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[Understanding Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	104
Number of Gates	14000
Voltage - Supply	3V ~ 3.6V, 4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	176-LQFP
Supplier Device Package	176-TQFP (24x24)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a42mx09-3tqg176

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Silicon Sculptor programs devices independently to achieve the fastest programming times possible. After being programmed, each fuse is verified to insure that it has been programmed correctly. Furthermore, at the end of programming, there are integrity tests that are run to ensure no extra fuses have been programmed. Not only does it test fuses (both programmed and non-programmed), Silicon Sculptor also allows self-test to verify its own hardware extensively.

The procedure for programming an MX device using Silicon Sculptor is as follows:

1. Load the *.AFM file
2. Select the device to be programmed
3. Begin programming

When the design is ready to go to production, Microsemi offers device volume-programming services either through distribution partners or via In-House Programming from the factory.

For more details on programming MX devices, see the *AC225: Programming Antifuse Devices* application note and the *Silicon Sculptor 3 Programmers User Guide*.

3.3.4 Power Supply

MX devices are designed to operate in both 5.0V and 3.3V environments. In particular, 42MX devices can operate in mixed 5.0 V/3.3 V systems. The following table describes the voltage support of MX devices.

Table 6 • Voltage Support of MX Devices

Device	VCC	VCCA	VCCI	Maximum Input Tolerance	Nominal Output Voltage
40MX	5.0 V	—	—	5.5 V	5.0 V
	3.3 V	—	—	3.6 V	3.3 V
42MX	—	5.0 V	5.0 V	5.5 V	5.0 V
	—	3.3 V	3.3 V	3.6 V	3.3 V
	—	5.0 V	3.3 V	5.5 V	3.3 V

For A42MX24 and A42MX36 devices the VCCA supply has to be monotonic during power up in order for the POR to issue reset to the JTAG state machine correctly. For more information, see the *AC291: 42MX Family Devices Power-Up Behavior*.

3.3.5 Power-Up/Down in Mixed-Voltage Mode

When powering up 42MX in mixed voltage mode (VCCA = 5.0 V and VCCI = 3.3 V), VCCA must be greater than or equal to VCCI throughout the power-up sequence. If VCCI exceeds VCCA during power-up, one of two things will happen:

- The input protection diode on the I/Os will be forward biased
- The I/Os will be at logical High

In either case, ICC rises to high levels. For power-down, any sequence with VCCA and VCCI can be implemented.

3.3.6 Transient Current

Due to the simultaneous random logic switching activity during power-up, a transient current may appear on the core supply (VCC). Customers must use a regulator for the VCC supply that can source a minimum of 100 mA for transient current during power-up. Failure to provide enough power can prevent the system from powering up properly and result in functional failure. However, there are no reliability concerns, since transient current is distributed across the die instead of confined to a localized spot.

Since the transient current is not due to I/O switching, its value and duration are independent of the VCCI.

Additionally, the back-annotation flow is compatible with all the major simulators and the simulation results can be cross-probed with Silicon Explorer II, Microsemi's integrated verification and logic analysis tool. Another tool included in the Libero software is the SmartGen macro builder, which easily creates popular and commonly used logic functions for implementation into your schematic or HDL design.

Microsemi's Libero software is compatible with the most popular FPGA design entry and verification tools from companies such as Mentor Graphics, Synopsys, and Cadence design systems.

See the Libero IDE web content at www.microsemi.com/soc/products/software/libero/default.aspx for further information on licensing and current operating system support.

3.6 Related Documents

The following sections give the list of related documents which can be referred for this datasheet.

3.6.1 Application Notes

- AC278: *BSDL Files Format Description*
- AC225: *Programming Antifuse Devices*
- AC168: *Implementation of Security in Microsemi Antifuse FPGAs*

3.6.2 User Guides and Manuals

- *Antifuse Macro Library Guide*
- *Silicon Sculptor Programmers User Guide*

3.6.3 Miscellaneous

Libero IDE Flow Diagram

3.7 5.0 V Operating Conditions

The following tables show 5.0 V operating conditions.

Table 12 • Absolute Maximum Ratings for 40MX Devices*

Symbol	Parameter	Limits	Units
VCC	DC Supply Voltage	-0.5 to +7.0	V
VI	Input Voltage	-0.5 to VCC+0.5	V
VO	Output Voltage	-0.5 to VCC+0.5	V
t _{STG}	Storage Temperature	-65 to +150	°C

Note: *Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Devices should not be operated outside the recommended operating conditions.

