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Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	24
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	A/D 5x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16f913-i-so">https://www.e-xfl.com/product-detail/microchip-technology/pic16f913-i-so</a>

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# PIC16F913/914/916/917/946

**TABLE 2-2: PIC16F91X/946 SPECIAL FUNCTION REGISTERS SUMMARY BANK 1**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Page
<b>Bank 1</b>											
80h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	41,226
81h	OPTION_REG	RBP $\overline{U}$	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	33,227
82h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	40,226
83h	STATUS	IRP	RP1	RP0	T0	P $\overline{D}$	Z	DC	C	0001 1xxx	32,226
84h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	41,226
85h	TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	44,227
86h	TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	54,227
87h	TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	62,227
88h	TRISD <sup>(3)</sup>	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	1111 1111	71,227
89h	TRISE	TRISE7 <sup>(2)</sup>	TRISE6 <sup>(2)</sup>	TRISE5 <sup>(2)</sup>	TRISE4 <sup>(2)</sup>	TRISE3 <sup>(5)</sup>	TRISE2 <sup>(3)</sup>	TRISE1 <sup>(3)</sup>	TRISE0 <sup>(3)</sup>	1111 1111	76,227
8Ah	PCLATH	—	—	—	Write Buffer for the upper 5 bits of the Program Counter					---0 0000	40,226
8Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	34,226
8Ch	PIE1	EEIE	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	0000 0000	35,227
8Dh	PIE2	OSFIE	C2IE	C1IE	LCDIE	—	LVDIE	—	CCP2IE <sup>(3)</sup>	0000 -0-0	36,227
8Eh	PCON	—	—	—	SBOREN	—	—	POR	BOR	---1 --qg	39,227
8Fh	OSCCON	—	IRCF2	IRCF1	IRCF0	OSTS <sup>(4)</sup>	HTS	LTS	SCS	-110 q000	88,227
90h	OSCTUNE	—	—	—	TUN4	TUN3	TUN2	TUN1	TUN0	---0 0000	92,227
91h	ANSEL	ANS7 <sup>(3)</sup>	ANS6 <sup>(3)</sup>	ANS5 <sup>(3)</sup>	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	43,227
92h	PR2	Timer2 Period Register								1111 1111	107,227
93h	SSPAD	Synchronous Serial Port (I <sup>2</sup> C mode) Address Register								0000 0000	202,227
94h	SSPSTAT	SMP	CKE	D/A	P	S	R/W	UA	BF	0000 0000	194,227
95h	WPUB	WPUB7	WPUB6	WPUB5	WPUB4	WPUB3	WPUB2	WPUB1	WPUB0	1111 1111	55,227
96h	IOCB	IOCB7	IOCB6	IOCB5	IOCB4	—	—	—	—	0000 ----	54,227
97h	CMCON1	—	—	—	—	—	—	T1GSS	C2SYNC	---- --10	117,227
98h	TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	130,227
99h	SPBRG	SPBRG7	SPBRG6	SPBRG5	SPBRG4	SPBRG3	SPBRG2	SPBRG1	SPBRG0	0000 0000	132,227
9Ah	—	Unimplemented								—	—
9Bh	—	Unimplemented								—	—
9Ch	CMCON0	C2OUT	C1OUT	C2INV	C1INV	CIS	CM2	CM1	CM0	0000 0000	116,227
9Dh	VRCON	VREN	—	VRR	—	VR3	VR2	VR1	VR0	0-0- 0000	118,227
9Eh	ADRESL	A/D Result Register Low Byte								xxxx xxxx	182,227
9Fh	ADCON1	—	ADCS2	ADCS1	ADCS0	—	—	—	—	-000 ----	181,227

**Legend:** — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

- Note**
- 1: Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.
  - 2: PIC16F946 only, forced '0' on PIC16F91X.
  - 3: PIC16F914/917 and PIC16F946 only, forced '0' on PIC16F913/916.
  - 4: The value of the OSTS bit is dependent on the value of the Configuration Word (CONFIG) of the device. See **Section 4.2 "Oscillator Control"**.
  - 5: Bit is read-only; TRISE3 = 1 always.

# PIC16F913/914/916/917/946

**TABLE 2-4: PIC16F91X/946 SPECIAL FUNCTION REGISTERS SUMMARY BANK 3**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Page
<b>Bank 3</b>											
180h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	41,226
181h	OPTION_REG	RBPÜ	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	33,227
182h	PCL	Program Counter (PC) Least Significant Byte								0000 0000	40,226
183h	STATUS	IRP	RP1	RP0	T0	PD	Z	DC	C	0001 1xxx	32,226
184h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	41,226
185h	TRISF <sup>(3)</sup>	TRISF7	TRISF6	TRISF5	TRISF4	TRISF3	TRISF2	TRISF1	TRISF0	1111 1111	81,228
186h	TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	54,227
187h	TRISG <sup>(3)</sup>	—	—	TRISG5	TRISG4	TRISG3	TRISG2	TRISG1	TRISG0	--11 1111	84,228
188h	PORTF <sup>(3)</sup>	RF7	RF6	RF5	RF4	RF3	RF2	RF1	RF0	xxxx xxxx	81,228
189h	PORTG <sup>(3)</sup>	—	—	RG5	RG4	RG3	RG2	RG1	RG0	--xx xxxx	84,228
18Ah	PCLATH	—	—	—	Write Buffer for the upper 5 bits of the Program Counter				---	0 0000	40,226
18Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	34,226
18Ch	EECON1	EEPGD	—	—	—	WRERR	WREN	WR	RD	0--- x000	189,229
18Dh	EECON2	EEPROM Control Register 2 (not a physical register)								---- ----	187
18Eh	—	Reserved								—	—
18Fh	—	Reserved								—	—
190h	LCDDATA12 <sup>(3)</sup>	SEG31 COM0	SEG30 COM0	SEG29 COM0	SEG28 COM0	SEG27 COM0	SEG26 COM0	SEG25 COM0	SEG24 COM0	xxxx xxxx	147,228
191h	LCDDATA13 <sup>(3)</sup>	SEG39 COM0	SEG38 COM0	SEG37 COM0	SEG36 COM0	SEG35 COM0	SEG34 COM0	SEG33 COM0	SEG32 COM0	xxxx xxxx	147,228
192h	LCDDATA14 <sup>(3)</sup>	—	—	—	—	—	—	SEG41 COM0	SEG40 COM0	---- --xx	147,228
193h	LCDDATA15 <sup>(3)</sup>	SEG31 COM1	SEG30 COM1	SEG29 COM1	SEG28 COM1	SEG27 COM1	SEG26 COM1	SEG25 COM1	SEG24 COM1	xxxx xxxx	147,228
194h	LCDDATA16 <sup>(3)</sup>	SEG39 COM1	SEG38 COM1	SEG37 COM1	SEG36 COM1	SEG35 COM1	SEG34 COM1	SEG33 COM1	SEG32 COM1	xxxx xxxx	147,228
195h	LCDDATA17 <sup>(3)</sup>	—	—	—	—	—	—	SEG41 COM1	SEG40 COM1	---- --xx	147,228
196h	LCDDATA18 <sup>(3)</sup>	SEG31 COM2	SEG30 COM2	SEG29 COM2	SEG28 COM2	SEG27 COM2	SEG26 COM2	SEG25 COM2	SEG24 COM2	xxxx xxxx	147,228
197h	LCDDATA19 <sup>(3)</sup>	SEG39 COM2	SEG38 COM2	SEG37 COM2	SEG36 COM2	SEG35 COM2	SEG34 COM2	SEG33 COM2	SEG32 COM2	xxxx xxxx	147,228
198h	LCDDATA20 <sup>(3)</sup>	—	—	—	—	—	—	SEG41 COM2	SEG40 COM2	---- --xx	147,228
199h	LCDDATA21 <sup>(3)</sup>	SEG31 COM3	SEG30 COM3	SEG29 COM3	SEG28 COM3	SEG27 COM3	SEG26 COM3	SEG25 COM3	SEG24 COM3	xxxx xxxx	147,228
19Ah	LCDDATA22 <sup>(3)</sup>	SEG39 COM3	SEG38 COM3	SEG37 COM3	SEG36 COM3	SEG35 COM3	SEG34 COM3	SEG33 COM3	SEG32 COM3	xxxx xxxx	147,228
19Bh	LCDDATA23 <sup>(3)</sup>	—	—	—	—	—	—	SEG41 COM3	SEG40 COM3	---- --xx	147,228
19Ch	LCDSE3 <sup>(2, 3)</sup>	SE31	SE30	SE29	SE28	SE27	SE26	SE25	SE24	0000 0000	147,229
19Dh	LCDSE4 <sup>(2, 3)</sup>	SE39	SE38	SE37	SE36	SE35	SE34	SE33	SE32	0000 0000	147,229
19Eh	LCDSE5 <sup>(2, 3)</sup>	—	—	—	—	—	—	SE41	SE40	---- --00	147,229
19Fh	—	Unimplemented								—	—

