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Understanding <u>Embedded - FPGAs (Field Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	640
Number of Logic Elements/Cells	6400
Total RAM Bits	81920
Number of I/O	316
Number of Gates	404000
Voltage - Supply	1.71V ~ 1.89V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	484-BBGA
Supplier Device Package	484-FBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep20k160efc484-2xb

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

- Flexible clock management circuitry with up to four phase-locked loops (PLLs)
 - Built-in low-skew clock tree
 - Up to eight global clock signals
 - ClockLock[®] feature reducing clock delay and skew
 - ClockBoost[®] feature providing clock multiplication and division
 - ClockShift™ programmable clock phase and delay shifting

Powerful I/O features

- Compliant with peripheral component interconnect Special Interest Group (PCI SIG) PCI Local Bus Specification, Revision 2.2 for 3.3-V operation at 33 or 66 MHz and 32 or 64 bits
- Support for high-speed external memories, including DDR SDRAM and ZBT SRAM (ZBT is a trademark of Integrated Device Technology, Inc.)
- Bidirectional I/O performance ($t_{CO} + t_{SU}$) up to 250 MHz
- LVDS performance up to 840 Mbits per channel
- Direct connection from I/O pins to local interconnect providing fast t_{CO} and t_{SU} times for complex logic
- MultiVolt I/O interface support to interface with 1.8-V, 2.5-V, 3.3-V, and 5.0-V devices (see Table 3)
- Programmable clamp to V_{CCIO}
- Individual tri-state output enable control for each pin
- Programmable output slew-rate control to reduce switching noise
- Support for advanced I/O standards, including low-voltage differential signaling (LVDS), LVPECL, PCI-X, AGP, CTT, stubseries terminated logic (SSTL-3 and SSTL-2), Gunning transceiver logic plus (GTL+), and high-speed terminated logic (HSTL Class I)
- Pull-up on I/O pins before and during configuration

Advanced interconnect structure

- Four-level hierarchical FastTrack[®] Interconnect structure providing fast, predictable interconnect delays
- Dedicated carry chain that implements arithmetic functions such as fast adders, counters, and comparators (automatically used by software tools and megafunctions)
- Dedicated cascade chain that implements high-speed, high-fan-in logic functions (automatically used by software tools and megafunctions)
- Interleaved local interconnect allows one LE to drive 29 other LEs through the fast local interconnect

Advanced packaging options

- Available in a variety of packages with 144 to 1,020 pins (see Tables 4 through 7)
- FineLine BGA® packages maximize board space efficiency

Advanced software support

 Software design support and automatic place-and-route provided by the Altera® Quartus® II development system for

Table 5. APEX 20K F	Table 5. APEX 20K FineLine BGA Package Options & I/O Count Notes (1), (2)										
Device	144 Pin	324 Pin	484 Pin	672 Pin	1,020 Pin						
EP20K30E	93	128									
EP20K60E	93	196									
EP20K100		252									
EP20K100E	93	246									
EP20K160E			316								
EP20K200			382								
EP20K200E			376	376							
EP20K300E				408							
EP20K400				502 <i>(3)</i>							
EP20K400E				488 (3)							
EP20K600E				508 (3)	588						
EP20K1000E				508 (3)	708						
EP20K1500E					808						

Notes to Tables 4 and 5:

- (1) I/O counts include dedicated input and clock pins.
- (2) APEX 20K device package types include thin quad flat pack (TQFP), plastic quad flat pack (PQFP), power quad flat pack (RQFP), 1.27-mm pitch ball-grid array (BGA), 1.00-mm pitch FineLine BGA, and pin-grid array (PGA) packages.
- (3) This device uses a thermally enhanced package, which is taller than the regular package. Consult the *Altera Device Package Information Data Sheet* for detailed package size information.

