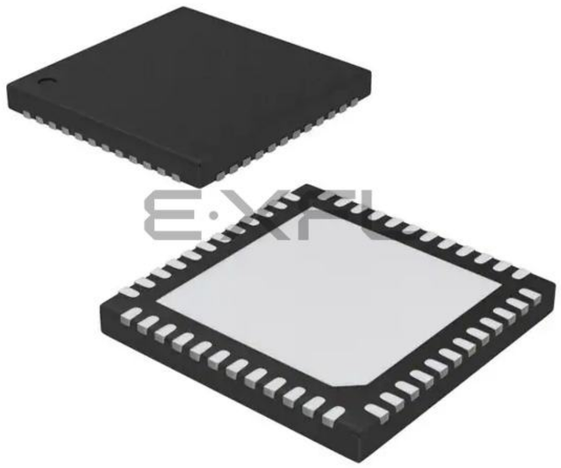

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Discontinued at Digi-Key
Number of LABs/CLBs	440
Number of Logic Elements/Cells	3520
Total RAM Bits	81920
Number of I/O	39
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	48-VFQFN Exposed Pad
Supplier Device Package	48-QFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/ice5lp4k-sg48itr50

iCE40 Ultra Family Data Sheet Introduction

June 2016 Data Sheet DS1048

General Description

iCE40 Ultra family is an ultra-low power FPGA and sensor manager designed for ultra-low power mobile applications, such as smartphones, tablets and hand-held devices. The iCE40 Ultra family includes integrated SPI and I²C blocks to interface with virtually all mobile sensors and application processors. The iCE40 Ultra family also features two on-chip oscillators, 10 kHz and 48 MHz. The LFOSC (10 kHz) is ideal for low power function in always-on applications, while HFOSC (48 MHz) can be used for awaken activities.

The iCE40 Ultra family also features DSP functional block to off-load Application Processor to pre-process information sent from the mobile sensors. The embedded RGB PWM IP, with the three 24 mA constant current RGB outputs on the iCE40 Ultra provides all the necessary logic to directly drive the service LED, without the need of external MOSFET or buffer.

The 500 mA constant current IR driver output provides a direct interface to external LED for application such as IrDA functions. Users simply implement the modulation logic that meets his needs, and connect the IR driver directly to the LED, without the need of external MOSFET or buffer. This high current IR driver can also be used as Barcode Emulation, sending barcode information to external Barcode Reader.

The iCE40 Ultra family of devices are targeting for mobile applications to perform functions such as IrDA, Service LED, Barcode Emulation, GPIO Expander, SDIO Level Shift, and other custom functions.

The iCE40 Ultra family features three device densities, from 1100 to 3520 Look Up Tables (LUTs) of logic with programmable I/Os that can be used as either SPI/I²C interface ports or general purpose I/O's. It also has up to 80 kbits of Block RAMs to work with user logic.

Features

- **Flexible Logic Architecture**
  - Three devices with 1100 to 3520 LUTs
  - Offered in WLCS, ucfBGA and QFN packages
- **Ultra-low Power Devices**
  - Advanced 40 nm ultra-low power process
  - As low as 71 µA standby current typical
- **Embedded Memory**
  - Up to 80 kbits sysMEM™ Embedded Block RAM
- **Two Hardened I²C Interfaces**
- **Two Hardened SPI Interfaces**
- **Two On-Chip Oscillators**
  - Low Frequency Oscillator – 10 kHz
  - High Frequency Oscillator – 48 MHz
- **24 mA Current Drive RGB LED Outputs**
  - Three drive outputs in each device
  - User selectable sink current up to 24 mA
- **500 mA Current Drive IR LED Output**
  - One IR drive output in each device
  - User selectable sink current up to 500 mA
- **On-chip DSP**
  - Signed and unsigned 8-bit or 16-bit functions
  - Functions include Multiplier, Accumulator, and Multiply-Accumulate (MAC)
- **Flexible On-Chip Clocking**
  - Eight low skew global signal resource, six can be directly driven from external pins
  - One PLL with dynamic interface per device
- **Flexible Device Configuration**
  - SRAM is configured through:
    - — Standard SPI Interface
    - — Internal Nonvolatile Configuration Memory (NVCM)
- **Ultra-Small Form Factor**
  - As small as 2.078 mm x 2.078 mm
- **Applications**
  - Smartphones
  - Tablets and Consumer Handheld Devices
  - Handheld Commercial and Industrial Devices
  - Multi Sensor Management Applications
  - Sensor Pre-processing and Sensor Fusion
  - Always-On Sensor Applications
  - USB 3.1 Type C Cable Detect / Power Delivery Applications

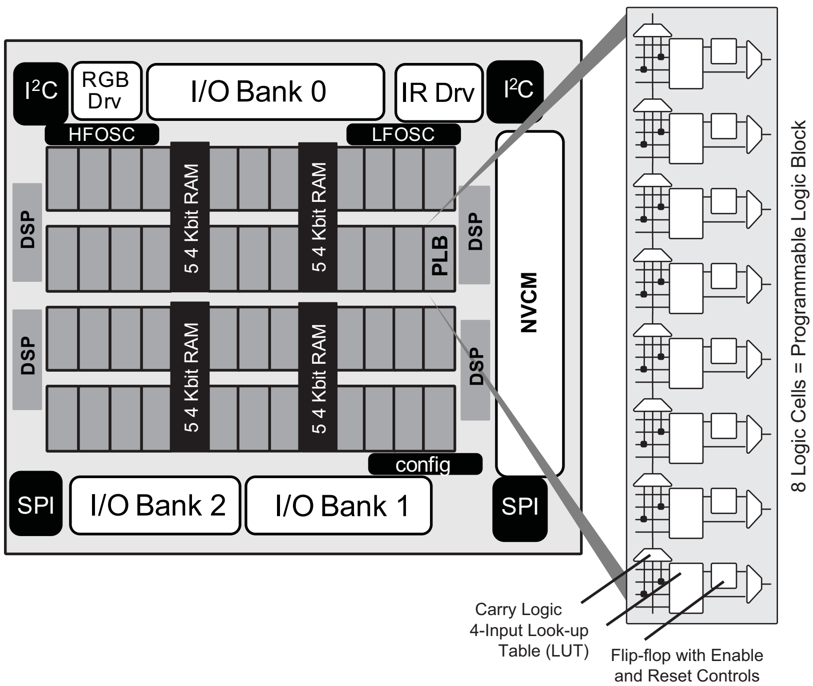
iCE40 Ultra Family Data Sheet
Architecture

June 2016 **Data Sheet DS1048**

Architecture Overview

The iCE40 Ultra family architecture contains an array of Programmable Logic Blocks (PLB), two Oscillator Generators, two user configurable I^{2}C controllers, two user configurable SPI controllers, and blocks of sysMEM™ Embedded Block RAM (EBR) surrounded by Programmable I/O (PIO). Figure 2-1shows the block diagram of the iCE5LP-4K device.

