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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	CANbus, I²C, IrDA, LINbus, PMP, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	49
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 28x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic32mx570f512h-50i-pt">https://www.e-xfl.com/product-detail/microchip-technology/pic32mx570f512h-50i-pt</a>

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

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## Table of Contents

1.0	Device Overview .....	13
2.0	Guidelines for Getting Started with 32-bit MCUs.....	25
3.0	CPU .....	35
4.0	Memory Organization .....	39
5.0	Interrupt Controller .....	53
6.0	Flash Program Memory.....	63
7.0	Resets .....	69
8.0	Oscillator Configuration .....	73
9.0	Direct Memory Access (DMA) Controller .....	85
10.0	USB On-The-Go (OTG).....	105
11.0	I/O Ports .....	129
12.0	Timer1 .....	159
13.0	Timer2/3, Timer4/5 .....	163
14.0	Watchdog Timer (WDT) .....	169
15.0	Input Capture.....	173
16.0	Output Compare .....	177
17.0	Serial Peripheral Interface (SPI).....	181
18.0	Inter-Integrated Circuit (I <sup>2</sup> C) .....	191
19.0	Universal Asynchronous Receiver Transmitter (UART) .....	199
20.0	Parallel Master Port (PMP).....	207
21.0	Real-Time Clock and Calendar (RTCC).....	221
22.0	10-bit Analog-to-Digital Converter (ADC) .....	231
23.0	Controller Area Network (CAN) .....	243
24.0	Comparator .....	271
25.0	Comparator Voltage Reference (CVREF) .....	275
26.0	Charge Time Measurement Unit (CTMU) .....	279
27.0	Power-Saving Features .....	285
28.0	Special Features .....	291
29.0	Instruction Set .....	303
30.0	Development Support.....	305
31.0	40 MHz Electrical Characteristics.....	309
32.0	50 MHz Electrical Characteristics.....	353
33.0	DC and AC Device Characteristics Graphs.....	359
34.0	Packaging Information.....	361
	The Microchip Web Site .....	377
	Customer Change Notification Service .....	377
	Customer Support .....	377
	Product Identification System .....	378

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	64-pin QFN/ TQFP	100-pin TQFP			
AN36	—	47	I	Analog	Analog input channels.
AN37	—	48	I	Analog	
AN38	—	52	I	Analog	
AN39	—	53	I	Analog	
AN40	—	79	I	Analog	
AN41	—	80	I	Analog	
AN42	—	83	I	Analog	
AN43	—	84	I	Analog	
AN44	—	87	I	Analog	
AN45	—	88	I	Analog	
AN46	—	93	I	Analog	
AN47	—	94	I	Analog	
CLKI	39	63	I	ST/CMOS	External clock source input. Always associated with OSC1 pin function.
CLKO	40	64	O	—	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes. Always associated with the OSC2 pin function.
OSC1	39	63	I	ST/CMOS	Oscillator crystal input. ST buffer when configured in RC mode; CMOS otherwise.
OSC2	40	64	O	—	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes.
SOSCI	47	73	I	ST/CMOS	32.768 kHz low-power oscillator crystal input; CMOS otherwise.
SOSCO	48	74	O	—	32.768 kHz low-power oscillator crystal output.
IC1	PPS	PPS	I	ST	Capture Input 1-5
IC2	PPS	PPS	I	ST	
IC3	PPS	PPS	I	ST	
IC4	PPS	PPS	I	ST	
IC5	PPS	PPS	I	ST	
OC1	PPS	PPS	O	ST	Output Compare Output 1
OC2	PPS	PPS	O	ST	Output Compare Output 2
OC3	PPS	PPS	O	ST	Output Compare Output 3
OC4	PPS	PPS	O	ST	Output Compare Output 4
OC5	PPS	PPS	O	ST	Output Compare Output 5
OCFA	PPS	PPS	I	ST	Output Compare Fault A Input
OCFB	30	44	I	ST	Output Compare Fault B Input

**Legend:** CMOS = CMOS compatible input or output      Analog = Analog input      I = Input  
 ST = Schmitt Trigger input with CMOS levels      TTL = TTL input buffer      O = Output  
 P = Power

**Note 1:** This pin is only available on devices without a USB module.

**2:** This pin is only available on devices with a USB module.

**3:** This pin is not available on 64-pin devices with a USB module.

**4:** This pin is only available on 100-pin devices without a USB module.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

