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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

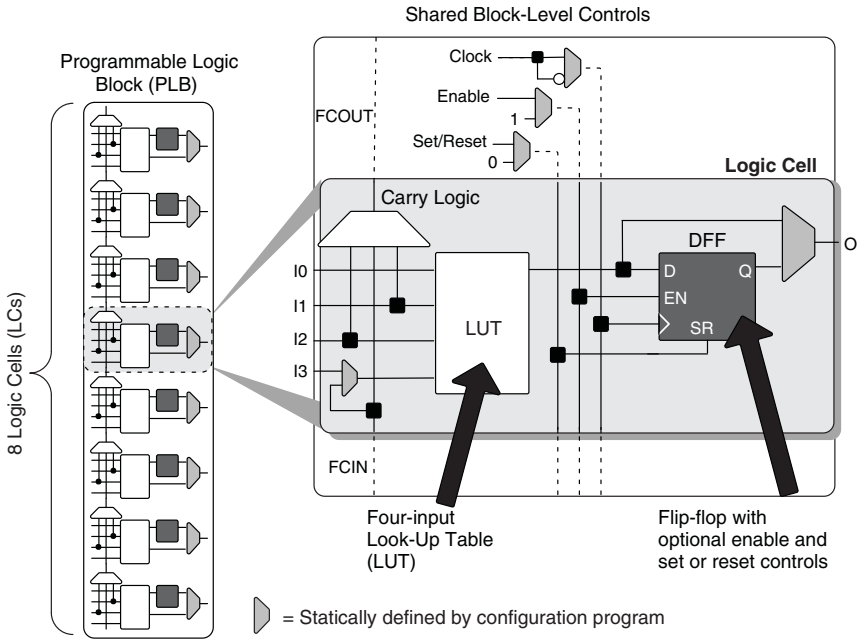
The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	138
Number of Logic Elements/Cells	1100
Total RAM Bits	65536
Number of I/O	12
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	20-UFBGA, WLCSP
Supplier Device Package	20-WLCSP (1.71x2.06)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/ice5lp1k-uwg20itr

PLB Blocks

The core of the iCE40 Ultra device consists of Programmable Logic Blocks (PLB) which can be programmed to perform logic and arithmetic functions. Each PLB consists of eight interconnected Logic Cells (LC) as shown in Figure 2-2. Each LC contains one LUT and one register.

Figure 2-2. PLB Block Diagram



Logic Cells

Each Logic Cell includes three primary logic elements shown in Figure 2-2.

- A four-input Look-Up Table (LUT) builds any combinational logic function, of any complexity, requiring up to four inputs. Similarly, the LUT element behaves as a 16x1 Read-Only Memory (ROM). Combine and cascade multiple LUTs to create wider logic functions.
- A 'D'-style Flip-Flop (DFF), with an optional clock-enable and reset control input, builds sequential logic functions. Each DFF also connects to a global reset signal that is automatically asserted immediately following device configuration.
- Carry Logic boosts the logic efficiency and performance of arithmetic functions, including adders, subtracters, comparators, binary counters and some wide, cascaded logic functions.

Table 2-1. Logic Cell Signal Descriptions

Function	Type	Signal Names	Description
Input	Data signal	I0, I1, I2, I3	Inputs to LUT
Input	Control signal	Enable	Clock enable shared by all LCs in the PLB
Input	Control signal	Set/Reset[1]	Asynchronous or synchronous local set/reset shared by all LCs in the PLB.
Input	Control signal	Clock	Clock one of the eight Global Buffers, or from the general-purpose interconnects fabric shared by all LCs in the PLB
Input	Inter-PLB signal	FCIN	Fast carry in
Output	Data signals	O	LUT or registered output
Output	Inter-PFU signal	FCOUT	Fast carry out

1. If Set/Reset is not used, then the flip-flop is never set/reset, except when cleared immediately after configuration.

sysCLOCK Phase Locked Loops (PLLs)

The sysCLOCK PLLs provide the ability to synthesize clock frequencies. The iCE40 Ultra devices have one sysCLOCK PLL. REFERENCECLK is the reference frequency input to the PLL and its source can come from an external I/O pin, the internal Oscillator Generators from internal routing. EXTFEEDBACK is the feedback signal to the PLL which can come from internal routing or an external I/O pin. The feedback divider is used to multiply the reference frequency and thus synthesize a higher frequency clock output.

The PLLOUT output has an output divider, thus allowing the PLL to generate different frequencies for each output. The output divider can have a value from 1 to 64 (in increments of 2X). The PLLOUT outputs can all be used to drive the iCE40 Ultra global clock network directly or general purpose routing resources can be used.

The LOCK signal is asserted when the PLL determines it has achieved lock and de-asserted if a loss of lock is detected. A block diagram of the PLL is shown in Figure 2-3.

The timing of the device registers can be optimized by programming a phase shift into the PLLOUT output clock which will advance or delay the output clock with reference to the REFERENCECLK clock. This phase shift can be either programmed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after a phase adjustment on the output used as the feedback source and not relock until the tLOCK parameter has been satisfied.

There is an additional feature in the iCE40 Ultra PLL. There are 2 FPGA controlled inputs, SCLK and SDI, that allows the user logic to serially shift in data thru SDI, clocked by SCLK clock. The data shifted in would change the configuration settings of the PLL. This feature allows the PLL to be time multiplexed for different functions, with different clock rates. After the data is shifted in, user would simply pulse the RESET input of the PLL block, and the PLL will re-lock with the new settings. For more details, please refer to TN1251, iCE40 sysCLOCK PLL Design and Usage Guide.

