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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	8051
Core Size	8-Bit
Speed	40MHz
Connectivity	EBI/EMI, UART/USART
Peripherals	POR, WDT
Number of I/O	32
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	External
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/nuvoton-technology-corporation-america/w78e051b40dl

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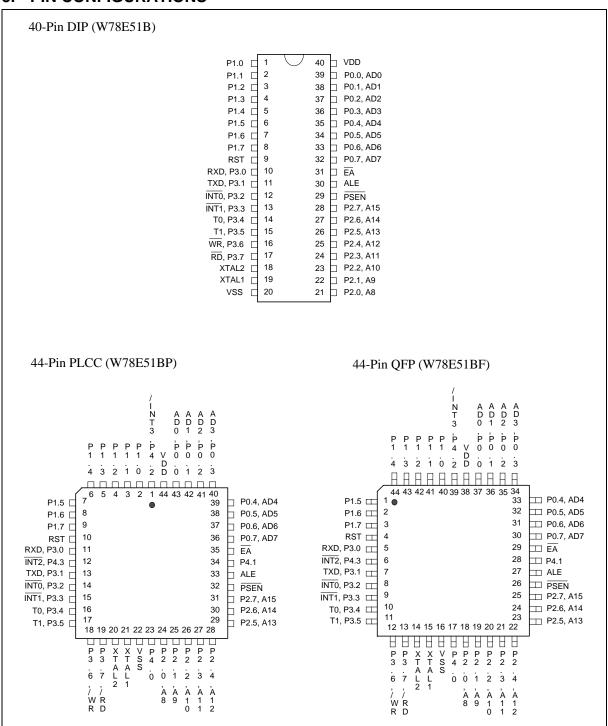
W78E51B



