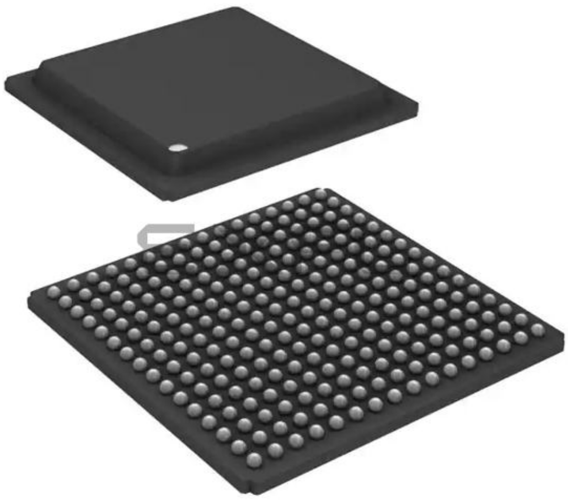


Welcome to E-XFL.COM

Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	80MHz
Co-Processors/DSP	Communications; CPM
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10Mbps (1)
SATA	-
USB	USB 1.x (1)
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 95°C (TA)
Security Features	-
Package / Case	256-BBGA
Supplier Device Package	256-PBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/xpc850vr80bu

2 Features

Figure 1 is a block diagram of the MPC850, showing its major components and the relationships among those components:

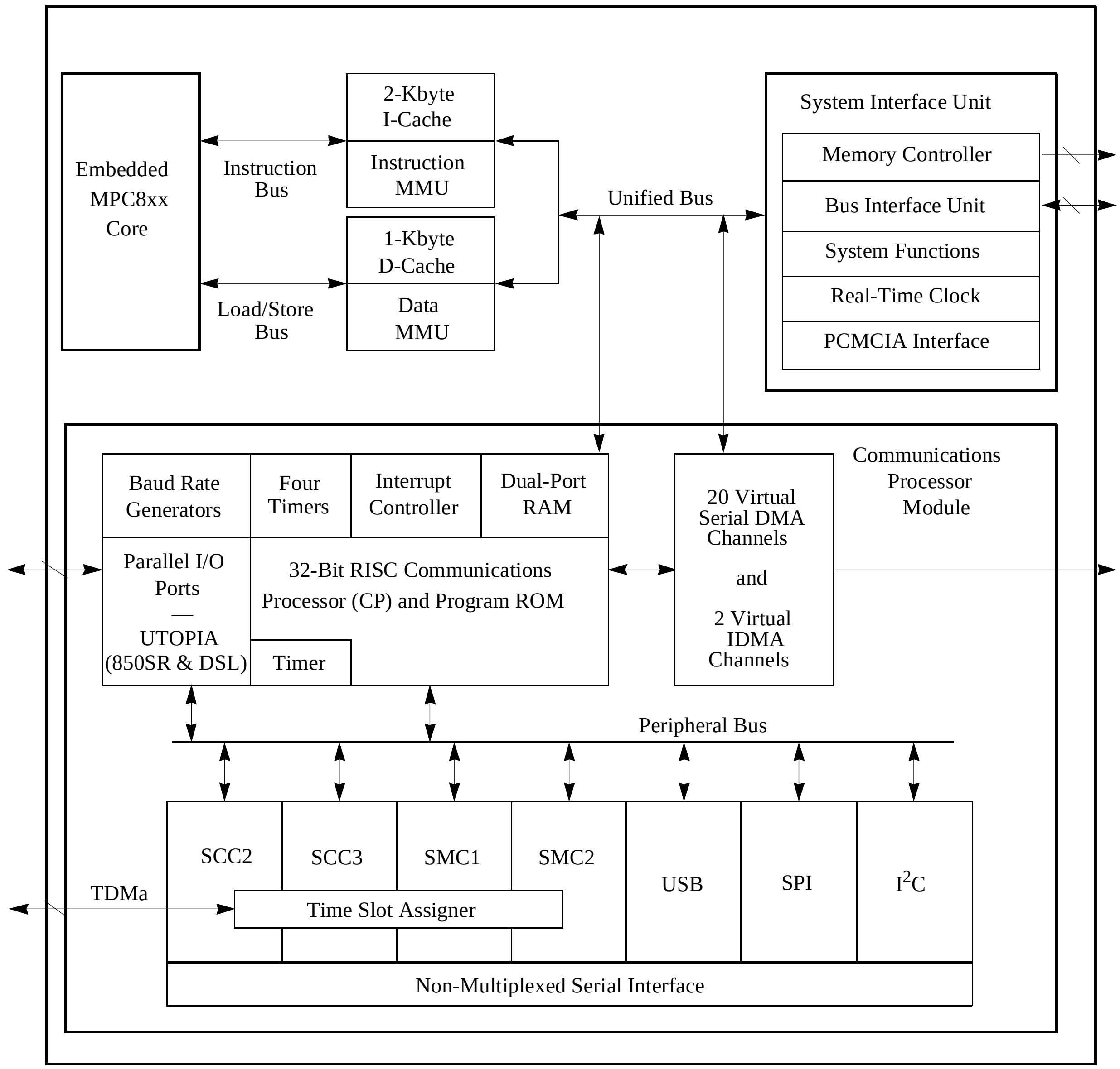


Figure 1. MPC850 Microprocessor Block Diagram

The following list summarizes the main features of the MPC850:

- Embedded single-issue, 32-bit MPC8xx core (implementing the PowerPC architecture) with thirty-two 32-bit general-purpose registers (GPRs)
  - — Performs branch folding and branch prediction with conditional prefetch, but without conditional execution

- 2-Kbyte instruction cache and 1-Kbyte data cache (Harvard architecture)
  - Caches are two-way, set-associative
  - Physically addressed
  - Cache blocks can be updated with a 4-word line burst
  - Least-recently used (LRU) replacement algorithm
  - Lockable one-line granularity
- Memory management units (MMUs) with 8-entry translation lookaside buffers (TLBs) and fully-associative instruction and data TLBs
- MMUs support multiple page sizes of 4 Kbytes, 16 Kbytes, 256 Kbytes, 512 Kbytes, and 8 Mbytes; 16 virtual address spaces and eight protection groups

• Advanced on-chip emulation debug mode
• Data bus dynamic bus sizing for 8, 16, and 32-bit buses
  - Supports traditional 68000 big-endian, traditional x86 little-endian and modified little-endian memory systems
  - Twenty-six external address lines
• Completely static design (0–80 MHz operation)
• System integration unit (SIU)
  - Hardware bus monitor
  - Spurious interrupt monitor
  - Software watchdog
  - Periodic interrupt timer
  - Low-power stop mode
  - Clock synthesizer
  - Decrementer, time base, and real-time clock (RTC) from the PowerPC architecture
  - Reset controller
  - IEEE 1149.1 test access port (JTAG)
• Memory controller (eight banks)
  - Glueless interface to DRAM single in-line memory modules (SIMMs), synchronous DRAM (SDRAM), static random-access memory (SRAM), electrically programmable read-only memory (EPROM), flash EPROM, etc.
  - Memory controller programmable to support most size and speed memory interfaces
  - Boot chip-select available at reset (options for 8, 16, or 32-bit memory)
  - Variable block sizes, 32 Kbytes to 256 Mbytes
  - Selectable write protection
  - On-chip bus arbiter supports one external bus master
  - Special features for burst mode support
• General-purpose timers
  - Four 16-bit timers or two 32-bit timers

