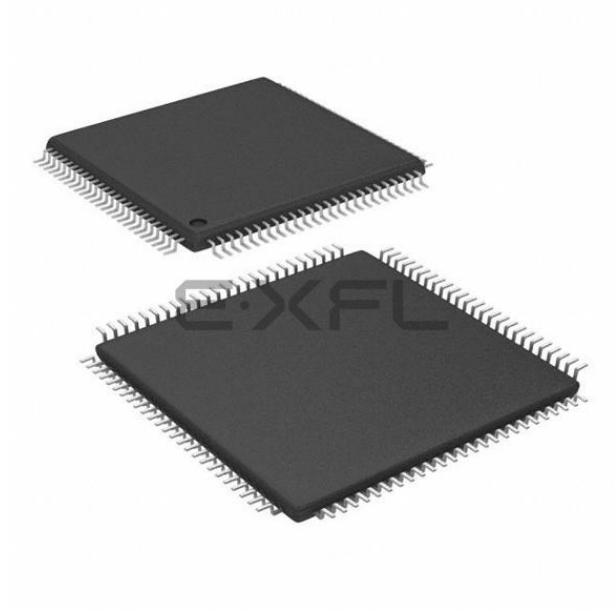
# Microchip Technology - PIC32MX150F256LT-I/PF Datasheet



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## Applications of "Embedded - Microcontrollers"

| Details | |
|---|---|
| Product Status | Active |
| Core Processor | MIPS32® M4K™ |
| Core Size | 32-Bit Single-Core |
| Speed | 40MHz |
| Connectivity | I²C, IrDA, LINbus, PMP, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT |
| Number of I/O | 85 |
| Program Memory Size | 256KB (256K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 32K x 8 |
| Voltage - Supply (Vcc/Vdd) | 2.3V ~ 3.6V |
| Data Converters | A/D 48x10b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 100-TQFP |
| Supplier Device Package | 100-TQFP (14x14) |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic32mx150f256lt-i-pf |

## 1.0 DEVICE OVERVIEW

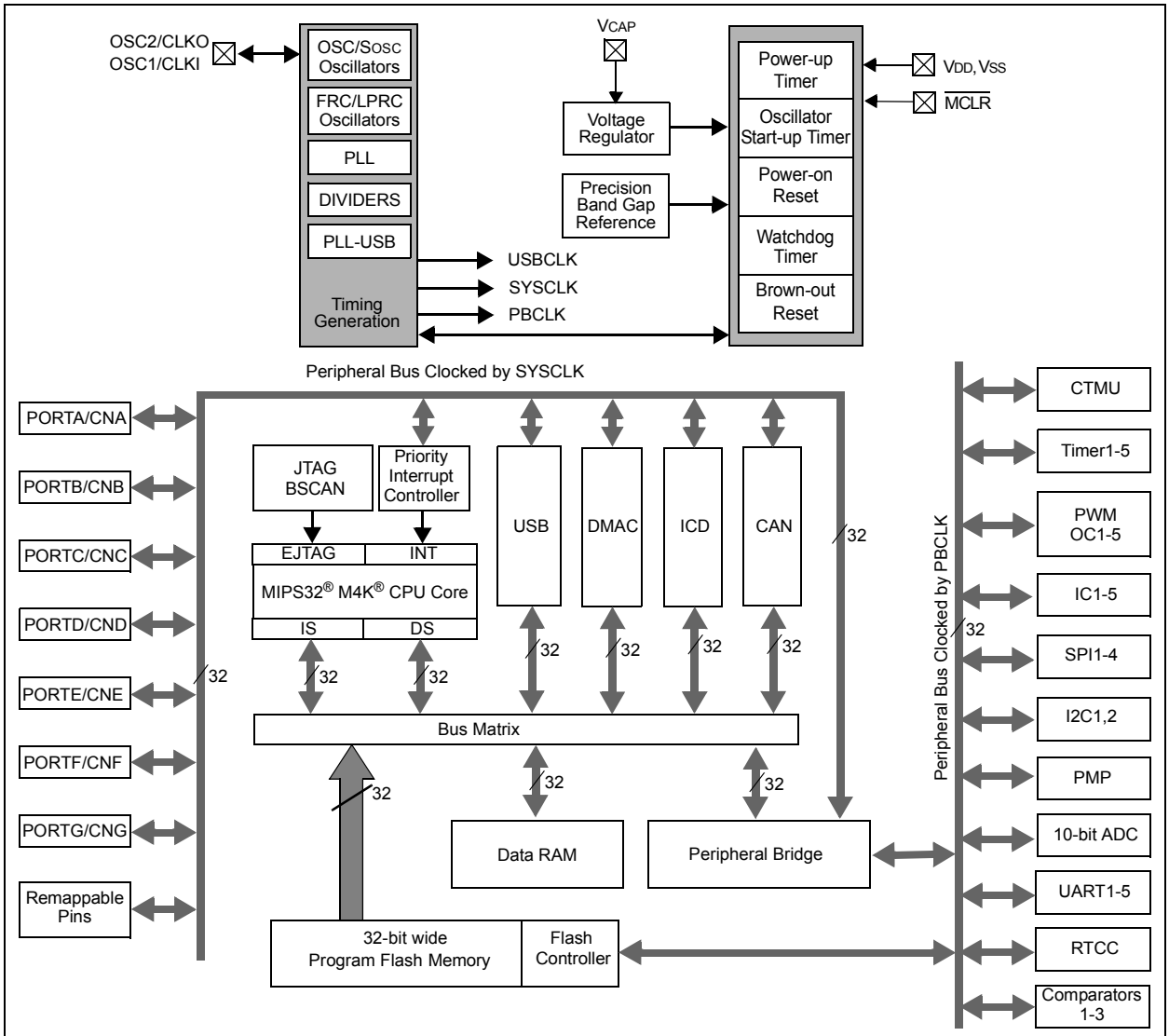
**Note 1:** This data sheet summarizes the features of the PIC32MX1XX/2XX/5XX 64/100-pin family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

This document contains device-specific information for PIC32MX1XX/2XX/5XX 64/100-pin devices.

Figure 1-1 illustrates a general block diagram of the core and peripheral modules in the PIC32MX1XX/2XX/5XX 64/100-pin family of devices.

Table 1-1 lists the functions of the various pins shown in the pinout diagrams.