Table 6. APEX 20K QFP, BGA & PGA Package Sizes											
Feature	144-Pin TQFP	208-Pin QFP	240-Pin QFP	356-Pin BGA	652-Pin BGA	655-Pin PGA					
Pitch (mm)	0.50	0.50	0.50	1.27	1.27	_					
Area (mm ²)	484	924	1,218	1,225	2,025	3,906					
$\begin{array}{c} \text{Length} \times \text{Width} \\ \text{(mm} \times \text{mm)} \end{array}$	22 × 22	30.4 × 30.4	34.9 × 34.9	35 × 35	45 × 45	62.5 × 62.5					

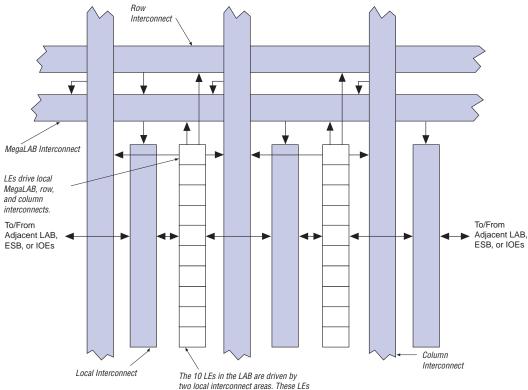
Table 7. APEX 20K FineLine BGA Package Sizes										
Feature	144 Pin	324 Pin	484 Pin	672 Pin	1,020 Pin					
Pitch (mm)	1.00	1.00	1.00	1.00	1.00					
Area (mm ²)	169	361	529	729	1,089					
$Length \times Width \ (mm \times mm)$	13 × 13	19×19	23 × 23	27 × 27	33 × 33					

Logic Array Block

Each LAB consists of 10 LEs, the LEs' associated carry and cascade chains, LAB control signals, and the local interconnect. The local interconnect transfers signals between LEs in the same or adjacent LABs, IOEs, or ESBs. The Quartus II Compiler places associated logic within an LAB or adjacent LABs, allowing the use of a fast local interconnect for high performance. Figure 3 shows the APEX 20K LAB.

APEX 20K devices use an interleaved LAB structure. This structure allows each LE to drive two local interconnect areas. This feature minimizes use of the MegaLAB and FastTrack interconnect, providing higher performance and flexibility. Each LE can drive 29 other LEs through the fast local interconnect.





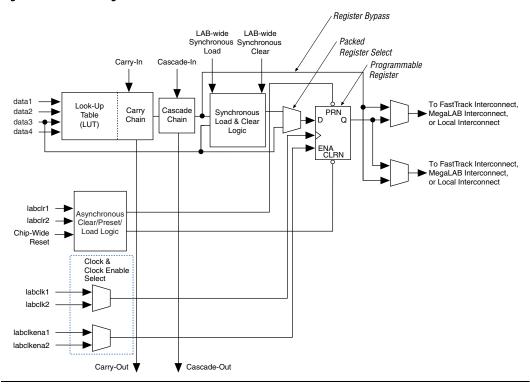
Altera Corporation 11

can drive two local interconnect areas.

Logic Element

The LE, the smallest unit of logic in the APEX 20K architecture, is compact and provides efficient logic usage. Each LE contains a four-input LUT, which is a function generator that can quickly implement any function of four variables. In addition, each LE contains a programmable register and carry and cascade chains. Each LE drives the local interconnect, MegaLAB interconnect, and FastTrack Interconnect routing structures. See Figure 5.

Figure 5. APEX 20K Logic Element



Each LE's programmable register can be configured for D, T, JK, or SR operation. The register's clock and clear control signals can be driven by global signals, general-purpose I/O pins, or any internal logic. For combinatorial functions, the register is bypassed and the output of the LUT drives the outputs of the LE.

Each LE has two outputs that drive the local, MegaLAB, or FastTrack Interconnect routing structure. Each output can be driven independently by the LUT's or register's output. For example, the LUT can drive one output while the register drives the other output. This feature, called register packing, improves device utilization because the register and the LUT can be used for unrelated functions. The LE can also drive out registered and unregistered versions of the LUT output.

The APEX 20K architecture provides two types of dedicated high-speed data paths that connect adjacent LEs without using local interconnect paths: carry chains and cascade chains. A carry chain supports high-speed arithmetic functions such as counters and adders, while a cascade chain implements wide-input functions such as equality comparators with minimum delay. Carry and cascade chains connect LEs 1 through 10 in an LAB and all LABs in the same MegaLAB structure.