**Legend:** — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

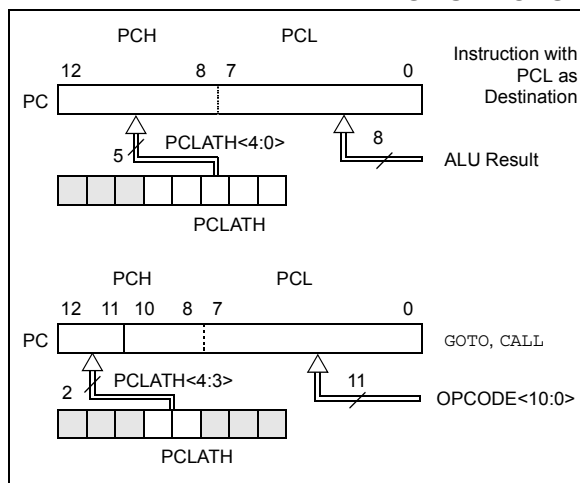
- Note**
- 1: Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.
  - 2: This register is only initialized by a POR or BOR reset and is unchanged by other Resets.
  - 3: PIC16F946 only.

# PIC16F913/914/916/917/946

## 2.3 PCL and PCLATH

The Program Counter (PC) is 13 bits wide. The low byte comes from the PCL register, which is a readable and writable register. The high byte (PC<12:8>) is not directly readable or writable and comes from PCLATH. On any Reset, the PC is cleared. Figure 2-6 shows the two situations for the loading of the PC. The upper example in Figure 2-6 shows how the PC is loaded on a write to PCL (PCLATH<4:0> → PCH). The lower example in Figure 2-6 shows how the PC is loaded during a CALL or GOTO instruction (PCLATH<4:3> → PCH).

**FIGURE 2-6: LOADING OF PC IN DIFFERENT SITUATIONS**



### 2.3.1 COMPUTED GOTO

A computed GOTO is accomplished by adding an offset to the program counter (ADDWF PCL). When performing a table read using a computed GOTO method, care should be exercised if the table location crosses a PCL memory boundary (each 256-byte block). Refer to the Application Note AN556, "Implementing a Table Read" (DS00556).

### 2.3.2 STACK

The PIC16F91X/946 family has an 8-level x 13-bit wide hardware stack (see Figures 2-1 and 2-2). The stack space is not part of either program or data space and the Stack Pointer is not readable or writable. The PC is PUSHed onto the stack when a CALL instruction is executed or an interrupt causes a branch. The stack is POPed in the event of a RETURN, RETLW or a RETFIE instruction execution. PCLATH is not affected by a PUSH or POP operation.

The stack operates as a circular buffer. This means that after the stack has been PUSHed eight times, the ninth PUSH overwrites the value that was stored from the first PUSH. The tenth PUSH overwrites the second PUSH (and so on).

**Note 1:** There are no Status bits to indicate stack overflow or stack underflow conditions.

**2:** There are no instructions/mnemonics called PUSH or POP. These are actions that occur from the execution of the CALL, RETURN, RETLW and RETFIE instructions or the vectoring to an interrupt address.

## 2.4 Program Memory Paging

All PIC16F91X/946 devices are capable of addressing a continuous 8K word block of program memory. The CALL and GOTO instructions provide only 11 bits of address to allow branching within any 2K program memory page. When doing a CALL or GOTO instruction, the upper 2 bits of the address are provided by PCLATH<4:3>. When doing a CALL or GOTO instruction, the user must ensure that the page select bits are programmed so that the desired program memory page is addressed. If a return from a CALL instruction (or interrupt) is executed, the entire 13-bit PC is POPed off the stack. Therefore, manipulation of the PCLATH<4:3> bits is not required for the RETURN instructions (which POPs the address from the stack).

**Note:** The contents of the PCLATH register are unchanged after a RETURN or RETFIE instruction is executed. The user must rewrite the contents of the PCLATH register for any subsequent subroutine calls or GOTO instructions.

Example 2-1 shows the calling of a subroutine in page 1 of the program memory. This example assumes that PCLATH is saved and restored by the Interrupt Service Routine (if interrupts are used).

### EXAMPLE 2-1: CALL OF A SUBROUTINE IN PAGE 1 FROM PAGE 0

```
ORG 500h
BCF PCLATH,4
BSF PCLATH,3 ;Select page 1
               ; (800h-FFFh)
CALL SUB1_P1 ;Call subroutine in
:           ;page 1 (800h-FFFh)
:
ORG 900h      ;page 1 (800h-FFFh)
SUB1_P1
:           ;called subroutine
               ;page 1 (800h-FFFh)
:
RETURN       ;return to
               ;Call subroutine
               ;in page 0
               ; (000h-7FFh)
```

# PIC16F913/914/916/917/946

## REGISTER 3-7: WPUB: WEAK PULL-UP REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
WPUB7	WPUB6	WPUB5	WPUB4	WPUB3	WPUB2	WPUB1	WPUB0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0

