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## What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "[Embedded - Microcontrollers](#)"

### Details

Product Status	Obsolete
Core Processor	78K/0
Core Size	8-Bit
Speed	20MHz
Connectivity	3-Wire SIO, I <sup>2</sup> C, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	40
Program Memory Size	48KB (48K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/upd78f0394gc-8ea-a">https://www.e-xfl.com/product-detail/renesas-electronics-america/upd78f0394gc-8ea-a</a>

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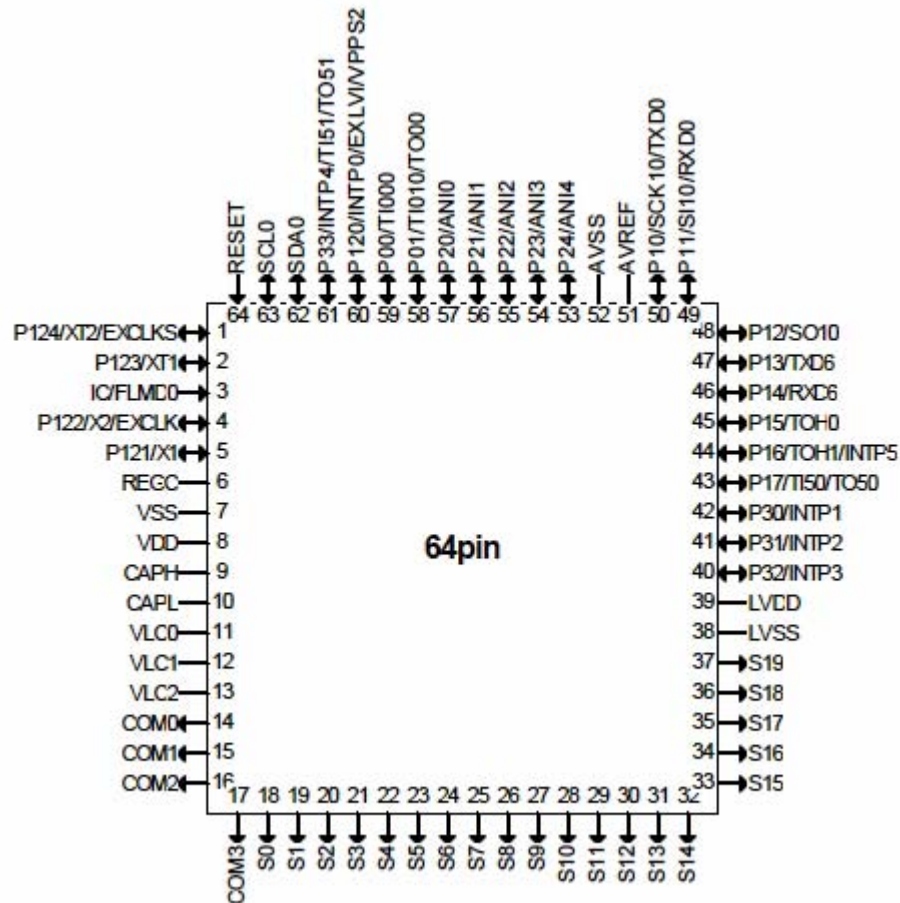
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## 2. Pin Function (uPD78F0373, uPD78F0375)

PIN NAME	Function
VDD	Positive power supply
VSS	Ground potential
LVDD	Positive power supply
LVSS	Ground potential
RESET_B	System reset input
FLMD0	Flash EEPROM programming mode setting
REGC	Connecting regulator stabilization capacitor. Connect to GND via a capacitor (0.47 $\mu$ F)
AVREF	A/D converter analog power supply and power supply for P20-P24
AVSS	Ground potential for A/D converter and P20 - P24
VLC0 VLC1 VLC2	LCD driving voltage <ul style="list-style-type: none"> <li>• VLC0: Three times VLC2 output voltage</li> <li>• VLC1: Two times VLC2 output voltage</li> <li>• VLC2: Reference voltage</li> </ul>
CAPH CAPL	Booster capacitor connection for LCD drive voltage
COM0-COM3	LCD controller/driver common signal output
P00 /TI000	I/O port External count clock input to 16-bit timer/event counter 00 Capture trigger input to capture registers (CR000, CR010) of 16-bit timer/event counter 00 (TM00)
P01 /TI010 /TO00	I/O port Capture trigger input to capture register (CR000) of 16-bit timer/event counter 00 (TM00) 16-bit timer/event counter 00 output (TM00) 16-bit timer/event counter 01 output (TM01)
P10 /SCK10 /TXD0	I/O port Clock input/ output for serial interface (CSI10) Serial data output from asynchronous serial interface (UART0)
P11 /SI10 /RXD0	I/O port Serial data input to serial interface (CSI10) Serial data input to asynchronous serial interface (UART0)
P12 /SO10	I/O port Serial data output form serial interface (CSI10)
P13 /TXD6	I/O port Serial data output from asynchronous serial interface (UART6)
P14 /RXD6	I/O port Serial data input to asynchronous serial interface (UART6)
P15 /TOH0	I/O port 8-bit timer H0 output (TMH0)
P16 /TOH1 /INTP5	I/O port 8-bit timer H1 output (TMH1) External interrupt request input with specifiable valid edges
P17 /TI50 /TO50	I/O port External count clock input to 8-bit timer/event counter 50 (TM50) 8-bit timer/event counter 50 output (TM50)
P20/ANI0- P24/ANI7	I/O port port/Analog input of A/D converter
P30/INTP1 P31/INTP2 P32/INTP3	I/O port External interrupt request input with specifiable valid edges
P33 /TI51 /TO51 /INTP4	I/O port External count clock input to 8-bit timer/event counter 51(TM51) 8-bit timer/event counter 51output(TM51) External interrupt request input with specifiable valid edges

