# Silicon Labs - EFM32WG980F128-QFP100T Datasheet

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## What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "Embedded - Microcontrollers"

| Details | |
|---|---|
| Product Status | Discontinued at Digi-Key |
| Core Processor | ARM® Cortex®-M4F |
| Core Size | 32-Bit Single-Core |
| Speed | 48MHz |
| Connectivity | EBI/EMI, I²C, IrDA, SmartCard, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT |
| Number of I/O | 81 |
| Program Memory Size | 128KB (128K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 32K x 8 |
| Voltage - Supply (Vcc/Vdd) | 1.98V ~ 3.8V |
| Data Converters | A/D 8x12b; D/A 2x12b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 100-LQFP |
| Supplier Device Package | 100-LQFP (14x14) |
| Purchase URL | https://www.e-xfl.com/product-detail/silicon-labs/efm32wg980f128-qfp100t |

### 2.1.18 Timer/Counter (TIMER)

The 16-bit general purpose Timer has 3 compare/capture channels for input capture and compare/Pulse-Width Modulation (PWM) output. TIMER0 also includes a Dead-Time Insertion module suitable for motor control applications.

### 2.1.19 Real Time Counter (RTC)

The Real Time Counter (RTC) contains a 24-bit counter and is clocked either by a 32.768 kHz crystal oscillator, or a 32.768 kHz RC oscillator. In addition to energy modes EM0 and EM1, the RTC is also available in EM2. This makes it ideal for keeping track of time since the RTC is enabled in EM2 where most of the device is powered down.

### 2.1.20 Backup Real Time Counter (BURTC)

The Backup Real Time Counter (BURTC) contains a 32-bit counter and is clocked either by a 32.768 kHz crystal oscillator, a 32.768 kHz RC oscillator or a 1 kHz ULFRCO. The BURTC is available in all Energy Modes and it can also run in backup mode, making it operational even if the main power should drain out.

### 2.1.21 Low Energy Timer (LETIMER)

The unique LETIMER™, the Low Energy Timer, is a 16-bit timer that is available in energy mode EM2 in addition to EM1 and EM0. Because of this, it can be used for timing and output generation when most of the device is powered down, allowing simple tasks to be performed while the power consumption of the system is kept at an absolute minimum. The LETIMER can be used to output a variety of waveforms with minimal software intervention. It is also connected to the Real Time Counter (RTC), and can be configured to start counting on compare matches from the RTC.

### 2.1.22 Pulse Counter (PCNT)

The Pulse Counter (PCNT) can be used for counting pulses on a single input or to decode quadrature encoded inputs. It runs off either the internal LFACLK or the PCNTn_S0IN pin as external clock source. The module may operate in energy mode EM0 – EM3.

### 2.1.23 Analog Comparator (ACMP)

The Analog Comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. Inputs can either be one of the selectable internal references or from external pins. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.24 Voltage Comparator (VCMP)

The Voltage Supply Comparator is used to monitor the supply voltage from software. An interrupt can be generated when the supply falls below or rises above a programmable threshold. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.25 Analog to Digital Converter (ADC)

The ADC is a Successive Approximation Register (SAR) architecture, with a resolution of up to 12 bits at up to one million samples per second. The integrated input mux can select inputs from 8 external pins and 6 internal signals.

### 2.1.26 Digital to Analog Converter (DAC)

The Digital to Analog Converter (DAC) can convert a digital value to an analog output voltage. The DAC is fully differential rail-to-rail, with 12-bit resolution. It has two single ended output buffers which can be combined into one differential output. The DAC may be used for a number of different applications such as sensor interfaces or sound output.

# 3 Electrical Characteristics

## 3.1 Test Conditions

### 3.1.1 Typical Values

The typical data are based on $T_{AMB}$=25°C and $V_{DD}$=3.0 V, as defined in Table 3.2 (p. 10), by simulation and/or technology characterisation unless otherwise specified.

### 3.1.2 Minimum and Maximum Values

The minimum and maximum values represent the worst conditions of ambient temperature, supply voltage and frequencies, as defined in Table 3.2 (p. 10), by simulation and/or technology characterisation unless otherwise specified.

## 3.2 Absolute Maximum Ratings

The absolute maximum ratings are stress ratings, and functional operation under such conditions are not guaranteed. Stress beyond the limits specified in Table 3.1 (p. 10) may affect the device reliability or cause permanent damage to the device. Functional operating conditions are given in Table 3.2 (p. 10) .

***Table 3.1. Absolute Maximum Ratings***

| Symbol | Parameter | Condition | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| $T_{STG}$ | Storage temperature range | | -40 | | 150[1] | °C |
| $T_S$ | Maximum soldering temperature | Latest IPC/JEDEC J-STD-020 Standard | | | 260 | °C |
| $V_{DDMAX}$ | External main supply voltage | | 0 | | 3.8 | V |
| $V_{IOPIN}$ | Voltage on any I/O pin | | -0.3 | | $V_{DD}$+0.3 | V |

[1]Based on programmed devices tested for 10000 hours at 150ºC. Storage temperature affects retention of preprogrammed calibration values stored in flash. Please refer to the Flash section in the Electrical Characteristics for information on flash data retention for different temperatures.

## 3.3 General Operating Conditions

### 3.3.1 General Operating Conditions

***Table 3.2. General Operating Conditions***

| Symbol | Parameter | Min | Typ | Max | Unit |
|---|---|---|---|---|---|
| $T_{AMB}$ | Ambient temperature range | -40 | | 85 | °C |
| $V_{DDOP}$ | Operating supply voltage | 1.98 | | 3.8 | V |
| $f_{APB}$ | Internal APB clock frequency | | | 48 | MHz |
| $f_{AHB}$ | Internal AHB clock frequency | | | 48 | MHz |

