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Details

Product Status	Active
Core Processor	HCS12
Core Size	16-Bit
Speed	25MHz
Connectivity	CANbus, I ² C, SCI, SPI
Peripherals	PWM, WDT
Number of I/O	59
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2.35V ~ 5.25V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-QFP
Supplier Device Package	80-QFP (14x14)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=s9s12d64f0cfue

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Section 1 Introduction

1.1 Overview

The MC9S12DJ64 microcontroller unit (MCU) is a 16-bit device composed of standard on-chip peripherals including a 16-bit central processing unit (HCS12 CPU), 64K bytes of Flash EEPROM, 4K bytes of RAM, 1K bytes of EEPROM, two asynchronous serial communications interfaces (SCI), one serial peripheral interfaces (SPI), an 8-channel IC/OC enhanced capture timer, two 8-channel, 10-bit analog-to-digital converters (ADC), an 8-channel pulse-width modulator (PWM), a digital Byte Data Link Controller (BDLC), 29 discrete digital I/O channels (Port A, Port B, Port K and Port E), 20 discrete digital I/O lines with interrupt and wakeup capability, a CAN 2.0 A, B software compatible modules (MSCAN12), and an Inter-IC Bus. The MC9S12DJ64 has full 16-bit data paths throughout. However, the external bus can operate in an 8-bit narrow mode so single 8-bit wide memory can be interfaced for lower cost systems. The inclusion of a PLL circuit allows power consumption and performance to be adjusted to suit operational requirements.

1.2 Features

- HCS12 Core
 - 16-bit HCS12 CPU
 - i. Upward compatible with M68HC11 instruction set
 - ii. Interrupt stacking and programmer's model identical to M68HC11
 - iii. Instruction queue
 - iv. Enhanced indexed addressing
 - MEBI (Multiplexed External Bus Interface)
 - MMC (Module Mapping Control)
 - INT (Interrupt control)
 - BKP (Breakpoints)
 - BDM (Background Debug Mode)
- CRG (low current Colpitts or Pierce oscillator, PLL, reset, clocks, COP watchdog, real time interrupt, clock monitor)
- 8-bit and 4-bit ports with interrupt functionality
 - Digital filtering
 - Programmable rising or falling edge trigger
- Memory
 - 64K Flash EEPROM
 - 1K byte EEPROM

1.4 Block Diagram

Figure 1-1 shows a block diagram of the MC9S12DJ64 device.

\$00A0 - \$00C7**PWM (Pulse Width Modulator 8 Bit 8 Channel)**

Address	Name		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
\$00C2	PWMDTY6	Read:	Bit 7	6	5	4	3	2	1	Bit 0
		Write:								
\$00C3	PWMDTY7	Read:	Bit 7	6	5	4	3	2	1	Bit 0
		Write:								
\$00C4	PWMSDN	Read:	PWMIF	PWMIE	PWMRSTRT	PWMLVL	0	PWM7IN	PWM7INL	PWM7ENA
		Write:								
\$00C5	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
\$00C6	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
\$00C7	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								

\$00C8 - \$00CF**SCI0 (Asynchronous Serial Interface)**

Address	Name		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
\$00C8	SCI0BDH	Read:	0	0	0	SBR12	SBR11	SBR10	SBR9	SBR8
		Write:								
\$00C9	SCI0BDL	Read:	SBR7	SBR6	SBR5	SBR4	SBR3	SBR2	SBR1	SBR0
		Write:								
\$00CA	SCI0CR1	Read:	LOOPS	SCISWAI	RSRC	M	WAKE	ILT	PE	PT
		Write:								
\$00CB	SCI0CR2	Read:	TIE	TCIE	RIE	ILIE	TE	RE	RWU	SBK
		Write:								
\$00CC	SCI0SR1	Read:	TDRE	TC	RDRF	IDLE	OR	NF	FE	PF
		Write:								
\$00CD	SCI0SR2	Read:	0	0	0	0	0	BRK13	TXDIR	RAF
		Write:								
\$00CE	SCI0DRH	Read:	R8	T8	0	0	0	0	0	0
		Write:								
\$00CF	SCI0DRL	Read:	R7	R6	R5	R4	R3	R2	R1	R0
		Write:	T7	T6	T5	T4	T3	T2	T1	T0

\$00D0 - \$00D7**SCI1 (Asynchronous Serial Interface)**

Address	Name		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
\$00D0	SCI1BDH	Read:	0	0	0	SBR12	SBR11	SBR10	SBR9	SBR8
		Write:								
\$00D1	SCI1BDL	Read:	SBR7	SBR6	SBR5	SBR4	SBR3	SBR2	SBR1	SBR0
		Write:								
\$00D2	SCI1CR1	Read:	LOOPS	SCISWAI	RSRC	M	WAKE	ILT	PE	PT
		Write:								
\$00D3	SCI1CR2	Read:	TIE	TCIE	RIE	ILIE	TE	RE	RWU	SBK
		Write:								
\$00D4	SCI1SR1	Read:	TDRE	TC	RDRF	IDLE	OR	NF	FE	PF
		Write:								

1.6 Part ID Assignments

The part ID is located in two 8-bit registers PARTIDH and PARTIDL (addresses \$001A and \$001B after reset). The read-only value is a unique part ID for each revision of the chip. **Table 1-4** shows the assigned part ID number.

