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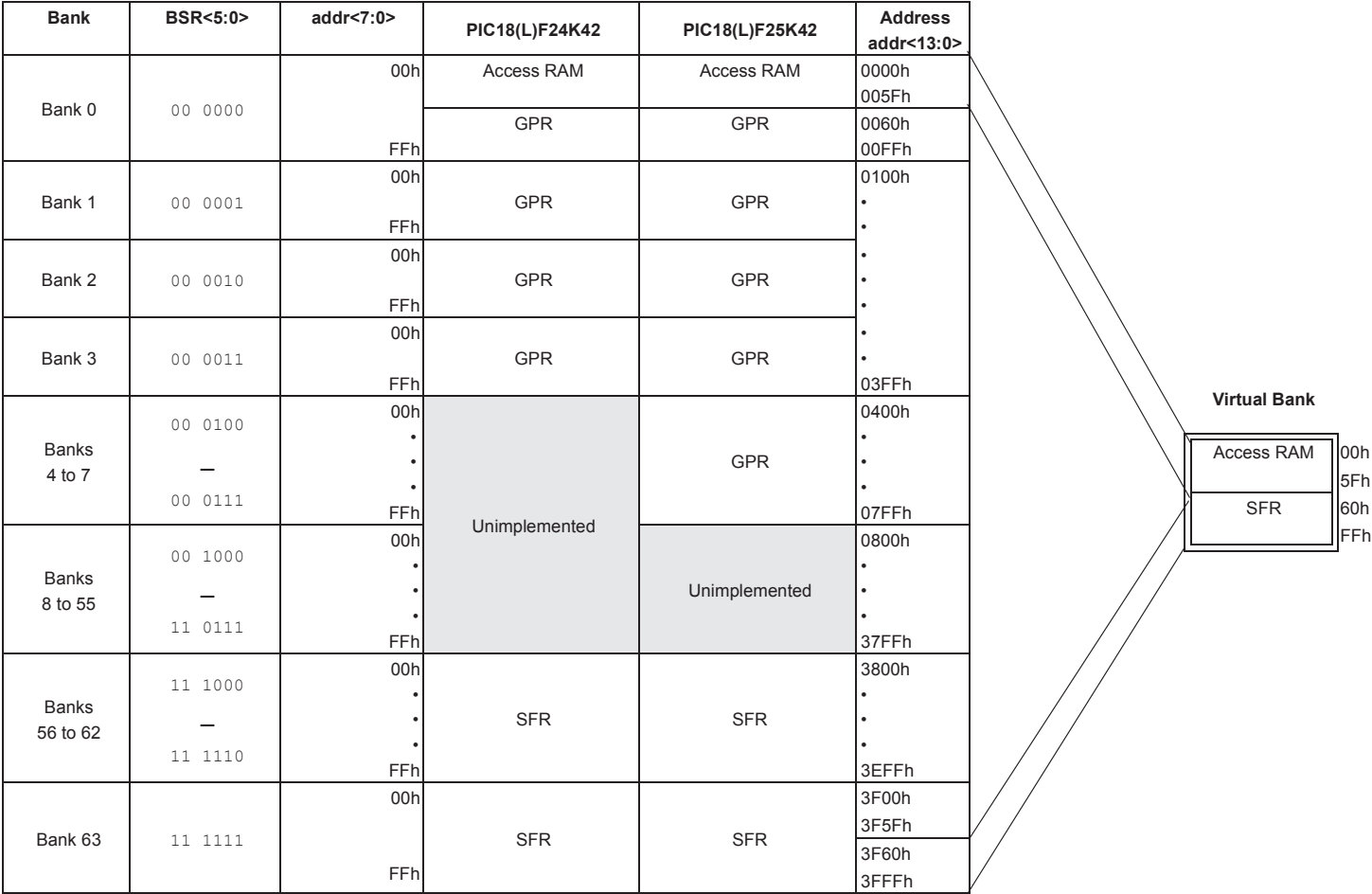
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, HLVD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	16KB (8K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 24x12b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f24k42-i-sp

FIGURE 4-4: DATA MEMORY MAP FOR PIC18(L)F24/25K42 DEVICES



4.6 Register Definitions: Status Registers

REGISTER 4-2: STATUS: STATUS REGISTER

U-0	R-1/q	R-1/q	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u
—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	N	OV	Z	DC	C
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Read as '0'

bit 6 **$\overline{\text{TO}}$:** Time-Out bit

1 = Set at power-up or by execution of `CLRWDT` or `SLEEP` instruction

0 = A WDT time-out occurred

bit 5 **$\overline{\text{PD}}$:** Power-Down bit

1 = Set at power-up or by execution of `CLRWDT` instruction

0 = Set by execution of the `SLEEP` instruction

bit 4 **N:** Negative bit used for signed arithmetic (2's complement); indicates if the result is negative, (ALU MSb = 1).

1 = The result is negative

0 = The result is positive

bit 3 **OV:** Overflow bit used for signed arithmetic (2's complement); indicates an overflow of the 7-bit magnitude, which causes the sign bit (bit 7) to change state.

1 = Overflow occurred for current signed arithmetic operation

0 = No overflow occurred

bit 2 **Z:** Zero bit

1 = The result of an arithmetic or logic operation is zero

0 = The result of an arithmetic or logic operation is not zero

bit 1 **DC:** Digit Carry/Borrow bit (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)⁽¹⁾

1 = A carry-out from the 4th low-order bit of the result occurred

0 = No carry-out from the 4th low-order bit of the result

bit 0 **C:** Carry/Borrow bit (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)^(1,2)

1 = A carry-out from the Most Significant bit of the result occurred

0 = No carry-out from the Most Significant bit of the result occurred

Note 1: For Borrow, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand.

2: For Rotate (`RRF`, `RLF`) instructions, this bit is loaded with either the high or low-order bit of the Source register.

TABLE 9-3: SUMMARY OF REGISTERS ASSOCIATED WITH CLOCK SOURCES

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
OSCCON1	—	NOSC<2:0>			NDIV<3:0>				109
OSCCON2	—	COSC<2:0>			CDIV<3:0>				110
OSCCON3	CSWHOLD	SOSCPWR	—	ORDY	NOSCR	—	—	—	110
OSCSTAT	EXTOR	HFOR	MFOR	LFOR	SOR	ADOR	—	PLLRL	111
OSCTUNE	—	—	TUN<5:0>						113
OSCFRQ	—	—	—	—	FRQ<3:0>				112
OSCCON	EXTOEN	HFOEN	MFOEN	LFOEN	SOSCEN	ADOEN	—	—	114

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by clock sources.

