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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	F <sup>2</sup> MC-8L
Core Size	8-Bit
Speed	10MHz
Connectivity	EBI/EMI, Serial I/O, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	53
Program Memory Size	16KB (16K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 6V
Data Converters	A/D 8x10b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-BQFP
Supplier Device Package	64-QFP (14x20)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/mb89635rpf-g-1494e1">https://www.e-xfl.com/product-detail/infineon-technologies/mb89635rpf-g-1494e1</a>

## *8-bit Proprietary Microcontroller*

CMOS

# F<sup>2</sup>MC-8L MB89630R Series

## MB89635R/636R/637R/P637/PV630

### ■ OUTLINE

The MB89630R series has been developed as a general-purpose version of the F<sup>2</sup>MC\*-8L family consisting of proprietary 8-bit, single-chip microcontrollers.

In addition to a compact instruction set, the microcontrollers contain a variety of peripheral functions such as dual-clock control system, five operating speed control stages, a UART, timers, a PWM timer, a serial interface, an A/D converter, an external interrupt, and a watch prescaler.

\* : F<sup>2</sup>MC is the abbreviation for Fujitsu Flexible Microcontroller.

### ■ FEATURES

- High-speed operating capability at low voltage
- Minimum execution time: 0.4  $\mu$ s@3.5 V, 0.8  $\mu$ s@2.7 V
- F<sup>2</sup>MC-8L family CPU core

Instruction set optimized for controllers	{	Multiplication and division instructions
		16-bit arithmetic operations
		Test and branch instructions
		Bit manipulation instructions, etc.

- Five types of timers
  - 8-bit PWM timer: 2 channels (Also usable as a reload timer)
  - 8-bit pulse-width count timer (Continuous measurement capable, applicable to remote control, etc.)
  - 16-bit timer/counter
  - 21-bit timebase timer

(Continued)

For the information for microcontroller supports, see the following web site.

<http://edevic.fujitsu.com/micom/en-support/>

*(Continued)*

- UART  
CLK-synchronous/CLK-asynchronous data transfer capable (6, 7, and 8 bits)
- Serial interface  
Switchable transfer direction to allows communication with various equipment.
- 10-bit A/D converter  
Start by an external input capable
- External interrupt: 4 channels  
Four channels are independent and capable of wake-up from low-power consumption modes (with an edge detection function).
- Low-power consumption modes  
Stop mode (Oscillation stops to minimize the current consumption.)  
Sleep mode (The CPU stops to reduce the current consumption to approx. 1/3 of normal.)  
Subclock mode  
Watch mode
- Bus interface function  
With hold and ready function

# MB89630R Series

(Continued)

Part number Item	MB89635R	MB89636R	MB89637R	MB89P637	MB89PV630
External interrupt input	4 independent channels (edge selection, interrupt vector, source flag). Rising edge/falling edge selectable Used also for wake-up from stop/sleep mode. (Edge detection is also permitted in stop mode.)				
Standby mode	Sleep mode, stop mode, watch mode, and subclock mode				
Process	CMOS				
Operating voltage*	2.2 V to 6.0 V			2.7 V to 6.0 V	
EPROM for use					MBM27C256A-20CZ MBM27C256A-20TV

\* : Varies with conditions such as the operating frequency. (See section “■ Electrical Characteristics.”)  
In the case of the MB89PV630, the voltage varies with the restrictions of the EPROM for use.

## ■ PACKAGE AND CORRESPONDING PRODUCTS

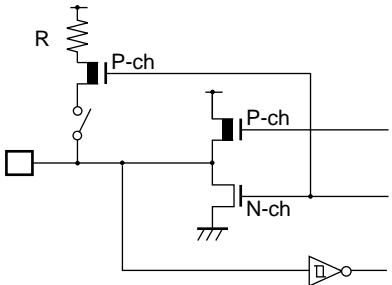
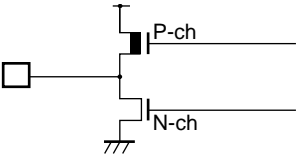
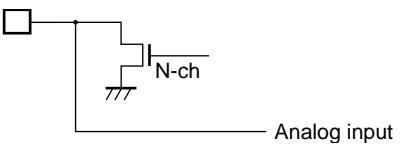
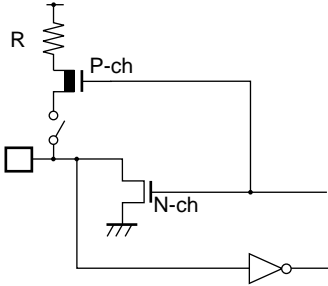
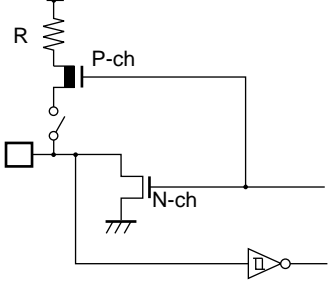
Package	MB89635R	MB89636R MB89637R	MB89P637	MB89PV630
DIP-64P-M01	○	○	○	×
FPT-64P-M06	○	○	○	×
FPT-64P-M23	○	○	×	×
MQP-64C-P01	×	×	×	○
MDP-64C-P02	×	×	×	○

○ : Available    ×: Not available

Note: For more information about each package, see section “■ Package Dimensions.”

# MB89630R Series

(Continued)

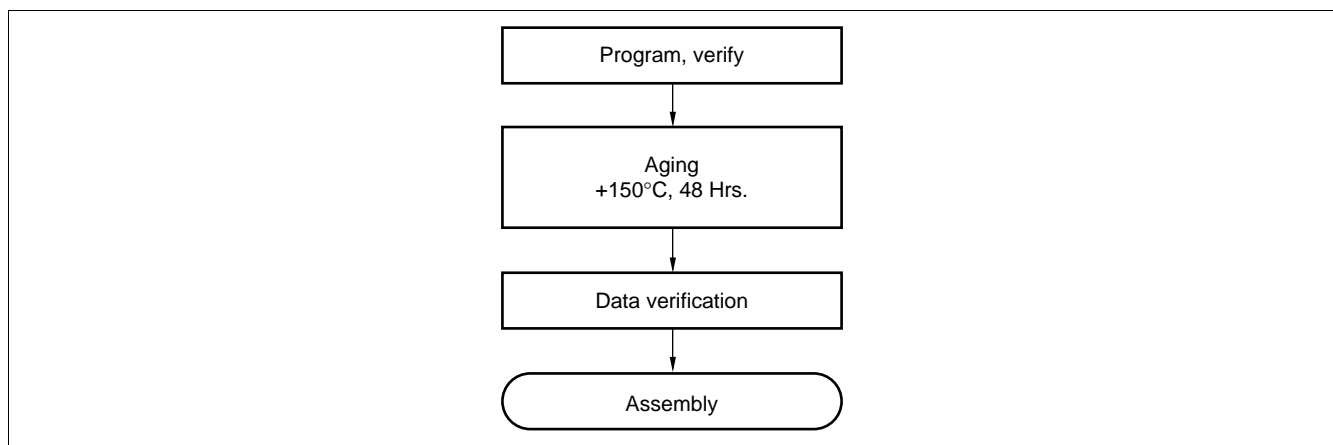
Type	Circuit	Remarks
G		<ul style="list-style-type: none"> <li>• CMOS output</li> <li>• Hysteresis input</li> <li>• Pull-up resistor optional</li> </ul>
H		CMOS output
I		Analog input
J		<ul style="list-style-type: none"> <li>• CMOS input</li> <li>• Pull-up resistor optional</li> </ul>
K		<ul style="list-style-type: none"> <li>• Hysteresis input</li> <li>• Pull-up resistor optional</li> </ul>

