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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	I <sup>2</sup> C, LINbus, SIO, SSU, UART/USART
Peripherals	POR, PWM, Voltage Detect, WDT
Number of I/O	75
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	2.5K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 20x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-LQFP (12x12)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f21386cdfp-30">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f21386cdfp-30</a>

### 1.1.2 Specifications

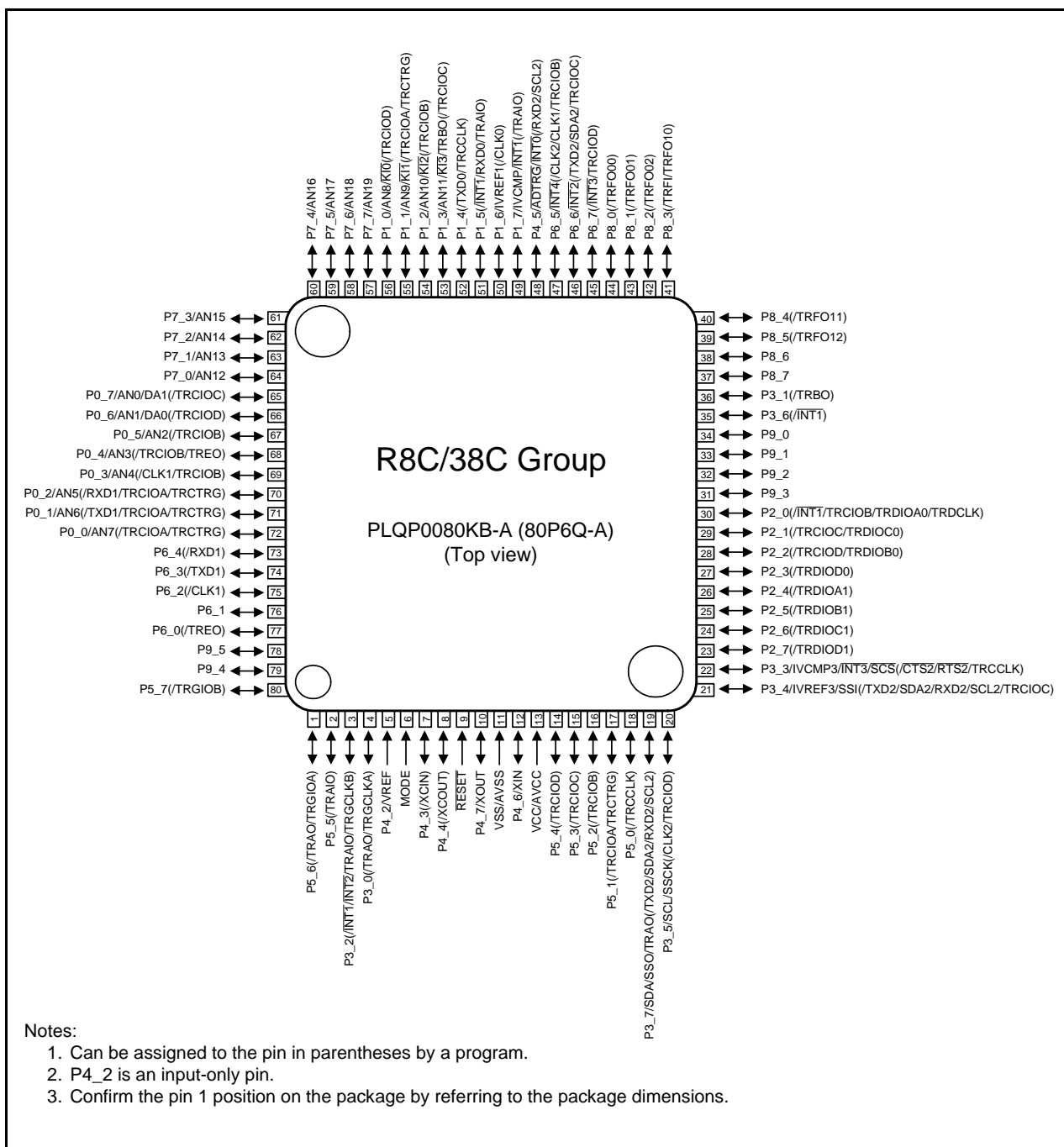
Tables 1.1 and 1.2 outline the Specifications for R8C/38C Group.

**Table 1.1 Specifications for R8C/38C Group (1)**

Item	Function	Specification
CPU	Central processing unit	R8C CPU core <ul style="list-style-type: none"><li>• Number of fundamental instructions: 89</li><li>• Minimum instruction execution time: 50 ns (f(XIN) = 20 MHz, VCC = 2.7 to 5.5 V) 200 ns (f(XIN) = 5 MHz, VCC = 1.8 to 5.5 V)</li><li>• Multiplier: 16 bits × 16 bits → 32 bits</li><li>• Multiply-accumulate instruction: 16 bits × 16 bits + 32 bits → 32 bits</li><li>• Operation mode: Single-chip mode (address space: 1 Mbyte)</li></ul>
Memory	ROM, RAM, Data flash	Refer to <b>Table 1.3 Product List for R8C/38C Group</b>
Power Supply Voltage Detection	Voltage detection circuit	<ul style="list-style-type: none"><li>• Power-on reset</li><li>• Voltage detection 3 (detection level of voltage detection 0 and voltage detection 1 selectable)</li></ul>
I/O Ports	Programmable I/O ports	<ul style="list-style-type: none"><li>• Input-only: 1 pin</li><li>• CMOS I/O ports: 75, selectable pull-up resistor</li><li>• High current drive ports: 75</li></ul>
Clock	Clock generation circuits	<ul style="list-style-type: none"><li>• 4 circuits: XIN clock oscillation circuit, XCIN clock oscillation circuit (32 kHz), High-speed on-chip oscillator (with frequency adjustment function), Low-speed on-chip oscillator</li><li>• Oscillation stop detection: XIN clock oscillation stop detection function</li><li>• Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16</li><li>• Low power consumption modes: Standard operating mode (high-speed clock, low-speed clock, high-speed on-chip oscillator, low-speed on-chip oscillator), wait mode, stop mode</li></ul>
		Real-time clock (timer RE)
Interrupts		<ul style="list-style-type: none"><li>• Interrupt Vectors: 69</li><li>• External: 9 sources (INT̄ × 5, key input × 4)</li><li>• Priority levels: 7 levels</li></ul>
Watchdog Timer		<ul style="list-style-type: none"><li>• 14 bits × 1 (with prescaler)</li><li>• Reset start selectable</li><li>• Low-speed on-chip oscillator for watchdog timer selectable</li></ul>
DTC (Data Transfer Controller)		<ul style="list-style-type: none"><li>• 1 channel</li><li>• Activation sources: 39</li><li>• Transfer modes: 2 (normal mode, repeat mode)</li></ul>
Timer	Timer RA	8 bits × 1 (with 8-bit prescaler) Timer mode (period timer), pulse output mode (output level inverted every period), event counter mode, pulse width measurement mode, pulse period measurement mode
	Timer RB	8 bits × 1 (with 8-bit prescaler) Timer mode (period timer), programmable waveform generation mode (PWM output), programmable one-shot generation mode, programmable wait one-shot generation mode
	Timer RC	16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin)
	Timer RD	16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period)

## 1.4 Pin Assignment

Figure 1.3 shows Pin Assignment (Top View). Tables 1.4 and 1.5 outline the Pin Name Information by Pin Number.