Table 1-4 Assigned Part ID Numbers

Device	Mask Set Number	Part ID ¹
MC9S12DJ64	0L86D	\$0200
MC9S12DJ64	1L86D	\$0201
MC9S12DJ64	2L86D	\$0201 ²
MC9S12DJ64	3L86D	\$0203
MC9S12DJ64	4L86D	\$0204
MC9S12DJ64	0M89C	\$0204

NOTES:

1. The coding is as follows:

Bit 15-12: Major family identifier

Bit 11-8: Minor family identifier

Bit 7-4: Major mask set revision number including FAB transfers

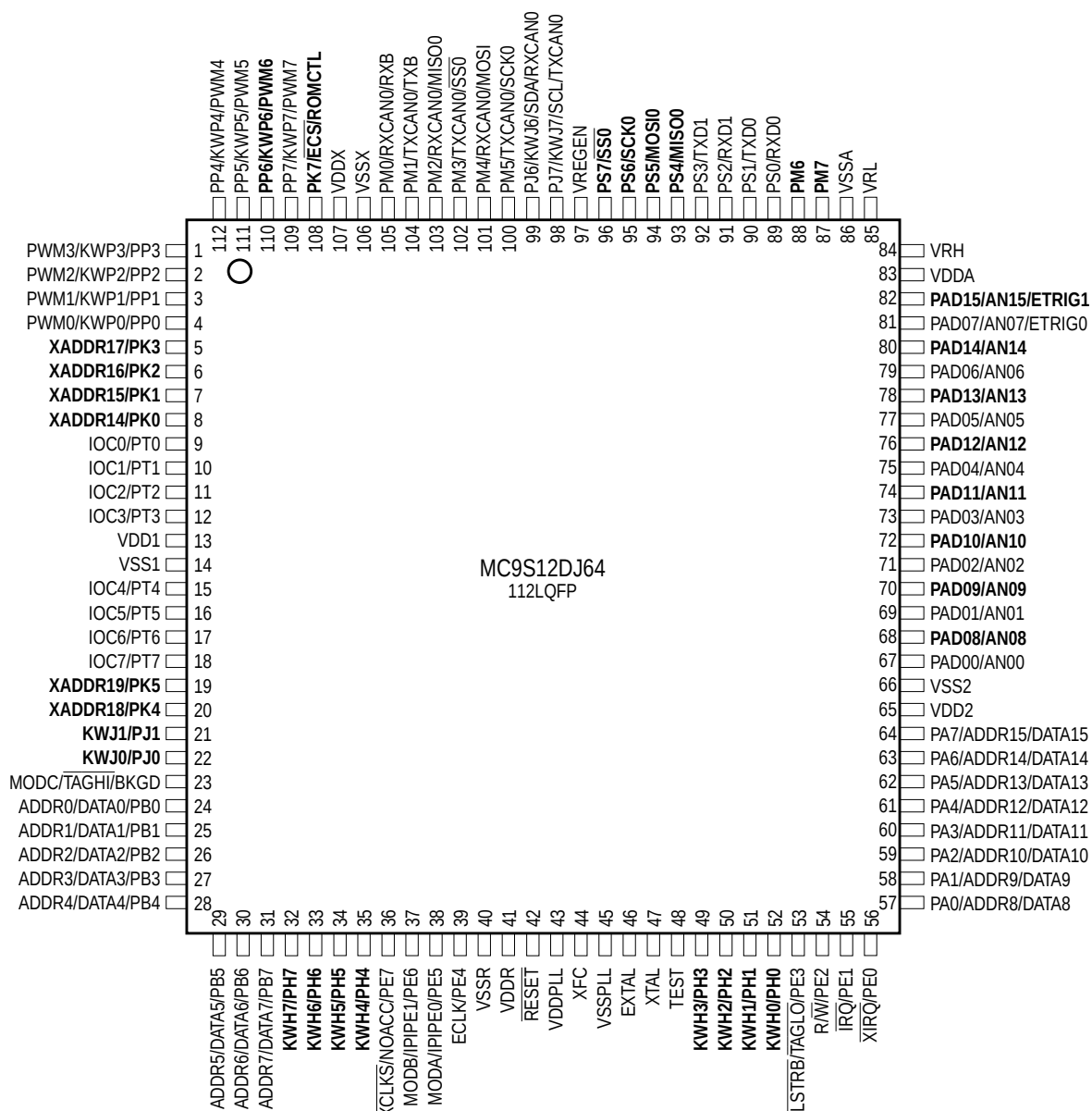
Bit 3-0: Minor - non full - mask set revision

2. 1L86D is identical to 2L86D except improved ESD performance on 2L86D

The device memory sizes are located in two 8-bit registers MEMSIZ0 and MEMSIZ1 (addresses \$001C and \$001D after reset). **Table 1-5** shows the read-only values of these registers. Refer to HCS12 Module Mapping Control (MMC) Block Guide for further details.