Figure 2-1. iCE5LP-4K Device, Top View



The Programmable Logic Blocks (PLB) and sysMEM EBR blocks, are arranged in a two-dimensional grid with rows and columns. Each column has either PLB or EBR blocks. The PIO cells are located at the top and bottom of the device, arranged in banks. The PLB contains the building blocks for logic, arithmetic, and register functions. The PIOs utilize a flexible I/O buffer referred to as a sysIO buffer that supports operation with a variety of interface standards. The blocks are connected with many vertical and horizontal routing channel resources. The place and route software tool automatically allocates these routing resources.

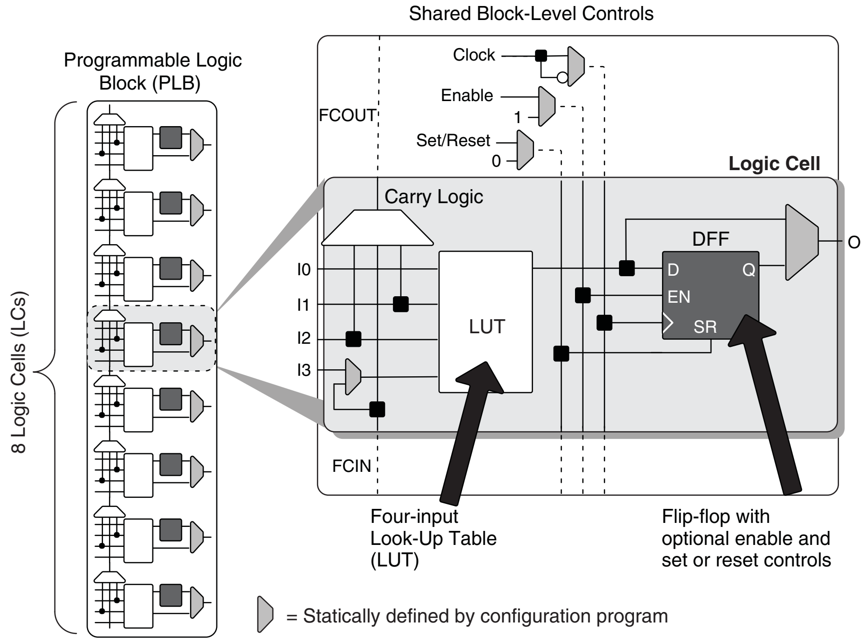
In the iCE40 Ultra family, there are three sysIO banks, one on top and two at the bottom. User can connect some V_{CCIO}s together, if all the I/Os are using the same voltage standard. Refer to the details in later sections of this document on Power Up Sequence. The sysMEM EBRs are large 4 kbit, dedicated fast memory blocks. These blocks can be configured as RAM, ROM or FIFO with user logic using PLBs.

Every device in the family has two user SPI ports, one of these (right side) SPI port also supports programming and configuration of the device. The iCE40 Ultra also includes two user I^{2}C ports, two Oscillators, and high current RGB and IR LED sinks.

PLB Blocks

The core of the iCE40 Ultra device consists of Programmable Logic Blocks (PLB) which can be programmed to perform logic and arithmetic functions. Each PLB consists of eight interconnected Logic Cells (LC) as shown in Figure 2-2. Each LC contains one LUT and one register.

Figure 2-2. PLB Block Diagram



Logic Cells

Each Logic Cell includes three primary logic elements shown in Figure 2-2.

- A four-input Look-Up Table (LUT) builds any combinational logic function, of any complexity, requiring up to four inputs. Similarly, the LUT element behaves as a 16x1 Read-Only Memory (ROM). Combine and cascade multiple LUTs to create wider logic functions.
- A 'D'-style Flip-Flop (DFF), with an optional clock-enable and reset control input, builds sequential logic functions. Each DFF also connects to a global reset signal that is automatically asserted immediately following device configuration.
- Carry Logic boosts the logic efficiency and performance of arithmetic functions, including adders, subtracters, comparators, binary counters and some wide, cascaded logic functions.

Table 2-1. Logic Cell Signal Descriptions

Function	Type	Signal Names	Description
Input	Data signal	I0, I1, I2, I3	Inputs to LUT
Input	Control signal	Enable	Clock enable shared by all LCs in the PLB
Input	Control signal	Set/Reset[1]	Asynchronous or synchronous local set/reset shared by all LCs in the PLB.
Input	Control signal	Clock	Clock one of the eight Global Buffers, or from the general-purpose interconnects fabric shared by all LCs in the PLB
Input	Inter-PLB signal	FCIN	Fast carry in
Output	Data signals	O	LUT or registered output
Output	Inter-PFU signal	FCOUT	Fast carry out

1. If Set/Reset is not used, then the flip-flop is never set/reset, except when cleared immediately after configuration.

sysCLOCK Phase Locked Loops (PLLs)

The sysCLOCK PLLs provide the ability to synthesize clock frequencies. The iCE40 Ultra devices have one sysCLOCK PLL. REFERENCECLK is the reference frequency input to the PLL and its source can come from an external I/O pin, the internal Oscillator Generators from internal routing. EXTFEEDBACK is the feedback signal to the PLL which can come from internal routing or an external I/O pin. The feedback divider is used to multiply the reference frequency and thus synthesize a higher frequency clock output.

The PLLOUT output has an output divider, thus allowing the PLL to generate different frequencies for each output. The output divider can have a value from 1 to 64 (in increments of 2X). The PLLOUT outputs can all be used to drive the iCE40 Ultra global clock network directly or general purpose routing resources can be used.

The LOCK signal is asserted when the PLL determines it has achieved lock and de-asserted if a loss of lock is detected. A block diagram of the PLL is shown in Figure 2-3.

The timing of the device registers can be optimized by programming a phase shift into the PLLOUT output clock which will advance or delay the output clock with reference to the REFERENCECLK clock. This phase shift can be either programmed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after a phase adjustment on the output used as the feedback source and not relock until the tLOCK parameter has been satisfied.

There is an additional feature in the iCE40 Ultra PLL. There are 2 FPGA controlled inputs, SCLK and SDI, that allows the user logic to serially shift in data thru SDI, clocked by SCLK clock. The data shifted in would change the configuration settings of the PLL. This feature allows the PLL to be time multiplexed for different functions, with different clock rates. After the data is shifted in, user would simply pulse the RESET input of the PLL block, and the PLL will re-lock with the new settings. For more details, please refer to TN1251, iCE40 sysCLOCK PLL Design and Usage Guide.

