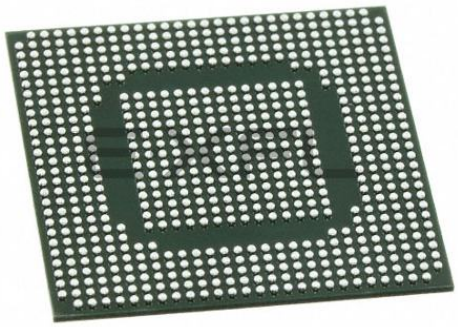

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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details	
Product Status	Active
Architecture	MCU, FPGA
Core Processor	Dual ARM® Cortex®-A9 MPCore™ with CoreSight™
Flash Size	-
RAM Size	64KB
Peripherals	DMA, POR, WDT
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, MMC/SD/SDIO, SPI, UART/USART, USB OTG
Speed	800MHz
Primary Attributes	FPGA - 110K Logic Elements
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	672-FBGA
Supplier Device Package	672-UBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/intel/5csxfc6c6u23i7n

Symbol	Description	Condition	Minimum(2)	Typical	Maximum(2)	Unit
V_{CCPGM}	Configuration pins power supply	3.3 V	3.135	3.3	3.465	V
		3.0 V	2.85	3.0	3.15	V
		2.5 V	2.375	2.5	2.625	V
		1.8 V	1.71	1.8	1.89	V
V_{CCA_FPLL}(5)	PLL analog voltage regulator power supply	—	2.375	2.5	2.625	V
V_{CCBAT}(6)	Battery back-up power supply (For design security volatile key register)	—	1.2	—	3.0	V
V_I	DC input voltage	—	–0.5	—	3.6	V
V_O	Output voltage	—	0	—	V_{CCIO}	V
T_J	Operating junction temperature	Commercial	0	—	85	°C
		Industrial	–40	—	100	°C
		Automotive	–40	—	125	°C
t_{RAMP}(7)	Power supply ramp time	Standard POR	200µs	—	100ms	—
		Fast POR	200µs	—	4ms	—

(2) The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

(5) PLL digital voltage is regulated from V_{CCA_FPLL}.

(6) If you do not use the design security feature in Cyclone V devices, connect V_{CCBAT} to a 1.5-V, 2.5-V, or 3.0-V power supply. Cyclone V power-on reset (POR) circuitry monitors V_{CCBAT}. Cyclone V devices do not exit POR if V_{CCBAT} is not powered up.

(7) This is also applicable to HPS power supply. For HPS power supply, refer to t_{RAMP} specifications for standard POR when HPS_P0RSEL = 0 and t_{RAMP} specifications for fast POR when HPS_P0RSEL = 1.

Transceiver Power Supply Operating Conditions

Table 5. Transceiver Power Supply Operating Conditions for Cyclone V GX, GT, SX, and ST Devices

Symbol	Description	Minimum[8]	Typical	Maximum[8]	Unit
V_{CCH_GXBL}	Transceiver high voltage power (left side)	2.375	2.5	2.625	V
V_{CCE_GXBL}[9][10]	Transmitter and receiver power (left side)	1.07/1.17	1.1/1.2	1.13/1.23	V
V_{CCL_GXBL}[9][10]	Clock network power (left side)	1.07/1.17	1.1/1.2	1.13/1.23	V

Related Information

- PCIe Supported Configurations and Placement Guidelines
  Provides more information about the maximum full duplex channels recommended in Cyclone V GT and ST devices which require full compliance to the PCIe Gen2 transmit jitter specification.
- 6.144-Gbps Support Capability in Cyclone V GT Devices
  Provides more information about the maximum full duplex channels recommended in Cyclone V GT and ST devices for CPRI 6.144 Gbps.

(8) The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

(9) Intel recommends increasing the V_{CCE_GXBL} and V_{CCL_GXBL} typical value from 1.1 V to 1.2 V for Cyclone V GT and ST FPGA systems which require full compliance to the PCIe Gen2 transmit jitter specification. For more information about the maximum full duplex channels recommended in Cyclone V GT and ST devices under this condition, refer to the *Transceiver Protocol Configurations in Cyclone V Devices* chapter.

(10) Intel recommends increasing the V_{CCE_GXBL} and V_{CCL_GXBL} typical value from 1.1 V to 1.2 V for full compliance to CPRI transmit jitter specification at 4.9152 Gbps (Cyclone V GT and ST devices) and 6.144Gbps (Cyclone V GT and ST devices only). For more information about the maximum full duplex channels recommended in Cyclone V GT and ST devices for CPRI 6.144 Gbps, refer to the *Transceiver Protocol Configurations in Cyclone V Devices* chapter.