***Figure 3.5. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 11MHz***

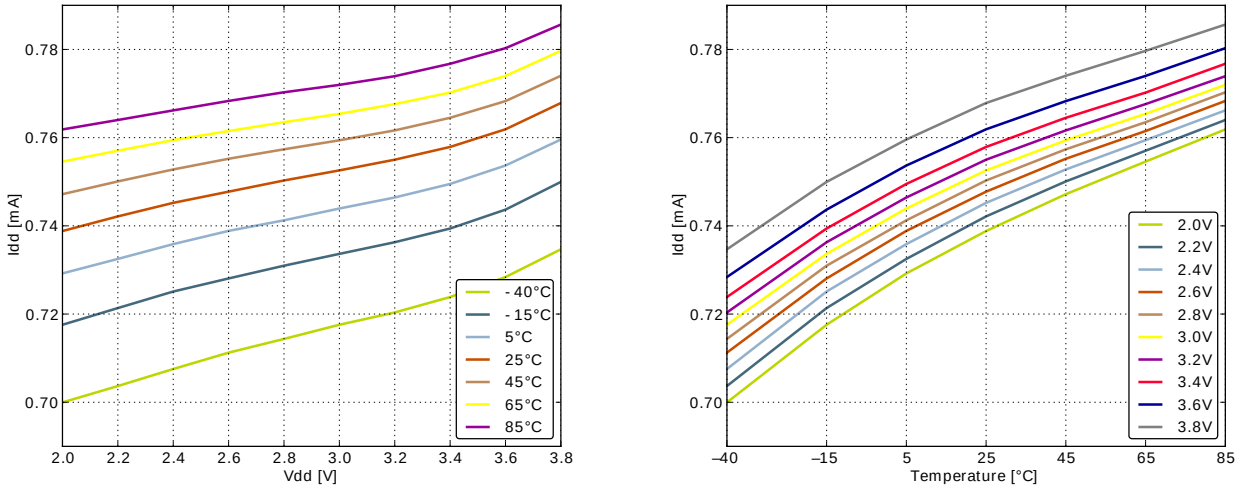



***Figure 3.6. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 6.6MHz***

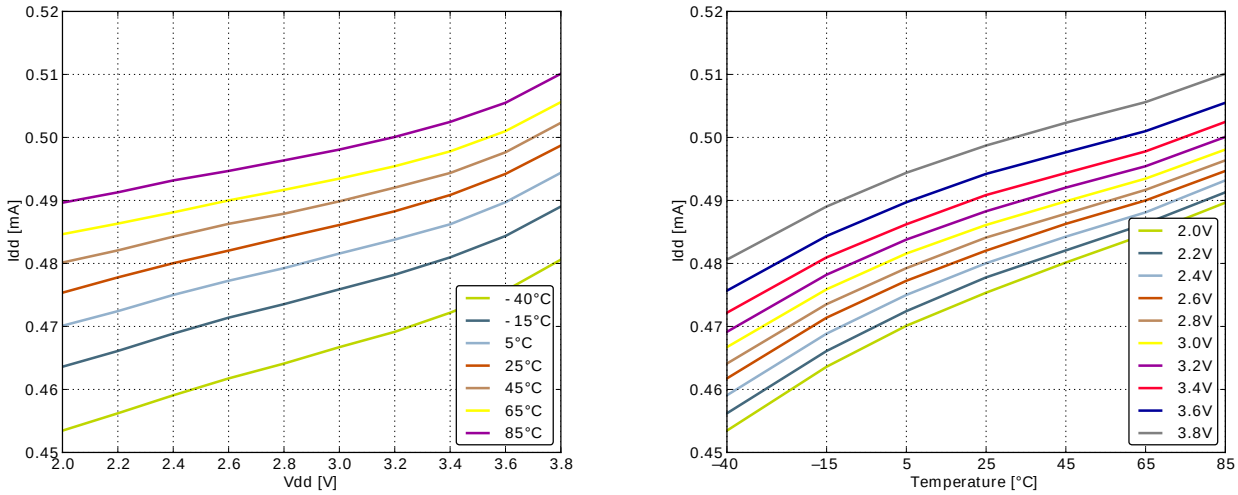
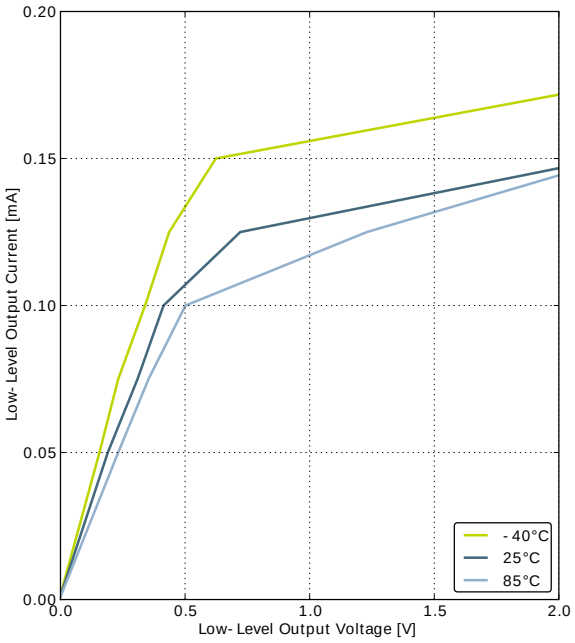
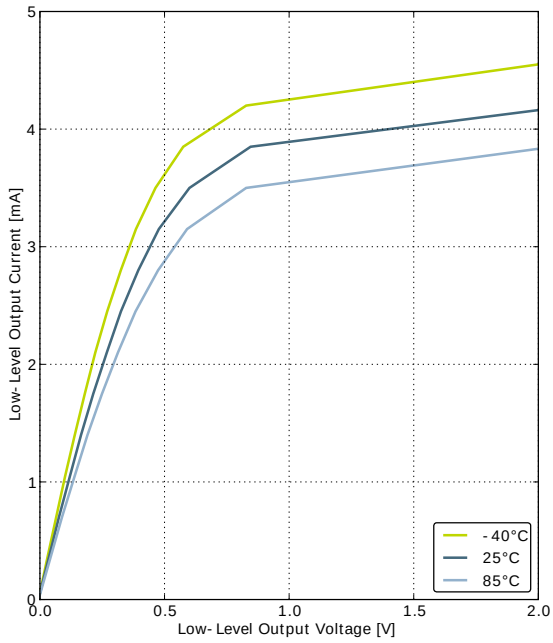


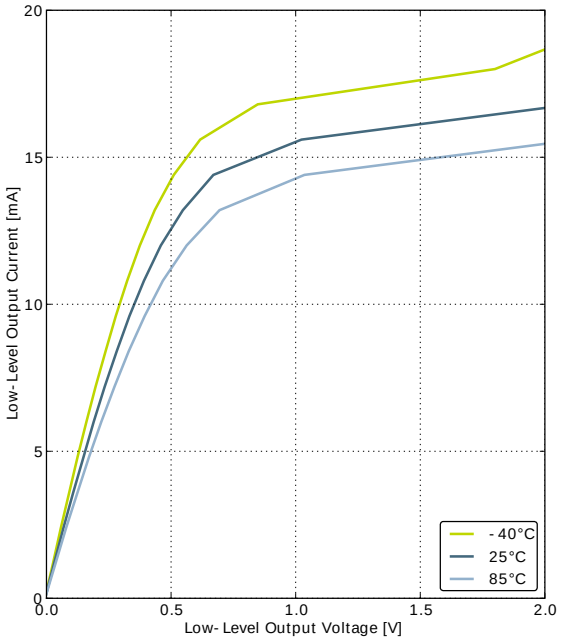
***Figure 3.11. Typical Low-Level Output Current, 2V Supply Voltage***



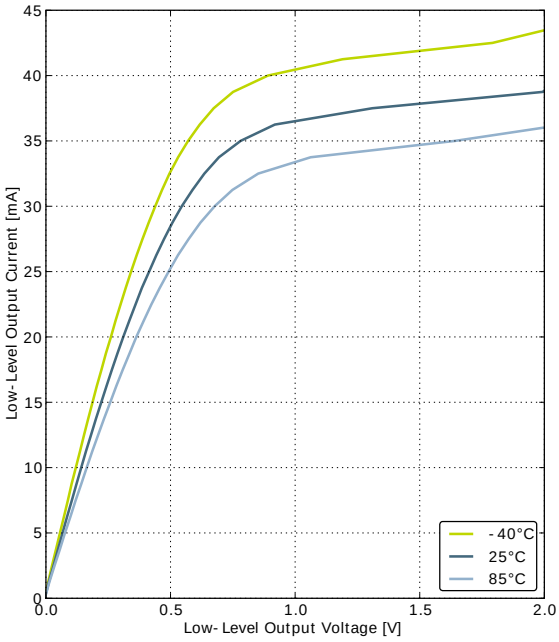

GPIO_Px_CTRL DRIVEMODE = LOWEST




GPIO_Px_CTRL DRIVEMODE = LOW

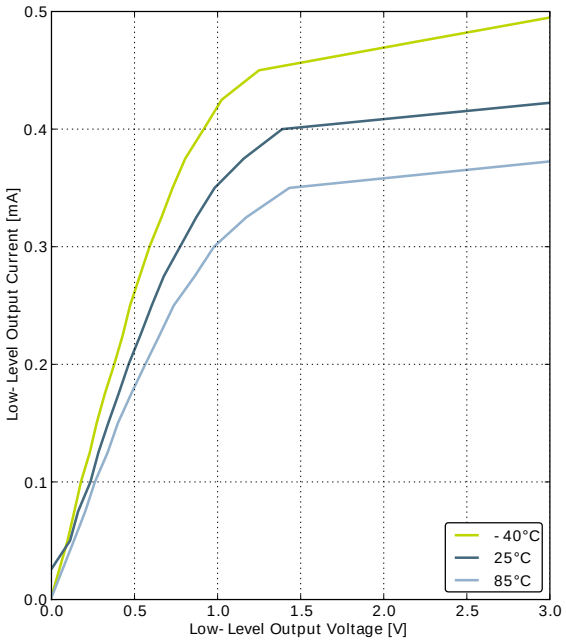



GPIO_Px_CTRL DRIVEMODE = STANDARD

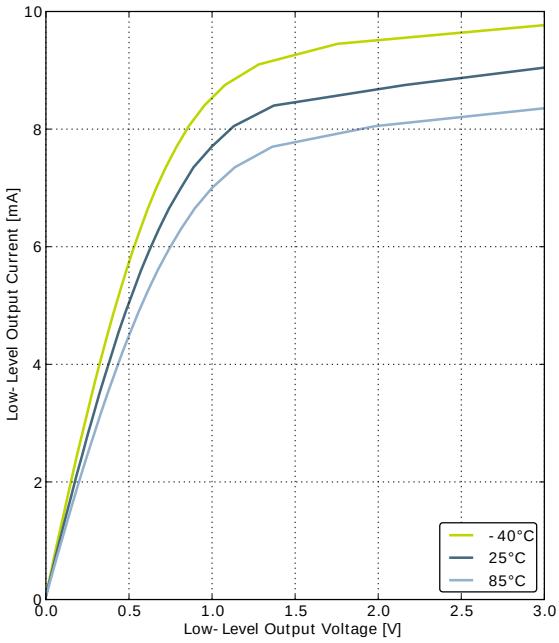



GPIO_Px_CTRL DRIVEMODE = HIGH

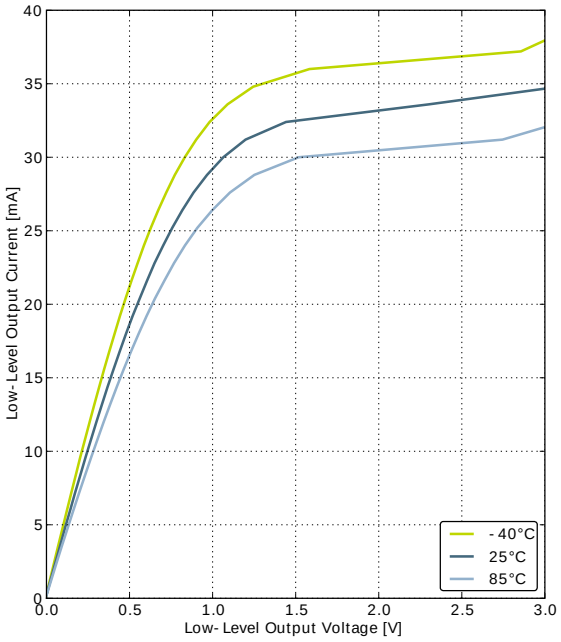
***Figure 3.13. Typical Low-Level Output Current, 3V Supply Voltage***