Table 1-5 Memory size registers

Register name	Value
MEMSIZ0	\$11
MEMSIZ1	\$80



Signals shown in **Bold** are not available on the 80 Pin Package

Figure 2-1 Pin Assignments in 112-pin LQFP for MC9S12DJ64

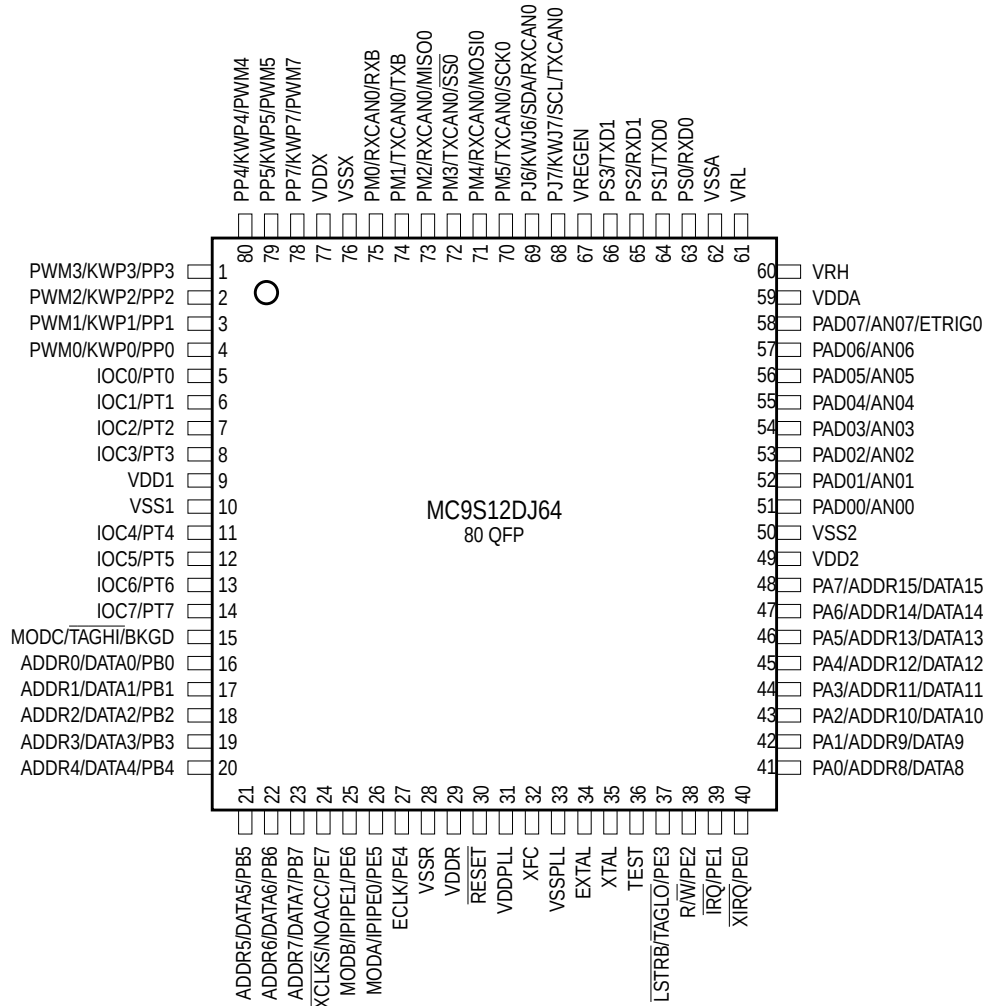
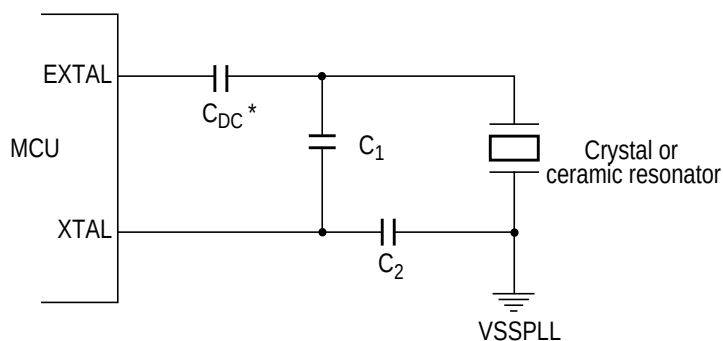


Figure 2-2 Pin Assignments in 80-pin QFP for MC9S12DJ64 and MC9S12D32

2.2 Signal Properties Summary

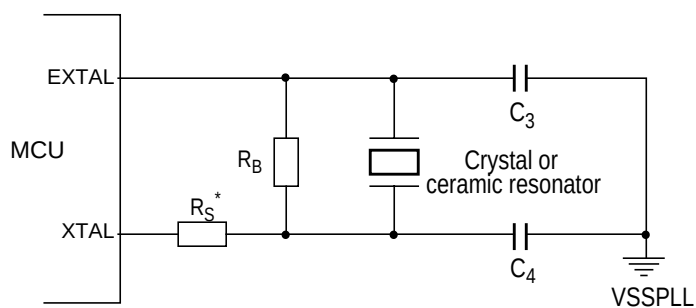
Table 2-1 summarizes the pin functionality. Signals shown in **bold** are not available in the 80 pin package.



* Due to the nature of a translated ground Colpitts oscillator a DC voltage bias is applied to the crystal

Please contact the crystal manufacturer for crystal DC bias conditions and recommended capacitor value C_{DC} .

Figure 2-4 Colpitts Oscillator Connections (PE7=1)



* R_S can be zero (shorted) when used with higher frequency crystals. Refer to manufacturer's data.

Figure 2-5 Pierce Oscillator Connections (PE7=0)

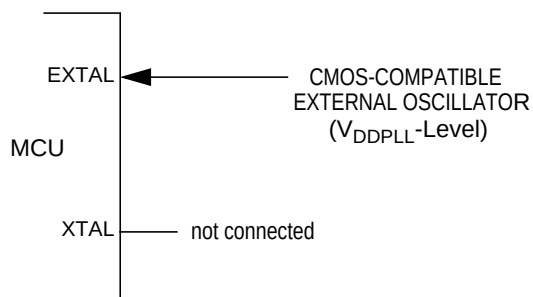


Figure 2-6 External Clock Connections (PE7=0)

Mnemonic	Pin Number	Nominal Voltage	Description
	112-pin QFP		
VDDPLL	43	2.5V	Provides operating voltage and ground for the Phased-Locked Loop. This allows the supply voltage to the PLL to be bypassed independently. Internal power and ground generated by internal regulator.
VSSPLL	45	0V	
VREGEN	97	5.0V	Internal Voltage Regulator enable/disable

2.4.1 VDDX, VSSX — Power & Ground Pins for I/O Drivers

External power and ground for I/O drivers. Because fast signal transitions place high, short-duration current demands on the power supply, use bypass capacitors with high-frequency characteristics and place them as close to the MCU as possible. Bypass requirements depend on how heavily the MCU pins are loaded.

VDDX and VSSX are the supplies for Ports J, K, M, P, T and S.

2.4.2 VDDR, VSSR — Power & Ground Pins for I/O Drivers & for Internal Voltage Regulator

External power and ground for I/O drivers and input to the internal voltage regulator. Because fast signal transitions place high, short-duration current demands on the power supply, use bypass capacitors with high-frequency characteristics and place them as close to the MCU as possible. Bypass requirements depend on how heavily the MCU pins are loaded.

VDDR and VSSR are the supplies for Ports A, B, E and H.

2.4.3 VDD1, VDD2, VSS1, VSS2 — Internal Logic Power Supply Pins

Power is supplied to the MCU through VDD and VSS. Because fast signal transitions place high, short-duration current demands on the power supply, use bypass capacitors with high-frequency characteristics and place them as close to the MCU as possible. This 2.5V supply is derived from the internal voltage regulator. There is no static load on those pins allowed. The internal voltage regulator is turned off, if VREGEN is tied to ground.