**WPUB<7:0>:** Weak Pull-up Register bits

1 = Pull-up enabled

0 = Pull-up disabled

**Note 1:** Global  $\overline{\text{RBPU}}$  must be enabled for individual pull-ups to be enabled.

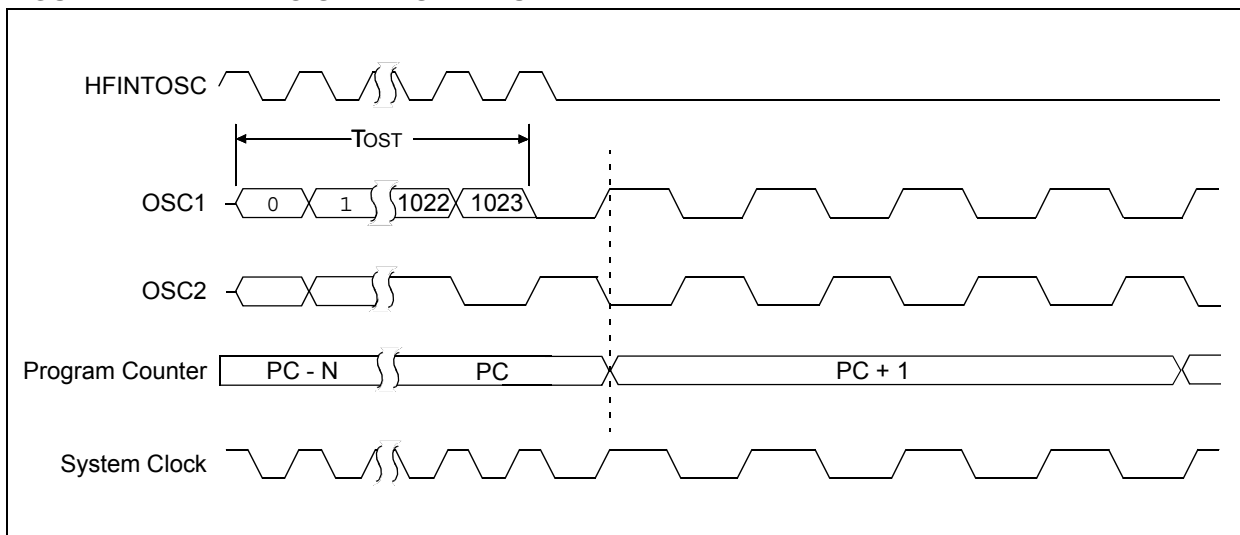
**2:** The weak pull-up device is automatically disabled if the pin is in Output mode ( $\text{TRISx}<7:0> = 0$ ).

# PIC16F913/914/916/917/946

## 4.7.3 CHECKING TWO-SPEED CLOCK STATUS

Checking the state of the OSTS bit of the OSCCON register will confirm if the microcontroller is running from the external clock source, as defined by the FOSC<2:0> bits in the Configuration Word register (CONFIG), or the internal oscillator.

**FIGURE 4-7: TWO-SPEED START-UP**



## 6.10 Timer1 Control Register

The Timer1 Control register (T1CON), shown in Register 6-1, is used to control Timer1 and select the various features of the Timer1 module.

**REGISTER 6-1: T1CON: TIMER 1 CONTROL REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
T1GINV <sup>(1)</sup>	TMR1GE <sup>(2)</sup>	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	TMR1CS	TMR1ON
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 7 **T1GINV:** Timer1 Gate Invert bit<sup>(1)</sup>  
 1 = Timer1 gate is active-high (Timer1 counts when gate is high)  
 0 = Timer1 gate is active-low (Timer1 counts when gate is low)
- bit 6 **TMR1GE:** Timer1 Gate Enable bit<sup>(2)</sup>  
If TMR1ON = 0:  
 This bit is ignored  
If TMR1ON = 1:  
 1 = Timer1 counting is controlled by the Timer1 Gate function  
 0 = Timer1 is always counting
- bit 5-4 **T1CKPS<1:0>:** Timer1 Input Clock Prescale Select bits  
 11 = 1:8 Prescale Value  
 10 = 1:4 Prescale Value  
 01 = 1:2 Prescale Value  
 00 = 1:1 Prescale Value
- bit 3 **T1OSCEN:** LP Oscillator Enable Control bit  
If INTOSC without CLKOUT oscillator is active:  
 1 = LP oscillator is enabled for Timer1 clock  
 0 = LP oscillator is off  
Else:  
 This bit is ignored. LP oscillator is disabled.
- bit 2 **T1SYNC:** Timer1 External Clock Input Synchronization Control bit  
TMR1CS = 1:  
 1 = Do not synchronize external clock input  
 0 = Synchronize external clock input  
TMR1CS = 0:  
 This bit is ignored. Timer1 uses the internal clock.
- bit 1 **TMR1CS:** Timer1 Clock Source Select bit  
 1 = External clock from T1CKI pin (on the rising edge)  
 0 = Internal clock (FOSC/4)
- bit 0 **TMR1ON:** Timer1 On bit  
 1 = Enables Timer1  
 0 = Stops Timer1

**Note 1:** T1GINV bit inverts the Timer1 gate logic, regardless of source.

**2:** TMR1GE bit must be set to use either T1G pin or C2OUT, as selected by the T1GSS bit of the CMCON1 register, as a Timer1 gate source.



## 8.1.1 ANALOG INPUT CONNECTION CONSIDERATIONS

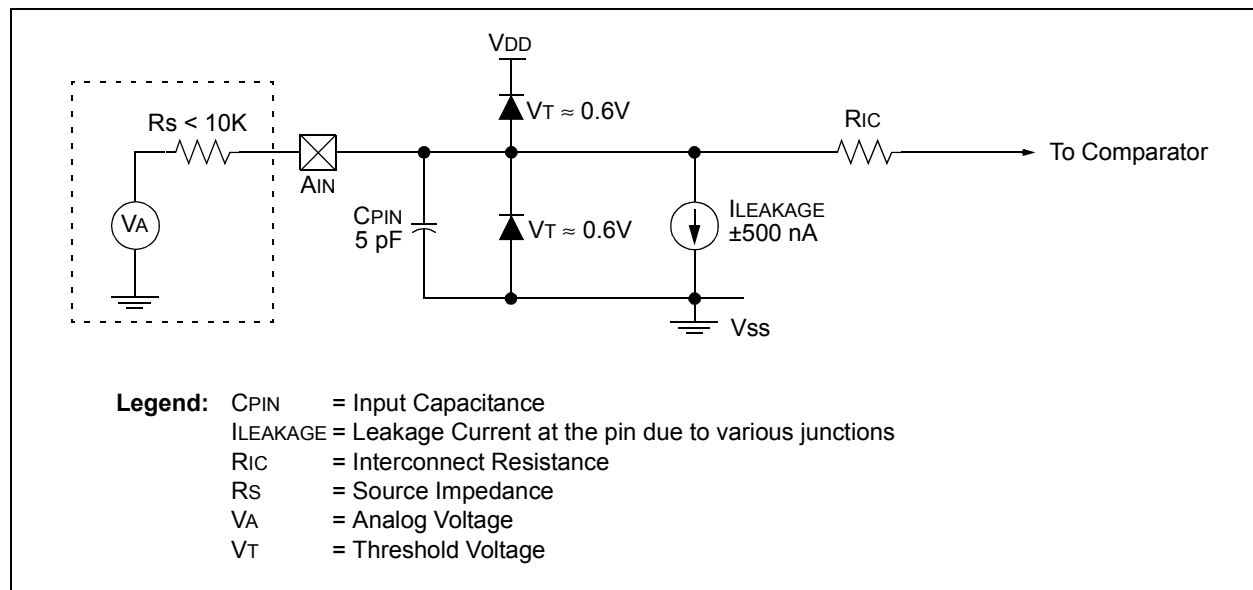
A simplified circuit for an analog input is shown in Figure 8-4. Since the analog input pins share their connection with a digital input, they have reverse biased ESD protection diodes to VDD and VSS. The analog input, therefore, must be between VSS and VDD. If the input voltage deviates from this range by more than 0.6V in either direction, one of the diodes is forward biased and a latch-up may occur.