Table 13 • Absolute Maximum Ratings for 42MX Devices*

Symbol	Parameter	Limits	Units
VCCI	DC Supply Voltage for I/Os	-0.5 to +7.0	V
VCCA	DC Supply Voltage for Array	-0.5 to +7.0	V
VI	Input Voltage	-0.5 to VCCI+0.5	V
VO	Output Voltage	-0.5 to VCCI+0.5	V
t _{STG}	Storage Temperature	-65 to +150	°C

3.8.1 3.3 V LVTTL Electrical Specifications

Table 19 • 3.3V LVTTL Electrical Specifications

Symbol	Parameter	Commercial		Commercial -F		Industrial		Military		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
VOH ¹	IOH = -4 mA	2.15		2.15		2.4		2.4		V
VOL ¹	IOL = 6 mA		0.4		0.4		0.48		0.48	V
VIL		-0.3	0.8	-0.3	0.8	-0.3	0.8	-0.3	0.8	V
VIH (40MX)		2.0	VCC + 0.3	2.0	VCC + 0.3	2.0	VCC + 0.3	2.0	VCC + 0.3	V
VIH (42MX)		2.0	VCCI + 0.3	2.0	VCCI + 0.3	2.0	VCCI + 0.3	2.0	VCCI + 0.3	V
IIL			-10		-10		-10		-10	µA
IIH			-10		-10		-10		-10	µA
Input Transition Time, T _R and T _F			500		500		500		500	ns
C _{IO} I/O Capacitance			10		10		10		10	pF
Standby Current, ICC ²	A40MX02, A40MX04	3		25		10		25		mA
	A42MX09	5		25		25		25		mA
	A42MX16	6		25		25		25		mA
	A42MX24, A42MX36	15		25		25		25		mA
Low-Power Mode Standby Current	42MX devices only	0.5		ICC - 5.0		ICC - 5.0		ICC - 5.0		mA
IIO, I/O source sink current	Can be derived from the <i>IB/S model</i> (http://www.microsemi.com/soc/techdocs/models/ibis.html)									

1. Only one output tested at a time. VCC/VCCI = min.
2. All outputs unloaded. All inputs = VCC/VCCI or GND.

3.9 Mixed 5.0 V / 3.3 V Operating Conditions (for 42MX Devices Only)

Table 20 • Absolute Maximum Ratings*

Symbol	Parameter	Limits	Units
VCCI	DC Supply Voltage for I/Os	-0.5 to +7.0	V
VCCA	DC Supply Voltage for Array	-0.5 to +7.0	V
VI	Input Voltage	-0.5 to VCCA + 0.5	V
VO	Output Voltage	-0.5 to VCCI + 0.5	V
t _{STG}	Storage Temperature	-65 to +150	°C

Note: *Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device

3.9.3 Output Drive Characteristics for 3.3 V PCI Signaling

Table 25 • DC Specification (3.3 V PCI Signaling)¹

Symbol	Parameter	Condition	PCI		MX		Units
			Min.	Max.	Min.	Max.	
VCCI	Supply Voltage for I/Os		3.0	3.6	3.0	3.6 ²	V
VIH	Input High Voltage		0.5	VCC + 0.5	0.5	VCCI + 0.3	V
VIL	Input Low Voltage		-0.5	0.8	-0.3	0.8	V
I _{IH}	Input High Leakage Current	VIN = 2.7 V		70		10	µA
I _{IL}	Input Leakage Current			-70		-10	µA
V _{OH}	Output High Voltage	I _{OUT} = -2 mA	0.9		3.3		V
V _{OL}	Output Low Voltage	I _{OUT} = 3 mA, 6 mA	0.1		0.1 VCCI		V
C _{IN}	Input Pin Capacitance			10		10	pF
C _{CLK}	CLK Pin Capacitance		5	12		10	pF
L _{PIN}	Pin Inductance			20		< 8 nH ³	nH

1. PCI Local Bus Specification, Version 2.1, Section 4.2.2.1.

2. Maximum rating for VCCI -0.5 V to 7.0V.

3. Dependent upon the chosen package. PCI recommends QFP and BGA packaging to reduce pin inductance and capacitance.

Table 26 • AC Specifications for (3.3 V PCI Signaling)^{*}

Symbol	Parameter	Condition	PCI		MX		Units
			Min.	Max.	Min.	Max.	
I _{CL}	Low Clamp Current	-5 < VIN ≤ -1	-25 + (VIN +1) /0.015		-60	-10	mA
Slew (r)	Output Rise Slew Rate	0.2 V to 0.6 V load	1		4	1.8	V/ns
Slew (f)	Output Fall Slew Rate	0.6 V to 0.2 V load	1		4	2.8	4.0
							V/ns

Note: *PCI Local Bus Specification, Version 2.1, Section 4.2.2.2.

