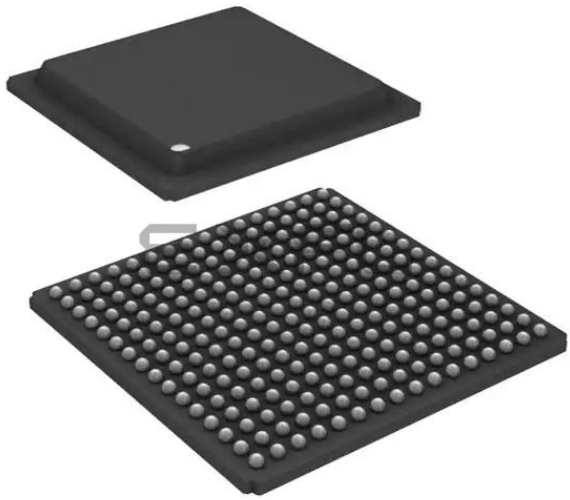

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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	66MHz
Co-Processors/DSP	Communications; CPM
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10Mbps (1)
SATA	-
USB	USB 1.x (1)
Voltage - I/O	3.3V
Operating Temperature	-40°C ~ 95°C (TA)
Security Features	-
Package / Case	256-BBGA
Supplier Device Package	256-PBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mpc850srcvr66bu

The CPM of the MPC850 supports up to seven serial channels, as follows:

- One or two serial communications controllers (SCCs). The SCCs support Ethernet, ATM (MPC850SR and MPC850DSL), HDLC and a number of other protocols, along with a transparent mode of operation.
- One USB channel
- Two serial management controllers (SMCs)
- One I^2C port
- One serial peripheral interface (SPI).

Table 1 shows the functionality supported by the members of the MPC850 family.

Table 1. MPC850 Functionality Matrix

Part	Number of SCCs Supported	Ethernet Support	ATM Support	USB Support	Multi-channel HDLC Support	Number of PCMCIA Slots Supported
MPC850	1	Yes	-	Yes	-	1
MPC850DE	2	Yes	-	Yes	-	1
MPC850SR	2	Yes	Yes	Yes	Yes	1
MPC850DSL	2	Yes	Yes	Yes	No	1

Additional documentation may be provided for parts listed in Table 1.

  - Gate mode can enable/disable counting
  - Interrupt can be masked on reference match and event capture
- Interrupts
  - Eight external interrupt request (IRQ) lines
  - Twelve port pins with interrupt capability
  - Fifteen internal interrupt sources
  - Programmable priority among SCCs and USB
  - Programmable highest-priority request
- Single socket PCMCIA-ATA interface
  - Master (socket) interface, release 2.1 compliant
  - Single PCMCIA socket
  - Supports eight memory or I/O windows
- Communications processor module (CPM)
  - 32-bit, Harvard architecture, scalar RISC communications processor (CP)
  - Protocol-specific command sets (for example, GRACEFUL STOP TRANSMIT stops transmission after the current frame is finished or immediately if no frame is being sent and CLOSE RXBD closes the receive buffer descriptor)
  - Supports continuous mode transmission and reception on all serial channels
  - Up to 8 Kbytes of dual-port RAM
  - Twenty serial DMA (SDMA) channels for the serial controllers, including eight for the four USB endpoints
  - Three parallel I/O registers with open-drain capability
- Four independent baud-rate generators (BRGs)
  - Can be connected to any SCC, SMC, or USB
  - Allow changes during operation
  - Autobaud support option
- Two SCCs (serial communications controllers)
  - Ethernet/IEEE 802.3, supporting full 10-Mbps operation
  - HDLC/SDLC™ (all channels supported at 2 Mbps)
  - HDLC bus (implements an HDLC-based local area network (LAN))
  - Asynchronous HDLC to support PPP (point-to-point protocol)
  - AppleTalk®
  - Universal asynchronous receiver transmitter (UART)
  - Synchronous UART
  - Serial infrared (IrDA)
  - Totally transparent (bit streams)
  - Totally transparent (frame based with optional cyclic redundancy check (CRC))

- QUICC multichannel controller (QMC) microcode features
  - Up to 64 independent communication channels on a single SCC
  - Arbitrary mapping of 0–31 channels to any of 0–31 TDM time slots
  - Supports either transparent or HDLC protocols for each channel
  - Independent TxBDs/Rx and event/interrupt reporting for each channel
- One universal serial bus controller (USB)
  - Supports host controller and slave modes at 1.5 Mbps and 12 Mbps
- Two serial management controllers (SMCs)
  - UART
  - Transparent
  - General circuit interface (GCI) controller
  - Can be connected to the time-division-multiplexed (TDM) channel
- One serial peripheral interface (SPI)
  - Supports master and slave modes
  - Supports multimaster operation on the same bus
- One $I^2C^{®}$ (interprocessor-integrated circuit) port
  - Supports master and slave modes
  - Supports multimaster environment
- Time slot assigner
  - Allows SCCs and SMCs to run in multiplexed operation
  - Supports T1, CEPT, PCM highway, ISDN basic rate, ISDN primary rate, user-defined
  - 1- or 8-bit resolution
  - Allows independent transmit and receive routing, frame syncs, clocking
  - Allows dynamic changes
  - Can be internally connected to four serial channels (two SCCs and two SMCs)
- Low-power support
  - Full high: all units fully powered at high clock frequency
  - Full low: all units fully powered at low clock frequency
  - Doze: core functional units disabled except time base, decrementer, PLL, memory controller, real-time clock, and CPM in low-power standby
  - Sleep: all units disabled except real-time clock and periodic interrupt timer. PLL is active for fast wake-up
  - Deep sleep: all units disabled including PLL, except the real-time clock and periodic interrupt timer
  - Low-power stop: to provide lower power dissipation

  - Separate power supply input to operate internal logic at 2.2 V when operating at or below 25 MHz
  - Can be dynamically shifted between high frequency (3.3 V internal) and low frequency (2.2 V internal) operation
- Debug interface
  - Eight comparators: four operate on instruction address, two operate on data address, and two operate on data
  - The MPC850 can compare using the =, ≠, <, and > conditions to generate watchpoints
  - Each watchpoint can generate a breakpoint internally
- 3.3-V operation with 5-V TTL compatibility on all general purpose I/O pins.

3 Electrical and Thermal Characteristics

This section provides the AC and DC electrical specifications and thermal characteristics for the MPC850. Table 2 provides the maximum ratings.

Table 2. Maximum Ratings

(GND = 0V)

Rating	Symbol	Value	Unit
Supply voltage	VDDH	-0.3 to 4.0	V
	VDDL	-0.3 to 4.0	V
	KAPWR	-0.3 to 4.0	V
	VDDSYN	-0.3 to 4.0	V
Input voltage [1]	V_{in}	GND-0.3 to VDDH + 2.5 V	V
Junction temperature [2]	T_j	0 to 95 (standard) -40 to 95 (extended)	°C
Storage temperature range	T_{stg}	-55 to +150	°C

1 Functional operating conditions are provided with the DC electrical specifications in Table 5. Absolute maximum ratings are stress ratings only; functional operation at the maxima is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage to the device.
CAUTION: All inputs that tolerate 5 V cannot be more than 2.5 V greater than the supply voltage. This restriction applies to power-up and normal operation (that is, if the MPC850 is unpowered, voltage greater than 2.5 V must not be applied to its inputs).

2 The MPC850, a high-frequency device in a BGA package, does not provide a guaranteed maximum ambient temperature. Only maximum junction temperature is guaranteed. It is the responsibility of the user to consider power dissipation and thermal management. Junction temperature ratings are the same regardless of frequency rating of the device.