  - Gate mode can enable/disable counting
  - Interrupt can be masked on reference match and event capture
- Interrupts
  - Eight external interrupt request (IRQ) lines
  - Twelve port pins with interrupt capability
  - Fifteen internal interrupt sources
  - Programmable priority among SCCs and USB
  - Programmable highest-priority request
- Single socket PCMCIA-ATA interface
  - Master (socket) interface, release 2.1 compliant
  - Single PCMCIA socket
  - Supports eight memory or I/O windows
- Communications processor module (CPM)
  - 32-bit, Harvard architecture, scalar RISC communications processor (CP)
  - Protocol-specific command sets (for example, GRACEFUL STOP TRANSMIT stops transmission after the current frame is finished or immediately if no frame is being sent and CLOSE RXBD closes the receive buffer descriptor)
  - Supports continuous mode transmission and reception on all serial channels
  - Up to 8 Kbytes of dual-port RAM
  - Twenty serial DMA (SDMA) channels for the serial controllers, including eight for the four USB endpoints
  - Three parallel I/O registers with open-drain capability
- Four independent baud-rate generators (BRGs)
  - Can be connected to any SCC, SMC, or USB
  - Allow changes during operation
  - Autobaud support option
- Two SCCs (serial communications controllers)
  - Ethernet/IEEE 802.3, supporting full 10-Mbps operation
  - HDLC/SDLC™ (all channels supported at 2 Mbps)
  - HDLC bus (implements an HDLC-based local area network (LAN))
  - Asynchronous HDLC to support PPP (point-to-point protocol)
  - AppleTalk®
  - Universal asynchronous receiver transmitter (UART)
  - Synchronous UART
  - Serial infrared (IrDA)
  - Totally transparent (bit streams)
  - Totally transparent (frame based with optional cyclic redundancy check (CRC))

4 Thermal Characteristics

Table 3 shows the thermal characteristics for the MPC850.

Table 3. Thermal Characteristics

Characteristic	Symbol	Value	Unit
Thermal resistance for BGA [1]	θ_{JA}	40 [2]	°C/W
	θ_{JA}	31 [3]	°C/W
	θ_{JA}	24 [4]	°C/W
Thermal Resistance for BGA (junction-to-case)	θ_{JC}	8	°C/W

1 For more information on the design of thermal vias on multilayer boards and BGA layout considerations in general, refer to AN-1231/D, *Plastic Ball Grid Array Application Note* available from your local Freescale sales office.

2 Assumes natural convection and a single layer board (no thermal vias).

3 Assumes natural convection, a multilayer board with thermal vias[4], 1 watt MPC850 dissipation, and a board temperature rise of 20°C above ambient.

4 Assumes natural convection, a multilayer board with thermal vias[4], 1 watt MPC850 dissipation, and a board temperature rise of 13°C above ambient.

$T_J = T_A + (P_D \bullet \theta_{JA})$

$P_D = (V_{DD} \bullet I_{DD}) + P_{I/O}$

where:

$P_{I/O}$ is the power dissipation on pins

Table 4 provides power dissipation information.

Table 4. Power Dissipation (P_D)

Characteristic	Frequency (MHz)	Typical [1]	Maximum [2]	Unit
Power Dissipation All Revisions (1:1) Mode	33	TBD	515	mW
	40	TBD	590	mW
	50	TBD	725	mW

1 Typical power dissipation is measured at 3.3V

2 Maximum power dissipation is measured at 3.65 V

Table 5 provides the DC electrical characteristics for the MPC850.

Table 5. DC Electrical Specifications

Characteristic	Symbol	Min	Max	Unit
Operating voltage at 40 MHz or less	VDDH, VDDL, KAPWR, VDDSYN	3.0	3.6	V
Operating voltage at 40 MHz or higher	VDDH, VDDL, KAPWR, VDDSYN	3.135	3.465	V
Input high voltage (address bus, data bus, EXTAL, EXTCLK, and all bus control/status signals)	VIH	2.0	3.6	V
Input high voltage (all general purpose I/O and peripheral pins)	VIH	2.0	5.5	V

Table 5. DC Electrical Specifications (continued)

Characteristic	Symbol	Min	Max	Unit
Input low voltage	VIL	GND	0.8	V
EXTAL, EXTCLK input high voltage	VIHC	0.7*(VCC)	VCC+0.3	V
Input leakage current, Vin = 5.5 V (Except TMS, TRST, DSCK and DSDI pins)	I_{in}	—	100	µA
Input leakage current, Vin = 3.6V (Except TMS, TRST, DSCK and DSDI pins)	I_{In}	—	10	µA
Input leakage current, Vin = 0V (Except TMS, TRST, DSCK and DSDI pins)	I_{In}	—	10	µA
Input capacitance	C_{in}	—	20	pF
Output high voltage, IOH = -2.0 mA, VDDH = 3.0V except XTAL, XFC, and open-drain pins	VOH	2.4	—	V
Output low voltage CLKOUT [3] IOL = 3.2 mA [1] IOL = 5.3 mA [2] IOL = 7.0 mA PA[14]/USBOE, PA[12]/TXD2 IOL = 8.9 mA TS, TA, TEA, BI, BB, HRESET, SRESET	VOL	—	0.5	V

1 A[6:31], TSIZ0/REG, TSIZ1, D[0:31], DP[0:3]/IRQ[3:6], RD/WR, BURST, RSV/IRQ2, IP_B[0:1]/IWP[0:1]/VFLS[0:1], IP_B2/IOIS16_B/AT2, IP_B3/IWP2/VF2, IP_B4/LWP0/VF0, IP_B5/LWP1/VF1, IP_B6/DSDI/AT0, IP_B7/PTR/AT3, PA[15]/USBRXD, PA[13]/RXD2, PA[9]/L1TXDA/SMRXD2, PA[8]/L1RXDA/SMTXD2, PA[7]/CLK1/TIN1/L1RCLKA/BRGO1, PA[6]/CLK2/TOUT1/TIN3, PA[5]/CLK3/TIN2/L1TCLKA/BRGO2, PA[4]/CLK4/TOUT2/TIN4, PB[31]/SPISEL, PB[30]/SPICLK/TXD3, PB[29]/SPIMOSI /RXD3, PB[28]/SPIMISO/BRGO3, PB[27]/I2CSDA/BRGO1, PB[26]/I2CSCL/BRGO2, PB[25]/SMTXD1/TXD3, PB[24]/SMRXD1/RXD3, PB[23]/SMSYN1/SDACK1, PB[22]/SMSYN2/SDACK2, PB[19]/L1ST1, PB[18]/RTS2/L1ST2, PB[17]/L1ST3, PB[16]/L1RQa/L1ST4, PC[15]/DREQ0/L1ST5, PC[14]/DREQ1/RTS2/L1ST6, PC[13]/L1ST7/RTS3, PC[12]/L1RQa/L1ST8, PC[11]/USBRXP, PC[10]/TGATE1/USBRXN, PC[9]/CTS2, PC[8]/CD2/TGATE1, PC[7]/USBTXP, PC[6]/USBTXN, PC[5]/CTS3/L1TSYNCA/SDACK1, PC[4]/CD3/L1RSYNCA, PD[15], PD[14], PD[13], PD[12], PD[11], PD[10], PD[9], PD[8], PD[7], PD[6], PD[5], PD[4], PD[3]

2 BDIP/GPL_B5, BR, BG, FRZ/IRQ6, CS[0:5], CS6/CE1_B, CS7/CE2_B, WE0/BS_AB0/IORD, WE1/BS_AB1/IOWR, WE2/BS_AB2/PCOE, WE3/BS_AB3/PCWE, GPL_A0/GPL_B0, OE/GPL_A1/GPL_B1, GPL_A[2:3]/GPL_B[2:3]/CS[2:3], UPWAITA/GPL_A4/AS, UPWAITB/GPL_B4, GPL_A5, ALE_B/DSCK/AT1, OP2/MODCK1/STS, OP3/MODCK2/DSDO

3 The MPC850 IBIS model must be used to accurately model the behavior of the Clkout output driver for the full and half drive setting. Due to the nature of the Clkout output buffer, IOH and IOL for Clkout should be extracted from the IBIS model at any output voltage level.

