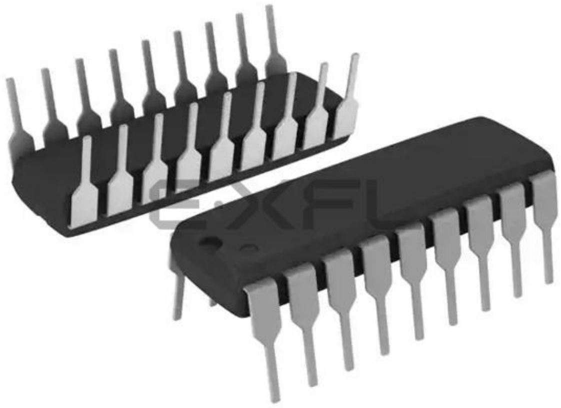

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	25MHz
Connectivity	UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	16
Program Memory Size	8KB (4K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 7x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	18-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f1320-e-p

Table of Contents

1.0 Device Overview 5
2.0 Oscillator Configurations 10
3.0 Power Managed Modes 18
4.0 Reset 31
5.0 Memory Organization 39
6.0 Flash Program Memory 55
7.0 Data EEPROM Memory 64
8.0 8 x 8 Hardware Multiplier 68
9.0 Interrupts 70
10.0 I/O Ports 83
11.0 Timer0 Module 95
12.0 Timer1 Module 98
13.0 Timer2 Module 104
14.0 Timer3 Module 106
15.0 Enhanced Capture/Compare/PWM (ECCP) Module 109
16.0 Enhanced Addressable Universal Synchronous Asynchronous Receiver Transmitter (EUSART) 126
17.0 10-Bit Analog-to-Digital Converter (A/D) Module 149
18.0 Low-Voltage Detect 160
19.0 Special Features of the CPU 165
20.0 Instruction Set Summary 184
21.0 Development Support 226
22.0 Electrical Characteristics 230
23.0 DC and AC Characteristics Graphs and Tables 262
24.0 Packaging Information 280
Appendix A: Revision History 290
Appendix B: Device Differences 290
Appendix C: Conversion Considerations 291
Appendix D: Migration from Baseline to Enhanced Devices 291
Appendix E: Migration from Mid-Range to Enhanced Devices 292
Appendix F: Migration from High-End to Enhanced Devices 292
The Microchip Web Site 293
Customer Change Notification Service 293
Customer Support 293
PIC18F1220/1320 Product Identification System 294

2.7.1 OSCILLATOR CONTROL REGISTER

The OSCCON register (Register 2-2) controls several aspects of the system clock's operation, both in full-power operation and in power managed modes.

The System Clock Select bits, SCS1:SCS0, select the clock source that is used when the device is operating in power managed modes. The available clock sources are the primary clock (defined in Configuration Register 1H), the secondary clock (Timer1 oscillator) and the internal oscillator block. The clock selection has no effect until a `SLEEP` instruction is executed and the device enters a power managed mode of operation. The SCS bits are cleared on all forms of Reset.

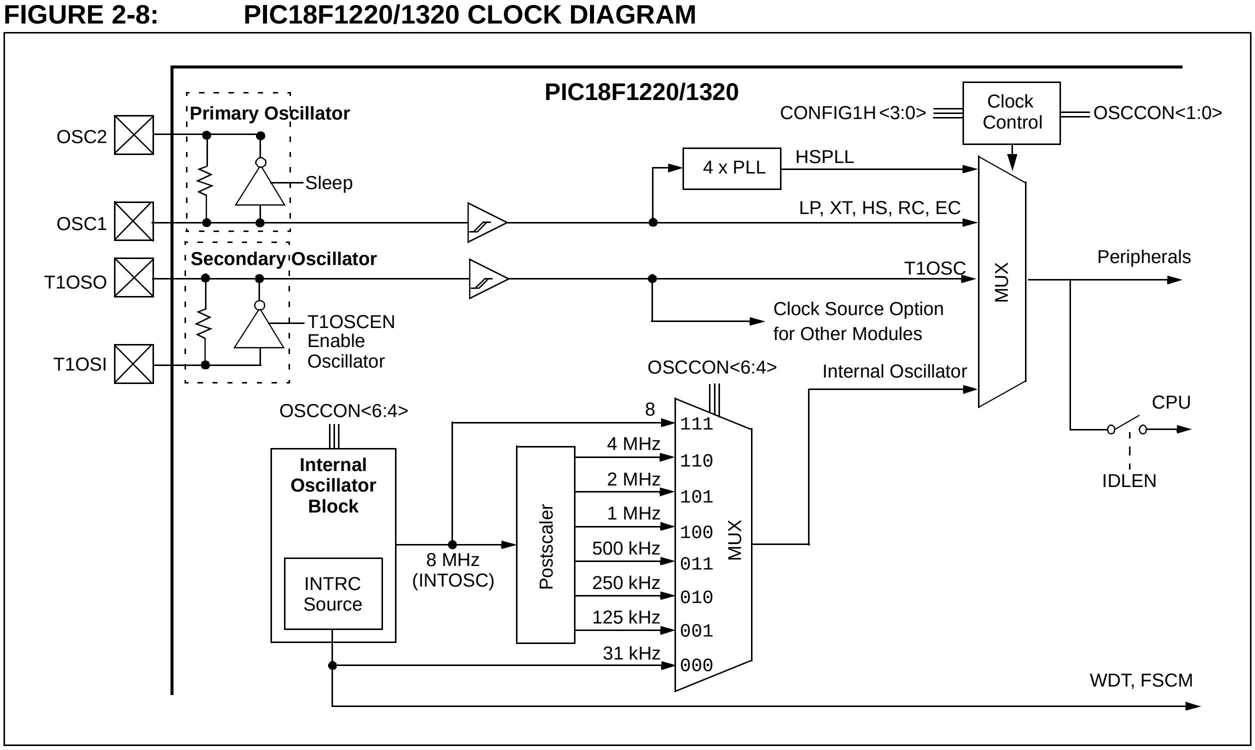
The Internal Oscillator Select bits, IRCF2:IRCF0, select the frequency output of the internal oscillator block that is used to drive the system clock. The choices are the INTRC source, the INTOSC source (8 MHz), or one of the six frequencies derived from the INTOSC postscaler (125 kHz to 4 MHz). If the internal oscillator block is supplying the system clock, changing the states of these bits will have an immediate change on the internal oscillator's output.

The OSTS, IOFS and T1RUN bits indicate which clock source is currently providing the system clock. The OSTS indicates that the Oscillator Start-up Timer has timed out and the primary clock is providing the system clock in Primary Clock modes. The IOFS bit indicates when the internal oscillator block has stabilized and is providing the system clock in RC Clock modes or during Two-Speed Start-ups. The T1RUN bit (T1CON<6>) indicates when the Timer1 oscillator is providing the system clock in Secondary Clock modes. In power managed modes, only one of these three bits will be set at any time. If none of these bits are set, the INTRC is providing the system clock, or the internal oscillator block has just started and is not yet stable.

The IDLEN bit controls the selective shutdown of the controller's CPU in power managed modes. The uses of these bits are discussed in more detail in **Section 3.0 "Power Managed Modes"**.

> **Note 1:** The Timer1 oscillator must be enabled to select the secondary clock source. The Timer1 oscillator is enabled by setting the T1OSCEN bit in the Timer1 Control register (T1CON<3>). If the Timer1 oscillator is not enabled, then any attempt to select a secondary clock source when executing a `SLEEP` instruction will be ignored.
>
> **2:** It is recommended that the Timer1 oscillator be operating and stable before executing the `SLEEP` instruction or a very long delay may occur while the Timer1 oscillator starts.

FIGURE 2-8: PIC18F1220/1320 CLOCK DIAGRAM



5.14 RCON Register

The Reset Control (RCON) register contains flag bits that allow differentiation between the sources of a device Reset. These flags include the $\overline{\text{TO}}$, $\overline{\text{PD}}$, $\overline{\text{POR}}$, $\overline{\text{BOR}}$ and $\overline{\text{RI}}$ bits. This register is readable and writable.

> **Note 1:** If the BOR Configuration bit is set (Brown-out Reset enabled), the $\overline{\text{BOR}}$ bit is '1' on a Power-on Reset. After a Brown-out Reset has occurred, the BOR bit will be cleared and must be set by firmware to indicate the occurrence of the next Brown-out Reset.
>
> **2:** It is recommended that the $\overline{\text{POR}}$ bit be set after a Power-on Reset has been detected, so that subsequent Power-on Resets may be detected.