(P60) /SCL0	(IIC only) Clock input/ output for serial interface (IIC0)
(P61) /SDA0	(IIC only) Serial data input/ output for serial interface (IIC0)
P120 /INTP0 /EXLVI	I/O port External interrupt request input with specifiable valid edges Reference voltage input for Low voltage Indicator
P121 /X1	I/O port (An external oscillation circuit is not used) Connecting resonator for main system clock oscillation
P122 /X2	I/O port (An external oscillation circuit is not used) Crystal connection for main system clock oscillation
P123 /XT1	I/O port (An external oscillation circuit is not used) Crystal connection for subsystem clock oscillation
P124 /XT2	I/O port (An external oscillation circuit is not used) Crystal connection for subsystem clock oscillation
S0-S19	LCD controller/driver segment signal output

### 3. Pin Lay Out



## 4. Memory space

78K0/LE2 have 64KB linear address area.

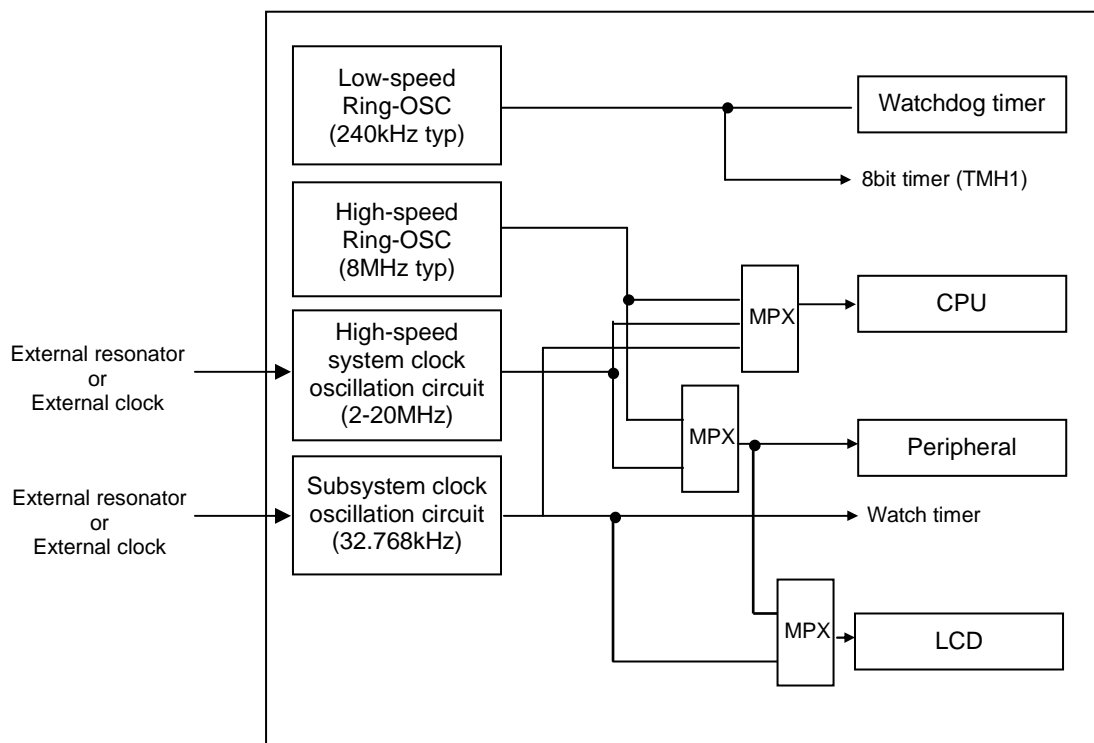
Products	ROM size	ROM address	Common area address	Bank area address	Number of Bank
$\mu$ PD78F0363	32KB	0000H-7FFFH	-	-	-
$\mu$ PD78F0341	16KB	0000H-3FFFH	-	-	-

## 5. Clock

78K0/LE2 have 3 type internal Ring-OSC and 2 type external resonator oscillation circuit.