Table 34 • A40MX02 Timing Characteristics (Nominal 5.0 V Operation) (continued)
(Worst-Case Commercial Conditions, VCC = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Input Module Propagation Delays											
t _{INYH}	Pad-to-Y HIGH		0.7		0.8		0.9		1.1		1.5 ns
t _{INYL}	Pad-to-Y LOW		0.6		0.7		0.8		1.0		1.3 ns
Input Module Predicted Routing Delays¹											
t _{IRD1}	FO = 1 Routing Delay		2.1		2.4		2.2		3.2		4.5 ns
t _{IRD2}	FO = 2 Routing Delay		2.6		3.0		3.4		4.0		5.6 ns
t _{IRD3}	FO = 3 Routing Delay		3.1		3.6		4.1		4.8		6.7 ns
t _{IRD4}	FO = 4 Routing Delay		3.6		4.2		4.8		5.6		7.8 ns
t _{IRD8}	FO = 8 Routing Delay		5.7		6.6		7.5		8.8		12.4 ns
Global Clock Network											
t _{CKH}	Input Low to HIGH	FO = 16	4.6		5.3		6.0		7.0		9.8 ns
		FO = 128	4.6		5.3		6.0		7.0		9.8
t _{CKL}	Input High to LOW	FO = 16	4.8		5.6		6.3		7.4		10.4 ns
		FO = 128	4.8		5.6		6.3		7.4		10.4
t _{PWH}	Minimum Pulse Width HIGH	FO = 16	2.2		2.6		2.9		3.4		4.8 ns
		FO = 128	2.4		2.7		3.1		3.6		5.1
t _{PWL}	Minimum Pulse Width LOW	FO = 16	2.2		2.6		2.9		3.4		4.8 ns
		FO = 128	2.4		2.7		3.01		3.6		5.1
t _{CKSW}	Maximum Skew	FO = 16	0.4		0.5		0.5		0.6		0.8 ns
		FO = 128	0.5		0.6		0.7		0.8		1.2
t _P	Minimum Period	FO = 16	4.7		5.4		6.1		7.2		10.0 ns
		FO = 128	4.8		5.6		6.3		7.5		10.4
f _{MAX}	Maximum Frequency	FO = 16	188		175		160		139		83 MHz
		FO = 128	181		168		154		134		80

Table 35 • A40MX02 Timing Characteristics (Nominal 3.3 V Operation) (continued)
(Worst-Case Commercial Conditions, VCC = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t _{RD1}	FO = 1 Routing Delay		2.0		2.2		2.5		3.0		4.2 ns
t _{RD2}	FO = 2 Routing Delay		2.7		3.1		3.5		4.1		5.7 ns
t _{RD3}	FO = 3 Routing Delay		3.4		3.9		4.4		5.2		7.3 ns
t _{RD4}	FO = 4 Routing Delay		4.2		4.8		5.4		6.3		8.9 ns
t _{RD8}	FO = 8 Routing Delay		7.1		8.2		9.2		10.9		15.2 ns
Logic Module Sequential Timing²											
t _{SUD}	Flip-Flop (Latch) Data Input Set-Up		4.3		4.9		5.6		6.6		9.2 ns
t _{HD} ³	Flip-Flop (Latch) Data Input Hold		0.0		0.0		0.0		0.0		ns
t _{SUENA}	Flip-Flop (Latch) Enable Set-Up	4.3		4.9		5.6		6.6		9.2	ns
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width		4.6		5.3		6.0		7.0		9.8 ns
t _{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width		4.6		5.3		6.0		7.0		9.8 ns
t _A	Flip-Flop Clock Input Period	6.8		7.8		8.9		10.4		14.6	ns
f _{MAX}	Flip-Flop (Latch) Clock Frequency (FO = 128)		109		101		92		80		48 MHz
Input Module Propagation Delays											
t _{INYH}	Pad-to-Y HIGH		1.0		1.1		1.3		1.5		2.1 ns
t _{INYL}	Pad-to-Y LOW		0.9		1.0		1.1		1.3		1.9 ns
Input Module Predicted Routing Delays¹											
t _{IRD1}	FO = 1 Routing Delay		2.9		3.4		3.8		4.5		6.3 ns
t _{IRD2}	FO = 2 Routing Delay		3.6		4.2		4.8		5.6		7.8 ns
t _{IRD3}	FO = 3 Routing Delay		4.4		5.0		5.7		6.7		9.4 ns
t _{IRD4}	FO = 4 Routing Delay		5.1		5.9		6.7		7.8		11.0 ns
t _{IRD8}	FO = 8 Routing Delay		8.0		9.26		10.5		12.6		17.3 ns
Global Clock Network											
t _{CKH}	Input LOW to HIGH FO = 16		6.4		7.4		8.3		9.8		13.7 ns
	FO = 128		6.4		7.4		8.3		9.8		13.7
t _{CKL}	Input HIGH to LOW FO = 16		6.7		7.8		8.8		10.4		14.5 ns
	FO = 128		6.7		7.8		8.8		10.4		14.5
t _{PWH}	Minimum Pulse Width HIGH	FO = 16	3.1		3.6		4.1		4.8		6.7 ns
	FO = 128		3.3		3.8		4.3		5.1		7.1
t _{PWL}	Minimum Pulse Width LOW	FO = 16	3.1		3.6		4.1		4.8		6.7 ns
	FO = 128		3.3		3.8		4.3		5.1		7.1
t _{CKSW}	Maximum Skew	FO = 16	0.6		0.6		0.7		0.8		1.2 ns
	FO = 128		0.8		0.9		1.0		1.2		1.6