This device contains circuitry protecting against damage due to high-static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for example, either GND or V_{CC}). Table 3 provides the package thermal characteristics for the MPC850.

Table 5. DC Electrical Specifications (continued)

Characteristic	Symbol	Min	Max	Unit
Input low voltage	VIL	GND	0.8	V
EXTAL, EXTCLK input high voltage	VIHC	0.7*(VCC)	VCC+0.3	V
Input leakage current, Vin = 5.5 V (Except TMS, TRST, DSCK and DSDI pins)	I_{in}	—	100	µA
Input leakage current, Vin = 3.6V (Except TMS, TRST, DSCK and DSDI pins)	I_{In}	—	10	µA
Input leakage current, Vin = 0V (Except TMS, TRST, DSCK and DSDI pins)	I_{In}	—	10	µA
Input capacitance	C_{in}	—	20	pF
Output high voltage, IOH = -2.0 mA, VDDH = 3.0V except XTAL, XFC, and open-drain pins	VOH	2.4	—	V
Output low voltage CLKOUT [3] IOL = 3.2 mA [1] IOL = 5.3 mA [2] IOL = 7.0 mA PA[14]/USBOE, PA[12]/TXD2 IOL = 8.9 mA TS, TA, TEA, BI, BB, HRESET, SRESET	VOL	—	0.5	V

1 A[6:31], TSIZ0/REG, TSIZ1, D[0:31], DP[0:3]/IRQ[3:6], RD/WR, BURST, RSV/IRQ2, IP_B[0:1]/IWP[0:1]/VFLS[0:1], IP_B2/IOIS16_B/AT2, IP_B3/IWP2/VF2, IP_B4/LWP0/VF0, IP_B5/LWP1/VF1, IP_B6/DSDI/AT0, IP_B7/PTR/AT3, PA[15]/USBRXD, PA[13]/RXD2, PA[9]/L1TXDA/SMRXD2, PA[8]/L1RXDA/SMTXD2, PA[7]/CLK1/TIN1/L1RCLKA/BRGO1, PA[6]/CLK2/TOUT1/TIN3, PA[5]/CLK3/TIN2/L1TCLKA/BRGO2, PA[4]/CLK4/TOUT2/TIN4, PB[31]/SPISEL, PB[30]/SPICLK/TXD3, PB[29]/SPIMOSI /RXD3, PB[28]/SPIMISO/BRGO3, PB[27]/I2CSDA/BRGO1, PB[26]/I2CSCL/BRGO2, PB[25]/SMTXD1/TXD3, PB[24]/SMRXD1/RXD3, PB[23]/SMSYN1/SDACK1, PB[22]/SMSYN2/SDACK2, PB[19]/L1ST1, PB[18]/RTS2/L1ST2, PB[17]/L1ST3, PB[16]/L1RQa/L1ST4, PC[15]/DREQ0/L1ST5, PC[14]/DREQ1/RTS2/L1ST6, PC[13]/L1ST7/RTS3, PC[12]/L1RQa/L1ST8, PC[11]/USBRXP, PC[10]/TGATE1/USBRXN, PC[9]/CTS2, PC[8]/CD2/TGATE1, PC[7]/USBTXP, PC[6]/USBTXN, PC[5]/CTS3/L1TSYNCA/SDACK1, PC[4]/CD3/L1RSYNCA, PD[15], PD[14], PD[13], PD[12], PD[11], PD[10], PD[9], PD[8], PD[7], PD[6], PD[5], PD[4], PD[3]

2 BDIP/GPL_B5, BR, BG, FRZ/IRQ6, CS[0:5], CS6/CE1_B, CS7/CE2_B, WE0/BS_AB0/IORD, WE1/BS_AB1/IOWR, WE2/BS_AB2/PCOE, WE3/BS_AB3/PCWE, GPL_A0/GPL_B0, OE/GPL_A1/GPL_B1, GPL_A[2:3]/GPL_B[2:3]/CS[2:3], UPWAITA/GPL_A4/AS, UPWAITB/GPL_B4, GPL_A5, ALE_B/DSCK/AT1, OP2/MODCK1/STS, OP3/MODCK2/DSDO

3 The MPC850 IBIS model must be used to accurately model the behavior of the Clkout output driver for the full and half drive setting. Due to the nature of the Clkout output buffer, IOH and IOL for Clkout should be extracted from the IBIS model at any output voltage level.

5 Power Considerations

The average chip-junction temperature, T_J, in °C can be obtained from the equation:

$T_J = T_A + (P_D \bullet \theta_{JA})(1)$

where

T_A = Ambient temperature, °C

Table 6. Bus Operation Timing [1] (continued)

Num	Characteristic	50 MHz		66 MHz		80 MHz		FFACT	Cap Load (default 50 pF)	Unit
		Min	Max	Min	Max	Min	Max			
B9	CLKOUT to A[6–31] RD/$\overline{WR}$, $\overline{BURST}$, D[0–31], DP[0–3], $\overline{TSIZ}$[0–1], $\overline{REG}$, $\overline{RSV}$, AT[0–3], $\overline{PTR}$ high-Z	5.00	11.75	7.58	14.33	6.25	13.00	0.250	50.00	ns
B11	CLKOUT to $\overline{TS}$, $\overline{BB}$ assertion	5.00	11.00	7.58	13.58	6.25	12.25	0.250	50.00	ns
B11a	CLKOUT to $\overline{TA}$, $\overline{BI}$ assertion, (When driven by the memory controller or PCMCIA interface)	2.50	9.25	2.50	9.25	2.50	9.25	—	50.00	ns
B12	CLKOUT to $\overline{TS}$, $\overline{BB}$ negation	5.00	11.75	7.58	14.33	6.25	13.00	0.250	50.00	ns
B12a	CLKOUT to $\overline{TA}$, $\overline{BI}$ negation (when driven by the memory controller or PCMCIA interface)	2.50	11.00	2.50	11.00	2.50	11.00	—	50.00	ns
B13	CLKOUT to $\overline{TS}$, $\overline{BB}$ high-Z	5.00	19.00	7.58	21.58	6.25	20.25	0.250	50.00	ns
B13a	CLKOUT to $\overline{TA}$, $\overline{BI}$ high-Z, (when driven by the memory controller or PCMCIA interface)	2.50	15.00	2.50	15.00	2.50	15.00	—	50.00	ns
B14	CLKOUT to $\overline{TEA}$ assertion	2.50	10.00	2.50	10.00	2.50	10.00	—	50.00	ns
B15	CLKOUT to $\overline{TEA}$ high-Z	2.50	15.00	2.50	15.00	2.50	15.00	—	50.00	ns
B16	$\overline{TA}$, $\overline{BI}$ valid to CLKOUT(setup time) [5]	9.75	—	9.75	—	9.75	—	—	50.00	ns
B16a	$\overline{TEA}$, $\overline{KR}$, $\overline{RETRY}$, valid to CLKOUT (setup time) [5]	10.00	—	10.00	—	10.00	—	—	50.00	ns
B16b	$\overline{BB}$, $\overline{BG}$, $\overline{BR}$ valid to CLKOUT (setup time) [6]	8.50	—	8.50	—	8.50	—	—	50.00	ns
B17	CLKOUT to $\overline{TA}$, $\overline{TEA}$, $\overline{BI}$, $\overline{BB}$, $\overline{BG}$, $\overline{BR}$ valid (Hold time).[5]	1.00	—	1.00	—	1.00	—	—	50.00	ns
B17a	CLKOUT to $\overline{KR}$, $\overline{RETRY}$, except $\overline{TEA}$ valid (hold time)	2.00	—	2.00	—	2.00	—	—	50.00	ns
B18	D[0–31], DP[0–3] valid to CLKOUT rising edge (setup time) [7]	6.00	—	6.00	—	6.00	—	—	50.00	ns
B19	CLKOUT rising edge to D[0–31], DP[0–3] valid (hold time) [7]	1.00	—	1.00	—	1.00	—	—	50.00	ns
B20	D[0–31], DP[0–3] valid to CLKOUT falling edge (setup time) [8]	4.00	—	4.00	—	4.00	—	—	50.00	ns
B21	CLKOUT falling edge to D[0–31], DP[0–3] valid (hold time) [8]	2.00	—	2.00	—	2.00	—	—	—	—

