	NC	I/O	WD, I/O
	152	PRA, I/O	PRA, I/O	PRA, I/O
	153	I/O	I/O	I/O
	154	CLKA, I/O	CLKA, I/O	CLKA, I/O
	155	VCCA	VCCA	VCCA
	156	GND	GND	GND
	157	I/O	I/O	I/O

Table 58 • CQ208

CQ208	
Pin Number	A42MX36 Function
1	GND
2	VCCA
3	MODE
4	I/O
5	I/O
6	I/O
7	I/O
8	I/O
9	I/O
10	I/O
11	I/O
12	I/O
13	I/O
14	I/O
15	I/O
16	I/O
17	VCCA
18	I/O
19	I/O
20	I/O
21	I/O
22	GND
23	I/O
24	I/O
25	I/O
26	I/O
27	GND
28	VCCI
29	VCCA
30	I/O
31	I/O
32	VCCA
33	I/O
34	I/O
35	I/O
36	I/O

Table 60 • BG272

BG272	
Pin Number	A42MX36 Function
C3	GND
C4	I/O
C5	WD, I/O
C6	I/O
C7	QCLKC, I/O
C8	I/O
C9	I/O
C10	CLKB
C11	PRA, I/O
C12	WD, I/O
C13	I/O
C14	QCLKD, I/O
C15	I/O
C16	WD, I/O
C17	SDI, I/O
C18	I/O
C19	I/O
C20	I/O
D1	I/O
D2	I/O
D3	I/O
D4	I/O
D5	VCCI
D6	I/O
D7	I/O
D8	VCCA
D9	WD, I/O
D10	VCCI
D11	I/O
D12	VCCI
D13	I/O
D14	VCCI
D15	I/O
D16	VCCA
D17	GND
D18	I/O
D19	I/O

Table 60 • BG272

BG272	
Pin Number	A42MX36 Function
M10	GND
M11	GND
M12	GND
M17	I/O
M18	I/O
M19	I/O
M20	I/O
N1	I/O
N2	I/O
N3	I/O
N4	VCCI
N17	VCCI
N18	I/O
N19	I/O
N20	I/O
P1	I/O
P2	I/O
P3	I/O
P4	VCCA
P17	I/O
P18	I/O
P19	I/O
P20	I/O
R1	I/O
R2	I/O
R3	I/O
R4	VCCI
R17	VCCI
R18	I/O
R19	I/O
R20	I/O
T1	I/O
T2	I/O
T3	I/O
T4	I/O
T17	VCCA
T18	I/O