**FIGURE 1-1: PIC32MX1XX/2XX/5XX 64/100-PIN BLOCK DIAGRAM**




**Note:** Not all features are available on all devices. Refer to **TABLE 1: "PIC32MX1XX/2XX/5XX 64/100-pin Controller Family Features"** for the list of features by device.

**TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)**

| Pin Name | Pin Number | | Pin Type | Buffer Type | Description |
|---|---|---|---|---|---|
| | 64-pin QFN/ TQFP | 100-pin TQFP | | | |
| $V_{USB3V3}$(2) | 35 | 55 | P | — | USB internal transceiver supply. If the USB module is not used, this pin must be connected to $V_{DD}$. |
| $V_{BUSON}$(2) | 11 | 20 | O | — | USB Host and OTG bus power control Output |
| D+(2) | 37 | 57 | I/O | Analog | USB D+ |
| D-(2) | 36 | 56 | I/O | Analog | USB D- |
| USBID(2) | 33 | 51 | I | ST | USB OTG ID Detect |
| PGED1 | 16 | 25 | I/O | ST | Data I/O pin for Programming/Debugging Communication Channel 1 |
| PGEC1 | 15 | 24 | I | ST | Clock Input pin for Programming/Debugging Communication Channel 1 |
| PGED2 | 18 | 27 | I/O | ST | Data I/O Pin for Programming/Debugging Communication Channel 2 |
| PGEC2 | 17 | 26 | I | ST | Clock Input Pin for Programming/Debugging Communication Channel 2 |
| PGED3 | 13 | 22 | I/O | ST | Data I/O Pin for Programming/Debugging Communication Channel 3 |
| PGEC3 | 14 | 23 | I | ST | Clock Input Pin for Programming/Debugging Communication Channel 3 |
| CTED1 | — | 17 | I | ST | CTMU External Edge Input 1 |
| CTED2 | — | 38 | I | ST | CTMU External Edge Input 2 |
| CTED3 | 18 | 27 | I | ST | CTMU External Edge Input 3 |
| CTED4 | 22 | 33 | I | ST | CTMU External Edge Input 4 |
| CTED5 | 29 | 43 | I | ST | CTMU External Edge Input 5 |
| CTED6 | 30 | 44 | I | ST | CTMU External Edge Input 6 |
| CTED7 | — | 9 | I | ST | CTMU External Edge Input 7 |
| CTED8 | — | 92 | I | ST | CTMU External Edge Input 8 |
| CTED9 | — | 60 | I | ST | CTMU External Edge Input 9 |
| CTED10 | 21 | 32 | I | ST | CTMU External Edge Input 10 |
| CTED11 | 23 | 34 | I | ST | CTMU External Edge Input 11 |
| CTED12 | 15 | 24 | I | ST | CTMU External Edge Input 12 |
| CTED13 | 14 | 23 | I | ST | CTMU External Edge Input 13 |
| C1RX | PPS | PPS | I | ST | Enhanced CAN Receive |
| C1TX | PPS | PPS | O | ST | Enhanced CAN Transmit |

**Legend:** CMOS = CMOS compatible input or output Analog = Analog input I = Input O = Output
ST = Schmitt Trigger input with CMOS levels TTL = TTL input buffer P = Power

**Note 1:** This pin is only available on devices without a USB module.

**2:** This pin is only available on devices with a USB module.

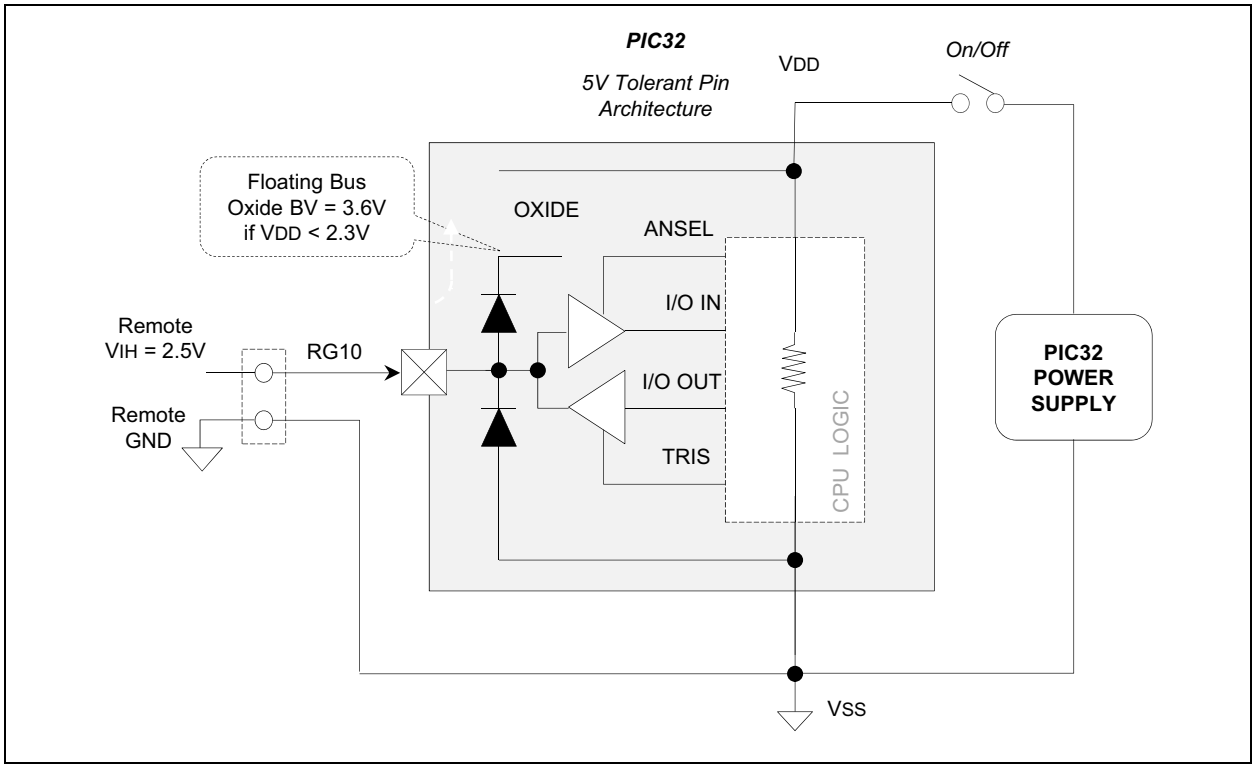
**3:** This pin is not available on 64-pin devices with a USB module.