**Figure 1.3 Pin Assignment (Top View)**

**Table 1.5 Pin Name Information by Pin Number (2)**

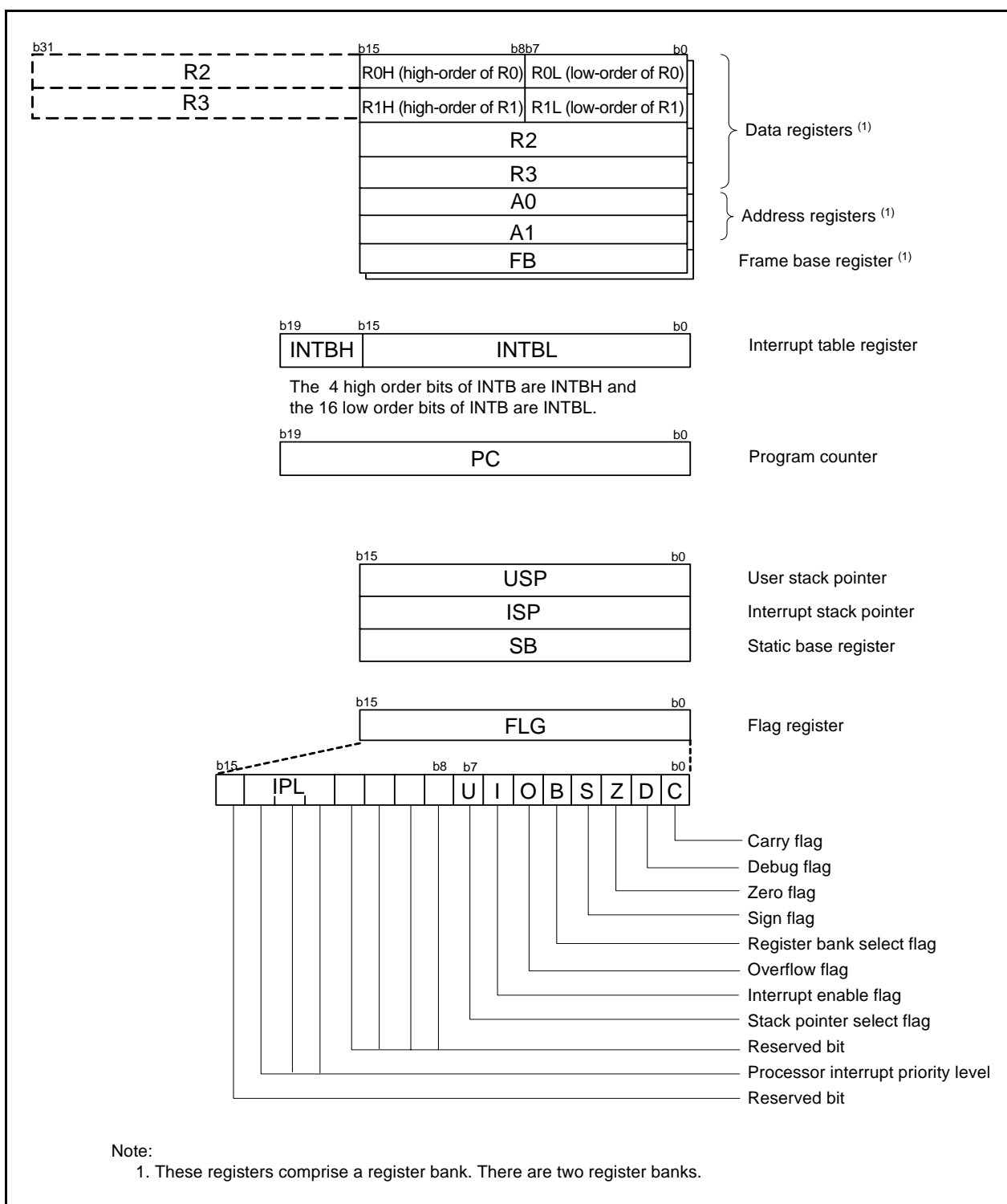
Pin Number	Control Pin	Port	I/O Pin Functions for Peripheral Modules					
			Interrupt	Timer	Serial Interface	SSU	I <sup>2</sup> C bus	A/D Converter, D/A Converter, Comparator B
41		P8_3		(TRFI/TRFO10)				
42		P8_2		(TRFO02)				
43		P8_1		(TRFO01)				
44		P8_0		(TRFO00)				
45		P6_7	(INT3)	(TRCIOD)				
46		P6_6	INT2	(TRCIOA)	(TXD2/SDA2)			
47		P6_5	INT4	(TRCIOB)	(CLK2/CLK1)			
48		P4_5	INT0		(RXD2/SCL2)			ADTRG
49		P1_7	INT1	(TRAIO)				IVCMP
50		P1_6			(CLK0)			IVREF1
51		P1_5	(INT1)	(TRAIO)	(RXD0)			
52		P1_4		(TRCCLK)	(TXD0)			
53		P1_3	KI3	TRBO/(TRCIOA)				AN11
54		P1_2	KI2	(TRCIOB)				AN10
55		P1_1	KI1	(TRCIOA/TRCTR)				AN9
56		P1_0	KI0	(TRCIOD)				AN8
57		P7_7						AN19
58		P7_6						AN18
59		P7_5						AN17
60		P7_4						AN16
61		P7_3						AN15
62		P7_2						AN14
63		P7_1						AN13
64		P7_0						AN12
65		P0_7		(TRCIOA)				AN0/DA1
66		P0_6		(TRCIOD)				AN1/DA0
67		P0_5		(TRCIOB)				AN2
68		P0_4		TREO/(TRCIOB)				AN3
69		P0_3		(TRCIOB)	(CLK1)			AN4
70		P0_2		(TRCIOA/TRCTR)	(RXD1)			AN5
71		P0_1		(TRCIOA/TRCTR)	(TXD1)			AN6
72		P0_0		(TRCIOA/TRCTR)				AN7
73		P6_4			(RXD1)			
74		P6_3			(TXD1)			
75		P6_2			(CLK1)			
76		P6_1						
77		P6_0		(TREO)				
78		P9_5						
79		P9_4						
80		P5_7		(TRGIOB)				

Note:

1. Can be assigned to the pin in parentheses by a program.

## 2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU Registers. The CPU contains 13 registers. R0, R1, R2, R3, A0, A1, and FB configure a register bank. There are two sets of register bank.