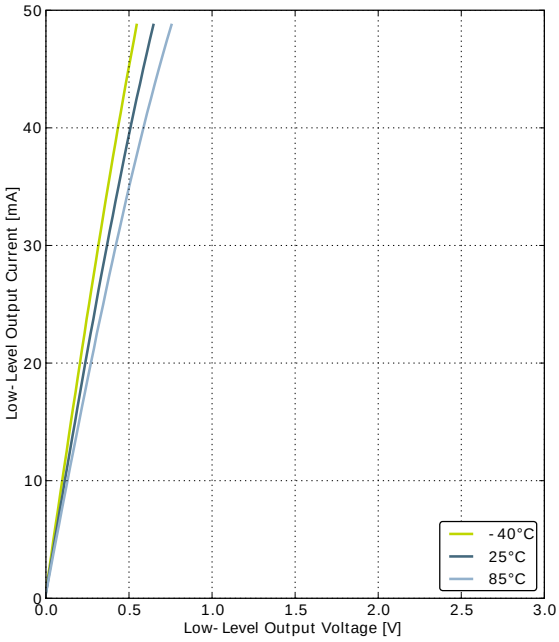

GPIO_Px_CTRL DRIVEMODE = LOWEST




GPIO_Px_CTRL DRIVEMODE = LOW

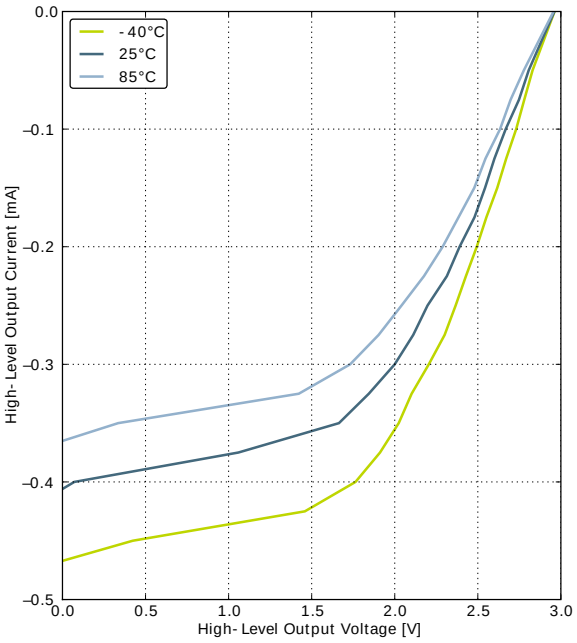



GPIO_Px_CTRL DRIVEMODE = STANDARD

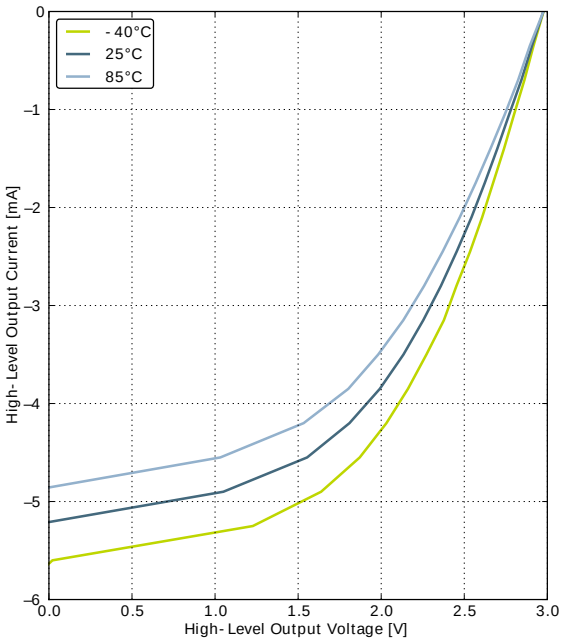



GPIO_Px_CTRL DRIVEMODE = HIGH

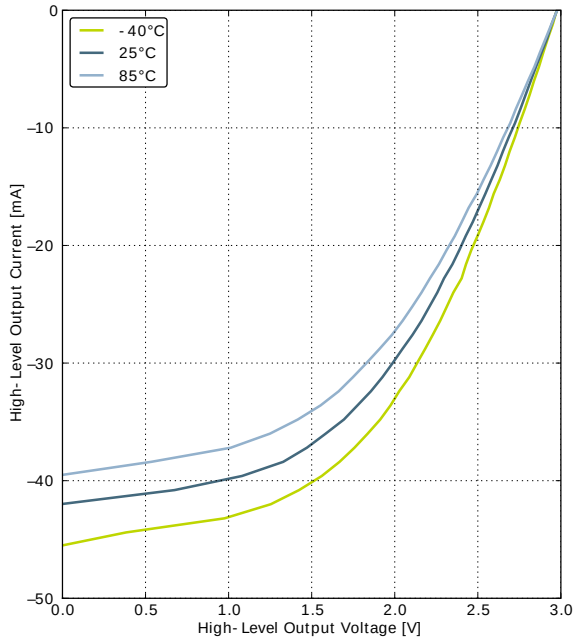
***Figure 3.14. Typical High-Level Output Current, 3V Supply Voltage***



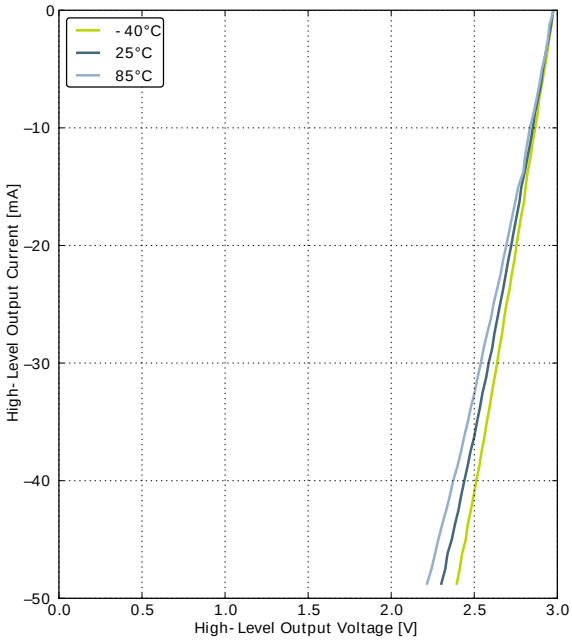

GPIO_Px_CTRL DRIVEMODE = LOWEST




GPIO_Px_CTRL DRIVEMODE = LOW

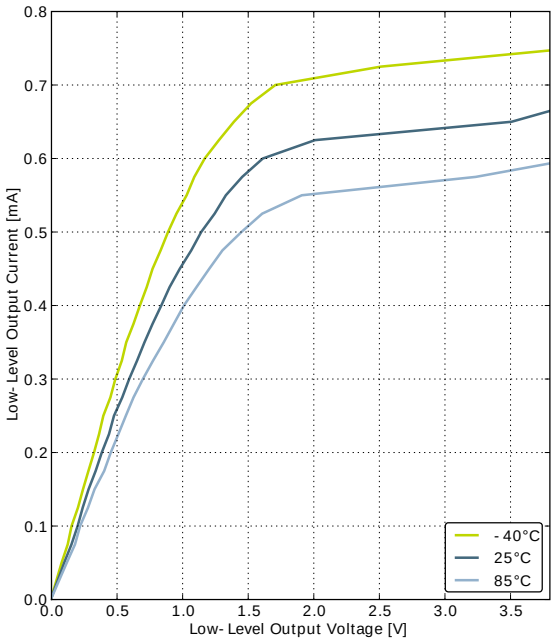



GPIO_Px_CTRL DRIVEMODE = STANDARD

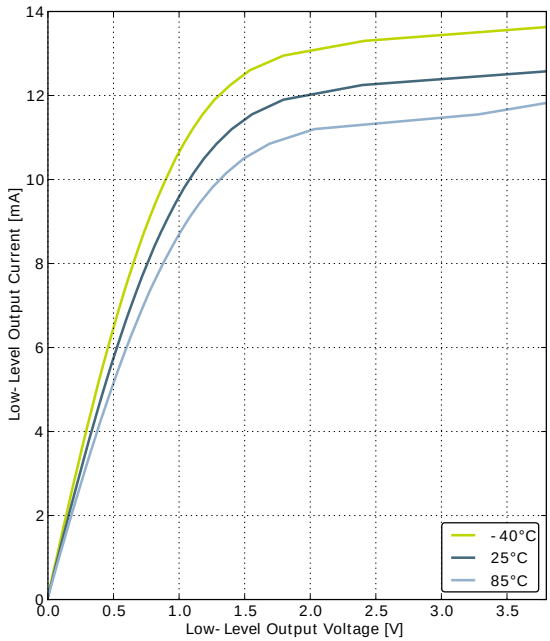



GPIO_Px_CTRL DRIVEMODE = HIGH

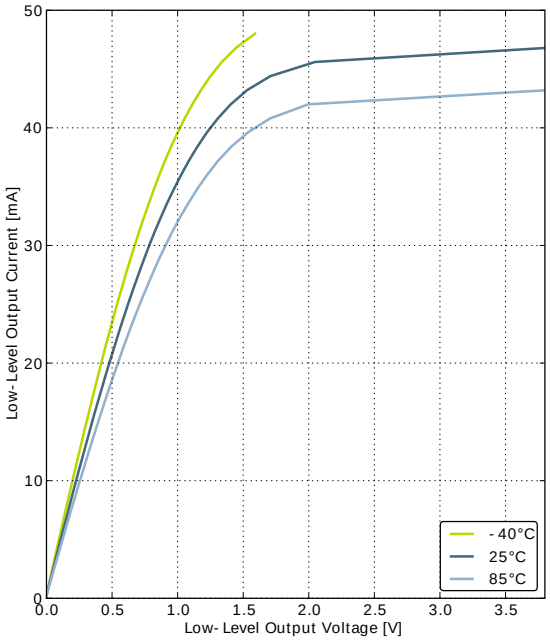
***Figure 3.15. Typical Low-Level Output Current, 3.8V Supply Voltage***



