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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

| | |
|----------------------------|---|
| Product Status | Not For New Designs |
| Core Processor | S08 |
| Core Size | 8-Bit |
| Speed | 20MHz |
| Connectivity | I ² C, LINbus, SPI, UART/USART |
| Peripherals | LVD, POR, PWM, WDT |
| Number of I/O | 14 |
| Program Memory Size | 8KB (8K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | 256 x 8 |
| RAM Size | 2K x 8 |
| Voltage - Supply (Vcc/Vdd) | 2.7V ~ 5.5V |
| Data Converters | A/D 12x12b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 105°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 16-TSSOP (0.173", 4.40mm Width) |
| Supplier Device Package | 16-TSSOP |
| Purchase URL | https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08pa8vtg |

- Input/Output
 - Up to 37 GPIOs including one output-only pin
 - One 8-bit keyboard interrupt module (KBI)
 - Two true open-drain output pins
 - Four, ultra-high current sink pins supporting 20 mA source/sink current
- Package options
 - 44-pin LQFP
 - 32-pin LQFP
 - 20-pin SOIC; 20-pin TSSOP
 - 16-pin TSSOP

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1 Ordering parts

1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to freescale.com and perform a part number search for the following device numbers: PA16 and PA8.

2 Part identification

2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

2.2 Format

Part numbers for this device have the following format:

MC 9 S08 PA AA (V) B CC

2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

| Field | Description | Values |
|-------|------------------------------|--|
| MC | Qualification status | <ul style="list-style-type: none"> • MC = fully qualified, general market flow |
| 9 | Memory | <ul style="list-style-type: none"> • 9 = flash based |
| S08 | Core | <ul style="list-style-type: none"> • S08 = 8-bit CPU |
| PA | Device family | <ul style="list-style-type: none"> • PA |
| AA | Approximate flash size in KB | <ul style="list-style-type: none"> • 16 = 16 KB • 8 = 8 KB |
| (V) | Mask set version | <ul style="list-style-type: none"> • (blank) = Any version • A = Rev. 2 or later version, this is recommended for new design |

Table continues on the next page...

4 Ratings

4.1 Thermal handling ratings

| Symbol | Description | Min. | Max. | Unit | Notes |
|-----------|-------------------------------|------|------|------|-------------------|
| T_{STG} | Storage temperature | -55 | 150 | °C | 1 |
| T_{SDR} | Solder temperature, lead-free | — | 260 | °C | 2 |

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

4.2 Moisture handling ratings

| Symbol | Description | Min. | Max. | Unit | Notes |
|--------|----------------------------|------|------|------|-------------------|
| MSL | Moisture sensitivity level | — | 3 | — | 1 |

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

4.3 ESD handling ratings

| Symbol | Description | Min. | Max. | Unit | Notes |
|-----------|---|-------|-------|------|-------------------|
| V_{HBM} | Electrostatic discharge voltage, human body model | -6000 | +6000 | V | 1 |
| V_{CDM} | Electrostatic discharge voltage, charged-device model | -500 | +500 | V | 2 |
| I_{LAT} | Latch-up current at ambient temperature of 105°C | -100 | +100 | mA | |

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.

4.4 Voltage and current operating ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in below table may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this document.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either V_{SS} or V_{DD}) or the programmable pullup resistor associated with the pin is enabled.

| Symbol | Description | Min. | Max. | Unit |
|-----------|---|----------------|----------------|------|
| V_{DD} | Supply voltage | -0.3 | 6.0 | V |
| I_{DD} | Maximum current into V_{DD} | — | 120 | mA |
| V_{DIO} | Digital input voltage (except \overline{RESET} , EXTAL, XTAL, or true open drain pin PTA2 and PTA3) | -0.3 | $V_{DD} + 0.3$ | V |
| | Digital input voltage (true open drain pin PTA2 and PTA3) | -0.3 | 6 | V |
| V_{AIO} | Analog ¹ , \overline{RESET} , EXTAL, and XTAL input voltage | -0.3 | $V_{DD} + 0.3$ | V |
| I_D | Instantaneous maximum current single pin limit (applies to all port pins) | -25 | 25 | mA |
| V_{DDA} | Analog supply voltage | $V_{DD} - 0.3$ | $V_{DD} + 0.3$ | V |

1. All digital I/O pins, except open-drain pin PTA2 and PTA3, are internally clamped to V_{SS} and V_{DD} . PTA2 and PTA3 is only clamped to V_{SS} .

5 General

5.1 Nonswitching electrical specifications

5.1.1 DC characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 2. DC characteristics

| Symbol | C | Descriptions | | Min | Typical ¹ | Max | Unit |
|----------|---|---|---------------------------------------|-----------------------------------|----------------------|-----|------|
| — | — | Operating voltage | | — | — | 5.5 | V |
| V_{OH} | C | Output high voltage | All I/O pins, standard-drive strength | 5 V, $I_{load} = -5 \text{ mA}$ | $V_{DD} - 0.8$ | — | V |
| | C | | | 3 V, $I_{load} = -2.5 \text{ mA}$ | $V_{DD} - 0.8$ | — | V |
| | C | High current drive pins, high-drive strength ² | | 5 V, $I_{load} = -20 \text{ mA}$ | $V_{DD} - 0.8$ | — | V |
| | C | | | 3 V, $I_{load} = -10 \text{ mA}$ | $V_{DD} - 0.8$ | — | V |

Table continues on the next page...

