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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I ² C, IrDA, LINbus, SAI, SDIO, SPI, UART/USART, USB, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I ² S, LCD, POR, PWM, WDT
Number of I/O	114
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	384K x 8
Voltage - Supply (Vcc/Vdd)	1.7V ~ 3.6V
Data Converters	A/D 24x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	168-UFBGA, WLCSP
Supplier Device Package	168-WLCSP (4.89x5.69)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f479aiy6tr

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2.21 Real-time clock (RTC), backup SRAM and backup registers

The backup domain includes:

- The real-time clock (RTC)
- 4 Kbytes of backup SRAM
- 20 backup registers

The real-time clock (RTC) is an independent BCD timer/counter. Dedicated registers contain the second, minute, hour (in 12/24 hour), week day, date, month, year, in BCD (binary-coded decimal) format. Correction for 28, 29 (leap year), 30, and 31 day of the month are performed automatically. The RTC provides a programmable alarm and programmable periodic interrupts with wakeup from Stop and Standby modes. The sub-seconds value is also available in binary format.

It is clocked by a 32.768 kHz external crystal, resonator or oscillator, the internal low-power RC oscillator or the high-speed external clock divided by 128. The internal low-speed RC has a typical frequency of 32 kHz. The RTC can be calibrated using an external 512 Hz output to compensate for any natural quartz deviation.

Two alarm registers are used to generate an alarm at a specific time and calendar fields can be independently masked for alarm comparison. To generate a periodic interrupt, a 16-bit programmable binary auto-reload downcounter with programmable resolution is available and allows automatic wakeup and periodic alarms from every 120 μ s to every 36 hours.

A 20-bit prescaler is used for the time base clock. It is by default configured to generate a time base of 1 second from a clock at 32.768 kHz.

The 4-Kbyte backup SRAM is an EEPROM-like memory area. It can be used to store data which need to be retained in VBAT and standby mode. This memory area is disabled by default to minimize power consumption (see [Section 2.22](#)). It can be enabled by software.

The backup registers are 32-bit registers used to store 80 bytes of user application data when V_{DD} power is not present. Backup registers are not reset by a system, a power reset, or when the device wakes up from the Standby mode (see [Section 2.22](#)).

Additional 32-bit registers contain the programmable alarm subseconds, seconds, minutes, hours, day, and date.

Like backup SRAM, the RTC and backup registers are supplied through a switch that is powered either from the V_{DD} supply when present or from the V_{BAT} pin.

2.32 Secure digital input/output interface (SDIO)

An SD/SDIO/MMC host interface is available, that supports MultiMediaCard System Specification Version 4.2 in three different databus modes: 1-bit (default), 4-bit and 8-bit.

The interface allows data transfer at up to 48 MHz, and is compliant with the SD Memory Card Specification Version 2.0.

The SDIO Card Specification Version 2.0 is also supported with two different databus modes: 1-bit (default) and 4-bit.

The current version supports only one SD/SDIO/MMC4.2 card at any one time and a stack of MMC4.1 or previous.

In addition to SD/SDIO/MMC, this interface is fully compliant with the CE-ATA digital protocol Rev1.1.

2.33 Ethernet MAC interface with dedicated DMA and IEEE 1588 support

The devices provide an IEEE-802.3-2002-compliant media access controller (MAC) for ethernet LAN communications through an industry-standard medium-independent interface (MII) or a reduced medium-independent interface (RMII). The microcontroller requires an external physical interface device (PHY) to connect to the physical LAN bus (twisted-pair, fiber, etc.). The PHY is connected to the device MII port using 17 signals for MII or 9 signals for RMII, and can be clocked using the 25 MHz (MII) from the microcontroller.

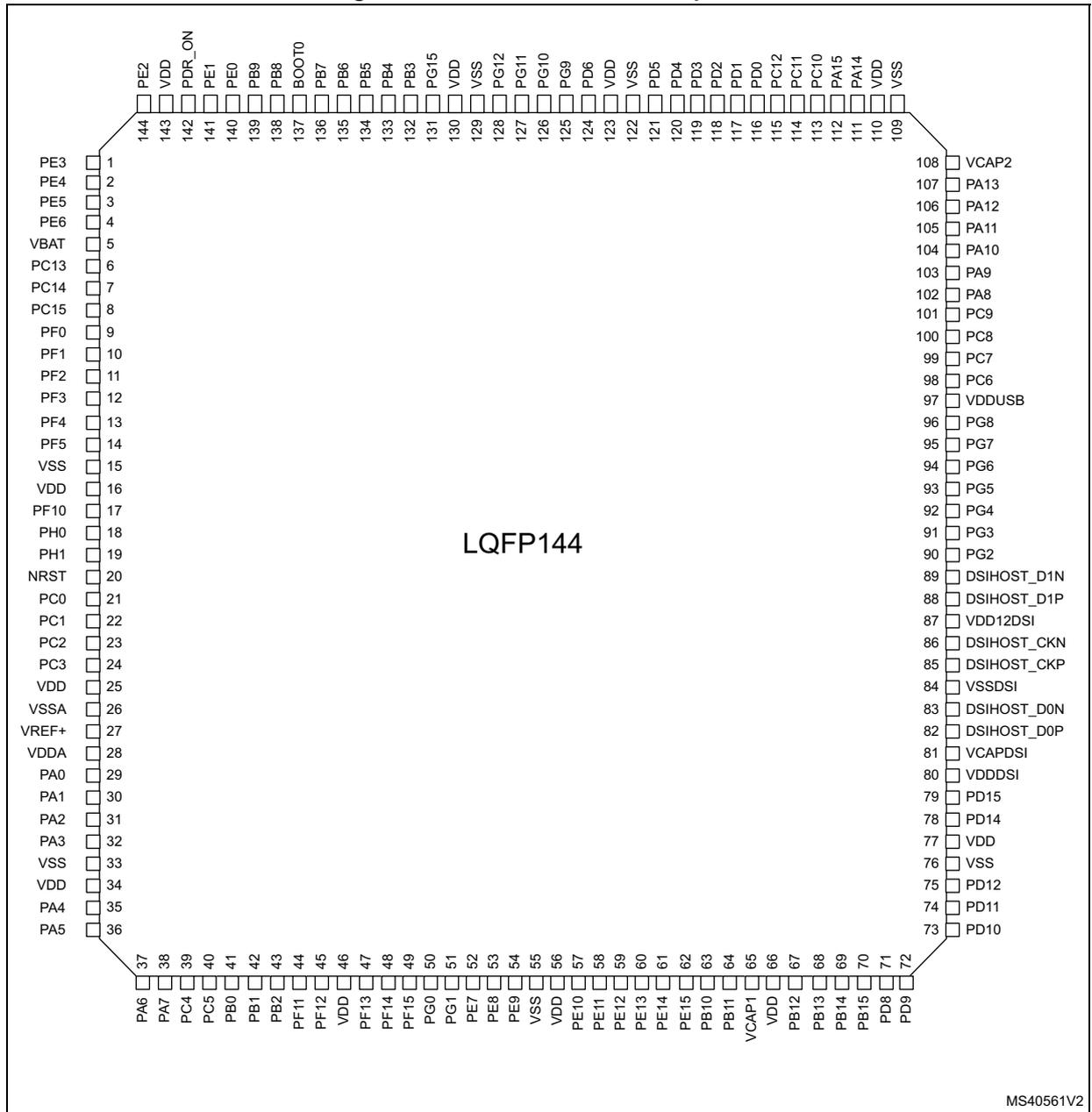
The devices include the following features:

