



Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	I ² C, IrDA, LINbus, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, POR, PWM, WDT
Number of I/O	53
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 28x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx130f128ht-i-mr

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)

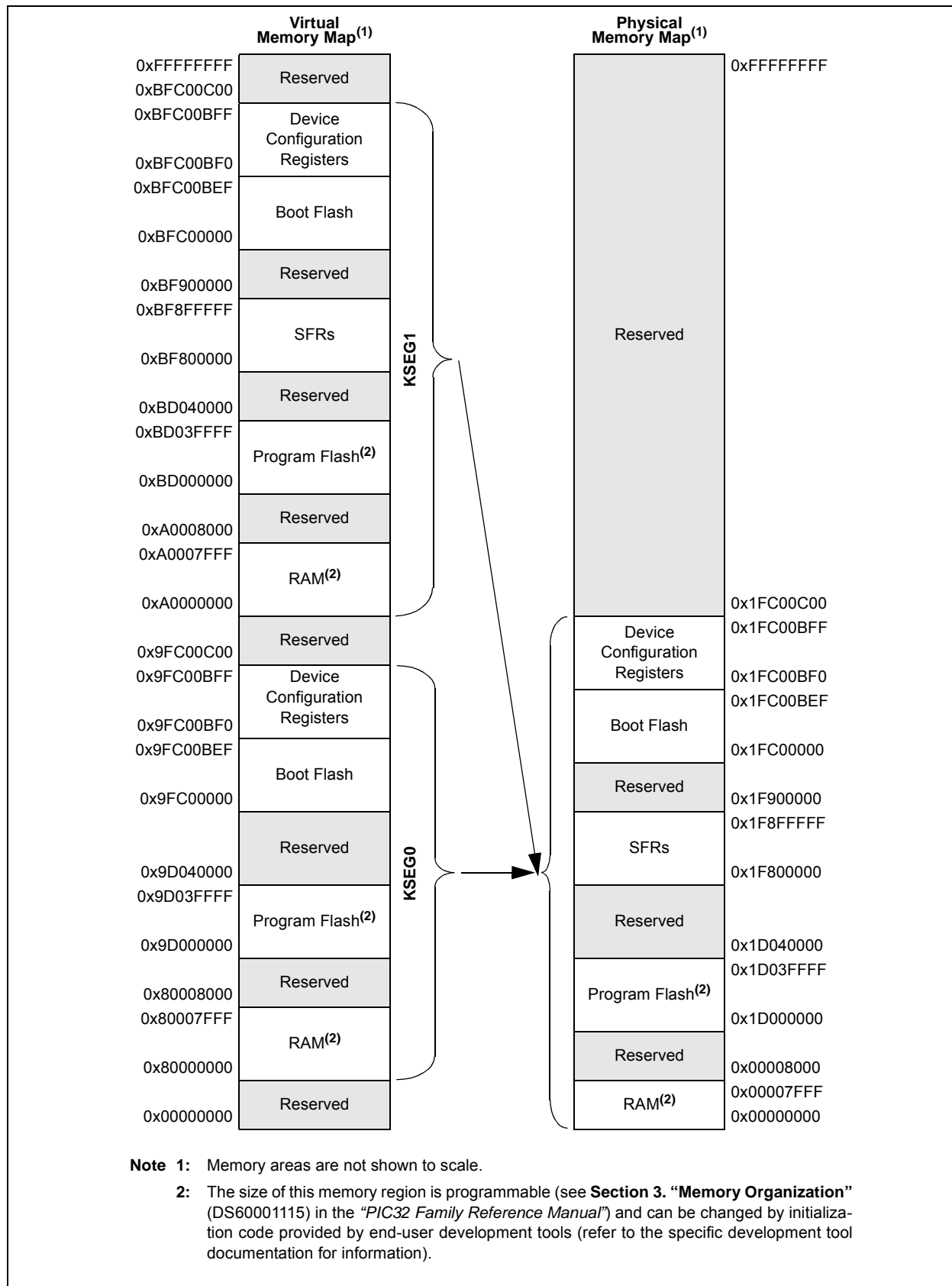
Pin Name	Pin Number		Pin Type	Buffer Type	Description
	64-pin QFN/TQFP	100-pin TQFP			
RF0	58	87	I/O	ST	PORTF is a bidirectional I/O port
RF1	59	88	I/O	ST	
RF2	34 ⁽³⁾	52	I/O	ST	
RF3	33	51	I/O	ST	
RF4	31	49	I/O	ST	
RF5	32	50	I/O	ST	
RF6	35 ⁽¹⁾	55 ⁽¹⁾	I/O	ST	
RF7	—	54 ⁽⁴⁾	I/O	ST	
RF8	—	53	I/O	ST	
RF12	—	40	I/O	ST	
RF13	—	39	I/O	ST	
RG0	—	90	I/O	ST	PORTG is a bidirectional I/O port
RG1	—	89	I/O	ST	
RG2	37 ⁽¹⁾	57 ⁽¹⁾	I/O	ST	
RG3	36 ⁽¹⁾	56 ⁽¹⁾	I/O	ST	
RG6	4	10	I/O	ST	
RG7	5	11	I/O	ST	
RG8	6	12	I/O	ST	
RG9	8	14	I/O	ST	
RG12	—	96	I/O	ST	
RG13	—	97	I/O	ST	
RG14	—	95	I/O	ST	
RG15	—	1	I/O	ST	
T1CK	48	74	I	ST	Timer1 External Clock Input
T2CK	PPS	PPS	I	ST	Timer2 External Clock Input
T3CK	PPS	PPS	I	ST	Timer3 External Clock Input
T4CK	PPS	PPS	I	ST	Timer4 External Clock Input
T5CK	PPS	PPS	I	ST	Timer5 External Clock Input
U1CTS	PPS	PPS	I	ST	UART1 Clear to Send
U1RTS	PPS	PPS	O	—	UART1 Ready to Send
U1RX	PPS	PPS	I	ST	UART1 Receive
U1TX	PPS	PPS	O	—	UART1 Transmit
U2CTS	PPS	PPS	I	ST	UART2 Clear to Send
U2RTS	PPS	PPS	O	—	UART2 Ready to Send
U2RX	PPS	PPS	I	ST	UART2 Receive
U2TX	PPS	PPS	O	—	UART2 Transmit