Carry Chain

The carry chain provides a very fast carry-forward function between LEs. The carry-in signal from a lower-order bit drives forward into the higher-order bit via the carry chain, and feeds into both the LUT and the next portion of the carry chain. This feature allows the APEX 20K architecture to implement high-speed counters, adders, and comparators of arbitrary width. Carry chain logic can be created automatically by the Quartus II software Compiler during design processing, or manually by the designer during design entry. Parameterized functions such as library of parameterized modules (LPM) and DesignWare functions automatically take advantage of carry chains for the appropriate functions.

The Quartus II software Compiler creates carry chains longer than ten LEs by linking LABs together automatically. For enhanced fitting, a long carry chain skips alternate LABs in a MegaLABTM structure. A carry chain longer than one LAB skips either from an even-numbered LAB to the next even-numbered LAB, or from an odd-numbered LAB to the next odd-numbered LAB. For example, the last LE of the first LAB in the upper-left MegaLAB structure carries to the first LE of the third LAB in the MegaLAB structure.

Figure 6 shows how an n-bit full adder can be implemented in n+1 LEs with the carry chain. One portion of the LUT generates the sum of two bits using the input signals and the carry-in signal; the sum is routed to the output of the LE. The register can be bypassed for simple adders or used for accumulator functions. Another portion of the LUT and the carry chain logic generates the carry-out signal, which is routed directly to the carryin signal of the next-higher-order bit. The final carry-out signal is routed to an LE, where it is driven onto the local, MegaLAB, or FastTrack Interconnect routing structures.

Read/Write Clock Mode

The read/write clock mode contains two clocks. One clock controls all registers associated with writing: data input, WE, and write address. The other clock controls all registers associated with reading: read enable (RE), read address, and data output. The ESB also supports clock enable and asynchronous clear signals; these signals also control the read and write registers independently. Read/write clock mode is commonly used for applications where reads and writes occur at different system frequencies. Figure 20 shows the ESB in read/write clock mode.

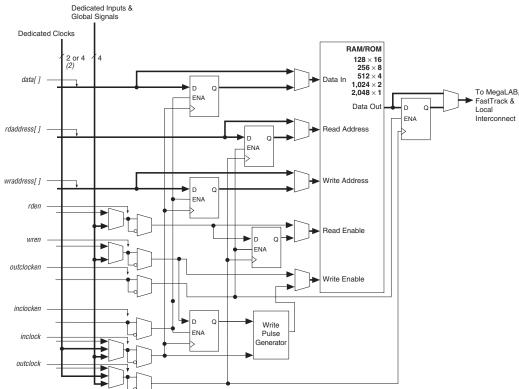


Figure 20. ESB in Read/Write Clock Mode Note (1)

Notes to Figure 20:

(1) All registers can be cleared asynchronously by ESB local interconnect signals, global signals, or the chip-wide reset.

(2) APEX 20KE devices have four dedicated clocks.

Input/Output Clock Mode

The input/output clock mode contains two clocks. One clock controls all registers for inputs into the ESB: data input, WE, RE, read address, and write address. The other clock controls the ESB data output registers. The ESB also supports clock enable and asynchronous clear signals; these signals also control the reading and writing of registers independently. Input/output clock mode is commonly used for applications where the reads and writes occur at the same system frequency, but require different clock enable signals for the input and output registers. Figure 21 shows the ESB in input/output clock mode.

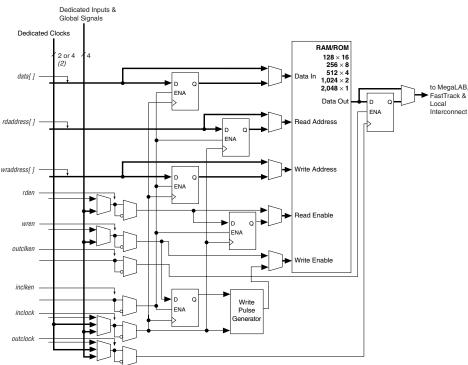


Figure 21. ESB in Input/Output Clock Mode Note (1)

Notes to Figure 21:

- (1) All registers can be cleared asynchronously by ESB local interconnect signals, global signals, or the chip-wide reset.
- (2) APEX 20KE devices have four dedicated clocks.

Single-Port Mode

The APEX 20K ESB also supports a single-port mode, which is used when simultaneous reads and writes are not required. See Figure 22.