- Supports 10 and 100 Mbit/s rates
- Dedicated DMA controller allowing high-speed transfers between the dedicated SRAM and the descriptors (see the STM32F4xx reference manual for details)
- Tagged MAC frame support (VLAN support)
- Half-duplex (CSMA/CD) and full-duplex operation
- MAC control sublayer (control frames) support
- 32-bit CRC generation and removal
- Several address filtering modes for physical and multicast address (multicast and group addresses)
- 32-bit status code for each transmitted or received frame
- Internal FIFOs to buffer transmit and receive frames. The transmit FIFO and the receive FIFO are both 2 Kbytes.
- Supports hardware PTP (precision time protocol) in accordance with IEEE 1588 2008 (PTP V2) with the time stamp comparator connected to the TIM2 input
- Triggers interrupt when system time becomes greater than target time

2.34 Controller area network (bxCAN)

The two CANs are compliant with the 2.0A and B (active) specifications with a bitrate up to 1 Mbit/s. They can receive and transmit standard frames with 11-bit identifiers as well as extended frames with 29-bit identifiers. Each CAN has three transmit mailboxes, two receive

Figure 14. STM32F47x LQFP144 pinout



1. The above figure shows the package top view.

Table 10. STM32F479xx pin and ball definitions (continued)

Pin number								Pin name (function after reset) ⁽¹⁾	Pin types	I/O structures	Notes	Alternate functions	Additional functions
LQFP100	LQFP144	UFBGA169	WLCSP168	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	L3	K8	J4	46	49	J3	PH5	I/O	FT	-	I2C2_SDA, SPI5_NSS, FMC_SDNWE, EVENTOUT	-
22	32	K3	N10	R2	47	50	R2	PA3	I/O	FT	(5)	TIM2_CH4, TIM5_CH4, TIM9_CH2, USART2_RX, LCD_B2, OTG_HS_ULPI_D0, ETH_MII_COL, LCD_B5, EVENTOUT	ADC123_IN3
23	33	J1	N11	-	-	51	K6	VSS	S	-	-	-	-
-	-	-	-	L4	48	-	L5	BYPASS_REG	I	FT	-	-	-
24	34	J4	P12	K4	49	52	K5	VDD	S	-	-	-	-
25	35	N2	M9	N4	50	53	N4	PA4	I/O	TTa	-	SPI1_NSS, SPI3_NSS/I2S3_WS, USART2_CK, OTG_HS_SOF, DCMI_HSYNC, LCD_VSYNC, EVENTOUT	ADC12_IN4, DAC_OUT1
26	36	M3	L8	P4	51	54	P4	PA5	I/O	TTa	-	TIM2_CH1/TIM2_ETR, TIM8_CH1N, SPI1_SCK, OTG_HS_ULPI_CK, LCD_R4, EVENTOUT	ADC12_IN5, DAC_OUT2
27	37	N3	P11	P3	52	55	P3	PA6	I/O	FT	(5)	TIM1_BKIN, TIM3_CH1, TIM8_BKIN, SPI1_MISO, TIM13_CH1, DCMI_PIXCLK, LCD_G2, EVENTOUT	ADC12_IN6
28	38	K4	J8	R3	53	56	R3	PA7	I/O	FT	(5)	TIM1_CH1N, TIM3_CH2, TIM8_CH1N, SPI1_MOSI, TIM14_CH1, QUADSPI_CLK, ETH_MII_RX_DV/ETH_RMII_CRS_DV, FMC_SDNWE, EVENTOUT	ADC12_IN7
NC ⁽²⁾	39	-	-	N5	54	57	N5	PC4	I/O	FT	(5)	ETH_MII_RXD0/ETH_RMII_RXD0, FMC_SDNE0, EVENTOUT	ADC12_IN14
NC ⁽²⁾	40	-	-	P5	55	58	P5	PC5	I/O	FT	(5)	ETH_MII_RXD1/ETH_RMII_RXD1, FMC_SDCKE0, EVENTOUT	ADC12_IN15
-	-	-	-	-	-	59	L7	VDD	S	-	-	-	-
-	-	-	-	-	-	60	L6	VSS	S	-	-	-	-
29	41	N4	P10	R5	56	61	R5	PB0	I/O	FT	(5)	TIM1_CH2N, TIM3_CH3, TIM8_CH2N, LCD_R3, OTG_HS_ULPI_D1, ETH_MII_RXD2, LCD_G1, EVENTOUT	ADC12_IN8



Table 12. Alternate function (continued)