Table 6. Bus Operation Timing [1] (continued)

Num	Characteristic	50 MHz		66 MHz		80 MHz		FFACT	Cap Load (default 50 pF)	Unit
		Min	Max	Min	Max	Min	Max			
B28c	CLKOUT falling edge to $\overline{\text{WE[0–3]}}$ negated GPCM write access TRLX = 0,1 CSNT = 1 write access TRLX = 0, CSNT = 1, EBDF = 1	7.00	14.00	11.00	18.00	9.00	16.00	0.375	50.00	ns
B28d	CLKOUT falling edge to $\overline{\text{CS}}$ negated GPCM write access TRLX = 0,1 CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1	—	14.00	—	18.00	—	16.00	0.375	50.00	ns
B29	$\overline{\text{WE[0–3]}}$ negated to D[0–31], DP[0–3] high-Z GPCM write access, CSNT = 0	3.00	—	6.00	—	4.00	—	0.250	50.00	ns
B29a	$\overline{\text{WE[0–3]}}$ negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 0 CSNT = 1, EBDF = 0	8.00	—	13.00	—	11.00	—	0.500	50.00	ns
B29b	$\overline{\text{CS}}$ negated to D[0–31], DP[0–3], high-Z GPCM write access, ACS = 00, TRLX = 0 & CSNT = 0	3.00	—	6.00	—	4.00	—	0.250	50.00	ns
B29c	$\overline{\text{CS}}$ negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0	8.00	—	13.00	—	11.00	—	0.500	50.00	ns
B29d	$\overline{\text{WE[0–3]}}$ negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 1, CSNT = 1, EBDF = 0	28.00	—	43.00	—	36.00	—	1.500	50.00	ns
B29e	$\overline{\text{CS}}$ negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 1, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0	28.00	—	43.00	—	36.00	—	1.500	50.00	ns
B29f	$\overline{\text{WE[0–3]}}$ negated to D[0–31], DP[0–3] high-Z GPCM write access TRLX = 0, CSNT = 1, EBDF = 1	5.00	—	9.00	—	7.00	—	0.375	50.00	ns
B29g	$\overline{\text{CS}}$ negated to D[0–31], DP[0–3] high-Z GPCM write access TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1	5.00	—	9.00	—	7.00	—	0.375	50.00	ns

Table 6. Bus Operation Timing [1] (continued)

Num	Characteristic	50 MHz		66 MHz		80 MHz		FFACT	Cap Load (default 50 pF)	Unit
		Min	Max	Min	Max	Min	Max			
B42	CLKOUT rising edge to $\overline{TS}$ valid (hold time)	2.00	—	2.00	—	2.00	—	—	50.00	ns
B43	$\overline{AS}$ negation to memory controller signals negation	—	TBD	—	TBD	TBD	—	—	50.00	ns

1 The minima provided assume a 0 pF load, whereas maxima assume a 50pF load. For frequencies not marked on the part, new bus timing must be calculated for all frequency-dependent AC parameters. Frequency-dependent AC parameters are those with an entry in the FFactor column. AC parameters without an FFactor entry do not need to be calculated and can be taken directly from the frequency column corresponding to the frequency marked on the part. The following equations should be used in these calculations.

For a frequency F, the following equations should be applied to each one of the above parameters:

For minima:

$$D = \frac{FFACTOR \times 1000}{F} + (D_{50} - 20 \times FFACTOR)$$

For maxima:

$$D = \frac{FFACTOR \times 1000}{F} + (D_{50} - 20 \times FFACTOR) + 1ns(CAP\ LOAD - 50) / 10$$

where:

D is the parameter value to the frequency required in ns

F is the operation frequency in MHz

D_{50} is the parameter value defined for 50 MHz

CAP LOAD is the capacitance load on the signal in question.

FFACTOR is the one defined for each of the parameters in the table.

2 Phase and frequency jitter performance results are valid only if the input jitter is less than the prescribed value.

3 If the rate of change of the frequency of EXTAL is slow (i.e. it does not jump between the minimum and maximum values in one cycle) or the frequency of the jitter is fast (i.e., it does not stay at an extreme value for a long time) then the maximum allowed jitter on EXTAL can be up to 2%.

4 The timing for $\overline{BR}$ output is relevant when the MPC850 is selected to work with external bus arbiter. The timing for $\overline{BG}$ output is relevant when the MPC850 is selected to work with internal bus arbiter.

5 The setup times required for $\overline{TA}$, $\overline{TEA}$, and $\overline{BI}$ are relevant only when they are supplied by an external device (and not when the memory controller or the PCMCIA interface drives them).

6 The timing required for $\overline{BR}$ input is relevant when the MPC850 is selected to work with the internal bus arbiter. The timing for $\overline{BG}$ input is relevant when the MPC850 is selected to work with the external bus arbiter.

7 The D[0–31] and DP[0–3] input timings B20 and B21 refer to the rising edge of the CLKOUT in which the $\overline{TA}$ input signal is asserted.

8 The D[0:31] and DP[0:3] input timings B20 and B21 refer to the falling edge of CLKOUT. This timing is valid only for read accesses controlled by chip-selects controlled by the UPM in the memory controller, for data beats where DLT3 = 1 in the UPM RAM words. (This is only the case where data is latched on the falling edge of CLKOUT.

9 The timing B30 refers to $\overline{CS}$ when ACS = '00' and to $\overline{WE[0:3]}$ when CSNT = '0'.

10 The signal UPWAIT is considered asynchronous to CLKOUT and synchronized internally. The timings specified in B37 and B38 are specified to enable the freeze of the UPM output signals.

11 The $\overline{AS}$ signal is considered asynchronous to CLKOUT.

Figure 2 is the control timing diagram.

