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#### Understanding **Embedded - FPGAs (Field Programmable Gate Array)**

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

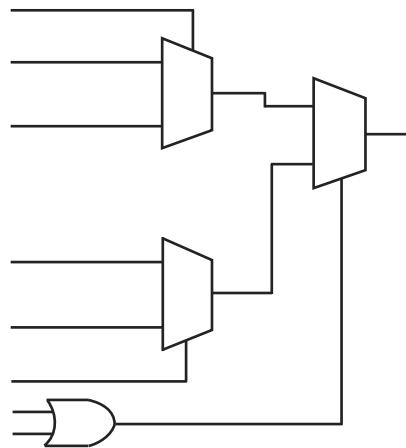
#### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

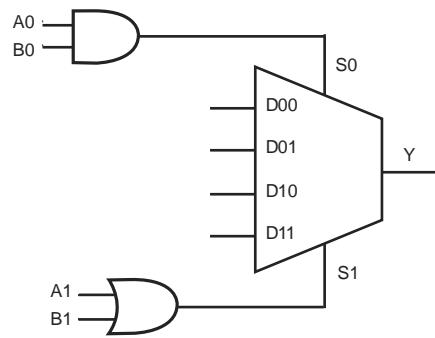
##### **Details**

Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	34
Number of Gates	6000
Voltage - Supply	3V ~ 3.6V, 4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	44-LCC (J-Lead)
Supplier Device Package	44-PLCC (16.59x16.59)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/a40mx04-3pl44">https://www.e-xfl.com/product-detail/microchip-technology/a40mx04-3pl44</a>

Figure 51	BG272 .....	145
Figure 52	PG132 .....	153
Figure 53	CQ172 .....	158

**Figure 2 • 42MX C-Module Implementation**

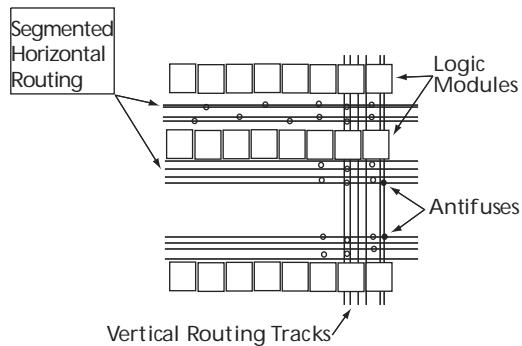
The 42MX devices contain three types of logic modules: combinatorial (C-modules), sequential (S-modules) and decode (D-modules). The following figure illustrates the combinatorial logic module. The S-module, shown in Figure 4, page 8, implements the same combinatorial logic function as the C-module while adding a sequential element. The sequential element can be configured as either a D-flip-flop or a transparent latch. The S-module register can be bypassed so that it implements purely combinatorial logic.

**Figure 3 • 42MX C-Module Implementation**

### 3.2.3.3 Antifuse Structures

An antifuse is a “normally open” structure. The use of antifuses to implement a programmable logic device results in highly testable structures as well as efficient programming algorithms. There are no pre-existing connections; temporary connections can be made using pass transistors. These temporary connections can isolate individual antifuses to be programmed and individual circuit structures to be tested, which can be done before and after programming. For instance, all metal tracks can be tested for continuity and shorts between adjacent tracks, and the functionality of all logic modules can be verified.

**Figure 7 • MX Routing Structure**



### 3.2.4 Clock Networks

The 40MX devices have one global clock distribution network (CLK). A signal can be put on the CLK network by being routed through the CLKBUF buffer.

In 42MX devices, there are two low-skew, high-fanout clock distribution networks, referred to as CLKA and CLKB. Each network has a clock module (CLKMOD) that can select the source of the clock signal from any of the following (Figure 8, page 11):

- Externally from the CLKA pad, using CLKBUF buffer
- Externally from the CLKB pad, using CLKBUF buffer
- Internally from the CLKINTA input, using CLKINT buffer
- Internally from the CLKINTB input, using CLKINT buffer

The clock modules are located in the top row of I/O modules. Clock drivers and a dedicated horizontal clock track are located in each horizontal routing channel.

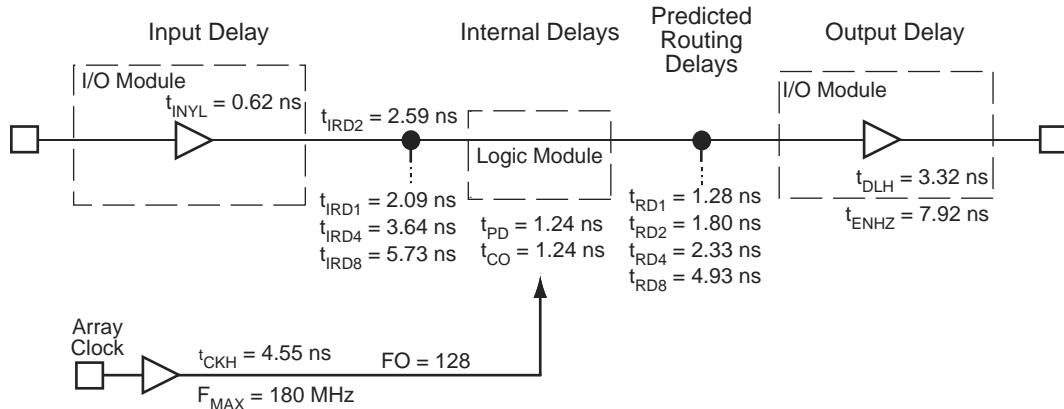
Clock input pads in both 40MX and 42MX devices can also be used as normal I/Os, bypassing the clock networks.