Table 35 • A40MX02 Timing Characteristics (Nominal 3.3 V Operation) (continued)
(Worst-Case Commercial Conditions, VCC = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t _P Minimum Period	FO = 16	6.5		7.5		8.5		10.1		14.1	ns
	FO = 128	6.8		7.8		8.9		10.4		14.6	
f _{MAX} Maximum Frequency	FO = 16		113		105		96		83		50 MHz
	FO = 128		109		101		92		80		48
TTL Output Module Timing⁴											
t _{DLH} Data-to-Pad HIGH			4.7		5.4		6.1		7.2		10.0 ns
t _{DHL} Data-to-Pad LOW			5.6		6.4		7.3		8.6		12.0 ns
t _{ENZH} Enable Pad Z to HIGH			5.2		6.0		6.8		8.1		11.3 ns
t _{ENZL} Enable Pad Z to LOW			6.6		7.6		8.6		10.1		14.1 ns
t _{ENHZ} Enable Pad HIGH to Z			11.1		12.8		14.5		17.1		23.9 ns
t _{ENLZ} Enable Pad LOW to Z			8.2		9.5		10.7		12.6		17.7 ns
d _{TLH} Delta LOW to HIGH			0.03		0.03		0.04		0.04		0.06 ns/pF
d _{THL} Delta HIGH to LOW			0.04		0.04		0.05		0.06		0.08 ns/pF

Table 35 • A40MX02 Timing Characteristics (Nominal 3.3 V Operation) (continued)
(Worst-Case Commercial Conditions, VCC = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing⁴											
t _{DH}	Data-to-Pad HIGH	5.5	6.4	7.2	8.5	11.9	ns				
t _{DHL}	Data-to-Pad LOW	4.8	5.5	6.2	7.3	10.2	ns				
t _{ENZH}	Enable Pad Z to HIGH	4.7	5.5	6.2	7.3	10.2	ns				
t _{ENZL}	Enable Pad Z to LOW	6.8	7.9	8.9	10.5	14.7	ns				
t _{ENHZ}	Enable Pad HIGH to Z	11.1	12.8	14.5	17.1	23.9	ns				
t _{ENLZ}	Enable Pad LOW to Z	8.2	9.5	10.7	12.6	17.7	ns				
d _{TLH}	Delta LOW to HIGH	0.05	0.05	0.06	0.07	0.10	ns/pF				
d _{THL}	Delta HIGH to LOW	0.03	0.03	0.04	0.04	0.06	ns/pF				

1. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
2. Set-up times assume fanout of 3. Further testing information can be obtained from the Timer utility.
3. The hold time for the DFME1A macro may be greater than 0 ns. Use the Timer tool from the Designer software to check the hold time for this macro
4. Delays based on 35 pF loading

Table 36 • A40MX04 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCC = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays											
t _{PD1}	Single Module	1.2	1.4	1.6	1.9	2.7	ns				
t _{PD2}	Dual-Module Macros	2.3	3.1	3.5	4.1	5.7	ns				
t _{CO}	Sequential Clock-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
t _{GO}	Latch G-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
t _{RS}	Flip-Flop (Latch) Reset-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
Logic Module Predicted Routing Delays¹											
t _{RD1}	FO = 1 Routing Delay	1.2	1.6	1.8	2.1	3.0	ns				
t _{RD2}	FO = 2 Routing Delay	1.9	2.2	2.5	2.9	4.1	ns				
t _{RD3}	FO = 3 Routing Delay	2.4	2.8	3.2	3.7	5.2	ns				
t _{RD4}	FO = 4 Routing Delay	2.9	3.4	3.9	4.5	6.3	ns				
t _{RD8}	FO = 8 Routing Delay	5.0	5.8	6.6	7.8	10.9	ns				
Logic Module Sequential Timing²											
t _{SUD}	Flip-Flop (Latch) Data Input Set-Up	3.1	3.5	4.0	4.7	6.6	ns				
t _{HD³}	Flip-Flop (Latch) Data Input Hold	0.0	0.0	0.0	0.0	0.0	ns				
t _{SUENA}	Flip-Flop (Latch) Enable Set-Up	3.1	3.5	4.0	4.7	6.6	ns				