Legend: CMOS = CMOS compatible input or output Analog = Analog input I = Input O = Output
ST = Schmitt Trigger input with CMOS levels TTL = TTL input buffer P = Power

- Note 1:** This pin is only available on devices without a USB module.
2: This pin is only available on devices with a USB module.
3: This pin is not available on 64-pin devices with a USB module.
4: This pin is only available on 100-pin devices without a USB module.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

FIGURE 4-3: MEMORY MAP FOR DEVICES WITH 256 KB OF PROGRAM MEMORY + 32 KB RAM



PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 10-8: U1EIR: USB ERROR INTERRUPT STATUS REGISTER (CONTINUED)

bit 1 **CRC5EF:** CRC5 Host Error Flag bit⁽⁴⁾
1 = Token packet rejected due to CRC5 error
0 = Token packet accepted
EOFEF: EOF Error Flag bit^(3,5)
1 = EOF error condition detected
0 = No EOF error condition

bit 0 **PIDEF:** PID Check Failure Flag bit
1 = PID check failed
0 = PID check passed

- Note 1:** This type of error occurs when the module's request for the DMA bus is not granted in time to service the module's demand for memory, resulting in an overflow or underflow condition, and/or the allocated buffer size is not sufficient to store the received data packet causing it to be truncated.
- 2:** This type of error occurs when more than 16-bit-times of Idle from the previous End-of-Packet (EOP) has elapsed.
- 3:** This type of error occurs when the module is transmitting or receiving data and the SOF counter has reached zero.
- 4:** Device mode.
- 5:** Host mode.

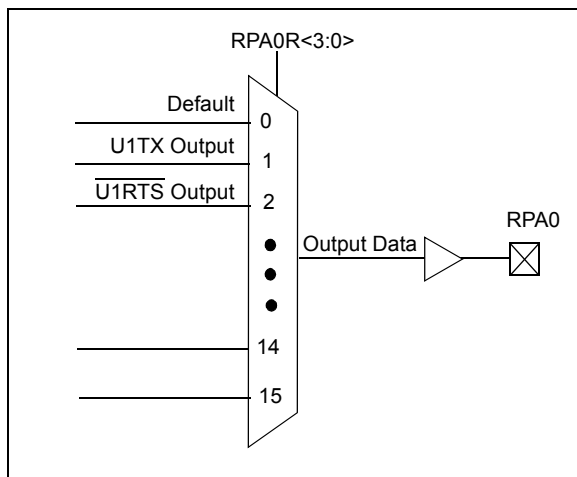
PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

11.3.5 OUTPUT MAPPING

In contrast to inputs, the outputs of the peripheral pin select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPNR registers (Register 11-2) are used to control output mapping. Like the *[pin name]R* registers, each register contains sets of 4 bit fields. The value of the bit field corresponds to one of the peripherals, and that peripheral's output is mapped to the pin (see Table 11-2 and Figure 11-3).