TABLE 9-4: SUMMARY OF CONFIGURATION WORD WITH CLOCK SOURCES

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFIG1	13:8	—	—	FCMEN	—	CSWEN	—	—	CLKOUTEN	71
	7:0	—	RSTOSC<2:0>			—	FEXTOSC<2:0>			

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by clock sources.

15.1 Program Flash Memory

The Program Flash Memory is readable, writable and erasable during normal operation over the entire VDD range.

A read from program memory is executed one byte at a time. A write to program memory or program memory erase is executed on blocks of n bytes at a time. Refer to [Table 15-2](#) for write and erase block sizes. A Bulk Erase operation cannot be issued from user code.

Writing or erasing program memory will cease instruction fetches until the operation is complete. The program memory cannot be accessed during the write or erase, therefore, code cannot execute. An internal programming timer terminates program memory writes and erases.

A value written to program memory does not need to be a valid instruction. Executing a program memory location that forms an invalid instruction results in a NOP.

It is important to understand the PFM memory structure for erase and programming operations. Program memory word size is 16 bits wide. PFM is arranged in

rows. A row is the minimum size that can be erased by user software. Refer to [Table 15-2](#) for the row sizes for the these devices.

After a row has been erased, all or a portion of this row can be programmed. Data to be written into the program memory row is written to 8-bit wide data write latches by means of 6 address lines. These latches are not directly accessible, but may be loaded via sequential writes to the TABLAT register.

Note: To modify only a portion of a previously programmed row, then the contents of the entire row must be read and saved in RAM prior to the erase. Then, the new data and retained data can be written into the write latches to reprogram the row of PFM. However, any unprogrammed locations can be written without first erasing the row. In this case, it is not necessary to save and rewrite the other previously programmed locations

TABLE 15-2: FLASH MEMORY ORGANIZATION BY DEVICE

Device	Row Erase Size (Words)	Write Latches (Words)	Program Flash Memory (Words)	Data Memory (Bytes)
PIC18(L)F24K42	32	64	8192	256
PIC18(L)F25K42			16384	

15.3.5 WRITE VERIFY

Depending on the application, good programming practice may dictate that the value written to the memory should be verified against the original value. This should be used in applications where excessive writes can stress bits near the specification limit.

EXAMPLE 15-5: DATA EEPROM READ

```
; Data Memory Address to read
      CLRF      NVMCON1          ; Setup Data EEPROM Access
      MOVF      EE_ADDRL, W      ;
      MOVWF     NVMADRL          ; Setup Address
      BSF       NVMCON1, RD      ; Issue EE Read
      MOVF      NVMDAT, W        ; W = EE_DATA
```

EXAMPLE 15-6: DATA EEPROM WRITE

```
; Data Memory Address to write
      CLRF      NVMCON1          ; Setup Data EEPROM Access
      MOVF      EE_ADDRL, W      ;
      MOVWF     NVMADRL          ; Setup Address
; Data Memory Value to write
      MOVF      EE_DATA, W       ;
      MOVWF     NVMDAT           ;
; Enable writes
      BSF       NVMCON1, WREN    ;
; Disable interrupts
      BCF       INTCON0, GIE     ;
; Required unlock sequence
      MOVLW     55h              ;
      MOVWF     NVMCON2          ;
      MOVLW     AAh              ;
      MOVWF     NVMCON2          ;
; Set WR bit to begin write
      BSF       NVMCON1, WR      ;
; Enable INT
      BSF       INTCON0, GIE     ;
; Wait for interrupt, write done
      SLEEP                      ;
; Disable writes
      BCF       NVMCON1, WREN    ;
```

15.3.6 OPERATION DURING CODE-PROTECT

Data EEPROM Memory has its own code-protect bits in Configuration Words. External read and write operations are disabled if code protection is enabled.

If the Data EEPROM is write-protected or if NVMADR points an invalid address location, the WR bit is cleared without any effect. WRERR is signaled in this scenario.

15.3.7 PROTECTION AGAINST SPURIOUS WRITE

There are conditions when the user may not want to write to the Data EEPROM Memory. To protect against spurious EEPROM writes, various mechanisms have been implemented. On power-up, the WREN bit is cleared. In addition, writes to the EEPROM are blocked during the Power-up Timer period (TPWRT).

The unlock sequence and the WREN bit together help prevent an accidental write during brown-out, power glitch or software malfunction.

REGISTER 16-9: CRCXORH: CRC XOR HIGH BYTE REGISTER

R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x
X<15:8>							
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0 **X<15:8>**: XOR of Polynomial Term X^n Enable bits

REGISTER 16-10: CRCXORL: CRC XOR LOW BYTE REGISTER

R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	U-1
X<7:1>							—
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-1 **X<7:1>**: XOR of Polynomial Term X^n Enable bits

bit 0 **Unimplemented**: Read as '1'

REGISTER 18-7: SLRCONx: SLEW RATE CONTROL REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
SLRx7	SLRx6	SLRx5	SLRx4	SLRx3	SLRx2	SLRx1	SLRx0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

bit 7-0

SLRx<7:0>: Slew Rate Control on Pins Rx<7:0>, respectively

1 = Port pin slew rate is limited

0 = Port pin slews at maximum rate

TABLE 18-7: SLEW RATE CONTROL REGISTERS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SLRCONA	SLRA7	SLRA6	SLRA5	SLRA4	SLRA3	SLRA2	SLRA1	SLRA0
SLRCONB	SLRB7	SLRB6	SLRB5	SLRB4	SLRB3	SLRB2	SLRB1	SLRB0
SLRCONC	SLRC7	SLRC6	SLRC5	SLRC4	SLRC3	SLRC2	SLRC1	SLRC0

20.6 Register Definitions: Interrupt-on-Change Control

REGISTER 20-1: IOCxP: INTERRUPT-ON-CHANGE POSITIVE EDGE REGISTER EXAMPLE

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
IOCxP7	IOCxP6	IOCxP5	IOCxP4	IOCxP3	IOCxP2	IOCxP1	IOCxP0
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **IOCxP<7:0>:** Interrupt-on-Change Positive Edge Enable bits
 1 = Interrupt-on-Change enabled on the IOCx pin for a positive-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge.
 0 = Interrupt-on-Change disabled for the associated pin.