The A42MX36 device has four additional register control resources, called quadrant clock networks (Figure 9, page 11). Each quadrant clock provides a local, high-fanout resource to the contiguous logic modules within its quadrant of the device. Quadrant clock signals can originate from specific I/O pins or from the internal array and can be used as a secondary register clock, register clear, or output enable.

### 3.10 Timing Models

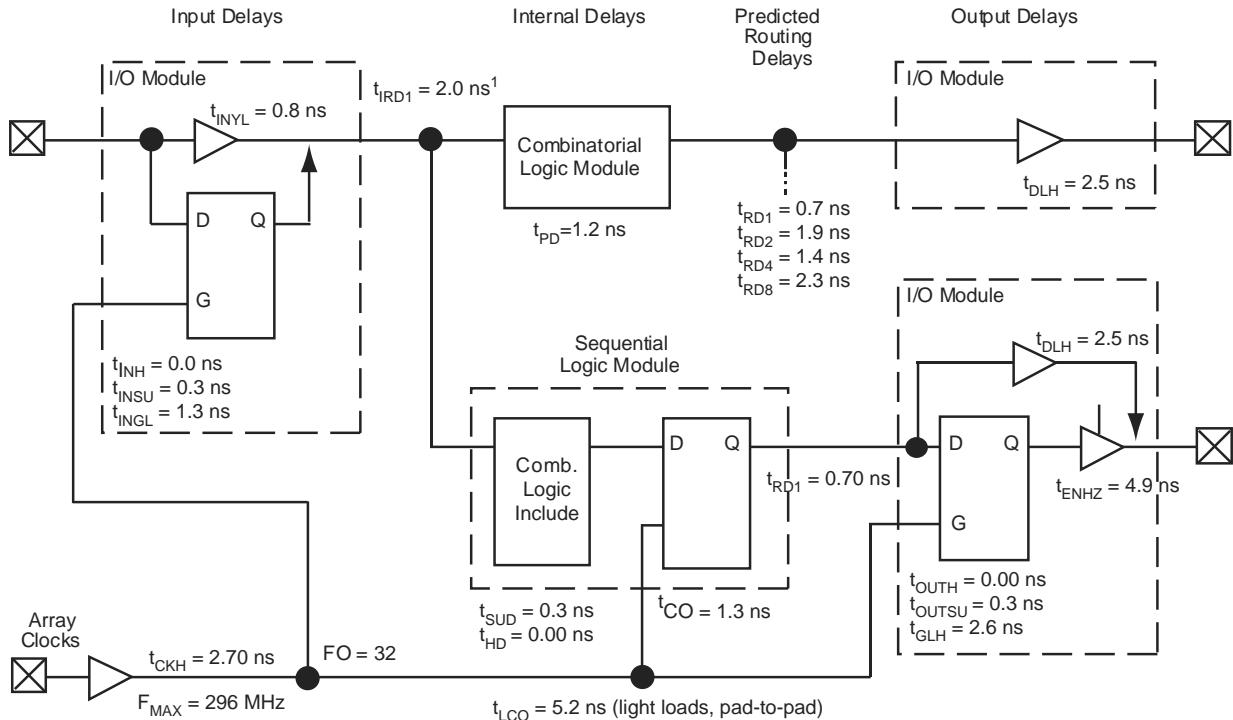
The following figures show various timing models.

**Figure 17 • 40MX Timing Model\***



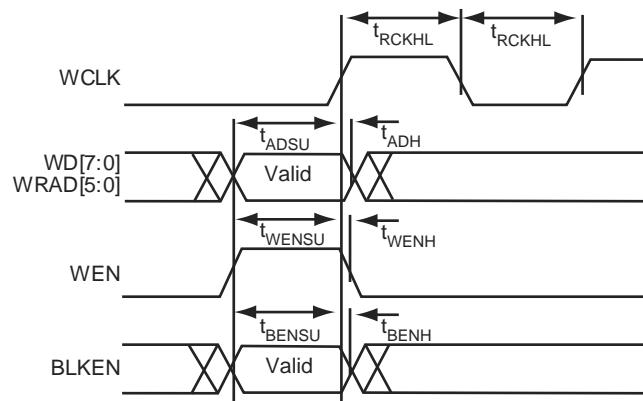
**Note:** Values are shown for 40MX –3 speed devices at 5.0 V worst-case commercial conditions.

