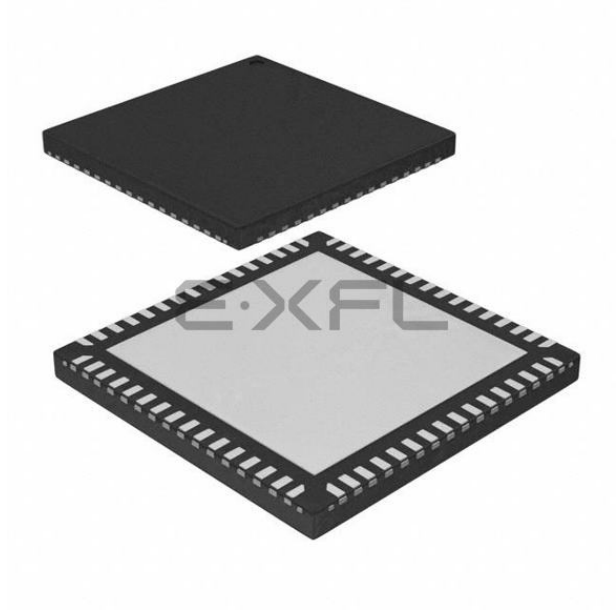

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I²C, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	50
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.62V ~ 3.63V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsaml22j18a-mut

1. Description

Atmel | SMART SAM L22 is a series of Ultra low-power segment LCD microcontrollers using the 32-bit ARM® Cortex®-M0+ processor, ranging from 48- to 100-pins with up to 256KB Flash and 32KB of SRAM and can drive up to 320 LCD segments. The SAM L22 devices operate at a maximum frequency of 32MHz and reach 2.46 Coremark/MHz. They are designed for simple and intuitive migration with identical peripheral modules, hex compatible code, identical linear address map and pin compatible migration paths between all devices in the product series. All devices include intelligent and flexible peripherals, Atmel Event System for inter-peripheral signaling, and support for capacitive touch button, slider and wheel user interfaces.

The Atmel SAM L22 devices provide the following features: Segment LCD (SLCD) controller with up to 48 selectable SLCD pins from max. 52 pins to drive up to 320 segments, all SLCD Pins can be used also as GPIOs (100-pin package: 8 of the SLCD pins can be used only as GP input), in-system programmable Flash, sixteen-channel direct memory access (DMA) controller, 8 channel Event System, programmable interrupt controller, up to 82 programmable I/O pins, 32-bit real-time clock and calendar, up to four 16-bit Timer/Counters (TC) and one 24-bit Timer/Counters for Control (TCC), where each TC can be configured to perform frequency and waveform generation, accurate program execution timing or input capture with time and frequency measurement of digital signals. The TCs can operate in 8- or 16-bit mode, selected TCs can be cascaded to form a 32-bit TC, and the TCC has extended functions optimized for motor, lighting and other control applications. The series provide one full-speed USB 2.0 device interface; up to six Serial Communication Modules (SERCOM) that each can be configured to act as an USART, UART, SPI, I^2C up to 3.4MHz, SMBus, PMBus, and ISO7816 smart card interface; up to twenty channel 1Msps 12-bit ADC with optional oversampling and decimation supporting up to 16-bit resolution, two analog comparators with window mode, Peripheral Touch Controller supporting up to 256 buttons, sliders, wheels and proximity sensing; programmable Watchdog Timer, brown-out detector and power-on reset and two-pin Serial Wire Debug (SWD) program and debug interface.

All devices have accurate and low-power external and internal oscillators. All oscillators can be used as a source for the system clock. Different clock domains can be independently configured to run at different frequencies, enabling power saving by running each peripheral at its optimal clock frequency, and thus maintaining a high CPU frequency while reducing power consumption.

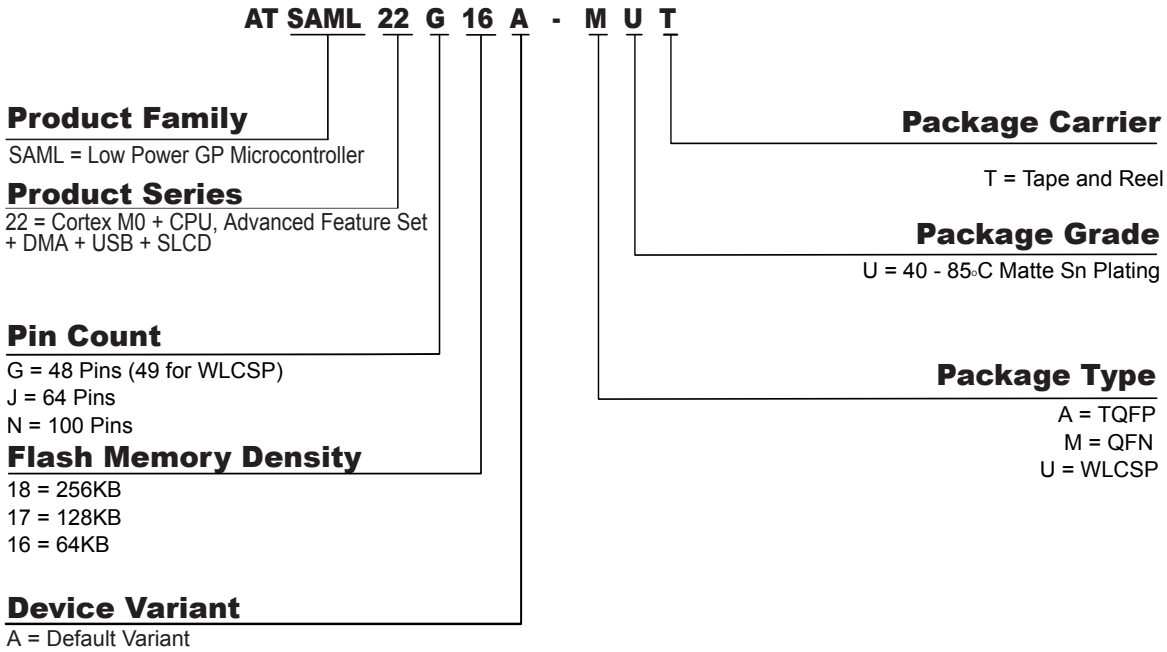
The SAM L22 devices have four software-selectable sleep modes, idle, standby, backup and off. In idle mode the CPU is stopped while all other functions can be kept running. In standby all clocks and functions are stopped expect those selected to continue running. In this mode all RAMs and logic contents are retained. The device supports SleepWalking. This feature allows the peripheral to wake up from sleep based on predefined conditions, and thus allows some internal operation like DMA transfer and/or the CPU to wake up only when needed, e.g. when a threshold is crossed or a result is ready. The Event System supports synchronous and asynchronous events, allowing peripherals to receive, react to and send events even in standby mode.

The SAM L22 devices have two software-selectable performance level (PL0 and PL2) allowing the user to scale the lowest core voltage level that will support the operating frequency.

The Flash program memory can be reprogrammed in-system through the SWD interface. The same interface can be used for nonintrusive on-chip debugging of application code. A boot loader running in the device can use any communication interface to download and upgrade the application program in the Flash memory.

The Atmel SAM L22 devices are supported with a full suite of program and system development tools, including C compilers, macro assemblers, program debugger/simulators, programmers and evaluation kits.

3. Ordering Information



Note: The device variant (last letter of the ordering number) is independent of the die revision (DSU.DID.REVISION): The device variant denotes functional differences, whereas the die revision marks evolution of the die.

