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Understanding Embedded - FPGAs (Field Programmable Gate Array)

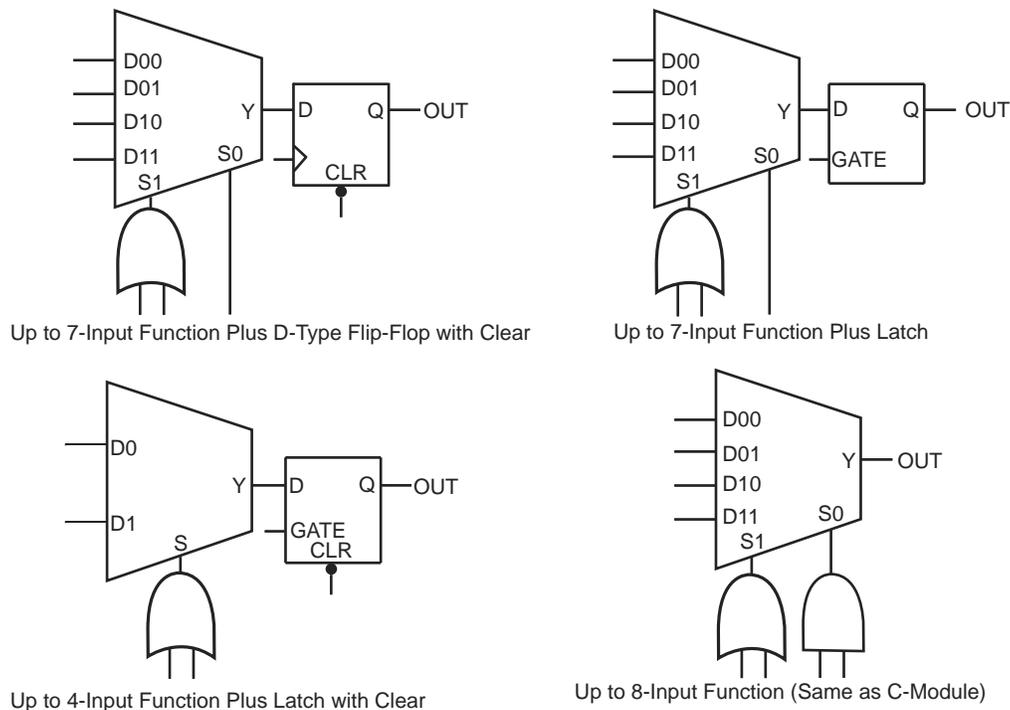
Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	125
Number of Gates	24000
Voltage - Supply	3V ~ 3.6V, 4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	-55°C ~ 125°C (TC)
Package / Case	160-BQFP
Supplier Device Package	160-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a42mx16-pqg160m

Figure 4 • 42MX S-Module Implementation

A42MX24 and A42MX36 devices contain D-modules, which are arranged around the periphery of the device. D-modules contain wide-decode circuitry, providing a fast, wide-input AND function similar to that found in CPLD architectures (Figure 5, page 9). The D-module allows A42MX24 and A42MX36 devices to perform wide-decode functions at speeds comparable to CPLDs and PALs. The output of the D-module has a programmable inverter for active HIGH or LOW assertion. The D-module output is hardwired to an output pin, and can also be fed back into the array to be incorporated into other logic.

3.2.2 Dual-Port SRAM Modules

The A42MX36 device contains dual-port SRAM modules that have been optimized for synchronous or asynchronous applications. The SRAM modules are arranged in 256-bit blocks that can be configured as 32x8 or 64x4. SRAM modules can be cascaded together to form memory spaces of user-definable width and depth. A block diagram of the A42MX36 dual-port SRAM block is shown in Figure 6, page 9.

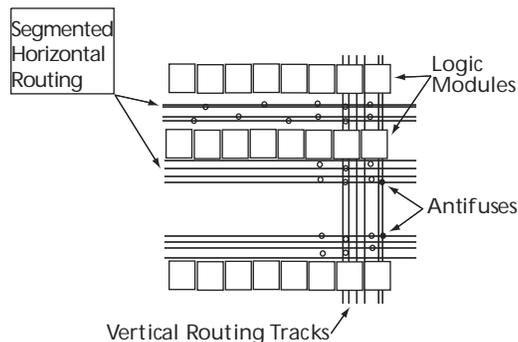
The A42MX36 SRAM modules are true dual-port structures containing independent read and write ports. Each SRAM module contains six bits of read and write addressing (RDAD[5:0] and WRAD[5:0], respectively) for 64x4-bit blocks. When configured in byte mode, the highest order address bits (RDAD5 and WRAD5) are not used. The read and write ports of the SRAM block contain independent clocks (RCLK and WCLK) with programmable polarities offering active HIGH or LOW implementation. The SRAM block contains eight data inputs (WD[7:0]), and eight outputs (RD[7:0]), which are connected to segmented vertical routing tracks.

The A42MX36 dual-port SRAM blocks provide an optimal solution for high-speed buffered applications requiring FIFO and LIFO queues. The ACTgen Macro Builder within Microsemi's designer software provides capability to quickly design memory functions with the SRAM blocks. Unused SRAM blocks can be used to implement registers for other user logic within the design.

