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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Details	
Product Status	Obsolete
Core Processor	RL78
Core Size	16-Bit
Speed	24MHz
Connectivity	CSI, I ² C, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	18
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 11x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-WFQFN Exposed Pad
Supplier Device Package	24-HWQFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f1037aana-u5

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Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

1.3 Differences between the R5F102 Products and the R5F103 Products

The following are differences between the R5F102 products and the R5F103 products.

- O Whether the data flash memory is mounted or not
- O High-speed on-chip oscillator oscillation frequency accuracy
- O Number of channels in serial interface
- O Whether the DMA function is mounted or not
- O Whether a part of the safety functions are mounted or not

1.3.1 Data Flash

The data flash memory of 2 KB is mounted on the R5F102 products, but not on the R5F103 products.

Product	Data Flash
R5F102 products	2KB
R5F1026A, R5F1027A, R5F102AA,	
R5F10269, R5F10279, R5F102A9,	
R5F10268, R5F10278, R5F102A8,	
R5F10267, R5F10277, R5F102A7,	
R5F10266 Note	
R5F103 products	Not mounted
R5F1036A, R5F1037A, R5F103AA,	
R5F10369, R5F10379, R5F103A9,	
R5F10368, R5F10378 R5F103A8,	
R5F10367, R5F10377, R5F103A7,	
R5F10366	

- **Note** The RAM in the R5F10266 has capacity as small as 256 bytes. Depending on the customer's program specification, the stack area to execute the data flash library may not be kept and data may not be written to or erased from the data flash memory.
- **Caution** When the flash memory is rewritten via a user program, the code flash area and RAM area are used because each library is used. When using the library, refer to RL78 Family Flash Self Programming Library Type01 User's Manual and RL78 Family Data Flash Library Type04 User's Manual.



1.4.3 30-pin products

• 30-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)



Note Provided only in the R5F102 products.

Caution Connect the REGC pin to Vss via capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see 1.5 Pin Identification.

2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). See Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR).



<R> 2. ELECTRICAL SPECIFICATIONS ($T_A = -40$ to +85°C)

<r></r>	This chapter de	scribes the following electrical specifications.
	Target products	A: Consumer applications T _A = -40 to +85°C
<r></r>		R5F102xxAxx, R5F103xxAxx
_		D: Industrial applications $T_A = -40$ to $+85^{\circ}C$
<r></r>		R5F102xxDxx, R5F103xxDxx
		G: Industrial applications when $T_A = -40$ to $+105^{\circ}C$ products is used in the range of $T_A = -40$ to $+85^{\circ}C$
<r></r>		R5F102xxGxx
	Cautions 1.	he RL78 microcontrollers have an on-chip debug function, which is provided for development and

Fautions 1. The RL78 microcontrollers have an on-chip debug function, which is provided for development and evaluation. Do not use the on-chip debug function in products designated for mass production, because the guaranteed number of rewritable times of the flash memory may be exceeded when this function is used, and product reliability therefore cannot be guaranteed. Renesas Electronics is not liable for problems occurring when the on-chip debug function is used.

2. The pins mounted depend on the product. Refer to 2.1 Port Functions to 2.2.1 Functions for each product.



(1/2)

