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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

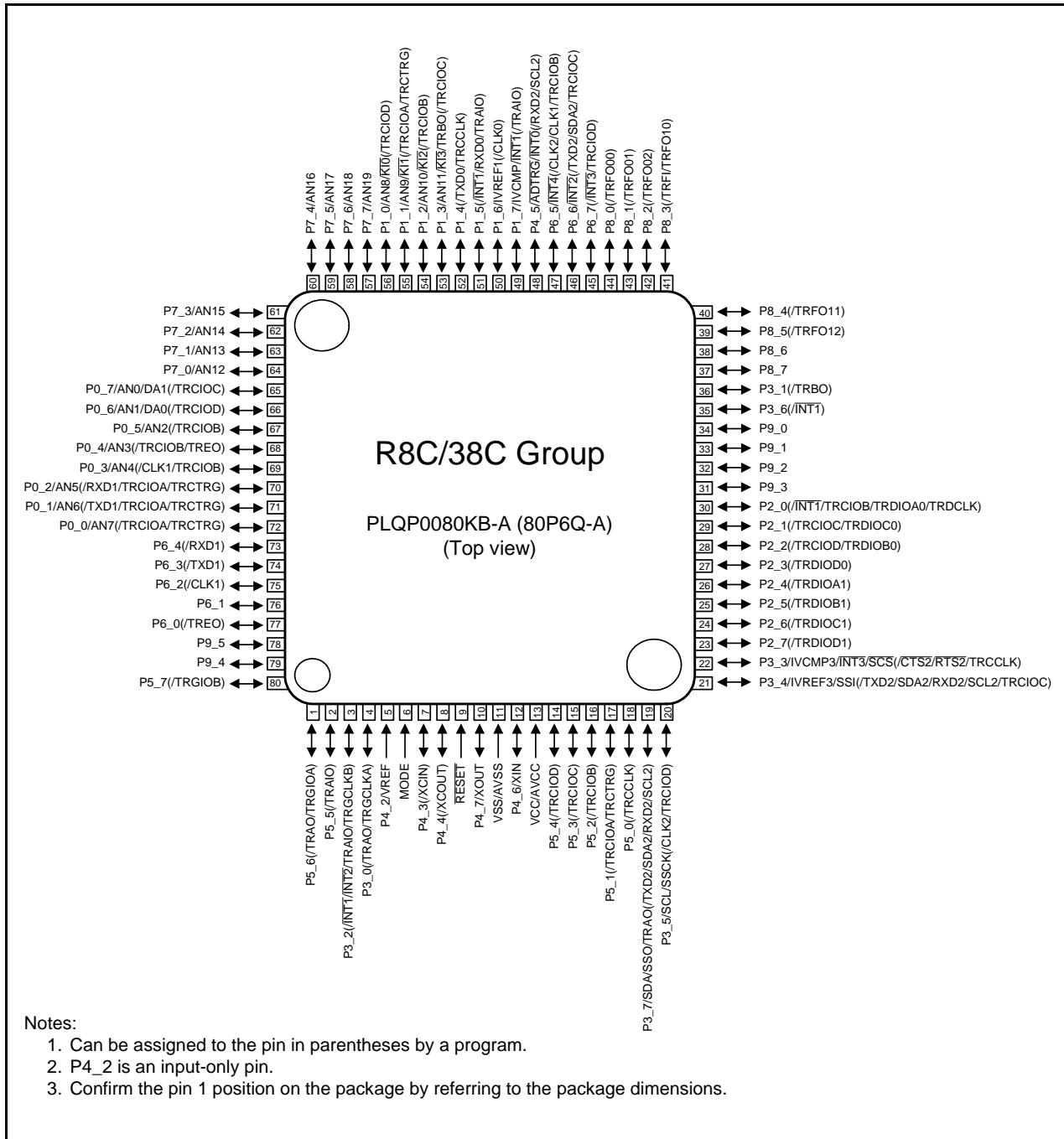
#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Obsolete
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	I²C, LINbus, SIO, SSU, UART/USART
Peripherals	POR, PWM, Voltage Detect, WDT
Number of I/O	75
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	2.5K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 20x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-LQFP (12x12)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f21386cdfp-v0">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f21386cdfp-v0</a>

## 1.4 Pin Assignment

Figure 1.3 shows Pin Assignment (Top View). Tables 1.4 and 1.5 outline the Pin Name Information by Pin Number.



**Figure 1.3 Pin Assignment (Top View)**

**Table 1.7 Pin Functions (2)**

Item	Pin Name	I/O Type	Description
SSU	SSI	I/O	Data I/O pin.
	SCS	I/O	Chip-select signal I/O pin.
	SSCK	I/O	Clock I/O pin.
	SSO	I/O	Data I/O pin.
I <sup>2</sup> C bus	SCL	I/O	Clock I/O pin
	SDA	I/O	Data I/O pin
Reference voltage input	VREF	I	Reference voltage input pin to A/D converter.
A/D converter	AN0 to AN19	I	Analog input pins to A/D converter.
	ADTRG	I	AD external trigger input pin.
D/A converter	DA0, DA1	O	D/A converter output pins.
Comparator B	IVCMP1, IVCMP3	I	Comparator B analog voltage input pins.
	IVREF1, IVREF3	I	Comparator B reference voltage input pins.
I/O port	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_3 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_5	I/O	CMOS I/O ports. Each port has an I/O select direction register, allowing each pin in the port to be directed for input or output individually. Any port set to input can be set to use a pull-up resistor or not by a program.
Input port	P4_2	I	Input-only port.

I: Input

O: Output

I/O: Input and output

### 2.8.7 Interrupt Enable Flag (I)

The I flag enables maskable interrupts.

Interrupts are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

### 2.8.8 Stack Pointer Select Flag (U)

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1.

The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

### 2.8.9 Processor Interrupt Priority Level (IPL)

IPL is 3 bits wide and assigns processor interrupt priority levels from level 0 to level 7.

If a requested interrupt has higher priority than IPL, the interrupt is enabled.

### 2.8.10 Reserved Bit

If necessary, set to 0. When read, the content is undefined.

### 3. Memory

#### 3.1 R8C/38C Group

Figure 3.1 is a Memory Map of R8C/38C Group. The R8C/38C Group has a 1-Mbyte address space from addresses 00000h to FFFFFh. The internal ROM (program ROM) is allocated lower addresses, beginning with address 0FFFFh. For example, a 64-Kbyte internal ROM area is allocated addresses 04000h to 13FFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. The starting address of each interrupt routine is stored here.