A null output is associated with the output register reset value of '0'. This is done to ensure that remappable outputs remain disconnected from all output pins by default.

FIGURE 11-3: EXAMPLE OF MULTIPLEXING OF REMAPPABLE OUTPUT FOR RPA0



11.3.6 CONTROLLING CONFIGURATION CHANGES

Because peripheral remapping can be changed during run time, some restrictions on peripheral remapping are needed to prevent accidental configuration changes. PIC32 devices include two features to prevent alterations to the peripheral map:

- Control register lock sequence
- Configuration bit select lock

11.3.6.1 Control Register Lock

Under normal operation, writes to the RPNR and *[pin name]R* registers are not allowed. Attempted writes appear to execute normally, but the contents of the registers remain unchanged. To change these registers, they must be unlocked in hardware. The register lock is controlled by the IOLOCK Configuration bit (CFGCON<13>). Setting IOLOCK prevents writes to the control registers; clearing IOLOCK allows writes.

To set or clear the IOLOCK bit, an unlock sequence must be executed. Refer to **Section 6. "Oscillator"** (DS60001112) in the *"PIC32 Family Reference Manual"* for details.

11.3.6.2 Configuration Bit Select Lock

As an additional level of safety, the device can be configured to prevent more than one write session to the RPNR and *[pin name]R* registers. The IOL1WAY Configuration bit (DEVCFG3<29>) blocks the IOLOCK bit from being cleared after it has been set once. If IOLOCK remains set, the register unlock procedure does not execute, and the peripheral pin select control registers cannot be written to. The only way to clear the bit and re-enable peripheral remapping is to perform a device Reset.

In the default (unprogrammed) state, IOL1WAY is set, restricting users to one write session.

TABLE 11-18: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP (CONTINUED)

Virtual Address (BF80_#)	Register Name	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
FB88	RPC2R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPC2<3:0>				0000	
FB8C	RPC3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPC3<3:0>				0000	
FB90	RPC4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPC4<3:0>				0000	
FBB4	RPC13R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPC13<3:0>				0000	
FBB8	RPC14R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPC14<3:0>				0000	
FBC0	RPD0R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD0<3:0>				0000	
FBC4	RPD1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD1<3:0>				0000	
FBC8	RPD2R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD2<3:0>				0000	
FBCC	RPD3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD3<3:0>				0000	
FBD0	RPD4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD4<3:0>				0000	
FBD4	RPD5R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD5<3:0>				0000	
FBE0	RPD8R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD8<3:0>				0000	
FBE4	RPD9R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD9<3:0>				0000	
FBE8	RPD10R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD10<3:0>				0000	
FBEC	RPD11R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD11<3:0>				0000	
FBF0	RPD12R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD12<3:0>				0000	
FBF8	RPD14R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD14<3:0>				0000	

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: This register is not available if the associated RPx function is not present on the device. Refer to the pin table for the specific device to determine availability.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 20-2: PMMODE: PARALLEL PORT MODE REGISTER (CONTINUED)

bit 5-2 **WAITM<3:0>**: Data Read/Write Strobe Wait States bits⁽¹⁾

1111 = Wait of 16 TPB

•
•
•

0001 = Wait of 2 TPB

0000 = Wait of 1 TPB (default)

bit 1-0 **WAITE<1:0>**: Data Hold After Read/Write Strobe Wait States bits⁽¹⁾

11 = Wait of 4 TPB

10 = Wait of 3 TPB

01 = Wait of 2 TPB

00 = Wait of 1 TPB (default)

For Read operations:

11 = Wait of 3 TPB

10 = Wait of 2 TPB

01 = Wait of 1 TPB

00 = Wait of 0 TPB (default)

Note 1: Whenever WAITM<3:0> = 0000, WAITB and WAITE bits are ignored and forced to 1 TPBCLK cycle for a write operation; WAITB = 1 TPBCLK cycle, WAITE = 0 TPBCLK cycles for a read operation.

2: Address bits, A15 and A14, are not subject to automatic increment/decrement if configured as Chip Select CS2 and CS1.

3: These pins are active when MODE16 = 1 (16-bit mode).

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 20-8: PMWADDR: PARALLEL PORT WRITE ADDRESS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
23:16	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
15:8	R/W-0 WCS2 ⁽¹⁾ WADDR15 ⁽²⁾	R/W-0 WCS1 ⁽³⁾ WADDR14 ⁽⁴⁾	WADDR<13:8>					
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WADDR<7:0>								

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **WCS2:** Chip Select 2 bit⁽¹⁾

1 = Chip Select 2 is active

0 = Chip Select 2 is inactive

bit 15 **WADDR<15>:** Target Address bit 15⁽²⁾

bit 14 **WCS1:** Chip Select 1 bit⁽³⁾

1 = Chip Select 1 is active

0 = Chip Select 1 is inactive

bit 14 **WADDR<14>:** Target Address bit 14⁽⁴⁾

bit 13-0 **WADDR<13:0>:** Address bits

Note 1: When the CSF<1:0> bits (PMCON<7:6>) = 10 or 01.