A maximum source impedance of 10 kΩ is recommended for the analog sources. Also, any external component connected to an analog input pin, such as a capacitor or a Zener diode, should have very little leakage current to minimize inaccuracies introduced.

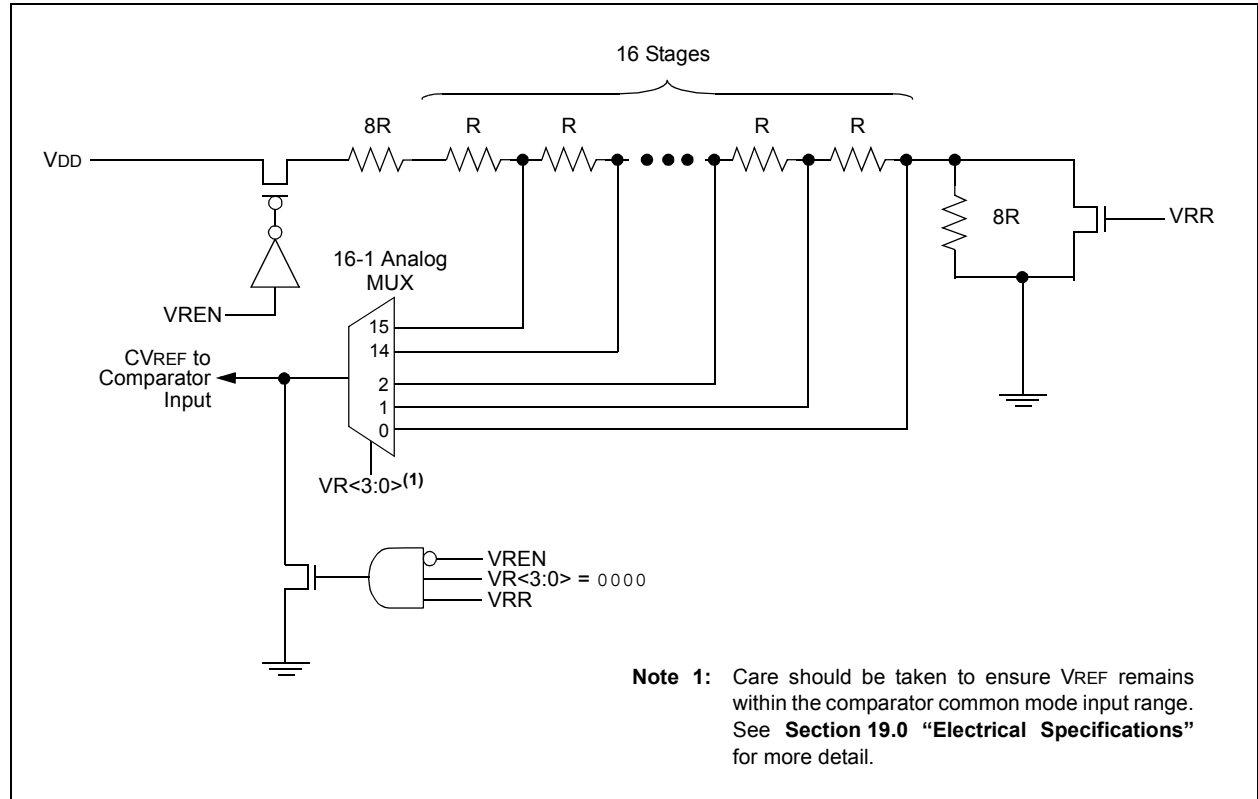
**Note 1:** When reading a PORT register, all pins configured as analog inputs will read as a '0'. Pins configured as digital inputs will convert as an analog input, according to the input specification.

**2:** Analog levels on any pin defined as a digital input, may cause the input buffer to consume more current than is specified.

**FIGURE 8-4: ANALOG INPUT MODEL**



**FIGURE 8-8: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM**



**TABLE 8-2: SUMMARY OF REGISTERS ASSOCIATED WITH THE COMPARATOR AND VOLTAGE REFERENCE MODULES**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSEL	ANS7	ANS6	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	1111 1111
CMCON0	C2OUT	C1OUT	C2INV	C1INV	CIS	CM2	CM1	CM0	0000 0000	0000 0000
CMCON1	—	—	—	—	—	—	T1GSS	C2SYNC	---- --10	---- --10
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE2	OSFIE	C2IE	C1IE	LCDIE	—	LVDIE	—	CCP2IE	0000 -0-0	0000 -0-0
PIR2	OSFIF	C2IF	C1IF	LCDIF	—	LVDIF	—	CCP2IF	0000 -0-0	0000 -0-0
PORTA	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	xxxx xxxx	uuuu uuuu
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	1111 1111
VRCON	VREN	—	VRR	—	VR3	VR2	VR1	VR0	0-0- 0000	0000 0000

**Legend:** x = unknown, u = unchanged, - = unimplemented, read as '0'. Shaded cells are not used for comparator.

# PIC16F913/914/916/917/946

**TABLE 9-1: REGISTERS ASSOCIATED WITH ASYNCHRONOUS TRANSMISSION**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
LCDCON	LCDEN	SLPEN	WERR	VLCDEN	CS1	CS0	LMUX1	LMUX0	0001 0011	0001 0011
LCDSE1	SE15	SE14	SE13	SE12	SE11	SE10	SE9	SE8	0000 0000	0000 0000
PIE1	EEIE	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	0000 0000	0000 0000
PIR1	EEIF	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	0000 0000	0000 0000
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SSPCON	WCOL	SSPOV	SSPEN	CKP	SSPM3	SSPM2	SSPM1	SSPM0	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TXREG	AUSART Transmit Data Register								0000 0000	0000 0000
TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	0000 -010

**Legend:** x = unknown, - = unimplemented read as '0'. Shaded cells are not used for Asynchronous Transmission.

# PIC16F913/914/916/917/946

## REGISTER 10-2: LCDPS: LCD PRESCALER SELECT REGISTER

R/W-0	R/W-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
WFT	BIASMD	LCDA	WA	LP3	LP2	LP1	LP0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