The internal ROM (data flash) is allocated addresses 03000h to 03FFFh.

The internal RAM is allocated higher addresses, beginning with address 00400h. For example, a 6-Kbyte internal RAM area is allocated addresses 00400h to 01BFFh. The internal RAM is used not only for data storage but also as a stack area when a subroutine is called or when an interrupt request is acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh and 02C00h to 02FFFh (the SFR areas for the DTC and other modules). Peripheral function control registers are allocated here. All unallocated spaces within the SFRs are reserved and cannot be accessed by users.

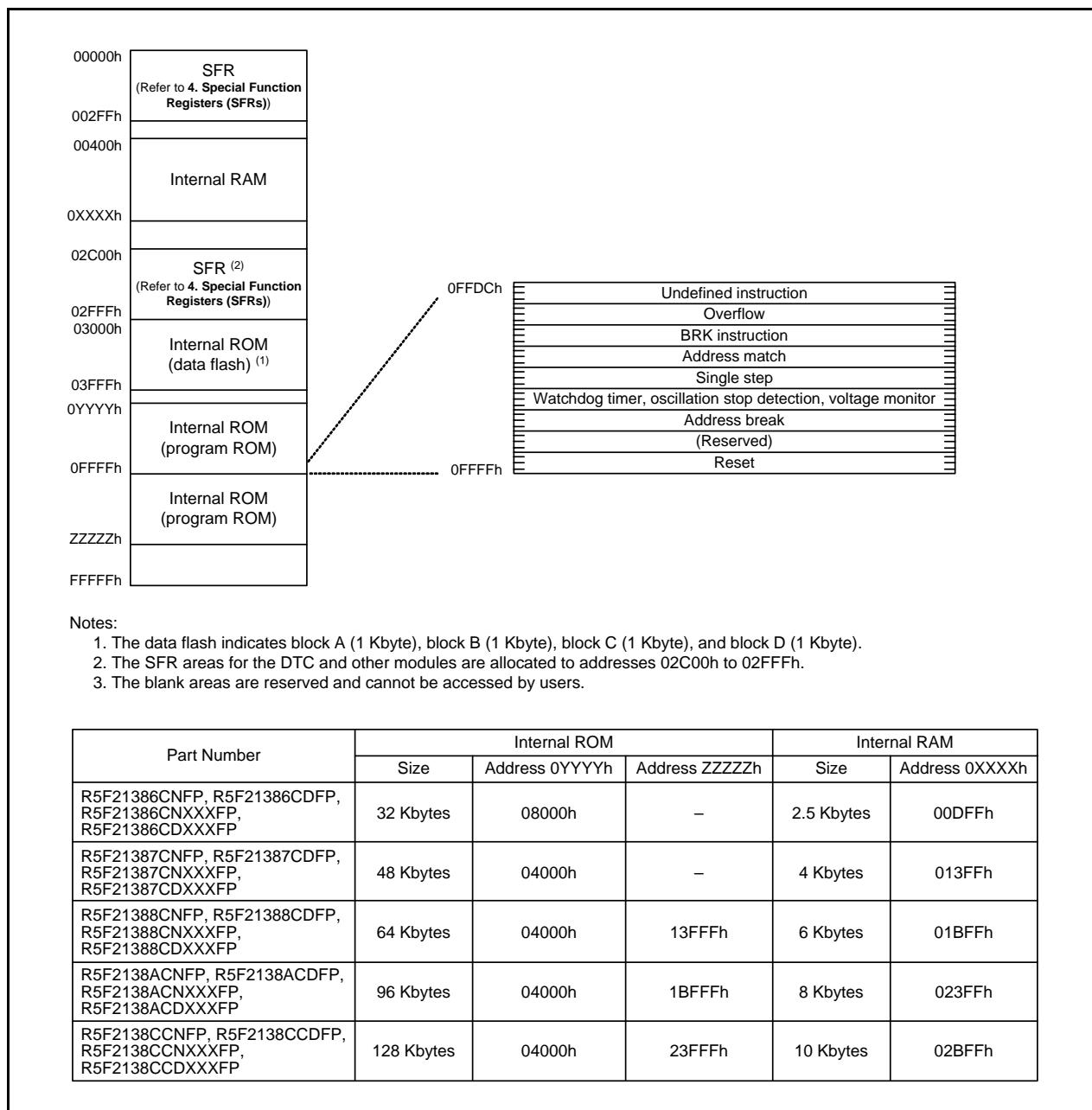


Figure 3.1 Memory Map of R8C/38C Group

**Table 4.4 SFR Information (4) (1)**

Address	Register	Symbol	After Reset
00C0h	A/D Register 0	AD0	XXh 000000XXb
00C1h			
00C2h	A/D Register 1	AD1	XXh 000000XXb
00C3h			
00C4h	A/D Register 2	AD2	XXh 000000XXb
00C5h			
00C6h	A/D Register 3	AD3	XXh 000000XXb
00C7h			
00C8h	A/D Register 4	AD4	XXh 000000XXb
00C9h			
00CAh	A/D Register 5	AD5	XXh 000000XXb
00CBh			
00CCh	A/D Register 6	AD6	XXh 000000XXb
00CDh			
00CEh	A/D Register 7	AD7	XXh 000000XXb
00CFh			
00D0h			
00D1h			
00D2h			
00D3h			
00D4h	A/D Mode Register	ADMOD	00h
00D5h	A/D Input Select Register	ADINSEL	11000000b
00D6h	A/D Control Register 0	ADCON0	00h
00D7h	A/D Control Register 1	ADCON1	00h
00D8h	D/A0 Register	DA0	00h
00D9h	D/A1 Register	DA1	00h
00DAh			
00DBh			
00DCh	D/A Control Register	DACON	00h
00DDh			
00DEh			
00DFh			
00E0h	Port P0 Register	P0	XXh
00E1h	Port P1 Register	P1	XXh
00E2h	Port P0 Direction Register	PD0	00h
00E3h	Port P1 Direction Register	PD1	00h
00E4h	Port P2 Register	P2	XXh
00E5h	Port P3 Register	P3	XXh
00E6h	Port P2 Direction Register	PD2	00h
00E7h	Port P3 Direction Register	PD3	00h
00E8h	Port P4 Register	P4	XXh
00E9h	Port P5 Register	P5	XXh
00EAh	Port P4 Direction Register	PD4	00h
00EBh	Port P5 Direction Register	PD5	00h
00ECb	Port P6 Register	P6	XXh
00EDh	Port P7 Register	P7	XXh
00EEh	Port P6 Direction Register	PD6	00h
00EFh	Port P7 Direction Register	PD7	00h
00F0h	Port P8 Register	P8	XXh
00F1h	Port P9 Register	P9	XXh
00F2h	Port P8 Direction Register	PD8	00h
00F3h	Port P9 Direction Register	PD9	00h
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCb			
00FDh			
00FEh			
00FFh			

