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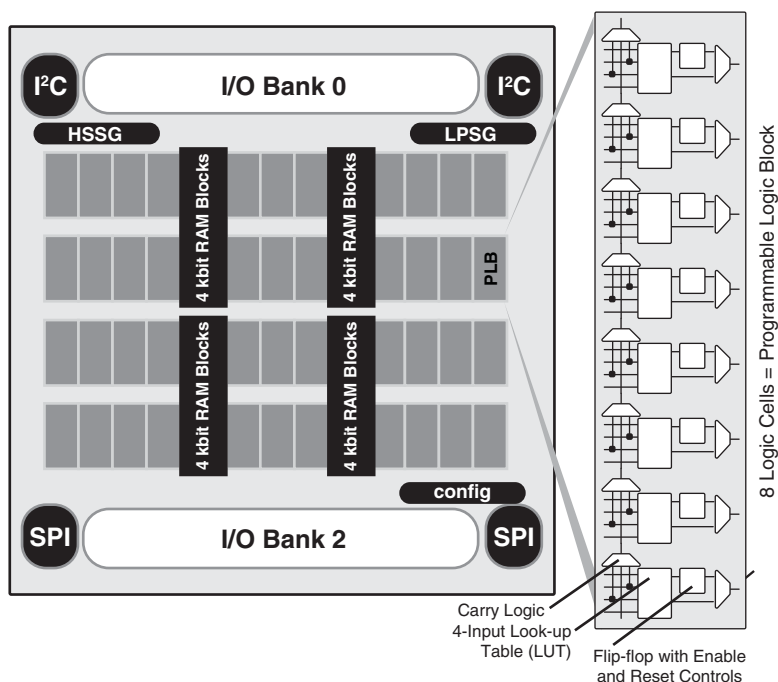
Details

Product Status	Obsolete
Number of LABs/CLBs	250
Number of Logic Elements/Cells	2000
Total RAM Bits	81920
Number of I/O	18
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	25-XFBGA, WLCSP
Supplier Device Package	25-WLCSP (1.7x1.7)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/ice40lm2k-swg25tr

Architecture Overview

The iCE40LM family architecture contains an array of Programmable Logic Blocks (PLB), two Strobe Generators, two user configurable I²C controllers, two user configurable SPI controllers, and blocks of sysMEM™ Embedded Block RAM (EBR) surrounded by Programmable I/O (PIO). Figure 2-1 shows the block diagram of the iCE40LM-4K device.

Figure 2-1. iCE40LM-4K Device, Top View



The logic blocks, Programmable Logic Blocks (PLB) and sysMEM EBR blocks, are arranged in a two-dimensional grid with rows and columns. Each column has either logic blocks or EBR blocks. The PIO cells are located at the top and bottom of the device, arranged in banks. The PLB contains the building blocks for logic, arithmetic, and register functions. The PIOs utilize a flexible I/O buffer referred to as a sysIO buffer that supports operation with a variety of interface standards. The blocks are connected with many vertical and horizontal routing channel resources. The place and route software tool automatically allocates these routing resources.

In the iCE40LM family, There are two sysIO banks, one on top and one on bottom. User can connect both V_{CCIO} s together, if all the I/Os are using the same voltage standard. Refer to the details in later sections of this document. The sysMEM EBRs are large 4 kbit, dedicated fast memory blocks. These blocks can be configured as RAM, ROM or FIFO with user logic using PLBs.

Every device in the family has two user SPI ports, one of these (right side) SPI port also supports programming and configuration of the device. The iCE40LM also includes two user I²C ports, and two Strobe Generators.

Routing

There are many resources provided in the iCE40LM devices to route signals individually with related control signals. The routing resources consist of switching circuitry, buffers and metal interconnect (routing) segments.

The inter-PLB connections are made with three different types of routing resources: Adjacent (spans two PLBs), x4 (spans five PLBs) and x12 (spans thirteen PLBs). The Adjacent, x4 and x12 connections provide fast and efficient connections in the diagonal, horizontal and vertical directions.

The design tool takes the output of the synthesis tool and places and routes the design.

Clock/Control Distribution Network

Each iCE40LM device has six global inputs, two pins on the top bank and four pins on the bottom bank

These global inputs can be used as high fanout nets, clock, reset or enable signals. The dedicated global pins are identified as Gxx and the global buffers are identified as GBUF[7:0]. These six inputs may be used as general purpose I/O if they are not used to drive the clock nets.

Table 2-2 lists the connections between a specific global buffer and the inputs on a PLB. All global buffers optionally connect to the PLB CLK input. Any four of the eight global buffers can drive logic inputs to a PLB. Even-numbered global buffers optionally drive the Set/Reset input to a PLB. Similarly, odd-numbered buffers optionally drive the PLB clock-enable input. GBUF[7:6, 3:0] can connect directly to G[7:6, 3:0] pins respectively. GBUF4 and GBUF5 can connect to the two on-chip Strobe Generators (GBUF4 connects to LPSG, GBUF5 connects to HSSG).

Table 2-2. Global Buffer (GBUF) Connections to Programmable Logic Blocks

Global Buffer	LUT Inputs	Clock	Clock Enable	Reset
GBUF0	Yes, any 4 of 8 GBUF Inputs	Yes	Yes	
GBUF1		Yes		Yes
GBUF2		Yes	Yes	
GBUF3		Yes		Yes
GBUF4		Yes	Yes	
GBUF5		Yes		Yes
GBUF6		Yes	Yes	
GBUF7		Yes		Yes

The maximum frequency for the global buffers are shown in the iCE40LM External Switching Characteristics tables later in this document.

Global Hi-Z Control

The global high-impedance control signal, GHIZ, connects to all I/O pins on the iCE40LM device. This GHIZ signal is automatically asserted throughout the configuration process, forcing all user I/O pins into their high-impedance state.

Global Reset Control

The global reset control signal connects to all PLB and PIO flip-flops on the iCE40LM device. The global reset signal is automatically asserted throughout the configuration process, forcing all flip-flops to their defined wake-up state. For PLB flip-flops, the wake-up state is always reset, regardless of the PLB flip-flop primitive used in the application.

sysCLOCK Phase Locked Loops (PLLs) - *NOT SUPPORTED on the 25-Pin WLCSP*

The sysCLOCK PLLs provide the ability to synthesize clock frequencies. The iCE40LM devices have one sysCLOCK PLL (Please note that the 25-pin WLCSP package does not support the PLL). REFERENCECLK is the reference frequency input to the PLL and its source can come from an external I/O pin, the internal strobe generator or from internal routing. EXTFEEDBACK is the feedback signal to the PLL which can come from internal routing or an external I/O pin. The feedback divider is used to multiply the reference frequency and thus synthesize a higher frequency clock output.

