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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

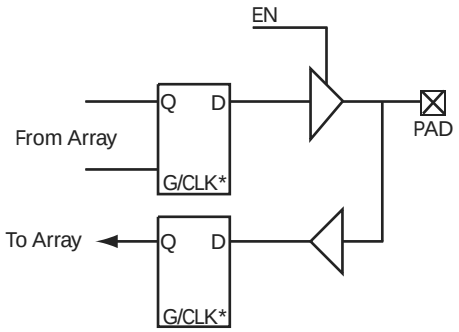
The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	69
Number of Gates	6000
Voltage - Supply	3V ~ 3.6V, 4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	-55°C ~ 125°C (TC)
Package / Case	80-TQFP
Supplier Device Package	80-VQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a40mx04-1vqg80m

Contents

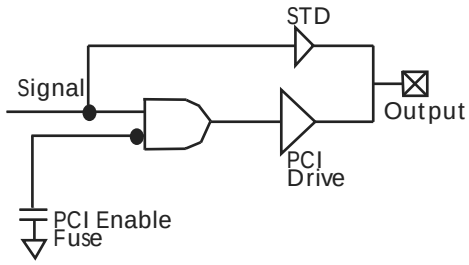
Designer software development tools provide a design library of I/O macro functions that can implement all I/O configurations supported by the MX FPGAs.

Figure 10 • **42MX I/O Module**



Note: **Can be configured as a Latch or D Flip-Flop (Using C-Module)*

Figure 11 • **PCI Output Structure of A42MX24 and A42MX36 Devices**



3.3 Other Architectural Features

The following sections cover other architectural features of 40MX and 42MX FPGAs.

3.3.1 Performance

MX devices can operate with internal clock frequencies of 250 MHz, enabling fast execution of complex logic functions. MX devices are live on power-up and do not require auxiliary configuration devices and thus are an optimal platform to integrate the functionality contained in multiple programmable logic devices. In addition, designs that previously would have required a gate array to meet performance can be integrated into an MX device with improvements in cost and time-to-market. Using timing-driven place-and-route (TDPR) tools, designers can achieve highly deterministic device performance.

3.3.2 User Security

Microsemi FuseLock provides robust security against design theft. Special security fuses are hidden in the fabric of the device and protect against unauthorized users attempting to access the programming and/or probe interfaces. It is virtually impossible to identify or bypass these fuses without damaging the device, making Microsemi antifuse FPGAs protected with the highest level of security available from both invasive and noninvasive attacks.

Special security fuses in 40MX devices include the Probe Fuse and Program Fuse. The former disables the probing circuitry while the latter prohibits further programming of all fuses, including the Probe Fuse. In 42MX devices, there is the Security Fuse which, when programmed, both disables the probing circuitry and prohibits further programming of the device.

3.3.3 Programming

Device programming is supported through the Silicon Sculptor series of programmers. Silicon Sculptor is a compact, robust, single-site and multi-site device programmer for the PC. With standalone software, Silicon Sculptor is designed to allow concurrent programming of multiple units from the same PC.

3. All outputs unloaded. All inputs = VCC/VCCI or GND

3.8 3.3 V Operating Conditions

The following table shows 3.3 V operating conditions.

Table 16 • **Absolute Maximum Ratings for 40MX Devices***

Symbol	Parameter	Limits	Units
VCC	DC Supply Voltage	–0.5 to +7.0	V
VI	Input Voltage	–0.5 to VCC + 0.5	V
VO	Output Voltage	–0.5 to VCC + 0.5	V
t_{STG}	Storage Temperature	–65 to + 150	°C

Note: *Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Devices should not be operated outside the recommended operating conditions.

Table 17 • **Absolute Maximum Ratings for 42MX Devices***

Symbol	Parameter	Limits	Units
VCCI	DC Supply Voltage for I/Os	–0.5 to +7.0	V
VCCA	DC Supply Voltage for Array	–0.5 to +7.0	V
VI	Input Voltage	–0.5 to VCCI+0.5	V
VO	Output Voltage	–0.5 to VCCI+0.5	V
t_{STG}	Storage Temperature	–65 to +150	°C

Note: *Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Devices should not be operated outside the recommended operating conditions.

Table 18 • **Recommended Operating Conditions**

Parameter	Commercial	Industrial	Military	Units
Temperature Range*	0 to +70	–40 to +85	–55 to +125	°C
VCC (40MX)	3.0 to 3.6	3.0 to 3.6	3.0 to 3.6	V
VCCA (42MX)	3.0 to 3.6	3.0 to 3.6	3.0 to 3.6	V
VCCI (42MX)	3.0 to 3.6	3.0 to 3.6	3.0 to 3.6	V

Note: *Ambient temperature (T_A) is used for commercial and industrial grades; case temperature (T_C) is used for military grades.

All the following tables show various specifications and operating conditions of 40MX and 42MX FPGAs.

