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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	PIC
Core Size	8-Bit
Speed	25MHz
Connectivity	UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	16
Program Memory Size	4KB (2K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 7x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 150°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	20-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f1220-h-ss

2.7.1 OSCILLATOR CONTROL REGISTER

The OSCCON register (Register 2-2) controls several aspects of the system clock's operation, both in full-power operation and in power managed modes.

The System Clock Select bits, SCS1:SCS0, select the clock source that is used when the device is operating in power managed modes. The available clock sources are the primary clock (defined in Configuration Register 1H), the secondary clock (Timer1 oscillator) and the internal oscillator block. The clock selection has no effect until a SLEEP instruction is executed and the device enters a power managed mode of operation. The SCS bits are cleared on all forms of Reset.

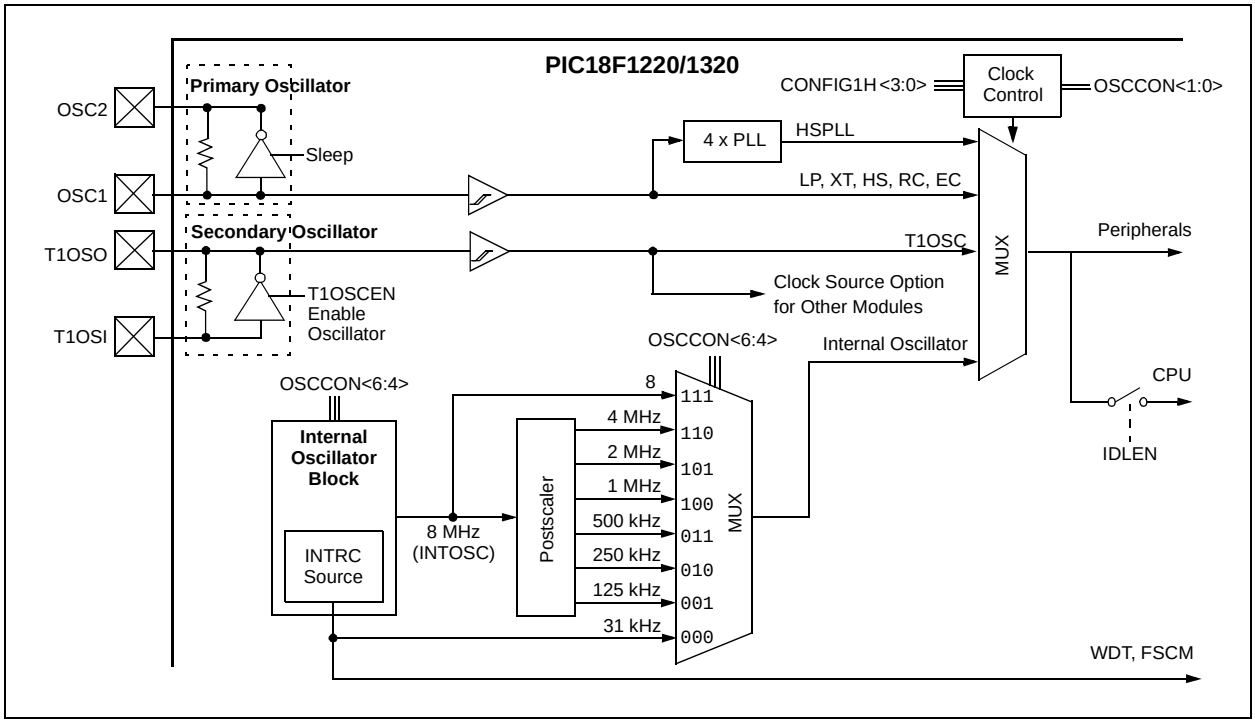
The Internal Oscillator Select bits, IRCF2:IRCF0, select the frequency output of the internal oscillator block that is used to drive the system clock. The choices are the INTRC source, the INTOSC source (8 MHz), or one of the six frequencies derived from the INTOSC postscaler (125 kHz to 4 MHz). If the internal oscillator block is supplying the system clock, changing the states of these bits will have an immediate change on the internal oscillator's output.

The OSTS, IOFS and T1RUN bits indicate which clock source is currently providing the system clock. The OSTS indicates that the Oscillator Start-up Timer has timed out and the primary clock is providing the system clock in Primary Clock modes. The IOFS bit indicates when the internal oscillator block has stabilized and is providing the system clock in RC Clock modes or during Two-Speed Start-ups. The T1RUN bit (T1CON<6>) indicates when the Timer1 oscillator is providing the system clock in Secondary Clock modes. In power managed modes, only one of these three bits will be set at any time. If none of these bits are set, the INTRC is providing the system clock, or the internal oscillator block has just started and is not yet stable.

The IDLEN bit controls the selective shutdown of the controller's CPU in power managed modes. The uses of these bits are discussed in more detail in **Section 3.0 "Power Managed Modes"**.

Note 1:	The Timer1 oscillator must be enabled to select the secondary clock source. The Timer1 oscillator is enabled by setting the T1OSCEN bit in the Timer1 Control register (T1CON<3>). If the Timer1 oscillator is not enabled, then any attempt to select a secondary clock source when executing a SLEEP instruction will be ignored.
2:	It is recommended that the Timer1 oscillator be operating and stable before executing the SLEEP instruction or a very long delay may occur while the Timer1 oscillator starts.

FIGURE 2-8: PIC18F1220/1320 CLOCK DIAGRAM



REGISTER 2-2: OSCCON: OSCILLATOR CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-1/1	R/W-1/1	R[(1)]	R-0/0	R/W-0/0	R/W-0/0
IDLEN	IRCF<2:0>			OSTS	IOFS	SCS<1:0>	
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7 **IDLEN:** Idle Enable bits
1 = Idle mode enabled; CPU core is not clocked in power managed modes
0 = Run mode enabled; CPU core is clocked in Run modes, but not Sleep mode

bit 6-4 **IRCF<2:0>:** Internal Oscillator Frequency Select bits
111 = 8 MHz (8 MHz source drives clock directly)
110 = 4 MHz
101 = 2 MHz
100 = 1 MHz
011 = 500 kHz
010 = 250 kHz
001 = 125 kHz
000 = 31 kHz (INTRC source drives clock directly)

bit 3 **OSTS:** Oscillator Start-up Time-out Status bit
1 = Oscillator Start-up Timer time-out has expired; primary oscillator is running
0 = Oscillator Start-up Timer time-out is running; primary oscillator is not ready

bit 2 **IOFS:** INTOSC Frequency Stable bit
1 = INTOSC frequency is stable
0 = INTOSC frequency is not stable

bit 1-0 **SCS<1:0>:** System Clock Select bits[(1)]
1x = Internal oscillator block (RC modes)
01 =Timer1 oscillator (Secondary modes)
00 = Primary oscillator (Sleep and PRI_IDLE modes)

Note 1: Depends on state of the IESO bit in Configuration Register 1H.

3.4.3 RC_RUN MODE

In RC_RUN mode, the CPU and peripherals are clocked from the internal oscillator block using the INTOSC multiplexer and the primary clock is shut down. When using the INTRC source, this mode provides the best power conservation of all the Run modes, while still executing code. It works well for user applications which are not highly timing sensitive, or do not require high-speed clocks at all times.