Implementing Logic in ROM

In addition to implementing logic with product terms, the ESB can implement logic functions when it is programmed with a read-only pattern during configuration, creating a large LUT. With LUTs, combinatorial functions are implemented by looking up the results, rather than by computing them. This implementation of combinatorial functions can be faster than using algorithms implemented in general logic, a performance advantage that is further enhanced by the fast access times of ESBs. The large capacity of ESBs enables designers to implement complex functions in one logic level without the routing delays associated with linked LEs or distributed RAM blocks. Parameterized functions such as LPM functions can take advantage of the ESB automatically. Further, the Quartus II software can implement portions of a design with ESBs where appropriate.

Programmable Speed/Power Control

APEX 20K ESBs offer a high-speed mode that supports very fast operation on an ESB-by-ESB basis. When high speed is not required, this feature can be turned off to reduce the ESB's power dissipation by up to 50%. ESBs that run at low power incur a nominal timing delay adder. This Turbo BitTM option is available for ESBs that implement product-term logic or memory functions. An ESB that is not used will be powered down so that it does not consume DC current.

Designers can program each ESB in the APEX 20K device for either high-speed or low-power operation. As a result, speed-critical paths in the design can run at high speed, while the remaining paths operate at reduced power.

I/O Structure

The APEX 20K IOE contains a bidirectional I/O buffer and a register that can be used either as an input register for external data requiring fast setup times, or as an output register for data requiring fast clock-to-output performance. IOEs can be used as input, output, or bidirectional pins. For fast bidirectional I/O timing, LE registers using local routing can improve setup times and OE timing. The Quartus II software Compiler uses the programmable inversion option to invert signals from the row and column interconnect automatically where appropriate. Because the APEX 20K IOE offers one output enable per pin, the Quartus II software Compiler can emulate open-drain operation efficiently.

The APEX 20K IOE includes programmable delays that can be activated to ensure zero hold times, minimum clock-to-output times, input IOE register-to-core register transfers, or core-to-output IOE register transfers. A path in which a pin directly drives a register may require the delay to ensure zero hold time, whereas a path in which a pin drives a register through combinatorial logic may not require the delay.

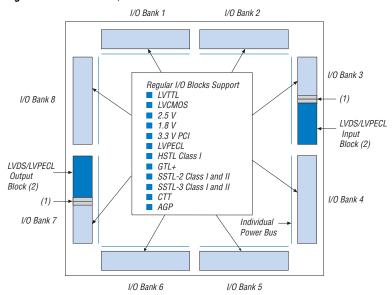


Figure 29. APEX 20KE I/O Banks

Notes to Figure 29:

- For more information on placing I/O pins in LVDS blocks, refer to the Guidelines for Using LVDS Blocks section in Application Note 120 (Using LVDS in APEX 20KE Devices).
- (2) If the LVDS input and output blocks are not used for LVDS, they can support all of the I/O standards and can be used as input, output, or bidirectional pins with V_{CCIO} set to 3.3 V, 2.5 V, or 1.8 V.

Power Sequencing & Hot Socketing

Because APEX 20K and APEX 20KE devices can be used in a mixed-voltage environment, they have been designed specifically to tolerate any possible power-up sequence. Therefore, the $V_{\rm CCIO}$ and $V_{\rm CCINT}$ power supplies may be powered in any order.



For more information, please refer to the "Power Sequencing Considerations" section in the *Configuring APEX 20KE & APEX 20KC Devices* chapter of the *Configuration Devices Handbook*.

Signals can be driven into APEX 20K devices before and during power-up without damaging the device. In addition, APEX 20K devices do not drive out during power-up. Once operating conditions are reached and the device is configured, APEX 20K and APEX 20KE devices operate as specified by the user.

APEX 20KE devices also support the MultiVolt I/O interface feature. The APEX 20KE VCCINT pins must always be connected to a 1.8-V power supply. With a 1.8-V V_{CCINT} level, input pins are 1.8-V, 2.5-V, and 3.3-V tolerant. The VCCIO pins can be connected to either a 1.8-V, 2.5-V, or 3.3-V power supply, depending on the I/O standard requirements. When the VCCIO pins are connected to a 1.8-V power supply, the output levels are compatible with 1.8-V systems. When VCCIO pins are connected to a 2.5-V power supply, the output levels are compatible with 2.5-V systems. When VCCIO pins are connected to a 3.3-V power supply, the output high is 3.3 V and compatible with 3.3-V or 5.0-V systems. An APEX 20KE device is 5.0-V tolerant with the addition of a resistor.