Figure 2-3. PLL Diagram

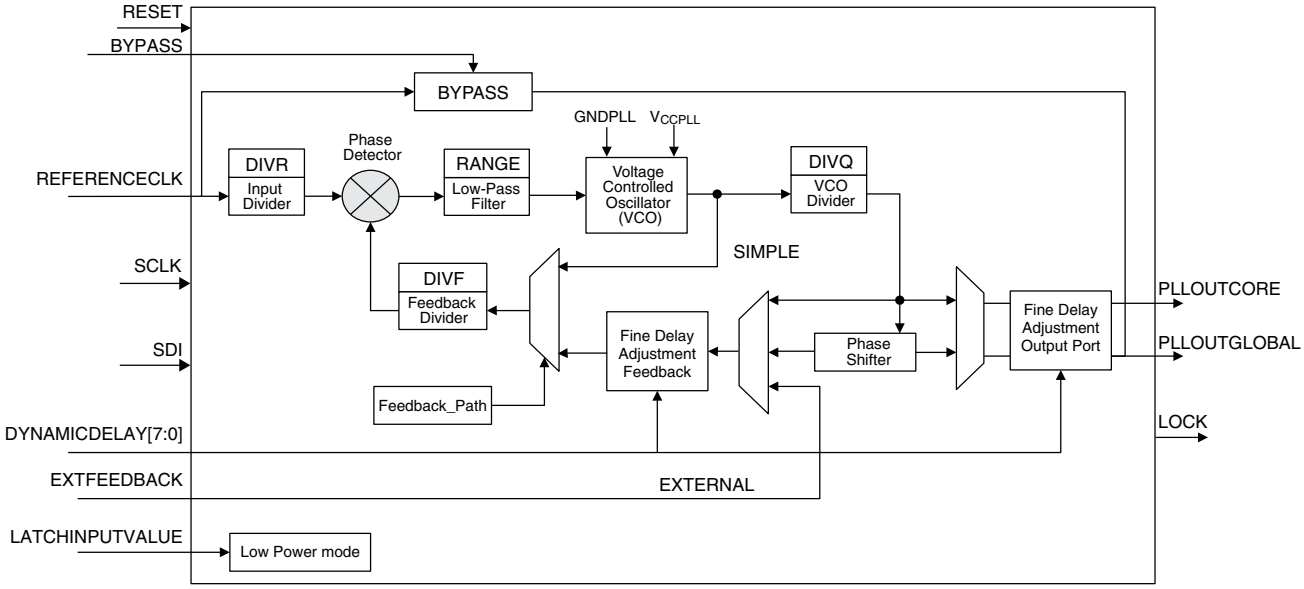


Table 2-3 provides signal descriptions of the PLL block.

Table 2-3. PLL Signal Descriptions

Signal Name	Direction	Description
REFERENCECLK	Input	Input reference clock
BYPASS	Input	The BYPASS control selects which clock signal connects to the PLL-OUT output. 0 = PLL generated signal 1 = REFERENCECLK
EXTFEEDBACK	Input	External feedback input to PLL. Enabled when the FEEDBACK_PATH attribute is set to EXTERNAL.
DYNAMICDELAY[7:0]	Input	Fine delay adjustment control inputs. Enabled when DELAY_ADJUSTMENT_MODE is set to DYNAMIC.
LATCHINPUTVALUE	Input	When enabled, puts the PLL into low-power mode; PLL output is held static at the last input clock value. Set ENABLE ICEGATE_PORTA and PORTB to '1' to enable.
PLLOUTGLOBAL	Output	Output from the Phase-Locked Loop (PLL). Drives a global clock network on the FPGA. The port has optimal connections to global clock buffers GBUF4 and GBUF5.
PLLOUTCORE	Output	Output clock generated by the PLL, drives regular FPGA routing. The frequency generated on this output is the same as the frequency of the clock signal generated on the PLLOUTLGOBAL port.
LOCK	Output	When High, indicates that the PLL output is phase aligned or locked to the input reference clock.
RESET	Input	Active low reset.
SCLK	Input	Input, Serial Clock used for re-programming PLL settings.
SDI	Input	Input, Serial Data used for re-programming PLL settings.

sysMEM Embedded Block RAM Memory

Larger iCE40 Ultra device includes multiple high-speed synchronous sysMEM Embedded Block RAMs (EBRs), each 4 kbit in size. This memory can be used for a wide variety of purposes including data buffering, and FIFO.