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TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	64-pin QFN/ TQFP	100-pin TQFP			
INT0	35 <sup>(1)</sup> , 46 <sup>(2)</sup>	55 <sup>(1)</sup> , 72 <sup>(2)</sup>	I	ST	External Interrupt 0
INT1	PPS	PPS	I	ST	External Interrupt 1
INT2	PPS	PPS	I	ST	External Interrupt 2
INT3	PPS	PPS	I	ST	External Interrupt 3
INT4	PPS	PPS	I	ST	External Interrupt 4
RA0	—	17	I/O	ST	PORTA is a bidirectional I/O port
RA1	—	38	I/O	ST	
RA2	—	58	I/O	ST	
RA3	—	59	I/O	ST	
RA4	—	60	I/O	ST	
RA5	—	61	I/O	ST	
RA6	—	91	I/O	ST	
RA7	—	92	I/O	ST	
RA9	—	28	I/O	ST	
RA10	—	29	I/O	ST	
RA14	—	66	I/O	ST	PORTB is a bidirectional I/O port
RA15	—	67	I/O	ST	
RB0	16	25	I/O	ST	
RB1	15	24	I/O	ST	
RB2	14	23	I/O	ST	
RB3	13	22	I/O	ST	
RB4	12	21	I/O	ST	
RB5	11	20	I/O	ST	
RB6	17	26	I/O	ST	
RB7	18	27	I/O	ST	
RB8	21	32	I/O	ST	
RB9	22	33	I/O	ST	
RB10	23	34	I/O	ST	
RB11	24	35	I/O	ST	
RB12	27	41	I/O	ST	
RB13	28	42	I/O	ST	
RB14	29	43	I/O	ST	
RB15	30	44	I/O	ST	

**Legend:** CMOS = CMOS compatible input or output      Analog = Analog input  
 ST = Schmitt Trigger input with CMOS levels      TTL = TTL input buffer      I = Input      O = Output  
 P = Power

- Note 1:** This pin is only available on devices without a USB module.  
**2:** This pin is only available on devices with a USB module.  
**3:** This pin is not available on 64-pin devices with a USB module.  
**4:** This pin is only available on 100-pin devices without a USB module.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

## REGISTER 4-4: BMXDUPBA: DATA RAM USER PROGRAM BASE ADDRESS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0
	BMXDUPBA<15:8>							
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	BMXDUPBA<7:0>							

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-10 **BMXDUPBA<15:10>:** DRM User Program Base Address bits

When non-zero, the value selects the relative base address for User mode program space in RAM, BMXDUPBA must be greater than BMXDUDBA.

bit 9-0 **BMXDUPBA<9:0>:** Read-Only bits

Value is always '0', which forces 1 KB increments

- Note 1:** At Reset, the value in this register is forced to zero, which causes all of the RAM to be allocated to Kernel mode data usage.
- 2:** The value in this register must be less than or equal to BMXDRMSZ.

## 7.1 Control Registers

TABLE 7-1: RESET SFR SUMMARY

	Virtual Address [FF00-#]	Register Name()	Bit Range	Bits															All Resets
				31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0
F600	RCON	31:16	—	—	HVDR	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	CMR	VREGS	EXTR	SWR	—	WDTO	SLEEP	IDLE	BOR	POR
F610	RSWRST	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	SWRST 0000

**Legend:** — = unimplemented, read as '0'. Address offset values are shown in hexadecimal.

**Note 1:** The Reset value is dependent on the DEVCFGx Configuration bits and the type of reset.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

## REGISTER 7-2: RSWRST: SOFTWARE RESET REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	W-0, HC
	—	—	—	—	—	—	—	SWRST <sup>(1)</sup>

### Legend:

HC = Cleared by hardware

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-1 **Unimplemented:** Read as '0'

bit 0 **SWRST:** Software Reset Trigger bit<sup>(1)</sup>

1 = Enable software Reset event

0 = No effect

**Note 1:** The system unlock sequence must be performed before the SWRST bit can be written. Refer to **Section 6. "Oscillator"** (DS60001112) in the "*PIC32 Family Reference Manual*" for details.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

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## REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER (CONTINUED)

bit 2 **UFRCEN:** USB FRC Clock Enable bit<sup>(1)</sup>

1 = Enable FRC as the clock source for the USB clock source

0 = Use the Primary Oscillator or USB PLL as the USB clock source

bit 1 **SOSCEN:** Secondary Oscillator (Sosc) Enable bit

1 = Enable Secondary Oscillator

0 = Disable Secondary Oscillator

bit 0 **OSWEN:** Oscillator Switch Enable bit

1 = Initiate an oscillator switch to selection specified by NOSC<2:0> bits

0 = Oscillator switch is complete

**Note 1:** This bit is available on PIC32MX2XX/5XX devices only.

**Note:** Writes to this register require an unlock sequence. Refer to **Section 6. “Oscillator”** (DS60001112) in the *“PIC32 Family Reference Manual”* for details.