3.2.3.3 Antifuse Structures

An antifuse is a “normally open” structure. The use of antifuses to implement a programmable logic device results in highly testable structures as well as efficient programming algorithms. There are no pre-existing connections; temporary connections can be made using pass transistors. These temporary connections can isolate individual antifuses to be programmed and individual circuit structures to be tested, which can be done before and after programming. For instance, all metal tracks can be tested for continuity and shorts between adjacent tracks, and the functionality of all logic modules can be verified.

Figure 7 • MX Routing Structure



3.2.4 Clock Networks

The 40MX devices have one global clock distribution network (CLK). A signal can be put on the CLK network by being routed through the CLKBUF buffer.

In 42MX devices, there are two low-skew, high-fanout clock distribution networks, referred to as CLKA and CLKB. Each network has a clock module (CLKMOD) that can select the source of the clock signal from any of the following (Figure 8, page 11):

- Externally from the CLKA pad, using CLKBUF buffer
- Externally from the CLKB pad, using CLKBUF buffer
- Internally from the CLKINTA input, using CLKINT buffer
- Internally from the CLKINTB input, using CLKINT buffer

The clock modules are located in the top row of I/O modules. Clock drivers and a dedicated horizontal clock track are located in each horizontal routing channel.

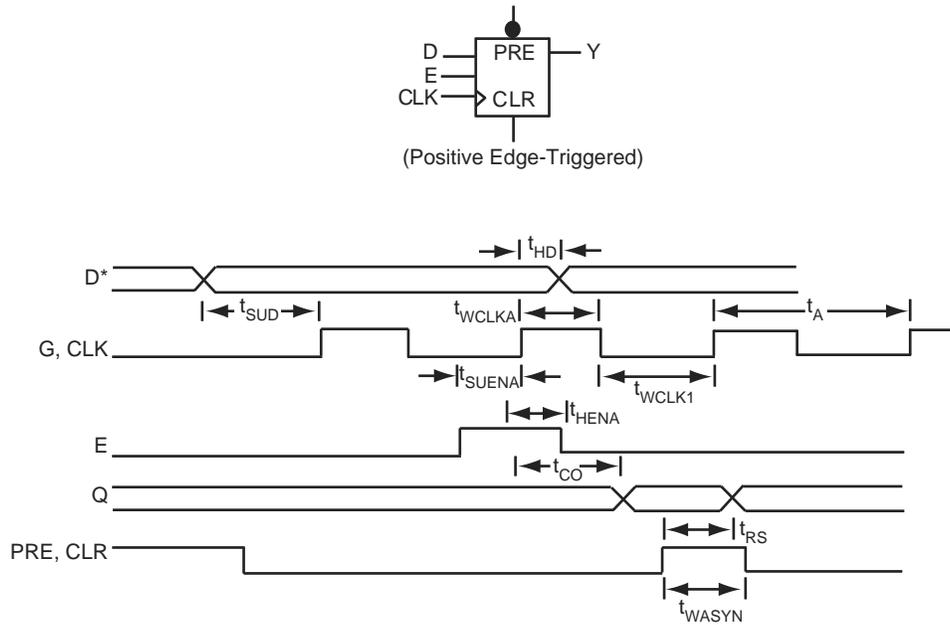
Clock input pads in both 40MX and 42MX devices can also be used as normal I/Os, bypassing the clock networks.

The A42MX36 device has four additional register control resources, called quadrant clock networks (Figure 9, page 11). Each quadrant clock provides a local, high-fanout resource to the contiguous logic modules within its quadrant of the device. Quadrant clock signals can originate from specific I/O pins or from the internal array and can be used as a secondary register clock, register clear, or output enable.

3.10.2 Sequential Module Timing Characteristics

The following figure shows sequential module timing characteristics.

Figure 25 • Flip-Flops and Latches



Note: *D represents all data functions involving A, B, and S for multiplexed flip-flops.

3.10.3 Sequential Timing Characteristics

The following figures show sequential timing characteristics.