5 Power Considerations

The average chip-junction temperature, T_J, in °C can be obtained from the equation:

$T_J = T_A + (P_D \bullet \theta_{JA})$(1)

where

T_A = Ambient temperature, °C

Table 6. Bus Operation Timing [1] (continued)

Num	Characteristic	50 MHz		66 MHz		80 MHz		FFACT	Cap Load (default 50 pF)	Unit
		Min	Max	Min	Max	Min	Max			
B9	CLKOUT to A[6–31] RD/WR, BURST, D[0–31], DP[0–3], TSIZ[0–1], REG, RSV, AT[0–3], PTR high-Z	5.00	11.75	7.58	14.33	6.25	13.00	0.250	50.00	ns
B11	CLKOUT to TS, BB assertion	5.00	11.00	7.58	13.58	6.25	12.25	0.250	50.00	ns
B11a	CLKOUT to TA, BI assertion, (When driven by the memory controller or PCMCIA interface)	2.50	9.25	2.50	9.25	2.50	9.25	—	50.00	ns
B12	CLKOUT to TS, BB negation	5.00	11.75	7.58	14.33	6.25	13.00	0.250	50.00	ns
B12a	CLKOUT to TA, BI negation (when driven by the memory controller or PCMCIA interface)	2.50	11.00	2.50	11.00	2.50	11.00	—	50.00	ns
B13	CLKOUT to TS, BB high-Z	5.00	19.00	7.58	21.58	6.25	20.25	0.250	50.00	ns
B13a	CLKOUT to TA, BI high-Z, (when driven by the memory controller or PCMCIA interface)	2.50	15.00	2.50	15.00	2.50	15.00	—	50.00	ns
B14	CLKOUT to TEA assertion	2.50	10.00	2.50	10.00	2.50	10.00	—	50.00	ns
B15	CLKOUT to TEA high-Z	2.50	15.00	2.50	15.00	2.50	15.00	—	50.00	ns
B16	TA, BI valid to CLKOUT(setup time) [5]	9.75	—	9.75	—	9.75	—	—	50.00	ns
B16a	TEA, KR, RETRY, valid to CLKOUT (setup time) [5]	10.00	—	10.00	—	10.00	—	—	50.00	ns
B16b	BB, BG, BR valid to CLKOUT (setup time) [6]	8.50	—	8.50	—	8.50	—	—	50.00	ns
B17	CLKOUT to TA, TEA, BI, BB, BG, BR valid (Hold time).[5]	1.00	—	1.00	—	1.00	—	—	50.00	ns
B17a	CLKOUT to KR, RETRY, except TEA valid (hold time)	2.00	—	2.00	—	2.00	—	—	50.00	ns
B18	D[0–31], DP[0–3] valid to CLKOUT rising edge (setup time) [7]	6.00	—	6.00	—	6.00	—	—	50.00	ns
B19	CLKOUT rising edge to D[0–31], DP[0–3] valid (hold time) [7]	1.00	—	1.00	—	1.00	—	—	50.00	ns
B20	D[0–31], DP[0–3] valid to CLKOUT falling edge (setup time) [8]	4.00	—	4.00	—	4.00	—	—	50.00	ns
B21	CLKOUT falling edge to D[0–31], DP[0–3] valid (hold time) [8]	2.00	—	2.00	—	2.00	—	—	—	—

Table 6. Bus Operation Timing [1] (continued)

Num	Characteristic	50 MHz		66 MHz		80 MHz		FFACT	Cap Load (default 50 pF)	Unit
		Min	Max	Min	Max	Min	Max			
B28c	CLKOUT falling edge to WE[0–3] negated GPCM write access TRLX = 0,1 CSNT = 1 write access TRLX = 0, CSNT = 1, EBDF = 1	7.00	14.00	11.00	18.00	9.00	16.00	0.375	50.00	ns
B28d	CLKOUT falling edge to CS negated GPCM write access TRLX = 0,1 CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1	—	14.00	—	18.00	—	16.00	0.375	50.00	ns
B29	WE[0–3] negated to D[0–31], DP[0–3] high-Z GPCM write access, CSNT = 0	3.00	—	6.00	—	4.00	—	0.250	50.00	ns
B29a	WE[0–3] negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 0 CSNT = 1, EBDF = 0	8.00	—	13.00	—	11.00	—	0.500	50.00	ns
B29b	CS negated to D[0–31], DP[0–3], high-Z GPCM write access, ACS = 00, TRLX = 0 & CSNT = 0	3.00	—	6.00	—	4.00	—	0.250	50.00	ns
B29c	CS negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0	8.00	—	13.00	—	11.00	—	0.500	50.00	ns
B29d	WE[0–3] negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 1, CSNT = 1, EBDF = 0	28.00	—	43.00	—	36.00	—	1.500	50.00	ns
B29e	CS negated to D[0–31], DP[0–3] high-Z GPCM write access, TRLX = 1, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0	28.00	—	43.00	—	36.00	—	1.500	50.00	ns
B29f	WE[0–3] negated to D[0–31], DP[0–3] high-Z GPCM write access TRLX = 0, CSNT = 1, EBDF = 1	5.00	—	9.00	—	7.00	—	0.375	50.00	ns
B29g	CS negated to D[0–31], DP[0–3] high-Z GPCM write access TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1	5.00	—	9.00	—	7.00	—	0.375	50.00	ns

Table 6. Bus Operation Timing [1] (continued)

Num	Characteristic	50 MHz		66 MHz		80 MHz		FFACT	Cap Load (default 50 pF)	Unit
		Min	Max	Min	Max	Min	Max			
B33a	CLKOUT rising edge to GPL valid - as requested by control bit GxT3 in the corresponding word in the UPM	5.00	12.00	8.00	14.00	6.00	13.00	0.250	50.00	ns
B34	A[6–31] and D[0–31] to $\overline{CS}$ valid - as requested by control bit CST4 in the corresponding word in the UPM	3.00	—	6.00	—	4.00	—	0.250	50.00	ns
B34a	A[6–31] and D[0–31] to $\overline{CS}$ valid - as requested by control bit CST1 in the corresponding word in the UPM	8.00	—	13.00	—	11.00	—	0.500	50.00	ns
B34b	A[6–31] and D[0–31] to $\overline{CS}$ valid - as requested by CST2 in the corresponding word in UPM	13.00	—	21.00	—	17.00	—	0.750	50.00	ns
B35	A[6–31] to $\overline{CS}$ valid - as requested by control bit BST4 in the corresponding word in UPM	3.00	—	6.00	—	4.00	—	0.250	50.00	ns
B35a	A[6–31] and D[0–31] to $\overline{BS}$ valid - as requested by BST1 in the corresponding word in the UPM	8.00	—	13.00	—	11.00	—	0.500	50.00	ns
B35b	A[6–31] and D[0–31] to $\overline{BS}$ valid - as requested by control bit BST2 in the corresponding word in the UPM	13.00	—	21.00	—	17.00	—	0.750	50.00	ns
B36	A[6–31] and D[0–31] to GPL valid - as requested by control bit GxT4 in the corresponding word in the UPM	3.00	—	6.00	—	4.00	—	0.250	50.00	ns
B37	UPWAIT valid to CLKOUT falling edge [10]	6.00	—	6.00	—	6.00	—	—	50.00	ns
B38	CLKOUT falling edge to UPWAIT valid [10]	1.00	—	1.00	—	1.00	—	—	50.00	ns
B39	$\overline{AS}$ valid to CLKOUT rising edge [11]	7.00	—	7.00	—	7.00	—	—	50.00	ns
B40	A[6–31], TSIZ[0–1], RD/$\overline{WR}$, $\overline{BURST}$, valid to CLKOUT rising edge.	7.00	—	7.00	—	7.00	—	—	50.00	ns
B41	$\overline{TS}$ valid to CLKOUT rising edge (setup time)	7.00	—	7.00	—	7.00	—	—	50.00	ns

Figure 13 through Figure 15 provide the timing for the external bus write controlled by various GPCM factors.

