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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Obsolete
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	150MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, SD, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	95
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 53x16b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LBGA
Supplier Device Package	144-MAPBGA (13x13)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/pk61fn1m0vmd15">https://www.e-xfl.com/product-detail/nxp-semiconductors/pk61fn1m0vmd15</a>

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## 4.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level	—	3	—	1

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

## 4.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
$V_{HBM}$	Electrostatic discharge voltage, human body model	-2000	+2000	V	1
$V_{CDM}$	Electrostatic discharge voltage, charged-device model	-500	+500	V	2
$I_{LAT}$	Latch-up current at ambient temperature of 105°C	-100	+100	mA	

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.

## 4.4 Voltage and current operating ratings

Symbol	Description	Min.	Max.	Unit
$V_{DD}$	Digital supply voltage <sup>1</sup>	-0.3	3.8	V
$I_{DD}$	Digital supply current	—	300	mA
$V_{DIO}$	Digital input voltage (except RESET, EXTAL0/XTAL0, and EXTAL1/XTAL1) <sup>2</sup>	-0.3	5.5	V
$V_{AIO}$	Analog <sup>3</sup> , RESET, EXTAL0/XTAL0, and EXTAL1/XTAL1 input voltage	-0.3	$V_{DD} + 0.3$	V
$I_D$	Maximum current single pin limit (applies to all digital pins)	-25	25	mA
$V_{DDA}$	Analog supply voltage	$V_{DD} - 0.3$	$V_{DD} + 0.3$	V
$V_{USB\_DP}$	USB_DP input voltage	-0.3	3.63	V
$V_{USB\_DM}$	USB_DM input voltage	-0.3	3.63	V
$V_{REGIN}$	USB regulator input	-0.3	6.0	V
$V_{BAT}$	RTC battery supply voltage	-0.3	3.8	V

1. It applies for all port pins.
2. It covers digital pins.
3. Analog pins are defined as pins that do not have an associated general purpose I/O port function.

**Table 2. LVD and POR operating requirements (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{LVW1H}$	Low-voltage warning thresholds — high range • Level 1 falling ( $LVWV=00$ )	2.62	2.70	2.78	V	1
$V_{LVW2H}$	• Level 2 falling ( $LVWV=01$ )	2.72	2.80	2.88	V	
$V_{LVW3H}$	• Level 3 falling ( $LVWV=10$ )	2.82	2.90	2.98	V	
$V_{LVW4H}$	• Level 4 falling ( $LVWV=11$ )	2.92	3.00	3.08	V	
$V_{HYSH}$	Low-voltage inhibit reset/recover hysteresis — high range	—	$\pm 80$	—	mV	
$V_{LVDL}$	Falling low-voltage detect threshold — low range ( $LVDV=00$ )	1.54	1.60	1.66	V	
$V_{LVW1L}$	Low-voltage warning thresholds — low range • Level 1 falling ( $LVWV=00$ )	1.74	1.80	1.86	V	1
$V_{LVW2L}$	• Level 2 falling ( $LVWV=01$ )	1.84	1.90	1.96	V	
$V_{LVW3L}$	• Level 3 falling ( $LVWV=10$ )	1.94	2.00	2.06	V	
$V_{LVW4L}$	• Level 4 falling ( $LVWV=11$ )	2.04	2.10	2.16	V	
$V_{HYSL}$	Low-voltage inhibit reset/recover hysteresis — low range	—	$\pm 60$	—	mV	
$V_{BG}$	Bandgap voltage reference	0.97	1.00	1.03	V	
$t_{LPO}$	Internal low power oscillator period factory trimmed	900	1000	1100	$\mu s$	

1. Rising thresholds are falling threshold + hysteresis voltage

**Table 3. VBAT power operating requirements**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{POR\_VBAT}$	Falling VBAT supply POR detect voltage	0.8	1.1	1.5	V	

### 5.2.3 Voltage and current operating behaviors

**Table 4. Voltage and current operating behaviors**

Symbol	Description	Min.	Max.	Unit	Notes
$V_{OH}$	Output high voltage — high drive strength • $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$ , $I_{OH} = -9\text{mA}$	$V_{DD} - 0.5$	—	V	
	• $1.71 \text{ V} \leq V_{DD} \leq 2.7 \text{ V}$ , $I_{OH} = -3\text{mA}$	$V_{DD} - 0.5$	—	V	
	Output high voltage — low drive strength • $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$ , $I_{OH} = -2\text{mA}$	$V_{DD} - 0.5$	—	V	
	• $1.71 \text{ V} \leq V_{DD} \leq 2.7 \text{ V}$ , $I_{OH} = -0.6\text{mA}$	$V_{DD} - 0.5$	—	V	

Table continues on the next page...

### 5.2.5.1 Diagram: Typical IDD\_RUN operating behavior

The following data was measured under these conditions:

- MCG in FBE mode for 50 MHz and lower frequencies. MCG in FEE mode at greater than 50 MHz frequencies. MCG in PEE mode is greater than 100 MHz frequencies.
- USB regulator disabled
- No GPIOs toggled
- Code execution from flash with cache enabled
- For the ALLOFF curve, all peripheral clocks are disabled except FTFL