**Figure 18 • 42MX Timing Model**

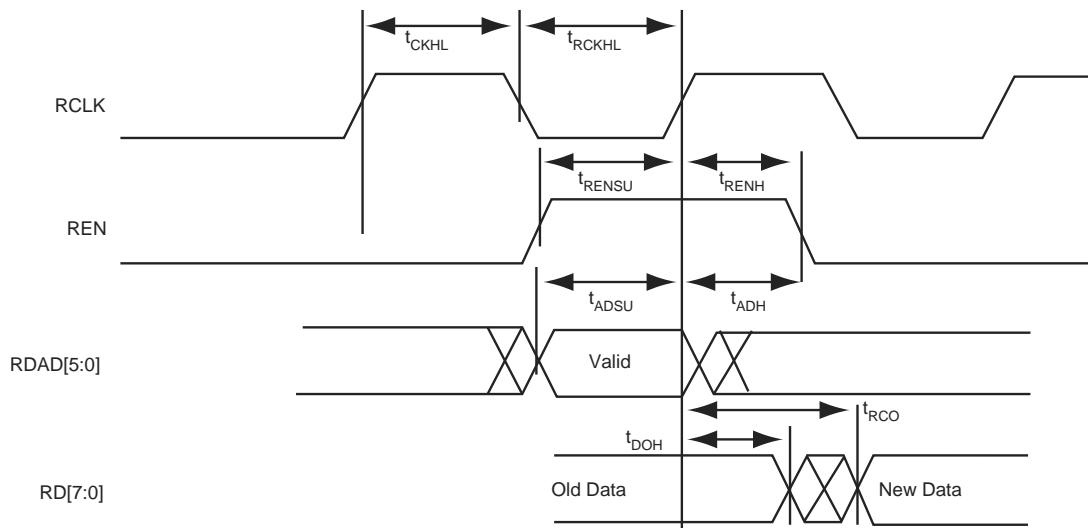


**Note:** 1. Input module predicted routing delay

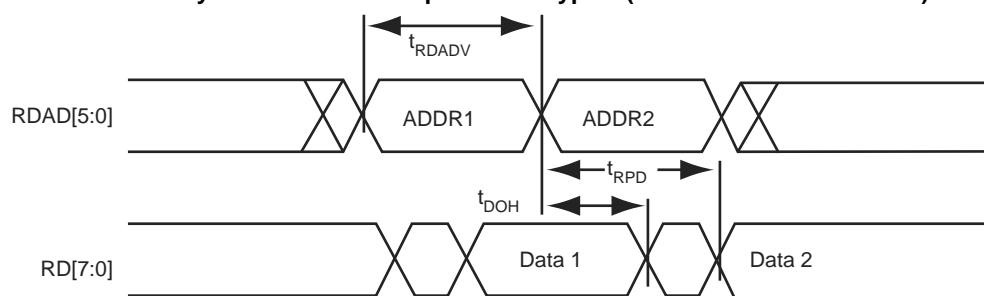
**Note:** 2. Values are shown for A42MX09 –3 at 5.0 V worst-case commercial conditions.

**Figure 30 • 42MX SRAM Write Operation**

**Note:** Identical timing for falling edge clock

**Figure 31 • 42MX SRAM Synchronous Read Operation**

**Note:** Identical timing for falling edge clock

**Figure 32 • 42MX SRAM Asynchronous Read Operation—Type 1 (Read Address Controlled)**

**Table 33 • Timing Parameters for 33 MHz PCI**

Symbol	Parameter	PCI		A42MX24		A42MX36		Units
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{SU(PTP)}$	Input Set-Up Time to CLK—Point-to-Point	10, 12 <sup>2</sup>	–	1.5	–	1.5	–	ns
$t_H$	Input Hold to CLK	0	–	0	–	0	–	ns

1. TOFF is system dependent. MX PCI devices have 7.4 ns turn-off time, reflection is typically an additional 10 ns.  
 2. REQ# and GNT# are point-to-point signals and have different output valid delay and input setup times than do bussed signals. GNT# has a setup of 10; REW# has a setup of 12.

### 3.11.6.1 Timing Characteristics

The following tables list the timing characteristics.

**Table 34 • A40MX02 Timing Characteristics (Nominal 5.0 V Operation)  
(Worst-Case Commercial Conditions, VCC = 4.75 V, T<sub>J</sub> = 70°C)**

Parameter / Description	–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
<b>Logic Module Propagation Delays</b>											
$t_{PD1}$	Single Module	1.2	1.4	1.6	1.9	2.7	ns				
$t_{PD2}$	Dual-Module Macros	2.7	3.1	3.5	4.1	5.7	ns				
$t_{CO}$	Sequential Clock-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
$t_{GO}$	Latch G-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
$t_{RS}$	Flip-Flop (Latch) Reset-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
<b>Logic Module Predicted Routing Delays<sup>1</sup></b>											
$t_{RD1}$	FO = 1 Routing Delay	1.3	1.5	1.7	2.0	2.8	ns				
$t_{RD2}$	FO = 2 Routing Delay	1.8	2.1	2.4	2.8	3.9	ns				
$t_{RD3}$	FO = 3 Routing Delay	2.3	2.7	3.0	3.6	5.0	ns				
$t_{RD4}$	FO = 4 Routing Delay	2.9	3.3	3.7	4.4	6.1	ns				
$t_{RD8}$	FO = 8 Routing Delay	4.9	5.7	6.5	7.6	10.6	ns				
<b>Logic Module Sequential Timing<sup>2</sup></b>											
$t_{SUD}$	Flip-Flop (Latch) Data Input Set-Up	3.1	3.5	4.0	4.7	6.6	ns				
$t_{HD}^3$	Flip-Flop (Latch) Data Input Hold	0.0	0.0	0.0	0.0	0.0	ns				
$t_{SUENA}$	Flip-Flop (Latch) Enable Set-Up	3.1	3.5	4.0	4.7	6.6	ns				
$t_{HEN}$	Flip-Flop (Latch) Enable Hold	0.0	0.0	0.0	0.0	0.0	ns				
$t_{WCLKA}$	Flip-Flop (Latch) Clock Active Pulse Width	3.3	3.8	4.3	5.0	7.0	ns				
$t_{WASYN}$	Flip-Flop (Latch) Asynchronous Pulse Width	3.3	3.8	4.3	5.0	7.0	ns				
$t_A$	Flip-Flop Clock Input Period	4.8	5.6	6.3	7.5	10.4	ns				
$f_{MAX}$	Flip-Flop (Latch) Clock Frequency (FO = 128)	181	168	154	134	80	MHz				