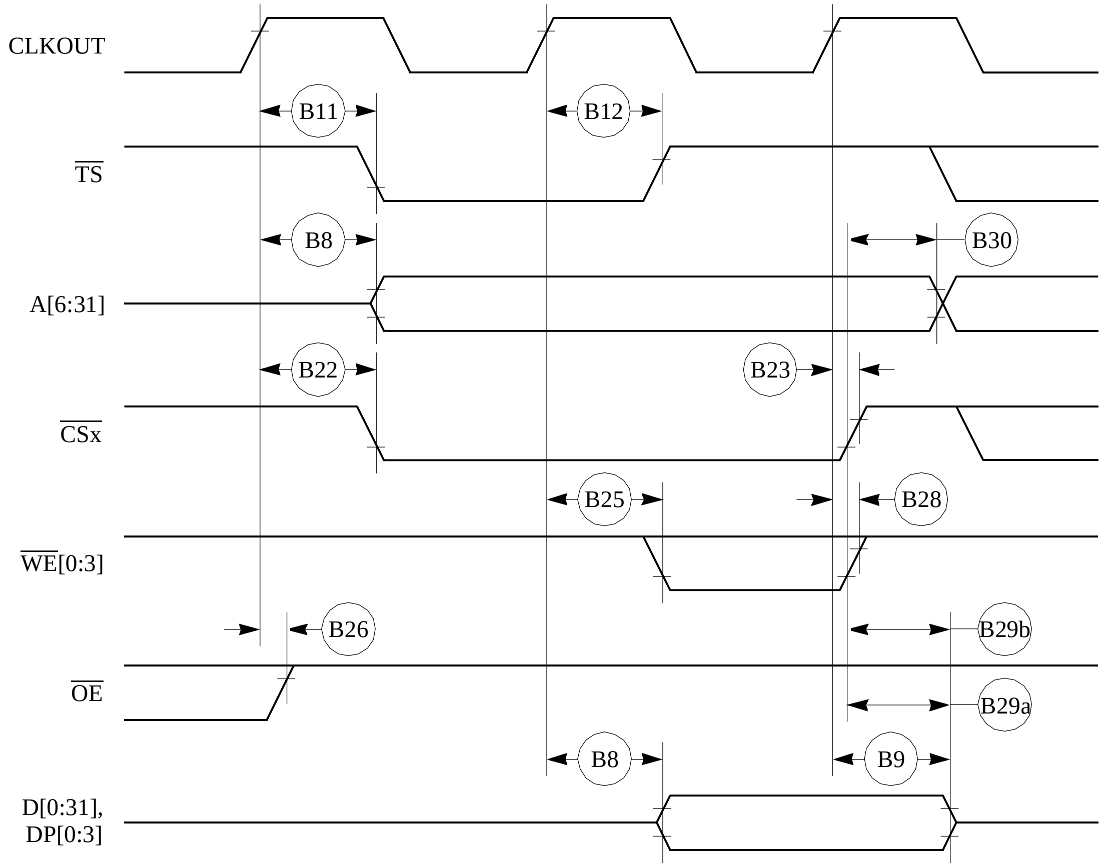


Figure 13. External Bus Write Timing (GPCM Controlled—TRLX = 0, CSNT = 0)

Figure 16 provides the timing for the external bus controlled by the UPM.

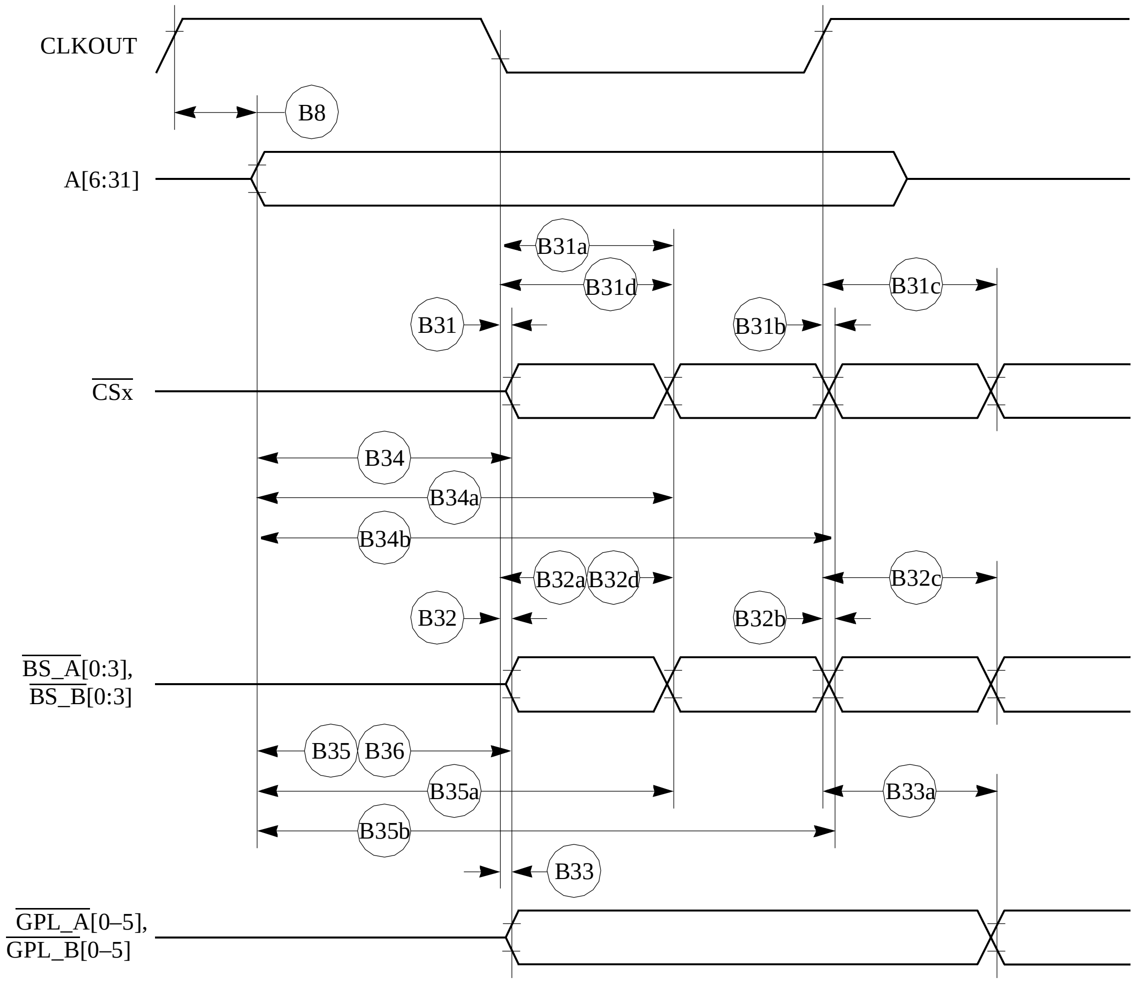


Figure 16. External Bus Timing (UPM Controlled Signals)

Table 7 provides interrupt timing for the MPC850.