NOTE: No load allowed except for bypass capacitors.

2.4.4 VDDA, VSSA — Power Supply Pins for ATD0/ATD1 and VREG

VDDA, VSSA are the power supply and ground input pins for the voltage regulator and the two analog to digital converters. It also provides the reference for the internal voltage regulator. This allows the supply voltage to ATD0/ATD1 and the reference voltage to be bypassed independently.

Section 3 System Clock Description

3.1 Overview

The Clock and Reset Generator provides the internal clock signals for the HCS12 Core and all peripheral modules. **Figure 3-1** shows the clock connections from the CRG to all modules.

Consult the CRG Block User Guide and OSC Block User Guide for details on clock generation.

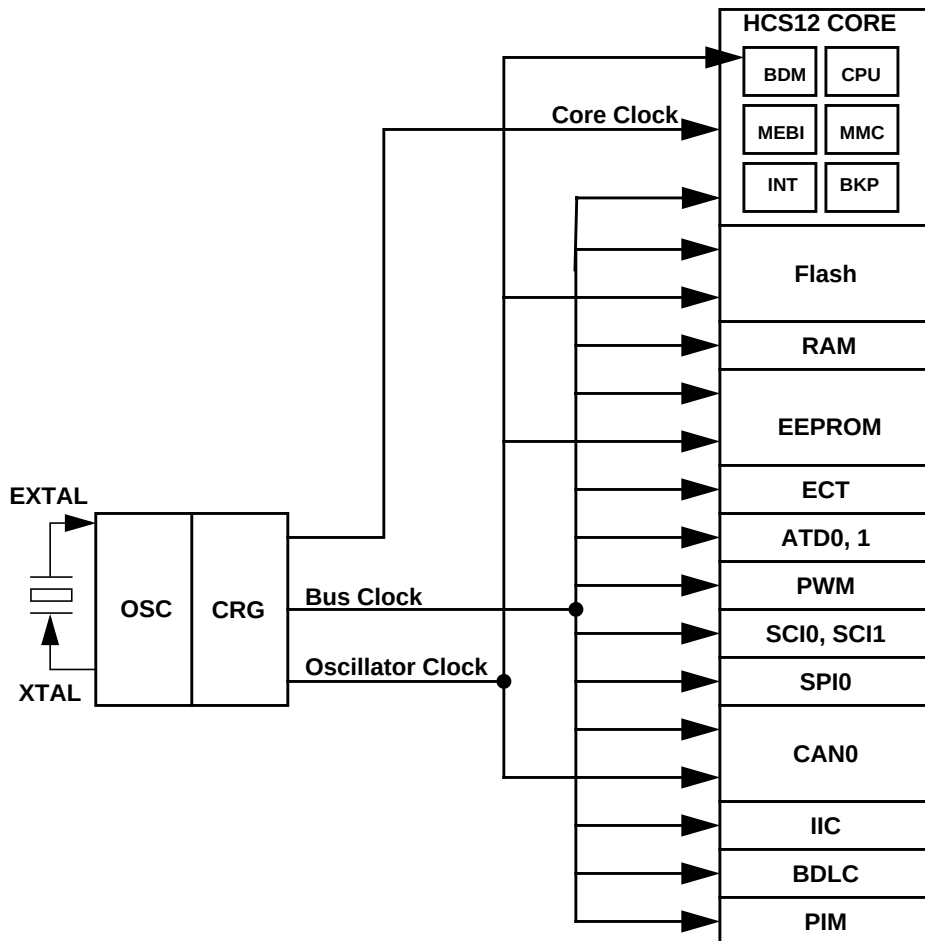


Figure 3-1 Clock Connections

Section 5 Resets and Interrupts

5.1 Overview

Consult the Exception Processing section of the CPU12 Reference Manual for information on resets and interrupts.

5.2 Vectors

5.2.1 Vector Table

Table 5-1 lists interrupt sources and vectors in default order of priority.

Table 5-1 Interrupt Vector Locations

Vector Address	Interrupt Source	CCR Mask	Local Enable	HPRIO Value to Elevate
\$FFFE, \$FFFF	Reset	None	None	—
\$FFFC, \$FFFD	Clock Monitor fail reset	None	PLLCTL (CME, SCME)	—
\$FFFA, \$FFFB	COP failure reset	None	COP rate select	—
\$FFF8, \$FFF9	Unimplemented instruction trap	None	None	—
\$FFF6, \$FFF7	SWI	None	None	—
\$FFF4, \$FFF5	XIRQ	X-Bit	None	—
\$FFF2, \$FFF3	IRQ	I-Bit	IRQCR (IRQEN)	\$F2
\$FFF0, \$FFF1	Real Time Interrupt	I-Bit	CRGINT (RTIE)	\$F0
\$FFEE, \$FFEF	Enhanced Capture Timer channel 0	I-Bit	TIE (C0I)	\$EE
\$FFEC, \$FFED	Enhanced Capture Timer channel 1	I-Bit	TIE (C1I)	\$EC
\$FFEA, \$FFEB	Enhanced Capture Timer channel 2	I-Bit	TIE (C2I)	\$EA
\$FFE8, \$FFE9	Enhanced Capture Timer channel 3	I-Bit	TIE (C3I)	\$E8
\$FFE6, \$FFE7	Enhanced Capture Timer channel 4	I-Bit	TIE (C4I)	\$E6
\$FFE4, \$FFE5	Enhanced Capture Timer channel 5	I-Bit	TIE (C5I)	\$E4
\$FFE2, \$FFE3	Enhanced Capture Timer channel 6	I-Bit	TIE (C6I)	\$E2
\$FFE0, \$FFE1	Enhanced Capture Timer channel 7	I-Bit	TIE (C7I)	\$E0
\$FFDE, \$FFDF	Enhanced Capture Timer overflow	I-Bit	TSRC2 (TOI)	\$DE
\$FFDC, \$FFDD	Pulse accumulator A overflow	I-Bit	PACTL (PAOVI)	\$DC
\$FFDA, \$FFDB	Pulse accumulator input edge	I-Bit	PACTL (PAI)	\$DA
\$FFD8, \$FFD9	SPI0	I-Bit	SPICR1 (SPIE, SPTIE)	\$D8
\$FFD6, \$FFD7	SCI0	I-Bit	SCICR2 (TIE, TCIE, RIE, ILIE)	\$D6
\$FFD4, \$FFD5	SCI1	I-Bit	SCICR2 (TIE, TCIE, RIE, ILIE)	\$D4
\$FFD2, \$FFD3	ATD0	I-Bit	ATDCTL2 (ASCIE)	\$D2
\$FFD0, \$FFD1	ATD1	I-Bit	ATDCTL2 (ASCIE)	\$D0
\$FFCE, \$FFCF	Port J	I-Bit	PIEJ (PIEJ7, PIEJ6, PIEJ1, PIEJ0)	\$CE
\$FFCC, \$FFCD	Port H	I-Bit	PIEH (PIEH7-0)	\$CC