REGISTER 20-2: IOCxN: INTERRUPT-ON-CHANGE NEGATIVE EDGE REGISTER EXAMPLE

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
IOCxN7	IOCxN6	IOCxN5	IOCxN4	IOCxN3	IOCxN2	IOCxN1	IOCxN0
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **IOCxN<7:0>:** Interrupt-on-Change Negative Edge Enable bits
 1 = Interrupt-on-Change enabled on the IOCx pin for a negative-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge.
 0 = Interrupt-on-Change disabled for the associated pin

REGISTER 20-3: IOCxF: INTERRUPT-ON-CHANGE FLAG REGISTER EXAMPLE

R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
IOCxF7	IOCxF6	IOCxF5	IOCxF4	IOCxF3	IOCxF2	IOCxF1	IOCxF0
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HS - Bit is set in hardware

bit 7-0 **IOCxF<7:0>:** Interrupt-on-Change Flag bits
 1 = A enabled change was detected on the associated pin. Set when IOCxP[n] = 1 and a positive edge was detected on the IOCn pin, or when IOCxN[n] = 1 and a negative edge was detected on the IOCn pin
 0 = No change was detected, or the user cleared the detected change

FIGURE 27-9: HIGH AND LOW MEASURE MODE SINGLE ACQUISITION TIMING DIAGRAM

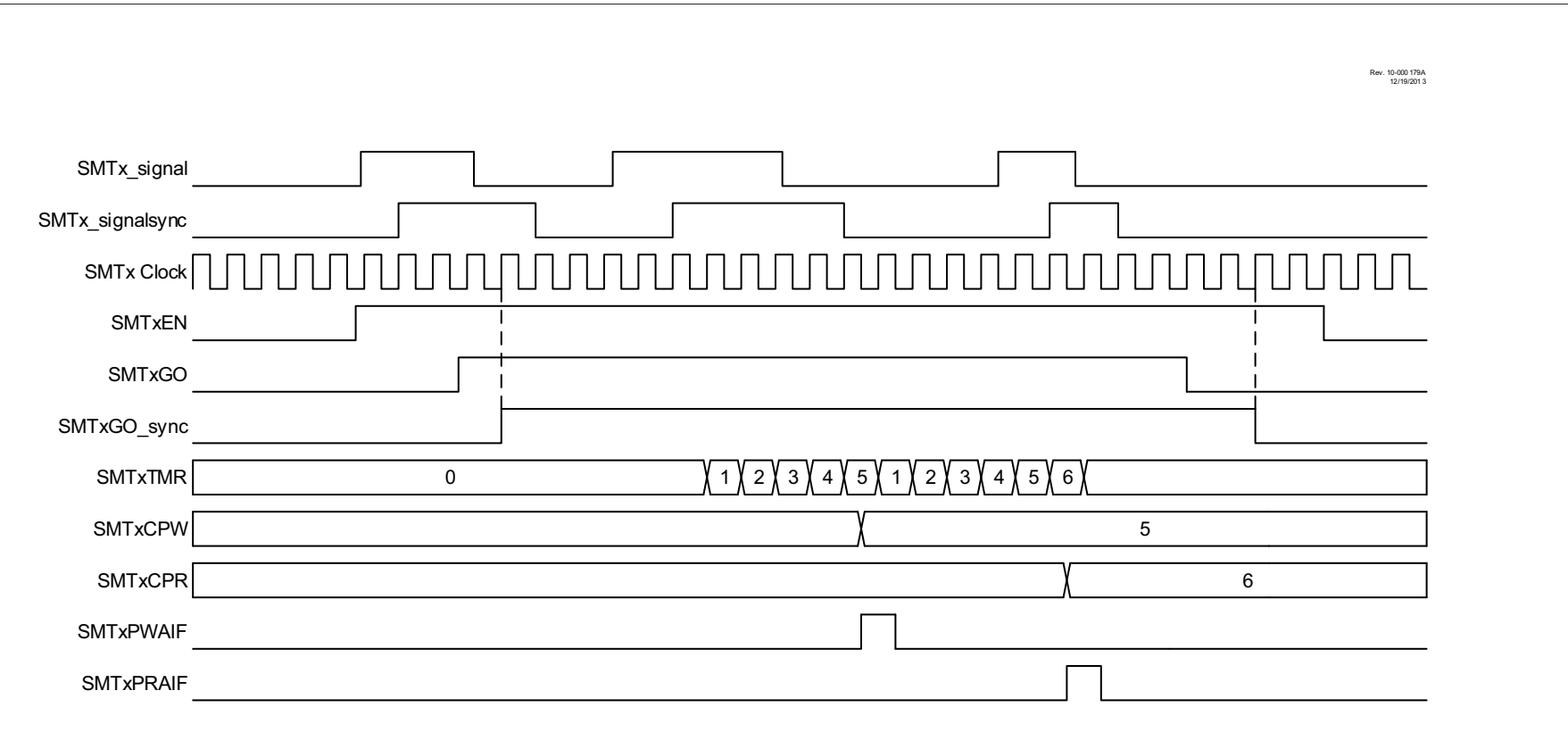


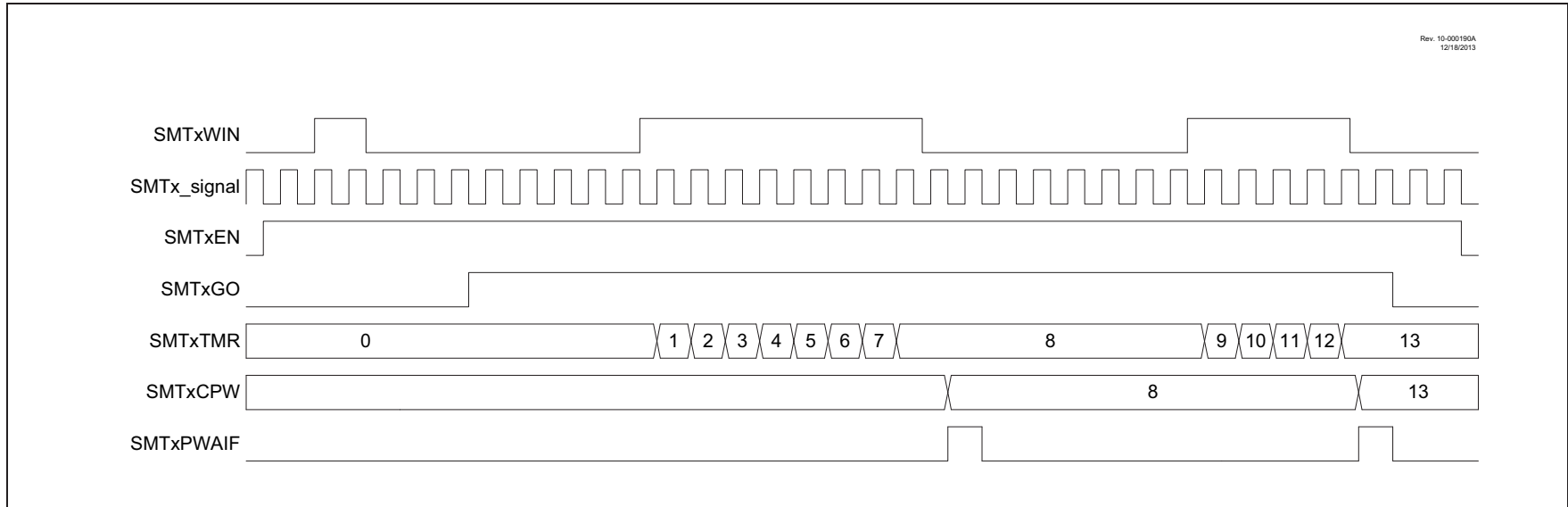
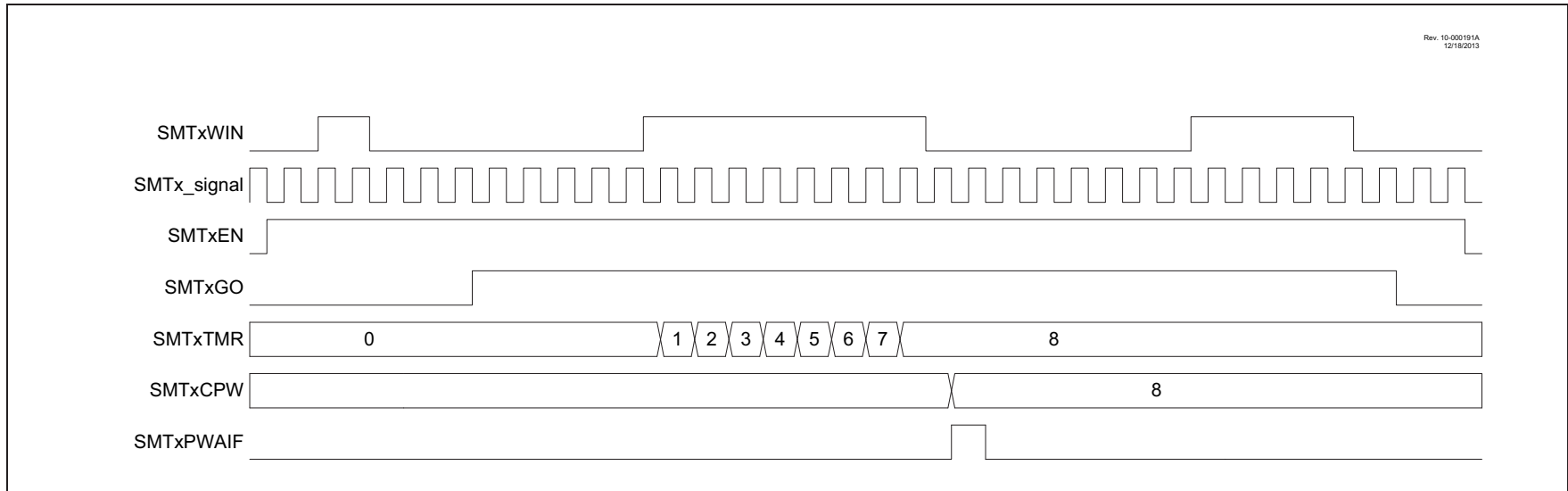
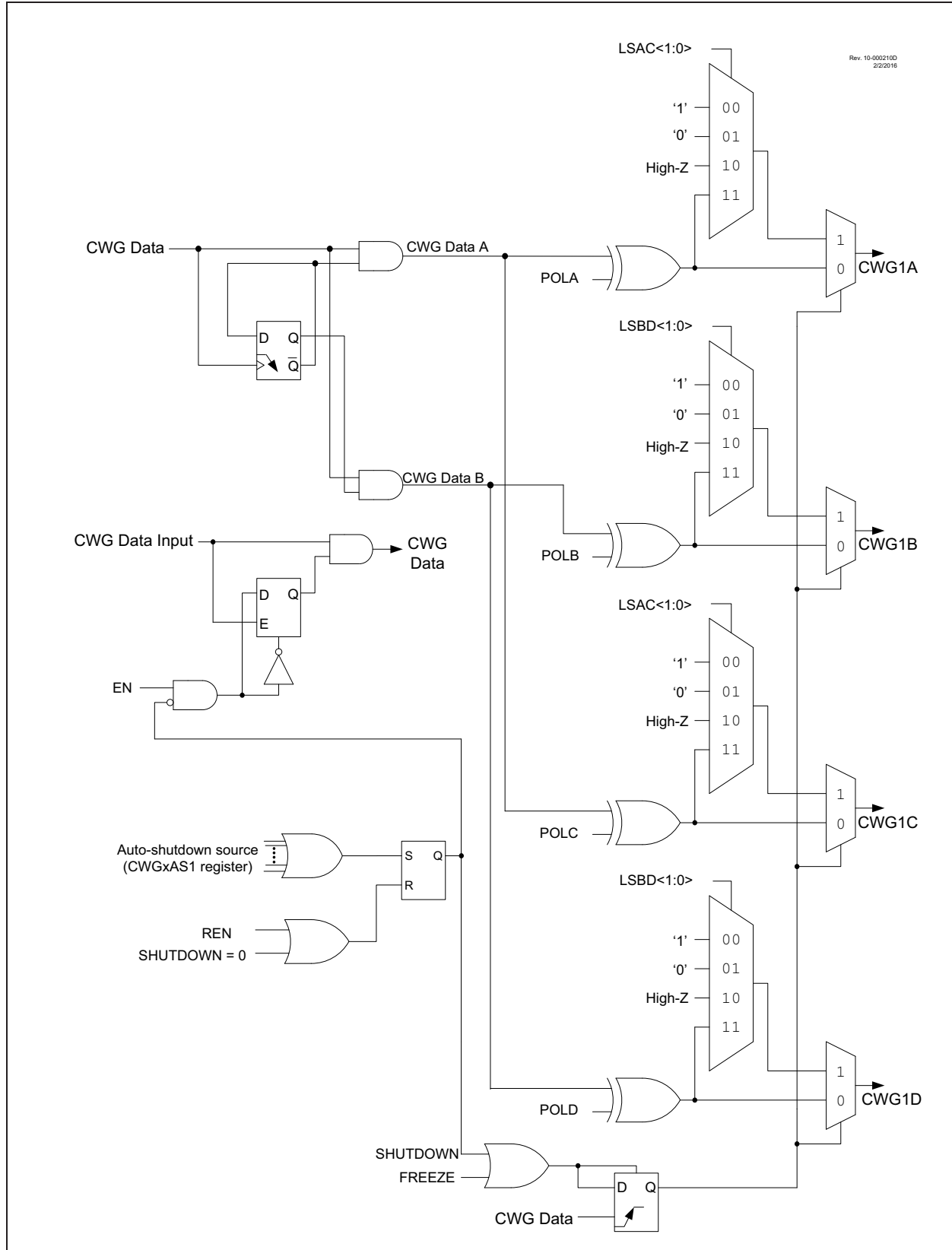
FIGURE 27-19: GATED COUNTER MODE REPEAT ACQUISITION TIMING DIAGRAM**FIGURE 27-20: GATED COUNTER MODE SINGLE ACQUISITION TIMING DIAGRAM**