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15		
	SYS	TIM1/2	TIM3/4/5	TIM8/9/10/11	I2C1/2/3	SPI1/2/3/4/5/6	SPI2/3/SAI1	SPI2/3/USART1/2/3	USART6/UART4/5/7/8	CAN1/2/TIM12/13/14/QUADSPI/LCD	QUADSPI/OTG2_HS/OTG1_FS	ETH	FMC/SDIO/OTG2_FS	DCMI/DSI/HOST	LCD	SYS		
Port B	PB0	-	TIM1_CH2N	TIM3_CH3	TIM8_CH2N	-	-	-	-	-	LCD_R3	OTG_HS_ULPI_D1	ETH_MII_RXD2	-	-	LCD_G1	EVENT OUT	
	PB1	-	TIM1_CH3N	TIM3_CH4	TIM8_CH3N	-	-	-	-	-	LCD_R6	OTG_HS_ULPI_D2	ETH_MII_RXD3	-	-	LCD_G0	EVENT OUT	
	PB2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT	
	PB3	JTDO / TRACES WO	TIM2_CH2	-	-	-	SPI1_SCK	SPI3_SCK/I2S3_SCK	-	-	-	-	-	-	-	-	-	EVENT OUT
	PB4	NJTRST	-	TIM3_CH1	-	-	SPI1_MISO	SPI3_MISO	I2S3ext_SD	-	-	-	-	-	-	-	-	EVENT OUT
	PB5	-	-	TIM3_CH2	-	I2C1_SMBA	SPI1_MOSI	SPI3_MOSI/I2S3_SD	-	-	CAN2_RX	OTG_HS_ULPI_D7	ETH_PPS_OUT	FMC_SDCKE1	DCMI_D10	LCD_G7	EVENT OUT	
	PB6	-	-	TIM4_CH1	-	I2C1_SCL	-	-	USART1_TX	-	CAN2_TX	QUADSPI_BK1_NCS	-	FMC_SDNE1	DCMI_D5	-	EVENT OUT	
	PB7	-	-	TIM4_CH2	-	I2C1_SDA	-	-	USART1_RX	-	-	-	-	FMC_NL	DCMI_VSYNC	-	EVENT OUT	
	PB8	-	-	TIM4_CH3	TIM10_CH1	I2C1_SCL	-	-	-	-	CAN1_RX	-	ETH_MII_TXD3	SDIO_D4	DCMI_D6	LCD_B6	EVENT OUT	
	PB9	-	-	TIM4_CH4	TIM11_CH1	I2C1_SDA	SPI2_NSS/I2S2_WS	-	-	-	CAN1_TX	-	-	SDIO_D5	DCMI_D7	LCD_B7	EVENT OUT	
	PB10	-	TIM2_CH3	-	-	I2C2_SCL	SPI2_SCK/I2S2_WS	-	USART3_TX	-	QUADSPI_BK1_NCS	OTG_HS_ULPI_D3	ETH_MII_RXD0	-	-	LCD_G4	EVENT OUT	
	PB11	-	TIM2_CH4	-	-	I2C2_SDA	-	-	USART3_RX	-	-	OTG_HS_ULPI_D4	ETH_MII_TXD0/ETH_RMII_TXD0	-	DSIHOST_TE	LCD_G5	EVENT OUT	
	PB12	-	TIM1_BKIN	-	-	I2C2_SMBA	SPI2_NSS/I2S2_WS	-	USART3_SCK	-	CAN2_RX	OTG_HS_ULPI_D5	ETH_MII_TXD0/ETH_RMII_TXD0	OTG_HS_ID	-	-	EVENT OUT	
	PB13	-	TIM1_CH1N	-	-	-	SPI2_SCK/I2S2_WS	-	USART3_CTS	-	CAN2_TX	OTG_HS_ULPI_D6	ETH_MII_TXD1/ETH_RMII_TXD1	-	-	-	EVENT OUT	
	PB14	-	TIM1_CH2N	-	TIM8_CH2N	-	SPI2_MISO	I2S2ext_SD	USART3_RTS	-	TIM12_CH1	-	-	OTG_HS_DM	-	-	EVENT OUT	
PB15	RTC_REFIN	TIM1_CH3N	-	TIM8_CH3N	-	SPI2_MOSI/I2S2_SD	-	-	-	TIM12_CH2	-	-	OTG_HS_DP	-	-	EVENT OUT		



Table 12. Alternate function (continued)

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
	SYS	TIM1/2	TIM3/4/5	TIM8/9/10/11	I2C1/2/3	SPI1/2/3/4/5/6	SPI2/3/SAI1	SPI2/3/USART1/2/3	USART6/UART4/5/7/8	CAN1/2/TIM12/13/14/QUADSPI/LCD	QUADSPI/OTG2_HS/OTG1_FS	ETH	FMC/SDIO/OTG2_FS	DCMI/DSI/HOST	LCD	SYS
Port I	PI0	-	-	TIM5_CH4	-	-	SPI2_NSS/2S2_WS	-	-	-	-	-	FMC_D24	DCMI_D13	LCD_G5	EVENT OUT
	PI1	-	-	-	-	-	SPI2_SCK/2S2_CK	-	-	-	-	-	FMC_D25	DCMI_D8	LCD_G6	EVENT OUT
	PI2	-	-	-	TIM8_CH4	-	SPI2_MISO	I2S2ext_SD	-	-	-	-	FMC_D26	DCMI_D9	LCD_G7	EVENT OUT
	PI3	-	-	-	TIM8_ETR	-	SPI2_MOSI/2S2_SD	-	-	-	-	-	FMC_D27	DCMI_D10		EVENT OUT
	PI4	-	-	-	TIM8_BKIN	-	-	-	-	-	-	-	FMC_NBL2	DCMI_D5	LCD_B4	EVENT OUT
	PI5	-	-	-	TIM8_CH1	-	-	-	-	-	-	-	FMC_NBL3	DCMI_VSYNC	LCD_B5	EVENT OUT
	PI6	-	-	-	TIM8_CH2	-	-	-	-	-	-	-	FMC_D28	DCMI_D6	LCD_B6	EVENT OUT
	PI7	-	-	-	TIM8_CH3	-	-	-	-	-	-	-	FMC_D29	DCMI_D7	LCD_B7	EVENT OUT
	PI8	-	-	-	-	-	-	-	-	-	-	-	-	-		EVENT OUT
	PI9	-	-	-	-	-	-	-	-	-	CAN1_RX	-	FMC_D30	-	LCD_VSYNC	EVENT OUT
	PI10	-	-	-	-	-	-	-	-	-	-	-	ETH_MII_RX_ER	FMC_D31	LCD_HSYNC	EVENT OUT
	PI11	-	-	-	-	-	-	-	-	-	LCD_G6	OTG_HS_ULPI_DIR	-	-	-	EVENT OUT
	PI12	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_HSYNC	EVENT OUT
	PI13	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_VSYNC	EVENT OUT
	PI14	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_CLK	EVENT OUT
	PI15	-	-	-	-	-	-	-	-	-	LCD_G2	-	-	-	LCD_R0	EVENT OUT

Table 13. STM32F479xx register boundary addresses⁽¹⁾ (continued)