Table 13 summarizes APEX 20KE MultiVolt I/O support.

Table 13. A	Table 13. APEX 20KE MultiVolt I/O Support Note (1)												
V _{CCIO} (V)		Input Sig	ınals (V)			Output S	ignals (V)						
	1.8	2.5	3.3	5.0	1.8	2.5	3.3	5.0					
1.8	✓	✓	✓		✓								
2.5	✓	✓	✓			✓							
3.3	✓	✓	\	(2)			√ (3)						

Notes to Table 13:

- The PCI clamping diode must be disabled to drive an input with voltages higher than V_{CCIO}, except for the 5.0-V input case.
- (2) An APEX 20KE device can be made 5.0-V tolerant with the addition of an external resistor. You also need a PCI clamp and series resistor.
- (3) When $V_{CCIO} = 3.3 \text{ V}$, an APEX 20KE device can drive a 2.5-V device with 3.3-V tolerant inputs.

ClockLock & ClockBoost Features

APEX 20K devices support the ClockLock and ClockBoost clock management features, which are implemented with PLLs. The ClockLock circuitry uses a synchronizing PLL that reduces the clock delay and skew within a device. This reduction minimizes clock-to-output and setup times while maintaining zero hold times. The ClockBoost circuitry, which provides a clock multiplier, allows the designer to enhance device area efficiency by sharing resources within the device. The ClockBoost circuitry allows the designer to distribute a low-speed clock and multiply that clock on-device. APEX 20K devices include a high-speed clock tree; unlike ASICs, the user does not have to design and optimize the clock tree. The ClockLock and ClockBoost features work in conjunction with the APEX 20K device's high-speed clock to provide significant improvements in system performance and band-width. Devices with an X-suffix on the ordering code include the ClockLock circuit.

The ClockLock and ClockBoost features in APEX 20K devices are enabled through the Quartus II software. External devices are not required to use these features.

The APEX 20K device instruction register length is 10 bits. The APEX 20K device USERCODE register length is 32 bits. Tables 20 and 21 show the boundary-scan register length and device IDCODE information for APEX 20K devices.

Table 20. APEX 20K Boundary-Sca	an Register Length
Device	Boundary-Scan Register Length
EP20K30E	420
EP20K60E	624
EP20K100	786
EP20K100E	774
EP20K160E	984
EP20K200	1,176
EP20K200E	1,164
EP20K300E	1,266
EP20K400	1,536
EP20K400E	1,506
EP20K600E	1,806
EP20K1000E	2,190
EP20K1500E	1 (1)

Note to Table 20:

(1) This device does not support JTAG boundary scan testing.

Device		IDCODE (32 Bits) (1)									
	Version (4 Bits)	Part Number (16 Bits)	Manufacturer Identity (11 Bits)	1 (1 Bit)							
EP20K30E	0000	1000 0000 0011 0000	000 0110 1110	1							
EP20K60E	0000	1000 0000 0110 0000	000 0110 1110	1							
EP20K100	0000	0000 0100 0001 0110	000 0110 1110	1							
EP20K100E	0000	1000 0001 0000 0000	000 0110 1110	1							
EP20K160E	0000	1000 0001 0110 0000	000 0110 1110	1							
EP20K200	0000	0000 1000 0011 0010	000 0110 1110	1							
EP20K200E	0000	1000 0010 0000 0000	000 0110 1110	1							
EP20K300E	0000	1000 0011 0000 0000	000 0110 1110	1							
EP20K400	0000	0001 0110 0110 0100	000 0110 1110	1							
EP20K400E	0000	1000 0100 0000 0000	000 0110 1110	1							
EP20K600E	0000	1000 0110 0000 0000	000 0110 1110	1							
EP20K1000E	0000	1001 0000 0000 0000	000 0110 1110	1							

Notes to Table 21:

- (1) The most significant bit (MSB) is on the left.
- (2) The IDCODE's least significant bit (LSB) is always 1.

Figure 31 shows the timing requirements for the JTAG signals.