2.3.2 Supply current characteristics

(1) 20-, 24-pin products

Parameter	Symbol			Conditions			MIN.	TYP.	MAX.	Unit												
Supply	IDD1	Operating	HS(High-speed	$f_{IH}=24~MHz^{\text{Note 3}}$	Basic	$V_{DD} = 5.0 V$		1.5		mA												
current ^{Note 1}		mode	main) mode ^{№te4}		operation	$V_{DD} = 3.0 V$		1.5														
					Normal	$V_{DD} = 5.0 V$		3.3	5.0	mA												
					operation	$V_{DD} = 3.0 V$		3.3	5.0													
				$f_{\text{IH}} = 16 \; MHz^{\text{Note 3}}$		$V_{DD} = 5.0 V$		2.5	3.7	mA												
						$V_{DD} = 3.0 V$		2.5	3.7													
			LS(Low-speed	$f_{\text{IH}} = 8 \; MHz^{\text{Note 3}}$		$V_{DD} = 3.0 V$		1.2	1.8	mA												
			main) mode ^{™e₄}			$V_{DD} = 2.0 V$		1.2	1.8													
			HS(High-speed	$f_{MX} = 20 \text{ MHz}^{Note 2},$		Square wave input		2.8	4.4	mA												
			main) mode ^{№064}	VDD = 5.0 V		Resonator connection		3.0	4.6													
				$\label{eq:masses} \begin{split} f_{\text{MX}} &= 20 \ \text{MHz}^{\text{Note 2}}, \\ V_{\text{DD}} &= 3.0 \ \text{V} \\ \\ f_{\text{MX}} &= 10 \ \text{MHz}^{\text{Note 2}}, \end{split}$		Square wave input		2.8	4.4	mA												
						$f_{MX} = 10 \text{ MHz}^{Note 2},$	f _{MX} = 10 MHz ^{Note 2} ,	$f_{MX} = 10 \text{ MHz}^{Note 2},$	$f_{MX} = 10 \text{ MHz}^{Note 2},$									Resonator connection		3.0	4.6	
																	$f_{MX} = 10 \text{ MHz}^{Note 2}$,		Square wave input		1.8	2.6
				V							Resonator connection		1.8	2.6								
		f _{MX} = 10 MHz ^{Note 2} , Square wave in		Square wave input		1.8	2.6	mA														
				$V_{DD} = 3.0 V$		Resonator connection		1.8	2.6													
			LS(Low-speed	$f_{\text{MX}} = 8 \text{ MHz}^{\text{Note 2}},$ $V_{\text{DD}} = 3.0 \text{ V}$	$f_{MX} = 8 \text{ MHz}^{Note 2},$		Square wave input		1.1	1.7	mA											
			main) mode ^{№te4}			Resonator connection		1.1	1.7													
				$f_{MX} = 8 MHz^{Note 2},$		Square wave input		1.1	1.7	mA												
				VDD = 2.0 V		Resonator connection		1.1	1.7													

Notes 1. Total current flowing into V_{DD}, including the input leakage current flowing when the level of the input pin is fixed to V_{DD} or V_{SS}. The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.

- 2. When high-speed on-chip oscillator clock is stopped.
- **3.** When high-speed system clock is stopped
- **4.** Relationship between operation voltage width, operation frequency of CPU and operation mode is as follows.

HS(High speed main) mode: $V_{DD} = 2.7 \text{ V}$ to 5.5 V @1 MHz to 24 MHz $V_{DD} = 2.4 \text{ V}$ to 5.5 V @1 MHz to 16 MHz

- LS(Low speed main) mode: $V_{DD} = 1.8 V$ to 5.5 V @1 MHz to 8 MHz
- Remarks 1. fmx: High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
 - 2. fil: high-speed on-chip oscillator clock frequency
 - **3.** Temperature condition of the TYP. value is $T_A = 25^{\circ}C$.



Minimum Instruction Execution Time during Main System Clock Operation



When the high-speed on-chip oscillator clock is selected During self programming When high-speed system clock is selected _ _ _

_ . _ .

TCY vs VDD (LS (low-speed main) mode)



When the high-speed on-chip oscillator clock is selected

--- During self programming ---. When high-speed system clock is selected



19

25

25

25

19

25

25

25

ns

ns

ns

ns

Delay time from

SOp output Note 1

SCKp↑ to

tkso1

 $(T_A = -40 \text{ to } +85^{\circ}\text{C}, 1.8 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}, \text{ V}_{SS} = 0 \text{ V})$ Parameter Symbol Conditions HS (high-speed LS (low-speed Unit main) Mode main) Mode MIN. MAX. MIN. MAX. SIp setup time $4.0 \text{ V} \le \text{V}_{\text{DD}} \le 5.5 \text{ V}, 2.7 \text{ V} \le \text{V}_{\text{b}} \le 4.0 \text{ V},$ 44 tsik1 110 ns (to SCKp↓) Note 1 $C_{\text{b}}=30 \text{ pF}, \text{ R}_{\text{b}}=1.4 \text{ k}\Omega$ $2.7 \text{ V} \le \text{V}_{\text{DD}} < 4.0 \text{ V}, 2.3 \text{ V} \le \text{V}_{\text{b}} \le 2.7 \text{ V},$ 44 110 ns $C_b = 30 \text{ pF}, R_b = 2.7 \text{ k}\Omega$ 1.8 V \leq V_{DD} < 3.3 V, 1.6 V \leq V_b \leq 2.0 V $^{\text{Note 2}},$ 110 110 ns $C_b = 30 \text{ pF}, R_b = 5.5 \text{ k}\Omega$ Slp hold time 4.0 V \leq V_{DD} \leq 5.5 V, 2.7 V \leq V_b \leq 4.0 V, 19 tksi1 19 ns (from SCKp \downarrow) ^{Note 1} $C_b = 30 \text{ pF}, \text{ R}_b = 1.4 \text{ k}\Omega$ $2.7 \text{ V} \le \text{V}_{\text{DD}} < 4.0 \text{ V}, 2.3 \text{ V} \le \text{V}_{\text{b}} \le 2.7 \text{ V},$ 19 19 ns $C_b = 30 \text{ pF}, \text{ } \text{R}_b = 2.7 \text{ } \text{k}\Omega$