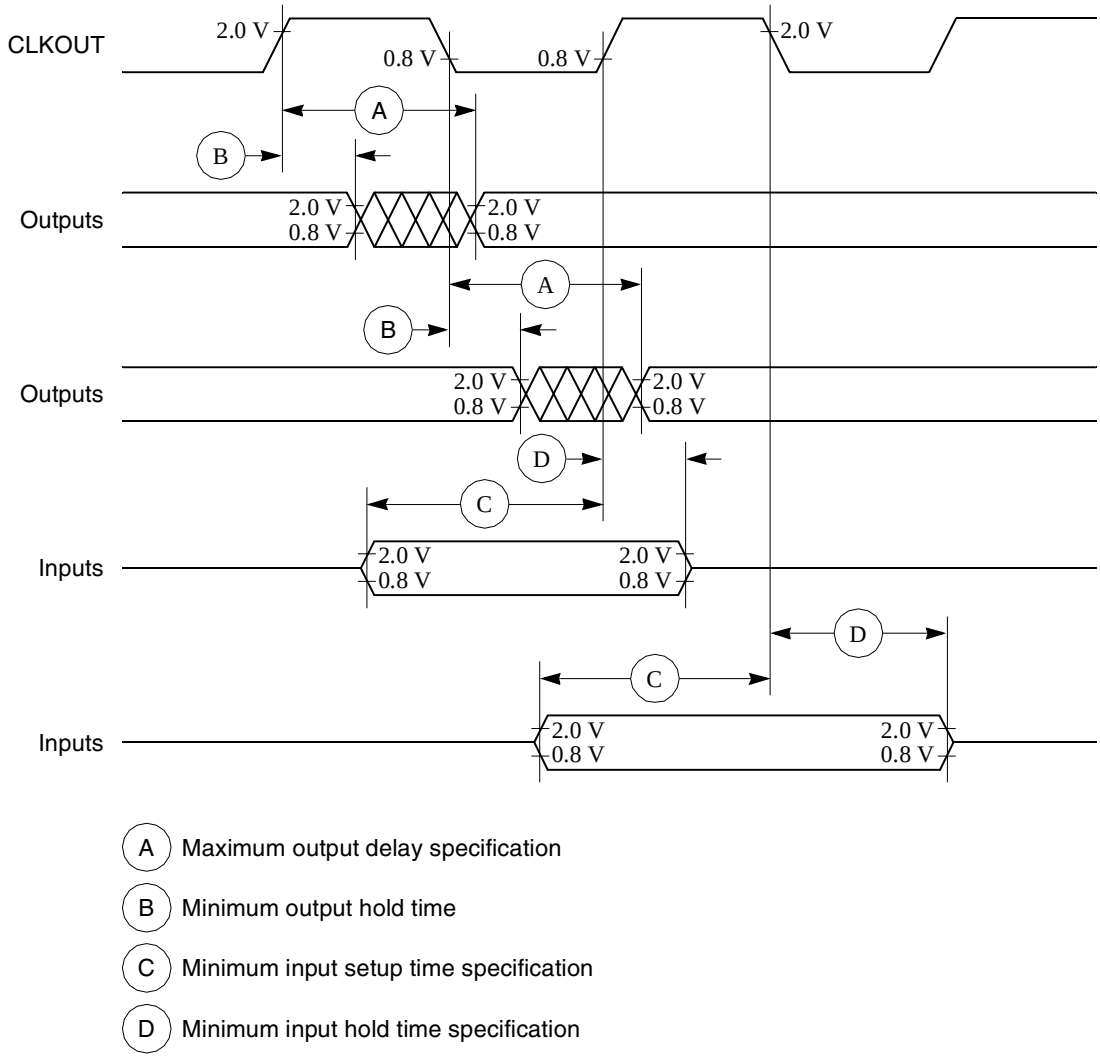

Figure 2. Control Timing

Figure 3 provides the timing for the external clock.

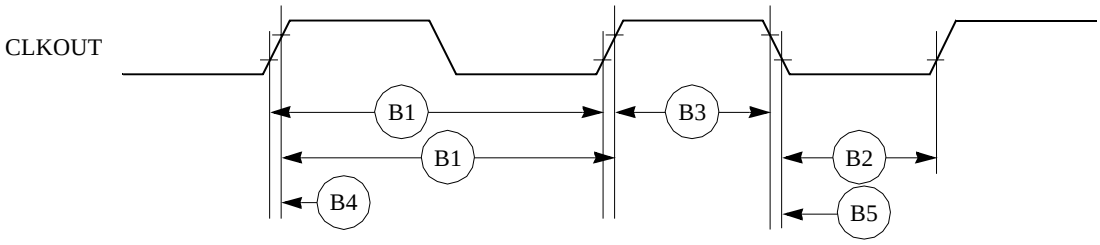

Figure 3. External Clock Timing

Figure 6 provides the timing for the synchronous input signals.

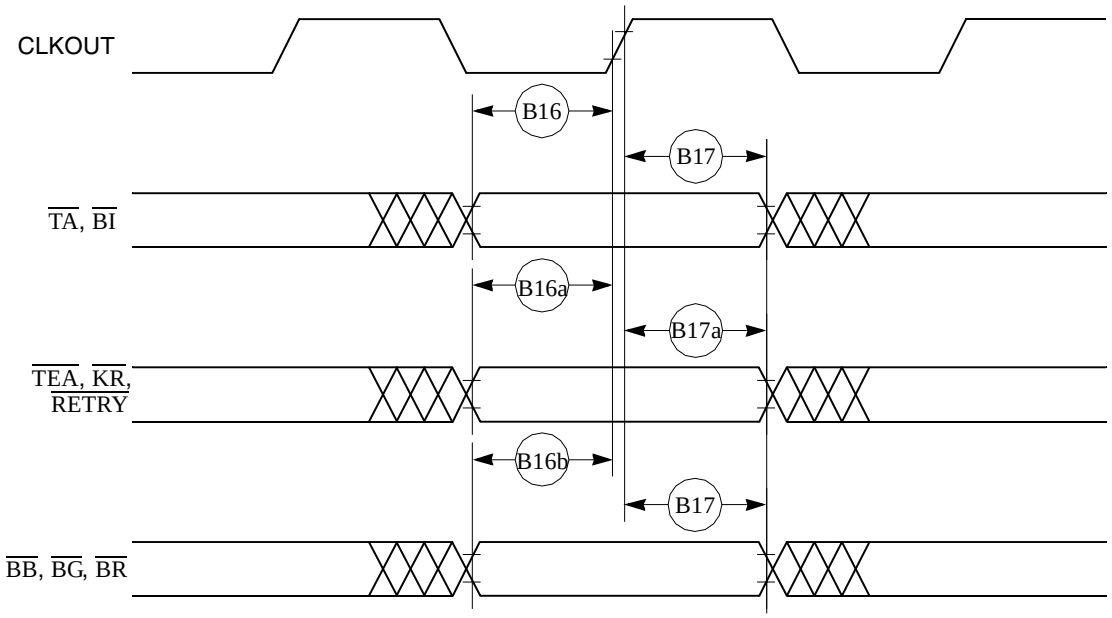

Figure 6. Synchronous Input Signals Timing

Figure 7 provides normal case timing for input data.