3.1. SAM L22N

Table 3-1. SAM L22N Ordering Codes

Ordering Code	FLASH (bytes)	SRAM (bytes)	Package	Carrier Type
ATSAML22N16A-AUT	64K	8K	TQFP100	Tape & Reel
ATSAML22N17A-AUT	128K	16K	TQFP100	Tape & Reel
ATSAML22N18A-AUT	256K	32K	TQFP100	Tape & Reel

3.2. SAM L22J

Table 3-2. SAM L22J Ordering Codes

Ordering Code	FLASH (bytes)	SRAM (bytes)	Package	Carrier Type
ATSAML22J16A-AUT	64K	8K	TQFP64	Tape & Reel
ATSAML22J16A-MUT			QFN64	
ATSAML22J17A-AUT	128K	16K	TQFP64	Tape & Reel
ATSAML22J17A-MUT			QFN64	

Ordering Code	FLASH (bytes)	SRAM (bytes)	Package	Carrier Type
ATSAML22J18A-AUT	256K	32K	TQFP64	Tape & Reel
ATSAML22J18A-MUT			QFN64	

3.3. SAM L22G

Table 3-3. SAM L22G Ordering Codes

Ordering Code	FLASH (bytes)	SRAM (bytes)	Package	Carrier Type
ATSAML22G16A-AUT	64K	8K	TQFP48	Tape & Reel
ATSAML22G16A-MUT			QFN48	
ATSAML22G17A-AUT	128K	16K	TQFP48	Tape & Reel
ATSAML22G17A-MUT			QFN48	
ATSAML22G17A-UUT			WLCSP49	
ATSAML22G18A-AUT	256K	32K	TQFP48	Tape & Reel
ATSAML22G18A-MUT			QFN48	
ATSAML22G18A-UUT			WLCSP49	

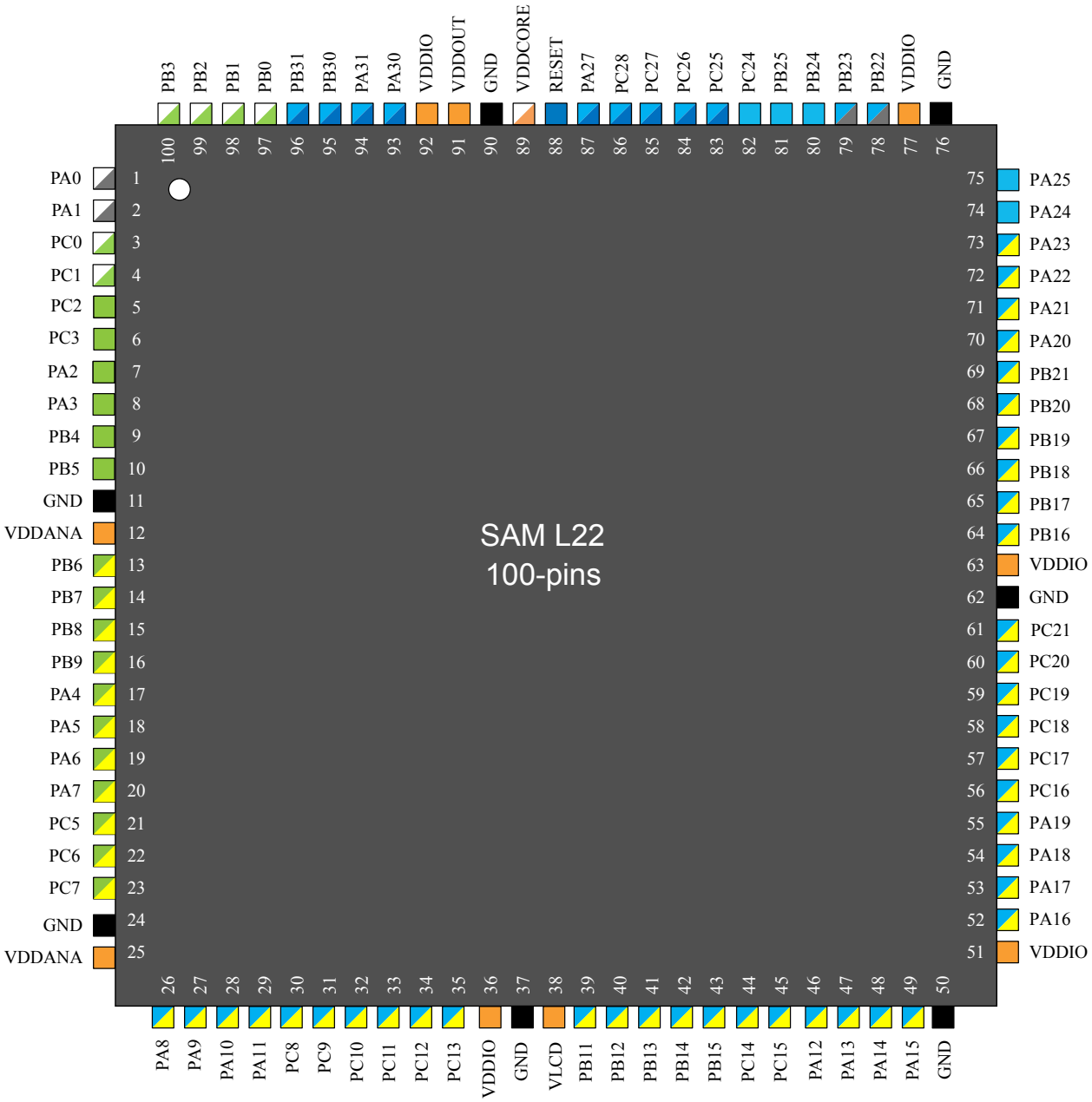
3.4. Device Identification

The DSU - Device Service Unit peripheral provides the Device Selection bits in the Device Identification register (DID.DEVSEL) in order to identify the device by software. The SAM L22 variants have a reset value of DID=0x10820xxx, with the last digits identifying the variant:

Table 3-4. SAM L22 Device Identification Values

DSU DID.DEVSEL	Device
0x0	L22N18
0x1	L22N17
0x2	L22N16
0x3-0x4	Reserved
0x5	L22J18
0x6	L22J17
0x7	L22J16
0x8-0x9	Reserved
0xA	L22G18
0xB	L22G17
0xC	L22G16
0xD-0xFF	Reserved

5.3. SAM L22N


SAM L22
100-pins
PB3 100
PB2 99
PB1 98
PB0 97
PB31 96
PB30 95
PA31 94
PA30 93
VDDIO 92
VDDOUT 91
GND 90
VDDCORE 89
RESET 88
PA27 87
PC28 86
PC27 85
PC26 84
PC25 83
PC24 82
PB25 81
PB24 80
PB23 79
PB22 78
VDDIO 77
GND 76
PA0 1
PA1 2
PC0 3
PC1 4
PC2 5
PC3 6
PA2 7
PA3 8
PB4 9
PB5 10
GND 11
VDDANA 12
PB6 13
PB7 14
PB8 15
PB9 16
PA4 17
PA5 18
PA6 19
PA7 20
PC5 21
PC6 22
PC7 23
GND 24
VDDANA 25
75 PA25
74 PA24
73 PA23
72 PA22
71 PA21
70 PA20
69 PB21
68 PB20
67 PB19
66 PB18
65 PB17
64 PB16
63 VDDIO
62 GND
61 PC21
60 PC20
59 PC19
58 PC18
57 PC17
56 PC16
55 PA19
54 PA18
53 PA17
52 PA16
51 VDDIO
26 PA8
27 PA9
28 PA10
29 PA11
30 PC8
31 PC9
32 PC10
33 PC11
34 PC12
35 PC13
36 VDDIO
37 GND
38 VLCD
39 PB11
40 PB12
41 PB13
42 PB14
43 PB15
44 PC14
45 PC15
46 PA12
47 PA13
48 PA14
49 PA15
50 GND

6. Signal Descriptions List

The following table gives details on signal names classified by peripheral.