**Figure 2.1 CPU Registers**

## 2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

## 2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

## 2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

## 2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the starting address of an interrupt vector table.

## 2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

## 2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

## 2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

## 2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

### 2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

### 2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

### 2.8.3 Zero Flag (Z)

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

### 2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

### 2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

### 2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.

### **2.8.7 Interrupt Enable Flag (I)**

The I flag enables maskable interrupts.

Interrupts are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

### **2.8.8 Stack Pointer Select Flag (U)**

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1.

The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

### **2.8.9 Processor Interrupt Priority Level (IPL)**

IPL is 3 bits wide and assigns processor interrupt priority levels from level 0 to level 7.

If a requested interrupt has higher priority than IPL, the interrupt is enabled.

### **2.8.10 Reserved Bit**

If necessary, set to 0. When read, the content is undefined.

## 3. Memory

### 3.1 R8C/38C Group

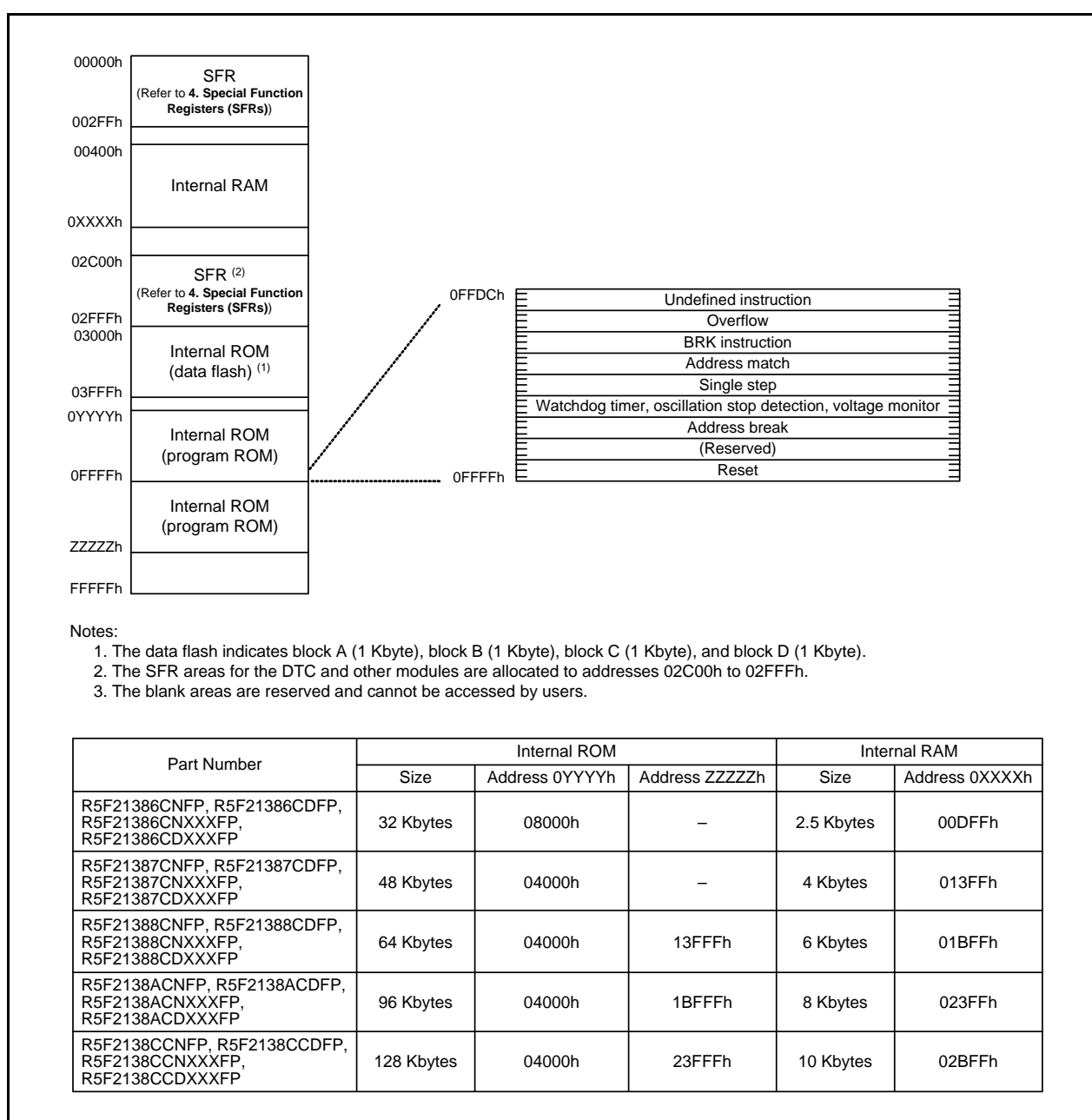
Figure 3.1 is a Memory Map of R8C/38C Group. The R8C/38C Group has a 1-Mbyte address space from addresses 00000h to FFFFFh. The internal ROM (program ROM) is allocated lower addresses, beginning with address 0FFFFh. For example, a 64-Kbyte internal ROM area is allocated addresses 04000h to 13FFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. The starting address of each interrupt routine is stored here.

The internal ROM (data flash) is allocated addresses 03000h to 03FFFh.

The internal RAM is allocated higher addresses, beginning with address 00400h. For example, a 6-Kbyte internal RAM area is allocated addresses 00400h to 01BFFh. The internal RAM is used not only for data storage but also as a stack area when a subroutine is called or when an interrupt request is acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh and 02C00h to 02FFFh (the SFR areas for the DTC and other modules). Peripheral function control registers are allocated here. All unallocated spaces within the SFRs are reserved and cannot be accessed by users.