- **Programming procedure**

- (1) Set the EPROM programmer to the MBM27C256A.
- (2) Load program data into the EPROM programmer at 0007<sub>H</sub> to 7FFF<sub>H</sub>. (Note that addresses 8000<sub>H</sub> to FFFF<sub>H</sub> in the operating mode assign to 0000<sub>H</sub> to 7FFF<sub>H</sub> in EPROM mode).
- (3) Load option data into addresses 0000<sub>H</sub> to 0006<sub>H</sub> of the EPROM programmer.  
(For information about each corresponding option, see "8. OTPROM Option Bit Map".)
- (4) Program with the EPROM programmer.

## 4. Recommended Screening Conditions

High-temperature aging is recommended as the pre-assembly screening procedure for a product with a blanked OTPROM microcomputer program.



## 5. Programming Yield

All bits cannot be programmed at Fujitsu shipping test to a blanked OTPROM microcomputer, due to its nature. For this reason, a programming yield of 100% cannot be assured at all times.

# MB89630R Series

## 6. OTPROM Option Bit Map

Address	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0000 <sub>H</sub>	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	Single/dual- clock system 1: Dual clock 0: Single clock	Reset pin output 1: Yes 0: No	Power-on reset 1: Yes 0: No	Oscillation stabilization (/F <sub>CH</sub> ) 11:2 <sup>18</sup> /F <sub>CH</sub> 01:2 <sup>17</sup> /F <sub>CH</sub> 10:2 <sup>14</sup> /F <sub>CH</sub> 00:2 <sup>4</sup> /F <sub>CH</sub>	
0001 <sub>H</sub>	P07 Pull-up 1: No 0: Yes	P06 Pull-up 1: No 0: Yes	P05 Pull-up 1: No 0: Yes	P04 Pull-up 1: No 0: Yes	P03 Pull-up 1: No 0: Yes	P02 Pull-up 1: No 0: Yes	P01 Pull-up 1: No 0: Yes	P00 Pull-up 1: No 0: Yes
0002 <sub>H</sub>	P17 Pull-up 1: No 0: Yes	P16 Pull-up 1: No 0: Yes	P15 Pull-up 1: No 0: Yes	P14 Pull-up 1: No 0: Yes	P13 Pull-up 1: No 0: Yes	P12 Pull-up 1: No 0: Yes	P11 Pull-up 1: No 0: Yes	P10 Pull-up 1: No 0: Yes
0003 <sub>H</sub>	P37 Pull-up 1: No 0: Yes	P36 Pull-up 1: No 0: Yes	P35 Pull-up 1: No 0: Yes	P34 Pull-up 1: No 0: Yes	P33 Pull-up 1: No 0: Yes	P32 Pull-up 1: No 0: Yes	P31 Pull-up 1: No 0: Yes	P30 Pull-up 1: No 0: Yes
0004 <sub>H</sub>	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	P43 Pull-up 1: No 0: Yes	P42 Pull-up 1: No 0: Yes	P41 Pull-up 1: No 0: Yes	P40 Pull-up 1: No 0: Yes
0005 <sub>H</sub>	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	P74 Pull-up 1: No 0: Yes	P73 Pull-up 1: No 0: Yes	P72 Pull-up 1: No 0: Yes	Vacancy Readable and writable	Vacancy Readable and writable
0006 <sub>H</sub>	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	Vacancy Readable and writable	Reserved bit Readable and writable

Note: Each bit is set to '1' as the initialized value.

# MB89630R Series

## 2. Registers

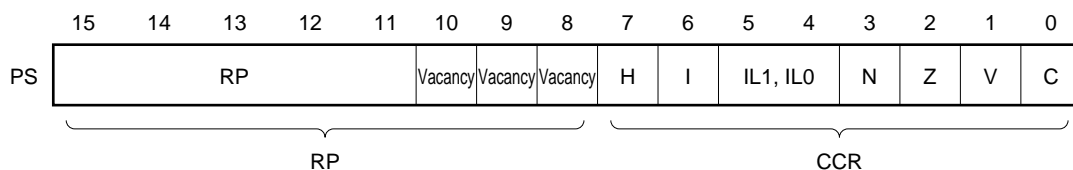
The F<sup>2</sup>MC-8L family has two types of registers; dedicated registers in the CPU and general-purpose registers in the memory. The following dedicated registers are provided:

Program counter (PC):	A 16-bit register for indicating the instruction storage positions
Accumulator (A):	A 16-bit temporary register for storing arithmetic operations, etc. When the instruction is an 8-bit data processing instruction, the lower byte is used.
Temporary accumulator (T):	A16-bit register which performs arithmetic operations with the accumulator When the instruction is an 8-bit data processing instruction, the lower byte is used.
Index register (IX):	A16-bit register for index modification
Extra pointer (EP):	A16-bit pointer for indicating a memory address
Stack pointer (SP):	A16-bit register for indicating a stack area
Program status (PS):	A16-bit register for storing a register pointer, a condition code

16 bits		Initial value
PC	: Program counter	FFFF <sub>H</sub>
A	: Accumulator	Indeterminate
T	: Temporary accumulator	Indeterminate
IX	: Index register	Indeterminate
EP	: Extra pointer	Indeterminate
SP	: Stack pointer	Indeterminate
PS	: Program status	I-flag = 0, IL1, IL0 = 11 The other bit values are indeterminate.

The PS can further be divided into higher 8 bits for use as a register bank pointer (RP) and the lower 8 bits for use as a condition code register (CCR). (See the diagram below.)