Table 37 • A40MX04 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCC = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t _{WCLKA} Flip-Flop (Latch) Clock Active Pulse Width	4.6		5.3		5.6		7.0		9.8		ns
t _{WASYN} Flip-Flop (Latch) Asynchronous Pulse Width	4.6		5.3		5.6		7.0		9.8		ns
t _A Flip-Flop Clock Input Period	6.8		7.8		8.9		10.4		14.6		ns
f _{MAX} Flip-Flop (Latch) Clock Frequency (FO = 128)		109		101		92		80		48	MHz
Input Module Propagation Delays											
t _{I_{NYH}} Pad-to-Y HIGH		1.0		1.1		1.3		1.5		2.1	ns
t _{I_{NYL}} Pad-to-Y LOW		0.9		1.0		1.1		1.3		1.9	ns

Table 39 • A42MX09 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing⁵											
t _{DLH}	Data-to-Pad HIGH		3.4		3.8		4.3		5.1		7.1 ns
t _{DHL}	Data-to-Pad LOW		4.0		4.5		5.1		6.1		8.3 ns
t _{ENZH}	Enable Pad Z to HIGH		3.7		4.1		4.6		5.5		7.6 ns
t _{ENZL}	Enable Pad Z to LOW		4.1		4.5		5.1		6.1		8.5 ns
t _{ENHZ}	Enable Pad HIGH to Z		6.9		7.6		8.6		10.2		14.2 ns
t _{ENLZ}	Enable Pad LOW to Z		7.5		8.3		9.4		11.1		15.5 ns
t _{GLH}	G-to-Pad HIGH		5.8		6.5		7.3		8.6		12.0 ns
t _{GHL}	G-to-Pad LOW		5.8		6.5		7.3		8.6		12.0 ns
t _{LSU}	I/O Latch Set-Up	0.7		0.8		0.9		1.0		1.4	ns
t _{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad), 64 Clock Loading		8.7		9.7		10.9		12.9		18.0 ns
t _{ACO}	Array Clock-to-Out (Pad-to-Pad), 64 Clock Loading		12.2		13.5		15.4		18.1		25.3 ns
d _{TLH}	Capacity Loading, LOW to HIGH	0.00		0.00		0.00		0.10		0.01	ns/pF
d _{THL}	Capacity Loading, HIGH to LOW	0.09		0.10		0.10		0.10		0.10	ns/pF

Table 40 • A42MX16 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t _{RD3}	FO = 3 Routing Delay		1.3		1.4		1.6		1.9		2.7 ns
t _{RD4}	FO = 4 Routing Delay		1.6		1.7		2.0		2.3		3.2 ns
t _{RD8}	FO = 8 Routing Delay		2.6		2.9		3.2		3.8		5.3 ns
Logic Module Sequential Timing^{3,4}											
t _{SUD}	Flip-Flop (Latch) Data Input Set-Up		0.3		0.4		0.4		0.5		0.7 ns
t _{HD}	Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{SUENA}	Flip-Flop (Latch) Enable Set-Up	0.7		0.8		0.9		1.0		1.4	ns
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	3.4		3.8		4.3		5.0		7.1	ns
t _{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width	4.5		5.0		5.6		6.6		9.2	ns
t _A	Flip-Flop Clock Input Period	6.8		7.6		8.6		10.1		14.1	ns
t _{INH}	Input Buffer Latch Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{INSU}	Input Buffer Latch Set-Up	0.5		0.5		0.6		0.7		1.0	ns
t _{OUTH}	Output Buffer Latch Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{OUTSU}	Output Buffer Latch Set-Up	0.5		0.5		0.6		0.7		1.0	ns
f _{MAX}	Flip-Flop (Latch) Clock Frequency	215		195		179		156		94	MHz
Input Module Propagation Delays											
t _{INYH}	Pad-to-Y HIGH		1.1		1.2		1.3		1.6		2.2 ns
t _{INYL}	Pad-to-Y LOW		0.8		0.9		1.0		1.2		1.7 ns
t _{INGH}	G to Y HIGH		1.4		1.6		1.8		2.1		2.9 ns
t _{INGL}	G to Y LOW		1.4		1.6		1.8		2.1		2.9 ns
Input Module Predicted Routing Delays²											
t _{IRD1}	FO = 1 Routing Delay		1.8		2.0		2.3		2.7		4.0 ns
t _{IRD2}	FO = 2 Routing Delay		2.1		2.3		2.6		3.1		4.3 ns
t _{IRD3}	FO = 3 Routing Delay		2.3		2.6		3.0		3.5		4.9 ns
t _{IRD4}	FO = 4 Routing Delay		2.6		3.0		3.3		3.9		5.4 ns
t _{IRD8}	FO = 8 Routing Delay		3.6		4.0		4.6		5.4		7.5 ns
Global Clock Network											
t _{CKH}	Input LOW to HIGH	FO = 32	2.6		2.9		3.3		3.9		5.4 ns
		FO = 384	2.9		3.2		3.6		4.3		6.0 ns
t _{CKL}	Input HIGH to LOW	FO = 32	3.8		4.2		4.8		5.6		7.8 ns
		FO = 384	4.5		5.0		5.6		6.6		9.2 ns
t _{PWH}	Minimum Pulse Width HIGH	FO = 32	3.2		3.5		4.0		4.7		6.6 ns
		FO = 384	3.7		4.1		4.6		5.4		7.6 ns