Table 7. Interrupt Timing

Num	Characteristic [1]	50 MHz		66MHz		80 MHz		Unit
		Min	Max	Min	Max	Min	Max	
I39	IRQx valid to CLKOUT rising edge (set up time)	6.00	—	6.00	—	6.00	—	ns
I40	IRQx hold time after CLKOUT.	2.00	—	2.00	—	2.00	—	ns
I41	IRQx pulse width low	3.00	—	3.00	—	3.00	—	ns
I42	IRQx pulse width high	3.00	—	3.00	—	3.00	—	ns
I43	IRQx edge-to-edge time	80.00	—	121.0	—	100.0	—	ns

[1] The timings I39 and I40 describe the testing conditions under which the IRQ lines are tested when being defined as level sensitive. The IRQ lines are synchronized internally and do not have to be asserted or negated with reference to the CLKOUT.

The timings I41, I42, and I43 are specified to allow the correct function of the IRQ lines detection circuitry, and has no direct relation with the total system interrupt latency that the MPC850 is able to support

Figure 22 provides the interrupt detection timing for the external level-sensitive lines.

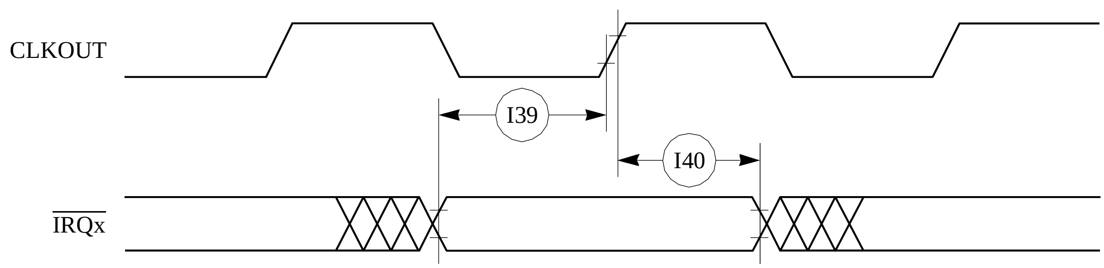


Figure 22. Interrupt Detection Timing for External Level Sensitive Lines

Figure 23 provides the interrupt detection timing for the external edge-sensitive lines.

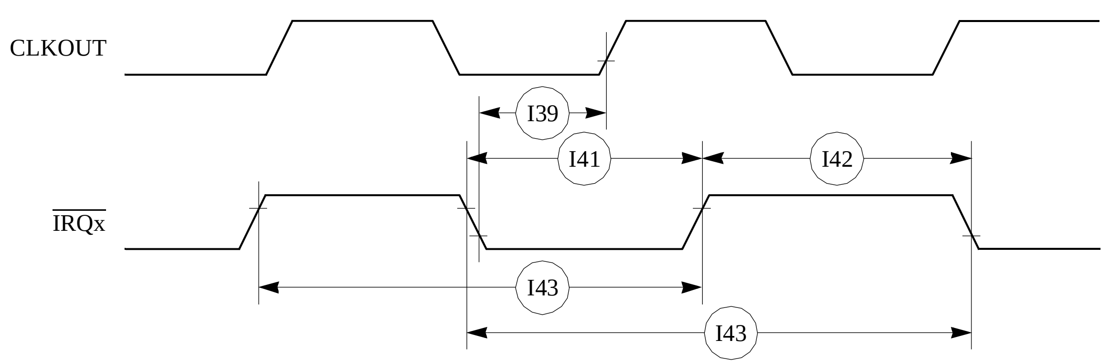


Figure 23. Interrupt Detection Timing for External Edge Sensitive Lines

Figure 25 provides the PCMCIA access cycle timing for the external bus write.

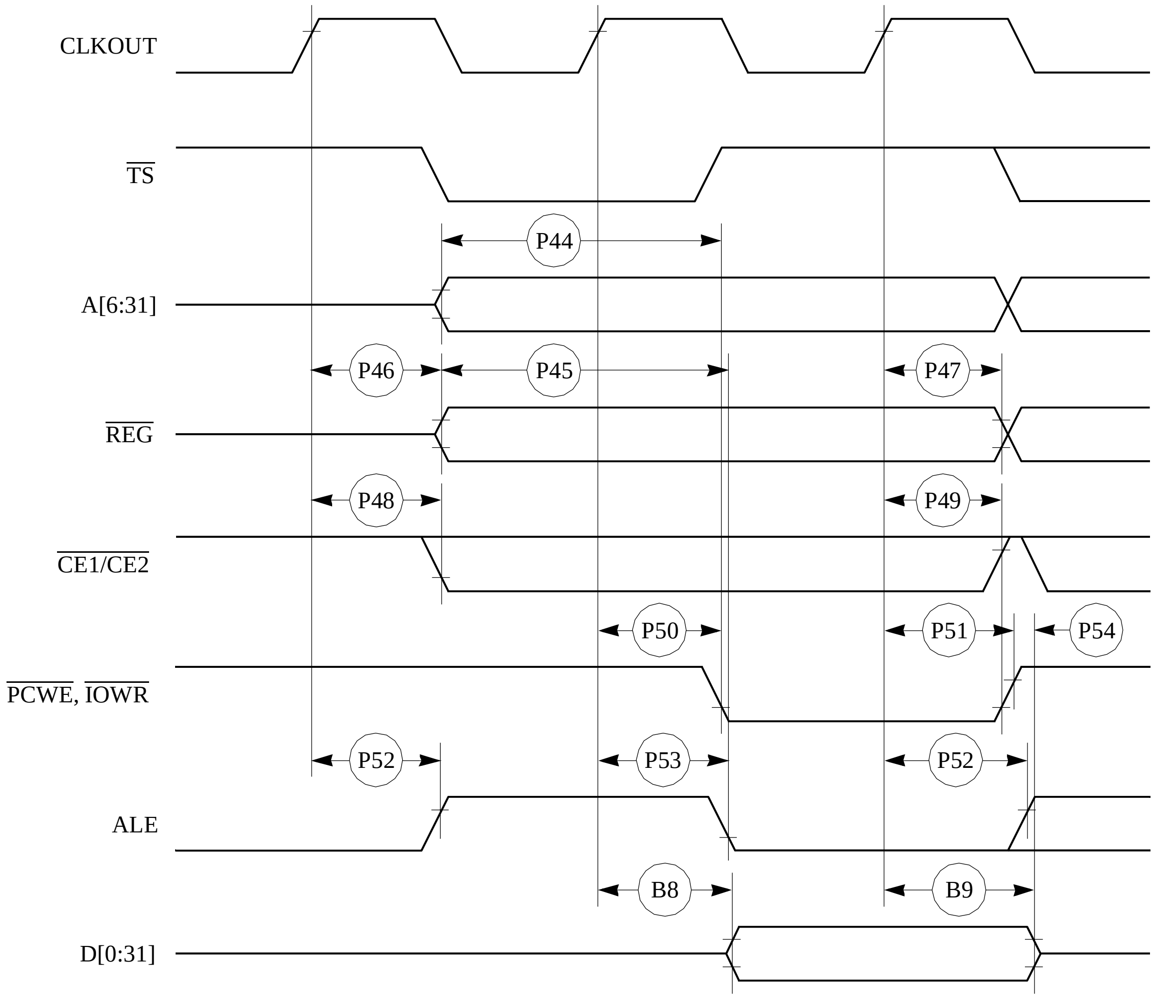


Figure 25. PCMCIA Access Cycles Timing External Bus Write

Figure 26 provides the PCMCIA WAIT signals detection timing.