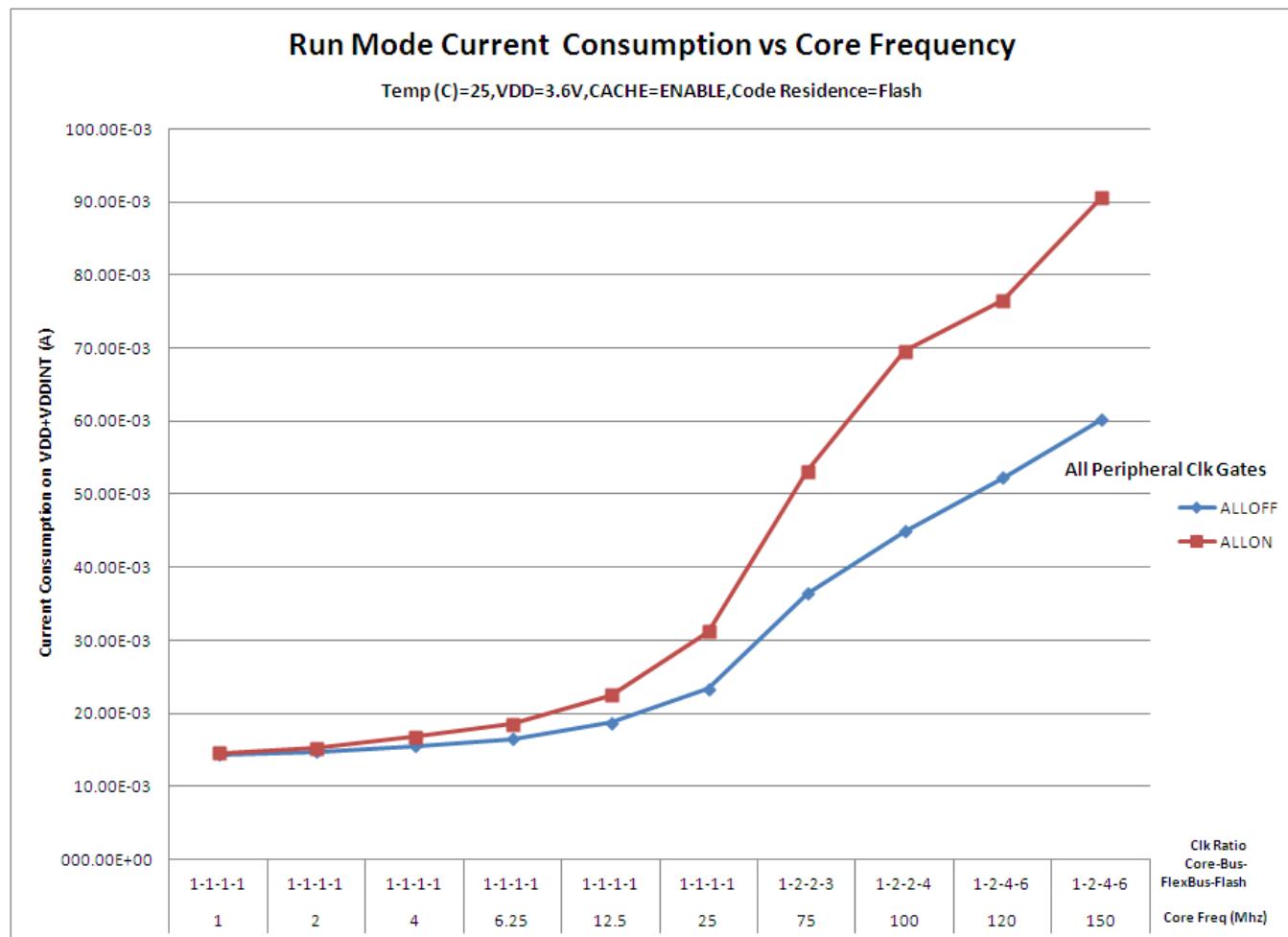


Figure 2. Run mode supply current vs. core frequency

## Peripheral operating requirements and behaviors

Board type	Symbol	Description	144 LQFP	144 MAPBGA	Unit	Notes
—	$\Psi_{JT}$	Thermal characterization parameter, junction to package top outside center (natural convection)	2	2	°C/W	4

1. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)*, or EIA/JEDEC Standard JESD51-6, *Integrated Circuit Thermal Test Method Environmental Conditions—Forced Convection (Moving Air)*.
2. Determined according to JEDEC Standard JESD51-8, *Integrated Circuit Thermal Test Method Environmental Conditions—Junction-to-Board*.
3. Determined according to Method 1012.1 of MIL-STD 883, *Test Method Standard, Microcircuits*, with the cold plate temperature used for the case temperature. The value includes the thermal resistance of the interface material between the top of the package and the cold plate.
4. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)*.

## 5.5 Power sequencing

Voltage supplies must be sequenced in the proper order to avoid damaging internal diodes. There is no limit on how long after one supply powers up before the next supply must power up. Note that  $V_{DD}$  and  $V_{DD\_INT}$  can use the same power source.

The power-up sequence is:

1.  $V_{DD}$
2.  $V_{DD\_INT}$
3.  $V_{DDA}$
4.  $V_{DD\_DDR}$

The power-down sequence is the reverse:

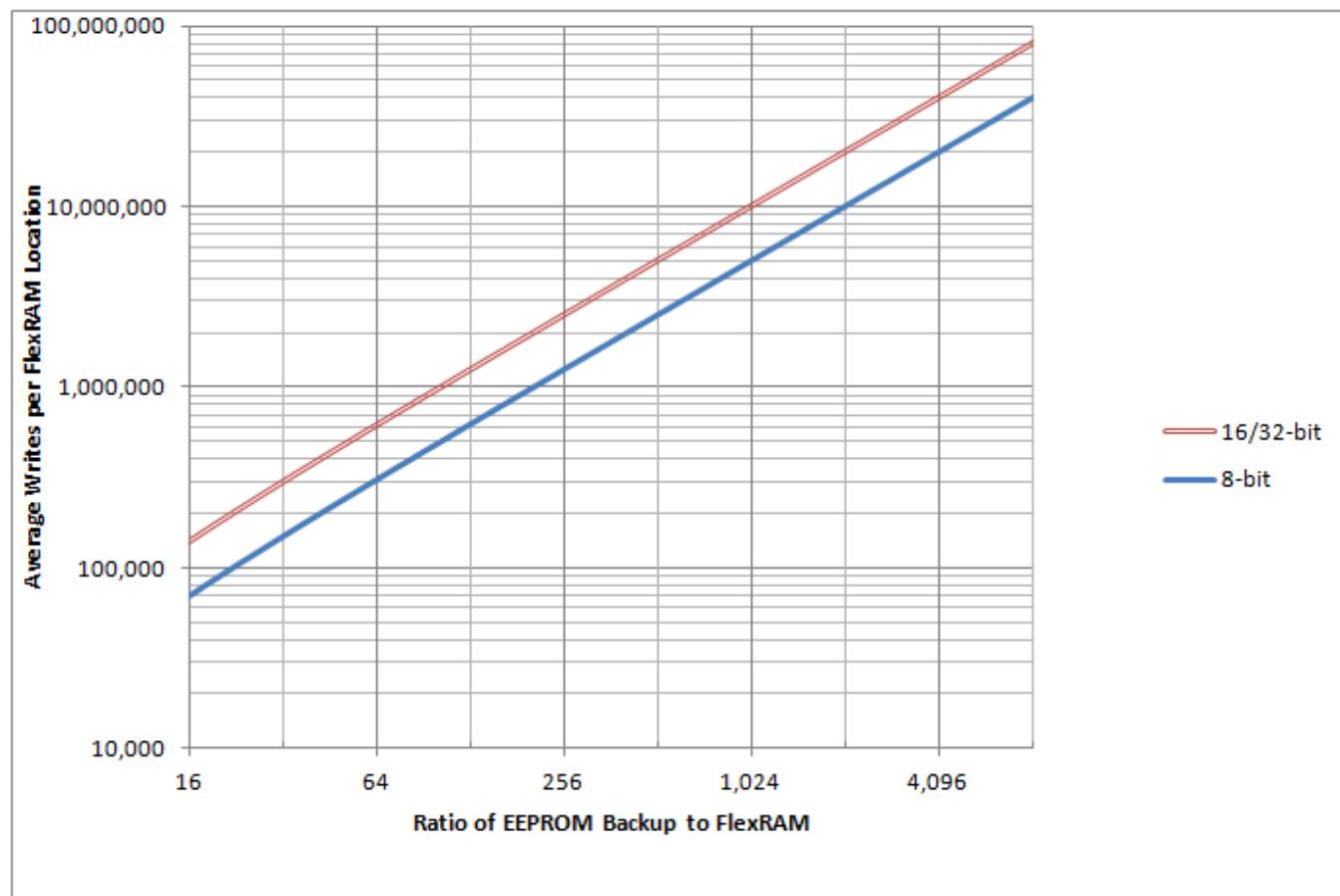
1.  $V_{DD\_DDR}$
2.  $V_{DDA}$
3.  $V_{DD\_INT}$
4.  $V_{DD}$