Figure 26 • Input Buffer Latches

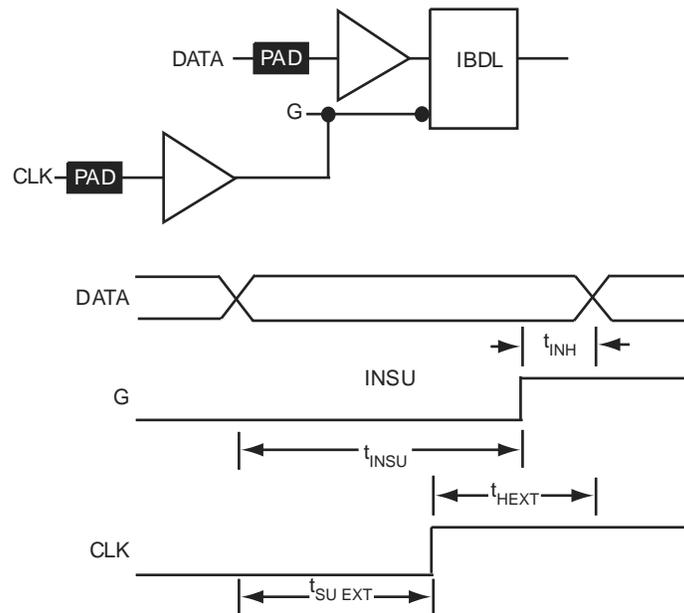
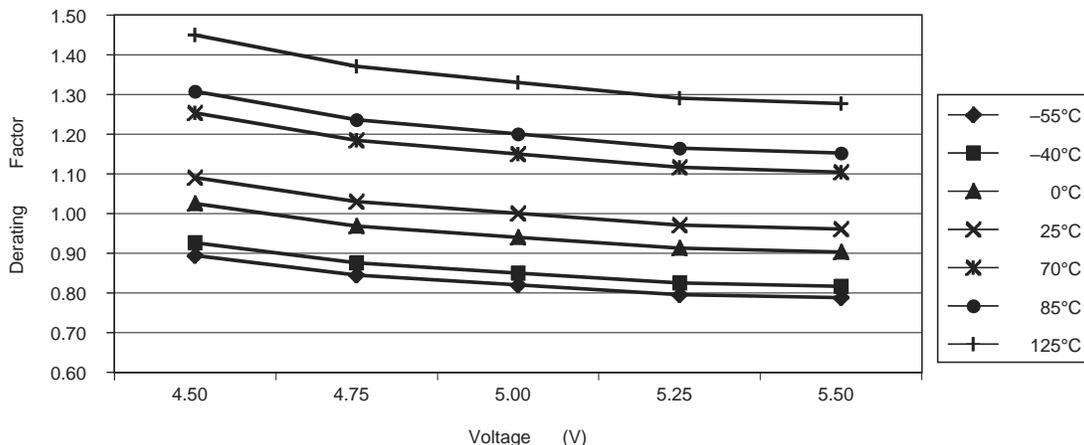


Figure 35 • 40MX Junction Temperature and Voltage Derating Curves (Normalized to TJ = 25°C, VCC = 5.0 V)

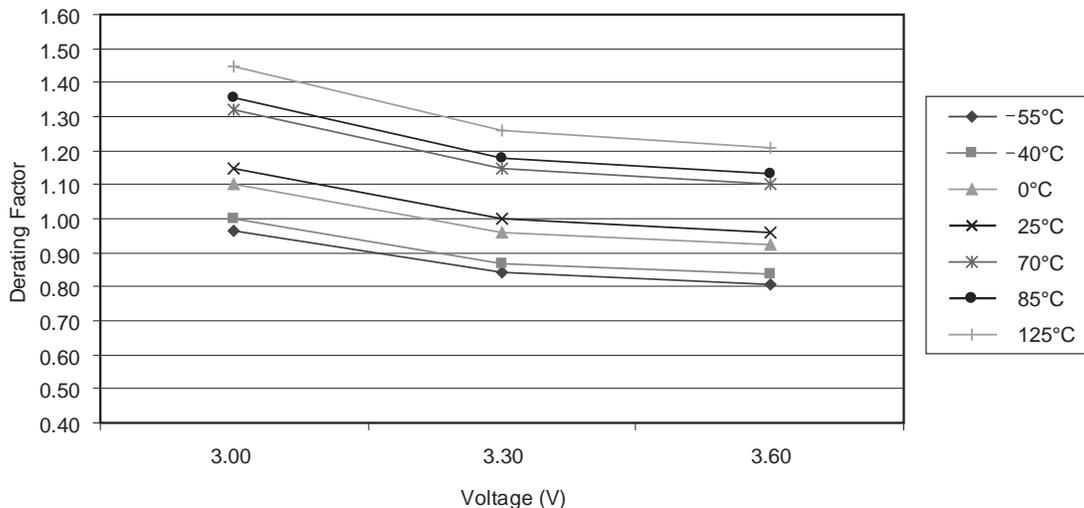


Note: This derating factor applies to all routing and propagation delays

Table 30 • 42MX Temperature and Voltage Derating Factors (Normalized to TJ = 25°C, VCCA = 3.3 V)

42MX Voltage	Temperature						
	-55°C	-40°C	0°C	25°C	70°C	85°C	125°C
3.00	0.97	1.00	1.10	1.15	1.32	1.36	1.45
3.30	0.84	0.87	0.96	1.00	1.15	1.18	1.26
3.60	0.81	0.84	0.92	0.96	1.10	1.13	1.21

Figure 36 • 42MX Junction Temperature and Voltage Derating Curves (Normalized to TJ = 25°C, VCCA = 3.3 V)



Note: This derating factor applies to all routing and propagation delays

Table 31 • 40MX Temperature and Voltage Derating Factors (Normalized to TJ = 25°C, VCC = 3.3 V)

40MX Voltage	Temperature						
	-55°C	-40°C	0°C	25°C	70°C	85°C	125°C
3.00	1.08	1.12	1.21	1.26	1.50	1.64	2.00
3.30	0.86	0.89	0.96	1.00	1.19	1.30	1.59

Table 38 • A42MX09 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)