 $1.8 \text{ V} \le V_{\text{DD}} < 3.3 \text{ V}, \ 1.6 \text{ V} \le V_{\text{b}} \le 2.0 \text{ V}^{\text{Note 2}},$

 $4.0 \text{ V} \le \text{V}_{\text{DD}} \le 5.5 \text{ V}, 2.7 \text{ V} \le \text{V}_{\text{b}} \le 4.0 \text{ V},$

 $2.7~V \leq V_{\text{DD}} < 4.0~V,\, 2.3~V \leq V_{\text{b}} \leq 2.7~V,$

 $1.8 \text{ V} \le V_{\text{DD}} < 3.3 \text{ V}, \ 1.6 \text{ V} \le V_{b} \le 2.0 \text{ V}^{\text{Note 2}},$

 $C_b = 30 \text{ pF}, R_b = 5.5 \text{ k}\Omega$

 $C_b = 30 \text{ pF}, R_b = 1.4 \text{ } \text{k}\Omega$

 $C_b = 30 \text{ pF}, R_b = 2.7 \text{ k}\Omega$

 $C_{\text{b}}=30 \text{ pF}, \text{ } \text{R}_{\text{b}}=5.5 \text{ } \text{k}\Omega$

(8) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock

output) (3/3) (T_1 = 40 to 180 (180 (180 (180 (180))

- **Notes 1.** When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0. **2.** Use it with $V_{DD} \ge V_b$.
- Cautions 1. Select the TTL input buffer for the SIp pin and the N-ch open drain output (V_{DD} tolerance) mode for the SOp pin and SCKp pin by using port input mode register 1 (PIM1) and port output mode register 1 (POM1). For V_{IH} and V_{IL}, see the DC characteristics with TTL input buffer selected.
 - 2. CSI01 and CSI11 cannot communicate at different potential.
- **Remarks 1.** R_b [Ω]: Communication line (SCKp, SOp) pull-up resistance, C_b [F]: Communication line (SCKp, SOp) load capacitance, V_b [V]: Communication line voltage
 - **2.** p: CSI number (p = 00, 20), m: Unit number (m = 0, 1), n: Channel number (n = 0)

CSI mode connection diagram (during communication at different potential)





CSI mode connection diagram (during communication at different potential)



Remarks 1. R_b [Ω]: Communication line (SOp) pull-up resistance, C_b [F]: Communication line (SOp) load capacitance, V_b [V]: Communication line voltage

2. p: CSI number (
$$p = 00, 20$$
), m: Unit number ($m = 0, 1$), n: Channel number ($n = 0$)

 fMCK: Serial array unit operation clock frequency (Operation clock to be set by the serial clock select register m (SPSm) and the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00, 10))

CSI mode serial transfer timing (slave mode) (during communication at different potential) (When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.)





Simplified I²C mode connection diagram (during communication at different potential)



Simplified I²C mode serial transfer timing (during communication at different potential)



- **Remarks 1.** R_b [Ω]: Communication line (SDAr, SCLr) pull-up resistance, C_b [F]: Communication line (SDAr, SCLr) load capacitance, V_b [V]: Communication line voltage
 - **2.** r: IIC Number (r = 00, 20)
 - fMCK: Serial array unit operation clock frequency (Operation clock to be set by the serial clock select register m (SPSm) and the CKSmn bit of serial mode register mn (SMRmn).
 m: Unit number (m = 0,1), n: Channel number (n = 0))
 - 4. Simplified l^2 C mode is supported only by the R5F102 products.