REGISTER 5-3: RCON: RESET CONTROL REGISTER

R/W-0	U-0	U-0	R/W-1	R-1	R-1	R/W-0	R/W-0
IPEN	—	—	$\overline{\text{RI}}$	$\overline{\text{TO}}$	$\overline{\text{PD}}$	$\overline{\text{POR}}$	$\overline{\text{BOR}}$
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7 **IPEN:** Interrupt Priority Enable bit
1 = Enable priority levels on interrupts
0 = Disable priority levels on interrupts (PIC16CXXX Compatibility mode)

bit 6-5 **Unimplemented:** Read as '0'

bit 4 **$\overline{\text{RI}}$:** `RESET` Instruction Flag bit
1 = The `RESET` instruction was not executed (set by firmware only)
0 = The `RESET` instruction was executed causing a device Reset (must be set in software after a Brown-out Reset occurs)

bit 3 **$\overline{\text{TO}}$:** Watchdog Time-out Flag bit
1 = Set by power-up, `CLRWDT` instruction or `SLEEP` instruction
0 = A WDT time-out occurred

bit 2 **$\overline{\text{PD}}$:** Power-down Detection Flag bit
1 = Set by power-up or by the `CLRWDT` instruction
0 = Cleared by execution of the `SLEEP` instruction

bit 1 **$\overline{\text{POR}}$:** Power-on Reset Status bit
1 = A Power-on Reset has not occurred (set by firmware only)
0 = A Power-on Reset occurred (must be set in software after a Power-on Reset occurs)

bit 0 **$\overline{\text{BOR}}$:** Brown-out Reset Status bit
1 = A Brown-out Reset has not occurred (set by firmware only)
0 = A Brown-out Reset occurred (must be set in software after a Brown-out Reset occurs)

Note 1: For $\overline{\text{Borrow}}$, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand. For rotate (`RRF`, `RLF`) instructions, this bit is loaded with either the high-order or low-order bit of the source register.

6.0 FLASH PROGRAM MEMORY

The Flash program memory is readable, writable and erasable during normal operation over the entire VDD range.

A read from program memory is executed on one byte at a time. A write to program memory is executed on blocks of 8 bytes at a time. Program memory is erased in blocks of 64 bytes at a time. A "Bulk Erase" operation may not be issued from user code.

While writing or erasing program memory, instruction fetches cease until the operation is complete. The program memory cannot be accessed during the write or erase, therefore, code cannot execute. An internal programming timer terminates program memory writes and erases.

A value written to program memory does not need to be a valid instruction. Executing a program memory location that forms an invalid instruction results in a `NOP`.

6.1 Table Reads and Table Writes

In order to read and write program memory, there are two operations that allow the processor to move bytes between the program memory space and the data RAM:

- Table Read (`TBLRD`)
- Table Write (`TBLWT`)

The program memory space is 16 bits wide, while the data RAM space is eight bits wide. Table reads and table writes move data between these two memory spaces through an 8-bit register (TABLAT).

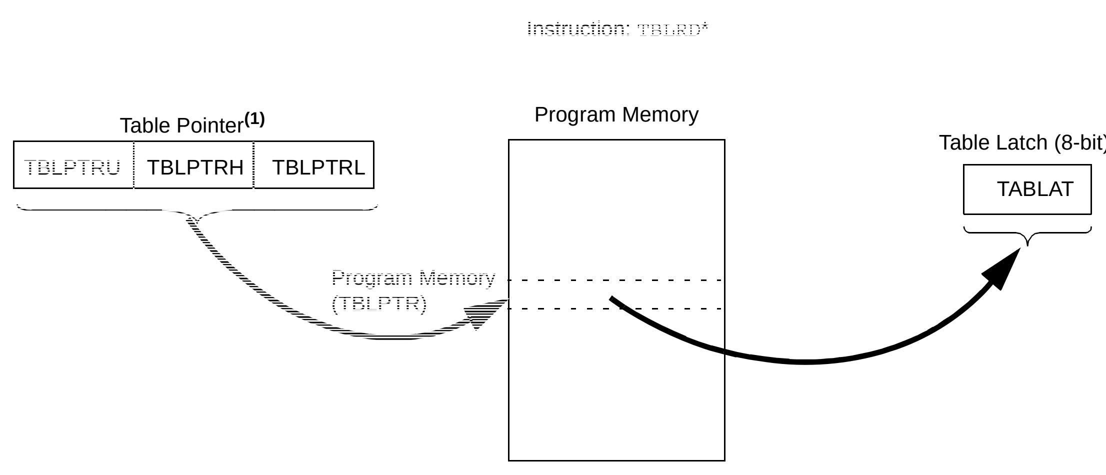
Table read operations retrieve data from program memory and place it into TABLAT in the data RAM space. Figure 6-1 shows the operation of a table read with program memory and data RAM.

Table write operations store data from TABLAT in the data memory space into holding registers in program memory. The procedure to write the contents of the holding registers into program memory is detailed in **Section 6.5 "Writing to Flash Program Memory"**. Figure 6-2 shows the operation of a table write with program memory and data RAM.

Table operations work with byte entities. A table block containing data, rather than program instructions, is not required to be word aligned. Therefore, a table block can start and end at any byte address. If a table write is being used to write executable code into program memory, program instructions will need to be word aligned (TBLPTRL<0> = 0).

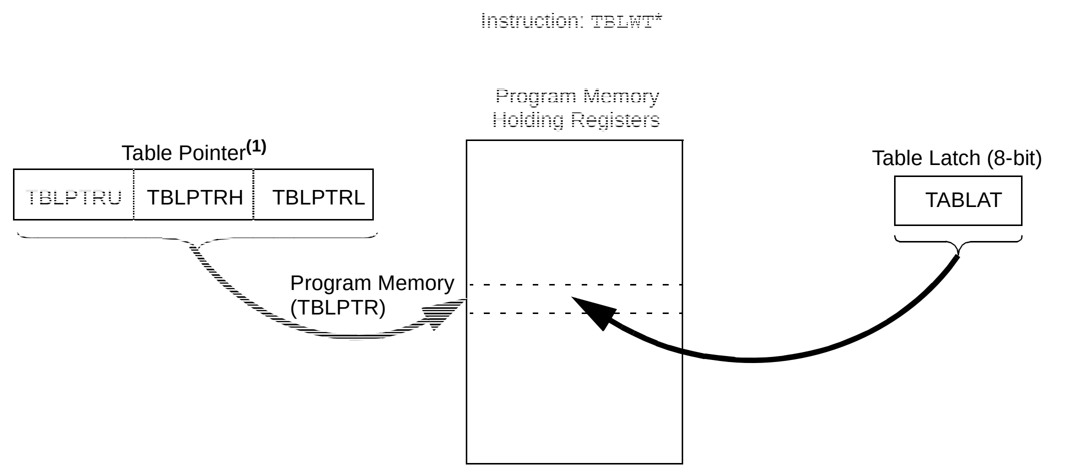
The EEPROM on-chip timer controls the write and erase times. The write and erase voltages are generated by an on-chip charge pump rated to operate over the voltage range of the device for byte or word operations.

FIGURE 6-1: TABLE READ OPERATION



Note 1: Table Pointer points to a byte in program memory.

FIGURE 6-2: TABLE WRITE OPERATION



Note 1: Table Pointer actually points to one of eight holding registers, the address of which is determined by TBLPTRL<2:0>. The process for physically writing data to the program memory array is discussed in **Section 6.5 "Writing to Flash Program Memory"**.

6.2 Control Registers

Several control registers are used in conjunction with the `TBLRD` and `TBLWT` instructions. These include the:

- EECON1 register
- EECON2 register
- TABLAT register
- TBLPTR registers

6.2.1 EECON1 AND EECON2 REGISTERS

EECON1 is the control register for memory accesses.

EECON2 is not a physical register. Reading EECON2 will read all '0's. The EECON2 register is used exclusively in the memory write and erase sequences.

Control bit, EEPGD, determines if the access will be to program or data EEPROM memory. When clear, operations will access the data EEPROM memory. When set, program memory is accessed.

Control bit, CFGS, determines if the access will be to the Configuration registers, or to program memory/data EEPROM memory. When set, subsequent operations access Configuration registers. When CFGS is clear, the EEPGD bit selects either program Flash or data EEPROM memory.

The FREE bit controls program memory erase operations. When the FREE bit is set, the erase operation is initiated on the next WR command. When FREE is clear, only writes are enabled.

The WREN bit enables and disables erase and write operations. When set, erase and write operations are allowed. When clear, erase and write operations are disabled – the WR bit cannot be set while the WREN bit is clear. This process helps to prevent accidental writes to memory due to errant (unexpected) code execution.

Firmware should keep the WREN bit clear at all times, except when starting erase or write operations. Once firmware has set the WR bit, the WREN bit may be cleared. Clearing the WREN bit will not affect the operation in progress.