The PLLOUT output has an output divider, thus allowing the PLL to generate different frequencies for each output. The output divider can have a value from 1 to 64 (in increments of 2X). The PLLOUT outputs can all be used to drive the iCE40 global clock network directly or general purpose routing resources can be used.

The LOCK signal is asserted when the PLL determines it has achieved lock and de-asserted if a loss of lock is detected. A block diagram of the PLL is shown in Figure 2-3.

The timing of the device registers can be optimized by programming a phase shift into the PLLOUT output clock which will advance or delay the output clock with reference to the REFERENCECLK clock. This phase shift can be either programmed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after a phase adjustment on the output used as the feedback source and not relock until the tLOCK parameter has been satisfied.

The iCE40LM PLL functions the same as the PLLs in the iCE40 family. For more details on the PLL, see TN1251, [iCE40 sysCLOCK PLL Design and Usage Guide](#).

Figure 2-3. PLL Diagram

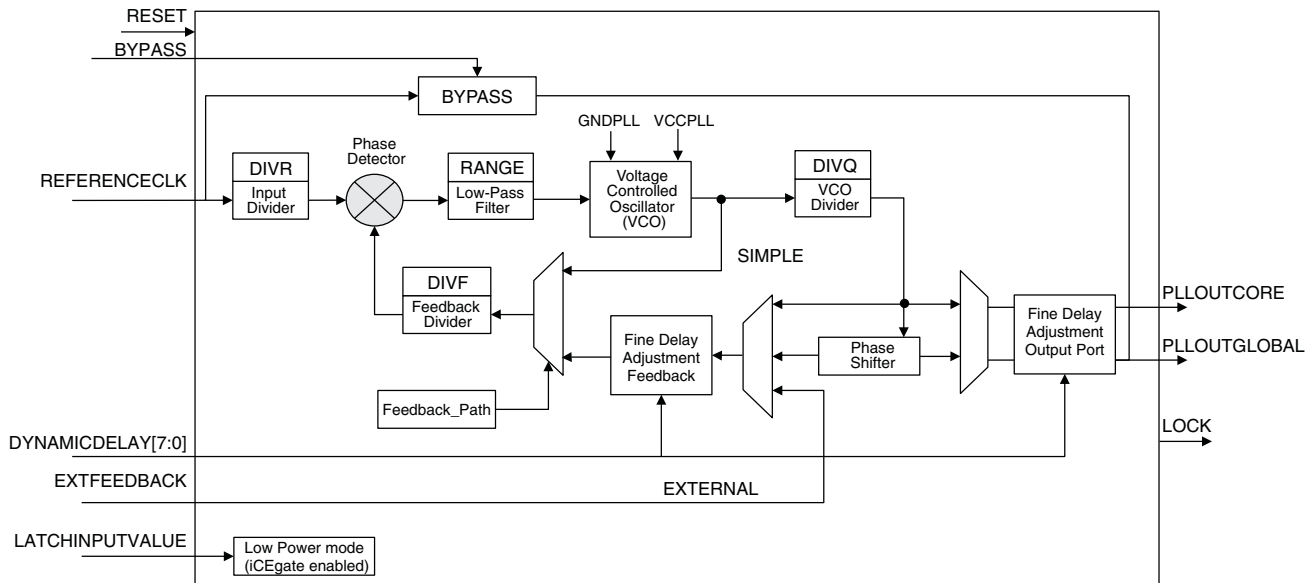


Table 2-3 provides signal descriptions of the PLL block.

RAM Initialization and ROM Operation

If desired, the contents of the RAM can be pre-loaded during device configuration.

By preloading the RAM block during the chip configuration cycle and disabling the write controls, the sysMEM block can also be utilized as a ROM.

Memory Cascading

Larger and deeper blocks of RAM can be created using multiple EBR sysMEM Blocks.

RAM4k Block

Figure 2-4 shows the 256x16 memory configurations and their input/output names. In all the sysMEM RAM modes, the input data and addresses for the ports are registered at the input of the memory array.

Figure 2-4. sysMEM Memory Primitives

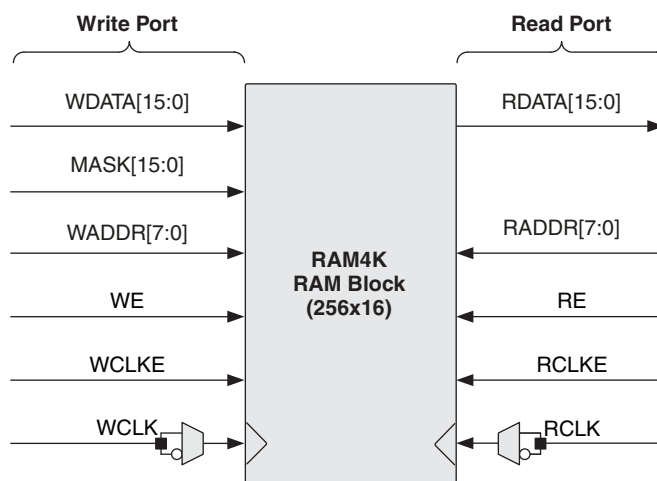


Table 2-5. EBR Signal Descriptions

Signal Name	Direction	Description
WDATA[15:0]	Input	Write Data input.
MASK[15:0]	Input	Masks write operations for individual data bit-lines. 0 = write bit; 1 = don't write bit
WADDR[7:0]	Input	Write Address input. Selects one of 256 possible RAM locations.
WE	Input	Write Enable input.
WCLKE	Input	Write Clock Enable input.
WCLK	Input	Write Clock input. Default rising-edge, but with falling-edge option.
RDATA[15:0]	Output	Read Data output.
RADDR[7:0]	Input	Read Address input. Selects one of 256 possible RAM locations.
RE	Input	Read Enable input.
RCLKE	Input	Read Clock Enable input.
RCLK	Input	Read Clock input. Default rising-edge, but with falling-edge option.

The iCE40LM EBR block functions the same as EBR blocks in the iCE40 family. For further information on the sysMEM EBR block, please refer to TN1250, [Memory Usage Guide for iCE40 Devices](#).