3.9.3 Output Drive Characteristics for 3.3 V PCI Signaling

Table 25 • **DC Specification (3.3 V PCI Signaling)[1]**

			PCI		MX		
Symbol	**Parameter**	**Condition**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
VCCI	Supply Voltage for I/Os		3.0	3.6	3.0	3.6[2]	V
VIH	Input High Voltage		0.5	VCC + 0.5	0.5	VCCI + 0.3	V
VIL	Input Low Voltage		–0.5	0.8	–0.3	0.8	V
IIH	Input High Leakage Current	VIN = 2.7 V		70		10	µA
IIL	Input Leakage Current			–70		–10	µA
VOH	Output High Voltage	IOUT = –2 mA	0.9		3.3		V
VOL	Output Low Voltage	IOUT = 3 mA, 6 mA		0.1		0.1 VCCI	V
C_{IN}	Input Pin Capacitance			10		10	pF
C_{CLK}	CLK Pin Capacitance		5	12		10	pF
L_{PIN}	Pin Inductance			20		< 8 nH[3]	nH

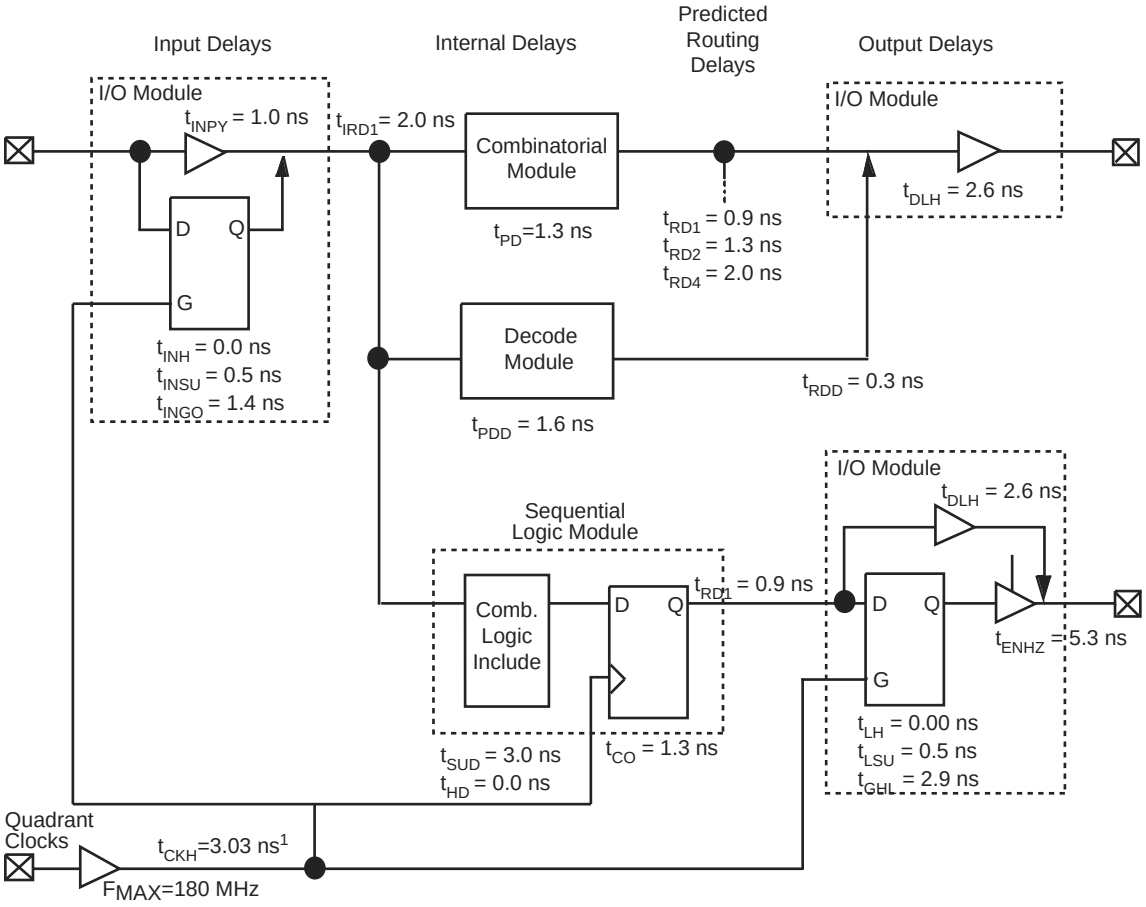
1. PCI Local Bus Specification, Version 2.1, Section 4.2.2.1.
2. Maximum rating for VCCI –0.5 V to 7.0V.
3. Dependent upon the chosen package. PCI recommends QFP and BGA packaging to reduce pin inductance and capacitance.