**Figure 3.1 Memory Map of R8C/38C Group**

**Table 4.3 SFR Information (3) (1)**

Address	Register	Symbol	After Reset
0080h	DTC Activation Control Register	DTCTL	00h
0081h			
0082h			
0083h			
0084h			
0085h			
0086h			
0087h			
0088h	DTC Activation Enable Register 0	DTCEN0	00h
0089h	DTC Activation Enable Register 1	DTCEN1	00h
008Ah	DTC Activation Enable Register 2	DTCEN2	00h
008Bh	DTC Activation Enable Register 3	DTCEN3	00h
008Ch	DTC Activation Enable Register 4	DTCEN4	00h
008Dh	DTC Activation Enable Register 5	DTCEN5	00h
008Eh	DTC Activation Enable Register 6	DTCEN6	00h
008Fh			
0090h	Timer RF Register	TRF	00h
0091h			00h
0092h			
0093h			
0094h			
0095h			
0096h			
0097h			
0098h			
0099h			
009Ah	Timer RF Control Register 0	TRFCR0	00h
009Bh	Timer RF Control Register 1	TRFCR1	00h
009Ch	Capture and Compare 0 Register	TRFM0	00h
009Dh			00h
009Eh	Compare 1 Register	TRFM1	FFh
009Fh			FFh
00A0h	UART0 Transmit/Receive Mode Register	U0MR	00h
00A1h	UART0 Bit Rate Register	U0BRG	XXh
00A2h	UART0 Transmit Buffer Register	U0TB	XXh
00A3h			XXh
00A4h	UART0 Transmit/Receive Control Register 0	U0C0	00001000b
00A5h	UART0 Transmit/Receive Control Register 1	U0C1	00000010b
00A6h	UART0 Receive Buffer Register	U0RB	XXh
00A7h			XXh
00A8h	UART2 Transmit/Receive Mode Register	U2MR	00h
00A9h	UART2 Bit Rate Register	U2BRG	XXh
00AAh	UART2 Transmit Buffer Register	U2TB	XXh
00ABh			XXh
00ACh	UART2 Transmit/Receive Control Register 0	U2C0	00001000b
00ADh	UART2 Transmit/Receive Control Register 1	U2C1	00000010b
00AEh	UART2 Receive Buffer Register	U2RB	XXh
00AFh			XXh
00B0h	UART2 Digital Filter Function Select Register	URXDF	00h
00B1h			
00B2h			
00B3h			
00B4h			
00B5h			
00B6h			
00B7h			
00B8h			
00B9h			
00BAh			
00BBh	UART2 Special Mode Register 5	U2SMR5	00h
00BCh	UART2 Special Mode Register 4	U2SMR4	00h
00BDh	UART2 Special Mode Register 3	U2SMR3	000X0X0Xb
00BEh	UART2 Special Mode Register 2	U2SMR2	X0000000b
00BFh	UART2 Special Mode Register	U2SMR	X0000000b

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

**Table 4.5 SFR Information (5) (1)**

Address	Register	Symbol	After Reset
0100h	Timer RA Control Register	TRACR	00h
0101h	Timer RA I/O Control Register	TRAIOC	00h
0102h	Timer RA Mode Register	TRAMR	00h
0103h	Timer RA Prescaler Register	TRAPRE	FFh
0104h	Timer RA Register	TRA	FFh
0105h	LIN Control Register 2	LINCR2	00h
0106h	LIN Control Register	LINCR	00h
0107h	LIN Status Register	LINST	00h
0108h	Timer RB Control Register	TRBCR	00h
0109h	Timer RB One-Shot Control Register	TRBOCR	00h
010Ah	Timer RB I/O Control Register	TRBIOC	00h
010Bh	Timer RB Mode Register	TRBMR	00h
010Ch	Timer RB Prescaler Register	TRBPRES	FFh
010Dh	Timer RB Secondary Register	TRBSC	FFh
010Eh	Timer RB Primary Register	TRBPR	FFh
010Fh			
0110h			
0111h			
0112h			
0113h			
0114h			
0115h			
0116h			
0117h			
0118h	Timer RE Second Data Register / Counter Data Register	TRESEC	00h
0119h	Timer RE Minute Data Register / Compare Data Register	TREMIN	00h
011Ah	Timer RE Hour Data Register	TREHR	00h
011Bh	Timer RE Day of Week Data Register	TREWK	00h
011Ch	Timer RE Control Register 1	TRECR1	00h
011Dh	Timer RE Control Register 2	TRECR2	00h
011Eh	Timer RE Count Source Select Register	TRECSR	00001000b
011Fh			
0120h	Timer RC Mode Register	TRCMR	01001000b
0121h	Timer RC Control Register 1	TRCCR1	00h
0122h	Timer RC Interrupt Enable Register	TRCIER	01110000b
0123h	Timer RC Status Register	TRCSR	01110000b
0124h	Timer RC I/O Control Register 0	TRCIOR0	10001000b
0125h	Timer RC I/O Control Register 1	TRCIOR1	10001000b
0126h	Timer RC Counter	TRC	00h
0127h			00h
0128h	Timer RC General Register A	TRCGRA	FFh
0129h			FFh
012Ah	Timer RC General Register B	TRCGRB	FFh
012Bh			FFh
012Ch	Timer RC General Register C	TRCGRC	FFh
012Dh			FFh
012Eh	Timer RC General Register D	TRCGRD	FFh
012Fh			FFh
0130h	Timer RC Control Register 2	TRCCR2	00011000b
0131h	Timer RC Digital Filter Function Select Register	TRCDF	00h
0132h	Timer RC Output Master Enable Register	TRCOER	01111111b
0133h	Timer RC Trigger Control Register	TRCADCR	00h
0134h			
0135h	Timer RD Control Expansion Register	TRDECR	00h
0136h	Timer RD Trigger Control Register	TRDADC	00h
0137h	Timer RD Start Register	TRDSTR	11111100b
0138h	Timer RD Mode Register	TRDMR	00001110b
0139h	Timer RD PWM Mode Register	TRDPMR	10001000b
013Ah	Timer RD Function Control Register	TRDFCR	10000000b
013Bh	Timer RD Output Master Enable Register 1	TRDOER1	FFh
013Ch	Timer RD Output Master Enable Register 2	TRDOER2	01111111b
013Dh	Timer RD Output Control Register	TRDOCR	00h
013Eh	Timer RD Digital Filter Function Select Register 0	TRDDF0	00h
013Fh	Timer RD Digital Filter Function Select Register 1	TRDDF1	00h

Note:

1. The blank areas are reserved and cannot be accessed by users.

**Table 4.6 SFR Information (6) (1)**

Address	Register	Symbol	After Reset
0140h	Timer RD Control Register 0	TRDCR0	00h
0141h	Timer RD I/O Control Register A0	TRDIOA0	10001000b
0142h	Timer RD I/O Control Register C0	TRDIORC0	10001000b
0143h	Timer RD Status Register 0	TRDSR0	11100000b
0144h	Timer RD Interrupt Enable Register 0	TRDIER0	11100000b
0145h	Timer RD PWM Mode Output Level Control Register 0	TRDPOCR0	11111000b
0146h	Timer RD Counter 0	TRD0	00h
0147h			00h
0148h	Timer RD General Register A0	TRDGRA0	FFh
0149h			FFh
014Ah	Timer RD General Register B0	TRDGRB0	FFh
014Bh			FFh
014Ch	Timer RD General Register C0	TRDGRC0	FFh
014Dh			FFh
014Eh	Timer RD General Register D0	TRDGRD0	FFh
014Fh			FFh
0150h	Timer RD Control Register 1	TRDCR1	00h
0151h	Timer RD I/O Control Register A1	TRDIOA1	10001000b
0152h	Timer RD I/O Control Register C1	TRDIORC1	10001000b
0153h	Timer RD Status Register 1	TRDSR1	11000000b
0154h	Timer RD Interrupt Enable Register 1	TRDIER1	11100000b
0155h	Timer RD PWM Mode Output Level Control Register 1	TRDPOCR1	11111000b
0156h	Timer RD Counter 1	TRD1	00h
0157h			00h
0158h	Timer RD General Register A1	TRDGRA1	FFh
0159h			FFh
015Ah	Timer RD General Register B1	TRDGRB1	FFh
015Bh			FFh
015Ch	Timer RD General Register C1	TRDGRC1	FFh
015Dh			FFh
015Eh	Timer RD General Register D1	TRDGRD1	FFh
015Fh			FFh
0160h	UART1 Transmit/Receive Mode Register	U1MR	00h
0161h	UART1 Bit Rate Register	U1BRG	XXh
0162h	UART1 Transmit Buffer Register	U1TB	XXh
0163h			XXh
0164h	UART1 Transmit/Receive Control Register 0	U1C0	00001000b
0165h	UART1 Transmit/Receive Control Register 1	U1C1	00000010b
0166h	UART1 Receive Buffer Register	U1RB	XXh
0167h			XXh
0168h			
0169h			
016Ah			
016Bh			
016Ch			
016Dh			
016Eh			
016Fh			
0170h	Timer RG Mode Register	TRGMR	01000000b
0171h	Timer RG Count Control Register	TRGCNTC	00h
0172h	Timer RG Control Register	TRGCR	10000000b
0173h	Timer RG Interrupt Enable Register	TRGIER	11110000b
0174h	Timer RG Status Register	TRGSR	11100000b
0175h	Timer RG I/O Control Register	TRGIOR	00h
0176h	Timer RG Counter	TRG	00h
0177h			00h
0178h	Timer RG General Register A	TRGGRA	FFh
0179h			FFh
017Ah	Timer RG General Register B	TRGGRB	FFh
017Bh			FFh
017Ch	Timer RG General Register C	TRGGRC	FFh
017Dh			FFh
017Eh	Timer RG General Register D	TRGGRD	FFh
017Fh			FFh

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

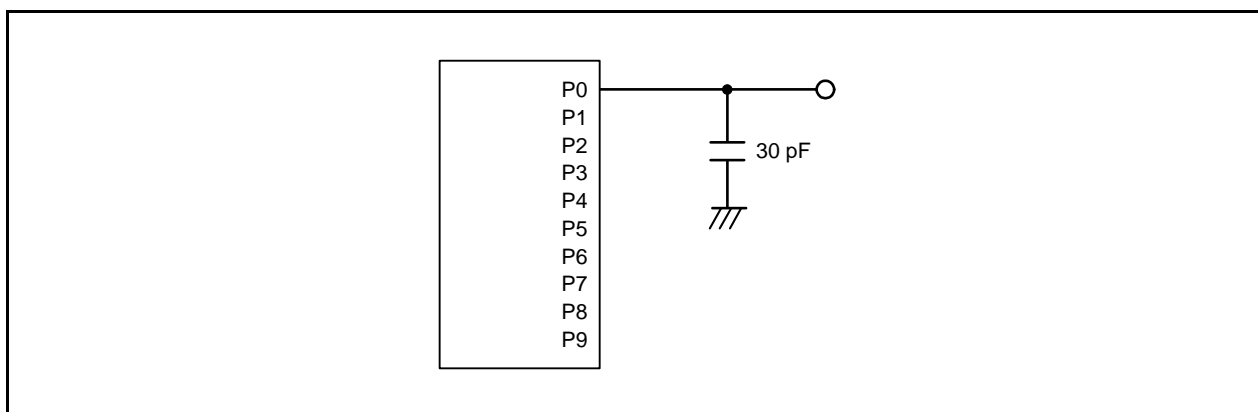
**Table 4.10 SFR Information (10) (1)**

Address	Register	Symbol	After Reset
2C70h	DTC Control Data 6	DTCD6	XXh
2C71h			XXh
2C72h			XXh
2C73h			XXh
2C74h			XXh
2C75h			XXh
2C76h			XXh
2C77h			XXh
2C78h	DTC Control Data 7	DTCD7	XXh
2C79h			XXh
2C7Ah			XXh
2C7Bh			XXh
2C7Ch			XXh
2C7Dh			XXh
2C7Eh			XXh
2C7Fh			XXh
2C80h	DTC Control Data 8	DTCD8	XXh
2C81h			XXh
2C82h			XXh
2C83h			XXh
2C84h			XXh
2C85h			XXh
2C86h			XXh
2C87h			XXh
2C88h	DTC Control Data 9	DTCD9	XXh
2C89h			XXh
2C8Ah			XXh
2C8Bh			XXh
2C8Ch			XXh
2C8Dh			XXh
2C8Eh			XXh
2C8Fh			XXh
2C90h	DTC Control Data 10	DTCD10	XXh
2C91h			XXh
2C92h			XXh
2C93h			XXh
2C94h			XXh
2C95h			XXh
2C96h			XXh
2C97h			XXh
2C98h	DTC Control Data 11	DTCD11	XXh
2C99h			XXh
2C9Ah			XXh
2C9Bh			XXh
2C9Ch			XXh
2C9Dh			XXh
2C9Eh			XXh
2C9Fh			XXh
2CA0h	DTC Control Data 12	DTCD12	XXh
2CA1h			XXh
2CA2h			XXh
2CA3h			XXh
2CA4h			XXh
2CA5h			XXh
2CA6h			XXh
2CA7h			XXh
2CA8h	DTC Control Data 13	DTCD13	XXh
2CA9h			XXh
2CAAh			XXh
2CABh			XXh
2CACH			XXh
2CADh			XXh
2CAEh			XXh
2CAFh			XXh

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.



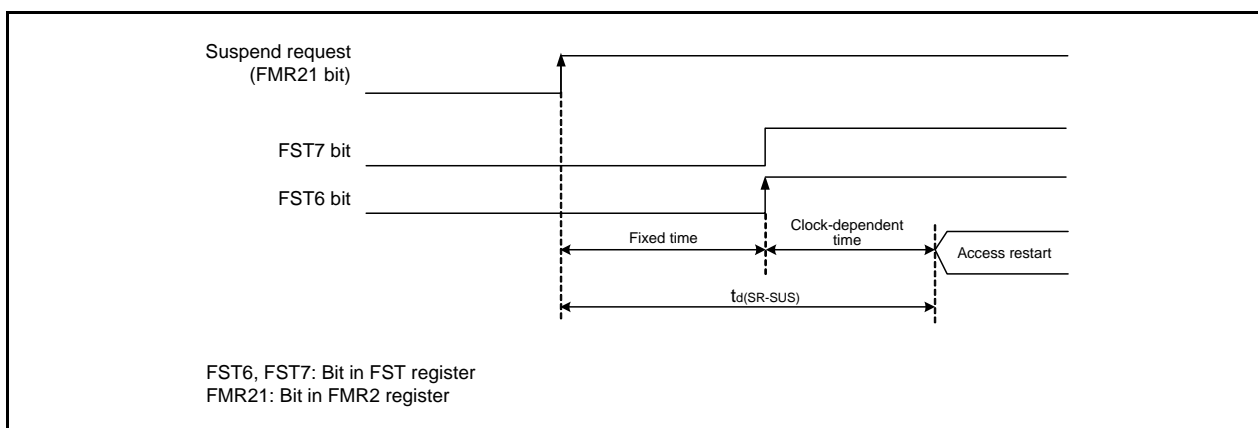
**Figure 5.1** Ports P0 to P9 Timing Measurement Circuit