Bus	Boundary address	Peripheral
-	0x4000 8000- 0x4000 FFFF	Reserved
APB1	0x4000 7C00 - 0x4000 7FFF	UART8
	0x4000 7800 - 0x4000 7BFF	UART7
	0x4000 7400 - 0x4000 77FF	DAC
	0x4000 7000 - 0x4000 73FF	PWR
	0x4000 6C00 - 0x4000 6FFF	Reserved
	0x4000 6800 - 0x4000 6BFF	CAN2
	0x4000 6400 - 0x4000 67FF	CAN1
	0x4000 6000 - 0x4000 63FF	Reserved
	0x4000 5C00 - 0x4000 5FFF	I2C3
	0x4000 5800 - 0x4000 5BFF	I2C2
	0x4000 5400 - 0x4000 57FF	I2C1
	0x4000 5000 - 0x4000 53FF	UART5
	0x4000 4C00 - 0x4000 4FFF	UART4
	0x4000 4800 - 0x4000 4BFF	USART3
	0x4000 4400 - 0x4000 47FF	USART2
	0x4000 4000 - 0x4000 43FF	I2S3ext
	0x4000 3C00 - 0x4000 3FFF	SPI3 / I2S3
	0x4000 3800 - 0x4000 3BFF	SPI2 / I2S2
	0x4000 3400 - 0x4000 37FF	I2S2ext
	0x4000 3000 - 0x4000 33FF	IWDG
	0x4000 2C00 - 0x4000 2FFF	WWDG
	0x4000 2800 - 0x4000 2BFF	RTC & BKP Registers
	0x4000 2400 - 0x4000 27FF	Reserved
	0x4000 2000 - 0x4000 23FF	TIM14
	0x4000 1C00 - 0x4000 1FFF	TIM13
	0x4000 1800 - 0x4000 1BFF	TIM12
	0x4000 1400 - 0x4000 17FF	TIM7
	0x4000 1000 - 0x4000 13FF	TIM6
	0x4000 0C00 - 0x4000 0FFF	TIM5
	0x4000 0800 - 0x4000 0BFF	TIM4
0x4000 0400 - 0x4000 07FF	TIM3	
0x4000 0000 - 0x4000 03FF	TIM2	

1. The reserved boundary address are shown in grayed cells

Typical and maximum current consumption

The MCU is placed under the following conditions:

- All I/O pins are in input mode with a static value at V_{DD} or V_{SS} (no load).
- All peripherals are disabled except if it is explicitly mentioned.
- The Flash memory access time is adjusted both to f_{HCLK} frequency and V_{DD} range (see [Table 18: Limitations depending on the operating power supply range](#)).
- When the regulator is OFF, the V_{12} is provided externally, as described in [Table 17: General operating conditions](#).
- The voltage scaling and over-drive mode are adjusted to f_{HCLK} frequency as follows:
 - Scale 3 for $f_{HCLK} \leq 120$ MHz
 - Scale 2 for $120 \text{ MHz} < f_{HCLK} \leq 144$ MHz
 - Scale 1 for $144 \text{ MHz} < f_{HCLK} \leq 180$ MHz. The over-drive is only ON at 180 MHz.
- The system clock is HCLK, $f_{PCLK1} = f_{HCLK}/4$, and $f_{PCLK2} = f_{HCLK}/2$.
- External clock frequency is 25 MHz and PLL is ON when f_{HCLK} is higher than 25 MHz.
- The typical current consumption values are obtained for $1.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$ voltage range and for ambient temperature $T_A = 25 \text{ }^\circ\text{C}$ unless otherwise specified.
- The maximum values are obtained for $1.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$ voltage range and a maximum ambient temperature (T_A), unless otherwise specified.
- For the voltage range $1.7 \text{ V} \leq V_{DD} \leq 2.1 \text{ V}$ the maximum frequency is 168 MHz.

Table 25. Typical and maximum current consumption in Run mode, code with data processing running from Flash memory (ART accelerator disabled), regulator ON

Symbol	Parameter	Conditions	f _{HCLK} (MHz)	Typ	Max ⁽¹⁾			Unit
					T _A = 25 °C	T _A = 85 °C	T _A = 105 °C	
I _{DD}	Supply current in RUN mode	All Peripherals enabled ⁽²⁾⁽³⁾	168	97	102	128	154	mA
			150	87	92	118	143	
			144	80	84	108	131	
			120	65	68	88	108	
			90	51	54	73	93	
			60	37	41	59	79	
			30	21	23	42	62	
		25	18	20	39	59		
		All Peripherals disabled	168	49	55	79	105	
			150	44	49	44	100	
			144	40	45	68	92	
			120	36	39	58	78	
			90	29	32	51	71	
			60	22	25	44	64	
30	13		15	34	54			
25	11	13	32	52				

1. Guaranteed based on test during characterization.
2. When analog peripheral blocks such as ADCs, DACs, HSE, LSE, HSI, or LSI are ON, an additional power consumption should be considered.
3. When the ADC is ON (ADON bit set in the ADC_CR2 register), add an additional power consumption of 1.6 mA per ADC for the analog part.

Table 45. MIPI D-PHY characteristics⁽¹⁾ (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{CMTX}	HS transmit common mode voltage	-	150	200	250	mV
$ \Delta V_{CMTX} $	V_{CMTX} mismatch when output is Differential-1 or Differential-0	-	-	-	5	
$ V_{OD} $	HS transmit differential voltage	-	140	200	270	
$ \Delta V_{OD} $	V_{OD} mismatch when output is Differential-1 or Differential-0	-	-	-	14	
V_{OHHS}	HS output high voltage	-	-	-	360	
Z_{OS}	Single ended output impedance	-	40	50	62.5	Ω
ΔZ_{OS}	Single ended output impedance mismatch	-	-	-	10	%
t_{HSr} & t_{HSf}	20%-80% rise and fall time	-	100	-	$0.35 \cdot UI$	ps
LP Receiver Input Characteristics						
V_{IL}	Logic 0 input voltage (not in ULP State)	-	-	-	550	mV
$V_{IL-ULPS}$	Logic 0 input voltage in ULP State	-	-	-	300	
V_{IH}	Input high level voltage	-	880	-	-	
V_{hys}	Voltage hysteresis	-	25	-	-	
LP Emitter Output Characteristics						
V_{IL}	Output low level voltage	-	1.1	1.2	1.2	V
$V_{IL-ULPS}$	Output high level voltage	-	-50	-	50	mV
V_{IH}	Output impedance of LP transmitter	-	110	-	-	Ω
V_{hys}	15%-85% rise and fall time	-	-	-	25	ns
LP Contention Detector Characteristics						
V_{ILCD}	Logic 0 contention threshold	-	-	-	200	mV
V_{IHCD}	Logic 0 contention threshold	-	450	-	-	

1. Guaranteed based on test during characterization.

Output voltage levels

Unless otherwise specified, the parameters given in [Table 59](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 17](#). All I/Os are CMOS and TTL compliant.