FIGURE 28-3: SIMPLIFIED CWG BLOCK DIAGRAM (PUSH-PULL MODE, MODE<2:0> = 101)



REGISTER 28-5: CWGxSTR⁽¹⁾: CWG STEERING CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
OVRD	OVRC	OVRB	OVRA	STRD ⁽²⁾	STRC ⁽²⁾	STRB ⁽²⁾	STRA ⁽²⁾
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

q = Value depends on condition

bit 7 **OVRD**: Steering Data D bit

bit 6 **OVRC**: Steering Data C bit

bit 5 **OVRB**: Steering Data B bit

bit 4 **OVRA**: Steering Data A bit

bit 3 **STRD**: Steering Enable bit D⁽²⁾

1 = CWGxD output has the CWG data input waveform with polarity control from POLD bit

0 = CWGxD output is assigned to value of OVRD bit

bit 2 **STRC**: Steering Enable bit C⁽²⁾

1 = CWGxC output has the CWG data input waveform with polarity control from POLC bit

0 = CWGxC output is assigned to value of OVRC bit

bit 1 **STRB**: Steering Enable bit B⁽²⁾

1 = CWGxB output has the CWG data input waveform with polarity control from POLB bit

0 = CWGxB output is assigned to value of OVRB bit

bit 0 **STRA**: Steering Enable bit A⁽²⁾

1 = CWGxA output has the CWG data input waveform with polarity control from POLA bit

0 = CWGxA output is assigned to value of OVRA bit

Note 1: The bits in this register apply only when MODE<2:0> = 00x ([Register 28-1](#), Steering modes).

2: This bit is double-buffered when MODE<2:0> = 001.

31.0 ZERO-CROSS DETECTION (ZCD) MODULE

The ZCD module detects when an A/C signal crosses through the ground potential. The actual zero-crossing threshold is the zero-crossing reference voltage, VCPINV, which is typically 0.75V above ground.

The connection to the signal to be detected is through a series current-limiting resistor. The module applies a current source or sink to the ZCD pin to maintain a constant voltage on the pin, thereby preventing the pin voltage from forward biasing the ESD protection diodes. When the applied voltage is greater than the reference voltage, the module sinks current. When the applied voltage is less than the reference voltage, the module sources current. The current source and sink action keeps the pin voltage constant over the full range of the applied voltage. The ZCD module is shown in the simplified block diagram [Figure 31-2](#).

The ZCD module is useful when monitoring an A/C waveform for, but not limited to, the following purposes:

- A/C period measurement
- Accurate long term time measurement
- Dimmer phase delayed drive
- Low EMI cycle switching

31.1 External Resistor Selection

The ZCD module requires a current-limiting resistor in series with the external voltage source. The impedance and rating of this resistor depends on the external source peak voltage. Select a resistor value that will drop all of the peak voltage when the current through the resistor is nominally 300 μ A. Refer to [Equation 31-1](#) and [Figure 31-1](#). Make sure that the ZCD I/O pin internal weak pull-up is disabled so it does not interfere with the current source and sink.

EQUATION 31-1: EXTERNAL RESISTOR

$$R_{SERIES} = \frac{V_{PEAK}}{3 \times 10^{-4}}$$

FIGURE 31-1: EXTERNAL VOLTAGE

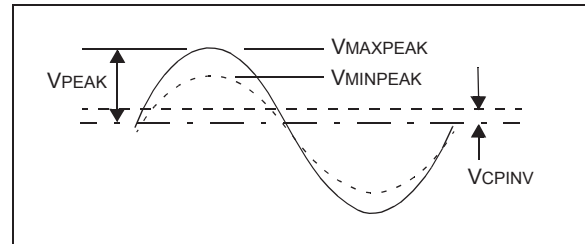


FIGURE 33-13: AUTO-WAKE-UP BIT (WUE) TIMING DURING NORMAL OPERATION

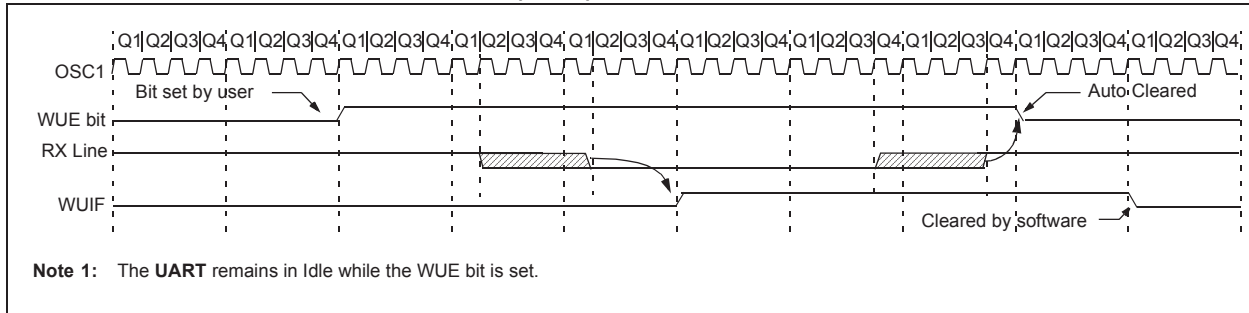
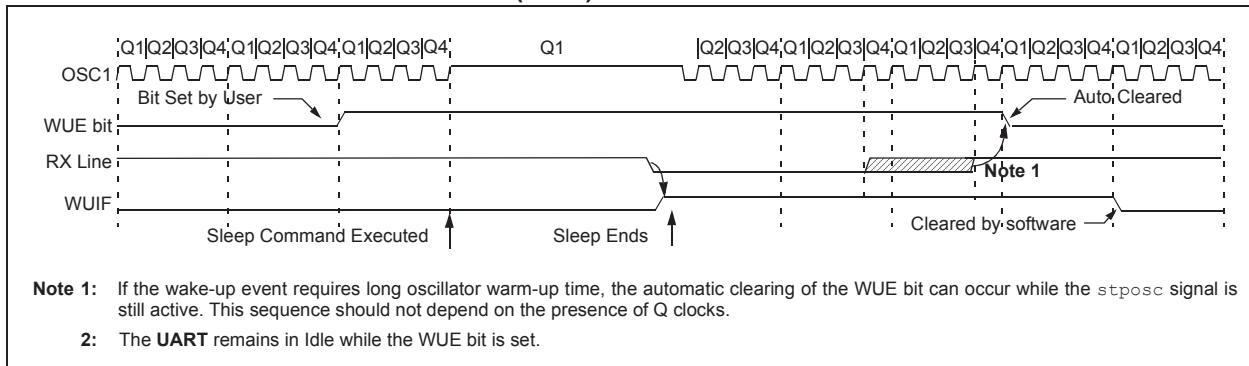


FIGURE 33-14: AUTO-WAKE-UP BIT (WUE) TIMINGS DURING SLEEP



33.18 Transmitting a Break

The UART module has the capability of sending either a fixed length Break period or a software timed Break period. The fixed length Break consists of a Start bit, followed by 12 '0' bits and a Stop bit. The software timed Break is generated by setting and clearing the BRKOVF bit in the UxCON1 register.