## 6 Peripheral operating requirements and behaviors

### 6.1 Core modules

## Peripheral operating requirements and behaviors

- EEPROM — allocated FlexNVM for each EEPROM subsystem based on DEPART; entered with Program Partition command
- EESPLIT — FlexRAM split factor for subsystem; entered with the Program Partition command
- EESIZE — allocated FlexRAM based on DEPART; entered with Program Partition command
- Write\_efficiency —
  - 0.25 for 8-bit writes to FlexRAM
  - 0.50 for 16-bit or 32-bit writes to FlexRAM
- $n_{nvmcyc}$  — EEPROM-backup cycling endurance



**Figure 10. EEPROM backup writes to FlexRAM**

## 6.4.2 EzPort Switching Specifications

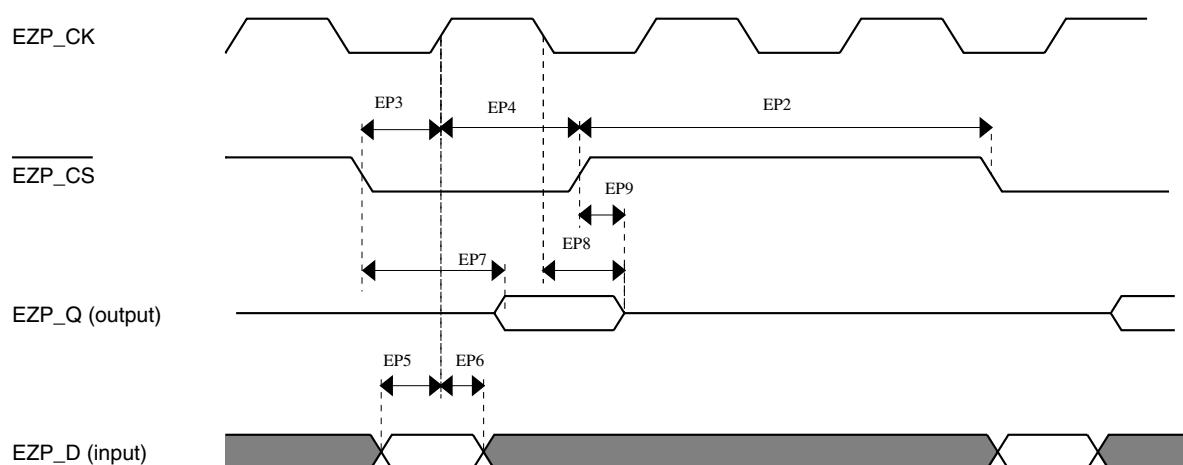
**Table 24. EzPort switching specifications**

Num	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V

*Table continues on the next page...*

**Table 24. EzPort switching specifications (continued)**

Num	Description	Min.	Max.	Unit
EP1	EZP_CK frequency of operation (all commands except READ)	—	$f_{SYS}/2$	MHz
EP1a	EZP_CK frequency of operation (READ command)	—	$f_{SYS}/8$	MHz
EP2	EZP_CS negation to next EZP_CS assertion	$2 \times t_{EZP\_CK}$	—	ns
EP3	EZP_CS input valid to EZP_CK high (setup)	5	—	ns
EP4	EZP_CK high to EZP_CS input invalid (hold)	5	—	ns
EP5	EZP_D input valid to EZP_CK high (setup)	2	—	ns
EP6	EZP_CK high to EZP_D input invalid (hold)	5	—	ns
EP7	EZP_CK low to EZP_Q output valid	—	16	ns
EP8	EZP_CK low to EZP_Q output invalid (hold)	0	—	ns
EP9	EZP_CS negation to EZP_Q tri-state	—	12	ns

**Figure 11. EzPort Timing Diagram**

### 6.4.3 NFC specifications

The NAND flash controller (NFC) implements the interface to standard NAND flash memory devices. This section describes the timing parameters of the NFC.

In the following table:

- $T_H$  is the flash clock high time and
- $T_L$  is flash clock low time,

## Peripheral operating requirements and behaviors

which are defined as:

$$T_{NFC} = T_L + T_H = \frac{T_{\text{input clock}}}{\text{SCALER}}$$

The SCALER value is derived from the fractional divider specified in the SIM's CLKDIV4 register:

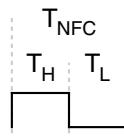
$$\text{SCALER} = \frac{\text{SIM\_CLKDIV4[NFCFRAC]} + 1}{\text{SIM\_CLKDIV4[NFCDIV]} + 1}$$

In case the reciprocal of SCALER is an integer, the duty cycle of NFC clock is 50%, means  $T_H = T_L$ . In case the reciprocal of SCALER is not an integer:

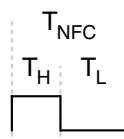
$$T_L = (1 + \text{SCALER} / 2) \times \frac{T_{NFC}}{2}$$

$$T_H = (1 - \text{SCALER} / 2) \times \frac{T_{NFC}}{2}$$

For example, if SCALER is 0.2, then  $T_H = T_L = T_{NFC}/2$ .



However, if SCALER is 0.667, then  $T_L = 2/3 \times T_{NFC}$  and  $T_H = 1/3 \times T_{NFC}$ .



### NOTE

The reciprocal of SCALER must be a multiple of 0.5. For example, 1, 1.5, 2, 2.5, etc.