Table 6-1. Signal Descriptions List

Signal Name	Function	Type	Active Level
Analog Comparators - AC			
AIN[3:0]	AC Analog Inputs	Analog	
CMP[1:0]	AC Analog Output	Analog	
Analog Digital Converter - ADC			
AIN[19:0]	ADC Analog Inputs	Analog	
VREFA	ADC Voltage External Reference A	Analog	
VREFB	ADC Voltage External Reference B	Analog	
External Interrupt Controller - EIC			
EXTINT[15:0]	External Interrupts inputs	Digital	
NMI	External Non-Maskable Interrupt input	Digital	
Generic Clock Generator - GCLK			
GCLK_IO[4:0]	Generic Clock (source clock inputs or generic clock generator output)	Digital	
Custom Control Logic - CCL			
IN[11:0]	Logic Inputs	Digital	
OUT[3:0]	Logic Outputs	Digital	
Supply Controller - SUPC			
VBAT	External battery supply Inputs	Analog	
PSOK	Main Power Supply OK input	Digital	
OUT[1:0]	Logic Outputs	Digital	
Power Manager - PM			
RESETN	Reset input	Digital	Low
Serial Communication Interface - SERCOMx			
PAD[3:0]	SERCOM Inputs/Outputs Pads	Digital	
Oscillators Control - OSCCTRL			
XIN	Crystal or external clock Input	Analog/Digital	
XOUT	Crystal Output	Analog	

Function	-				A	B					C	D	E		F	H	I
Type	L22G[5]	L22J	L22N	Pad Name	EIC	ANAREF	ADC	AC	PTC	SLCD	SERCOM[6]	SERCOM[6]	TC/TCC	TCC/RTC	COM/RTC	AC/ GCLK/ SUPC	CCL
digital: input only			30	PC08	EIC/EXTINT[0]					SLCD/ LP[15]							
			31	PC09	EIC/EXTINT[1]					SLCD/ LP[16]							
			32	PC10	EIC/EXTINT[2]					SLCD/ LP[17]	SERCOM1/ PAD[2]						
			33	PC11	EIC/EXTINT[3]					SLCD/ LP[18]	SERCOM1/ PAD[3]						
			34	PC12	EIC/EXTINT[4]					SLCD/ LP[19]	SERCOM1/ PAD[0]						
			35	PC13	EIC/EXTINT[5]					SLCD/ LP[20]	SERCOM1/ PAD[1]						
	19	23	38	VLCD													
	20	24	39	PB11	EIC/EXTINT[11]					SLCD/ LP[21]		SERCOM3/ PAD[3]	TC/1/ WO[1]	TCC/ WO[5]			CCL/ OUT[1]
I2C: full Fm+. Limited currents for Sm, Fm		25	40	PB12	EIC/EXTINT[12]					SLCD/ LP[22]	SERCOM3/ PAD[0]		TC/0/ WO[0]	TCC/ WO[6]			
		26	41	PB13	EIC/EXTINT[13]					SLCD/ LP[23]	SERCOM3/ PAD[1]		TC/0/ WO[1]	TCC/ WO[7]			
		27	42	PB14	EIC/EXTINT[14]					SLCD/ LP[24]	SERCOM3/ PAD[2]		TC/1/ WO[0]			GCLK/ IO[0]	CCL/IN[9]
		28	43	PB15	EIC/EXTINT[15]					SLCD/ LP[25]	SERCOM3/ PAD[3]		TC/1/ WO[1]			GCLK/ IO[1]	CCL/ IN[10]
			44	PC14	EIC/EXTINT[6]					SLCD/ LP[26]							
			45	PC15	EIC/EXTINT[7]					SLCD/ LP[27]							
I2C: Sm, Fm, Fm+	21	29	46	PA12	EIC/EXTINT[12]					SLCD/ LP[28]	SERCOM4/ PAD[0]	SERCOM3/ PAD[0]		TCC/ WO[6]		AC/ CMP[0]	
	22	30	47	PA13	EIC/EXTINT[13]					SLCD/ LP[29]	SERCOM4/ PAD[1]	SERCOM3/ PAD[1]		TCC/ WO[7]		AC/ CMP[1]	
	23	31	48	PA14	EIC/EXTINT[14]					SLCD/ LP[30]	SERCOM4/ PAD[2]	SERCOM3/ PAD[2]		TCC/ WO[4]		GCLK/ IO[0]	
	24	32	49	PA15	EIC/EXTINT[15]					SLCD/ LP[31]	SERCOM4/ PAD[3]	SERCOM3/ PAD[3]		TCC/ WO[5]		GCLK/ IO[1]	
	25	35	52	PA16	EIC/EXTINT[0]				PTC/ X[28]	SLCD/ LP[32]	SERCOM1/ PAD[0]	SERCOM2/ PAD[0]		TCC/ WO[6]		GCLK/ IO[2]	CCL/IN[0]
	26	36	53	PA17	EIC/EXTINT[1]				PTC/ X[29]	SLCD/ LP[33]	SERCOM1/ PAD[1]	SERCOM2/ PAD[1]		TCC/ WO[7]		GCLK/ IO[3]	CCL/IN[1]
	27	37	54	PA18	EIC/EXTINT[2]				PTC/ X[30]	SLCD/ LP[34]	SERCOM1/ PAD[2]	SERCOM2/ PAD[2]		TCC/ WO[2]		AC/ CMP[0]	CCL/IN[2]
	28	38	55	PA19	EIC/EXTINT[3]				PTC/ X[31]	SLCD/ LP[35]	SERCOM1/ PAD[3]	SERCOM2/ PAD[3]		TCC/ WO[3]		AC/ CMP[1]	CCL/ OUT[0]
			56	PC16	EIC/EXTINT[8]					SLCD/ LP[36]							
			57	PC17	EIC/EXTINT[9]					SLCD/ LP[37]							
digital: input only			58	PC18	EIC/EXTINT[10]					SLCD/ LP[38]							
			59	PC19	EIC/EXTINT[11]					SLCD/ LP[39]							
			60	PC20	EIC/EXTINT[12]					SLCD/ LP[40]							CCL/IN[9]
			61	PC21	EIC/EXTINT[13]					SLCD/ LP[41]							CCL/ IN[10]
		39	64	PB16	EIC/EXTINT[0]					SLCD/ LP[42]	SERCOM5/ PAD[0]		TC/2/ WO[0]	TCC/ WO[4]		GCLK/ IO[2]	CCL/IN[11]
		40	65	PB17	EIC/EXTINT[1]					SLCD/ LP[43]	SERCOM5/ PAD[1]		TC/2/ WO[1]	TCC/ WO[5]		GCLK/ IO[3]	CCL/ OUT[3]
			66	PB18	EIC/EXTINT[2]					SLCD/ LP[44]	SERCOM5/ PAD[2]	SERCOM3/ PAD[2]		TCC/ WO[0]			
			67	PB19	EIC/EXTINT[3]					SLCD/ LP[45]	SERCOM5/ PAD[3]	SERCOM3/ PAD[3]		TCC/ WO[1]			
			68	PB20	EIC/EXTINT[4]					SLCD/ LP[46]	SERCOM3/ PAD[0]	SERCOM5/ PAD[0]		TCC/ WO[2]			
			69	PB21	EIC/EXTINT[5]					SLCD/ LP[47]	SERCOM3/ PAD[1]	SERCOM5/ PAD[1]		TCC/ WO[3]			
	29	41	70	PA20	EIC/EXTINT[4]				PTC/ XY[16]	SLCD/ LP[48]	SERCOM0/ PAD[0]	SERCOM2/ PAD[2]	TC/3/ WO[0]	TCC/ WO[6]		GCLK/ IO[4]	
	30	42	71	PA21	EIC/EXTINT[5]				PTC/ XY[17]	SLCD/ LP[49]	SERCOM0/ PAD[1]	SERCOM2/ PAD[3]	TC/3/ WO[1]	TCC/ WO[7]			
I2C: Sm, Fm, Fm+	31	43	72	PA22	EIC/EXTINT[6]				PTC/ XY[18]	SLCD/ LP[50]	SERCOM0/ PAD[2]	SERCOM2/ PAD[0]	TC/0/ WO[0]	TCC/ WO[4]			CCL/IN[6]
	32	44	73	PA23	EIC/EXTINT[7]				PTC/ XY[19]	SLCD/ LP[51]	SERCOM0/ PAD[3]	SERCOM2/ PAD[1]	TC/0/ WO[1]	TCC/ WO[5]	USB/SOF_1KHZ		CCL/IN[7]
	33	45	74	PA24	EIC/EXTINT[12]						SERCOM2/ PAD[2]	SERCOM5/ PAD[0]	TC/1/ WO[0]	TCC/ WO[0]	USB/DM		CCL/IN[8]
	34	46	75	PA25	EIC/EXTINT[13]						SERCOM2/ PAD[3]	SERCOM5/ PAD[1]	TC/1/ WO[1]	TCC/ WO[1]	USB/DP		CCL/ OUT[2]
	37	49	78	PB22	EIC/EXTINT[6]						SERCOM0/ PAD[2]	SERCOM5/ PAD[2]	TC/3/ WO[0]	TCC/ WO[2]	USB/SOF_1KHZ	GCLK/ IO[0]	CCL/IN[0]

