Microchip Technology - A42MX24-3PQ160I Datasheet

Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	125
Number of Gates	36000
Voltage - Supply	3V ~ 3.6V, 4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 85°C (TA)
Package / Case	160-BQFP
Supplier Device Package	160-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a42mx24-3pq160i

Microsemi Corporate Headquarters
One Enterprise, Aliso Viejo,
CA 92656 USA
Within the USA: +1 (800) 713-4113
Outside the USA: +1 (949) 380-6100
Fax: +1 (949) 215-4996
Email: sales.support@microsemi.com
www.microsemi.com

© 2016 Microsemi Corporation. All rights reserved. Microsemi and the Microsemi logo are trademarks of Microsemi Corporation. All other trademarks and service marks are the property of their respective owners.

Microsemi makes no warranty, representation, or guarantee regarding the information contained herein or the suitability of its products and services for any particular purpose, nor does Microsemi assume any liability whatsoever arising out of the application or use of any product or circuit. The products sold hereunder and any other products sold by Microsemi have been subject to limited testing and should not be used in conjunction with mission-critical equipment or applications. Any performance specifications are believed to be reliable but are not verified, and Buyer must conduct and complete all performance and other testing of the products, alone and together with, or installed in, any end-products. Buyer shall not rely on any data and performance specifications or parameters provided by Microsemi. It is the Buyer's responsibility to independently determine suitability of any products and to test and verify the same. The information provided by Microsemi hereunder is provided “as is, where is” and with all faults, and the entire risk associated with such information is entirely with the Buyer. Microsemi does not grant, explicitly or implicitly, to any party any patent rights, licenses, or any other IP rights, whether with regard to such information itself or anything described by such information. Information provided in this document is proprietary to Microsemi, and Microsemi reserves the right to make any changes to the information in this document or to any products and services at any time without notice.

About Microsemi

Microsemi Corporation (Nasdaq: MSCC) offers a comprehensive portfolio of semiconductor and system solutions for aerospace & defense, communications, data center and industrial markets. Products include high-performance and radiation-hardened analog mixed-signal integrated circuits, FPGAs, SoCs and ASICs; power management products; timing and synchronization devices and precise time solutions, setting the world's standard for time; voice processing devices; RF solutions; discrete components; enterprise storage and communication solutions, security technologies and scalable anti-tamper products; Ethernet solutions; Power-over-Ethernet ICs and midspans; as well as custom design capabilities and services. Microsemi is headquartered in Aliso Viejo, California, and has approximately 4,800 employees globally. Learn more at www.microsemi.com.

5172136. 15.0 12/16

Contents

2.4 Plastic Device Resources

Table 2 • **Plastic Device Resources**

	User I/Os											
Device	**PLCC 44-Pin**	**PLCC 68-Pin**	**PLCC 84-Pin**	**PQFP 100-Pin**	**PQFP 144-Pin**	**PQFP 160-Pin**	**PQFP 208-Pin**	**PQFP 240-Pin**	**VQFP 80-Pin**	**VQFP 100-Pin**	**TQFP 176-Pin**	**PBGA 272-Pin**
A40MX02	34	57	–	57	–	–	–	–	57	–	–	–
A40MX04	34	57	69	69	–	–	–	–	69	–	–	–
A42MX09	–	–	72	83	95	101	–	–	–	83	104	–
A42MX16	–	–	72	83	–	125	140	–	–	83	140	–
A42MX24	–	–	72	–	–	125	176	–	–	–	150	–
A42MX36	–	–	–	–	–	–	176	202	–	–	–	202

Note: **Package Definitions:** PLCC = Plastic Leaded Chip Carrier, PQFP = Plastic Quad Flat Pack, TQFP = Thin Quad Flat Pack, VQFP = Very Thin Quad Flat Pack, PBGA = Plastic Ball Grid Array

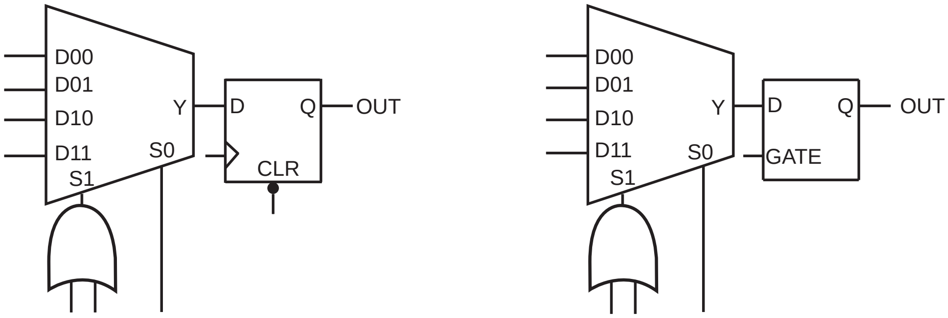
2.5 Ceramic Device Resources

Table 3 • **Ceramic Device Resources**

	User I/Os			
Device	**CPGA 132-Pin**	**CQFP 172-Pin**	**CQFP 208-Pin**	**CQFP 256-Pin**
A42MX09	95			
A42MX16		131		
A42MX36			176	202