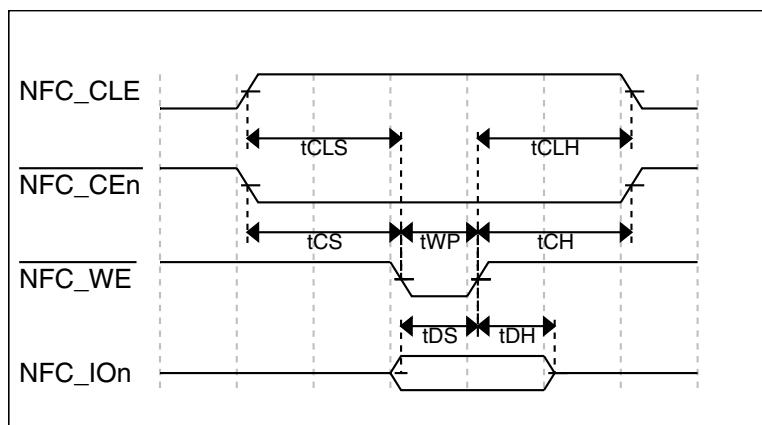
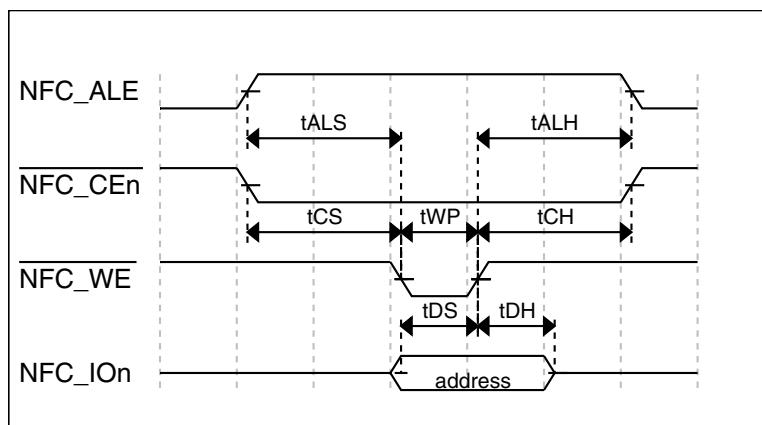
**Table 25. NFC specifications**

Num	Description	Min.	Max.	Unit
$t_{CLS}$	NFC_CLE setup time	$2T_H + T_L - 1$	—	ns
$t_{CLH}$	NFC_CLE hold time	$T_H + T_L - 1$	—	ns
$t_{CS}$	NFC_CEn setup time	$2T_H + T_L - 1$	—	ns
$t_{CH}$	NFC_CEn hold time	$T_H + T_L$	—	ns
$t_{WP}$	NFC_WP pulse width	$T_L - 1$	—	ns
$t_{ALS}$	NFC_ALE setup time	$2T_H + T_L$	—	ns

*Table continues on the next page...*

**Table 25. NFC specifications (continued)**

Num	Description	Min.	Max.	Unit
$t_{ALH}$	NFC_ALE hold time	$T_H + T_L$	—	ns
$t_{DS}$	Data setup time	$T_L - 1$	—	ns
$t_{DH}$	Data hold time	$T_H - 1$	—	ns
$t_{WC}$	Write cycle time	$T_H + T_L - 1$	—	ns
$t_{WH}$	NFC_WE hold time	$T_H - 1$	—	ns
$t_{RR}$	Ready to $\overline{\text{NFC}_R\text{E}}$ low	$4T_H + 3T_L + 90$	—	ns
$t_{RP}$	$\overline{\text{NFC}_R\text{E}}$ pulse width	$T_L + 1$	—	ns
$t_{RC}$	Read cycle time	$T_L + T_H - 1$	—	ns
$t_{REH}$	NFC_R $\overline{\text{E}}$ high hold time	$T_H - 1$	—	ns
$t_{IS}$	Data input setup time	11	—	ns

**Figure 12. Command latch cycle timing****Figure 13. Address latch cycle timing**

The following timing numbers indicate when data is latched or driven onto the external bus, relative to the Flexbus output clock (FB\_CLK). All other timing relationships can be derived from these values.

**Table 26. Flexbus limited voltage range switching specifications**

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	FB_CLK	MHz	
FB1	Clock period	20	—	ns	
FB2	Address, data, and control output valid	—	11.5	ns	1
FB3	Address, data, and control output hold	0.5	—	ns	1
FB4	Data and FB_TA input setup	8.5	—	ns	2
FB5	Data and FB_TA input hold	0.5	—	ns	2

1. Specification is valid for all FB\_AD[31:0], FB\_BE/BWE<sub>n</sub>, FB\_CS<sub>n</sub>, FB\_OE, FB\_R/W, FB\_TBST, FB\_TSIZ[1:0], FB\_ALE, and FB\_TS.
2. Specification is valid for all FB\_AD[31:0] and FB\_TA.

**Table 27. Flexbus full voltage range switching specifications**

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	1.71	3.6	V	
	Frequency of operation	—	FB_CLK	MHz	
FB1	Clock period	1/FB_CLK	—	ns	
FB2	Address, data, and control output valid	—	13.5	ns	1
FB3	Address, data, and control output hold	0	—	ns	1
FB4	Data and FB_TA input setup	13.7	—	ns	2
FB5	Data and FB_TA input hold	0.5	—	ns	2

1. Specification is valid for all FB\_AD[31:0], FB\_BE/BWE<sub>n</sub>, FB\_CS<sub>n</sub>, FB\_OE, FB\_R/W, FB\_TBST, FB\_TSIZ[1:0], FB\_ALE, and FB\_TS.
2. Specification is valid for all FB\_AD[31:0] and FB\_TA.