Table 7-2. Oscillator Pinout

Oscillator	Supply	Signal	I/O pin
XOSC	VDDIO	XIN	PB22
		XOUT	PB23
XOSC32K	VSWOUT	XIN32	PA00
		XOUT32	PA01

Note: In order to minimize the cycle-to-cycle jitter of the external oscillator, keep the neighboring pins as steady as possible. For neighboring pin details, refer to the Oscillator Pinout section.

Table 7-3. XOSC32K Jitter Minimization

Package	Steady Signal Recommended
L22N	PB00, PB01, PB02, PB03, PC00, PC01
L22J	PB00, PB01, PB02, PB03, PA02, PA03
L22G	PB02, PB03, PA02, PA03

7.2.2. Serial Wire Debug Interface Pinout

Only the SWCLK pin is mapped to the normal PORT functions. A debugger cold-plugging or hot-plugging detection will automatically switch the SWDIO port to the SWDIO function.

Table 7-4. Serial Wire Debug Interface Pinout

Signal	Supply	I/O pin
SWCLK	VDDIO	PA30
SWDIO	VDDIO	PA31

7.2.3. SERCOM USART and I²C Configurations

The SAM L22 has up to six instances of the serial communication interface (SERCOM) peripheral. The following table lists the supported communication protocols for each SERCOM instance.

Table 7-5. SERCOM USART and I²C Protocols

	SERCOM Instance					
Protocol	SERCOM0	SERCOM1	SERCOM2	SERCOM3	SERCOM4	SERCOM5
I²C	no	yes	yes	yes	yes	yes
I²C at 3.4MHz	no	yes	no	no	no	yes
USART including RS485 and ISO 7816	yes	yes	yes	yes	yes	yes
SPI	yes	yes	yes	yes	yes	yes

Note: Not all available I²C pins support I²C mode at 3.4MHz.

7.2.4. GPIO Pin Clusters

Table 7-6. GPIO Clusters

Package	Cluster	GPIO	Supplies Pin connected to the cluster	
100 pins	1	PA02, PA03, PB04, PB05, PC02, PC03	V_{DDANA} pin12	GNDANA pin11
	2	PA04, PA05, PA06, PA07, PB06, PB07, PB08, PB09, PC05, PC06, PC07	V_{DDANA} pin12, V_{DDANA} pin25	GNDANA pin11, GNDANA pin24
	3	PA08, PA09, PA10, PA11, PC08, PC09, PC10, PC11, PC12, PC13	V_{DDIO} pin36	GND pin37
	4	PA12, PA13, PA14, PA15, PB11, PB12, PB13, PB14, PB15, PC14, PC15	V_{DDIO} pin36, V_{DDIO} pin51	GND pin37, GND pin50
	5	PA16, PA17, PA18, PA19, PC16, PC17, PC18, PC19, PC20, PC21	V_{DDIO} pin51, V_{DDIO} pin63	GND pin50, GND pin62
	6	PA20, PA21, PA22, PA23, PA24, PA25, PB16, PB17, PB18, PB19, PB20, PB21	V_{DDIO} pin63, V_{DDIO} pin77	GND pin62, GND pin76
	7	PA27, PB22, PB23, PB24, PB25, PC24, PC25, PC26, PC27, PC28	V_{DDIO} pin77, V_{DDIO} pin92	GND pin76, GND pin90
	8	PA00, PA01, PA30, PA31, PB00, PB01, PB02, PB03, PB30, PB31, PC00, PC01	V_{DDIO} pin92	GND pin90
64 pins	1	PA02, PA03, PA04, PA05, PA06, PA07, PB04, PB05, PB06, PB07, PB08, PB09	V_{DDANA} pin8	GNDANA pin7
	2	PA08, PA09, PA10, PA11	V_{DDIO} pin21	GND pin22
	3	PA12, PA13, PA14, PA15, PB11, PB12, PB13, PB14, PB15	V_{DDIO} pin21, V_{DDIO} pin34	GND pin22, GND pin33
	4	PA16, PA17, PA18, PA19, PA20, PA21, PA22, PA23, PA24, PA25, PB16, PB17	V_{DDIO} pin34, V_{DDIO} pin48	GND pin33, GND pin47
	5	PA27, PB22, PB23	V_{DDIO} pin48, V_{DDIO} pin56	GND pin47, GND pin54
	6	PA00, PA01, PA30, PA31, PB00, PB01, PB02, PB03, PB30, PB31	V_{DDIO} pin56	GND pin54
48 pins	1	PA02, PA03, PA04, PA05, PA06, PA07, PB08, PB09	V_{DDANA} pin6	GNDANA pin5
	2	PA08, PA09, PA10, PA11	V_{DDIO} pin17	GND pin18
	3	PA12, PA13, PA14, PA15, PA16, PA17, PA18, PA19, PA20, PA21, PA22, PA23, PA24, PA25, PB11	V_{DDIO} pin17, V_{DDIO} pin36	GND pin18, GND pin35
	4	PA27, PB22, PB23	V_{DDIO} pin36, V_{DDIO} pin44	GND pin35, GND pin42
	5	PA00, PA01, PA30, PA31, PB02, PB03	V_{DDIO} pin44	GND pin42
49 pins	1	PA02, PA03, PA04, PA05, PA06, PA07, PB08, PB09	V_{DDANA} pin D7	GNDANA pin C7
	2	PA08, PA09, PA10, PA11	V_{DDIO} pin G5	GND pin F5
	3	PA12, PA13, PA14, PA15, PA16, PA17, PA18, PA19, PB11	V_{DDIO} pin G5, V_{DDIO} pin E1	GND pin F5, GND pin E2
	4	PA20, PA21, PA22, PA23, PA24, PA25	V_{DDIO} pin E1, V_{DDIO} pin A5	GND pin E2, GND pin D4
	4	PA27, PB22, PB23	V_{DDIO} pin E1, V_{DDIO} pin A5	GND pin D4, GND pin B3
	5	PA00, PA01, PA30, PA31, PB02, PB03	V_{DDIO} pin A5	GND pin B3

The same voltage must be applied to both VDDIO and VDDANA. This common voltage is referred to as VDD in the datasheet.