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3. PIN CONFIGURATIONS



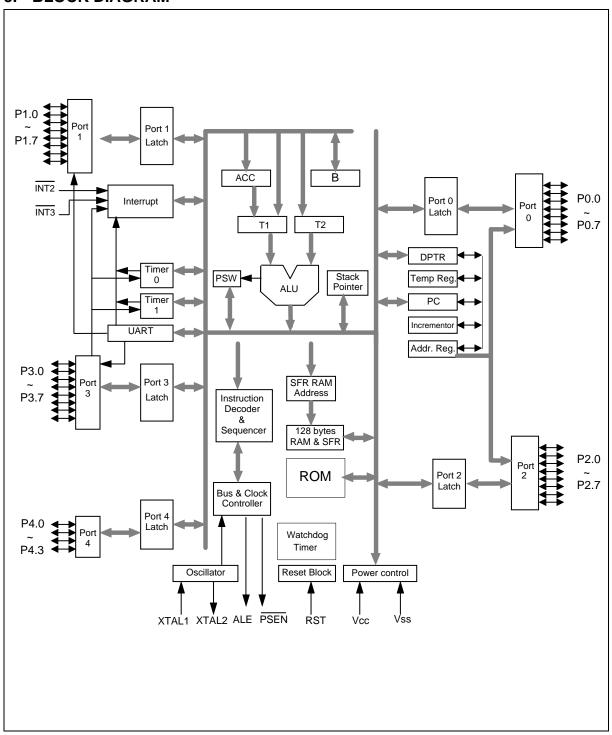


4. PIN DESCRIPTION

SYMBOL	DESCRIPTIONS
ĒĀ	EXTERNAL ACCESS ENABLE : This pin forces the processor to execute out of external ROM. It should be kept high to access internal ROM. The ROM address and data will not be presented on the bus if \overline{EA} pin is high and the program counter is within on-chip ROM area.
PSEN	PROGRAM STORE ENABLE: PSEN enables the external ROM data onto the Port 0 address/ data bus during fetch and MOVC operations. When internal ROM access is performed, no PSEN strobe signal outputs from this pin.
ALE	ADDRESS LATCH ENABLE: ALE is used to enable the address latch that separates the address from the data on Port 0.
RST	RESET : A high on this pin for two machine cycles while the oscillator is running resets the device.
XTAL1	CRYSTAL1: This is the crystal oscillator input. This pin may be driven by an external clock.
XTAL2	CRYSTAL2: This is the crystal oscillator output. It is the inversion of XTAL1.
Vss	GROUND: Ground potential
VDD	POWER SUPPLY: Supply voltage for operation.
P0.0-P0.7	PORT 0 : Port 0 is a bi-directional I/O port which also provides a multiplexed low order address/data bus during accesses to external memory. The pins of Port 0 are opendrain and should connect to pull up resistors if necessary while in programming.
P1.0-P1.7	PORT 1 : Port 1 is a bi-directional I/O port with internal pull-ups. The bits have alternate functions which are described below: T2(P1.0): Timer/Counter 2 external count input
	T2EX(P1.1): Timer/Counter 2 Reload/Capture control
P2.0-P2.7	PORT 2 : Port 2 is a bi-directional I/O port with internal pull-ups. This port also provides the upper address bits for accesses to external memory.
	PORT 3: Port 3 is a bi-directional I/O port with internal pull-ups. All bits have alternate functions, which are described below: RXD(P3.0): Serial Port receiver input TXD(P3.1): Serial Port transmitter output
D2 0 D2 7	INT0 (P3.2): External Interrupt 0
P3.0-P3.7	INT1(P3.3): External Interrupt 1 T0(P3.4): Timer 0 External Input T1(P3.5): Timer 1 External Input
	WR (P3.6) : External Data Memory Write Strobe
	RD (P3.7) : External Data Memory Read Strobe
P4.0-P4.3	PORT 4: Another bit-addressable bidirectional I/O port P4. P4.3 and P4.2 are alternative function pins. It can be used as general I/O port or external interrupt input sources (INT2 /INT3).



5. BLOCK DIAGRAM





Port 4

Another bit-addressable port P4 is also available and only 4 bits (P4<3:0>) can be used. This port address is located at 0D8H with the same function as that of port P1, except the P4.3 and P4.2 are alternative function pins. It can be used as general I/O pins or external interrupt input sources ($\overline{\text{INT2}}$, $\overline{\text{INT3}}$).

Example:

P4 REG 0D8H

MOV P4, #0AH ; Output data "A" through P4.0–P4.3. MOV A, P4 ; Read P4 status to Accumulator.

ORL P4,#00000001B; Set bit P4.0 ANL P4,#11111101B; Clear bit P4.1

6.2 Reduce EMI Emission

Because of on-chip Flash EPROM, when a program is running in internal ROM space, the ALE will be unused. The transition of ALE will cause noise, so it can be turned off to reduce the EMI emission if it is useless. Turning off the ALE signal transition only requires setting the bit 0 of the AUXR SFR, which is located at 08Eh. When ALE is turned off, it will be reactivated when the program accesses external ROM/RAM data or jumps to execute an external ROM code. The ALE signal will turn off again after it has been completely accessed or the program returns to internal ROM code space. The AO bit in the AUXR register, when set, disables the ALE output. In order to reduce EMI emission from oscillation circuitry, W78E51B allows user to diminish the gain of on-chip oscillator amplifiers by using programmer to clear the B7 bit of security register. Once B7 is set to 0, a half of gain will be decreased. Care must be taken if user attempts to diminish the gain of oscillator amplifier, reducing a half of gain may effect to external crystal operating improperly at high frequency above 24 MHz. The value of R and C1, C2 may need adjustment while running at lower gain.

***AUXR - Auxiliary register (8EH)

-		-	-	-	-	AO	ı
---	--	---	---	---	---	----	---

AO: Turn off ALE output.

Power-off Flag

***PCON - Power control (87H)

	1	1	1				
-	-	-	POF	GF1	GF0	PD	IDL

POF: Power off flag. Bit is set by hardware when power on reset. It can be cleared by software to determine chip reset is a warm boot or cold boot.

GF1, GF0: These two bits are general-purpose flag bits for the user.

PD: Power down mode bit. Set it to enter power down mode.

IDL: Idle mode bit. Set it to enter idle mode.

The power-off flag is located at PCON.4. This bit is set when VDD has been applied to the part. It can be used to determine if a reset is a warm boot or a cold boot if it is subsequently reset by software.



6.3 Watchdog Timer

The Watchdog timer is a free-running timer which can be programmed by the user to serve as a system monitor, a time-base generator or an event timer. It is basically a set of dividers that divide the system clock. The divider output is selectable and determines the time-out interval. When the time-out occurs a system reset can also be caused if it is enabled. The main use of the Watchdog timer is as a system monitor. This is important in real-time control applications. In case of power glitches or electromagnetic interference, the processor may begin to execute errant code. If this is left unchecked the entire system may crash. The watchdog time-out selection will result in different time-out values depending on the clock speed. The Watchdog timer will de disabled on reset. In general, software should restart the Watchdog timer to put it into a known state. The control bits that support the Watchdog timer are discussed below.