HPS Power Supply Operating Conditions

Table 6. HPS Power Supply Operating Conditions for Cyclone V SX and ST Devices

This table lists the steady-state voltage and current values expected from Cyclone V system-on-a-chip (SoC) devices with Arm*-based hard processor system (HPS). Power supply ramps must all be strictly monotonic, without plateaus. Refer to the *Recommended Operating Conditions for Cyclone V Devices* table for the steady-state voltage values expected from the FPGA portion of the Cyclone V SoC devices.

Symbol	Description	Condition	Minimum(11)	Typical	Maximum(11)	Unit
V_{CC_HPS}	HPS core voltage and periphery circuitry power supply	—	1.07	1.1	1.13	V
V_{CCPD_HPS} (12)	HPS I/O pre-driver power supply	3.3 V	3.135	3.3	3.465	V
		3.0 V	2.85	3.0	3.15	V
		2.5 V	2.375	2.5	2.625	V
V_{CCIO_HPS}	HPS I/O buffers power supply	3.3 V	3.135	3.3	3.465	V
		3.0 V	2.85	3.0	3.15	V
		2.5 V	2.375	2.5	2.625	V
		1.8 V	1.71	1.8	1.89	V
		1.5 V	1.425	1.5	1.575	V
		1.35 V (13)	1.283	1.35	1.418	V
		1.2 V	1.14	1.2	1.26	V
$V_{CCRSTCLK\_HPS}$	HPS reset and clock input pins power supply	3.3 V	3.135	3.3	3.465	V
		3.0 V	2.85	3.0	3.15	V
		2.5 V	2.375	2.5	2.625	V

continued...

(11) The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

(12) V_{CCPD_HPS} must be 2.5 V when V_{CCIO_HPS} is 2.5, 1.8, 1.5, or 1.2 V. V_{CCPD_HPS} must be 3.0 V when V_{CCIO_HPS} is 3.0 V. V_{CCPD_HPS} must be 3.3 V when V_{CCIO_HPS} is 3.3 V.

(13) V_{CCIO_HPS} 1.35 V is supported for HPS row I/O bank only.

- ΔV is the variation of voltage with respect to the V_{CCIO} at power up.
- dR/dT is the percentage change of R_{SCAL} with temperature.
- dR/dV is the percentage change of R_{SCAL} with voltage.

OCT Variation after Power-Up Calibration

Table 11. OCT Variation after Power-Up Calibration for Cyclone V Devices

This table lists OCT variation with temperature and voltage after power-up calibration. The OCT variation is valid for a V_{CCIO} range of ±5% and a temperature range of 0°C to 85°C.

Symbol	Description	V_{CCIO} (V)	Value	Unit
dR/dV	OCT variation with voltage without recalibration	3.0	0.100	%/mV
		2.5	0.100	
		1.8	0.100	
		1.5	0.100	
		1.35	0.150	
		1.25	0.150	
		1.2	0.150	
dR/dT	OCT variation with temperature without recalibration	3.0	0.189	%/°C
		2.5	0.208	
		1.8	0.266	
		1.5	0.273	
		1.35	0.200	
		1.25	0.200	
		1.2	0.317	

I/O Standard	V_{CCIO} (V)			V_{ID} (mV)[21]			$V_{ICM(DC)}$ (V)			V_{OD} (V)[22]			V_{OCM} (V)[22][23]		
	Min	Typ	Max	Min	Condition	Max	Min	Condition	Max	Min	Typ	Max	Min	Typ	Max
LVPECL[29]	—	—	—	300	—	—	0.60	D_{MAX} ≤ 700 Mbps	1.80	—	—	—	—	—	—
							1.00	D_{MAX} > 700 Mbps	1.60						
SLVS	2.375	2.5	2.625	100	V_{CM} = 1.25 V	—	0.05	—	1.80	—	—	—	—	—	—
Sub-LVDS	2.375	2.5	2.625	100	V_{CM} = 1.25 V	—	0.05	—	1.80	—	—	—	—	—	—
HiSpi	2.375	2.5	2.625	100	V_{CM} = 1.25 V	—	0.05	—	1.80	—	—	—	—	—	—

Related Information

- AN522: Implementing Bus LVDS Interface in Supported Intel Device Families
  Provides more information about BLVDS interface support in Intel devices.
- Transceiver Specifications for Cyclone V GX, GT, SX, and ST Devices on page 25
  Provides the specifications for transmitter, receiver, and reference clock I/O pin.

Switching Characteristics

This section provides performance characteristics of Cyclone V core and periphery blocks.

(21) The minimum V_{ID} value is applicable over the entire common mode range, V_{CM}.

(22) R_L range: 90 ≤ R_L ≤ 110 Ω.

(23) This applies to default pre-emphasis setting only.

(29) For optimized LVPECL receiver performance, the receiver voltage input range must be within 0.85 V to 1.75 V for data rate above 700 Mbps and 0.45 V to 1.95 V for data rate below 700 Mbps.