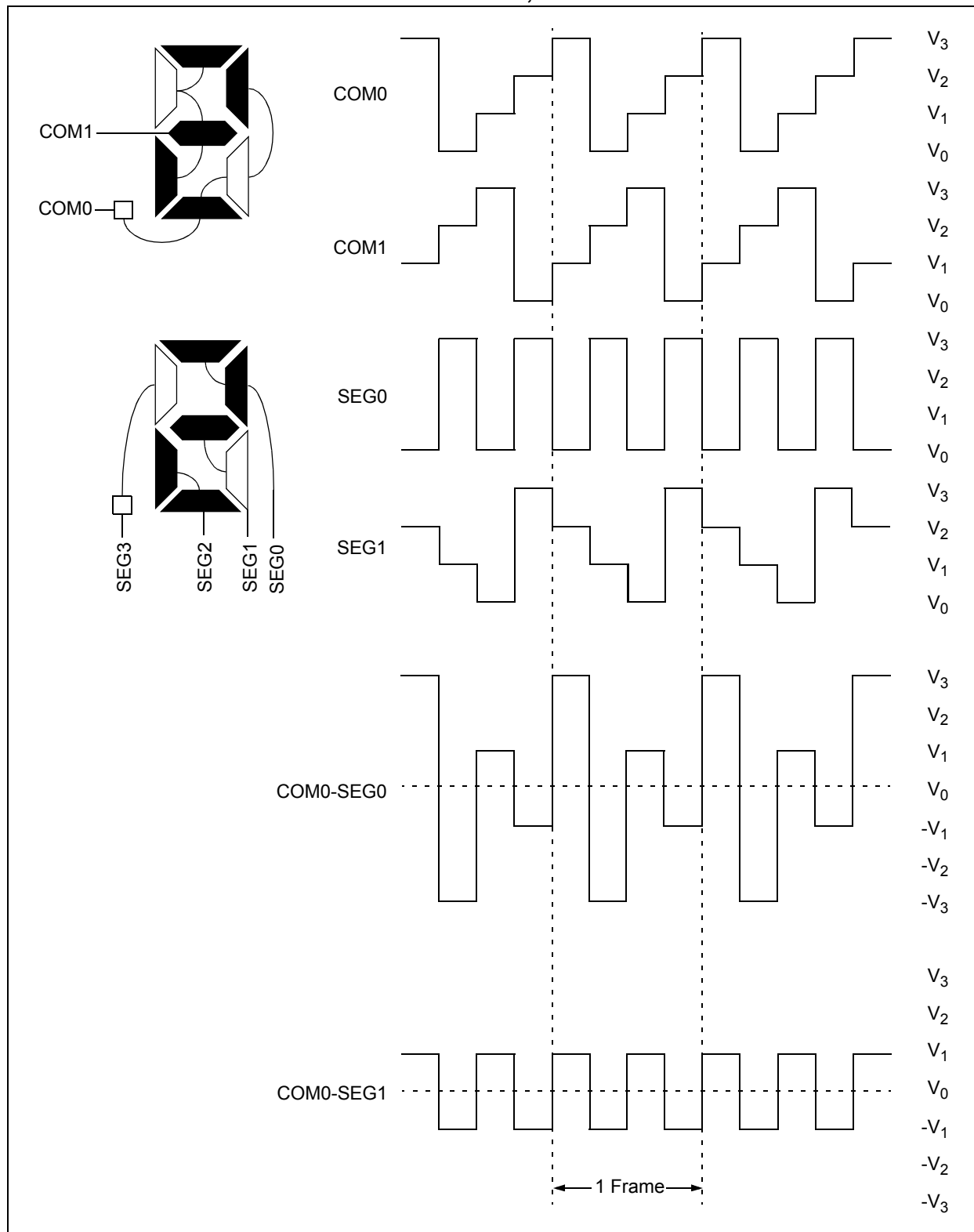
'0' = Bit is cleared

x = Bit is unknown

- bit 7      **WFT:** Waveform Type Select bit  
1 = Type-B waveform (phase changes on each frame boundary)  
0 = Type-A waveform (phase changes within each common interval)
- bit 6      **BIASMD:** Bias Mode Select bit  
When LMUX<1:0> = 00:  
0 = Static Bias mode (do not set this bit to '1')  
When LMUX<1:0> = 01:  
1 = 1/2 Bias mode  
0 = 1/3 Bias mode  
When LMUX<1:0> = 10:  
1 = 1/2 Bias mode  
0 = 1/3 Bias mode  
When LMUX<1:0> = 11:  
0 = 1/3 Bias mode (do not set this bit to '1')
- bit 5      **LCDA:** LCD Active Status bit  
1 = LCD driver module is active  
0 = LCD driver module is inactive
- bit 4      **WA:** LCD Write Allow Status bit  
1 = Write into the LCDDATAx registers is allowed  
0 = Write into the LCDDATAx registers is not allowed
- bit 3-0    **LP<3:0>:** LCD Prescaler Select bits  
1111 = 1:16  
1110 = 1:15  
1101 = 1:14  
1100 = 1:13  
1011 = 1:12  
1010 = 1:11  
1001 = 1:10  
1000 = 1:9  
0111 = 1:8  
0110 = 1:7  
0101 = 1:6  
0100 = 1:5  
0011 = 1:4  
0010 = 1:3  
0001 = 1:2  
0000 = 1:1