The ground pins, GND, are common to VDDCORE, and VDDIO. The ground pin for VDDANA is GNDANA.

For decoupling recommendations for the different power supplies, refer to the schematic checklist.

8.2.2. Voltage Regulator

The SAM L22 internal Voltage Regulator has four different modes:

- Linear mode : This is the default mode when CPU and peripherals are running. It does not require an external inductor.
- Switching mode. This is the most efficient mode when the CPU and peripherals are running. This mode can be selected by software on the fly.
- Low Power (LP) mode. This is the default mode used when the chip is in standby mode.
- Shutdown mode. When the chip is in backup mode, the internal regulator is off.

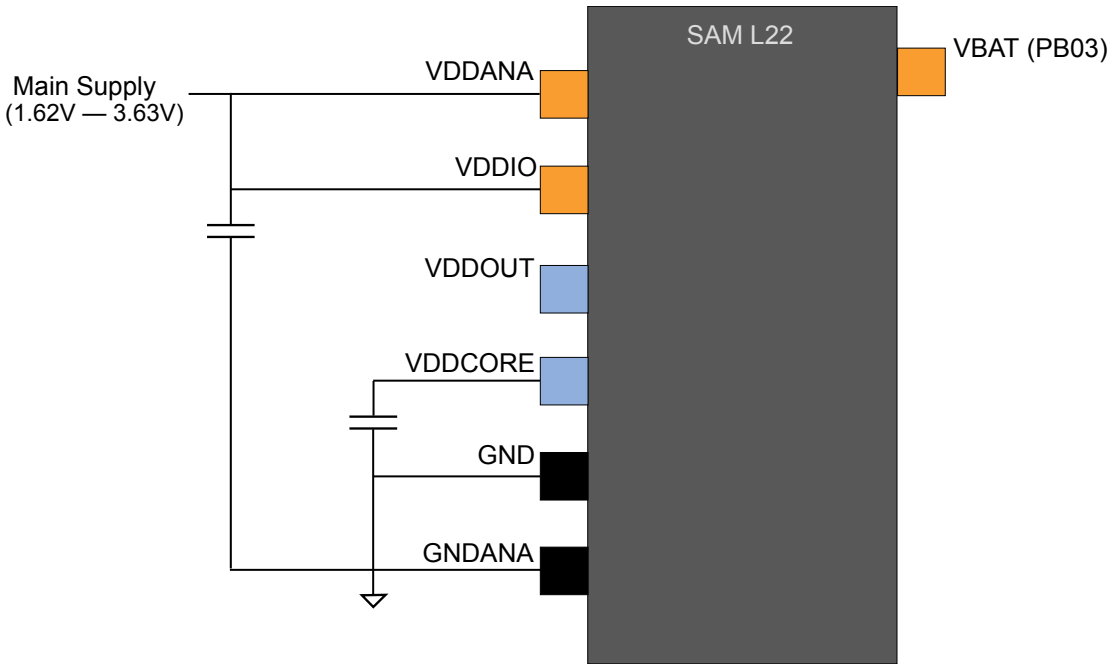
Note that the Voltage Regulator modes are controlled by the Power Manager.

8.2.3. Typical Powering Schematic

The SAM L22 uses a single supply from 1.62V to 3.63V.

The following figure shows the recommended power supply connection.

Figure 8-1. Power Supply Connection for Linear Mode Only



8.4.4. Brown-Out Detector on VDDCORE

Once the device has started up, BOD12 monitors the internal VDDCORE.

8.5. Performance Level Overview

By default, the device will start in Performance Level 0. This PL0 is aiming for the lowest power consumption by limiting logic speeds and the CPU frequency. As a consequence, all GCLK will have limited capabilities, and some peripherals and clock sources will not work or with limited capabilities:

List of peripherals/clock sources not available in PL0:

- USB (limited by logic frequency)
- DFLL48M

List of peripherals/clock sources with limited capabilities in PL0:

- All AHB/APB peripherals are limited by CPU frequency
- DPLL96M: may be able to generate 48MHz internally, but the output cannot be used by logic
- GCLK: the maximum frequency is by factor 4 compared to PL2
- SW interface: the maximum frequency is by factor 4 compared to PL2
- TC: the maximum frequency is by factor 4 compared to PL2
- TCC:the maximum frequency is by factor 4 compared to PL2
- SERCOM: the maximum frequency is by factor 4 compared to PL2

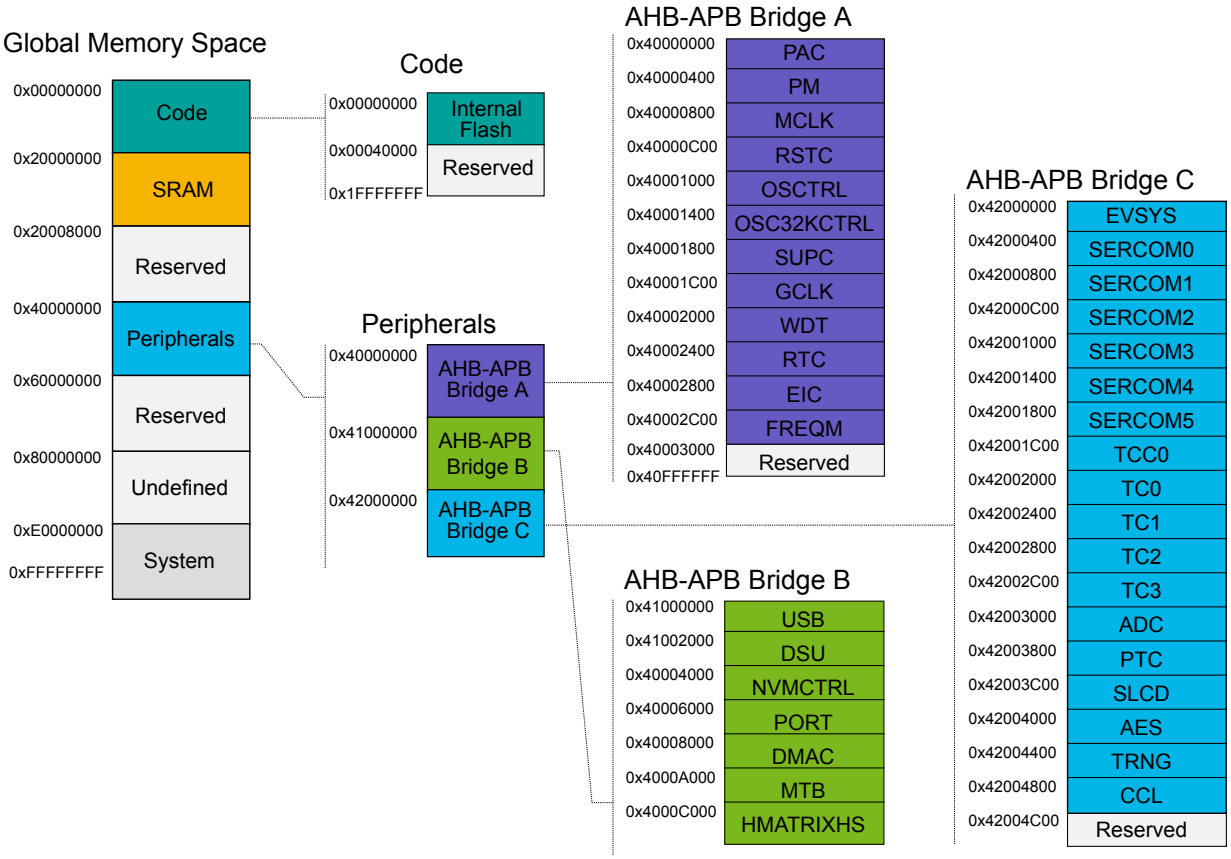
List of peripherals/clock sources with full capabilities in PL0:

- AC
- ADC
- EIC
- OSC16M
- PTC
- All 32KHz clock sources and peripherals

Full functionality and capability will be ensured in PL2. When transitioning between performance levels, the Supply Controller (SUPC) will provide a configurable smooth voltage scaling transition.