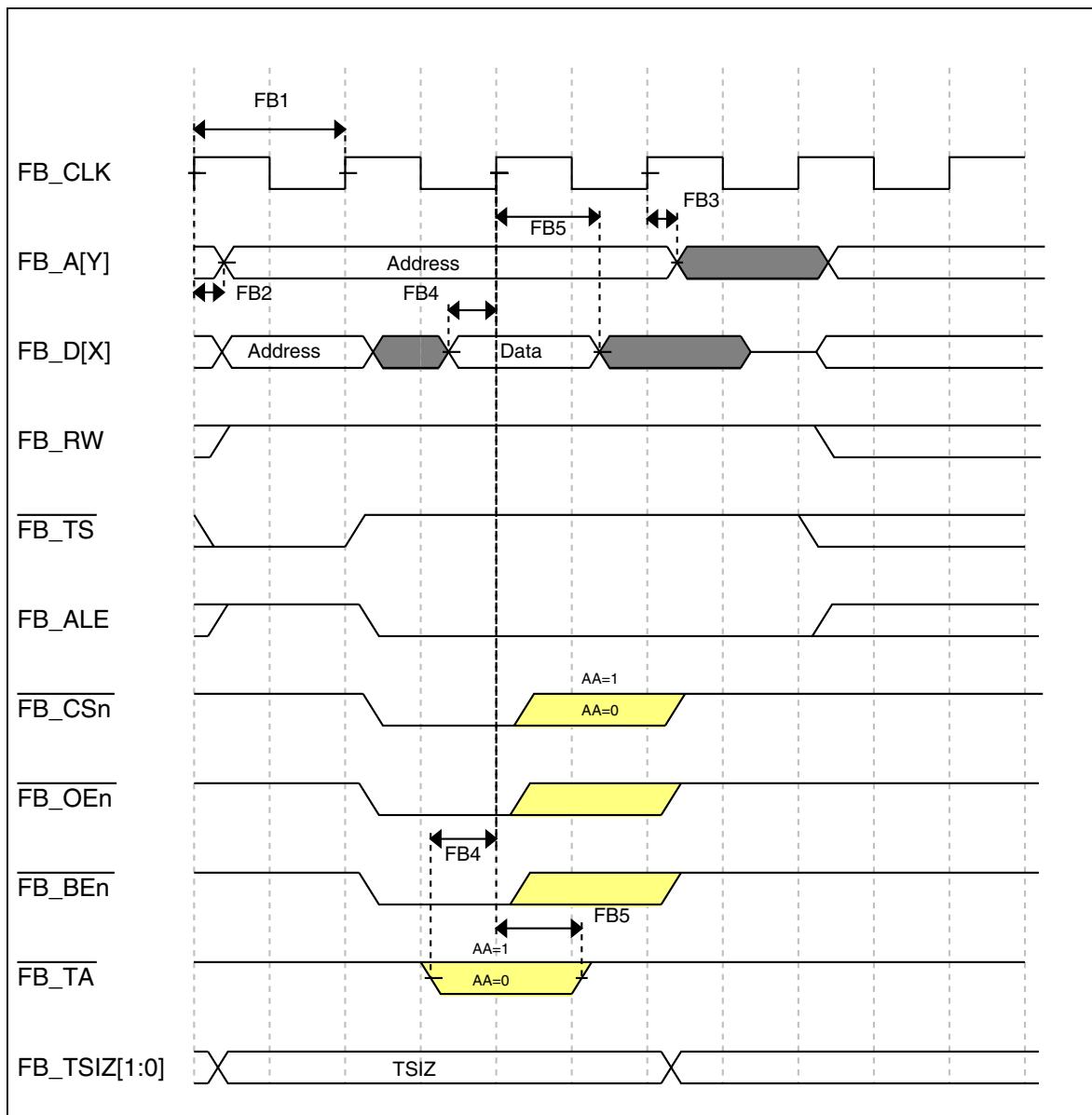
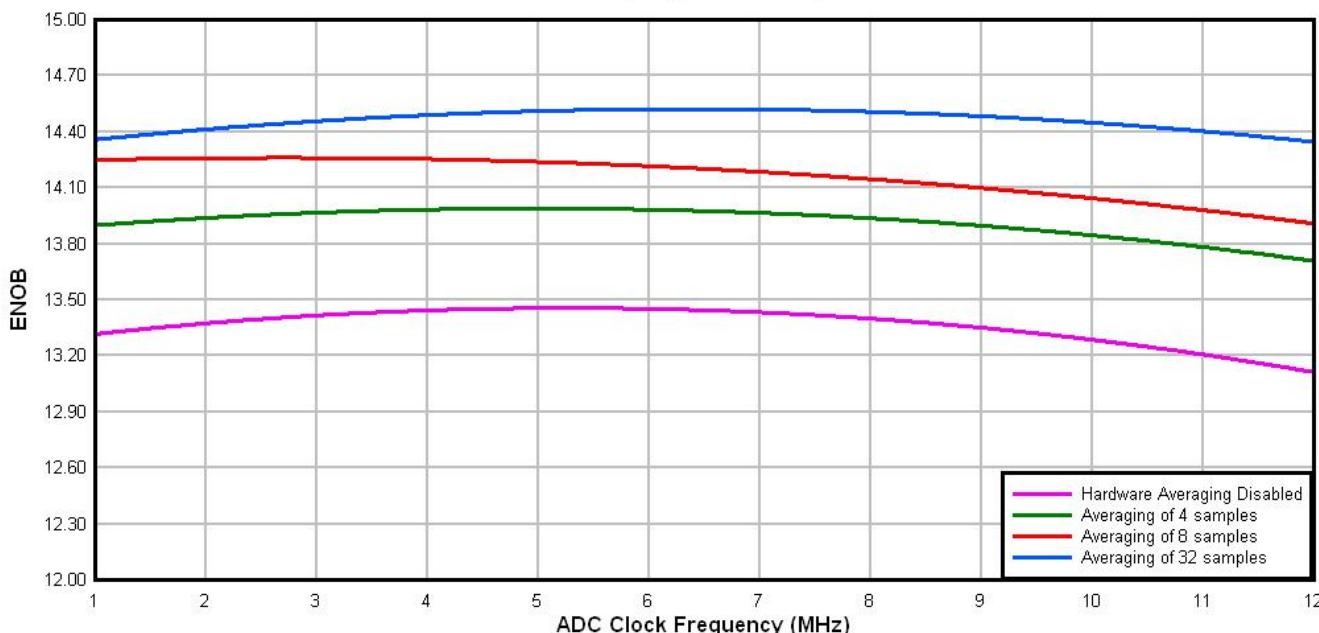


Figure 17. FlexBus read timing diagram

**Table 29. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$E_{IL}$	Input leakage error			$I_{in} \times R_{AS}$		mV	$I_{in}$ = leakage current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	Across the full temperature range of the device	—	1.715	—	mV/°C	
$V_{TEMP25}$	Temp sensor voltage	25 °C	—	719	—	mV	

1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDA}$
2. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25°C,  $f_{ADCK} = 2.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
3. The ADC supply current depends on the ADC conversion clock speed, conversion rate and the ADLPC bit (low power). For lowest power operation the ADLPC bit must be set, the HSC bit must be clear with 1 MHz ADC conversion clock speed.
4. 1 LSB =  $(V_{REFH} - V_{REFL})/2^N$
5. ADC conversion clock < 16 MHz, Max hardware averaging (AVGE = %1, AVGS = %11)
6. Input data is 100 Hz sine wave. ADC conversion clock < 12 MHz.
7. Input data is 1 kHz sine wave. ADC conversion clock < 12 MHz.