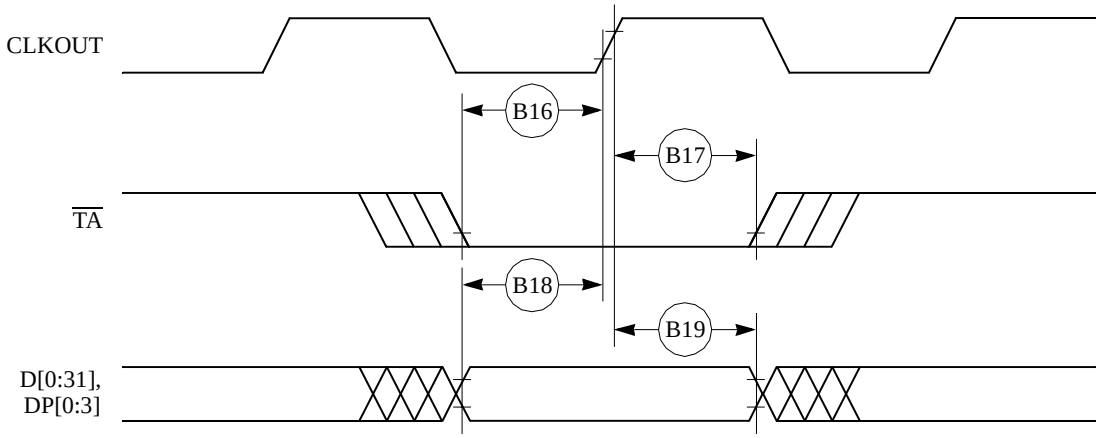

Figure 7. Input Data Timing in Normal Case

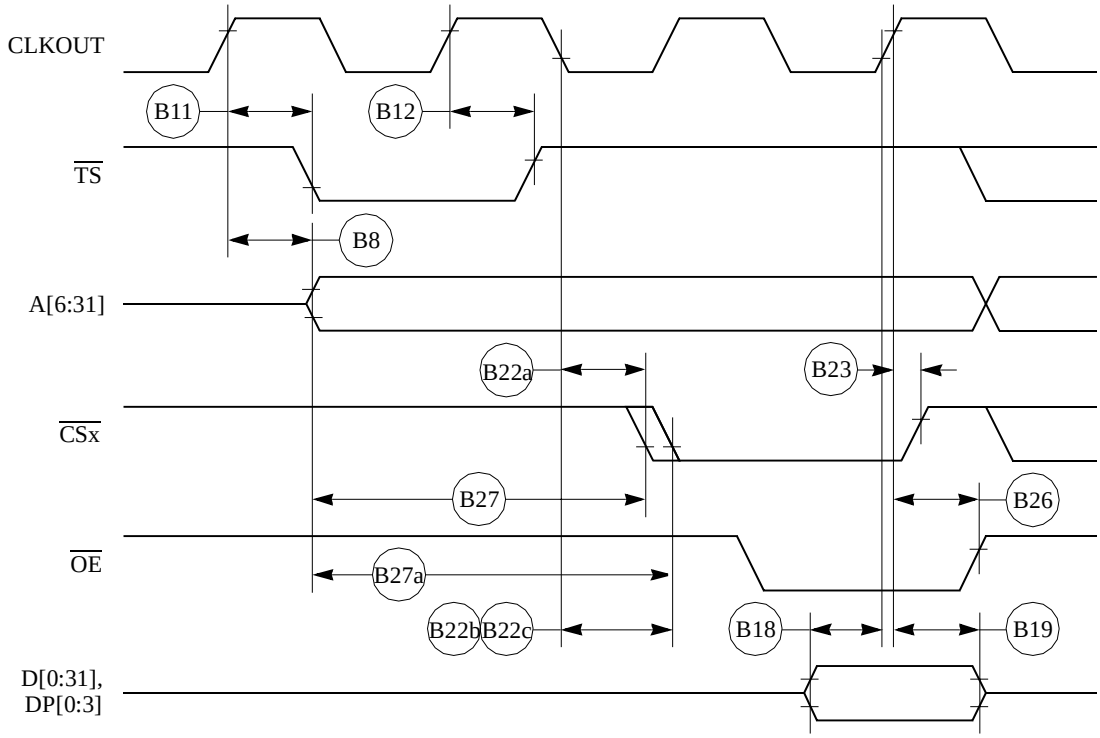

Figure 12. External Bus Read Timing (GPCM Controlled—TRLX = 1, ACS = 10, ACS = 11)

Figure 17 provides the timing for the asynchronous asserted UPWAIT signal controlled by the UPM.

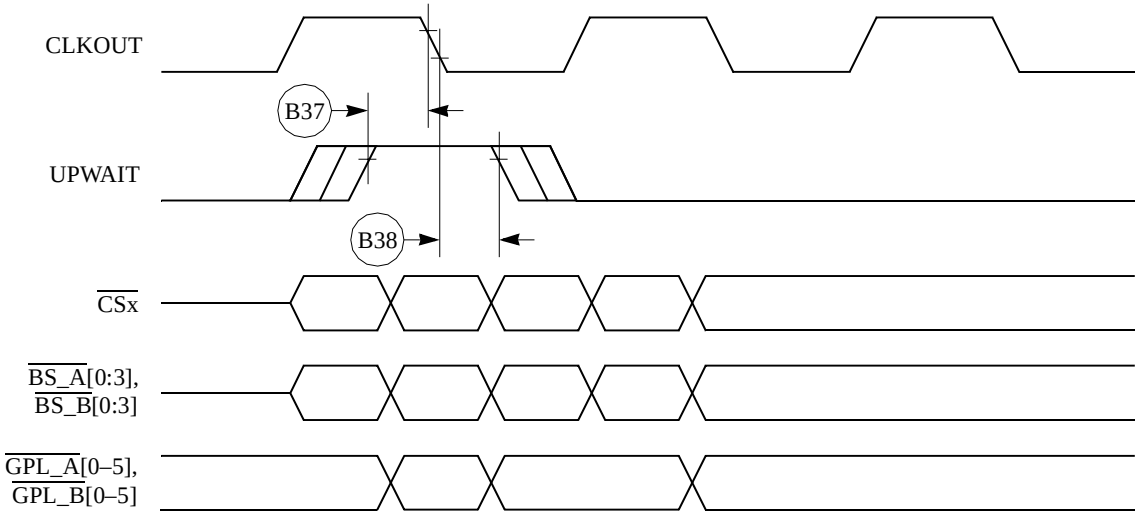

Figure 17. Asynchronous UPWAIT Asserted Detection in UPM Handled Cycles Timing

Figure 18 provides the timing for the asynchronous negated UPWAIT signal controlled by the UPM.

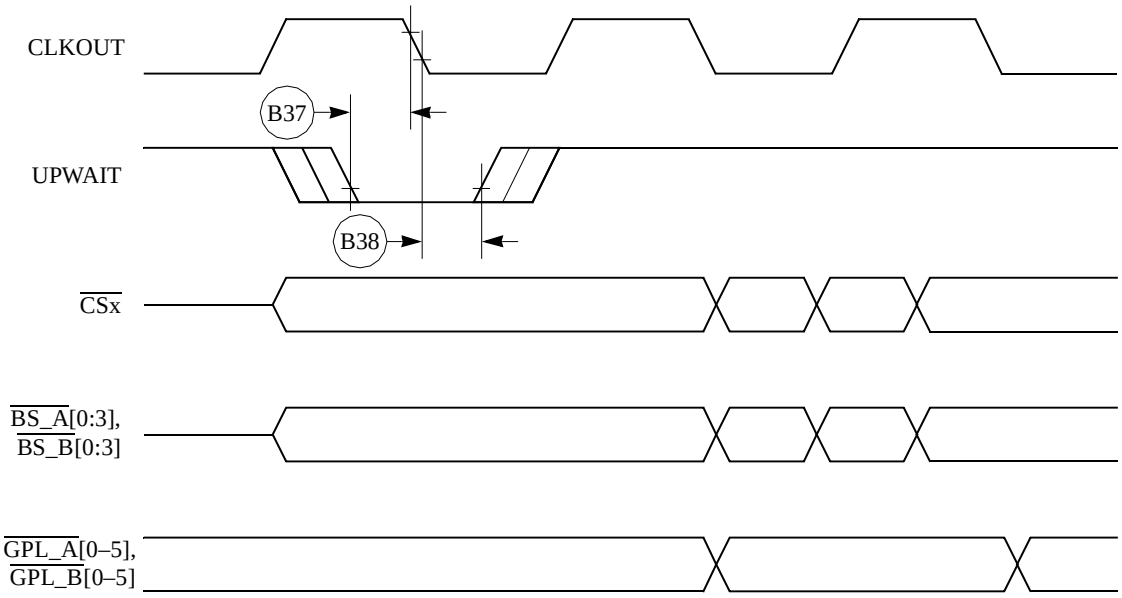

Figure 18. Asynchronous UPWAIT Negated Detection in UPM Handled Cycles Timing

Figure 19 provides the timing for the synchronous external master access controlled by the GPCM.