9. Product Mapping

Figure 9-1. Atmel SAM L22 Product Mapping



10.4. NVM Software Calibration Area Mapping

The NVM Software Calibration Area contains calibration data that are determined and written during production test. These calibration values should be read by the application software and written back to the corresponding register.

The NVM Software Calibration Area can be read at address 0x00806020.

The NVM Software Calibration Area can not be written.

Table 10-5. NVM Software Calibration Area Mapping

Bit Position	Name	Description
2:0	ADC LINEARITY	ADC Linearity Calibration. Should be written to CALIB register.
5:3	ADC BIASCAL	ADC Bias Calibration. Should be written to CALIB register.
12:6	Reserved	Reserved for future use.
17:13	USB TRANSN	USB TRANSN calibration value. Should be written to the USB PADCAL register.
22:18	USB TRANSP	USB TRANSP calibration value. Should be written to the USB PADCAL register.
25:23	USB TRIM	USB TRIM calibration value. Should be written to the USB PADCAL register.
31:26	DFLL48M COARSE CAL	DFLL48M Coarse calibration value. Should be written to the OSCCTRL DFLLVAL register.

10.5. Serial Number

Each device has a unique 128-bit serial number which is a concatenation of four 32-bit words contained at the following addresses:

Word 0: 0x0080A00C

Word 1: 0x0080A040

Word 2: 0x0080A044

Word 3: 0x0080A048

The uniqueness of the serial number is guaranteed only when using all 128 bits.

11. Processor and Architecture

11.1. Cortex M0+ Processor

The Atmel SAM L22 implements the ARM ARM®Cortex™-M0+ processor, based on the ARMv6 Architecture and Thumb®-2 ISA. The Cortex M0+ is 100% instruction set compatible with its predecessor, the Cortex-M0 core, and upward compatible to Cortex-M3 and M4 cores. The implemented ARM Cortex-M0+ is revision r0p1. For more information refer to http://www.arm.com

11.1.1. Cortex M0+ Configuration

Table 11-1. Cortex M0+ Configuration

Features	Cortex-M0+ options	SAM L22 configuration
Interrupts	External interrupts 0-32	27
Data endianness	Little-endian or big-endian	Little-endian
SysTick timer	Present or absent	Present
Number of watchpoint comparators	0, 1, 2	2
Number of breakpoint comparators	0, 1, 2, 3, 4	4
Halting debug support	Present or absent	Present
Multiplier	Fast or small	Fast (single cycle)
Single-cycle I/O port	Present or absent	Present
Wake-up interrupt controller	Supported or not supported	Not supported
Vector Table Offset Register	Present or absent	Present
Unprivileged/Privileged support	Present or absent	Present
Memory Protection Unit	Not present or 8-region	8-region
Reset all registers	Present or absent	Absent
Instruction fetch width	16-bit only or mostly 32-bit	32-bit

The ARM Cortex-M0+ core has two bus interfaces:

- Single 32-bit AMBA-3 AHB-Lite system interface that provides connections to peripherals and all system memory, which includes flash and RAM.
- Single 32-bit I/O port bus interfacing to the PORT and DIVAS with 1-cycle loads and stores.

11.1.2. Cortex M0+ Peripherals

- System Control Space (SCS)
  - The processor provides debug through registers in the SCS. Refer to the Cortex-M0+ Technical Reference Manual for details (http://www.arm.com)
- Nested Vectored Interrupt Controller (NVIC)
  - External interrupt signals connect to the NVIC, and the NVIC prioritizes the interrupts. Software can set the priority of each interrupt. The NVIC and the Cortex-M0+ processor core are closely coupled, providing low latency interrupt processing and efficient processing of late

arriving interrupts. Refer to NVIC-Nested Vector Interrupt Controller and the Cortex-M0+ Technical Reference Manual for details (http://www.arm.com).

Note: When the CPU frequency is much higher than the APB frequency it is recommended to insert a memory read barrier after each CPU write to registers mapped on the APB. Failing to do so in such conditions may lead to unexpected behavior such as e.g. re-entering a peripheral interrupt handler just after leaving it.

- System Timer (SysTick)
  - The System Timer is a 24-bit timer clocked by CLK_CPU that extends the functionality of both the processor and the NVIC. Refer to the Cortex-M0+ Technical Reference Manual for details (http://www.arm.com).
- System Control Block (SCB)
  - The System Control Block provides system implementation information, and system control. This includes configuration, control, and reporting of the system exceptions. Refer to the Cortex-M0+ Devices Generic User Guide for details (http://www.arm.com).
- Micro Trace Buffer (MTB)
  - The CoreSight MTB-M0+ (MTB) provides a simple execution trace capability to the Cortex-M0+ processor. Refer to section MTB-Micro Trace Buffer and the CoreSight MTB-M0+ Technical Reference Manual for details (http://www.arm.com).
- Memory Protection Unit (MPU)
  - The Memory Protection Unit divides the memory map into a number of regions, and defines the location, size, access permissions and memory attributes of each region. Refer to the Cortex-M0+ Devices Generic User Guide for details (http://www.arm.com)

11.1.3. Cortex M0+ Address Map

Table 11-2. Cortex-M0+ Address Map

Address	Peripheral
0xE000E000	System Control Space (SCS)
0xE000E010	System Timer (SysTick)
0xE000E100	Nested Vectored Interrupt Controller (NVIC)
0xE000ED00	System Control Block (SCB)
0x41006000	Micro Trace Buffer (MTB)

Related Links

Product Mapping on page 30

11.1.4. I/O Interface

The device allows direct access to PORT registers. Accesses to the AMBA® AHB-Lite™ and the single cycle I/O interface can be made concurrently, so the Cortex M0+ processor can fetch the next instructions while accessing the I/Os. This enables single cycle I/O access to be sustained for as long as necessary.

branch instructions or during exception entry. See the CoreSight MTB-M0+ Technical Reference Manual for more details on the MTB execution trace packet format.

Tracing is enabled when the MASTER.EN bit in the Master Trace Control Register is 1. There are various ways to set the bit to 1 to start tracing, or to 0 to stop tracing. See the CoreSight Cortex-M0+ Technical Reference Manual for more details on the Trace start and stop and for a detailed description of the MTB's MASTER register. The MTB can be programmed to stop tracing automatically when the memory fills to a specified watermark level or to start or stop tracing by writing directly to the MASTER.EN bit. If the watermark mechanism is not being used and the trace buffer overflows, then the buffer wraps around overwriting previous trace packets.

The base address of the MTB registers is 0x41006000; this address is also written in the CoreSight ROM Table. The offset of each register from the base address is fixed and as defined by the CoreSight MTB-M0+ Technical Reference Manual. The MTB has four programmable registers to control the behavior of the trace features:

- POSITION: Contains the trace write pointer and the wrap bit
- MASTER: Contains the main trace enable bit and other trace control fields
- FLOW: Contains the WATERMARK address and the AUTOSTOP and AUTOHALT control bits
- BASE: Indicates where the SRAM is located in the processor memory map. This register is provided to enable auto discovery of the MTB SRAM location by a debug agent

See the CoreSight MTB-M0+ Technical Reference Manual for a detailed description of these registers.

11.4. High-Speed Bus System

11.4.1. Overview

11.4.2. Features

High-Speed Bus Matrix has the following features:

- Symmetric crossbar bus switch implementation
- Allows concurrent accesses from different masters to different slaves
- 32-bit data bus
- Operation at a one-to-one clock frequency with the bus masters

12. Packaging Information

12.1. Thermal Considerations

12.1.1. Thermal Resistance Data

The following table summarizes the thermal resistance data depending on the package.