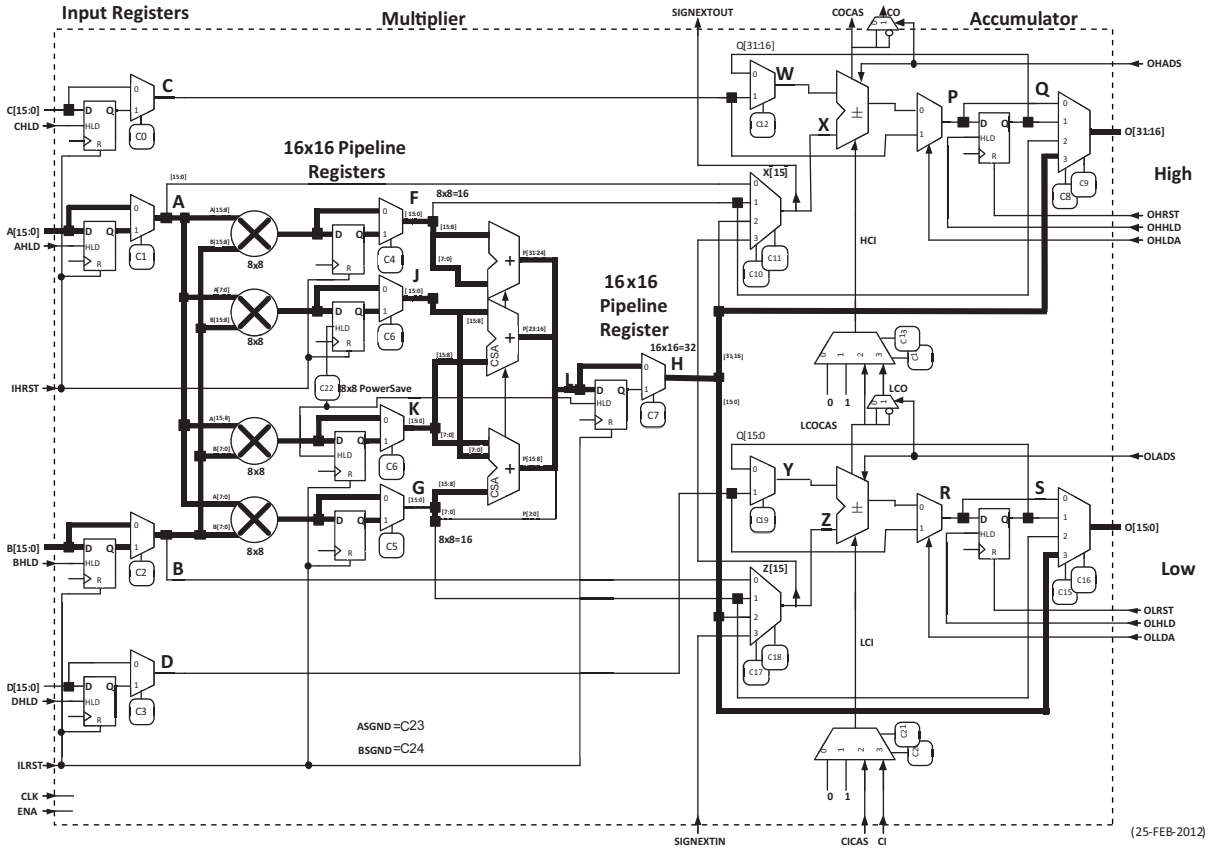
sysMEM Memory Block

The sysMEM block can implement single port, pseudo dual port, or FIFO memories with programmable logic resources. Each block can be used in a variety of depths and widths as shown in Table 2-4.

Table 2-6. sysDSP Input/Output List

Signal	Primitive Port Name	Width	Input / Output	Function	Default
CLK	CLK	1	Input	Clock Input. Applies to all clocked elements in the sysDSP block	
ENA	CE	1	Input	Clock Enable Input. Applies to all clocked elements in the sysDSP block. 0 = Not Enabled 1 = Enabled	0: Enabled
A[15:0]	A[15:0]	16	Input	Input to the A Register. Feeds the Multiplier or is a direct input to the Adder Accumulator	16'b0
B[15:0]	B[15:0]	16	Input	Input to the B Register. Feeds the Multiplier or is a direct input to the Adder Accumulator	16'b0
C[15:0]	C[15:0]	16	Input	Input to the C Register. It is a direct input to the Adder Accumulator	16'b0
D[15:0]	D[15:0]	16	Input	Input to the D Register. It is a direct input to the Adder Accumulator	16'b0
AHLD	AHOLD	1	Input	A Register Hold. 0 = Update 1 = Hold	0: Update
BHLD	BHOLD	1	Input	B Register Hold. 0 = Update 1 = Hold	0: Update
CHLD	CHOLD	1	Input	C Register Hold. 0 = Update 1 = Hold	0: Update
DHLD	DHOLD	1	Input	D Register Hold. 0 = Update 1 = Hold	0: Update
IHRST	IRSTTOP	1	Input	Reset input to A and C input registers, and the pipeline registers in the upper half of the Multiplier Section. 0 = No Reset 1 = Reset	0: No Reset
ILRST	IRSTBOT	1	Input	Reset input to B and D input registers, and the pipeline registers in the lower half of the Multiplier Section. It also resets the Multiplier result pipeline register. 0 = No Reset 1 = Reset	0: No Reset
O[31:0]	O[31:0]	32	Output	Output of the sysDSP block. This output can be: — O[31:0] – 32-bit result of 16x16 Multiplier or MAC — O[31:16] – 16-bit result of 8x8 upper half Multiplier or MAC — O[15:0] – 16-bit result of 8x8 lower half Multiplier or MAC	
OHHLD	OHOLDTOP	1	Input	High-order (upper half) Accumulator Register Hold. 0 = Update 1 = Hold	0: Update
OHRST	ORSTTOP	1	Input	Reset input to high-order (upper half) bits of the Accumulator Register. 0 = No Reset 1 = Reset	0: No Reset

Figure 2-7. DSP 16-bit x 16-bit Multiplier



Typical I/O Behavior During Power-up

The internal power-on-reset (POR) signal is deactivated when V_{CC}, SPI_V_{CCIO1}, and V_{PP_2V5} reach the level defined in the Power-On-Reset Voltage table in the DC and Switching Characteristics section of this data sheet. After the POR signal is deactivated, the FPGA core logic becomes active. You must ensure that all V_{CCIO} banks are active with valid input logic levels to properly control the output logic states of all the I/O banks that are critical to the application. The default configuration of the I/O pins in a device prior to configuration is tri-stated with a weak pull-up to V_{CCIO}. The I/O pins maintain the pre-configuration state until V_{CC}, SPI_V_{CCIO1}, and V_{PP_2V5} reach the defined levels. The I/Os take on the software user-configured settings only after POR signal is deactivated and the device performs a proper download/configuration. Unused I/Os are automatically blocked and the pull-up termination is disabled.

Supported Standards

The iCE40 Ultra sysIO buffer supports both single-ended input/output standards, and used as differential comparators. The buffer supports the LVCMOS 1.8, 2.5, and 3.3 V standards. The buffer has individually configurable options for bus maintenance (weak pull-up or none).

Table 2-8 and Table 2-9 show the I/O standards (together with their supply and reference voltages) supported by the iCE40 Ultra devices.

Differential Comparators

The iCE40 Ultra devices provide differential comparator on pairs of I/O pins. These comparators are useful in some mobile applications. Please refer to the Pin Information Summary section to locate the corresponding paired I/Os with differential comparators.

Table 2-8. Supported Input Standards

Input Standard	V_{CCIO} (Typical)		
	3.3 V	2.5 V	1.8 V
Single-Ended Interfaces			
LVCMOS33	✓		
LVCMOS25		✓	
LVCMOS18			✓

Table 2-9. Supported Output Standards

Output Standard	V_{CCIO} (Typical)
Single-Ended Interfaces	
LVCMOS33	3.3 V
LVCMOS25	2.5 V
LVCMOS18	1.8 V

On-Chip Oscillator

The iCE40 Ultra devices feature two different frequency Oscillator. One is tailored for low-power operation that runs at low frequency (LFOSC). Both Oscillators are controlled with internally generated current.

The LFOSC runs at nominal frequency of 10 kHz. The high frequency oscillator (HFOSC) runs at a nominal frequency of 48 MHz, divisible to 24 MHz, 12 MHz, or 6 MHz by user option. The LFOSC can be used to perform all always-on functions, with the lowest power possible. The HFOSC can be enabled when the always-on functions detect a condition that would need to wake up the system to perform higher frequency functions.