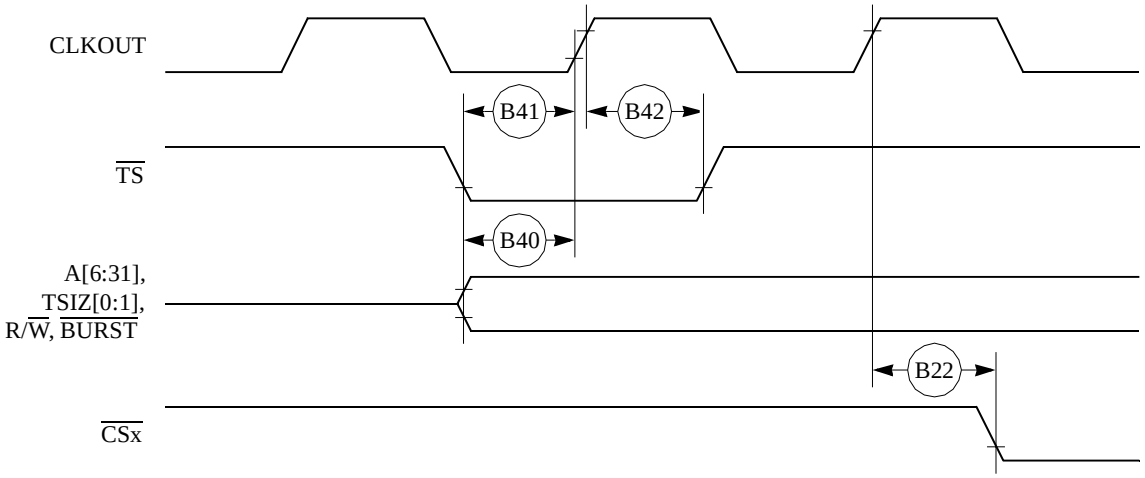

Figure 19. Synchronous External Master Access Timing (GPCM Handled ACS = 00)

Figure 20 provides the timing for the asynchronous external master memory access controlled by the GPCM.

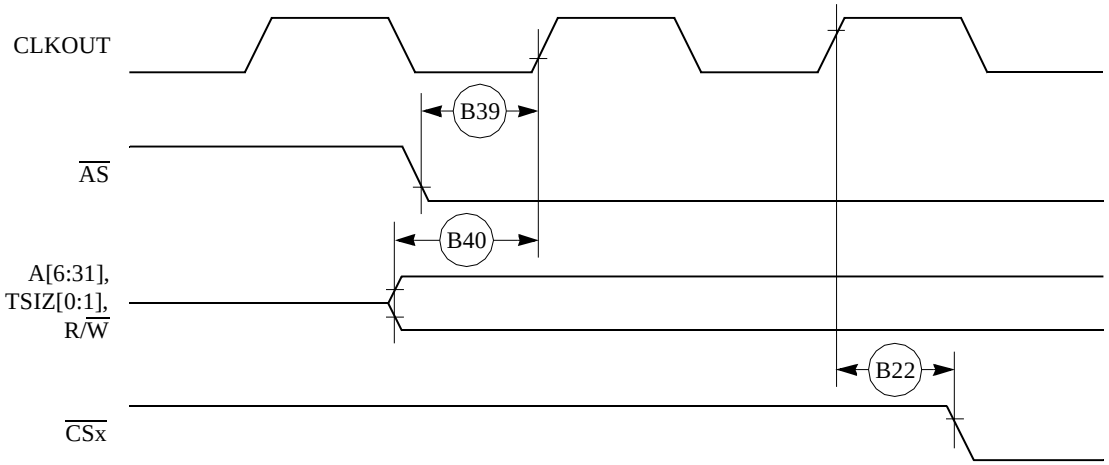

Figure 20. Asynchronous External Master Memory Access Timing (GPCM Controlled—ACS = 00)

Figure 21 provides the timing for the asynchronous external master control signals negation.

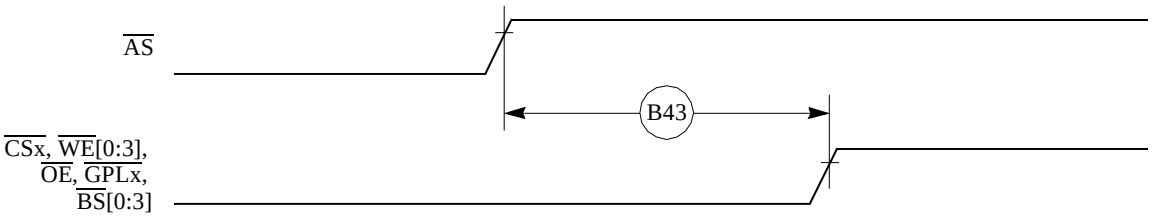

Figure 21. Asynchronous External Master—Control Signals Negation Timing

Table 8 shows the PCMCIA timing for the MPC850.

Table 8. PCMCIA Timing

Num	Characteristic	50MHz		66MHz		80 MHz		FFACTOR	Unit
		Min	Max	Min	Max	Min	Max		
P44	A[6–31], REG valid to PCMCIA strobe asserted. [1]	13.00	—	21.00	—	17.00	—	0.750	ns
P45	A[6–31], REG valid to ALE negation.[1]	18.00	—	28.00	—	23.00	—	1.000	ns
P46	CLKOUT to REG valid	5.00	13.00	8.00	16.00	6.00	14.00	0.250	ns
P47	CLKOUT to REG Invalid.	6.00	—	9.00	—	7.00	—	0.250	ns
P48	CLKOUT to CE1, CE2 asserted.	5.00	13.00	8.00	16.00	6.00	14.00	0.250	
P49	CLKOUT to CE1, CE2 negated.	5.00	13.00	8.00	16.00	6.00	14.00	0.250	ns
P50	CLKOUT to PCOE, IORD, PCWE, IOWR assert time.	—	11.00	—	11.00	—	11.00	—	ns
P51	CLKOUT to PCOE, IORD, PCWE, IOWR negate time.	2.00	11.00	2.00	11.00	2.00	11.00	—	ns
P52	CLKOUT to ALE assert time	5.00	13.00	8.00	16.00	6.00	14.00	0.250	ns
P53	CLKOUT to ALE negate time	—	13.00	—	16.00	—	14.00	0.250	ns
P54	PCWE, IOWR negated to D[0–31] invalid.[1]	3.00	—	6.00	—	4.00	—	0.250	ns
P55	WAIT_B valid to CLKOUT rising edge.[1]	8.00	—	8.00	—	8.00	—	—	ns
P56	CLKOUT rising edge to WAIT_B invalid.[1]	2.00	—	2.00	—	2.00	—	—	ns

[1] PSST = 1. Otherwise add PSST times cycle time.
PSHT = 0. Otherwise add PSHT times cycle time.

These synchronous timings define when the WAIT_B signal is detected in order to freeze (or relieve) the PCMCIA current cycle. The WAIT_B assertion will be effective only if it is detected 2 cycles before the PSL timer expiration. See PCMCIA Interface in the MPC850 PowerQUICC User's Manual.

Table 9 shows the PCMCIA port timing for the MPC850.

Table 9. PCMCIA Port Timing

Num	Characteristic	50 MHz		66 MHz		80 MHz		Unit
		Min	Max	Min	Max	Min	Max	
P57	CLKOUT to OPx valid	—	19.00	—	19.00	—	19.00	ns
P58	$\overline{\text{HRESET}}$ negated to OPx drive [1]	18.00	—	26.00	—	22.00	—	ns
P59	IP_Xx valid to CLKOUT rising edge	5.00	—	5.00	—	5.00	—	ns
P60	CLKOUT rising edge to IP_Xx invalid	1.00	—	1.00	—	1.00	—	ns

[1] OP2 and OP3 only.

Figure 27 provides the PCMCIA output port timing for the MPC850.