The WRERR bit is set when a write operation is interrupted by a Reset. In these situations, the user can check the WRERR bit and rewrite the location. It will be necessary to reload the data and address registers (EEDATA and EEADR) as these registers have cleared as a result of the Reset.

Control bits, RD and WR, start read and erase/write operations, respectively. These bits are set by firmware and cleared by hardware at the completion of the operation.

The RD bit cannot be set when accessing program memory (EEPGD = 1). Program memory is read using table read instructions. See **Section 6.3 "Reading the Flash Program Memory"** regarding table reads.

Note: Interrupt flag bit, EEIF in the PIR2 register, is set when the write is complete. It must be cleared in software.

6.2.2 TABLAT – TABLE LATCH REGISTER

The Table Latch (TABLAT) is an 8-bit register mapped into the SFR space. The table latch is used to hold 8-bit data during data transfers between program memory and data RAM.

6.2.3 TBLPTR – TABLE POINTER REGISTER

The Table Pointer (TBLPTR) addresses a byte within the program memory. The TBLPTR is comprised of three SFR registers: Table Pointer Upper Byte, Table Pointer High Byte and Table Pointer Low Byte (TBLPTRU:TBLPTRH:TBLPTRL). These three registers join to form a 22-bit wide pointer. The low-order 21 bits allow the device to address up to 2 Mbytes of program memory space. Setting the 22nd bit allows access to the device ID, the user ID and the configuration bits.

The Table Pointer (TBLPTR) register is used by the `TBLRD` and `TBLWT` instructions. These instructions can update the TBLPTR in one of four ways based on the table operation. These operations are shown in Table 6-1. These operations on the TBLPTR only affect the low-order 21 bits.

6.2.4 TABLE POINTER BOUNDARIES

TBLPTR is used in reads, writes and erases of the Flash program memory.

When a `TBLRD` is executed, all 22 bits of the Table Pointer determine which byte is read from program or configuration memory into TABLAT.

When a `TBLWT` is executed, the three LSbs of the Table Pointer (TBLPTR<2:0>) determine which of the eight program memory holding registers is written to. When the timed write to program memory (long write) begins, the 19 MSbs of the Table Pointer (TBLPTR<21:3>) will determine which program memory block of 8 bytes is written to (TBLPTR<2:0> are ignored). For more detail, see **Section 6.5 "Writing to Flash Program Memory"**.

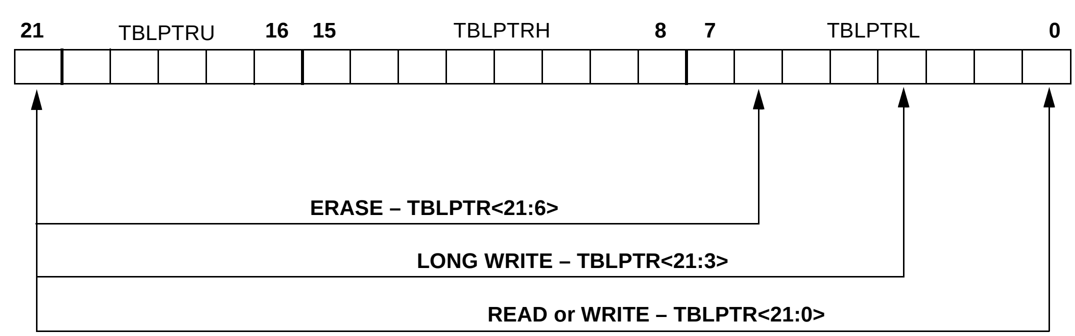
When an erase of program memory is executed, the 16 MSbs of the Table Pointer (TBLPTR<21:6>) point to the 64-byte block that will be erased. The Least Significant bits (TBLPTR<5:0>) are ignored.

Figure 6-3 describes the relevant boundaries of TBLPTR based on Flash program memory operations.

TABLE 6-1: TABLE POINTER OPERATIONS WITH TBLRD AND TBLWT INSTRUCTIONS

Example	Operation on Table Pointer
`TBLRD*` `TBLWT*`	TBLPTR is not modified
`TBLRD*+` `TBLWT*+`	TBLPTR is incremented after the read/write
`TBLRD*-` `TBLWT*-`	TBLPTR is decremented after the read/write
`TBLRD+*` `TBLWT+*`	TBLPTR is incremented before the read/write

FIGURE 6-3: TABLE POINTER BOUNDARIES BASED ON OPERATION



9.3 PIE Registers

The PIE registers contain the individual enable bits for the peripheral interrupts. Due to the number of peripheral interrupt sources, there are two Peripheral Interrupt Enable registers (PIE1, PIE2). When IPEN = 0, the PEIE bit must be set to enable any of these peripheral interrupts.

REGISTER 9-6: PIE1: PERIPHERAL INTERRUPT ENABLE REGISTER 1

U-0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0
—	ADIE	RCIE	TXIE	—	CCP1IE	TMR2IE	TMR1IE
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7 **Unimplemented:** Read as ‘0’

bit 6 **ADIE:** A/D Converter Interrupt Enable bit
1 = Enables the A/D interrupt
0 = Disables the A/D interrupt

bit 5 **RCIE:** EUSART Receive Interrupt Enable bit
1 = Enables the EUSART receive interrupt
0 = Disables the EUSART receive interrupt

bit 4 **TXIE:** EUSART Transmit Interrupt Enable bit
1 = Enables the EUSART transmit interrupt
0 = Disables the EUSART transmit interrupt

bit 3 **Unimplemented:** Read as ‘0’

bit 2 **CCP1IE:** CCP1 Interrupt Enable bit
1 = Enables the CCP1 interrupt
0 = Disables the CCP1 interrupt

bit 1 **TMR2IE:** TMR2 to PR2 Match Interrupt Enable bit
1 = Enables the TMR2 to PR2 match interrupt
0 = Disables the TMR2 to PR2 match interrupt

bit 0 **TMR1IE:** TMR1 Overflow Interrupt Enable bit
1 = Enables the TMR1 overflow interrupt
0 = Disables the TMR1 overflow interrupt

11.0 TIMER0 MODULE

The Timer0 module has the following features:

- Software selectable as an 8-bit or 16-bit timer/counter
- Readable and writable
- Dedicated 8-bit software programmable prescaler
- Clock source selectable to be external or internal
- Interrupt-on-overflow from FFh to 00h in 8-bit mode and FFFFh to 0000h in 16-bit mode
- Edge select for external clock

Figure 11-1 shows a simplified block diagram of the Timer0 module in 8-bit mode and Figure 11-2 shows a simplified block diagram of the Timer0 module in 16-bit mode.

The T0CON register (Register 11-1) is a readable and writable register that controls all the aspects of Timer0, including the prescale selection.

REGISTER 11-1: T0CON: TIMER0 CONTROL REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
TMR0ON	T08BIT	T0CS	T0SE	PSA	T0PS2	T0PS1	T0PS0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7 **TMR0ON:** Timer0 On/Off Control bit
1 = Enables Timer0
0 = Stops Timer0

bit 6 **T08BIT:** Timer0 8-bit/16-bit Control bit
1 = Timer0 is configured as an 8-bit timer/counter
0 = Timer0 is configured as a 16-bit timer/counter

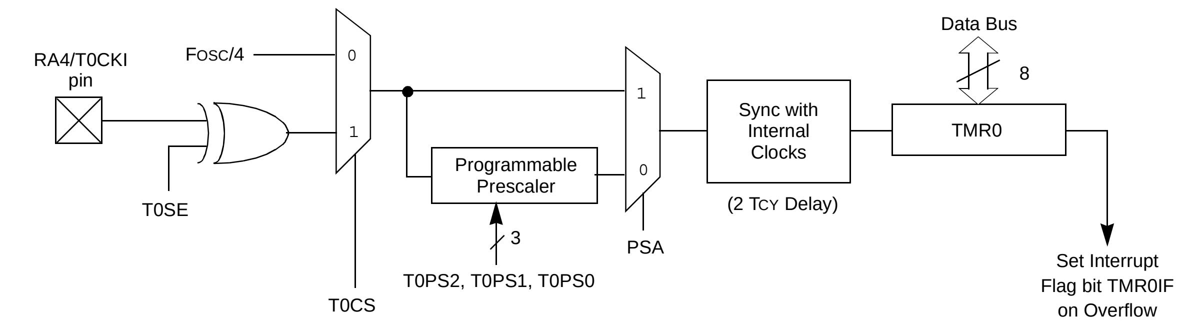
bit 5 **T0CS:** Timer0 Clock Source Select bit
1 = Transition on T0CKI pin
0 = Internal instruction cycle clock (CLKO)

bit 4 **T0SE:** Timer0 Source Edge Select bit
1 = Increment on high-to-low transition on T0CKI pin
0 = Increment on low-to-high transition on T0CKI pin

bit 3 **PSA:** Timer0 Prescaler Assignment bit
1 = TImer0 prescaler is NOT assigned. Timer0 clock input bypasses prescaler.
0 = Timer0 prescaler is assigned. Timer0 clock input comes from prescaler output.