- **Structure of the program status register**





# MB89630R Series

(Continued)

Address	Read/write	Register name	Register description
20 <sub>H</sub>	(R/W)	ADC1	A/D converter control register 1
21 <sub>H</sub>	(R/W)	ADC2	A/D converter control register 2
22 <sub>H</sub>	(R/W)	ADDH	A/D converter data register (H)
23 <sub>H</sub>	(R/W)	ADDL	A/D converter data register (L)
24 <sub>H</sub>	(R/W)	EIC1	External interrupt control register 1
25 <sub>H</sub>	(R/W)	EIC2	External interrupt control register 2
26 <sub>H</sub>	Vacancy		
27 <sub>H</sub>	Vacancy		
28 <sub>H</sub>	(R/W)	CNTR1	PWM timer control register 1
29 <sub>H</sub>	(R/W)	CNTR2	PWM timer control register 2
2A <sub>H</sub>	(R/W)	CNTR3	PWM timer control register 3
2B <sub>H</sub>	(W)	COMR1	PWM timer compare register 1
2C <sub>H</sub>	(W)	COMR2	PWM timer compare register 2
2D <sub>H</sub>	(R/W)	SMC	UART serial mode control register
2E <sub>H</sub>	(R/W)	SRC	UART serial rate control register
2F <sub>H</sub>	(R/W)	SSD	UART serial status/data register
30 <sub>H</sub>	(R) (W)	SIDR SODR	UART serial input data control register UART serial output data control register
31 <sub>H</sub> to 7B <sub>H</sub>	Vacancy		
7C <sub>H</sub>	(W)	ILR1	Interrupt level setting register 1
7D <sub>H</sub>	(W)	ILR2	Interrupt level setting register 2
7E <sub>H</sub>	(W)	ILR3	Interrupt level setting register 3
7F <sub>H</sub>	Vacancy		

Note: Do not use vacancies.

# MB89630R Series

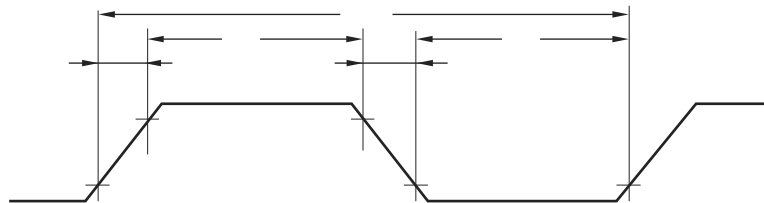
## 3. DC Characteristics

( $AV_{CC} = V_{CC} = 5.0\text{ V}$ ,  $AV_{SS} = V_{SS} = 0.0\text{ V}$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

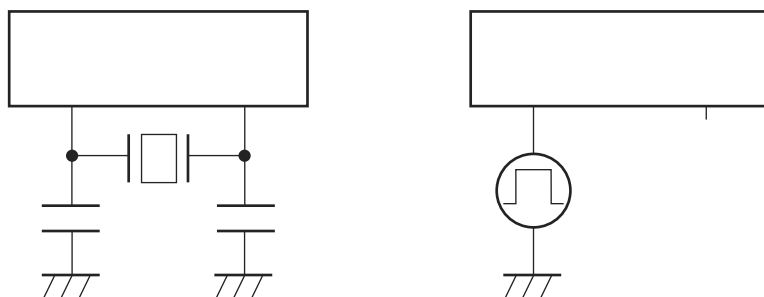
Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min.	Typ.	Max.		
“H” level input voltage	$V_{IH1}$	P00 to P07, P10 to P17, P22, P23, P31, P34, P37, P41, P43, P51 to P53	—	$0.7 V_{CC}$	—	$V_{CC} + 0.3$	V	P51 to P53 with pull-up resistor
	$V_{IH2}$	P51 to P53		$0.7 V_{CC}$	—	$V_{SS} + 6.0$	V	Without pull-up resistor
	$V_{IHS}$	$\overline{RST}$ , MOD0, MOD1, P30, P32, P33, P35, P36, P40, P42, P50, P72 to P74		$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	P50 with pull-up resistor
	$V_{IHS2}$	P50, P70, P71		$0.8 V_{CC}$	—	$V_{SS} + 6.0$	V	Without pull-up resistor
“L” level input voltage	$V_{IL}$	P00 to P07, P10 to P17, P22, P23, P31, P34, P37, P41, P43		$V_{SS} - 0.3$	—	$0.3 V_{CC}$	V	
	$V_{ILS}$	P30, P32, P33, P35, P36, P40, P42, P50 to P53, P70 to P74, $\overline{RST}$ , MOD0, MOD1		$V_{SS} - 0.3$	—	$0.2 V_{CC}$	V	
Open-drain output pin application voltage	$V_D$	P50 to P53		$V_{SS} - 0.3$	—	$V_{SS} + 6.0$	V	
“H” level output voltage	$V_{OH}$	P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P43	$I_{OH} = -2.0\text{ mA}$	4.0	—	—	V	
“L” level output voltage	$V_{OL}$	P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P43, P50 to P53, P60 to P67, $\overline{RST}$	$I_{OL} = 4.0\text{ mA}$	—	—	0.4	V	
Input leakage current (Hi-z output leakage current)	$I_{LI}$	P00 to P07, P10 to P17, P20 to P23, P30 to P37, P40 to P43, P50 to P53, P70 to P74, MOD0, MOD1	$0.0\text{ V} < V_I < V_{CC}$	—	—	$\pm 5$	$\mu\text{A}$	Without pull-up resistor

(Continued)