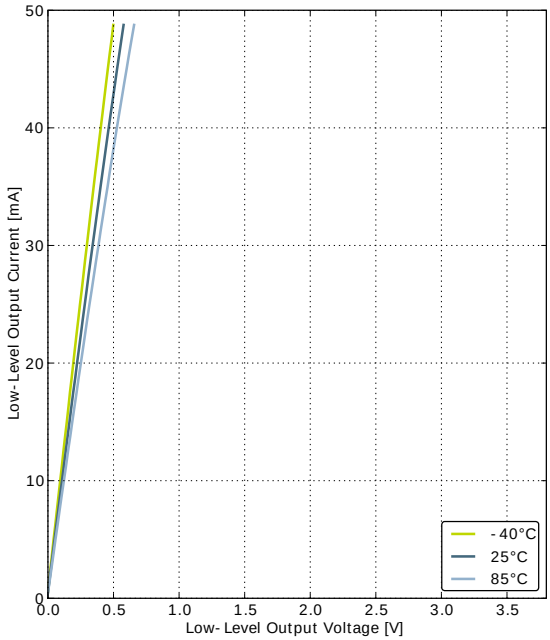

GPIO_Px_CTRL DRIVEMODE = LOWEST




GPIO_Px_CTRL DRIVEMODE = LOW

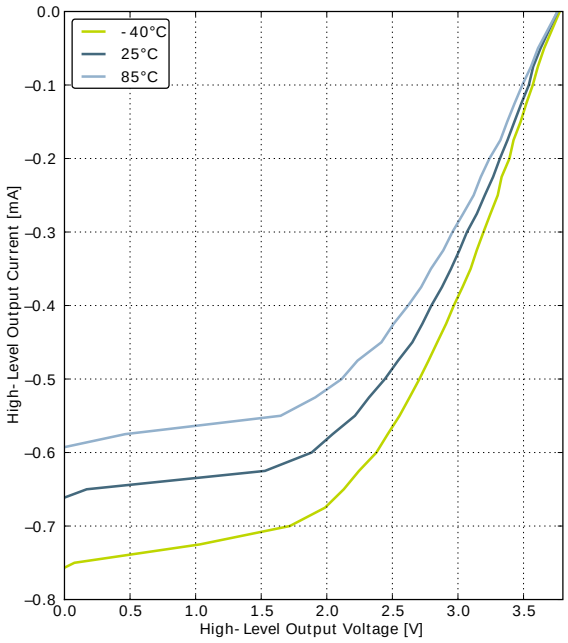



GPIO_Px_CTRL DRIVEMODE = STANDARD

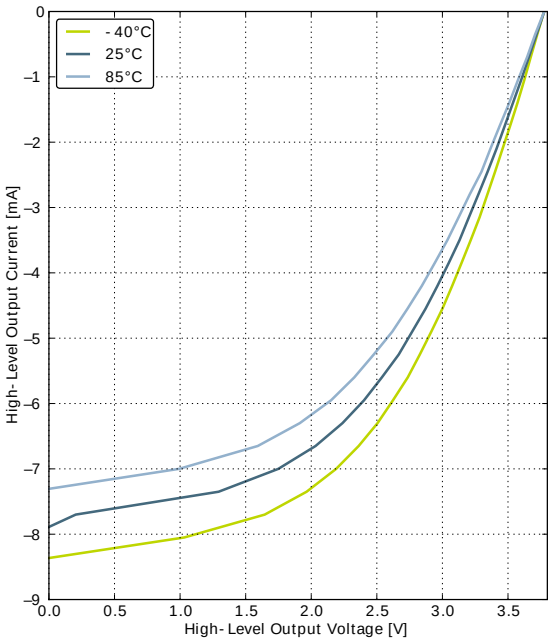



GPIO_Px_CTRL DRIVEMODE = HIGH

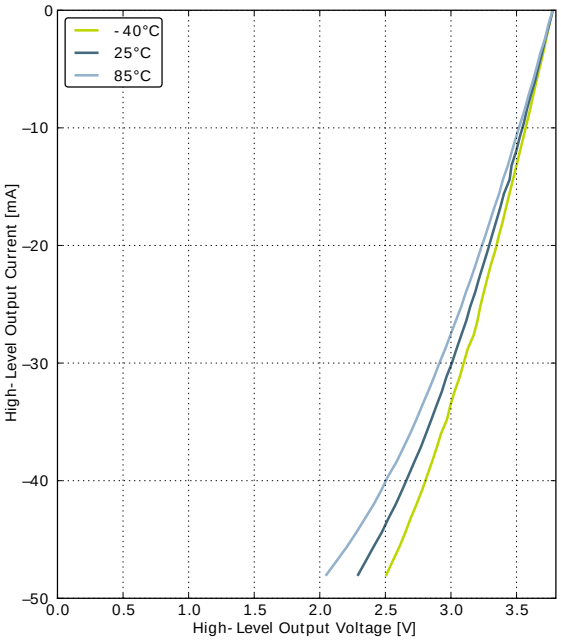
***Figure 3.16. Typical High-Level Output Current, 3.8V Supply Voltage***



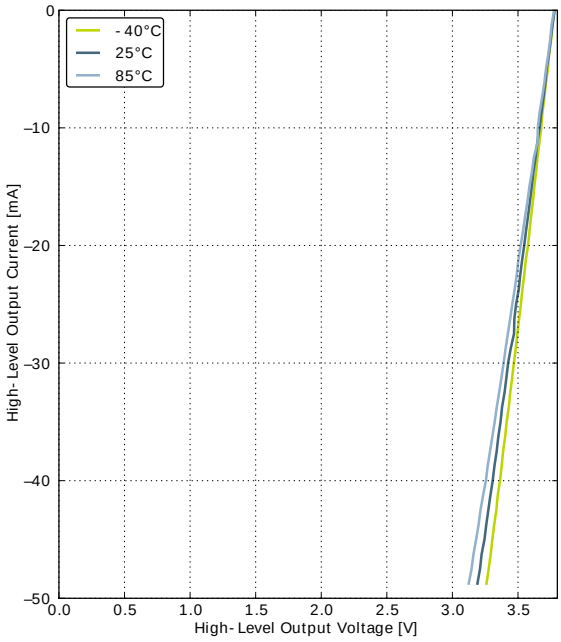

GPIO_Px_CTRL DRIVEMODE = LOWEST




GPIO_Px_CTRL DRIVEMODE = LOW




GPIO_Px_CTRL DRIVEMODE = STANDARD




GPIO_Px_CTRL DRIVEMODE = HIGH

# 3.9 Oscillators

## 3.9.1 LFXO

***Table 3.9. LFXO***

| Symbol | Parameter | Condition | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| $f_{LFXO}$ | Supported nominal crystal frequency | | | 32.768 | | kHz |
| $ESR_{LFXO}$ | Supported crystal equivalent series resistance (ESR) | | | 30 | 120 | kOhm |
| $C_{LFXOL}$ | Supported crystal external load range | | X[1] | | 25 | pF |
| $I_{LFXO}$ | Current consumption for core and buffer after startup. | ESR=30 kOhm, $C_L$=10 pF, LFXOBOOST in CMU_CTRL is 1 | | 190 | | nA |
| $t_{LFXO}$ | Start- up time. | ESR=30 kOhm, $C_L$=10 pF, 40% - 60% duty cycle has been reached, LFXOBOOST in CMU_CTRL is 1 | | 400 | | ms |

[1]See Minimum Load Capacitance ($C_{LFXOL}$) Requirement For Safe Crystal Startup in energyAware Designer in Simplicity Studio

For safe startup of a given crystal, the energyAware Designer in Simplicity Studio contains a tool to help users configure both load capacitance and software settings for using the LFXO. For details regarding the crystal configuration, the reader is referred to application note "AN0016 EFM32 Oscillator Design Consideration".