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

**Table 4.6 SFR Information (6) (1)**

Address	Register	Symbol	After Reset
0140h	Timer RD Control Register 0	TRDCR0	00h
0141h	Timer RD I/O Control Register A0	TRDIORA0	10001000b
0142h	Timer RD I/O Control Register C0	TRDIORC0	10001000b
0143h	Timer RD Status Register 0	TRDSR0	11100000b
0144h	Timer RD Interrupt Enable Register 0	TRDIER0	11100000b
0145h	Timer RD PWM Mode Output Level Control Register 0	TRDPOCR0	11111000b
0146h	Timer RD Counter 0	TRD0	00h 00h
0147h			
0148h	Timer RD General Register A0	TRDGRA0	FFh
0149h			FFh
014Ah	Timer RD General Register B0	TRDGRB0	FFh
014Bh			FFh
014Ch	Timer RD General Register C0	TRDGRC0	FFh
014Dh			FFh
014Eh	Timer RD General Register D0	TRDGRD0	FFh
014Fh			FFh
0150h	Timer RD Control Register 1	TRDCR1	00h
0151h	Timer RD I/O Control Register A1	TRDIORA1	10001000b
0152h	Timer RD I/O Control Register C1	TRDIORC1	10001000b
0153h	Timer RD Status Register 1	TRDSR1	11000000b
0154h	Timer RD Interrupt Enable Register 1	TRDIER1	11100000b
0155h	Timer RD PWM Mode Output Level Control Register 1	TRDPOCR1	11111000b
0156h	Timer RD Counter 1	TRD1	00h 00h
0157h			
0158h	Timer RD General Register A1	TRDGRA1	FFh
0159h			FFh
015Ah	Timer RD General Register B1	TRDGRB1	FFh
015Bh			FFh
015Ch	Timer RD General Register C1	TRDGRC1	FFh
015Dh			FFh
015Eh	Timer RD General Register D1	TRDGRD1	FFh
015Fh			FFh
0160h	UART1 Transmit/Receive Mode Register	U1MR	00h
0161h	UART1 Bit Rate Register	U1BRG	XXh
0162h	UART1 Transmit Buffer Register	U1TB	XXh
0163h			XXh
0164h	UART1 Transmit/Receive Control Register 0	U1C0	00001000b
0165h	UART1 Transmit/Receive Control Register 1	U1C1	00000010b
0166h	UART1 Receive Buffer Register	U1RB	XXh
0167h			XXh
0168h			
0169h			
016Ah			
016Bh			
016Ch			
016Dh			
016Eh			
016Fh			
0170h	Timer RG Mode Register	TRGMR	01000000b
0171h	Timer RG Count Control Register	TRGCNTC	00h
0172h	Timer RG Control Register	TRGCR	10000000b
0173h	Timer RG Interrupt Enable Register	TRGIER	11110000b
0174h	Timer RG Status Register	TRGSR	11100000b
0175h	Timer RG I/O Control Register	TRGIOR	00h
0176h	Timer RG Counter	TRG	00h 00h
0177h			
0178h	Timer RG General Register A	TRGGRA	FFh
0179h			FFh
017Ah	Timer RG General Register B	TRGGRB	FFh
017Bh			FFh
017Ch	Timer RG General Register C	TRGGRC	FFh
017Dh			FFh
017Eh	Timer RG General Register D	TRGGRD	FFh
017Fh			FFh

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

**Table 4.8 SFR Information (8) (1)**

Address	Register	Symbol	After Reset
01C0h	Address Match Interrupt Register 0	RMAD0	XXh XXh 0000XXXXb
01C1h			
01C2h			
01C3h	Address Match Interrupt Enable Register 0	AIER0	00h
01C4h	Address Match Interrupt Register 1	RMAD1	XXh XXh 0000XXXXb
01C5h			
01C6h			
01C7h	Address Match Interrupt Enable Register 1	AIER1	00h
01C8h			
01C9h			
01CAh			
01CBh			
01CCh			
01CDh			
01CEh			
01CFh			
01D0h			
01D1h			
01D2h			
01D3h			
01D4h			
01D5h			
01D6h			
01D7h			
01D8h			
01D9h			
01DAh			
01DBh			
01DCh			
01DDh			
01DEh			
01DFh			
01E0h	Pull-Up Control Register 0	PUR0	00h
01E1h	Pull-Up Control Register 1	PUR1	00h
01E2h	Pull-Up Control Register 2	PUR2	00h
01E3h			
01E4h			
01E5h			
01E6h			
01E7h			
01E8h			
01E9h			
01EAh			
01EBh			
01ECb			
01EDh			
01EEh			
01EFh			
01F0h	Port P1 Drive Capacity Control Register	P1DRR	00h
01F1h	Port P2 Drive Capacity Control Register	P2DRR	00h
01F2h	Drive Capacity Control Register 0	DRR0	00h
01F3h	Drive Capacity Control Register 1	DRR1	00h
01F4h	Drive Capacity Control Register 2	DRR2	00h
01F5h	Input Threshold Control Register 0	VLT0	00h
01F6h	Input Threshold Control Register 1	VLT1	00h
01F7h	Input Threshold Control Register 2	VLT2	00h
01F8h	Comparator B Control Register 0	INTCMP	00h
01F9h			
01FAh	External Input Enable Register 0	INTEN	00h
01FBh	External Input Enable Register 1	INTEN1	00h
01FCb	INT Input Filter Select Register 0	INTF	00h
01FDh	INT Input Filter Select Register 1	INTF1	00h
01FEh	Key Input Enable Register 0	KIEN	00h
01FFh			

