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#### **Understanding Embedded - Microprocessors**

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

#### **Applications of Embedded - Microprocessors**

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	50MHz
Co-Processors/DSP	Communications; CPM
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10Mbps (1)
SATA	-
USB	USB 1.x (1)
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 95°C (TA)
Security Features	-
Package / Case	256-BBGA
Supplier Device Package	256-PBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/kmpc850dslvr50bu

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



- Gate mode can enable/disable counting
- Interrupt can be masked on reference match and event capture

#### Interrupts

- Eight external interrupt request (IRQ) lines
- Twelve port pins with interrupt capability
- Fifteen internal interrupt sources
- Programmable priority among SCCs and USB
- Programmable highest-priority request
- Single socket PCMCIA-ATA interface
  - Master (socket) interface, release 2.1 compliant
  - Single PCMCIA socket
  - Supports eight memory or I/O windows
- Communications processor module (CPM)
  - 32-bit, Harvard architecture, scalar RISC communications processor (CP)
  - Protocol-specific command sets (for example, GRACEFUL STOP TRANSMIT stops transmission
    after the current frame is finished or immediately if no frame is being sent and CLOSE RXBD
    closes the receive buffer descriptor)
  - Supports continuous mode transmission and reception on all serial channels
  - Up to 8 Kbytes of dual-port RAM
  - Twenty serial DMA (SDMA) channels for the serial controllers, including eight for the four USB endpoints
  - Three parallel I/O registers with open-drain capability
- Four independent baud-rate generators (BRGs)
  - Can be connected to any SCC, SMC, or USB
  - Allow changes during operation
  - Autobaud support option
- Two SCCs (serial communications controllers)
  - Ethernet/IEEE 802.3, supporting full 10-Mbps operation
  - HDLC/SDLC<sup>TM</sup> (all channels supported at 2 Mbps)
  - HDLC bus (implements an HDLC-based local area network (LAN))
  - Asynchronous HDLC to support PPP (point-to-point protocol)
  - AppleTalk<sup>®</sup>
  - Universal asynchronous receiver transmitter (UART)
  - Synchronous UART
  - Serial infrared (IrDA)
  - Totally transparent (bit streams)
  - Totally transparent (frame based with optional cyclic redundancy check (CRC))

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2



- Separate power supply input to operate internal logic at 2.2 V when operating at or below 25 MHz
- Can be dynamically shifted between high frequency (3.3 V internal) and low frequency (2.2 V internal) operation
- Debug interface
  - Eight comparators: four operate on instruction address, two operate on data address, and two operate on data
  - The MPC850 can compare using the =,  $\neq$ , <, and > conditions to generate watchpoints
  - Each watchpoint can generate a breakpoint internally
- 3.3-V operation with 5-V TTL compatibility on all general purpose I/O pins.

## 3 Electrical and Thermal Characteristics

This section provides the AC and DC electrical specifications and thermal characteristics for the MPC850. Table 2 provides the maximum ratings.

**Table 2. Maximum Ratings** 

(GND = 0V)

Rating	Symbol	Value	Unit
Supply voltage	VDDH	-0.3 to 4.0	V
	VDDL	-0.3 to 4.0	V
	KAPWR	-0.3 to 4.0	V
	VDDSYN	-0.3 to 4.0	V
Input voltage <sup>1</sup>	V <sub>in</sub>	GND-0.3 to VDDH + 2.5 V	V
Junction temperature <sup>2</sup>	Тј	0 to 95 (standard) -40 to 95 (extended)	°C
Storage temperature range	T <sub>stg</sub>	-55 to +150	°C

Functional operating conditions are provided with the DC electrical specifications in Table 5. Absolute maximum ratings are stress ratings only; functional operation at the maxima is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage to the device.

CAUTION: All inputs that tolerate 5 V cannot be more than 2.5 V greater than the supply voltage. This restriction

This device contains circuitry protecting against damage due to high-static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for example, either GND or  $V_{CC}$ ). Table 3 provides the package thermal characteristics for the MPC850.

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2

applies to power-up and normal operation (that is, if the MPC850 is unpowered, voltage greater than 2.5 V must not be applied to its inputs).

The MPC850, a high-frequency device in a BGA package, does not provide a guaranteed maximum ambient temperature. Only maximum junction temperature is guaranteed. It is the responsibility of the user to consider power dissipation and thermal management. Junction temperature ratings are the same regardless of frequency rating of the device.