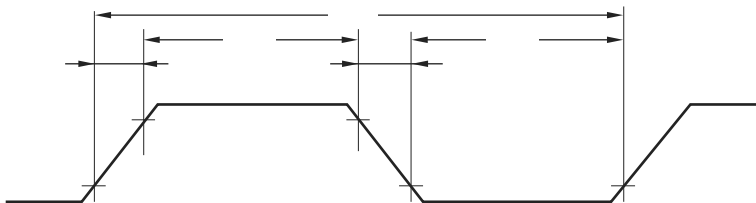
## • Main clock timing condition



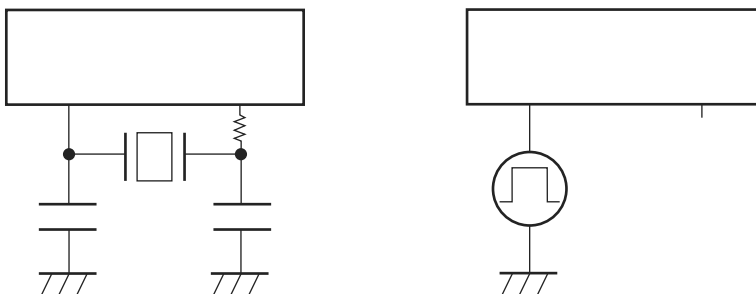
## • Main clock configurations



## • Subclock timing condition



## • Subclock configurations



## (4) Instruction Cycle

Parameter	Symbol	Value (typical)	Unit	Remarks
Instruction cycle (minimum execution time)	$t_{\text{inst}}$	$4/F_{\text{CH}}, 8/F_{\text{CH}}, 16/F_{\text{CH}}, 64/F_{\text{CH}}$	$\mu\text{s}$	$(4/F_{\text{CH}}) t_{\text{inst}} = 0.4 \mu\text{s}$ , operating at $F_{\text{CH}} = 10 \text{ MHz}$
		$2/F_{\text{CL}}$	$\mu\text{s}$	$t_{\text{inst}} = 61.036 \mu\text{s}$ , operating at $F_{\text{CL}} = 32.768 \text{ kHz}$

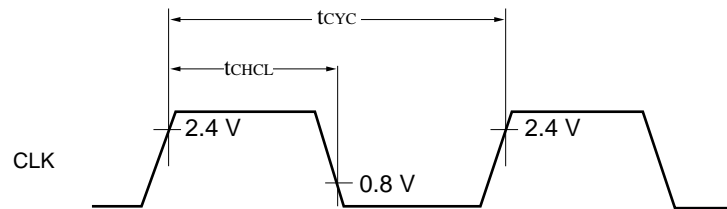
Note: Operating at 10 MHz, the cycle varies with the set execution time.

## (5) Clock Output Timing

( $V_{\text{CC}} = 5.0 \text{ V} \pm 10\%$ ,  $A_{\text{VSS}} = V_{\text{SS}} = 0.0 \text{ V}$ ,  $T_{\text{A}} = -40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ )

Parameter	Symbol	Pin name	Condition	Value		Unit	Remarks
				Min.	Max.		
Cycle time	$t_{\text{CYC}}$	CLK	—	$1/2 t_{\text{inst}}^*$	—	$\mu\text{s}$	
CLK $\uparrow \rightarrow$ CLK $\downarrow$	$t_{\text{CHCL}}$	CLK		$1/4 t_{\text{inst}}^* - 70 \text{ ns}$	$1/4 t_{\text{inst}}^*$	$\mu\text{s}$	

\* : For information on  $t_{\text{inst}}$ , see “(4) Instruction Cycle”.



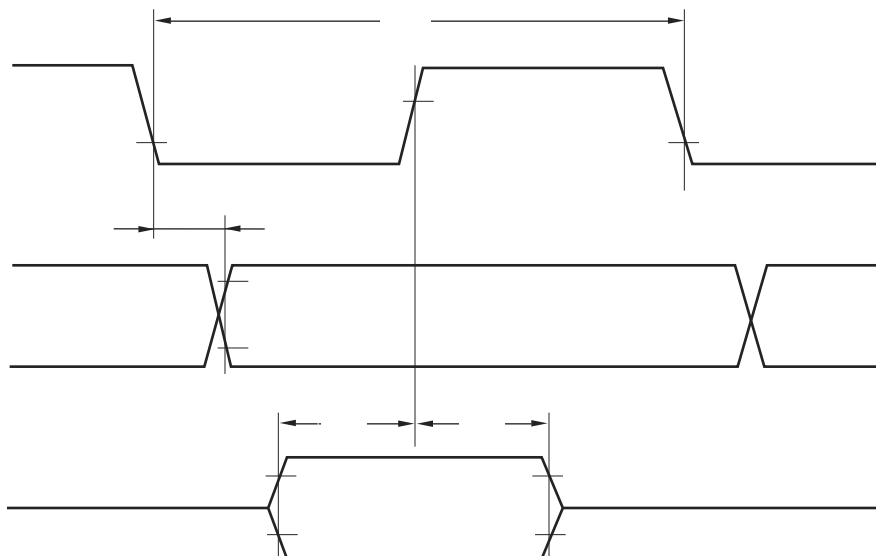
## (9) Serial I/O Timing

( $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $F_{CH} = 10\text{ MHz}$ ,  $AV_{SS} = V_{SS} = 0.0\text{ V}$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

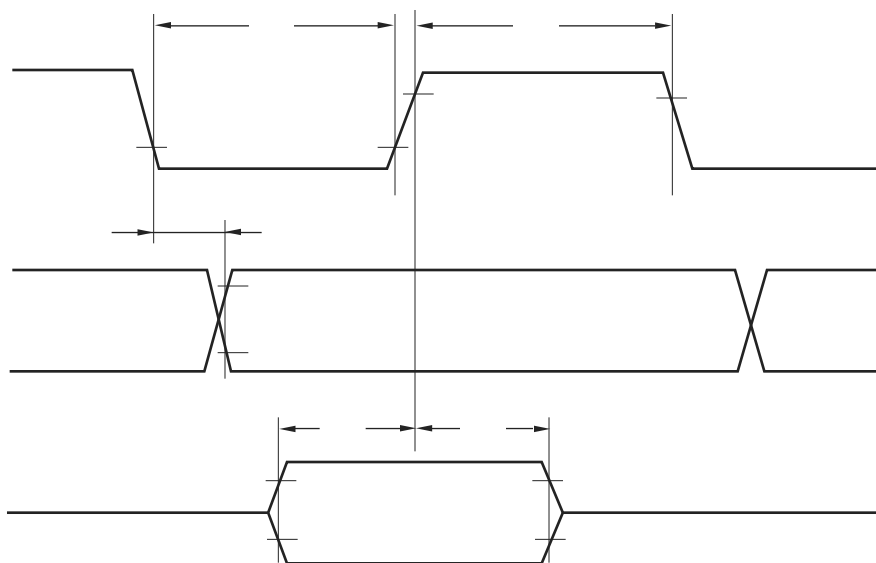
Parameter	Symbol	Pin name	Condition	Value		Unit	Remarks
				Min.	Max.		
Serial clock cycle time	$t_{SCYC}$	SCK1, UCK1, UCK2	Internal shift clock mode	$2\ t_{inst}^*$	—	$\mu\text{s}$	
SCK1 $\downarrow \rightarrow$ SO1 time UCK1 $\downarrow \rightarrow$ UO1 time UCK2 $\downarrow \rightarrow$ UO2 time	$t_{SLOV}$	SCK1, SO1 UCK1, UO1 UCK2, UO2		−200	200	ns	
Valid SI1 $\rightarrow$ SCK1 $\uparrow$ Valid UI1 $\rightarrow$ UCK1 $\uparrow$ Valid UI2 $\rightarrow$ UCK2 $\uparrow$	$t_{IVSH}$	SI1, SCK1 UI1, UCK1 UI2, UCK2		$1/2\ t_{inst}^*$	—	$\mu\text{s}$	
SCK1 $\uparrow \rightarrow$ valid SI1 hold time UCK1 $\uparrow \rightarrow$ valid UI1 hold time UCK2 $\uparrow \rightarrow$ valid UI2 hold time	$t_{SHIX}$	SCK1, SI1 UCK1, UI1 UCK2, UI2		$1/2\ t_{inst}^*$	—	$\mu\text{s}$	
Serial clock “H” pulse width	$t_{SHSL}$	SCK1, UCK1, UCK2	External shift clock mode	$1\ t_{inst}^*$	—	$\mu\text{s}$	
Serial clock “L” pulse width	$t_{SLSH}$	SCK1, UCK1, UCK2		$1\ t_{inst}^*$	—	$\mu\text{s}$	
SCK1 $\downarrow \rightarrow$ SO1 time UCK1 $\downarrow \rightarrow$ UO1 time UCK2 $\downarrow \rightarrow$ UO2 time	$t_{SLOV}$	SCK1, SO1 UCK1, UO1 UCK2, UO2		0	200	ns	
Valid SI1 $\rightarrow$ SCK1 $\uparrow$ Valid UI1 $\rightarrow$ UCK1 $\uparrow$ Valid UI2 $\rightarrow$ UCK2 $\uparrow$	$t_{IVSH}$	SI1, SCK1 UI1, UCK1 UI2, UCK2		$1/2\ t_{inst}^*$	—	$\mu\text{s}$	
SCK1 $\downarrow \rightarrow$ valid SI1 hold time UCK1 $\downarrow \rightarrow$ valid UI1 hold time UCK2 $\downarrow \rightarrow$ valid UI2 hold time	$t_{SHIX}$	SCK1, SI1 UCK1, UI1 UCK2, UI2		$1/2\ t_{inst}^*$	—	$\mu\text{s}$	