Figure 22-1 Recommended PCB Layout 112LQFP Colpitts Oscillator

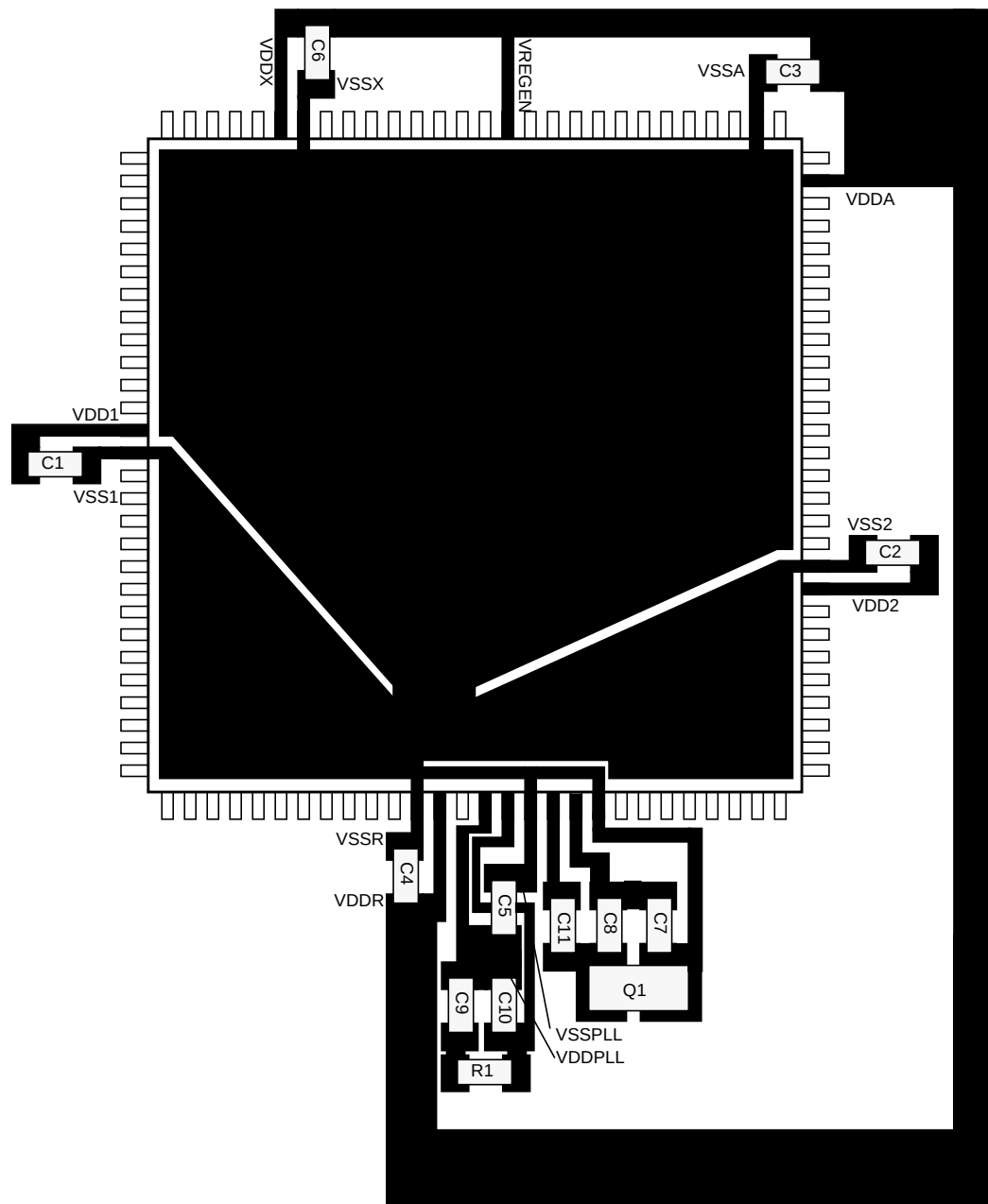
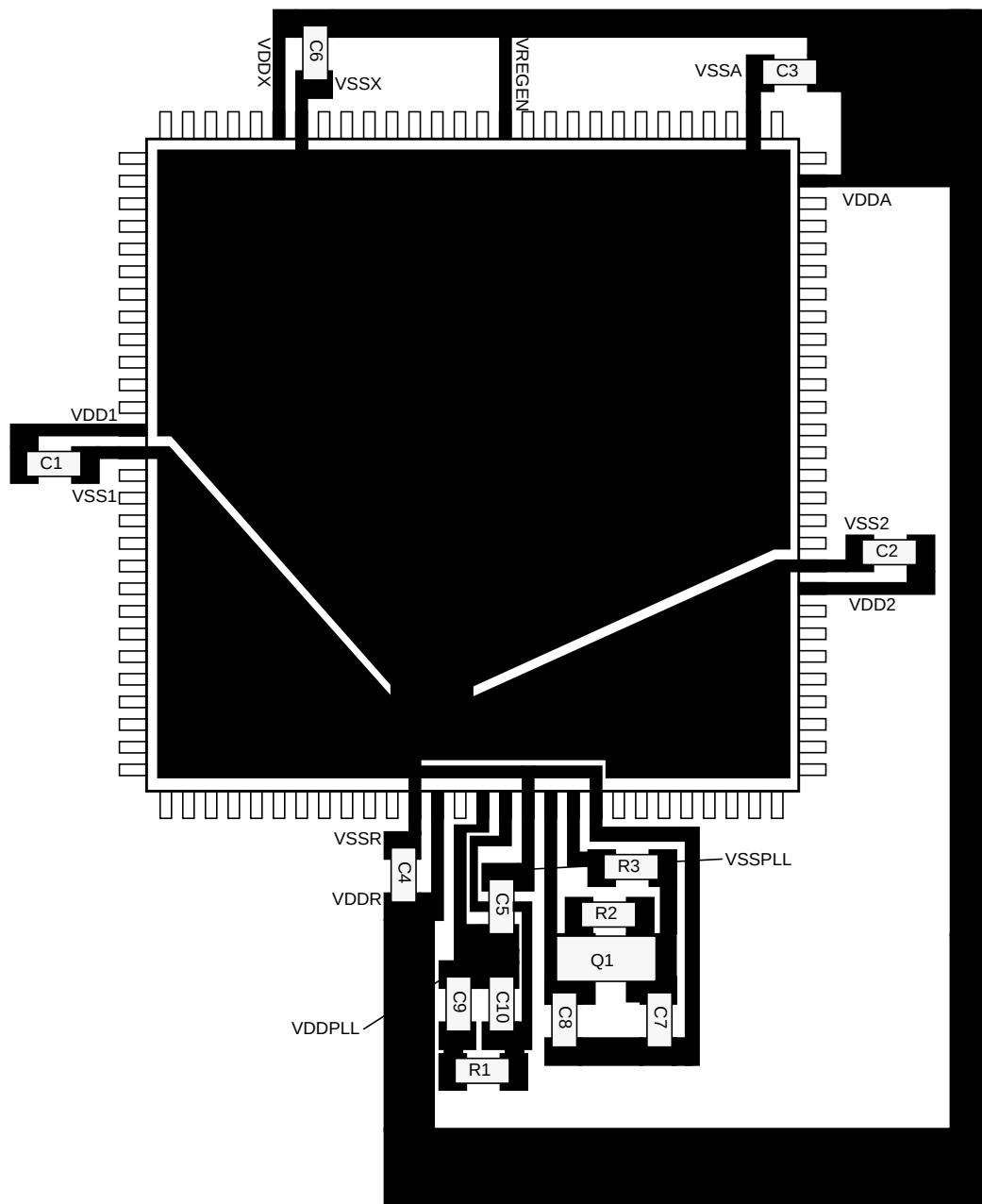