**Table 35 • A40MX02 Timing Characteristics (Nominal 3.3 V Operation) (continued)**  
**(Worst-Case Commercial Conditions, VCC = 3.0 V, TJ = 70°C)**

<b>Parameter / Description</b>	<b>-3 Speed</b>		<b>-2 Speed</b>		<b>-1 Speed</b>		<b>Std Speed</b>		<b>-F Speed</b>		<b>Units</b>
	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	
<b>CMOS Output Module Timing<sup>4</sup></b>											
t <sub>DH</sub>	Data-to-Pad HIGH	5.5	6.4	7.2	8.5	11.9	ns				
t <sub>DHL</sub>	Data-to-Pad LOW	4.8	5.5	6.2	7.3	10.2	ns				
t <sub>ENZH</sub>	Enable Pad Z to HIGH	4.7	5.5	6.2	7.3	10.2	ns				
t <sub>ENZL</sub>	Enable Pad Z to LOW	6.8	7.9	8.9	10.5	14.7	ns				
t <sub>ENHZ</sub>	Enable Pad HIGH to Z	11.1	12.8	14.5	17.1	23.9	ns				
t <sub>ENLZ</sub>	Enable Pad LOW to Z	8.2	9.5	10.7	12.6	17.7	ns				
d <sub>TLH</sub>	Delta LOW to HIGH	0.05	0.05	0.06	0.07	0.10	ns/pF				
d <sub>THL</sub>	Delta HIGH to LOW	0.03	0.03	0.04	0.04	0.06	ns/pF				

1. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
2. Set-up times assume fanout of 3. Further testing information can be obtained from the Timer utility.
3. The hold time for the DFME1A macro may be greater than 0 ns. Use the Timer tool from the Designer software to check the hold time for this macro
4. Delays based on 35 pF loading

**Table 36 • A40MX04 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCC = 4.75 V, TJ = 70°C)**

<b>Parameter / Description</b>	<b>-3 Speed</b>		<b>-2 Speed</b>		<b>-1 Speed</b>		<b>Std Speed</b>		<b>-F Speed</b>		<b>Units</b>
	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	
<b>Logic Module Propagation Delays</b>											
t <sub>PD1</sub>	Single Module	1.2	1.4	1.6	1.9	2.7	ns				
t <sub>PD2</sub>	Dual-Module Macros	2.3	3.1	3.5	4.1	5.7	ns				
t <sub>CO</sub>	Sequential Clock-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
t <sub>GO</sub>	Latch G-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
t <sub>RS</sub>	Flip-Flop (Latch) Reset-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
<b>Logic Module Predicted Routing Delays<sup>1</sup></b>											
t <sub>RD1</sub>	FO = 1 Routing Delay	1.2	1.6	1.8	2.1	3.0	ns				
t <sub>RD2</sub>	FO = 2 Routing Delay	1.9	2.2	2.5	2.9	4.1	ns				
t <sub>RD3</sub>	FO = 3 Routing Delay	2.4	2.8	3.2	3.7	5.2	ns				
t <sub>RD4</sub>	FO = 4 Routing Delay	2.9	3.4	3.9	4.5	6.3	ns				
t <sub>RD8</sub>	FO = 8 Routing Delay	5.0	5.8	6.6	7.8	10.9	ns				
<b>Logic Module Sequential Timing<sup>2</sup></b>											
t <sub>SUD</sub>	Flip-Flop (Latch) Data Input Set-Up	3.1	3.5	4.0	4.7	6.6	ns				
t <sub>HD<sup>3</sup></sub>	Flip-Flop (Latch) Data Input Hold	0.0	0.0	0.0	0.0	0.0	ns				
t <sub>SUENA</sub>	Flip-Flop (Latch) Enable Set-Up	3.1	3.5	4.0	4.7	6.6	ns				