Symbol/Description	Condition	Transceiver Speed Grade 5[30]			Transceiver Speed Grade 6			Transceiver Speed Grade 7			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
V_{ICM} (AC coupled)	—	V_{CCE_GXBL} supply[34][35]			V_{CCE_GXBL} supply			V_{CCE_GXBL} supply			V
V_{ICM} (DC coupled)	HCSL I/O standard for the PCIe reference clock	250	—	550	250	—	550	250	—	550	mV
Transmitter REFCLK phase noise[36]	10 Hz	—	—	–50	—	—	–50	—	—	–50	dBc/Hz
	100 Hz	—	—	–80	—	—	–80	—	—	–80	dBc/Hz
	1 KHz	—	—	–110	—	—	–110	—	—	–110	dBc/Hz
	10 KHz	—	—	–120	—	—	–120	—	—	–120	dBc/Hz
	100 KHz	—	—	–120	—	—	–120	—	—	–120	dBc/Hz
	≥1 MHz	—	—	–130	—	—	–130	—	—	–130	dBc/Hz
R_{REF}	—	—	2000 ±1%	—	—	2000 ±1%	—	—	2000 ±1%	—	Ω

(30) Transceiver Speed Grade 5 covers specifications for Cyclone V GT and ST devices.

(34) Intel recommends increasing the V_{CCE_GXBL} and V_{CCL_GXBL} typical value from 1.1 V to 1.2 V for Cyclone V GT and ST FPGA systems which require full compliance to the PCIe Gen2 transmit jitter specification. For more information about the maximum full duplex channels recommended in Cyclone V GT and ST devices under this condition, refer to the *Transceiver Protocol Configurations in Cyclone V Devices* chapter.

(35) Intel recommends increasing the V_{CCE_GXBL} and V_{CCL_GXBL} typical value from 1.1 V to 1.2 V for full compliance to CPRI transmit jitter specification at 4.9152 Gbps (Cyclone V GT and ST devices) and 6.144 Gbps (Cyclone V GT and ST devices only). For more information about the maximum full duplex channels recommended in Cyclone V GT and ST devices for CPRI 6.144 Gbps, refer to the *Transceiver Protocol Configurations in Cyclone V Devices* chapter.

(36) The transmitter REFCLK phase jitter is 30 ps p-p at bit error rate (BER) 10^{-12}.

Intel Quartus Prime 1st Post Tap Pre-Emphasis Setting	Intel Quartus Prime V_{OD} Setting							Unit
	10 (200 mV)	20 (400 mV)	30 (600 mV)	35 (700 mV)	40 (800 mV)	45 (900 mV)	50 (1000 mV)	
11	—	10.2	6.09	5.01	4.23	3.61	—	dB
12	—	11.56	6.74	5.51	4.68	3.97	—	dB
13	—	12.9	7.44	6.1	5.12	4.36	—	dB
14	—	14.44	8.12	6.64	5.57	4.76	—	dB
15	—	—	8.87	7.21	6.06	5.14	—	dB
16	—	—	9.56	7.73	6.49	—	—	dB
17	—	—	10.43	8.39	7.02	—	—	dB
18	—	—	11.23	9.03	7.52	—	—	dB
19	—	—	12.18	9.7	8.02	—	—	dB
20	—	—	13.17	10.34	8.59	—	—	dB
21	—	—	14.2	11.1	—	—	—	dB
22	—	—	15.38	11.87	—	—	—	dB
23	—	—	—	12.67	—	—	—	dB
24	—	—	—	13.48	—	—	—	dB
25	—	—	—	14.37	—	—	—	dB
26	—	—	—	—	—	—	—	dB
27	—	—	—	—	—	—	—	dB
28	—	—	—	—	—	—	—	dB
29	—	—	—	—	—	—	—	dB
30	—	—	—	—	—	—	—	dB
31	—	—	—	—	—	—	—	dB

Related Information

SPICE Models for Intel Devices
Provides the Cyclone V HSSI HSPICE models.

Memory	Mode	Resources Used		Performance			Unit
		ALUTs	Memory	–C6	–C7, –I7	–C8, –A7	
	ROM, all supported width	0	1	420	350	300	MHz
M10K Block	Single-port, all supported widths	0	1	315	275	240	MHz
	Simple dual-port, all supported widths	0	1	315	275	240	MHz
	Simple dual-port with the **read-during-write** option set to **Old Data**, all supported widths	0	1	275	240	180	MHz
	True dual port, all supported widths	0	1	315	275	240	MHz
	ROM, all supported widths	0	1	315	275	240	MHz

Periphery Performance

This section describes the periphery performance, high-speed I/O, and external memory interface.