Table 41 • A42MX16 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Sequential Timing^{3, 4}											
t _{SUD}	Flip-Flop (Latch) Data Input Set-Up	0.5	0.5	0.6	0.7	0.9					ns
t _{HD}	Flip-Flop (Latch) Data Input Hold	0.0	0.0	0.0	0.0	0.0					ns
t _{SUENA}	Flip-Flop (Latch) Enable Set-Up	1.0	1.1	1.2	1.4	2.0					ns
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0	0.0	0.0	0.0	0.0					ns
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	4.8	5.3	6.0	7.1	9.9					ns
t _{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width	6.2	6.9	7.9	9.2	12.9					ns
t _A	Flip-Flop Clock Input Period	9.5	10.6	12.0	14.1	19.8					ns
t _{IINH}	Input Buffer Latch Hold	0.0	0.0	0.0	0.0	0.0					ns
t _{INSU}	Input Buffer Latch Set-Up	0.7	0.8	0.9	1.01	1.4					ns
t _{OUTH}	Output Buffer Latch Hold	0.0	0.0	0.0	0.0	0.0					ns
t _{OUTSU}	Output Buffer Latch Set-Up	0.7	0.8	0.89	1.01	1.4					ns
f _{MAX}	Flip-Flop (Latch) Clock Frequency	129	117	108	94	56	MHz				
Input Module Propagation Delays											
t _{IINYH}	Pad-to-Y HIGH	1.5	1.6	1.9	2.2	3.1	ns				
t _{IINYL}	Pad-to-Y LOW	1.1	1.3	1.4	1.7	2.4	ns				
t _{INGH}	G to Y HIGH	2.0	2.2	2.5	2.9	4.1	ns				
t _{INGL}	G to Y LOW	2.0	2.2	2.5	2.9	4.1	ns				
Input Module Predicted Routing Delays²											
t _{IRD1}	FO = 1 Routing Delay	2.6	2.9	3.2	3.8	5.3	ns				
t _{IRD2}	FO = 2 Routing Delay	2.9	3.2	3.7	4.3	6.1	ns				
t _{IRD3}	FO = 3 Routing Delay	3.3	3.6	4.1	4.9	6.8	ns				
t _{IRD4}	FO = 4 Routing Delay	3.6	4.0	4.6	5.4	7.6	ns				
t _{IRD8}	FO = 8 Routing Delay	5.1	5.6	6.4	7.5	10.5	ns				
Global Clock Network											
t _{CKH}	Input LOW to HIGH	FO = 32	4.4	4.8	5.5	6.5	9.0	ns			
		FO = 384	4.8	5.3	6.0	7.1	9.9	ns			
t _{CKL}	Input HIGH to LOW	FO = 32	5.3	5.9	6.7	7.8	11.0	ns			
		FO = 384	6.2	6.9	7.9	9.2	12.9	ns			
t _{PWH}	Minimum Pulse Width HIGH	FO = 32	5.7	6.3	7.1	8.4	11.8	ns			
		FO = 384	6.6	7.4	8.3	9.8	13.7	ns			