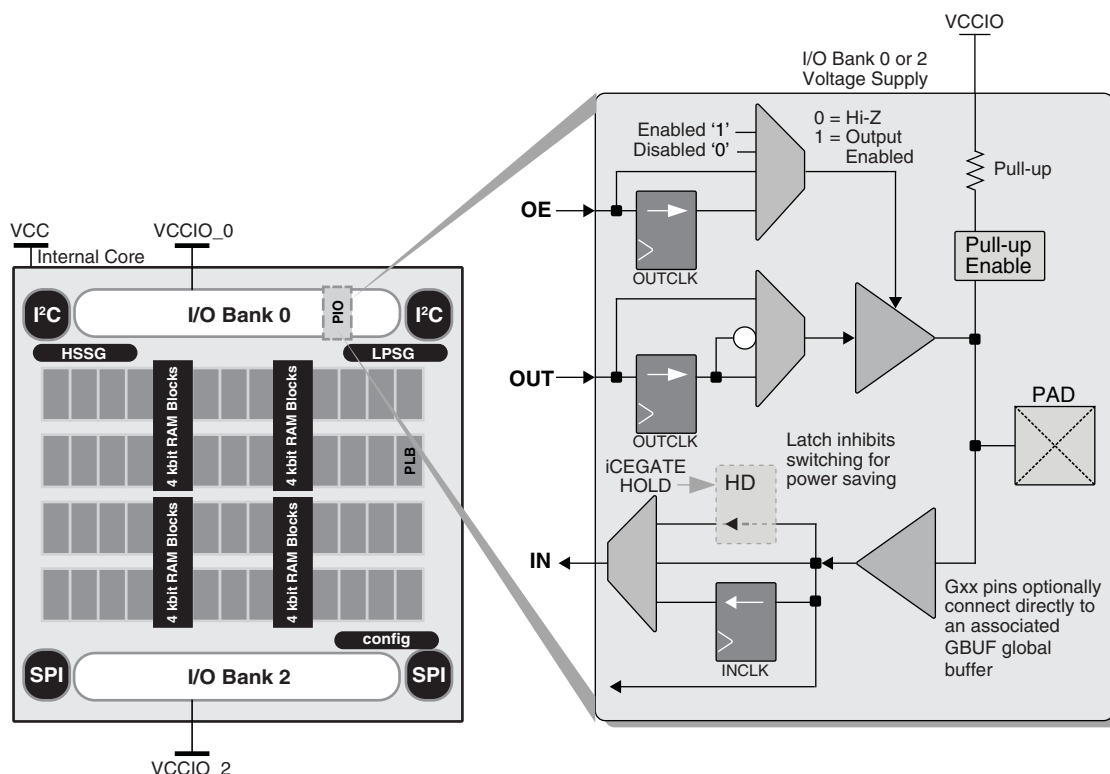
sysIO Buffer Banks

iCE40LM devices have up to two I/O banks with independent V_{CCIO} rails. Configuration bank V_{CC_SPI} for the SPI I/Os is connected to V_{CCIO2} on the 25-pin WLCSP package.

Programmable I/O (PIO)

The programmable logic associated with an I/O is called a PIO. The individual PIOs are connected to their respective sysIO buffers and pads. The PIOs are placed on the top and bottom of the devices.

Figure 2-5. I/O Bank and Programmable I/O Cell



The PIO contains three blocks: an input register block, output register block iCEGate™ and tri-state register block. To save power, the optional iCEGate™ latch can selectively freeze the state of individual, non-registered inputs within an I/O bank. Note that the freeze signal is common to the bank. These blocks can operate in a variety of modes along with the necessary clock and selection logic.

Input Register Block

The input register blocks for the PIOs on all edges contain registers that can be used to condition high-speed interface signals before they are passed to the device core.

Output Register Block

The output register block can optionally register signals from the core of the device before they are passed to the sysIO buffers.

Figure 2-6 shows the input/output register block for the PIOs.

Figure 2-6. iCE I/O Register Block Diagram

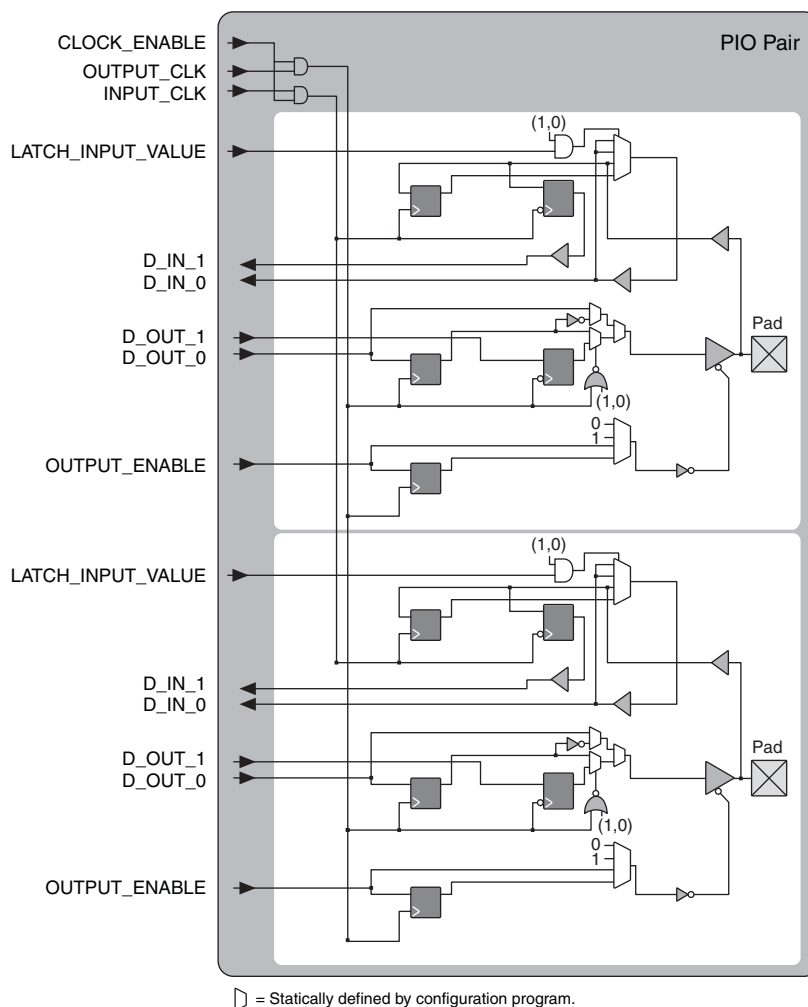


Table 2-6. PIO Signal List

Pin Name	I/O Type	Description
OUTPUT_CLK	Input	Output register clock
CLOCK_ENABLE	Input	Clock enable
INPUT_CLK	Input	Input register clock
OUTPUT_ENABLE	Input	Output enable
D_OUT_0/1	Input	Data from the core
D_IN_0/1	Output	Data to the core
LATCH_INPUT_VALUE	Input	Latches/holds the Input Value

sysIO Buffer

Each I/O is associated with a flexible buffer referred to as a sysIO buffer. These buffers are arranged around the periphery of the device in groups referred to as banks. The sysIO buffers allow users to implement a wide variety of standards that are found in today's systems with LVCMOS interfaces.