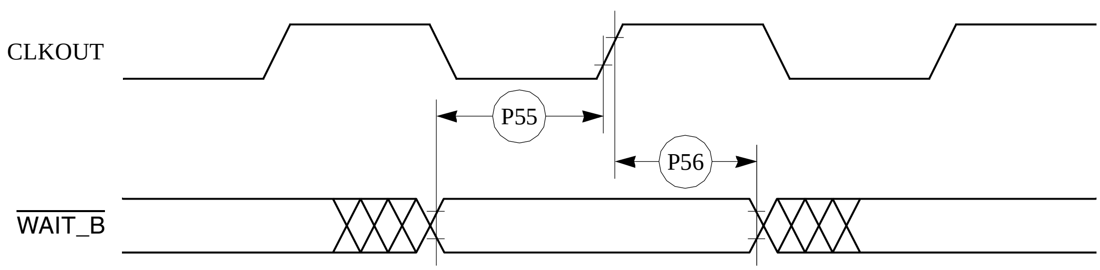


Figure 26. PCMCIA WAIT Signal Detection Timing

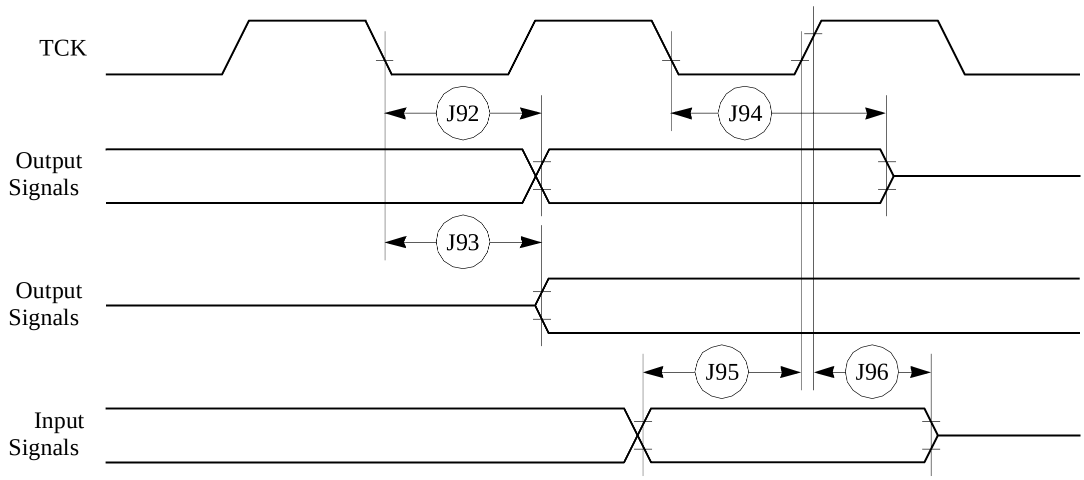


Figure 37. Boundary Scan (JTAG) Timing Diagram

8 CPM Electrical Characteristics

This section provides the AC and DC electrical specifications for the communications processor module (CPM) of the MPC850.

8.1 PIO AC Electrical Specifications

Table 13 provides the parallel I/O timings for the MPC850 as shown in Figure 38.

Table 13. Parallel I/O Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
29	Data-in setup time to clock high	15	—	ns
30	Data-in hold time from clock high	7.5	—	ns
31	Clock low to data-out valid (CPU writes data, control, or direction)	—	25	ns

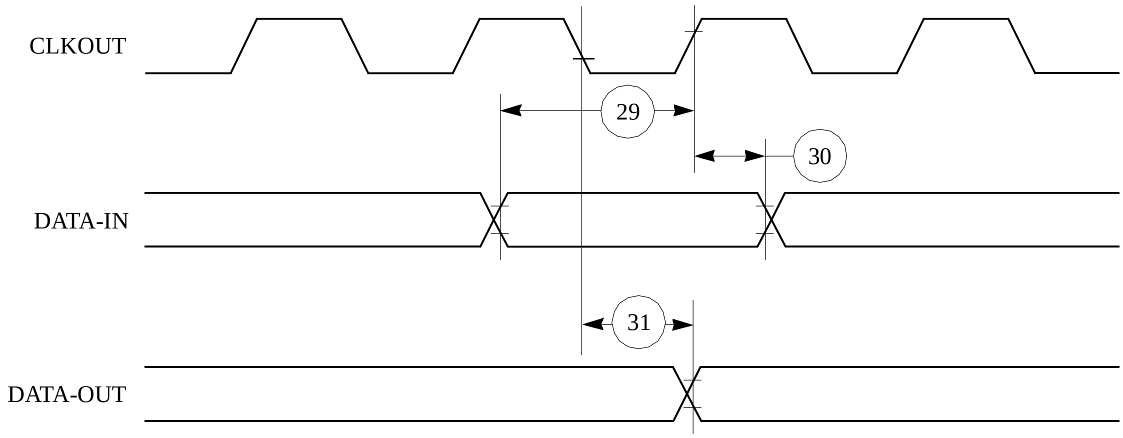


Figure 38. Parallel I/O Data-In/Data-Out Timing Diagram

8.2 IDMA Controller AC Electrical Specifications

Table 14 provides the IDMA controller timings as shown in Figure 39 to Figure 42.

Table 14. IDMA Controller Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
40	$\overline{\text{DREQ}}$ setup time to clock high	7.00	—	ns
41	$\overline{\text{DREQ}}$ hold time from clock high	3.00	—	ns
42	$\overline{\text{SDACK}}$ assertion delay from clock high	—	12.00	ns
43	$\overline{\text{SDACK}}$ negation delay from clock low	—	12.00	ns
44	$\overline{\text{SDACK}}$ negation delay from $\overline{\text{TA}}$ low	—	20.00	ns
45	$\overline{\text{SDACK}}$ negation delay from clock high	—	15.00	ns
46	$\overline{\text{TA}}$ assertion to falling edge of the clock setup time (applies to external $\overline{\text{TA}}$)	7.00	—	ns

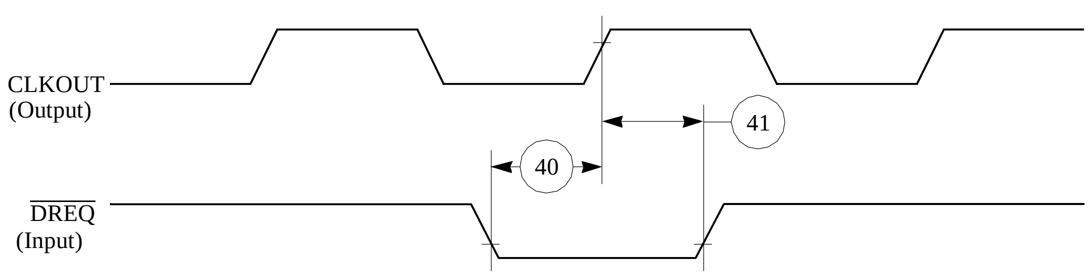


Figure 39. IDMA External Requests Timing Diagram

Table 17. SI Timing (continued)