**4:** This pin is only available on 100-pin devices without a USB module.

### 2.9.2 5V TOLERANT INPUT PINS

The internal high side diode on 5V tolerant pins are bussed to an internal floating node, rather than being connected to VDD, as shown in Figure 2-7. Voltages on these pins, if VDD < 2.3V, should not exceed roughly 3.2V relative to VSS of the PIC32 device. Voltage of 3.6V or higher will violate the absolute maximum specification, and will stress the oxide layer separating the high side floating node, which impacts device reliability. If a remotely powered "digital-only" signal can be guaranteed to always be ≤ 3.2V relative to Vss on the PIC32 device side, a 5V tolerant pin could be used without the need for a digital isolator. This is assuming there is not a ground loop issue, logic ground of the two circuits not at the same absolute level, and a remote logic low input is not less than VSS - 0.3V.

**FIGURE 2-7: PIC32 5V TOLERANT PIN ARCHITECTURE EXAMPLE**



## 6.0 FLASH PROGRAM MEMORY

**Note:** This data sheet summarizes the features of the PIC32MX1XX/2XX/5XX 64/100-pin family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 5. "Flash Program Memory"** (DS60001121) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

PIC32MX1XX/2XX/5XX 64/100-pin devices contain an internal Flash program memory for executing user code. There are three methods by which the user can program this memory:

- Run-Time Self-Programming (RTSP)
- EJTAG Programming
- In-Circuit Serial Programming™ (ICSP™)

RTSP is performed by software executing from either Flash or RAM memory. Information about RTSP techniques is available in **Section 5. "Flash Program Memory"** (DS60001121) in the *"PIC32 Family Reference Manual".*

EJTAG is performed using the EJTAG port of the device and an EJTAG capable programmer.

ICSP is performed using a serial data connection to the device and allows much faster programming times than RTSP.

The EJTAG and ICSP methods are described in the "*PIC32 Flash Programming Specification*" (DS60001145), which can be downloaded from the Microchip web site.

**Note:** On PIC32MX1XX/2XX/5XX 64/100-pin devices, the Flash page size is 1 KB and the row size is 128 bytes (256 IW and 32 IW, respectively).

## 6.1 Control Registers

**TABLE 6-1: FLASH CONTROLLER REGISTER MAP**

| Virtual Address (BF80_#) | Register Name | Bit Range | Bits | | | | | | | | | | | | | | | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | | | 31/15 | 30/14 | 29/13 | 28/12 | 27/11 | 26/10 | 25/9 | 24/8 | 23/7 | 22/6 | 21/5 | 20/4 | 19/3 | 18/2 | 17/1 | 16/0 | |
| F400 | NVMCON(1) | 31:16 | — | — | — | — | — | — | — | — | — | — | — | — | — | — | — | — | 0000 |
| | | 15:0 | WR | WREN | WRERR | LVDERR | LVDSTAT | — | — | — | — | — | — | — | NVMOP<3:0> | | | | 0000 |
| F410 | NVMKEY | 31:16 | NVMKEY<31:0> | | | | | | | | | | | | | | | | 0000 |
| | | 15:0 | | | | | | | | | | | | | | | | | 0000 |
| F420 | NVMADDR(1) | 31:16 | NVMADDR<31:0> | | | | | | | | | | | | | | | | 0000 |
| | | 15:0 | | | | | | | | | | | | | | | | | 0000 |
| F430 | NVMDATA | 31:16 | NVMDATA<31:0> | | | | | | | | | | | | | | | | 0000 |
| | | 15:0 | | | | | | | | | | | | | | | | | 0000 |
| F440 | NVMSRC ADDR | 31:16 | NVMSRCADDR<31:0> | | | | | | | | | | | | | | | | 0000 |
| | | 15:0 | | | | | | | | | | | | | | | | | 0000 |

**Legend:** x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** This register has corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 11.2 "CLR, SET, and INV Registers"** for more information.

## 7.0 RESETS

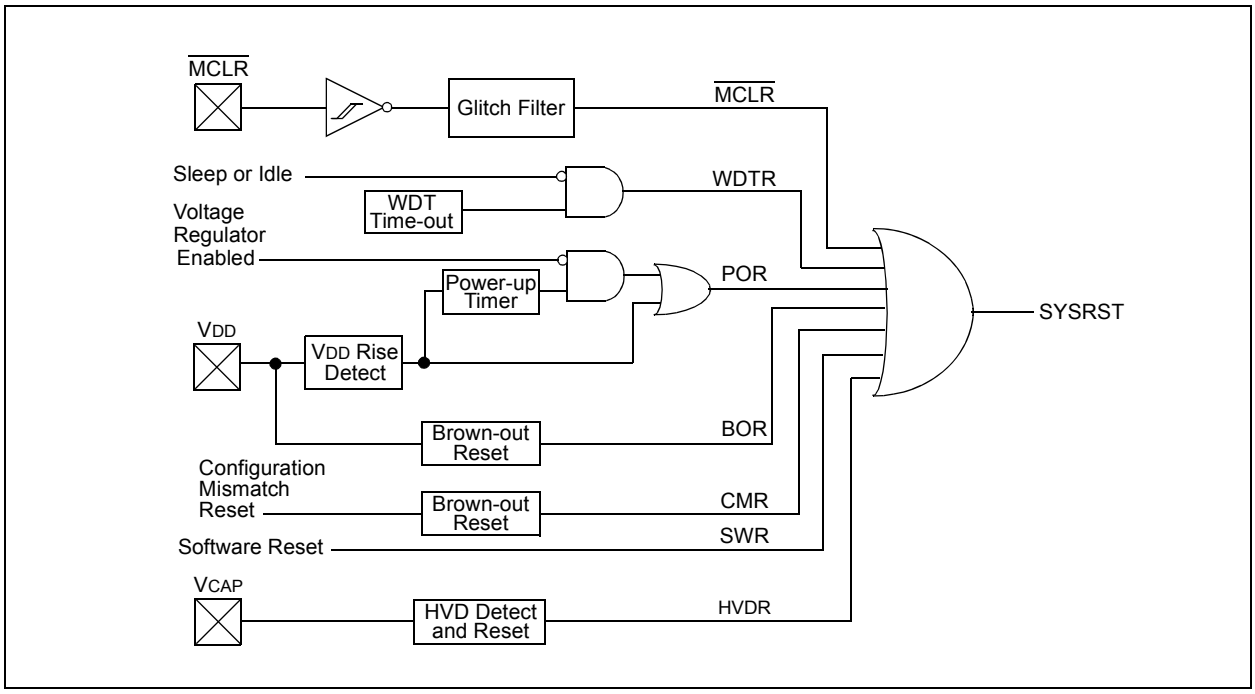
**Note:** This data sheet summarizes the features of the PIC32MX1XX/2XX/5XX 64/100-pin family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 7. "Resets"** (DS60001118) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

The Reset module combines all Reset sources and controls the device Master Reset signal, SYSRST. The following is a list of device Reset sources:

- POR: Power-on Reset
- $\overline{\text{MCLR}}$: Master Clear Reset pin
- SWR: Software Reset
- WDTR: Watchdog Timer Reset
- BOR: Brown-out Reset
- CMR: Configuration Mismatch Reset
- HVDR: High Voltage Detect Reset

A simplified block diagram of the Reset module is illustrated in Figure 7-1.