Actual achievable frequency depends on design and system specific factors. Ensure proper timing closure in your design and perform HSPICE/IBIS simulations based on your specific design and system setup to determine the maximum achievable frequency in your system.

OCT Calibration Block Specifications

Table 38. OCT Calibration Block Specifications for Cyclone V Devices

Symbol	Description	Min	Typ	Max	Unit
OCTUSRCLK	Clock required by OCT calibration blocks	—	—	20	MHz
T_{OCTCAL}	Number of OCTUSRCLK clock cycles required for R_S OCT/R_T OCT calibration	—	1000	—	Cycles
$T_{OCTSHIFT}$	Number of OCTUSRCLK clock cycles required for OCT code to shift out	—	32	—	Cycles
T_{RS_RT}	Time required between the dyn_term_ctrl and oe signal transitions in a bidirectional I/O buffer to dynamically switch between R_S OCT and R_T OCT	—	2.5	—	ns

Figure 5. Timing Diagram for oe and dyn_term_ctrl Signals

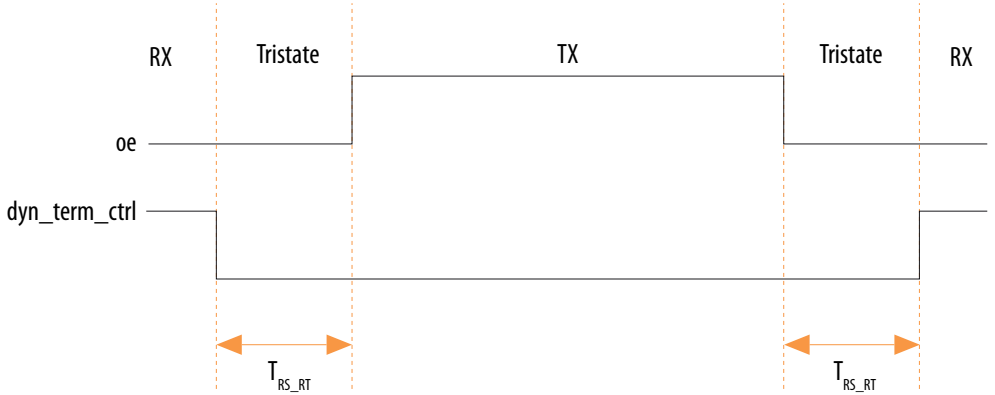
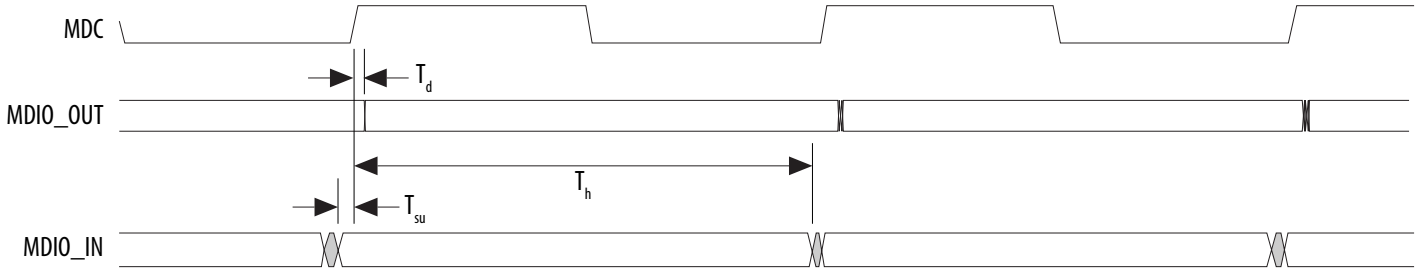