\* : For information on  $t_{inst}$ , see “(4) Instruction Cycle”.

- Internal shift clock mode

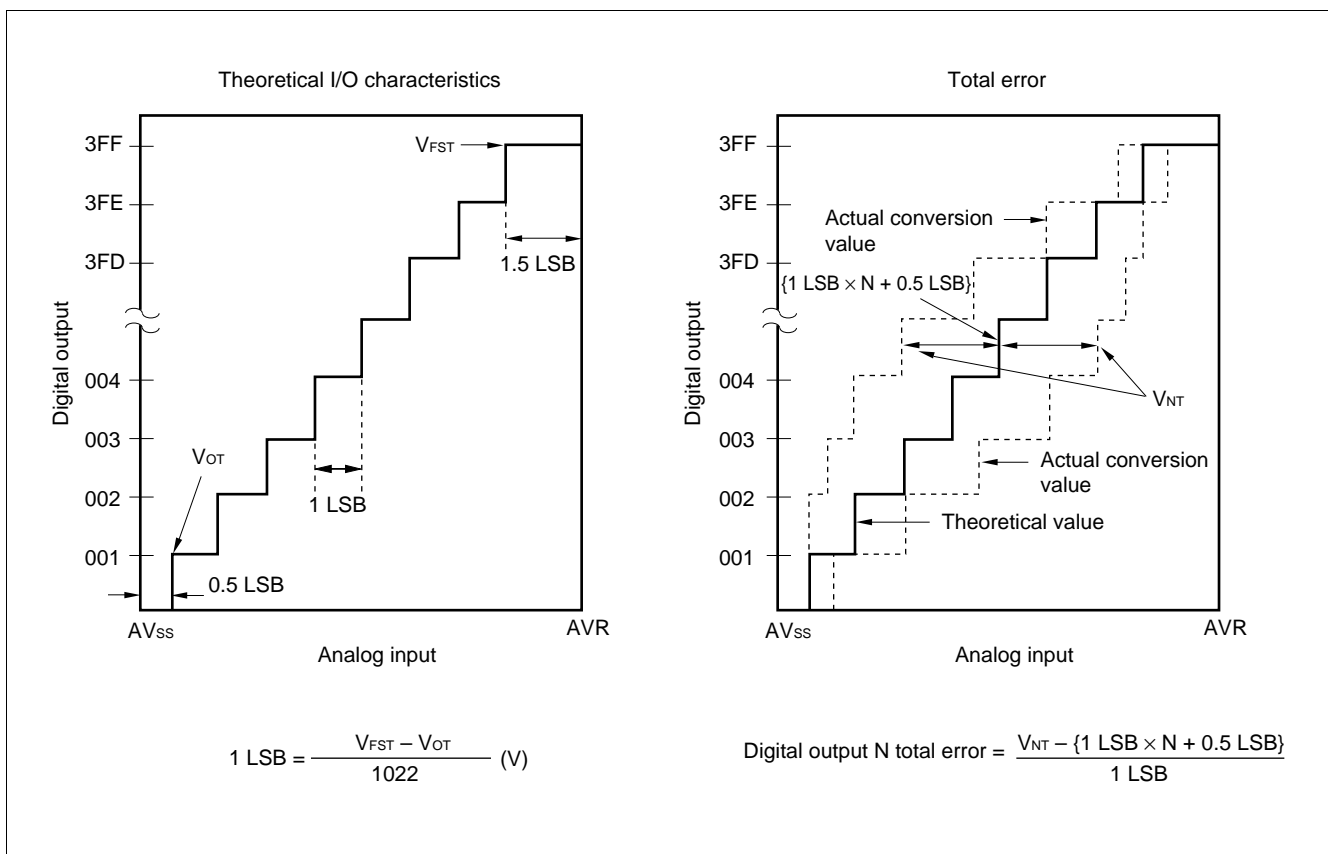


- External shift clock mode



## 6. A/D Converter Glossary

- Resolution  
Analog changes that are identifiable with the A/D converter
- Linearity error  
The deviation of the straight line connecting the zero transition point ("00 0000 0000" ↔ "00 0000 0001") with the full-scale transition point ("11 1111 1110" ↔ "11 1111 1111") from actual conversion characteristics
- Differential linearity error  
The deviation of input voltage needed to change the output code by 1 LSB from the theoretical value
- Total error (unit: LSB)  
The difference between theoretical and actual conversion values caused by the zero transition error, full-scale transition error, linearity error, quantization error, and noise



(Continued)

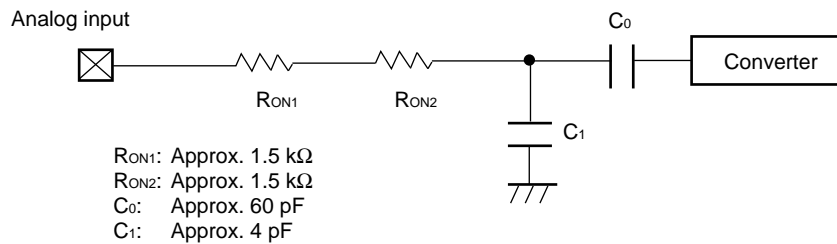
## 7. Notes on Using A/D Converter

### • Input impedance of the analog input pins

The output impedance of the external circuit for the analog input must satisfy the following conditions.