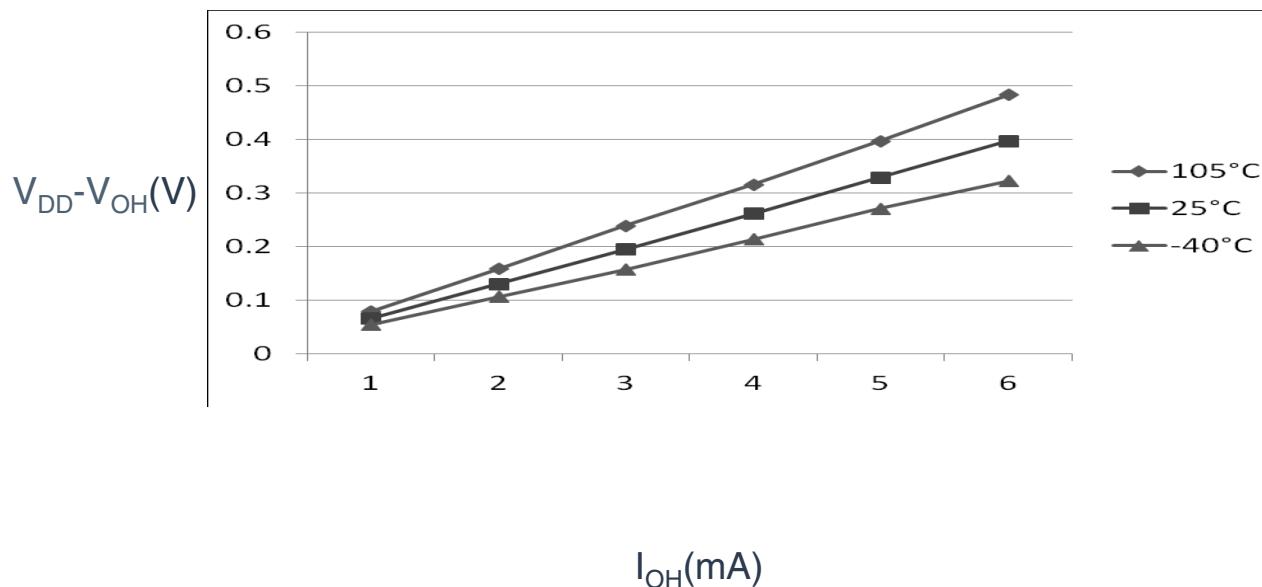


Figure 1. Typical I_{OH} Vs. $V_{DD} - V_{OH}$ (standard drive strength) ($V_{DD} = 5$ V)

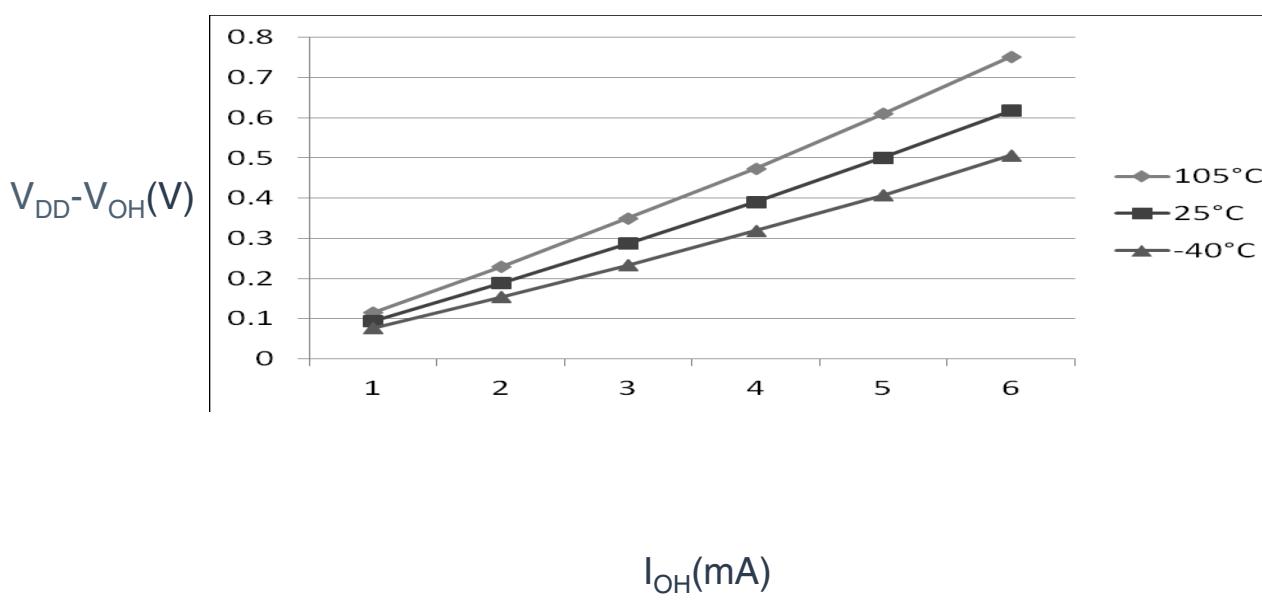


Figure 2. Typical I_{OH} Vs. $V_{DD} - V_{OH}$ (standard drive strength) ($V_{DD} = 3$ V)

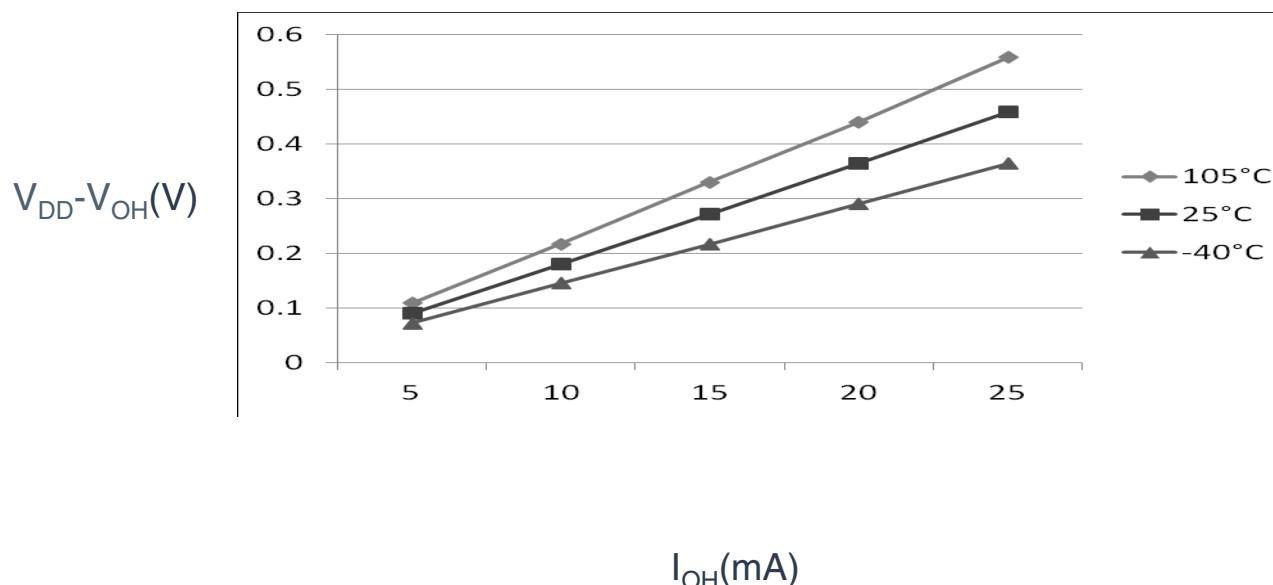


Figure 3. Typical I_{OH} Vs. $V_{DD} - V_{OH}$ (high drive strength) ($V_{DD} = 5$ V)