Figure 13. MDIO Timing Diagram



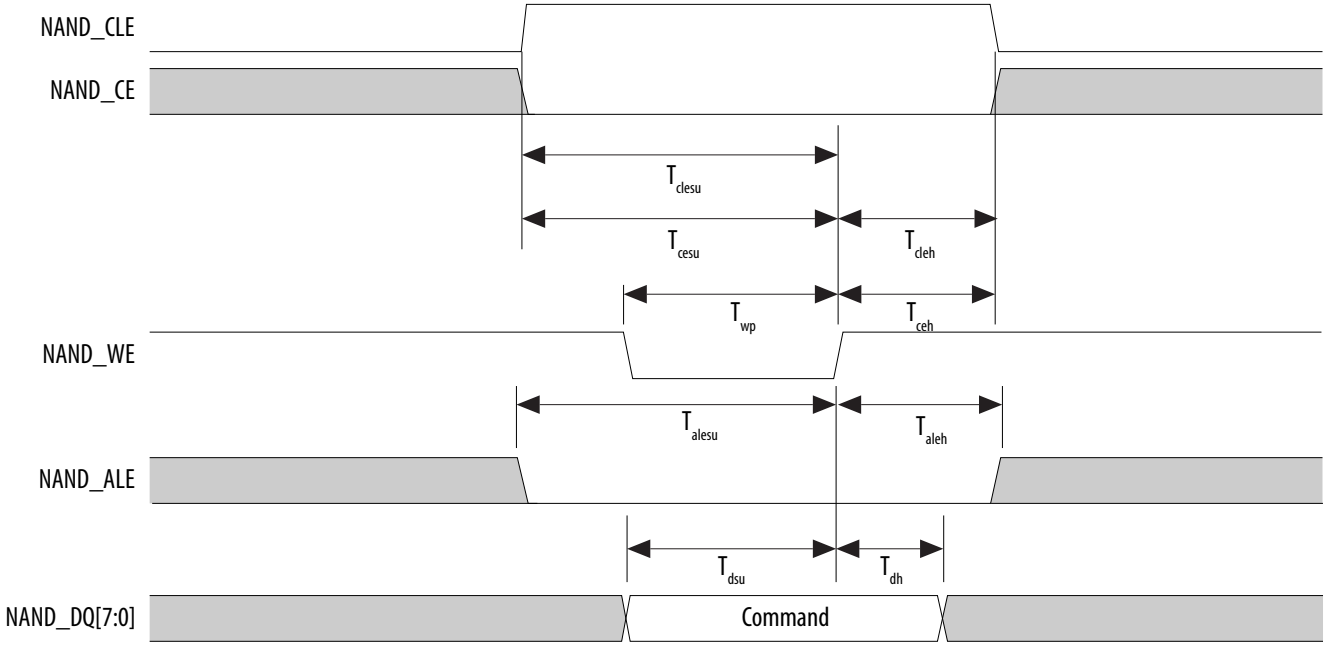
I²C Timing Characteristics

Table 51. I²C Timing Requirements for Cyclone V Devices

Symbol	Description	Standard Mode		Fast Mode		Unit
		Min	Max	Min	Max	
T_{clk}	Serial clock (SCL) clock period	10	—	2.5	—	µs
$T_{clkhigh}$	SCL high time	4.7	—	0.6	—	µs
T_{clklow}	SCL low time	4	—	1.3	—	µs
T_s	Setup time for serial data line (SDA) data to SCL	0.25	—	0.1	—	µs
T_h	Hold time for SCL to SDA data	0	3.45	0	0.9	µs
T_d	SCL to SDA output data delay	—	0.2	—	0.2	µs
T_{su_start}	Setup time for a repeated start condition	4.7	—	0.6	—	µs
T_{hd_start}	Hold time for a repeated start condition	4	—	0.6	—	µs
T_{su_stop}	Setup time for a stop condition	4	—	0.6	—	µs

Symbol	Description	Min	Max	Unit
T_{cea}	Chip enable to data access time	—	25	ns
T_{rea}	Read enable to data access time	—	16	ns
T_{rhz}	Read enable to data high impedance	—	100	ns
T_{rr}	Ready to read enable low	20	—	ns

Figure 15. NAND Command Latch Timing Diagram



POR Specifications

Table 55. Fast and Standard POR Delay Specification for Cyclone V Devices

POR Delay	Minimum	Maximum	Unit
Fast	4	12[74]	ms
Standard	100	300	ms

Related Information

MSEL Pin Settings

Provides more information about POR delay based on MSEL pin settings for each configuration scheme.

FPGA JTAG Configuration Timing

Table 56. FPGA JTAG Timing Parameters and Values for Cyclone V Devices

Symbol	Description	Min	Max	Unit
t_{JCP}	TCK clock period	30, 167[75]	—	ns
t_{JCH}	TCK clock high time	14	—	ns
t_{JCL}	TCK clock low time	14	—	ns
$t_{JPSU\ (TDI)}$	TDI JTAG port setup time	1	—	ns
$t_{JPSU\ (TMS)}$	TMS JTAG port setup time	3	—	ns
t_{JPH}	JTAG port hold time	5	—	ns

continued...

(74) The maximum pulse width of the fast POR delay is 12 ms, providing enough time for the PCIe hard IP to initialize after the POR trip.

(75) The minimum TCK clock period is 167 ns if V_{CCBAT} is within the range 1.2 V – 1.5 V when you perform the volatile key programming.

Symbol	Description	Min	Max	Unit
t_{JPCO}	JTAG port clock to output	—	11[76]	ns
t_{JPZX}	JTAG port high impedance to valid output	—	14[76]	ns
t_{JPXZ}	JTAG port valid output to high impedance	—	14[76]	ns

FPP Configuration Timing

DCLK-to-DATA[] Ratio (r) for FPP Configuration

Fast passive parallel (FPP) configuration requires a different DCLK-to-DATA[] ratio when you turn on encryption or the compression feature.