**TABLE 11-8: PORTD REGISTER MAP FOR 64-PIN DEVICES ONLY**

Register Name	Bit Range #	Virtual Address (B8-BF)	Bits																		All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0			
6300 ANSELD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	—	—	—	—	—	—	—	—	ANSELD3	ANSELD2	ANSELD1	—	—	000E		
6310 TRISD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	TRISD11	TRISD10	TRISD9	TRISD8	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	0FFF	—	—	
5320 PORTD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	RD11	RD10	RD9	RD8	RD7	RD6	RD5	RD4	RD3	RD2	RD1	RD0	xxxx	—	—	
6330 LATD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	LATD11	LATD10	LATD9	LATD8	LATD7	LATD6	LATD5	LATD4	LATD3	LATD2	LATD1	LATD0	xxxx	—	—	
6340 ODCD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	ODCD11	ODCD10	ODCD9	ODCD8	ODCD7	ODCD6	ODCD5	ODCD4	ODCD3	ODCD2	ODCD1	ODCD0	0000	—	—	
6350 CNPUD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	CNPUD11	CNPUD10	CNPUD9	CNPUD8	CNPUD7	CNPUD6	CNPUD5	CNPUD4	CNPUD3	CNPUD2	CNPUD1	CNPUD0	0000	—	—	
6360 CNPDD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	CNPDD11	CNPDD10	CNPDD9	CNPDD8	CNPDD7	CNPDD6	CNPDD5	CNPDD4	CNPDD3	CNPDD2	CNPDD1	CNPDD0	0000	—	—	
6370 CNCOND	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	ON	—	SIDL	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
6380 CNEND	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	CNIED11	CNIED10	CNIED9	CNIED8	CNIED7	CNIED6	CNIED5	CNIED4	CNIED3	CNIED2	CNIED1	CNIED0	0000	—	—	
6390 CNSTATD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
	15:0	—	—	—	—	CNSTATD11	CNSTATD10	CNSTATD9	CNSTATD8	CNSTATD7	CNSTATD6	CNSTATD5	CNSTATD4	CNSTATD3	CNSTATD2	CNSTATD1	CNSTATD0	0000	—	—	

**Legend:** x = Unknown value on Reset; — = Unimplemented, read as '0'; Reset values are shown in hexadecimal.

**Note 1:** All registers in this table have corresponding CLR, SET and INV registers at its virtual address, plus an offset of 0x4, 0x8 and 0xC, respectively. See **Section 11.2 “CLR, SET, and INV Registers”** for more information.

**TABLE 11-17: PERIPHERAL PIN SELECT INPUT REGISTER MAP (CONTINUED)**

Virtual Address (BF80 <sub>#</sub> )	Register Name	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0
FA5C	U2CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA60	U3RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA64	U3CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA68	U4RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA6C	U4CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA70	U5RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA74	U5CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA84	SDI1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA88	SS1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA90	SDI2R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA94	SS2R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FA9C	SDI3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FAA0	SS3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FAA8	SDI4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FAAC	SS4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FAC8	C1RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
FAD0	REFCLKIR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

## REGISTER 20-1: PMCON: PARALLEL PORT CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	R/W-0, HC	U-0	U-0	U-0	U-0	U-0	R/W-0	U-0
	RDSTART	—	—	—	—	—	DUALBUF	—
15:8	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ON <sup>(1)</sup>	—	SIDL	ADRMUX<1:0>		PMPTTL	PTWREN	PTRDEN
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
	CSF<1:0> <sup>(2)</sup>		ALP <sup>(2)</sup>	CS2P <sup>(2)</sup>	CS1P <sup>(2)</sup>	—	WRSP	RDSP

<b>Legend:</b>	HC = Hardware cleared	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 31-24 **Unimplemented:** Read as '0'
- bit 23 **RDSTART:** Start a Read on the PMP Bus bit<sup>(3)</sup>
- 1 = Start a read cycle on the PMP bus
  - 0 = No effect
- This bit is cleared by hardware at the end of the read cycle when the BUSY bit (PMMODE<15>) = 0.
- bit 22-18 **Unimplemented:** Read as '0'
- bit 17 **DUALBUF:** Parallel Master Port Dual Read/Write Buffer Enable bit
- This bit is only valid in Master mode.
  - 1 = PMP uses separate registers for reads and writes
  - Reads: PMRADDR and PMRDIN
  - Writes: PMRWADDR and PMDOUT
  - 0 = PMP uses legacy registers for reads and writes
  - Reads/Writes: PMADDR and PMRDIN
- bit 16 **Unimplemented:** Read as '0'
- bit 15 **ON:** Parallel Master Port Enable bit<sup>(1)</sup>
- 1 = PMP enabled
  - 0 = PMP disabled, no off-chip access performed
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **SIDL:** Stop in Idle Mode bit
- 1 = Discontinue module operation when device enters Idle mode
  - 0 = Continue module operation in Idle mode
- bit 12-11 **ADRMUX<1:0>:** Address/Data Multiplexing Selection bits
- 11 = Lower 8 bits of address are multiplexed on PMD<15:0> pins
  - 10 = All 16 bits of address are multiplexed on PMD<7:0> pins
  - 01 = Lower 8 bits of address are multiplexed on PMD<7:0> pins, upper bits are on PMA<15:8>
  - 00 = Address and data appear on separate pins
- bit 10 **PMPTTL:** PMP Module TTL Input Buffer Select bit
- 1 = PMP module uses TTL input buffers
  - 0 = PMP module uses Schmitt Trigger input buffer
- bit 9 **PTWREN:** Write Enable Strobe Port Enable bit
- 1 = PMWR/PMENB port enabled
  - 0 = PMWR/PMENB port disabled

**Note 1:** When using 1:1 PBCLK divisor, the user software should not read/write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON control bit.