**FIGURE 7-1: SYSTEM RESET BLOCK DIAGRAM**



**REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER**

| Bit Range | Bit 31/23/15/7 | Bit 30/22/14/6 | Bit 29/21/13/5 | Bit 28/20/12/4 | Bit 27/19/11/3 | Bit 26/18/10/2 | Bit 25/17/9/1 | Bit 24/16/8/0 |
|---|---|---|---|---|---|---|---|---|
| 31:24 | U-0 | U-0 | R/W-y | R/W-y | R/W-y | R/W-0 | R/W-0 | R/W-1 |
| | — | — | PLLODIV<2:0> | | | FRCDIV<2:0> | | |
| 23:16 | U-0 | R-0 | R-1 | R/W-y | R/W-y | R/W-y | R/W-y | R/W-y |
| | — | SOSCRDY | PBDIVRDY | PBDIV<1:0> | | PLLMULT<2:0> | | |
| 15:8 | U-0 | R-0 | R-0 | R-0 | U-0 | R/W-y | R/W-y | R/W-y |
| | — | COSC<2:0> | | | — | NOSC<2:0> | | |
| 7:0 | R/W-0 | R-0 | R-0 | R/W-0 | R/W-0 | R/W-0 | R/W-y | R/W-0 |
| | CLKLOCK | ULOCK(1) | SLOCK | SLPEN | CF | UFRCEN(1) | SOSCEN | OSWEN |

| Legend: | y = Value set from Configuration bits on POR | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 31-30 **Unimplemented:** Read as '0'

bit 29-27 **PLLODIV<2:0>:** Output Divider for PLL
- 111 = PLL output divided by 256
- 110 = PLL output divided by 64
- 101 = PLL output divided by 32
- 100 = PLL output divided by 16
- 011 = PLL output divided by 8
- 010 = PLL output divided by 4
- 001 = PLL output divided by 2
- 000 = PLL output divided by 1

bit 26-24 **FRCDIV<2:0>:** Internal Fast RC (FRC) Oscillator Clock Divider bits
- 111 = FRC divided by 256
- 110 = FRC divided by 64
- 101 = FRC divided by 32
- 100 = FRC divided by 16
- 011 = FRC divided by 8
- 010 = FRC divided by 4
- 001 = FRC divided by 2 (default setting)
- 000 = FRC divided by 1

bit 23 **Unimplemented:** Read as '0'

bit 22 **SOSCRDY:** Secondary Oscillator (SOSC) Ready Indicator bit
- 1 = Indicates that the Secondary Oscillator is running and is stable
- 0 = Secondary Oscillator is still warming up or is turned off

bit 21 **PBDIVRDY:** Peripheral Bus Clock (PBCLK) Divisor Ready bit
- 1 = PBDIV<1:0> bits can be written
- 0 = PBDIV<1:0> bits cannot be written

bit 20-19 **PBDIV<1:0>:** Peripheral Bus Clock (PBCLK) Divisor bits
- 11 = PBCLK is SYSCLK divided by 8 (default)
- 10 = PBCLK is SYSCLK divided by 4
- 01 = PBCLK is SYSCLK divided by 2
- 00 = PBCLK is SYSCLK divided by 1

**Note 1:** This bit is available on PIC32MX2XX/5XX devices only.

**Note:** Writes to this register require an unlock sequence. Refer to **Section 6. "Oscillator"** (DS60001112) in the *"PIC32 Family Reference Manual"* for details.

**REGISTER 10-9: U1EIE: USB ERROR INTERRUPT ENABLE REGISTER**

| Bit Range | Bit 31/23/15/7 | Bit 30/22/14/6 | Bit 29/21/13/5 | Bit 28/20/12/4 | Bit 27/19/11/3 | Bit 26/18/10/2 | Bit 25/17/9/1 | Bit 24/16/8/0 |
|---|---|---|---|---|---|---|---|---|
| 31:24 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 23:16 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 15:8 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 7:0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| | BTSEE | BMXEE | DMAEE | BTOEE | DFN8EE | CRC16EE | CRC5EE(1) / EOFEE(2) | PIDEE |

| Legend: | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 31-8 **Unimplemented:** Read as '0'

bit 7 **BTSEE:** Bit Stuff Error Interrupt Enable bit
- 1 = BTSEF interrupt enabled
- 0 = BTSEF interrupt disabled

bit 6 **BMXEE:** Bus Matrix Error Interrupt Enable bit
- 1 = BMXEF interrupt enabled
- 0 = BMXEF interrupt disabled

bit 5 **DMAEE:** DMA Error Interrupt Enable bit
- 1 = DMAEF interrupt enabled
- 0 = DMAEF interrupt disabled

bit 4 **BTOEE:** Bus Turnaround Time-out Error Interrupt Enable bit
- 1 = BTOEF interrupt enabled
- 0 = BTOEF interrupt disabled

bit 3 **DFN8EE:** Data Field Size Error Interrupt Enable bit
- 1 = DFN8EF interrupt enabled
- 0 = DFN8EF interrupt disabled

bit 2 **CRC16EE:** CRC16 Failure Interrupt Enable bit
- 1 = CRC16EF interrupt enabled
- 0 = CRC16EF interrupt disabled

bit 1 **CRC5EE:** CRC5 Host Error Interrupt Enable bit(1)
- 1 = CRC5EF interrupt enabled
- 0 = CRC5EF interrupt disabled

**EOFEE:** EOF Error Interrupt Enable bit(2)
- 1 = EOF interrupt enabled
- 0 = EOF interrupt disabled

bit 0 **PIDEE:** PID Check Failure Interrupt Enable bit
- 1 = PIDEF interrupt enabled
- 0 = PIDEF interrupt disabled