If the output impedance of the external circuit is too high, an analog voltage sampling time might be insufficient (sampling time = 6  $\mu$ s at 10 MHz oscillation.) Therefore, it is recommended to keep the output impedance of the external circuit below 10 k $\Omega$ .

### • Analog input circuit model



Note: The values mentioned here should be used as a guideline.

### • Error

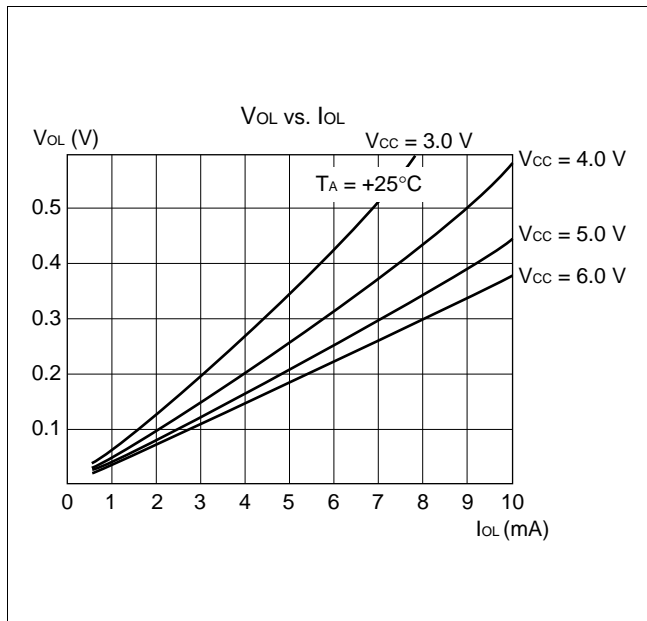
The smaller the  $|AVR - AV_{ss}|$ , the greater the error would become relatively.



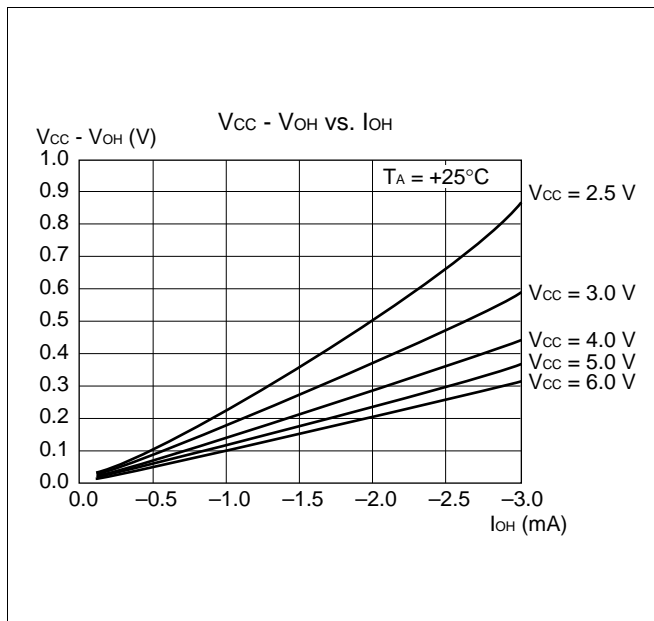
# MB89630R Series

## ■ CHARACTERISTICS EXAMPLE

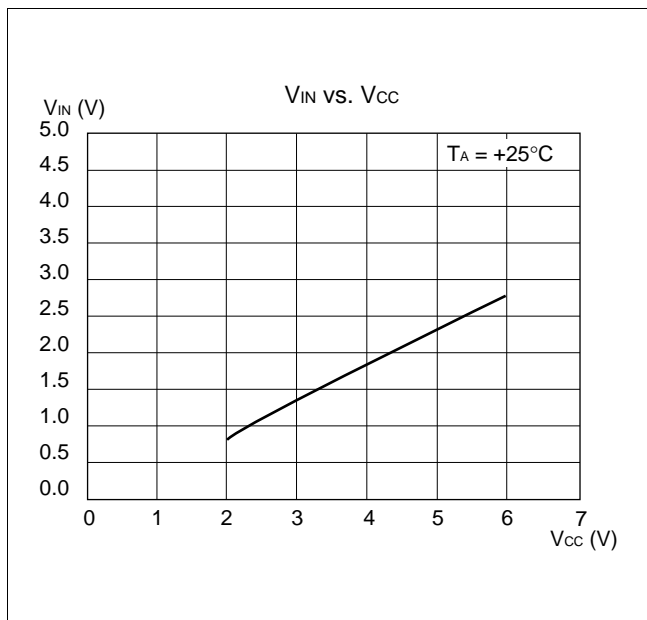
(1) “L” Level Output Voltage



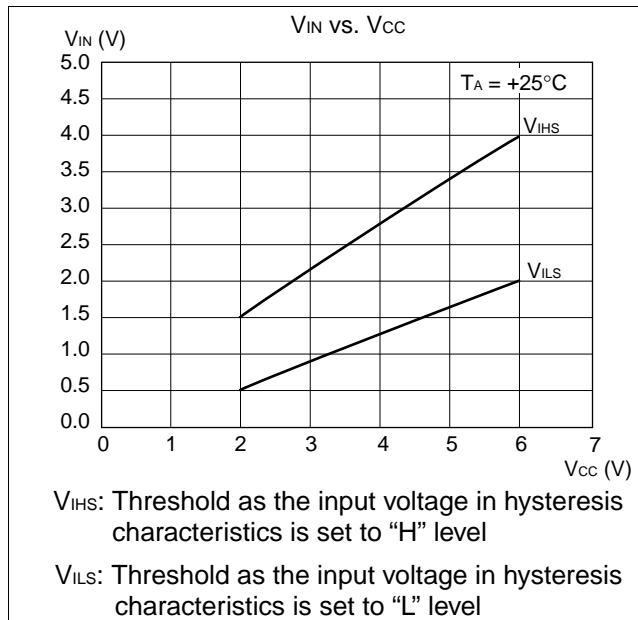
(2) “H” Level Output Voltage



(3) “H” Level Input Voltage/“L” Level Input Voltage (CMOS Input)