Figure 2-3. PLL Diagram

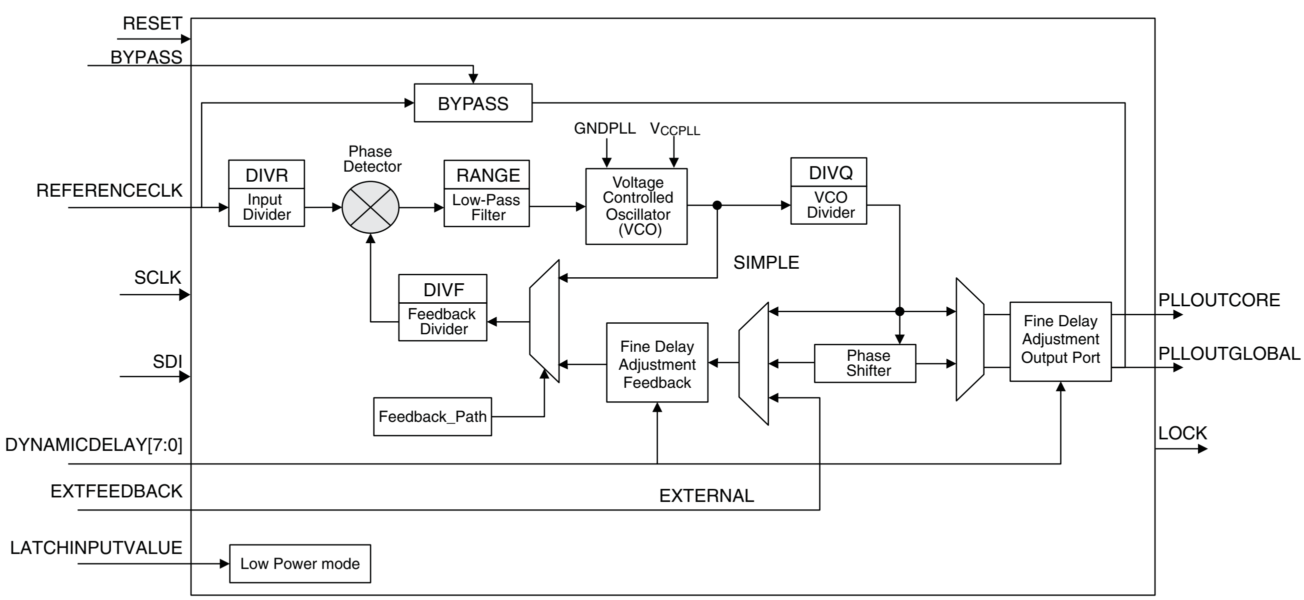


Table 2-3 provides signal descriptions of the PLL block.

Table 2-3. PLL Signal Descriptions

Signal Name	Direction	Description
REFERENCECLK	Input	Input reference clock
BYPASS	Input	The BYPASS control selects which clock signal connects to the PLL-OUT output. 0 = PLL generated signal 1 = REFERENCECLK
EXTFEEDBACK	Input	External feedback input to PLL. Enabled when the FEEDBACK_PATH attribute is set to EXTERNAL.
DYNAMICDELAY[7:0]	Input	Fine delay adjustment control inputs. Enabled when DELAY_ADJUSTMENT_MODE is set to DYNAMIC.
LATCHINPUTVALUE	Input	When enabled, puts the PLL into low-power mode; PLL output is held static at the last input clock value. Set ENABLE ICEGATE_PORTA and PORTB to ‘1’ to enable.
PLLOUTGLOBAL	Output	Output from the Phase-Locked Loop (PLL). Drives a global clock network on the FPGA. The port has optimal connections to global clock buffers GBUF4 and GBUF5.
PLLOUTCORE	Output	Output clock generated by the PLL, drives regular FPGA routing. The frequency generated on this output is the same as the frequency of the clock signal generated on the PLLOUTLGOBAL port.
LOCK	Output	When High, indicates that the PLL output is phase aligned or locked to the input reference clock.
RESET	Input	Active low reset.
SCLK	Input	Input, Serial Clock used for re-programming PLL settings.
SDI	Input	Input, Serial Data used for re-programming PLL settings.

sysMEM Embedded Block RAM Memory

Larger iCE40 Ultra device includes multiple high-speed synchronous sysMEM Embedded Block RAMs (EBRs), each 4 kbit in size. This memory can be used for a wide variety of purposes including data buffering, and FIFO.

sysMEM Memory Block

The sysMEM block can implement single port, pseudo dual port, or FIFO memories with programmable logic resources. Each block can be used in a variety of depths and widths as shown in Table 2-4.

Table 2-4. sysMEM Block Configurations[1]

Block RAM Configuration	Block RAM Configuration and Size	WADDR Port Size (Bits)	WDATA Port Size (Bits)	RADDR Port Size (Bits)	RDATA Port Size (Bits)	MASK Port Size (Bits)
SB_RAM256x16 SB_RAM256x16NR SB_RAM256x16NW SB_RAM256x16NRNW	256x16 (4 k)	8 [7:0]	16 [15:0]	8 [7:0]	16 [15:0]	16 [15:0]
SB_RAM512x8 SB_RAM512x8NR SB_RAM512x8NW SB_RAM512x8NRNW	512x8 (4 k)	9 [8:0]	8 [7:0]	9 [8:0]	8 [7:0]	No Mask Port
SB_RAM1024x4 SB_RAM1024x4NR SB_RAM1024x4NW SB_RAM1024x4NRNW	1024x4 (4 k)	10 [9:0]	4 [3:0]	10 [9:0]	4 [3:0]	No Mask Port
SB_RAM2048x2 SB_RAM2048x2NR SB_RAM2048x2NW SB_RAM2048x2NRNW	2048x2 (4 k)	11 [10:0]	2 [1:0]	11 [10:0]	2 [1:0]	No Mask Port

1. For iCE40 Ultra, the primitive name without "Nxx" uses rising-edge Read and Write clocks. "NR" uses rising-edge Write clock, falling-edge Read clock. "NW" uses falling-edge Write clock and rising-edge Read clock. "NRNW" uses falling-edge clocks on both Read and Write.

RAM Initialization and ROM Operation

If desired, the contents of the RAM can be pre-loaded during device configuration.

By preloading the RAM block during the chip configuration cycle and disabling the write controls, the sysMEM block can also be utilized as a ROM.

Memory Cascading

Larger and deeper blocks of RAM can be created using multiple EBR sysMEM Blocks.

RAM4k Block

Figure 2-4 shows the 256x16 memory configurations and their input/output names. In all the sysMEM RAM modes, the input data and addresses for the ports are registered at the input of the memory array.