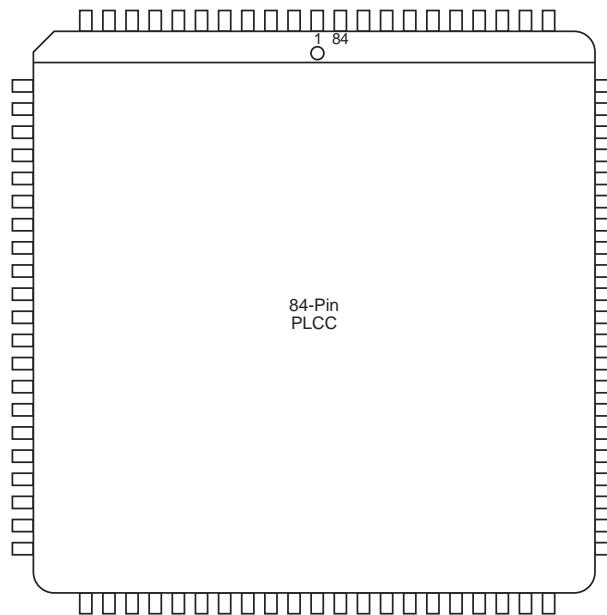
Table 43 • A42MX24 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description		-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed	
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.
TTL Output Module Timing⁵ (continued)											
t _{LH}	I/O Latch Output Hold	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	ns	
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.7	8.5	9.6		11.3		15.9	ns	
t _{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		14.8	16.5	18.7		22.0		30.8	ns	
d _{TLH}	Capacitive Loading, LOW to HIGH	0.05	0.05	0.06	0.07		0.10	ns/pF			
d _{THL}	Capacitive Loading, HIGH to LOW	0.04	0.04	0.05	0.06		0.08	ns/pF			
CMOS Output Module Timing⁵											
t _{DLH}	Data-to-Pad HIGH	4.8	5.3	5.5	6.4		9.0	ns			
t _{DHL}	Data-to-Pad LOW	3.5	3.9	4.1	4.9		6.8	ns			
t _{ENZH}	Enable Pad Z to HIGH	3.6	4.0	4.5	5.3		7.4	ns			
t _{ENZL}	Enable Pad Z to LOW	3.4	4.0	5.0	5.8		8.2	ns			
t _{ENHZ}	Enable Pad HIGH to Z	7.2	8.0	9.0	10.7		14.9	ns			
t _{ENLZ}	Enable Pad LOW to Z	6.7	7.5	8.5	9.9		13.9	ns			
t _{GLH}	G-to-Pad HIGH	6.8	7.6	8.6	10.1		14.2	ns			
t _{GHL}	G-to-Pad LOW	6.8	7.6	8.6	10.1		14.2	ns			
t _{LSU}	I/O Latch Set-Up	0.7	0.7	0.8	1.0		1.4	ns			
t _{LH}	I/O Latch Hold	0.0	0.0	0.0	0.0		0.0	ns			
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.7	8.5	9.6		11.3		15.9	ns	
t _{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		14.8	16.5	18.7		22.0		30.8	ns	
d _{TLH}	Capacitive Loading, LOW to HIGH	0.05	0.05	0.06	0.07		0.10	ns/pF			
d _{THL}	Capacitive Loading, HIGH to LOW	0.04	0.04	0.05	0.06		0.08	ns/pF			
t _{HEXT}	Input Latch External Hold	FO = 32 FO = 486	3.9 4.6	4.3 5.2	4.9 5.8		5.7 6.9	8.1 9.6	ns ns		
t _P	Minimum Period (1/f _{MAX})	FO = 32 FO = 486	7.8 8.6	8.7 9.5	9.5 10.4		10.8 11.9	18.2 19.9	ns ns		

- For dual-module macros, use t_{PD1} + t_{RD1} + t_{PDn}, t_{CO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUP}, whichever is appropriate.
- Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
- Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
- Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
- Delays based on 35 pF loading.

Table 48 • PL68

PL68		
Pin Number	A40MX02 Function	A40MX04 Function
61	I/O	I/O
62	I/O	I/O
63	I/O	I/O
64	I/O	I/O
65	I/O	I/O
66	GND	GND
67	I/O	I/O
68	I/O	I/O

Figure 40 • PL84**Table 49 • PL84**

PL84				
Pin Number	A40MX04 Function	A42MX09 Function	A42MX16 Function	A42MX24 Function
1	I/O	I/O	I/O	I/O
2	I/O	CLKB, I/O	CLKB, I/O	CLKB, I/O
3	I/O	I/O	I/O	I/O
4	VCC	PRB, I/O	PRB, I/O	PRB, I/O
5	I/O	I/O	I/O	WD, I/O
6	I/O	GND	GND	GND
7	I/O	I/O	I/O	I/O
8	I/O	I/O	I/O	WD, I/O
9	I/O	I/O	I/O	WD, I/O

Table 50 • PQ 100

PQ100	Pin Number	A40MX02 Function	A40MX04 Function	A42MX09 Function	A42MX16 Function
19	VCC	V _{CC}		I/O	I/O
20	I/O	I/O		I/O	I/O
21	I/O	I/O		I/O	I/O
22	I/O	I/O	GND		GND
23	I/O	I/O		I/O	I/O
24	I/O	I/O		I/O	I/O
25	I/O	I/O		I/O	I/O
26	I/O	I/O		I/O	I/O
27	NC	NC		I/O	I/O
28	NC	NC		I/O	I/O
29	NC	NC		I/O	I/O
30	NC	NC		I/O	I/O
31	NC	I/O		I/O	I/O
32	NC	I/O		I/O	I/O
33	NC	I/O		I/O	I/O
34	I/O	I/O	GND		GND
35	I/O	I/O		I/O	I/O
36	GND	GND		I/O	I/O
37	GND	GND		I/O	I/O
38	I/O	I/O		I/O	I/O
39	I/O	I/O		I/O	I/O
40	I/O	I/O	VCCA		VCCA
41	I/O	I/O		I/O	I/O
42	I/O	I/O		I/O	I/O
43	VCC	VCC		I/O	I/O
44	VCC	VCC		I/O	I/O
45	I/O	I/O		I/O	I/O
46	I/O	I/O	GND		GND
47	I/O	I/O		I/O	I/O
48	NC	I/O		I/O	I/O
49	NC	I/O		I/O	I/O
50	NC	I/O		I/O	I/O
51	NC	NC		I/O	I/O
52	NC	NC	SDO, I/O		SDO, I/O
53	NC	NC		I/O	I/O
54	NC	NC		I/O	I/O
55	NC	NC		I/O	I/O