User I²C IP

The iCE40 Ultra devices have two I²C IP cores. Either of the two cores can be configured either as an I²C master or as an I²C slave. The pins for the I²C interface are not pre-assigned. User can use any General Purpose I/O pins.

In each of the two cores, there are options to delay the either the input or the output, or both, by 50 ns nominal, using dedicated on-chip delay elements. This provides an easier interface with any external I²C components.

When the IP core is configured as master, it will be able to control other devices on the I²C bus through the pre-assigned pin interface. When the core is configured as the slave, the device will be able to provide I/O expansion to an I²C Master. The I²C cores support the following functionality:

- Master and Slave operation
- 7-bit and 10-bit addressing
- Multi-master arbitration support
- Clock stretching
- Up to 400 kHz data transfer speed
- General Call support
- Optionally delaying input or output data, or both

For further information on the User I²C, please refer to TN1274, iCE40 SPI/I2C Hardened IP Usage Guide.

User SPI IP

The iCE40 Ultra devices have two SPI IP cores. The pins for the SPI interface are not pre-assigned. User can use any General Purpose I/O pins. Both SPI IP cores can be configured as a SPI master or as a slave. When the SPI IP core is configured as a master, it controls the other SPI enabled devices connected to the SPI Bus. When SPI IP core is configured as a slave, the device will be able to interface to an external SPI master.

The SPI IP core supports the following functions:

- Configurable Master and Slave modes
- Full-Duplex data transfer
- Mode fault error flag with CPU interrupt capability
- Double-buffered data register
- Serial clock with programmable polarity and phase
- LSB First or MSB First Data Transfer

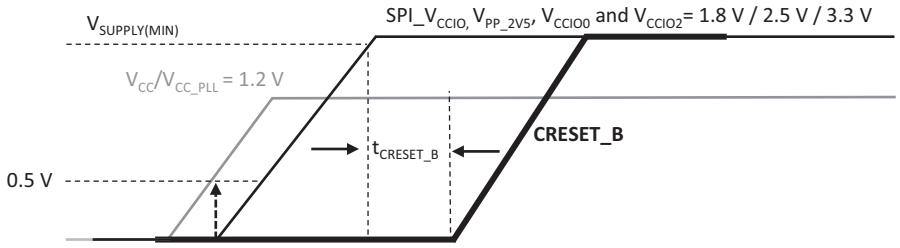
For further information on the User SPI, please refer to TN1274, iCE40 SPI/I2C Hardened IP Usage Guide.

High Current LED Drive I/O Pins

The iCE40 Ultra family devices offer multiple high current LED drive outputs in each device in the family to allow the iCE40 Ultra product to drive LED signals directly on mobile applications.

There are three outputs on each device that can sink up to 24 mA current. These outputs are open-drain outputs, and provides sinking current to an LED connecting to the positive supply. These three outputs are designed to drive the RBG LEDs, such as the service LED found in a lot of mobile devices. An embedded RGB PWM IP is also offered in the family. This RGB drive current is user programmable from 4 mA to 24 mA, in increments of 4 mA. This output functions as General Purpose I/O with open-drain when the high current LED drive is not needed.

Figure 3-2. Power Up Sequence with All Supplies Connected Together



Power-On-Reset Voltage Levels[1]

Symbol	Parameter		Min.	Max.	Units
V_{PORUP}	Power-On-Reset ramp-up trip point (circuit monitoring V_{CC}, SPI_V_{CCIO1}, V_{PP_2V5})	V_{CC}	0.62	0.92	V
		SPI_V_{CCIO1}	0.87	1.50	V
		V_{PP_2V5}	0.90	1.53	V
V_{PORDN}	Power-On-Reset ramp-down trip point (circuit monitoring V_{CC}, SPI_V_{CCIO1}, V_{PP_2V5})	V_{CC}	—	0.79	V
		SPI_V_{CCIO1}	—	1.50	V
		V_{PP_2V5}	—	1.53	V

1. These POR trip points are only provided for guidance. Device operation is only characterized for power supply voltages specified under recommended operating conditions.

ESD Performance

Please contact Lattice Semiconductor for additional information.

DC Electrical Characteristics

Over Recommended Operating Conditions

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
I_{IL}, I_{IH}[1, 3, 4]	Input or I/O Leakage	0V < V_{IN} < V_{CCIO} + 0.2 V	—	—	+/–10	µA
C_1	I/O Capacitance, excluding LED Drivers[2]	V_{CCIO} = 3.3 V, 2.5 V, 1.8 V V_{CC} = Typ., V_{IO} = 0 to V_{CCIO} + 0.2 V	—	6	—	pF
C_2	Global Input Buffer Capacitance[2]	V_{CCIO} = 3.3 V, 2.5 V, 1.8 V V_{CC} = Typ., V_{IO} = 0 to V_{CCIO} + 0.2 V	—	6	—	pF
C_3	RGB Pin Capacitance[2]	V_{CC} = Typ., V_{IO} = 0 to 3.5 V	—	15	—	pF
C_4	IRLED Pin Capacitance[2]	V_{CC} = Typ., V_{IO} = 0 to 3.5 V	—	53	—	pF
V_{HYST}	Input Hysteresis	V_{CCIO} = 1.8 V, 2.5 V, 3.3 V	—	200	—	mV
I_{PU}	Internal PIO Pull-up Current	V_{CCIO} = 1.8 V, 0=<V_{IN}<=0.65 V_{CCIO}	–3	—	–31	µA
		V_{CCIO} = 2.5 V, 0=<V_{IN}<=0.65 V_{CCIO}	–8	—	–72	µA
		V_{CCIO} = 3.3 V, 0=<V_{IN}<=0.65 V_{CCIO}	–11	—	–128	µA

1. Input or I/O leakage current is measured with the pin configured as an input or as an I/O with the output driver tri-stated. It is not measured with the output driver active. Internal pull-up resistors are disabled.
2. T_J 25 °C, f = 1.0 MHz.
3. Please refer to V_{IL} and V_{IH} in the sysIO Single-Ended DC Electrical Characteristics table of this document.
4. Input pins are clamped to V_{CCIO} and GND by a diode. When input is higher than V_{CCIO} or lower than GND, the Input Leakage current will be higher than the I_{IL} and I_{IH}.