## 3.9.2 HFXO

***Table 3.10. HFXO***

| Symbol | Parameter | Condition | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| $f_{HFXO}$ | Supported nominal crystal Frequency | | 4 | | 48 | MHz |
| $ESR_{HFXO}$ | Supported crystal equivalent series resistance (ESR) | Crystal frequency 48 MHz | | | 50 | Ohm |
| | | Crystal frequency 32 MHz | | 30 | 60 | Ohm |
| | | Crystal frequency 4 MHz | | 400 | 1500 | Ohm |
| $g_{mHFXO}$ | The transconductance of the HFXO input transistor at crystal startup | HFXOBOOST in CMU_CTRL equals 0b11 | 20 | | | mS |
| $C_{HFXOL}$ | Supported crystal external load range | | 5 | | 25 | pF |
| $I_{HFXO}$ | Current consumption for HFXO after startup | 4 MHz: ESR=400 Ohm, $C_L$=20 pF, HFXOBOOST in CMU_CTRL equals 0b11 | | 85 | | µA |
| | | 32 MHz: ESR=30 Ohm, $C_L$=10 pF, HFXOBOOST in CMU_CTRL equals 0b11 | | 165 | | µA |
| $t_{HFXO}$ | Startup time | 32 MHz: ESR=30 Ohm, $C_L$=10 pF, HFXOBOOST in CMU_CTRL equals 0b11 | | 400 | | µs |

***Figure 3.19. Calibrated HFRCO 7 MHz Band Frequency vs Supply Voltage and Temperature***

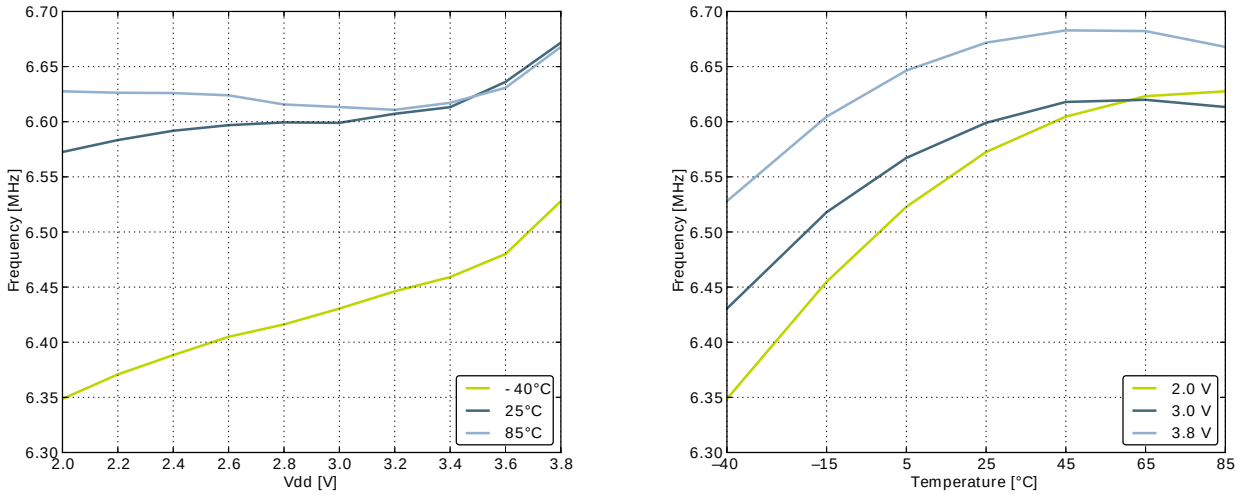



***Figure 3.20. Calibrated HFRCO 11 MHz Band Frequency vs Supply Voltage and Temperature***

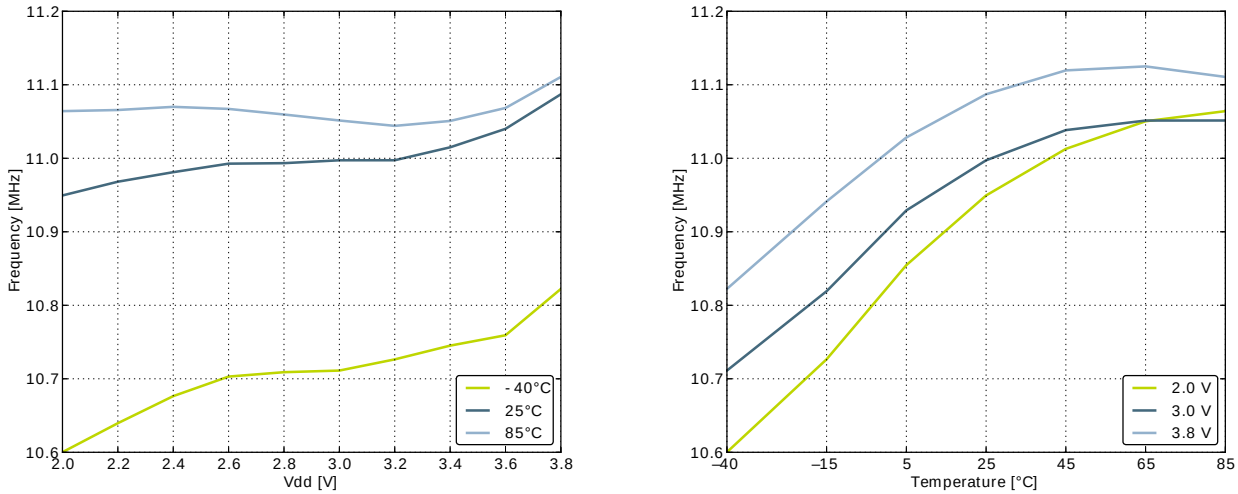



***Figure 3.21. Calibrated HFRCO 14 MHz Band Frequency vs Supply Voltage and Temperature***

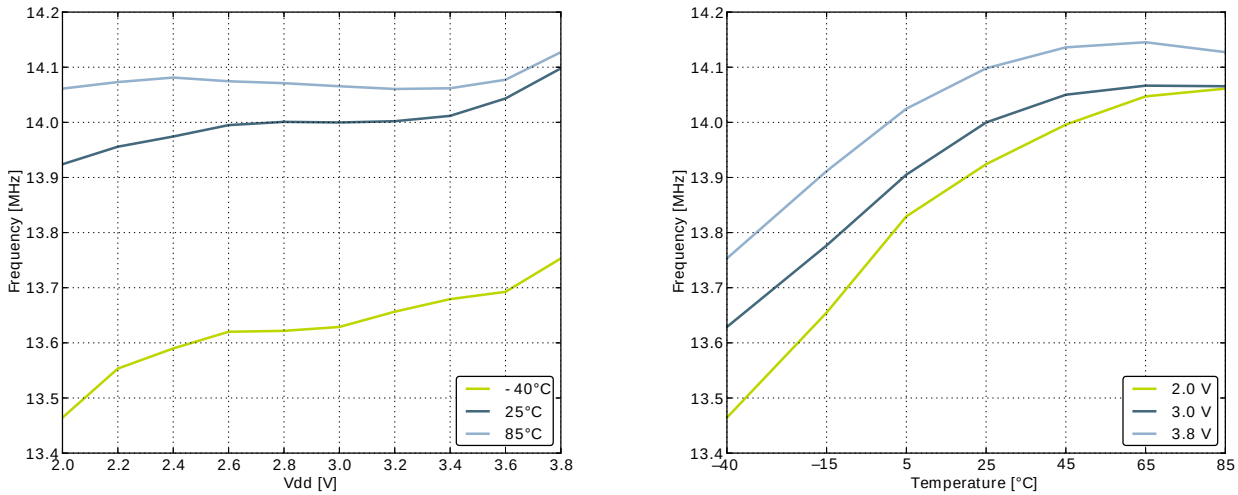
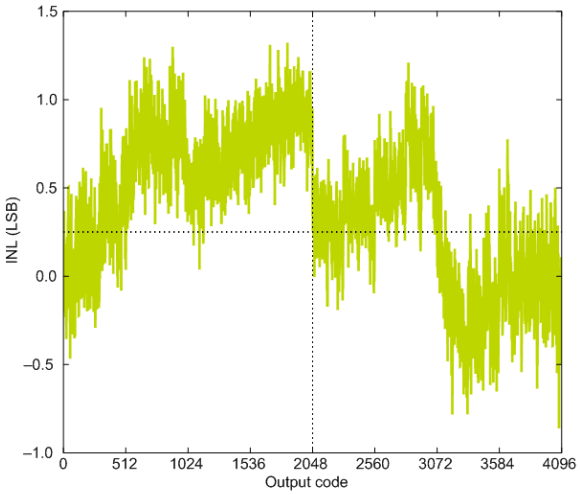
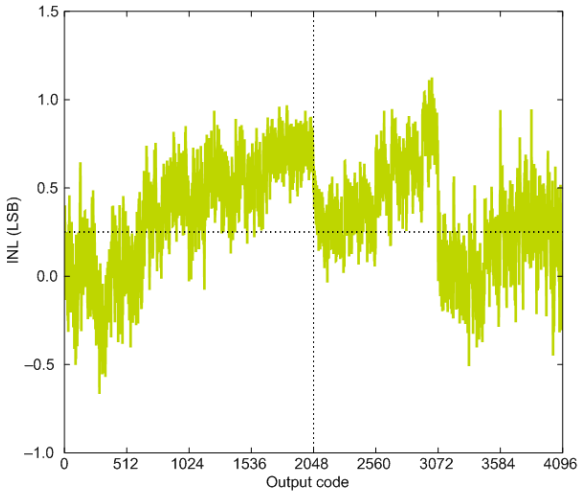