Table 12-1. Thermal Resistance Data

Package Type	θ_{JA}	θ_{JC}
48-pin TQFP	64.2°C/W	12.3°C/W
64-pin TQFP	60.8°C/W	12.0°C/W
100-pin TQFP	58.5°C/W	12.7°C/W
48-pin QFN	32.4°C/W	11.2°C/W
64-pin QFN	32.7°C/W	10.8°C/W
49-pin WLCSP	37.3°C/W	5.8°C/W

Related Links

Junction Temperature on page 42

12.1.2. Junction Temperature

The average chip-junction temperature, T_J, in °C can be obtained from the following:

1. $T_J = T_A + (P_D \times \theta_{JA})$
2. $T_J = T_A + (P_D \times (\theta_{HEATSINK} + \theta_{JC}))$

where:

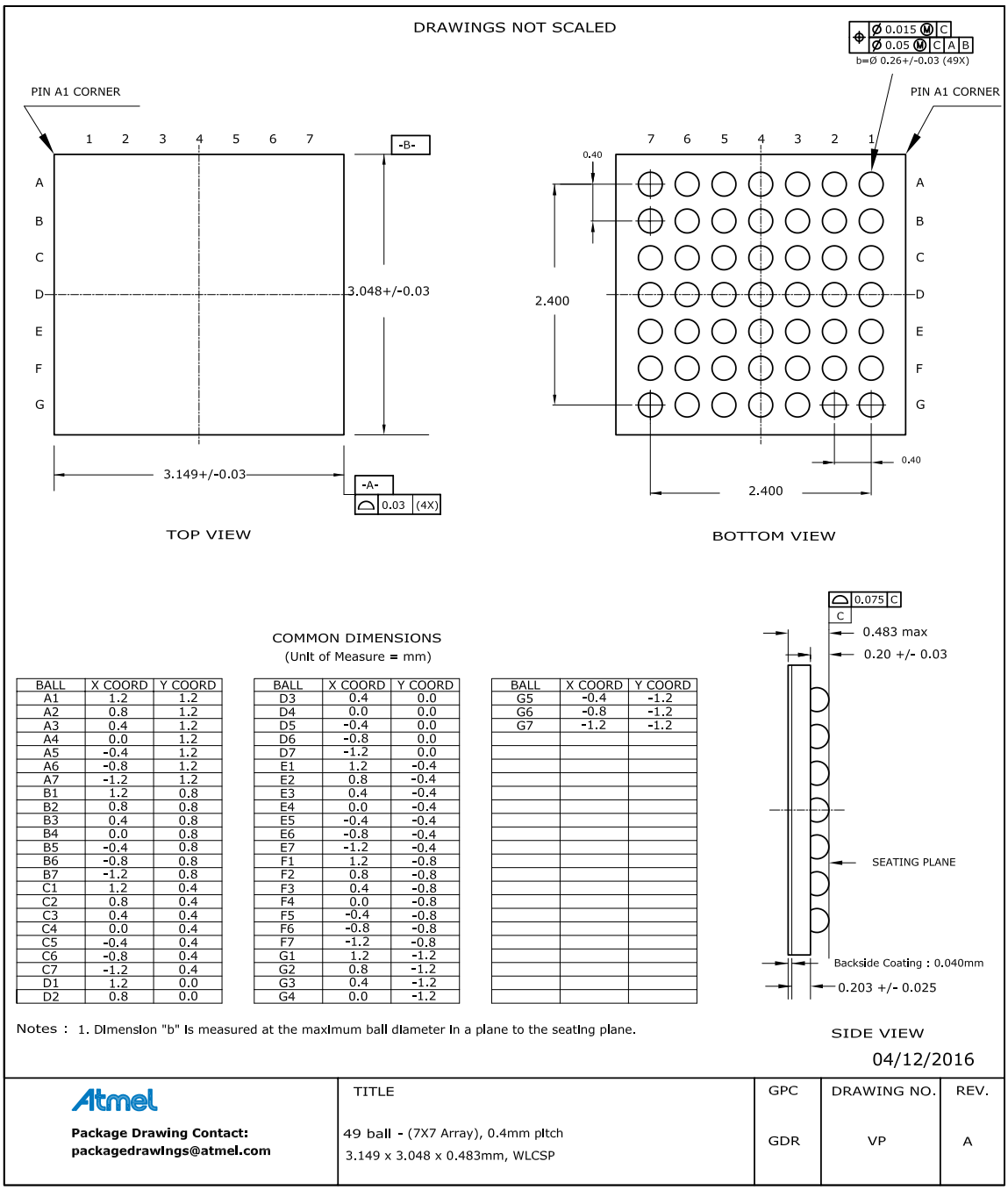
- θ_{JA} = Package thermal resistance, Junction-to-ambient (°C/W), see Thermal Resistance Data
- θ_{JC} = Package thermal resistance, Junction-to-case thermal resistance (°C/W), see Thermal Resistance Data
- $\theta_{HEATSINK}$ = Thermal resistance (°C/W) specification of the external cooling device
- P_D = Device power consumption (W)
- T_A = Ambient temperature (°C)

From the first equation, the user can derive the estimated lifetime of the chip and decide if a cooling device is necessary or not. If a cooling device is to be fitted on the chip, the second equation should be used to compute the resulting average chip-junction temperature T_J in °C.

Related Links

Thermal Resistance Data on page 42

12.2.4. 49-Ball WLCSP



BALL	X COORD	Y COORD
A1	1.2	1.2
A2	0.8	1.2
A3	0.4	1.2
A4	0.0	1.2
A5	-0.4	1.2
A6	-0.8	1.2
A7	-1.2	1.2
B1	1.2	0.8
B2	0.8	0.8
B3	0.4	0.8
B4	0.0	0.8
B5	-0.4	0.8
B6	-0.8	0.8
B7	-1.2	0.8
C1	1.2	0.4
C2	0.8	0.4
C3	0.4	0.4
C4	0.0	0.4
C5	-0.4	0.4
C6	-0.8	0.4
C7	-1.2	0.4
D1	1.2	0.0
D2	0.8	0.0

BALL	X COORD	Y COORD
D3	0.4	0.0
D4	0.0	0.0
D5	-0.4	0.0
D6	-0.8	0.0
D7	-1.2	0.0
E1	1.2	-0.4
E2	0.8	-0.4
E3	0.4	-0.4
E4	0.0	-0.4
E5	-0.4	-0.4
E6	-0.8	-0.4
E7	-1.2	-0.4
F1	1.2	-0.8
F2	0.8	-0.8
F3	0.4	-0.8
F4	0.0	-0.8
F5	-0.4	-0.8
F6	-0.8	-0.8
F7	-1.2	-0.8
G1	1.2	-1.2
G2	0.8	-1.2
G3	0.4	-1.2
G4	0.0	-1.2