Typical Building Block Function Performance[1, 2]

Pin-to-Pin Performance (LVCMOS25)

Function	Timing	Units
Basic Functions		
16-bit decoder	16.5	ns
4:1 MUX	18.0	ns
16:1 MUX	19.5	ns

Register-to-Register Performance

Function	Timing	Units
Basic Functions		
16:1 MUX	110	MHz
16-bit adder	100	MHz
16-bit counter	100	MHz
64-bit counter	40	MHz
Embedded Memory Functions		
256x16 Pseudo-Dual Port RAM	150	MHz

1. The above timing numbers are generated using the Lattice Design Software tool. Exact performance may vary with device and tool version. The tool uses internal parameters that have been characterized but are not tested on every device.
2. Under worst case operating conditions.

Derating Logic Timing

Logic timing provided in the following sections of the data sheet and the Lattice design tools are worst case numbers in the operating range. Actual delays may be much faster. Lattice design tools can provide logic timing numbers at a particular temperature and voltage.

Maximum sysIO Buffer Performance[1]

I/O Standard	Max. Speed	Units
Inputs		
LVCMOS33	250	MHz
LVCMOS25	250	MHz
LVCMOS18	250	MHz
Outputs		
LVCMOS33	250	MHz
LVCMOS25	250	MHz
LVCMOS18	155	MHz

1. Measured with a toggling pattern

iCE40 Ultra Family Timing Adders

Over Recommended Commercial Operating Conditions[1, 2, 3]

Buffer Type	Description	Timing (Typ.)	Units
Input Adjusters			
LVCMOS33	LVCMOS, V_{CCIO} = 3.3 V	0.18	ns
LVCMOS25	LVCMOS, V_{CCIO} = 2.5 V	0	ns
LVCMOS18	LVCMOS, V_{CCIO} = 1.8 V	0.19	ns
Output Adjusters			
LVCMOS33	LVCMOS, V_{CCIO} = 3.3 V	–0.12	ns
LVCMOS25	LVCMOS, V_{CCIO} = 2.5 V	0	ns
LVCMOS18	LVCMOS, V_{CCIO} = 1.8 V	1.32	ns

1. Timing adders are relative to LVCMOS25 and characterized but not tested on every device.
2. LVCMOS timing measured with the load specified in Switching Test Condition table.
3. Commercial timing numbers are shown.

iCE40 Ultra External Switching Characteristics

Over Recommended Commercial Operating Conditions

Parameter	Description	Device	Min	Max	Units
Clocks					
Global Clocks					
f_{MAX_GBUF}	Frequency for Global Buffer Clock network	All devices	—	185	MHz
t_{W_GBUF}	Clock Pulse Width for Global Buffer	All devices	2	—	ns
t_{SKEW_GBUF}	Global Buffer Clock Skew Within a Device	All devices	—	500	ps
Pin-LUT-Pin Propagation Delay					
t_{PD}	Best case propagation delay through one LUT logic	All devices	—	9.0	ns
General I/O Pin Parameters (Using Global Buffer Clock without PLL)[1]					
t_{SKEW_IO}	Data bus skew across a bank of IOs	All devices	—	410	ps
t_{CO}	Clock to Output – PIO Output Register	All devices	—	9.0	ns
t_{SU}	Clock to Data Setup – PIO Input Register	All devices	–0.5	—	ns
t_{H}	Clock to Data Hold – PIO Input Register	All devices	5.55	—	ns
General I/O Pin Parameters (Using Global Buffer Clock with PLL)					
t_{COPLL}	Clock to Output – PIO Output Register	All Devices	—	2.9	ns
t_{SUPLL}	Clock to Data Setup – PIO Input Register	All Devices	5.9	—	ns
t_{HPLL}	Clock to Data Hold – PIO Input Register	All Devices	–0.6	—	ns

1. All the data is from the worst case condition.

sysCLOCK PLL Timing

Over Recommended Operating Conditions

Parameter	Descriptions	Conditions	Min.	Max.	Units
f_{IN}	Input Clock Frequency (REFERENCECLK, EXTFEEDBACK)		10	133	MHz
f_{OUT}	Output Clock Frequency (PLLOUT)		16	275	MHz
f_{VCO}	PLL VCO Frequency		533	1066	MHz
f_{PFD}	Phase Detector Input Frequency		10	133	MHz
AC Characteristics					
t_{DT}	Output Clock Duty Cycle		40	60	%
t_{PH}	Output Phase Accuracy		—	+/–12	deg
t_{OPJIT}[1, 5, 6]	Output Clock Period Jitter	f_{OUT} >= 100 MHz	—	450	ps p-p
		f_{OUT} < 100 MHz	—	0.05	UIPP
	Output Clock Cycle-to-cycle Jitter	f_{OUT} >= 100 MHz	—	750	ps p-p
		f_{OUT} < 100 MHz	—	0.10	UIPP
	Output Clock Phase Jitter	f_{PFD} >= 25 MHz	—	275	ps p-p
		f_{PFD} < 25 MHz	—	0.05	UIPP
t_W	Output Clock Pulse Width	At 90% or 10%	1.33	—	ns
t_{LOCK}[2, 3]	PLL Lock-in Time		—	50	µs
t_{UNLOCK}	PLL Unlock Time		—	50	ns
t_{IPJIT}[4]	Input Clock Period Jitter	$f_{PFD} \geq 20$ MHz	—	1000	ps p-p
		f_{PFD} < 20 MHz	—	0.02	UIPP
t_{STABLE}[3]	LATCHINPUTVALUE LOW to PLL Stable		—	500	ns
t_{STABLE_PW}[3]	LATCHINPUTVALUE Pulse Width		100	—	ns
t_{RST}	RESET Pulse Width		10	—	ns
t_{RSTREC}	RESET Recovery Time		10	—	µs
$t_{DYNAMIC\_WD}$	DYNAMICDELAY Pulse Width		100	—	VCO Cycles