78K0/LE2 can be operated high-speed internal Ring-OSC only. 240KHz Ring-OSC can connect to Watch dog timer and 8bit timer (TMH1) only for high secure.

Fig. Clock connecting block image



## 6. Outline of Functions of 78K0/Lx2

**Table 78K0/Lx2 Functions**

			LE2	LF2	LF2F		LG2		
Package			64	80				100	
CPU			8bit CPU						
Oscillation circuit	Main	Cera/ Crystal	Vdd=4.0V-5.5V:20MHz Vdd=2.7V-5.5V:10MHz Vdd=1.8V-5.5V:5MHz						
		Ring OSC	Vdd=1.8V-5.5V:8MHz						
	Ring-OSC		Vdd=2.7V-5.5V:240KHz						
	Sub Clock		32.768KHz						
	VDD			1.8V-5.5V					
Flash ROM (K byte)			16/32	32	60	32	60	32	60/128
RAM (K byte)			768/1	1	3	1	3	1	3/7
LCD Segment (MAX.)			80	104		144		160	
Timer	16bit	TM0	1		2	1	2	1	2
	8bit	TM5	2						
		TMH	2						
	WDT		1						
	WT		1						
Serial	3SIO/UART		1						
	3SIO		-						1
	UART		1						
	IIC*		1						
10bit A/D			5ch	8ch		-		8ch	
Key return			-	7pins				8pins	
Multiplier/Divider			-		Yes	-	Yes	-	Yes
LVI/POC			Yes						
Flash Self Programming			Yes						

\*Shared with internal communication

	Ratings	
	-0.5 to +6.5	
	-0.5 to +6.5	
	-0.5 to +0.3	
	-0.5 to +0.3	
	-0.5 to VDD+0.3 <sup>Note</sup>	
	-0.5 to +0.3	
P33, T_B	-0.3 to VDD+0.3 <sup>Note</sup>	
	-0.3 to +6.5	
	-0.3 to VDD+0.3 <sup>Note</sup>	
	-0.3 to AVREF+0.3 <sup>Note</sup> and -0.3 to VDD+0.3 <sup>Note</sup>	
	-10	
124	-25	
r, P30-P33	-55	
	30	
124	60	
3, P60-P61	140	
	-40 to +85	
ode		
	-65 to +150	

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## Ring-OSC Oscillator Characteristics

(TA = -40 to +85°C, 1.8 V < VDD = LVDD < 5.5 V, 2.3 V < AVREF . VDD= LVDD, VSS = LVSS = AVSS = 0 V)

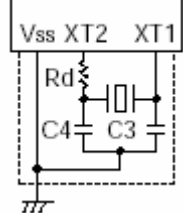
Resonator	Parameter		MIN.	TYP.	MAX.	Unit
8MHz Ring-OSC oscillator	High-speed Ring-OSC Oscillation frequency(fRH) <small>Note</small>	2.7 V < VDD < 5.5 V	7.6 <small>Note2</small>	8.0 <small>Note2</small>	8.4 <small>Note2</small>	MHz
		1.8 V < VDD < 2.7 V		8.0 <small>Note2</small>		MHz
240KHz Ring-OSC oscillator	Low-speed Ring-OSC Oscillation frequency(fRL) <small>Note</small>	2.7 V < VDD < 5.5 V	216	240	264	KHz
		1.8 V < VDD < 2.7 V	TBD	240	TBD	KHz

### Note

1. Indicates only oscillator characteristics. Refer to AC Characteristics for instruction execution time.
2. This is the frequency in the case of RSTS(RCM.7)=1. This is 5 MHz(TYP.) in the case of RSTS=0.

## Subsystem Clock Oscillator Characteristics

(TA = -40 to +85°C, 1.8 V < VDD = LVDD < 5.5 V, 2.3 V < AVREF . VDD= LVDD, VSS = LVSS = AVSS = 0 V)

Resonator	Recommended Circuit	Conditions		MIN.	TYP.	MAX.	Unit
Crystal resonator		Oscillation frequency(fSUB) <small>Note</small>	1.8 V < VDD < 2.7 V	32	32.768	35	KHz

**Note** Indicates only oscillator characteristics. Refer to AC Characteristics for instruction execution time.

### Cautions

1. When using the subsystem clock oscillator, wire as follows in the area enclosed by the broken lines in the above figures to avoid an adverse effect from wiring capacitance.