**2:** These bits have no effect when their corresponding pins are used as address lines.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

## REGISTER 22-3: AD1CON3: ADC CONTROL REGISTER 3

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ADRC	—	—	SAMC<4:0> <sup>(1)</sup>				
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W	R/W-0
	ADCS<7:0> <sup>(2)</sup>							

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ADRC:** ADC Conversion Clock Source bit

1 = Clock derived from FRC

0 = Clock derived from Peripheral Bus Clock (PBCLK)

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **SAMC<4:0>:** Auto-Sample Time bits<sup>(1)</sup>

11111 = 31 TAD

•

•

•

00001 = 1 TAD

00000 = 0 TAD (Not allowed)

bit 7-0 **ADCS<7:0>:** ADC Conversion Clock Select bits<sup>(2)</sup>

11111111 = TPB • 2 • (ADCS<7:0> + 1) = 512 • TPB = TAD

•

•

•

00000001 = TPB • 2 • (ADCS<7:0> + 1) = 4 • TPB = TAD

00000000 = TPB • 2 • (ADCS<7:0> + 1) = 2 • TPB = TAD

**Note 1:** This bit is only used if the SSRC<2:0> bits (AD1CON1<7:5>) = 111.

**2:** This bit is not used if the ADRC bit (AD1CON3<15>) = 1.

## 23.0 CONTROLLER AREA NETWORK (CAN)

**Note:** This data sheet summarizes the features of the PIC32MX1XX/2XX/5XX 64/100-pin family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 34. "Controller Area Network (CAN)"** (DS60001154) in the "*PIC32 Family Reference Manual*", which is available from the Microchip web site ([www.microchip.com/PIC32](http://www.microchip.com/PIC32)).

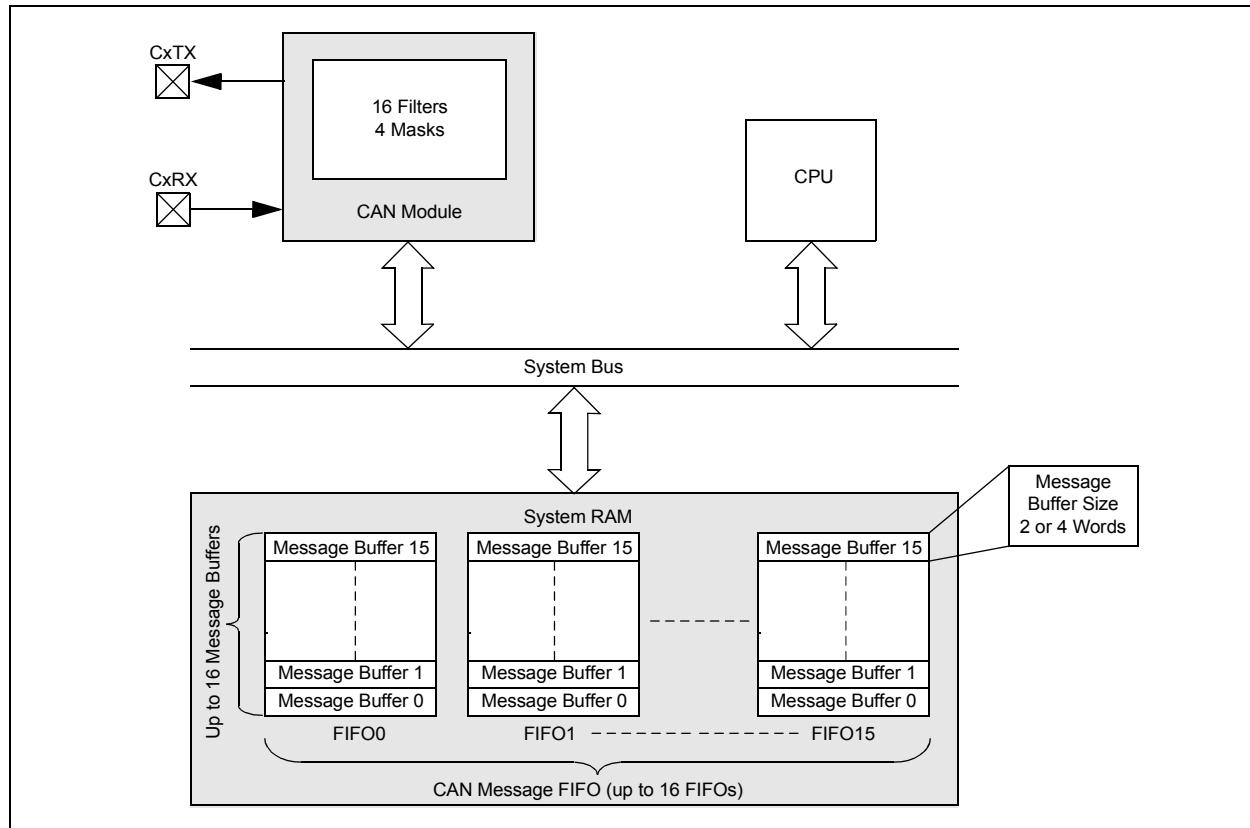
The Controller Area Network (CAN) module supports the following key features:

- Standards Compliance:
  - Full CAN 2.0B compliance
  - Programmable bit rate up to 1 Mbps
- Message Reception and Transmission:
  - 16 message FIFOs
  - Each FIFO can have up to 16 messages for a total of 256 messages

- FIFO can be a transmit message FIFO or a receive message FIFO
- User-defined priority levels for message FIFOs used for transmission
- 16 acceptance filters for message filtering
- Four acceptance filter mask registers for message filtering
- Automatic response to remote transmit request
- DeviceNet™ addressing support
- Additional Features:
  - Loopback, Listen All Messages, and Listen Only modes for self-test, system diagnostics and bus monitoring
  - Low-power operating modes
  - CAN module is a bus master on the PIC32 system bus
  - Use of DMA is not required
  - Dedicated time-stamp timer
  - Dedicated DMA channels
  - Data-only Message Reception mode

Figure 23-1 illustrates the general structure of the CAN module.