Table 6. Bus Operation Timing <sup>1</sup> (continued)

Num	Characteristic	50 [	ИНz	66 [	ИНz	1 08	ИНz	FEACT	Cap Load	Hait
Num	Characteristic	Min	Max	Min	Max	Min	Max	FFACT	(default 50 pF)	Unit
В9	CLKOUT to A[6–31] RD/WR, BURST, D[0–31], DP[0–3], TSIZ[0–1], REG, RSV, AT[0–3], PTR high-Z	5.00	11.75	7.58	14.33	6.25	13.00	0.250	50.00	ns
B11	CLKOUT to TS, BB assertion	5.00	11.00	7.58	13.58	6.25	12.25	0.250	50.00	ns
B11a	CLKOUT to TA, BI assertion, (When driven by the memory controller or PCMCIA interface)	2.50	9.25	2.50	9.25	2.50	9.25	_	50.00	ns
B12	CLKOUT to TS, BB negation	5.00	11.75	7.58	14.33	6.25	13.00	0.250	50.00	ns
B12a	CLKOUT to TA, BI negation (when driven by the memory controller or PCMCIA interface)	2.50	11.00	2.50	11.00	2.50	11.00	_	50.00	ns
B13	CLKOUT to TS, BB high-Z	5.00	19.00	7.58	21.58	6.25	20.25	0.250	50.00	ns
B13a	CLKOUT to TA, BI high-Z, (when driven by the memory controller or PCMCIA interface)	2.50	15.00	2.50	15.00	2.50	15.00	_	50.00	ns
B14	CLKOUT to TEA assertion	2.50	10.00	2.50	10.00	2.50	10.00	_	50.00	ns
B15	CLKOUT to TEA high-Z	2.50	15.00	2.50	15.00	2.50	15.00	_	50.00	ns
B16	TA, BI valid to CLKOUT(setup time) 5	9.75	_	9.75	_	9.75	_	_	50.00	ns
B16a	TEA, KR, RETRY, valid to CLKOUT (setup time) 5	10.00	_	10.00	_	10.00	_	_	50.00	ns
B16b	BB, BG, BR valid to CLKOUT (setup time) 6	8.50	_	8.50	_	8.50	_	_	50.00	ns
B17	CLKOUT to TA, TEA, BI, BB, BG, BR valid (Hold time).5	1.00	_	1.00	_	1.00		_	50.00	ns
B17a	CLKOUT to KR, RETRY, except TEA valid (hold time)	2.00	_	2.00	_	2.00	_	_	50.00	ns
B18	D[0–31], DP[0–3] valid to CLKOUT rising edge (setup time) <sup>7</sup>	6.00	_	6.00	_	6.00	_	_	50.00	ns
B19	CLKOUT rising edge to D[0–31], DP[0–3] valid (hold time) <sup>7</sup>	1.00	_	1.00	_	1.00	_	_	50.00	ns
B20	D[0-31], DP[0-3] valid to CLKOUT falling edge (setup time) <sup>8</sup>	4.00	_	4.00	_	4.00	_	_	50.00	ns
B21	CLKOUT falling edge to D[0-31], DP[0-3] valid (hold time) <sup>8</sup>	2.00	—	2.00	_	2.00	_	_	_	_

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2



Table 6. Bus Operation Timing <sup>1</sup> (continued)

Num	Chavastavistis	50 I	ИНz	66 I	ИНz	80 1	ИНz	FEACT	Cap Load	l lmit
Num	Characteristic	Min	Max	Min	Max	Min	Max	FFACT	(default 50 pF)	Unit
B28c	CLKOUT falling edge to WE[0-3] negated GPCM write access TRLX = 0,1 CSNT = 1 write access TRLX = 0, CSNT = 1, EBDF = 1	7.00	14.00	11.00	18.00	9.00	16.00	0.375	50.00	ns
B28d	CLKOUT falling edge to CS negated GPCM write access TRLX = 0,1 CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1	_	14.00	_	18.00	_	16.00	0.375	50.00	ns
B29	WE[0-3] negated to D[0-31], DP[0-3] high-Z GPCM write access, CSNT = 0	3.00	_	6.00	_	4.00	_	0.250	50.00	ns
B29a	WE[0-3] negated to D[0-31], DP[0-3] high-Z GPCM write access, TRLX = 0 CSNT = 1, EBDF = 0	8.00	_	13.00	_	11.00	_	0.500	50.00	ns
B29b	CS negated to D[0-31], DP[0-3], high-Z GPCM write access, ACS = 00, TRLX = 0 & CSNT = 0	3.00	_	6.00	_	4.00	_	0.250	50.00	ns
B29c	CS negated to D[0-31], DP[0-3] high-Z GPCM write access, TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0	8.00	_	13.00	_	11.00	_	0.500	50.00	ns
B29d	WE[0-3] negated to D[0-31], DP[0-3] high-Z GPCM write access, TRLX = 1, CSNT = 1, EBDF = 0	28.00	_	43.00	_	36.00	_	1.500	50.00	ns
B29e	CS negated to D[0-31], DP[0-3] high-Z GPCM write access, TRLX = 1, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0	28.00	_	43.00	_	36.00	_	1.500	50.00	ns
B29f	WE[0-3] negated to D[0-31], DP[0-3] high-Z GPCM write access TRLX = 0, CSNT = 1, EBDF = 1	5.00	_	9.00	_	7.00	_	0.375	50.00	ns
B29g	CS negated to D[0–31], DP[0–3] high-Z GPCM write access TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1	5.00	_	9.00	_	7.00	_	0.375	50.00	ns