- Keep the wiring length as short as possible.
- Do not cross the wiring with the other signal lines.
- Do not route the wiring near a signal line through which a high fluctuating current flows.
- Always make the ground point of the oscillator capacitor the same potential as Vss.
- Do not ground the capacitor to a ground pattern through which a high current flows.
- Do not fetch signals from the oscillator.

2. The subsystem clock oscillator is designed as a low-amplitude circuit for reducing power

**Remark** For the resonator selection and oscillator constant, customers are requested to either evaluate the oscillation themselves or apply to the resonator manufacturer for evaluation.

## DC Characteristics (1/3)

(TA = -40 to +85°C, 1.8V < VDD = LVDD < 5.5 V, VSS = EVSS = AVSS = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output current, high	IOH1	Per pin of P00-P01, P10-P17, P30-P33, P120	4.0 V < VDD < 5.5 V		-3.0	mA
			2.7 V < VDD < 4.0 V		-2.5	
			1.8 V < VDD < 2.7 V		-1.0	
		Total of P00-P01, P120	4.0 V < VDD < 5.5 V		-20.0	mA
			2.7 V < VDD < 4.0 V		-10.0	
			1.8 V < VDD < 2.7 V		-5.0	
		Total of P10-P17, P30-P33	4.0 V < VDD < 5.5 V		-30.0	mA
			2.7 V < VDD < 4.0 V		-19.0	
			1.8 V < VDD < 2.7 V		-10.0	
		Total of all pins	4.0 V < VDD < 5.5 V		-50.0	mA
			2.7 V < VDD < 4.0 V		-29.0	
			1.8 V < VDD < 2.7 V		-15.0	
Output current, low	IOH2	Per pin of P20-P24 <small>Note</small>	1.8 V < VDD < 5.5 V		-100	
	IOH3	Per pin of P121-P124	4.0 V < VDD < 5.5 V		-1.0	mA
	IOL1	Per pin of P00-P06, P10-P17, P30-P33, P120	4.0 V < VDD < 5.5 V		8.5	mA
			2.7 V < VDD < 4.0 V		5.0	
			1.8 V < VDD < 2.7 V		2.0	
		Per pin of P60-P61	4.0 V < VDD < 5.5 V		15.0	mA
			2.7 V < VDD < 4.0 V		5.0	
			1.8 V < VDD < 2.7 V		2.0	
		Total of P00-P01, P120	4.0 V < VDD < 5.5 V		20.0	mA
			2.7 V < VDD < 4.0 V		15.0	
			1.8 V < VDD < 2.7 V		9.0	
		Total of P10-P17, P30-P33	4.0 V < VDD < 5.5 V		45.0	mA
			2.7 V < VDD < 4.0 V		35.0	
			1.8 V < VDD < 2.7 V		20.0	
		Total of all pins	4.0 V < VDD < 5.5 V		65.0	mA
			2.7 V < VDD < 4.0 V		50.0	
			1.8 V < VDD < 2.7 V		29.0	
	IOL2	Per pin of P20-P24 <small>Note</small>	1.8 V < VDD < 5.5 V		400	uA
	IOL3	Per pin of P121-P124	4.0 V < VDD < 5.5 V		1.0	mA
Input voltage, high	VIH1	P12, P13, P15, P60-P61, P121-P124	0.7VDD		VDD	V
	VIH2	P10-P11, P14, P16-P17, P30-P33, P120, RESET_B	0.8VDD		VDD	V
	VIH3	P20-P24 <small>Note</small>	0.7AVREF		AVREF	V
Input voltage, high	VIH1	P12, P13, P15, P60-P61, P121-P124	0		0.3VDD	
	VIH2	P00, P01, P10-P11, P14, P16-P17, P30-P33, P120, RESET_B	0		0.2VDD	V
	VIH3	P20-P24 <small>Note</small>	0		0.3AVREF	V

**Note** When used as digital input ports, set AVREF = VDD, = LVDD.

**Caution** This specification is Duty = 70% condition of IOH and IOL.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of port pins.

## AC Characteristics

### (1) Basic operation

(TA = -40 to +85°C, 1.8V < VDD = LVDD < 5.5 V, VSS = LVSS = AVSS = 0 V)