**FIGURE 23-1: PIC32 CAN MODULE BLOCK DIAGRAM**



**TABLE 23-1: CAN1 REGISTER SUMMARY (CONTINUED)**

Virtual Address (BF88 #)	Register Name()	Bit Range	Bits															All Resets	
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
B340	C1FIFOBA	31:16	C1FIFOBA<31:0>															0000	
		15:0																0000	
B350	C1FIFOCONn (n = 0-15)	31:16	—	—	—	—	—	—	—	—	—	TXEN	TXABAT	TXLARB	TXERR	TXREQ	RTREN	TXPRI<1:0>	0000
		15:0	—	FRESET	UINC	DONLY	—	—	—	—	TXEN	TXABAT	TXLARB	TXERR	TXREQ	RTREN	TXPRI<1:0>	0000	
B360	C1FIFOINTn (n = 0-15)	31:16	—	—	—	—	—	TXNFULLIE	TXHALFIE	TXEMPTYIE	—	—	—	—	RXOVFLIE	RXFULLIE	RXHALFIE	RXN EMPTYIE	0000
		15:0	—	—	—	—	—	TXNFULLIF	TXHALFIF	TXEMPTYIF	—	—	—	—	RXOVFLIF	RXFULLIF	RXHALFIF	RXN EMPTYIF	0000
B370	C1FIFOUAn (n = 0-15)	31:16	C1FIFOUA<31:0>															0000	
		15:0																0000	
B380	C1FIFOCln (n = 0-15)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000

**Legend:** x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 11.2 “CLR, SET, and INV Registers”** for more information.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

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## REGISTER 23-16: C1FIFOCONn: CAN FIFO CONTROL REGISTER ‘n’ (‘n’ = 0 THROUGH 15) (CONTINUED)

bit 7	<b>TXEN:</b> TX/RX Buffer Selection bit 1 = FIFO is a Transmit FIFO 0 = FIFO is a Receive FIFO
bit 6	<b>TXABAT:</b> Message Aborted bit <sup>(2)</sup> 1 = Message was aborted 0 = Message completed successfully
bit 5	<b>TXLARB:</b> Message Lost Arbitration bit <sup>(3)</sup> 1 = Message lost arbitration while being sent 0 = Message did not lose arbitration while being sent
bit 4	<b>TXERR:</b> Error Detected During Transmission bit <sup>(3)</sup> 1 = A bus error occurred while the message was being sent 0 = A bus error did not occur while the message was being sent
bit 3	<b>TXREQ:</b> Message Send Request <u>TXEN = 1:</u> (FIFO configured as a Transmit FIFO) Setting this bit to ‘1’ requests sending a message. The bit will automatically clear when all the messages queued in the FIFO are successfully sent. Clearing the bit to ‘0’ while set (‘1’) will request a message abort. <u>TXEN = 0:</u> (FIFO configured as a receive FIFO) This bit has no effect.
bit 2	<b>RTREN:</b> Auto RTR Enable bit 1 = When a remote transmit is received, TXREQ will be set 0 = When a remote transmit is received, TXREQ will be unaffected
bit 1-0	<b>TXPR&lt;1:0&gt;:</b> Message Transmit Priority bits 11 = Highest message priority 10 = High intermediate message priority 01 = Low intermediate message priority 00 = Lowest message priority

- Note 1:** These bits can only be modified when the CAN module is in Configuration mode (OPMOD<2:0> bits (C1CON<23:21>) = 100).
- 2:** This bit is updated when a message completes (or aborts) or when the FIFO is reset.
- 3:** This bit is reset on any read of this register or when the FIFO is reset.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

## REGISTER 23-18: C1FIFOAn: CAN FIFO USER ADDRESS REGISTER ‘n’ (‘n’ = 0 THROUGH 15)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R-x	R-x						
C1FIFOAn<31:24>								
23:16	R-x	R-x						
C1FIFOAn<23:16>								
15:8	R-x	R-x						
C1FIFOAn<15:8>								
7:0	R-x	R-x	R-x	R-x	R-x	R-x	R-0 <sup>(1)</sup>	R-0 <sup>(1)</sup>
C1FIFOAn<7:0>								

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared
		x = Bit is unknown

bit 31-0 **C1FIFOAn<31:0>: CAN FIFO User Address bits**

TXEN = 1: (FIFO configured as a transmit buffer)

A read of this register will return the address where the next message is to be written (FIFO head).

TXEN = 0: (FIFO configured as a receive buffer)

A read of this register will return the address where the next message is to be read (FIFO tail).