Table 59. Output voltage characteristics

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{OL}^{(1)}$	Output low level voltage for an I/O pin	CMOS port ⁽²⁾ $I_{IO} = +8 \text{ mA}$ $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$	-	0.4	V
$V_{OH}^{(3)}$	Output high level voltage for an I/O pin		$V_{DD} - 0.4$	-	
$V_{OL}^{(1)}$	Output low level voltage for an I/O pin	TTL port ⁽²⁾ $I_{IO} = +8 \text{ mA}$ $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$	-	0.4	
$V_{OH}^{(3)}$	Output high level voltage for an I/O pin		2.4	-	
$V_{OL}^{(1)}$	Output low level voltage for an I/O pin	$I_{IO} = +20 \text{ mA}$ $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$	-	$1.3^{(4)}$	
$V_{OH}^{(3)}$	Output high level voltage for an I/O pin		$V_{DD} - 1.3^{(4)}$	-	
$V_{OL}^{(1)}$	Output low level voltage for an I/O pin	$I_{IO} = +6 \text{ mA}$ $1.8 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$	-	$0.4^{(4)}$	
$V_{OH}^{(3)}$	Output high level voltage for an I/O pin		$V_{DD} - 0.4^{(4)}$	-	
$V_{OL}^{(1)}$	Output low level voltage for an I/O pin	$I_{IO} = +4 \text{ mA}$ $1.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$	-	$0.4^{(5)}$	
$V_{OH}^{(3)}$	Output high level voltage for an I/O pin		$V_{DD} - 0.4^{(5)}$	-	

1. The I_{IO} current sunk by the device must always respect the absolute maximum rating specified in [Table 15](#) and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VSS} .
2. TTL and CMOS outputs are compatible with JEDEC standards JESD36 and JESD52.
3. The I_{IO} current sourced by the device must always respect the absolute maximum rating specified in [Table 15](#) and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VDD} .
4. Based on characterization data.
5. Guaranteed by design.

Input/output AC characteristics

The definition and values of input/output AC characteristics are given in [Figure 40](#) and [Table 60](#), respectively.

Unless otherwise specified, the parameters given in [Table 60](#) are derived from tests performed under the ambient temperature and V_{DD} supply voltage conditions summarized in [Table 17](#).

USB OTG full speed (FS) characteristics

This interface is present in both the USB OTG HS and USB OTG FS controllers.

Table 67. USB OTG full speed startup time

Symbol	Parameter	Max	Unit
$t_{STARTUP}^{(1)}$	USB OTG full speed transceiver startup time	1	μs

1. Guaranteed by design.

Table 68. USB OTG full speed DC electrical characteristics

Symbol	Parameter	Conditions	Min. ⁽¹⁾	Typ.	Max. ⁽¹⁾	Unit	
Input levels	V_{DD}	USB OTG full speed transceiver operating voltage	-	3.0 ⁽²⁾	-	3.6	V
	$V_{DI}^{(3)}$	Differential input sensitivity	I(USB_FS_DP/DM, USB_HS_DP/DM)	0.2	-	-	
	$V_{CM}^{(3)}$	Differential common mode range	Includes V_{DI} range	0.8	-	2.5	
	$V_{SE}^{(3)}$	Single ended receiver threshold	-	1.3	-	2.0	
Output levels	V_{OL}	Static output level low	R_L of 1.5 k Ω to 3.6 V ⁽⁴⁾	-	-	0.3	
	V_{OH}	Static output level high	R_L of 15 k Ω to $V_{SS}^{(4)}$	2.8	-	3.6	
R_{PD}	PA11, PA12, PB14, PB15 (USB_FS_DP/DM, USB_HS_DP/DM)	$V_{IN} = V_{DD}$	17	21	24	k Ω	
	PA9, PB13 (OTG_FS_VBUS, OTG_HS_VBUS)		0.65	1.1	2.0		
R_{PU}	PA12, PB15 (USB_FS_DP, USB_HS_DP)	$V_{IN} = V_{SS}$	1.5	1.8	2.1		
	PA9, PB13 (OTG_FS_VBUS, OTG_HS_VBUS)	$V_{IN} = V_{SS}$	0.25	0.37	0.55		

1. All the voltages are measured from the local ground potential.
2. The USB OTG full speed transceiver functionality is ensured down to 2.7 V but not the full USB full speed electrical characteristics which are degraded in the 2.7-to-3.0 V V_{DD} voltage range.
3. Guaranteed by design.
4. R_L is the load connected on the USB OTG full speed drivers.

Note: *When VBUS sensing feature is enabled, PA9 and PB13 should be left at their default state (floating input), not as alternate function. A typical 200 μA current consumption of the sensing block (current to voltage conversion to determine the different sessions) can be observed on PA9 and PB13 when the feature is enabled.*

Table 85. internal reference voltage (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$T_{\text{Coeff}}^{(2)}$	Temperature coefficient		-	30	50	ppm/°C
$t_{\text{START}}^{(2)}$	Startup time		-	6	10	µs

- Shortest sampling time can be determined in the application by multiple iterations.
- Guaranteed by design