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

**Table 4.11 SFR Information (11) (1)**

Address	Register	Symbol	After Reset
2CB0h	DTC Control Data 14	DTCD14	XXh
2CB1h			XXh
2CB2h			XXh
2CB3h			XXh
2CB4h			XXh
2CB5h			XXh
2CB6h			XXh
2CB7h			XXh
2CB8h	DTC Control Data 15	DTCD15	XXh
2CB9h			XXh
2CBAh			XXh
2CBBh			XXh
2CBCh			XXh
2CBDh			XXh
2CBEh			XXh
2CBFh			XXh
2CC0h	DTC Control Data 16	DTCD16	XXh
2CC1h			XXh
2CC2h			XXh
2CC3h			XXh
2CC4h			XXh
2CC5h			XXh
2CC6h			XXh
2CC7h			XXh
2CC8h	DTC Control Data 17	DTCD17	XXh
2CC9h			XXh
2CCAh			XXh
2CCBh			XXh
2CCCCh			XXh
2CCDh			XXh
2CCEh			XXh
2CCFh			XXh
2CD0h	DTC Control Data 18	DTCD18	XXh
2CD1h			XXh
2CD2h			XXh
2CD3h			XXh
2CD4h			XXh
2CD5h			XXh
2CD6h			XXh
2CD7h			XXh
2CD8h	DTC Control Data 19	DTCD19	XXh
2CD9h			XXh
2CDAh			XXh
2CDBh			XXh
2CDCh			XXh
2CDDh			XXh
2CDEh			XXh
2CDFh			XXh
2CE0h	DTC Control Data 20	DTCD20	XXh
2CE1h			XXh
2CE2h			XXh
2CE3h			XXh
2CE4h			XXh
2CE5h			XXh
2CE6h			XXh
2CE7h			XXh
2CE8h	DTC Control Data 21	DTCD21	XXh
2CE9h			XXh
2CEAh			XXh
2CEBh			XXh
2CECh			XXh
2CEDh			XXh
2CEEh			XXh
2CEFh			XXh

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

**Table 4.12 SFR Information (12) (1)**

Address	Register	Symbol	After Reset
2CF0h	DTC Control Data 22	DTCD22	XXh
2CF1h			XXh
2CF2h			XXh
2CF3h			XXh
2CF4h			XXh
2CF5h			XXh
2CF6h			XXh
2CF7h			XXh
2CF8h	DTC Control Data 23	DTCD23	XXh
2CF9h			XXh
2CFAh			XXh
2CFBh			XXh
2CFCh			XXh
2CFDh			XXh
2CFEh			XXh
2CFFh			XXh
2D00h			
:			
2FFFh			

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

**Table 4.13 ID Code Areas and Option Function Select Area**

Address	Area Name	Symbol	After Reset
:			
FFDBh	Option Function Select Register 2	OFS2	(Note 1)
:			
FFDFh	ID1		(Note 2)
:			
FFE3h	ID2		(Note 2)
:			
FFE9h	ID3		(Note 2)
:			
FEF4h	ID4		(Note 2)
:			
FFF3h	ID5		(Note 2)
:			
FFF7h	ID6		(Note 2)
:			
FFFCh	ID7		(Note 2)
:			
FFFFh	Option Function Select Register	OFS	(Note 1)

Notes:

1. The option function select area is allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program.  
Do not write additions to the option function select area. If the block including the option function select area is erased, the option function select area is set to FFh.  
When blank products are shipped, the option function select area is set to FFh. It is set to the written value after written by the user.  
When factory-programming products are shipped, the value of the option function select area is the value programmed by the user.
2. The ID code areas are allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program.  
Do not write additions to the ID code areas. If the block including the ID code areas is erased, the ID code areas are set to FFh.  
When blank products are shipped, the ID code areas are set to FFh. They are set to the written value after written by the user.  
When factory-programming products are shipped, the value of the ID code areas is the value programmed by the user.

## 5. Electrical Characteristics

**Table 5.1 Absolute Maximum Ratings**

Symbol	Parameter	Condition	Rated Value	Unit
Vcc/AVcc	Supply voltage		-0.3 to 6.5	V
Vi	Input voltage		-0.3 to Vcc + 0.3	V
Vo	Output voltage		-0.3 to Vcc + 0.3	V
Pd	Power dissipation	-40°C ≤ Topr ≤ 85°C	500	mW
Topr	Operating ambient temperature		-20 to 85 (N version)/ -40 to 85 (D version)	°C
Tstg	Storage temperature		-65 to 150	°C

**Table 5.3 A/D Converter Characteristics**

Symbol	Parameter	Conditions	Standard			Unit		
			Min.	Typ.	Max.			
—	Resolution	V <sub>ref</sub> = AV <sub>cc</sub>	—	—	10	Bit		
—	Absolute accuracy	10-bit mode	V <sub>ref</sub> = AV <sub>cc</sub> = 5.0 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±3	LSB
			V <sub>ref</sub> = AV <sub>cc</sub> = 3.3 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±5	LSB
			V <sub>ref</sub> = AV <sub>cc</sub> = 3.0 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±5	LSB
			V <sub>ref</sub> = AV <sub>cc</sub> = 2.2 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±5	LSB
		8-bit mode	V <sub>ref</sub> = AV <sub>cc</sub> = 5.0 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±2	LSB
			V <sub>ref</sub> = AV <sub>cc</sub> = 3.3 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±2	LSB
			V <sub>ref</sub> = AV <sub>cc</sub> = 3.0 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±2	LSB
			V <sub>ref</sub> = AV <sub>cc</sub> = 2.2 V	AN0 to AN7 input, AN8 to AN11 input, AN12 to AN19 input	—	—	±2	LSB
φAD	A/D conversion clock	4.0 V ≤ V <sub>ref</sub> = AV <sub>cc</sub> ≤ 5.5 V (2)		2	—	20	MHz	
		3.2 V ≤ V <sub>ref</sub> = AV <sub>cc</sub> ≤ 5.5 V (2)		2	—	16	MHz	
		2.7 V ≤ V <sub>ref</sub> = AV <sub>cc</sub> ≤ 5.5 V (2)		2	—	10	MHz	
		2.2 V ≤ V <sub>ref</sub> = AV <sub>cc</sub> ≤ 5.5 V (2)		2	—	5	MHz	
—	Tolerance level impedance				—	3	—	kΩ
tCONV	Conversion time	10-bit mode	V <sub>ref</sub> = AV <sub>cc</sub> = 5.0 V, φAD = 20 MHz	2.2	—	—	μs	
		8-bit mode	V <sub>ref</sub> = AV <sub>cc</sub> = 5.0 V, φAD = 20 MHz	2.2	—	—	μs	
tsAMP	Sampling time	φAD = 20 MHz			0.8	—	—	μs
I <sub>Vref</sub>	V <sub>ref</sub> current	V <sub>CC</sub> = 5.0 V, XIN = f1 = φAD = 20 MHz			—	45	—	μA
V <sub>ref</sub>	Reference voltage				2.2	—	AV <sub>cc</sub>	V
V <sub>IA</sub>	Analog input voltage (3)				0	—	V <sub>ref</sub>	V
OCVREF	On-chip reference voltage	2 MHz ≤ φAD ≤ 4 MHz			1.19	1.34	1.49	V