Table 26 • **AC Specifications for (3.3 V PCI Signaling)***

			PCI		MX		
Symbol	**Parameter**	**Condition**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
ICL	Low Clamp Current	–5 < VIN ≤ –1	–25 + (VIN +1) /0.015		–60	–10	mA
Slew (r)	Output Rise Slew Rate	0.2 V to 0.6 V load	1	4	1.8	2.8	V/ns
Slew (f)	Output Fall Slew Rate	0.6 V to 0.2 V load	1	4	2.8	4.0	V/ns

Note: *PCI Local Bus Specification, Version 2.1, Section 4.2.2.2.

Figure 19 • **42MX Timing Model (Logic Functions Using Quadrant Clocks)**



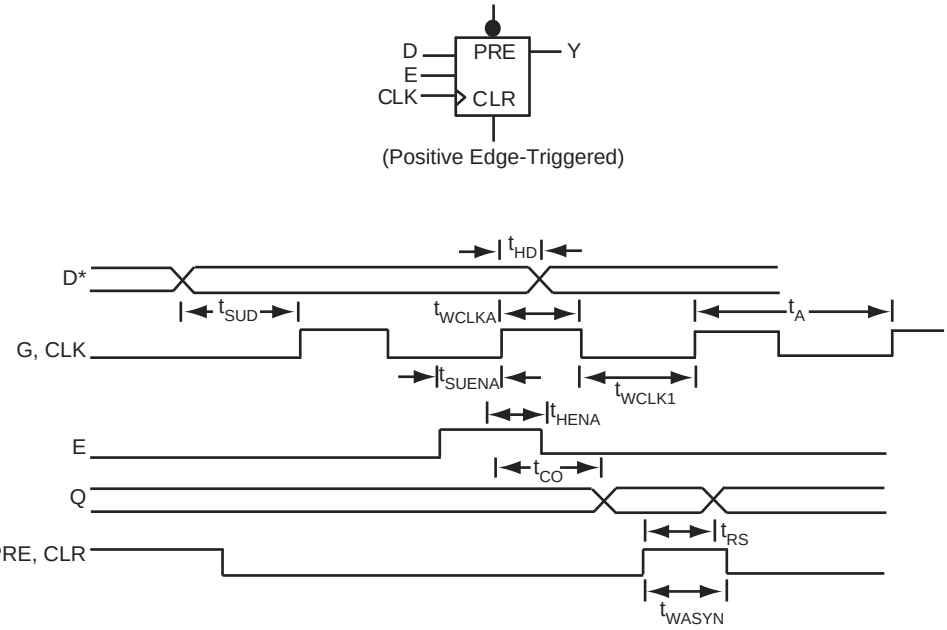
Note: 1. Load-dependent

Note: 2. Values are shown for A42MX36 –3 at 5.0 V worst-case commercial conditions

3.10.2 Sequential Module Timing Characteristics

The following figure shows sequential module timing characteristics.

Figure 25 • **Flip-Flops and Latches**



Note: *D represents all data functions involving A, B, and S for multiplexed flip-flops.

3.10.3 Sequential Timing Characteristics

The following figures show sequential timing characteristics.

Figure 26 • **Input Buffer Latches**

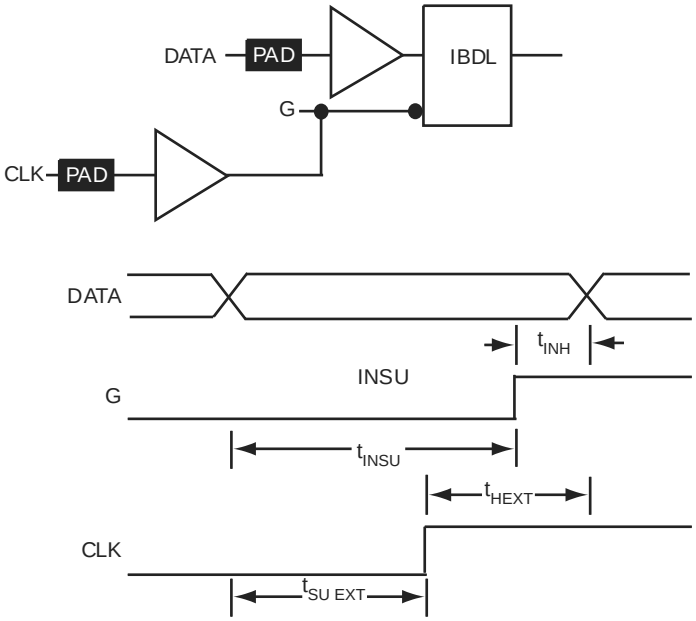


Table 34 • **A40MX02 Timing Characteristics (Nominal 5.0 V Operation) *(continued)***
(Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C)