Table 52 • PQ160

PQ160	Pin Number	A42MX09 Function	A42MX16 Function	A42MX24 Function
	21	CLKA, I/O	CLKA, I/O	CLKA, I/O
	22	I/O	I/O	I/O
	23	PRA, I/O	PRA, I/O	PRA, I/O
	24	NC	I/O	WD, I/O
	25	I/O	I/O	WD, I/O
	26	I/O	I/O	I/O
	27	I/O	I/O	I/O
	28	NC	I/O	I/O
	29	I/O	I/O	WD, I/O
	30	GND	GND	GND
	31	NC	I/O	WD, I/O
	32	I/O	I/O	I/O
	33	I/O	I/O	I/O
	34	I/O	I/O	I/O
	35	NC	VCCI	VCCI
	36	I/O	I/O	WD, I/O
	37	I/O	I/O	WD, I/O
	38	SDI, I/O	SDI, I/O	SDI, I/O
	39	I/O	I/O	I/O
	40	GND	GND	GND
	41	I/O	I/O	I/O
	42	I/O	I/O	I/O
	43	I/O	I/O	I/O
	44	GND	GND	GND
	45	I/O	I/O	I/O
	46	I/O	I/O	I/O
	47	I/O	I/O	I/O
	48	I/O	I/O	I/O
	49	GND	GND	GND
	50	I/O	I/O	I/O
	51	I/O	I/O	I/O
	52	NC	I/O	I/O
	53	I/O	I/O	I/O
	54	NC	VCCA	VCCA
	55	I/O	I/O	I/O
	56	I/O	I/O	I/O
	57	VCCA	VCCA	VCCA

Table 54 • PQ240

PQ240	
Pin Number	A42MX36 Function
200	I/O
201	I/O
202	I/O
203	I/O
204	I/O
205	I/O
206	VCCA
207	I/O
208	I/O
209	VCCA
210	VCCI
211	I/O
212	I/O
213	I/O
214	I/O
215	I/O
216	I/O
217	I/O
218	I/O
219	VCCA
220	I/O
221	I/O
222	I/O
223	I/O
224	I/O
225	I/O
226	I/O
227	VCCI
228	I/O
229	I/O
230	I/O
231	I/O
232	I/O
233	I/O
234	I/O
235	I/O
236	I/O

Table 57 • TQ176

TQ176	Pin Number	A42MX09 Function	A42MX16 Function	A42MX24 Function
	84	I/O	I/O	WD, I/O
	85	I/O	I/O	WD, I/O
	86	NC	I/O	I/O
	87	SDO, I/O	SDO, I/O	SDO, TDO, I/O
	88	I/O	I/O	I/O
	89	GND	GND	GND
	90	I/O	I/O	I/O
	91	I/O	I/O	I/O
	92	I/O	I/O	I/O
	93	I/O	I/O	I/O
	94	I/O	I/O	I/O
	95	I/O	I/O	I/O
	96	NC	I/O	I/O
	97	NC	I/O	I/O
	98	I/O	I/O	I/O
	99	I/O	I/O	I/O
	100	I/O	I/O	I/O
	101	NC	NC	I/O
	102	I/O	I/O	I/O
	103	NC	I/O	I/O
	104	I/O	I/O	I/O
	105	I/O	I/O	I/O
	106	GND	GND	GND
	107	NC	I/O	I/O
	108	NC	I/O	TCK, I/O
	109	LP	LP	LP
	110	VCCA	VCCA	VCCA
	111	GND	GND	GND
	112	VCCI	VCCI	VCCI
	113	VCCA	VCCA	VCCA
	114	NC	I/O	I/O
	115	NC	I/O	I/O
	116	NC	VCCA	VCCA
	117	I/O	I/O	I/O
	118	I/O	I/O	I/O
	119	I/O	I/O	I/O
	120	I/O	I/O	I/O

Figure 53 • CQ172**Table 62 • CQ172**

CQ172	
Pin Number	A42MX16 Function
1	MODE
2	I/O
3	I/O
4	I/O
5	I/O
6	I/O
7	GND
8	I/O
9	I/O
10	I/O
11	I/O
12	VCC
13	I/O
14	I/O
15	I/O
16	I/O
17	GND
18	I/O
19	I/O
20	I/O