If the primary clock source is the internal oscillator block (either of the INTIO1 or INTIO2 oscillators), there are no distinguishable differences between PRI_RUN and RC_RUN modes during execution. However, a clock switch delay will occur during entry to and exit from RC_RUN mode. Therefore, if the primary clock source is the internal oscillator block, the use of RC_RUN mode is not recommended.

This mode is entered by clearing the IDLEN bit, setting SCS1 (SCS0 is ignored) and executing a SLEEP instruction. The IRCF bits may select the clock frequency before the SLEEP instruction is executed. When the clock source is switched to the INTOSC multiplexer (see Figure 3-10), the primary oscillator is shut down and the OSTS bit is cleared.

The IRCF bits may be modified at any time to immediately change the system clock speed. Executing a SLEEP instruction is not required to select a new clock frequency from the INTOSC multiplexer.

Note:	Caution should be used when modifying a single IRCF bit. If V_{DD} is less than 3V, it is possible to select a higher clock speed than is supported by the low V_{DD}. Improper device operation may result if the V_{DD}/F_{OSC} specifications are violated.

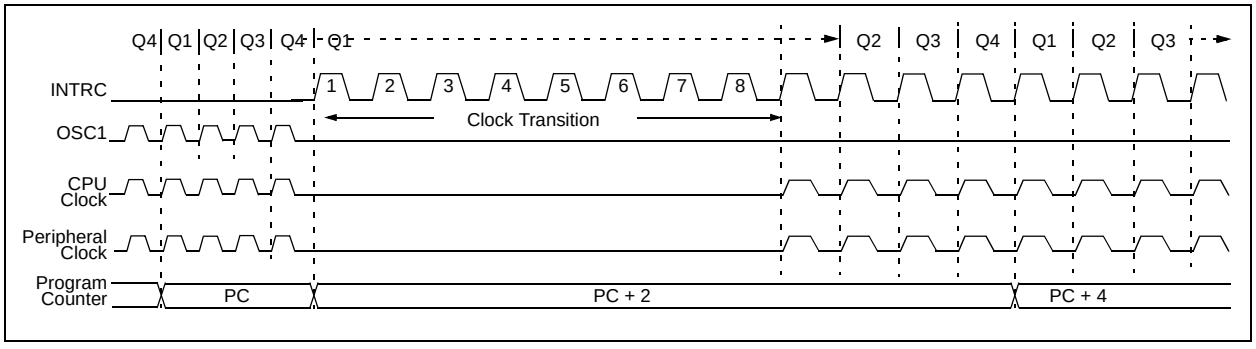
If the IRCF bits are all clear, the INTOSC output is not enabled and the IOFS bit will remain clear; there will be no indication of the current clock source. The INTRC source is providing the system clocks.

If the IRCF bits are changed from all clear (thus, enabling the INTOSC output), the IOFS bit becomes set after the INTOSC output becomes stable. Clocks to the system continue while the INTOSC source stabilizes, in approximately 1 ms.

If the IRCF bits were previously at a non-zero value before the SLEEP instruction was executed and the INTOSC source was already stable, the IOFS bit will remain set.

When a wake event occurs, the system continues to be clocked from the INTOSC multiplexer while the primary clock is started. When the primary clock becomes ready, a clock switch to the primary clock occurs (see Figure 3-8). When the clock switch is complete, the IOFS bit is cleared, the OSTS bit is set and the primary clock is providing the system clock. The IDLEN and SCS bits are not affected by the wake-up. The INTRC source will continue to run if either the WDT or the Fail-Safe Clock Monitor is enabled.

FIGURE 3-10: TIMING TRANSITION TO RC_RUN MODE



15.0 ENHANCED CAPTURE/ COMPARE/PWM (ECCP) MODULE

The Enhanced CCP module is implemented as a standard CCP module with Enhanced PWM capabilities. These capabilities allow for two or four output channels, user-selectable polarity, dead-band control and automatic shutdown and restart and are discussed in detail in **Section 15.5 "Enhanced PWM Mode"**.

The control register for CCP1 is shown in Register 15-1.

In addition to the expanded functions of the CCP1CON register, the ECCP module has two additional registers associated with Enhanced PWM operation and auto-shutdown features:

- PWM1CON
- ECCPAS

REGISTER 15-1: CCP1CON REGISTER FOR ENHANCED CCP OPERATION

R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
P1M1	P1M0	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **P1M<1:0>:** PWM Output Configuration bits

If CCP1M<3:2> = 00, 01, 10:

xx = P1A assigned as Capture/Compare input; P1B, P1C, P1D assigned as port pins

If CCP1M<3:2> = 11:

00 = Single output; P1A modulated; P1B, P1C, P1D assigned as port pins

01 = Full-bridge output forward; P1D modulated; P1A active; P1B, P1C inactive

10 = Half-bridge output; P1A, P1B modulated with dead-band control; P1C, P1D assigned as port pins

11 = Full-bridge output reverse; P1B modulated; P1C active; P1A, P1D inactive

bit 5-4 **DC1B<1:0>:** PWM Duty Cycle Least Significant bits

Capture mode:

Unused.

Compare mode:

Unused.

PWM mode:

These bits are the two LSbs of the PWM duty cycle. The eight MSbs are found in CCPR1L.

bit 3-0 **CCP1M<3:0>:** ECCP1 Mode Select bits

0000 = Capture/Compare/PWM off (resets ECCP module)

0001 = Unused (reserved)

0010 = Compare mode, toggle output on match (ECCP1IF bit is set)

0011 = Unused (reserved)

0100 = Capture mode, every falling edge

0101 = Capture mode, every rising edge

0110 = Capture mode, every 4th rising edge

0111 = Capture mode, every 16th rising edge

1000 = Compare mode, set output on match (ECCP1IF bit is set)

1001 = Compare mode, clear output on match (ECCP1IF bit is set)

1010 = Compare mode, generate software interrupt on match (ECCP1IF bit is set, ECCP1 pin returns to port pin operation)

1011 = Compare mode, trigger special event (ECCP1IF bit is set; ECCP resets TMR1 or TMR3 and starts an A/D conversion if the A/D module is enabled)