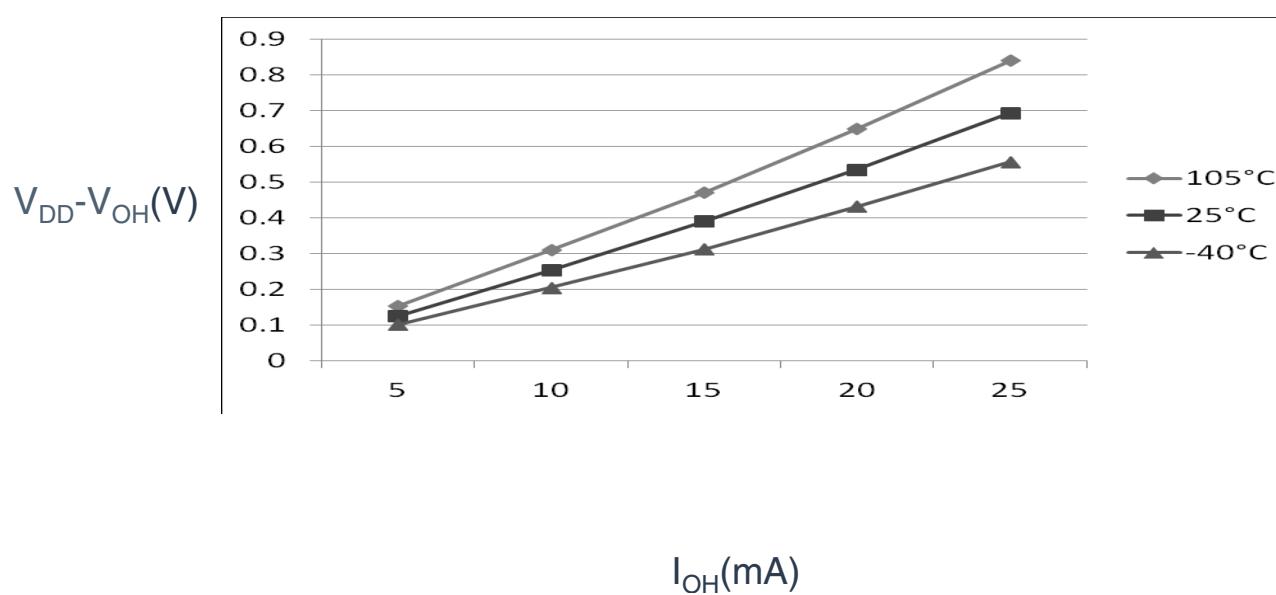


Figure 4. Typical I_{OH} Vs. $V_{DD} - V_{OH}$ (high drive strength) ($V_{DD} = 3$ V)

5.1.2 Supply current characteristics

This section includes information about power supply current in various operating modes.

Table 4. Supply current characteristics

| Num | C | Parameter | Symbol | Bus Freq | V _{DD} (V) | Typical ¹ | Max | Unit | Temp |
|-----|---|--|-------------------|----------|---------------------|----------------------|------|------|---------------|
| 1 | C | Run supply current FEI mode, all modules on; run from flash | RI _{DD} | 20 MHz | 5 | 7.60 | — | mA | -40 to 105 °C |
| | C | | | 10 MHz | | 4.65 | — | | |
| | C | | | 1 MHz | | 1.90 | — | | |
| | C | | | 20 MHz | 3 | 7.05 | — | | |
| | C | | | 10 MHz | | 4.40 | — | | |
| | C | | | 1 MHz | | 1.85 | — | | |
| 2 | C | Run supply current FEI mode, all modules off & gated; run from flash | RI _{DD} | 20 MHz | 5 | 5.88 | — | mA | -40 to 105 °C |
| | C | | | 10 MHz | | 3.70 | — | | |
| | C | | | 1 MHz | | 1.85 | — | | |
| | C | | | 20 MHz | 3 | 5.35 | — | | |
| | C | | | 10 MHz | | 3.42 | — | | |
| | C | | | 1 MHz | | 1.80 | — | | |
| 3 | P | Run supply current FBE mode, all modules on; run from RAM | RI _{DD} | 20 MHz | 5 | 10.9 | 14.0 | mA | -40 to 105 °C |
| | C | | | 10 MHz | | 6.10 | — | | |
| | C | | | 1 MHz | | 1.69 | — | | |
| | P | | | 20 MHz | 3 | 8.18 | — | | |
| | C | | | 10 MHz | | 5.14 | — | | |
| | C | | | 1 MHz | | 1.44 | — | | |
| 4 | P | Run supply current FBE mode, all modules off & gated; run from RAM | RI _{DD} | 20 MHz | 5 | 8.50 | 13.0 | mA | -40 to 105 °C |
| | C | | | 10 MHz | | 5.07 | — | | |
| | C | | | 1 MHz | | 1.59 | — | | |
| | P | | | 20 MHz | 3 | 6.11 | — | | |
| | C | | | 10 MHz | | 4.10 | — | | |
| | C | | | 1 MHz | | 1.34 | — | | |
| 5 | P | Wait mode current FEI mode, all modules on | WI _{DD} | 20 MHz | 5 | 5.95 | — | mA | -40 to 105 °C |
| | C | | | 10 MHz | | 3.50 | — | | |
| | C | | | 1 MHz | | 1.24 | — | | |
| | P | | | 20 MHz | 3 | 5.45 | — | | |
| | C | | | 10 MHz | | 3.25 | — | | |
| | C | | | 1 MHz | | 1.20 | — | | |
| 6 | C | Stop3 mode supply current no clocks active (except 1kHz LPO clock) ^{2, 3} | S3I _{DD} | — | 5 | 4.6 | — | µA | -40 to 105 °C |
| | C | | | — | 3 | 4.5 | — | | -40 to 105 °C |
| 7 | C | ADC adder to stop3 | — | — | 5 | 40 | — | µA | -40 to 105 °C |

Table continues on the next page...