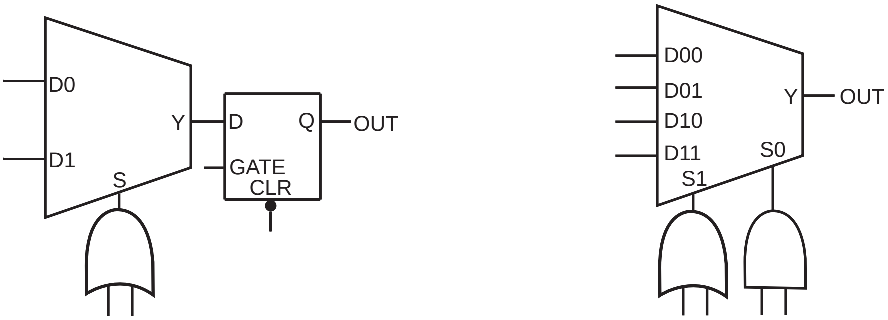
Note: **Package Definitions:** CQFP = Ceramic Quad Flat Pack

Figure 4 • **42MX S-Module Implementation**



Up to 7-Input Function Plus D-Type Flip-Flop with Clear

Up to 7-Input Function Plus Latch



Up to 4-Input Function Plus Latch with Clear

Up to 8-Input Function (Same as C-Module)

A42MX24 and A42MX36 devices contain D-modules, which are arranged around the periphery of the device. D-modules contain wide-decode circuitry, providing a fast, wide-input AND function similar to that found in CPLD architectures (Figure 5, page 9). The D-module allows A42MX24 and A42MX36 devices to perform wide-decode functions at speeds comparable to CPLDs and PALs. The output of the D-module has a programmable inverter for active HIGH or LOW assertion. The D-module output is hardwired to an output pin, and can also be fed back into the array to be incorporated into other logic.

3.2.2 Dual-Port SRAM Modules

The A42MX36 device contains dual-port SRAM modules that have been optimized for synchronous or asynchronous applications. The SRAM modules are arranged in 256-bit blocks that can be configured as 32x8 or 64x4. SRAM modules can be cascaded together to form memory spaces of user-definable width and depth. A block diagram of the A42MX36 dual-port SRAM block is shown in Figure 6, page 9.

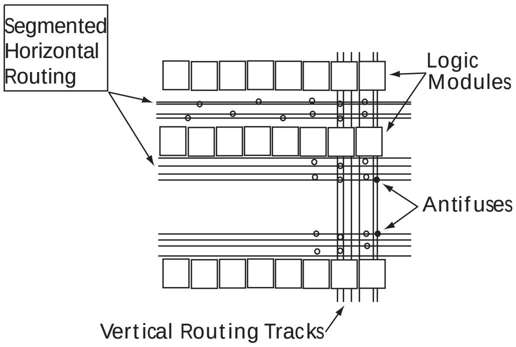
The A42MX36 SRAM modules are true dual-port structures containing independent read and write ports. Each SRAM module contains six bits of read and write addressing (RDAD[5:0] and WRAD[5:0], respectively) for 64x4-bit blocks. When configured in byte mode, the highest order address bits (RDAD5 and WRAD5) are not used. The read and write ports of the SRAM block contain independent clocks (RCLK and WCLK) with programmable polarities offering active HIGH or LOW implementation. The SRAM block contains eight data inputs (WD[7:0]), and eight outputs (RD[7:0]), which are connected to segmented vertical routing tracks.

The A42MX36 dual-port SRAM blocks provide an optimal solution for high-speed buffered applications requiring FIFO and LIFO queues. The ACTgen Macro Builder within Microsemi's designer software provides capability to quickly design memory functions with the SRAM blocks. Unused SRAM blocks can be used to implement registers for other user logic within the design.

3.2.3.3 Antifuse Structures

An antifuse is a “normally open” structure. The use of antifuses to implement a programmable logic device results in highly testable structures as well as efficient programming algorithms. There are no pre-existing connections; temporary connections can be made using pass transistors. These temporary connections can isolate individual antifuses to be programmed and individual circuit structures to be tested, which can be done before and after programming. For instance, all metal tracks can be tested for continuity and shorts between adjacent tracks, and the functionality of all logic modules can be verified.

Figure 7 • **MX Routing Structure**



3.2.4 Clock Networks

The 40MX devices have one global clock distribution network (CLK). A signal can be put on the CLK network by being routed through the CLKBUF buffer.

In 42MX devices, there are two low-skew, high-fanout clock distribution networks, referred to as CLKA and CLKB. Each network has a clock module (CLKMOD) that can select the source of the clock signal from any of the following (Figure 8, page 11):

- Externally from the CLKA pad, using CLKBUF buffer
- Externally from the CLKB pad, using CLKBUF buffer
- Internally from the CLKINTA input, using CLKINT buffer
- Internally from the CLKINTB input, using CLKINT buffer

The clock modules are located in the top row of I/O modules. Clock drivers and a dedicated horizontal clock track are located in each horizontal routing channel.

Clock input pads in both 40MX and 42MX devices can also be used as normal I/Os, bypassing the clock networks.

The A42MX36 device has four additional register control resources, called quadrant clock networks (Figure 9, page 11). Each quadrant clock provides a local, high-fanout resource to the contiguous logic modules within its quadrant of the device. Quadrant clock signals can originate from specific I/O pins or from the internal array and can be used as a secondary register clock, register clear, or output enable.

