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[Understanding Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	72
Number of Gates	36000
Voltage - Supply	3V ~ 3.6V, 4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	84-LCC (J-Lead)
Supplier Device Package	84-PLCC (29.31x29.31)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a42mx24-3pl84

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- The Transient Current, page 13 is new (SAR 36930).
- Package names were revised according to standards established in *Package Mechanical Drawings* (SAR 34774)

1.7 Revision 9.0

The following is a summary of the changes in revision 9.0 of this document

- In Table 20, page 23, the limits in VI were changed from -0.5 to VCCI + 0.5 to -0.5 to VCCA + 0.5
- In Table 22, page 25, V_{OH} was changed from 3.7 to 2.4 for the min in industrial and military. V_{IH} had V_{CCI} and that was changed to VCCA

1.8 Revision 6.0

The following is a summary of the changes in revision 6.0 of this document.

- The Ease of Integration, page 1 was updated
- The Temperature Grade Offerings, page 5 is new
- The Speed Grade Offerings, page 5 is new
- The General Description, page 6 was updated
- The MultiPlex I/O Modules, page 11 was updated
- The User Security, page 12 was updated
- Table 6, page 13 was updated
- The Power Dissipation, page 14 was updated.
- The Static Power Component, page 14 was updated
- The Equivalent Capacitance, page 15 was updated
- Figure 13, page 17 was updated
- Table 10, page 18 was updated.
- Figure 14, page 18 was updated.
- Table 11, page 19 was updated.

Table 1 • Product profile

Device	A40MX02	A40MX04	A42MX09	A42MX16	A42MX24	A42MX36
Maximum Flip-Flops	147	273	516	928	1,410	1,822
Clocks	1	1	2	2	2	6
User I/O (maximum)	57	69	104	140	176	202
PCI	–	–	–	–	Yes	Yes
Boundary Scan Test (BST)	–	–	–	–	Yes	Yes
Packages (by pin count)						
PLCC	44, 68	44, 68, 84	84	84	84	–
PQFP	100	100	100, 144, 160	100, 160, 208	160, 208	208, 240
VQFP	80	80	100	100	–	–
TQFP	–	–	176	176	176	–
CQFP	–	–	–	172	–	208, 256
PBGA	–	–	–	–	–	272
CPGA	–	–	132	–	–	–

2.6 Temperature Grade Offerings

Table 4 • Temperature Grade Offerings

Package	A40MX02	A40MX04	A42MX09	A42MX16	A42MX24	A42MX36
PLCC 44	C, I, M	C, I, M				
PLCC 68	C, I, A, M	C, I, M				
PLCC 84		C, I, A, M	C, I, A, M	C, I, M	C, I, M	
PQFP 100	C, I, A, M	C, I, A, M	C, I, A, M	C, I, M		
PQFP 144			C			
PQFP 160			C, I, A, M	C, I, M	C, I, A, M	
PQFP 208				C, I, A, M	C, I, A, M	C, I, A, M
PQFP 240						C, I, A, M
VQFP 80	C, I, A, M	C, I, A, M				
VQFP 100			C, I, A, M	C, I, A, M		
TQFP 176			C, I, A, M	C, I, A, M	C, I, A, M	
PBGA 272						C, I, M
CQFP 172				C, M, B		
CQFP 208						C, M, B
CQFP 256						C, M, B
CPGA 132			C, M, B			

Note: C = Commercial
I = Industrial
A = Automotive
M = Military
B = MIL-STD-883 Class B

2.7 Speed Grade Offerings

Table 5 • Speed Grade Offerings

	-F	Std	-1	-2	-3
C	P	P	P	P	P
I		P	P	P	P
A		P			
M		P	P		
B		P	P		

Note: See the 40MX and 42MX Automotive Family FPGAs datasheet for details on automotive-grade MX offerings.

Contact your local *Microsemi Sales representative* for device availability.

3.3.7 Low Power Mode

42MX devices have been designed with a Low Power Mode. This feature, activated with setting the special LP pin to HIGH for a period longer than 800 ns, is particularly useful for battery-operated systems where battery life is a primary concern. In this mode, the core of the device is turned off and the device consumes minimal power with low standby current. In addition, all input buffers are turned off, and all outputs and bidirectional buffers are tristated. Since the core of the device is turned off, the states of the registers are lost. The device must be re-initialized when exiting Low Power Mode. I/Os can be driven during LP mode, and clock pins should be driven HIGH or LOW and should not float to avoid drawing current. To exit LP mode, the LP pin must be pulled LOW for over 200 μ s to allow for charge pumps to power up, and device initialization will begin.