**Note 1:** This bit will always read ‘0’, which forces byte-alignment of messages.

**Note:** This register is not guaranteed to read correctly in Configuration mode, and should only be accessed when the module is not in Configuration mode.

## REGISTER 23-19: C1FIFOCl<sub>n</sub>: CAN MODULE MESSAGE INDEX REGISTER ‘n’ ('n' = 0 THROUGH 15)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0
	—	—	—	C1FIFOCl <sub>n</sub> <4:0>				

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared
		x = Bit is unknown

bit 31-5 **Unimplemented:** Read as ‘0’

bit 4-0 **C1FIFOCl<sub>n</sub><4:0>: CAN Side FIFO Message Index bits**

TXEN = 1: (FIFO configured as a transmit buffer)

A read of this register will return an index to the message that the FIFO will next attempt to transmit.

TXEN = 0: (FIFO configured as a receive buffer)

A read of this register will return an index to the message that the FIFO will use to save the next message.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

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## REGISTER 26-1: CTMUCON: CTMU CONTROL REGISTER (CONTINUED)

bit 24	<b>EDG1STAT:</b> Edge 1 Status bit	Indicates the status of Edge 1 and can be written to control edge source 1 = Edge 1 has occurred 0 = Edge 1 has not occurred
bit 23	<b>EDG2MOD:</b> Edge 2 Edge Sampling Select bit	1 = Input is edge-sensitive 0 = Input is level-sensitive
bit 22	<b>EDG2POL:</b> Edge 2 Polarity Select bit	1 = Edge 2 programmed for a positive edge response 0 = Edge 2 programmed for a negative edge response
bit 21-18	<b>EDG2SEL&lt;3:0&gt;:</b> Edge 2 Source Select bits	1111 = IC4 Capture Event is selected 1110 = C2OUT pin is selected 1101 = C1OUT pin is selected 1100 = PBCLK clock is selected 1011 = IC3 Capture Event is selected 1010 = IC2 Capture Event is selected 1001 = IC1 Capture Event is selected 1000 = CTED13 pin is selected 0111 = CTED12 pin is selected 0110 = CTED11 pin is selected 0101 = CTED10 pin is selected 0100 = CTED9 pin is selected 0011 = CTED1 pin is selected 0010 = CTED2 pin is selected 0001 = OC1 Compare Event is selected 0000 = Timer1 Event is selected
bit 17-16	<b>Unimplemented:</b> Read as '0'	
bit 15	<b>ON:</b> ON Enable bit	1 = Module is enabled 0 = Module is disabled
bit 14	<b>Unimplemented:</b> Read as '0'	
bit 13	<b>CTMUSIDL:</b> Stop in Idle Mode bit	1 = Discontinue module operation when device enters Idle mode 0 = Continue module operation in Idle mode
bit 12	<b>TGEN:</b> Time Generation Enable bit <sup>(1)</sup>	1 = Enables edge delay generation 0 = Disables edge delay generation
bit 11	<b>EDGEN:</b> Edge Enable bit	1 = Edges are not blocked 0 = Edges are blocked

- Note 1:** When this bit is set for Pulse Delay Generation, the EDG2SEL<3:0> bits must be set to '1110' to select C2OUT.
- 2:** The ADC module Sample and Hold capacitor is not automatically discharged between sample/conversion cycles. Software using the ADC as part of a capacitive measurement, must discharge the ADC capacitor before conducting the measurement. The IDISSEN bit, when set to '1', performs this function. The ADC module must be sampling while the IDISSEN bit is active to connect the discharge sink to the capacitor array.
- 3:** Refer to the CTMU Current Source Specifications (Table 31-41) in **Section 31.0 “40 MHz Electrical Characteristics”** for current values.
- 4:** This bit setting is not available for the CTMU temperature diode.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

## 28.3 On-Chip Voltage Regulator

All PIC32MX1XX/2XX/5XX 64/100-pin devices' core and digital logic are designed to operate at a nominal 1.8V. To simplify system designs, most devices in the PIC32MX1XX/2XX/5XX 64/100-pin family incorporate an on-chip regulator providing the required core logic voltage from VDD.

A low-ESR capacitor (such as tantalum) must be connected to the VCAP pin (see Figure 28-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in **Section 31.1 “DC Characteristics”**.

**Note:** It is important that the low-ESR capacitor is placed as close as possible to the VCAP pin.

### 28.3.1 HIGH VOLTAGE DETECT (HVD)

The HVD module monitors the core voltage at the VCAP pin. If a voltage above the required level is detected on VCAP, the I/O pins are disabled and the device is held in Reset as long as the HVD condition persists. See parameter HV10 (VHVD) in Table 31-11 in **Section 31.1 “DC Characteristics”** for more information.