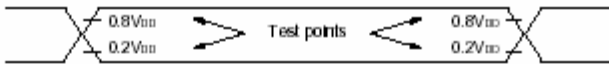
Parameter	Symbol	Conditions			MIN.	TYP.	MAX.	Unit
Instruction cycle (minimum instruction execution time)	T <sub>CY</sub>	Main system clock(f <sub>XP</sub> ) operation	High-speed system clock(f <sub>XH</sub> )	4.0 V< VDD < 5.5 V	0.1		16	uS
				2.7 V< VDD < 4.0 V	0.2		16	uS
				1.8 V< VDD < 2.7 V	0.4		16	uS
			High-speed Ring-OSC clock(f <sub>RH</sub> )	2.7 V< VDD < 5.5 V	0.25		4	uS
				1.8 V< VDD < 2.7 V	0.5		4	uS
		Subsystem clock(f <sub>SUB</sub> )operation				114	122	125
External main system clock frequency	f <sub>EXCLK</sub>	4.0 V< VDD < 5.5 V			2.0		20.0	MHz
		2.7 V< VDD < 4.0 V			2.0		10.0	MHz
		1.8 V< VDD < 2.7 V			2.0		5.0	MHz
External main system clock input high-/low-level width	t <sub>EXCLKH</sub> , t <sub>EXCLKL</sub>				(1/ f <sub>EXCLK</sub> x 1/2) - 1			nS
External subsystem clock frequency	f <sub>EXCLKS</sub>				32	32.768	35	kHz
External subsystem clock input high-/low-level width	t <sub>EXCLKSH</sub> , t <sub>EXCLKSL</sub>				(1/ f <sub>EXCLKS</sub> x 1/2) - 5			nS
TI000, TI010, TI001, TI011 input high-level width, low-level width	t <sub>TIH0</sub> , t <sub>TIL0</sub>	4.0 V< VDD < 5.5 V			2/f <sub>sam</sub> + 0.1 <sup>Note1</sup>			nS
		2.7 V< VDD < 4.0 V			2/f <sub>sam</sub> + 0.2 <sup>Note1</sup>			nS
TI50, TI51 input frequency	f <sub>TI5</sub>	4.0 V< VDD < 5.5 V					10	MHz
		2.7 V< VDD < 4.0 V					10	MHz
		1.8 V< VDD < 2.7 V					5	MHz
TI50, TI51 input high-level width, low-level width	t <sub>TIH5</sub> , t <sub>TIL5</sub>	4.0 V< VDD < 5.5 V			50			nS
		2.7 V< VDD < 4.0 V			50			nS
		1.8 V< VDD < 2.7 V			100			nS
Interrupt input high-level width, low-level width	t <sub>INTH</sub> , t <sub>INTL</sub>				1			uS
Key return input low-level Width	t <sub>KR</sub>				250			nS
RESET low-level width	t <sub>RSL</sub>				10 <sup>Note2</sup>			uS

### Notes

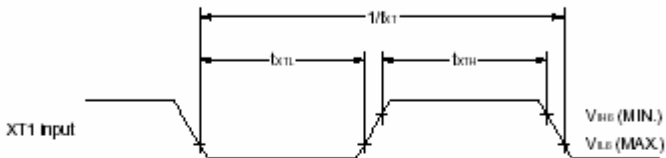
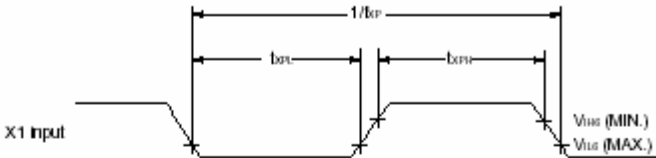
1. Selection of f<sub>sam</sub> = f<sub>PRS</sub>, f<sub>PRS</sub>/4, f<sub>PRS</sub>/256 or f<sub>PRS</sub>, f<sub>PRS</sub>/16, f<sub>PRS</sub>/64 is possible using bits 0 and 1 (PRM000, PRM001 or PRM010,PRM011) of prescaler mode register 00 and 01 (PRM00,PRM01). Note that when selecting the TI000 or TI001 valid edge as the count clock, f<sub>sam</sub> = f<sub>PRS</sub>.

2. Input low level signal into RESET pin until power supply voltage is stabilized in the case of the power supply voltage rise time is slowly (more than 3.4ms).

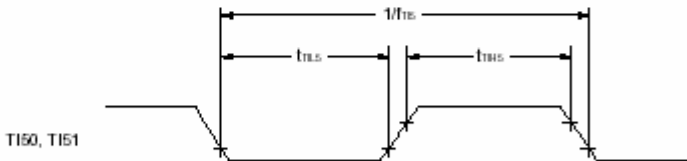
AC Timing Test Points (Excluding X1 Input)



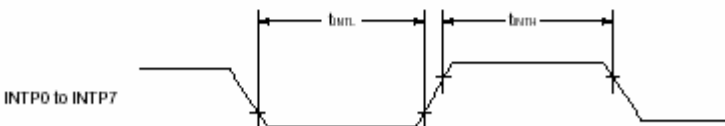
Clock Timing



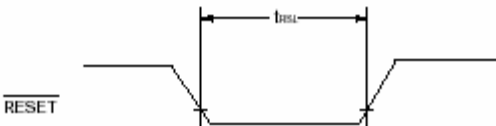
T1 Timing



Interrupt Request Input Timing



RESET Input Timing



## (2) Serial interface

(TA = -40 to +85°C, 1.8V < VDD = LVDD < 5.5 V, VSS = LVSS = AVSS = 0 V)