Figure 22-3 Recommended PCB Layout for 112LQFP Pierce Oscillator



T_A = Ambient Temperature, [°C]

P_D = Total Chip Power Dissipation, [W]

Θ_{JA} = Package Thermal Resistance, [°C/W]

The total power dissipation can be calculated from:

$$P_D = P_{INT} + P_{IO}$$

P_{INT} = Chip Internal Power Dissipation, [W]

Two cases with internal voltage regulator enabled and disabled must be considered:

1. Internal Voltage Regulator disabled

$$P_{INT} = I_{DD} \cdot V_{DD} + I_{DDPLL} \cdot V_{DDPLL} + I_{DDA} \cdot V_{DDA}$$

$$P_{IO} = \sum_i R_{DS(on)} \cdot I_{IO_i}^2$$

P_{IO} is the sum of all output currents on I/O ports associated with VDDX and VDDR.

For $R_{DS(on)}$ is valid:

$$R_{DS(on)} = \frac{V_{OL}}{I_{OL}}; \text{for outputs driven low}$$

respectively

$$R_{DS(on)} = \frac{V_{DD5} - V_{OH}}{I_{OH}}; \text{for outputs driven high}$$

2. Internal voltage regulator enabled

$$P_{INT} = I_{DDR} \cdot V_{DDR} + I_{DDA} \cdot V_{DDA}$$

I_{DDR} is the current shown in **Table A-7** and not the overall current flowing into VDDR, which additionally contains the current flowing into the external loads with output high.

$$P_{IO} = \sum_i R_{DS(on)} \cdot I_{IO_i}^2$$

P_{IO} is the sum of all output currents on I/O ports associated with VDDX and VDDR.

NOTES:

1. Depending on the crystal a damping series resistor might be necessary
2. $f_{osc} = 4\text{MHz}$, $C = 22\text{pF}$.
3. Maximum value is for extreme cases using high Q, low frequency crystals
4. Only valid if Pierce oscillator/external clock mode is selected

A.5.3 Phase Locked Loop

The oscillator provides the reference clock for the PLL. The PLL's Voltage Controlled Oscillator (VCO) is also the system clock source in self clock mode.

A.5.3.1 XFC Component Selection

This section describes the selection of the XFC components to achieve a good filter characteristics.