2: When the CSF<1:0> bits (PMCON<7:6>) = 00.

3: When the CSF<1:0> bits (PMCON<7:6>) = 10.

4: When the CSF<1:0> bits (PMCON<7:6>) = 00 or 01.

Note: This register is only used when the DUALBUF bit (PMCON<17>) is set to '1'.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 22-4: AD1CHS: ADC INPUT SELECT REGISTER (CONTINUED)

bit 21-16 **CH0SA<5:0>**: Positive Input Select bits for Sample A Multiplexer Setting

For 64-pin devices:

011110 = Channel 0 positive input is Open⁽¹⁾
011101 = Channel 0 positive input is CTMU temperature sensor (CTMUT)⁽²⁾
011100 = Channel 0 positive input is IVREF⁽³⁾
011011 = Channel 0 positive input is AN27
.
.
.
000001 = Channel 0 positive input is AN1
000000 = Channel 0 positive input is AN0

For 100-pin devices:

110010 = Channel 0 positive input is Open⁽¹⁾
110001 = Channel 0 positive input is CTMU temperature sensor (CTMUT)⁽²⁾
110000 = Channel 0 positive input is IVREF⁽³⁾
101111 = Channel 0 positive input is AN47
.
.
.
0000001 = Channel 0 positive input is AN1
0000000 = Channel 0 positive input is AN0

bit 15-0 **Unimplemented**: Read as '0'

- Note 1:** This selection is only used with CTMU capacitive and time measurement.
2: See **Section 26.0 “Charge Time Measurement Unit (CTMU)”** for more information.
3: Internal precision 1.2V reference. See **Section 24.0 “Comparator”** for more information.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 23-3: C1INT: CAN INTERRUPT REGISTER (CONTINUED)

- bit 14 **WAKIF:** CAN Bus Activity Wake-up Interrupt Flag bit
1 = A bus wake-up activity interrupt has occurred
0 = A bus wake-up activity interrupt has not occurred
- bit 13 **CERRIF:** CAN Bus Error Interrupt Flag bit
1 = A CAN bus error has occurred
0 = A CAN bus error has not occurred
- bit 12 **SERRIF:** System Error Interrupt Flag bit⁽¹⁾
1 = A system error occurred (typically an illegal address was presented to the system bus)
0 = A system error has not occurred
- bit 11 **RBOVIF:** Receive Buffer Overflow Interrupt Flag bit
1 = A receive buffer overflow has occurred
0 = A receive buffer overflow has not occurred
- bit 10-4 **Unimplemented:** Read as '0'
- bit 3 **MODIF:** CAN Mode Change Interrupt Flag bit
1 = A CAN module mode change has occurred (OPMOD<2:0> has changed to reflect REQOP)
0 = A CAN module mode change has not occurred
- bit 2 **CTMRIF:** CAN Timer Overflow Interrupt Flag bit
1 = A CAN timer (CANTMR) overflow has occurred
0 = A CAN timer (CANTMR) overflow has not occurred
- bit 1 **RBIF:** Receive Buffer Interrupt Flag bit
1 = A receive buffer interrupt is pending
0 = A receive buffer interrupt is not pending
- bit 0 **TBIF:** Transmit Buffer Interrupt Flag bit
1 = A transmit buffer interrupt is pending
0 = A transmit buffer interrupt is not pending

Note 1: This bit can only be cleared by turning the CAN module Off and On by clearing or setting the ON bit (C1CON<15>).

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 23-7: C1RXOVF: CAN RECEIVE FIFO OVERFLOW STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	RXOVF15	RXOVF14	RXOVF13	RXOVF12	RXOVF11	RXOVF10	RXOVF9	RXOVF8
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	RXOVF7	RXOVF6	RXOVF5	RXOVF4	RXOVF3	RXOVF2	RXOVF1	RXOVF0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **RXOVF<15:0>:** FIFOx Receive Overflow Interrupt Pending bit

1 = FIFO has overflowed

0 = FIFO has not overflowed

REGISTER 23-8: C1TMR: CAN TIMER REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CANTS<15:8>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CANTS<7:0>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CANTSPRE<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CANTSPRE<7:0>							

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-0 **CANTS<15:0>:** CAN Time Stamp Timer bits

This is a free-running timer that increments every CANTSPRE system clocks when the CANCAP bit (C1CON<20>) is set.

bit 15-0 **CANTSPRE<15:0>:** CAN Time Stamp Timer Prescaler bits

1111 1111 1111 1111 = CAN time stamp timer (CANTS) increments every 65,535 system clocks

.