**Note 1:** Device mode.
**2:** Host mode.

**Note:** For an interrupt to propagate USBIF, the UERRIE bit (U1IE<1>) must be set.

**REGISTER 10-20: U1CNFG1: USB CONFIGURATION 1 REGISTER**

| Bit Range | Bit 31/23/15/7 | Bit 30/22/14/6 | Bit 29/21/13/5 | Bit 28/20/12/4 | Bit 27/19/11/3 | Bit 26/18/10/2 | Bit 25/17/9/1 | Bit 24/16/8/0 |
|---|---|---|---|---|---|---|---|---|
| 31:24 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 23:16 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 15:8 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 7:0 | R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 | U-0 | U-0 | R/W-0 |
| | UTEYE | — | — | USBSIDL | USBSIDL | — | — | UASUSPND |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 31-8 **Unimplemented:** Read as '0'

bit 7 **UTEYE:** USB Eye-Pattern Test Enable bit
- 1 = Eye-Pattern Test enabled
- 0 = Eye-Pattern Test disabled

bit 6-5 **Unimplemented:** Read as '0'

bit 4 **USBSIDL:** Stop in Idle Mode bit
- 1 = Discontinue module operation when device enters Idle mode
- 0 = Continue module operation in Idle mode

bit 3 **LSDEV:** Low-Speed Device Enable bit
- 1 = USB module operates in Low-Speed Device mode only
- 0 = USB module operates in OTG, Host, or Full-Speed Device mode

bit 2-1 **Unimplemented:** Read as '0'

bit 0 **UASUSPND:** Automatic Suspend Enable bit
- 1 = USB module automatically suspends upon entry to Sleep mode. See the USUSPEND bit (U1PWRC<1>) in Register 10-5.
- 0 = USB module does not automatically suspend upon entry to Sleep mode. Software must use the USUSPEND bit (U1PWRC<1>) to suspend the module, including the USB 48 MHz clock

## 11.1 Parallel I/O (PIO) Ports

All port pins have ten registers directly associated with their operation as digital I/O. The data direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a '1', then the pin is an input. All port pins are defined as inputs after a Reset. Reads from the latch (LATx) read the latch. Writes to the latch write the latch. Reads from the port (PORTx) read the port pins, while writes to the port pins write the latch.

### 11.1.1 OPEN-DRAIN CONFIGURATION

In addition to the PORTx, LATx, and TRISx registers for data control, some port pins can also be individually configured for either digital or open-drain output. This is controlled by the Open-Drain Control register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin, regardless of the output function including PPS remapped output functions to act as an open-drain output. The only exception is the $I^2C$ pins that are open drain by default.

The open-drain feature allows the presence of outputs higher than VDD (e.g., 5V) on any desired 5V-tolerant pins by using external pull-up resistors. The maximum open-drain voltage allowed is the same as the maximum VIH specification.

See the **"Device Pin Tables"** section for the available pins and their functionality.

### 11.1.2 CONFIGURING ANALOG AND DIGITAL PORT PINS

The ANSELx register controls the operation of the analog port pins. The port pins that are to function as analog inputs must have their corresponding ANSEL and TRIS bits set. In order to use port pins for I/O functionality with digital modules, such as Timers, UARTs, etc., the corresponding ANSELx bit must be cleared.

The ANSELx register has a default value of 0xFFFF; therefore, all pins that share analog functions are analog (not digital) by default. The ANSELx register bit, when cleared, disables the corresponding digital input buffer pin(s).

If the TRIS bit is cleared (output) while the ANSELx bit is set, the digital output level (VOH or VOL) is converted by an analog peripheral, such as the ADC module or Comparator module. The TRISx bits only control the corresponding digital output buffer pin(s).

When the PORT register is read, all pins configured as analog input channels are read as cleared (a low level; i.e., when ANSELx = 1; TRISx = x).

Analog levels on any pin defined as a digital input (including the ANx pins) can cause the input buffer to consume current that exceeds the device specifications.

### 11.1.3 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically, this instruction would be an NOP.

### 11.1.4 INPUT CHANGE NOTIFICATION

The input Change Notification (CN) function of the I/O ports allows the PIC32MX1XX/2XX/5XX 64/100-pin devices to generate interrupt requests to the processor in response to a change-of-state on selected input pins. This feature can detect input change-of-states even in Sleep mode, when the clocks are disabled. Every I/O port pin can be selected (enabled) for generating an interrupt request on a change-of-state.

Five control registers are associated with the CN functionality of each I/O port. The CNENx registers contain the CN interrupt enable control bits for each of the input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

The CNSTATx register indicates whether a change occurred on the corresponding pin since the last read of the PORTx bit.

### 11.1.5 INTERNALLY SELECTABLE PULL-UPS AND PULL-DOWNS

Each I/O pin also has a weak pull-up and every I/O pin has a weak pull-down connected to it, which are independent of any other I/O pin functionality (i.e., PPS, Open Drain, or CN). The pull-ups act as a current source or sink source connected to the pin, and eliminate the need for external resistors when push-button or keypad devices are connected. The pull-ups and pull-downs are enabled separately using the CNPUx and the CNPDx registers, which contain the control bits for each of the pins. Setting any of the control bits enables the weak pull-ups and/or pull-downs for the corresponding pins.

| | |
|---|---|
| **Note:** | Pull-ups and pull-downs on change notification pins should always be disabled when the port pin is configured as a digital output. They should also be disabled on 5V tolerant pins when the pin voltage can exceed VDD. |

An additional control register (CNCONx) is shown in Register 11-3.

## 11.2 CLR, SET, and INV Registers

Every I/O module register has a corresponding CLR (clear), SET (set) and INV (invert) register designed to provide fast atomic bit manipulations. As the name of the register implies, a value written to a SET, CLR or INV register effectively performs the implied operation, but only on the corresponding base register and only bits specified as '1' are modified. Bits specified as '0' are not modified.

Reading SET, CLR and INV registers returns undefined values. To see the affects of a write operation to a SET, CLR or INV register, the base register must be read.

## 11.3 Peripheral Pin Select

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. The challenge is even greater on low pin count devices. In an application where more than one peripheral needs to be assigned to a single pin, inconvenient workarounds in application code or a complete redesign may be the only options.

Peripheral pin select configuration provides an alternative to these choices by enabling peripheral set selection and their placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the device to their entire application, rather than trimming the application to fit the device.