Table 6. Bus Operation Timing <sup>1</sup> (continued)

NI	Oh ava ataviatia	50 I	MHz	66 1	ИHz	80 1	ИHz	EEA OT	Cap Load	11!4
Num	Characteristic	Min	Max	Min	Max	Min	Max	FFACT	(default 50 pF)	Unit
B31	CLKOUT falling edge to CS valid - as requested by control bit CST4 in the corresponding word in the UPM	1.50	6.00	1.50	6.00	1.50	6.00	_	50.00	ns
B31a	CLKOUT falling edge to $\overline{\text{CS}}$ valid - as requested by control bit CST1 in the corresponding word in the UPM	5.00	12.00	8.00	14.00	6.00	13.00	0.250	50.00	ns
B31b	CLKOUT rising edge to CS valid - as requested by control bit CST2 in the corresponding word in the UPM	1.50	8.00	1.50	8.00	1.50	8.00	_	50.00	ns
B31c	CLKOUT rising edge to CS valid - as requested by control bit CST3 in the corresponding word in the UPM	5.00	12.00	8.00	14.00	6.00	13.00	0.250	50.00	ns
B31d	CLKOUT falling edge to CS valid - as requested by control bit CST1 in the corresponding word in the UPM EBDF = 1	9.00	14.00	13.00	18.00	11.00	16.00	0.375	50.00	ns
B32	CLKOUT falling edge to BS valid - as requested by control bit BST4 in the corresponding word in the UPM	1.50	6.00	1.50	6.00	1.50	6.00	_	50.00	ns
B32a	CLKOUT falling edge to BS valid - as requested by control bit BST1 in the corresponding word in the UPM, EBDF = 0	5.00	12.00	8.00	14.00	6.00	13.00	0.250	50.00	ns
B32b	CLKOUT rising edge to BS valid - as requested by control bit BST2 in the corresponding word in the UPM	1.50	8.00	1.50	8.00	1.50	8.00	_	50.00	ns
B32c	CLKOUT rising edge to BS valid - as requested by control bit BST3 in the corresponding word in the UPM	5.00	12.00	8.00	14.00	6.00	13.00	0.250	50.00	ns
B32d	CLKOUT falling edge to BS valid - as requested by control bit BST1 in the corresponding word in the UPM, EBDF = 1	9.00	14.00	13.00	18.00	11.00	16.00	0.375	50.00	ns
B33	CLKOUT falling edge to GPL valid - as requested by control bit GxT4 in the corresponding word in the UPM	1.50	6.00	1.50	6.00	1.50	6.00	_	50.00	ns

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2



Table 6. Bus Operation Timing <sup>1</sup> (continued)