Parameter / Description		-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing⁵												
t _{DLH}	Data-to-Pad HIGH		2.5		2.7		3.1		3.6		5.1	ns
t _{DHL}	Data-to-Pad LOW		2.9		3.2		3.6		4.3		6.0	ns
t _{ENZH}	Enable Pad Z to HIGH		2.6		2.9		3.3		3.9		5.5	ns
t _{ENZL}	Enable Pad Z to LOW		2.9		3.2		3.7		4.3		6.1	ns
t _{ENHZ}	Enable Pad HIGH to Z		4.9		5.4		6.2		7.3		10.2	ns
t _{ENLZ}	Enable Pad LOW to Z		5.3		5.9		6.7		7.9		11.1	ns
t _{GLH}	G-to-Pad HIGH		2.6		2.9		3.3		3.8		5.3	ns
t _{GHL}	G-to-Pad LOW		2.6		2.9		3.3		3.8		5.3	ns
t _{LSU}	I/O Latch Set-Up	0.5		0.5		0.6		0.7		1.0		ns
t _{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad), 64 Clock Loading		5.2		5.8		6.6		7.7		10.8	ns
t _{ACO}	Array Clock-to-Out (Pad-to-Pad), 64 Clock Loading		7.4		8.2		9.3		10.9		15.3	ns
d _{TLH}	Capacity Loading, LOW to HIGH		0.03		0.03		0.03		0.04		0.06	ns/pF
d _{THL}	Capacity Loading, HIGH to LOW		0.04		0.04		0.04		0.05		0.07	ns/pF

Table 39 • A42MX09 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing⁵											
t _{DLH}	Data-to-Pad HIGH	3.4	3.8	5.5	6.4	9.0	ns				
t _{DHL}	Data-to-Pad LOW	4.1	4.5	4.2	5.0	7.0	ns				
t _{ENZH}	Enable Pad Z to HIGH	3.7	4.1	4.6	5.5	7.6	ns				
t _{ENZL}	Enable Pad Z to LOW	4.1	4.5	5.1	6.1	8.5	ns				
t _{ENHZ}	Enable Pad HIGH to Z	6.9	7.6	8.6	10.2	14.2	ns				
t _{ENLZ}	Enable Pad LOW to Z	7.5	8.3	9.4	11.1	15.5	ns				
t _{GLH}	G-to-Pad HIGH	5.8	6.5	7.3	8.6	12.0	ns				
t _{GHL}	G-to-Pad LOW	5.8	6.5	7.3	8.6	12.0	ns				
t _{LSU}	I/O Latch Set-Up	0.7	0.8	0.9	1.0	1.4	ns				
t _{LH}	I/O Latch Hold	0.0	0.0	0.0	0.0	0.0	ns				
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad), 64 Clock Loading	8.7	9.7	10.9	12.9	18.0	ns				
t _{ACO}	Array Clock-to-Out (Pad-to-Pad), 64 Clock Loading	12.2	13.5	15.4	18.1	25.3	ns				
d _{TLH}	Capacity Loading, LOW to HIGH	0.04	0.04	0.05	0.06	0.08	ns/pF				
d _{THL}	Capacity Loading, HIGH to LOW	0.05	0.05	0.06	0.07	0.10	ns/pF				

1. For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
4. Set-up and hold timing parameters for the input buffer latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
5. Delays based on 35 pF loading.

Table 40 • A42MX16 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays¹											
t _{PD1}	Single Module	1.4	1.5	1.7	2.0	2.8	ns				
t _{CO}	Sequential Clock-to-Q	1.4	1.6	1.8	2.1	3.0	ns				
t _{GO}	Latch G-to-Q	1.4	1.5	1.7	2.0	2.8	ns				
t _{RS}	Flip-Flop (Latch) Reset-to-Q	1.6	1.7	2.0	2.3	3.3	ns				
Logic Module Predicted Routing Delays²											
t _{RD1}	FO = 1 Routing Delay	0.8	0.9	1.0	1.2	1.6	ns				
t _{RD2}	FO = 2 Routing Delay	1.0	1.2	1.3	1.5	2.1	ns				

Table 42 • A42MX24 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing⁵											
t _{DLH}	Data-to-Pad HIGH	2.4	2.7	3.1	3.6	5.1	ns				
t _{DHL}	Data-to-Pad LOW	2.8	3.2	3.6	4.2	5.9	ns				
t _{ENZH}	Enable Pad Z to HIGH	2.5	2.8	3.2	3.8	5.3	ns				
t _{ENZL}	Enable Pad Z to LOW	2.8	3.1	3.5	4.2	5.9	ns				
t _{ENHZ}	Enable Pad HIGH to Z	5.2	5.7	6.5	7.6	10.7	ns				
t _{ENLZ}	Enable Pad LOW to Z	4.8	5.3	6.0	7.1	9.9	ns				
t _{GLH}	G-to-Pad HIGH	2.9	3.2	3.6	4.3	6.0	ns				
t _{GHL}	G-to-Pad LOW	2.9	3.2	3.6	4.3	6.0	ns				
t _{LSU}	I/O Latch Output Set-Up	0.5	0.5	0.6	0.7	1.0	ns				
t _{LH}	I/O Latch Output Hold	0.0	0.0	0.0	0.0	0.0	ns				
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O	5.6	6.1	6.9	8.1	11.4	ns				
t _{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O	10.6	11.8	13.4	15.7	22.0	ns				
d _{TLH}	Capacitive Loading, LOW to HIGH	0.04	0.04	0.04	0.05	0.07	ns/pF				
d _{THL}	Capacitive Loading, HIGH to LOW	0.03	0.03	0.03	0.04	0.06	ns/pF				

Table 44 • A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)