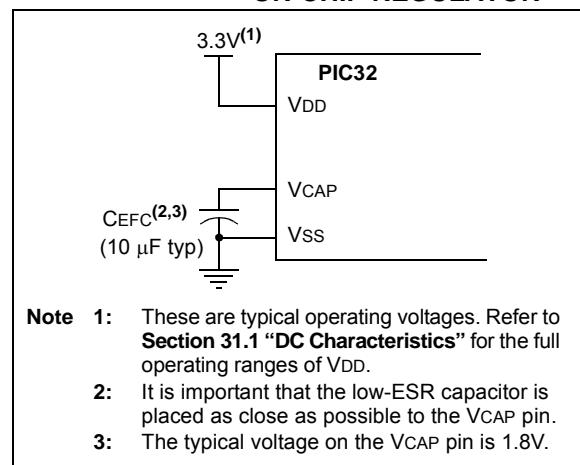
### 28.3.2 ON-CHIP REGULATOR AND POR

It takes a fixed delay for the on-chip regulator to generate an output. During this time, designated as TPU, code execution is disabled. TPU is applied every time the device resumes operation after any power-down, including Sleep mode.

### 28.3.3 ON-CHIP REGULATOR AND BOR

PIC32MX1XX/2XX/5XX 64/100-pin devices also have a simple brown-out capability. If the voltage supplied to the regulator is inadequate to maintain a regulated level, the regulator Reset circuitry will generate a Brown-out Reset. This event is captured by the BOR flag bit (RCON<1>). The brown-out voltage levels are specific in **Section 31.1 “DC Characteristics”**.

**FIGURE 28-1: CONNECTIONS FOR THE ON-CHIP REGULATOR**



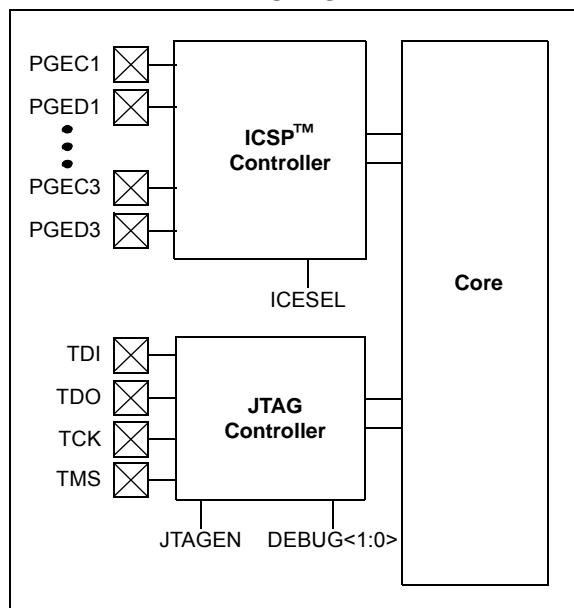
## 28.4 Programming and Diagnostics

PIC32MX1XX/2XX/5XX 64/100-pin devices provide a complete range of programming and diagnostic features that can increase the flexibility of any application using them. These features allow system designers to include:

- Simplified field programmability using two-wire In-Circuit Serial Programming™ (ICSP™) interfaces
- Debugging using ICSP
- Programming and debugging capabilities using the EJTAG extension of JTAG
- JTAG boundary scan testing for device and board diagnostics

PIC32 devices incorporate two programming and diagnostic modules that provide a range of functions to the application developer.

**FIGURE 28-2: BLOCK DIAGRAM OF PROGRAMMING, DEBUGGING AND TRACE PORTS**



# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

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**TABLE 31-12: DC CHARACTERISTICS: PROGRAM MEMORY**

DC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)				
Param. No.	Symbol	Characteristics	Min.	Typical <sup>(1)</sup>	Max.	Units	Conditions
D130	EP	Program Flash Memory <sup>(3)</sup> Cell Endurance	20,000	—	—	E/W	—
D131	VPR	VDD for Read	2.3	—	3.6	V	—
D132	VPEW	VDD for Erase or Write	2.3	—	3.6	V	—
D134	TRETD	Characteristic Retention	20	—	—	Year	Provided no other specifications are violated
D135	IDDP	Supply Current during Programming	—	10	—	mA	—
	TWW	Word Write Cycle Time	—	411	—	FRC Cycles	See Note 4
D136	TRW	Row Write Cycle Time	—	6675	—	FRC Cycles	See Note 2,4
D137	TPE	Page Erase Cycle Time	—	20011	—	FRC Cycles	See Note 4
	TCE	Chip Erase Cycle Time	—	80180	—	FRC Cycles	See Note 4

**Note 1:** Data in "Typical" column is at 3.3V, 25°C unless otherwise stated.

- 2:** The minimum SYSCLK for row programming is 4 MHz. Care should be taken to minimize bus activities during row programming, such as suspending any memory-to-memory DMA operations. If heavy bus loads are expected, selecting Bus Matrix Arbitration mode 2 (rotating priority) may be necessary. The default Arbitration mode is mode 1 (CPU has lowest priority).
- 3:** Refer to the "PIC32 Flash Programming Specification" (DS60001145) for operating conditions during programming and erase cycles.
- 4:** This parameter depends on FRC accuracy (See Table 31-19) and FRC tuning values (See Register 8-2).