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing[4]												
t_{DLH}	Data-to-Pad HIGH		3.3		3.8		4.3		5.1		7.2	ns
t_{DHL}	Data-to-Pad LOW		4.0		4.6		5.2		6.1		8.6	ns
t_{ENZH}	Enable Pad Z to HIGH		3.7		4.3		4.9		5.8		8.0	ns
t_{ENZL}	Enable Pad Z to LOW		4.7		5.4		6.1		7.2		10.1	ns
t_{ENHZ}	Enable Pad HIGH to Z		7.9		9.1		10.4		12.2		17.1	ns
t_{ENLZ}	Enable Pad LOW to Z		5.9		6.8		7.7		9.0		12.6	ns
d_{TLH}	Delta LOW to HIGH		0.02		0.02		0.03		0.03		0.04	ns/pF
d_{THL}	Delta HIGH to LOW		0.03		0.03		0.03		0.04		0.06	ns/pF
CMOS Output Module Timing[4]												
t_{DLH}	Data-to-Pad HIGH		3.9		4.5		5.1		6.05		8.5	ns
t_{DHL}	Data-to-Pad LOW		3.4		3.9		4.4		5.2		7.3	ns
t_{ENZH}	Enable Pad Z to HIGH		3.4		3.9		4.4		5.2		7.3	ns
t_{ENZL}	Enable Pad Z to LOW		4.9		5.6		6.4		7.5		10.5	ns
t_{ENHZ}	Enable Pad HIGH to Z		7.9		9.1		10.4		12.2		17.0	ns
t_{ENLZ}	Enable Pad LOW to Z		5.9		6.8		7.7		9.0		12.6	ns
d_{TLH}	Delta LOW to HIGH		0.03		0.04		0.04		0.05		0.07	ns/pF
d_{THL}	Delta HIGH to LOW		0.02		0.02		0.03		0.03		0.04	ns/pF

1. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance
2. Set-up times assume fanout of 3. Further testing information can be obtained from the Timer utility
3. The hold time for the DFME1A macro may be greater than 0 ns. Use the Timer tool from the Designer software to check the hold time for this macro.
4. Delays based on 35pF loading

Table 35 • **A40MX02 Timing Characteristics (Nominal 3.3 V Operation)**
(Worst-Case Commercial Conditions, VCC = 3.0 V, T_J = 70°C)

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays												
t_{PD1}	Single Module		1.7		2.0		2.3		2.7		3.7	ns
t_{PD2}	Dual-Module Macros		3.7		4.3		4.9		5.7		8.0	ns
t_{CO}	Sequential Clock-to-Q		1.7		2.0		2.3		2.7		3.7	ns
t_{GO}	Latch G-to-Q		1.7		2.0		2.3		2.7		3.7	ns
t_{RS}	Flip-Flop (Latch) Reset-to-Q		1.7		2.0		2.3		2.7		3.7	ns
Logic Module Predicted Routing Delays[1]												

Table 35 • **A40MX02 Timing Characteristics (Nominal 3.3 V Operation) *(continued)***
(Worst-Case Commercial Conditions, VCC = 3.0 V, T_J = 70°C)

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing[4]												
t_{DLH}	Data-to-Pad HIGH		5.5		6.4		7.2		8.5		11.9	ns
t_{DHL}	Data-to-Pad LOW		4.8		5.5		6.2		7.3		10.2	ns
t_{ENZH}	Enable Pad Z to HIGH		4.7		5.5		6.2		7.3		10.2	ns
t_{ENZL}	Enable Pad Z to LOW		6.8		7.9		8.9		10.5		14.7	ns
t_{ENHZ}	Enable Pad HIGH to Z		11.1		12.8		14.5		17.1		23.9	ns
t_{ENLZ}	Enable Pad LOW to Z		8.2		9.5		10.7		12.6		17.7	ns
d_{TLH}	Delta LOW to HIGH		0.05		0.05		0.06		0.07		0.10	ns/pF
d_{THL}	Delta HIGH to LOW		0.03		0.03		0.04		0.04		0.06	ns/pF

1. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
2. Set-up times assume fanout of 3. Further testing information can be obtained from the Timer utility.
3. The hold time for the DFME1A macro may be greater than 0 ns. Use the Timer tool from the Designer software to check the hold time for this macro
4. Delays based on 35 pF loading

Table 36 • **A40MX04 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C)**

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays												
t_{PD1}	Single Module		1.2		1.4		1.6		1.9		2.7	ns
t_{PD2}	Dual-Module Macros		2.3		3.1		3.5		4.1		5.7	ns
t_{CO}	Sequential Clock-to-Q		1.2		1.4		1.6		1.9		2.7	ns
t_{GO}	Latch G-to-Q		1.2		1.4		1.6		1.9		2.7	ns
t_{RS}	Flip-Flop (Latch) Reset-to-Q		1.2		1.4		1.6		1.9		2.7	ns
Logic Module Predicted Routing Delays[1]												
t_{RD1}	FO = 1 Routing Delay		1.2		1.6		1.8		2.1		3.0	ns
t_{RD2}	FO = 2 Routing Delay		1.9		2.2		2.5		2.9		4.1	ns
t_{RD3}	FO = 3 Routing Delay		2.4		2.8		3.2		3.7		5.2	ns
t_{RD4}	FO = 4 Routing Delay		2.9		3.4		3.9		4.5		6.3	ns
t_{RD8}	FO = 8 Routing Delay		5.0		5.8		6.6		7.8		10.9	ns
Logic Module Sequential Timing[2]												
t_{SUD}	Flip-Flop (Latch) Data Input Set-Up	3.1		3.5		4.0		4.7		6.6		ns
t_{HD}[3]	Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{SUENA}	Flip-Flop (Latch) Enable Set-Up	3.1		3.5		4.0		4.7		6.6		ns