(a) UART mode (UART6, dedicated baud rate generator output)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Transfer rate					312.5	kbps

(b) UART mode (UART0, dedicated baud rate generator output)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Transfer rate					312.5	kbps

(c) IIC0 mode

Parameter	Symbol	Normal mode		High speed mode		Unit
		MIN.	MAX.	MIN.	MAX.	
SCL0 clock frequency	f <sub>CLK</sub>	0	100	0	400	kbps
Start/restart condition setup time <sup>Note1</sup>	t <sub>SU: STA</sub>	4.8		0.7		
hold time	t <sub>HD: STA</sub>	4.1		0.7		
Hold time in SCL = "L"	t <sub>LOW</sub>	5.0		1.25		
Hold time in SCL = "H"	t <sub>HIGH</sub>	5.0		1.25		
Data setup time (reception)	t <sub>SU: DAT</sub>	0		0		
Data hold time (sending) <sup>Note2</sup>	t <sub>HD: DAT</sub>	0.47	4.0	0.23	1.0	

### Notes

1. The first clock pulse is generated after this period in the case of the start/restart condition.
2. The MAX of t<sub>HD: DAT</sub> is normal transition value. Wait is occurred in the term of ACK(acknowledge) .

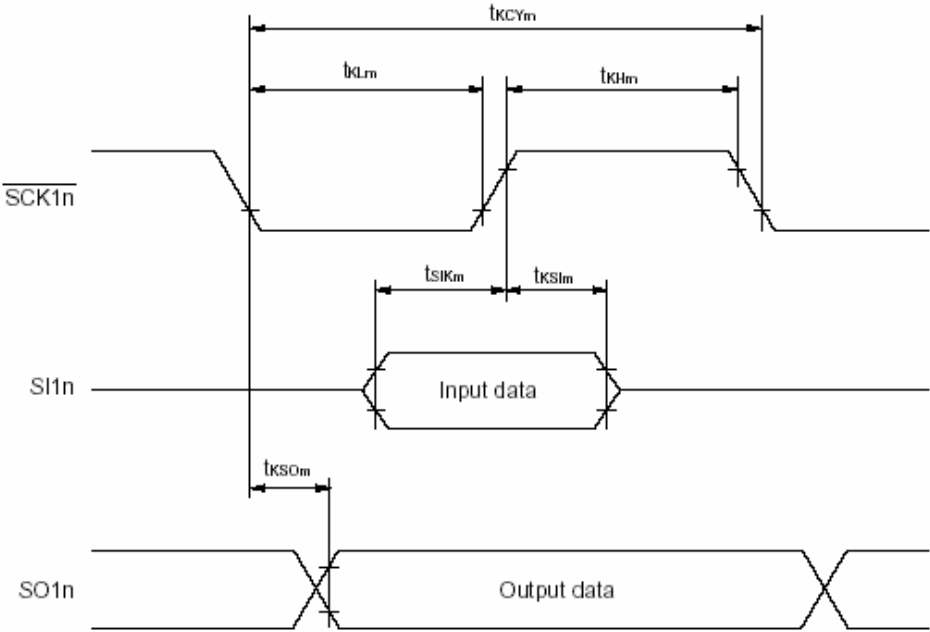
**Caution Specification at 1.8 V ° V<sub>DD</sub> < 2.7V is not fixed.**

(d) 3-wire serial I/O mode (CSI10, CSI11 master mode, SCK1n···internal clock output)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
SCK1n cycle time $t_{KCY1}$	$t_{KCY1}$	$4.0\text{ V} < V_{DD} < 5.5\text{ V}$	100			ns
		$2.7\text{ V} < V_{DD} < 4.0\text{ V}$	200			ns
		$1.8\text{ V} < V_{DD} < 2.7\text{ V}$	400			
SCK1n high-/low-level width	$t_{KH1}$ , $t_{KL1}$		$t_{KCY1}/2 - 10_{\text{Not1}}$			ns
SI1n setup time (to SCK1n $\uparrow$ )	$t_{SIK1}$		30			ns
SI1n hold time (to SCK1n $\uparrow$ )	$t_{KSI1}$		30			ns
Delay time from SCK1n $\downarrow$ to SO1n output	$t_{KSO1}$	$C = 50\text{ pF}_{\text{Note2}}$			40	ns

- Notes** 1. This is the value when the high-speed system clock ( $f_{XH}$ ) is operating.  
2. C is the load capacitance of the SCK1n and SO1n output lines.