Figure 2-4. sysMEM Memory Primitives

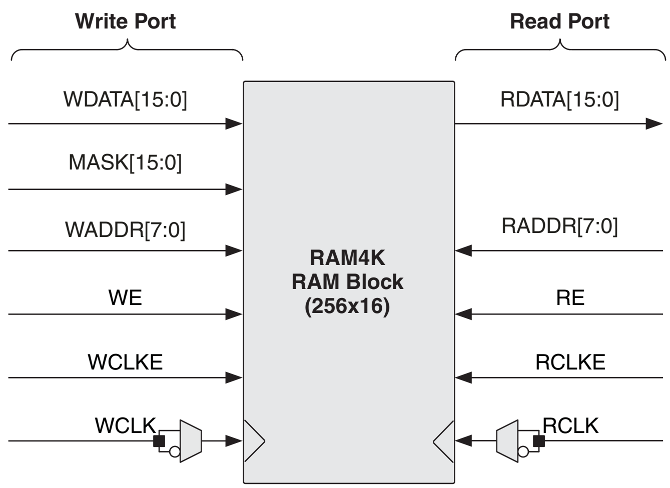


Table 2-5. EBR Signal Descriptions

Signal Name	Direction	Description
WDATA[15:0]	Input	Write Data input.
MASK[15:0]	Input	Masks write operations for individual data bit-lines. 0 = write bit 1 = do not write bit
WADDR[7:0]	Input	Write Address input. Selects one of 256 possible RAM locations.
WE	Input	Write Enable input.
WCLKE	Input	Write Clock Enable input.
WCLK	Input	Write Clock input. Default rising-edge, but with falling-edge option.
RDATA[15:0]	Output	Read Data output.
RADDR[7:0]	Input	Read Address input. Selects one of 256 possible RAM locations.
RE	Input	Read Enable input.
RCLKE	Input	Read Clock Enable input.
RCLK	Input	Read Clock input. Default rising-edge, but with falling-edge option.

For further information on the sysMEM EBR block, please refer to TN1250, Memory Usage Guide for iCE40 Devices.

sysDSP

The iCE40 Ultra family provides an efficient sysDSP architecture that is very suitable for low-cost Digital Signal Processing (DSP) functions for mobile applications. Typical functions used in these applications are Multiply, Accumulate, and Multiply-Accumulate. The block can also be used for simple Add and Subtract functions.

iCE40 Ultra sysDSP Architecture Features

The iCE40 Ultra sysDSP supports many functions that include the following:

- Single 16-bit x 16-bit Multiplier, or two independent 8-bit x 8-bit Multipliers
- Optional independent pipeline control on Input Register, Output Register, and Intermediate Reg faster clock performance
- Single 32-bit Accumulator, or two independent 16-bit Accumulators
- Single 32-bit, or two independent 16-bit Adder/Subtracter functions, registered or asynchronous
- Cascadable to create wider Accumulator blocks

Figure 2-5 shows the block diagram of the sysDSP block. The block consists Multiplier section, with an bypassable Output register. The Input Register, Intermediate register between Multiplier and AC timing to achieve the highest performance.

Figure 2-5. sysDSP Functional Block Diagram (16-bit x 16-bit Multiply-Accumulate)