Depending on the DCLK-to-DATA[] ratio, the host must send a DCLK frequency that is *r* times the DATA[] rate in byte per second (Bps) or word per second (Wps). For example, in FPP ×16 where the *r* is 2, the DCLK frequency must be 2 times the DATA[] rate in Wps.

Cyclone V devices use additional clock cycles to decrypt and decompress the configuration data. If the DCLK-to-DATA[] ratio is greater than 1, at the end of configuration, you can only stop the DCLK (DCLK-to-DATA[] ratio – 1) clock cycles after the last data is latched into the Cyclone V device.

Table 57. DCLK-to-DATA[] Ratio for Cyclone V Devices

Configuration Scheme	Encryption	Compression	DCLK-to-DATA[] Ratio (r)
FPP (8-bit wide)	Off	Off	1
	On	Off	1
	Off	On	2
	On	On	2
FPP (16-bit wide)	Off	Off	1

continued...

(76) A 1-ns adder is required for each VCCIO voltage step down from 3.0 V. For example, tJPCO= 13 ns if VCCIO of the TDO I/O bank = 2.5 V, or 14 ns if it equals 1.8 V.

Configuration Files

Table 64. Uncompressed .rbf Sizes for Cyclone V Devices

Use this table to estimate the file size before design compilation. Different configuration file formats, such as a hexadecimal file (`.hex`) or tabular text file (`.ttf`) format, have different file sizes.

For the different types of configuration file and file sizes, refer to the Intel Quartus Prime software. However, for a specific version of the Intel Quartus Prime software, any design targeted for the same device has the same uncompressed configuration file size.

The IOCSR raw binary file (`.rbf`) size is specifically for the Configuration via Protocol (CvP) feature.

Variant	Member Code	Configuration .rbf Size (bits)	IOCSR .rbf Size (bits)	Recommended EPCQ Serial Configuration Device(94)
Cyclone V E (95)	A2	21,061,280	275,608	EPCQ64
	A4	21,061,280	275,608	EPCQ64
	A5	33,958,560	322,072	EPCQ128
	A7	56,167,552	435,288	EPCQ128
	A9	102,871,776	400,408	EPCQ256
Cyclone V GX	C3	14,510,912	320,280	EPCQ32
	C4	33,958,560	322,072	EPCQ128
	C5	33,958,560	322,072	EPCQ128
	C7	56,167,552	435,288	EPCQ128
	C9	102,871,776	400,408	EPCQ256
Cyclone V GT	D5	33,958,560	322,072	EPCQ128
	D7	56,167,552	435,288	EPCQ128
	D9	102,871,776	400,408	EPCQ256
Cyclone V SE (95)	A2	33,958,560	322,072	EPCQ128

continued...

(94) The recommended EPCQ serial configuration devices are able to store more than one image.

(95) No PCIe hard IP, configuration via protocol (CvP) is not supported in this family.

Variant	Member Code	Configuration .rbf Size (bits)	IOCSR .rbf Size (bits)	Recommended EPCQ Serial Configuration Device(94)
	A4	33,958,560	322,072	EPCQ128
	A5	56,057,632	324,888	EPCQ128
	A6	56,057,632	324,888	EPCQ128
Cyclone V SX	C2	33,958,560	322,072	EPCQ128
	C4	33,958,560	322,072	EPCQ128
	C5	56,057,632	324,888	EPCQ128
	C6	56,057,632	324,888	EPCQ128
Cyclone V ST	D5	56,057,632	324,888	EPCQ128
	D6	56,057,632	324,888	EPCQ128

Minimum Configuration Time Estimation

Table 65. Minimum Configuration Time Estimation for Cyclone V Devices

The estimated values are based on the configuration `.rbf` sizes in *Uncompressed .rbf Sizes for Cyclone V Devices* table.

Variant	Member Code	Active Serial(96)			Fast Passive Parallel(97)		
		Width	DCLK (MHz)	Minimum Configuration Time (ms)	Width	DCLK (MHz)	Minimum Configuration Time (ms)
Cyclone V E	A2	4	100	53	16	125	11
	A4	4	100	53	16	125	11
	A5	4	100	85	16	125	17
	A7	4	100	140	16	125	28

continued...

(94) The recommended EPCQ serial configuration devices are able to store more than one image.

(96) DCLK frequency of 100 MHz using external CLKUSR.

(97) Maximum FPGA FPP bandwidth may exceed bandwidth available from some external storage or control logic.