- VCCA = Power supply in volts (V)
- F = Switching frequency in megahertz (MHz)

3.4.4 Equivalent Capacitance

Equivalent capacitance is calculated by measuring ICCactive at a specified frequency and voltage for each circuit component of interest. Measurements have been made over a range of frequencies at a fixed value of VCC. Equivalent capacitance is frequency-independent, so the results can be used over a wide range of operating conditions. Equivalent capacitance values are shown below.

3.4.5 C_{EQ} Values for Microsemi MX FPGAs

Modules (C_{EQM})3.5

Input Buffers (C_{EQI})6.9

Output Buffers (C_{EQO})18.2

Routed Array Clock Buffer Loads (C_{EQCR})1.4

To calculate the active power dissipated from the complete design, the switching frequency of each part of the logic must be known. The equation below shows a piece-wise linear summation over all components.

$$\begin{aligned}
&\text{Power} = \text{VCCA}^2 *[(m \times C_{EQM}*f_m)_{modules} + (n*C_{EQI}*f_n)_{inputs} + {}^{-}(p*(C_{EQO} + C_L)*f_p)_{outputs} + \\
&0.5*(q_1*C_{EQCR}*f_{q1})_{routed\_Clk1} + (r_{1*}f_{q1})_{routed\_Clk1} + \\
&0.5*(q_2*C_{EQCR}*f_{q2})_{routed\_Clk2} + (r_{2*}f_{q2})_{routed\_Clk2}(2)]
\end{aligned}$$

EQ 3

where:

m = Number of logic modules switching at frequency f_m

n = Number of input buffers switching at frequency f_n

p = Number of output buffers switching at frequency f_p

q_1 = Number of clock loads on the first routed array clock

q_2 = Number of clock loads on the second routed array clock

r_1 = Fixed capacitance due to first routed array clock

r_2 = Fixed capacitance due to second routed array clock

C_{EQM} = Equivalent capacitance of logic modules in pF

C_{EQI} = Equivalent capacitance of input buffers in pF

C_{EQO} = Equivalent capacitance of output buffers in pF

C_{EQCR} = Equivalent capacitance of routed array clock in pF

C_L = Output load capacitance in pF

f_m = Average logic module switching rate in MHz

f_n = Average input buffer switching rate in MHz

f_p = Average output buffer switching rate in MHz

f_{q1} = Average first routed array clock rate in MHz reliability. Devices should not be operated outside the recommended operating conditions.

Table 21 • **Recommended Operating Conditions**

Parameter	Commercial	Industrial	Military	Units
Temperature Range*	0 to +70	–40 to +85	–55 to +125	°C
VCCA	4.75 to 5.25	4.5 to 5.5	4.5 to 5.5	V
VCCI	3.14 to 3.47	3.0 to 3.6	3.0 to 3.6	V

Note: *Ambient temperature (T_A) is used for commercial and industrial grades; case temperature (T_C) is used for military grades.

Table 23 • DC Specification (5.0 V PCI Signaling)[1]

			PCI		MX		
Symbol	**Parameter**	**Condition**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
C_{IN}	Input Pin Capacitance			10	—	10	pF
C_{CLK}	CLK Pin Capacitance		5	12	—	10	pF
L_{PIN}	Pin Inductance			20	—	< 8 nH[4]	nH

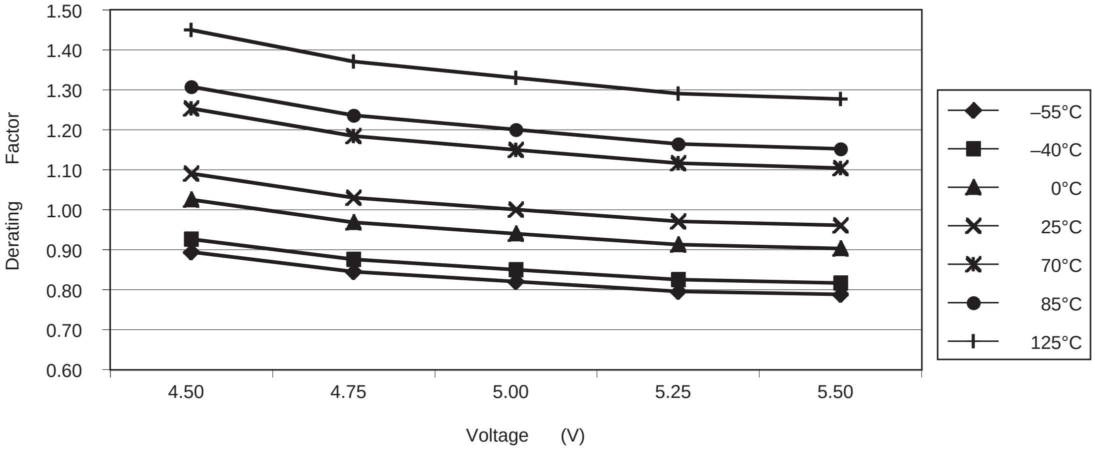
1. PCI Local Bus Specification, Version 2.1, Section 4.2.1.1.
2. Maximum rating for VCCI –0.5 V to 7.0 V
3. VIH(Min) is 2.4V for A42MX36 family. This applies only to VCCI of 5V and is not applicable to VCCI of 3.3V.
4. Dependent upon the chosen package. PCI recommends QFP and BGA packaging to reduce pin inductance and capacitance.