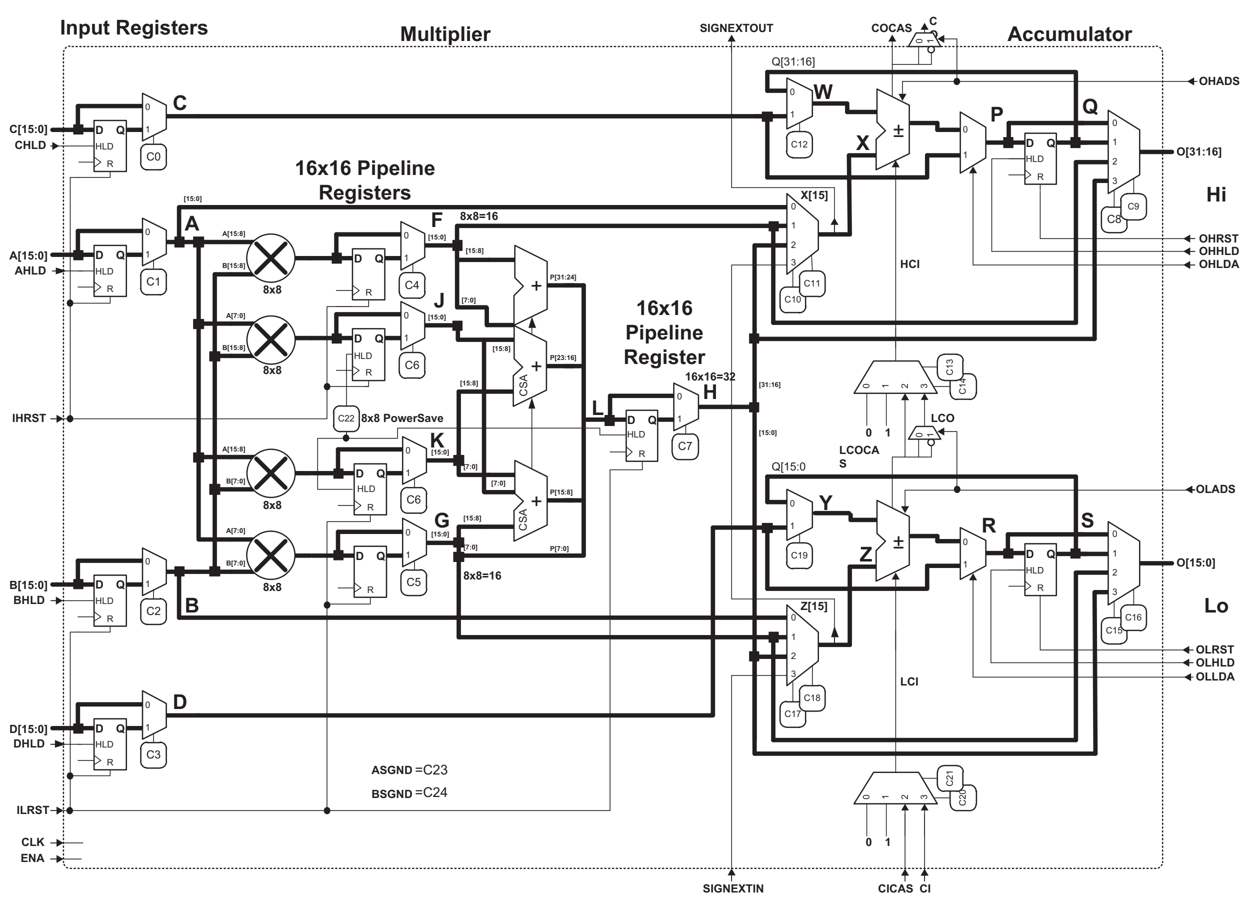


Table 2-6. sysDSP Input/Output List

Signal	Primitive Port Name	Width	Input / Output	Function	Default
CLK	CLK	1	Input	Clock Input. Applies to all clocked elements in the sysDSP block	
ENA	CE	1	Input	Clock Enable Input. Applies to all clocked elements in the sysDSP block. 0 = Not Enabled 1 = Enabled	0: Enabled
A[15:0]	A[15:0]	16	Input	Input to the A Register. Feeds the Multiplier or is a direct input to the Adder Accumulator	16'b0
B[15:0]	B[15:0]	16	Input	Input to the B Register. Feeds the Multiplier or is a direct input to the Adder Accumulator	16'b0
C[15:0]	C[15:0]	16	Input	Input to the C Register. It is a direct input to the Adder Accumulator	16'b0
D[15:0]	D[15:0]	16	Input	Input to the D Register. It is a direct input to the Adder Accumulator	16'b0
AHLD	AHOLD	1	Input	A Register Hold. 0 = Update 1 = Hold	0: Update
BHLD	BHOLD	1	Input	B Register Hold. 0 = Update 1 = Hold	0: Update
CHLD	CHOLD	1	Input	C Register Hold. 0 = Update 1 = Hold	0: Update
DHLD	DHOLD	1	Input	D Register Hold. 0 = Update 1 = Hold	0: Update
IHRST	IRSTTOP	1	Input	Reset input to A and C input registers, and the pipeline registers in the upper half of the Multiplier Section. 0 = No Reset 1 = Reset	0: No Reset
ILRST	IRSTBOT	1	Input	Reset input to B and D input registers, and the pipeline registers in the lower half of the Multiplier Section. It also resets the Multiplier result pipeline register. 0 = No Reset 1 = Reset	0: No Reset
O[31:0]	O[31:0]	32	Output	Output of the sysDSP block. This output can be: — O[31:0] – 32-bit result of 16x16 Multiplier or MAC — O[31:16] – 16-bit result of 8x8 upper half Multiplier or MAC — O[15:0] – 16-bit result of 8x8 lower half Multiplier or MAC	
OHHLD	OHOLDTOP	1	Input	High-order (upper half) Accumulator Register Hold. 0 = Update 1 = Hold	0: Update
OHRST	ORSTTOP	1	Input	Reset input to high-order (upper half) bits of the Accumulator Register. 0 = No Reset 1 = Reset	0: No Reset

User I²C IP

The iCE40 Ultra devices have two I²C IP cores. Either of the two cores can be configured either as an I²C master or as an I²C slave. The pins for the I²C interface are not pre-assigned. User can use any General Purpose I/O pins.

In each of the two cores, there are options to delay the either the input or the output, or both, by 50 ns nominal, using dedicated on-chip delay elements. This provides an easier interface with any external I²C components.

When the IP core is configured as master, it will be able to control other devices on the I²C bus through the pre-assigned pin interface. When the core is configured as the slave, the device will be able to provide I/O expansion to an I²C Master. The I²C cores support the following functionality:

- Master and Slave operation
- 7-bit and 10-bit addressing
- Multi-master arbitration support
- Clock stretching
- Up to 400 kHz data transfer speed
- General Call support
- Optionally delaying input or output data, or both

For further information on the User I²C, please refer to TN1274, iCE40 SPI/I2C Hardened IP Usage Guide.

User SPI IP

The iCE40 Ultra devices have two SPI IP cores. The pins for the SPI interface are not pre-assigned. User can use any General Purpose I/O pins. Both SPI IP cores can be configured as a SPI master or as a slave. When the SPI IP core is configured as a master, it controls the other SPI enabled devices connected to the SPI Bus. When SPI IP core is configured as a slave, the device will be able to interface to an external SPI master.

The SPI IP core supports the following functions:

- Configurable Master and Slave modes
- Full-Duplex data transfer
- Mode fault error flag with CPU interrupt capability
- Double-buffered data register
- Serial clock with programmable polarity and phase
- LSB First or MSB First Data Transfer

For further information on the User SPI, please refer to TN1274, iCE40 SPI/I2C Hardened IP Usage Guide.

High Current LED Drive I/O Pins

The iCE40 Ultra family devices offer multiple high current LED drive outputs in each device in the family to allow the iCE40 Ultra product to drive LED signals directly on mobile applications.

There are three outputs on each device that can sink up to 24 mA current. These outputs are open-drain outputs, and provides sinking current to an LED connecting to the positive supply. These three outputs are designed to drive the RBG LEDs, such as the service LED found in a lot of mobile devices. An embedded RGB PWM IP is also offered in the family. This RGB drive current is user programmable from 4 mA to 24 mA, in increments of 4 mA. This output functions as General Purpose I/O with open-drain when the high current LED drive is not needed.

There is one output on each device that can sink up to 500 mA current. This output is open-drain, and provides sinking current to drive an external IR LED connecting to the positive supply. This IR drive current is user programmable from 50 mA to 500 mA in increments of 50 mA. This output functions as General Purpose I/O with open-drain when the high current LED drive is not needed.

Embedded PWM IP

To provide an easier usage of the RGB high current drivers to drive RGB LED, a Pulse-Width Modulator IP can be embedded into the user design. This PWM IP provides the flexibility for user to dynamically change the settings on the ON-time duration, OFF-time duration, and ability to turn the LED lights on and off gradually with user set breath-on and breath-off time.

For additional information on the embedded PWM IP, please refer to TN1288, iCE40 LED Driver Usage Guide.

Non-Volatile Configuration Memory

All iCE40 Ultra devices provide a Non-Volatile Configuration Memory (NVCM) block which can be used to configure the device.

For more information on the NVCM, please refer to TN1248, iCE40 Programming and Configuration.

iCE40 Ultra Programming and Configuration

This section describes the programming and configuration of the iCE40 Ultra family.

Device Programming

The NVCM memory can be programmed through the SPI port. The SPI port is located in Bank 1, using SPI_V_{CCIO1} power supply.

Device Configuration

There are various ways to configure the Configuration RAM (CRAM), using SPI port, including:

- From a SPI Flash (Master SPI mode)
- System microprocessor to drive a Serial Slave SPI port (SSPI mode)

For more details on configuring the iCE40 Ultra, please see TN1248, iCE40 Programming and Configuration.

Power Saving Options

The iCE40 Ultra devices feature iCEGate and PLL low power mode to allow users to meet the static and dynamic power requirements of their applications. Table 2-10 describes the function of these features.

Table 2-10. iCE40 Ultra Power Saving Features Description

Device Subsystem	Feature Description
PLL	When LATCHINPUTVALUE is enabled, puts the PLL into low-power mode; PLL output held static at last input clock value.
iCEGate	To save power, the optional iCEGate latch can selectively freeze the state of individual, non-registered inputs within an I/O bank. Registered inputs are effectively frozen by their associated clock or clock-enable control.

Absolute Maximum Ratings[1, 2, 3]

Supply Voltage V_{CC} . . . . –0.5 V to 1.42 V

Output Supply Voltage V_{CCIO} . . . . –0.5 V to 3.60 V

NVCM Supply Voltage V_{PP_2V5} . . . . –0.5 V to 3.60 V

PLL Supply Voltage V_{CCPLL} . . . . –0.5 V to 1.42 V

I/O Tri-state Voltage Applied. . . . . –0.5 V to 3.60 V

Dedicated Input Voltage Applied . . . . –0.5 V to 3.60 V

Storage Temperature (Ambient). . . . . –65 °C to 150 °C

Junction Temperature (T_J) . . . . –65 °C to 125 °C

1. Stress above those listed under the “Absolute Maximum Ratings” may cause permanent damage to the device. Functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.
2. Compliance with the Lattice Thermal Management document is required.
3. All voltages referenced to GND.