.

0000 0000 0000 0000 = CAN time stamp timer (CANTS) increments every system clock

Note 1: C1TMR will be paused when CANCAP = 0.

2: The C1TMR prescaler count will be reset on any write to C1TMR (CANTSPRE will be unaffected).

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 23-12: C1FLTCON2: CAN FILTER CONTROL REGISTER 2 (CONTINUED)

- bit 20-16 **FSEL10<4:0>**: FIFO Selection bits
11111 = Reserved
.
.
.
10000 = Reserved
01111 = Message matching filter is stored in FIFO buffer 15
.
.
.
00000 = Message matching filter is stored in FIFO buffer 0
- bit 15 **FLTEN9**: Filter 9 Enable bit
1 = Filter is enabled
0 = Filter is disabled
- bit 14-13 **MSEL9<1:0>**: Filter 9 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected
- bit 12-8 **FSEL9<4:0>**: FIFO Selection bits
11111 = Reserved
.
.
.
10000 = Reserved
01111 = Message matching filter is stored in FIFO buffer 15
.
.
.
00000 = Message matching filter is stored in FIFO buffer 0
- bit 7 **FLTEN8**: Filter 8 Enable bit
1 = Filter is enabled
0 = Filter is disabled
- bit 6-5 **MSEL8<1:0>**: Filter 8 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected
- bit 4-0 **FSEL8<4:0>**: FIFO Selection bits
11111 = Reserved
.
.
.
10000 = Reserved
01111 = Message matching filter is stored in FIFO buffer 15
.
.
.
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 23-16: C1FIFOCONn: CAN FIFO CONTROL REGISTER 'n' ('n' = 0 THROUGH 15) (CONTINUED)

bit 7	TXEN: TX/RX Buffer Selection bit 1 = FIFO is a Transmit FIFO 0 = FIFO is a Receive FIFO
bit 6	TXABAT: Message Aborted bit ⁽²⁾ 1 = Message was aborted 0 = Message completed successfully
bit 5	TXLARB: Message Lost Arbitration bit ⁽³⁾ 1 = Message lost arbitration while being sent 0 = Message did not lose arbitration while being sent
bit 4	TXERR: Error Detected During Transmission bit ⁽³⁾ 1 = A bus error occurred while the message was being sent 0 = A bus error did not occur while the message was being sent
bit 3	TXREQ: Message Send Request <u>TXEN = 1:</u> (FIFO configured as a Transmit FIFO) Setting this bit to '1' requests sending a message. The bit will automatically clear when all the messages queued in the FIFO are successfully sent. Clearing the bit to '0' while set ('1') will request a message abort. <u>TXEN = 0:</u> (FIFO configured as a receive FIFO) This bit has no effect.
bit 2	RTREN: Auto RTR Enable bit 1 = When a remote transmit is received, TXREQ will be set 0 = When a remote transmit is received, TXREQ will be unaffected
bit 1-0	TXPR<1:0>: Message Transmit Priority bits 11 = Highest message priority 10 = High intermediate message priority 01 = Low intermediate message priority 00 = Lowest message priority

Note 1: These bits can only be modified when the CAN module is in Configuration mode (OPMOD<2:0> bits (C1CON<23:21>) = 100).

2: This bit is updated when a message completes (or aborts) or when the FIFO is reset.

3: This bit is reset on any read of this register or when the FIFO is reset.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 23-18: C1FIFOUAn: CAN FIFO USER ADDRESS REGISTER 'n' ('n' = 0 THROUGH 15)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
	C1FIFOUAn<31:24>							
23:16	R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
	C1FIFOUAn<23:16>							
15:8	R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
	C1FIFOUAn<15:8>							
7:0	R-x	R-x	R-x	R-x	R-x	R-x	R-0 ⁽¹⁾	R-0 ⁽¹⁾
	C1FIFOUAn<7:0>							

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-0 **C1FIFOUAn<31:0>**: CAN FIFO User Address bits

TXEN = 1: (FIFO configured as a transmit buffer)

A read of this register will return the address where the next message is to be written (FIFO head).

TXEN = 0: (FIFO configured as a receive buffer)

A read of this register will return the address where the next message is to be read (FIFO tail).

Note 1: This bit will always read '0', which forces byte-alignment of messages.

Note: This register is not guaranteed to read correctly in Configuration mode, and should only be accessed when the module is not in Configuration mode.