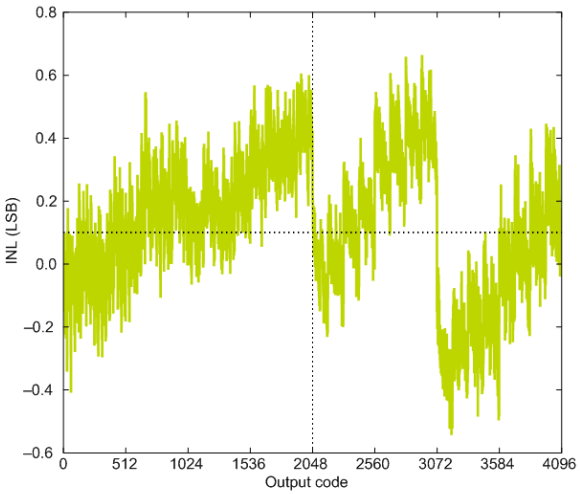
***Figure 3.27. ADC Integral Linearity Error vs Code, Vdd = 3V, Temp = 25°C***



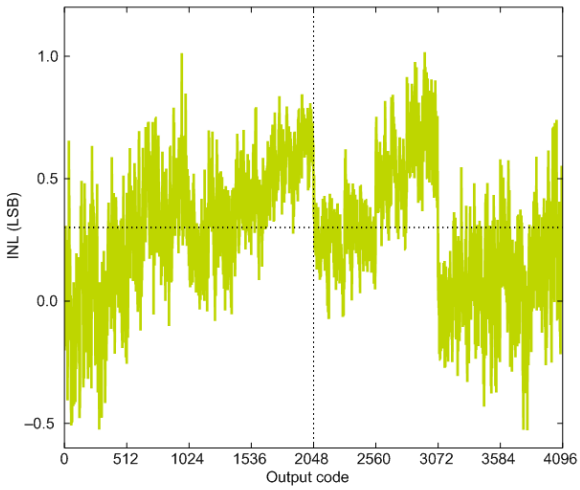

1.25V Reference



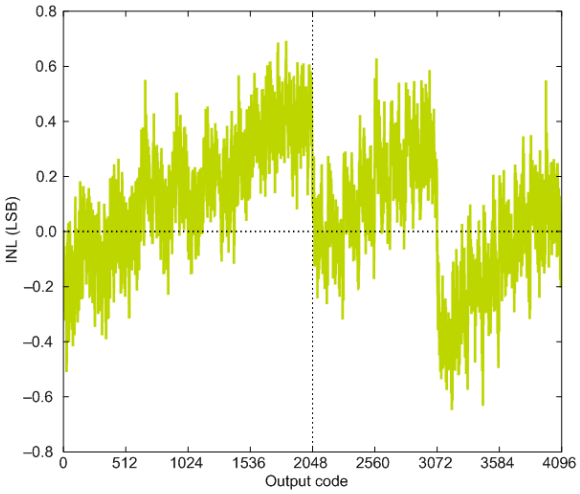

2.5V Reference




2XVDDVSS Reference

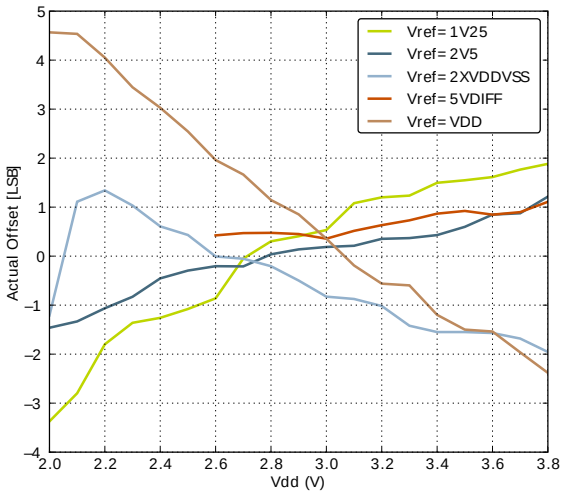



5VDIFF Reference

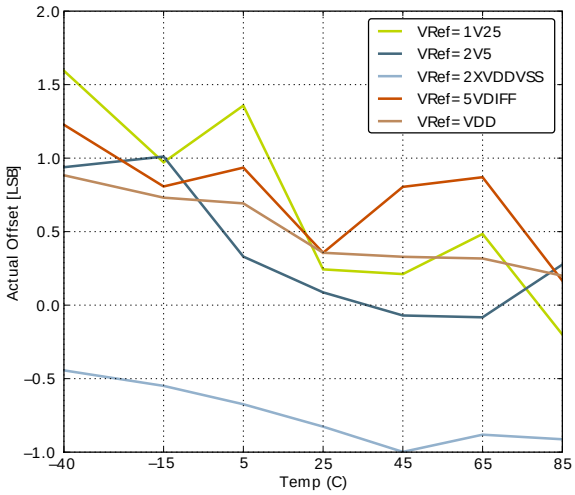



VDD Reference

***Figure 3.29. ADC Absolute Offset, Common Mode = Vdd /2***

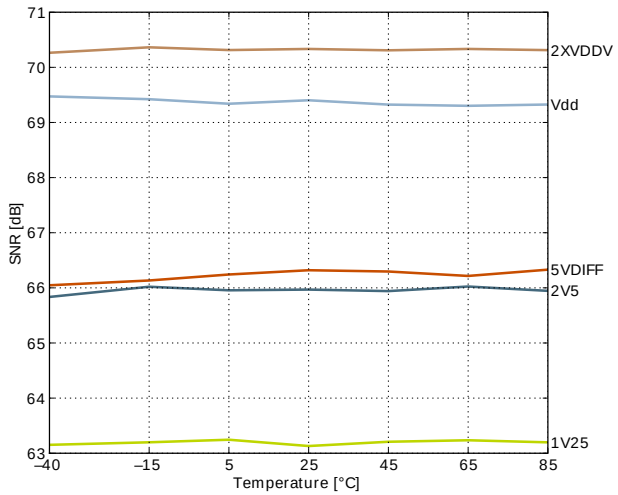



Offset vs Supply Voltage, Temp = 25°C

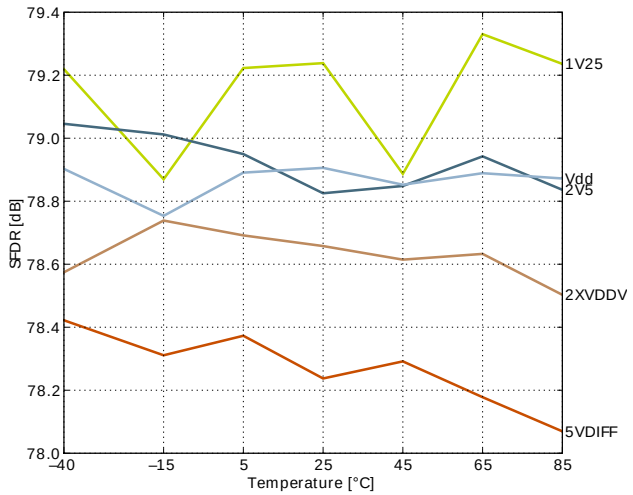



Offset vs Temperature, Vdd = 3V

***Figure 3.30. ADC Dynamic Performance vs Temperature for all ADC References, Vdd = 3V***




Signal to Noise Ratio (SNR)




Spurious-Free Dynamic Range (SFDR)

| Symbol | Parameter | Condition | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| | | $V_{out}$=1V, RESSEL=0, 0.1 Hz<f<1 MHz, OPAxHCMDIS=0 | | 196 | | $\mu V_{RMS}$ |
| | | $V_{out}$=1V, RESSEL=0, 0.1 Hz<f<1 MHz, OPAxHCMDIS=1 | | 229 | | $\mu V_{RMS}$ |
| | | RESSEL=7, 0.1 Hz<f<10 kHz, OPAxHCMDIS=0 | | 1230 | | $\mu V_{RMS}$ |
| | | RESSEL=7, 0.1 Hz<f<10 kHz, OPAxHCMDIS=1 | | 2130 | | $\mu V_{RMS}$ |
| | | RESSEL=7, 0.1 Hz<f<1 MHz, OPAxHCMDIS=0 | | 1630 | | $\mu V_{RMS}$ |
| | | RESSEL=7, 0.1 Hz<f<1 MHz, OPAxHCMDIS=1 | | 2590 | | $\mu V_{RMS}$ |