5.2.3 FTM module timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 8. FTM input timing

| No. | C | Function | Symbol | Min | Max | Unit |
|-----|---|---------------------------|------------|-----|-------------|-----------|
| 1 | D | External clock frequency | f_{TCLK} | 0 | $f_{Bus}/4$ | Hz |
| 2 | D | External clock period | t_{TCLK} | 4 | — | t_{cyc} |
| 3 | D | External clock high time | t_{clkh} | 1.5 | — | t_{cyc} |
| 4 | D | External clock low time | t_{clkl} | 1.5 | — | t_{cyc} |
| 5 | D | Input capture pulse width | t_{ICPW} | 1.5 | — | t_{cyc} |

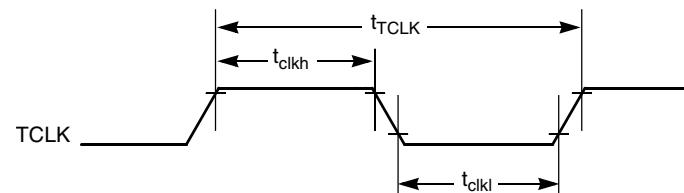


Figure 13. Timer external clock

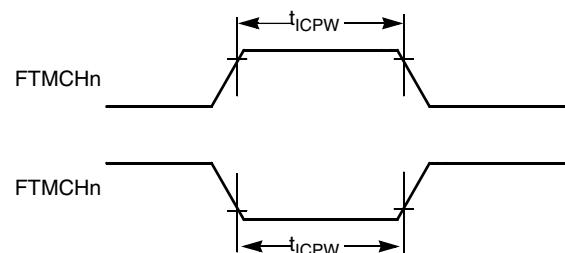


Figure 14. Timer input capture pulse

5.3 Thermal specifications

5.3.1 Thermal characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

Table 9. Thermal characteristics

| Rating | Symbol | Value | Unit |
|--|-----------------|---------------------------|------|
| Operating temperature range (packaged) | T_A^1 | T_L to T_H -40 to 105 | °C |
| Junction temperature range | T_J | -40 to 150 | °C |
| Thermal resistance single-layer board | | | |
| 44-pin LQFP | $R_{\theta JA}$ | 76 | °C/W |
| 32-pin LQFP | $R_{\theta JA}$ | 88 | °C/W |
| 20-pin SOIC | $R_{\theta JA}$ | 82 | °C/W |
| 20-pin TSSOP | $R_{\theta JA}$ | 116 | °C/W |
| 16-pin TSSOP | $R_{\theta JA}$ | 130 | °C/W |
| Thermal resistance four-layer board | | | |
| 44-pin LQFP | $R_{\theta JA}$ | 54 | °C/W |
| 32-pin LQFP | $R_{\theta JA}$ | 59 | °C/W |
| 20-pin SOIC | $R_{\theta JA}$ | 54 | °C/W |
| 20-pin TSSOP | $R_{\theta JA}$ | 76 | °C/W |
| 16-pin TSSOP | $R_{\theta JA}$ | 87 | °C/W |

1. Maximum T_A can be exceeded only if the user ensures that T_J does not exceed the maximum. The simplest method to determine T_J is: $T_J = T_A + R_{\theta JA} \times \text{chip power dissipation}$.

6 Peripheral operating requirements and behaviors

6.1 External oscillator (XOSC) and ICS characteristics

Table 10. XOSC and ICS specifications (temperature range = -40 to 105 °C ambient)

| Num | C | Characteristic | | Symbol | Min | Typical ¹ | Max | Unit |
|-----|---|--|---|---------------------|-----------------------|----------------------|---------|-------------|
| 1 | C | Oscillator crystal or resonator | Low range (RANGE = 0) | f_{lo} | 31.25 | 32.768 | 39.0625 | kHz |
| | C | | High range (RANGE = 1) FEE or FBE mode ² | f_{hi} | 4 | — | 20 | MHz |
| | C | | High range (RANGE = 1), high gain (HGO = 1), FBELP mode | f_{hi} | 4 | — | 20 | MHz |
| | C | | High range (RANGE = 1), low power (HGO = 0), FBELP mode | f_{hi} | 4 | — | 20 | MHz |
| 2 | D | Load capacitors | | C1, C2 | See Note ³ | | | |
| 3 | D | Feedback resistor | Low Frequency, Low-Power Mode ⁴ | R_F | — | — | — | MΩ |
| | | | Low Frequency, High-Gain Mode | | — | 10 | — | MΩ |
| | | | High Frequency, Low-Power Mode | | — | 1 | — | MΩ |
| | | | High Frequency, High-Gain Mode | | — | 1 | — | MΩ |
| 4 | D | Series resistor - Low Frequency | Low-Power Mode ⁴ | R_S | — | — | — | kΩ |
| | | | High-Gain Mode | | — | 200 | — | kΩ |
| 5 | D | Series resistor - High Frequency | Low-Power Mode ⁴ | R_S | — | — | — | kΩ |
| | D | Series resistor - High Frequency, High-Gain Mode | 4 MHz | | — | 0 | — | kΩ |
| | D | | 8 MHz | | — | 0 | — | kΩ |
| | D | | 16 MHz | | — | 0 | — | kΩ |
| 6 | C | Crystal start-up time Low range = 32.768 kHz crystal; High range = 20 MHz crystal ^{5, 6} | Low range, low power | t_{CSTL} | — | 1000 | — | ms |
| | C | | Low range, high power | | — | 800 | — | ms |
| | C | | High range, low power | t_{CSTH} | — | 3 | — | ms |
| | C | | High range, high power | | — | 1.5 | — | ms |
| 7 | T | Internal reference start-up time | | t_{IRST} | — | 20 | 50 | μs |
| 8 | D | Square wave input clock frequency | FEE or FBE mode ² | f_{extal} | 0.03125 | — | 5 | MHz |
| | D | | FBELP mode | | 0 | — | 20 | MHz |
| 9 | P | Average internal reference frequency - trimmed | | f_{int_t} | — | 31.25 | — | kHz |
| 10 | P | DCO output frequency range - trimmed | | f_{dco_t} | 16 | — | 20 | MHz |
| 11 | P | Total deviation of DCO output from trimmed frequency ⁵ | Over full voltage and temperature range | Δf_{dco_t} | — | — | ±2.0 | % f_{dco} |
| | C | | Over fixed voltage and temperature range of 0 to 70 °C | | — | — | ±1.0 | |
| 12 | C | FLL acquisition time ^{5, 7} | | $t_{Acquire}$ | — | — | 2 | ms |

Table continues on the next page...