Recommended Operating Conditions[1]

Symbol	Parameter		Min.	Max.	Units
V_{CC}[1]	Core Supply Voltage		1.14	1.26	V
V_{PP_2V5}	VPP_2V5 NVCM Programming and Operating Supply Voltage	Slave SPI Configuration	1.71[4]	3.46	V
		Master SPI Configuration	2.30	3.46	V
		Configuration from NVCM	2.30	3.46	V
		NVCM Programming	2.30	3.00	V
V_{CCIO}[1, 2, 3]	I/O Driver Supply Voltage	V_{CCIO_0}, SPI_V_{CCIO1}, V_{CCIO_2}	1.71	3.46	V
V_{CCPLL}	PLL Supply Voltage		1.14	1.26	V
t_{JCOM}	Junction Temperature Commercial Operation		0	85	°C
t_{JIND}	Junction Temperature Industrial Operation		–40	100	°C
t_{PROG}	Junction Temperature NVCM Programming		10.00	30.00	°C

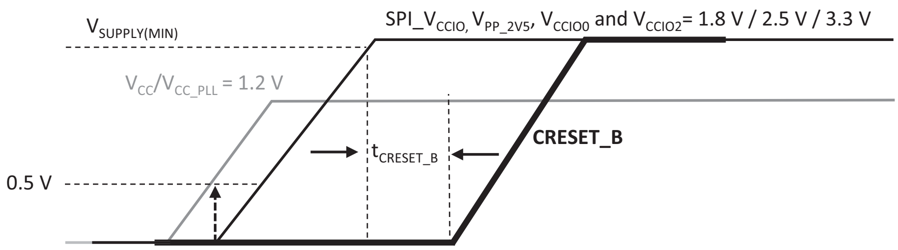
1. Like power supplies must be tied together if they are at the same supply voltage and they meet the power up sequence requirement. Please refer to Power-Up Supply Sequencing section. V_{CC} and V_{CCPLL} are recommended to tie to same supply with an RC-based noise filter between them. Please refer to TN1252, iCE40 Hardware Checklist.
2. See recommended voltages by I/O standard in subsequent table.
3. V_{CCIO} pins of unused I/O banks should be connected to the V_{CC} power supply on boards.
4. V_{PP_2V5} can, optionally, be connected to a 1.8 V (+/-5%) power supply in Slave SPI Configuration mode subject to the condition that none of the HFOSC/LFOSC and RGB LED / IR LED driver features are used. Otherwise, V_{PP_2V5} must be connected to a power supply with a minimum 2.30 V level.

Power Supply Ramp Rates[1, 2]

Symbol	Parameter	Min.	Max.	Units
t_{RAMP}	Power supply ramp rates for all power supplies.	0.6	10	V/ms

1. Assumes monotonic ramp rates.
2. Power up sequence must be followed. Please refer to Power-Up Supply Sequencing section.

Figure 3-2. Power Up Sequence with All Supplies Connected Together



Power-On-Reset Voltage Levels[1]

Symbol	Parameter		Min.	Max.	Units
V_{PORUP}	Power-On-Reset ramp-up trip point (circuit monitoring V_{CC}, SPI_V_{CCIO1}, V_{PP_2V5})	V_{CC}	0.62	0.92	V
		SPI_V_{CCIO1}	0.87	1.50	V
		V_{PP_2V5}	0.90	1.53	V
V_{PORDN}	Power-On-Reset ramp-down trip point (circuit monitoring V_{CC}, SPI_V_{CCIO1}, V_{PP_2V5})	V_{CC}	—	0.79	V
		SPI_V_{CCIO1}	—	1.50	V
		V_{PP_2V5}	—	1.53	V

1. These POR trip points are only provided for guidance. Device operation is only characterized for power supply voltages specified under recommended operating conditions.

ESD Performance

Please contact Lattice Semiconductor for additional information.

DC Electrical Characteristics

Over Recommended Operating Conditions

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
I_{IL}, I_{IH}[1, 3, 4]	Input or I/O Leakage	$0V < V_{IN} < V_{CCIO} + 0.2$ V	—	—	+/–10	µA
C_1	I/O Capacitance, excluding LED Drivers[2]	V_{CCIO} = 3.3 V, 2.5 V, 1.8 V V_{CC} = Typ., V_{IO} = 0 to V_{CCIO} + 0.2 V	—	6	—	pF
C_2	Global Input Buffer Capacitance[2]	V_{CCIO} = 3.3 V, 2.5 V, 1.8 V V_{CC} = Typ., V_{IO} = 0 to V_{CCIO} + 0.2 V	—	6	—	pF
C_3	RGB Pin Capacitance[2]	V_{CC} = Typ., V_{IO} = 0 to 3.5 V	—	15	—	pF
C_4	IRLED Pin Capacitance[2]	V_{CC} = Typ., V_{IO} = 0 to 3.5 V	—	53	—	pF
V_{HYST}	Input Hysteresis	V_{CCIO} = 1.8 V, 2.5 V, 3.3 V	—	200	—	mV
I_{PU}	Internal PIO Pull-up Current	V_{CCIO} = 1.8 V, $0 \le V_{IN} \le 0.65\ V_{CCIO}$	–3	—	–31	µA
		V_{CCIO} = 2.5 V, $0 \le V_{IN} \le 0.65\ V_{CCIO}$	–8	—	–72	µA
		V_{CCIO} = 3.3 V, $0 \le V_{IN} \le 0.65\ V_{CCIO}$	–11	—	–128	µA

1. Input or I/O leakage current is measured with the pin configured as an input or as an I/O with the output driver tri-stated. It is not measured with the output driver active. Internal pull-up resistors are disabled.
2. T_J 25 °C, f = 1.0 MHz.
3. Please refer to V_{IL} and V_{IH} in the sysIO Single-Ended DC Electrical Characteristics table of this document.
4. Input pins are clamped to V_{CCIO} and GND by a diode. When input is higher than V_{CCIO} or lower than GND, the Input Leakage current will be higher than the I_{IL} and I_{IH}.

Internal Oscillators (HFOSC, LFOSC)[1]

Parameter		Parameter Description	Spec/Recommended			Units
Symbol	Conditions		Min	Typ	Max	
f_{CLKHF}	Commercial Temp	HFOSC clock frequency (t_J = 0 °C–85 °C)	–10%	48	10%	MHz
	Industrial Temp	HFOSC clock frequency (t_J = –40 °C–100 °C)	–20%	48	20%	MHz
f_{CLKLF}		LFOSC CLKK clock frequency	–10%	10	10%	kHz
DCH_{CLKHF}	Commercial Temp	HFOSC clock frequency (t_J = 0 °C–85 °C)	45	50	55	%
	Industrial Temp	HFOSC clock frequency (t_J = –45 °C–100 °C)	40	50	60	%
DCH_{CLKLF}		LFOSC Duty Cycle (Clock High Period)	45	50	55	%
Tsync_on		Oscillator output synchronizer delay	—	—	5	Cycles
Tsync_off		Oscillator output disable delay	—	—	5	Cycles