User I²C IP

The iCE40LM devices have two I²C IP cores. Either of the two cores can be configured either as an I²C master or as an I²C slave. Both I²C cores have preassigned pins, or user can select different pins, when the core is used.

When the IP core is configured as master, it will be able to control other devices on the I²C bus through the pre-assigned pin interface. When the core is configured as the slave, the device will be able to provide I/O expansion to an I²C Master. The I²C cores support the following functionality:

- Master and Slave operation
- 7-bit and 10-bit addressing
- Multi-master arbitration support
- Clock stretching
- Up to 400 kHz data transfer speed
- General Call support

For further information on the User I²C, please refer to TN1274, [iCE40 I2C and SPI Hardened IP Usage Guide](#).

User SPI IP

The iCE40LM devices have two SPI IP cores. Both SPI cores have preassigned pins, or user can select different pins, when the SPI core is used. Both SPI IP core can be configured as a SPI master or as a slave. When the SPI IP core is configured as a master, it controls the other SPI enabled devices connected to the SPI Bus. When SPI IP core is configured as a slave, the device will be able to interface to an external SPI master.

The SPI IP core supports the following functions:

- Configurable Master and Slave modes
- Full-Duplex data transfer
- Mode fault error flag with CPU interrupt capability
- Double-buffered data register
- Serial clock with programmable polarity and phase
- LSB First or MSB First Data Transfer

For further information on the User SPI, please refer to TN1274, [iCE40 I2C and SPI Hardened IP Usage Guide](#).

High Drive I/O Pins

The iCE40LM family devices offer 3 High Drive (HD) outputs in each device in the family. The HD outputs are ideal to drive LED signals on mobile application.

These HD outputs can be driven in different drive modes. The default is standard drive, which source/sink 8mA current nominally. When HD drive option is selected, these HD outputs can source/sink 24mA current nominally.

The pins on the HD I/Os are labeled with HD in it.

Power On Reset

iCE40LM devices have power-on reset circuitry to monitor V_{CC} , V_{CCIO_0} , V_{CCIO_2} and V_{CC_SPI} voltage levels during power-up and operation. At power-up, the POR circuitry monitors these voltage levels. It then triggers download from the external Flash memory after reaching the power-up levels specified in the Power-On-Reset Voltage table in the DC and Switching Characteristics section of this data sheet. Before and during configuration, the I/Os are held in tri-state. I/Os are released to user functionality once the device has finished configuration.

iCE40LM Configuration

This section describes the programming and configuration of the iCE40LM family.

Device Configuration

There are various ways to configure the Configuration RAM (CRAM) including:

- From a SPI Flash (Master SPI mode)
- System microprocessor to drive a Serial Slave SPI port (SSPI mode)

For more details on configuring the iCE40LM, please see TN1248, [iCE40 Programming and Configuration](#).

Power Saving Options

The iCE40LM devices feature iCEGate and PLL low power mode to allow users to meet the static and dynamic power requirements of their applications. Table 2-9 describes the function of these features.

Table 2-9. iCE40LM Power Saving Features Description

Device Subsystem	Feature Description
PLL	When LATCHINPUTVALUE is enabled, forces the PLL into low-power mode; PLL output held static at last input clock value.
iCEGate	To save power, the optional iCEGate latch can selectively freeze the state of individual, non-registered inputs within an I/O bank. Registered inputs are effectively frozen by their associated clock or clock-enable control.

Power-On-Reset Voltage Levels¹

Symbol	Parameter		Min.	Max.	Units
V _{PORUP}	Power-On-Reset ramp-up trip point (circuit monitoring V _{CC} , V _{CCIO_2} and V _{CC_SPI})	V _{CC}	0.67	0.99	V
		V _{CCIO_2} , V _{CC_SPI}	0.70	1.59	V
V _{PORDN}	Power-On-Reset ramp-down trip point (circuit monitoring V _{CC} , V _{CCIO_2} and V _{CC_SPI})	V _{CC}	—	0.66	V
		V _{CCIO_2} , V _{CC_SPI}	—	1.59	V

1. These POR trip points are only provided for guidance. Device operation is only characterized for power supply voltages specified under recommended operating conditions.

Power Up Sequence

For all iCE40LM devices, it is required to have the V_{CC}/V_{CCPLL} power supply powered up before all other power supplies. The V_{CC}/V_{CCPLL} has to be higher than 0.5 V before other supplies are powered from GND.

In addition, for all iCE40LM devices, it is required that V_{CCSPI} not be the last power supply to ramp up. The V_{CCSPI} has to be higher than 0.5 V before the last supply is ramped.

In the required power up sequence, V_{CC}/V_{CCPLL} should be ramped first. Following V_{CC}/V_{CCPLL} , V_{CCSPI} should be ramped next, followed by the remaining supplies. On the 25-pin WLCSP, V_{CCPLL} is connected to V_{CC} , and is powered up together with V_{CC} . On the 25-pin WLCSP and 36-pin caBGA, V_{CCIO_2} is connected to V_{CCSPI} , and should be powered up right after V_{CC}/V_{CCPLL} with V_{CCSPI} . Due to this connection, V_{CCIO_0} cannot connect to V_{CCIO_2} even if they are at the same supply voltage. The sequence is defined below:

- For 49-pin caBGA: V_{CC} , V_{CCPLL} , V_{CC_SPI} , V_{CCIO_0} and V_{CCIO_2} ; Order of V_{CCIO_0} and V_{CCIO_2} is not important.
- For 36-pin caBGA: V_{CC} , V_{CCPLL} , V_{CC_SPI}/V_{CCIO_2} , V_{CCIO_0}
- For 25-pin WLCSP: V_{CC}/V_{CCPLL} , V_{CC_SPI}/V_{CCIO_2} , V_{CCIO_0}

There is no power down sequence required. However, when partial power supplies are powered down, it is required that the above sequence is followed when these supplies are powered up again.