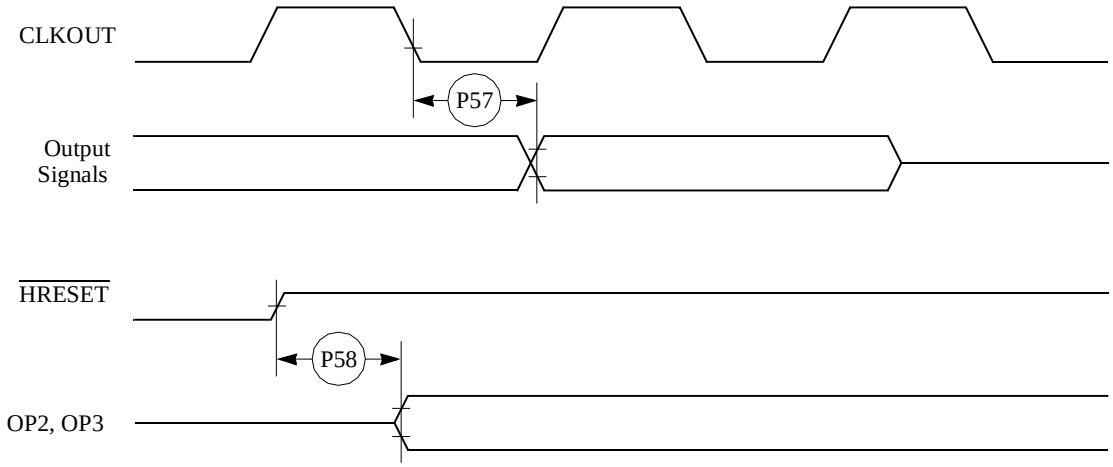

Figure 27. PCMCIA Output Port Timing

Figure 28 provides the PCMCIA output port timing for the MPC850.

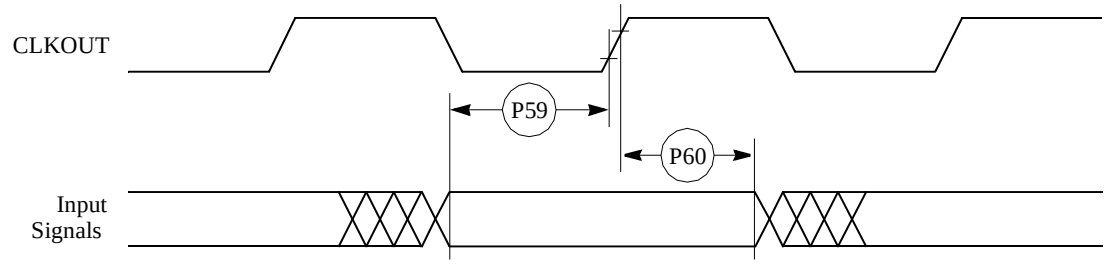

Figure 28. PCMCIA Input Port Timing

Table 17. SI Timing (continued)

Num	Characteristic	All Frequencies		Unit
		Min	Max	
82	L1RCLK, L1TCLK frequency (DSC =1)	—	16.00 or SYNCCLK/2	MHz
83	L1RCLK, L1TCLK width low (DSC =1)	P + 10	—	ns
83A	L1RCLK, L1TCLK width high (DSC = 1)[3]	P + 10	—	ns
84	L1CLK edge to L1CLKO valid (DSC = 1)	—	30.00	ns
85	$\overline{\text{L1RQ}}$ valid before falling edge of L1TSYNC[4]	1.00	—	L1TCLK
86	L1GR setup time[2]	42.00	—	ns
87	L1GR hold time	42.00	—	ns
88	L1xCLK edge to L1SYNC valid (FSD = 00) CNT = 0000, BYT = 0, DSC = 0)	—	0.00	ns

1 The ratio SyncCLK/L1RCLK must be greater than 2.5/1.

2 These specs are valid for IDL mode only.

3 Where P = 1/CLKOUT. Thus for a 25-MHz CLKO1 rate, P = 40 ns.

4 These strobes and TxD on the first bit of the frame become valid after L1CLK edge or L1SYNC, whichever is later.

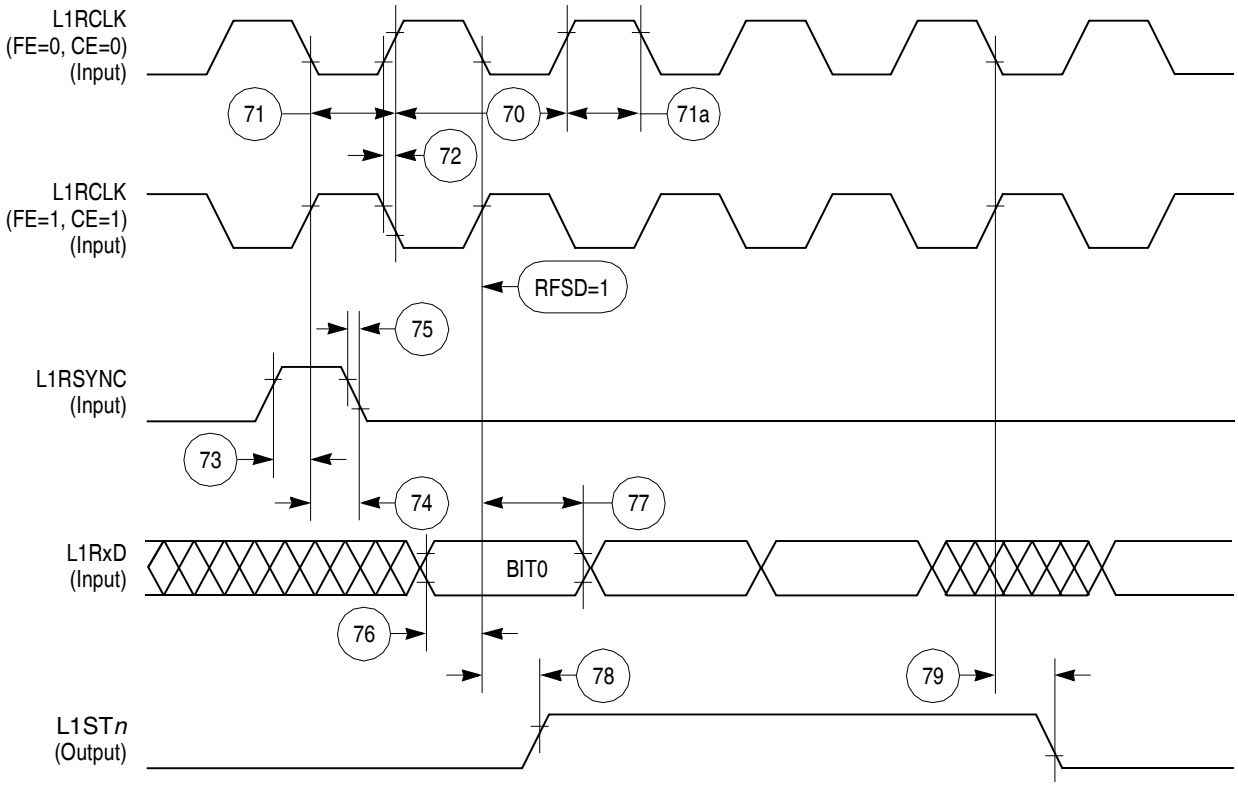

Figure 45. SI Receive Timing Diagram with Normal Clocking (DSC = 0)