**Table 36 • A40MX04 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCC = 4.75 V, TJ = 70°C)**

		-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		
Parameter / Description		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Units
t <sub>HENA</sub>	Flip-Flop (Latch) Enable Hold	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	ns	
t <sub>WCLKA</sub>	Flip-Flop (Latch) Clock Active Pulse Width	3.3	3.8	4.3	5.0	5.0	7.0	7.0	7.0	7.0	ns	
t <sub>WASYN</sub>	Flip-Flop (Latch) Asynchronous Pulse Width	3.3	3.8	4.3	5.0	5.0	7.0	7.0	7.0	7.0	ns	
t <sub>A</sub>	Flip-Flop Clock Input Period	4.8	5.6	6.3	7.5	7.5	10.4	10.4	10.4	10.4	ns	
f <sub>MAX</sub>	Flip-Flop (Latch) Clock Frequency (FO = 128)		181	167	154	134	80	80	80	80	MHz	
<b>Input Module Propagation Delays</b>												
t <sub>INYH</sub>	Pad-to-Y HIGH		0.7	0.8	0.9	1.1	1.5	1.5	1.5	1.5	ns	
t <sub>INYL</sub>	Pad-to-Y LOW		0.6	0.7	0.8	1.0	1.3	1.3	1.3	1.3	ns	
<b>Input Module Predicted Routing Delays<sup>1</sup></b>												
t <sub>IRD1</sub>	FO = 1 Routing Delay		2.1	2.4	2.2	3.2	4.5	4.5	4.5	4.5	ns	
t <sub>IRD2</sub>	FO = 2 Routing Delay		2.6	3.0	3.4	4.0	5.6	5.6	5.6	5.6	ns	
t <sub>IRD3</sub>	FO = 3 Routing Delay		3.1	3.6	4.1	4.8	6.7	6.7	6.7	6.7	ns	
t <sub>IRD4</sub>	FO = 4 Routing Delay		3.6	4.2	4.8	5.6	7.8	7.8	7.8	7.8	ns	
t <sub>IRD8</sub>	FO = 8 Routing Delay		5.7	6.6	7.5	8.8	12.4	12.4	12.4	12.4	ns	
<b>Global Clock Network</b>												
t <sub>CKH</sub>	Input Low to HIGH	FO = 16	4.6	5.3	6.0	7.0	9.8	9.8	9.8	9.8	ns	
		FO = 128	4.6	5.3	6.0	7.0	9.8	9.8	9.8	9.8	ns	
t <sub>CKL</sub>	Input High to LOW	FO = 16	4.8	5.6	6.3	7.4	10.4	10.4	10.4	10.4	ns	
		FO = 128	4.8	5.6	6.3	7.4	10.4	10.4	10.4	10.4	ns	
t <sub>PWH</sub>	Minimum Pulse Width HIGH	FO = 16	2.2	2.6	2.9	3.4	4.8	4.8	4.8	4.8	ns	
		FO = 128	2.4	2.7	3.1	3.6	5.1	5.1	5.1	5.1	ns	
t <sub>PWL</sub>	Minimum Pulse Width LOW	FO = 16	2.2	2.6	2.9	3.4	4.8	4.8	4.8	4.8	ns	
		FO = 128	2.4	2.7	3.01	3.6	5.1	5.1	5.1	5.1	ns	
t <sub>CKSW</sub>	Maximum Skew	FO = 16	0.4	0.5	0.5	0.6	0.8	0.8	0.8	0.8	ns	
		FO = 128	0.5	0.6	0.7	0.8	1.2	1.2	1.2	1.2	ns	
t <sub>P</sub>	Minimum Period	FO = 16	4.7	5.4	6.1	7.2	10.0	10.0	10.0	10.0	ns	
		FO = 128	4.8	5.6	6.3	7.5	10.4	10.4	10.4	10.4	ns	
f <sub>MAX</sub>	Maximum Frequency	FO = 16	188	175	160	139	83	83	83	83	MHz	
		FO = 128	181	168	154	134	80	80	80	80	ns	
<b>TTL Output Module Timing<sup>4</sup></b>												
t <sub>DLH</sub>	Data-to-Pad HIGH		3.3	3.8	4.3	5.1	7.2	7.2	7.2	7.2	ns	
t <sub>DHL</sub>	Data-to-Pad LOW		4.0	4.6	5.2	6.1	8.6	8.6	8.6	8.6	ns	
t <sub>ENZH</sub>	Enable Pad Z to HIGH		3.7	4.3	4.9	5.8	8.0	8.0	8.0	8.0	ns	
t <sub>ENZL</sub>	Enable Pad Z to LOW		4.7	5.4	6.1	7.2	10.1	10.1	10.1	10.1	ns	
t <sub>ENHZ</sub>	Enable Pad HIGH to Z		7.9	9.1	10.4	12.2	17.1	17.1	17.1	17.1	ns	