Nivee	Characteristic	50 I	ИНz	66 N	ИHz	80 1	MHz	EEAOT	Cap Load	Unit
Num	Characteristic	Min	Max	Min	Max	Min	Max	FFACT	(default 50 pF)	Unit
B33a	CLKOUT rising edge to GPL valid - as requested by control bit GxT3 in the corresponding word in the UPM	5.00	12.00	8.00	14.00	6.00	13.00	0.250	50.00	ns
B34	A[6–31] and D[0–31] to $\overline{\text{CS}}$ valid - as requested by control bit CST4 in the corresponding word in the UPM	3.00	_	6.00	_	4.00	_	0.250	50.00	ns
B34a	A[6–31] and D[0–31] to $\overline{\text{CS}}$ valid - as requested by control bit CST1 in the corresponding word in the UPM	8.00	_	13.00	_	11.00	_	0.500	50.00	ns
B34b	A[6–31] and D[0–31] to $\overline{\text{CS}}$ valid - as requested by CST2 in the corresponding word in UPM	13.00	_	21.00	_	17.00	_	0.750	50.00	ns
B35	A[6–31] to CS valid - as requested by control bit BST4 in the corresponding word in UPM	3.00	_	6.00	_	4.00	_	0.250	50.00	ns
B35a	A[6–31] and D[0–31] to $\overline{BS}$ valid - as requested by BST1 in the corresponding word in the UPM	8.00	_	13.00	_	11.00	_	0.500	50.00	ns
B35b	A[6–31] and D[0–31] to BS valid - as requested by control bit BST2 in the corresponding word in the UPM	13.00	_	21.00	_	17.00	_	0.750	50.00	ns
B36	A[6–31] and D[0–31] to GPL valid - as requested by control bit GxT4 in the corresponding word in the UPM	3.00	_	6.00	_	4.00	_	0.250	50.00	ns
B37	UPWAIT valid to CLKOUT falling edge 10	6.00	_	6.00	_	6.00	_	_	50.00	ns
B38	CLKOUT falling edge to UPWAIT valid <sup>10</sup>	1.00	_	1.00	_	1.00	_	_	50.00	ns
B39	AS valid to CLKOUT rising edge	7.00	_	7.00	_	7.00	_	_	50.00	ns
B40	A[6–31], TSIZ[0–1], RD/WR, BURST, valid to CLKOUT rising edge.	7.00	_	7.00	_	7.00	_	_	50.00	ns
B41	TS valid to CLKOUT rising edge (setup time)	7.00	_	7.00	_	7.00	_	_	50.00	ns



Figure 6 provides the timing for the synchronous input signals.

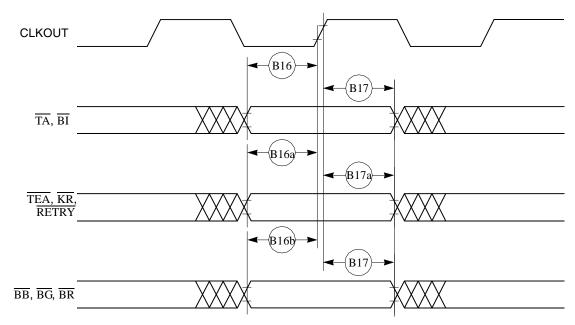


Figure 6. Synchronous Input Signals Timing

Figure 7 provides normal case timing for input data.

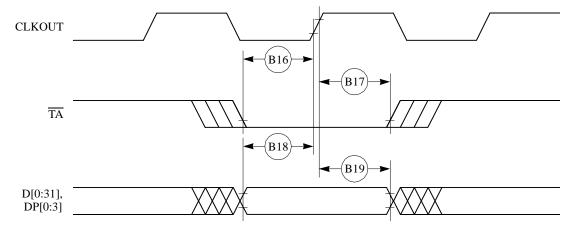


Figure 7. Input Data Timing in Normal Case



Figure 13 through Figure 15 provide the timing for the external bus write controlled by various GPCM factors.

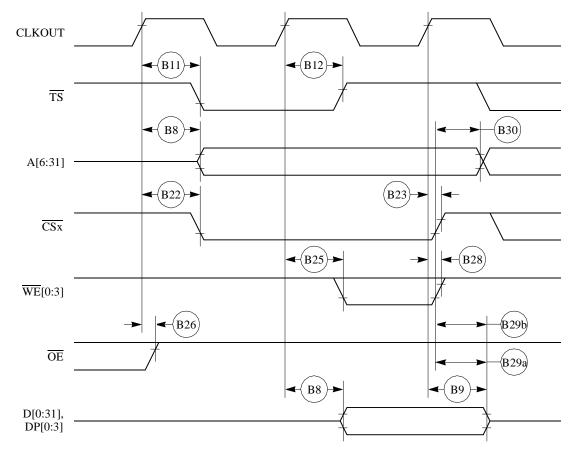


Figure 13. External Bus Write Timing (GPCM Controlled—TRLX = 0, CSNT = 0)



Figure 19 provides the timing for the synchronous external master access controlled by the GPCM.