3.4 Power Dissipation

The general power consumption of MX devices is made up of static and dynamic power and can be expressed with the following equation.

3.4.1 General Power Equation

$$P = [ICC_{\text{standby}} + ICC_{\text{active}}] * V_{CC1} + I_{OL} * V_{OL} * N + I_{OH} * (V_{CC1} - V_{OH}) * M$$

EQ 1

where:

- ICC_{standby} is the current flowing when no inputs or outputs are changing.
- ICC_{active} is the current flowing due to CMOS switching.
- I_{OL} , I_{OH} are TTL sink/source currents.
- V_{OL} , V_{OH} are TTL level output voltages.
- N equals the number of outputs driving TTL loads to V_{OL} .
- M equals the number of outputs driving TTL loads to V_{OH} .

Accurate values for N and M are difficult to determine because they depend on the family type, on design details, and on the system I/O. The power can be divided into two components: static and active.

3.4.2 Static Power Component

The static power due to standby current is typically a small component of the overall power consumption. Standby power is calculated for commercial, worst-case conditions. The static power dissipation by TTL loads depends on the number of outputs driving, and on the DC load current. For instance, a 32-bit bus sinking 4mA at 0.33V will generate 42mW with all outputs driving LOW, and 140mW with all outputs driving HIGH. The actual dissipation will average somewhere in between, as I/Os switch states with time.

3.4.3 Active Power Component

Power dissipation in CMOS devices is usually dominated by the dynamic power dissipation. Dynamic power consumption is frequency-dependent and is a function of the logic and the external I/O. Active power dissipation results from charging internal chip capacitances of the interconnect, unprogrammed antifuses, module inputs, and module outputs, plus external capacitances due to PC board traces and load device inputs. An additional component of the active power dissipation is the totem pole current in the CMOS transistor pairs. The net effect can be associated with an equivalent capacitance that can be combined with frequency and voltage to represent active power dissipation.

The power dissipated by a CMOS circuit can be expressed by the equation:

$$\text{Power}(\mu\text{W}) = C_{EQ} * V_{CCA2}^2 * F(1)$$

EQ 2

where:

- C_{EQ} = Equivalent capacitance expressed in picofarads (pF)

- VCCA = Power supply in volts (V)
- F = Switching frequency in megahertz (MHz)

3.4.4 Equivalent Capacitance

Equivalent capacitance is calculated by measuring ICCactive at a specified frequency and voltage for each circuit component of interest. Measurements have been made over a range of frequencies at a fixed value of VCC. Equivalent capacitance is frequency-independent, so the results can be used over a wide range of operating conditions. Equivalent capacitance values are shown below.

3.4.5 C_{EQ} Values for Microsemi MX FPGAs

Modules (C_{EQM})3.5

Input Buffers (C_{EQI})6.9

Output Buffers (C_{EQO})18.2

Routed Array Clock Buffer Loads (C_{EQCR})1.4

To calculate the active power dissipated from the complete design, the switching frequency of each part of the logic must be known. The equation below shows a piece-wise linear summation over all components.

$$\text{Power} = \text{VCCA}^2 * [(m * C_{EQM} * f_m)_{\text{modules}} + (n * C_{EQI} * f_n)_{\text{inputs}} + (p * (C_{EQO} + C_L) * f_p)_{\text{outputs}} + \\ 0.5 * (q_1 * C_{EQCR} * f_{q1})_{\text{routed_Clk1}} + (r_1 * f_{q1})_{\text{routed_Clk1}} + \\ 0.5 * (q_2 * C_{EQCR} * f_{q2})_{\text{routed_Clk2}} + (r_2 * f_{q2})_{\text{routed_Clk2}}(2)]$$