Table 24 • AC Specifications (5.0V PCI Signaling)*

			PCI		MX		
Symbol	**Parameter**	**Condition**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
ICL	Low Clamp Current	–5 < VIN ≤ –1	–25 + (VIN +1) /0.015		–60	–10	mA
Slew (r)	Output Rise Slew Rate	0.4 V to 2.4 V load	1	5	1.8	2.8	V/ns
Slew (f)	Output Fall Slew Rate	2.4 V to 0.4 V load	1	5	2.8	4.3	V/ns

Note: *PCI Local Bus Specification, Version 2.1, Section 4.2.1.2.

Figure 35 • **40MX Junction Temperature and Voltage Derating Curves (Normalized to TJ = 25°C, VCC = 5.0 V)**

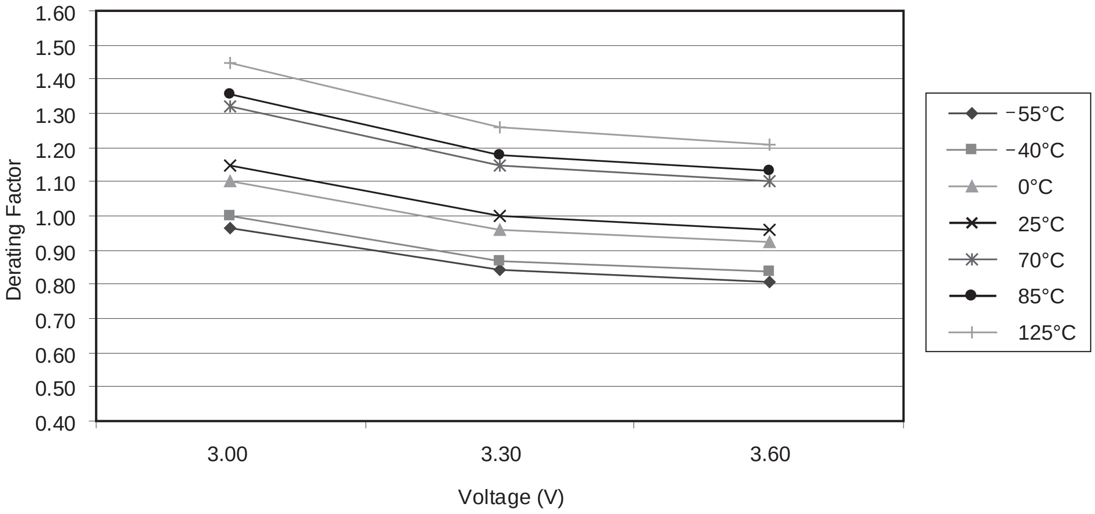


Note: This derating factor applies to all routing and propagation delays

Table 30 • **42MX Temperature and Voltage Derating Factors(Normalized to TJ = 25°C, VCCA = 3.3 V)**

	Temperature						
42MX Voltage	**–55°C**	**–40°C**	**0°C**	**25°C**	**70°C**	**85°C**	**125°C**
3.00	0.97	1.00	1.10	1.15	1.32	1.36	1.45
3.30	0.84	0.87	0.96	1.00	1.15	1.18	1.26
3.60	0.81	0.84	0.92	0.96	1.10	1.13	1.21

Figure 36 • **42MX Junction Temperature and Voltage Derating Curves (Normalized to TJ = 25°C, VCCA = 3.3 V)**



Note: This derating factor applies to all routing and propagation delays

Table 31 • **40MX Temperature and Voltage Derating Factors (Normalized to TJ = 25°C, VCC = 3.3 V)**

	Temperature						
40MX Voltage	**–55°C**	**–40°C**	**0°C**	**25°C**	**70°C**	**85°C**	**125°C**
3.00	1.08	1.12	1.21	1.26	1.50	1.64	2.00
3.30	0.86	0.89	0.96	1.00	1.19	1.30	1.59

Table 38 • **A42MX09 Timing Characteristics (Nominal 5.0 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)**

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
		Min.	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
t_{WASYN}	Flip-Flop (Latch) Asynchronous Pulse Width	4.5		4.9		5.6		6.6		9.2		ns
t_A	Flip-Flop Clock Input Period	3.5		3.8		4.3		5.1		7.1		ns
t_{INH}	Input Buffer Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{INSU}	Input Buffer Latch Set-Up	0.3		0.3		0.4		0.4		0.6		ns
t_{OUTH}	Output Buffer Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{OUTSU}	Output Buffer Latch Set-Up	0.3		0.3		0.4		0.4		0.6		ns
f_{MAX}	Flip-Flop (Latch) Clock Frequency		268		244		224		195		117	MHz

Table 39 • **A42MX09 Timing Characteristics (Nominal 3.3 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)**