Notes:

1. V<sub>CC</sub>/AV<sub>cc</sub> = V<sub>ref</sub> = 2.2 to 5.5 V, V<sub>SS</sub> = 0 V, and T<sub>opr</sub> = -20 to 85 °C (N version)/-40 to 85 °C (D version), unless otherwise specified.
2. The A/D conversion result will be undefined in wait mode, stop mode, when the flash memory stops, and in low-current-consumption mode. Do not perform A/D conversion in these states or transition to these states during A/D conversion.
3. When the analog input voltage is over the reference voltage, the A/D conversion result will be 3FFh in 10-bit mode and FFh in 8-bit mode.

**Table 5.4 D/A Converter Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
—	Resolution		—	—	8	Bit
—	Absolute accuracy		—	—	2.5	LSB
tsu	Setup time		—	—	3	μs
Ro	Output resistor		—	6	—	kΩ
I <sub>Vref</sub>	Reference power input current	(Note 2)	—	—	1.5	mA

Notes:

1. V<sub>cc</sub>/AV<sub>cc</sub> = V<sub>ref</sub> = 2.7 to 5.5 V and T<sub>opr</sub> = -20 to 85 °C (N version)/-40 to 85 °C (D version), unless otherwise specified.
2. This applies when one D/A converter is used and the value of the DAi register (i = 0 or 1) for the unused D/A converter is 00h.  
The resistor ladder of the A/D converter is not included.

**Table 5.5 Comparator B Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>ref</sub>	IVREF1, IVREF3 input reference voltage		0	—	V <sub>cc</sub> - 1.4	V
V <sub>I</sub>	IVCMP1, IVCMP3 input voltage		-0.3	—	V <sub>cc</sub> + 0.3	V
—	Offset		—	5	100	mV
t <sub>d</sub>	Comparator output delay time (2)	V <sub>I</sub> = V <sub>ref</sub> ± 100 mV	—	0.1	—	μs
I <sub>CMP</sub>	Comparator operating current	V <sub>cc</sub> = 5.0 V	—	17.5	—	μA

Notes:

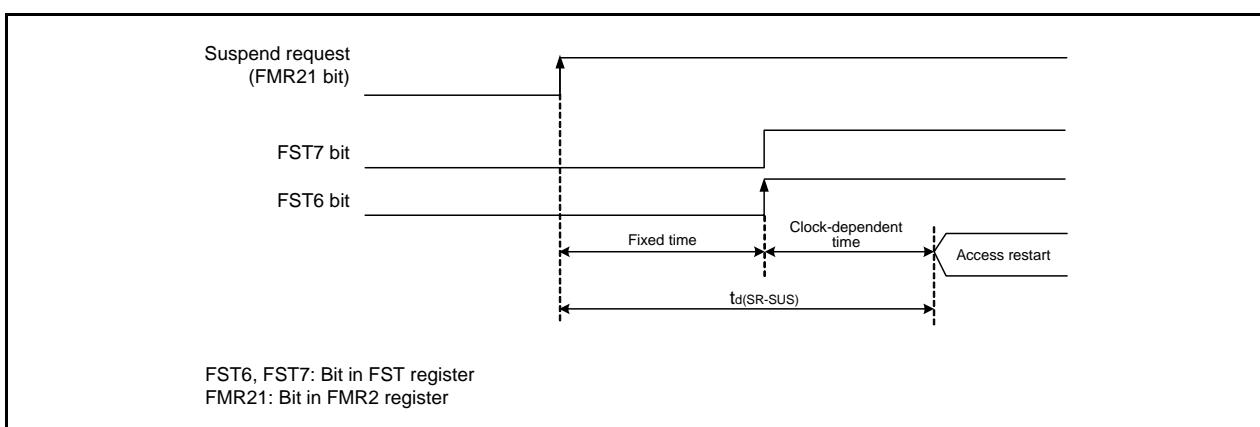
1. V<sub>cc</sub> = 2.7 to 5.5 V and T<sub>opr</sub> = -20 to 85 °C (N version)/-40 to 85 °C (D version), unless otherwise specified.
2. When the digital filter is disabled.

**Table 5.7 Flash Memory (Data flash Block A to Block D) Electrical Characteristics**

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
—	Program/erase endurance (2)		10,000 (3)	—	—	times
—	Byte program time (program/erase endurance $\leq$ 1,000 times)		—	160	1500	μs
—	Byte program time (program/erase endurance $>$ 1,000 times)		—	300	1500	μs
—	Block erase time (program/erase endurance $\leq$ 1,000 times)		—	0.2	1	s
—	Block erase time (program/erase endurance $>$ 1,000 times)		—	0.3	1	s
td(SR-SUS)	Time delay from suspend request until suspend		—	—	5 + CPU clock $\times$ 3 cycles	ms
—	Interval from erase start/restart until following suspend request		0	—	—	μs
—	Time from suspend until erase restart		—	—	30 + CPU clock $\times$ 1 cycle	μs
td(CMDRST-READY)	Time from when command is forcibly stopped until reading is enabled		—	—	30 + CPU clock $\times$ 1 cycle	μs
—	Program, erase voltage		2.7	—	5.5	V
—	Read voltage		1.8	—	5.5	V
—	Program, erase temperature		-20 (7)	—	85	°C
—	Data hold time (8)	Ambient temperature = 55 °C	20	—	—	year

## Notes:

1. Vcc = 2.7 to 5.5 V and T<sub>opr</sub> = -20 to 85 °C (N version)/-40 to 85 °C (D version), unless otherwise specified.
2. Definition of programming/erasure endurance  
The programming and erasure endurance is defined on a per-block basis.  
If the programming and erasure endurance is n (n = 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to different addresses in block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one. However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed.)
4. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. In addition, averaging the erasure endurance between blocks A to D can further reduce the actual erasure endurance. It is also advisable to retain data on the erasure endurance of each block and limit the number of erase operations to a certain number.
5. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
6. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
7. -40 °C for D version.
8. The data hold time includes time that the power supply is off or the clock is not supplied.