Table 36 • **A40MX04 Timing Characteristics (Nominal 5.0 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C)**

Parameter / Description			–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{HENA}	Flip-Flop (Latch) Enable Hold		0.0		0.0		0.0		0.0		0.0		ns
t_{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width		3.3		3.8		4.3		5.0		7.0		ns
t_{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width		3.3		3.8		4.3		5.0		7.0		ns
t_A	Flip-Flop Clock Input Period		4.8		5.6		6.3		7.5		10.4		ns
f_{MAX}	Flip-Flop (Latch) Clock Frequency (FO = 128)			181		167		154		134		80	MHz
Input Module Propagation Delays													
t_{INYH}	Pad-to-Y HIGH			0.7		0.8		0.9		1.1		1.5	ns
t_{INYL}	Pad-to-Y LOW			0.6		0.7		0.8		1.0		1.3	ns
Input Module Predicted Routing Delays[1]													
t_{IRD1}	FO = 1 Routing Delay			2.1		2.4		2.2		3.2		4.5	ns
t_{IRD2}	FO = 2 Routing Delay			2.6		3.0		3.4		4.0		5.6	ns
t_{IRD3}	FO = 3 Routing Delay			3.1		3.6		4.1		4.8		6.7	ns
t_{IRD4}	FO = 4 Routing Delay			3.6		4.2		4.8		5.6		7.8	ns
t_{IRD8}	FO = 8 Routing Delay			5.7		6.6		7.5		8.8		12.4	ns
Global Clock Network													
t_{CKH}	Input Low to HIGH	FO = 16 FO = 128		4.6 4.6		5.3 5.3		6.0 6.0		7.0 7.0		9.8 9.8	ns
t_{CKL}	Input High to LOW	FO = 16 FO = 128		4.8 4.8		5.6 5.6		6.3 6.3		7.4 7.4		10.4 10.4	ns
t_{PWH}	Minimum Pulse Width HIGH	FO = 16 FO = 128	2.2 2.4		2.6 2.7		2.9 3.1		3.4 3.6		4.8 5.1		ns
t_{PWL}	Minimum Pulse Width LOW	FO = 16 FO = 128	2.2 2.4		2.6 2.7		2.9 3.01		3.4 3.6		4.8 5.1		ns
t_{CKSW}	Maximum Skew	FO = 16 FO = 128		0.4 0.5		0.5 0.6		0.5 0.7		0.6 0.8		0.8 1.2	ns
t_P	Minimum Period	FO = 16 FO = 128	4.7 4.8		5.4 5.6		6.1 6.3		7.2 7.5		10.0 10.4		ns
f_{MAX}	Maximum Frequency	FO = 16 FO = 128		188 181		175 168		160 154		139 134		83 80	MHz
TTL Output Module Timing[4]													
t_{DLH}	Data-to-Pad HIGH			3.3		3.8		4.3		5.1		7.2	ns
t_{DHL}	Data-to-Pad LOW			4.0		4.6		5.2		6.1		8.6	ns
t_{ENZH}	Enable Pad Z to HIGH			3.7		4.3		4.9		5.8		8.0	ns
t_{ENZL}	Enable Pad Z to LOW			4.7		5.4		6.1		7.2		10.1	ns
t_{ENHZ}	Enable Pad HIGH to Z			7.9		9.1		10.4		12.2		17.1	ns

Table 36 • **A40MX04 Timing Characteristics (Nominal 5.0 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C)**

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing[1]												
t_{DLH}	Data-to-Pad HIGH		3.9		4.5		5.1		6.05		8.5	ns
t_{DHL}	Data-to-Pad LOW		3.4		3.9		4.4		5.2		7.3	ns
t_{ENZH}	Enable Pad Z to HIGH		3.4		3.9		4.4		5.2		7.3	ns
t_{ENZL}	Enable Pad Z to LOW		4.9		5.6		6.4		7.5		10.5	ns
t_{ENHZ}	Enable Pad HIGH to Z		7.9		9.1		10.4		12.2		17.0	ns
t_{ENLZ}	Enable Pad LOW to Z		5.9		6.8		7.7		9.0		12.6	ns
d_{TLH}	Delta LOW to HIGH		0.03		0.04		0.04		0.05		0.07	ns/pF
d_{THL}	Delta HIGH to LOW		0.02		0.02		0.03		0.03		0.04	ns/pF

1. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.*
2. Set-up times assume fanout of 3. Further testing information can be obtained from the Timer utility
3. The hold time for the DFME1A macro may be greater than 0 ns. Use the Timer utility from the Designer software to check the hold time for this macro.
4. Delays based on 35 pF loading