Variant	Member Code	Active Serial[96]			Fast Passive Parallel[97]		
		Width	DCLK (MHz)	Minimum Configuration Time (ms)	Width	DCLK (MHz)	Minimum Configuration Time (ms)
	A9	4	100	257	16	125	51
Cyclone V GX	C3	4	100	36	16	125	7
	C4	4	100	85	16	125	17
	C5	4	100	85	16	125	17
	C7	4	100	140	16	125	28
	C9	4	100	257	16	125	51
Cyclone V GT	D5	4	100	85	16	125	17
	D7	4	100	140	16	125	28
	D9	4	100	257	16	125	51
Cyclone V SE	A2	4	100	85	16	125	17
	A4	4	100	85	16	125	17
	A5	4	100	140	16	125	28
	A6	4	100	140	16	125	28
Cyclone V SX	C2	4	100	85	16	125	17
	C4	4	100	85	16	125	17
	C5	4	100	140	16	125	28
	C6	4	100	140	16	125	28
Cyclone V ST	D5	4	100	140	16	125	28
	D6	4	100	140	16	125	28

(96) DCLK frequency of 100 MHz using external CLKUSR.

(97) Maximum FPGA FPP bandwidth may exceed bandwidth available from some external storage or control logic.

Programmable Output Buffer Delay

Table 69. Programmable Output Buffer Delay for Cyclone V Devices

This table lists the delay chain settings that control the rising and falling edge delays of the output buffer.

You can set the programmable output buffer delay in the Intel Quartus Prime software by setting the **Output Buffer Delay Control** assignment to either positive, negative, or both edges, with the specific values stated here (in ps) for the **Output Buffer Delay** assignment.

Symbol	Parameter	Typical	Unit
D_{OUTBUF}	Rising and/or falling edge delay	0 (default)	ps
		50	ps
		100	ps
		150	ps

Glossary

Table 70. Glossary

Term	Definition
Differential I/O standards	Receiver Input Waveforms

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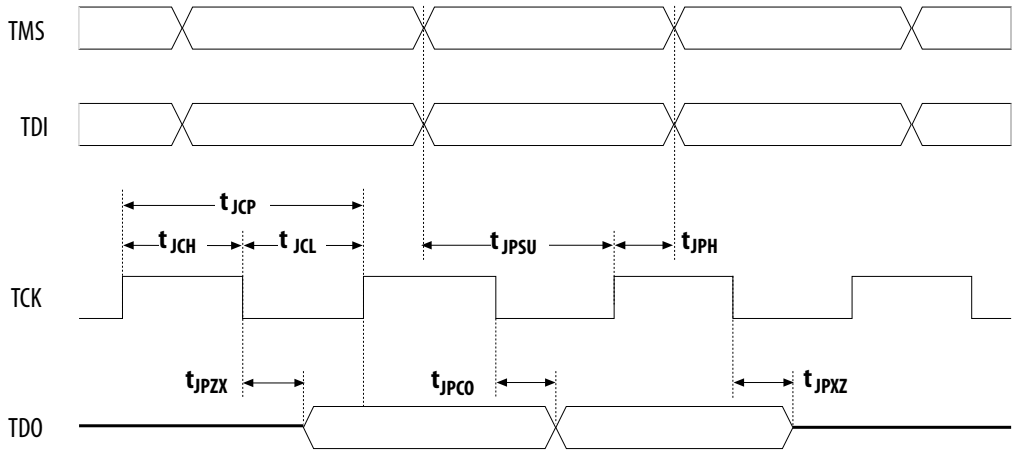
Term	Definition
	