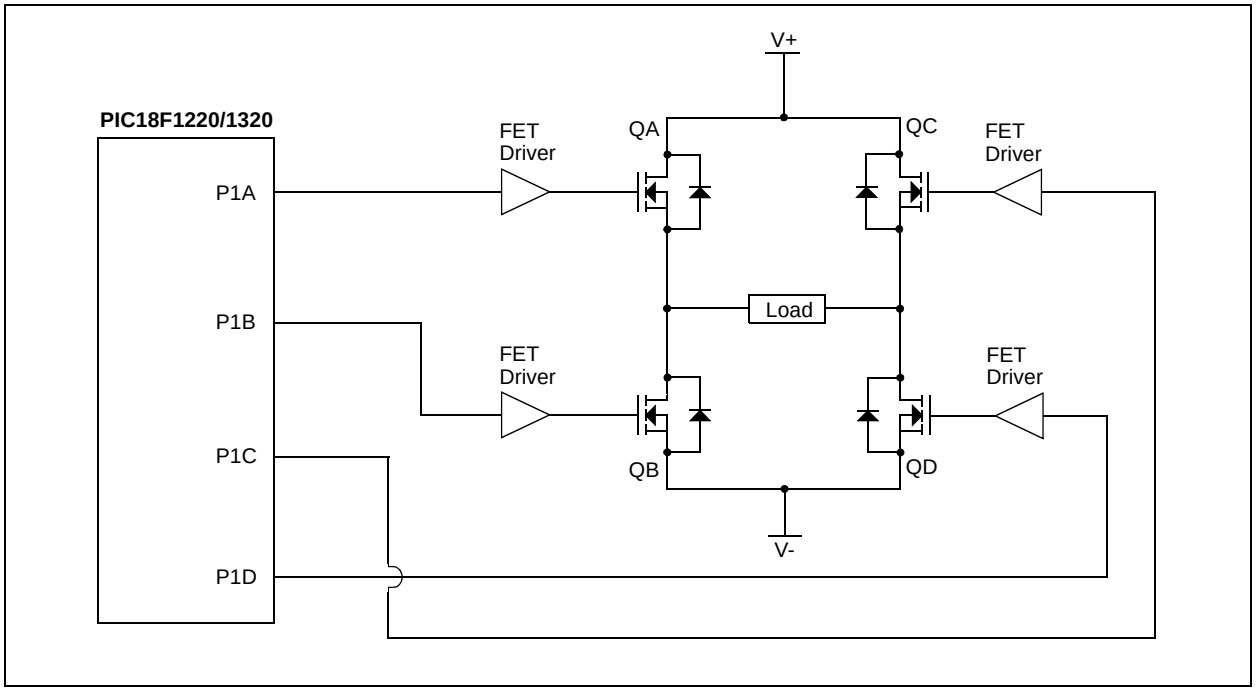
1100 = PWM mode; P1A, P1C active-high; P1B, P1D active-high

1101 = PWM mode; P1A, P1C active-high; P1B, P1D active-low

1110 = PWM mode; P1A, P1C active-low; P1B, P1D active-high

1111 = PWM mode; P1A, P1C active-low; P1B, P1D active-low

FIGURE 15-9: EXAMPLE OF FULL-BRIDGE APPLICATION



15.5.5.1 Direction Change in Full-Bridge Mode

In the Full-Bridge Output mode, the P1M1 bit in the CCP1CON register allows the user to control the Forward/Reverse direction. When the application firmware changes this direction control bit, the module will assume the new direction on the next PWM cycle.

Just before the end of the current PWM period, the modulated outputs (P1B and P1D) are placed in their inactive state, while the unmodulated outputs (P1A and P1C) are switched to drive in the opposite direction. This occurs in a time interval of (4 TOSC * (Timer2 Prescale Value) before the next PWM period begins. The Timer2 prescaler will be either 1,4 or 16, depending on the value of the T2CKPS bit (T2CON<1:0>). During the interval from the switch of the unmodulated outputs to the beginning of the next period, the modulated outputs (P1B and P1D) remain inactive. This relationship is shown in Figure 15-10.

Note that in the Full-Bridge Output mode, the ECCP module does not provide any dead-band delay. In general, since only one output is modulated at all times, dead-band delay is not required. However, there is a situation where a dead-band delay might be required. This situation occurs when both of the following conditions are true:

1. The direction of the PWM output changes when the duty cycle of the output is at or near 100%.
2. The turn-off time of the power switch, including the power device and driver circuit, is greater than the turn-on time.

Figure 15-11 shows an example where the PWM direction changes from forward to reverse, at a near 100% duty cycle. At time t1, the output P1A and P1D become inactive, while output P1C becomes active. In this example, since the turn-off time of the power devices is longer than the turn-on time, a shoot-through current may flow through power devices QC and QD (see Figure 15-9) for the duration of ‘t’. The same phenomenon will occur to power devices QA and QB for PWM direction change from reverse to forward.

If changing PWM direction at high duty cycle is required for an application, one of the following requirements must be met:

1. Reduce PWM for a PWM period before changing directions.
2. Use switch drivers that can drive the switches off faster than they can drive them on.

Other options to prevent shoot-through current may exist.

REGISTER 16-2: RCSTA: RECEIVE STATUS AND CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R-0/0	R-0/0	R-x
SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7 **SPEN:** Serial Port Enable bit
1 = Serial port enabled (configures RX/DT and TX/CK pins as serial port pins)
0 = Serial port disabled (held in Reset)

bit 6 **RX9:** 9-bit Receive Enable bit
1 = Selects 9-bit reception
0 = Selects 8-bit reception

bit 5 **SREN:** Single Receive Enable bit
Asynchronous mode:
Don't care.
Synchronous mode – Master:
1 = Enables single receive
0 = Disables single receive
This bit is cleared after reception is complete.
Synchronous mode – Slave:
Don't care.

bit 4 **CREN:** Continuous Receive Enable bit
Asynchronous mode:
1 = Enables receiver
0 = Disables receiver
Synchronous mode:
1 = Enables continuous receive until enable bit, CREN, is cleared (CREN overrides SREN)
0 = Disables continuous receive

bit 3 **ADDEN:** Address Detect Enable bit
Asynchronous mode 9-bit (RX9 = 1):
1 = Enables address detection, generates RCIF interrupt and loads RCREG when RX9D is set
0 = Disables address detection, all bytes are received and ninth bit can be used as parity bit
Asynchronous mode 8-bit (RX9 = 0):
Don't care.

bit 2 **FERR:** Framing Error bit
1 = Framing error (can be updated by reading RCREG register and receiving next valid byte)
0 = No framing error

bit 1 **OERR:** Overrun Error bit
1 = Overrun error (can be cleared by clearing bit CREN)
0 = No overrun error

bit 0 **RX9D:** 9th bit of Received Data
This can be address/data bit or a parity bit and must be calculated by user firmware.

TABLE 16-8: REGISTERS ASSOCIATED WITH SYNCHRONOUS MASTER RECEPTION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
INTCON	GIE/GIEH	PEIE/GIEL	TMR0IE	INT0IE	RBIE	TMR0IF	INT0IF	RBIF	0000 000x	0000 000u
PIR1	—	ADIF	RCIF	TXIF	—	CCP1IF	TMR2IF	TMR1IF	-000 -000	-000 -000
PIE1	—	ADIE	RCIE	TXIE	—	CCP1IE	TMR2IE	TMR1IE	-000 -000	-000 -000
IPR1	—	ADIP	RCIP	TXIP	—	CCP1IP	TMR2IP	TMR1IP	-111 -111	-111 -111
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
RCREG	EUSART Receive Register								0000 0000	0000 0000
TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	0000 0010	0000 0010
BAUDCTL	—	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	-1-1 0-00	-1-1 0-00
SPBRGH	Baud Rate Generator Register High Byte								0000 0000	0000 0000
SPBRG	Baud Rate Generator Register Low Byte								0000 0000	0000 0000

Legend: x = unknown, – = unimplemented, read as '0'. Shaded cells are not used for synchronous master reception.