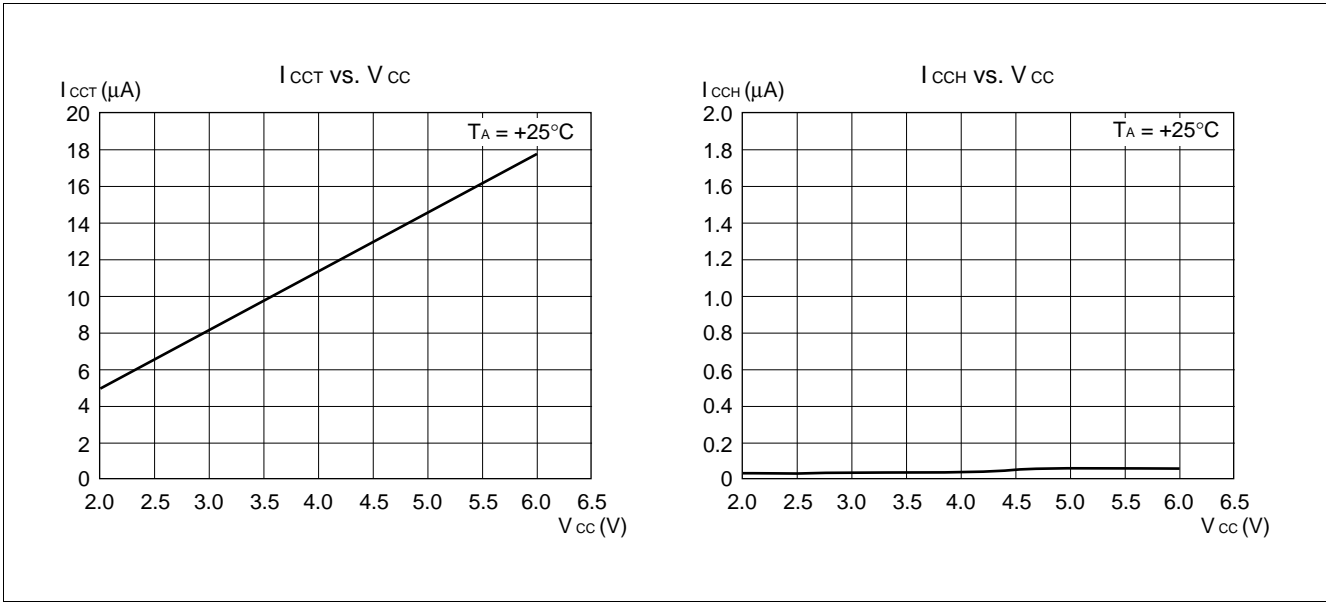


(4) “H” Level Input Voltage/“L” Level Input Voltage (Hysteresis Input)