**Table 39 • A42MX09 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)**

Parameter / Description		-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed	
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.
<b>Input Module Propagation Delays</b>											
t <sub>INYH</sub>	Pad-to-Y HIGH			1.5	1.6	1.8		2.17		3.0	ns
t <sub>INYL</sub>	Pad-to-Y LOW			1.2	1.3	1.4		1.7		2.4	ns
t <sub>INGH</sub>	G to Y HIGH			1.8	2.0	2.3		2.7		3.7	ns
t <sub>INGL</sub>	G to Y LOW			1.8	2.0	2.3		2.7		3.7	ns
<b>Input Module Predicted Routing Delays<sup>2</sup></b>											
t <sub>IRD1</sub>	FO = 1 Routing Delay			2.8	3.2	3.6		4.2		5.9	ns
t <sub>IRD2</sub>	FO = 2 Routing Delay			3.2	3.5	4.0		4.7		6.6	ns
t <sub>IRD3</sub>	FO = 3 Routing Delay			3.5	3.9	4.4		5.2		7.3	ns
t <sub>IRD4</sub>	FO = 4 Routing Delay			3.9	4.3	4.9		5.7		8.0	ns
t <sub>IRD8</sub>	FO = 8 Routing Delay			5.2	5.8	6.6		7.7		10.8	ns
<b>Global Clock Network</b>											
t <sub>CKH</sub>	Input LOW to HIGH	FO = 32		4.1	4.5	5.1		6.0		8.4	ns
		FO = 256		4.5	5.0	5.6		6.7		9.3	ns
t <sub>CKL</sub>	Input HIGH to LOW	FO = 32		5.0	5.5	6.2		7.3		10.2	ns
		FO = 256		5.4	6.0	6.8		8.0		11.2	ns
t <sub>PWH</sub>	Minimum Pulse Width HIGH	FO = 32	1.7	1.9	2.1	2.5		3.5		ns	
		FO = 256	1.9	2.1	2.3	2.7		3.8		ns	
t <sub>PWL</sub>	Minimum Pulse Width LOW	FO = 32	1.7	1.9	2.1	2.5		3.5		ns	
		FO = 256	1.9	2.1	2.3	2.7		3.8		ns	
t <sub>CKSW</sub>	Maximum Skew	FO = 32		0.4	0.5	0.5		0.6		0.9	ns
		FO = 256		0.4	0.5	0.5		0.6		0.9	ns
t <sub>SUEXT</sub>	Input Latch External Set-Up	FO = 32	0.0	0.0	0.0	0.0		0.0		0.0	ns
		FO = 256	0.0	0.0	0.0	0.0		0.0		0.0	ns
t <sub>HEXT</sub>	Input Latch External Hold	FO = 32	3.3	3.7	4.2	4.9		6.9		ns	
		FO = 256	3.7	4.1	4.6	5.5		7.6		ns	
t <sub>P</sub>	Minimum Period	FO = 32	5.6	6.2	6.7	7.8		12.9		ns	
		FO = 256	6.1	6.8	7.4	8.5		14.2		ns	
f <sub>MAX</sub>	Maximum Frequency	FO = 32	177	161	148	129		77		MHz	
		FO = 256	161	146	135	117		70		MHz	

**Table 40 • A42MX16 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T<sub>J</sub> = 70°C)**

<b>Parameter / Description</b>		<b>-3 Speed</b>		<b>-2 Speed</b>		<b>-1 Speed</b>		<b>Std Speed</b>		<b>-F Speed</b>		<b>Units</b>
		<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	
$t_{PWL}$	Minimum Pulse Width LOW	FO = 32	3.2	3.5	4.0	4.7	6.6	ns				
		FO = 384	3.7	4.1	4.6	5.4	7.6	ns				
$t_{CKSW}$	Maximum Skew	FO = 32		0.3	0.4	0.4	0.5	0.5	0.7	ns		
		FO = 384		0.3	0.4	0.4	0.5	0.5	0.7	ns		
$t_{SUEXT}$	Input Latch External Set-Up	FO = 32	0.0	0.0	0.0	0.0	0.0	0.0	0.0	ns		
		FO = 384	0.0	0.0	0.0	0.0	0.0	0.0	0.0	ns		
$t_{HEXT}$	Input Latch External Hold	FO = 32	2.8	3.1	5.5	4.1	5.7	ns				
		FO = 384	3.2	3.5	4.0	4.7	6.6	ns				
$t_P$	Minimum Period	FO = 32	4.2	4.67	5.1	5.8	9.7	ns				
		FO = 384	4.6	5.1	5.6	6.4	10.7	ns				
$f_{MAX}$	Maximum Frequency	FO = 32		237	215	198	172	103	MHz			
		FO = 384		215	195	179	156	94	MHz			

**Table 42 • A42MX24 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)**

<b>Parameter / Description</b>		<b>-3 Speed</b>		<b>-2 Speed</b>		<b>-1 Speed</b>		<b>Std Speed</b>		<b>-F Speed</b>		<b>Units</b>
		<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	
<b>Input Module Propagation Delays</b>												
t <sub>INPY</sub>	Input Data Pad-to-Y	1.0		1.1		1.3		1.5		2.1		ns
t <sub>INGO</sub>	Input Latch Gate-to-Output	1.3		1.4		1.6		1.9		2.6		ns
t <sub>INH</sub>	Input Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t <sub>INSU</sub>	Input Latch Set-Up	0.5		0.5		0.6		0.7		1.0		ns
t <sub>ILA</sub>	Latch Active Pulse Width	4.7		5.2		5.9		6.9		9.7		ns

**Table 44 • A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)**

<b>Parameter / Description</b>	<b>-3 Speed</b>		<b>-2 Speed</b>		<b>-1 Speed</b>		<b>Std Speed</b>		<b>-F Speed</b>		<b>Units</b>
	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	
<b>TTL Output Module Timing<sup>5</sup> (Continued)</b>											
t <sub>ENLZ</sub>	Enable Pad LOW to Z	4.9	5.5	6.2	7.3	10.2	ns				
t <sub>GLH</sub>	G-to-Pad HIGH	2.9	3.3	3.7	4.4	6.1	ns				
t <sub>GHL</sub>	G-to-Pad LOW	2.9	3.3	3.7	4.4	6.1	ns				
t <sub>LSU</sub>	I/O Latch Output Set-Up	0.5	0.5	0.6	0.7	1.0	ns				
t <sub>LH</sub>	I/O Latch Output Hold	0.0	0.0	0.0	0.0	0.0	ns				
t <sub>LCO</sub>	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O	5.7	6.3	7.1	8.4	11.8	ns				
t <sub>ACO</sub>	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O	7.8	8.6	9.8	11.5	16.1	ns				
d <sub>TLH</sub>	Capacitive Loading, LOW to HIGH	0.07	0.08	0.09	0.10	0.14	ns/pF				
d <sub>THL</sub>	Capacitive Loading, HIGH to LOW	0.07	0.08	0.09	0.10	0.14	ns/pF				