ESD Performance

Please contact Lattice Semiconductor for additional information.

DC Electrical Characteristics

Over Recommended Operating Conditions

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
I_{IL} , I_{IH} ^{1, 3, 4}	Input or I/O Leakage	$0V < V_{IN} < V_{CCIO} + 0.2 V$	—	—	+/-10	μA
C_1	I/O Capacitance ²	$V_{CCIO} = 3.3 V, 2.5 V, 1.8 V$ $V_{CC} = \text{Typ.}, V_{IO} = 0 \text{ to } V_{CCIO} + 0.2 V$	—	6	—	pf
C_2	Global Input Buffer Capacitance ²	$V_{CCIO} = 3.3 V, 2.5 V, 1.8 V$ $V_{CC} = \text{Typ.}, V_{IO} = 0 \text{ to } V_{CCIO} + 0.2 V$	—	6	—	pf
V_{HYST}	Input Hysteresis	$V_{CCIO} = 1.8 V, 2.5 V, 3.3 V$	—	200	—	mV
I_{PU}	Internal PIO Pull-up Current	$V_{CCIO} = 1.8 V, 0 < V_{IN} < 0.65 V_{CCIO}$	-3	—	-31	μA
		$V_{CCIO} = 2.5 V, 0 < V_{IN} < 0.65 V_{CCIO}$	-8	—	-72	μA
		$V_{CCIO} = 3.3 V, 0 < V_{IN} < 0.65 V_{CCIO}$	-11	—	-128	μA

1. Input or I/O leakage current is measured with the pin configured as an input or as an I/O with the output driver tri-stated. It is not measured with the output driver active. Internal pull-up resistors are disabled.

2. T_J 25 °C, $f = 1.0 \text{ MHz}$.

3. Please refer to V_{IL} and V_{IH} in the sysIO Single-Ended DC Electrical Characteristics table of this document.

4. Some products are clamped to a diode when V_{IN} is larger than V_{CCIO} .

Supply Current ^{1, 2, 3, 4}

Symbol	Parameter	Typ. VCC ⁴	Units
I _{CCSTDBY}	Core Power Supply Static Current	100	uA
I _{CCPLLSTDBY}	PLL Power Supply Static Current	11	uA
I _{CCIOSTDBY} , I _{CC_SPISTDBY}	V _{CCIO} , V _{CC_SPI} Power Supply Static Current	2.5	uA
I _{CCPEAK}	Core Power Supply Startup Peak Current	11.2	mA
I _{CCPLLPEAK}	PLL Power Supply Startup Peak Current	2.8	mA
I _{CCIOPEAK} , I _{CC_SPIPEAK}	V _{CCIO} , V _{CC_SPI} Power Supply Startup Peak Current	21.4	mA

- Assumes blank pattern with the following characteristics: all outputs are tri-stated, all inputs are configured as LVCMOS and held at V_{CCIO} or GND, on-chip PLL is off. For more detail with your specific design, use the Power Calculator tool. Power specified with master SPI configuration mode. Other modes may be up to 25% higher.
- Frequency = 0 MHz.
- T_J = 25 °C, power supplies at nominal voltage.
- Does not include pull-up.
- For 25-pin WLCSP, V_{CCPLL} is tied internally on the package, and V_{CC_SPI} is also connected to V_{CCIO_2} on the package.

User I²C Specifications

Parameter Symbol	Parameter Description	spec (STD Mode)			spec (FAST Mode)			Units
		Min	Typ	Max	Min	Typ	Max	
f _{SCL}	Maximum SCL clock frequency	—	—	100	—	—	400	kHz
t _{HI}	SCL clock HIGH Time	4	—	—	0.6	—	—	μs
t _{LO}	SCL clock LOW Time	4.7	—	—	1.3	—	—	μs
t _{SU,DAT}	Setup time (DATA)	250	—	—	100	—	—	ns
t _{HD,DAT}	Hold time (DATA)	0	—	—	0	—	—	ns
t _{SU,STA}	Setup time (START condition)	4.7	—	—	0.6	—	—	μs
t _{HD,STA}	Hold time (START condition)	4	—	—	0.6	—	—	μs
t _{SU,STO}	Setup time (STOP condition)	4	—	—	0.6	—	—	μs
t _{BUF}	Bus free time between STOP and START	4.7	—	—	1.3	—	—	μs
t _{CO,DAT}	SCL LOW to DATAOUT valid	—	—	3.4	—	—	0.9	μs

User SPI Specifications

Parameter Symbol	Parameter Description	Min	Typ	Max	Units
f _{MAX}	Maximum SCK clock frequency	—	—	45	MHz
t _{HI}	HIGH period of SCK clock	9	—	—	ns
t _{LO}	LOW period of SCK clock	9	—	—	ns
t _{SUmaster}	Setup time (master mode)	2	—	—	ns
t _{HOLDmaster}	Hold time (master mode)	5	—	—	ns
t _{SUslave}	Setup time (slave mode)	2	—	—	ns
t _{HOLDslave}	Hold time (slave mode)	5	—	—	ns
t _{SCK2OUT}	SCK to out (slave mode)	—	—	13.5	ns

sysIO Recommended Operating Conditions

Standard	V _{CCIO} (V)		
	Min.	Typ.	Max.
LVC MOS 3.3	3.14	3.3	3.46
LVC MOS 2.5	2.37	2.5	2.62
LVC MOS 1.8	1.71	1.8	1.89

sysIO Single-Ended DC Electrical Characteristics

Input/ Output Standard	V _{IL}		V _{IH} ¹		V _{OL} Max. (V)	V _{OH} Min. (V)	I _{OL} Max. (mA)	I _{OH} Max. (mA)
	Min. (V)	Max. (V)	Min. (V)	Max. (V)				
LVC MOS 3.3	−0.3	0.8	2.0	V _{CCIO} + 0.2V	0.4	V _{CCIO} − 0.4	8	−8
					0.2	V _{CCIO} − 0.2	0.1	−0.1
LVC MOS 2.5	−0.3	0.7	1.7	V _{CCIO} + 0.2V	0.4	V _{CCIO} − 0.4	6	−6
					0.2	V _{CCIO} − 0.2	0.1	−0.1
LVC MOS 1.8	−0.3	0.35V _{CCIO}	0.65V _{CCIO}	V _{CCIO} + 0.2V	0.4	V _{CCIO} − 0.4	4	−4
					0.2	V _{CCIO} − 0.2	0.1	−0.1