2.5.2 Serial interface IICA

Parameter	Symbol	Conditions	HS	HS (high-speed main) mode			Unit	
			LS	LS (low-speed Standard Mode		ed main) mode		
			Standa			Fast Mode		
			MIN.	MAX.	MIN.	MAX.		
SCLA0 clock frequency	fsc∟	Fast mode: fclk≥ 3.5 MHz			0	400	kHz	
		Normal mode: fcLK≥ 1 MHz	0	100			kHz	
Setup time of restart condition	tsu:sta		4.7		0.6		μS	
Hold time ^{Note 1}	thd:sta		4.0		0.6		μS	
Hold time when SCLA0 = "L"	tLOW		4.7		1.3		μs	
Hold time when SCLA0 = "H"	tніgн		4.0		0.6		μs	
Data setup time (reception)	tsu:dat		250		100		ns	
Data hold time (transmission) ^{Note 2}	thd:dat		0	3.45	0	0.9	μs	
Setup time of stop condition	tsu:sto		4.0		0.6		μs	
Bus-free time	t BUF		4.7		1.3		μs	

$(T_A = -40 \text{ to } +85^{\circ}\text{C}, 1.8 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}, \text{ V}_{SS} = 0 \text{ V})$

<R>

The first clock pulse is generated after this period when the start/restart condition is detected. Notes 1.

2. The maximum value (MAX.) of thD:DAT is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

- Caution Only in the 30-pin products, the values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (IOH1, IOL1, VOH1, VOL1) must satisfy the values in the redirect destination.
- Remark The maximum value of Cb (communication line capacitance) and the value of Rb (communication line pull-up resistor) at that time in each mode are as follows.

Normal mode:	$C_b = 400 \text{ pF}, \text{ Rb} = 2.7 \text{ k}\Omega$
Fast mode:	C_b = 320 pF, Rb = 1.1 k Ω

IICA serial transfer timing





(4) When reference voltage (+) = Internal reference voltage (ADREFP1 = 1, ADREFP0 = 0), reference voltage (-) = AV_{REFM} (ADREFM = 1), target pin: ANI0, ANI2, ANI3, and ANI16 to ANI22

(TA = -40 to +85°C, 2.4 V \leq V_{DD} \leq 5.5 V, V_{SS} = 0 V, Reference voltage (+) = V_{BGR}^{Note 3}, Reference voltage (-) = AV_{REFM} Note ⁴ = 0 V, HS (high-speed main) mode)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Resolution	Res			8		bit
Conversion time	t CONV	8-bit resolution	17		39	μs
Zero-scale error ^{Notes 1, 2}	EZS	8-bit resolution			±0.60	%FSR
Integral linearity error ^{Note 1}	ILE	8-bit resolution			±2.0	LSB
Differential linearity error Note 1	DLE	8-bit resolution			±1.0	LSB
Analog input voltage	VAIN		0		$V_{\text{BGR}}{}^{\text{Note 3}}$	V

Notes 1. Excludes quantization error ($\pm 1/2$ LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. Refer to 28.6.2 Temperature sensor/internal reference voltage characteristics.

4. When reference voltage (-) = Vss, the MAX. values are as follows.

Zero-scale error: Add $\pm 0.35\%$ FSR to the MAX. value when reference voltage (–) = AV_{REFM}. Integral linearity error: Add ± 0.5 LSB to the MAX. value when reference voltage (–) = AV_{REFM}. Differential linearity error: Add ± 0.2 LSB to the MAX. value when reference voltage (–) = AV_{REFM}.



2.6.2 Temperature sensor/internal reference voltage characteristics

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Temperature sensor output voltage	VTMPS25	Setting ADS register = 80H, TA = +25°C		1.05		V
Internal reference voltage	VBGR	Setting ADS register = 81H	1.38	1.45	1.50	V
Temperature coefficient	Fvtmps	Temperature sensor output voltage that depends on the temperature		-3.6		mV/°C
Operation stabilization wait time	tamp		5			μs

(T_A = -40 to +85°C, 2.4 V \leq V_{DD} \leq 5.5 V, V_{SS} = 0 V, HS (high-speed main) mode

2.6.3 POR circuit characteristics

$(T_A = -40 \text{ to } +85^{\circ}\text{C}, \text{ V}_{\text{SS}} = 0 \text{ V})$

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Detection voltage	VPOR	Power supply rise time	1.47	1.51	1.55	V
	VPDR	Power supply fall time	1.46	1.50	1.54	V
Minimum pulse width Note	TPW		300			μS

Note Minimum time required for a POR reset when V_{DD} exceeds below V_{PDR}. This is also the minimum time required for a POR reset from when V_{DD} exceeds below 0.7 V to when V_{DD} exceeds V_{POR} while STOP mode is entered or the main system clock is stopped through setting bit 0 (HIOSTOP) and bit 7 (MSTOP) in the clock operation status control register (CSC).