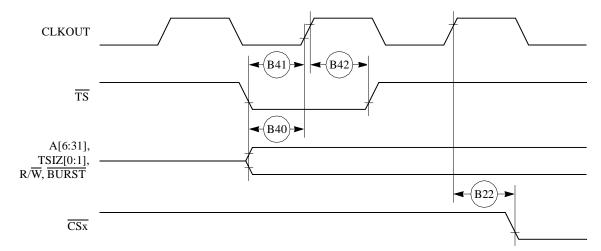


Figure 19. Synchronous External Master Access Timing (GPCM Handled ACS = 00)

Figure 20 provides the timing for the asynchronous external master memory access controlled by the GPCM.

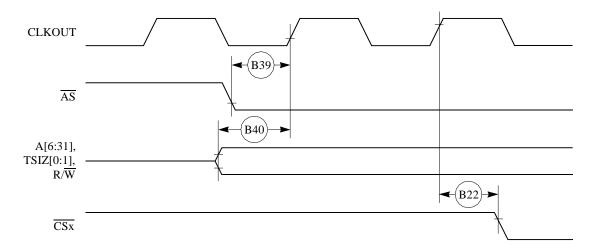


Figure 20. Asynchronous External Master Memory Access Timing (GPCM Controlled—ACS = 00)

Figure 21 provides the timing for the asynchronous external master control signals negation.

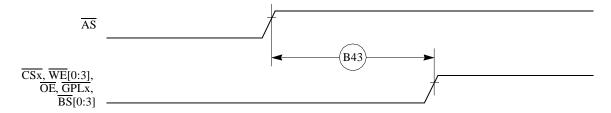


Figure 21. Asynchronous External Master—Control Signals Negation Timing

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2



## Table 8 shows the PCMCIA timing for the MPC850.

### **Table 8. PCMCIA Timing**

Num	Characteristic	501	ЛНz	661	ЛHz	80 1	ИНz	FFACTOR	Unit
Num	Cital acteristic	Min	Max	Min	Max	Min	Max	FFACION	Oiiit
P44	A[6–31], REG valid to PCMCIA strobe asserted. 1	13.00	_	21.00	_	17.00	_	0.750	ns
P45	A[6–31], REG valid to ALE negation.1	18.00	_	28.00	_	23.00	_	1.000	ns
P46	CLKOUT to REG valid	5.00	13.00	8.00	16.00	6.00	14.00	0.250	ns
P47	CLKOUT to REG Invalid.	6.00	_	9.00	_	7.00	_	0.250	ns
P48	CLKOUT to CE1, CE2 asserted.	5.00	13.00	8.00	16.00	6.00	14.00	0.250	
P49	CLKOUT to CE1, CE2 negated.	5.00	13.00	8.00	16.00	6.00	14.00	0.250	ns
P50	CLKOUT to PCOE, IORD, PCWE, IOWR assert time.	_	11.00	_	11.00	_	11.00	_	ns
P51	CLKOUT to PCOE, IORD, PCWE, IOWR negate time.	2.00	11.00	2.00	11.00	2.00	11.00	_	ns
P52	CLKOUT to ALE assert time	5.00	13.00	8.00	16.00	6.00	14.00	0.250	ns
P53	CLKOUT to ALE negate time	_	13.00	_	16.00	_	14.00	0.250	ns
P54	PCWE, IOWR negated to D[0–31] invalid.1	3.00	_	6.00	_	4.00	_	0.250	ns
P55	WAIT_B valid to CLKOUT rising edge.1	8.00	_	8.00	_	8.00	_	_	ns
P56	CLKOUT rising edge to WAIT_B invalid.1	2.00	_	2.00	_	2.00	_	_	ns

<sup>1</sup> PSST = 1. Otherwise add PSST times cycle time.

These synchronous timings define when the WAIT\_B signal is detected in order to freeze (or relieve) the PCMCIA current cycle. The WAIT\_B assertion will be effective only if it is detected 2 cycles before the PSL timer expiration. See PCMCIA Interface in the MPC850 PowerQUICC User's Manual.

PSHT = 0. Otherwise add PSHT times cycle time.



Figure 25 provides the PCMCIA access cycle timing for the external bus write.