Table 86. Internal reference voltage calibration values

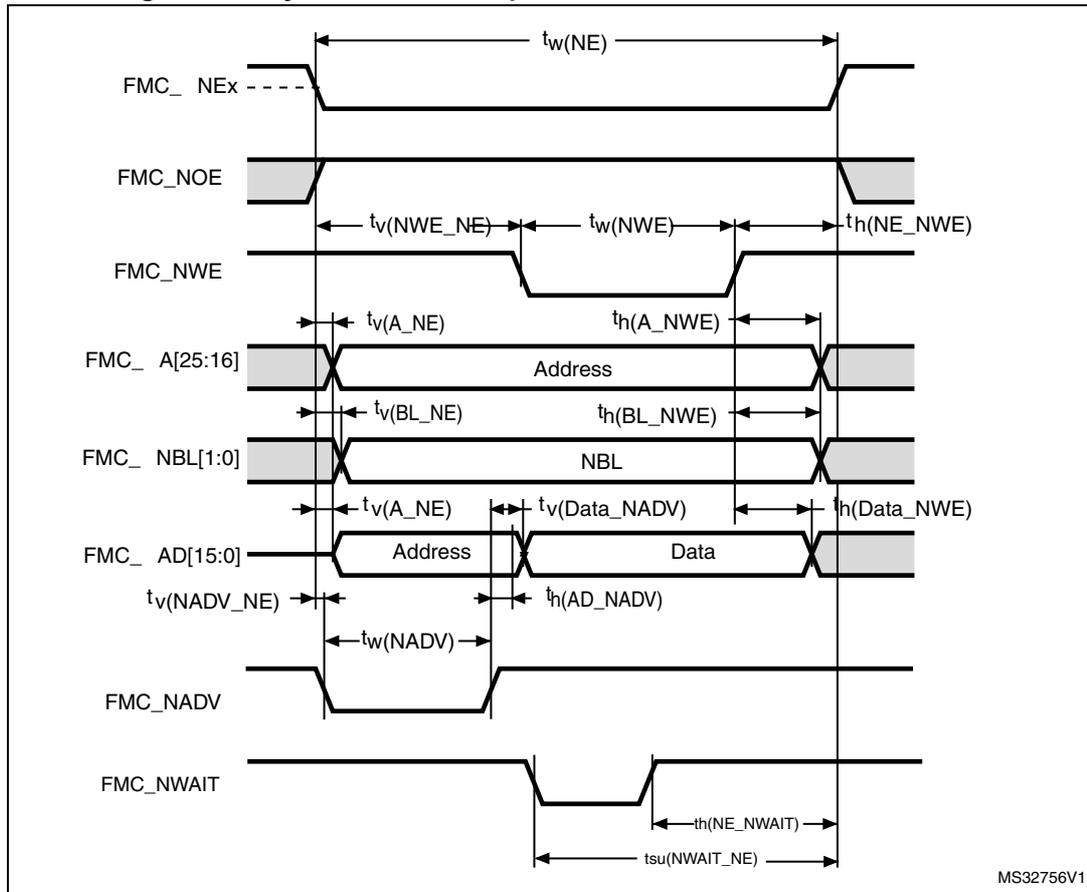
Symbol	Parameter	Memory address
$V_{\text{REFIN_CAL}}$	Raw data acquired at temperature of 30 °C $V_{\text{DDA}} = 3.3 \text{ V}$	0x1FFF 7A2A - 0x1FFF 7A2B

5.3.28 DAC electrical characteristics

Table 87. DAC characteristics

Symbol	Parameter	Min	Typ	Max	Unit	Comments
V_{DDA}	Analog supply voltage	1.7 ⁽¹⁾	-	3.6	V	-
$V_{\text{REF+}}$	Reference supply voltage	1.7 ⁽¹⁾	-	3.6	V	$V_{\text{REF+}} \leq V_{\text{DDA}}$
V_{SSA}	Ground	0	-	0	V	-
$R_{\text{LOAD}}^{(2)}$	Resistive load with buffer ON	5	-	-	kΩ	-
$R_{\text{O}}^{(2)}$	Impedance output with buffer OFF	-	-	15	kΩ	When the buffer is OFF, the Minimum resistive load between DAC_OUT and V_{SS} to have a 1% accuracy is 1.5 MΩ
$C_{\text{LOAD}}^{(2)}$	Capacitive load	-	-	50	pF	Maximum capacitive load at DAC_OUT pin (when the buffer is ON).
$\text{DAC_OUT}_{\text{min}}^{(2)}$	Lower DAC_OUT voltage with buffer ON	0.2	-	-	V	It gives the maximum output excursion of the DAC. It corresponds to 12-bit input code (0x0E0) to (0xF1C) at $V_{\text{REF+}} = 3.6 \text{ V}$ and (0x1C7) to (0xE38) at $V_{\text{REF+}} = 1.7 \text{ V}$
$\text{DAC_OUT}_{\text{max}}^{(2)}$	Higher DAC_OUT voltage with buffer ON	-	-	$V_{\text{DDA}} - 0.2$	V	
$\text{DAC_OUT}_{\text{min}}^{(2)}$	Lower DAC_OUT voltage with buffer OFF	-	0.5	-	mV	It gives the maximum output excursion of the DAC.
$\text{DAC_OUT}_{\text{max}}^{(2)}$	Higher DAC_OUT voltage with buffer OFF	-	-	$V_{\text{REF+}} - 1\text{LSB}$	V	
$I_{\text{VREF+}}^{(4)}$	DAC DC V_{REF} current consumption in quiescent mode (Standby mode)	-	170	240	µA	With no load, worst code (0x800) at $V_{\text{REF+}} = 3.6 \text{ V}$ in terms of DC consumption on the inputs
		-	50	75		With no load, worst code (0xF1C) at $V_{\text{REF+}} = 3.6 \text{ V}$ in terms of DC consumption on the inputs

Figure 62. Asynchronous multiplexed PSRAM/NOR write waveforms



MS32756V1

Table 94. Asynchronous multiplexed PSRAM/NOR write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$4T_{HCLK}$	$4T_{HCLK}+0.5$	ns
$t_{v(NWE_NE)}$	FMC_NEx low to FMC_NWE low	$T_{HCLK} - 1$	$T_{HCLK}+0.5$	
$t_{w(NWE)}$	FMC_NWE low time	$2T_{HCLK}$	$2T_{HCLK}+0.5$	
$t_{h(NE_NWE)}$	FMC_NWE high to FMC_NE high hold time	T_{HCLK}	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	0	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	0.5	1	
$t_{w(NADV)}$	FMC_NADV low time	$T_{HCLK} - 0.5$	$T_{HCLK}+ 0.5$	
$t_{h(AD_NADV)}$	FMC_AD (address) valid hold time after FMC_NADV high	$T_{HCLK} - 2$	-	
$t_{h(A_NWE)}$	Address hold time after FMC_NWE high	T_{HCLK}	-	
$t_{h(BL_NWE)}$	FMC_BL hold time after FMC_NWE high	$T_{HCLK} - 2$	-	
$t_{v(BL_NE)}$	FMC_NEx low to FMC_BL valid	-	2	
$t_{v(Data_NADV)}$	FMC_NADV high to Data valid	-	$T_{HCLK} +1.5$	
$t_{h(Data_NWE)}$	Data hold time after FMC_NWE high	$T_{HCLK} +0.5$	-	