REGISTER 19-6: CONFIG5L: CONFIGURATION REGISTER 5 LOW (BYTE ADDRESS 300008h)

U-0	U-0	U-0	U-0	U-0	U-0	R/C-1	R/C-1
—	—	—	—	—	—	CP1	CP0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	C = Clearable bit

bit 7-2 **Unimplemented:** Read as ‘0’

bit 1 **CP1:** Code Protection bit (PIC18F1320)
1 = Block 1 (001000-001FFFh) not code-protected
0 = Block 1 (001000-001FFFh) code-protected

bit 0 **CP0:** Code Protection bit (PIC18F1320)
1 = Block 0 (00200-000FFFh) not code-protected
0 = Block 0 (00200-000FFFh) code-protected

bit 1 **CP1:** Code Protection bit (PIC18F1220)
1 = Block 1 (000800-000FFFh) not code-protected
0 = Block 1 (000800-000FFFh) code-protected

bit 0 **CP0:** Code Protection bit (PIC18F1220)
1 = Block 0 (000200-0007FFh) not code-protected
0 = Block 0 (000200-0007FFh) code-protected

REGISTER 19-7: CONFIG5H: CONFIGURATION REGISTER 5 HIGH (BYTE ADDRESS 300009h)

R/C-1	R/C-1	U-0	U-0	U-0	U-0	U-0	U-0
CPD	CPB	—	—	—	—	—	—
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	C = Clearable bit

bit 7 **CPD:** Data EEPROM Code Protection bit
1 = Data EEPROM not code-protected
0 = Data EEPROM code-protected

bit 6 **CPB:** Boot Block Code Protection bit
1 = Boot Block (000000-0001FFh) not code-protected
0 = Boot Block (000000-0001FFh) code-protected

bit 5-0 **Unimplemented:** Read as ‘0’

TABLE 20-1: OPCODE FIELD DESCRIPTIONS

Field	Description
a	RAM access bit a = 0: RAM location in Access RAM (BSR register is ignored) a = 1: RAM bank is specified by BSR register
bbb	Bit address within an 8-bit file register (0 to 7).
BSR	Bank Select Register. Used to select the current RAM bank.
d	Destination select bit d = 0: store result in WREG d = 1: store result in file register f
dest	Destination either the WREG register or the specified register file location.
f	8-bit register file address (0x00 to 0xFF).
fs	12-bit register file address (0x000 to 0xFFF). This is the source address.
fd	12-bit register file address (0x000 to 0xFFF). This is the destination address.
k	Literal field, constant data or label (may be either an 8-bit, 12-bit or a 20-bit value).
label	Label name.
mm * *+ *- +*	The mode of the TBLPTR register for the table read and table write instructions. Only used with table read and table write instructions: No change to register (such as TBLPTR with table reads and writes) Post-Increment register (such as TBLPTR with table reads and writes) Post-Decrement register (such as TBLPTR with table reads and writes) Pre-Increment register (such as TBLPTR with table reads and writes)
n	The relative address (2's complement number) for relative branch instructions, or the direct address for call/branch and return instructions.
PRODH	Product of Multiply High Byte.
PRODL	Product of Multiply Low Byte.
s	Fast Call/Return mode select bit s = 0: do not update into/from shadow registers s = 1: certain registers loaded into/from shadow registers (Fast mode)
u	Unused or unchanged.
WREG	Working register (accumulator).
x	Don't care ('0' or '1'). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools.
TBLPTR	21-bit Table Pointer (points to a program memory location).
TABLAT	8-bit Table Latch.
TOS	Top-of-Stack.
PC	Program Counter.
PCL	Program Counter Low Byte.
PCH	Program Counter High Byte.
PCLATH	Program Counter High Byte Latch.
PCLATU	Program Counter Upper Byte Latch.
GIE	Global Interrupt Enable bit.
WDT	Watchdog Timer.
$\overline{TO}$	Time-out bit.
$\overline{PD}$	Power-down bit.
C, DC, Z, OV, N	ALU Status bits: Carry, Digit Carry, Zero, Overflow, Negative.
[ ]	Optional.
( )	Contents.
→	Assigned to.
< >	Register bit field.
∈	In the set of.
italics	User defined term (font is Courier).

BZ **Branch if Zero**

Syntax: [*label*] BZ n

Operands: $-128 \le n \le 127$

Operation: if Zero bit is '1'
(PC) + 2 + 2n → PC

Status Affected: None

Encoding:

1110	0000	nnnn	nnnn

Description: If the Zero bit is '1', then the program will branch.
The 2's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a 2-cycle instruction.

Words: 1

Cycles: 1(2)

Q Cycle Activity:
If Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	Write to PC
No operation	No operation	No operation	No operation

If No Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	No operation

Example: HERE BZ Jump

Before Instruction
PC = address (HERE)
After Instruction
If Zero = 1;
PC = address (Jump)
If Zero = 0;
PC = address (HERE + 2)

CALL **Subroutine Call**

Syntax: [*label*] CALL k [,s]

Operands: $0 \le k \le 1048575$
$s \in [0,1]$

Operation: (PC) + 4 → TOS,
k → PC<20:1>,
if s = 1
(W) → WS,
(Status) → STATUSS,
(BSR) → BSRS

Status Affected: None

Encoding:

1st word (k<7:0>)	1110	110s	$k_7$kkk	kkkk$_0$
2nd word(k<19:8>)	1111	k_{19}kkk	kkkk	kkkk$_8$

Description: Subroutine call of entire 2-Mbyte memory range. First, return address (PC + 4) is pushed onto the return stack. If 's' = 1, the W, Status and BSR registers are also pushed into their respective shadow registers, WS, STATUSS and BSRS. If 's' = 0, no update occurs (default). Then, the 20-bit value 'k' is loaded into PC<20:1>. CALL is a 2-cycle instruction.

Words: 2

Cycles: 2

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read literal 'k'<7:0>,	Push PC to stack	Read literal 'k'<19:8>, Write to PC
No operation	No operation	No operation	No operation

Example: HERE CALL THERE, FAST

Before Instruction
PC = address (HERE)
After Instruction
PC = address (THERE)
TOS = address (HERE + 4)
WS = W
BSRS = BSR
STATUSS = Status

GOTO **Unconditional Branch**

Syntax: [*label*] GOTO k

Operands: $0 \le k \le 1048575$

Operation: $k \rightarrow PC<20:1>$

Status Affected: None

Encoding:

1st word (k<7:0>)	1110	1111	k_7kkk	$kkkk_0$
2nd word(k<19:8>)	1111	$k_{19}kkk$	kkkk	$kkkk_8$

Description: GOTO allows an unconditional branch anywhere within the entire 2-Mbyte memory range. The 20-bit value 'k' is loaded into PC<20:1>. GOTO is always a 2-cycle instruction.