**Typical ADC 16-bit Differential ENOB vs ADC Clock  
100Hz, 90% FS Sine Input****Figure 20. Typical ENOB vs. ADC\_CLK for 16-bit differential mode**

**Table 31. 16-bit ADC with PGA characteristics (continued)**

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
G	Gain <sup>4</sup>	<ul style="list-style-type: none"> <li>PGAG=0</li> <li>PGAG=1</li> <li>PGAG=2</li> <li>PGAG=3</li> <li>PGAG=4</li> <li>PGAG=5</li> <li>PGAG=6</li> </ul>	0.95 1.9 3.8 7.6 15.2 30.0 58.8	1 2 4 8 16 31.6 63.3	1.05 2.1 4.2 8.4 16.6 33.2 67.8		R <sub>AS</sub> < 100Ω
BW	Input signal bandwidth	<ul style="list-style-type: none"> <li>16-bit modes</li> <li>&lt; 16-bit modes</li> </ul>	— —	— —	4 40	kHz kHz	
PSRR	Power supply rejection ratio	Gain=1	—	-84	—	dB	V <sub>DDA</sub> = 3V ±100mV, f <sub>VDDA</sub> = 50Hz, 60Hz
CMRR	Common mode rejection ratio	<ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul>	— —	-84 -85	— —	dB dB	V <sub>CM</sub> = 500mVpp, f <sub>CM</sub> = 50Hz, 100Hz
V <sub>OFS</sub>	Input offset voltage	<ul style="list-style-type: none"> <li>Chopping disabled (ADC_PGA[PGACHPb]=1)</li> <li>Chopping enabled (ADC_PGA[PGACHPb]=0)</li> </ul>	— —	2.4 0.2	— —	mV mV	Output offset = V <sub>OFS</sub> *(Gain+1)
T <sub>GSW</sub>	Gain switching settling time		—	—	10	μs	5
dG/dT	Gain drift over full temperature range	<ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul>	— —	6 31	10 42	ppm/°C ppm/°C	
dG/dV <sub>DDA</sub>	Gain drift over supply voltage	<ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul>	— —	0.07 0.14	0.21 0.31	%/V %/V	V <sub>DDA</sub> from 1.71 to 3.6V
E <sub>IL</sub>	Input leakage error	All modes	I <sub>In</sub> × R <sub>AS</sub>			mV	I <sub>In</sub> = leakage current (refer to the MCU's voltage and current operating ratings)
V <sub>PP,DIFF</sub>	Maximum differential input signal swing		$\left( \frac{(\min(V_x V_{DDA} - V_x) - 0.2) \times 4}{\text{Gain}} \right)$ where V <sub>X</sub> = V <sub>REFPGA</sub> × 0.583			V	6
SNR	Signal-to-noise ratio	<ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul>	80 52	90 66	— —	dB dB	16-bit differential mode, Average=32

Table continues on the next page...

**Table 32. Comparator and 6-bit DAC electrical specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit
$V_H$	Analog comparator hysteresis <sup>1</sup> <ul style="list-style-type: none"> <li>• CR0[HYSTCTR] = 00</li> <li>• CR0[HYSTCTR] = 01</li> <li>• CR0[HYSTCTR] = 10</li> <li>• CR0[HYSTCTR] = 11</li> </ul>	—	5	—	mV
$V_{CMPOh}$	Output high	$V_{DD} - 0.5$	—	—	V
$V_{CMPOl}$	Output low	—	—	0.5	V
$t_{DHS}$	Propagation delay, high-speed mode (EN=1, PMODE=1)	20	50	200	ns
$t_{DLS}$	Propagation delay, low-speed mode (EN=1, PMODE=0)	80	250	600	ns
	Analog comparator initialization delay <sup>2</sup>	—	—	40	μs
$I_{DAC6b}$	6-bit DAC current adder (enabled)	—	7	—	μA
INL	6-bit DAC integral non-linearity	-0.5	—	0.5	LSB <sup>3</sup>
DNL	6-bit DAC differential non-linearity	-0.3	—	0.3	LSB

1. Typical hysteresis is measured with input voltage range limited to 0.6 to  $V_{DD}$ -0.6V.
2. Comparator initialization delay is defined as the time between software writes to change control inputs (Writes to DACEN, VRSEL, PSEL, MSEL, VOSEL) and the comparator output settling to a stable level.
3. 1 LSB =  $V_{reference}/64$

**Table 36. VREF full-range operating behaviors**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{out}$	Voltage reference output with factory trim at nominal $V_{DDA}$ and temperature=25°C	1.1915	1.195	1.1977	V	
$V_{out}$	Voltage reference output — factory trim	1.1584	—	1.2376	V	
$V_{out}$	Voltage reference output — user trim	1.193	—	1.197	V	
$V_{step}$	Voltage reference trim step	—	0.5	—	mV	
$V_{tdrift}$	Temperature drift (Vmax -Vmin across the full temperature range)	—	—	80	mV	
$I_{bg}$	Bandgap only current	—	—	80	μA	1
$I_{hp}$	High-power buffer current	—	—	1	mA	1
$\Delta V_{LOAD}$	Load regulation <ul style="list-style-type: none"> <li>• current = + 1.0 mA</li> <li>• current = - 1.0 mA</li> </ul>	—	2	—	mV	1, 2
$T_{stup}$	Buffer startup time	—	—	100	μs	
$V_{vdrift}$	Voltage drift (Vmax -Vmin across the full voltage range)	—	2	—	mV	1

1. See the chip's Reference Manual for the appropriate settings of the VREF Status and Control register.
2. Load regulation voltage is the difference between the VREF\_OUT voltage with no load vs. voltage with defined load

**Table 37. VREF limited-range operating requirements**

Symbol	Description	Min.	Max.	Unit	Notes
$T_A$	Temperature	0	50	°C	

**Table 38. VREF limited-range operating behaviors**

Symbol	Description	Min.	Max.	Unit	Notes
$V_{out}$	Voltage reference output with factory trim	1.173	1.225	V	

## 6.7 Timers

See [General switching specifications](#).