EQ 3

where:

m = Number of logic modules switching at frequency f_m

n = Number of input buffers switching at frequency f_n

p = Number of output buffers switching at frequency f_p

q₁ = Number of clock loads on the first routed array clock

q₂ = Number of clock loads on the second routed array clock

r₁ = Fixed capacitance due to first routed array clock

r₂ = Fixed capacitance due to second routed array clock

C_{EQM} = Equivalent capacitance of logic modules in pF

C_{EQI} = Equivalent capacitance of input buffers in pF

C_{EQO} = Equivalent capacitance of output buffers in pF

C_{EQCR} = Equivalent capacitance of routed array clock in pF

C_L = Output load capacitance in pF

f_m = Average logic module switching rate in MHz

f_n = Average input buffer switching rate in MHz

f_p = Average output buffer switching rate in MHz

f_{q1} = Average first routed array clock rate in MHz

Table 33 • Timing Parameters for 33 MHz PCI

Symbol	Parameter	PCI		A42MX24		A42MX36		Units
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{SU(PTP)}$	Input Set-Up Time to CLK—Point-to-Point	10, 12 ²	–	1.5	–	1.5	–	ns
t_H	Input Hold to CLK	0	–	0	–	0	–	ns

1. TOFF is system dependent. MX PCI devices have 7.4 ns turn-off time, reflection is typically an additional 10 ns.
 2. REQ# and GNT# are point-to-point signals and have different output valid delay and input setup times than do bussed signals. GNT# has a setup of 10; REW# has a setup of 12.

3.11.6.1 Timing Characteristics

The following tables list the timing characteristics.

**Table 34 • A40MX02 Timing Characteristics (Nominal 5.0 V Operation)
(Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C)**

Parameter / Description	–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays											
t_{PD1}	Single Module	1.2	1.4	1.6	1.9	2.7	ns				
t_{PD2}	Dual-Module Macros	2.7	3.1	3.5	4.1	5.7	ns				
t_{CO}	Sequential Clock-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
t_{GO}	Latch G-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
t_{RS}	Flip-Flop (Latch) Reset-to-Q	1.2	1.4	1.6	1.9	2.7	ns				
Logic Module Predicted Routing Delays¹											
t_{RD1}	FO = 1 Routing Delay	1.3	1.5	1.7	2.0	2.8	ns				
t_{RD2}	FO = 2 Routing Delay	1.8	2.1	2.4	2.8	3.9	ns				
t_{RD3}	FO = 3 Routing Delay	2.3	2.7	3.0	3.6	5.0	ns				
t_{RD4}	FO = 4 Routing Delay	2.9	3.3	3.7	4.4	6.1	ns				
t_{RD8}	FO = 8 Routing Delay	4.9	5.7	6.5	7.6	10.6	ns				
Logic Module Sequential Timing²											
t_{SUD}	Flip-Flop (Latch) Data Input Set-Up	3.1	3.5	4.0	4.7	6.6	ns				
t_{HD}^3	Flip-Flop (Latch) Data Input Hold	0.0	0.0	0.0	0.0	0.0	ns				
t_{SUENA}	Flip-Flop (Latch) Enable Set-Up	3.1	3.5	4.0	4.7	6.6	ns				
t_{HEN}	Flip-Flop (Latch) Enable Hold	0.0	0.0	0.0	0.0	0.0	ns				
t_{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	3.3	3.8	4.3	5.0	7.0	ns				
t_{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width	3.3	3.8	4.3	5.0	7.0	ns				
t_A	Flip-Flop Clock Input Period	4.8	5.6	6.3	7.5	10.4	ns				
f_{MAX}	Flip-Flop (Latch) Clock Frequency (FO = 128)	181	168	154	134	80	MHz				

Table 36 • A40MX04 Timing Characteristics (Nominal 5.0 V Operation) (continued)(Worst-Case Commercial Conditions, VCC = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t _{ENLZ}	Enable Pad LOW to Z	5.9	6.8	7.7	9.0	12.6	ns				
d _{TLH}	Delta LOW to HIGH	0.02	0.02	0.03	0.03	0.04	ns/pF				
d _{THL}	Delta HIGH to LOW	0.03	0.03	0.03	0.04	0.06	ns/pF				