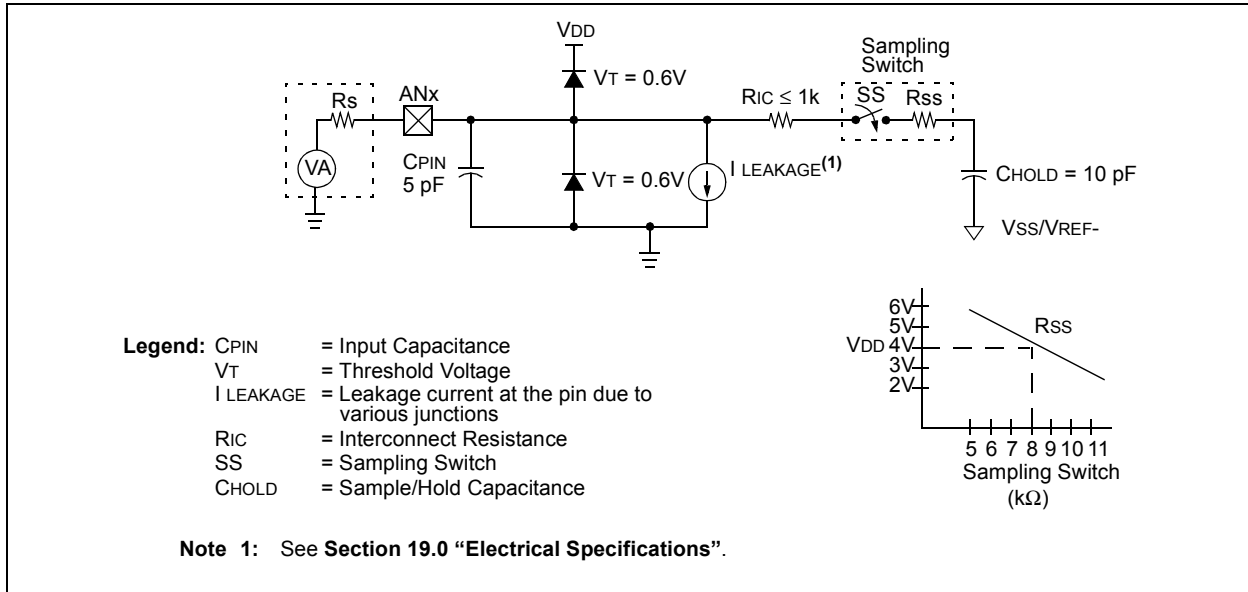
# PIC16F913/914/916/917/946

**FIGURE 10-9: TYPE-A WAVEFORMS IN 1/2 MUX, 1/3 BIAS DRIVE**

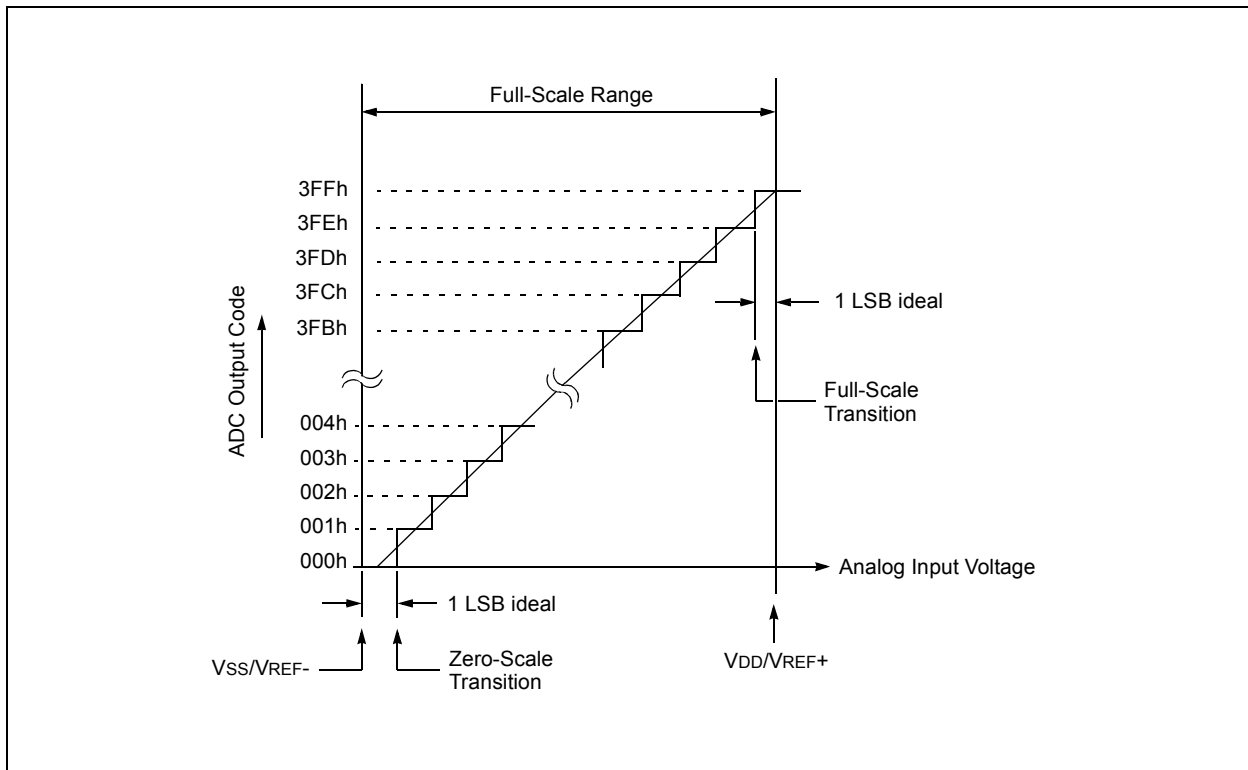


# PIC16F913/914/916/917/946

**FIGURE 12-4: ANALOG INPUT MODEL**



**FIGURE 12-5: ADC TRANSFER FUNCTION**



## 17.0 INSTRUCTION SET SUMMARY

The PIC16F913/914/916/917/946 instruction set is highly orthogonal and is comprised of three basic categories:

- **Byte-oriented** operations
- **Bit-oriented** operations
- **Literal and control** operations

Each PIC16 instruction is a 14-bit word divided into an **opcode**, which specifies the instruction type and one or more **operands**, which further specify the operation of the instruction. The formats for each of the categories is presented in Figure 17-1, while the various opcode fields are summarized in Table 17-1.

Table 17-2 lists the instructions recognized by the MPASM™ assembler.

For **byte-oriented** instructions, 'f' represents a file register designator and 'd' represents a destination designator. The file register designator specifies which file register is to be used by the instruction.

The destination designator specifies where the result of the operation is to be placed. If 'd' is zero, the result is placed in the W register. If 'd' is one, the result is placed in the file register specified in the instruction.

For **bit-oriented** instructions, 'b' represents a bit field designator, which selects the bit affected by the operation, while 'f' represents the address of the file in which the bit is located.

For **literal and control** operations, 'k' represents an 8-bit or 11-bit constant, or literal value.

One instruction cycle consists of four oscillator periods; for an oscillator frequency of 4 MHz, this gives a nominal instruction execution time of 1 μs. All instructions are executed within a single instruction cycle, unless a conditional test is true, or the program counter is changed as a result of an instruction. When this occurs, the execution takes two instruction cycles, with the second cycle executed as a NOP.

All instruction examples use the format '0xhh' to represent a hexadecimal number, where 'h' signifies a hexadecimal digit.

### 17.1 Read-Modify-Write Operations

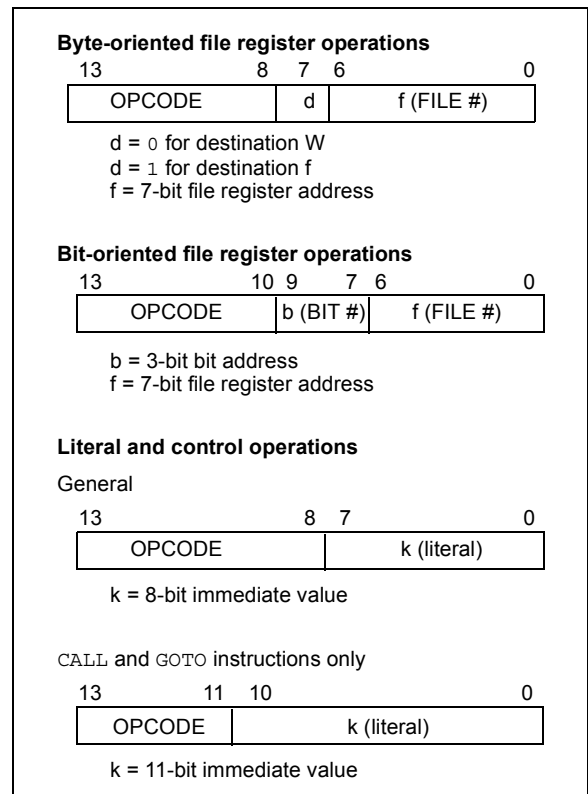
Any instruction that specifies a file register as part of the instruction performs a Read-Modify-Write (R-M-W) operation. The register is read, the data is modified, and the result is stored according to either the instruction, or the destination designator 'd'. A read operation is performed on a register even if the instruction writes to that register.

For example, a `CLRF PORTA` instruction will read PORTA, clear all the data bits, then write the result back to PORTA. This example would have the unintended consequence of clearing the condition that set the RBIF flag.

TABLE 17-1: OPCODE FIELD DESCRIPTIONS

Field	Description
f	Register file address (0x00 to 0x7F)
W	Working register (accumulator)
b	Bit address within an 8-bit file register
k	Literal field, constant data or label
x	Don't care location (= 0 or 1). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools.
d	Destination select; d = 0: store result in W, d = 1: store result in file register f. Default is d = 1.
PC	Program Counter
TO	Time-out bit
C	Carry bit
DC	Digit carry bit
Z	Zero bit
PD	Power-down bit

FIGURE 17-1: GENERAL FORMAT FOR INSTRUCTIONS



## 17.2 Instruction Descriptions

### ADDLW Add literal and W

**Syntax:** [ *label* ] ADDLW *k*

**Operands:**  $0 \leq k \leq 255$

**Operation:**  $(W) + k \rightarrow (W)$

**Status Affected:** C, DC, Z

**Description:** The contents of the W register are added to the eight-bit literal 'k' and the result is placed in the W register.