LVD detection voltage of interrupt & reset mode
$(T_A = -40 \text{ to } +85^{\circ}\text{C} \text{ V}_{PDR} < \text{V}_{DD} < 5.5 \text{ V} \text{ V}_{SS} = 0.\text{ V})$

Parameter	Symbol		Con	MIN.	TYP.	MAX.	Unit	
Interrupt and reset	VLVDB0	VPOC2,	VPOC1, VPOC0 = 0, 0, 1, fa	ling reset voltage	1.80	1.84	1.87	V
mode	VLVDB1		LVIS1, LVIS0 = 1, 0	Rising reset release voltage	1.94	1.98	2.02	V
				Falling interrupt voltage	1.90	1.94	1.98	V
	VLVDB2		LVIS1, LVIS0 = 0, 1	Rising reset release voltage	2.05	2.09	2.13	V
				Falling interrupt voltage	2.00	2.04	2.08	V
	V LVDB3		LVIS1, LVIS0 = 0, 0	Rising reset release voltage	3.07	3.13	3.19	V
VLVDC0 VLVDC1 VLVDC2				Falling interrupt voltage	3.00	3.06	3.12	V
	VLVDC0	VPOC2,	VPOC1, VPOC0 = 0, 1, 0, fa	2.40	2.45	2.50	V	
	VLVDC1		LVIS1, LVIS0 = 1, 0	Rising reset release voltage	2.56	2.61	2.66	V
				Falling interrupt voltage	2.50	2.55	2.60	V
		LVIS1, LVIS0 = 0, 1	Rising reset release voltage	2.66	2.71	2.76	V	
				Falling interrupt voltage	2.60	2.65	2.70	V
	VLVDC3		LVIS1, LVIS0 = 0, 0	Rising reset release voltage	3.68	3.75	3.82	V
				Falling interrupt voltage	3.60	3.67	3.74	V
	VLVDD0	VPOC2,	VPOC1, VPOC1 = 0, 1, 1, fa	ling reset voltage	2.70	2.75	2.81	V
	VLVDD1		LVIS1, LVIS0 = 1, 0	Rising reset release voltage	2.86	2.92	2.97	V
				Falling interrupt voltage	2.80	2.86	2.91	V
`	VLVDD2		LVIS1, LVIS0 = 0, 1	Rising reset release voltage	2.96	3.02	3.08	V
				Falling interrupt voltage	2.90	2.96	3.02	V
	V LVDD3		LVIS1, LVIS0 = 0, 0	Rising reset release voltage	3.98	4.06	4.14	V
				Falling interrupt voltage	3.90	3.98	4.06	V

2.6.5 Power supply voltage rising slope characteristics

$(T_A = -40 \text{ to } +85^{\circ}C, \text{ Vss} = 0 \text{ V})$

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Power supply voltage rising slope	SVDD				54	V/ms

Caution Make sure to keep the internal reset state by the LVD circuit or an external reset until V_{DD} reaches the operating voltage range shown in 28.4 AC Characteristics.



3.2 Oscillator Characteristics

3.2.1 X1 oscillator characteristics

$(T_A = -40 \text{ to } +105^{\circ}\text{C}, 2.4 \text{ V} \le \text{V}_{DD} \le \text{V}_{DD} \le 5.5 \text{ V}, \text{V}_{SS} = 0 \text{ V})$

Parameter	Resonator	Conditions	MIN.	TYP.	MAX.	Unit
X1 clock oscillation	Ceramic resonator /	$2.7~V \leq V_{\text{DD}} \leq 5.5~V$	1.0		20.0	MHz
frequency (fx) ^{Note}	crystal oscillator	$2.4~V \leq V_{\text{DD}} < 2.7~V$	1.0		8.0	

Note Indicates only permissible oscillator frequency ranges. Refer to AC Characteristics for instruction execution time. Request evaluation by the manufacturer of the oscillator circuit mounted on a board to check the oscillator characteristics.

- **Caution** Since the CPU is started by the high-speed on-chip oscillator clock after a reset release, check the X1 clock oscillation stabilization time using the oscillation stabilization time counter status register (OSTC) by the user. Determine the oscillation stabilization time of the OSTC register and the oscillation stabilization time select register (OSTS) after sufficiently evaluating the oscillation stabilization time with the resonator to be used.
- Remark When using the X1 oscillator, refer to 5.4 System Clock Oscillator.