REGISTER 23-19: C1FIFOCIn: CAN MODULE MESSAGE INDEX REGISTER 'n' ('n' = 0 THROUGH 15)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0
	—	—	—	C1FIFOCIn<4:0>				

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-5 **Unimplemented:** Read as '0'

bit 4-0 **C1FIFOCIn<4:0>**: CAN Side FIFO Message Index bits

TXEN = 1: (FIFO configured as a transmit buffer)

A read of this register will return an index to the message that the FIFO will next attempt to transmit.

TXEN = 0: (FIFO configured as a receive buffer)

A read of this register will return an index to the message that the FIFO will use to save the next message.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 24-1: CMxCON: COMPARATOR CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	R-0
	ON ⁽¹⁾	COE	CPOL ⁽²⁾	—	—	—	—	COUT
7:0	R/W-1	R/W-1	U-0	R/W-0	U-0	U-0	R/W-1	R/W-1
	EVPOL<1:0>		—	CREF	—	—	CCH<1:0>	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** Comparator ON bit⁽¹⁾

1 = Module is enabled. Setting this bit does not affect the other bits in this register

0 = Module is disabled and does not consume current. Clearing this bit does not affect the other bits in this register

bit 14 **COE:** Comparator Output Enable bit

1 = Comparator output is driven on the output CxOUT pin

0 = Comparator output is not driven on the output CxOUT pin

bit 13 **CPOL:** Comparator Output Inversion bit⁽²⁾

1 = Output is inverted

0 = Output is not inverted

bit 12-9 **Unimplemented:** Read as '0'

bit 8 **COUT:** Comparator Output bit

1 = Output of the Comparator is a '1'

0 = Output of the Comparator is a '0'

bit 7-6 **EVPOL<1:0>:** Interrupt Event Polarity Select bits

11 = Comparator interrupt is generated on a low-to-high or high-to-low transition of the comparator output

10 = Comparator interrupt is generated on a high-to-low transition of the comparator output

01 = Comparator interrupt is generated on a low-to-high transition of the comparator output

00 = Comparator interrupt generation is disabled

bit 5 **Unimplemented:** Read as '0'

bit 4 **CREF:** Comparator Positive Input Configure bit

1 = Comparator non-inverting input is connected to the internal CVREF

0 = Comparator non-inverting input is connected to the CxINA pin

bit 3-2 **Unimplemented:** Read as '0'

bit 1-0 **CCH<1:0>:** Comparator Negative Input Select bits for Comparator

11 = Comparator inverting input is connected to the IVREF

10 = Comparator inverting input is connected to the CxIND pin

01 = Comparator inverting input is connected to the CxINC pin

00 = Comparator inverting input is connected to the CxINB pin

Note 1: When using the 1:1 PBCLK divisor, the user's software should not read/write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON bit.

2: Setting this bit will invert the signal to the comparator interrupt generator as well. This will result in an interrupt being generated on the opposite edge from the one selected by EVPOL<1:0>.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

28.0 SPECIAL FEATURES

Note: This data sheet summarizes the features of the PIC32MX1XX/2XX/5XX 64/100-pin family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 9. “Watchdog Timer and Power-up Timer”** (DS60001114), **Section 32. “Configuration”** (DS60001124) and **Section 33. “Programming and Diagnostics”** (DS60001129) in the *“PIC32 Family Reference Manual”*, which are available from the Microchip web site (www.microchip.com/PIC32).

PIC32MX1XX/2XX/5XX 64/100-pin devices include several features intended to maximize application flexibility and reliability and minimize cost through elimination of external components. These are:

- Flexible device configuration
- Watchdog Timer (WDT)
- Joint Test Action Group (JTAG) interface
- In-Circuit Serial Programming™ (ICSP™)

28.1 Configuration Bits

The Configuration bits can be programmed using the following registers to select various device configurations.

- DEVCFG0: Device Configuration Word 0
- DEVCFG1: Device Configuration Word 1
- DEVCFG2: Device Configuration Word 2
- DEVCFG3: Device Configuration Word 3
- CFGCON: Configuration Control Register

In addition, the DEVID register (Register 28-6) provides device and revision information.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

REGISTER 28-1: DEVCFG0: DEVICE CONFIGURATION WORD 0 (CONTINUED)

bit 19-10 **PWP<9:0>**: Program Flash Write-Protect bits

Prevents selected program Flash memory pages from being modified during code execution. The PWP bits represent the one's complement of the number of write protected program Flash memory pages.