Parameter / Description		-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Asynchronous SRAM Operations												
t _{RPD}	Asynchronous Access Time		8.1		9.0		10.2		12.0		16.8	ns
t _{RDADV}	Read Address Valid		8.8		9.8		11.1		13.0		18.2	ns
t _{ADSU}	Address/Data Set-Up Time		1.6		1.8		2.0		2.4		3.4	ns
t _{ADH}	Address/Data Hold Time		0.0		0.0		0.0		0.0		0.0	ns
t _{RENSUA}	Read Enable Set-Up to Address Valid		0.6		0.7		0.8		0.9		1.3	ns
t _{RENHA}	Read Enable Hold		3.4		3.8		4.3		5.0		7.0	ns
t _{WENSU}	Write Enable Set-Up		2.7		3.0		3.4		4.0		5.6	ns
t _{WENH}	Write Enable Hold		0.0		0.0		0.0		0.0		0.0	ns
t _{DOH}	Data Out Hold Time		1.2		1.3		1.5		1.8		2.5	ns
Input Module Propagation Delays												
t _{INPY}	Input Data Pad-to-Y		1.0		1.1		1.3		1.5		2.1	ns
t _{INGO}	Input Latch Gate-to-Output		1.4		1.6		1.8		2.1		2.9	ns
t _{INH}	Input Latch Hold		0.0		0.0		0.0		0.0		0.0	ns
t _{INSU}	Input Latch Set-Up		0.5		0.5		0.6		0.7		1.0	ns
t _{ILA}	Latch Active Pulse Width		4.7		5.2		5.9		6.9		9.7	ns
Input Module Predicted Routing Delays²												
t _{IRD1}	FO = 1 Routing Delay		2.0		2.2		2.5		2.9		4.1	ns
t _{IRD2}	FO = 2 Routing Delay		2.3		2.6		2.9		3.4		4.8	ns
t _{IRD3}	FO = 3 Routing Delay		2.6		2.9		3.3		3.9		5.5	ns
t _{IRD4}	FO = 4 Routing Delay		3.0		3.3		3.8		4.4		6.2	ns
t _{IRD8}	FO = 8 Routing Delay		4.3		4.8		5.5		6.4		9.0	ns
Global Clock Network												
t _{CKH}	Input LOW to HIGH	FO = 32	2.7		3.0		3.4		4.0		5.6	ns
		FO = 635	3.0		3.3		3.8		4.4		6.2	ns
t _{CKL}	Input HIGH to LOW	FO = 32	3.8		4.2		4.8		5.6		7.8	ns
		FO = 635	4.9		5.4		6.1		7.2		10.1	ns
t _{PWH}	Minimum Pulse Width HIGH	FO = 32	1.8		2.0		2.2		2.6		3.6	ns
		FO = 635	2.0		2.2		2.5		2.9		4.1	ns
t _{PWL}	Minimum Pulse Width LOW	FO = 32	1.8		2.0		2.2		2.6		3.6	ns
		FO = 635	2.0		2.2		2.5		2.9		4.1	ns
t _{CKSW}	Maximum Skew	FO = 32	0.8		0.8		0.9		1.0		1.4	ns
		FO = 635	0.8		0.8		0.9		1.0		1.4	ns

Table 44 • A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing⁵ (Continued)											
t _{ENLZ}	Enable Pad LOW to Z		4.9	5.5	6.2	7.3	10.2	ns			
t _{GLH}	G-to-Pad HIGH		2.9	3.3	3.7	4.4	6.1	ns			
t _{GHL}	G-to-Pad LOW		2.9	3.3	3.7	4.4	6.1	ns			
t _{LSU}	I/O Latch Output Set-Up		0.5	0.5	0.6	0.7	1.0	ns			
t _{LH}	I/O Latch Output Hold		0.0	0.0	0.0	0.0	0.0	ns			
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		5.7	6.3	7.1	8.4	11.8	ns			
t _{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.8	8.6	9.8	11.5	16.1	ns			
d _{TLH}	Capacitive Loading, LOW to HIGH		0.07	0.08	0.09	0.10	0.14	ns/pF			
d _{THL}	Capacitive Loading, HIGH to LOW		0.07	0.08	0.09	0.10	0.14	ns/pF			

Table 45 • A42MX36 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)