Table 37 • **A40MX04 Timing Characteristics (Nominal 3.3 V Operation) (Worst-Case Commercial Conditions, VCC = 3.0 V, T_J = 70°C)**

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays												
t_{PD1}	Single Module		1.7		2.0		2.3		2.7		3.7	ns
t_{PD2}	Dual-Module Macros		3.7		4.3		4.9		5.7		8.0	ns
t_{CO}	Sequential Clock-to-Q		1.7		2.0		2.3		2.7		3.7	ns
t_{GO}	Latch G-to-Q		1.7		2.0		2.3		2.7		3.7	ns
t_{RS}	Flip-Flop (Latch) Reset-to-Q		1.7		2.0		2.3		2.7		3.7	ns
Logic Module Predicted Routing Delays[1]												
t_{RD1}	FO = 1 Routing Delay		1.9		2.2		2.5		3.0		4.2	ns
t_{RD2}	FO = 2 Routing Delay		2.7		3.1		3.5		4.1		5.7	ns
t_{RD3}	FO = 3 Routing Delay		3.4		3.9		4.4		5.2		7.3	ns
t_{RD4}	FO = 4 Routing Delay		4.1		4.8		5.4		6.3		8.9	ns
t_{RD8}	FO = 8 Routing Delay		7.1		8.1		9.2		10.9		15.2	ns
Logic Module Sequential Timing[2]												
t_{SUD}	Flip-Flop (Latch) Data Input Set-Up	4.3		5.0		5.6		6.6		9.2		ns
t_{HD}[3]	Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{SUENA}	Flip-Flop (Latch) Enable Set-Up	4.3		5.0		5.6		6.6		9.2		ns
t_{HENA}	Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		0.0		0.0		ns

Table 42 • **A42MX24 Timing Characteristics (Nominal 5.0 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)**

Parameter / Description			–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Input Module Predicted Routing Delays[2]													
t_{IRD1}	FO = 1 Routing Delay			1.8		2.0		2.3		2.7		3.8	ns
t_{IRD2}	FO = 2 Routing Delay			2.1		2.3		2.6		3.1		4.3	ns
t_{IRD3}	FO = 3 Routing Delay			2.3		2.5		2.9		3.4		4.8	ns
t_{IRD4}	FO = 4 Routing Delay			2.5		2.8		3.2		3.7		5.2	ns
t_{IRD8}	FO = 8 Routing Delay			3.4		3.8		4.3		5.1		7.1	ns
Global Clock Network													
t_{CKH}	Input LOW to HIGH	FO = 32		2.6		2.9		3.3		3.9		5.4	ns
		FO = 486		2.9		3.2		3.6		4.3		5.9	ns
t_{CKL}	Input HIGH to LOW	FO = 32		3.7		4.1		4.6		5.4		7.6	ns
		FO = 486		4.3		4.7		5.4		6.3		8.8	ns
t_{PWH}	Minimum Pulse Width HIGH	FO = 32	2.2		2.4		2.7		3.2		4.5		ns
		FO = 486	2.4		2.6		3.0		3.5		4.9		ns
t_{PWL}	Minimum Pulse Width LOW	FO = 32	2.2		2.4		2.7		3.2		4.5		ns
		FO = 486	2.4		2.6		3.0		3.5		4.9		ns
t_{CKSW}	Maximum Skew	FO = 32		0.5		0.6		0.7		0.8		1.1	ns
		FO = 486		0.5		0.6		0.7		0.8		1.1	ns
t_{SUEXT}	Input Latch External Set-Up	FO = 32	0.0		0.0		0.0		0.0		0.0		ns
		FO = 486	0.0		0.0		0.0		0.0		0.0		ns
t_{HEXT}	Input Latch External Hold	FO = 32	2.8		3.1		3.5		4.1		5.7		ns
		FO = 486	3.3		3.7		4.2		4.9		6.9		ns
t_P	Minimum Period ($1/f_{MAX}$)	FO = 32	4.7		5.2		5.7		6.5		10.9		ns
		FO = 486	5.1		5.7		6.2		7.1		11.9		ns

Table 43 • **A42MX24 Timing Characteristics (Nominal 3.3 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)**