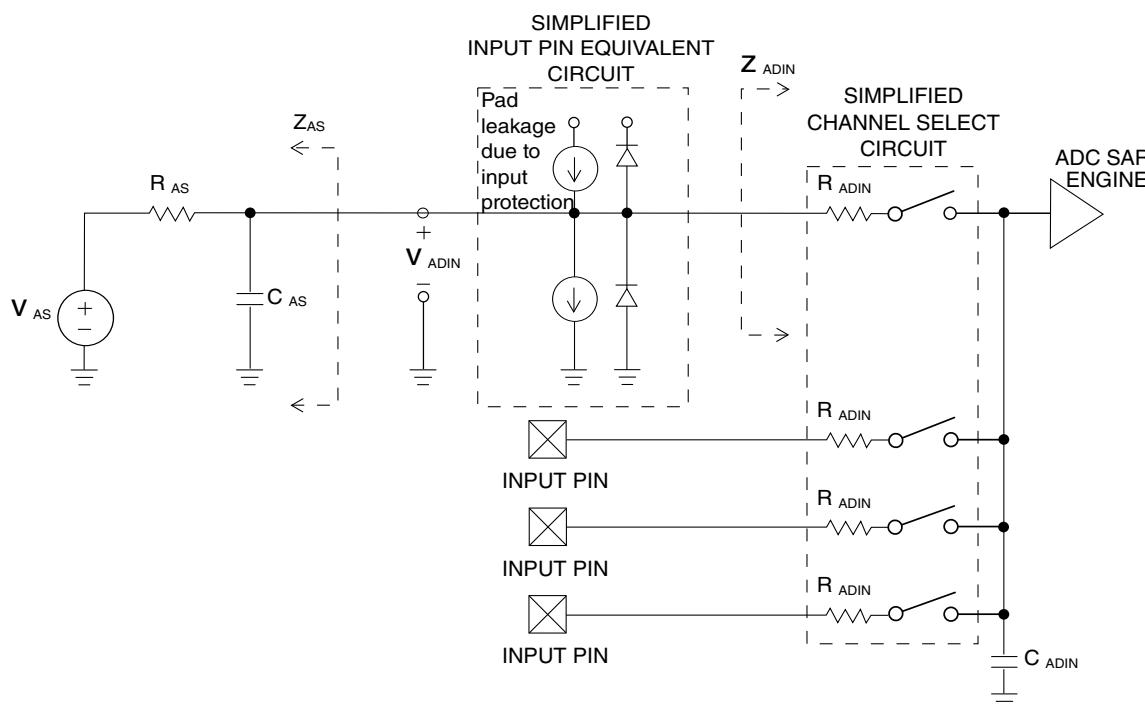


Figure 16. ADC input impedance equivalency diagram

Table 13. 12-bit ADC Characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$)

| Characteristic | Conditions | C | Symb | Min | Typ ¹ | Max | Unit |
|---|-------------------------|---|--------------------|-----|------------------|-----|------|
| Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1 | | T | I _{DDA} | — | 133 | — | µA |
| Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1 | | T | I _{DDA} | — | 218 | — | µA |
| Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1 | | T | I _{DDA} | — | 327 | — | µA |
| Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1 | | T | I _{DDAD} | — | 582 | 990 | µA |
| Supply current | Stop, reset, module off | T | I _{DDA} | — | 0.011 | 1 | µA |
| ADC asynchronous clock source | High speed (ADLPC = 0) | P | f _{ADACK} | 2 | 3.3 | 5 | MHz |

Table continues on the next page...

6.3.2 Analog comparator (ACMP) electricals

Table 14. Comparator electrical specifications

| C | Characteristic | Symbol | Min | Typical | Max | Unit |
|---|---|--------------|----------------|---------|-----------|---------|
| D | Supply voltage | V_{DDA} | 2.7 | — | 5.5 | V |
| T | Supply current (Operation mode) | I_{DDA} | — | 10 | 20 | μA |
| D | Analog input voltage | V_{AIN} | $V_{SS} - 0.3$ | — | V_{DDA} | V |
| P | Analog input offset voltage | V_{AIO} | — | — | 40 | mV |
| C | Analog comparator hysteresis ($HYST=0$) | V_H | — | 15 | 20 | mV |
| C | Analog comparator hysteresis ($HYST=1$) | V_H | — | 20 | 30 | mV |
| T | Supply current (Off mode) | I_{DDAOFF} | — | 60 | — | nA |
| C | Propagation Delay | t_D | — | 0.4 | 1 | μs |

6.4 Communication interfaces

6.4.1 SPI switching specifications

The serial peripheral interface (SPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The following tables provide timing characteristics for classic SPI timing modes. Refer to the SPI chapter of the chip's reference manual for information about the modified transfer formats used for communicating with slower peripheral devices. All timing is shown with respect to 20% V_{DD} and 70% V_{DD} , unless noted, and 100 pF load on all SPI pins. All timing assumes high drive strength is enabled for SPI output pins.