Watchdog Timer Control Register

7 Bit: 0 6 5 3 2 1 **ENW CLRW** WIDL PS₂ PS₁ PS₀ Mnemonic: WDTC Address: 8FH

ENW: Enable watch-dog if set.

CLRW: Clear watch-dog timer and prescaler if set. This flag will be cleared automatically

WIDL: If this bit is set, watch-dog is enabled under IDLE mode. If cleared, watch-dog is disabled under IDLE mode. Default is cleared.

PS2, PS1, PS0: Watch-dog prescaler timer select. Prescaler is selected when set PS2~0 as follows:

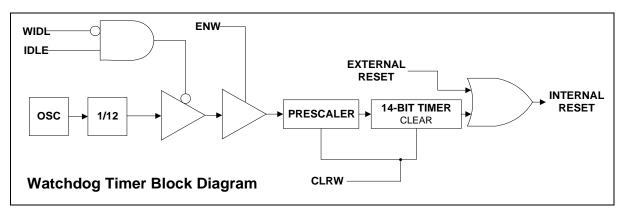
PS2 PS1 PS0	PRESCALER SELECT
0 0 0	2
0 1 0	4
0 0 1	8
0 1 1	16
1 0 0	32
1 0 1	64
1 1 0	128
1 1 1	256

The time-out period is obtained using the following equation:

$$\frac{1}{OSC} \times 2^{14} \times PRESCALER \times 1000 \times 12 \text{ mS}$$

Before Watchdog time-out occurs, the program must clear the 14-bit timer by writing 1 to WDTC.6 (CLRW). After 1 is written to this bit, the 14-bit timer, prescaler and this bit will be reset on the next instruction cycle. The Watchdog timer is cleared on reset.





Typical Watch-dog time-out period when OSC = 20 MHz

PS2 PS1 PS0	WATCHDOG TIME-OUT PERIOD
0 0 0	19.66 mS
0 1 0	39.32 mS
0 0 1	78.64 mS
0 1 1	157.28 mS
1 0 0	314.57 mS
1 0 1	629.14 mS
1 1 0	1.25 S
1 1 1	2.50 S

6.4 Clock

The W78E51B is designed to be used with either a crystal oscillator or an external clock. Internally, the clock is divided by two before it is used. This makes the W78E51B relatively insensitive to duty cycle variations in the clock. The W78E51B incorporates a built-in crystal oscillator. To make the oscillator work, a crystal must be connected across pins XTAL1 and XTAL2. In addition, a load capacitor must be connected from each pin to ground. An external clock source should be connected to pin XTAL1. Pin XTAL2 should be left unconnected. The XTAL1 input is a CMOS-type input, as required by the crystal oscillator.

6.5 Power Management

Idle Mode

The idle mode is entered by setting the IDL bit in the PCON register. In the idle mode, the internal clock to the processor is stopped. The peripherals and the interrupt logic continue to be clocked. The processor will exit idle mode when either an interrupt or a reset occurs.

Power-down Mode

When the PD bit of the PCON register is set, the processor enters the power-down mode. In this mode all of the clocks are stopped, including the oscillator. The only way to exit power-down mode is by a reset.



6.6 Reset

The external RESET signal is sampled at S5P2. To take effect, it must be held high for at least two machine cycles while the oscillator is running. An internal trigger circuit in the reset line is used to deglitch the reset line when the W78E51B is used with an external RC network. The reset logic also has a special glitch removal circuit that ignores glitches on the reset line.

During reset, the ports are initialized to FFH, the stack pointer to 07H, PCON (with the exception of bit 4) to 00H, and all of the other SFR registers except SBUF to 00H. SBUF is not reset.

6.7 On-Chip ROM Characteristics

The W78E51B has several modes to program the on-chip Flash EPROM. All these operations are configured by the pins RST, ALE, $\overline{\text{PSEN}}$, A9CTRL(P3.0), A13CTRL(P3.1), A14CTRL(P3.2), OECTRL(P3.3), $\overline{\text{CE}}$ (P3.6), $\overline{\text{OE}}$ (P3.7), A0(P1.0) and VPP($\overline{\text{EA}}$). Moreover, the A15–A0(P2.7–P2.0, P1.7–P1.0) and the D7–D0(P0.7–P0.0) serve as the address and data bus respectively for these operations.