Table 39 • A42MX09 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing⁵											
t _{DLH}	Data-to-Pad HIGH		3.4		3.8		4.3		5.1		7.1 ns
t _{DHL}	Data-to-Pad LOW		4.0		4.5		5.1		6.1		8.3 ns
t _{ENZH}	Enable Pad Z to HIGH		3.7		4.1		4.6		5.5		7.6 ns
t _{ENZL}	Enable Pad Z to LOW		4.1		4.5		5.1		6.1		8.5 ns
t _{ENHZ}	Enable Pad HIGH to Z		6.9		7.6		8.6		10.2		14.2 ns
t _{ENLZ}	Enable Pad LOW to Z		7.5		8.3		9.4		11.1		15.5 ns
t _{GLH}	G-to-Pad HIGH		5.8		6.5		7.3		8.6		12.0 ns
t _{GHL}	G-to-Pad LOW		5.8		6.5		7.3		8.6		12.0 ns
t _{LSU}	I/O Latch Set-Up	0.7		0.8		0.9		1.0		1.4	ns
t _{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad), 64 Clock Loading		8.7		9.7		10.9		12.9		18.0 ns
t _{ACO}	Array Clock-to-Out (Pad-to-Pad), 64 Clock Loading		12.2		13.5		15.4		18.1		25.3 ns
d _{TLH}	Capacity Loading, LOW to HIGH	0.00		0.00		0.00		0.10		0.01	ns/pF
d _{THL}	Capacity Loading, HIGH to LOW	0.09		0.10		0.10		0.10		0.10	ns/pF

Table 39 • A42MX09 Timing Characteristics (Nominal 3.3 V Operation) (continued)(Worst-Case Commercial Conditions, VCCA = 3.0 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
CMOS Output Module Timing⁵											
t _{D LH}	Data-to-Pad HIGH		3.4		3.8		5.5		6.4		9.0 ns
t _{D HL}	Data-to-Pad LOW		4.1		4.5		4.2		5.0		7.0 ns
t _{ENZH}	Enable Pad Z to HIGH		3.7		4.1		4.6		5.5		7.6 ns
t _{ENZL}	Enable Pad Z to LOW		4.1		4.5		5.1		6.1		8.5 ns
t _{ENHZ}	Enable Pad HIGH to Z		6.9		7.6		8.6		10.2		14.2 ns
t _{ENLZ}	Enable Pad LOW to Z		7.5		8.3		9.4		11.1		15.5 ns
t _{GLH}	G-to-Pad HIGH		5.8		6.5		7.3		8.6		12.0 ns
t _{GHL}	G-to-Pad LOW		5.8		6.5		7.3		8.6		12.0 ns
t _{LSU}	I/O Latch Set-Up	0.7		0.8		0.9		1.0		1.4	ns
t _{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0	ns
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad), 64 Clock Loading		8.7		9.7		10.9		12.9		18.0 ns
t _{ACO}	Array Clock-to-Out (Pad-to-Pad), 64 Clock Loading		12.2		13.5		15.4		18.1		25.3 ns
d _{TLH}	Capacity Loading, LOW to HIGH	0.04		0.04		0.05		0.06		0.08	ns/pF
d _{THL}	Capacity Loading, HIGH to LOW	0.05		0.05		0.06		0.07		0.10	ns/pF

- For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.
- Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
- Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
- Set-up and hold timing parameters for the input buffer latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
- Delays based on 35 pF loading.

Table 40 • A42MX16 Timing Characteristics (Nominal 5.0 V Operation) (Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Logic Module Propagation Delays¹											
t _{PD1}	Single Module	1.4		1.5		1.7		2.0		2.8	ns
t _{CO}	Sequential Clock-to-Q	1.4		1.6		1.8		2.1		3.0	ns
t _{GO}	Latch G-to-Q	1.4		1.5		1.7		2.0		2.8	ns
t _{RS}	Flip-Flop (Latch) Reset-to-Q	1.6		1.7		2.0		2.3		3.3	ns
Logic Module Predicted Routing Delays²											
t _{RD1}	FO = 1 Routing Delay	0.8		0.9		1.0		1.2		1.6	ns
t _{RD2}	FO = 2 Routing Delay	1.0		1.2		1.3		1.5		2.1	ns

Table 44 • A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, TJ = 70°C)