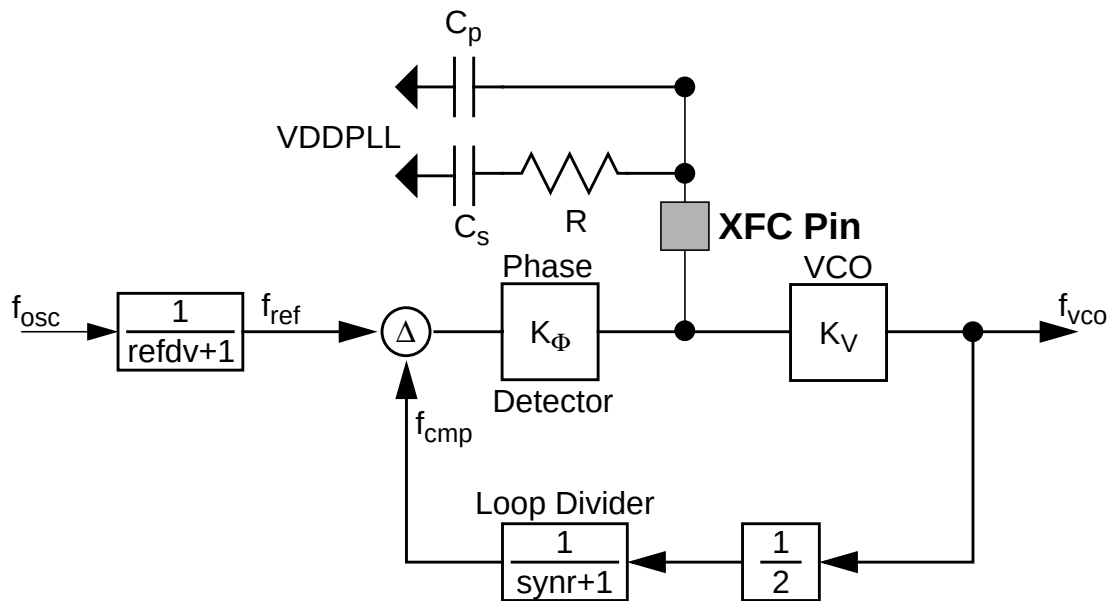


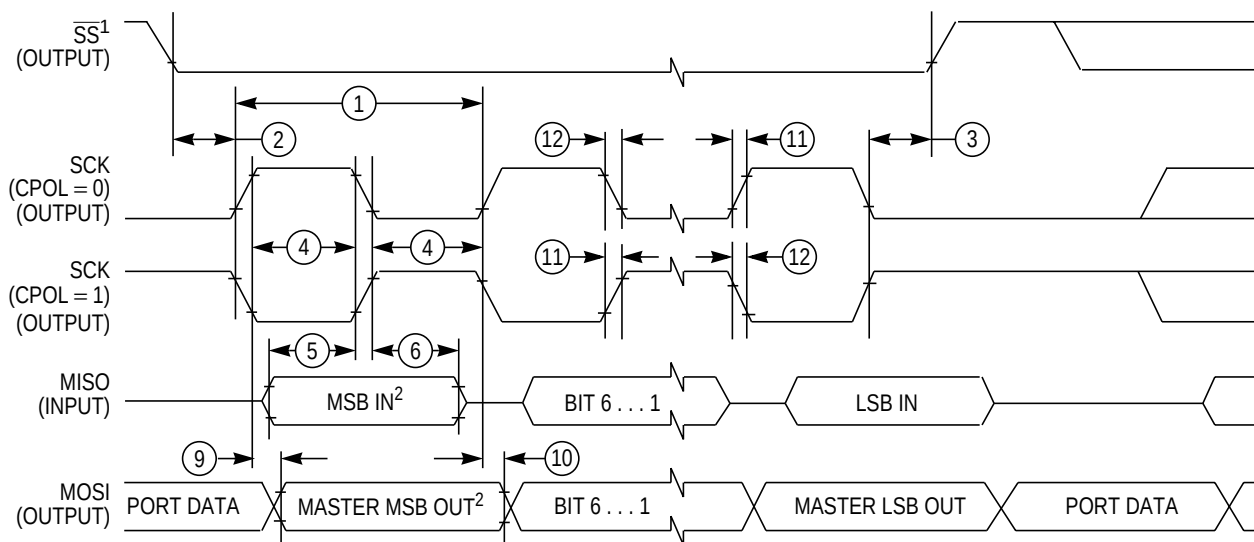
Figure A-2 Basic PLL functional diagram

The following procedure can be used to calculate the resistance and capacitance values using typical values for K_1 , f_1 and i_{ch} from **Table A-16**.

The grey boxes show the calculation for $f_{VCO} = 50\text{MHz}$ and $f_{ref} = 1\text{MHz}$. E.g., these frequencies are used for $f_{OSC} = 4\text{MHz}$ and a 25MHz bus clock.

The VCO Gain at the desired VCO frequency is approximated by:

$$K_V = K_1 \cdot e^{\frac{(f_1 - f_{VCO})}{K_1 \cdot 1V}} = -100 \cdot e^{\frac{(60 - 50)}{-100}} = -90.48\text{MHz/V}$$



1. If configured as output

2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure A-6 SPI Master Timing (CPHA = 1)

Table A-18 SPI Master Mode Timing Characteristics¹

Conditions are shown in Table A-4 unless otherwise noted, $C_{LOAD} = 200pF$ on all outputs							
Num	C	Rating	Symbol	Min	Typ	Max	Unit
1	P	Operating Frequency	f_{op}	DC		1/2	f_{bus}
1	P	SCK Period $t_{sck} = 1/f_{op}$	t_{sck}	4		2048	t_{bus}
2	D	Enable Lead Time	t_{lead}	1/2		—	t_{sck}
3	D	Enable Lag Time	t_{lag}	1/2			t_{sck}
4	D	Clock (SCK) High or Low Time	t_{wsck}	$t_{bus} - 30$		1024 t_{bus}	ns
5	D	Data Setup Time (Inputs)	t_{su}	25			ns
6	D	Data Hold Time (Inputs)	t_{hi}	0			ns
9	D	Data Valid (after SCK Edge)	t_v			25	ns
10	D	Data Hold Time (Outputs)	t_{ho}	0			ns
11	D	Rise Time Inputs and Outputs	t_r			25	ns
12	D	Fall Time Inputs and Outputs	t_f			25	ns

NOTES:

1. The numbers 7, 8 in the column labeled "Num" are missing. This has been done on purpose to be consistent between the Master and the Slave timing shown in **Table A-19**.