***Figure 3.32. OPAMP Common Mode Rejection Ratio***

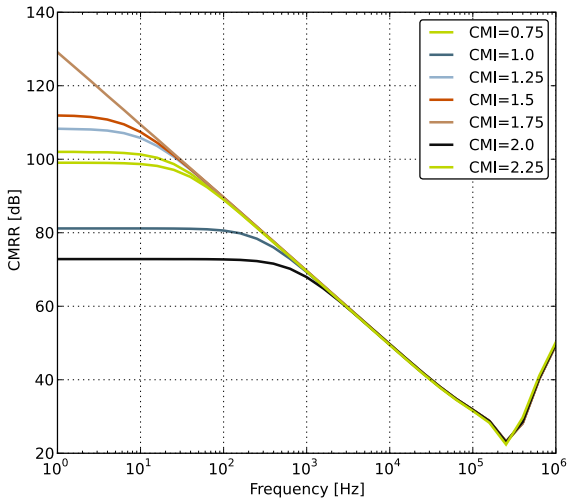
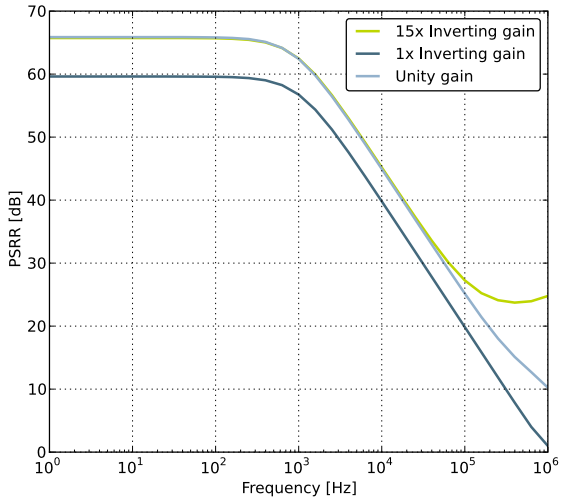
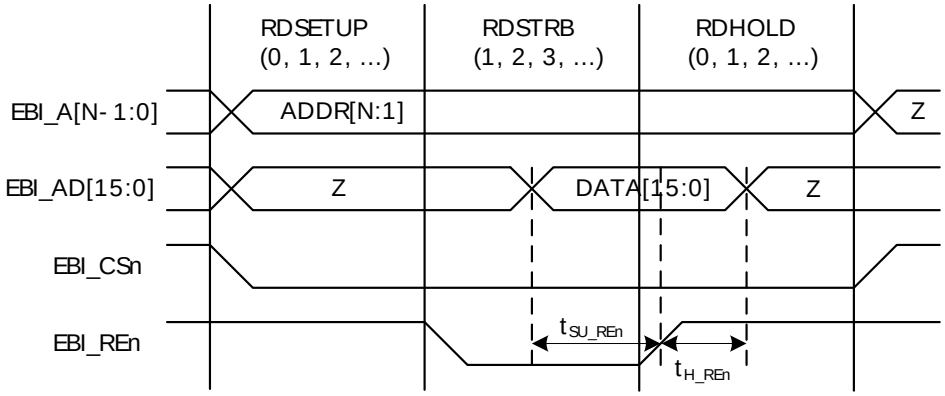



***Figure 3.33. OPAMP Positive Power Supply Rejection Ratio***



### Figure 3.41. EBI Read Enable Related Timing Requirements

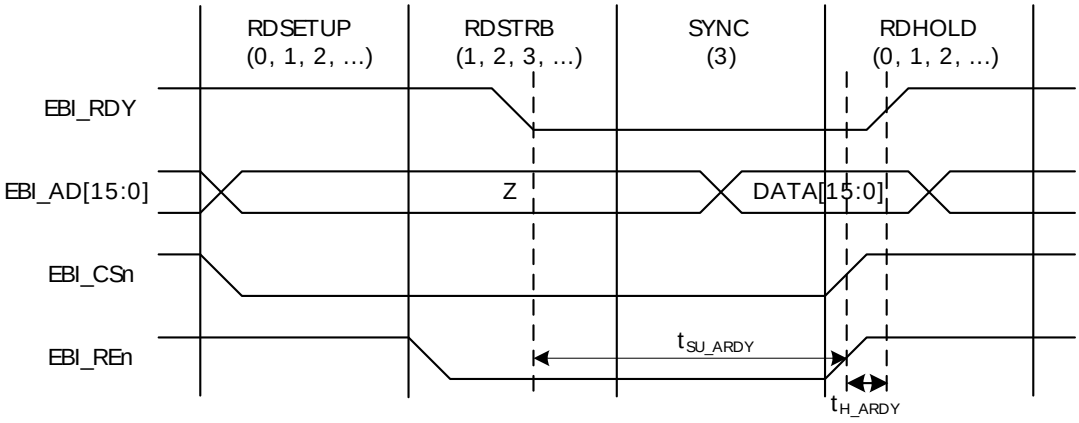



### Table 3.23. EBI Read Enable Related Timing Requirements

| Symbol | Parameter | Min | Typ | Max | Unit |
|---|---|---|---|---|---|
| $t_{SU\_REn}$ [1 2 3 4] | Setup time, from EBI_AD valid to trailing EBI_REn edge | 37 | | | ns |
| $t_{H\_Ren}$ [1 2 3 4] | Hold time, from trailing EBI_REn edge to EBI_AD invalid | -1 | | | ns |

[1]Applies for all addressing modes (figure only shows D16A8).
[2]Applies for both EBI_REn and EBI_NANDREn (figure only shows EBI_REn)
[3]Applies for all polarities (figure only shows active low signals)
[4]Measurement done at 10% and 90% of $V_{DD}$ (figure shows 50% of $_{VDD}$)

### Figure 3.42. EBI Ready/Wait Related Timing Requirements




### Table 3.24. EBI Ready/Wait Related Timing Requirements

| Symbol | Parameter | Min | Typ | Max | Unit |
|---|---|---|---|---|---|
| $t_{SU\_ARDY}$ [1 2 3 4] | Setup time, from EBI_ARDY valid to trailing EBI_REn, EBI_WEn edge | 37 + (3 * $t_{HFCORECLK}$) | | | ns |

# 3.17 I2C

### Table 3.26. I2C Standard-mode (Sm)

| Symbol | Parameter | Min | Typ | Max | Unit |
|---|---|---|---|---|---|
| $f_{SCL}$ | SCL clock frequency | 0 | | 100[1] | kHz |
| $t_{LOW}$ | SCL clock low time | 4.7 | | | µs |
| $t_{HIGH}$ | SCL clock high time | 4.0 | | | µs |
| $t_{SU,DAT}$ | SDA set-up time | 250 | | | ns |
| $t_{HD,DAT}$ | SDA hold time | 8 | | 3450[2,3] | ns |
| $t_{SU,STA}$ | Repeated START condition set-up time | 4.7 | | | µs |
| $t_{HD,STA}$ | (Repeated) START condition hold time | 4.0 | | | µs |
| $t_{SU,STO}$ | STOP condition set-up time | 4.0 | | | µs |
| $t_{BUF}$ | Bus free time between a STOP and a START condition | 4.7 | | | µs |

[1]For the minimum HFPERCLK frequency required in Standard-mode, see the I2C chapter in the EFM32WG Reference Manual.
[2]The maximum SDA hold time ($t_{HD,DAT}$) needs to be met only when the device does not stretch the low time of SCL ($t_{LOW}$).
[3]When transmitting data, this number is guaranteed only when I2Cn_CLKDIV < ((3450*$10^{-9}$ [s] * $f_{HFPERCLK}$ [Hz]) - 4).

### Table 3.27. I2C Fast-mode (Fm)

| Symbol | Parameter | Min | Typ | Max | Unit |
|---|---|---|---|---|---|
| $f_{SCL}$ | SCL clock frequency | 0 | | 400[1] | kHz |
| $t_{LOW}$ | SCL clock low time | 1.3 | | | µs |
| $t_{HIGH}$ | SCL clock high time | 0.6 | | | µs |
| $t_{SU,DAT}$ | SDA set-up time | 100 | | | ns |
| $t_{HD,DAT}$ | SDA hold time | 8 | | 900[2,3] | ns |
| $t_{SU,STA}$ | Repeated START condition set-up time | 0.6 | | | µs |
| $t_{HD,STA}$ | (Repeated) START condition hold time | 0.6 | | | µs |
| $t_{SU,STO}$ | STOP condition set-up time | 0.6 | | | µs |
| $t_{BUF}$ | Bus free time between a STOP and a START condition | 1.3 | | | µs |

[1]For the minimum HFPERCLK frequency required in Fast-mode, see the I2C chapter in the EFM32WG Reference Manual.
[2]The maximum SDA hold time ($t_{HD,DAT}$) needs to be met only when the device does not stretch the low time of SCL ($t_{LOW}$).
[3]When transmitting data, this number is guaranteed only when I2Cn_CLKDIV < ((900*$10^{-9}$ [s] * $f_{HFPERCLK}$ [Hz]) - 4).