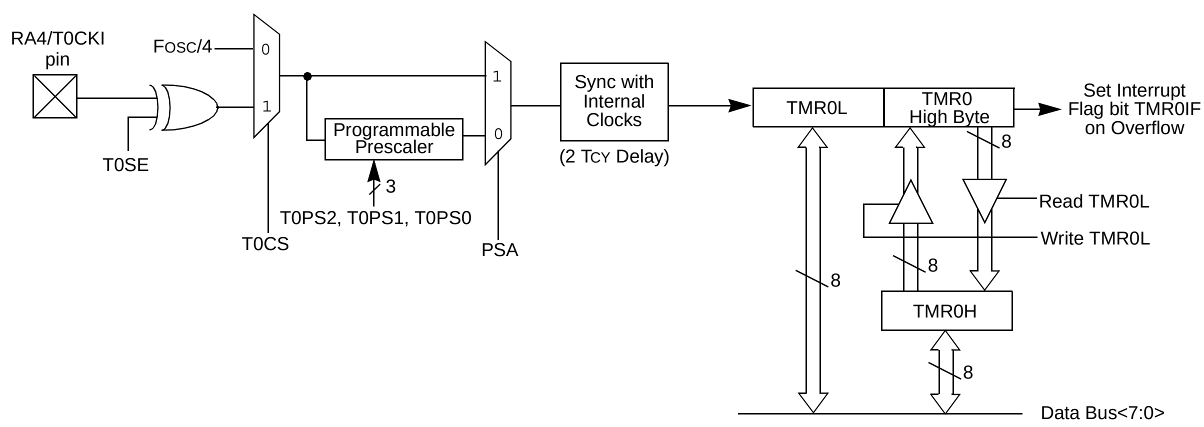
bit 2-0 **T0PS<2:0>:** Timer0 Prescaler Select bits
111 = 1:256 Prescale value
110 = 1:128 Prescale value
101 = 1:64 Prescale value
100 = 1:32 Prescale value
011 = 1:16 Prescale value
010 = 1:8 Prescale value
001 = 1:4 Prescale value
000 = 1:2 Prescale value

FIGURE 11-1: TIMER0 BLOCK DIAGRAM IN 8-BIT MODE



Note: Upon Reset, Timer0 is enabled in 8-bit mode with clock input from T0CKI maximum prescale.

FIGURE 11-2: TIMER0 BLOCK DIAGRAM IN 16-BIT MODE



Note: Upon Reset, Timer0 is enabled in 8-bit mode with clock input from T0CKI maximum prescale.

15.3.4 CCP PRESCALER

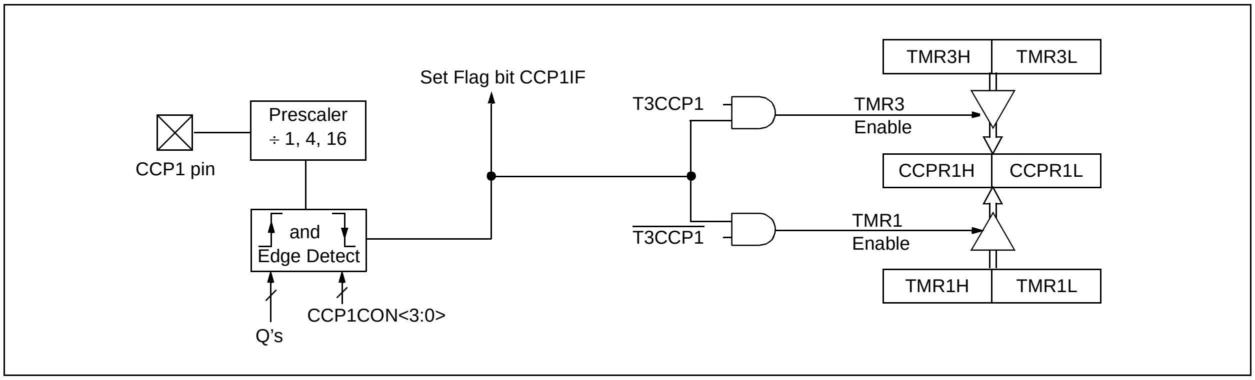
There are four prescaler settings, specified by bits CCP1M3:CCP1M0. Whenever the CCP module is turned off or the CCP module is not in Capture mode, the prescaler counter is cleared. This means that any Reset will clear the prescaler counter.

Switching from one capture prescaler to another may generate an interrupt. Also, the prescaler counter will not be cleared; therefore, the first capture may be from a non-zero prescaler. Example 15-1 shows the recommended method for switching between capture prescalers. This example also clears the prescaler counter and will not generate the “false” interrupt.

EXAMPLE 15-1: CHANGING BETWEEN CAPTURE PRESCALERS

```
CLRF    CCP1CON        ; Turn CCP module off
MOVLW   NEW_CAPT_PS    ; Load WREG with the
                       ; new prescaler mode
                       ; value and CCP ON
MOVWF   CCP1CON        ; Load CCP1CON with
                       ; this value
```

FIGURE 15-1: CAPTURE MODE OPERATION BLOCK DIAGRAM



15.4 Compare Mode

In Compare mode, the 16-bit CCPR1 register value is constantly compared against either the TMR1 register pair value, or the TMR3 register pair value. When a match occurs, the RB3/CCP1/P1A pin:

- Is driven high
- Is driven low
- Toggles output (high-to-low or low-to-high)
- Remains unchanged (interrupt only)

The action on the pin is based on the value of control bits, CCP1M3:CCP1M0. At the same time, interrupt flag bit, CCP1IF, is set.

15.4.1 CCP PIN CONFIGURATION

The user must configure the RB3/CCP1/P1A pin as an output by clearing the TRISB<3> bit.

Note:	Clearing the CCP1CON register will force the RB3/CCP1/P1A compare output latch to the default low level. This is not the PORTB I/O data latch.

15.4.2 TIMER1/TIMER3 MODE SELECTION

Timer1 and/or Timer3 must be running in Timer mode or Synchronized Counter mode if the CCP module is using the compare feature. In Asynchronous Counter mode, the compare operation may not work.

15.4.3 SOFTWARE INTERRUPT MODE

When generate software interrupt is chosen, the RB3/CCP1/P1A pin is not affected. CCP1IF is set and an interrupt is generated (if enabled).

15.4.4 SPECIAL EVENT TRIGGER

In this mode, an internal hardware trigger is generated, which may be used to initiate an action.

The special event trigger output of CCP1 resets the TMR1 register pair. This allows the CCPR1 register to effectively be a 16-bit programmable period register for Timer1.

The special event trigger also sets the GO/$\overline{\text{DONE}}$ bit (ADCON0<1>). This starts a conversion of the currently selected A/D channel if the A/D is on.

15.5.6 PROGRAMMABLE DEAD-BAND DELAY

In half-bridge applications where all power switches are modulated at the PWM frequency at all times, the power switches normally require more time to turn off than to turn on. If both the upper and lower power switches are switched at the same time (one turned on and the other turned off), both switches may be on for a short period of time until one switch completely turns off. During this brief interval, a very high current (shoot-through current) may flow through both power switches, shorting the bridge supply. To avoid this potentially destructive shoot-through current from flowing during switching, turning on either of the power switches is normally delayed to allow the other switch to completely turn off.

In the Half-Bridge Output mode, a digitally programmable dead-band delay is available to avoid shoot-through current from destroying the bridge power switches. The delay occurs at the signal transition from the non-active state to the active state. See Figure 15-6 for an illustration. The lower seven bits of the PWM1CON register (Register 15-2) sets the delay period in terms of microcontroller instruction cycles (T_{CY} or 4 T_{OSC}).

15.5.7 ENHANCED PWM AUTO-SHUTDOWN

When the ECCP is programmed for any of the Enhanced PWM modes, the active output pins may be configured for auto-shutdown. Auto-shutdown immediately places the Enhanced PWM output pins into a defined shutdown state when a shutdown event occurs.

A shutdown event can be caused by the INT0, INT1 or INT2 pins (or any combination of these three sources). The auto-shutdown feature can be disabled by not selecting any auto-shutdown sources. The auto-shutdown sources to be used are selected using the ECCPAS2:ECCPAS0 bits (bits <6:4> of the ECCPAS register).

When a shutdown occurs, the output pins are asynchronously placed in their shutdown states, specified by the PSSAC1:PSSAC0 and PSSBD1:PSSBD0 bits (ECCPAS<3:0>). Each pin pair (P1A/P1C and P1B/P1D) may be set to drive high, drive low or be tri-stated (not driving). The ECCPASE bit (ECCPAS<7>) is also set to hold the Enhanced PWM outputs in their shutdown states.