**Table 5.7 Flash Memory (Data flash Block A to Block D) Electrical Characteristics**

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
—	Program/erase endurance <sup>(2)</sup>		10,000 <sup>(3)</sup>	—	—	times
—	Byte program time (program/erase endurance ≤ 1,000 times)		—	160	1500	μs
—	Byte program time (program/erase endurance > 1,000 times)		—	300	1500	μs
—	Block erase time (program/erase endurance ≤ 1,000 times)		—	0.2	1	s
—	Block erase time (program/erase endurance > 1,000 times)		—	0.3	1	s
t <sub>d</sub> (SR-SUS)	Time delay from suspend request until suspend		—	—	5 + CPU clock × 3 cycles	ms
—	Interval from erase start/restart until following suspend request		0	—	—	μs
—	Time from suspend until erase restart		—	—	30 + CPU clock × 1 cycle	μs
t <sub>d</sub> (CMDRST-READY)	Time from when command is forcibly stopped until reading is enabled		—	—	30 + CPU clock × 1 cycle	μs
—	Program, erase voltage		2.7	—	5.5	V
—	Read voltage		1.8	—	5.5	V
—	Program, erase temperature		−20 <sup>(7)</sup>	—	85	°C
—	Data hold time <sup>(8)</sup>	Ambient temperature = 55 °C	20	—	—	year

**Notes:**

- V<sub>CC</sub> = 2.7 to 5.5 V and T<sub>opr</sub> = −20 to 85 °C (N version)/−40 to 85 °C (D version), unless otherwise specified.
- Definition of programming/erasure endurance  
The programming and erasure endurance is defined on a per-block basis.  
If the programming and erasure endurance is n (n = 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to different addresses in block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one. However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
- Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed.)
- In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. In addition, averaging the erasure endurance between blocks A to D can further reduce the actual erasure endurance. It is also advisable to retain data on the erasure endurance of each block and limit the number of erase operations to a certain number.
- If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
- Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
- −40 °C for D version.
- The data hold time includes time that the power supply is off or the clock is not supplied.

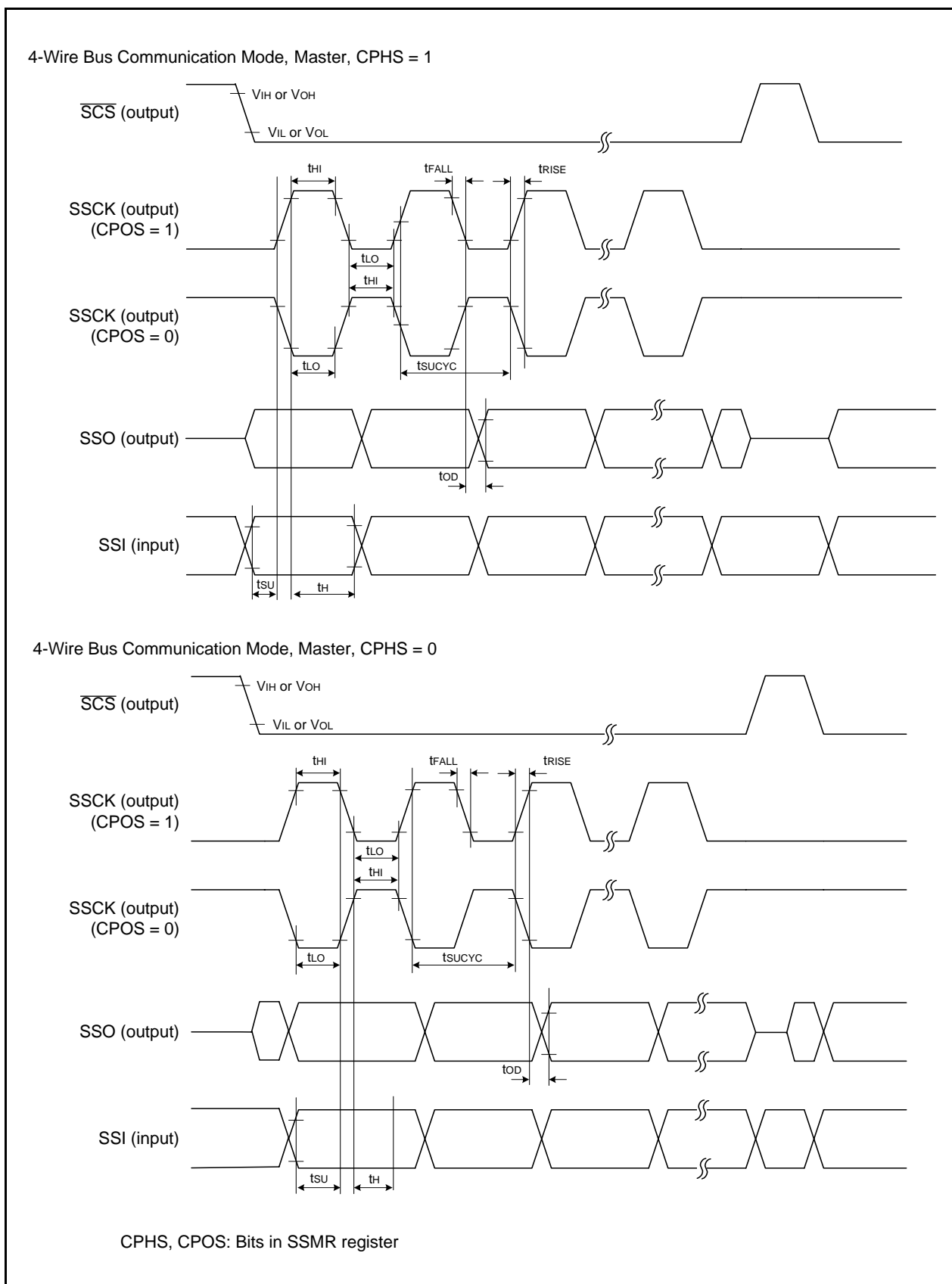
**Figure 5.2 Time delay until Suspend**

**Table 5.15 Timing Requirements of Synchronous Serial Communication Unit (SSU)**

Symbol	Parameter		Conditions	Standard			Unit
				Min.	Typ.	Max.	
tsucyc	SSCK clock cycle time			4	—	—	tcyc (2)
tHI	SSCK clock "H" width			0.4	—	0.6	tsucyc
tLO	SSCK clock "L" width			0.4	—	0.6	tsucyc
tRISE	SSCK clock rising time	Master		—	—	1	tcyc (2)
		Slave		—	—	1	μs
tFALL	SSCK clock falling time	Master		—	—	1	tcyc (2)
		Slave		—	—	1	μs
tsu	SSO, SSI data input setup time			100	—	—	ns
tH	SSO, SSI data input hold time			1	—	—	tcyc (2)
tLEAD	SCS setup time	Slave		1tcyc + 50	—	—	ns
tLAG	SCS hold time	Slave		1tcyc + 50	—	—	ns
tOD	SSO, SSI data output delay time			—	—	1	tcyc (2)
tsA	SSI slave access time		$2.7\text{ V} \leq V_{CC} \leq 5.5\text{ V}$	—	—	$1.5tcyc + 100$	ns
			$1.8\text{ V} \leq V_{CC} < 2.7\text{ V}$	—	—	$1.5tcyc + 200$	ns
toR	SSI slave out open time		$2.7\text{ V} \leq V_{CC} \leq 5.5\text{ V}$	—	—	$1.5tcyc + 100$	ns
			$1.8\text{ V} \leq V_{CC} < 2.7\text{ V}$	—	—	$1.5tcyc + 200$	ns