### BCF Bit Clear f

**Syntax:** [ *label* ] BCF *f*,*b*

**Operands:**  $0 \leq f \leq 127$   
 $0 \leq b \leq 7$

**Operation:**  $0 \rightarrow (f<b>)$

**Status Affected:** None

**Description:** Bit 'b' in register 'f' is cleared.

### ADDWF Add W and f

**Syntax:** [ *label* ] ADDWF *f*,*d*

**Operands:**  $0 \leq f \leq 127$   
 $d \in [0,1]$

**Operation:**  $(W) + (f) \rightarrow (\text{destination})$

**Status Affected:** C, DC, Z

**Description:** Add the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

### BSF Bit Set f

**Syntax:** [ *label* ] BSF *f*,*b*

**Operands:**  $0 \leq f \leq 127$   
 $0 \leq b \leq 7$

**Operation:**  $1 \rightarrow (f<b>)$

**Status Affected:** None

**Description:** Bit 'b' in register 'f' is set.

### ANDLW AND literal with W

**Syntax:** [ *label* ] ANDLW *k*

**Operands:**  $0 \leq k \leq 255$

**Operation:**  $(W) .\text{AND.} (k) \rightarrow (W)$

**Status Affected:** Z

**Description:** The contents of W register are AND'ed with the eight-bit literal 'k'. The result is placed in the W register.

### BTFSC Bit Test f, Skip if Clear

**Syntax:** [ *label* ] BTFSC *f*,*b*

**Operands:**  $0 \leq f \leq 127$   
 $0 \leq b \leq 7$

**Operation:** skip if  $(f<b>) = 0$

**Status Affected:** None

**Description:** If bit 'b' in register 'f' is '1', the next instruction is executed.  
If bit 'b', in register 'f', is '0', the next instruction is discarded, and a NOP is executed instead, making this a 2-cycle instruction.

### ANDWF AND W with f

**Syntax:** [ *label* ] ANDWF *f*,*d*

**Operands:**  $0 \leq f \leq 127$   
 $d \in [0,1]$

**Operation:**  $(W) .\text{AND.} (f) \rightarrow (\text{destination})$

**Status Affected:** Z

**Description:** AND the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.



## 19.6 Thermal Considerations

Standard Operating Conditions (unless otherwise stated)					
Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$					
Param No.	Symbol	Characteristic	Typ.	Units	Conditions
TH01	$\theta_{JA}$	Thermal Resistance Junction to Ambient	60.0	$^{\circ}\text{C/W}$	28-pin PDIP package
			80.0	$^{\circ}\text{C/W}$	28-pin SOIC package
			90.0	$^{\circ}\text{C/W}$	28-pin SSOP package
			27.5	$^{\circ}\text{C/W}$	28-pin QFN 6x6 mm package
			47.2	$^{\circ}\text{C/W}$	40-pin PDIP package
			46.0	$^{\circ}\text{C/W}$	44-pin TQFP package
			24.4	$^{\circ}\text{C/W}$	44-pin QFN 8x8 mm package
			77.0	$^{\circ}\text{C/W}$	64-pin TQFP package
TH02	$\theta_{JC}$	Thermal Resistance Junction to Case	31.4	$^{\circ}\text{C/W}$	28-pin PDIP package
			24.0	$^{\circ}\text{C/W}$	28-pin SOIC package
			24.0	$^{\circ}\text{C/W}$	28-pin SSOP package
			20.0	$^{\circ}\text{C/W}$	28-pin QFN 6x6 mm package
			24.7	$^{\circ}\text{C/W}$	40-pin PDIP package
			14.5	$^{\circ}\text{C/W}$	44-pin TQFP package
			20.0	$^{\circ}\text{C/W}$	44-pin QFN 8x8 mm package
			24.4	$^{\circ}\text{C/W}$	64-pin TQFP package
TH03	$T_J$	Junction Temperature	150	$^{\circ}\text{C}$	For derated power calculations
TH04	PD	Power Dissipation	—	W	$PD = P_{INTERNAL} + P_{I/O}$
TH05	$P_{INTERNAL}$	Internal Power Dissipation	—	W	$P_{INTERNAL} = I_{DD} \times V_{DD}$ <b>(NOTE 1)</b>
TH06	$P_{I/O}$	I/O Power Dissipation	—	W	$P_{I/O} = \sum (I_{OL} \times V_{OL}) + \sum (I_{OH} \times (V_{DD} - V_{OH}))$
TH07	$P_{DER}$	Derated Power	—	W	$P_{DER} = (T_J - T_A) / \theta_{JA}$ <b>(NOTE 2, 3)</b>

**Note 1:**  $I_{DD}$  is current to run the chip alone without driving any load on the output pins.

**2:**  $T_A$  = Ambient Temperature.

**3:** Maximum allowable power dissipation is the lower value of either the absolute maximum total power dissipation or derated power ( $P_{DER}$ ).

# PIC16F913/914/916/917/946

**TABLE 19-9: PIC16F913/914/916/917/946 A/D CONVERSION REQUIREMENTS**

Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
AD130*	TAD	A/D Clock Period	1.6	—	9.0	$\mu\text{s}$	TOSC-based, $V_{\text{REF}} \geq 3.0\text{V}$
			3.0	—	9.0	$\mu\text{s}$	TOSC-based, $V_{\text{REF}}$ full range
		A/D Internal RC Oscillator Period	3.0	6.0	9.0	$\mu\text{s}$	ADCS<1:0> = 11 (ADRC mode)
			1.6	4.0	6.0	$\mu\text{s}$	At $V_{\text{DD}} = 2.5\text{V}$ At $V_{\text{DD}} = 5.0\text{V}$
AD131	TCNV	Conversion Time (not including Acquisition Time) <sup>(1)</sup>	—	11	—	TAD	Set GO/DONE bit to new data in A/D Result register
AD132*	TACQ	Acquisition Time		11.5	—	$\mu\text{s}$	
AD133*	TAMP	Amplifier Settling Time	—	—	5	$\mu\text{s}$	
AD134	TGO	Q4 to A/D Clock Start	—	Tosc/2	—	—	If the A/D clock source is selected as RC, a time of $T_{\text{CY}}$ is added before the A/D clock starts. This allows the <code>SLEEP</code> instruction to be executed.
			—	Tosc/2 + $T_{\text{CY}}$	—	—	

\* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

**Note 1:** ADRESH and ADRESL registers may be read on the following  $T_{\text{CY}}$  cycle.

**2:** See **Section 12.3 "A/D Acquisition Requirements"** for minimum conditions.

# PIC16F913/914/916/917/946

**TABLE 19-13: PIC16F913/914/916/917/946 PLVD CHARACTERISTICS:**

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated)					
			Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$					
			Operating Voltage $V_{DD}$ Range 2.0V-5.5V					
Sym.	Characteristic		Min.	Typ†	Max. (85°C)	Max. (125°C)	Units	Conditions
VPLVD	PLVD Voltage	LVDL<2:0> = 001	1.900	2.0	2.100	2.125	V	
		LVDL<2:0> = 010	2.000	2.1	2.200	2.225	V	
		LVDL<2:0> = 011	2.100	2.2	2.300	2.325	V	
		LVDL<2:0> = 100	2.200	2.3	2.400	2.425	V	
		LVDL<2:0> = 101	3.825	4.0	4.175	4.200	V	
		LVDL<2:0> = 110	4.025	4.2	4.375	4.400	V	
		LVDL<2:0> = 111	4.425	4.5	4.675	4.700	V	
*TPLVDS	PLVD Settling time		—	50 25	—	—	μs	$V_{DD} = 5.0\text{V}$ $V_{DD} = 3.0\text{V}$