The ECCPASE bit is set by hardware when a shutdown event occurs. If automatic restarts are not enabled, the ECCPASE bit is cleared by firmware when the cause of the shutdown clears. If automatic restarts are enabled, the ECCPASE bit is automatically cleared when the cause of the auto-shutdown has cleared.

If the ECCPASE bit is set when a PWM period begins, the PWM outputs remain in their shutdown state for that entire PWM period. When the ECCPASE bit is cleared, the PWM outputs will return to normal operation at the beginning of the next PWM period.

Note:	Writing to the ECCPASE bit is disabled while a shutdown condition is active.

REGISTER 16-3: BAUDCTL: BAUD RATE CONTROL REGISTER

U-0	R-1	U-0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0
—	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7 **Unimplemented:** Read as ‘0’

bit 6 **RCIDL**: Receive Operation Idle Status bit
1 = Receiver is Idle
0 = Receiver is busy

bit 5 **Unimplemented:** Read as ‘0’

bit 4 **SCKP**: Synchronous Clock Polarity Select bit
Asynchronous mode:
Unused in this mode.
Synchronous mode:
1 = Idle state for clock (CK) is a high level
0 = Idle state for clock (CK) is a low level

bit 3 **BRG16:** 16-bit Baud Rate Register Enable bit
1 = 16-bit Baud Rate Generator – SPBRGH and SPBRG
0 = 8-bit Baud Rate Generator – SPBRG only (Compatible mode), SPBRGH value ignored

bit 2 **Unimplemented:** Read as ‘0’

bit 1 **WUE:** Wake-up Enable bit
Asynchronous mode:
1 = EUSART will continue to sample the RX pin – interrupt generated on falling edge; bit cleared in hardware on following rising edge
0 = RX pin not monitored or rising edge detected
Synchronous mode:
Unused in this mode.

bit 0 **ABDEN**: Auto-Baud Detect Enable bit
Asynchronous mode:
1 = Enable baud rate measurement on the next character – requires reception of a Sync byte (55h); cleared in hardware upon completion
0 = Baud rate measurement disabled or completed
Synchronous mode:
Unused in this mode.

16.3.2 EUSART ASYNCHRONOUS RECEIVER

The receiver block diagram is shown in Figure 16-5. The data is received on the RB4/AN6/RX/DT/KBI0 pin and drives the data recovery block. The data recovery block is actually a high-speed shifter, operating at x16 times the baud rate, whereas the main receive serial shifter operates at the bit rate or at FOSC. This mode would typically be used in RS-232 systems.

To set up an Asynchronous Reception:

1. Initialize the SPBRGH:SPBRG registers for the appropriate baud rate. Set or clear the BRGH and BRG16 bits, as required, to achieve the desired baud rate.
2. Enable the asynchronous serial port by clearing bit SYNC and setting bit SPEN.
3. If interrupts are desired, set enable bit RCIE.
4. If 9-bit reception is desired, set bit RX9.
5. Enable the reception by setting bit CREN.
6. Flag bit, RCIF, will be set when reception is complete and an interrupt will be generated if enable bit RCIE was set.
7. Read the RCSTA register to get the 9th bit (if enabled) and determine if any error occurred during reception.
8. Read the 8-bit received data by reading the RCREG register.
9. If any error occurred, clear the error by clearing enable bit CREN.
10. If using interrupts, ensure that the GIE and PEIE bits in the INTCON register (INTCON<7:6>) are set.

16.3.3 SETTING UP 9-BIT MODE WITH ADDRESS DETECT

This mode would typically be used in RS-485 systems. To set up an Asynchronous Reception with Address Detect Enable:

1. Initialize the SPBRGH:SPBRG registers for the appropriate baud rate. Set or clear the BRGH and BRG16 bits, as required, to achieve the desired baud rate.
2. Enable the asynchronous serial port by clearing the SYNC bit and setting the SPEN bit.
3. If interrupts are required, set the RCEN bit and select the desired priority level with the RCIP bit.
4. Set the RX9 bit to enable 9-bit reception.
5. Set the ADDEN bit to enable address detect.
6. Enable reception by setting the CREN bit.
7. The RCIF bit will be set when reception is complete. The interrupt will be Acknowledged if the RCIE and GIE bits are set.
8. Read the RCSTA register to determine if any error occurred during reception, as well as read bit 9 of data (if applicable).
9. Read RCREG to determine if the device is being addressed.
10. If any error occurred, clear the CREN bit.
11. If the device has been addressed, clear the ADDEN bit to allow all received data into the receive buffer and interrupt the CPU.

FIGURE 16-5: EUSART RECEIVE BLOCK DIAGRAM

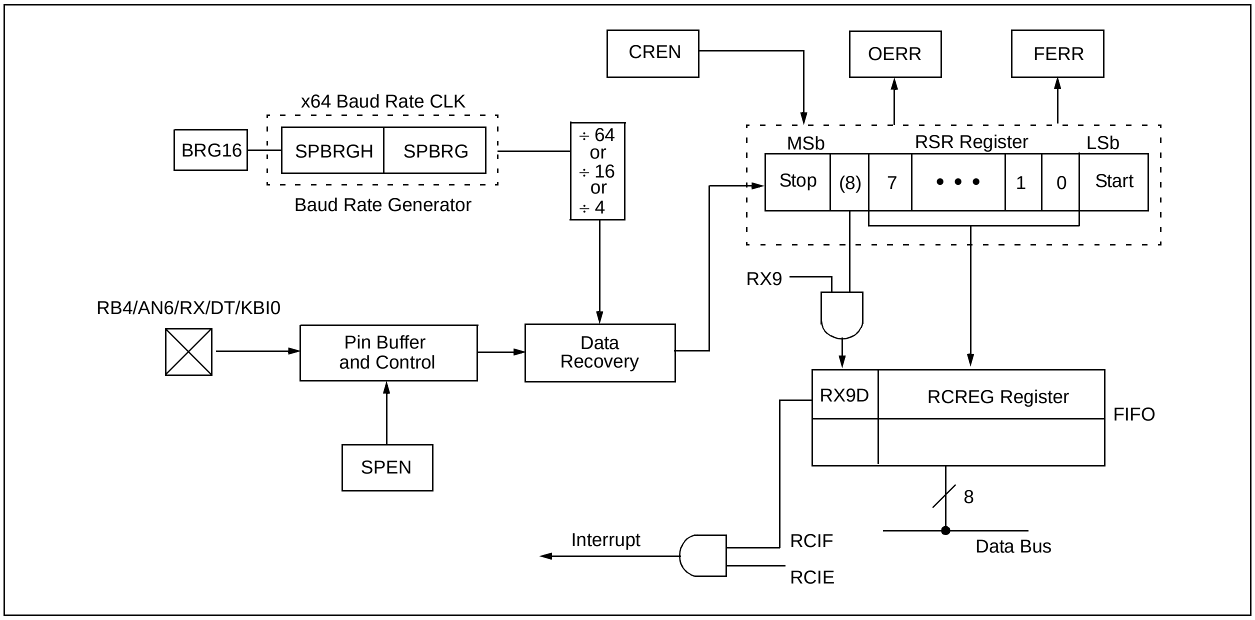


FIGURE 20-1: GENERAL FORMAT FOR INSTRUCTIONS

Byte-oriented file register operations

Example Instruction: `ADDWF MYREG, W, B`

15–10	9	8	7–0
OPCODE	d	a	f (FILE #)

d = `0` for result destination to be WREG register
d = `1` for result destination to be file register (f)
a = `0` to force Access Bank
a = `1` for BSR to select bank
f = 8-bit file register address

Byte to Byte move operations (2-word)

Example Instruction: `MOVFF MYREG1, MYREG2`

15–12	11–0
OPCODE	f (Source FILE #)
`1111`	f (Destination FILE #)

f = 12-bit file register address

Bit-oriented file register operations

Example Instruction: `BSF MYREG, bit, B`

15–12	11–9	8	7–0
OPCODE	b (BIT #)	a	f (FILE #)

b = 3-bit position of bit in file register (f)
a = `0` to force Access Bank
a = `1` for BSR to select bank
f = 8-bit file register address

Literal operations

Example Instruction: `MOVLW 0x7F`

15–8	7–0
OPCODE	k (literal)

k = 8-bit immediate value

Control operations

CALL, GOTO and Branch operations

Example Instruction: `GOTO Label`

15–8	7–0
OPCODE	n<7:0> (literal)

15–12	11–0
`1111`	n<19:8> (literal)

n = 20-bit immediate value

Example Instruction: `CALL MYFUNC`

15–8	8	7–0
OPCODE	S	n<7:0> (literal)