1. Based on test during characterization.

Table 95. Asynchronous multiplexed PSRAM/NOR write-NWAIT timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$9T_{HCLK}$	$9T_{HCLK}+0.5$	ns
$t_{w(NWE)}$	FMC_NWE low time	$7T_{HCLK}$	$7T_{HCLK}+2$	
$t_{su(NWAIT_NE)}$	FMC_NWAIT valid before FMC_NEx high	$6T_{HCLK}+1.5$	-	
$t_{h(NE_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$4T_{HCLK}-1$	-	

1. Based on test during characterization.

Synchronous waveforms and timings

Figures 63 through 66 represent synchronous waveforms and Table 96 through Table 99 provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- BurstAccessMode = FMC_BurstAccessMode_Enable;
- MemoryType = FMC_MemoryType_CRAM;
- WriteBurst = FMC_WriteBurst_Enable;
- CLKDivision = 1;
- DataLatency = 1 for NOR Flash; DataLatency = 0 for PSRAM
- C_L = 30 pF on data and address lines. C_L = 10 pF on FMC_CLK unless otherwise specified.

In all timing tables, the T_{HCLK} is the HCLK clock period:

- For $2.7 V \leq V_{DD} \leq 3.6 V$, maximum FMC_CLK = 90 MHz at C_L = 30 pF (on FMC_CLK).
- For $1.71 V \leq V_{DD} < 1.9 V$, maximum FMC_CLK = 60 MHz at C_L = 10 pF (on FMC_CLK).

Table 116. UFBGA169 - 169-pin, 7 x 7 mm, 0.50 mm pitch, ultra fine pitch ball grid array package mechanical data (continued)

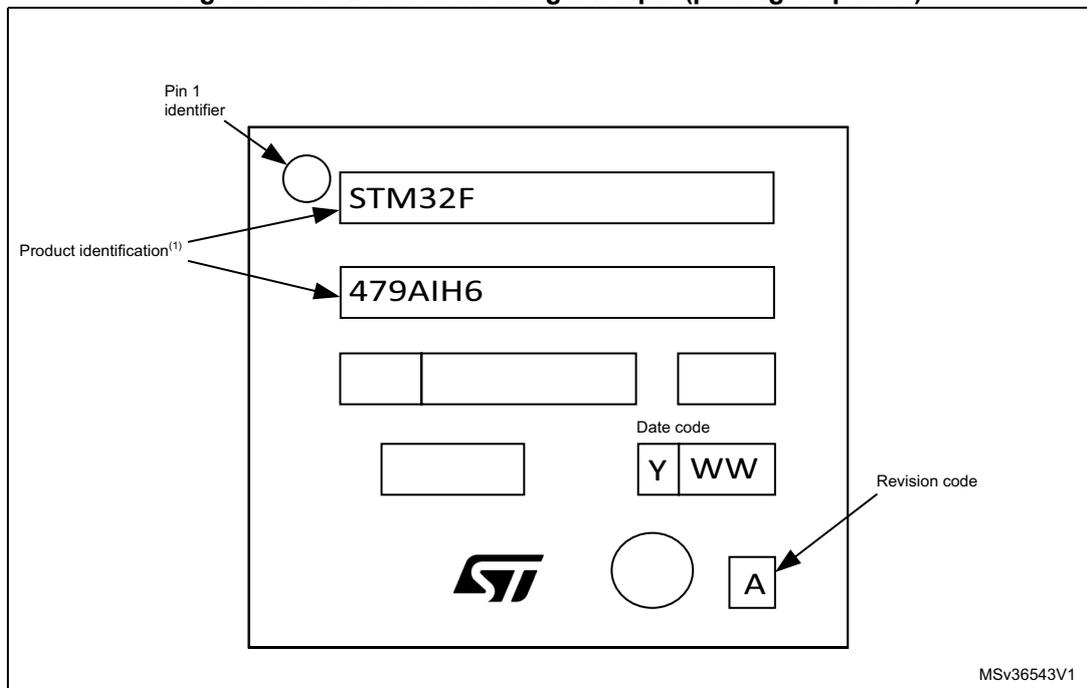
Symbol	millimeters			inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
ddd	-	-	0.100	-	-	0.0039
eee	-	-	0.150	-	-	0.0059
fff	-	-	0.050	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Device Marking for UFBGA169

The following figure gives an example of topside marking orientation versus ball A1 identifier location. Other optional marking or inset/upset marks, which identify the parts throughout supply chain operations, are not indicated below.

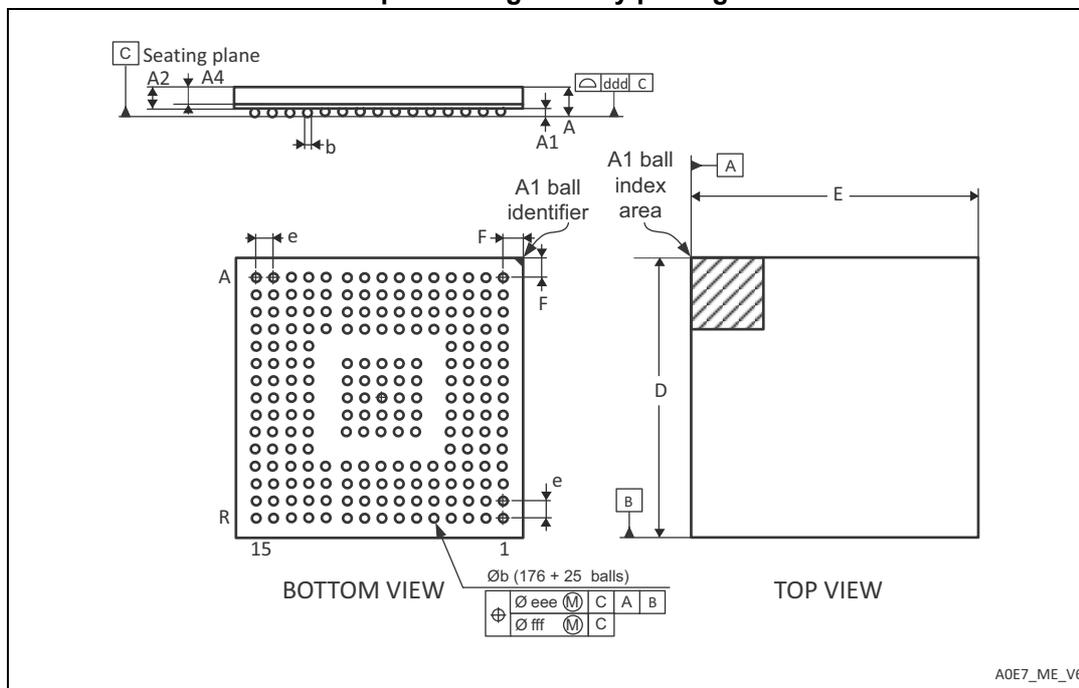
Figure 88. UFBGA169 marking example (package top view)