Parameter / Description			–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		Units
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Input Module Propagation Delays													
t_{INYH}	Pad-to-Y HIGH			1.5		1.6		1.8		2.17		3.0	ns
t_{INYL}	Pad-to-Y LOW			1.2		1.3		1.4		1.7		2.4	ns
t_{INGH}	G to Y HIGH			1.8		2.0		2.3		2.7		3.7	ns
t_{INGL}	G to Y LOW			1.8		2.0		2.3		2.7		3.7	ns
Input Module Predicted Routing Delays[2]													
t_{IRD1}	FO = 1 Routing Delay			2.8		3.2		3.6		4.2		5.9	ns
t_{IRD2}	FO = 2 Routing Delay			3.2		3.5		4.0		4.7		6.6	ns
t_{IRD3}	FO = 3 Routing Delay			3.5		3.9		4.4		5.2		7.3	ns
t_{IRD4}	FO = 4 Routing Delay			3.9		4.3		4.9		5.7		8.0	ns
t_{IRD8}	FO = 8 Routing Delay			5.2		5.8		6.6		7.7		10.8	ns
Global Clock Network													
t_{CKH}	Input LOW to HIGH	FO = 32 FO = 256		4.1 4.5		4.5 5.0		5.1 5.6		6.0 6.7		8.4 9.3	ns ns
t_{CKL}	Input HIGH to LOW	FO = 32 FO = 256		5.0 5.4		5.5 6.0		6.2 6.8		7.3 8.0		10.2 11.2	ns ns
t_{PWH}	Minimum Pulse Width HIGH	FO = 32 FO = 256	1.7 1.9		1.9 2.1		2.1 2.3		2.5 2.7		3.5 3.8		ns ns
t_{PWL}	Minimum Pulse Width LOW	FO = 32 FO = 256	1.7 1.9		1.9 2.1		2.1 2.3		2.5 2.7		3.5 3.8		ns ns
t_{CKSW}	Maximum Skew	FO = 32 FO = 256		0.4 0.4		0.5 0.5		0.5 0.5		0.6 0.6		0.9 0.9	ns ns
t_{SUEXT}	Input Latch External Set-Up	FO = 32 FO = 256	0.0 0.0		0.0 0.0		0.0 0.0		0.0 0.0		0.0 0.0		ns ns
t_{HEXT}	Input Latch External Hold	FO = 32 FO = 256	3.3 3.7		3.7 4.1		4.2 4.6		4.9 5.5		6.9 7.6		ns ns
t_P	Minimum Period	FO = 32 FO = 256	5.6 6.1		6.2 6.8		6.7 7.4		7.8 8.5		12.9 14.2		ns ns
f_{MAX}	Maximum Frequency	FO = 32 FO = 256		177 161		161 146		148 135		129 117		77 70	MHz MHz

Table 43 • **A42MX24 Timing Characteristics (Nominal 3.3 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)**

			–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
Parameter / Description			**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
Input Module Predicted Routing Delays[2]													
t_{IRD1}	FO = 1 Routing Delay			2.6		2.9		3.2		3.8		5.3	ns
t_{IRD2}	FO = 2 Routing Delay			2.9		3.2		3.6		4.3		6.0	ns
t_{IRD3}	FO = 3 Routing Delay			3.2		3.6		4.0		4.8		6.6	ns
t_{IRD4}	FO = 4 Routing Delay			3.5		3.9		4.4		5.2		7.3	ns
t_{IRD8}	FO = 8 Routing Delay			4.8		5.3		6.1		7.1		10.0	ns
Global Clock Network													
t_{CKH}	Input LOW to HIGH	FO = 32		4.4		4.8		5.5		6.5		9.1	ns
		FO = 486		4.8		5.3		6.0		7.1		10.0	ns
t_{CKL}	Input HIGH to LOW	FO = 32		5.1		5.7		6.4		7.6		10.6	ns
		FO = 486		6.0		6.6		7.5		8.8		12.4	ns
t_{PWH}	Minimum Pulse Width HIGH	FO = 32	3.0		3.3		3.8		4.5		6.3		ns
		FO = 486	3.3		3.7		4.2		4.9		6.9		ns
t_{PWL}	Minimum Pulse Width LOW	FO = 32	3.0		3.4		3.8		4.5		6.3		ns
		FO = 486	3.3		3.7		4.2		4.9		6.9		ns
t_{CKSW}	Maximum Skew	FO = 32		0.8		0.8		1.0		1.1		1.6	ns
		FO = 486		0.8		0.8		1.0		1.1		1.6	ns
t_{SUEXT}	Input Latch External Set-Up	FO = 32	0.0		0.0		0.0		0.0		0.0		ns
		FO = 486	0.0		0.0		0.0		0.0		0.0		ns
TTL Output Module Timing[5]													
t_{DLH}	Data-to-Pad HIGH			3.4		3.8		4.3		5.0		7.1	ns
t_{DHL}	Data-to-Pad LOW			4.0		4.4		5.0		5.9		8.3	ns
t_{ENZH}	Enable Pad Z to HIGH			3.6		4.0		4.5		5.3		7.4	ns
t_{ENZL}	Enable Pad Z to LOW			3.9		4.4		5.0		5.8		8.2	ns
t_{ENHZ}	Enable Pad HIGH to Z			7.2		8.0		9.1		10.7		14.9	ns
t_{ENLZ}	Enable Pad LOW to Z			6.7		7.5		8.5		9.9		13.9	ns
t_{GLH}	G-to-Pad HIGH			4.8		5.3		6.0		7.2		10.0	ns
t_{GHL}	G-to-Pad LOW			4.8		5.3		6.0		7.2		10.0	ns
t_{LSU}	I/O Latch Output Set-Up		0.7		0.7		0.8		1.0		1.4		ns