Words: 2

Cycles: 2

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read literal 'k'<7:0>,	No operation	Read literal 'k'<19:8>, Write to PC
No operation	No operation	No operation	No operation

Example: GOTO THERE

After Instruction
PC = Address (THERE)

INCF **Increment f**

Syntax: [*label*] INCF f [,d [,a]]

Operands: $0 \le f \le 255$
$d \in [0,1]$
$a \in [0,1]$

Operation: (f) + 1 → dest

Status Affected: C, DC, N, OV, Z

Encoding:

0010	10da	ffff	ffff

Description: The contents of register 'f' are incremented. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default). If 'a' is '0', the Access Bank will be selected, overriding the BSR value. If 'a' = 1, then the bank will be selected as per the BSR value (default).

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write to destination

Example: INCF CNT

Before Instruction
CNT = 0xFF
Z = 0
C = ?
DC = ?

After Instruction
CNT = 0x00
Z = 1
C = 1
DC = 1

SUBLW **Subtract W from literal**

Syntax: [*label*] SUBLW k

Operands: $0 \le k \le 255$

Operation: $k - (W) \rightarrow W$

Status Affected: N, OV, C, DC, Z

Encoding:

0000	1000	kkkk	kkkk

Description: W is subtracted from the 8-bit literal ‘k’. The result is placed in W.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read literal ‘k’	Process Data	Write to W

Example 1: `SUBLW 0x02`

Before Instruction
W = 1
C = ?

After Instruction
W = 1
C = 1 ; result is positive
Z = 0
N = 0

Example 2: `SUBLW 0x02`

Before Instruction
W = 2
C = ?

After Instruction
W = 0
C = 1 ; result is zero
Z = 1
N = 0

Example 3: `SUBLW 0x02`

Before Instruction
W = 3
C = ?

After Instruction
W = FF ; (2’s complement)
C = 0 ; result is negative
Z = 0
N = 1

SUBWF **Subtract W from f**

Syntax: [*label*] SUBWF f [,d [,a]]

Operands: $0 \le f \le 255$
$d \in [0,1]$
$a \in [0,1]$

Operation: $(f) - (W) \rightarrow dest$

Status Affected: N, OV, C, DC, Z

Encoding:

0101	11da	ffff	ffff

Description: Subtract W from register ‘f’ (2’s complement method). If ‘d’ is ‘0’, the result is stored in W. If ‘d’ is ‘1’, the result is stored back in register ‘f’ (default). If ‘a’ is ‘0’, the Access Bank will be selected, overriding the BSR value. If ‘a’ is ‘1’, then the bank will be selected as per the BSR value (default).

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register ‘f’	Process Data	Write to destination

Example 1: `SUBWF REG`

Before Instruction
REG = 3
W = 2
C = ?

After Instruction
REG = 1
W = 2
C = 1 ; result is positive
Z = 0
N = 0

Example 2: `SUBWF REG, W`

Before Instruction
REG = 2
W = 2
C = ?

After Instruction
REG = 2
W = 0
C = 1 ; result is zero
Z = 1
N = 0

Example 3: `SUBWF REG`

Before Instruction
REG = 0x01
W = 0x02
C = ?

After Instruction
REG = 0xFFh ;(2’s complement)
W = 0x02
C = 0x00 ;result is negative
Z = 0x00
N = 0x01

TBLRD **Table Read**

Syntax: [*label*] TBLRD (*; *+; *-; +*)

Operands: None

Operation: if TBLRD *,
(Prog Mem (TBLPTR)) → TABLAT;
TBLPTR – No Change;
if TBLRD *+,
(Prog Mem (TBLPTR)) → TABLAT;
(TBLPTR) + 1 → TBLPTR;
if TBLRD *-,
(Prog Mem (TBLPTR)) → TABLAT;
(TBLPTR) – 1 → TBLPTR;
if TBLRD +*,
(TBLPTR) + 1 → TBLPTR;
(Prog Mem (TBLPTR)) → TABLAT;

Status Affected: None

Encoding:

0000	0000	0000	10nn nn = 0* = 1*+ = 2*- = 3+*

Description: This instruction is used to read the contents of Program Memory (P.M.). To address the program memory, a pointer called Table Pointer (TBLPTR) is used. The TBLPTR (a 21-bit pointer) points to each byte in the program memory. TBLPTR has a 2-Mbyte address range.

TBLPTR[0] = 0: Least Significant Byte of Program Memory Word

TBLPTR[0] = 1: Most Significant Byte of Program Memory Word

The TBLRD instruction can modify the value of TBLPTR as follows:

- no change
- post-increment
- post-decrement
- pre-increment

Words: 1

Cycles: 2

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	No operation	No operation	No operation
No operation	No operation (Read Program Memory)	No operation	No operation (Write TABLAT)

TBLRD **Table Read (Continued)**

Example 1: `TBLRD *+ ;`

Before Instruction

TABLAT	=	0x55
TBLPTR	=	0x00A356
MEMORY(0x00A356)	=	0x34

After Instruction

TABLAT	=	0x34
TBLPTR	=	0x00A357

Example 2: `TBLRD +* ;`

Before Instruction

TABLAT	=	0xAA
TBLPTR	=	0x01A357
MEMORY(0x01A357)	=	0x12
MEMORY(0x01A358)	=	0x34

After Instruction

TABLAT	=	0x34
TBLPTR	=	0x01A358

FIGURE 22-1: PIC18F1220/1320 VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)

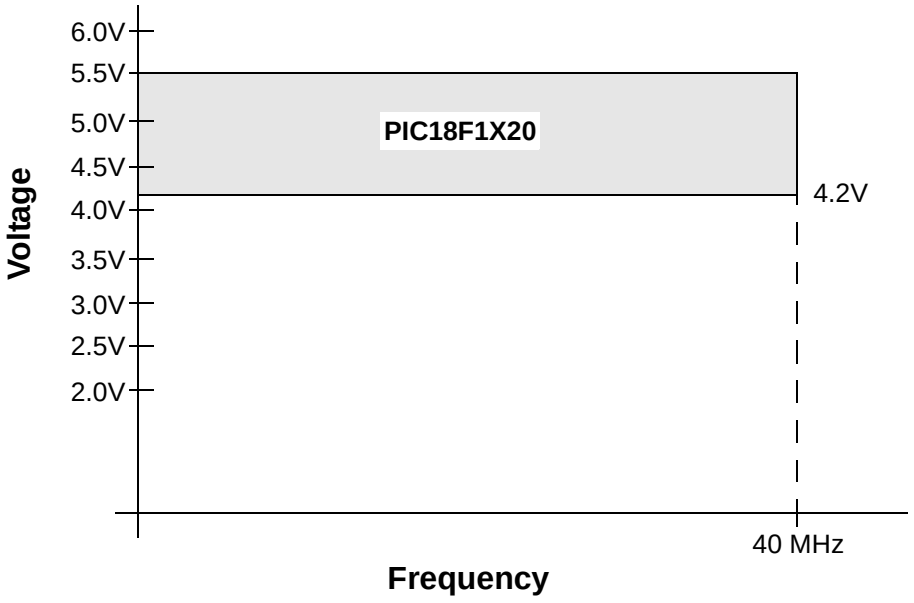
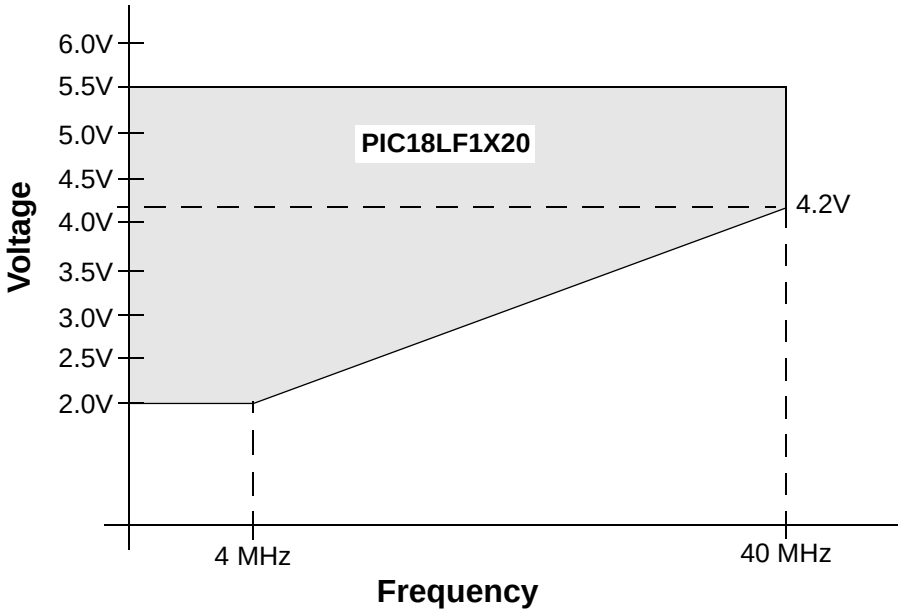