Num	Characteristic	All Frequencies		Unit
		Min	Max	
82	L1RCLK, L1TCLK frequency (DSC =1)	—	16.00 or SYNCCLK/2	MHz
83	L1RCLK, L1TCLK width low (DSC =1)	P + 10	—	ns
83A	L1RCLK, L1TCLK width high (DSC = 1)[3]	P + 10	—	ns
84	L1CLK edge to L1CLKO valid (DSC = 1)	—	30.00	ns
85	$\overline{\text{L1RQ}}$ valid before falling edge of L1TSYNC[4]	1.00	—	L1TCLK
86	L1GR setup time[2]	42.00	—	ns
87	L1GR hold time	42.00	—	ns
88	L1xCLK edge to L1SYNC valid (FSD = 00) CNT = 0000, BYT = 0, DSC = 0)	—	0.00	ns

1 The ratio SyncCLK/L1RCLK must be greater than 2.5/1.

2 These specs are valid for IDL mode only.

3 Where P = 1/CLKOUT. Thus for a 25-MHz CLKO1 rate, P = 40 ns.

4 These strobes and TxD on the first bit of the frame become valid after L1CLK edge or L1SYNC, whichever is later.

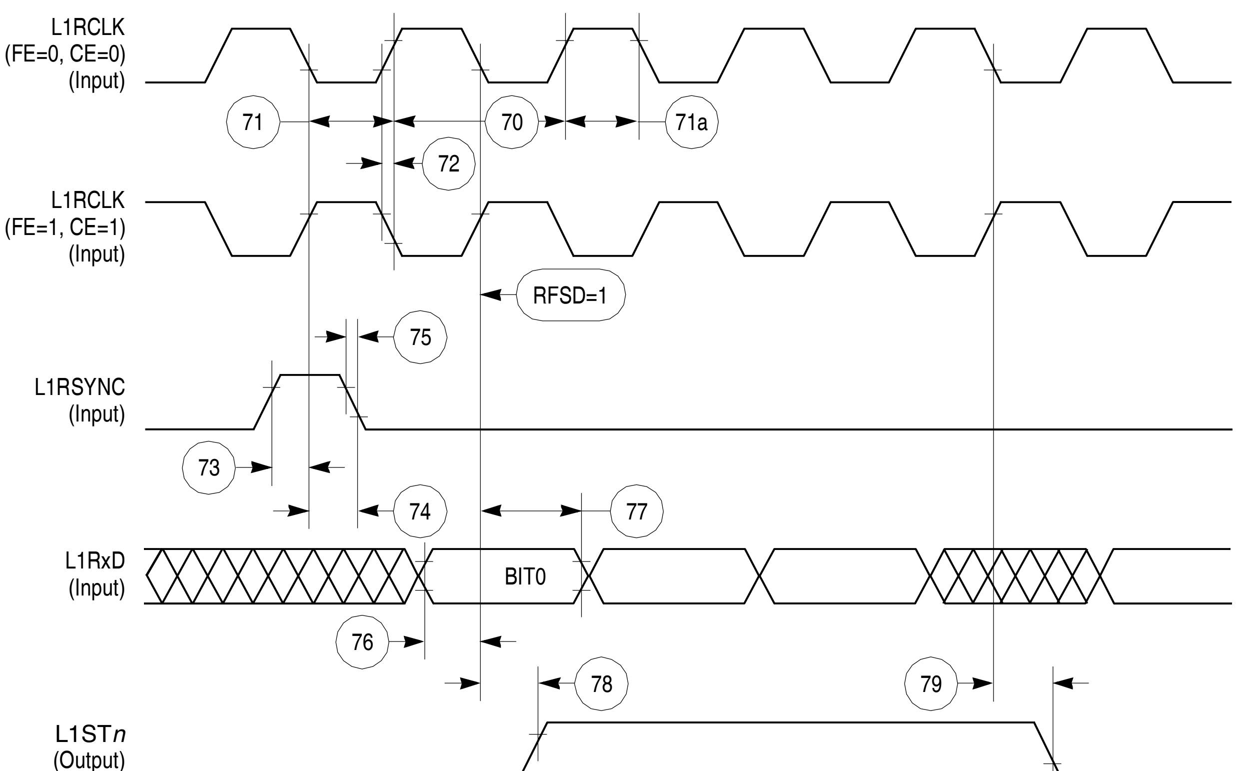


Figure 45. SI Receive Timing Diagram with Normal Clocking (DSC = 0)

8.6 SCC in NMSI Mode Electrical Specifications

Table 18 provides the NMSI external clock timing.

Table 18. NMSI External Clock Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
100	RCLKx and TCLKx frequency [1] (x = 2, 3 for all specs in this table)	1/SYNCCLK	—	ns
101	RCLKx and TCLKx width low	1/SYNCCLK +5	—	ns
102	RCLKx and TCLKx rise/fall time	—	15.00	ns
103	TXDx active delay (from TCLKx falling edge)	0.00	50.00	ns
104	$\overline{\text{RTSx}}$ active/inactive delay (from TCLKx falling edge)	0.00	50.00	ns
105	$\overline{\text{CTSx}}$ setup time to TCLKx rising edge	5.00	—	ns
106	RXDx setup time to RCLKx rising edge	5.00	—	ns
107	RXDx hold time from RCLKx rising edge [2]	5.00	—	ns
108	$\overline{\text{CDx}}$ setup time to RCLKx rising edge	5.00	—	ns

[1] The ratios SyncCLK/RCLKx and SyncCLK/TCLKx must be greater than or equal to 2.25/1.
[2] Also applies to $\overline{\text{CD}}$ and $\overline{\text{CTS}}$ hold time when they are used as an external sync signal.

Table 19 provides the NMSI internal clock timing.

Table 19. NMSI Internal Clock Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
100	RCLKx and TCLKx frequency [1] (x = 2, 3 for all specs in this table)	0.00	SYNCCLK/3	MHz
102	RCLKx and TCLKx rise/fall time	—	—	ns
103	TXDx active delay (from TCLKx falling edge)	0.00	30.00	ns
104	$\overline{\text{RTSx}}$ active/inactive delay (from TCLKx falling edge)	0.00	30.00	ns
105	$\overline{\text{CTSx}}$ setup time to TCLKx rising edge	40.00	—	ns
106	RXDx setup time to RCLKx rising edge	40.00	—	ns
107	RXDx hold time from RCLKx rising edge [2]	0.00	—	ns
108	$\overline{\text{CDx}}$ setup time to RCLKx rising edge	40.00	—	ns

[1] The ratios SyncCLK/RCLKx and SyncCLK/TCLK1x must be greater or equal to 3/1.
[2] Also applies to $\overline{\text{CD}}$ and $\overline{\text{CTS}}$ hold time when they are used as an external sync signals.