**Table 45 • A42MX36 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)**

<b>Parameter / Description</b>	<b>-3 Speed</b>		<b>-2 Speed</b>		<b>-1 Speed</b>		<b>Std Speed</b>		<b>-F Speed</b>		<b>Units</b>
	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	<b>Min.</b>	<b>Max.</b>	
t <sub>ACO</sub>	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		10.9		12.1		13.7		16.1		22.5 ns
d <sub>TLH</sub>	Capacitive Loading, LOW to HIGH		0.10		0.11		0.12		0.14		0.20 ns/pF
d <sub>THL</sub>	Capacitive Loading, HIGH to LOW		0.10		0.11		0.12		0.14		0.20 ns/pF
<b>CMOS Output Module Timing<sup>5</sup></b>											
t <sub>DLH</sub>	Data-to-Pad HIGH		4.9		5.5		6.2		7.3		10.3 ns
t <sub>DHL</sub>	Data-to-Pad LOW		3.4		3.8		4.3		5.1		7.1 ns
t <sub>ENZH</sub>	Enable Pad Z to HIGH		3.7		4.1		4.7		5.5		7.7 ns
t <sub>ENZL</sub>	Enable Pad Z to LOW		4.1		4.6		5.2		6.1		8.5 ns
t <sub>ENHZ</sub>	Enable Pad HIGH to Z		7.4		8.2		9.3		10.9		15.3 ns
t <sub>ENLZ</sub>	Enable Pad LOW to Z		6.9		7.6		8.7		10.2		14.3 ns
t <sub>GLH</sub>	G-to-Pad HIGH		7.0		7.8		8.9		10.4		14.6 ns
t <sub>GHL</sub>	G-to-Pad LOW		7.0		7.8		8.9		10.4		14.6 ns
t <sub>LSU</sub>	I/O Latch Set-Up		0.7		0.7		0.8		1.0		1.4 ns
t <sub>LH</sub>	I/O Latch Hold		0.0		0.0		0.0		0.0		ns
t <sub>LCO</sub>	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.9		8.8		10.0		11.8		16.5 ns

- For dual-module macros, use t<sub>PD1</sub> + t<sub>RD1</sub> + t<sub>PDn</sub>, t<sub>CO</sub> + t<sub>RD1</sub> + t<sub>PDn</sub>, or t<sub>PD1</sub> + t<sub>RD1</sub> + t<sub>SUD</sub>, whichever is appropriate.
- Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
- Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
- Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.*
- Delays based on 35 pF loading.

## 3.12 Pin Descriptions

This section lists the pin descriptions for 40MX and 42MX series FPGAs.

### CLK/A/B, I/O Global Clock

Clock inputs for clock distribution networks. CLK is for 40MX while CLKA and CLKB are for 42MX devices. The clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

### DCLK, I/O Diagnostic Clock

Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

### GND, Ground

Input LOW supply voltage.