3.2.2 On-chip oscillator characteristics

$(T_A = -40 \text{ to } +105^{\circ}\text{C}, 2.4 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}, \text{ V}_{SS} = 0 \text{ V})$

Oscillators	Parameters	Сог	nditions	MIN.	TYP.	MAX.	Unit
High-speed on-chip oscillator clock frequency Notes 1, 2	fін			1		24	MHz
High-speed on-chip oscillator		R5F102 products	T _A = -20 to +85°C	-1.0		+1.0	%
clock frequency accuracy			$T_A = -40$ to $-20^{\circ}C$	-1.5		+1.5	%
			T _A = +85 to +105°C	-2.0		+2.0	%
Low-speed on-chip oscillator clock frequency	fı∟				15		kHz
Low-speed on-chip oscillator clock frequency accuracy				-15		+15	%

Notes 1. High-speed on-chip oscillator frequency is selected by bits 0 to 3 of option byte (000C2H) and bits 0 to 2 of HOCODIV register.

2. This only indicates the oscillator characteristics. Refer to AC Characteristics for instruction execution time.



(3) Peripheral functions (Common to all products)

$(T_A = -40 \text{ to } +105^{\circ}\text{C}, 2.4 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}, \text{V}_{SS} = 0 \text{ V})$

Parameter	Symbol		Conditions	MIN.	TYP.	MAX.	Unit
Low-speed onchip oscillator operating current	FIL Note 1				0.20		μA
12-bit interval timer operating current	ITMKA Notes 1, 2, 3				0.02		μA
Watchdog timer operating current	WDT Notes 1, 2, 4	fı∟ = 15 kHz	. = 15 kHz		0.22		μA
A/D converter	IADC	When conversion	Normal mode, AV _{REFP} = V _{DD} = 5.0 V		1.30	1.70	mA
operating current	Notes 1, 5	at maximum speed	at maximum speed Low voltage mode, AVREFP = VDD = 3.0 V		0.50	0.70	mA
A/D converter reference voltage operating current	IADREF Note 1				75.0		μA
Temperature sensor operating current	ITMPS Note 1				75.0		μA
LVD operating current	ILVD Notes 1, 6				0.08		μA
Self-programming operating current	IFSP Notes 1, 8				2.00	12.20	mA
BGO operating current	BGO Notes 1, 7				2.00	12.20	mA
SNOOZE operating	Isnoz	ADC operation	The mode is performed Note 9		0.50	1.10	mA
current Note 1			The A/D conversion operations are performed, Low voltage mode, $AV_{REFP} = V_{DD} = 3.0 \text{ V}$		1.20	2.04	mA
		CSI/UART operation	<u>ו</u>		0.70	1.54	mA

Notes 1. Current flowing to the VDD.

- 2. When high speed on-chip oscillator and high-speed system clock are stopped.
- 3. Current flowing only to the 12-bit interval timer (excluding the operating current of the low-speed on-chip oscillator). The current value of the RL78 microcontrollers is the sum of IDD1, IDD2 or IDD3, and IFIL and ITMKA when the 12-bit interval timer operates.
- 4. Current flowing only to the watchdog timer (including the operating current of the low-speed on-chip oscillator). The current value of the RL78 microcontrollers is the sum of IDD1, IDD2 or IDD3 and IWDT when the watchdog timer operates.
- 5. Current flowing only to the A/D converter. The current value of the RL78 microcontrollers is the sum of IDD1 or IDD2 and IADC when the A/D converter operates in an operation mode or the HALT mode.
- 6. Current flowing only to the LVD circuit. The current value of the RL78 microcontrollers is the sum of IDD1, IDD2 or IDD3 and ILVD when the LVD circuit operates.
- 7. Current flowing only during data flash rewrite.
- **8.** Current flowing only during self programming.
- 9. For shift time to the SNOOZE mode, see 17.3.3 SNOOZE mode.

Remarks 1. fill: Low-speed on-chip oscillator clock frequency

2. Temperature condition of the TYP. value is $T_A = 25^{\circ}C$



Baud rate error (theoretical value) =

$$) = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln (1 - \frac{2.2}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \,[\%]$$

* This value is the theoretical value of the relative difference between the transmission and reception sides.