The peripheral pin select configuration feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of most digital peripherals to these I/O pins. Peripheral pin select is performed in software and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

### 11.3.1 AVAILABLE PINS

The number of available pins is dependent on the particular device and its pin count. Pins that support the peripheral pin select feature include the designation "RPn" in their full pin designation, where "RP" designates a remappable peripheral and "n" is the remappable port number.

### 11.3.2 AVAILABLE PERIPHERALS

The peripherals managed by the peripheral pin select are all digital-only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer-related peripherals (input capture and output compare) and interrupt-on-change inputs.

In comparison, some digital-only peripheral modules are never included in the peripheral pin select feature. This is because the peripheral's function requires special I/O circuitry on a specific port and cannot be easily connected to multiple pins. These modules include $I^2C$ among others. A similar requirement excludes all modules with analog inputs, such as the Analog-to-Digital Converter (ADC).

A key difference between remappable and non-remappable peripherals is that remappable peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-remappable peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

When a remappable peripheral is active on a given I/O pin, it takes priority over all other digital I/O and digital communication peripherals associated with the pin. Priority is given regardless of the type of peripheral that is mapped. Remappable peripherals never take priority over any analog functions associated with the pin.

### 11.3.3 CONTROLLING PERIPHERAL PIN SELECT

Peripheral pin select features are controlled through two sets of SFRs: one to map peripheral inputs, and one to map outputs. Because they are separately controlled, a particular peripheral's input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

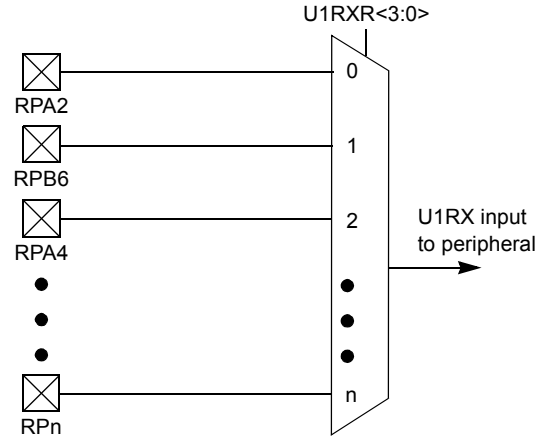
The association of a peripheral to a peripheral-selectable pin is handled in two different ways, depending on whether an input or output is being mapped.

### 11.3.4 INPUT MAPPING

The inputs of the peripheral pin select options are mapped on the basis of the peripheral. That is, a control register associated with a peripheral dictates the pin it will be mapped to. The [*pin name*]R registers, where [*pin name*] refers to the peripheral pins listed in Table 11-1, are used to configure peripheral input mapping (see Register 11-1). Each register contains sets of 4 bit fields. Programming these bit fields with an appropriate value maps the RPn pin with the corresponding value to that peripheral. For any given device, the valid range of values for any bit field is shown in Table 11-1.

For example, Figure 11-2 illustrates the remappable pin selection for the U1RX input.

**FIGURE 11-2: REMAPPABLE INPUT EXAMPLE FOR U1RX**




**Note:** For input only, peripheral pin select functionality does not have priority over TRISx settings. Therefore, when configuring RPn pin for input, the corresponding bit in the TRISx register must also be configured for input (set to '1').

**REGISTER 11-3: CNCONx: CHANGE NOTICE CONTROL FOR PORTx REGISTER (x = A – G)**

| Bit Range | Bit 31/23/15/7 | Bit 30/22/14/6 | Bit 29/21/13/5 | Bit 28/20/12/4 | Bit 27/19/11/3 | Bit 26/18/10/2 | Bit 25/17/9/1 | Bit 24/16/8/0 |
|---|---|---|---|---|---|---|---|---|
| 31:24 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 23:16 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |
| 15:8 | R/W-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | ON | — | SIDL | — | — | — | — | — |
| 7:0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| | — | — | — | — | — | — | — | — |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** Change Notice (CN) Control ON bit
- 1 = CN is enabled
- 0 = CN is disabled

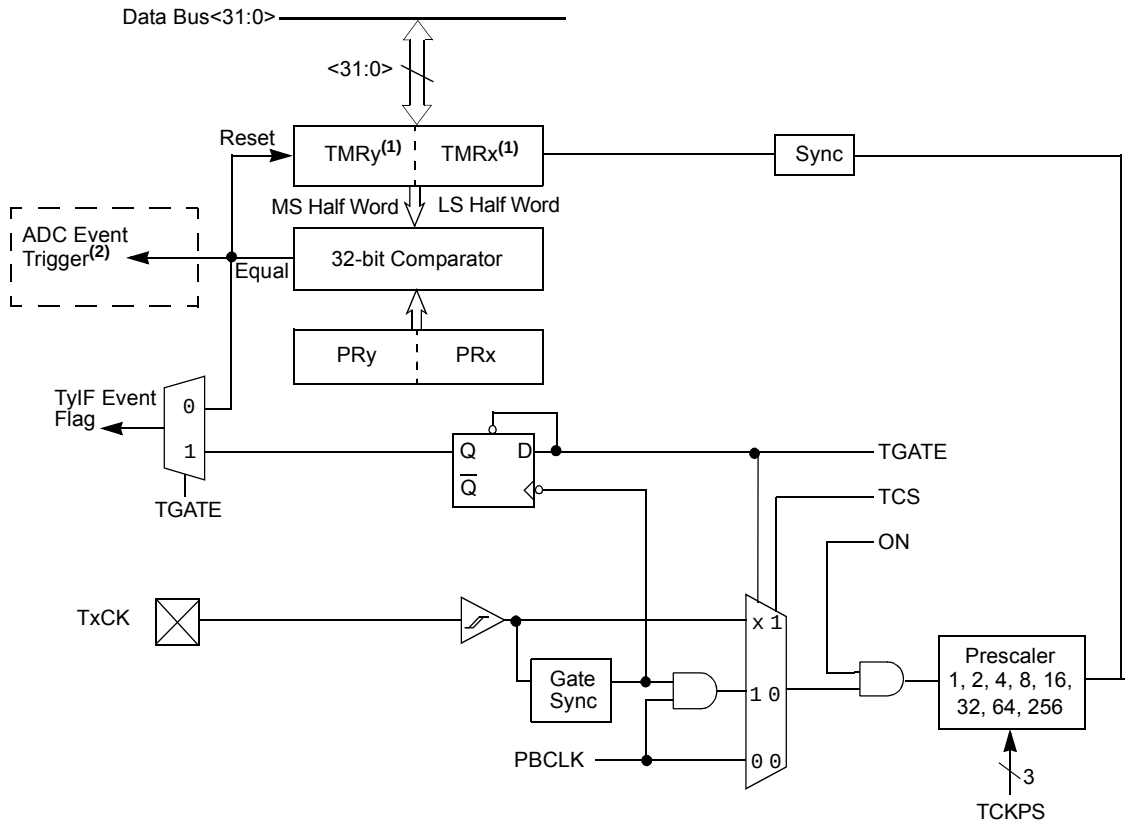
bit 14 **Unimplemented:** Read as '0'