FIGURE 22-2: PIC18LF1220/1320 VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)



F_{MAX} = (16.36 MHz/V) ($V_{DDAPPMIN}$ – 2.0V) + 4 MHz

Note: $V_{DDAPPMIN}$ is the minimum voltage of the PIC® device in the application.

22.2 DC Characteristics: Power-Down and Supply Current PIC18F1220/1320 (Industrial) PIC18LF1220/1320 (Industrial) (Continued)

PIC18LF1220/1320 (Industrial)	Standard Operating Conditions (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for industrial
PIC18F1220/1320 (Industrial, Extended)	**Standard Operating Conditions (unless otherwise stated)** Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended

Param No.	Device	Typ.	Max.	Units	Conditions		
	Supply Current (IDD)(2,3)						
	PIC18LF1220/1320	415	600	µA	-40°C	VDD = 2.0V	FOSC = 4 MHz (**PRI_RUN** mode, EC oscillator)
		425	600	µA	+25°C		
		435	600	µA	+85°C		
	PIC18LF1220/1320	0.87	1.0	mA	-40°C	VDD = 3.0V	
		0.75	1.0	mA	+25°C		
		0.75	1.0	mA	+85°C		
	All devices	1.6	2.0	mA	-40°C	VDD = 5.0V	
		1.6	2.0	mA	+25°C		
		1.5	2.0	mA	+85°C		
	Extended devices	1.5	2.0	mA	+125°C		
	Extended devices	6.3	9.0	mA	+125°C	VDD = 4.2V	FOSC = 25 MHz (**PRI_RUN** mode, EC oscillator)
		9.7	10.0	mA	+125°C	VDD = 5.0V	
	All devices	9.4	12	mA	-40°C	VDD = 4.2V	FOSC = 40 MHz (**PRI_RUN** mode, EC oscillator)
		9.5	12	mA	+25°C		
		9.6	12	mA	+85°C		
	All devices	11.9	15	mA	-40°C	VDD = 5.0V	
		12.1	15	mA	+25°C		
		12.2	15	mA	+85°C		

Legend: Shading of rows is to assist in readability of the table.

Note 1: The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in high-impedance state and tied to VDD or VSS and all features that add delta current disabled (such as WDT, Timer1 Oscillator, BOR, etc.).

2: The supply current is mainly a function of operating voltage, frequency and mode. Other factors, such as I/O pin loading and switching rate, oscillator type and circuit, internal code execution pattern and temperature, also have an impact on the current consumption.
The test conditions for all IDD measurements in active operation mode are:
OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to VDD;
$\overline{MCLR}$ = VDD; WDT enabled/disabled as specified.

3: For RC oscillator configurations, current through REXT is not included. The current through the resistor can be estimated by the formula Ir = VDD/2REXT (mA) with REXT in kΩ.

4: Standard low-cost 32 kHz crystals have an operating temperature range of -10°C to +70°C. Extended temperature crystals are available at a much higher cost.

22.2 DC Characteristics: Power-Down and Supply Current PIC18F1220/1320 (Industrial) PIC18LF1220/1320 (Industrial) (Continued)

PIC18LF1220/1320 (Industrial)		**Standard Operating Conditions (unless otherwise stated)** Operating temperature -40°C ≤ TA ≤ +85°C for industrial					
PIC18F1220/1320 (Industrial, Extended)		**Standard Operating Conditions (unless otherwise stated)** Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended					
Param No.	**Device**	**Typ.**	**Max.**	**Units**	**Conditions**		
	Module Differential Currents (ΔIWDT, ΔIBOR, ΔILVD, ΔIOSCB, ΔIAD)						
D022 (ΔIWDT)	**Watchdog Timer**	1.5	4.0	µA	-40°C	VDD = 2.0V	
		2.2	4.0	µA	+25°C		
		3.1	5.0	µA	+85°C		
		2.5	6.0	µA	-40°C	VDD = 3.0V	
		3.3	6.0	µA	+25°C		
		4.7	7.0	µA	+85°C		
		3.7	10.0	µA	-40°C	VDD = 5.0V	
		4.5	10.0	µA	+25°C		
		6.1	13.0	µA	+85°C		
D022A (ΔIBOR)	**Brown-out Reset**	19	35.0	µA	-40°C to +85°C	VDD = 3.0V	
		24	45.0	µA	-40°C to +85°C	VDD = 5.0V	
D022B (ΔILVD)	**Low-Voltage Detect**	8.5	25.0	µA	-40°C to +85°C	VDD = 2.0V	
		16	35.0	µA	-40°C to +85°C	VDD = 3.0V	
		20	45.0	µA	-40°C to +85°C	VDD = 5.0V	
D025 (ΔIOSCB)	**Timer1 Oscillator**	1.7	3.5	µA	-40°C	VDD = 2.0V	32 kHz on Timer1(4)
		1.8	3.5	µA	+25°C		
		2.1	4.5	µA	+85°C		
		2.2	4.5	µA	-40°C	VDD = 3.0V	32 kHz on Timer1(4)
		2.6	4.5	µA	+25°C		
		2.8	5.5	µA	+85°C		
		3.0	6.0	µA	-40°C	VDD = 5.0V	32 kHz on Timer1(4)
		3.3	6.0	µA	+25°C		
		3.6	7.0	µA	+85°C		
D026 (ΔIAD)	**A/D Converter**	1.0	3.0	µA	-40°C to +85°C	VDD = 2.0V	A/D on, not converting
		1.0	4.0	µA	-40°C to +85°C	VDD = 3.0V	
		2.0	10.0	µA	-40°C to +85°C	VDD = 5.0V	
		1.0	8.0	µA	-40°C to +125°C	VDD = 5.0V	

Legend: Shading of rows is to assist in readability of the table.