1. Glitchless enabling and disabling OSC clock outputs.

sysIO Recommended Operating Conditions

Standard	V_{CCIO} (V)		
	Min.	Typ.	Max.
LVCMOS 3.3	3.14	3.3	3.46
LVCMOS 2.5	2.37	2.5	2.62
LVCMOS 1.8	1.71	1.8	1.89

sysIO Single-Ended DC Electrical Characteristics

Input/ Output Standard	V_{IL}		V_{IH}		V_{OL} Max. (V)	V_{OH} Min. (V)	I_{OL} Max. (mA)	I_{OH} Max. (mA)
	Min. (V)	Max. (V)	Min. (V)	Max. (V)				
LVCMOS 3.3	–0.3	0.8	2.0	V_{CCIO} + 0.2V	0.4	V_{CCIO} – 0.4	8	–8
					0.2	V_{CCIO} – 0.2	0.1	–0.1
LVCMOS 2.5	–0.3	0.7	1.7	V_{CCIO} + 0.2V	0.4	V_{CCIO} – 0.4	6	–6
					0.2	V_{CCIO} – 0.2	0.1	–0.1
LVCMOS 1.8	–0.3	0.35V_{CCIO}	0.65V_{CCIO}	V_{CCIO} + 0.2V	0.4	V_{CCIO} – 0.4	4	–4
					0.2	V_{CCIO} – 0.2	0.1	–0.1

Differential Comparator Electrical Characteristics

Parameter Symbol	Parameter Description	Test Conditions	Min.	Max.	Units
V_{REF}	Reference Voltage to compare, on V_{INM}	V_{CCIO} = 2.5 V	0.25	V_{CCIO} –0.25 V	V
V_{DIFFIN_H}	Differential input HIGH (V_{INP} - V_{INM})	V_{CCIO} = 2.5 V	250	—	mV
V_{DIFFIN_L}	Differential input LOW (V_{INP} - V_{INM})	V_{CCIO} = 2.5 V	—	–250	mV
I_{IN}	Input Current, V_{INP} and V_{INM}	V_{CCIO} = 2.5 V	–10	10	µA

Typical Building Block Function Performance[1, 2]

Pin-to-Pin Performance (LVCMOS25)

Function	Timing	Units
Basic Functions		
16-bit decoder	16.5	ns
4:1 MUX	18.0	ns
16:1 MUX	19.5	ns

Register-to-Register Performance

Function	Timing	Units
Basic Functions		
16:1 MUX	110	MHz
16-bit adder	100	MHz
16-bit counter	100	MHz
64-bit counter	40	MHz
Embedded Memory Functions		
256x16 Pseudo-Dual Port RAM	150	MHz

1. The above timing numbers are generated using the Lattice Design Software tool. Exact performance may vary with device and tool version. The tool uses internal parameters that have been characterized but are not tested on every device.
2. Under worst case operating conditions.

Derating Logic Timing

Logic timing provided in the following sections of the data sheet and the Lattice design tools are worst case numbers in the operating range. Actual delays may be much faster. Lattice design tools can provide logic timing numbers at a particular temperature and voltage.

Maximum sysIO Buffer Performance[1]

I/O Standard	Max. Speed	Units
Inputs		
LVCMOS33	250	MHz
LVCMOS25	250	MHz
LVCMOS18	250	MHz
Outputs		
LVCMOS33	250	MHz
LVCMOS25	250	MHz
LVCMOS18	155	MHz

1. Measured with a toggling pattern

sysCLOCK PLL Timing

Over Recommended Operating Conditions

Parameter	Descriptions	Conditions	Min.	Max.	Units
f_{IN}	Input Clock Frequency (REFERENCECLK, EXTFEEDBACK)		10	133	MHz
f_{OUT}	Output Clock Frequency (PLLOUT)		16	275	MHz
f_{VCO}	PLL VCO Frequency		533	1066	MHz
f_{PFD}	Phase Detector Input Frequency		10	133	MHz
AC Characteristics					
t_{DT}	Output Clock Duty Cycle		40	60	%
t_{PH}	Output Phase Accuracy		—	+/–12	deg
t_{OPJIT}[1, 5, 6]	Output Clock Period Jitter	f_{OUT} >= 100 MHz	—	450	ps p-p
		f_{OUT} < 100 MHz	—	0.05	UIPP
	Output Clock Cycle-to-cycle Jitter	f_{OUT} >= 100 MHz	—	750	ps p-p
		f_{OUT} < 100 MHz	—	0.10	UIPP
	Output Clock Phase Jitter	f_{PFD} >= 25 MHz	—	275	ps p-p
		f_{PFD} < 25 MHz	—	0.05	UIPP
t_W	Output Clock Pulse Width	At 90% or 10%	1.33	—	ns
t_{LOCK}[2, 3]	PLL Lock-in Time		—	50	µs
t_{UNLOCK}	PLL Unlock Time		—	50	ns
t_{IPJIT}[4]	Input Clock Period Jitter	$f_{PFD} \geq$ 20 MHz	—	1000	ps p-p
		f_{PFD} < 20 MHz	—	0.02	UIPP
t_{STABLE}[3]	LATCHINPUTVALUE LOW to PLL Stable		—	500	ns
t_{STABLE_PW}[3]	LATCHINPUTVALUE Pulse Width		100	—	ns
t_{RST}	RESET Pulse Width		10	—	ns
t_{RSTREC}	RESET Recovery Time		10	—	µs
$t_{DYNAMIC\_WD}$	DYNAMICDELAY Pulse Width		100	—	VCO Cycles

1. Period jitter sample is taken over 10,000 samples of the primary PLL output with a clean reference clock. Cycle-to-cycle jitter is taken over 1000 cycles. Phase jitter is taken over 2000 cycles. All values per JESD65B.
2. Output clock is valid after t_{LOCK} for PLL reset and dynamic delay adjustment.
3. At minimum f_{PFD}. As the f_{PFD} increases the time will decrease to approximately 60% the value listed.
4. Maximum limit to prevent PLL unlock from occurring. Does not imply the PLL will operate within the output specifications listed in this table.
5. The jitter values will increase with loading of the PLD fabric and in the presence of SSO noise.

sysDSP Timing

Over Recommended Operating Conditions

Parameter	Description	Min.	Max.	Units
$f_{MAX8x8SMULT}$	Max frequency signed MULT8x8 bypassing pipeline register	50	—	MHz
$f_{MAX16x16SMULT}$	Max frequency signed MULT16x16 bypassing pipeline register	50	—	MHz

SPI Master or NVCM Configuration Time[1, 2]

Symbol	Parameter	Conditions	Max.	Units
t_{CONFIG}	POR/CRESET_B to Device I/O Active	All devices – Low Frequency (Default)	95	ms
		All devices – Medium frequency	35	ms
		All devices – High frequency	18	ms

1. Assumes sysMEM Block is initialized to an all zero pattern if they are used.
2. The NVCM download time is measured with a fast ramp rate starting from the maximum voltage of POR trip point.