bit 13 **SIDL:** Stop in Idle Control bit
- 1 = CPU Idle Mode halts CN operation
- 0 = CPU Idle does not affect CN operation

bit 12-0 **Unimplemented:** Read as '0'

**FIGURE 13-2: TIMER2/3, 4/5 BLOCK DIAGRAM (32-BIT)(1)**




**Note 1:** In this diagram, the use of 'x' in registers, TxCON, TMRx, PRx and TxCK, refers to either Timer2 or Timer4; the use of 'y' in registers, TyCON, TMRy, PRy, TyIF, refers to either Timer3 or Timer5.

**2:** ADC event trigger is available only on the Timer2/3 pair.

**NOTES:**

**REGISTER 23-1: C1CON: CAN MODULE CONTROL REGISTER**

| Bit Range | Bit 31/23/15/7 | Bit 30/22/14/6 | Bit 29/21/13/5 | Bit 28/20/12/4 | Bit 27/19/11/3 | Bit 26/18/10/2 | Bit 25/17/9/1 | Bit 24/16/8/0 |
|---|---|---|---|---|---|---|---|---|
| 31:24 | U-0 | U-0 | U-0 | U-0 | S/HC-0 | R/W-1 | R/W-0 | R/W-0 |
| | — | — | — | — | ABAT | REQOP<2:0> | | |
| 23:16 | R-1 | R-0 | R-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
| | OPMOD<2:0> | | | CANCAP | — | — | — | — |
| 15:8 | R/W-0 | U-0 | R/W-0 | U-0 | R-0 | U-0 | U-0 | U-0 |
| | ON(1) | — | SIDLE | — | CANBUSY | — | — | — |
| 7:0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| | — | — | — | DNCNT<4:0> | | | | |

| Legend: | HC = Hardware Clear | S = Settable bit | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 31-28 **Unimplemented:** Read as '0'

bit 27 **ABAT:** Abort All Pending Transmissions bit
1 = Signal all transmit buffers to abort transmission
0 = Module will clear this bit when all transmissions aborted

bit 26-24 **REQOP<2:0>:** Request Operation Mode bits
111 = Set Listen All Messages mode
110 = Reserved
101 = Reserved
100 = Set Configuration mode
011 = Set Listen Only mode
010 = Set Loopback mode
001 = Set Disable mode
000 = Set Normal Operation mode

bit 23-21 **OPMOD<2:0>:** Operation Mode Status bits
111 = Module is in Listen All Messages mode
110 = Reserved
101 = Reserved
100 = Module is in Configuration mode
011 = Module is in Listen Only mode
010 = Module is in Loopback mode
001 = Module is in Disable mode
000 = Module is in Normal Operation mode

bit 20 **CANCAP:** CAN Message Receive Time Stamp Timer Capture Enable bit
1 = CANTMR value is stored on valid message reception and is stored with the message
0 = Disable CAN message receive time stamp timer capture and stop CANTMR to conserve power

bit 19-16 **Unimplemented:** Read as '0'

bit 15 **ON:** CAN On bit(1)
1 = CAN module is enabled
0 = CAN module is disabled

bit 14 **Unimplemented:** Read as '0'

**Note 1:** If the user application clears this bit, it may take a number of cycles before the CAN module completes the current transaction and responds to this request. The user application should poll the CANBUSY bit to verify that the request has been honored.

**REGISTER 23-13: C1FLTCON3: CAN FILTER CONTROL REGISTER 3 (CONTINUED)**

bit 20-16 **FSEL14<4:0>:** FIFO Selection bits
11111 = Reserved
.
.
.
10000 = Reserved
01111 = Message matching filter is stored in FIFO buffer 15
.
.
.
00000 = Message matching filter is stored in FIFO buffer 0

bit 15 **FLTEN13:** Filter 13 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 14-13 **MSEL13<1:0>:** Filter 13 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 12-8 **FSEL13<4:0>:** FIFO Selection bits
11111 = Reserved
.
.
.
10000 = Reserved
01111 = Message matching filter is stored in FIFO buffer 15
.
.
.
00000 = Message matching filter is stored in FIFO buffer 0

bit 7 **FLTEN12:** Filter 12 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 6-5 **MSEL12<1:0>:** Filter 12 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 4-0 **FSEL12<4:0>:** FIFO Selection bits
11111 = Reserved
.
.
.
10000 = Reserved
01111 = Message matching filter is stored in FIFO buffer 15
.
.
.
00000 = Message matching filter is stored in FIFO buffer 0

**Note:** The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

**TABLE 31-9: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +105°C for V-temp | | | | |
|---|---|---|---|---|---|---|---|
| **Param.** | **Symbol** | **Characteristic** | **Min.** | **Typ.** | **Max.** | **Units** | **Conditions** |
| DO10 | VOL | **Output Low Voltage**<br>I/O Pins:<br>4x Sink Driver Pins - All I/O output pins not defined as 8x Sink Driver pins | — | — | 0.4 | V | IOL ≤ 9 mA, VDD = 3.3V |
| | | **Output Low Voltage**<br>I/O Pins:<br>8x Sink Driver Pins - RB14, RC15, RD2, RD10, RD15, RF6, RF13, RG6 | — | — | 0.4 | V | IOL ≤ 15 mA, VDD = 3.3V |
| DO20 | VOH | **Output High Voltage**<br>I/O Pins:<br>4x Source Driver Pins - All I/O output pins not defined as 8x Source Driver pins | 2.4 | — | — | V | IOH ≥ -10 mA, VDD = 3.3V |
| | | **Output High Voltage**<br>I/O Pins:<br>8x Source Driver Pins - RB14, RC15, RD2, RD10, RD15, RF6, RF13, RG6 | 2.4 | — | — | V | IOH ≥ -15 mA, VDD = 3.3V |
| DO20A | VOH1 | **Output High Voltage**<br>I/O Pins:<br>4x Source Driver Pins - All I/O output pins not defined as 8x Sink Driver pins | 1.5(1) | — | — | V | IOH ≥ -14 mA, VDD = 3.3V |
| | | | 2.0(1) | — | — | | IOH ≥ -12 mA, VDD = 3.3V |
| | | | 3.0(1) | — | — | | IOH ≥ -7 mA, VDD = 3.3V |
| | | **Output High Voltage**<br>I/O Pins:<br>8x Source Driver Pins - RB14, RC15, RD2, RD10, RD15, RF6, RF13, RG6 | 1.5(1) | — | — | V | IOH ≥ -22 mA, VDD = 3.3V |
| | | | 2.0(1) | — | — | | IOH ≥ -18 mA, VDD = 3.3V |
| | | | 3.0(1) | — | — | | IOH ≥ -10 mA, VDD = 3.3V |