**Figure 5.2 Time delay until Suspend**

**Table 5.8 Voltage Detection 0 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>det0</sub>	Voltage detection level V <sub>det0_0</sub> (2)		1.80	1.90	2.05	V
	Voltage detection level V <sub>det0_1</sub> (2)		2.15	2.35	2.50	V
	Voltage detection level V <sub>det0_2</sub> (2)		2.70	2.85	3.05	V
	Voltage detection level V <sub>det0_3</sub> (2)		3.55	3.80	4.05	V
—	Voltage detection 0 circuit response time (4)	At the falling of Vcc from 5.0 V to (V <sub>det0_0</sub> – 0.1) V	—	6	150	μs
—	Voltage detection circuit self power consumption	VCA25 = 1, Vcc = 5.0 V	—	1.5	—	μA
td(E-A)	Waiting time until voltage detection circuit operation starts (3)		—	—	100	μs

Notes:

1. The measurement condition is Vcc = 1.8 to 5.5 V and T<sub>opr</sub> = –20 to 85 °C (N version)/–40 to 85 °C (D version).
2. Select the voltage detection level with bits VDSEL0 and VDSEL1 in the OFS register.
3. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA25 bit in the VCA2 register to 0.
4. Time until the voltage monitor 0 reset is generated after the voltage passes V<sub>det0</sub>.

**Table 5.9 Voltage Detection 1 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>det1</sub>	Voltage detection level V <sub>det1_0</sub> (2)	At the falling of Vcc	2.00	2.20	2.40	V
	Voltage detection level V <sub>det1_1</sub> (2)	At the falling of Vcc	2.15	2.35	2.55	V
	Voltage detection level V <sub>det1_2</sub> (2)	At the falling of Vcc	2.30	2.50	2.70	V
	Voltage detection level V <sub>det1_3</sub> (2)	At the falling of Vcc	2.45	2.65	2.85	V
	Voltage detection level V <sub>det1_4</sub> (2)	At the falling of Vcc	2.60	2.80	3.00	V
	Voltage detection level V <sub>det1_5</sub> (2)	At the falling of Vcc	2.75	2.95	3.15	V
	Voltage detection level V <sub>det1_6</sub> (2)	At the falling of Vcc	2.85	3.10	3.40	V
	Voltage detection level V <sub>det1_7</sub> (2)	At the falling of Vcc	3.00	3.25	3.55	V
	Voltage detection level V <sub>det1_8</sub> (2)	At the falling of Vcc	3.15	3.40	3.70	V
	Voltage detection level V <sub>det1_9</sub> (2)	At the falling of Vcc	3.30	3.55	3.85	V
	Voltage detection level V <sub>det1_A</sub> (2)	At the falling of Vcc	3.45	3.70	4.00	V
	Voltage detection level V <sub>det1_B</sub> (2)	At the falling of Vcc	3.60	3.85	4.15	V
	Voltage detection level V <sub>det1_C</sub> (2)	At the falling of Vcc	3.75	4.00	4.30	V
	Voltage detection level V <sub>det1_D</sub> (2)	At the falling of Vcc	3.90	4.15	4.45	V
—	Hysteresis width at the rising of Vcc in voltage detection 1 circuit	V <sub>det1_0</sub> to V <sub>det1_5</sub> selected	—	0.07	—	V
		V <sub>det1_6</sub> to V <sub>det1_F</sub> selected	—	0.10	—	V
	Voltage detection 1 circuit response time (3)	At the falling of Vcc from 5.0 V to (V <sub>det1_0</sub> – 0.1) V	—	60	150	μs
—	Voltage detection circuit self power consumption	VCA26 = 1, Vcc = 5.0 V	—	1.7	—	μA
td(E-A)	Waiting time until voltage detection circuit operation starts (4)		—	—	100	μs

Notes:

1. The measurement condition is Vcc = 1.8 to 5.5 V and T<sub>opr</sub> = –20 to 85 °C (N version)/–40 to 85 °C (D version).
2. Select the voltage detection level with bits VD1S0 to VD1S3 in the VD1LS register.
3. Time until the voltage monitor 1 interrupt request is generated after the voltage passes V<sub>det1</sub>.
4. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.