15–12	11–0
	n<19:8> (literal)

S = Fast bit

Example Instruction: `BRA MYFUNC`

15–11	10–0
OPCODE	n<10:0> (literal)

Example Instruction: `BC MYFUNC`

15–8	7–0
OPCODE	n<7:0> (literal)

TABLE 20-1: PIC18FXXXX INSTRUCTION SET

Mnemonic, Operands		Description	Cycles	16-Bit Instruction Word				Status Affected	Notes
				MSb			LSb		
BYTE-ORIENTED FILE REGISTER OPERATIONS									
ADDWF	f, d, a	Add WREG and f	1	0010	01da	ffff	ffff	C, DC, Z, OV, N	1, 2
ADDWFC	f, d, a	Add WREG and Carry bit to f	1	0010	00da	ffff	ffff	C, DC, Z, OV, N	1, 2
ANDWF	f, d, a	AND WREG with f	1	0001	01da	ffff	ffff	Z, N	1,2
CLRF	f, a	Clear f	1	0110	101a	ffff	ffff	Z	2
COMF	f, d, a	Complement f	1	0001	11da	ffff	ffff	Z, N	1, 2
CPFSEQ	f, a	Compare f with WREG, skip =	1 (2 or 3)	0110	001a	ffff	ffff	None	4
CPFSGT	f, a	Compare f with WREG, skip >	1 (2 or 3)	0110	010a	ffff	ffff	None	4
CPFSLT	f, a	Compare f with WREG, skip <	1 (2 or 3)	0110	000a	ffff	ffff	None	1, 2
DECF	f, d, a	Decrement f	1	0000	01da	ffff	ffff	C, DC, Z, OV, N	1, 2, 3, 4
DECFSZ	f, d, a	Decrement f, Skip if 0	1 (2 or 3)	0010	11da	ffff	ffff	None	1, 2, 3, 4
DCFSNZ	f, d, a	Decrement f, Skip if Not 0	1 (2 or 3)	0100	11da	ffff	ffff	None	1, 2
INCF	f, d, a	Increment f	1	0010	10da	ffff	ffff	C, DC, Z, OV, N	1, 2, 3, 4
INCFSZ	f, d, a	Increment f, Skip if 0	1 (2 or 3)	0011	11da	ffff	ffff	None	4
INFSNZ	f, d, a	Increment f, Skip if Not 0	1 (2 or 3)	0100	10da	ffff	ffff	None	1, 2
IORWF	f, d, a	Inclusive OR WREG with f	1	0001	00da	ffff	ffff	Z, N	1, 2
MOVF	f, d, a	Move f	1	0101	00da	ffff	ffff	Z, N	1
MOVFF	f_s, f_d	Move f_s (source) to 1st word f_d (destination) 2nd word	2	1100 1111	ffff ffff	ffff ffff	ffff ffff	None	
MOVWF	f, a	Move WREG to f	1	0110	111a	ffff	ffff	None	
MULWF	f, a	Multiply WREG with f	1	0000	001a	ffff	ffff	None	
NEGF	f, a	Negate f	1	0110	110a	ffff	ffff	C, DC, Z, OV, N	1, 2
RLCF	f, d, a	Rotate Left f through Carry	1	0011	01da	ffff	ffff	C, Z, N	
RLNCF	f, d, a	Rotate Left f (No Carry)	1	0100	01da	ffff	ffff	Z, N	1, 2
RRCF	f, d, a	Rotate Right f through Carry	1	0011	00da	ffff	ffff	C, Z, N	
RRNCF	f, d, a	Rotate Right f (No Carry)	1	0100	00da	ffff	ffff	Z, N	
SETF	f, a	Set f	1	0110	100a	ffff	ffff	None	
SUBFWB	f, d, a	Subtract f from WREG with borrow	1	0101	01da	ffff	ffff	C, DC, Z, OV, N	1, 2
SUBWF	f, d, a	Subtract WREG from f	1	0101	11da	ffff	ffff	C, DC, Z, OV, N	
SUBWFB	f, d, a	Subtract WREG from f with borrow	1	0101	10da	ffff	ffff	C, DC, Z, OV, N	1, 2
SWAPF	f, d, a	Swap nibbles in f	1	0011	10da	ffff	ffff	None	4
TSTFSZ	f, a	Test f, skip if 0	1 (2 or 3)	0110	011a	ffff	ffff	None	1, 2
XORWF	f, d, a	Exclusive OR WREG with f	1	0001	10da	ffff	ffff	Z, N	
BIT-ORIENTED FILE REGISTER OPERATIONS									
BCF	f, b, a	Bit Clear f	1	1001	bbba	ffff	ffff	None	1, 2
BSF	f, b, a	Bit Set f	1	1000	bbba	ffff	ffff	None	1, 2
BTFSC	f, b, a	Bit Test f, Skip if Clear	1 (2 or 3)	1011	bbba	ffff	ffff	None	3, 4
BTFSS	f, b, a	Bit Test f, Skip if Set	1 (2 or 3)	1010	bbba	ffff	ffff	None	3, 4
BTG	f, d, a	Bit Toggle f	1	0111	bbba	ffff	ffff	None	1, 2

Note 1: When a Port register is modified as a function of itself (e.g., `MOVF PORTB, 1, 0`), the value used will be that value present on the pins themselves. For example, if the data latch is '1' for a pin configured as input and is driven low by an external device, the data will be written back with a '0'.

2: If this instruction is executed on the TMR0 register (and where applicable, d = 1), the prescaler will be cleared if assigned.

3: If Program Counter (PC) is modified or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a `NOP`.

4: Some instructions are 2-word instructions. The second word of these instructions will be executed as a `NOP`, unless the first word of the instruction retrieves the information embedded in these 16 bits. This ensures that all program memory locations have a valid instruction.

5: If the table write starts the write cycle to internal memory, the write will continue until terminated.

SLEEP **Enter Sleep mode**

Syntax:	[*label*] SLEEP
Operands:	None
Operation:	00h → WDT, 0 → WDT postscaler, 1 → $\overline{TO}$, 0 → $\overline{PD}$
Status Affected:	$\overline{TO}$, $\overline{PD}$
Encoding:	`0000` `0000` `0000` `0011`
Description:	The Power-down Status bit ($\overline{PD}$) is cleared. The Time-out status bit ($\overline{TO}$) is set. The Watchdog Timer and its postscaler are cleared. The processor is put into Sleep mode with the oscillator stopped.
Words:	1
Cycles:	1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	No operation	Process Data	Go to Sleep

Example: `SLEEP`

Before Instruction
- $\overline{TO}$ = ?
- $\overline{PD}$ = ?

After Instruction
- $\overline{TO}$ = 1 †
- $\overline{PD}$ = 0

† If WDT causes wake-up, this bit is cleared.

SUBFWB **Subtract f from W with borrow**

Syntax:	[*label*] SUBFWB f [,d [,a]]
Operands:	$0 \le f \le 255$ $d \in [0,1]$ $a \in [0,1]$
Operation:	(W) – (f) – ($\overline{C}$) → dest
Status Affected:	N, OV, C, DC, Z
Encoding:	`0101` `01da` `ffff` `ffff`
Description:	Subtract register 'f' and Carry flag (borrow) from W (2's complement method). If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored in register 'f' (default). If 'a' is '0', the Access Bank will be selected, overriding the BSR value. If 'a' is '1', then the bank will be selected as per the BSR value (default).
Words:	1
Cycles:	1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write to destination

Example 1: `SUBFWB REG`

Before Instruction
- REG = 0x03
- W = 0x02
- C = 0x01

After Instruction
- REG = 0xFF
- W = 0x02
- C = 0x00
- Z = 0x00
- N = 0x01 ; result is negative

Example 2: `SUBFWB REG, 0, 0`

Before Instruction
- REG = 2
- W = 5
- C = 1

After Instruction
- REG = 2
- W = 3
- C = 1
- Z = 0
- N = 0 ; result is positive

Example 3: `SUBFWB REG, 1, 0`

Before Instruction
- REG = 1
- W = 2
- C = 0

After Instruction
- REG = 0
- W = 2
- C = 1
- Z = 1 ; result is zero
- N = 0

FIGURE 22-1: PIC18F1220/1320 VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)