Parameter / Description	-3 Speed		-2 Speed		-1 Speed		Std Speed		-F Speed		Units
	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL Output Module Timing⁵ (Continued)											
t _{ENLZ}	Enable Pad LOW to Z	4.9	5.5	6.2	7.3	10.2	ns				
t _{GLH}	G-to-Pad HIGH	2.9	3.3	3.7	4.4	6.1	ns				
t _{GHL}	G-to-Pad LOW	2.9	3.3	3.7	4.4	6.1	ns				
t _{LSU}	I/O Latch Output Set-Up	0.5	0.5	0.6	0.7	1.0	ns				
t _{LH}	I/O Latch Output Hold	0.0	0.0	0.0	0.0	0.0	ns				
t _{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O	5.7	6.3	7.1	8.4	11.8	ns				
t _{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O	7.8	8.6	9.8	11.5	16.1	ns				
d _{TLH}	Capacitive Loading, LOW to HIGH	0.07	0.08	0.09	0.10	0.14	ns/pF				
d _{THL}	Capacitive Loading, HIGH to LOW	0.07	0.08	0.09	0.10	0.14	ns/pF				

Clock signal to shift the Boundary Scan Test (BST) data into the device. This pin functions as an I/O when "Reserve JTAG" is not checked in the Designer Software. BST pins are only available in A42MX24 and A42MX36 devices.

TDI, I/OTest Data In

Serial data input for BST instructions and data. Data is shifted in on the rising edge of TCK. This pin functions as an I/O when "Reserve JTAG" is not checked in the Designer Software. BST pins are only available in A42MX24 and A42MX36 devices.

TDO, I/OTest Data Out

Serial data output for BST instructions and test data. This pin functions as an I/O when "Reserve JTAG" is not checked in the Designer Software. BST pins are only available in A42MX24 and A42MX36 devices.

TMS, I/OTest Mode Select

The TMS pin controls the use of the IEEE 1149.1 Boundary Scan pins (TCK, TDI, TDO). In flexible mode when the TMS pin is set LOW, the TCK, TDI and TDO pins are boundary scan pins. Once the boundary scan pins are in test mode, they will remain in that mode until the internal boundary scan state machine reaches the "logic reset" state. At this point, the boundary scan pins will be released and will function as regular I/O pins. The "logic reset" state is reached 5 TCK cycles after the TMS pin is set HIGH. In dedicated test mode, TMS functions as specified in the IEEE 1149.1 specifications. IEEE JTAG specification recommends a 10kΩ pull-up resistor on the pin. BST pins are only available in A42MX24 and A42MX36 devices.

VCC, Supply Voltage

Input supply voltage for 40MX devices

VCCA, Supply Voltage

Supply voltage for array in 42MX devices

VCCI, Supply Voltage

Supply voltage for I/Os in 42MX devices

WD, IOWide Decode Output

When a wide decode module is used in a 42MX device this pin can be used as a dedicated output from the wide decode module. This direct connection eliminates additional interconnect delays associated with regular logic modules. To implement the direct I/O connection, connect an output buffer of any type to the output of the wide decode macro and place this output on one of the reserved WD pins.

Table 47 • PL44

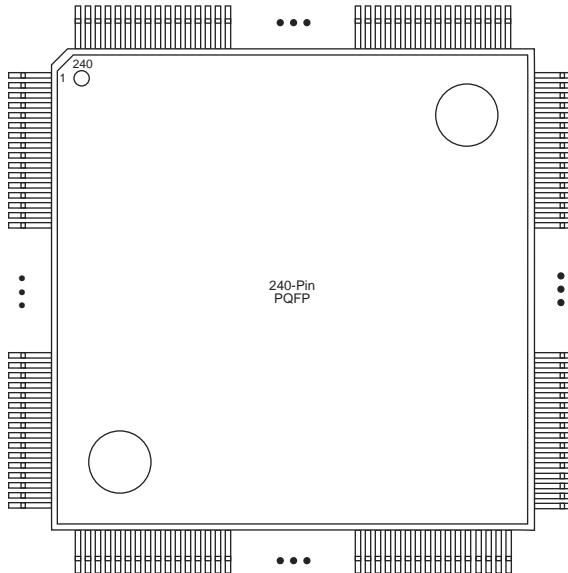
PL44		
Pin Number	A40MX02 Function	A40MX04 Function
21	GND	GND
22	I/O	I/O
23	I/O	I/O
24	I/O	I/O
25	VCC	VCC
26	I/O	I/O
27	I/O	I/O
28	I/O	I/O
29	I/O	I/O
30	I/O	I/O
31	I/O	I/O
32	GND	GND
33	CLK, I/O	CLK, I/O
34	MODE	MODE
35	VCC	VCC
36	SDI, I/O	SDI, I/O
37	DCLK, I/O	DCLK, I/O
38	PRA, I/O	PRA, I/O
39	PRB, I/O	PRB, I/O
40	I/O	I/O
41	I/O	I/O
42	I/O	I/O
43	GND	GND
44	I/O	I/O