1. Some products are clamped to a diode when V_{IN} is larger than V_{CCIO}.

Typical Building Block Function Performance^{1, 2}

Pin-to-Pin Performance (LVC MOS25)

Function	Timing	Units
Basic Functions		
16-bit decoder	16.5	ns
4:1 MUX	18.0	ns
16:1 MUX	19.5	ns

Register-to-Register Performance

Function	Timing	Units
Basic Functions		
16:1 MUX	110	MHz
16-bit adder	100	MHz
16-bit counter	100	MHz
64-bit counter	40	MHz
Embedded Memory Functions		
256x16 Pseudo-Dual Port RAM	150	MHz

1. The above timing numbers are generated using the iCECube2 design tool. Exact performance may vary with device and tool version. The tool uses internal parameters that have been characterized but are not tested on every device.

2. Using a V_{CC} of 1.14 V at Junction Temp 85 °C.

Derating Logic Timing

Logic timing provided in the following sections of the data sheet and the Lattice design tools are worst case numbers in the operating range. Actual delays may be much faster. Lattice design tools can provide logic timing numbers at a particular temperature and voltage.

Maximum sysIO Buffer Performance¹

I/O Standard	Max. Speed	Units
Inputs		
LVC MOS33	250	MHz
LVC MOS25	250	MHz
LVC MOS18	250	MHz
Outputs		
LVC MOS33	250	MHz
LVC MOS25	250	MHz
LVC MOS18	155	MHz

1. Measured with a toggling pattern.

iCE40LM Family Timing Adders

Over Recommended Commercial Operating Conditions^{1, 2, 3}

Buffer Type	Description	Timing (Typ.)	Units
Input Adjusters			
LVC MOS33	LVC MOS, $V_{CCIO} = 3.3\text{ V}$	0.18	nS
LVC MOS25	LVC MOS, $V_{CCIO} = 2.5\text{ V}$	0.00	nS
LVC MOS18	LVC MOS, $V_{CCIO} = 1.8\text{ V}$	0.19	nS
Output Adjusters			
LVC MOS33	LVC MOS, $V_{CCIO} = 3.3\text{ V}$	-0.12	nS
LVC MOS25	LVC MOS, $V_{CCIO} = 2.5\text{ V}$	0.00	nS
LVC MOS18	LVC MOS, $V_{CCIO} = 1.8\text{ V}$	1.32	nS

1. Timing adders are relative to LVC MOS25 and characterized but not tested on every device.

2. LVC MOS timing measured with the load specified in Switching Test Condition table.

3. Commercial timing numbers are shown.

iCE40LM External Switching Characteristics

Over Recommended Commercial Operating Conditions

Parameter	Description	Device			Units
Clocks					
Global Clocks					
$f_{\text{MAX_GBUF}}$	Frequency for Global Buffer Clock network	All devices		185	MHz
$t_{\text{W_GBUF}}$	Clock Pulse Width for Global Buffer	All devices	2	—	ns
$t_{\text{SKEW_GBUF}}$	Global Buffer Clock Skew Within a Device	All devices	—	650	ps
Pin-LUT-Pin Propagation Delay					
t_{PD}	Best case propagation delay through one LUT logic	All devices	—	9.1	ns
General I/O Pin Parameters (Using Global Buffer Clock without PLL)¹					
$t_{\text{SKEW_IO}}$	Data bus skew across a bank of IOs	All devices	—	450	ps
t_{CO}	Clock to Output - PIO Output Register	All devices	—	11.5	ns
t_{SU}	Clock to Data Setup - PIO Input Register	All devices	−0.23	—	ns
t_{H}	Clock to Data Hold - PIO Input Register	All devices	5.55	—	ns
1. 25-pin WLCSP package does not support PLL.					

sysCLOCK PLL Timing – Preliminary

Over Recommended Operating Conditions

Parameter	Descriptions	Conditions	Min.	Max.	Units
f_{IN}	Input Clock Frequency (REFERENCECLK, EXTFEEDBACK)		10	133	MHz
f_{OUT}	Output Clock Frequency (PLLOUT)		16	275	MHz
f_{VCO}	PLL VCO Frequency		533	1066	MHz
f_{PFD}	Phase Detector Input Frequency		10	133	MHz
AC Characteristics					
t_{DT}	Output Clock Duty Cycle		40	60	%
t_{PH}	Output Phase Accuracy		—	+/-12	deg
$t_{OPJIT}^{1, 5, 6}$	Output Clock Period Jitter	$f_{OUT} \leq 100$ MHz	—	450	ps p-p
		$f_{OUT} > 100$ MHz	—	0.5	UIPP
	Output Clock Cycle-to-cycle Jitter	$f_{OUT} \leq 100$ MHz	—	750	ps p-p
		$f_{OUT} > 100$ MHz	—	0.10	UIPP
	Output Clock Phase Jitter	$f_{PFD} \leq 25$ MHz	—	275	ps p-p
		$f_{PFD} > 25$ MHz	—	0.05	UIPP
t_W	Output Clock Pulse Width	At 90% or 10%	1.33	—	ns
$t_{LOCK}^{2,3}$	PLL Lock-in Time		—	50	us
t_{UNLOCK}	PLL Unlock Time		—	50	ns
t_{IPJIT}^4	Input Clock Period Jitter	$f_{PFD} \geq 20$ MHz	—	1000	ps p-p
		$f_{PFD} < 20$ MHz	—	0.02	UIPP
t_{FDTAP}	Fine Delay adjustment, per Tap		98	226	ps
t_{STABLE}^3	LATCHINPUTVALUE LOW to PLL Stable		—	500	ns
$t_{STABLE_PW}^3$	LATCHINPUTVALUE Pulse Width		100	—	ns
t_{RST}	RESET Pulse Width		10	—	ns
t_{RSTREC}	RESET Recovery Time		10	—	us
$t_{DYNAMIC_WD}$	DYNAMICDELAY Pulse Width		100	—	VCO Cycles

1. Period jitter sample is taken over 10,000 samples of the primary PLL output with a clean reference clock. Cycle-to-cycle jitter is taken over 1000 cycles. Phase jitter is taken over 2000 cycles. All values per JESD65B.
2. Output clock is valid after t_{LOCK} for PLL reset and dynamic delay adjustment.
3. At minimum f_{PFD} . As the f_{PFD} increases the time will decrease to approximately 60% the value listed.
4. Maximum limit to prevent PLL unlock from occurring. Does not imply the PLL will operate within the output specifications listed in this table.
5. The jitter values will increase with loading of the PLD fabric and in the presence of SSO noise.
6. PLL jitter and lock time measurements are based on an external clean clock source. With different clock source, these values may be different.