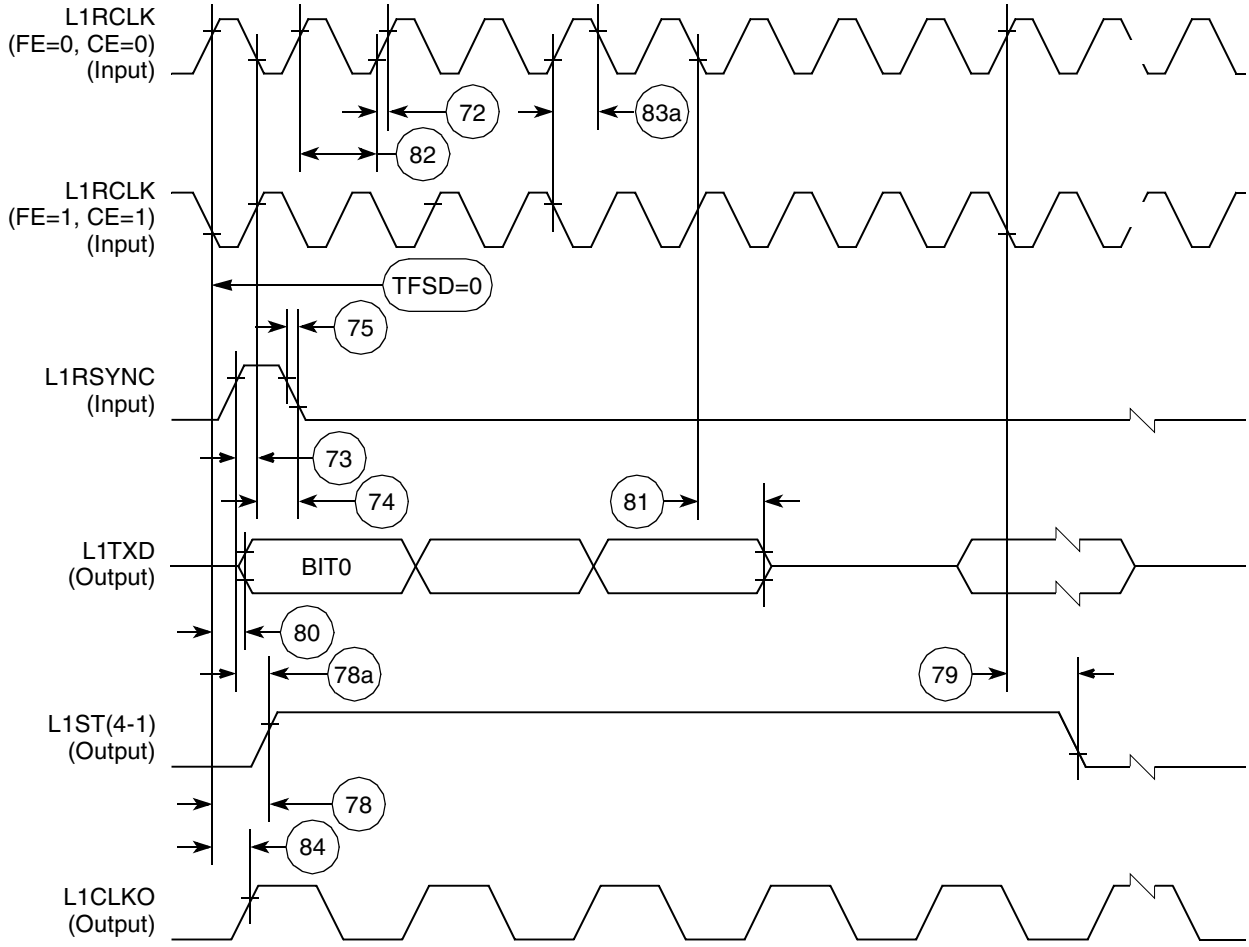

Figure 48. SI Transmit Timing with Double Speed Clocking (DSC = 1)

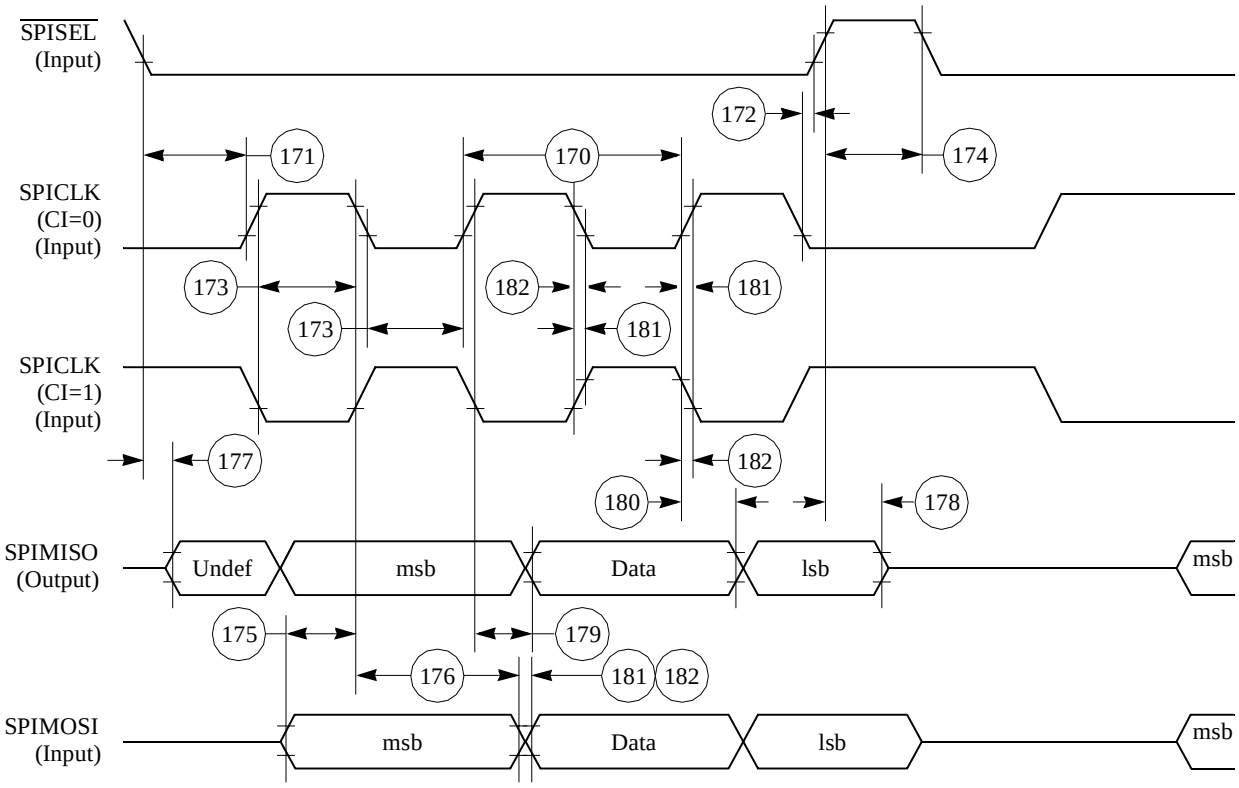

Figure 60. SPI Slave (CP = 1) Timing Diagram

8.11 I²C AC Electrical Specifications

Table 24 provides the I²C (SCL < 100 KHz) timings.

Table 24. I²C Timing (SCL < 100 KHz)

Num	Characteristic	All Frequencies		Unit
		Min	Max	
200	SCL clock frequency (slave)	0.00	100.00	KHz
200	SCL clock frequency (master) [1]	1.50	100.00	KHz
202	Bus free time between transmissions	4.70	—	µs
203	Low period of SCL	4.70	—	µs
204	High period of SCL	4.00	—	µs
205	Start condition setup time	4.70	—	µs
206	Start condition hold time	4.00	—	µs
207	Data hold time	0.00	—	µs
208	Data setup time	250.00	—	ns
209	SDL/SCL rise time	—	1.00	µs

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