PLL specifications	Diagram of PLL specifications

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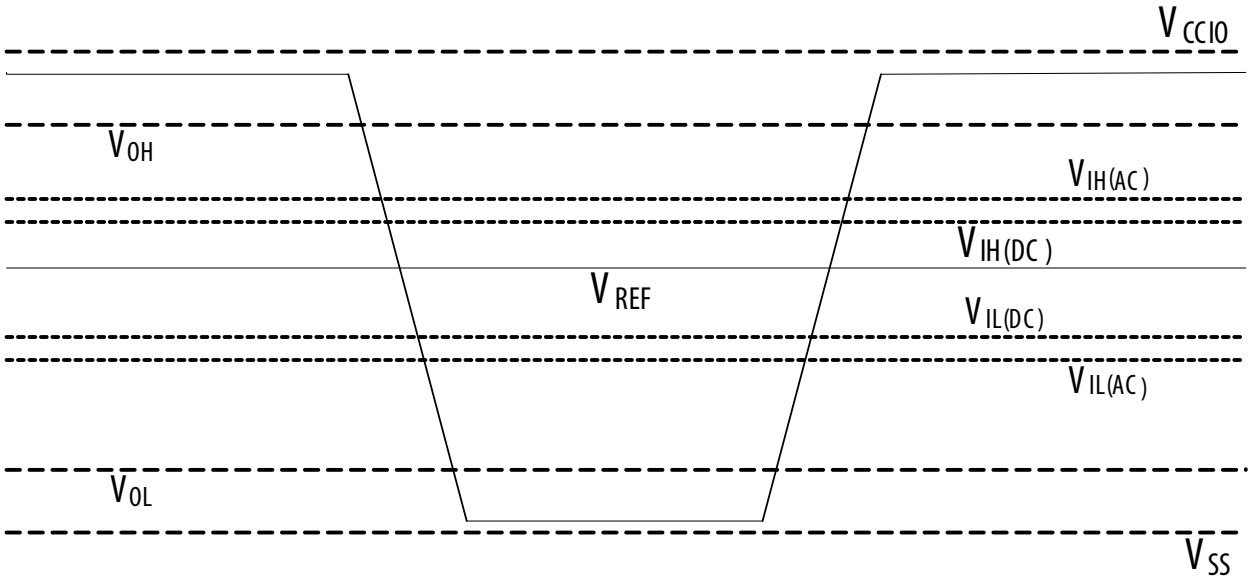
Term	Definition
Single-ended voltage referenced I/O standard	The JEDEC standard for the SSTL and HSTL I/O defines both the AC and DC input signal values. The AC values indicate the voltage levels at which the receiver must meet its timing specifications. The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined. After the receiver input has crossed the AC value, the receiver changes to the new logic state. The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform ringing. Single-Ended Voltage Referenced I/O Standard 
t_C	High-speed receiver/transmitter input and output clock period.
TCCS (channel-to-channel-skew)	The timing difference between the fastest and slowest output edges, including the t_{CO} variation and clock skew, across channels driven by the same PLL. The clock is included in the TCCS measurement (refer to the Timing Diagram figure under SW in this table).
t_{DUTY}	High-speed I/O block—Duty cycle on high-speed transmitter output clock.
t_{FALL}	Signal high-to-low transition time (80–20%)
t_{INCCJ}	Cycle-to-cycle jitter tolerance on the PLL clock input

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Date	Version	Changes
January 2015	2015.01.23	• Updated the transceiver specification for Cyclone V ST from 5 Gbps to 6.144 Gbps. Updated the note in the following tables: — Transceiver Power Supply Operating Conditions for Cyclone V GX, GT, SX, and ST Devices — Transceiver Specifications for Cyclone V GX, GT, SX, and ST Devices — Transceiver Compliance Specification for All Supported Protocol for Cyclone V Devices • Updated the description for $V_{CC\_AUX\_SHARED}$ to "HPS auxiliary power supply". Added a note to state that $V_{CC\_AUX\_SHARED}$ must be powered by the same source as VCC_AUX for Cyclone V SX C5, C6, D5, and D6 devices, and Cyclone V SE A5 and A6 devices. Updated in the following tables: — Absolute Maximum Ratings for Cyclone V Devices — HPS Power Supply Operating Conditions for Cyclone V SE, SX, and ST Devices • Added statement in I/O Standard Specifications: You must perform timing closure analysis to determine the maximum achievable frequency for general purpose I/O standards. • Updated the conditions for transceiver reference clock rise time and fall time: Measure at ±60 mV of differential signal. Added a note to the conditions: REFCLK performance requires to meet transmitter REFCLK phase noise specification. • Updated f_{VCO} maximum value from 1400 MHz to 1600 MHz for –C7 and –I7 speed grades in the PLL specifications table. • Updated the description in Periphery Performance Specifications to mention that proper timing closure is required in design. • Added the following notes in the High-Speed I/O Specifications for Cyclone V Devices table: — The Cyclone V devices support true RSDS output standard with data rates of up to 230 Mbps using true LVDS output buffer types on all I/O banks. — The Cyclone V devices support true mini-LVDS output standard with data rates of up to 340 Mbps using true LVDS output buffer types on all I/O banks. • Updated HPS Clock Performance main_base_clk specifications from 462 MHz to 400 MHz for –C6 speed grade. • Updated HPS PLL VCO maximum frequency to 1,600 MHz (for –C7, –I7, –A7, and –C8 speed grades) and 1,850 MHz (for –C6 speed grade). • Changed the symbol for HPS PLL input jitter divide value from NR to N. • Removed "Slave select pulse width (Texas Instruments SSP mode)" parameter from the following tables: — SPI Master Timing Requirements for Cyclone V Devices — SPI Slave Timing Requirements for Cyclone V Devices • Added descriptions to USB Timing Characteristics section in HPS Specifications: PHYs that support LPM mode may not function properly with the USB controller due to a timing issue. It is recommended that designers use the MicroChip USB3300 PHY device that has been proven to be successful on the development board. • Added HPS JTAG timing specifications. • Updated the configuration `.rbf` size (bits) for Cyclone V devices. • Added a note to Uncompressed .rbf Sizes for Cyclone V Devices table: The recommended EPCQ serial configuration devices are able to store more than one image.

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