Table 44 • **A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)**

Parameter / Description			–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Units
t_{SUEXT}	Input Latch External Set-Up	FO = 32 FO = 635	0.0 0.0		0.0 0.0		0.0 0.0		0.0 0.0		0.0 0.0		ns ns
t_{HEXT}	Input Latch External Hold	FO = 32 FO = 635	2.8 3.3		3.2 3.7		3.6 4.2		4.2 4.9		5.9 6.9		ns ns
t_P	Minimum Period ($1/f_{MAX}$)	FO = 32 FO = 635	5.5 6.0		6.1 6.6		6.6 7.2		7.6 8.3		12.7 13.8		ns ns
f_{MAX}	Maximum Datapath Frequency	FO = 32 FO = 635		180 166		164 151		151 139		131 121		79 73	MHz MHz
TTL Output Module Timing[5]													
t_{DLH}	Data-to-Pad HIGH			2.6		2.8		3.2		3.8		5.3	ns
t_{DHL}	Data-to-Pad LOW			3.0		3.3		3.7		4.4		6.2	ns
t_{ENZH}	Enable Pad Z to HIGH			2.7		3.0		3.3		3.9		5.5	ns
t_{ENZL}	Enable Pad Z to LOW			3.0		3.3		3.7		4.3		6.1	ns
t_{ENHZ}	Enable Pad HIGH to Z			5.3		5.8		6.6		7.8		10.9	ns

Table 44 • **A42MX36 Timing Characteristics (Nominal 5.0 V Operation)(Worst-Case Commercial Conditions, VCCA = 4.75 V, T_J = 70°C)**

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Units
CMOS Output Module Timing[5]												
t_{DLH}	Data-to-Pad HIGH		3.5		3.9		4.5		5.2		7.3	ns
t_{DHL}	Data-to-Pad LOW		2.5		2.7		3.1		3.6		5.1	ns
t_{ENZH}	Enable Pad Z to HIGH		2.7		3.0		3.3		3.9		5.5	ns
t_{ENZL}	Enable Pad Z to LOW		2.9		3.3		3.7		4.3		6.1	ns
t_{ENHZ}	Enable Pad HIGH to Z		5.3		5.8		6.6		7.8		10.9	ns
t_{ENLZ}	Enable Pad LOW to Z		4.9		5.5		6.2		7.3		10.2	ns
t_{GLH}	G-to-Pad HIGH		5.0		5.6		6.3		7.5		10.4	ns
t_{GHL}	G-to-Pad LOW		5.0		5.6		6.3		7.5		10.4	ns
t_{LSU}	I/O Latch Set-Up	0.5		0.5		0.6		0.7		1.0		ns
t_{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		5.7		6.3		7.1		8.4		11.8	ns
t_{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.8		8.6		9.8		11.5		16.1	ns
d_{TLH}	Capacitive Loading, LOW to HIGH		0.07		0.08		0.09		0.10		0.14	ns/pF
d_{THL}	Capacitive Loading, HIGH to LOW		0.07		0.08		0.09		0.10		0.14	ns/pF

1. For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
4. Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.
5. Delays based on 35 pF loading.

Table 45 • **A42MX36 Timing Characteristics (Nominal 3.3 V Operation) (Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)**

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Units
Logic Module Combinatorial Functions[1]												
t_{PD}	Internal Array Module Delay		1.9		2.1		2.3		2.7		3.8	ns
t_{PDD}	Internal Decode Module Delay		2.2		2.5		2.8		3.3		4.7	ns
Logic Module Predicted Routing Delays[2]												
t_{RD1}	FO = 1 Routing Delay		1.3		1.5		1.7		2.0		2.7	ns
t_{RD2}	FO = 2 Routing Delay		1.8		2.0		2.3		2.7		3.7	ns
t_{RD3}	FO = 3 Routing Delay		2.3		2.5		2.8		3.4		4.7	ns
t_{RD4}	FO = 4 Routing Delay		2.8		3.1		3.5		4.1		5.7	ns

Table 45 • **A42MX36 Timing Characteristics (Nominal 3.3 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)**