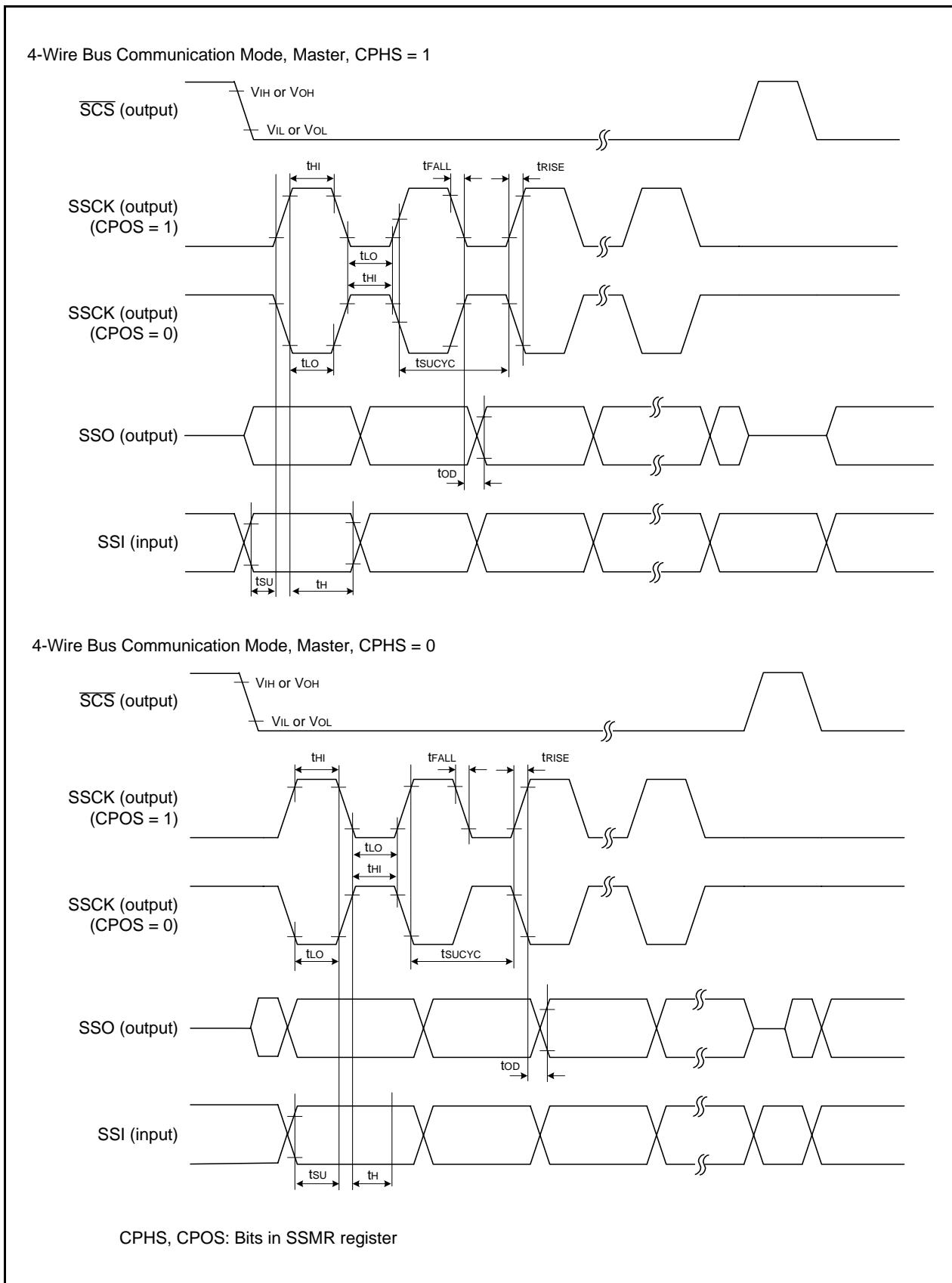


Figure 5.4 I/O Timing of Synchronous Serial Communication Unit (SSU) (Master)

**Table 5.24 Electrical Characteristics (3) [2.7 V ≤ Vcc < 4.2 V]**

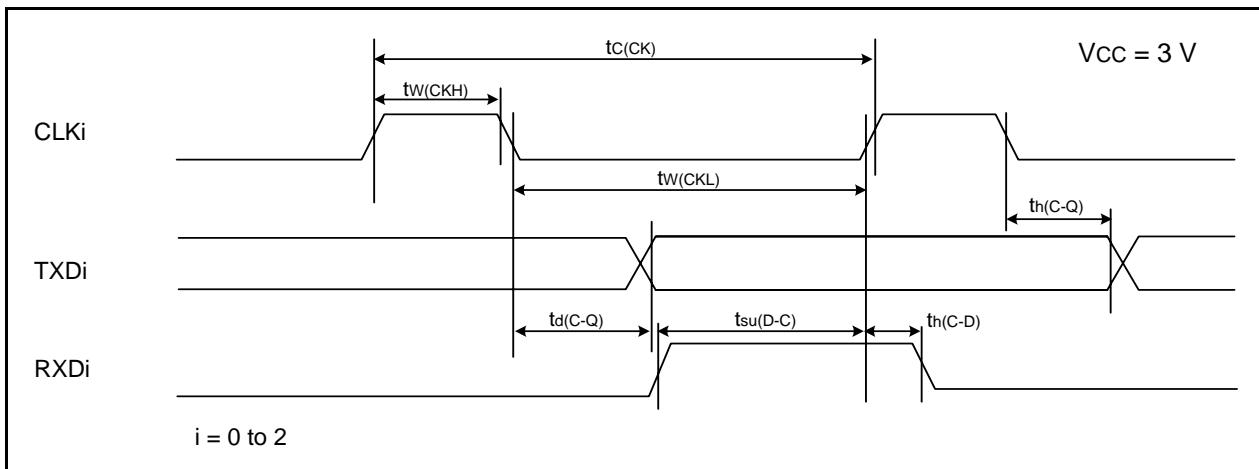
Symbol	Parameter	Condition	Standard			Unit		
			Min.	Typ.	Max.			
V <sub>OH</sub>	Output "H" voltage	Other than X <sub>OUT</sub>	Drive capacity High	I <sub>OH</sub> = -5 mA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
			Drive capacity Low	I <sub>OH</sub> = -1 mA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
		X <sub>OUT</sub>		I <sub>OH</sub> = -200 μA	1.0	—	V <sub>CC</sub>	V
V <sub>OL</sub>	Output "L" voltage	Other than X <sub>OUT</sub>	Drive capacity High	I <sub>OL</sub> = 5 mA	—	—	0.5	V
			Drive capacity Low	I <sub>OL</sub> = 1 mA	—	—	0.5	V
		X <sub>OUT</sub>		I <sub>OL</sub> = 200 μA	—	—	0.5	V
V <sub>T+VT-</sub>	Hysteresis	INT0, INT1, INT2, INT3, INT4, K10, K11, K12, K13, TRAO, TRBO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRDIOA0, TRDIOB0, TRDIOC0, TRDIOD0, TRDIOA1, TRDIOB1, TRDIOD1, TRCTRG, TRCCLK, TRFI, TRGIOA, TRGIOB, ADTRG, RXD0, RXD1, RXD2, CLK0, CLK1, CLK2, SSI, SCL, SDA, SSO	V <sub>CC</sub> = 3.0 V		0.1	0.4	—	V
		RESET	V <sub>CC</sub> = 3.0 V		0.1	0.5	—	V
I <sub>IH</sub>	Input "H" current		V <sub>I</sub> = 3 V, V <sub>CC</sub> = 3.0 V		—	—	4.0	μA
I <sub>IL</sub>	Input "L" current		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 3.0 V		—	—	-4.0	μA
R <sub>PULLUP</sub>	Pull-up resistance		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 3.0 V		42	84	168	kΩ
R <sub>IXIN</sub>	Feedback resistance	XIN			—	0.3	—	MΩ
R <sub>IXCIN</sub>	Feedback resistance	XCIN			—	8	—	MΩ
V <sub>RAM</sub>	RAM hold voltage		During stop mode		1.8	—	—	V

Note:

1. 2.7 V ≤ V<sub>CC</sub> < 4.2 V, T<sub>OPR</sub> = -20 to 85 °C (N version)/-40 to 85 °C (D version), and f(XIN) = 10 MHz, unless otherwise specified.