6.7.1 Read Operation

This operation is supported for customer to read their code and the Security bits. The data will not be valid if the Lock bit is programmed to low.

6.7.2 Output Disable Condition

When the \overline{OE} is set to high, no data output appears on the D7..D0.

6.7.3 Program Operation

This operation is used to program the data to ROM and the security bits. Program operation is done when the VPP is reach to VCP (12.5V) level, \overline{CE} set to low, and \overline{OE} set to high.

6.7.4 Program Verify Operation

All the programming data must be checked after program operations. This operation should be performed after each byte is programmed; it will ensure a substantial program margin.

6.7.5 Erase Operation

An erase operation is the only way to change data from 0 to 1. This operation will erase all the ROM cells and the security bits from 0 to 1. This erase operation is done when the VPP is reach to VEP level, \overline{CE} set to low, and \overline{OE} set to high.

6.7.6 Erase Verify Operation

After an erase operation, all of the bytes in the chip must be verified to check whether they have been successfully erased to 1 or not. The erase verify operation automatically ensures a substantial erase margin. This operation will be done after the erase operation if VPP = VEP (14.5V), \overline{CE} is high and \overline{OE} is low.



6.7.7 Program/Erase Inhibit Operation

This operation allows parallel erasing or programming of multiple chips with different data. When $P3.6(\overline{CE}) = VIH$, $P3.7(\overline{OE}) = VIH$, erasing or programming of non-targeted chips is inhibited. So, except for the P3.6 and P3.7 pins, the individual chips may have common inputs.

OPERATIONS	P3.0 (A9 CTRL)	P3.1 (A13 CTRL)	P3.2 (A14 CTRL)	P3.3 (OE CTRL)	P3.6 (CE)	P3.7 (OE)	EA (VPP)	P2, P1 (A15A0)	P0 (D7D0)	NOTE
Read	0	0	0	0	0	0	1	Address	Data Out	
Output Disable	0	0	0	0	0	1	1	X	Hi-Z	
Program	0	0	0	0	0	1	VCP	Address	Data In	
Program Verify	0	0	0	0	1	0	VCP	Address	Data Out	@3
Erase	1	0	0	0	0	1	VEP	A0:0, others: X	Data In 0FFH	@4
Erase Verify	1	0	0	0	1	0	VEP	Address	Data Out	@5
Program/Erase Inhibit	Х	0	0	0	1	1	VCP/ VEP	Х	Х	

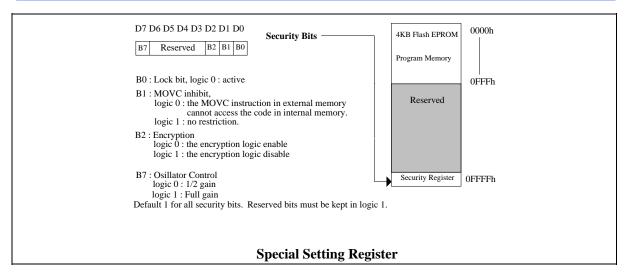
Notes:

- 1. All these operations happen in RST = VIH, ALE = VIL and \overline{PSEN} = VIH.
- 2. VCP = 12.5V, VEP = 14.5V, VIH = VDD, VIL = Vss.
- 3. The program verify operation follows behind the program operation.
- 4. This erase operation will erase all the on-chip Flash EPROM cells and the Security bits.
- 5. The erase verify operation follows behind the erase operation.

7. SECURITY BITS

During the programmer operation mode, the Flash EPROM can be programmed and verified repeatedly. Until the code inside the Flash EPROM is confirmed OK, the code can be protected. The protection of Flash EPROM and those operations on it are described below. The W78E51B has a Special Setting Register, the Security Register, which can be accessed in normal mode. The register can only be accessed from the Flash EPROM operation mode. Those bits of the Security Registers can not be changed once they have been programmed from high to low. They can only be reset through erase-all operation. The Security Register is addressed in the Flash EPROM operation mode by address #0FFFFh.