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

TABLE 31-32: I<sup>2</sup>C BUS DATA TIMING REQUIREMENTS (MASTER MODE)

AC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)			
Param. No.	Symbol	Characteristics	Min. <sup>(1)</sup>	Max.	Units	Conditions
IM10	TLO:SCL	Clock Low Time	100 kHz mode	TPB * (BRG + 2)	—	μs
			400 kHz mode	TPB * (BRG + 2)	—	μs
			1 MHz mode <b>(Note 2)</b>	TPB * (BRG + 2)	—	μs
IM11	THI:SCL	Clock High Time	100 kHz mode	TPB * (BRG + 2)	—	μs
			400 kHz mode	TPB * (BRG + 2)	—	μs
			1 MHz mode <b>(Note 2)</b>	TPB * (BRG + 2)	—	μs
IM20	TF:SCL	SDAx and SCLx Fall Time	100 kHz mode	—	300	ns
			400 kHz mode	20 + 0.1 CB	300	ns
			1 MHz mode <b>(Note 2)</b>	—	100	ns
IM21	TR:SCL	SDAx and SCLx Rise Time	100 kHz mode	—	1000	ns
			400 kHz mode	20 + 0.1 CB	300	ns
			1 MHz mode <b>(Note 2)</b>	—	300	ns
IM25	TSU:DAT	Data Input Setup Time	100 kHz mode	250	—	ns
			400 kHz mode	100	—	ns
			1 MHz mode <b>(Note 2)</b>	100	—	ns
IM26	THD:DAT	Data Input Hold Time	100 kHz mode	0	—	μs
			400 kHz mode	0	0.9	μs
			1 MHz mode <b>(Note 2)</b>	0	0.3	μs
IM30	TSU:STA	Start Condition Setup Time	100 kHz mode	TPB * (BRG + 2)	—	μs
			400 kHz mode	TPB * (BRG + 2)	—	μs
			1 MHz mode <b>(Note 2)</b>	TPB * (BRG + 2)	—	μs
IM31	THD:STA	Start Condition Hold Time	100 kHz mode	TPB * (BRG + 2)	—	μs
			400 kHz mode	TPB * (BRG + 2)	—	μs
			1 MHz mode <b>(Note 2)</b>	TPB * (BRG + 2)	—	μs
IM33	TSU:STO	Stop Condition Setup Time	100 kHz mode	TPB * (BRG + 2)	—	μs
			400 kHz mode	TPB * (BRG + 2)	—	μs
			1 MHz mode <b>(Note 2)</b>	TPB * (BRG + 2)	—	μs
IM34	THD:STO	Stop Condition Hold Time	100 kHz mode	TPB * (BRG + 2)	—	ns
			400 kHz mode	TPB * (BRG + 2)	—	ns
			1 MHz mode <b>(Note 2)</b>	TPB * (BRG + 2)	—	ns

**Note 1:** BRG is the value of the I<sup>2</sup>C Baud Rate Generator.

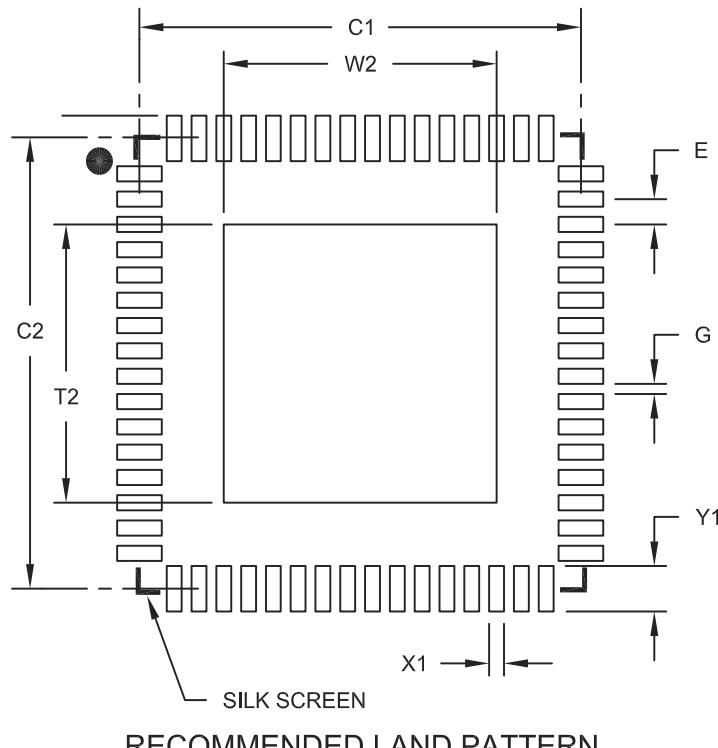
**2:** Maximum pin capacitance = 10 pF for all I<sup>2</sup>Cx pins (for 1 MHz mode only).

**3:** The typical value for this parameter is 104 ns.

# PIC32MX1XX/2XX/5XX 64/100-PIN FAMILY

64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body [QFN]  
With 0.40 mm Contact Length and 5.40x5.40mm Exposed Pad

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at  
<http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch		0.50 BSC		
Optional Center Pad Width	W2			5.50
Optional Center Pad Length	T2			5.50
Contact Pad Spacing	C1		8.90	
Contact Pad Spacing	C2		8.90	
Contact Pad Width (X64)	X1			0.30
Contact Pad Length (X64)	Y1			0.85
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2154A