			–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
Parameter / Description			**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
Input Module Predicted Routing Delays[2]													
t_{IRD1}	FO = 1 Routing Delay			2.8		3.1		3.5		4.1		5.7	ns
t_{IRD2}	FO = 2 Routing Delay			3.2		3.5		4.1		4.8		6.7	ns
t_{IRD3}	FO = 3 Routing Delay			3.7		4.1		4.7		5.5		7.7	ns
t_{IRD4}	FO = 4 Routing Delay			4.2		4.6		5.3		6.2		8.7	ns
t_{IRD8}	FO = 8 Routing Delay			6.1		6.8		7.7		9.0		12.6	ns
Global Clock Network													
t_{CKH}	Input LOW to HIGH	FO = 32		4.6		5.1		5.7		6.7		9.3	ns
		FO = 635		5.0		5.6		6.3		7.4		10.3	ns
t_{CKL}	Input HIGH to LOW	FO = 32		5.3		5.9		6.7		7.8		11.0	ns
		FO = 635		6.8		7.6		8.6		10.1		14.1	ns
t_{PWH}	Minimum Pulse	FO = 32	2.5		2.7		3.1		3.6		5.1		ns
	Width HIGH	FO = 635	2.8		3.1		3.5		4.1		5.7		ns
t_{PWL}	Minimum Pulse	FO = 32	2.5		2.7		3.1		3.6		5.1		ns
	Width LOW	FO = 635	2.8		3.1		3.5		4.1		5.7		ns
t_{CKSW}	Maximum Skew	FO = 32		1.0		1.2		1.3		1.5		2.2	ns
		FO = 635		1.0		1.2		1.3		1.5		2.2	ns
t_{SUEXT}	Input Latch	FO = 32	0.0		0.0		0.0		0.0		0.0		ns
	External Set-Up	FO = 635	0.0		0.0		0.0		0.0		0.0		ns
t_{HEXT}	Input Latch	FO = 32	4.0		4.4		5.0		5.9		8.2		ns
	External Hold	FO = 635	4.6		5.2		5.9		6.9		9.6		ns
t_P	Minimum Period	FO = 32	9.2		10.2		11.1		12.7		21.2		ns
	(1/f_{MAX})	FO = 635	9.9		11.0		12.0		13.8		23.0		ns
f_{MAX}	Maximum Datapath	FO = 32		108		98		90		79		47	MHz
	Frequency	FO = 635		100		91		83		73		44	MHz
TTL Output Module Timing[5]													
t_{DLH}	Data-to-Pad HIGH			3.6		4.0		4.5		5.3		7.4	ns
t_{DHL}	Data-to-Pad LOW			4.2		4.6		5.2		6.2		8.6	ns
t_{ENZH}	Enable Pad Z to HIGH			3.7		4.2		4.7		5.5		7.7	ns
t_{ENZL}	Enable Pad Z to LOW			4.1		4.6		5.2		6.1		8.5	ns
t_{ENHZ}	Enable Pad HIGH to Z			7.34		8.2		9.3		10.9		15.3	ns
TTL Output Module Timing[5]													
t_{ENLZ}	Enable Pad LOW to Z			6.9		7.6		8.7		10.2		14.3	ns
t_{GLH}	G-to-Pad HIGH			4.9		5.5		6.2		7.3		10.2	ns
t_{GHL}	G-to-Pad LOW			4.9		5.5		6.2		7.3		10.2	ns
t_{LSU}	I/O Latch Output Set-Up		0.7		0.7		0.8		1.0		1.4		ns
t_{LH}	I/O Latch Output Hold		0.0		0.0		0.0		0.0		0.0		ns
t_{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O			7.9		8.8		10.0		11.8		16.5	ns

Table 45 • **A42MX36 Timing Characteristics (Nominal 3.3 V Operation) *(continued)*(Worst-Case Commercial Conditions, VCCA = 3.0 V, T_J = 70°C)**

Parameter / Description		–3 Speed		–2 Speed		–1 Speed		Std Speed		–F Speed		
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Units
t_{ACO}	Array Latch Clock-to-Out (Pad-to-Pad) 32 I/O		10.9		12.1		13.7		16.1		22.5	ns
d_{TLH}	Capacitive Loading, LOW to HIGH		0.10		0.11		0.12		0.14		0.20	ns/pF
d_{THL}	Capacitive Loading, HIGH to LOW		0.10		0.11		0.12		0.14		0.20	ns/pF
CMOS Output Module Timing[5]												
t_{DLH}	Data-to-Pad HIGH		4.9		5.5		6.2		7.3		10.3	ns
t_{DHL}	Data-to-Pad LOW		3.4		3.8		4.3		5.1		7.1	ns
t_{ENZH}	Enable Pad Z to HIGH		3.7		4.1		4.7		5.5		7.7	ns
t_{ENZL}	Enable Pad Z to LOW		4.1		4.6		5.2		6.1		8.5	ns
t_{ENHZ}	Enable Pad HIGH to Z		7.4		8.2		9.3		10.9		15.3	ns
t_{ENLZ}	Enable Pad LOW to Z		6.9		7.6		8.7		10.2		14.3	ns
t_{GLH}	G-to-Pad HIGH		7.0		7.8		8.9		10.4		14.6	ns
t_{GHL}	G-to-Pad LOW		7.0		7.8		8.9		10.4		14.6	ns
t_{LSU}	I/O Latch Set-Up	0.7		0.7		0.8		1.0		1.4		ns
t_{LH}	I/O Latch Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{LCO}	I/O Latch Clock-to-Out (Pad-to-Pad) 32 I/O		7.9		8.8		10.0		11.8		16.5	ns

1. For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the Timer utility.
4. *Set-up and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.*
5. Delays based on 35 pF loading.

3.12 Pin Descriptions

This section lists the pin descriptions for 40MX and 42MX series FPGAs.

CLK/A/B, I/O Global Clock

Clock inputs for clock distribution networks. CLK is for 40MX while CLKA and CLKB are for 42MX devices. The clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

DCLK, I/ODiagnostic Clock

Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

GND, Ground

Input LOW supply voltage.