**Table 5.29 Serial Interface**

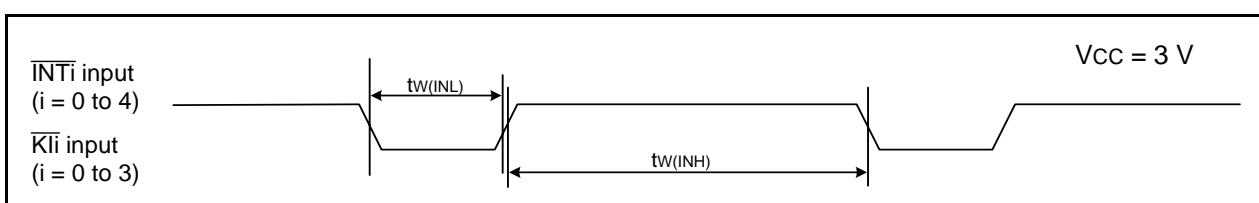
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(CK)$	CLK <i>i</i> input cycle time	300	—	ns
$t_w(CKH)$	CLK <i>i</i> input "H" width	150	—	ns
$t_w(CKL)$	CLK <i>i</i> Input "L" width	150	—	ns
$t_d(C-Q)$	TXD <i>i</i> output delay time	—	80	ns
$t_h(C-Q)$	TXD <i>i</i> hold time	0	—	ns
$t_{su}(D-C)$	RXD <i>i</i> input setup time	70	—	ns
$t_h(C-D)$	RXD <i>i</i> input hold time	90	—	ns

 $i = 0 \text{ to } 2$ **Figure 5.16 Serial Interface Timing Diagram when  $V_{CC} = 3 \text{ V}$** **Table 5.30 External Interrupt  $\overline{\text{INT}}_i$  ( $i = 0 \text{ to } 4$ ) Input, Key Input Interrupt  $\overline{\text{K}}_i$  ( $i = 0 \text{ to } 3$ )**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_w(\overline{\text{INH}})$	$\overline{\text{INT}}_i$ input "H" width, $\overline{\text{K}}_i$ input "H" width	380 (1)	—	ns
$t_w(\overline{\text{INL}})$	$\overline{\text{INT}}_i$ input "L" width, $\overline{\text{K}}_i$ input "L" width	380 (2)	—	ns

Notes:

- When selecting the digital filter by the  $\overline{\text{INT}}_i$  input filter select bit, use an  $\overline{\text{INT}}_i$  input HIGH width of either (1/digital filter clock frequency  $\times$  3) or the minimum value of standard, whichever is greater.
- When selecting the digital filter by the  $\overline{\text{INT}}_i$  input filter select bit, use an  $\overline{\text{INT}}_i$  input LOW width of either (1/digital filter clock frequency  $\times$  3) or the minimum value of standard, whichever is greater.

**Figure 5.17 Input Timing Diagram for External Interrupt  $\overline{\text{INT}}_i$  and Key Input Interrupt  $\overline{\text{K}}_i$  when  $V_{CC} = 3 \text{ V}$**

**Table 5.31 Electrical Characteristics (5) [1.8 V ≤ Vcc < 2.7 V]**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>OH</sub>	Output "H" voltage Other than X <sub>OUT</sub>	Drive capacity High	I <sub>OH</sub> = -2 mA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub> V
		Drive capacity Low	I <sub>OH</sub> = -1 mA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub> V
	X <sub>OUT</sub>		I <sub>OH</sub> = -200 μA	1.0	—	V <sub>CC</sub> V
V <sub>OL</sub>	Output "L" voltage Other than X <sub>OUT</sub>	Drive capacity High	I <sub>OL</sub> = 2 mA	—	—	0.5 V
		Drive capacity Low	I <sub>OL</sub> = 1 mA	—	—	0.5 V
	X <sub>OUT</sub>		I <sub>OL</sub> = 200 μA	—	—	0.5 V
V <sub>T+VT-</sub>	Hysteresis  NT0, INT1, INT2, INT3, INT4, KI0, KI1, KI2, KI3, TRAIO, TRBO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRDIOA0, TRDIOB0, TRDIOC0, TRDIOD0, TRDIOA1, TRDIOB1, TRDIOD1, TRDIOD1, TRCTRG, TRCCLK, TRFI, TRGIOA, TRGIOB, ADTRG, RXD0, RXD1, RXD2, CLK0, CLK1, CLK2, SSI, SCL, SDA, SSO  RESET			0.05	0.20	— V
				0.05	0.20	— V
I <sub>IH</sub>	Input "H" current		V <sub>I</sub> = 2.2 V, V <sub>CC</sub> = 2.2 V	—	—	4.0 μA
I <sub>IL</sub>	Input "L" current		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 2.2 V	—	—	-4.0 μA
R <sub>PULLUP</sub>	Pull-up resistance		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 2.2 V	70	140	300 kΩ
R <sub>IXIN</sub>	Feedback resistance	X <sub>IN</sub>		—	0.3	— MΩ
R <sub>IXCIN</sub>	Feedback resistance	X <sub>CIN</sub>		—	8	— MΩ
V <sub>RAM</sub>	RAM hold voltage		During stop mode	1.8	—	— V

Note:

1. 1.8 V ≤ V<sub>CC</sub> < 2.7 V, T<sub>OPR</sub> = -20 to 85 °C (N version)/-40 to 85 °C (D version), and f(X<sub>IN</sub>) = 5 MHz, unless otherwise specified.

REVISION HISTORY		R8C/38C Group Datasheet	
Rev.	Date	Description	
		Page	Summary
0.01	Oct 30, 2009	—	First Edition issued
1.00	Apr 23, 2010	All pages 4 27 to 53	“Preliminary”, “Under development” deleted Table 1.3 revised “5. Electrical Characteristics” added
1.10	Nov 02, 2010	— 3 4 5 15 31 45 49 53	TN-R8C-A015A/E reflected Table 1.2 “Timer RG” revised Table 1.3 revised Figure 1.1 revised Figure 3.1 revised Table 5.3 “tCONV”, “tSAMP” revised Table 5.21 revised Table 5.28 revised Table 5.35 revised

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## General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

### 1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

### 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

### 5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

- The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.