\* These parameters are characterized but not tested

† Data in “Typ” column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

# PIC16F913/914/916/917/946

FIGURE 20-34: ADC CLOCK PERIOD vs. VDD OVER TEMPERATURE

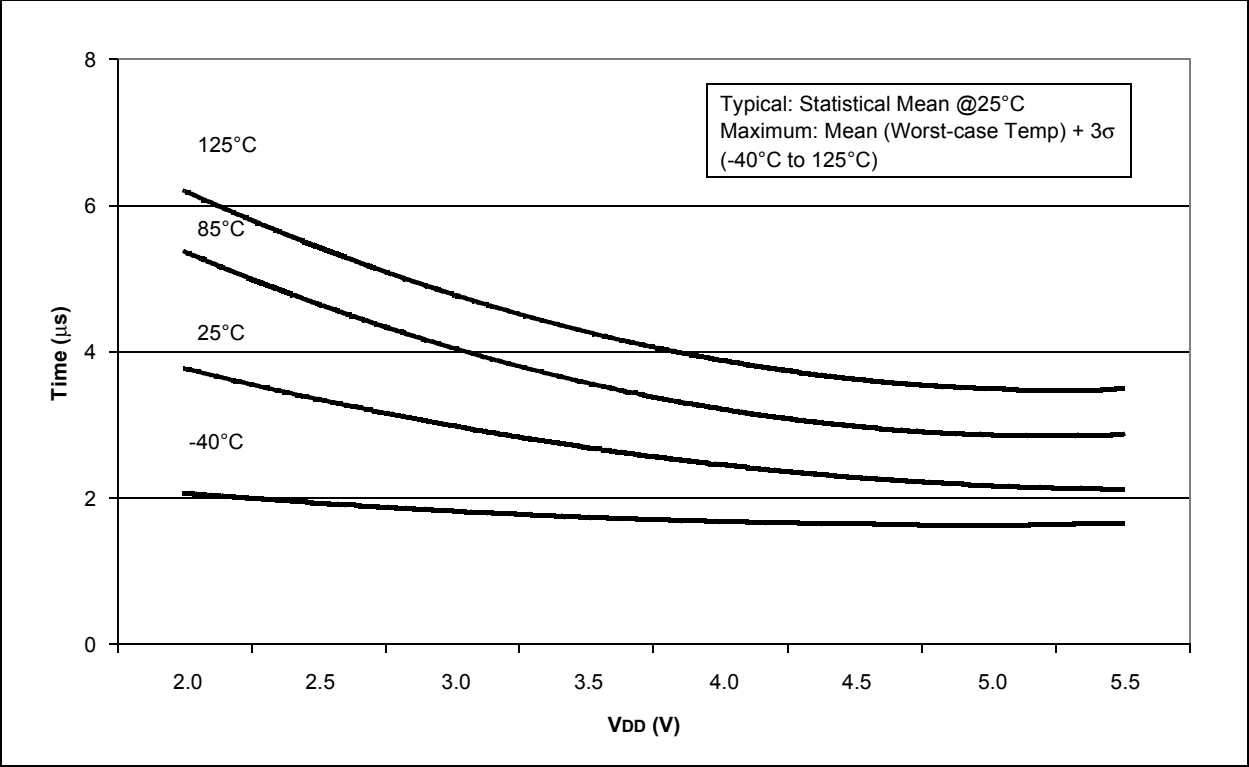
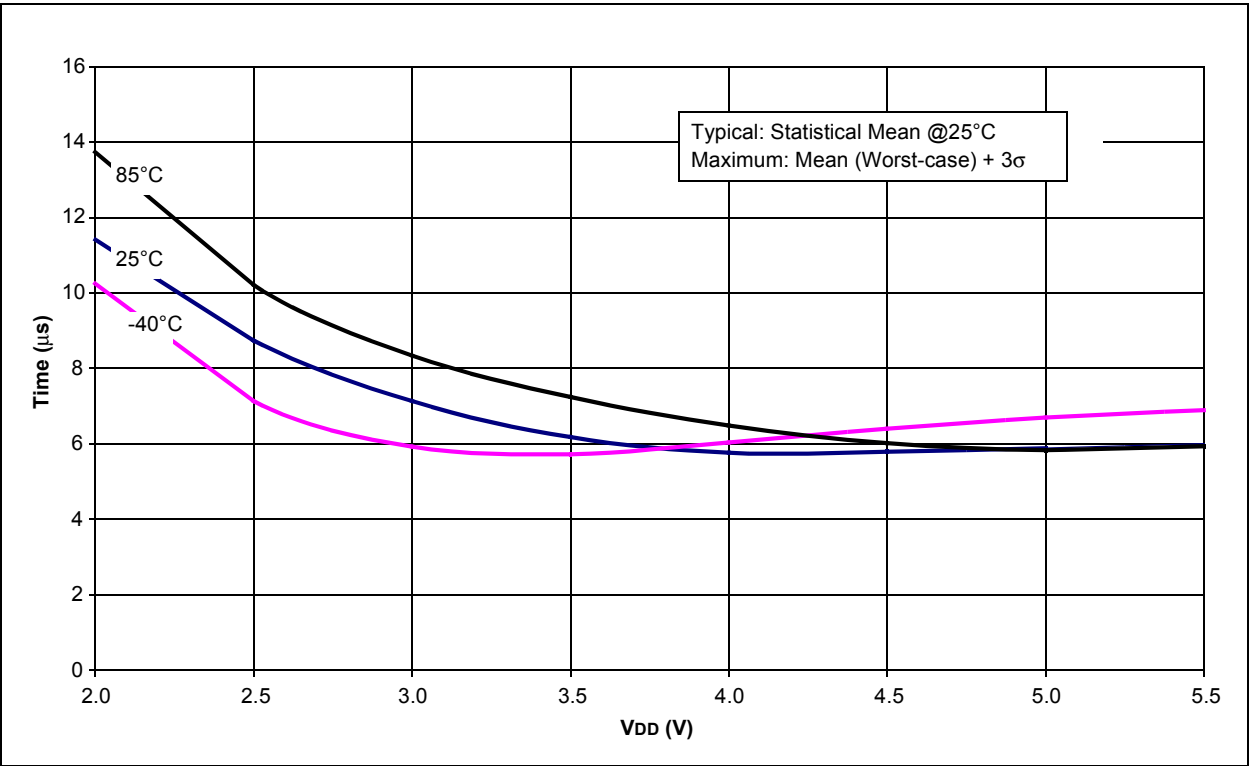


FIGURE 20-35: TYPICAL HFINTOSC START-UP TIMES vs. VDD OVER TEMPERATURE



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