I/O, Input/Output

Figure 42 • **PQ144**

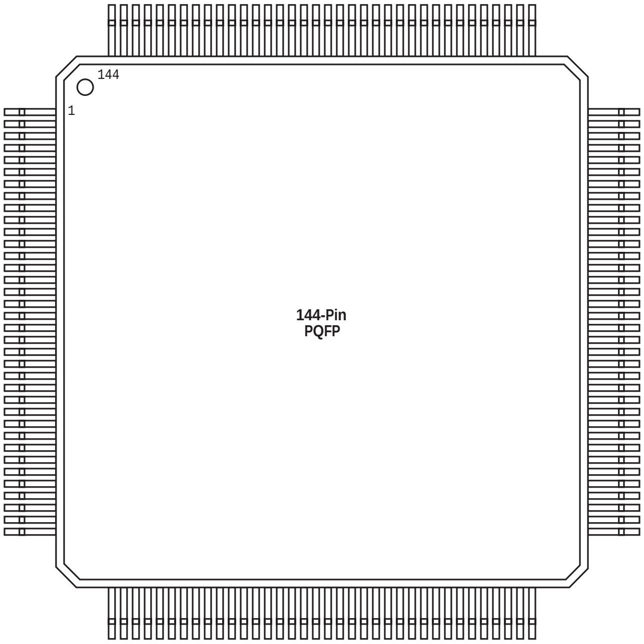


Table 51 • **PQ144**

PQ144	
Pin Number	**A42MX09 Function**
1	I/O
2	MODE
3	I/O
4	I/O
5	I/O

Table 52 • **PQ160**

PQ160			
Pin Number	**A42MX09 Function**	**A42MX16 Function**	**A42MX24 Function**
95	I/O	I/O	I/O
96	I/O	I/O	WD, I/O
97	I/O	I/O	I/O
98	VCCA	VCCA	VCCA
99	GND	GND	GND
100	NC	I/O	I/O
101	I/O	I/O	I/O
102	I/O	I/O	I/O
103	NC	I/O	I/O
104	I/O	I/O	I/O
105	I/O	I/O	I/O
106	I/O	I/O	WD, I/O
107	I/O	I/O	WD, I/O
108	I/O	I/O	I/O
109	GND	GND	GND
110	NC	I/O	I/O
111	I/O	I/O	WD, I/O
112	I/O	I/O	WD, I/O
113	I/O	I/O	I/O
114	NC	VCCI	VCCI
115	I/O	I/O	WD, I/O
116	NC	I/O	WD, I/O
117	I/O	I/O	I/O
118	I/O	I/O	TDI, I/O
119	I/O	I/O	TMS, I/O
120	GND	GND	GND
121	I/O	I/O	I/O
122	I/O	I/O	I/O
123	I/O	I/O	I/O
124	NC	I/O	I/O
125	GND	GND	GND
126	I/O	I/O	I/O
127	I/O	I/O	I/O
128	I/O	I/O	I/O
129	NC	I/O	I/O
130	GND	GND	GND
131	I/O	I/O	I/O

Table 53 • **PQ208**

PQ208			
Pin Number	**A42MX16 Function**	**A42MX24 Function**	**A42MX36 Function**
58	I/O	WD, I/O	WD, I/O
59	I/O	I/O	I/O
60	VCCI	VCCI	VCCI
61	NC	I/O	I/O
62	NC	I/O	I/O
63	I/O	I/O	I/O
64	I/O	I/O	I/O
65	I/O	I/O	QCLKA, I/O
66	I/O	WD, I/O	WD, I/O
67	NC	WD, I/O	WD, I/O
68	NC	I/O	I/O
69	I/O	I/O	I/O
70	I/O	WD, I/O	WD, I/O
71	I/O	WD, I/O	WD, I/O
72	I/O	I/O	I/O
73	I/O	I/O	I/O
74	I/O	I/O	I/O
75	I/O	I/O	I/O
76	I/O	I/O	I/O
77	I/O	I/O	I/O
78	GND	GND	GND
79	VCCA	VCCA	VCCA
80	NC	VCCI	VCCI
81	I/O	I/O	I/O
82	I/O	I/O	I/O
83	I/O	I/O	I/O
84	I/O	I/O	I/O
85	I/O	WD, I/O	WD, I/O
86	I/O	WD, I/O	WD, I/O
87	I/O	I/O	I/O
88	I/O	I/O	I/O
89	NC	I/O	I/O
90	NC	I/O	I/O
91	I/O	I/O	QCLKB, I/O
92	I/O	I/O	I/O
93	I/O	WD, I/O	WD, I/O
94	I/O	WD, I/O	WD, I/O

Table 55 • **VQ80**

VQ80		
Pin Number	**A40MX02 Function**	**A40MX04 Function**
49	I/O	I/O
50	CLK, I/O	CLK, I/O
51	I/O	I/O
52	MODE	MODE
53	VCC	VCC
54	NC	I/O
55	NC	I/O
56	NC	I/O
57	SDI, I/O	SDI, I/O
58	DCLK, I/O	DCLK, I/O
59	PRA, I/O	PRA, I/O
60	NC	NC
61	PRB, I/O	PRB, I/O
62	I/O	I/O
63	I/O	I/O
64	I/O	I/O
65	I/O	I/O
66	I/O	I/O
67	I/O	I/O
68	GND	GND
69	I/O	I/O
70	I/O	I/O
71	I/O	I/O
72	I/O	I/O
73	I/O	I/O
74	VCC	**VCC**
75	I/O	I/O
76	I/O	I/O
77	I/O	I/O
78	I/O	I/O
79	I/O	I/O
80	I/O	I/O