1. Period jitter sample is taken over 10,000 samples of the primary PLL output with a clean reference clock. Cycle-to-cycle jitter is taken over 1000 cycles. Phase jitter is taken over 2000 cycles. All values per JESD65B.
2. Output clock is valid after t_{LOCK} for PLL reset and dynamic delay adjustment.
3. At minimum f_{PFD}. As the f_{PFD} increases the time will decrease to approximately 60% the value listed.
4. Maximum limit to prevent PLL unlock from occurring. Does not imply the PLL will operate within the output specifications listed in this table.
5. The jitter values will increase with loading of the PLD fabric and in the presence of SSO noise.

sysDSP Timing

Over Recommended Operating Conditions

Parameter	Description	Min.	Max.	Units
$f_{MAX8x8SMULT}$	Max frequency signed MULT8x8 bypassing pipeline register	50	—	MHz
$f_{MAX16x16SMULT}$	Max frequency signed MULT16x16 bypassing pipeline register	50	—	MHz

SPI Master or NVCM Configuration Time[1, 2]

Symbol	Parameter	Conditions	Max.	Units
t_{CONFIG}	POR/CRESET_B to Device I/O Active	All devices – Low Frequency (Default)	95	ms
		All devices – Medium frequency	35	ms
		All devices – High frequency	18	ms

1. Assumes sysMEM Block is initialized to an all zero pattern if they are used.
2. The NVCM download time is measured with a fast ramp rate starting from the maximum voltage of POR trip point.

sysCONFIG Port Timing Specifications

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
All Configuration Modes						
t_{CRESET_B}	Minimum CRESET_B LOW pulse width required to restart configuration, from falling edge to rising edge		200	—	—	ns
t_{DONE_IO}	Number of configuration clock cycles after CDONE goes HIGH before the PIO pins are activated		49	—	—	Clock Cycles
Slave SPI						
t_{CR_SCK}	Minimum time from a rising edge on CRESET_B until the first SPI WRITE operation, first SPI_XCK clock. During this time, the iCE40 Ultra device is clearing its internal configuration memory		1200	—	—	µs
f_{MAX}	CCLK clock frequency	Write	1	—	25	MHz
		Read[1]	—	15	—	MHz
t_{CCLKH}	CCLK clock pulsewidth HIGH		20	—	—	ns
t_{CCLKL}	CCLK clock pulsewidth LOW		20	—	—	ns
t_{STSU}	CCLK setup time		12	—	—	ns
t_{STH}	CCLK hold time		12	—	—	ns
t_{STCO}	CCLK falling edge to valid output		13	—	—	ns
Master SPI[3]						
f_{MCLK}	MCLK clock frequency	Low Frequency (Default)	7.0	12.0	17.0	MHz
		Medium Frequency[2]	21.0	33.0	45.0	MHz
		High Frequency[2]	33.0	53.0	71.0	MHz
t_{MCLK}	CRESET_B HIGH to first MCLK edge		1200	—	—	µs
t_{SU}	CCLK setup time[4]		9.9	—	—	ns
t_{HD}	CCLK hold time		1	—	—	ns

1. Supported with 1.2 V Vcc and at 25 °C.
2. Extended range fMAX Write operations support up to 53 MHz with 1.2 V Vcc and at 25 °C.
3. t_{SU} and t_{HD} timing must be met for all MCLK frequency choices.
4. For considerations of SPI Master Configuration Mode, please refer to TN1248, iCE40 Programming and Configuration.

RGB LED and IR LED Drive

Symbol	Parameter	Min.	Max.	Units
ILED_ACCURACY	RGB0, RGB1, RGB2 Sink Current Accuracy to selected current @ V_{LEDOUT} >= 0.5 V	–12	+12	%
ILED_MATCH	RGB0, RGB1, RGB2 Sink Current Matching among the 3 outputs @ V_{LEDOUT} >= 0.5 V	–5	+5	%
IIR_ACCURACY	IR LED Sink Current Accuracy to selected current @ V_{IROUT} >= 0.8 V	–14	+14	%

Switching Test Conditions

Figure 3-3 shows the output test load used for AC testing. The specific values for resistance, capacitance, voltage, and other test conditions are shown in Table 3-1.

Figure 3-3. Output Test Load, LVCMOS Standards

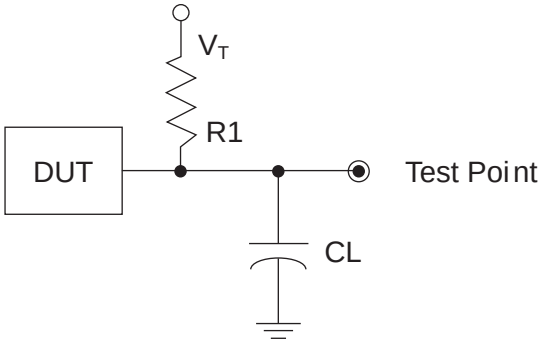


Table 3-1. Test Fixture Required Components, Non-Terminated Interfaces

Test Condition	R_1	C_L	Timing Reference	V_T
LVCMOS settings (L -> H, H -> L)	∞	0 pF	LVCMOS 3.3 = 1.5 V	—
			LVCMOS 2.5 = $V_{CCIO}/2$	—
			LVCMOS 1.8 = $V_{CCIO}/2$	—
LVCMOS 3.3 (Z -> H)	188	0 pF	1.5 V	V_{OL}
LVCMOS 3.3 (Z -> L)			1.5 V	V_{OH}
Other LVCMOS (Z -> H)			$V_{CCIO}/2$	V_{OL}
Other LVCMOS (Z -> L)			$V_{CCIO}/2$	V_{OH}
LVCMOS (H -> Z)			V_{OH} – 0.15 V	V_{OL}
LVCMOS (L -> Z)			V_{OL} – 0.15 V	V_{OH}