**Serial Transfer Timing**  
**3-wire serial I/O mode:**



**Remark**  $m = 1, 2$   
 $n = 0, 1$

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $2.3\text{ V} < AV_{REF} < V_{DD} = EV_{DD} < V_{DD} = LV_{DD}$ ,  $V_{SS} = LV_{SS} = AV_{SS} = 0\text{ V}$ )

## Notes

- ### POC Circuit Characteristics (T<sub>A</sub> = -40 to +85° C)

## Notes

- ## POC Circuit Timing

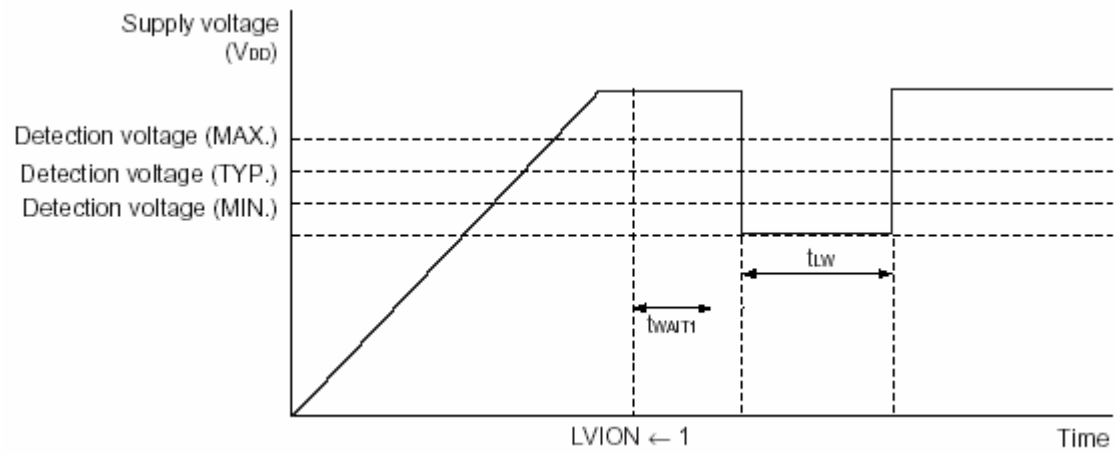


Parameter		Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Detection voltage	Supply voltage level	V <sub>LVI0</sub>		4.10	4.20	4.30	V
		V <sub>LVI1</sub>		3.95	4.05	4.15	V
		V <sub>LVI2</sub>		3.81	3.91	4.01	V
		V <sub>LVI3</sub>		3.66	3.76	3.86	V
		V <sub>LVI4</sub>		3.51	3.61	3.71	V
		V <sub>LVI5</sub>		3.37	3.47	3.57	V
		V <sub>LVI6</sub>		3.22	3.32	3.42	V
		V <sub>LVI7</sub>		3.07	3.17	3.27	V
		V <sub>LVI8</sub>		2.93	3.03	4.03	V
		V <sub>LVI9</sub>		2.78	2.88	2.98	V
		V <sub>LVI10</sub>		2.63	2.73	2.83	V
		V <sub>LVI11</sub>		2.49	2.59	2.69	V
		V <sub>LVI12</sub>		2.34	2.44	2.54	V
		V <sub>LVI13</sub>		2.19	2.29	2.39	V
		V <sub>LVI14</sub>		2.05	2.15	2.25	V
		V <sub>LVI15</sub>		1.90	2.00	2.10	V
	External input pin <sup>Note1</sup>	EXLVI	EXLVI < V <sub>DD</sub> = LV <sub>DD</sub>		1.21		V
Minimum pulse width		t <sub>LW</sub>		T.B.D.	50		us
Operation stabilization wait time <sup>Note2</sup>	T <sub>LWAIT1</sub>				10	T.B.D.	us

- Note**
- 1. Using EXLVI/P120/INTP0 pin
  - 2. Time required from setting LVION to 1 to operation stabilization

**Remark** V<sub>LVI(n-1)</sub> > V<sub>LVI</sub>n : n = 1-15

LVI Circuit Timing





## LCD

a) LCD Ladder type( $T_A = -40$  to  $+85^{\circ}\text{C}$  ,  $2.0\text{V} < \text{LVDD} < 5.5\text{V}$ )

(1) Static

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
LCD power supply	VLCD		2.0		LVDD	V
LCD ladder resistance	RLCD		60.	100	150	k $\Omega$
LCD output Deflection(COMON)	VODC	$I_O = \pm 5\mu\text{A}$	0		$\pm 0.2$	V
LCD output Deflection(SEGMENT)	VODS	$I_O = \pm 1\mu\text{A}$	0		$\pm 0.2$	V