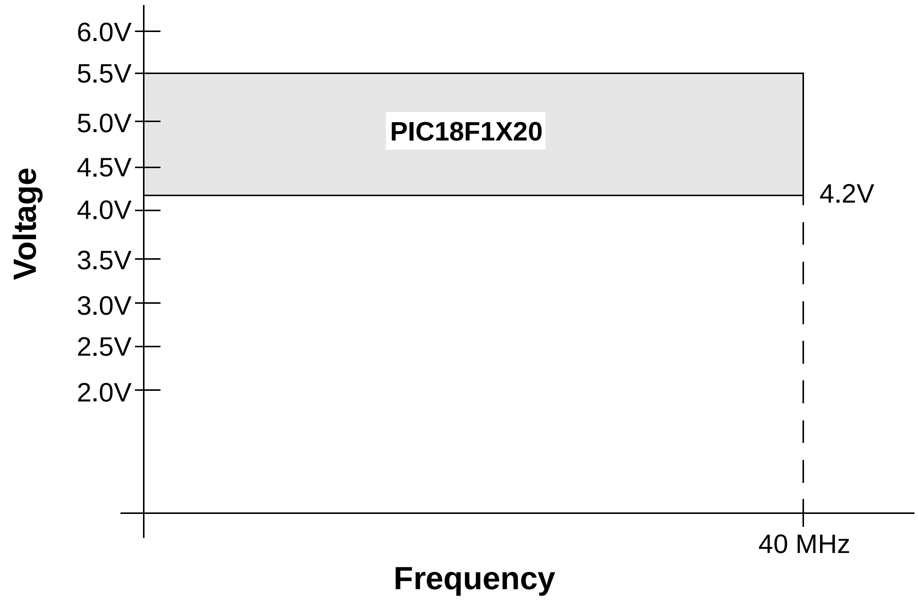
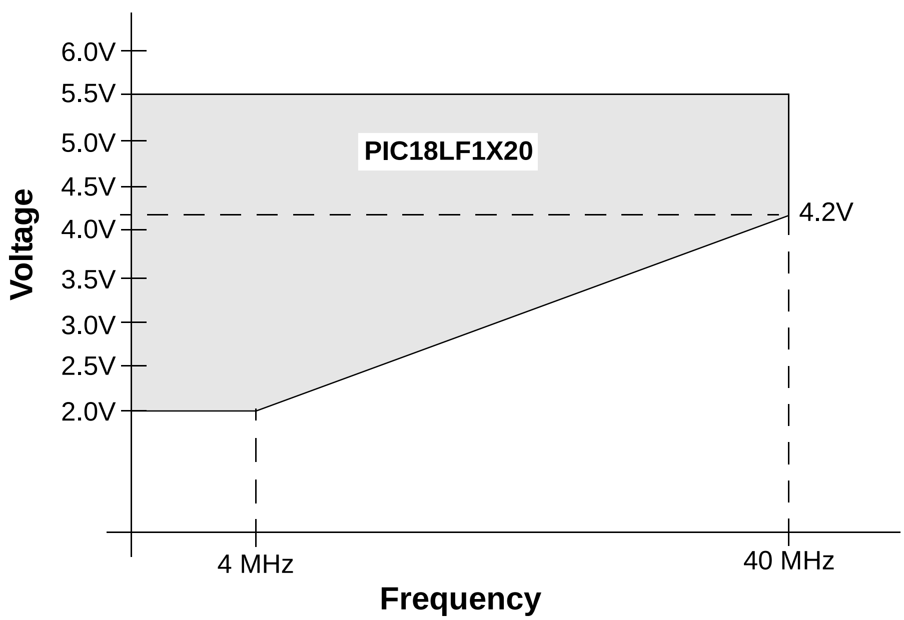


FIGURE 22-2: PIC18LF1220/1320 VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)



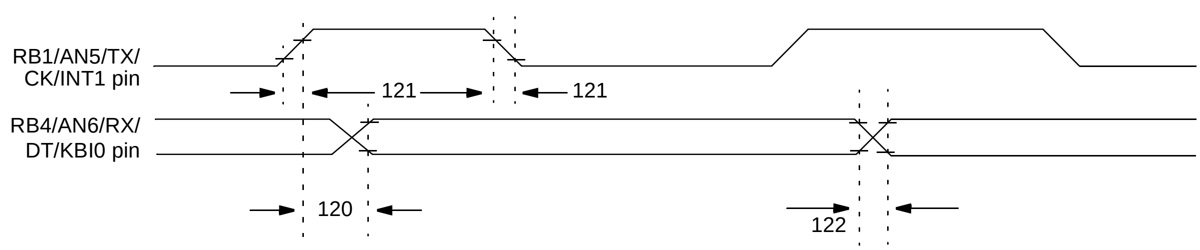
F_{MAX} = (16.36 MHz/V) ($V_{DDAPPMIN}$ – 2.0V) + 4 MHz

Note: $V_{DDAPPMIN}$ is the minimum voltage of the PIC® device in the application.

TABLE 22-10: CAPTURE/COMPARE/PWM REQUIREMENTS (ALL CCP MODULES)

Param. No.	Symbol	Characteristic			Min.	Max.	Units	Conditions
50	TccL	CCPx Input Low Time	No prescaler		0.5 TCY + 20	—	ns	
			With prescaler	PIC18F1X20	10	—	ns	
				PIC18LF1X20	20	—	ns	
51	TccH	CCPx Input High Time	No prescaler		0.5 TCY + 20	—	ns	
			With prescaler	PIC18F1X20	10	—	ns	
				PIC18LF1X20	20	—	ns	
52	TccP	CCPx Input Period			$\frac{3\,T_{CY} + 40}{N}$	—	ns	N = prescale value (1, 4 or 16)
53	TccR	CCPx Output Fall Time		PIC18F1X20	—	25	ns	
				PIC18LF1X20	—	45	ns	
54	TccF	CCPx Output Fall Time		PIC18F1X20	—	25	ns	
				PIC18LF1X20	—	45	ns	

FIGURE 22-12: EUSART SYNCHRONOUS TRANSMISSION (MASTER/SLAVE) TIMING

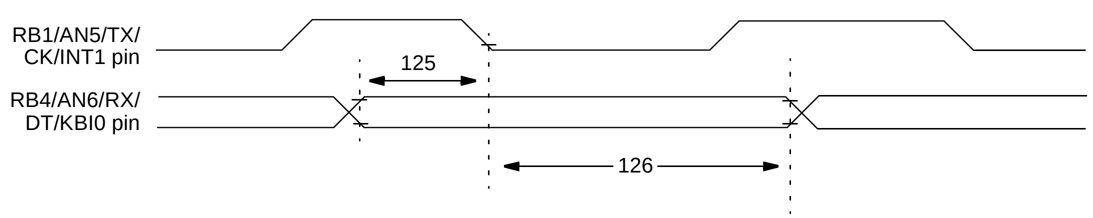


Note: Refer to Figure 22-5 for load conditions.

TABLE 22-11: EUSART SYNCHRONOUS TRANSMISSION REQUIREMENTS

Param. No.	Symbol	Characteristic		Min.	Max.	Units	Conditions
120	TckH2dtV	<u>SYNC XMIT (MASTER & SLAVE)</u> Clock High to Data Out Valid	PIC18F1X20	—	40	ns	
			PIC18LF1X20	—	100	ns	
121	Tckrf	Clock Out Rise Time and Fall Time (Master mode)	PIC18F1X20	—	20	ns	
			PIC18LF1X20	—	50	ns	
122	Tdtrf	Data Out Rise Time and Fall Time	PIC18F1X20	—	20	ns	
			PIC18LF1X20	—	50	ns	

FIGURE 22-13: EUSART SYNCHRONOUS RECEIVE (MASTER/SLAVE) TIMING



Note: Refer to Figure 22-5 for load conditions.