111111111 = Disabled
111111110 = Memory below 0x0400 address is write-protected
111111101 = Memory below 0x0800 address is write-protected
111111100 = Memory below 0x0C00 address is write-protected
111111011 = Memory below 0x1000 (4K) address is write-protected
111111010 = Memory below 0x1400 address is write-protected
111111001 = Memory below 0x1800 address is write-protected
111111000 = Memory below 0x1C00 address is write-protected
111110111 = Memory below 0x2000 (8K) address is write-protected
111110110 = Memory below 0x2400 address is write-protected
111110101 = Memory below 0x2800 address is write-protected
111110100 = Memory below 0x2C00 address is write-protected
111110011 = Memory below 0x3000 address is write-protected
111110010 = Memory below 0x3400 address is write-protected
111110001 = Memory below 0x3800 address is write-protected
111110000 = Memory below 0x3C00 address is write-protected
111101111 = Memory below 0x4000 (16K) address is write-protected
.
.
.
111011111 = Memory below 0x10000 (64K) address is write-protected
.
.
.
110111111 = Memory below 0x20000 (128K) address is write-protected
.
.
.
101111111 = Memory below 0x40000 (256K) address is write-protected
.
.
.
011111111 = Memory below 0x80000 (512K) address is write-protected
.
.
.
000000000 = All possible memory is write-protected

Note: These bits are effective only if Boot Flash is also protected by clearing the BWP bit (DEVCFG0<24>).

bit 9-5 **Reserved:** Write '1'

bit 4-3 **ICESEL<1:0>**: In-Circuit Emulator/Debugger Communication Channel Select bits

11 = PGEC1/PGED1 pair is used
10 = PGEC2/PGED2 pair is used
01 = PGEC3/PGED3 pair is used
00 = Reserved

bit 2 **JTAGEN:** JTAG Enable bit⁽¹⁾

1 = JTAG is enabled
0 = JTAG is disabled

bit 1-0 **DEBUG<1:0>**: Background Debugger Enable bits (forced to '11' if code-protect is enabled)

1x = Debugger is disabled
0x = Debugger is enabled

Note 1: This bit sets the value for the JTAGEN bit in the CFGCON register.

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

TABLE 31-12: DC CHARACTERISTICS: PROGRAM MEMORY

DC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-temp				
Param. No.	Symbol	Characteristics	Min.	Typical ⁽¹⁾	Max.	Units	Conditions
Program Flash Memory⁽³⁾							
D130	EP	Cell Endurance	20,000	—	—	E/W	—
D131	VPR	VDD for Read	2.3	—	3.6	V	—
D132	VPEW	VDD for Erase or Write	2.3	—	3.6	V	—
D134	TRETD	Characteristic Retention	20	—	—	Year	Provided no other specifications are violated
D135	IDDP	Supply Current during Programming	—	10	—	mA	—
	TWW	Word Write Cycle Time	—	411	—	FRC Cycles	See Note 4
D136	TRW	Row Write Cycle Time	—	6675	—	FRC Cycles	See Note 2,4
D137	TPE	Page Erase Cycle Time	—	20011	—	FRC Cycles	See Note 4
	TCE	Chip Erase Cycle Time	—	80180	—	FRC Cycles	See Note 4

Note 1: Data in “Typical” column is at 3.3V, 25°C unless otherwise stated.

2: The minimum SYSCLK for row programming is 4 MHz. Care should be taken to minimize bus activities during row programming, such as suspending any memory-to-memory DMA operations. If heavy bus loads are expected, selecting Bus Matrix Arbitration mode 2 (rotating priority) may be necessary. The default Arbitration mode is mode 1 (CPU has lowest priority).

3: Refer to the “PIC32 Flash Programming Specification” (DS60001145) for operating conditions during programming and erase cycles.

4: This parameter depends on FRC accuracy (See Table 31-19) and FRC tuning values (See Register 8-2).