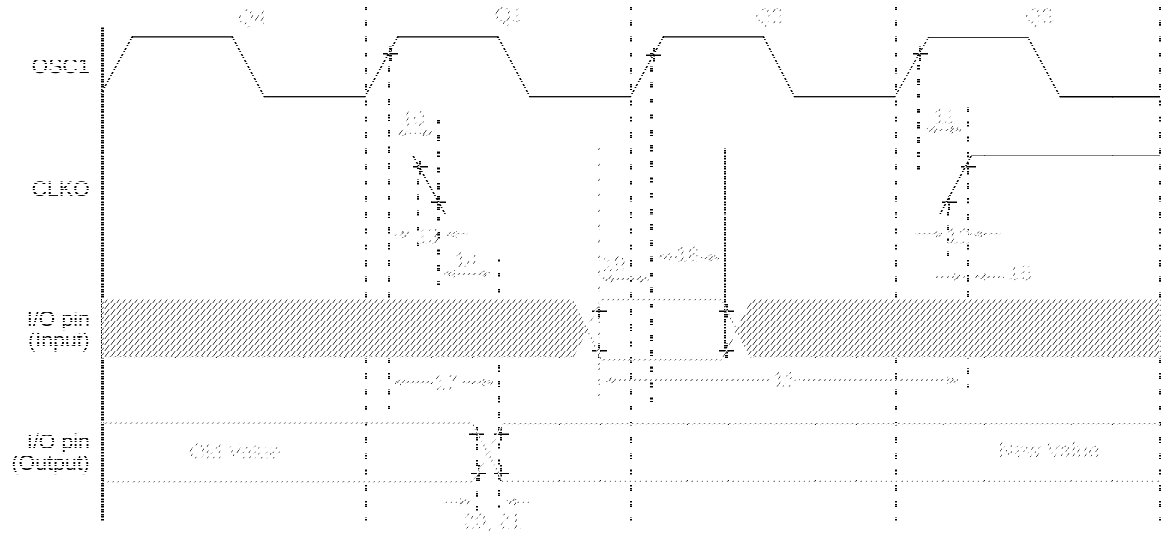
Note 1: The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in high-impedance state and tied to VDD or VSS and all features that add delta current disabled (such as WDT, Timer1 Oscillator, BOR, etc.).

2: The supply current is mainly a function of operating voltage, frequency and mode. Other factors, such as I/O pin loading and switching rate, oscillator type and circuit, internal code execution pattern and temperature, also have an impact on the current consumption.
The test conditions for all IDD measurements in active operation mode are:
OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to VDD;
MCLR = VDD; WDT enabled/disabled as specified.

3: For RC oscillator configurations, current through REXT is not included. The current through the resistor can be estimated by the formula Ir = VDD/2REXT (mA) with REXT in kΩ.

4: Standard low-cost 32 kHz crystals have an operating temperature range of -10°C to +70°C. Extended temperature crystals are available at a much higher cost.

FIGURE 22-7: CLKO AND I/O TIMING



Note: Refer to Figure 22-5 for load conditions.

TABLE 22-7: CLKO AND I/O TIMING REQUIREMENTS

Param. No.	Symbol	Characteristic		Min.	Typ.	Max.	Units	Conditions
10	TosH2ckL	OSC1↑ to CLKO↓		—	75	200	ns	**(Note 1)**
11	TosH2ckH	OSC1↑ to CLKO↑		—	75	200	ns	**(Note 1)**
12	TckR	CLKO Rise Time		—	35	100	ns	**(Note 1)**
13	TckF	CLKO Fall Time		—	35	100	ns	**(Note 1)**
14	TckL2ioV	CLKO↓ to Port Out Valid		—	—	0.5 TCY + 20	ns	**(Note 1)**
15	TioV2ckH	Port In Valid before CLKO↑		0.25 TCY + 25	—	—	ns	**(Note 1)**
16	TckH2ioI	Port In Hold after CLKO↑		0	—	—	ns	**(Note 1)**
17	TosH2ioV	OSC1↑ (Q1 cycle) to Port Out Valid		—	50	150	ns	
18	TosH2ioI	OSC1↑ (Q2 cycle) to Port Input Invalid (I/O in hold time)	PIC18F1X20	100	—	—	ns	
18A			PIC18LF1X20	200	—	—	ns	
19	TioV2osH	Port Input Valid to OSC1↑ (I/O in setup time)		0	—	—	ns	
20	TioR	Port Output Rise Time	PIC18F1X20	—	10	25	ns	
20A			PIC18LF1X20	—	—	60	ns	
21	TioF	Port Output Fall Time	PIC18F1X20	—	10	25	ns	
21A			PIC18LF1X20	—	—	60	ns	

Note 1: Measurements are taken in RC mode, where CLKO output is 4 x TOSC.