1. Parts marked as “ES”, “E” or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

6.6 UFBGA176+25 package information

Figure 92. UFBGA176+25 - 201-ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package outline



1. Drawing is not to scale.

Table 118. UFBGA176+25, - 201-ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package mechanical data

Symbol	millimeters			inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	0.460	0.530	0.600	0.0181	0.0209	0.0236
A1	0.050	0.080	0.110	0.0020	0.0031	0.0043
A2	0.400	0.450	0.500	0.0157	0.0177	0.0197
A4	0.270	0.320	0.370	0.0106	0.0126	0.0146
b	0.230	0.280	0.330	0.0091	0.0110	0.0130
D	9.950	10.000	10.050	0.3917	0.3937	0.3957
E	9.950	10.000	10.050	0.3917	0.3937	0.3957
e	-	0.650	-	-	0.0256	-
F	0.400	0.450	0.500	0.0157	0.0177	0.0197
ddd	-	-	0.080	-	-	0.0031
eee	-	-	0.150	-	-	0.0059
fff	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 93. UFBGA176+25 - 201-ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package recommended footprint

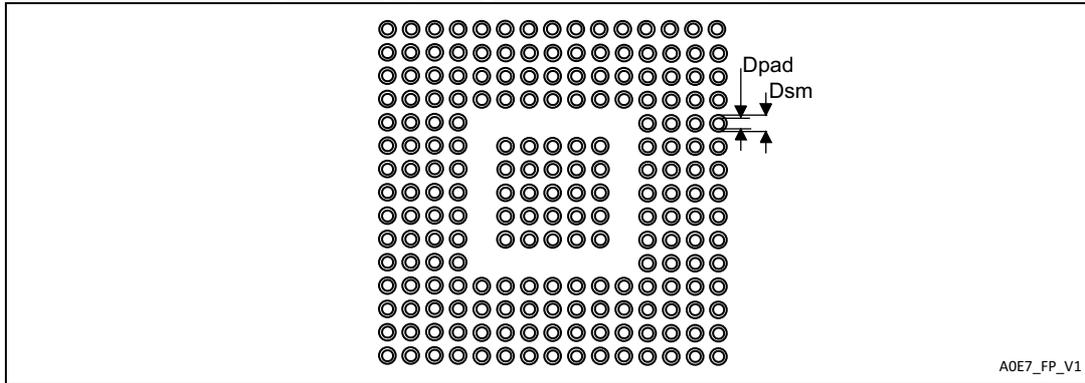
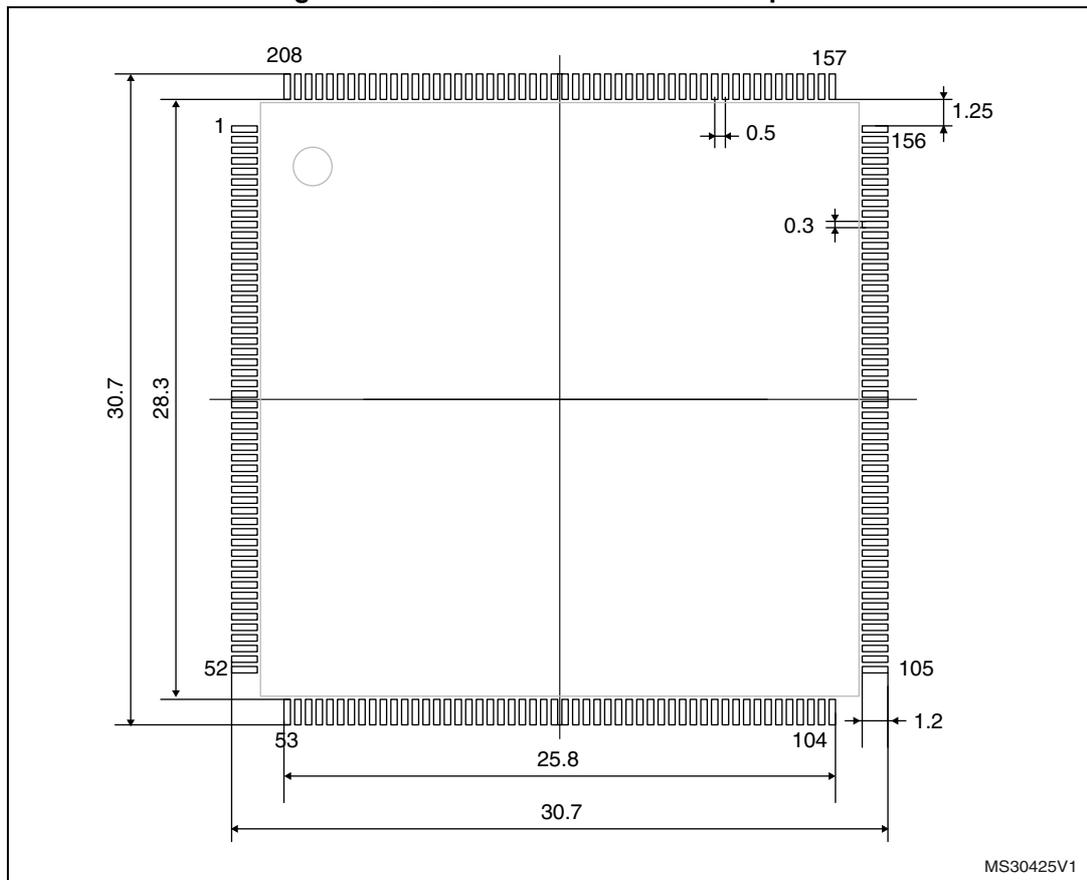


Table 119. UFBGA176+25 recommended PCB design rules (0.65 mm pitch BGA)

Dimension	Recommended values
Pitch	0.65 mm
Dpad	0.300 mm
Dsm	0.400 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.300 mm
Stencil thickness	Between 0.100 mm and 0.125 mm
Pad trace width	0.100 mm

Figure 95. LQFP208 recommended footprint



1. Dimensions are expressed in millimeters.