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

FIGURE 31-6: TIMER1, 2, 3, 4, 5 EXTERNAL CLOCK TIMING CHARACTERISTICS

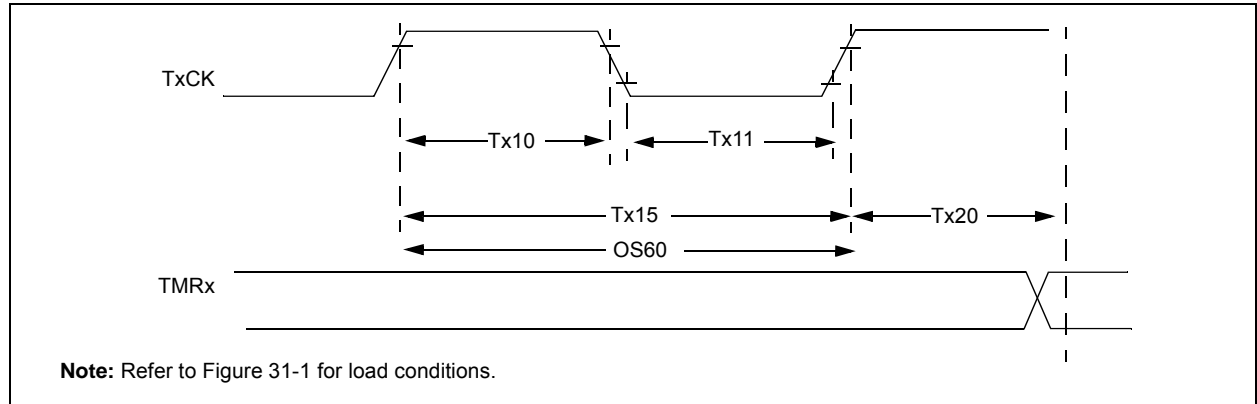


TABLE 31-23: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS

AC CHARACTERISTICS ⁽¹⁾				Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-temp				
Param. No.	Symbol	Characteristics ⁽²⁾		Min.	Typical	Max.	Units	Conditions
TA10	TtxH	TxCK High Time	Synchronous, with prescaler	[(12.5 ns or 1 TPB)/N] + 25 ns	—	—	ns	Must also meet parameter TA15
			Asynchronous, with prescaler	10	—	—	ns	—
TA11	TtxL	TxCK Low Time	Synchronous, with prescaler	[(12.5 ns or 1 TPB)/N] + 25 ns	—	—	ns	Must also meet parameter TA15
			Asynchronous, with prescaler	10	—	—	ns	—
TA15	TtxP	TxCK Input Period	Synchronous, with prescaler	[(Greater of 25 ns or 2 TPB)/N] + 30 ns	—	—	ns	VDD > 2.7V
				[(Greater of 25 ns or 2 TPB)/N] + 50 ns	—	—	ns	VDD < 2.7V
			Asynchronous, with prescaler	20	—	—	ns	VDD > 2.7V (Note 3)
				50	—	—	ns	VDD < 2.7V (Note 3)
OS60	Ft1	SOSC1/T1CK Oscillator Input Frequency Range (oscillator enabled by setting the TCS (T1CON<1>) bit)		32	—	100	kHz	—
TA20	TckEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		—		1	TPB	—

Note 1: Timer1 is a Type A timer.

2: This parameter is characterized, but not tested in manufacturing.

3: N = Prescale Value (1, 8, 64, 256).

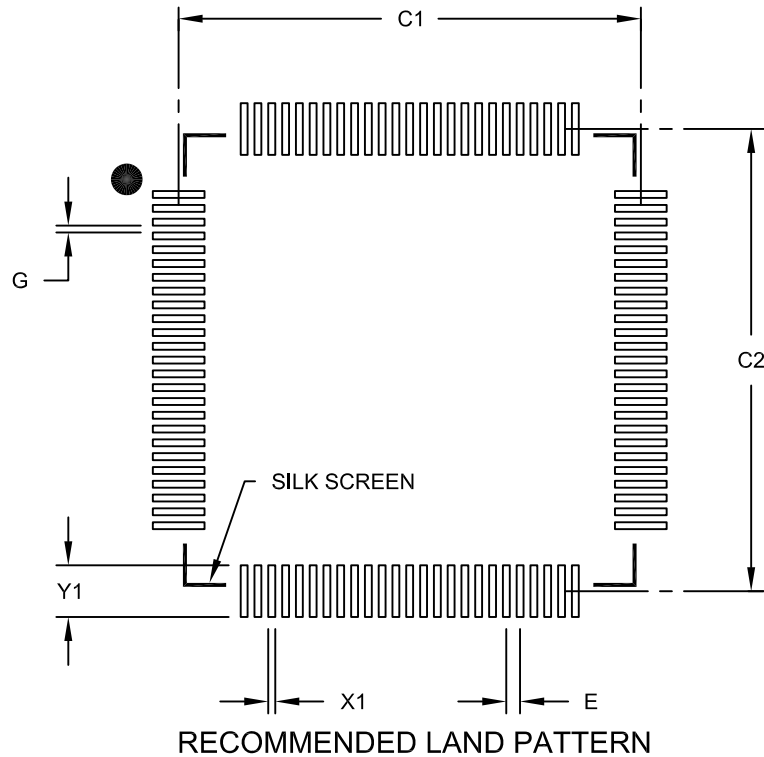
PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

NOTES:

PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

100-Lead Plastic Thin Quad Flatpack (PT)-12x12x1mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X100)	X1			0.20
Contact Pad Length (X100)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2100B