Table 49 • PL84

PL84	Pin Number	A40MX04 Function	A42MX09 Function	A42MX16 Function	A42MX24 Function
47	I/O	I/O	I/O	I/O	WD, I/O
48	I/O	I/O	I/O	I/O	I/O
49	I/O	GND	GND	GND	GND
50	I/O	I/O	I/O	I/O	WD, I/O
51	I/O	I/O	I/O	I/O	WD, I/O
52	I/O	SDO, I/O	SDO, I/O	SDO, TDO, I/O	
53	I/O	I/O	I/O	I/O	I/O
54	I/O	I/O	I/O	I/O	I/O
55	I/O	I/O	I/O	I/O	I/O
56	I/O	I/O	I/O	I/O	I/O
57	I/O	I/O	I/O	I/O	I/O
58	I/O	I/O	I/O	I/O	I/O
59	I/O	I/O	I/O	I/O	I/O
60	GND	I/O	I/O	I/O	I/O
61	GND	I/O	I/O	I/O	I/O
62	I/O	I/O	I/O	I/O	TCK, I/O
63	I/O	LP	LP	LP	LP
64	CLK, I/O	VCCA	VCCA	VCCA	VCCA
65	I/O	VCCI	VCCI	VCCI	VCCI
66	MODE	I/O	I/O	I/O	I/O
67	VCC	I/O	I/O	I/O	I/O
68	VCC	I/O	I/O	I/O	I/O
69	I/O	I/O	I/O	I/O	I/O
70	I/O	GND	GND	GND	GND
71	I/O	I/O	I/O	I/O	I/O
72	SDI, I/O	I/O	I/O	I/O	I/O
73	DCLK, I/O	I/O	I/O	I/O	I/O
74	PRA, I/O	I/O	I/O	I/O	I/O
75	PRB, I/O	I/O	I/O	I/O	I/O
76	I/O	SDI, I/O	SDI, I/O	SDI, I/O	SDI, I/O
77	I/O	I/O	I/O	I/O	I/O
78	I/O	I/O	I/O	I/O	WD, I/O
79	I/O	I/O	I/O	I/O	WD, I/O
80	I/O	I/O	I/O	I/O	WD, I/O
81	I/O	PRA, I/O	PRA, I/O	PRA, I/O	PRA, I/O
82	GND	I/O	I/O	I/O	I/O
83	I/O	CLKA, I/O	CLKA, I/O	CLKA, I/O	CLKA, I/O

Table 53 • PQ208

PQ208			
Pin Number	A42MX16 Function	A42MX24 Function	A42MX36 Function
206	I/O	I/O	I/O
207	DCLK, I/O	DCLK, I/O	DCLK, I/O
208	I/O	I/O	I/O

Figure 45 • PQ240

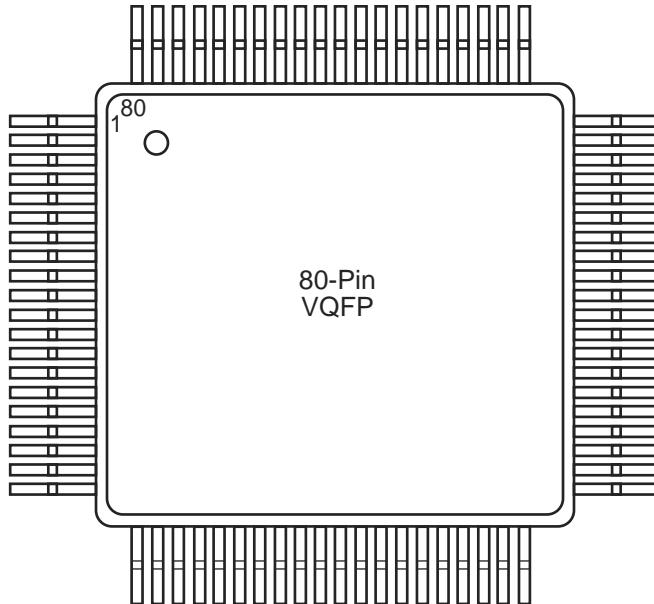
Note: This figure shows the 240-Pin PQFP Package top view.