FIGURE 23-15: TYPICAL IPD vs. VDD (+25°C), 125 kHz TO 8 MHz RC_RUN MODE, ALL PERIPHERALS DISABLED

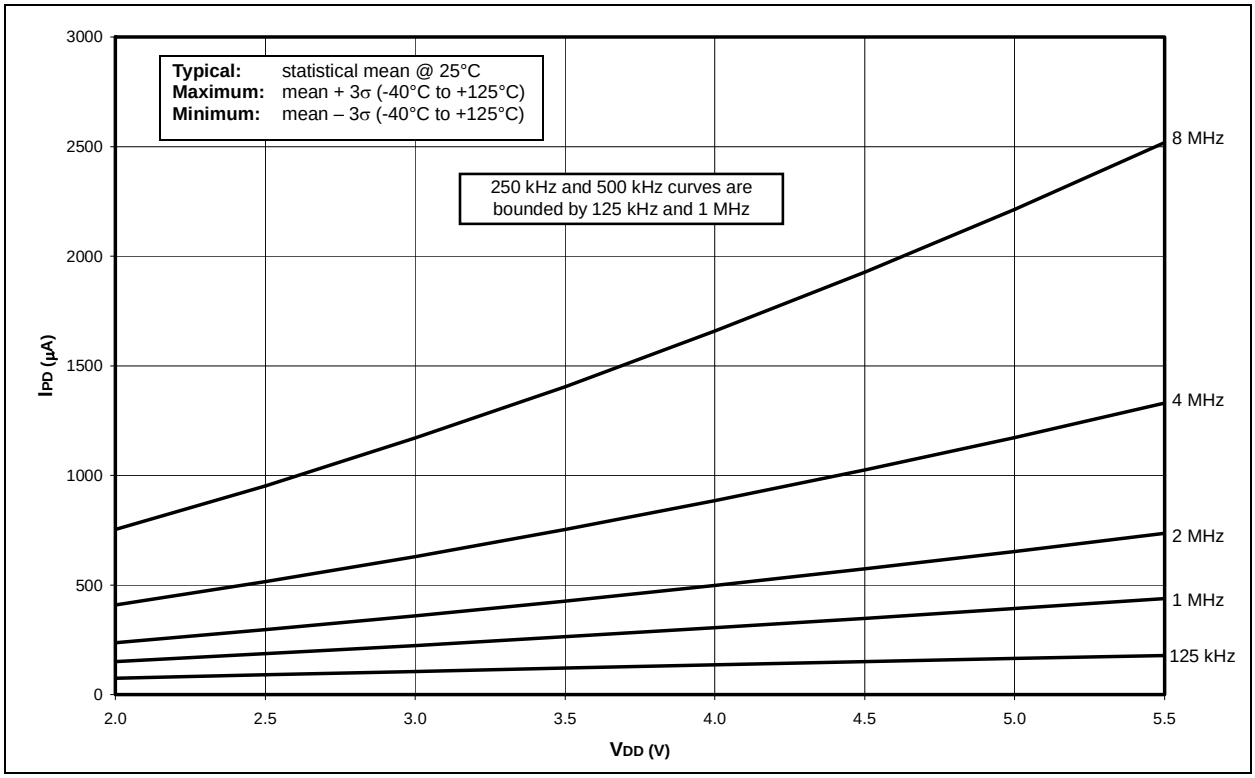
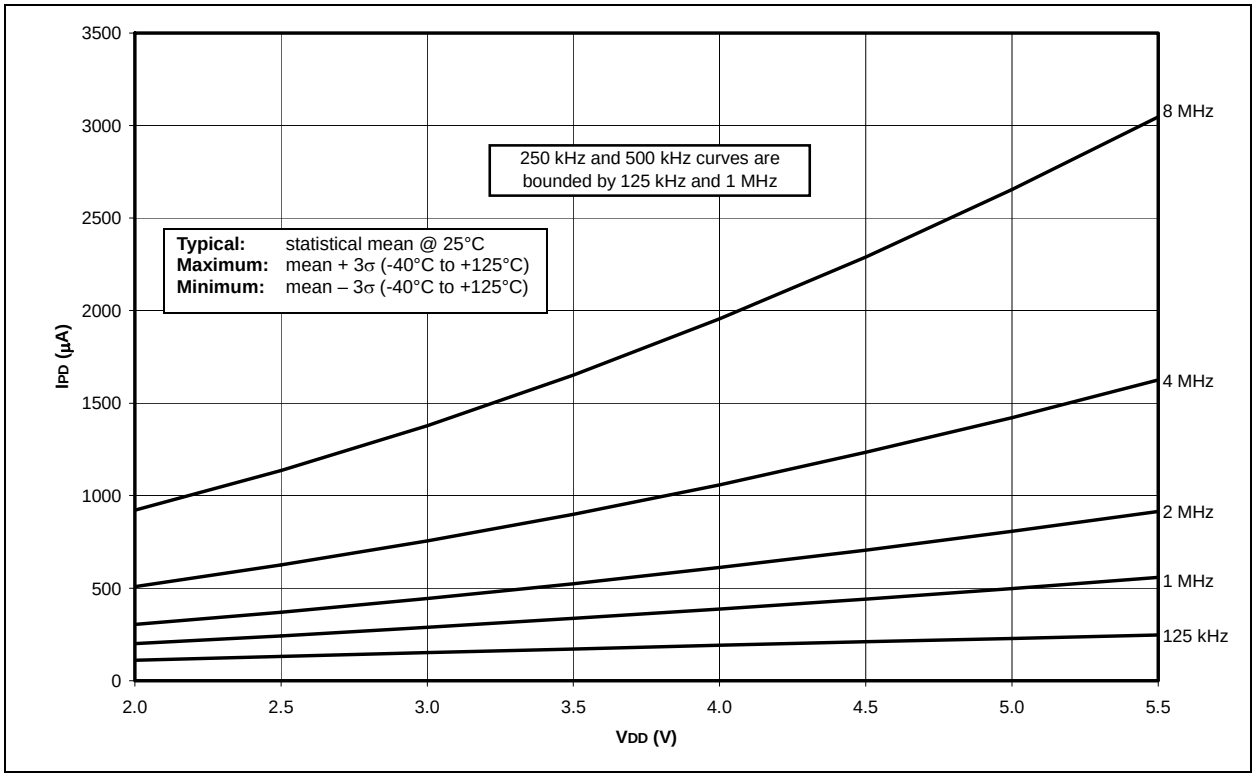
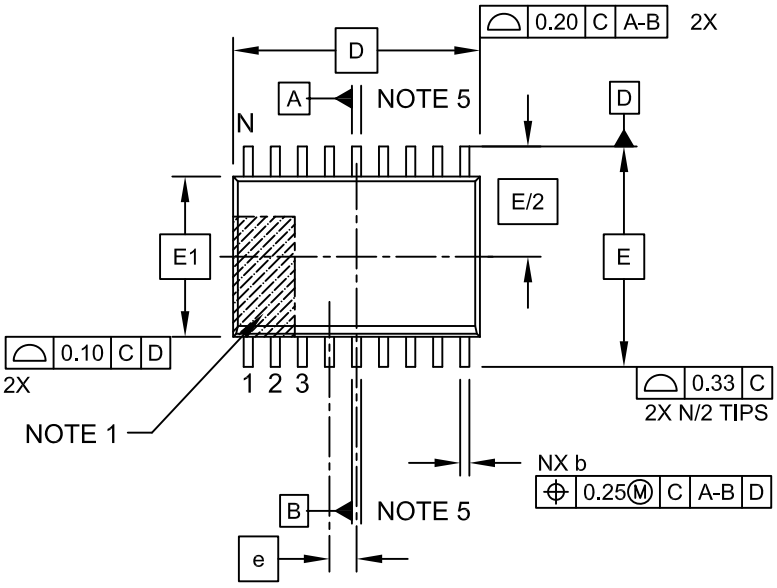


FIGURE 23-16: MAXIMUM IPD vs. VDD (-40°C TO +125°C), 125 kHz TO 8 MHz RC_RUN MODE, ALL PERIPHERALS DISABLED

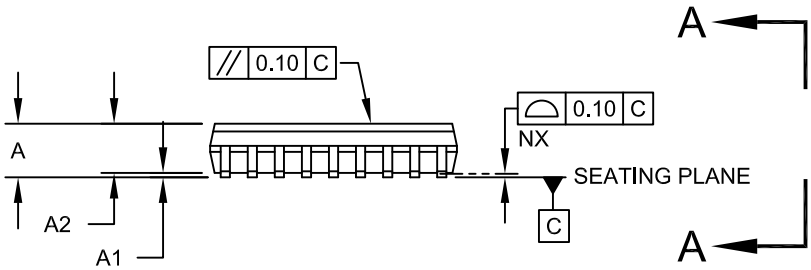


18-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

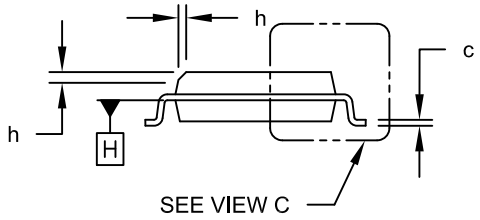
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



TOP VIEW



SIDE VIEW



VIEW A-A

Microchip Technology Drawing C04-051C Sheet 1 of 2

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