sysCONFIG Port Timing Specifications

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
All Configuration Modes						
t_{CRESET_B}	Minimum CRESET_B LOW pulse width required to restart configuration, from falling edge to rising edge		200	—	—	ns
t_{DONE_IO}	Number of configuration clock cycles after CDONE goes HIGH before the PIO pins are activated		49	—	—	Clock Cycles
Slave SPI						
t_{CR_SCK}	Minimum time from a rising edge on CRESET_B until the first SPI WRITE operation, first SPI_XCK clock. During this time, the iCE40 Ultra device is clearing its internal configuration memory		1200	—	—	µs
f_{MAX}	CCLK clock frequency	Write	1	—	25	MHz
		Read[1]	—	15	—	MHz
t_{CCLKH}	CCLK clock pulsewidth HIGH		20	—	—	ns
t_{CCLKL}	CCLK clock pulsewidth LOW		20	—	—	ns
t_{STSU}	CCLK setup time		12	—	—	ns
t_{STH}	CCLK hold time		12	—	—	ns
t_{STCO}	CCLK falling edge to valid output		13	—	—	ns
Master SPI[3]						
f_{MCLK}	MCLK clock frequency	Low Frequency (Default)	7.0	12.0	17.0	MHz
		Medium Frequency[2]	21.0	33.0	45.0	MHz
		High Frequency[2]	33.0	53.0	71.0	MHz
t_{MCLK}	CRESET_B HIGH to first MCLK edge		1200	—	—	µs
t_{SU}	CCLK setup time[4]		9.9	—	—	ns
t_{HD}	CCLK hold time		1	—	—	ns

1. Supported with 1.2 V Vcc and at 25 °C.
2. Extended range fMAX Write operations support up to 53 MHz with 1.2 V Vcc and at 25 °C.
3. t_{SU} and t_{HD} timing must be met for all MCLK frequency choices.
4. For considerations of SPI Master Configuration Mode, please refer to TN1248, iCE40 Programming and Configuration.

Signal Name		Function	I/O	Description
PIOB_33b	SPI_SI	Configuration	Input	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin receives data from external SPI memory. In Slave SPI mode, this pin connects to the MOSI pin of the external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
PIOB_35b	SPI_SS_B	Configuration	I/O	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin outputs to the external SPI memory. In Slave SPI mode, this pin inputs from the external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
Global Signals				
Primary	Secondary			
PIOT_46b	G0	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G0 pin drives the GBUF0 global buffer
PIOT_45a	G1	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G1 pin drives the GBUF1 global buffer
PIOT_25b	G3	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G3 pin drives the GBUF3 global buffer
PIOT_12a	G4	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G4 pin drives the GBUF4 global buffer
PIOT_11b	G5	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G5 pin drives the GBUF5 global buffer
PIOB_3b	G6	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function
		Global	Input	Global input used for high fanout, or clock/reset net. The G6 pin drives the GBUF6 global buffer
LED Signals				
RGB0		General I/O	Open-Drain I/O	In user mode, with user's choice, this pin can be programmed as open drain I/O in user function
		LED	Open-Drain Output	In user mode, with user's choice, this pin can be programmed as open drain 24mA output to drive external LED
RGB1		General I/O	Open-Drain I/O	In user mode, with user's choice, this pin can be programmed as open drain I/O in user function
		LED	Open-Drain Output	In user mode, with user's choice, this pin can be programmed as open drain 24mA output to drive external LED

iCE40 Ultra Family Data Sheet
Ordering Information

June 2016 **Data Sheet DS1048**

iCE5LP Part Number Description

iCE5LPXX-XXXXXITR

Device Family
iCE5LP FPGA

Logic Cells
1K = 1,100 Logic Cells
2K = 2,048 Logic Cells
4K = 3,520 Logic Cells

All parts are shipped in tape-and-reel.

TR
TR = Tape and Reel (See quantity below)
TR50 = Tape and Reel, 50 units
TR1K = Tape and Reel, 1,000 units

Grade
I = Industrial

Package
CM36 = 36-Ball ucfBGA (0.40 mm Ball Pitch)
SWG36 = 36-Ball WLCSP (0.35 mm Ball Pitch)
SG48 = 48-Pin QFN (0.50 mm Pin Pitch)

Tape and Reel Quantity

Package	TR Quantity
CM36	4,000
SWG36	5,000
SG48	2,000

Date	Version	Section	Change Summary
			Updated Supply Current section. — Corrected $I_{PP2V5STDBY}$ parameter. — Added Typ. VCC = 1.2 V values for I_{CCPEAK}, $I_{PP\_2V5PEAK}$, $I_{SPI\_VCCIO1PEAK}$, and $I_{CCIOPEAK}$. — Added footnote 5. — Corrected S_{PI_VCCIO1} character format.
			Updated User SPI Specifications section. Removed parameters and added footnotes.
			Updated Internal Oscillators (HFOSC, LFOSC) section. Added Commercial and Industrial Temp values for DCH_{CLKHF}.
			Updated sysIO Single-Ended DC Electrical Characteristics section. Removed footnote.
			Updated Register-to-Register Performance section. Modified footnotes.
			Updated iCE40 Ultra External Switching Characteristics section. Modified footnote.
			Updated sysCLOCK PLL Timing section. Reversed t_{OPJIT} conditions.
			Updated sysCONFIG Port Timing Specifications section. — Modified t_{CR_SCK} Min. value. — Added footnote 4 to t_{SU} parameter. — Modified t_{SU} Min. value. — Modified t_{HD} parameter.
			Updated section heading to RGB LED and IR LED Drive. Modified ILED_ACCURACY and IIR_ACCURACY parameters, Min. and Max. values.
		Pinout Information	Updated Signal Descriptions section. Changed V_{CCIO_1} to SPI_V_{CCIO1} in the CDONE, CRESETB and PIOB_xx descriptions.
			Updated Pin Information Summary section. — Corrected symbol character format. — Corrected VCPP_2V5 to V_{PP_2V5}.
	1.9	Introduction	Updated Features section. Updated BGA package to ucfBGA.
		DC and Switching Characteristics	Updated Differential Comparator Electrical Characteristics section. Corrected typo in V_{REF} Max. value.
		Pinout Information	Updated Signal Descriptions section. — Changed PIOB_12a to PIOB_xx — Changed SPI_CSN to SPI_SS_B and revised description when in Slave SPI mode. — Corrected minor typo errors.
			Updated Pin Information Summary section. Added footnote to SG48.
		Ordering Information	Updated iCE5LP Part Number Description section. Updated BGA package to ucfBGA.
			Updated Ordering Part Numbers section. Updated BGA package to ucfBGA.
June 2015	1.8	DC and Switching Characteristics	Updated Internal Oscillators (HFOSC, LFOSC) section. Removed decimals.
		Ordering Information	Updated iCE5LP Part Number Description section. — Added TR items. — Corrected formatting errors.
			Updated Ordering Part Numbers section. Updated CM36 and SG48 packages.