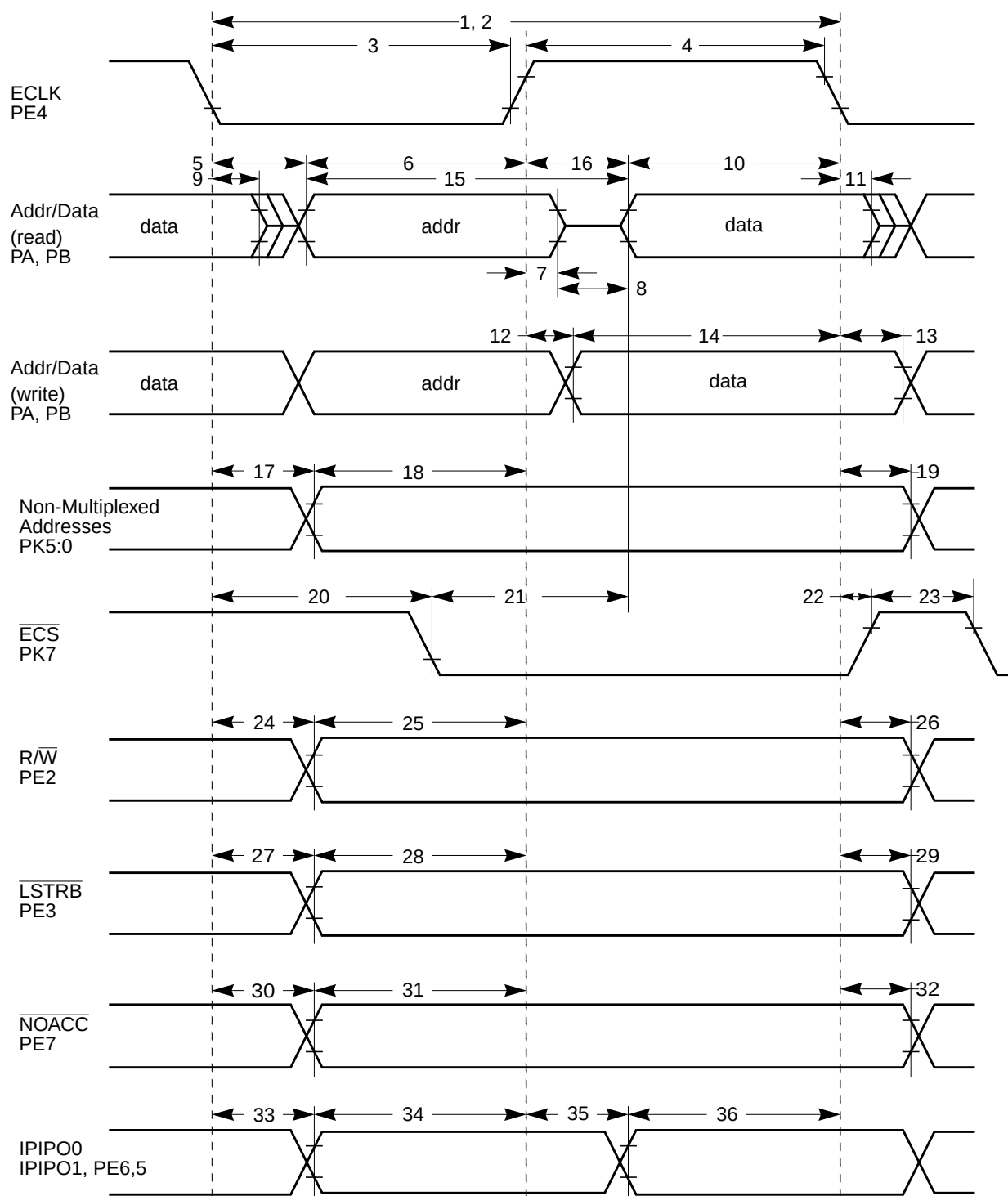


Figure A-9 General External Bus Timing

Table A-20 Expanded Bus Timing Characteristics

Conditions are shown in Table A-4 unless otherwise noted, $C_{LOAD} = 50\text{pF}$							
Num	C	Rating	Symbol	Min	Typ	Max	Unit
1	P	Frequency of operation (E-clock)	f_o	0		25.0	MHz
2	P	Cycle time	t_{cyc}	40			ns
3	D	Pulse width, E low	PW_{EL}	19			ns
4	D	Pulse width, E high ¹	PW_{EH}	19			ns
5	D	Address delay time	t_{AD}			8	ns
6	D	Address valid time to E rise ($PW_{EL}-t_{AD}$)	t_{AV}	11			ns
7	D	Muxed address hold time	t_{MAH}	2			ns
8	D	Address hold to data valid	t_{AHDS}	7			ns
9	D	Data hold to address	t_{DHA}	2			ns
10	D	Read data setup time	t_{DSR}	13			ns
11	D	Read data hold time	t_{DHR}	0			ns
12	D	Write data delay time	t_{DDW}			7	ns
13	D	Write data hold time	t_{DHW}	2			ns
14	D	Write data setup time ¹ ($PW_{EH}-t_{DDW}$)	t_{DSW}	12			ns
15	D	Address access time ¹ ($t_{cyc}-t_{AD}-t_{DSR}$)	t_{ACCA}	19			ns
16	D	E high access time ¹ ($PW_{EH}-t_{DSR}$)	t_{ACCE}	6			ns
17	D	Non-multiplexed address delay time	t_{NAD}			6	ns
18	D	Non-muxed address valid to E rise ($PW_{EL}-t_{NAD}$)	t_{NAV}	15			ns
19	D	Non-multiplexed address hold time	t_{NAH}	2			ns
20	D	Chip select delay time	t_{CSD}			16	ns
21	D	Chip select access time ¹ ($t_{cyc}-t_{CSD}-t_{DSR}$)	t_{ACCS}	11			ns
22	D	Chip select hold time	t_{CSH}	2			ns
23	D	Chip select negated time	t_{CSN}	8			ns
24	D	Read/write delay time	t_{RWD}			7	ns
25	D	Read/write valid time to E rise ($PW_{EL}-t_{RWD}$)	t_{RWV}	14			ns
26	D	Read/write hold time	t_{RWH}	2			ns
27	D	Low strobe delay time	t_{LSD}			7	ns
28	D	Low strobe valid time to E rise ($PW_{EL}-t_{LSD}$)	t_{LSV}	14			ns
29	D	Low strobe hold time	t_{LSH}	2			ns
30	D	NOACC strobe delay time	t_{NOD}			7	ns
31	D	NOACC valid time to E rise ($PW_{EL}-t_{NOD}$)	t_{NOV}	14			ns

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