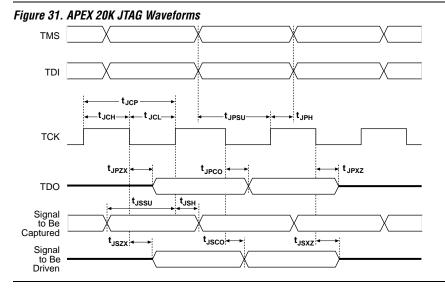


Table 22 shows the JTAG timing parameters and values for APEX 20K devices

Table 2	2. APEX 20K JTAG Timing Parameters & Values			
Symbol	Parameter	Min	Max	Unit
t _{JCP}	TCK clock period	100		ns
t _{JCH}	TCK clock high time	50		ns
t_{JCL}	TCK clock low time	50		ns
t _{JPSU}	JTAG port setup time	20		ns
t _{JPH}	JTAG port hold time	45		ns
t _{JPCO}	JTAG port clock to output		25	ns
t _{JPZX}	JTAG port high impedance to valid output		25	ns
t _{JPXZ}	JTAG port valid output to high impedance		25	ns
t _{JSSU}	Capture register setup time	20		ns
t _{JSH}	Capture register hold time	45		ns
t _{JSCO}	Update register clock to output		35	ns
t _{JSZX}	Update register high impedance to valid output		35	ns
t _{JSXZ}	Update register valid output to high impedance		35	ns



For more information, see the following documents:

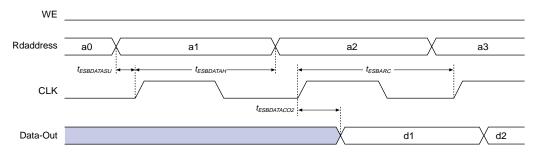
- Application Note 39 (IEEE Std. 1149.1 (JTAG) Boundary-Scan Testing in Altera Devices)
- Jam Programming & Test Language Specification

Generic Testing

Each APEX 20K device is functionally tested. Complete testing of each configurable static random access memory (SRAM) bit and all logic functionality ensures 100% yield. AC test measurements for APEX 20K devices are made under conditions equivalent to those shown in Figure 32. Multiple test patterns can be used to configure devices during all stages of the production flow.

Figure 39. ESB Synchronous Timing Waveforms

ESB Synchronous Read



ESB Synchronous Write (ESB Output Registers Used)

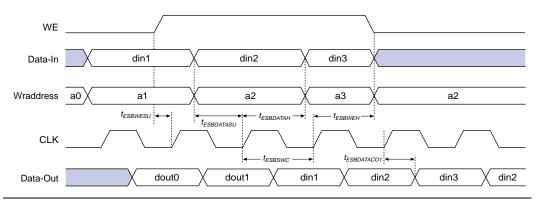


Figure 40 shows the timing model for bidirectional I/O pin timing.

Table 43. EP20	Table 43. EP20K100 External Timing Parameters											
Symbol	-1 Speed Grade		-2 Spe	-2 Speed Grade		-3 Speed Grade						
	Min	Max	Min	Max	Min	Max						
t _{INSU} (1)	2.3		2.8		3.2		ns					
t _{INH} (1)	0.0		0.0		0.0		ns					
t _{OUTCO} (1)	2.0	4.5	2.0	4.9	2.0	6.6	ns					
t _{INSU} (2)	1.1		1.2		-		ns					
t _{INH} (2)	0.0		0.0		-		ns					
t _{OUTCO} (2)	0.5	2.7	0.5	3.1	_	4.8	ns					

Symbol	-1 Spee	ed Grade	-2 Spee	d Grade	-3 Spee	d Grade	Unit
	Min	Max	Min	Max	Min	Max	
t _{INSUBIDIR} (1)	2.3		2.8		3.2		ns
t _{INHBIDIR} (1)	0.0		0.0		0.0		ns
toutcobidir (1)	2.0	4.5	2.0	4.9	2.0	6.6	ns
t _{XZBIDIR} (1)		5.0		5.9		6.9	ns
t _{ZXBIDIR} (1)		5.0		5.9		6.9	ns
t _{INSUBIDIR} (2)	1.0		1.2		-		ns
t _{INHBIDIR} (2)	0.0		0.0		-		ns
toutcobidir (2)	0.5	2.7	0.5	3.1	-	-	ns
t _{XZBIDIR} (2)		4.3		5.0		_	ns
t _{ZXBIDIR} (2)		4.3		5.0		_	ns