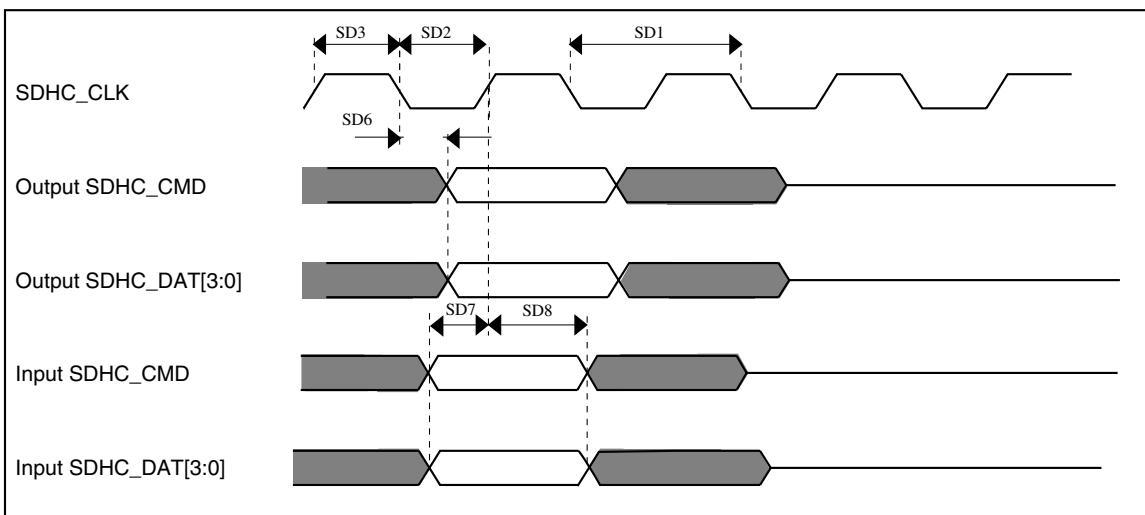
## 6.8 Communication interfaces

**Table 48. SDHC switching specifications over a limited operating voltage range (continued)**

Num	Symbol	Description	Min.	Max.	Unit
<b>SDHC output / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b>					
SD6	$t_{OD}$	SDHC output delay (output valid)	-5	6.5	ns
<b>SDHC input / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b>					
SD7	$t_{ISU}$	SDHC input setup time	5	—	ns
SD8	$t_{IH}$	SDHC input hold time	0	—	ns

**Table 49. SDHC switching specifications over the full operating voltage range**

Num	Symbol	Description	Min.	Max.	Unit
Operating voltage			1.71	3.6	V
SD1	fpp	Clock frequency (low speed)	0	400	kHz
	fpp	Clock frequency (SD/SDIO full speed)	0	25	MHz
	fpp	Clock frequency (MMC full speed)	0	20	MHz
	$f_{OD}$	Clock frequency (identification mode)	0	400	kHz
SD2	$t_{WL}$	Clock low time	7	—	ns
SD3	$t_{WH}$	Clock high time	7	—	ns
SD4	$t_{TLH}$	Clock rise time	—	3	ns
SD5	$t_{THL}$	Clock fall time	—	3	ns
<b>SDHC output / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b>					
SD6	$t_{OD}$	SDHC output delay (output valid)	-5	6.5	ns
<b>SDHC input / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b>					
SD7	$t_{ISU}$	SDHC input setup time	5	—	ns
SD8	$t_{IH}$	SDHC input hold time	1.3	—	ns

**Figure 33. SDHC timing**

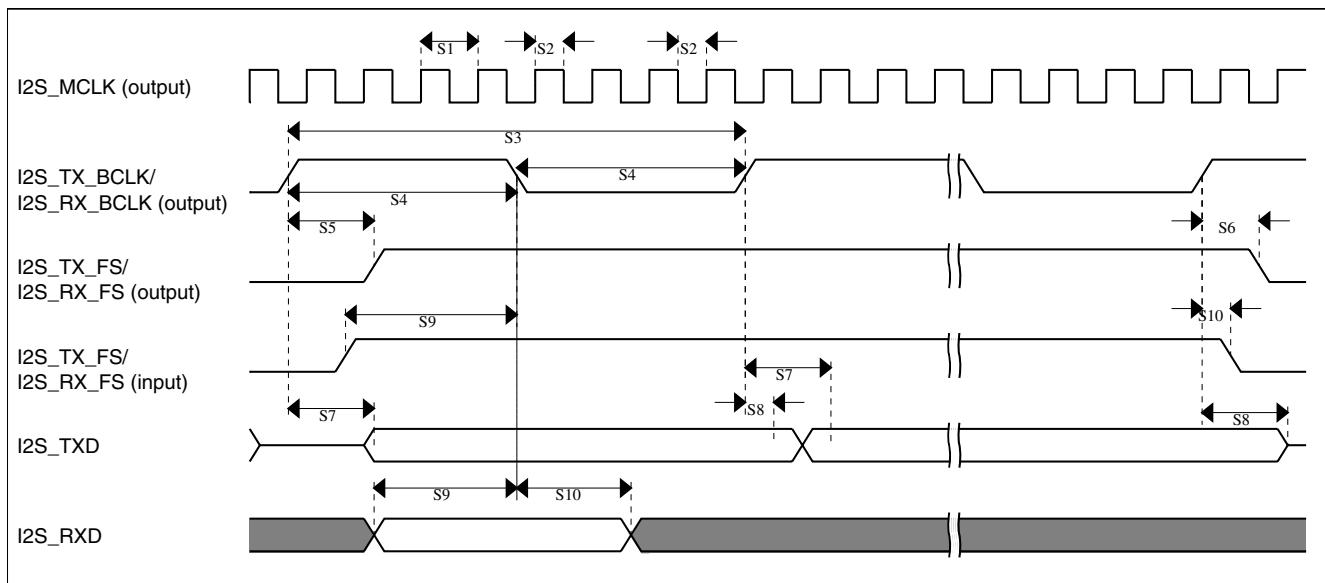


Figure 34. I2S/SAI timing — master modes

Table 51. I2S/SAI slave mode timing in Normal Run, Wait and Stop modes  
(limited voltage range)

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
S11	I2S_TX_BCLK/I2S_RX_BCLK cycle time (input)	80	—	ns
S12	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low (input)	45%	55%	MCLK period
S13	I2S_TX_FS/I2S_RX_FS input setup before I2S_TX_BCLK/I2S_RX_BCLK	4.5	—	ns
S14	I2S_TX_FS/I2S_RX_FS input hold after I2S_TX_BCLK/I2S_RX_BCLK	2	—	ns
S15	I2S_TX_BCLK to I2S_TxD/I2S_TX_FS output valid <ul style="list-style-type: none"> <li>• Multiple SAI Synchronous mode</li> <li>• All other modes</li> </ul>	—	21	ns
S16	I2S_TX_BCLK to I2S_TxD/I2S_TX_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_RX_BCLK	4.5	—	ns
S18	I2S_RXD hold after I2S_RX_BCLK	2	—	ns
S19	I2S_TX_FS input assertion to I2S_TxD output valid <sup>1</sup>	—	25	ns