- 4. This value as an example is calculated when the conditions described in the "Conditions" column are met. Refer to Note 3 above to calculate the maximum transfer rate under conditions of the customer.
- 5. The smaller maximum transfer rate derived by using fMCK/12 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 2.7 V \leq VDD < 4.0 V and 2.3 V \leq Vb \leq 2.7 V

Maximum transfer rate =
$$\frac{1}{\{-C_b \times R_b \times \ln (1 - \frac{2.0}{V_b})\} \times 3}$$
 [bps]

Baud rate error (theoretical value) =

 $\begin{array}{c} \displaystyle \frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln (1 - \frac{2.0}{V_b})\} \\ \hline \\ \displaystyle (\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits} \end{array} \times 100 \ [\%]$

- * This value is the theoretical value of the relative difference between the transmission and reception sides.
- 6. This value as an example is calculated when the conditions described in the "Conditions" column are met. Refer to **Note 5** above to calculate the maximum transfer rate under conditions of the customer.
- 7. The smaller maximum transfer rate derived by using fMCK/12 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 2.4 V \leq V_DD < 3.3 V, 1.6 V \leq V_b \leq 2.0 V

Maximum transfer rate =

$$\frac{1}{\{-C_b \times R_b \times \ln (1 - \frac{1.5}{V_b})\} \times 3}$$
 [bps]

Baud rate error (theoretical value) = $\frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \,[\%]$

- * This value is the theoretical value of the relative difference between the transmission and reception sides.
- This value as an example is calculated when the conditions described in the "Conditions" column are met. Refer to Note 7 above to calculate the maximum transfer rate under conditions of the customer.
- Caution Select the TTL input buffer for the RxDq pin and the N-ch open drain output (VDD tolerance) mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg). For VIH and VIL, see the DC characteristics with TTL input buffer selected.



3.6.4 LVD circuit characteristics

LVD Detection Voltage of Reset Mode and Interrupt Mode (T_A = -40 to +105°C, V_{PDR} \leq V_{DD} \leq 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Detection supply voltage	VLVDO	Power supply rise time	3.90	4.06	4.22	V
		Power supply fall time	3.83	3.98	4.13	V
	VLVD1	Power supply rise time	3.60	3.75	3.90	V
		Power supply fall time	3.53	3.67	3.81	V
	VLVD2	Power supply rise time	3.01	3.13	3.25	V
		Power supply fall time	2.94	3.06	3.18	V
	V _{LVD3}	Power supply rise time	2.90	3.02	3.14	V
		Power supply fall time	2.85	2.96	3.07	V
	VLVD4	Power supply rise time	2.81	2.92	3.03	V
		Power supply fall time	2.75	2.86	2.97	V
	VLVD5	Power supply rise time	2.70	2.81	2.92	V
		Power supply fall time	2.64	2.75	2.86	V
	VLVD6	Power supply rise time	2.61	2.71	2.81	V
		Power supply fall time	2.55	2.65	2.75	V
	VLVD7	Power supply rise time	2.51	2.61	2.71	V
		Power supply fall time	2.45	2.55	2.65	V
Minimum pulse width	tıw		300			μs
Detection delay time					300	μs



4. PACKAGE DRAWINGS

4.1 20-pin products

R5F1026AASP, R5F10269ASP, R5F10268ASP, R5F10267ASP, R5F10266ASP R5F1036AASP, R5F10369ASP, R5F10368ASP, R5F10367ASP, R5F10366ASP R5F1026ADSP, R5F10269DSP, R5F10268DSP, R5F10267DSP, R5F10266DSP R5F1036ADSP, R5F10369DSP, R5F10368DSP, R5F10367DSP, R5F10366DSP R5F1026AGSP, R5F10269GSP, R5F10268GSP, R5F10267GSP, R5F10266GSP

<R>

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LSSOP20-4.4x6.5-0.65	PLSP0020JB-A	P20MA-65-NAA-1	0.1



 detail of lead end





	(UNIT:mm)
ITEM	DIMENSIONS
D	6.50±0.10
E	4.40±0.10
HE	6.40±0.20
А	1.45 MAX.
A1	0.10±0.10
A2	1.15
е	0.65±0.12
bp	0.22 + 0.10 - 0.05
С	0.15 + 0.05 - 0.02
L	0.50±0.20
У	0.10
θ	0° to 10°

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1.Dimensions "%1" and "%2" do not include mold flash.

2.Dimension "X3" does not include trim offset.