**Notes:**

1.  $V_{CC} = 1.8$  to  $5.5\text{ V}$ ,  $V_{SS} = 0\text{ V}$ , and  $T_{opr} = -20$  to  $85\text{ °C}$  (N version)/ $-40$  to  $85\text{ °C}$  (D version), unless otherwise specified.
2.  $1tcyc = 1/f_1(s)$



**Figure 5.4 I/O Timing of Synchronous Serial Communication Unit (SSU) (Master)**

**Table 5.17 Electrical Characteristics (1) [4.2 V ≤ V<sub>CC</sub> ≤ 5.5 V]**

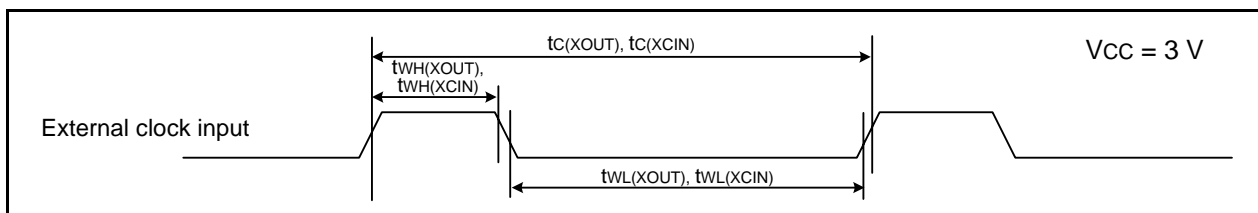
Symbol	Parameter		Condition		Standard			Unit
					Min.	Typ.	Max.	
V <sub>OH</sub>	Output "H" voltage	Other than XOUT	Drive capacity High V <sub>CC</sub> = 5 V	I <sub>OH</sub> = -20 mA	V <sub>CC</sub> - 2.0	—	V <sub>CC</sub>	V
			Drive capacity Low V <sub>CC</sub> = 5 V	I <sub>OH</sub> = -5 mA	V <sub>CC</sub> - 2.0	—	V <sub>CC</sub>	V
		XOUT	V <sub>CC</sub> = 5 V	I <sub>OH</sub> = -200 μA	1.0	—	V <sub>CC</sub>	V
V <sub>OL</sub>	Output "L" voltage	Other than XOUT	Drive capacity High V <sub>CC</sub> = 5 V	I <sub>OL</sub> = 20 mA	—	—	2.0	V
			Drive capacity Low V <sub>CC</sub> = 5 V	I <sub>OL</sub> = 5 mA	—	—	2.0	V
		XOUT	V <sub>CC</sub> = 5 V	I <sub>OL</sub> = 200 μA	—	—	0.5	V
V <sub>T+</sub> -V <sub>T-</sub>	Hysteresis	INT0, INT1, INT2, INT3, INT4, KI0, KI1, KI2, KI3, TRAIO, TRBO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRDIOA0, TRDIOB0, TRDIOC0, TRDIOD0, TRDIOA1, TRDIOB1, TRDIOC1, TRDIOD1, TRCTRG, TRCCLK, TRFI, TRGIOA, TRGIOB, ADTRG, RXD0, RXD1, RXD2, CLK0, CLK1, CLK2, SSI, SCL, SDA, SSO			0.1	1.2	—	V
		RESET			0.1	1.2	—	V
I <sub>IH</sub>	Input "H" current		V <sub>I</sub> = 5 V, V <sub>CC</sub> = 5.0 V		—	—	5.0	μA
I <sub>IL</sub>	Input "L" current		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 5.0 V		—	—	-5.0	μA
R <sub>PULLUP</sub>	Pull-up resistance		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 5.0 V		25	50	100	kΩ
R <sub>FXIN</sub>	Feedback resistance	XIN			—	0.3	—	MΩ
R <sub>FXCIN</sub>	Feedback resistance	XCIN			—	8	—	MΩ
V <sub>RAM</sub>	RAM hold voltage		During stop mode		1.8	—	—	V

Note:

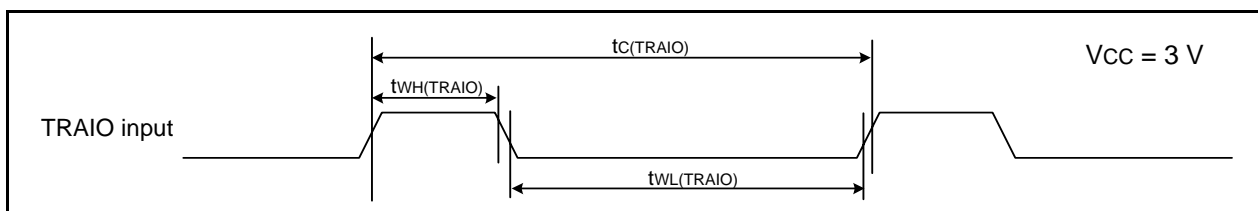
1. 4.2 V ≤ V<sub>CC</sub> ≤ 5.5 V, T<sub>opr</sub> = -20 to 85 °C (N version)/-40 to 85 °C (D version), and f(XIN) = 20 MHz, unless otherwise specified.