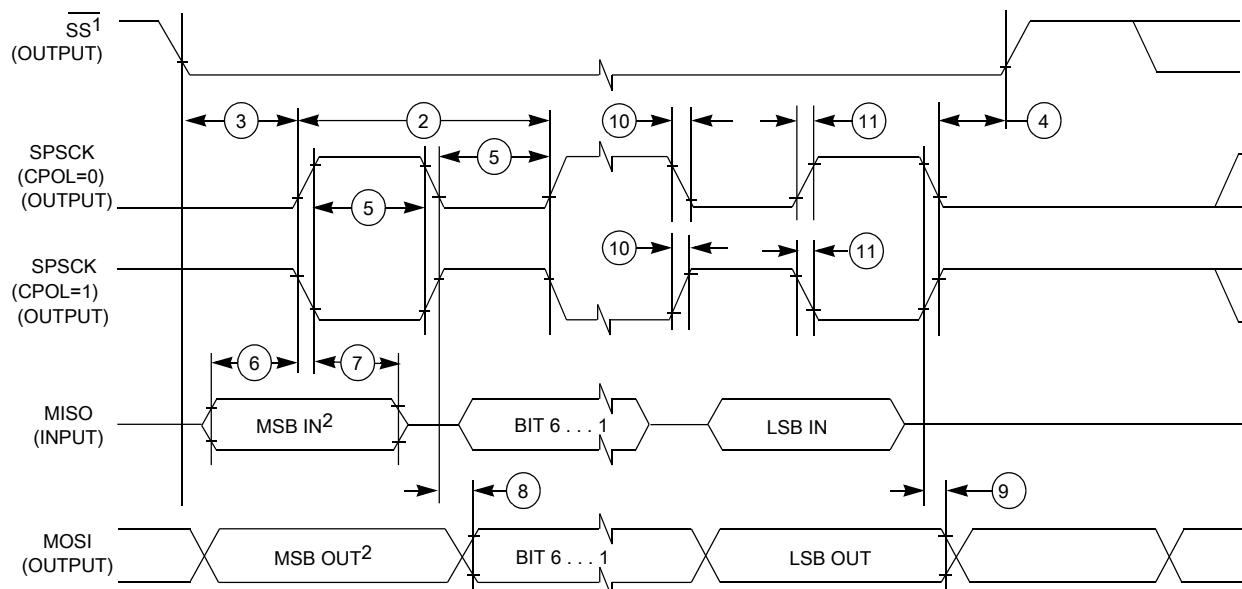
Table 15. SPI master mode timing

| Nu. m. | Symbol | Description | Min. | Max. | Unit | Comment |
|-----------|--------------|--------------------------------|--------------------|-----------------------|-------------|----------------------------|
| 1 | f_{op} | Frequency of operation | $f_{Bus}/2048$ | $f_{Bus}/2$ | Hz | f_{Bus} is the bus clock |
| 2 | t_{SPSCK} | SPSCK period | $2 \times t_{Bus}$ | $2048 \times t_{Bus}$ | ns | $t_{Bus} = 1/f_{Bus}$ |
| 3 | t_{Lead} | Enable lead time | 1/2 | — | t_{SPSCK} | — |
| 4 | t_{Lag} | Enable lag time | 1/2 | — | t_{SPSCK} | — |
| 5 | t_{WSPSCK} | Clock (SPSCK) high or low time | $t_{Bus} - 30$ | $1024 \times t_{Bus}$ | ns | — |
| 6 | t_{SU} | Data setup time (inputs) | 15 | — | ns | — |
| 7 | t_{HI} | Data hold time (inputs) | 0 | — | ns | — |
| 8 | t_v | Data valid (after SPSCK edge) | — | 25 | ns | — |
| 9 | t_{HO} | Data hold time (outputs) | 0 | — | ns | — |
| 10 | t_{RI} | Rise time input | — | $t_{Bus} - 25$ | ns | — |

Table continues on the next page...

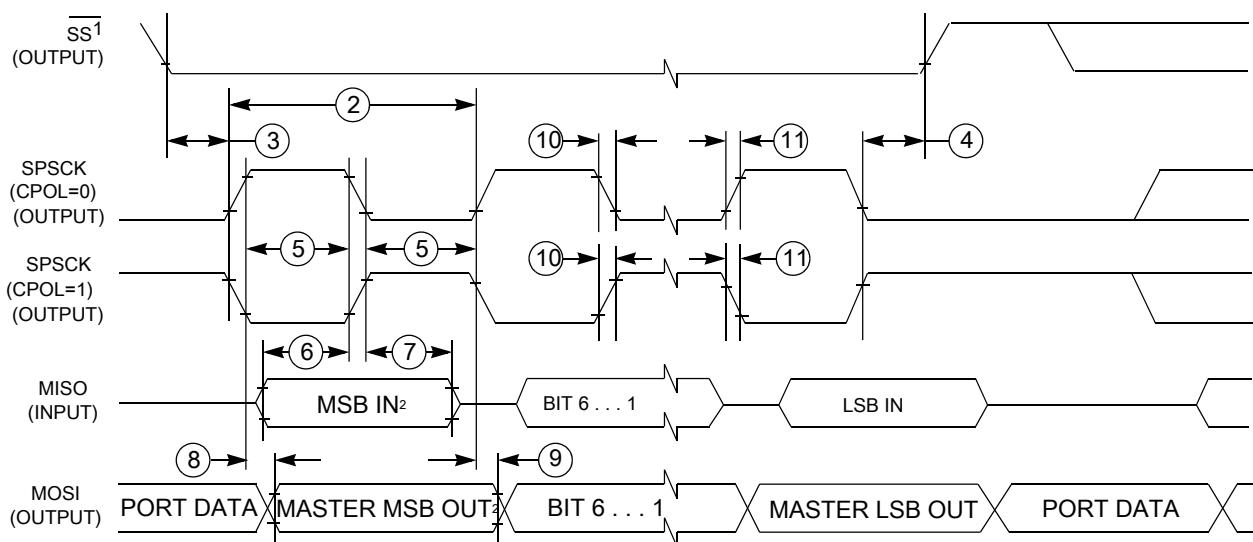
Table 15. SPI master mode timing (continued)

| Nu. m. | Symbol | Description | Min. | Max. | Unit | Comment |
|-----------|----------|------------------|------|------|------|---------|
| | t_{FI} | Fall time input | | | | |
| 11 | t_{RO} | Rise time output | — | 25 | ns | — |
| | t_{FO} | Fall time output | | | | |



1. If configured as an output.

2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 17. SPI master mode timing (CPHA=0)

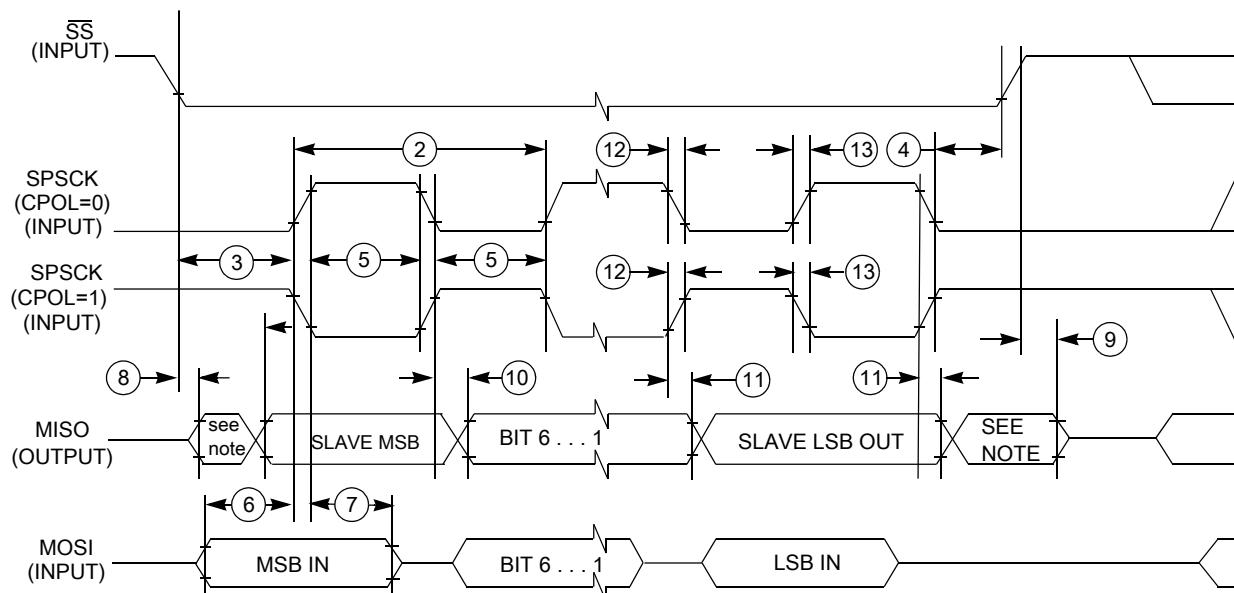
1. If configured as output

2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 18. SPI master mode timing (CPHA=1)