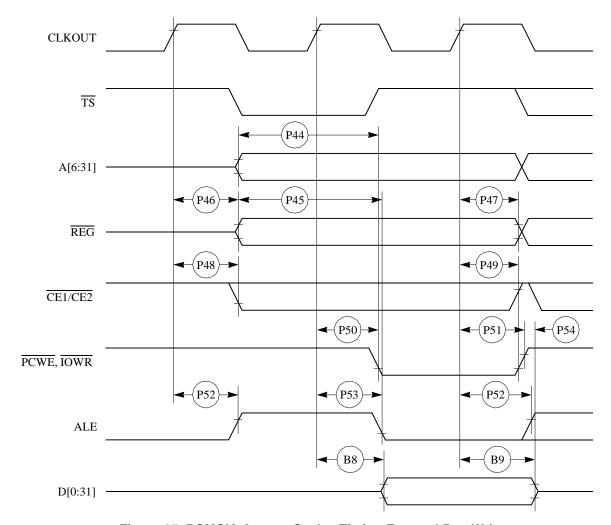


Figure 25. PCMCIA Access Cycles Timing External Bus Write

Figure 26 provides the PCMCIA WAIT signals detection timing.

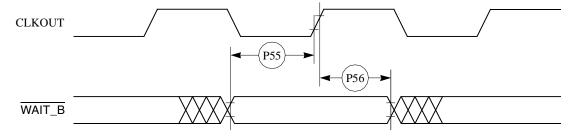


Figure 26. PCMCIA WAIT Signal Detection Timing

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2



Table 9 shows the PCMCIA port timing for the MPC850.

**Table 9. PCMCIA Port Timing** 

Num	Characteristic	50 MHz		66 MHz		80 MHz		Unit
Num	Gilai acteristic	Min	Max	Min	Max	Min	Max	Oiiit
P57	CLKOUT to OPx valid	_	19.00	_	19.00	_	19.00	ns
P58	HRESET negated to OPx drive <sup>1</sup>	18.00	_	26.00	_	22.00	_	ns
P59	IP_Xx valid to CLKOUT rising edge	5.00	_	5.00	_	5.00	_	ns
P60	CLKOUT rising edge to IP_Xx invalid	1.00	_	1.00	_	1.00	_	ns

OP2 and OP3 only.

Figure 27 provides the PCMCIA output port timing for the MPC850.

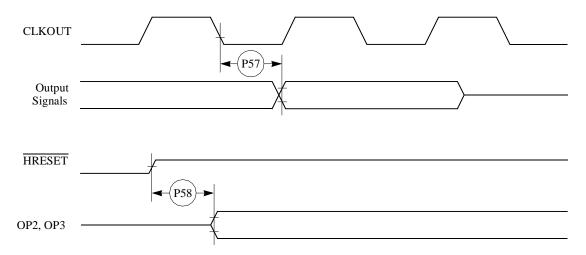


Figure 27. PCMCIA Output Port Timing

Figure 28 provides the PCMCIA output port timing for the MPC850.

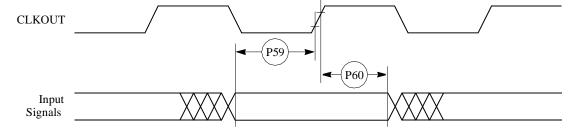


Figure 28. PCMCIA Input Port Timing



Table 10 shows the debug port timing for the MPC850.

**Table 10. Debug Port Timing** 

Num	Characteristic	50 MHz		66 MHz		80 MHz		Unit
	Characteristic	Min	Max	Min	Max	Min	Max	
D61	DSCK cycle time	60.00	_	91.00	_	75.00	_	ns
D62	DSCK clock pulse width	25.00	_	38.00	_	31.00	_	ns
D63	DSCK rise and fall times	0.00	3.00	0.00	3.00	0.00	3.00	ns
D64	DSDI input data setup time	8.00	_	8.00	_	8.00	_	ns
D65	DSDI data hold time	5.00	_	5.00	_	5.00	_	ns
D66	DSCK low to DSDO data valid	0.00	15.00	0.00	15.00	0.00	15.00	ns
D67	DSCK low to DSDO invalid	0.00	2.00	0.00	2.00	0.00	2.00	ns

Figure 29 provides the input timing for the debug port clock.

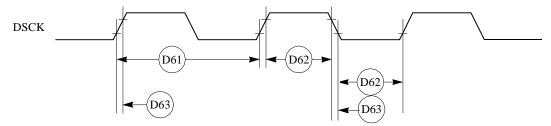


Figure 29. Debug Port Clock Input Timing

Figure 30 provides the timing for the debug port.