Parameter / Description			–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing[5] (continued)													
t_{LH}	I/O Latch Output Hold		0.0		0.0		0.0		0.0		0.0		ns
t_{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O			7.7		8.5		9.6		11.3		15.9	ns
t_{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O			14.8		16.5		18.7		22.0		30.8	ns
d_{TLH}	Capacitive Loading, LOW to HIGH			0.05		0.05		0.06		0.07		0.10	ns/pF
d_{THL}	Capacitive Loading, HIGH to LOW			0.04		0.04		0.05		0.06		0.08	ns/pF
CMOS Output Module Timing[5]													
t_{DLH}	Data-to-Pad HIGH			4.8		5.3		5.5		6.4		9.0	ns
t_{DHL}	Data-to-Pad LOW			3.5		3.9		4.1		4.9		6.8	ns
t_{ENZH}	Enable Pad Z to HIGH			3.6		4.0		4.5		5.3		7.4	ns
t_{ENZL}	Enable Pad Z to LOW			3.4		4.0		5.0		5.8		8.2	ns
t_{ENHZ}	Enable Pad HIGH to Z			7.2		8.0		9.0		10.7		14.9	ns
t_{ENLZ}	Enable Pad LOW to Z			6.7		7.5		8.5		9.9		13.9	ns
t_{GLH}	G-to-Pad HIGH			6.8		7.6		8.6		10.1		14.2	ns
t_{GHL}	G-to-Pad LOW			6.8		7.6		8.6		10.1		14.2	ns
t_{LSU}	I/O Latch Set-Up		0.7		0.7		0.8		1.0		1.4		ns
t_{LH}	I/O Latch Hold		0.0		0.0		0.0		0.0		0.0		ns
t_{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O			7.7		8.5		9.6		11.3		15.9	ns
t_{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O			14.8		16.5		18.7		22.0		30.8	ns
d_{TLH}	Capacitive Loading, LOW to HIGH			0.05		0.05		0.06		0.07		0.10	ns/pF
d_{THL}	Capacitive Loading, HIGH to LOW			0.04		0.04		0.05		0.06		0.08	ns/pF
t_{HEXT}	Input Latch External Hold	FO = 32	3.9		4.3		4.9		5.7		8.1		ns
		FO = 486	4.6		5.2		5.8		6.9		9.6		ns
t_P	Minimum Period ($1/f_{MAX}$)	FO = 32	7.8		8.7		9.5		10.8		18.2		ns
		FO = 486	8.6		9.5		10.4		11.9		19.9		ns

1. For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
4. Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
5. Delays based on 35 pF loading.

Table 44 • **A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)**

		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
Parameter / Description		**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
CMOS Output Module Timing[5]												
t_{DLH}	Data-to-Pad HIGH		3.5		3.9		4.5		5.2		7.3	ns
t_{DHL}	Data-to-Pad LOW		2.5		2.7		3.1		3.6		5.1	ns
t_{ENZH}	Enable Pad Z to HIGH		2.7		3.0		3.3		3.9		5.5	ns
t_{ENZL}	Enable Pad Z to LOW		2.9		3.3		3.7		4.3		6.1	ns
t_{ENHZ}	Enable Pad HIGH to Z		5.3		5.8		6.6		7.8		10.9	ns
t_{ENLZ}	Enable Pad LOW to Z		4.9		5.5		6.2		7.3		10.2	ns
t_{GLH}	G-to-Pad HIGH		5.0		5.6		6.3		7.5		10.4	ns
t_{GHL}	G-to-Pad LOW		5.0		5.6		6.3		7.5		10.4	ns
t_{LSU}	I/O Latch Set-Up	0.5		0.5		0.6		0.7		1.0		ns
t_{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		5.7		6.3		7.1		8.4		11.8	ns
t_{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.8		8.6		9.8		11.5		16.1	ns
d_{TLH}	Capacitive Loading, LOW to HIGH		0.07		0.08		0.09		0.10		0.14	ns/pF
d_{THL}	Capacitive Loading, HIGH to LOW		0.07		0.08		0.09		0.10		0.14	ns/pF

1. For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
4. Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
5. Delays based on 35 pF loading.

Table 45 • **A42MX36 Timing Characteristics (Nominal 3.3 V Operation) (Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)**

		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
Parameter / Description		**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
Logic Module Combinatorial Functions[1]												
t_{PD}	Internal Array Module Delay		1.9		2.1		2.3		2.7		3.8	ns
t_{PDD}	Internal Decode Module Delay		2.2		2.5		2.8		3.3		4.7	ns
Logic Module Predicted Routing Delays[2]												
t_{RD1}	FO = 1 Routing Delay		1.3		1.5		1.7		2.0		2.7	ns
t_{RD2}	FO = 2 Routing Delay		1.8		2.0		2.3		2.7		3.7	ns
t_{RD3}	FO = 3 Routing Delay		2.3		2.5		2.8		3.4		4.7	ns
t_{RD4}	FO = 4 Routing Delay		2.8		3.1		3.5		4.1		5.7	ns