Table 16. SPI slave mode timing

| Nu. m. | Symbol | Description | Min. | Max. | Unit | Comment |
|-----------|--------------|--------------------------------|--------------------|----------------|-----------|---|
| 1 | f_{op} | Frequency of operation | 0 | $f_{Bus}/4$ | Hz | f_{Bus} is the bus clock as defined in . |
| 2 | t_{SPSCK} | SPSCK period | $4 \times t_{Bus}$ | — | ns | $t_{Bus} = 1/f_{Bus}$ |
| 3 | t_{Lead} | Enable lead time | 1 | — | t_{Bus} | — |
| 4 | t_{Lag} | Enable lag time | 1 | — | t_{Bus} | — |
| 5 | t_{WSPSCK} | Clock (SPSCK) high or low time | $t_{Bus} - 30$ | — | ns | — |
| 6 | t_{SU} | Data setup time (inputs) | 15 | — | ns | — |
| 7 | t_{HI} | Data hold time (inputs) | 25 | — | ns | — |
| 8 | t_a | Slave access time | — | t_{Bus} | ns | Time to data active from high-impedance state |
| 9 | t_{dis} | Slave MISO disable time | — | t_{Bus} | ns | Hold time to high-impedance state |
| 10 | t_v | Data valid (after SPSCK edge) | — | 25 | ns | — |
| 11 | t_{HO} | Data hold time (outputs) | 0 | — | ns | — |
| 12 | t_{RI} | Rise time input | — | $t_{Bus} - 25$ | ns | — |
| | t_{FI} | Fall time input | — | — | — | — |
| 13 | t_{RO} | Rise time output | — | 25 | ns | — |
| | t_{FO} | Fall time output | — | — | — | — |

**Figure 19. SPI slave mode timing (CPHA = 0)**

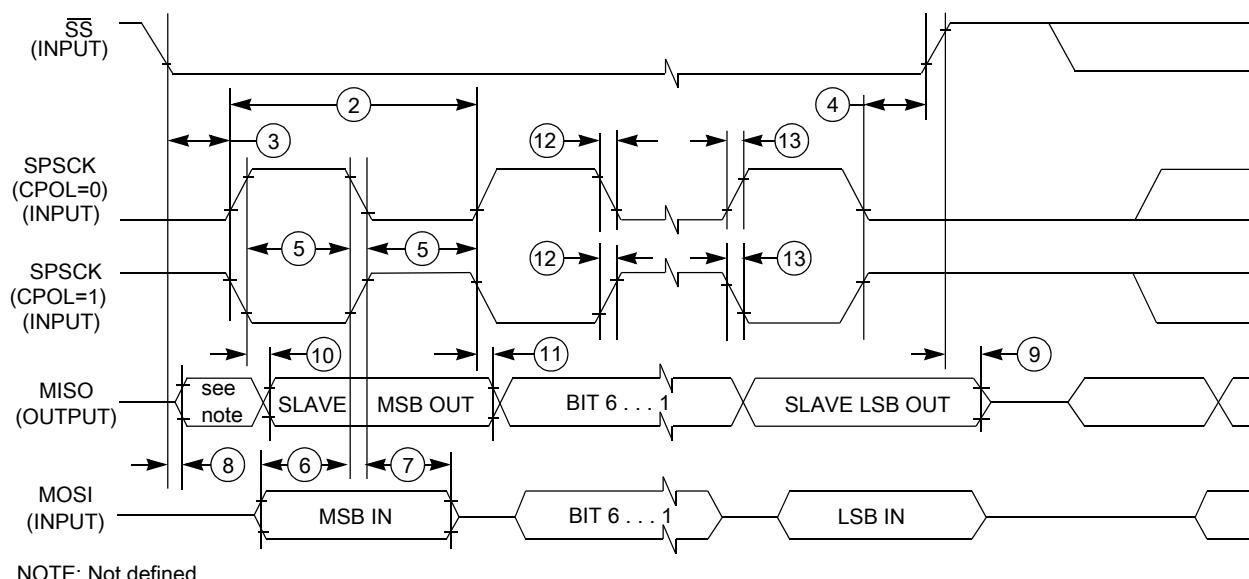


Figure 20. SPI slave mode timing (CPHA=1)

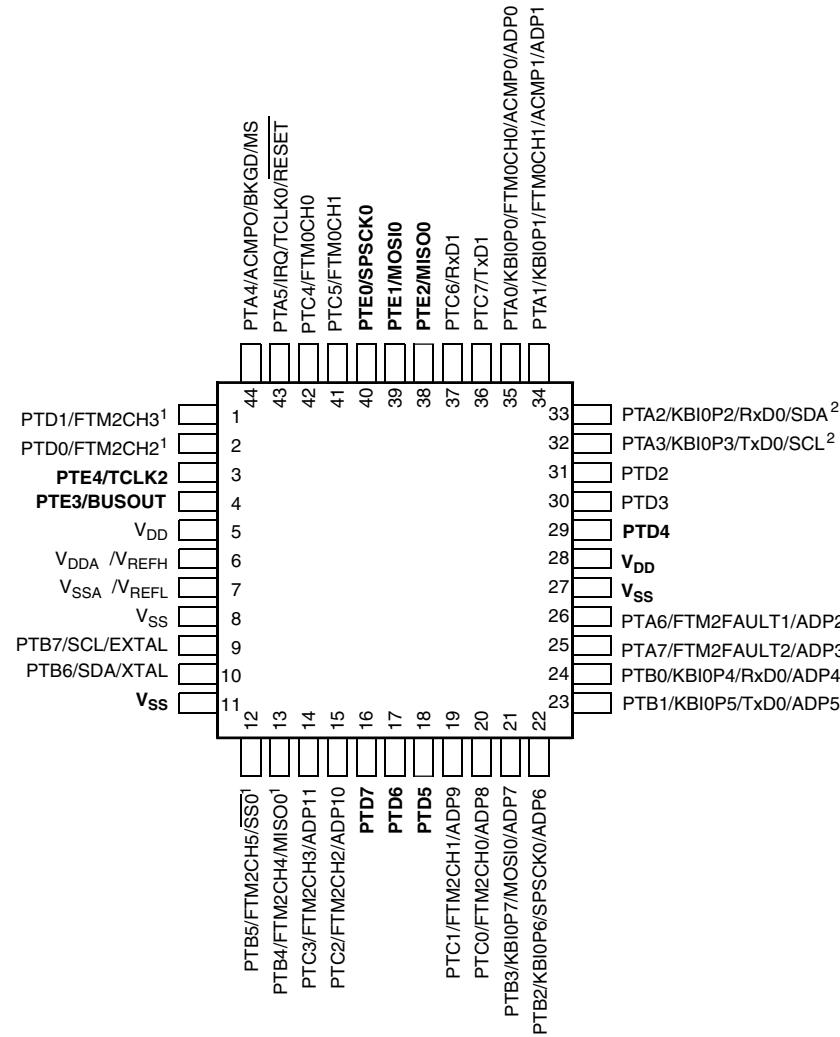
7 Dimensions

7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to freescale.com and perform a keyword search for the drawing's document number:

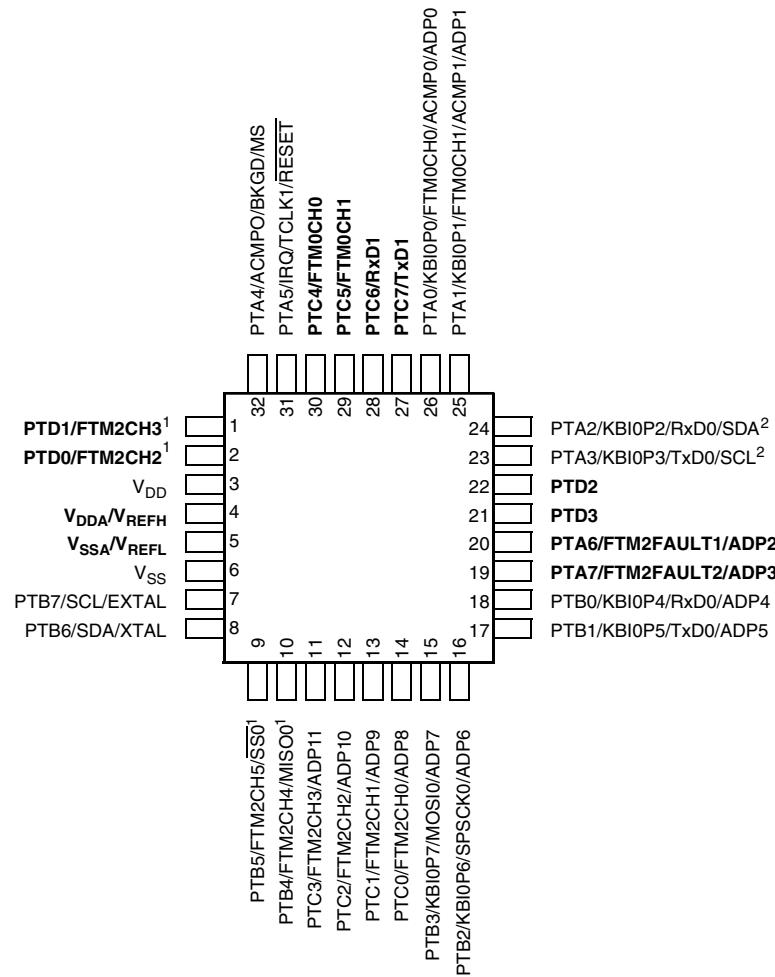
| If you want the drawing for this package | Then use this document number |
|--|-------------------------------|
| 16-pin TSSOP | 98ASH70247A |
| 20-pin SOIC | 98ASB42343B |
| 20-pin TSSOP | 98ASH70169A |
| 32-pin LQFP | 98ASH70029A |
| 44-pin LQFP | 98ASS23225W |



Pins in **bold** are not available on less pin-count packages.

1. High source/sink current pins
2. True open drain pins

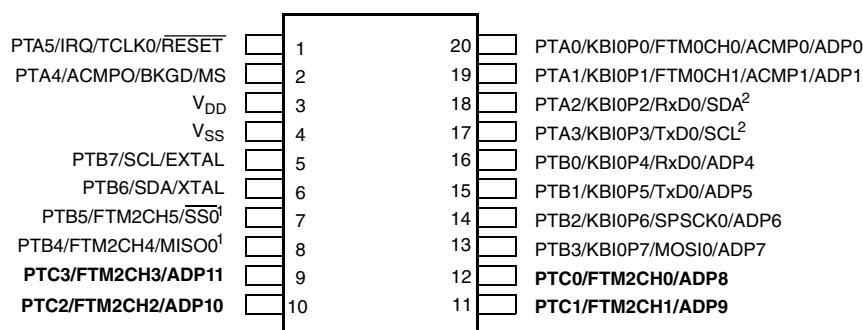
Figure 21. MC9S08PA16 44-pin LQFP package



Pins in **bold** are not available on less pin-count packages.

1. High source/sink current pins
2. True open drain pins

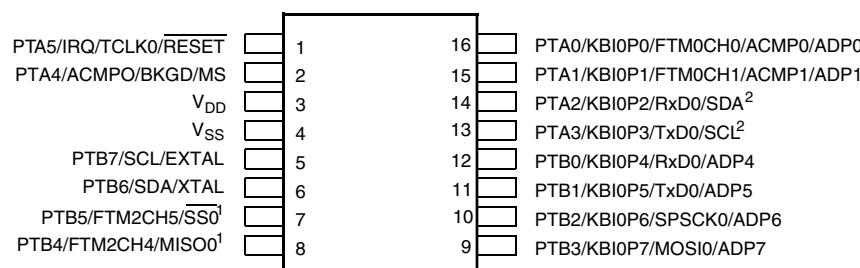
Figure 22. MC9S08PA16 32-pin LQFP package



Pins in **bold** are not available on less pin-count packages.

1. High source/sink current pins
2. True open drain pins

Figure 23. MC9S08PA16 20-pin SOIC and TSSOP package



Pins in **bold** are not available on less pin-count packages.

1. High source/sink current pins

2. True open drain pins

Figure 24. MC9S08PA16 16-pin TSSOP package

9 Revision history

The following table provides a revision history for this document.

Table 18. Revision history

| Rev. No. | Date | Substantial Changes |
|----------|---------|---|
| 1 | 10/2012 | Initial public release |
| 2 | 09/2014 | <ul style="list-style-type: none"> Updated V_{OH} and V_{OL} in DC characteristics Updated footnote on the $S3I_{DD}$ in Supply current characteristics Added EMC radiated emissions operating behaviors Updated the typical of f_{int_t} to 31.25 kHz and updated footnote to $t_{Acquire}$ in External oscillator (XOSC) and ICS characteristics Updated the assumption for all the timing values in SPI switching specifications Updated the rating descriptions for t_{Rise} and t_{Fall} in Control timing Updated the part number format to add new field for new part numbers in Fields |
| 3 | 06/2015 | <ul style="list-style-type: none"> Corrected the Min. of the t_{extrst} in Control timing Updated Thermal characteristics to add footnote to the T_A and removed redundant information. Updated the symbol of θ_{JA} to $R_{\theta JA}$. |

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