BALL	X COORD	Y COORD
G5	-0.4	-1.2
G6	-0.8	-1.2
G7	-1.2	-1.2

Table 12-11. Device and Package Maximum Weight

8.45	mg

Table 12-12. Package Characteristics

Moisture Sensitivity Level	MSL1

Table 12-13. Package Reference

JEDEC Drawing Reference	N/A
JESD97 Classification	E1

12.2.5. 48 pin TQFP

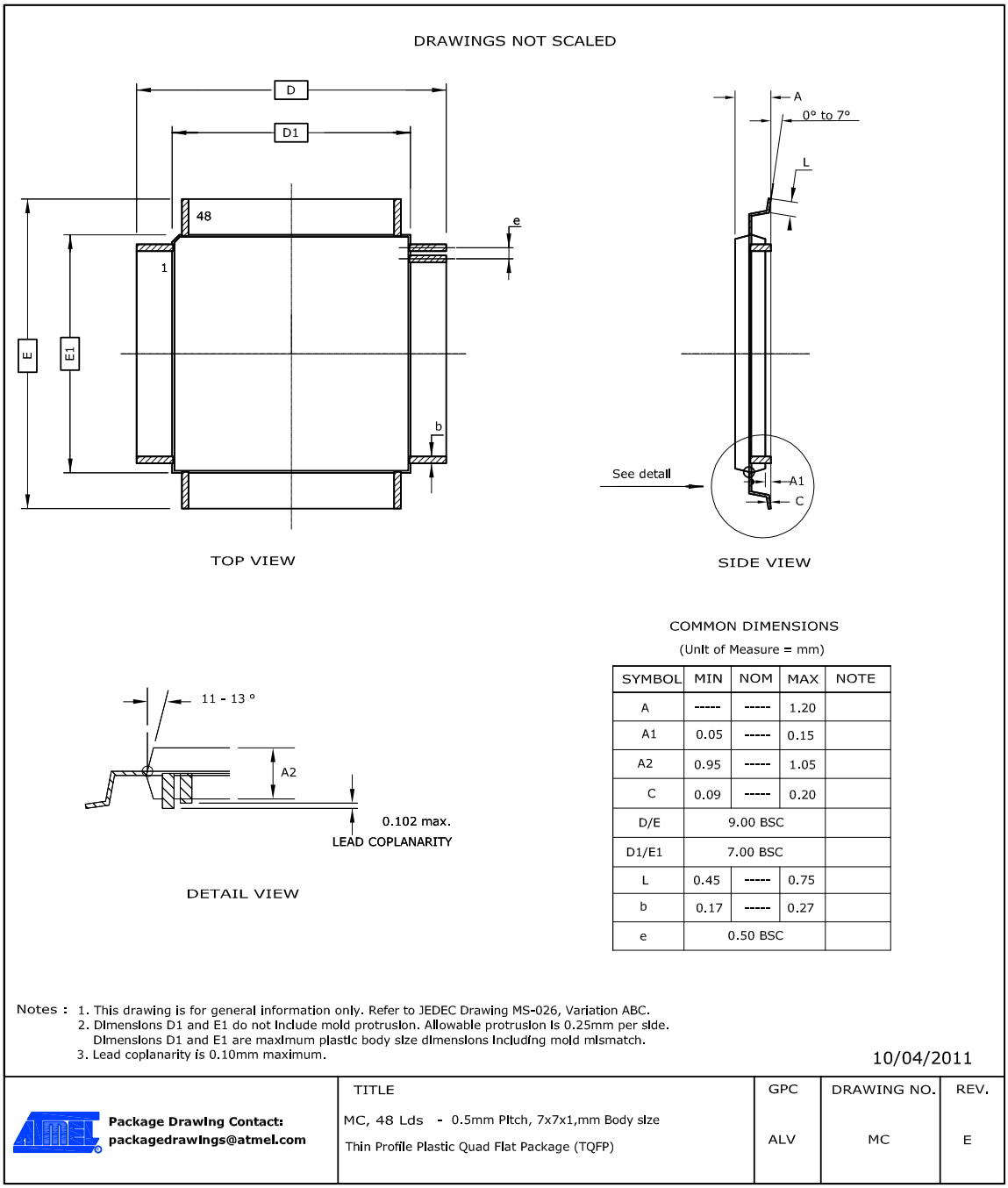


Table 12-14. Device and Package Maximum Weight

140	mg

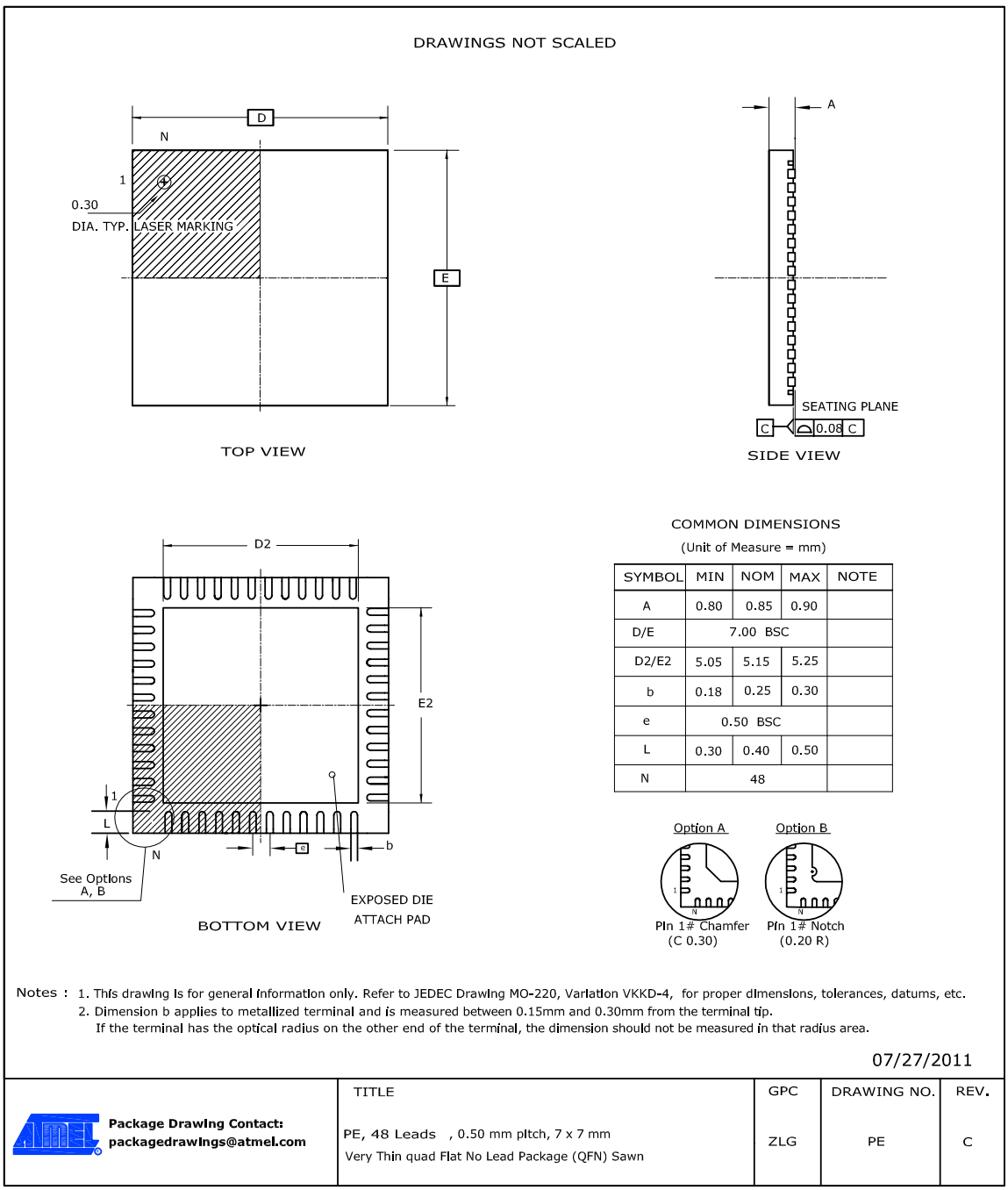
Table 12-15. Package Characteristics

Moisture Sensitivity Level	MSL3

Table 12-16. Package Reference

JEDEC Drawing Reference	MS-026
JESD97 Classification	E3

12.2.6. 48 pin QFN



Note: The exposed die attach pad is not connected electrically inside the device.

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