FIGURE 23-11: TYPICAL I_{DD} vs. F_{OSC} OVER V_{DD} PRI_IDLE, EC MODE, +25°C

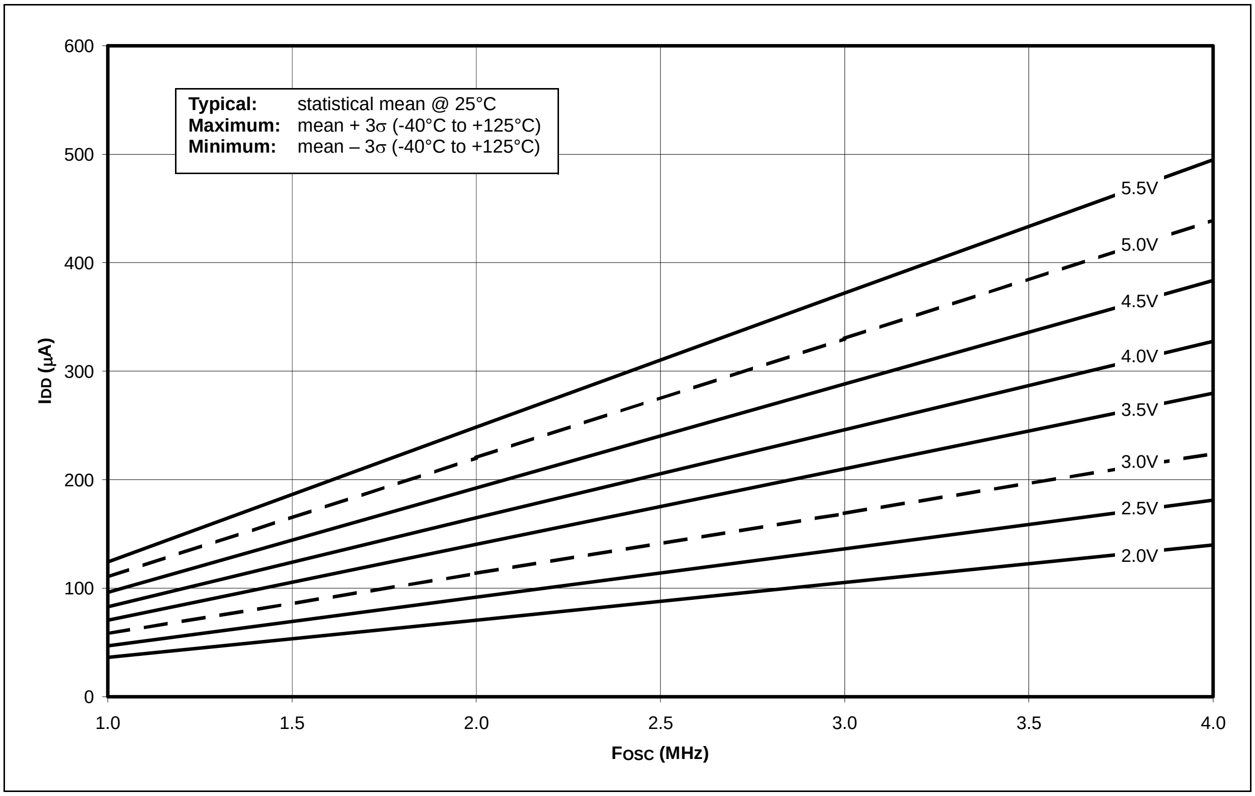


FIGURE 23-12: MAXIMUM I_{DD} vs. F_{OSC} OVER V_{DD} PRI_IDLE, EC MODE, -40°C TO +125°C

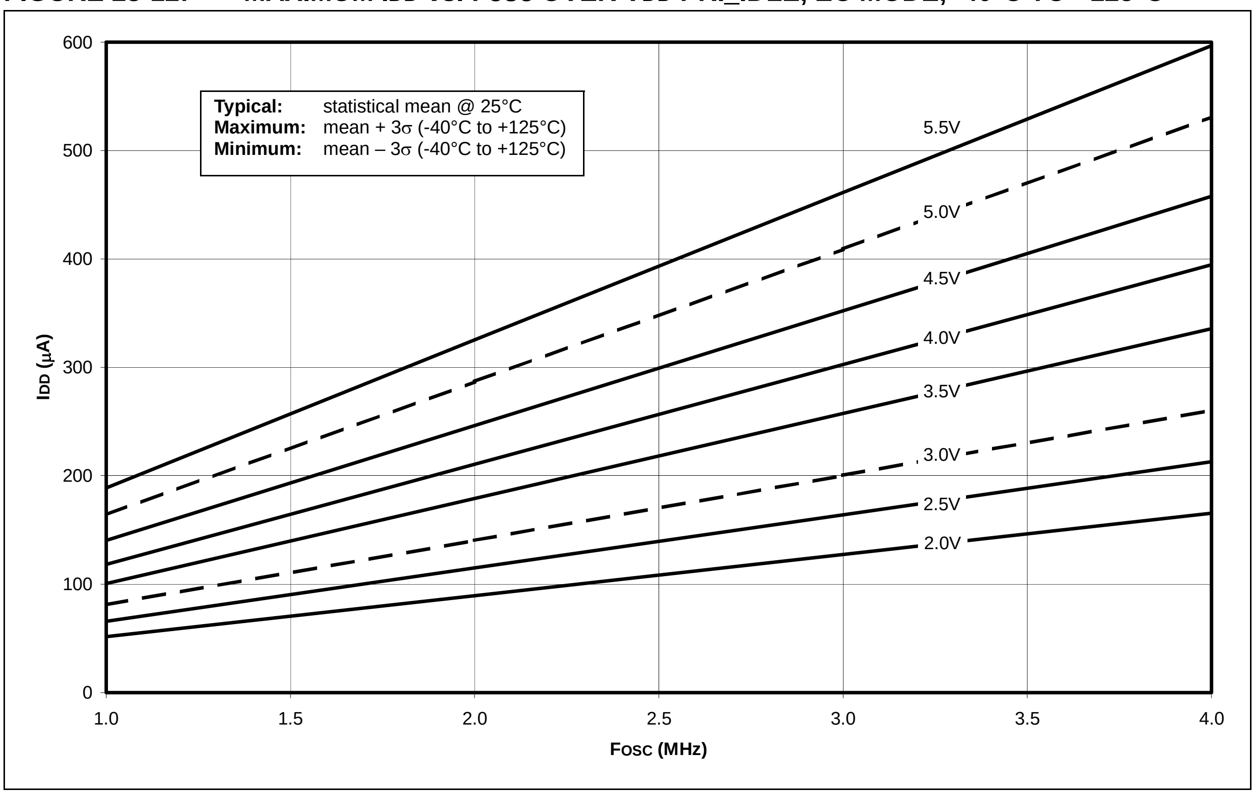


FIGURE 23-25: VOH vs. IOH OVER TEMPERATURE (-40°C TO +125°C), VDD = 5.0V

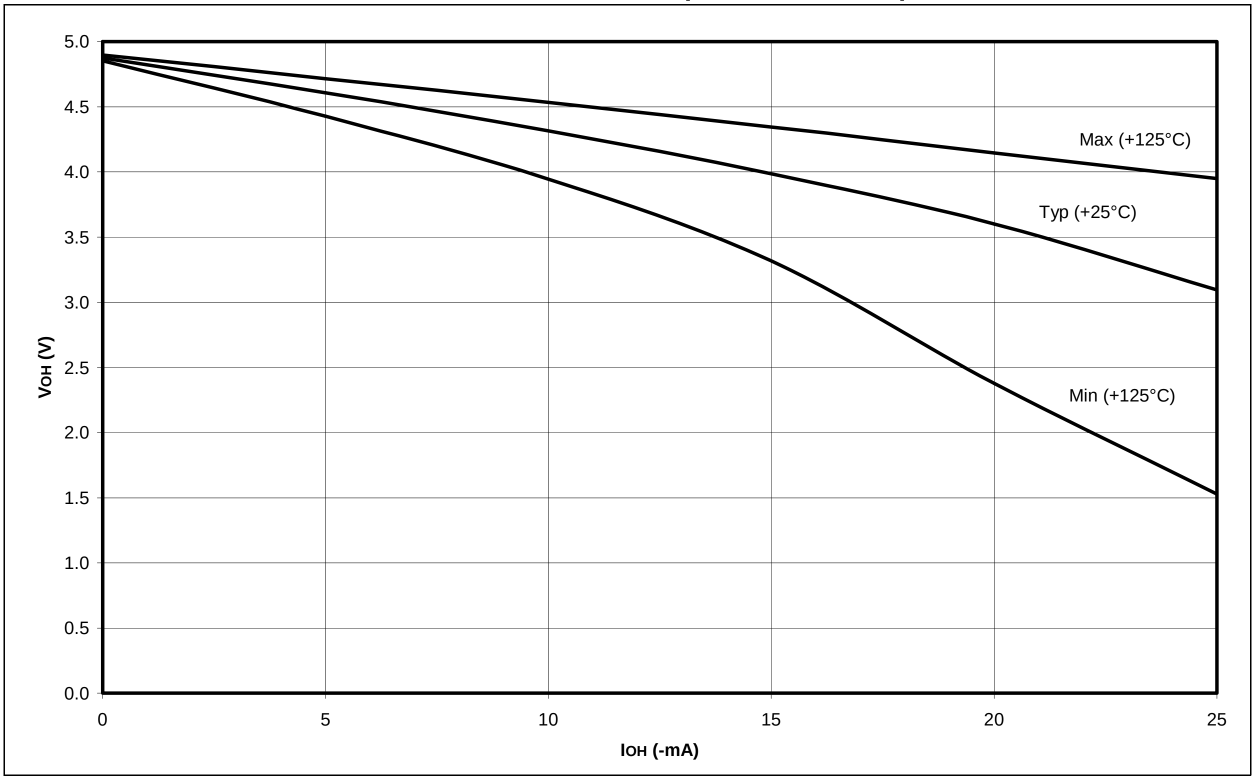


FIGURE 23-26: VOL vs. IOL OVER TEMPERATURE (-40°C TO +125°C), VDD = 3.0V