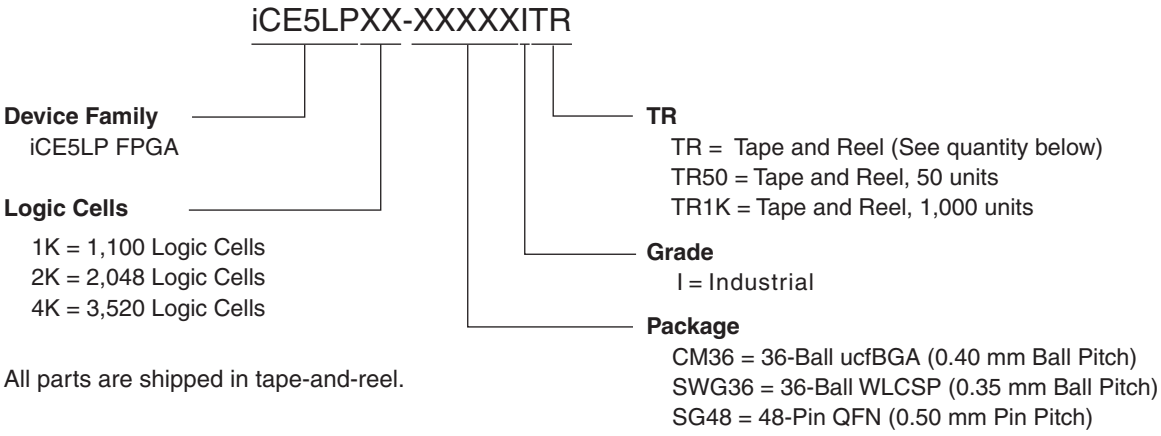
Note: Output test conditions for all other interfaces are determined by the respective standards.

Signal Name		Function	I/O	Description
PIOB_33b	SPI_SI	Configuration	Input	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin receives data from external SPI memory. In Slave SPI mode, this pin connects to the MOSI pin of the external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
PIOB_35b	SPI_SS_B	Configuration	I/O	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin outputs to the external SPI memory. In Slave SPI mode, this pin inputs from the external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
Global Signals				
Primary	Secondary			
PIOT_46b	G0	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G0 pin drives the GBUF0 global buffer
PIOT_45a	G1	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G1 pin drives the GBUF1 global buffer
PIOT_25b	G3	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G3 pin drives the GBUF3 global buffer
PIOT_12a	G4	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G4 pin drives the GBUF4 global buffer
PIOT_11b	G5	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G5 pin drives the GBUF5 global buffer
PIOB_3b	G6	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G6 pin drives the GBUF6 global buffer
LED Signals				
RGB0		General I/O	Open-Drain I/O	In user mode, with user's choice, this pin can be programmed as open drain I/O in user function
		LED	Open-Drain Output	In user mode, with user's choice, this pin can be programmed as open drain 24mA output to drive external LED
RGB1		General I/O	Open-Drain I/O	In user mode, with user's choice, this pin can be programmed as open drain I/O in user function
		LED	Open-Drain Output	In user mode, with user's choice, this pin can be programmed as open drain 24mA output to drive external LED

Signal Name	Function	I/O	Description
RGB2	General I/O	Open-Drain I/O	In user mode, with user's choice, this pin can be programmed as open drain I/O in user function
	LED	Open-Drain Output	In user mode, with user's choice, this pin can be programmed as open drain 24mA output to drive external LED
IRLED	General I/O	Open-Drain I/O	In user mode, with user's choice, this pin can be programmed as open drain I/O in user function
	LED	Open-Drain Output	In user mode, with user's choice, this pin can be programmed as open drain 500mA output to drive external LED
PIOT_xx	General I/O	I/O	In user mode, with user's choice, this pin can be programmed as I/O in user function in the top (xx = I/O location)
PIOB_xx	General I/O	I/O	In user mode, with user's choice, this pin can be programmed as I/O in user function in the bottom (xx = I/O location)

iCE40 Ultra Family Data Sheet Ordering Information

iCE5LP Part Number Description



All parts are shipped in tape-and-reel.

Tape and Reel Quantity

Package	TR Quantity
CM36	4,000
SWG36	5,000
SG48	2,000

iCE40 Ultra Family Data Sheet Revision History

June 2016 **Data Sheet DS1048**

Date	Version	Section	Change Summary
June 2016	2.0	Introduction	Updated General Description section. Changed “high current driver” to “high current IR driver”.
			Updated Features section. In Table 1-1, iCE40 Ultra Family Selection Guide, corrected HF Oscillator (48 kHz) to (48 MHz).
		Architecture	Updated Architecture Overview section. — Changed content to “The Programmable Logic Blocks (PLB) and sysMEM EBR blocks, are arranged in a two-dimensional grid with rows and columns. Each column has either PLB or EBR blocks." — Changed “high current LED sink” to "high current RGB and IR LED sinks".
			Updated sysCLOCK Phase Locked Loops (PLLs) section. Corrected V_{CCPLL} character format in Figure 2-3, PLL Diagram.
			Updated sysMEM Embedded Block RAM Memory section. Updated footnote in Table 2-4, sysMEM Block Configurations.
			Updated sysIO Buffer Banks section. — Changed statement to “The configuration SPI interface signals are powered by SPI_V_{CCIO1}.” — Corrected V_{CCIO} character format in Figure 2-8, I/O Bank and Programmable I/O Cell.
			Updated Typical I/O Behavior During Power-up section. Modified text content.
			Updated Supported Standards section. Changed statement to “The iCE40 Ultra sysIO buffer supports both single-ended input/output standards, and used as differential comparators.”
			Updated On-Chip Oscillator section. Changed statement to “The high frequency oscillator (HFOSC) runs at a nominal frequency of 48 MHz, divisible to 24 MHz, 12 MHz, or 6 MHz by user option.”
			Updated section heading to High Current LED Drive I/O Pins. Changed “high current drive” to “high current LED drive”.
			Removed Power On Reset section.
		DC and Switching Characteristics	Updated Absolute Maximum Ratings section. — Corrected symbol character format.
			Updated Recommended Operating Conditions section. — Corrected symbol character format. — Revised footnote 1. — Added footnote 4.
			Updated Power Supply Ramp Rates section. Changed t_{RAMP} Max. value.
			Added Power-On Reset section.
			Updated section heading to Power-Up Supply Sequencing. Revised text content.
			Added External Reset section.
			Updated DC Electrical Characteristics section. Revised footnote 4.