7.1 Lock Bit

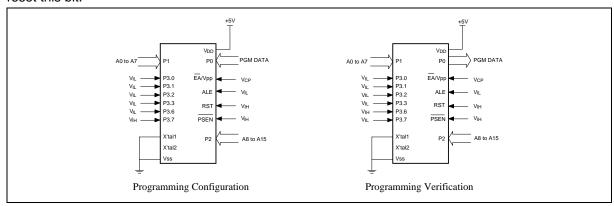
This bit is used to protect the customer's program code in the W78E51B. It may be set after the programmer finishes the programming and verifies sequence. Once this bit is set to logic 0, both the on-chip ROM data and Special Setting Registers can not be accessed again.

7.2 MOVC Inhibit

This bit is used to restrict the accessible region of the MOVC instruction. It can prevent the MOVC instruction in external program memory from reading the internal program code. When this bit is set to logic 0, a MOVC instruction in external program memory space will be able to access code only in the external memory, not in the internal memory. A MOVC instruction in internal program memory space will always be able to access the ROM data in both internal and external memory. If this bit is logic 1, there are no restrictions on the MOVC instruction.

7.3 Encryption

This bit is used to enable/disable the encryption logic for code protection. Once encryption feature is enabled, the data presented on port 0 will be encoded via encryption logic. Only whole chip erase will reset this bit.





8. ELECREICAL CHARACTERISTICS

8.1 Absolute Maximum Ratings

PARAMETER	SYMBOL	MIN.	MAX.	UNIT
DC Power Supply	VDD-VSS	-0.3	+7.0	V
Input Voltage	VIN	Vss -0.3	VDD +0.3	V
Operating Temperature	TA	0	70	°C
Storage Temperature	Тѕт	-55	+150	°C

Note: Exposure to conditions beyond those listed under Absolute Maximum Ratings may adversely affect the life and reliability of the device.

8.2 D.C. Characteristics

Vcc–Vss = 5V $\pm 10\%$, TA = 25° C, unless otherwise specified.

PARAMETER	SYMBOL	TEST CONDITIONS	SPECIFI	UNIT	
FARAMETER	STIMBOL	TEST CONDITIONS	MIN.	MAX.	UNIT
Operating Voltage	VDD		4.5	5.5	V
Operating Current	IDD	No load VDD = 5.5V	-	20	mA
Idle Current	IDLE	Idle mode VDD = 5.5V	-	6	mA
Power Down Current	IPWDN	Power-down mode VDD = 5.5V	-	50	μΑ
Input Current P1, P2, P3, P4	lin1	VDD = 5.5V VIN = 0V or VDD	-50	+10	μА
Logical 1-to-0 Transition Current P1, P2, P3 ^(*1) , P4	lτι	VDD = 5.5V $VIN = 2.0V$ (*1)	-550	-	μΑ
Input Current RST (*2)	lin2	VDD = 5.5V VIN = VDD	-10	+300	μА
Input Leakage Current P0, EA	ILK	VDD = 5.5V 0V < VIN < VDD	-10	+10	μΑ
Output Low Voltage P1, P2, P3, P4	VOL1	VDD = 4.5V IOL1 = +2 mA	-	0.45	V
Output Low Voltage ALE, PSEN, P0 (*3)	VOL2	VDD = 4.5V IOL2 = +4 mA	-	0.45	V
Output High Voltage P1, P2, P3, P4	Voн1	VDD = 4.5V IOH1 = -100 μA	2.4	-	V
Output High Voltage ALE, PSEN, P0 (*3)	VOH2	VDD = 4.5V IOH2 = -400 μA	2.4	-	V



DC Characteristics, continued

PARAMETER	SYMBOL	TEST CONDITIONS	SPECIF	UNIT		
TANAMETEN	31MBOL 1E31 CONDITIONS		MIN. MAX.			
Input Low Voltage (Except RST)	VIL1	VDD = 4.5V	0	0.8	٧	
Input Low Voltage RST ^(*4)	VIL2	VDD = 4.5V	0	0.8	V	
Input Low Voltage XTAL1 (*4)	VIL3	VDD = 4.5V	0	0.8	V	
Input High Voltage (Except RST)	VIH1	VDD = 4.5V	2.4	VDD +0.2	V	
Sink Current P1, P2, P3, P4	ISK1	VDD = 4.5V Vs = 0.45V	4	12	mA	
Input High Voltage RST ^(*4)	VIH2	VDD = 4.5V	0.67 VDD	VDD +0.2	٧	
Input High Voltage XTAL1 (*4)	VIH3	VDD = 4.5V	0.67 VDD	VDD +0.2	٧	
Sink Current P0, ALE, PSEN (*3)	ISK2	VDD = 4.5V Vs = 0.45V	8	16	mA	
Source Current P1, P2, P3, P4	ISR1	$VDD = 4.5V$ $V_S = 2.4V$	-100	-250	uA	
Source Current P0, ALE, PSEN (*3)	ISR2	$VDD = 4.5V$ $V_s = 2.4V$	-8	-14	mA	