SPI Master Configuration Time¹

Symbol	Parameter	Conditions	Max.	Units
t_{CONFIG}	POR/CRESET_B to Device I/O Active	All devices - Low Frequency (Default)	95	ms
		All devices - Medium frequency	35	ms
		All devices - High frequency	18	ms

1. Assumes sysMEM Block is initialized to an all zero pattern if they are used.

sysCONFIG Port Timing Specifications

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
All Configuration Modes						
$t_{\text{CRESET_B}}$	Minimum CRESET_B LOW pulse width required to restart configuration, from falling edge to rising edge		200	—	—	ns
$t_{\text{DONE_IO}}$	Number of configuration clock cycles after CDONE goes HIGH before the PIO pins are activated		49	—	—	Cycles
Slave SPI						
$t_{\text{CR_SCK}}$	Minimum time from a rising edge on CRESET_B until the first SPI WRITE operation, first SPI_XCK clock. During this time, the iCE40LM device is clearing its internal configuration memory		1200	—	—	μs
f_{MAX}	CCLK clock frequency	Write	1	—	25	MHz
		Read ¹	—	15	—	MHz
t_{CCLKH}	CCLK clock pulsewidth HIGH		20	—	—	ns
t_{CCLKL}	CCLK clock pulsewidth LOW		20	—	—	ns
t_{STSU}	CCLK setup time		12	—	—	ns
t_{STH}	CCLK hold time		12	—	—	ns
t_{STCO}	CCLK falling edge to valid output		13	—	—	ns
Master SPI						
f_{MCLK}	MCLK clock frequency	Low Frequency (Default)	6.5		13	MHz
		Medium Frequency	19.5		38	MHz
		High Frequency	33		66	MHz
t_{MCLK}	CRESET_B HIGH to first MCLK edge		1200	—	—	μs

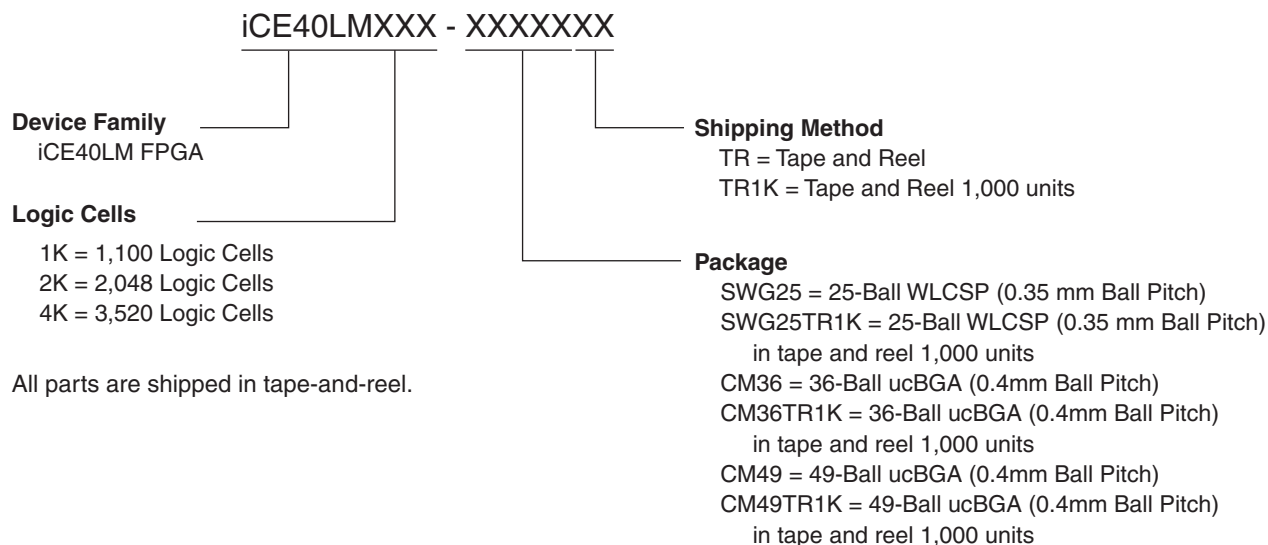
1. Supported with 1.2 V Vcc and at 25 °C.

Signal Descriptions

Signal Name		Function	I/O	Description
Power Supplies				
V _{CC}		Power	—	Core Power Supply
V _{CCIO_0} , V _{CCIO_2}		Power	—	Power for I/Os in Bank 0 and 2.
V _{CC_SPI}		Power	—	Power supply for SPI1 ports. For 25-pin WLCSP and 36-pin ucBGA packages, this signal is connected to V _{CCIO_2} .
V _{CCPLL}		Power	—	Power supply for PLL. For 25-pin WLCSP, this is connected internally to V _{CC} .
GND/GNDPLL		GROUND	—	Ground
Configuration				
CRESETB		Configuration	I	Configuration Reset, active LOW. No internal pull-up resistor. Either actively driven externally or connect an 10 kOhm pull-up to V _{CCIO_2} .
CDONE		Configuration	I/O	Configuration Done. Includes a weak pull-up resistor to V _{CCIO_2} .
Config SPI				
Primary	Secondary			
PIOB_xx[HD]	SPI_SCK	Configuration	I/O	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin outputs the clock to external SPI memory. In Slave SPI mode, this pin inputs the clock from external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function [HD]=High Drive I/O.
PIOB_xx[HD]	SPI_SDO	Configuration	Output	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin outputs the command data to external SPI memory. In Slave SPI mode, this pin connects to the MISO pin of the external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function [HD]=High Drive I/O.
PIOB_xx[HD]	SPI_SI	Configuration	Input	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin receives data from external SPI memory. In Slave SPI mode, this pin connects to the MOSI pin of the external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function [HD]=High Drive I/O.