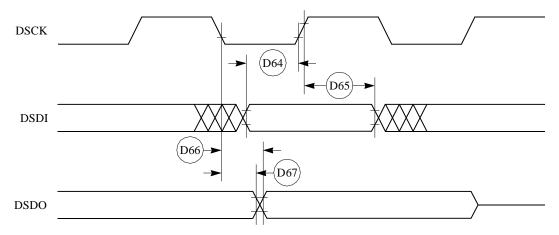


Figure 30. Debug Port Timings

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2



#### IEEE 1149.1 Electrical Specifications

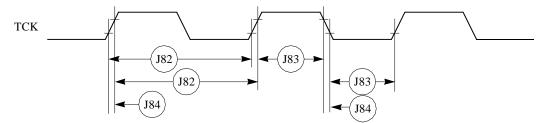


Figure 34. JTAG Test Clock Input Timing

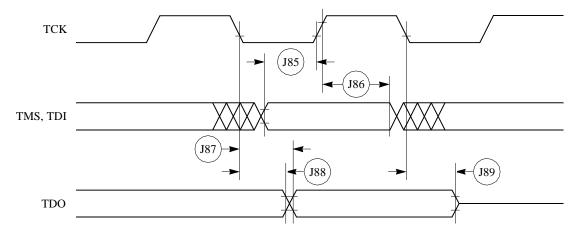


Figure 35. JTAG Test Access Port Timing Diagram

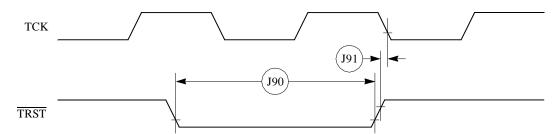


Figure 36. JTAG TRST Timing Diagram



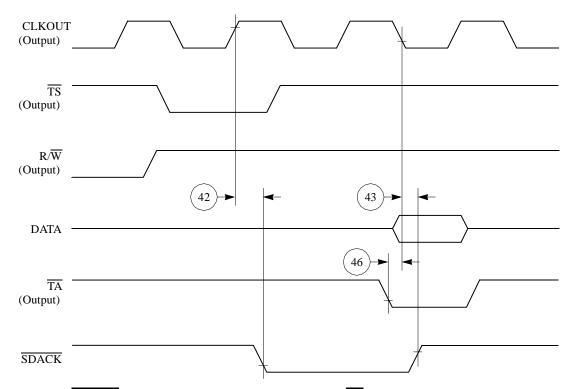
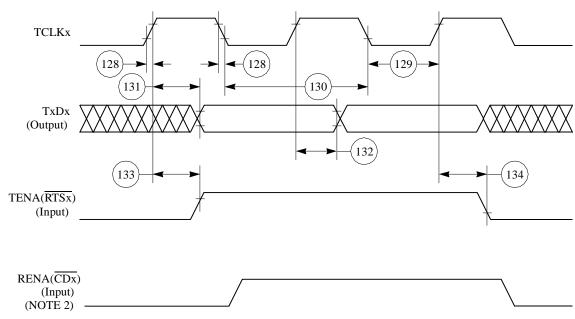


Figure 40. SDACK Timing Diagram—Peripheral Write, TA Sampled Low at the Falling Edge of the Clock

#### **CPM Electrical Characteristics**



- NOTES:
  - 1. Transmit clock invert (TCI) bit in GSMR is set.
  - If RENA is deasserted before TENA, or RENA is not asserted at all during transmit, then the CSL bit is set in the buffer descriptor at the end of the frame transmission.

Figure 55. Ethernet Transmit Timing Diagram

# 8.8 SMC Transparent AC Electrical Specifications

Figure 21 provides the SMC transparent timings as shown in Figure 56.

**Table 21. Serial Management Controller Timing** 

Num	Characteristic	All Frequ	encies	Unit	
Num	Characteristic	Min	Max	Oilit	
150	SMCLKx clock period <sup>1</sup>	100.00	_	ns	
151	SMCLKx width low	50.00	_	ns	
151a	SMCLKx width high	50.00	_	ns	
152	SMCLKx rise/fall time	_	15.00	ns	
153	SMTXDx active delay (from SMCLKx falling edge)	10.00	50.00	ns	
154	SMRXDx/SMSYNx setup time	20.00	_	ns	
155	SMRXDx/SMSYNx hold time	5.00	_	ns	

<sup>1</sup> The ratio SyncCLK/SMCLKx must be greater or equal to 2/1.