Table 45. EP20	Table 45. EP20K200 External Timing Parameters											
Symbol	-1 Spec	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade						
	Min	Max	Min	Max	Min	Max						
t _{INSU} (1)	1.9		2.3		2.6		ns					
t _{INH} (1)	0.0		0.0		0.0		ns					
t _{OUTCO} (1)	2.0	4.6	2.0	5.6	2.0	6.8	ns					
t _{INSU} (2)	1.1		1.2		-		ns					
t _{INH} (2)	0.0		0.0		-		ns					
t _{оитсо} <i>(2)</i>	0.5	2.7	0.5	3.1	-	_	ns					

Symbol	-1			-2		-3	
	Min	Max	Min	Max	Min	Max	
t _{ESBARC}		2.03		2.86		4.24	ns
t _{ESBSRC}		2.58		3.49		5.02	ns
t _{ESBAWC}		3.88		5.45		8.08	ns
t _{ESBSWC}		4.08		5.35		7.48	ns
t _{ESBWASU}	1.77		2.49		3.68		ns
t _{ESBWAH}	0.00		0.00		0.00		ns
t _{ESBWDSU}	1.95		2.74		4.05		ns
t _{ESBWDH}	0.00		0.00		0.00		ns
t _{ESBRASU}	1.96		2.75		4.07		ns
t _{ESBRAH}	0.00		0.00		0.00		ns
t _{ESBWESU}	1.80		2.73		4.28		ns
t _{ESBWEH}	0.00		0.00		0.00		ns
t _{ESBDATASU}	0.07		0.48		1.17		ns
t _{ESBDATAH}	0.13		0.13		0.13		ns
t _{ESBWADDRSU}	0.30		0.80		1.64		ns
t _{ESBRADDRSU}	0.37		0.90		1.78		ns
t _{ESBDATACO1}		1.11		1.32		1.67	ns
t _{ESBDATACO2}		2.65		3.73		5.53	ns
t _{ESBDD}		3.88		5.45		8.08	ns
t _{PD}		1.91	_	2.69		3.98	ns
t _{PTERMSU}	1.04		1.71		2.82		ns
t _{PTERMCO}		1.13		1.34		1.69	ns

Table 51. EP20K30E f _{MAX} Routing Delays										
Symbol	-	1	,	-2	-3		Unit			
	Min	Max	Min	Max	Min	Max				
t _{F1-4}		0.24		0.27		0.31	ns			
t _{F5-20}		1.03		1.14		1.30	ns			
t _{F20+}		1.42		1.54		1.77	ns			

Symbol	-1		-2		-3		Unit
	Min	Max	Min	Max	Min	Max	1
t _{INSUBIDIR}	2.77		2.91		3.11		ns
t _{INHBIDIR}	0.00		0.00		0.00		ns
t _{OUTCOBIDIR}	2.00	4.84	2.00	5.31	2.00	5.81	ns
t _{XZBIDIR}		6.47		7.44		8.65	ns
t _{ZXBIDIR}		6.47		7.44		8.65	ns
t _{INSUBIDIRPLL}	3.44		3.24		-		ns
tinhbidirpll	0.00		0.00		-		ns
^t OUTCOBIDIRPLL	0.50	3.37	0.50	3.69	-	-	ns
t _{XZBIDIRPLL}		5.00		5.82		-	ns
tzxbidirpll		5.00		5.82		-	ns

Tables 61 through 66 describe f_{MAX} LE Timing Microparameters, f_{MAX} ESB Timing Microparameters, f_{MAX} Routing Delays, Minimum Pulse Width Timing Parameters, External Timing Parameters, and External Bidirectional Timing Parameters for EP20K100E APEX 20KE devices.

Table 61. EP20K100E f _{MAX} LE Timing Microparameters									
Symbol	-	1	-2		-1	3	Unit		
	Min	Max	Min	Max	Min	Max	7		
t _{SU}	0.25		0.25		0.25		ns		
t _H	0.25		0.25		0.25		ns		
t _{CO}		0.28		0.28		0.34	ns		
t _{LUT}		0.80		0.95		1.13	ns		

Tables 67 through 72 describe f_{MAX} LE Timing Microparameters, f_{MAX} ESB Timing Microparameters, f_{MAX} Routing Delays, Minimum Pulse Width Timing Parameters, External Timing Parameters, and External Bidirectional Timing Parameters for EP20K160E APEX 20KE devices.