4.2 24-pin products

R5F1027AANA, R5F10279ANA, R5F10278ANA, R5F10277ANA R5F1037AANA, R5F10379ANA, R5F10378ANA, R5F10377ANA R5F1027ADNA, R5F10279DNA, R5F10278DNA, R5F10277DNA R5F1037ADNA, R5F10379DNA, R5F10378DNA, R5F10377DNA R5F1027AGNA, R5F10279GNA, R5F10278GNA, R5F10277GNA

<R>

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-HWQFN24-4x4-0.50	PWQN0024KE-A	P24K8-50-CAB-1	0.04

S



(UNIT:mm) DIMENSIONS ITEM D $4.00\pm\!0.05$ Е 4.00 ± 0.05 А 0.75±0.05 0.25 + 0.05 - 0.07b 0.50 е Lp $0.40\pm\!0.10$ х 0.05 у 0.05

l r	ITEM			D2			E2	
			MIN	NOM	MAX	MIN	NOM	MAX
EXPO DIE PA VARIA		А	2.45	2.50	2.55	2.45	2.50	2.55

DETAIL OF (A) PART

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Revision History

RL78/G12 Data Sheet

			Description				
Rev.	Date	Page	Summary				
1.00	Dec 10, 2012	-	First Edition issued				
2.00	Sep 06, 2013	1	Modification of 1.1 Features				
		3	Modification of 1.2 List of Part Numbers				
		4	Modification of Table 1-1. List of Ordering Part Numbers, Note, and Caution				
		7 to 9	Modification of package name in 1.4.1 to 1.4.3				
		14	Modification of tables in 1.7 Outline of Functions				
		17	Modification of description of table in 2.1 Absolute Maximum Ratings (TA = 25°C)				
		18	Modification of table, Note, and Caution in 2.2.1 X1 oscillator characteristics				
		18 19	Modification of table in 2.2.2 On-chip oscillator characteristics				
		20	Modification of Note 3 in 2.3.1 Pin characteristics (1/4)				
			Modification of Note 3 in 2.3.1 Pin characteristics (2/4)				
		23	Modification of Notes 1 and 2 in (1) 20-, 24-pin products (1/2)				
		24	Modification of Notes 1 and 3 in (1) 20-, 24-pin products (2/2)				
		25	Modification of Notes 1 and 2 in (2) 30-pin products (1/2)				
		26	Modification of Notes 1 and 3 in (2) 30-pin products (2/2)				
		27	Modification of (3) Peripheral functions (Common to all products)				
		28	Modification of table in 2.4 AC Characteristics				
		29	Addition of Minimum Instruction Execution Time during Main System Clock Operation				
		30	Modification of figures of AC Timing Test Point and External Main System Clock Timing				
		31	Modification of figure of AC Timing Test Point				
		31	Modification of description and Note 2 in (1) During communication at same potential (UART mode)				
		32	Modification of description in (2) During communication at same potential (CSI mode)				
		33	Modification of description in (3) During communication at same potential (CSI mode)				
		34	Modification of description in (4) During communication at same potential (CSI mode)				
		36	Modification of table and Note 2 in (5) During communication at same potential				
			(simplified l ² C mode)				
		38, 39	Modification of table and Notes 1 to 9 in (6) Communication at different potential				
		00,00	(1.8 V, 2.5 V, 3 V) (UART mode)				
		40	Modification of Remarks 1 to 3 in (6) Communication at different potential (1.8 V,				
		10	2.5 V, 3 V) (UART mode)				
		41	Modification of table in (7) Communication at different potential (2.5 V, 3 V) (CSI mode)				
		42	Modification of Caution in (7) Communication at different potential (2.5 V, 3 V) (CSI mode)				
		43	Modification of table in (8) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI				
		40	mode) (1/3)				
		44	Modification of table and Notes 1 and 2 in (8) Communication at different potential (1.8				
		44	V, 2.5 V, 3 V) (CSI mode) (2/3)				
		45	Modification of table, Note 1, and Caution 1 in (8) Communication at different potential				
		45	(1.8 V, 2.5 V, 3 V) (CSI mode) (3/3)				
		47	Modification of table in (9) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI				
		47	mode)				
		50	Modification of table, Note 1, and Caution 1 in (10) Communication at different potential				
		50	(1.8 V, 2.5 V, 3 V) (simplified I ² C mode)				
		50	Modification of Remark in 2.5.2 Serial interface IICA				
		52	Addition of table to 2.6.1 A/D converter characteristics				
		53					
		53	Modification of description in 2.6.1 (1)				
		54	Modification of Notes 3 to 5 in 2.6.1 (1)				
		54	Modification of description and Notes 2 to 4 in 2.6.1 (2)				

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