### I/O, Input/Output

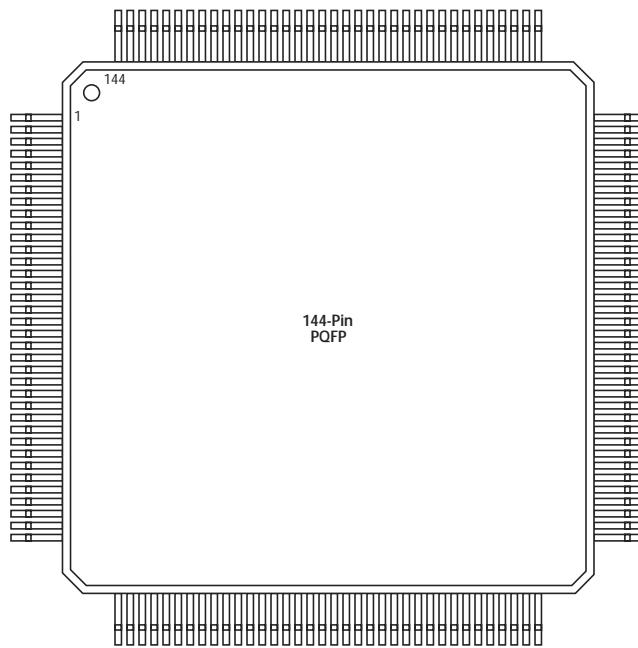
**Table 49 • PL84**

<b>PL84</b>	<b>Pin Number</b>	<b>A40MX04 Function</b>	<b>A42MX09 Function</b>	<b>A42MX16 Function</b>	<b>A42MX24 Function</b>
47	I/O	I/O	I/O	I/O	WD, I/O
48	I/O	I/O	I/O	I/O	I/O
49	I/O	GND	GND	GND	GND
50	I/O	I/O	I/O	I/O	WD, I/O
51	I/O	I/O	I/O	I/O	WD, I/O
52	I/O	SDO, I/O	SDO, I/O	SDO, TDO, I/O	
53	I/O	I/O	I/O	I/O	I/O
54	I/O	I/O	I/O	I/O	I/O
55	I/O	I/O	I/O	I/O	I/O
56	I/O	I/O	I/O	I/O	I/O
57	I/O	I/O	I/O	I/O	I/O
58	I/O	I/O	I/O	I/O	I/O
59	I/O	I/O	I/O	I/O	I/O
60	GND	I/O	I/O	I/O	I/O
61	GND	I/O	I/O	I/O	I/O
62	I/O	I/O	I/O	I/O	TCK, I/O
63	I/O	LP	LP	LP	LP
64	CLK, I/O	VCCA	VCCA	VCCA	VCCA
65	I/O	VCCI	VCCI	VCCI	VCCI
66	MODE	I/O	I/O	I/O	I/O
67	VCC	I/O	I/O	I/O	I/O
68	VCC	I/O	I/O	I/O	I/O
69	I/O	I/O	I/O	I/O	I/O
70	I/O	GND	GND	GND	GND
71	I/O	I/O	I/O	I/O	I/O
72	SDI, I/O	I/O	I/O	I/O	I/O
73	DCLK, I/O	I/O	I/O	I/O	I/O
74	PRA, I/O	I/O	I/O	I/O	I/O
75	PRB, I/O	I/O	I/O	I/O	I/O
76	I/O	SDI, I/O	SDI, I/O	SDI, I/O	SDI, I/O
77	I/O	I/O	I/O	I/O	I/O
78	I/O	I/O	I/O	I/O	WD, I/O
79	I/O	I/O	I/O	I/O	WD, I/O
80	I/O	I/O	I/O	I/O	WD, I/O
81	I/O	PRA, I/O	PRA, I/O	PRA, I/O	PRA, I/O
82	GND	I/O	I/O	I/O	I/O
83	I/O	CLKA, I/O	CLKA, I/O	CLKA, I/O	CLKA, I/O

**Table 50 • PQ 100**

<b>PQ100</b>				
<b>Pin Number</b>	<b>A40MX02 Function</b>	<b>A40MX04 Function</b>	<b>A42MX09 Function</b>	<b>A42MX16 Function</b>
93	VCC	VCC	I/O	I/O
94	VCC	VCC	PRB, I/O	PRB, I/O
95	NC	I/O	I/O	I/O
96	NC	I/O	GND	GND
97	NC	I/O	I/O	I/O
98	SDI, I/O	SDI, I/O	I/O	I/O
99	DCLK, I/O	DCLK, I/O	I/O	I/O
100	PRA, I/O	PRA, I/O	I/O	I/O

**Figure 42 • PQ144**



**Table 51 • PQ144**

PQ144	
Pin Number	A42MX09 Function
1	I/O
2	MODE
3	I/O
4	I/O
5	I/O

**Table 54 • PQ240**

<b>PQ240</b>	
<b>Pin Number</b>	<b>A42MX36 Function</b>
126	WD, I/O
127	I/O
128	VCCI
129	I/O
130	I/O
131	I/O
132	WD, I/O
133	WD, I/O
134	I/O
135	QCLKB, I/O
136	I/O
137	I/O
138	I/O
139	I/O
140	I/O
141	I/O
142	WD, I/O
143	WD, I/O
144	I/O
145	I/O
146	I/O
147	I/O
148	I/O
149	I/O
150	VCCI
151	VCCA
152	GND
153	I/O
154	I/O
155	I/O
156	I/O
157	I/O
158	I/O
159	WD, I/O
160	WD, I/O
161	I/O
162	I/O

**Table 54 • PQ240**

<b>PQ240</b>	
<b>Pin Number</b>	<b>A42MX36 Function</b>
163	WD, I/O
164	WD, I/O
165	I/O
166	QCLKA, I/O
167	I/O
168	I/O
169	I/O
170	I/O
171	I/O
172	VCCI
173	I/O
174	WD, I/O
175	WD, I/O
176	I/O
177	I/O
178	TDI, I/O
179	TMS, I/O
180	GND
181	VCCA
182	GND
183	I/O
184	I/O
185	I/O
186	I/O
187	I/O
188	I/O
189	I/O
190	I/O
191	I/O
192	VCCI
193	I/O
194	I/O
195	I/O
196	I/O
197	I/O
198	I/O
199	I/O

**Table 60 • BG272**

<b>BG272</b>	
<b>Pin Number</b>	<b>A42MX36 Function</b>
J9	GND
J10	GND
J11	GND
J12	GND
J17	VCCA
J18	I/O
J19	I/O
J20	I/O
K1	I/O
K2	I/O
K3	I/O
K4	VCCI
K9	GND
K10	GND
K11	GND
K12	GND
K17	I/O
K18	VCCA
K19	VCCA
K20	LP
L1	I/O
L2	I/O
L3	VCCA
L4	VCCA
L9	GND
L10	GND
L11	GND
L12	GND
L17	VCCI
L18	I/O
L19	I/O
L20	TCK, I/O
M1	I/O
M2	I/O
M3	I/O
M4	VCCI
M9	GND

**Table 62 • CQ172**

60	I/O
61	I/O
62	I/O
63	I/O
64	I/O
65	GND
66	VCC
67	I/O
68	I/O
69	I/O
70	I/O
71	I/O
72	I/O
73	I/O
74	I/O
75	GND
76	I/O
77	I/O
78	I/O
79	I/O
80	VCCI
81	I/O
82	I/O
83	I/O
84	I/O
85	SDO
86	I/O
87	I/O
88	I/O
89	I/O
90	I/O
91	I/O
92	I/O
93	I/O
94	I/O
95	I/O
96	I/O
97	I/O
98	GND