(2) 1/3 bias

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
LCD power supply	VLCD		2.5		LVDD	V
LCD ladder resistance	RLCD		60.	100	150	k $\Omega$
LCD output Deflection(COMON)	VODC	$I_O = \pm 5\mu\text{A}$	0		$\pm 0.2$	V
LCD output Deflection(SEGMENT)	VODS	$I_O = \pm 1\mu\text{A}$	0		$\pm 0.2$	V

(3) 1/2 bias

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
LCD power supply	VLCD		2.7		LVDD	V
LCD ladder resistance	RLCD		60.	100	150	k $\Omega$
LCD output Deflection(COMON)	VODC	$I_O = \pm 5\mu\text{A}$	0		$\pm 0.2$	V
LCD output Deflection(SEGMENT)	VODS	$I_O = \pm 1\mu\text{A}$	0		$\pm 0.2$	V

a) LCD booster type( $T_A = -40$  to  $+85^{\circ}\text{C}$  ,  $1.8\text{V} < \text{LVDD} < 5.5\text{V}$ )

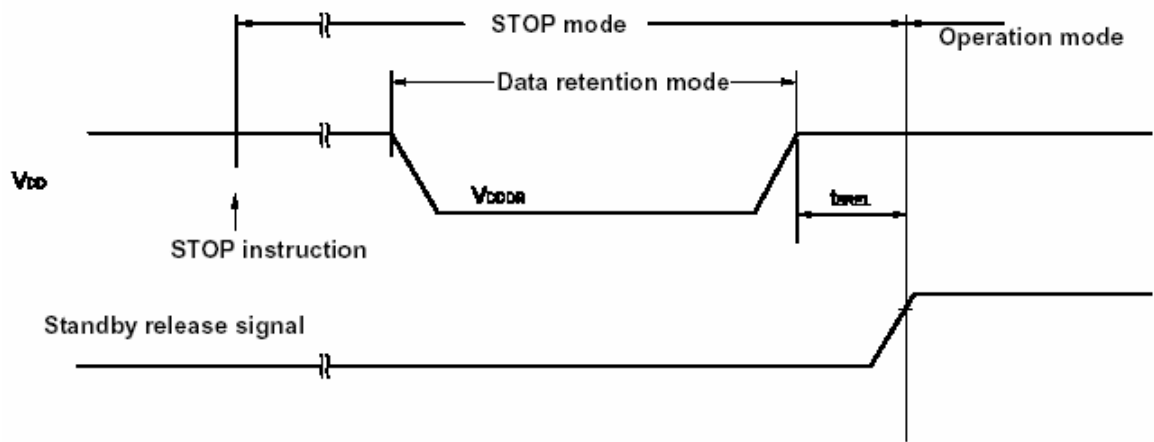
Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
LCD output voltage	VLCD2	C1-C4=0.47uF	GAIN=1	0.87	0.93	1	V
				0.94	1	1.06	V
				1	1.07	1.14	V
				1.16 <sub>Note</sub>	1.13 <sub>Note</sub>	1.2 <sub>Note</sub>	V
		GAIN=1.5	1.35	1.43	1.51	V	
			1.42	1.5	1.58	V	
			1.48	1.57	1.66	V	
			1.54	1.63	1.72	V	
Two times voltage	VLCD1	C1-C4=0.47uF			2xVLCD2		
Three times voltage	LVCD2	C1-C4=0.47uF			3xVLCD2		
Booster wait time	tVAWAIT	GAIN=1	4.0 V < V <sub>DD</sub> < 5.5 V	4			S
			2.7 V < V <sub>DD</sub> < 4.0 V	0.5			S
		GAIN=1.5		0.5			S
LCD output resistor (COMMON)	RODC					40	kΩ
LCD output resistor (SEGMENT)	RODS					200	kΩ

**Note 2.0V < LVDD < 5.5V**

Data Memory STOP Mode Low Supply Voltage Data Retention Characteristics (TA = -40 to +85° C)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Data retention supply voltage	VDDDR		1.3 <sup>Note</sup>		5.5	V

**Note** Dependence on POC detection voltage. The data is held before POC reset, but is not held after POC reset when voltage drops.



(TA = -40 to +85°C, 2.7V < VDD = LVDD < 5.5 V, VSS = LVSS = AVSS = 0 V)

## Notes

- ## (2) Serial write operation characteristics

**Remark** These values may change after evaluation.

## NOTES FOR CMOS DEVICES

### 1 VOLTAGE APPLICATION WAVEFORM AT INPUT PIN

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between VIL (MAX) and VIH (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between VIL (MAX) and VIH (MIN).

### 2 HANDLING OF UNUSED INPUT PINS

Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.

### 3 PRECAUTION AGAINST ESD

A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.

### 4 STATUS BEFORE INITIALIZATION

Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.

### 5 POWER ON/OFF SEQUENCE

In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current.

The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.

### 6 INPUT OF SIGNAL DURING POWER OFF STATE

Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.

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