Parameter / Description		-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Input Module Predicted Routing Delays²												
t _{IRD1}	FO = 1 Routing Delay		2.8	3.1	3.5	4.1	5.7	ns				
t _{IRD2}	FO = 2 Routing Delay		3.2	3.5	4.1	4.8	6.7	ns				
t _{IRD3}	FO = 3 Routing Delay		3.7	4.1	4.7	5.5	7.7	ns				
t _{IRD4}	FO = 4 Routing Delay		4.2	4.6	5.3	6.2	8.7	ns				
t _{IRD8}	FO = 8 Routing Delay		6.1	6.8	7.7	9.0	12.6	ns				
Global Clock Network												
t _{CKH}	Input LOW to HIGH	FO = 32	4.6	5.1	5.7	6.7	9.3	ns				
		FO = 635	5.0	5.6	6.3	7.4	10.3	ns				
t _{CKL}	Input HIGH to LOW	FO = 32	5.3	5.9	6.7	7.8	11.0	ns				
		FO = 635	6.8	7.6	8.6	10.1	14.1	ns				
t _{PWH}	Minimum Pulse Width HIGH	FO = 32	2.5	2.7	3.1	3.6	5.1	ns				
		FO = 635	2.8	3.1	3.5	4.1	5.7	ns				
t _{PWL}	Minimum Pulse Width LOW	FO = 32	2.5	2.7	3.1	3.6	5.1	ns				
		FO = 635	2.8	3.1	3.5	4.1	5.7	ns				
t _{CKSW}	Maximum Skew	FO = 32	1.0	1.2	1.3	1.5	2.2	ns				
		FO = 635	1.0	1.2	1.3	1.5	2.2	ns				
t _{SUEXT}	Input Latch External Set-Up	FO = 32	0.0	0.0	0.0	0.0	0.0	ns				
		FO = 635	0.0	0.0	0.0	0.0	0.0	ns				
t _{HEXT}	Input Latch External Hold	FO = 32	4.0	4.4	5.0	5.9	8.2	ns				
		FO = 635	4.6	5.2	5.9	6.9	9.6	ns				
t _P	Minimum Period (1/f _{MAX})	FO = 32	9.2	10.2	11.1	12.7	21.2	ns				
		FO = 635	9.9	11.0	12.0	13.8	23.0	ns				
f _{MAX}	Maximum Datapath Frequency	FO = 32	108	98	90	79	47	MHz				
		FO = 635	100	91	83	73	44	MHz				
TTL Output Module Timing⁵												
t _{DLH}	Data-to-Pad HIGH		3.6	4.0	4.5	5.3	7.4	ns				
t _{DHL}	Data-to-Pad LOW		4.2	4.6	5.2	6.2	8.6	ns				
t _{ENZH}	Enable Pad Z to HIGH		3.7	4.2	4.7	5.5	7.7	ns				
t _{ENZL}	Enable Pad Z to LOW		4.1	4.6	5.2	6.1	8.5	ns				
t _{ENHZ}	Enable Pad HIGH to Z		7.34	8.2	9.3	10.9	15.3	ns				
TTL Output Module Timing⁵												
t _{ENLZ}	Enable Pad LOW to Z		6.9	7.6	8.7	10.2	14.3	ns				
t _{GLH}	G-to-Pad HIGH		4.9	5.5	6.2	7.3	10.2	ns				
t _{GHL}	G-to-Pad LOW		4.9	5.5	6.2	7.3	10.2	ns				
t _{LSU}	I/O Latch Output Set-Up		0.7	0.7	0.8	1.0	1.4	ns				
t _{LH}	I/O Latch Output Hold		0.0	0.0	0.0	0.0	0.0	ns				
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.9	8.8	10.0	11.8	16.5	ns				

Table 45 • A42MX36 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t _{ACO} Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		10.9		12.1		13.7		16.1		22.5	ns
d _{TLH} Capacitive Loading, LOW to HIGH		0.10		0.11		0.12		0.14		0.20	ns/pF
d _{THL} Capacitive Loading, HIGH to LOW		0.10		0.11		0.12		0.14		0.20	ns/pF
CMOS Output Module Timing⁵											
t _{DLH} Data-to-Pad HIGH		4.9		5.5		6.2		7.3		10.3	ns
t _{DHL} Data-to-Pad LOW		3.4		3.8		4.3		5.1		7.1	ns
t _{ENZH} Enable Pad Z to HIGH		3.7		4.1		4.7		5.5		7.7	ns
t _{ENZL} Enable Pad Z to LOW		4.1		4.6		5.2		6.1		8.5	ns
t _{ENHZ} Enable Pad HIGH to Z		7.4		8.2		9.3		10.9		15.3	ns
t _{ENLZ} Enable Pad LOW to Z		6.9		7.6		8.7		10.2		14.3	ns
t _{GLH} G-to-Pad HIGH		7.0		7.8		8.9		10.4		14.6	ns
t _{GHL} G-to-Pad LOW		7.0		7.8		8.9		10.4		14.6	ns
t _{LSU} I/O Latch Set-Up	0.7		0.7		0.8		1.0		1.4		ns
t _{LH} I/O Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t _{LCO} I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.9		8.8		10.0		11.8		16.5	ns

1. For dual-module macros, use t_{PD1} + t_{RD1} + t_{PDn}, t_{CO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
4. *Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.*
5. Delays based on 35 pF loading.

3.12 Pin Descriptions

This section lists the pin descriptions for 40MX and 42MX series FPGAs.

CLK/A/B, I/O Global Clock

Clock inputs for clock distribution networks. CLK is for 40MX while CLKA and CLKB are for 42MX devices. The clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

DCLK, I/O Diagnostic Clock

Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

GND, Ground

Input LOW supply voltage.

I/O, Input/Output

Clock signal to shift the Boundary Scan Test (BST) data into the device. This pin functions as an I/O when "Reserve JTAG" is not checked in the Designer Software. BST pins are only available in A42MX24 and A42MX36 devices.

TDI, I/O Test Data In

Serial data input for BST instructions and data. Data is shifted in on the rising edge of TCK. This pin functions as an I/O when "Reserve JTAG" is not checked in the Designer Software. BST pins are only available in A42MX24 and A42MX36 devices.

TDO, I/O Test Data Out

Serial data output for BST instructions and test data. This pin functions as an I/O when "Reserve JTAG" is not checked in the Designer Software. BST pins are only available in A42MX24 and A42MX36 devices.