Notes:

8.3 A.C. Characteristics

The AC specifications are a function of the particular process used to manufacture the part, the ratings of the I/O buffers, the capacitive load, and the internal routing capacitance. Most of the specifications can be expressed in terms of multiple input clock periods (TcP), and actual parts will usually experience less than a ± 20 nS variation. The numbers below represent the performance expected from a 0.6micron CMOS process when using 2 and 4 mA output buffers.

^{*1.} Pins P1, P2 and P3 source a transition current when they are being externally driven from 1 to 0. The transition current reaches its maximum value when VIN is approximately 2V.

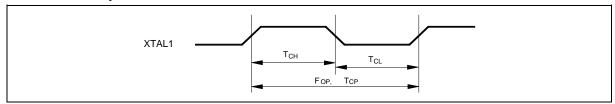
^{*2.} RST pin has an internal pull-down resistor.

^{*3.} P0, ALE, PSEN are in the external access memory mode.

^{*4.} XTAL1 is a CMOS input and RST is a Schmitt trigger input.



8.3.1 Clock Input Waveform



PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT	NOTES
Operating Speed	FOP	0	-	40	MHz	1
Clock Period	Тср	25	-	-	nS	2
Clock High	Тсн	10	-	-	nS	3
Clock Low	TCL	10	-	-	nS	3

Notes:

- 1. The clock may be stopped indefinitely in either state.
- 2. The Tcp specification is used as a reference in other specifications.
- 3. There are no duty cycle requirements on the XTAL1 input.

8.3.2 Program Fetch Cycle

PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT	NOTES
Address Valid to ALE Low	TAAS	1 Tcp -∆	1	-	nS	4
Address Hold from ALE Low	Таан	1 Tcp -∆	1	-	nS	1, 4
ALE Low to PSEN Low	TAPL	1 Tcp -Δ	ı	ı	nS	4
PSEN Low to Data Valid	TPDA	-	1	2 TCP	nS	2
Data Hold after PSEN High	TPDH	0	ı	1 Tcp	nS	3
Data Float after PSEN High	TPDZ	0	-	1 Tcp	nS	
ALE Pulse Width	TALW	2 Tcp -∆	2 Tcp	-	nS	4
PSEN Pulse Width	TPSW	3 TCP -∆	3 Тср	-	nS	4

Notes:

- 1. P0.0-P0.7, P2.0-P2.7 remain stable throughout entire memory cycle.
- 2. Memory access time is 3 Tcp.
- 3. Data have been latched internally prior to PSEN going high.
- 4. " Δ " (due to buffer driving delay and wire loading) is 20 nS.

8.3.3 Data Read Cycle

PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT	NOTES
ALE Low to RD Low	TDAR	3 Tcp -Δ	ı	3 Tcp +∆	nS	1, 2
RD Low to Data Valid	TDDA	-	-	4 TCP	nS	1
Data Hold from RD High	TDDH	0	-	2 Tcp	nS	
Data Float from RD High	TDDZ	0	-	2 Tcp	nS	
RD Pulse Width	TDRD	6 Tcp -∆	6 Tcp	-	nS	2

Notes:

- 1. Data memory access time is 8 Tcp.
- 2. " Δ " (due to buffer driving delay and wire loading) is 20 nS.



8.3.4 Data Write Cycle

PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT
ALE Low to WR Low	TDAW	3 Tcp -Δ	-	3 Tcp +∆	nS
Data Valid to WR Low	TDAD	1 Tcp -Δ	-	-	nS
Data Hold from WR High	Towd	1 Tcp -Δ	-	-	nS
WR Pulse Width	Towr	6 Tcp -Δ	6 Тср	-	nS

Note: "\Delta" (due to buffer driving delay and wire loading) is 20 nS.