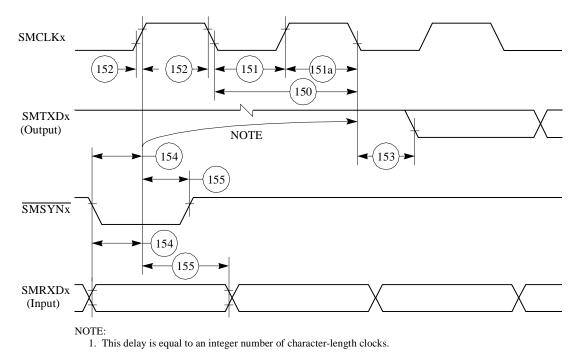


Figure 56. SMC Transparent Timing Diagram

# 8.9 SPI Master AC Electrical Specifications

Table 22 provides the SPI master timings as shown in Figure 57 and Figure 58.

**All Frequencies** Characteristic Unit Num Min Max 160 MASTER cycle time 4 1024 t<sub>cyc</sub> 161 MASTER clock (SCK) high or low time 2 512 t<sub>cyc</sub> 162 MASTER data setup time (inputs) 50.00 ns 163 Master data hold time (inputs) 0.00 ns 164 Master data valid (after SCK edge) 20.00 ns 165 Master data hold time (outputs) 0.00 ns 15.00 166 Rise time output ns 167 Fall time output 15.00 ns

Table 22. SPI Master Timing



# 9 Mechanical Data and Ordering Information

Table 26 provides information on the MPC850 derivative devices.

Table 26. MPC850 Family Derivatives

Device	Ethernet Support	Number of SCCs <sup>1</sup>	32-Channel HDLC Support	64-Channel HDLC Support <sup>2</sup>
MPC850	N/A	One	N/A	N/A
MPC850DE	Yes	Two	N/A	N/A
MPC850SR	Yes	Two	N/A	Yes
MPC850DSL	Yes	Two	No	No

Serial Communication Controller (SCC)

Table 27 identifies the packages and operating frequencies available for the MPC850.

Table 27. MPC850 Package/Frequency/Availability

Package Type	Frequency (MHz)	Temperature (Tj)	Order Number
256-Lead Plastic Ball Grid Array (ZT suffix)	50	0°C to 95°C	XPC850ZT50BU XPC850DEZT50BU XPC850SRZT50BU XPC850DSLZT50BU
	66	0°C to 95°C	XPC850ZT66BU XPC850DEZT66BU XPC850SRZT66BU
	80	0°C to 95°C	XPC850ZT80BU XPC850DEZT80BU XPC850SRZT80BU
256-Lead Plastic Ball Grid Array (CZT suffix)	50	-40°C to 95°C	XPC850CZT50BU XPC850DECZT50BU XPC850SRCZT50BU XPC850DSLCZT50BU
	66		XPC850CZT66BU XPC850DECZT66BU XPC850SRCZT66BU
	80		XPC850CZT80B XPC850DECZT80B XPC850SRCZT80B

# 9.1 Pin Assignments and Mechanical Dimensions of the PBGA

The original pin numbering of the MPC850 conformed to a Freescale proprietary pin numbering scheme that has since been replaced by the JEDEC pin numbering standard for this package type. To support

MPC850 PowerQUICC™ Integrated Communications Processor Hardware Specifications, Rev. 2

<sup>&</sup>lt;sup>2</sup> 50 MHz version supports 64 time slots on a time division multiplexed line using one SCC



#### **Mechanical Data and Ordering Information**

customers that are currently using the non-JEDEC pin numbering scheme, two sets of pinouts, JEDEC and non-JEDEC, are presented in this document.

Figure 62 shows the non-JEDEC pinout of the PBGA package as viewed from the top surface.

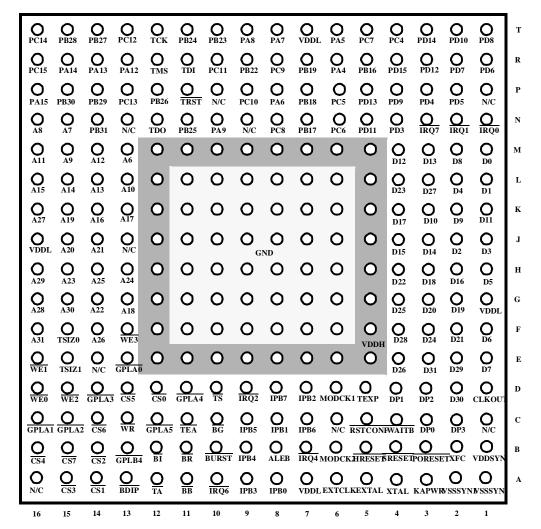


Figure 62. Pin Assignments for the PBGA (Top View)—non-JEDEC Standard

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