Table 54 • PQ240

PQ240	
Pin Number	A42MX36 Function
1	I/O
2	DCLK, I/O
3	I/O
4	I/O
5	I/O
6	WD, I/O
7	WD, I/O
8	VCCI
9	I/O
10	I/O
11	I/O
12	I/O
13	I/O
14	I/O

Table 54 • PQ240

PQ240	
Pin Number	A42MX36 Function
237	GND
238	MODE
239	VCCA
240	GND

Figure 46 • VQ80**Table 55 • VQ80**

VQ80		
Pin Number	A40MX02 Function	A40MX04 Function
1	I/O	I/O
2	NC	I/O
3	NC	I/O
4	NC	I/O
5	I/O	I/O
6	I/O	I/O
7	GND	GND
8	I/O	I/O
9	I/O	I/O
10	I/O	I/O
11	I/O	I/O
12	I/O	I/O

Table 56 • VQ100

VQ100		
Pin Number	A42MX09 Function	A42MX16 Function
57	I/O	I/O
58	I/O	I/O
59	I/O	I/O
60	I/O	I/O
61	I/O	I/O
62	LP	LP
63	VCCA	VCCA
64	VCCI	VCCI
65	VCCA	VCCA
66	I/O	I/O
67	I/O	I/O
68	I/O	I/O
69	I/O	I/O
70	GND	GND
71	I/O	I/O
72	I/O	I/O
73	I/O	I/O
74	I/O	I/O
75	I/O	I/O
76	I/O	I/O
77	SDI, I/O	SDI, I/O
78	I/O	I/O
79	I/O	I/O
80	I/O	I/O
81	I/O	I/O
82	GND	GND
83	I/O	I/O
84	I/O	I/O
85	PRA, I/O	PRA, I/O
86	I/O	I/O
87	CLKA, I/O	CLKA, I/O
88	VCCA	VCCA
89	I/O	I/O
90	CLKB, I/O	CLKB, I/O
91	I/O	I/O
92	PRB, I/O	PRB, I/O

Table 59 • CQ256

CQ256	
Pin Number	A42MX36 Function
22	I/O
23	I/O
24	I/O
25	I/O
26	VCCA
27	I/O
28	I/O
29	VCCA
30	VCCI
31	GND
32	VCCA
33	LP
34	TCK, I/O
35	I/O
36	GND
37	I/O
38	I/O
39	I/O
40	I/O
41	I/O
42	I/O
43	I/O
44	I/O
45	I/O
46	I/O
47	I/O
48	GND
49	I/O
50	I/O
51	I/O
52	I/O
53	I/O
54	I/O
55	I/O
56	I/O
57	I/O
58	I/O

Table 61 • PG132

PG132	
Pin Number	A42MX09 Function
G12	VSV
F13	I/O
F12	I/O
F11	I/O
F10	I/O
E13	I/O
D13	I/O
D12	I/O
C13	I/O
B13	I/O
D11	I/O
C12	I/O
A13	I/O
C11	I/O
B12	SDI
B11	I/O
C10	I/O
A12	I/O
A11	I/O
B10	I/O
D8	I/O
A10	I/O
C8	I/O
A9	I/O
B8	PRBA
A8	I/O
B7	CLKA
A7	I/O
B6	CLKB
A6	I/O
C6	PRBB
A5	I/O
D6	I/O
A4	I/O
B4	I/O
A3	I/O
C4	I/O

Table 62 • CQ172

138	I/O
139	I/O
140	I/O
141	GND
142	I/O
143	I/O
144	I/O
145	I/O
146	I/O
147	I/O
148	PROBA
149	I/O
150	CLKA
151	VCC
152	GND
153	I/O
154	CLKB
155	I/O
156	PROBB
157	I/O
158	I/O
159	I/O
160	I/O
161	GND
162	I/O
163	I/O
164	I/O
165	I/O
166	VCCI
167	I/O
168	I/O
169	I/O
170	I/O
171	DCLK