Signal Name		Function	I/O	Description
PIOB_xx[HD]	SPI_SS_B	Configuration	I/O	This pin is shared with device configuration. During configuration: In Master SPI mode, this pin outputs to the external SPI memory. In Slave SPI mode, this pin inputs from the external processor.
		General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function [HD]=High Drive I/O.
Global Signals				
Primary	Secondary			
PIOT_xx	G0	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
		Global	Input	Global input used for high fanout, or clock/reset net. The G0 pin drives the GBUF0 global buffer.
PIOT_xx	G1	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
		Global	Input	Global input used for high fanout, or clock/reset net. The G1 pin drives the GBUF1 global buffer.
PIOT_xx	G3	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
		Global	Input	Global input used for high fanout, or clock/reset net. The G3 pin drives the GBUF3 global buffer.
PIOT_xx	G4	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
		Global	Input	Global input used for high fanout, or clock/reset net. The G4 pin drives the GBUF4 global buffer.
PIOT_xx	G5	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
		Global	Input	Global input used for high fanout, or clock/reset net. The G5 pin drives the GBUF5 global buffer.
PIOB_xx	G6	General I/O	I/O	In user mode, after configuration, this pin can be programmed as general I/O in user function.
		Global	Input	Global input used for high fanout, or clock/reset net. The G6 pin drives the GBUF6 global buffer.
LED Signals				
PIOT_xx		General I/O	I/O	In user mode, with user's choice, this pin can be programmed as I/O in user function in the top (xx = I/O location).
PIOB_xx		General I/O	I/O	In user mode, with user's choice, this pin can be programmed as I/O in user function in the bottom (xx = I/O location) [HD]=High Drive I/O.

iCE40LM Part Number Description



Ordering Part Numbers

Part Number	LUTs	Supply Voltage	Package	Leads	Temp.
iCE40LM1K-SWG25TR	1100	1.2 V	Halogen-Free caBGA	25	IND
iCE40LM1K-SWG25TR1K	1100	1.2 V	Halogen-Free caBGA	25	IND
iCE40LM1K-CM36TR	1100	1.2 V	Halogen-Free ucBGA	36	IND
iCE40LM1K-CM36TR1K	1100	1.2 V	Halogen-Free ucBGA	36	IND
iCE40LM1K-CM49TR	1100	1.2 V	Halogen-Free ucBGA	49	IND
iCE40LM1K-CM49TR1K	1100	1.2 V	Halogen-Free ucBGA	49	IND
iCE40LM2K-SWG25TR	2048	1.2 V	Halogen-Free caBGA	25	IND
iCE40LM2K-SWG25TR1K	2048	1.2 V	Halogen-Free caBGA	25	IND
iCE40LM2K-CM36TR	2048	1.2 V	Halogen-Free ucBGA	36	IND
iCE40LM2K-CM36TR1K	2048	1.2 V	Halogen-Free ucBGA	36	IND
iCE40LM2K-CM49TR	2048	1.2 V	Halogen-Free ucBGA	49	IND
iCE40LM2K-CM49TR1K	2048	1.2 V	Halogen-Free ucBGA	49	IND
iCE40LM4K-SWG25TR	3520	1.2 V	Halogen-Free caBGA	25	IND
iCE40LM4K-SWG25TR1K	3520	1.2 V	Halogen-Free caBGA	25	IND
iCE40LM4K-CM36TR	3520	1.2 V	Halogen-Free ucBGA	36	IND
iCE40LM4K-CM36TR1K	3520	1.2 V	Halogen-Free ucBGA	36	IND
iCE40LM4K-CM49TR	3520	1.2 V	Halogen-Free ucBGA	49	IND
iCE40LM4K-CM49TR1K	3520	1.2 V	Halogen-Free ucBGA	49	IND

For Further Information

A variety of technical notes for the iCE40 family are available on the Lattice web site.

- TN1248, [iCE40 Programming and Configuration](#)
- TN1274, [iCE40 I2C and SPI Hardened IP Usage Guide](#)
- TN1275, [iCE40LM On-Chip Strobe Generator Usage Guide](#)
- TN1276, [Advanced iCE40 I2C and SPI Hardened IP Usage Guide](#)
- TN1250, [Memory Usage Guide for iCE40 Devices](#)
- TN1251, [iCE40 sysCLOCK PLL Design and Usage Guide](#)
- iCE40LM Pinout Files
- iCE40LM Pin Migration Files
- [Thermal Management](#) document
- [Lattice design tools](#)
- [Schematic Symbols](#)



iCE40LM Family Data Sheet

Revision History

March 2016

Data Sheet DS1045

Date	Version	Section	Change Summary
March 2016	1.6	Architecture	Updated Typical I/O Behavior During Power-up section. Indicated 36-pin ucBGA in package in description.
		DC and Switching Characteristics	Updated Recommended Operating Conditions ¹ section. Revised footnote 5.
		Pinout Information	Updated Signal Descriptions section. General update of signal names and descriptions.
March 2015	1.5	DC and Switching Characteristics	Updated sysIO Single-Ended DC Electrical Characteristics section. Changed LVCMOS 3.3 and LVCMOS 2.5 V _{OH} Min. (V) from 0.5 to 0.4.
August 2014	1.4	DC and Switching Characteristics	Updated the Recommended Operating Conditions section. Added V _{CC} and V _{CCPLL} information to footnote 1.
			Updated Power Up Sequence section. Revised and added information on required power up sequence.
March 2014	1.3	Ordering Information	Updated Ordering Part Numbers section. Changed packages from csBGA to ucBGA.
	01.2	Architecture	Updated Typical I/O Behavior During Power-up section. Added V _{CCIO_0} to the first statement.
			Updated Power On Reset section. Added V _{CCIO_0} to the first statement.
		Ordering Information	Updated iCE40LM Part Number Description section. Added shipping method and packages.
			Added part numbers in Ordering Part Numbers section.
January 2014	01.1	All	Updated document status from Advance.
		Introduction	Updated device features.
		DC and Switching Characteristics	Updated the following tables: — sysCLOCK PLL Timing – Preliminary — Supply Current — sysCONFIG Port Timing Specifications.
		Pinout Information	Updated SPI and Config SPI Ports information in Signal Descriptions table.
October 2013	01.0	All	General updates for product launch.
		Pinout Information	Updated ball map to 25-pin WLCSP.
September 2013	00.2 EAP	All	General updates to all sections.
August 2013	00.1 EAP	All	Initial release.