8.3.5 Port Access Cycle

PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT
Port Input Setup to ALE Low	TPDS	1 Tcp	ı	ı	nS
Port Input Hold from ALE Low	TPDH	0	-	-	nS
Port Output to ALE	TPDA	1 Tcp	-	-	nS

Note: Ports are read during S5P2, and output data becomes available at the end of S6P2. The timing data are referenced to ALE, since it provides a convenient reference.

8.3.6 Program Operation

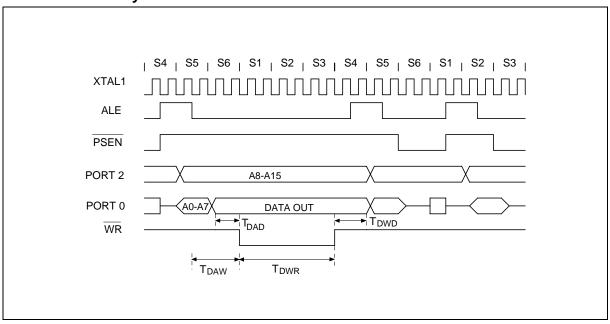
PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT
VPP Setup Time	Tvps	2.0	-	-	μS
Data Setup Time	TDS	2.0	-	-	μS
Data Hold Time	TDH	2.0	-	-	μS
Address Setup Time	Tas	2.0	-	-	μS
Address Hold Time	Тан	0	-	-	μS
CE Program Pulse Width for Program Operation	TPWP	290	300	310	μS
OECTRL Setup Time	Tocs	2.0	-	-	μS
OECTRL Hold Time	Тосн	2.0	-	-	μS
OE Setup Time	Toes	2.0	-	-	μS
OE High to Output Float	TDFP	0	-	130	nS
Data Valid from OE	TOEV	-	-	150	nS

Note: Flash data can be accessed only in flash mode. The RST pin must pull in VIH status, the ALE pin must pull in VIL status, and the PSEN pin must pull in VIH status.