Date	Version	Section	Change Summary
April 2015	1.7	Architecture	Updated sysDSP section. Revised the following figures: — Figure 2-5, sysDSP Functional Block Diagram (16-bit x 16-bit Multiply-Accumulate) — Figure 2-6, sysDSP 8-bit x 8-bit Multiplier — Figure 2-7, DSP 16-bit x 16-bit Multiplier
		Ordering Information	Updated iCE5LP Part Number Description section. Added TR items.
			Updated Ordering Part Numbers section. Added CM36, SW36 and SG48 part numbers.
March 2015	1.6	Introduction	Updated Features section. — Added BGA and QFN packages in Flexible Logic Architecture. — Added USB 3.1 Type C Cable Detect / Power Delivery Applications in Applications. — Updated Table 1-1, iCE40 Ultra Family Selection Guide. Added 36-ball ucfBGA and 48-ball QFN packages. Changed subheading to Total User I/O Count. Changed RBW IP to PWM IP. Deleted footnotes.
		DC and Switching Characteristics	Updated Power-up Sequence section. Indicated all devices in second paragraph.
			Updated sysIO Single-Ended DC Electrical Characteristics section. Changed LVCMOS 3.3 and LVCMOS 2. 5 V_{OH} Min. (V) from 0.5 to 0.4.
			Replaced the Differential Comparator Electrical Characteristics table.
		Pinout Information	Updated Pin Information Summary section. — Added CM36 and SG48 values. — Changed CRESET_B to Dedicated Config Pins.
		Ordering Information	Updated iCE5LP Part Number Description section. — Added CM36 and SG48 package. — Added TR items.
			Updated Ordering Part Numbers section. Added CM36, SW36 and SG48 part numbers.
October 2014	1.5	Introduction	Updated Features section. — Removed 26 I/O pins for 36-pin WLCSP under Flexible Logic Architecture. — Changed form factor to 2.078 mm x 2.078 mm. — Updated Table 1-1, iCE40 Ultra Family Selection Guide. Removed 20-Ball WLCSP.
			Updated Introduction section. Changed form factor to 2.078 mm x 2.078 mm.
		Architecture	Updated sysCLOCK Phase Locked Loops (PLLs) section. Removed note in heading regarding sysCLOCK PLL support.
		DC and Switching Characteristics	Updated Recommended Operating Conditions section. Removed footnote on sysCLOCK PLL support.
			Updated Power-up Sequence section. Removed information on 20-pin WLCSP.
		Pinout Information	Updated Signal Descriptions section. Removed references 20-pin WLCSP.
			Updated Pin Information Summary section. Removed references to UWG20 values.
		Ordering Information	Updated iCE5LP Part Number Description section. Removed 20-ball WLCSP.
			Updated Ordering Part Numbers section. Removed UWG20 part numbers.
		Further Information	Added technical note references.

Date	Version	Section	Change Summary
August 2014	1.4	All	Removed Preliminary document status.
		Introduction	Updated General Description section. Added information on high current driver.
			Updated Features section. — Changed standby current typical to as low as 71 µA. — Changed feature to Embedded Memory. — Updated Table 1-1, iCE40 Ultra Family Selection Guide. Added NVCM and Embedded PWM IP rows. Added (MULT16 with 32-bit Accumulator) to DSP Block. Added Total I/O (Dedicated I/O) Count data.
			General update to Introduction section.
		Architecture	Updated Architecture Overview section. — Revised and added information on sysIO banks. — Updated reference for embedded PWM IP.
			Updated iCE40 Ultra Programming and Configuration section. — Changed SPI1 to SPI. — Changed VCCIO_1 to SPI_V_{CCIO1}.
		DC and Switching Characteristics	Updated Absolute Maximum Ratings section. Changed PLL Supply Voltage VCCPLL value.
			Updated Recommended Operating Conditions section. Added footnote to VCCPLL.
			Updated Power-up Sequence section. General update.
			Updated Power-On-Reset Voltage Levels section. Changed the V_{PORUP} V_{CC} Max.value.
			Updated DC Electrical Characteristics section. Added C_3 and C_4 information.
			Updated Supply Current section. — Completed Typ. VCC =1.2 V4 data. — Changed symbols to $I_{SPI\_VCCIO1STDBY}$ and $I_{SPI\_VCCIO1PEAK}$. — Added information to footnote 3.
			Updated Internal Oscillators (HFOSC, LFOSC) section. General update.
			Updated iCE40 Ultra External Switching Characteristics section. Added Max. value for t_{COPLL}. Added Min. values for t_{SUPLL} and t_{HPLL}.
			Updated sysCLOCK PLL Timing section. Added Max. value for t_{OPJIT}.
			Updated sysCONFIG Port Timing Specifications section. — Added T_{SU} and T_{HD} information. — Added footnote 3 to Master SPI.
			Updated High Current LED and IR LED Drive section. Updated Min. value.
July 2014	1.3	All	Changed document status from Advance to Preliminary.
		Introduction	Updated Features section. Adjusted Ultra-low Power Devices standby current.
		DC and Switching Characteristics	Updated AC/DC specifications numbers.

Date	Version	Section	Change Summary
June 2014	1.2	All	Product name changed to iCE40 Ultra.
		Introduction	Updated Table 1-1, iCE40 Ultra Family Selection Guide. Removed 30-ball WLCSP.
		DC and Switching Characteristics	Updated values in the following sections: — Supply Current — Internal Oscillators (HFOSC, LFOSC) — Power Supply Ramp Rates — Power-On-Reset Voltage Levels — SPI Master or NVCM Configuration Time
			Indicated TBD for values to be determined.
		Pinout Information	Updated Signal Descriptions section. Removed 30-pin WLCSP.
			Updated Pin Information Summary section. Removed SWG30 values.
		Ordering Information	Updated iCE5LP Part Number Description section. Removed 30-ball WLCSP.
			Updated Ordering Part Numbers section. Removed SWG30 and UWG30 part numbers.
May 2014	01.1	Introduction	Updated General Description, Features, and Introduction sections. Removed hardened RGB PWM IP information.
		Architecture	Updated Architecture Overview section. Removed the RGB IP block in Figure 2-1, iCE5LP-4K Device, Top View, Figure 2-8, I/O Bank and Programmable I/O, and in the text content.
			Updated High Current Drive I/O Pins section. Removed hardened RGB PWM IP information.
			Updated Power On Reset section. Removed content on Vccio_2 power down option.
			Replaced RGB PWM Block section with Embedded PWM IP section.
		DC and Switching Characteristics	Removed RGB PWM Block Timing section.
April 2014	01.0	All	Initial release.