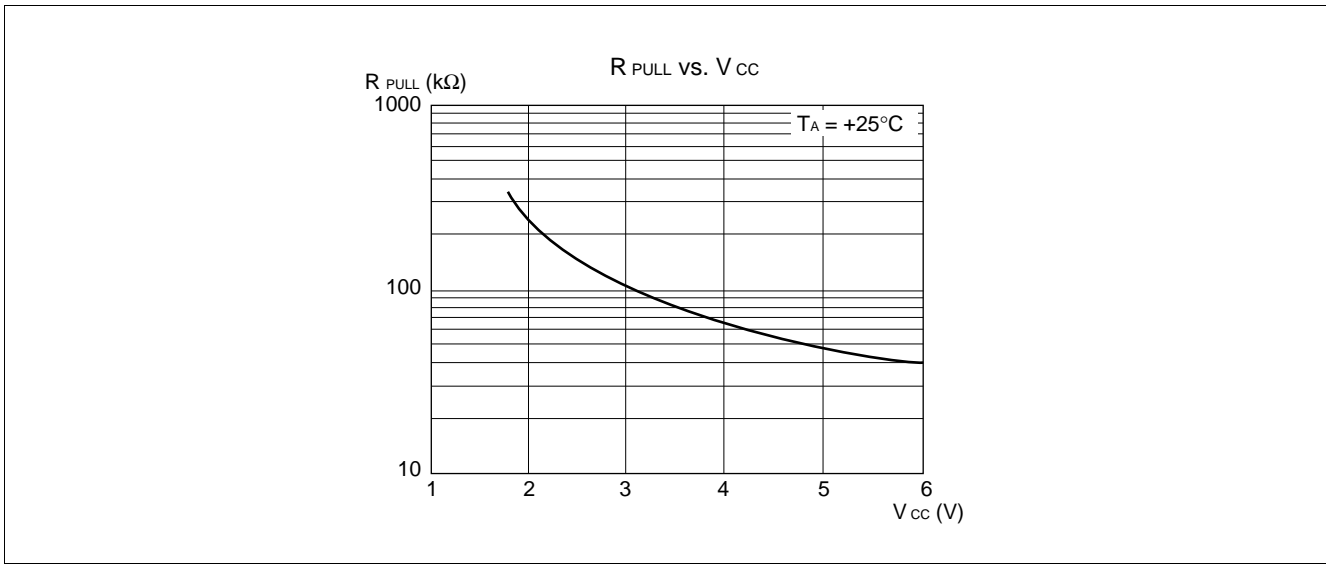


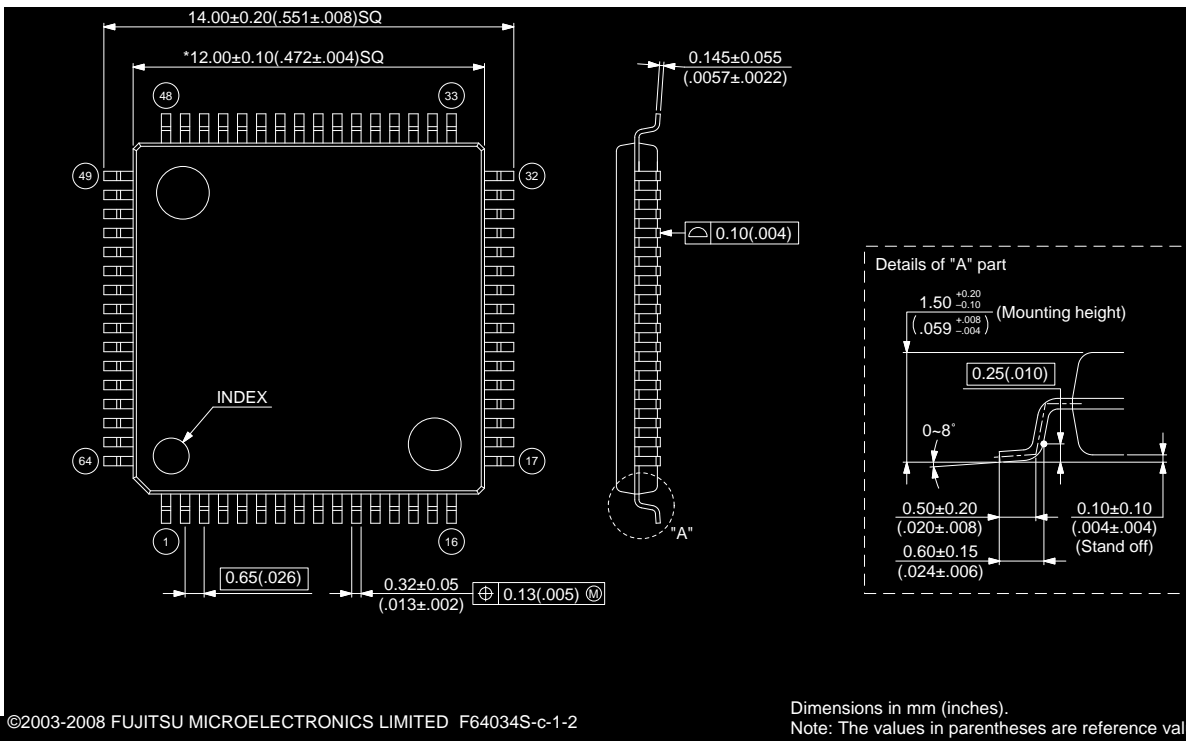
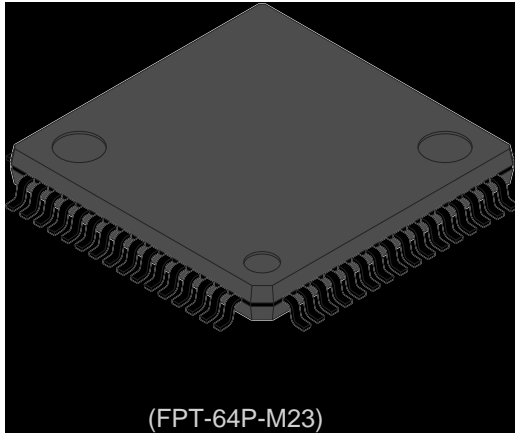
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## (6) Pull-up Resistance

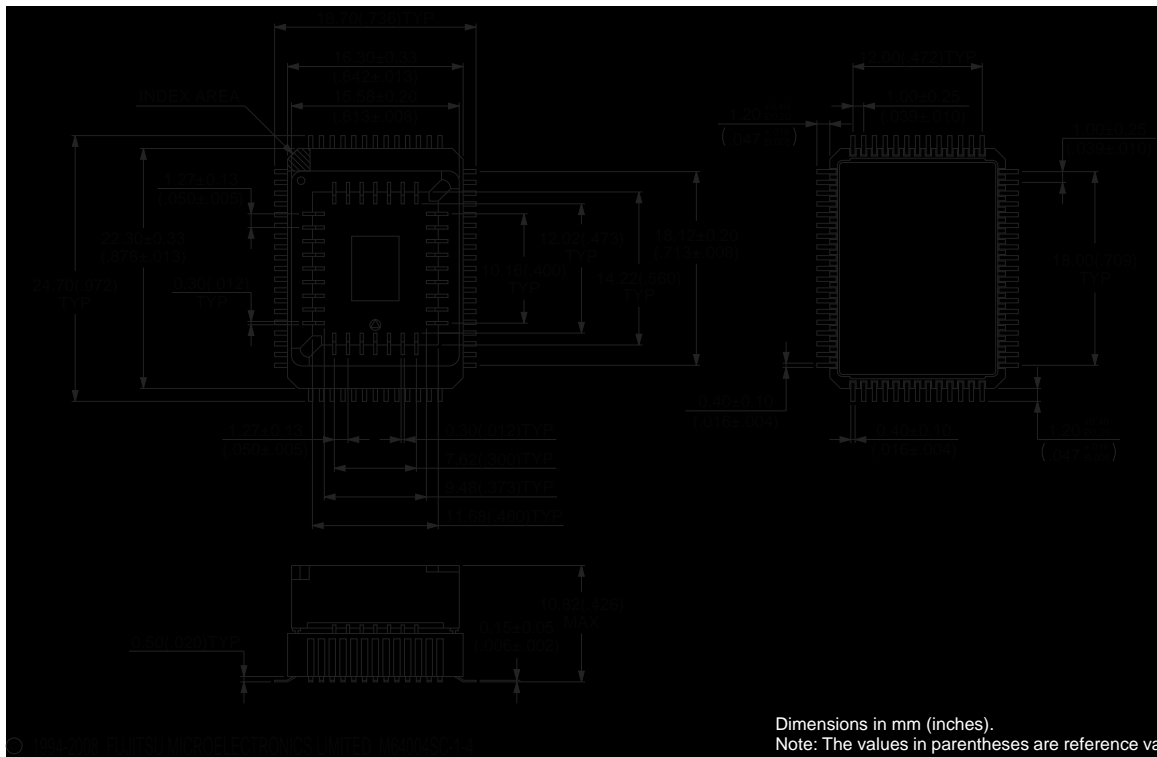
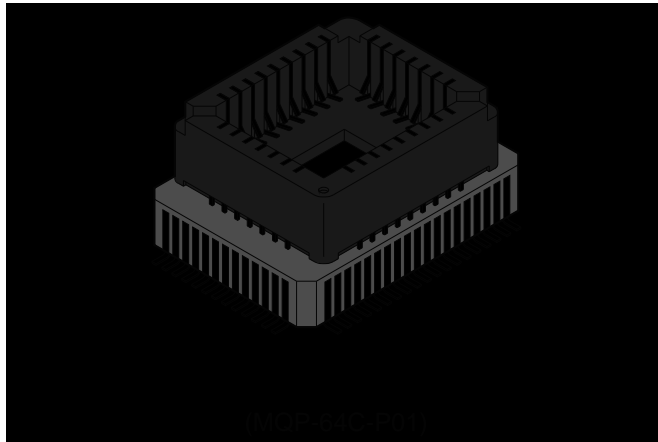




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