To send the fixed length Break, set the SENDB and TXEN bits in the UxCON0 register. The Break sequence is then initiated by a write to UxTXB. The timed Break will occur first, followed by the character written to UxTXB that initiated the Break. The initiating character is typically the Sync character of the LIN specification.

SENB is disabled in the LIN and DMX modes because those modes generate the Break sequence automatically.

The SENDB bit is automatically reset by hardware after the Break Stop bit is complete.

The TXMTIF bit in the UxERRIR register indicates when the transmit operation is active or idle, just as it does during normal transmission. See Figure 33-15 for the timing of the Break sequence.

33.19 Receiving a Break

The UART has counters to detect when the RX input remains in the space state for an extended period of time. When this happens, the RXBKIF bit in the UxERRIR register is set.

A Break is detected when the RX input remains in the space state for 11 bit periods for asynchronous and LIN modes, and 23 bit periods for DMX mode.

The user can select to receive the Break interrupt as soon as the Break is detected or at the end of the Break, when the RX input returns to the Idle state. When the RXBIMD bit in the UxCON1 is '1' then RXBKIF is set immediately upon Break detection. When RXBIMD is '0' then RXBKIF is set when the RX input returns to the Idle state.

33.20 UART Operation During Sleep

The UART ceases to operate during Sleep. The safe way to wake the device from Sleep by a serial operation is to use the Wake-on-Break feature of the UART. See Section 33.17.3, Auto-Wake-up on Break

REGISTER 33-12: UxP1H: UART PARAMETER 1 HIGH REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0/0
—	—	—	—	—	—	—	P1<8>
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **Unimplemented:** Read as '0'

bit 0 **P1<8>:** Most Significant Bit of Parameter 1

DMX mode:

Most Significant bit of number of bytes to transmit between Start Code and automatic Break generation

DALI Control Device mode:

Most Significant bit of idle time delay after which a Forward Frame is sent. Measured in half-bit periods

DALI Control Gear mode:

Most Significant bit of delay between the end of a Forward Frame and the start of the Back Frame
Measured in half-bit periods

Other modes:

Not used

REGISTER 33-13: UxP1L: UART PARAMETER 1 LOW REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
P1<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **P1<7:0>:** Least Significant Bits of Parameter 1

DMX mode:

Least Significant Byte of number of bytes to transmit between Start Code and automatic Break generation

DALI Control Device mode:

Least Significant Byte of idle time delay after which a Forward Frame is sent. Measured in half-bit periods

DALI Control Gear mode:

Least Significant Byte of delay between the end of a Forward Frame and the start of the Back Frame
Measured in half-bit periods

LIN mode:

PID to transmit (Only Least Significant 6 bits used)

Asynchronous Address mode:

Address to transmit (9th transmit bit automatically set to '1')

Other modes:

Not used

REGISTER 33-18: UxTXCHK: UART TRANSMIT CHECKSUM RESULT REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
TXCHK<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **TXCHK<7:0>**: Checksum calculated from TX bytes

LIN mode and C0EN = 1:

Sum of all transmitted bytes including PID

LIN mode and C0EN = 0:

Sum of all transmitted bytes except PID

All other modes and C0EN = 1:

Sum of all transmitted bytes since last clear

All other modes and C0EN = 0:

Not used

REGISTER 33-19: UxRXCHK: UART RECEIVE CHECKSUM RESULT REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
RXCHK<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **RXCHK<7:0>**: Checksum calculated from RX bytes

LIN mode and C0EN = 1:

Sum of all received bytes including PID

LIN mode and C0EN = 0:

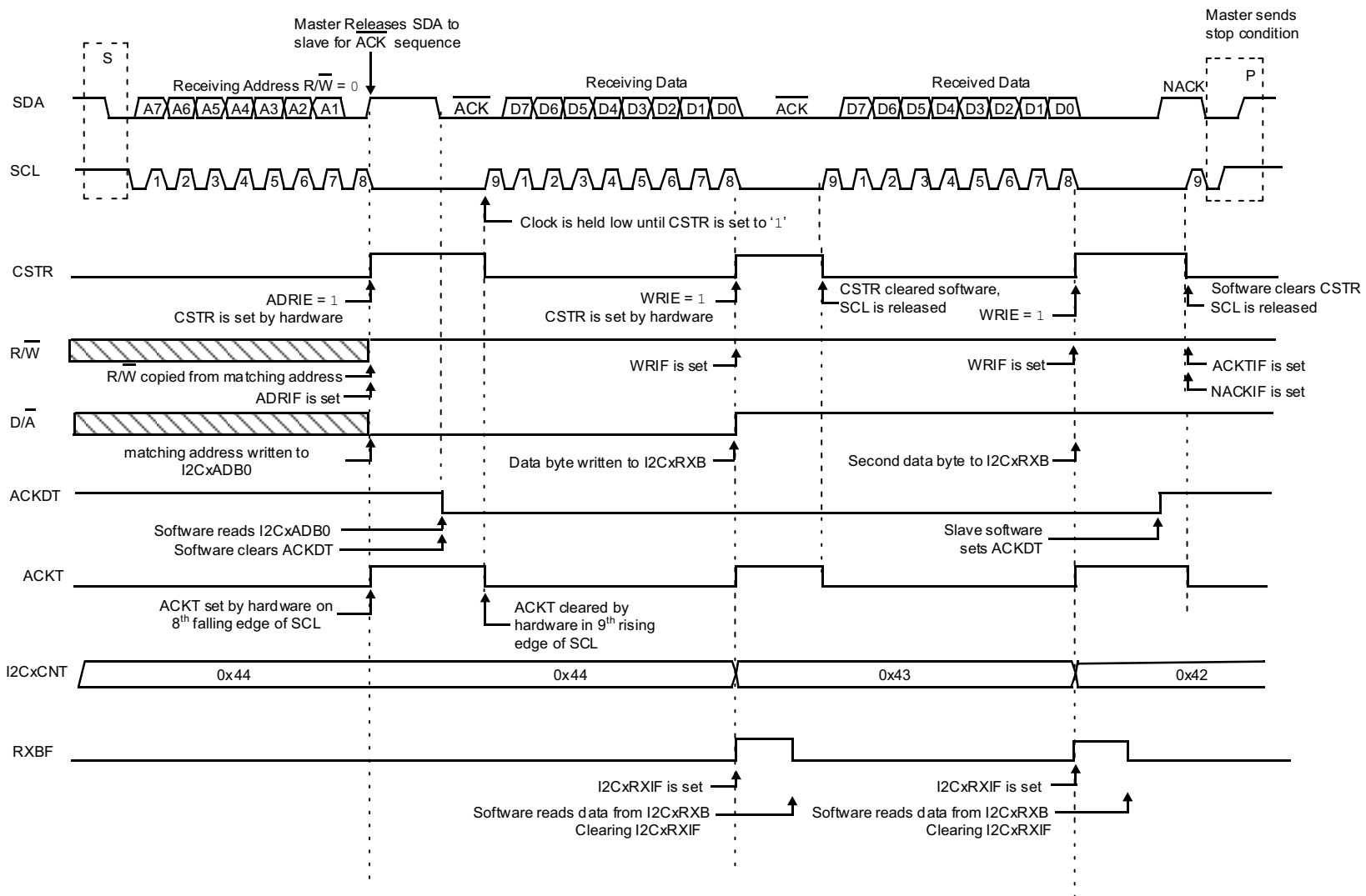
Sum of all received bytes except PID

All other modes and C0EN = 1:

Sum of all received bytes since last clear

All other modes and C0EN = 0:

Not used

FIGURE 35-8: I²C SLAVE, 7-BIT ADDRESS, RECEPTION NO I2CxCNT (ACKTIE = 0, ADRIE = 1, WRIE = 1)Rev. 10-000-252A
11/2/2016

40.7 Comparator Response Time

The comparator output is indeterminate for a period of time after the change of an input source or the selection of a new reference voltage. This period is referred to as the response time. The response time of the comparator differs from the settling time of the voltage reference. Therefore, both of these times must be considered when determining the total response time to a comparator input change. See the Comparator and Voltage Reference Specifications in [Table 46-15](#) and [Table 46-17](#) for more details.

40.8 Analog Input Connection Considerations

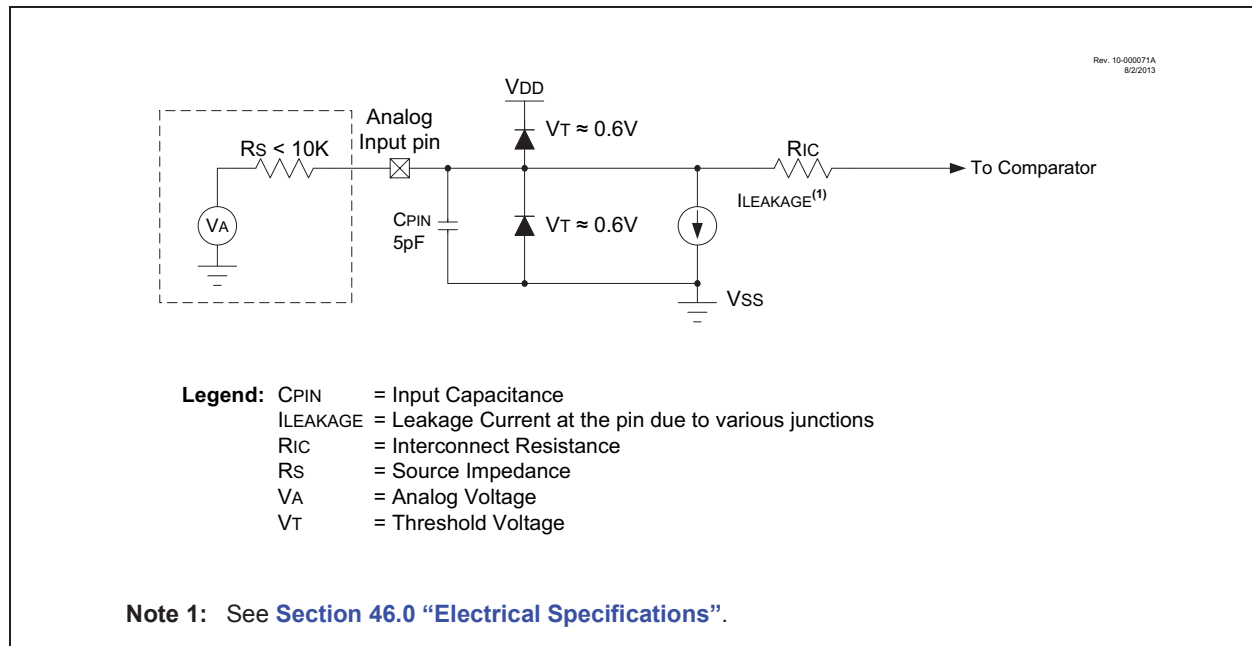
A simplified circuit for an analog input is shown in [Figure 40-3](#). Since the analog input pins share their connection with a digital input, they have reverse biased ESD protection diodes to V_{DD} and V_{SS} . The analog input, therefore, must be between V_{SS} and V_{DD} . If the input voltage deviates from this range by more than 0.6V in either direction, one of the diodes is forward biased and a latch-up may occur.

A maximum source impedance of 10 k Ω is recommended for the analog sources. Also, any external component connected to an analog input pin, such as a capacitor or a Zener diode, should have very little leakage current to minimize inaccuracies introduced.

Note 1: When reading a PORT register, all pins configured as analog inputs will read as a '0'. Pins configured as digital inputs will convert as an analog input, according to the input specification.

2: Analog levels on any pin defined as a digital input, may cause the input buffer to consume more current than is specified.