Table 67. EP20K160E f _{MAX} LE Timing Microparameters										
Symbol	-1			-2		3	Unit			
	Min	Max	Min	Max	Min	Max	1			
t _{SU}	0.22		0.24		0.26		ns			
t _H	0.22		0.24		0.26		ns			
t _{CO}		0.25		0.31		0.35	ns			
t _{LUT}		0.69		0.88		1.12	ns			

Symbol	-1		-2		-3		Unit
	Min	Max	Min	Max	Min	Max	
t _{ESBARC}		1.79		2.44		3.25	ns
t _{ESBSRC}		2.40		3.12		4.01	ns
t _{ESBAWC}		3.41		4.65		6.20	ns
t _{ESBSWC}		3.68		4.68		5.93	ns
t _{ESBWASU}	1.55		2.12		2.83		ns
t _{ESBWAH}	0.00		0.00		0.00		ns
t _{ESBWDSU}	1.71		2.33		3.11		ns
t _{ESBWDH}	0.00		0.00		0.00		ns
t _{ESBRASU}	1.72		2.34		3.13		ns
t _{ESBRAH}	0.00		0.00		0.00		ns
t _{ESBWESU}	1.63		2.36		3.28		ns
t _{ESBWEH}	0.00		0.00		0.00		ns
t _{ESBDATASU}	0.07		0.39		0.80		ns
t _{ESBDATAH}	0.13		0.13		0.13		ns
t _{ESBWADDRSU}	0.27		0.67		1.17		ns
t _{ESBRADDRSU}	0.34		0.75		1.28		ns
t _{ESBDATACO1}		1.03		1.20		1.40	ns
t _{ESBDATACO2}		2.33		3.18		4.24	ns
t _{ESBDD}		3.41		4.65		6.20	ns
t _{PD}		1.68		2.29		3.06	ns
t _{PTERMSU}	0.96		1.48		2.14		ns
t _{PTERMCO}		1.05		1.22		1.42	ns

Table 81. EP20K300E f _{MAX} Routing Delays										
Symbol	-	1		2	-3		Unit			
	Min	Max	Min	Max	Min	Max	1			
t _{F1-4}		0.22		0.24		0.26	ns			
t _{F5-20}		1.33		1.43		1.58	ns			
t _{F20+}		3.63		3.93		4.35	ns			

Symbol	-1 Speed Grade		-2 Spee	d Grade	-3 Spee	Unit	
	Min	Max	Min	Max	Min	Max	1
t _{INSUBIDIR}	3.22		3.33		3.51		ns
t _{INHBIDIR}	0.00		0.00		0.00		ns
toutcobidir	2.00	5.75	2.00	6.33	2.00	6.90	ns
t _{XZBIDIR}		6.31		7.09		7.76	ns
tzxbidir		6.31		7.09		7.76	ns
t _{INSUBIDIRPL} L	3.25		3.26				ns
t _{INHBIDIRPLL}	0.00		0.00				ns
toutcobidirpll	0.50	2.25	0.50	2.99			ns
txzbidirpll		2.81		3.80			ns
t _{ZXBIDIRPLL}		2.81		3.80			ns

Tables 103 through 108 describe f_{MAX} LE Timing Microparameters, f_{MAX} ESB Timing Microparameters, f_{MAX} Routing Delays, Minimum Pulse Width Timing Parameters, External Timing Parameters, and External Bidirectional Timing Parameters for EP20K1500E APEX 20KE devices.

Table 103. EP20K1500E f _{MAX} LE Timing Microparameters									
Symbol	-1 Spee	d Grade	-2 Spee	d Grade	e -3 Speed Grade		Unit		
	Min	Max	Min	Max	Min	Max			
t _{SU}	0.25		0.25		0.25		ns		
t _H	0.25		0.25		0.25		ns		
t _{CO}		0.28		0.32		0.33	ns		
t _{LUT}		0.80		0.95		1.13	ns		