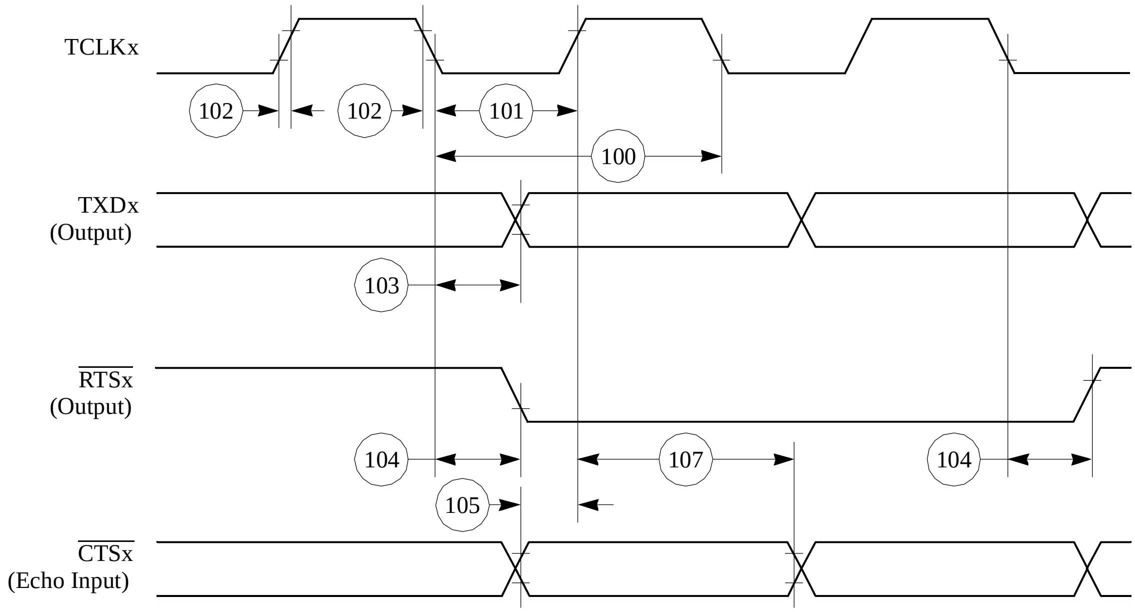


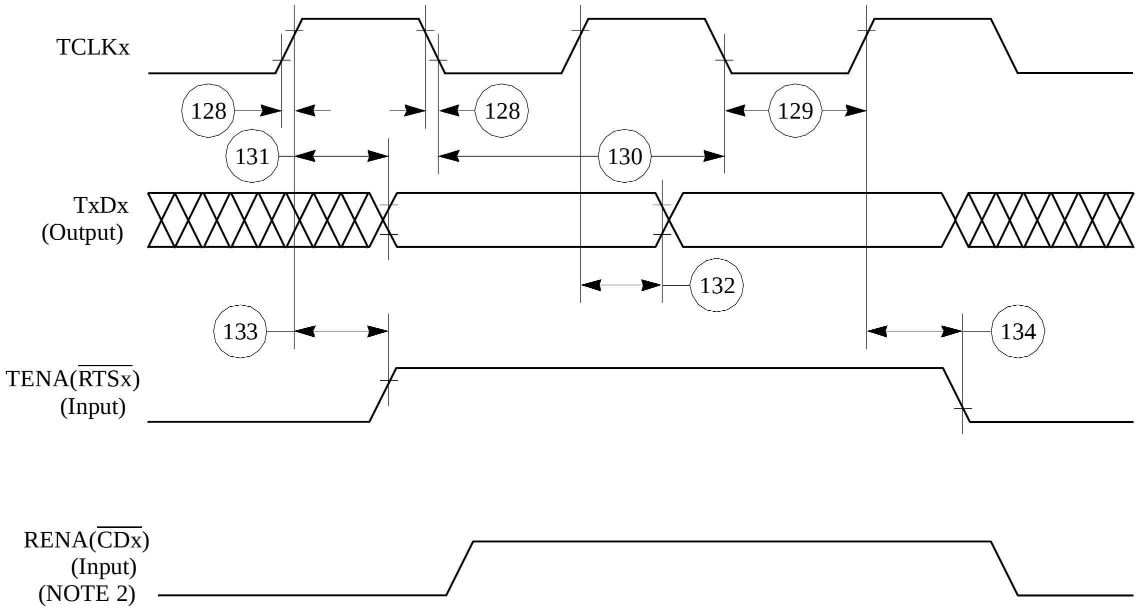
Figure 52. HDLC Bus Timing Diagram

8.7 Ethernet Electrical Specifications

Table 20 provides the Ethernet timings as shown in Figure 53 to Figure 55.

Table 20. Ethernet Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
120	CLSN width high	40.00	—	ns
121	RCLKx rise/fall time (x = 2, 3 for all specs in this table)	—	15.00	ns
122	RCLKx width low	40.00	—	ns
123	RCLKx clock period [1]	80.00	120.00	ns
124	RXDx setup time	20.00	—	ns
125	RXDx hold time	5.00	—	ns
126	RENA active delay (from RCLKx rising edge of the last data bit)	10.00	—	ns
127	RENA width low	100.00	—	ns
128	TCLKx rise/fall time	—	15.00	ns
129	TCLKx width low	40.00	—	ns
130	TCLKx clock period[1]	99.00	101.00	ns
131	TXDx active delay (from TCLKx rising edge)	10.00	50.00	ns
132	TXDx inactive delay (from TCLKx rising edge)	10.00	50.00	ns
133	TENA active delay (from TCLKx rising edge)	10.00	50.00	ns



NOTES:
1. Transmit clock invert (TCI) bit in GSMR is set.
2. If RENA is deasserted before TENA, or RENA is not asserted at all during transmit, then the CSL bit is set in the buffer descriptor at the end of the frame transmission.

Figure 55. Ethernet Transmit Timing Diagram

8.8 SMC Transparent AC Electrical Specifications

Figure 21 provides the SMC transparent timings as shown in Figure 56.

Table 21. Serial Management Controller Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
150	SMCLKx clock period [1]	100.00	—	ns
151	SMCLKx width low	50.00	—	ns
151a	SMCLKx width high	50.00	—	ns
152	SMCLKx rise/fall time	—	15.00	ns
153	SMTXDx active delay (from SMCLKx falling edge)	10.00	50.00	ns
154	SMRXDx/SMSYNx setup time	20.00	—	ns
155	SMRXDx/SMSYNx hold time	5.00	—	ns

[1] The ratio SyncCLK/SMCLKx must be greater or equal to 2/1.

9 Mechanical Data and Ordering Information

Table 26 provides information on the MPC850 derivative devices.

Table 26. MPC850 Family Derivatives

Device	Ethernet Support	Number of SCCs [1]	32-Channel HDLC Support	64-Channel HDLC Support [2]
MPC850	N/A	One	N/A	N/A
MPC850DE	Yes	Two	N/A	N/A
MPC850SR	Yes	Two	N/A	Yes
MPC850DSL	Yes	Two	No	No

[1] Serial Communication Controller (SCC)

[2] 50 MHz version supports 64 time slots on a time division multiplexed line using one SCC

Table 27 identifies the packages and operating frequencies available for the MPC850.

Table 27. MPC850 Package/Frequency/Availability

Package Type	Frequency (MHz)	Temperature (Tj)	Order Number
256-Lead Plastic Ball Grid Array (ZT suffix)	50	0°C to 95°C	XPC850ZT50BU XPC850DEZT50BU XPC850SRZT50BU XPC850DSLZT50BU
	66	0°C to 95°C	XPC850ZT66BU XPC850DEZT66BU XPC850SRZT66BU
	80	0°C to 95°C	XPC850ZT80BU XPC850DEZT80BU XPC850SRZT80BU
256-Lead Plastic Ball Grid Array (CZT suffix)	50	-40°C to 95°C	XPC850CZT50BU XPC850DECZT50BU XPC850SRCZT50BU XPC850DSLCZT50BU
	66		XPC850CZT66BU XPC850DECZT66BU XPC850SRCZT66BU
	80		XPC850CZT80B XPC850DECZT80B XPC850SRCZT80B

9.1 Pin Assignments and Mechanical Dimensions of the PBGA

The original pin numbering of the MPC850 conformed to a Freescale proprietary pin numbering scheme that has since been replaced by the JEDEC pin numbering standard for this package type. To support

THIS PAGE INTENTIONALLY LEFT BLANK