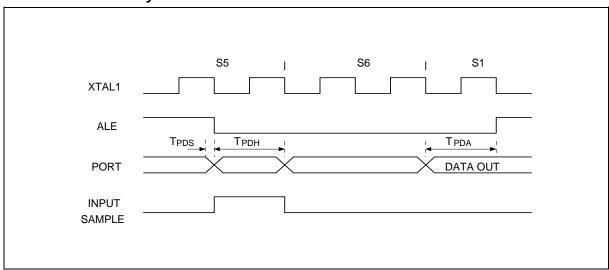


Timing Waveforms, continued

9.3 Data Write Cycle



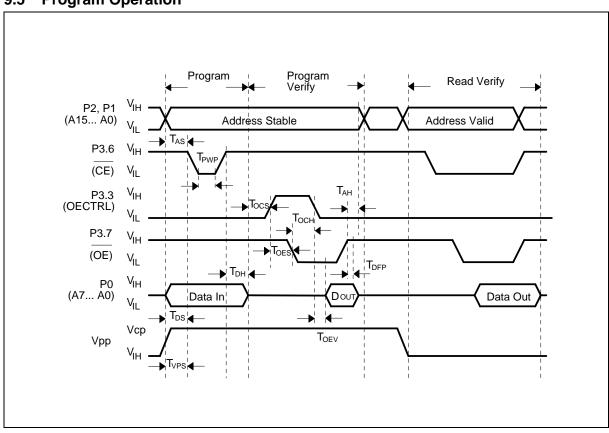
9.4 Port Access Cycle





Timing Waveforms, continued

9.5 Program Operation





10. TYPICAL APPLICATION CIRCUITS

10.1 Expanded External Program Memory and Crystal

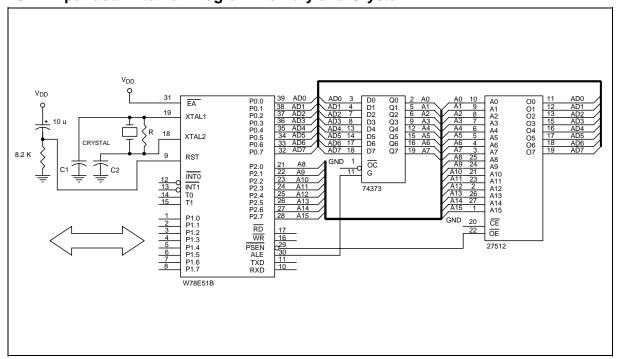


Figure A

CRYSTAL	C1	C2	R
16 MHz	30P	30P	-
24 MHz	15P	15P	-
33 MHz	10P	10P	6.8K
40 MHz	5P	5P	4.7K

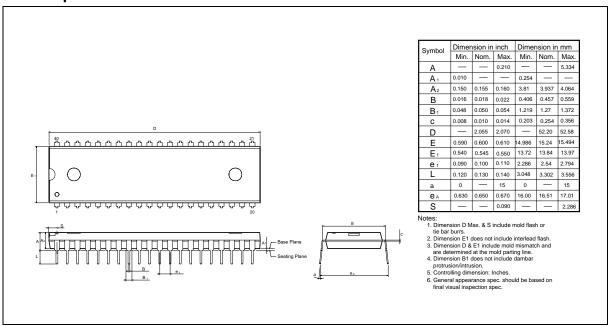
Above table shows the reference values for crystal applications (full gain).

Note: C1, C2, R components refer to Figure A.

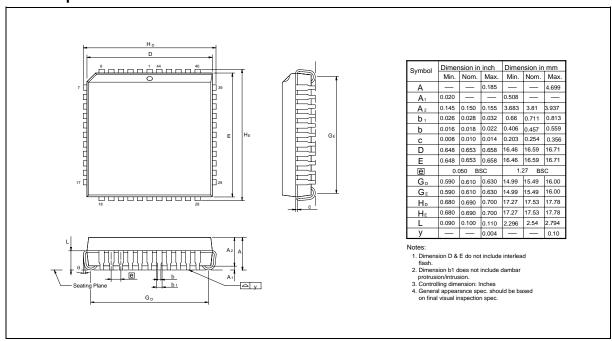


11. PACKAGE DIMENSIONS

11.1 40-pin DIP



11.2 44-pin PLCC



0.5

0.254

10.1

10.1

0.952

13.45 13.45

0.95

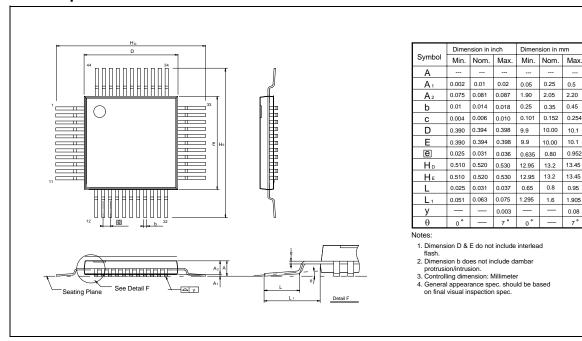
1.905

0.08



Package Dimensions, continued

11.3 44-pin PQFP





12. REVISION HISTORY

VERSION	DATE	PAGE	DESCRIPTION
A4	July, 2001	-	Formerly issued
A5	June, 2004	3	Revise part number in the item of packages
A6	April 20, 2005	25	Add Important Notice
A7	Sep. 6, 2005	3	Add lead free (RoHS) parts

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Headquarters

No. 4, Creation Rd. III, Science-Based Industrial Park, Hsinchu, Taiwan TEL: 886-3-5770066 FAX: 886-3-5665577 http://www.winbond.com.tw/

Taipei Office 9F, No.480, Rueiguang Rd., Neihu District, Taipei, 114, Taiwan, R.O.C. TEL: 886-2-8177-7168 FAX: 886-2-8751-3579 Winbond Electronics Corporation America Winbond Electronics (Shanghai) Ltd.

2727 North First Street, San Jose, CA 95134, U.S.A. TEL: 1.408.9436666 FAX: 1.408.5441798

Winbond Electronics Corporation Japan 7F Daini-ueno BLDG, 3-7-18 Shinyokohama Kohoku-ku, Yokohama, 222-0033

- 25 -

27F, 2299 Yan An W. Rd. Shanghai, 200336 China TEL: 86-21-62365999 FAX: 86-21-62365998

Winbond Electronics (H.K.) Ltd. Unit 9-15, 22F, Millennium City, No. 378 Kwun Tong Rd., Kowloon, Hong Kong TEL: 852-27513100 FAX: 852-27552064

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TEL: 81-45-4781881

FAX: 81-45-4781800

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