FIGURE 40-3: ANALOG INPUT MODEL



PIC18(L)F24/25K42

TABLE 43-1: PIC18(L)F24/25K42 INSTRUCTION SET

Mnemonic, Operands	Description	Cycles	16-Bit Instruction Word				Status Affected	Notes		
			MSb		LSb					
BYTE-ORIENTED FILE REGISTER INSTRUCTIONS										
ADDWF	f, d ,a	Add WREG and f	1	0010	01da	ffff	ffff	C, DC, Z, OV, N		
ADDWFC	f, d, a	Add WREG and Carry bit to f	1	0010	00da	ffff	ffff	C, DC, Z, OV, N		
ANDWF	f, d, a	AND WREG with f	1	0001	01da	ffff	ffff	Z, N		
CLRF	f, a	Clear f	1	0110	101a	ffff	ffff	Z		
COMF	f, d, a	Complement f	1	0001	11da	ffff	ffff	Z, N		
DECF	f, d, a	Decrement f	1	0000	01da	ffff	ffff	C, DC, Z, OV, N		
INCF	f, d, a	Increment f	1	0010	10da	ffff	ffff	C, DC, Z, OV, N		
IORWF	f, d, a	Inclusive OR WREG with f	1	0001	00da	ffff	ffff	Z, N		
MOVF	f, d, a	Move f to WREG or f	1	0101	00da	ffff	ffff	Z, N		
MOVFF	f _s , f _d	Move f _s (source) to f _d (destination)	2	1100	ffff	ffff	ffff	None		
MOVFFL	f _s , f _d	Move f _s (source) to g (full destination) f _d (full destination)3rd word	3	0000	0000	0110	ffff	None		
				1111	ffff	ffff	ffgg			
				1111	gggg	gggg	gggg			
				0110	111a	ffff	ffff			
MOVWF	f, a	Move WREG to f	1	0110	111a	ffff	ffff	None	2, 3	
MULWF	f, a	Multiply WREG with f	1	0000	001a	ffff	ffff	None		
NEGF	f, a	Negate f	1	0110	110a	ffff	ffff	C, DC, Z, OV, N		
RLCF	f, d, a	Rotate Left f through Carry	1	0011	01da	ffff	ffff	C, Z, N		
RLNCF	f, d, a	Rotate Left f (No Carry)	1	0100	01da	ffff	ffff	Z, N		
RRCF	f, d, a	Rotate Right f through Carry	1	0011	00da	ffff	ffff	C, Z, N		
RRNCF	f, d, a	Rotate Right f (No Carry)	1	0100	00da	ffff	ffff	Z, N		
SETF	f, a	Set f	1	0110	100a	ffff	ffff	None		
SUBFWB	f, d, a	Subtract f from WREG with borrow	1	0101	01da	ffff	ffff	C, DC, Z, OV, N		
SUBWF	f, d, a	Subtract WREG from f	1	0101	11da	ffff	ffff	C, DC, Z, OV, N		2
SUBWFB	f, d, a	Subtract WREG from f with borrow	1	0101	10da	ffff	ffff	C, DC, Z, OV, N		
SWAPF	f, d, a	Swap nibbles in f	1	0011	10da	ffff	ffff	None		
XORWF	f, d, a	Exclusive OR WREG with f	1	0001	10da	ffff	ffff	Z, N		
BYTE-ORIENTED SKIP INSTRUCTIONS										
CPFSEQ	f, a	Compare f with WREG, skip =	1 (2 or 3)	0110	001a	ffff	ffff	None	1	
CPFSGT	f, a	Compare f with WREG, skip >	1 (2 or 3)	0110	010a	ffff	ffff	None	1	
CPFSLT	f, a	Compare f with WREG, skip <	1 (2 or 3)	0110	000a	ffff	ffff	None	1	
DECFSZ	f, d, a	Decrement f, Skip if 0	1 (2 or 3)	0010	11da	ffff	ffff	None	1	
DCFSNZ	f, d, a	Decrement f, Skip if Not 0	1 (2 or 3)	0100	11da	ffff	ffff	None	1	
INCFSZ	f, d, a	Increment f, Skip if 0	1 (2 or 3)	0011	11da	ffff	ffff	None	1	
INFSNZ	f, d, a	Increment f, Skip if Not 0	1 (2 or 3)	0100	10da	ffff	ffff	None	1	
TSTFSZ	f, a	Test f, skip if 0	1 (2 or 3)	0110	011a	ffff	ffff	None	1	
BIT-ORIENTED FILE REGISTER INSTRUCTIONS										
BCF	f, b, a	Bit Clear f	1	1001	bbba	ffff	ffff	None		
BSF	f, b, a	Bit Set f	1	1000	bbba	ffff	ffff	None		
BTG	f, d, a	Bit Toggle f	1	0111	bbba	ffff	ffff	None		
BIT-ORIENTED SKIP INSTRUCTIONS										
BTFSC	f, b, a	Bit Test f, Skip if Clear	1 (2 or 3)	1011	bbba	ffff	ffff	None	1	
BTFSS	f, b, a	Bit Test f, Skip if Set	1 (2 or 3)	1010	bbba	ffff	ffff	None	1	

Note 1: If Program Counter (PC) is modified or a conditional test is true, the instruction requires an additional cycle. The extra cycle is executed as a NOP.

2: Some instructions are multi word instructions. The second/third words of these instructions will be decoded as a NOP, unless the first word of the instruction retrieves the information embedded in these 16-bits. This ensures that all program memory locations have a valid instruction.

3: f_s and f_d do not cover the full memory range. 2 MSBs of bank selection are forced to 'b00 to limit the range of these instructions to lower 4k addressing space.

CLRWDT Clear Watchdog Timer

Syntax:	CLRWDT				
Operands:	None				
Operation:	000h → WDT, 000h → WDT postscaler, 1 → \overline{TO} , 1 → PD				
Status Affected:	\overline{TO} , \overline{PD}				
Encoding:	<table border="1"><tr><td>0000</td><td>0000</td><td>0000</td><td>0100</td></tr></table>	0000	0000	0000	0100
0000	0000	0000	0100		
Description:	CLRWDT instruction resets the Watchdog Timer. It also resets the postscaler of the WDT. Status bits, \overline{TO} and PD, are set.				
Words:	1				
Cycles:	1				

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	No operation	Process Data	No operation

Example: CLRWDT

Before Instruction	
WDT Counter	= ?
After Instruction	
WDT Counter	= 00h
WDT Postscaler	= 0
\overline{TO}	= 1
PD	= 1

COMF Complement f

Syntax:	COMF f {,d {,a}}				
Operands:	$0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$				
Operation:	$(\bar{f}) \rightarrow \text{dest}$				
Status Affected:	N, Z				
Encoding:	<table border="1"><tr><td>0001</td><td>11da</td><td>ffff</td><td>ffff</td></tr></table>	0001	11da	ffff	ffff
0001	11da	ffff	ffff		
Description:	The contents of register 'f' are				

If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See [Section 43.2.3 "Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode"](#) for details.

Words:	1
Cycles:	1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write to destination

Example: COMF REG, 0, 0

Before Instruction	
REG	= 13h
After Instruction	
REG	= 13h
W	= ECh