Table 49 • **PL84**

PL84				
Pin Number	**A40MX04 Function**	**A42MX09 Function**	**A42MX16 Function**	**A42MX24 Function**
10	I/O	DCLK, I/O	DCLK, I/O	DCLK, I/O
11	I/O	I/O	I/O	I/O
12	NC	MODE	MODE	MODE
13	I/O	I/O	I/O	I/O
14	I/O	I/O	I/O	I/O
15	I/O	I/O	I/O	I/O
16	I/O	I/O	I/O	I/O
17	I/O	I/O	I/O	I/O
18	GND	I/O	I/O	I/O
19	GND	I/O	I/O	I/O
20	I/O	I/O	I/O	I/O
21	I/O	I/O	I/O	I/O
22	I/O	VCCA	VCCI	VCCI
23	I/O	VCCI	VCCA	VCCA
24	I/O	I/O	I/O	I/O
25	VCC	I/O	I/O	I/O
26	VCC	I/O	I/O	I/O
27	I/O	I/O	I/O	I/O
28	I/O	GND	GND	GND
29	I/O	I/O	I/O	I/O
30	I/O	I/O	I/O	I/O
31	I/O	I/O	I/O	I/O
32	I/O	I/O	I/O	I/O
33	VCC	I/O	I/O	I/O
34	I/O	I/O	I/O	TMS, I/O
35	I/O	I/O	I/O	TDI, I/O
36	I/O	I/O	I/O	WD, I/O
37	I/O	I/O	I/O	I/O
38	I/O	I/O	I/O	WD, I/O
39	I/O	I/O	I/O	WD, I/O
40	GND	I/O	I/O	I/O
41	I/O	I/O	I/O	I/O
42	I/O	I/O	I/O	I/O
43	I/O	VCCA	VCCA	VCCA
44	I/O	I/O	I/O	WD, I/O
45	I/O	I/O	I/O	WD, I/O
46	VCC	I/O	I/O	WD, I/O

Table 54 • **PQ240**

PQ240	
Pin Number	**A42MX36 Function**
163	WD, I/O
164	WD, I/O
165	I/O
166	QCLKA, I/O
167	I/O
168	I/O
169	I/O
170	I/O
171	I/O
172	VCCI
173	I/O
174	WD, I/O
175	WD, I/O
176	I/O
177	I/O
178	TDI, I/O
179	TMS, I/O
180	GND
181	VCCA
182	GND
183	I/O
184	I/O
185	I/O
186	I/O
187	I/O
188	I/O
189	I/O
190	I/O
191	I/O
192	VCCI
193	I/O
194	I/O
195	I/O
196	I/O
197	I/O
198	I/O
199	I/O

Table 58 • **CQ208**

CQ208	
Pin Number	**A42MX36 Function**
1	GND
2	VCCA
3	MODE
4	I/O
5	I/O
6	I/O
7	I/O
8	I/O
9	I/O
10	I/O
11	I/O
12	I/O
13	I/O
14	I/O
15	I/O
16	I/O
17	VCCA
18	I/O
19	I/O
20	I/O
21	I/O
22	GND
23	I/O
24	I/O
25	I/O
26	I/O
27	GND
28	VCCI
29	VCCA
30	I/O
31	I/O
32	VCCA
33	I/O
34	I/O
35	I/O
36	I/O

Table 58 • **CQ208**

CQ208	
Pin Number	**A42MX36 Function**
148	I/O
149	I/O
150	GND
151	I/O
152	I/O
153	I/O
154	I/O
155	I/O
156	I/O
157	GND
158	I/O
159	SDI, I/O
160	I/O
161	WD, I/O
162	WD, I/O
163	I/O
164	VCCI
165	I/O
166	I/O
167	I/O
168	WD, I/O
169	WD, I/O
170	I/O
171	QCLKD, I/O
172	I/O
173	I/O
174	I/O
175	I/O
176	WD, I/O
177	WD, I/O
178	PRA, I/O
179	I/O
180	CLKA, I/O
181	I/O
182	VCCI
183	VCCA
184	GND

Table 60 • **BG272**

BG272	
Pin Number	**A42MX36 Function**
V16	I/O
V17	I/O
V18	SDO, TDO, I/O
V19	I/O
V20	I/O
W1	GND
W2	GND
W3	I/O
W4	TMS, I/O
W5	I/O
W6	I/O
W7	I/O
W8	WD, I/O
W9	WD, I/O
W10	I/O
W11	I/O
W12	I/O
W13	WD, I/O
W14	I/O
W15	I/O
W16	WD, I/O
W17	I/O
W18	WD, I/O
W19	GND
W20	GND
Y1	GND
Y2	GND
Y3	I/O
Y4	TDI, I/O
Y5	WD, I/O
Y6	I/O
Y7	QCLKA, I/O
Y8	I/O
Y9	I/O
Y10	I/O
Y11	I/O
Y12	I/O

Table 62 • **CQ172**

60	I/O
61	I/O
62	I/O
63	I/O
64	I/O
65	GND
66	VCC
67	I/O
68	I/O
69	I/O
70	I/O
71	I/O
72	I/O
73	I/O
74	I/O
75	GND
76	I/O
77	I/O
78	I/O
79	I/O
80	VCCI
81	I/O
82	I/O
83	I/O
84	I/O
85	SDO
86	I/O
87	I/O
88	I/O
89	I/O
90	I/O
91	I/O
92	I/O
93	I/O
94	I/O
95	I/O
96	I/O
97	I/O
98	GND