**Note 1:** Parameters are characterized, but not tested.

**TABLE 31-31: SPIx MODULE SLAVE MODE (CKE = 1) TIMING REQUIREMENTS (CONTINUED)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +105°C for V-temp | | | | |
|---|---|---|---|---|---|---|---|
| **Param. No.** | **Symbol** | **Characteristics(1)** | **Min.** | **Typical(2)** | **Max.** | **Units** | **Conditions** |
| SP51 | TSSH2DOZ | $\overline{SSx}$ ↑ to SDOx Output High-Impedance **(Note 4)** | 5 | — | 25 | ns | — |
| SP52 | TSCH2SSH<br>TSCL2SSH | $\overline{SSx}$ ↑ after SCKx Edge | TSCK + 20 | — | — | ns | — |
| SP60 | TSSL2DOV | SDOx Data Output Valid after $\overline{SSx}$ Edge | — | — | 25 | ns | — |

**Note 1:** These parameters are characterized, but not tested in manufacturing.

**2:** Data in "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**3:** The minimum clock period for SCKx is 50 ns.

**4:** Assumes 50 pF load on all SPIx pins.

## 32.2 AC Characteristics and Timing Parameters

The information contained in this section defines PIC32MX1XX/2XX/5XX 64/100-pin AC characteristics and timing parameters.

**TABLE 32-5: EXTERNAL CLOCK TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial | | | | |
|---|---|---|---|---|---|---|---|
| **Param. No.** | **Symbol** | **Characteristics** | **Min.** | **Typical** | **Max.** | **Units** | **Conditions** |
| MOS10 | FOSC | External CLKI Frequency<br>(External clocks allowed only in EC and ECPLL modes) | DC<br>4 | —<br>— | 50<br>50 | MHz<br>MHz | EC **(Note 2)**<br>ECPLL **(Note 1)** |

**Note 1:** PLL input requirements: 4 MHz ≤ FPLLIN ≤ 5 MHz (use PLL prescaler to reduce Fosc). This parameter is characterized, but tested at 10 MHz only at manufacturing.

**2:** This parameter is characterized, but not tested in manufacturing.

**TABLE 32-6: SPIx MASTER MODE (CKE = 0) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial | | | | |
|---|---|---|---|---|---|---|---|
| **Param. No.** | **Symbol** | **Characteristics** | **Min.** | **Typical** | **Max.** | **Units** | **Conditions** |
| MSP10 | TscL | SCKx Output Low Time **(Note 1,2)** | TSCK/2 | — | — | ns | — |
| MSP11 | TscH | SCKx Output High Time **(Note 1,2)** | TSCK/2 | — | — | ns | — |

**Note 1:** These parameters are characterized, but not tested in manufacturing.

**2:** The minimum clock period for SCKx is 40 ns. Therefore, the clock generated in Master mode must not violate this specification.

**TABLE 32-7: SPIx MODULE MASTER MODE (CKE = 1) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial | | | | |
|---|---|---|---|---|---|---|---|
| **Param. No.** | **Symbol** | **Characteristics(1)** | **Min.** | **Typ.** | **Max.** | **Units** | **Conditions** |
| MSP10 | TscL | SCKx Output Low Time **(Note 1,2)** | TSCK/2 | — | — | ns | — |
| MSP11 | TscH | SCKx Output High Time **(Note 1,2)** | TSCK/2 | — | — | ns | — |

**Note 1:** These parameters are characterized, but not tested in manufacturing.

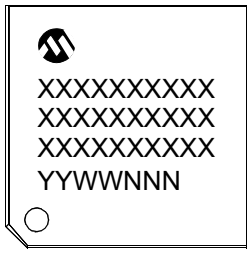
**2:** The minimum clock period for SCKx is 40 ns. Therefore, the clock generated in Master mode must not violate this specification.

## 34.0 PACKAGING INFORMATION

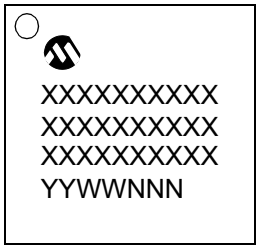
### 34.1 Package Marking Information

64-Lead TQFP (10x10x1 mm)

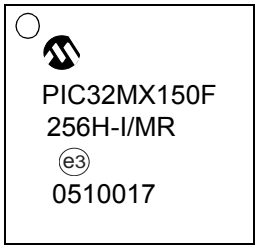



Example

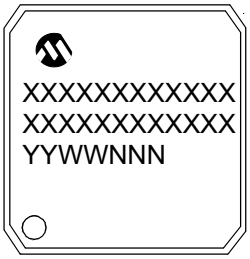

64-Lead QFN (9x9x0.9 mm)




Example

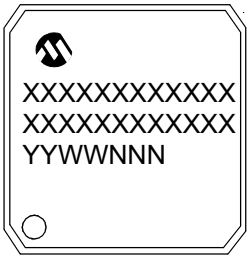



100-Lead TQFP (14x14x1 mm)




Example


100-Lead TQFP (12x12x1 mm)




Example


| | | |
|---|---|---|
| **Legend:** | XX...X | Customer-specific information |
| | Y | Year code (last digit of calendar year) |
| | YY | Year code (last 2 digits of calendar year) |
| | WW | Week code (week of January 1 is week '01') |
| | NNN | Alphanumeric traceability code |
| | | Pb-free JEDEC designator for Matte Tin (Sn) |
| | * | This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package. |

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.