**Timing requirements** (Unless Otherwise Specified:  $V_{CC} = 3\text{ V}$ ,  $V_{SS} = 0\text{ V}$ ,  $T_{opr} = 25\text{ }^{\circ}\text{C}$ )**Table 5.26 External Clock Input (XOUT, XCIN)**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{XOUT})$	XOUT input cycle time	50	—	ns
$t_{WH}(\text{XOUT})$	XOUT input "H" width	24	—	ns
$t_{WL}(\text{XOUT})$	XOUT input "L" width	24	—	ns
$t_c(\text{XCIN})$	XCIN input cycle time	14	—	$\mu\text{s}$
$t_{WH}(\text{XCIN})$	XCIN input "H" width	7	—	$\mu\text{s}$
$t_{WL}(\text{XCIN})$	XCIN input "L" width	7	—	$\mu\text{s}$

**Figure 5.13 External Clock Input Timing Diagram when  $V_{CC} = 3\text{ V}$** **Table 5.27 TRAIO Input**

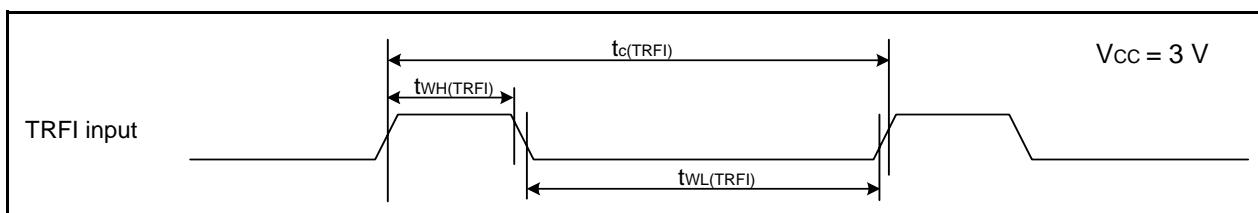
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{TRAIO})$	TRAIO input cycle time	300	—	ns
$t_{WH}(\text{TRAIO})$	TRAIO input "H" width	120	—	ns
$t_{WL}(\text{TRAIO})$	TRAIO input "L" width	120	—	ns

**Figure 5.14 TRAIO Input Timing Diagram when  $V_{CC} = 3\text{ V}$** **Table 5.28 TRFI Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{TRFI})$	TRFI input cycle time	1200 (1)	—	ns
$t_{WH}(\text{TRFI})$	TRFI input "H" width	600 (2)	—	ns
$t_{WL}(\text{TRFI})$	TRFI input "L" width	600 (2)	—	ns

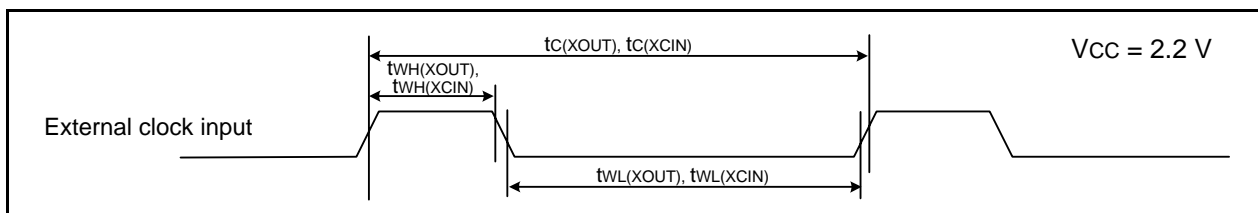
Notes:

1. When using timer RF input capture mode, adjust the cycle time to  $(1/\text{timer RF count source frequency} \times 3)$  or above.
2. When using timer RF input capture mode, adjust the pulse width to  $(1/\text{timer RF count source frequency} \times 1.5)$  or above.

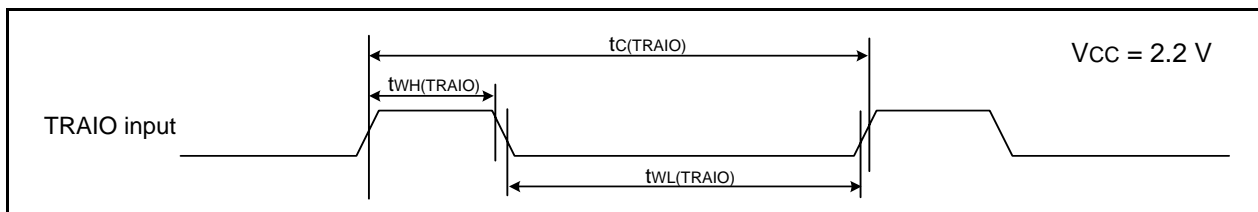
**Figure 5.15 TRFI Input Timing Diagram when  $V_{CC} = 3\text{ V}$**

**Timing requirements** (Unless Otherwise Specified:  $V_{CC} = 2.2\text{ V}$ ,  $V_{SS} = 0\text{ V}$ ,  $T_{opr} = 25\text{ }^{\circ}\text{C}$ )**Table 5.33 External Clock Input (XOUT, XCIN)**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{XOUT})$	XOUT input cycle time	200	—	ns
$t_{WH}(\text{XOUT})$	XOUT input "H" width	90	—	ns
$t_{WL}(\text{XOUT})$	XOUT input "L" width	90	—	ns
$t_c(\text{XCIN})$	XCIN input cycle time	14	—	$\mu\text{s}$
$t_{WH}(\text{XCIN})$	XCIN input "H" width	7	—	$\mu\text{s}$
$t_{WL}(\text{XCIN})$	XCIN input "L" width	7	—	$\mu\text{s}$

**Figure 5.18 External Clock Input Timing Diagram when  $V_{CC} = 2.2\text{ V}$** **Table 5.34 TRAIO Input**

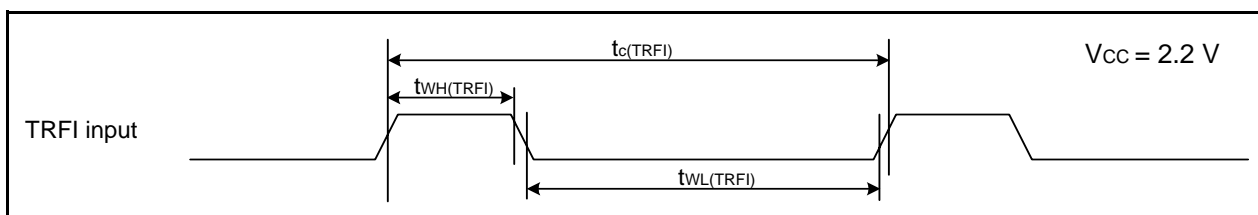
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{TRAIO})$	TRAIO input cycle time	500	—	ns
$t_{WH}(\text{TRAIO})$	TRAIO input "H" width	200	—	ns
$t_{WL}(\text{TRAIO})$	TRAIO input "L" width	200	—	ns

**Figure 5.19 TRAIO Input Timing Diagram when  $V_{CC} = 2.2\text{ V}$** **Table 5.35 TRFI Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{TRFI})$	TRFI input cycle time	2000 (1)	—	ns
$t_{WH}(\text{TRFI})$	TRFI input "H" width	1000 (2)	—	ns
$t_{WL}(\text{TRFI})$	TRFI input "L" width	1000 (2)	—	ns

**Notes:**

1. When using timer RF input capture mode, adjust the cycle time to  $(1/\text{timer RF count source frequency} \times 3)$  or above.
2. When using timer RF input capture mode, adjust the pulse width to  $(1/\text{timer RF count source frequency} \times 1.5)$  or above.

**Figure 5.20 TRFI Input Timing Diagram when  $V_{CC} = 2.2\text{ V}$**

## General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

### 1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

### 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

### 5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

- The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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