| Alternate | LOCATION | | | | | | | |
|---|---|---|---|---|---|---|---|---|
| Functionality | 0 | 1 | 2 | 3 | 4 | 5 | 6 | Description |
| LCD_SEG21/ LCD_COM5 | PB4 | | | | | | | LCD segment line 21. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 5 |
| LCD_SEG22/ LCD_COM6 | PB5 | | | | | | | LCD segment line 22. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 6 |
| LCD_SEG23/ LCD_COM7 | PB6 | | | | | | | LCD segment line 23. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 7 |
| LCD_SEG24 | PF6 | | | | | | | LCD segment line 24. Segments 24, 25, 26 and 27 are controlled by SEGEN6. |
| LCD_SEG25 | PF7 | | | | | | | LCD segment line 25. Segments 24, 25, 26 and 27 are controlled by SEGEN6. |
| LCD_SEG26 | PF8 | | | | | | | LCD segment line 26. Segments 24, 25, 26 and 27 are controlled by SEGEN6. |
| LCD_SEG27 | PF9 | | | | | | | LCD segment line 27. Segments 24, 25, 26 and 27 are controlled by SEGEN6. |
| LCD_SEG28 | PD9 | | | | | | | LCD segment line 28. Segments 28, 29, 30 and 31 are controlled by SEGEN7. |
| LCD_SEG29 | PD10 | | | | | | | LCD segment line 29. Segments 28, 29, 30 and 31 are controlled by SEGEN7. |
| LCD_SEG30 | PD11 | | | | | | | LCD segment line 30. Segments 28, 29, 30 and 31 are controlled by SEGEN7. |
| LCD_SEG31 | PD12 | | | | | | | LCD segment line 31. Segments 28, 29, 30 and 31 are controlled by SEGEN7. |
| LCD_SEG32 | PB0 | | | | | | | LCD segment line 32. Segments 32, 33, 34 and 35 are controlled by SEGEN8. |
| LCD_SEG33 | PB1 | | | | | | | LCD segment line 33. Segments 32, 33, 34 and 35 are controlled by SEGEN8. |
| LCD_SEG34 | PB2 | | | | | | | LCD segment line 34. Segments 32, 33, 34 and 35 are controlled by SEGEN8. |
| LCD_SEG35 | PA7 | | | | | | | LCD segment line 35. Segments 32, 33, 34 and 35 are controlled by SEGEN8. |
| LCD_SEG36 | PA8 | | | | | | | LCD segment line 36. Segments 36, 37, 38 and 39 are controlled by SEGEN9. |
| LCD_SEG37 | PA9 | | | | | | | LCD segment line 37. Segments 36, 37, 38 and 39 are controlled by SEGEN9. |
| LCD_SEG38 | PA10 | | | | | | | LCD segment line 38. Segments 36, 37, 38 and 39 are controlled by SEGEN9. |
| LCD_SEG39 | PA11 | | | | | | | LCD segment line 39. Segments 36, 37, 38 and 39 are controlled by SEGEN9. |
| LES_ALTEX0 | PD6 | | | | | | | LESENSE alternate exite output 0. |
| LES_ALTEX1 | PD7 | | | | | | | LESENSE alternate exite output 1. |
| LES_ALTEX2 | PA3 | | | | | | | LESENSE alternate exite output 2. |
| LES_ALTEX3 | PA4 | | | | | | | LESENSE alternate exite output 3. |
| LES_ALTEX4 | PA5 | | | | | | | LESENSE alternate exite output 4. |
| LES_ALTEX5 | PE11 | | | | | | | LESENSE alternate exite output 5. |
| LES_ALTEX6 | PE12 | | | | | | | LESENSE alternate exite output 6. |
| LES_ALTEX7 | PE13 | | | | | | | LESENSE alternate exite output 7. |
| LES_CH0 | PC0 | | | | | | | LESENSE channel 0. |
| LES_CH1 | PC1 | | | | | | | LESENSE channel 1. |
| LES_CH2 | PC2 | | | | | | | LESENSE channel 2. |

## 4.3 GPIO Pinout Overview

The specific GPIO pins available in *EFM32WG980* is shown in Table 4.3 (p. 70). Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port in indicated by a number from 15 down to 0.

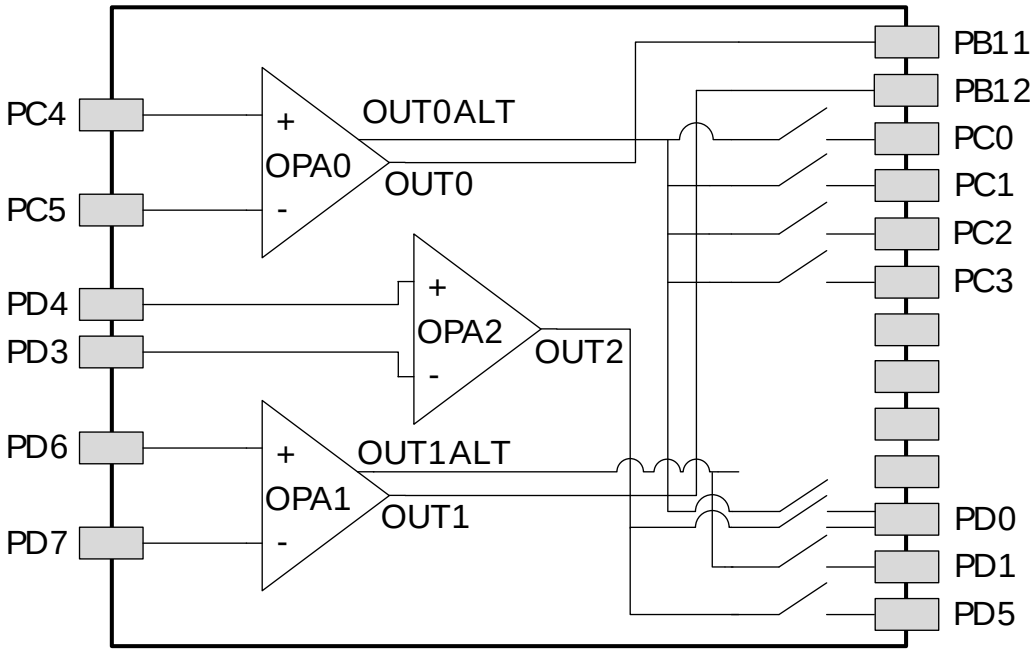
***Table 4.3. GPIO Pinout***

| Port | Pin 15 | Pin 14 | Pin 13 | Pin 12 | Pin 11 | Pin 10 | Pin 9 | Pin 8 | Pin 7 | Pin 6 | Pin 5 | Pin 4 | Pin 3 | Pin 2 | Pin 1 | Pin 0 |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Port A | PA15 | PA14 | PA13 | PA12 | PA11 | PA10 | PA9 | PA8 | PA7 | PA6 | PA5 | PA4 | PA3 | PA2 | PA1 | PA0 |
| Port B | - | PB14 | PB13 | PB12 | PB11 | PB10 | PB9 | PB8 | PB7 | PB6 | PB5 | PB4 | PB3 | PB2 | PB1 | PB0 |
| Port C | - | - | - | - | PC11 | PC10 | PC9 | PC8 | PC7 | PC6 | PC5 | PC4 | PC3 | PC2 | PC1 | PC0 |
| Port D | - | - | - | PD12 | PD11 | PD10 | PD9 | PD8 | PD7 | PD6 | PD5 | PD4 | PD3 | PD2 | PD1 | PD0 |
| Port E | PE15 | PE14 | PE13 | PE12 | PE11 | PE10 | PE9 | PE8 | PE7 | PE6 | PE5 | PE4 | PE3 | PE2 | PE1 | PE0 |
| Port F | - | - | - | PF12 | PF11 | PF10 | PF9 | PF8 | PF7 | PF6 | PF5 | - | - | PF2 | PF1 | PF0 |

## 4.4 Opamp Pinout Overview

The specific opamp terminals available in *EFM32WG980* is shown in Figure 4.2 (p. 70) .

***Figure 4.2. Opamp Pinout***



# 7 Revision History

## 7.1 Revision 1.40

June 13th, 2014

Removed "Preliminary" markings.

Corrected single power supply voltage minimum value from 1.85V to 1.98V.

Added AUXHFRCO to blockdiagram and electrical characteristics.

Updated current consumption data.

Updated transition between energy modes data.

Updated power management data.

Updated GPIO data.

Updated LFRCO, HFRCO and ULFRCO data.

Updated ADC data.

Updated DAC data.

Updated OPAMP data.

Updated ACMP data.

Updated VCMP data.

Added EBI timing chapter.

## 7.2 Revision 1.31

November 21st, 2013

Updated figures.

Updated errata-link.

Updated chip marking.

Added link to Environmental and Quality information.

Re-added missing DAC-data.

## 7.3 Revision 1.30

September 30th, 2013

Added I2C characterization data.

Added SPI characterization data.

Corrected the DAC and OPAMP2 pin sharing information in the Alternate Functionality Pinout section.

Added the USB bootloader information.

# A Disclaimer and Trademarks

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