TMS, I/O Test Mode Select

The TMS pin controls the use of the IEEE 1149.1 Boundary Scan pins (TCK, TDI, TDO). In flexible mode when the TMS pin is set LOW, the TCK, TDI and TDO pins are boundary scan pins. Once the boundary scan pins are in test mode, they will remain in that mode until the internal boundary scan state machine reaches the "logic reset" state. At this point, the boundary scan pins will be released and will function as regular I/O pins. The "logic reset" state is reached 5 TCK cycles after the TMS pin is set HIGH. In dedicated test mode, TMS functions as specified in the IEEE 1149.1 specifications. IEEE JTAG specification recommends a 10k Ω pull-up resistor on the pin. BST pins are only available in A42MX24 and A42MX36 devices.

VCC, Supply Voltage

Input supply voltage for 40MX devices

VCCA, Supply Voltage

Supply voltage for array in 42MX devices

VCCI, Supply Voltage

Supply voltage for I/Os in 42MX devices

WD, I/O Wide Decode Output

When a wide decode module is used in a 42MX device this pin can be used as a dedicated output from the wide decode module. This direct connection eliminates additional interconnect delays associated with regular logic modules. To implement the direct I/O connection, connect an output buffer of any type to the output of the wide decode macro and place this output on one of the reserved WD pins.

Table 51 • PQ144

PQ144	
Pin Number	A42MX09 Function
6	I/O
7	I/O
8	I/O
9	GNDQ
10	GNDI
11	NC
12	I/O
13	I/O
14	I/O
15	I/O
16	I/O
17	I/O
18	VSV
19	VCC
20	VCCI
21	NC
22	I/O
23	I/O
24	I/O
25	I/O
26	I/O
27	I/O
28	GND
29	GNDI
30	NC
31	I/O
32	I/O
33	I/O
34	I/O
35	I/O
36	I/O
37	BININ
38	BINOUT
39	I/O
40	I/O
41	I/O
42	I/O

Table 55 • VQ80

VQ80		
Pin Number	A40MX02 Function	A40MX04 Function
13	VCC	VCC
14	I/O	I/O
15	I/O	I/O
16	I/O	I/O
17	NC	I/O
18	NC	I/O
19	NC	I/O
20	VCC	VCC
21	I/O	I/O
22	I/O	I/O
23	I/O	I/O
24	I/O	I/O
25	I/O	I/O
26	I/O	I/O
27	GND	GND
28	I/O	I/O
29	I/O	I/O
30	I/O	I/O
31	I/O	I/O
32	I/O	I/O
33	VCC	VCC
34	I/O	I/O
35	I/O	I/O
36	I/O	I/O
37	I/O	I/O
38	I/O	I/O
39	I/O	I/O
40	I/O	I/O
41	NC	I/O
42	NC	I/O
43	NC	I/O
44	I/O	I/O
45	I/O	I/O
46	I/O	I/O
47	GND	GND
48	I/O	I/O

Table 57 • TQ176

TQ176			
Pin Number	A42MX09 Function	A42MX16 Function	A42MX24 Function
121	NC	NC	I/O
122	I/O	I/O	I/O
123	I/O	I/O	I/O
124	NC	I/O	I/O
125	NC	I/O	I/O
126	NC	NC	I/O
127	I/O	I/O	I/O
128	I/O	I/O	I/O
129	I/O	I/O	I/O
130	I/O	I/O	I/O
131	I/O	I/O	I/O
132	I/O	I/O	I/O
133	GND	GND	GND
134	I/O	I/O	I/O
135	SDI, I/O	SDI, I/O	SDI, I/O
136	NC	I/O	I/O
137	I/O	I/O	WD, I/O
138	I/O	I/O	WD, I/O
139	I/O	I/O	I/O
140	NC	VCCI	VCCI
141	I/O	I/O	I/O
142	I/O	I/O	I/O
143	NC	I/O	I/O
144	NC	I/O	WD, I/O
145	NC	NC	WD, I/O
146	I/O	I/O	I/O
147	NC	I/O	I/O
148	I/O	I/O	I/O
149	I/O	I/O	I/O
150	I/O	I/O	WD, I/O
151	NC	I/O	WD, I/O
152	PRA, I/O	PRA, I/O	PRA, I/O
153	I/O	I/O	I/O
154	CLKA, I/O	CLKA, I/O	CLKA, I/O
155	VCCA	VCCA	VCCA
156	GND	GND	GND
157	I/O	I/O	I/O

Table 57 • TQ176

TQ176			
Pin Number	A42MX09 Function	A42MX16 Function	A42MX24 Function
158	CLKB, I/O	CLKB, I/O	CLKB, I/O
159	I/O	I/O	I/O
160	PRB, I/O	PRB, I/O	PRB, I/O
161	NC	I/O	WD, I/O
162	I/O	I/O	WD, I/O
163	I/O	I/O	I/O
164	I/O	I/O	I/O
165	NC	NC	WD, I/O
166	NC	I/O	WD, I/O
167	I/O	I/O	I/O
168	NC	I/O	I/O
169	I/O	I/O	I/O
170	NC	VCCI	VCCI
171	I/O	I/O	WD, I/O
172	I/O	I/O	WD, I/O
173	NC	I/O	I/O
174	I/O	I/O	I/O
175	DCLK, I/O	DCLK, I/O	DCLK, I/O
176	I/O	I/O	I/O