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
14	G4	PTE11	ADC3_SE16	ADC3_SE16	PTE11		UART5_RTS_b	I2S0_TX_FS		FTM3_CH6		
15	G3	PTE12	ADC3_SE17	ADC3_SE17	PTE12			I2S0_TX_BCLK		FTM3_CH7		
16	E6	VDD	VDD	VDD								
17	F7	VSS	VSS	VSS								
18	H3	VSS	VSS	VSS								
19	H1	USB0_DP	USB0_DP	USB0_DP								
20	H2	USB0_DM	USB0_DM	USB0_DM								
21	G1	VOUT33	VOUT33	VOUT33								
22	G2	VREGIN	VREGIN	VREGIN								
23	J1	PGA2_DP/ ADC2_DP0/ ADC3_DP3/ ADC0_DP1	PGA2_DP/ ADC2_DP0/ ADC3_DP3/ ADC0_DP1	PGA2_DP/ ADC2_DP0/ ADC3_DP3/ ADC0_DP1								
24	J2	PGA2_DM/ ADC2_DM0/ ADC3_DM3/ ADC0_DM1	PGA2_DM/ ADC2_DM0/ ADC3_DM3/ ADC0_DM1	PGA2_DM/ ADC2_DM0/ ADC3_DM3/ ADC0_DM1								
25	K1	PGA3_DP/ ADC3_DP0/ ADC2_DP3/ ADC1_DP1	PGA3_DP/ ADC3_DP0/ ADC2_DP3/ ADC1_DP1	PGA3_DP/ ADC3_DP0/ ADC2_DP3/ ADC1_DP1								
26	K2	PGA3_DM/ ADC3_DM0/ ADC2_DM3/ ADC1_DM1	PGA3_DM/ ADC3_DM0/ ADC2_DM3/ ADC1_DM1	PGA3_DM/ ADC3_DM0/ ADC2_DM3/ ADC1_DM1								
27	L1	PGA0_DP/ ADC0_DP0/ ADC1_DP3	PGA0_DP/ ADC0_DP0/ ADC1_DP3	PGA0_DP/ ADC0_DP0/ ADC1_DP3								
28	L2	PGA0_DM/ ADC0_DM0/ ADC1_DM3	PGA0_DM/ ADC0_DM0/ ADC1_DM3	PGA0_DM/ ADC0_DM0/ ADC1_DM3								
29	M1	PGA1_DP/ ADC1_DP0/ ADC0_DP3	PGA1_DP/ ADC1_DP0/ ADC0_DP3	PGA1_DP/ ADC1_DP0/ ADC0_DP3								
30	M2	PGA1_DM/ ADC1_DM0/ ADC0_DM3	PGA1_DM/ ADC1_DM0/ ADC0_DM3	PGA1_DM/ ADC1_DM0/ ADC0_DM3								
31	H5	VDDA	VDDA	VDDA								
32	G5	VREFH	VREFH	VREFH								
33	G6	VREFL	VREFL	VREFL								
34	H6	VSSA	VSSA	VSSA								
35	K3	ADC1_SE16/ CMP2_IN2/ ADC0_SE22	ADC1_SE16/ CMP2_IN2/ ADC0_SE22	ADC1_SE16/ CMP2_IN2/ ADC0_SE22								

**Pinout**

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
36	J3	ADC0_SE16/ CMP1_IN2/ ADC0_SE21	ADC0_SE16/ CMP1_IN2/ ADC0_SE21	ADC0_SE16/ CMP1_IN2/ ADC0_SE21								
37	M3	VREF_OUT/ CMP1_IN5/ CMP0_IN5/ ADC1_SE18	VREF_OUT/ CMP1_IN5/ CMP0_IN5/ ADC1_SE18	VREF_OUT/ CMP1_IN5/ CMP0_IN5/ ADC1_SE18								
38	L3	DAC0_OUT/ CMP1_IN3/ ADC0_SE23	DAC0_OUT/ CMP1_IN3/ ADC0_SE23	DAC0_OUT/ CMP1_IN3/ ADC0_SE23								
39	L4	DAC1_OUT/ CMP0_IN4/ CMP2_IN3/ ADC1_SE23	DAC1_OUT/ CMP0_IN4/ CMP2_IN3/ ADC1_SE23	DAC1_OUT/ CMP0_IN4/ CMP2_IN3/ ADC1_SE23								
40	M7	XTAL32	XTAL32	XTAL32								
41	M6	EXTAL32	EXTAL32	EXTAL32								
42	L6	VBAT	VBAT	VBAT								
43	—	VDD	VDD	VDD								
44	—	VSS	VSS	VSS								
45	M4	PTE24	ADC0_SE17/ EXTAL1	ADC0_SE17/ EXTAL1	PTE24	CAN1_TX	UART4_TX	I2S1_TX_FS		EWM_OUT_b	I2S1_RXD1	
46	K5	PTE25	ADC0_SE18/ XTAL1	ADC0_SE18/ XTAL1	PTE25	CAN1_RX	UART4_RX	I2S1_TX_BCLK		EWM_IN	I2S1_RXD1	
47	K4	PTE26	ADC3_SE5b	ADC3_SE5b	PTE26	ENET_1588_CLKIN	UART4_CTS_b	I2S1_RXD0		RTC_CLKOUT	USB_CLKIN	
48	J4	PTE27	ADC3_SE4b	ADC3_SE4b	PTE27		UART4_RTS_b	I2S1_MCLK				
49	H4	PTE28	ADC3_SE7a	ADC3_SE7a	PTE28							
50	J5	PTA0	JTAG_TCLK/ SWD_CLK/ EZP_CLK	TSI0_CH1	PTA0	UART0_CTS_b/ UART0_COL_b	FTM0_CH5				JTAG_TCLK/ SWD_CLK	EZP_CLK
51	J6	PTA1	JTAG_TDI/ EZP_DI	TSI0_CH2	PTA1	UART0_RX	FTM0_CH6				JTAG_TDI	EZP_DI
52	K6	PTA2	JTAG_TDO/ TRACE_SWO/ EZP_DO	TSI0_CH3	PTA2	UART0_TX	FTM0_CH7				JTAG_TDO/ TRACE_SWO	EZP_DO
53	K7	PTA3	JTAG_TMS/ SWD_DIO	TSI0_CH4	PTA3	UART0_RTS_b	FTM0_CH0				JTAG_TMS/ SWD_DIO	
54	L7	PTA4/ LLWU_P3	NMI_b/ EZP_CS_b	TSI0_CH5	PTA4/ LLWU_P3		FTM0_CH1				NMI_b	EZP_CS_b
55	M8	PTA5	DISABLED		PTA5	USB_CLKIN	FTM0_CH2	RMII0_RXER/ MII0_RXER	CMP2_OUT	I2S0_TX_BCLK	JTAG_TRST_b	
56	E7	VDD	VDD	VDD								
57	G7	VSS	VSS	VSS								
58	J7	PTA6	ADC3_SE6a	ADC3_SE6a	PTA6	ULPI_CLK	FTM0_CH3	I2S1_RXD0	CLKOUT		TRACE_CLKOUT	