Figure 49 • CQ208

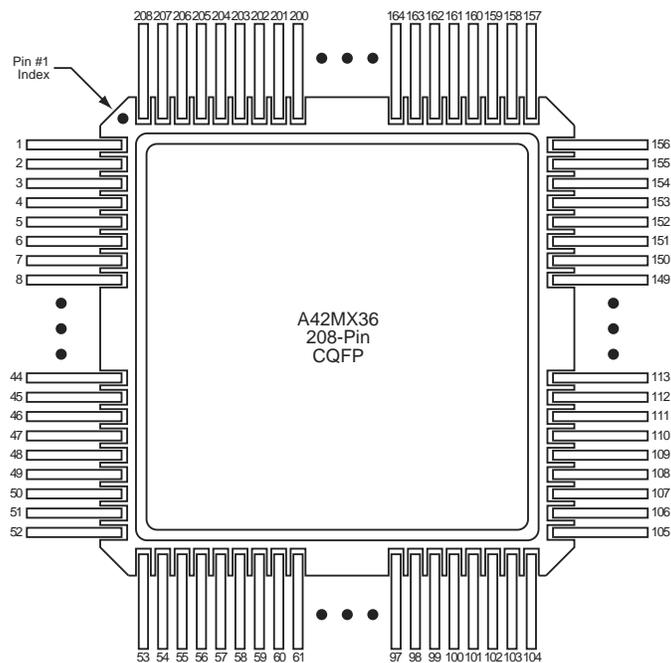


Table 59 • CQ256

CQ256	
Pin Number	A42MX36 Function
133	I/O
134	I/O
135	I/O
136	I/O
137	I/O
138	I/O
139	GND
140	I/O
141	I/O
142	I/O
143	I/O
144	I/O
145	I/O
146	I/O
147	I/O
148	I/O
149	I/O
150	I/O
151	I/O
152	I/O
153	I/O
154	I/O
155	VCCA
156	I/O
157	I/O
158	VCCA
159	VCCI
160	GND
161	I/O
162	I/O
163	I/O
164	I/O
165	GND
166	I/O
167	I/O
168	I/O
169	I/O

Table 59 • CQ256

CQ256	
Pin Number	A42MX36 Function
244	WD, I/O
245	I/O
246	I/O
247	I/O
248	VCCI
249	I/O
250	WD, I/O
251	WD, I/O
252	I/O
253	SDI, I/O
254	I/O
255	GND
256	NC

Figure 51 • BG272

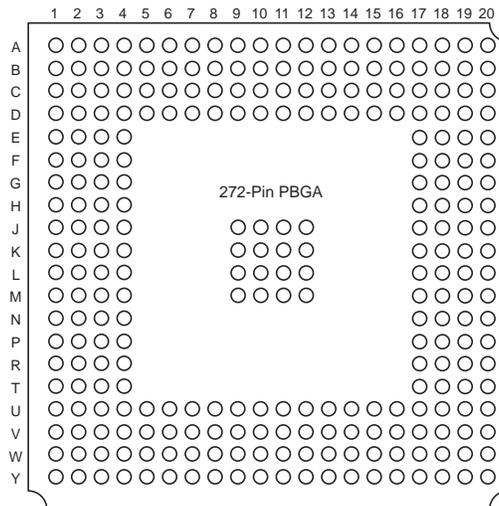


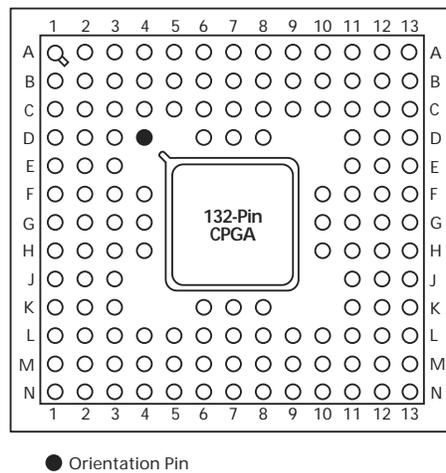
Table 60 • BG272

BG272	
Pin Number	A42MX36 Function
A1	GND
A2	GND
A3	I/O
A4	WD, I/O
A5	I/O

Table 60 • BG272

BG272	
Pin Number	A42MX36 Function
Y13	I/O
Y14	I/O
Y15	I/O
Y16	I/O
Y17	I/O
Y18	WD, I/O
Y19	GND
Y20	GND

Figure 52 • PG132



● Orientation Pin

Table 61 • PG132

PG132	
Pin Number	A42MX09 Function
–	PMPOUT
B2	I/O
A1	MODE
B1	I/O
D3	I/O
C2	I/O
C1	I/O
D2	I/O
D1	I/O
E2	I/O
E1	I/O
F3	I/O

Table 61 • PG132

PG132	
Pin Number	A42MX09 Function
F2	I/O
F1	I/O
G1	I/O
G4	VSV
H1	I/O
H2	I/O
H3	I/O
H4	I/O
J1	I/O
K1	I/O
L1	I/O
K2	I/O
M1	I/O
K3	I/O
L2	I/O
N1	I/O
L3	BININ
M2	BINOUT
N2	I/O
M3	I/O
L4	I/O
N3	I/O
M4	I/O
N4	I/O
M5	I/O
K6	I/O
N5	I/O
N6	I/O
L6	I/O
M6	I/O
M7	I/O
N7	I/O
N8	I/O
M8	I/O
L8	I/O
K8	I/O
N9	I/O